



ACAT 2022

COVFIE: a compositional library for heterogeneous vector fields

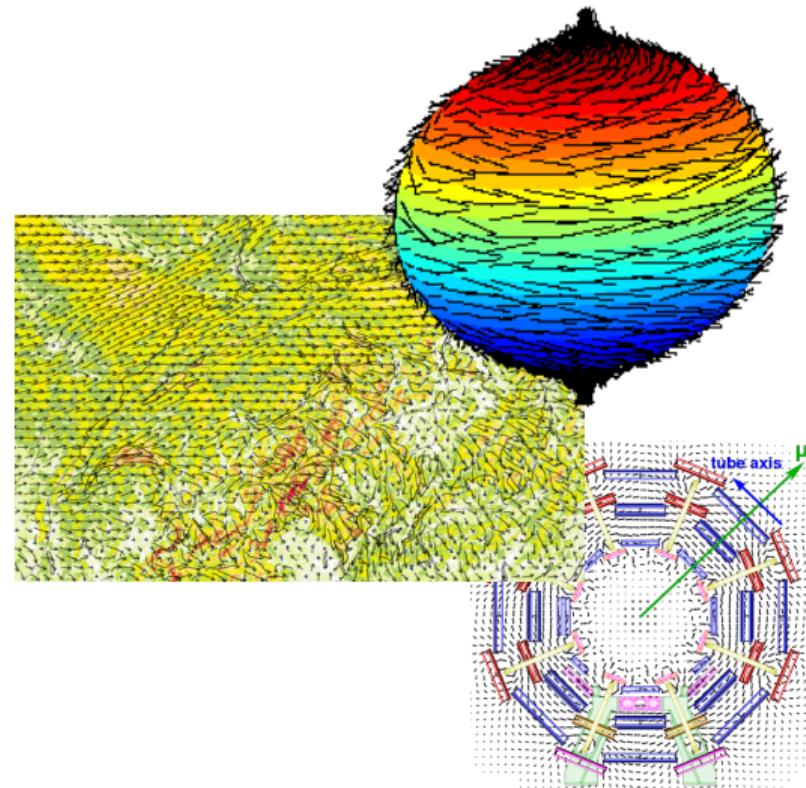
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Wednesday, October 26, 2022

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Introduction

- Vector fields are used everywhere
 - Oceanography
 - Atmospheric science
 - High-energy physics
- Different functional and non-functional properties
- Many non-unified different implementations of fields



Introduction

- Enter COVFILE, the **compositional vector field library**
- Goal is to...
 - support arbitrary vector fields...
 - across many devices...
 - with high performance...
 - in a simple way...
 - through composition.

The screenshot shows the GitHub repository page for `acts-project / covfile`. The repository is public and has 219 commits. The main branch is `main`, and there is 1 branch. The repository has 3 logos. The commit history shows various contributions from `stephenswat`, including updates for building with CUDA in CI, changes to Lorentz-Euler execution parameters, and improvements to compiler messages. Other commits mention ATLAS experiments, throughput analysis, and generic CUDA tests. The repository includes files like `github/workflows`, `benchmarks`, `cmake`, `docs`, `examples`, `extra_layers`, `lib`, `tests`, `clang-format`, `gitignore`, `CMakeLists.txt`, `LICENSE`, and `README.md`. The `README.md` file is visible at the bottom. On the right side, there are sections for **About** (describing it as a library for storing interpolable vector fields on co-processors), **Releases** (with 3 tags and a link to create a new release), **Packages** (no packages published), and **Languages** (C++ 90.3%, CUDA 6.0%, Cuda 2.0%, and Haskell 1.7%).

Composition

- Let's consider the simplest vector field f :
 \mathbb{R}^3 in memory

$$f: \mathbb{N} \rightarrow \mathbb{R}^3$$

Composition

- Let's consider the simplest vector field f :
 \mathbb{R}^3 in memory
- We can turn this into an $\mathbb{N} \rightarrow B$ field by covariantly composing a function
 $g_1 : \mathbb{R}^3 \rightarrow B\dots$

$$\begin{array}{ccc} f : \mathbb{N} & \xrightarrow{\quad} & \mathbb{R}^3 \\ & \searrow & \\ & & g_1 \circ f : \mathbb{N} \rightarrow B \end{array}$$

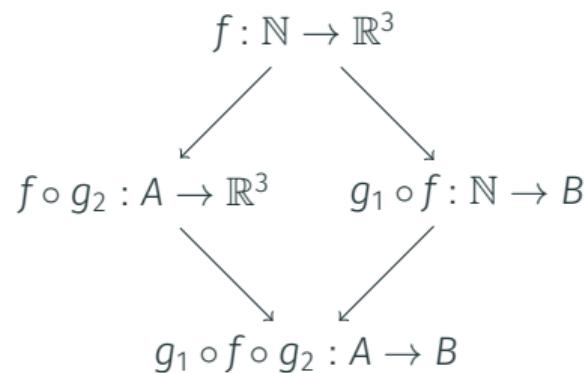
Composition

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- ...into an $A \rightarrow \mathbb{R}^3$ field by contravariantly composing a function $g_2 : A \rightarrow \mathbb{R}^3$

$$\begin{array}{ccc} f : \mathbb{N} & \xrightarrow{\quad} & \mathbb{R}^3 \\ & \searrow & \swarrow \\ f \circ g_2 : A & \xrightarrow{\quad} & \mathbb{R}^3 & g_1 \circ f : \mathbb{N} & \xrightarrow{\quad} & B \end{array}$$

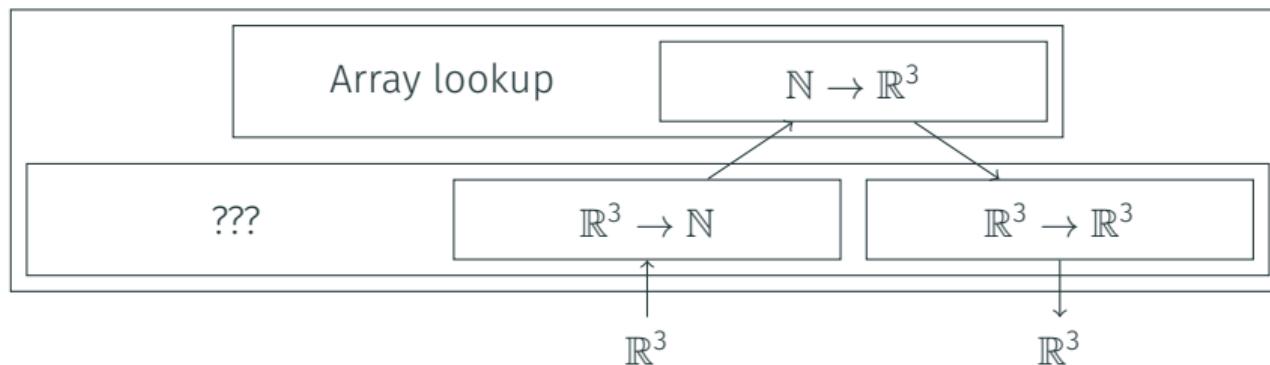
Composition

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- ...into an $A \rightarrow \mathbb{R}^3$ field by contravariantly composing a function $g_2 : A \rightarrow \mathbb{R}^3$
- Transformer* $t = \langle g_1, g_2 \rangle$ lets us build any field



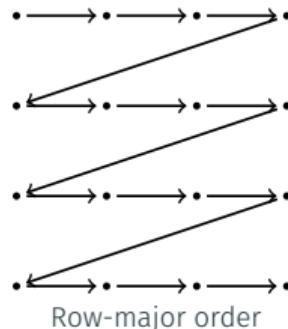
Example: ATLAS

- Let's consider the ATLAS magnetic field, which we can build using:
 - A primitive storage backend $\mathbb{N} \rightarrow \mathbb{R}^3$: our memory
 - ...and a transformer $(\mathbb{R}^3 \rightarrow \mathbb{N}, \mathbb{R}^3 \rightarrow \mathbb{R}^3)$
- But this is too complex, let's decompose!

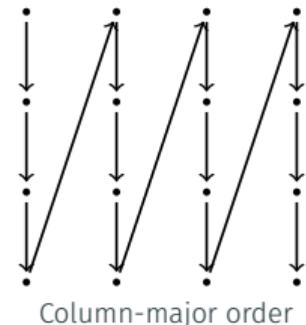


3D Layouts

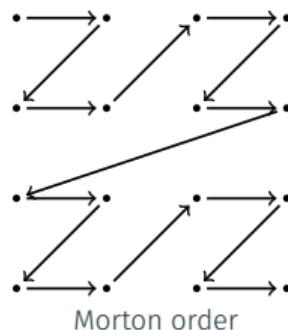
- Primitive backends are intentionally simple
- Add functional and non-functional properties on a need-to-have basis
- Functionally, we need three-dimensional access
- Non-functionally, layouts matter (caching!)



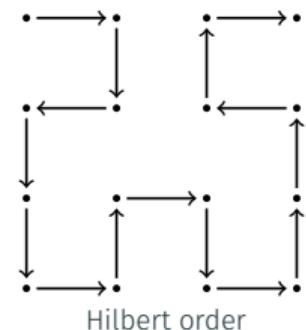
Row-major order



Column-major order



Morton order



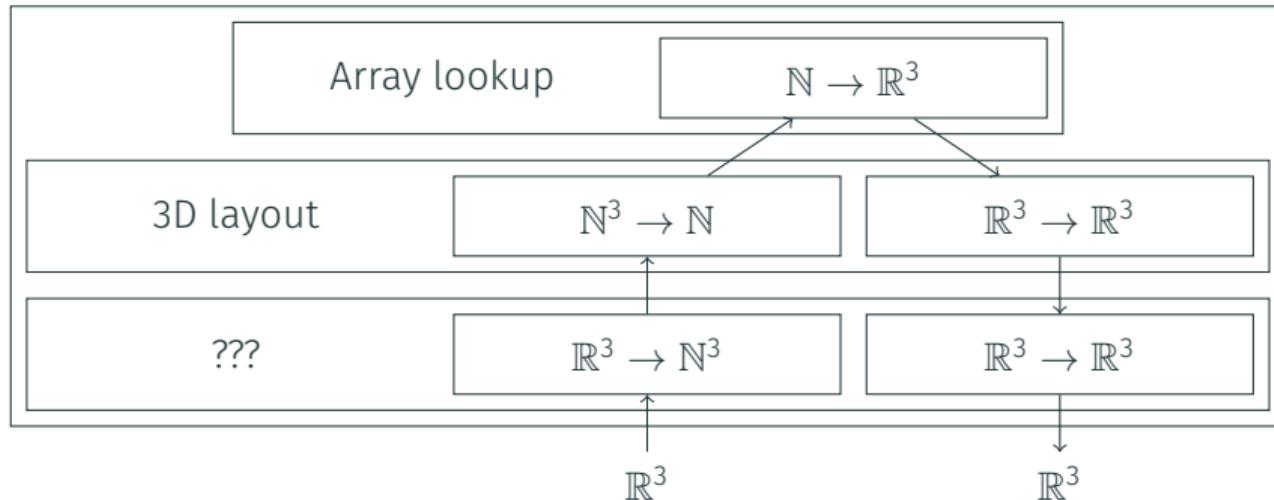
Hilbert order

3D Layouts

- Let's pick a Morton curve and compose it with our primitive backend:

```
1 using field_t = covfie::layout::morton<
2     ulong2,
3     covfie::storage::array<float2>
4 >;
```

Example: ATLAS



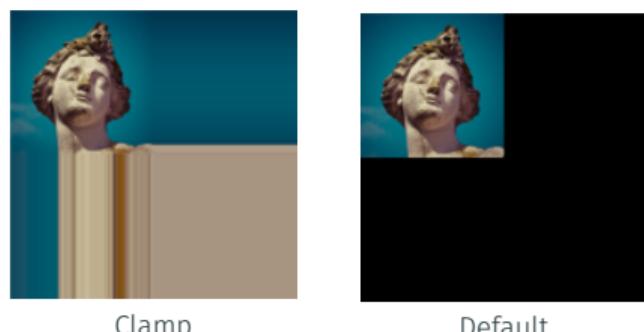
Bounds checking

- LDMX talk yesterday: behaviour at B-field bounds is important
- Borrow schemes from computer graphics:
 - Repeat
 - Mirror
 - Clamp
 - Default



Repeat

Mirror



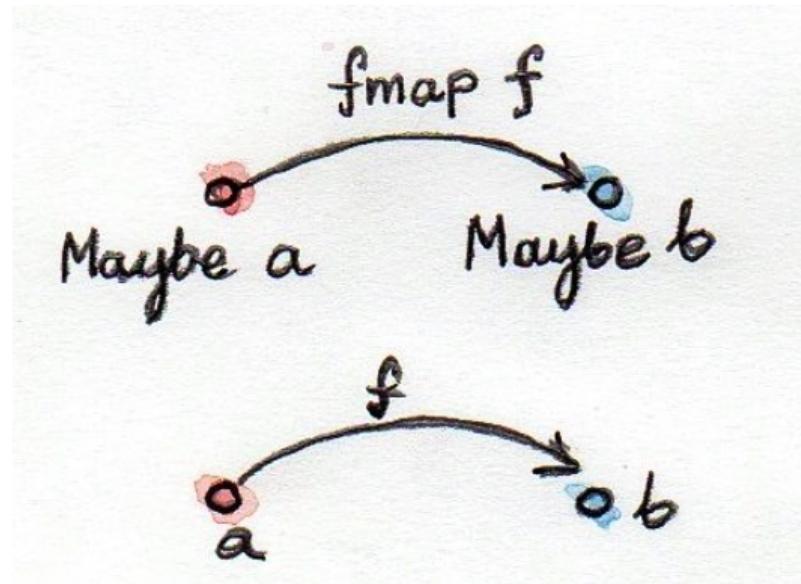
Clamp

Default

Source: Julien Delezenne

Bounds Checking

- Let's return the zero vector $\vec{0}$ for our of bounds errors
- Problem: out-of-bounds-ness is only known contravariantly...
- ...and we need this information covariantly
- How do we pass this information around?
- Wrap our contravariant output and covariant input in an optional functor $F(a) = a + \mathbb{1}$



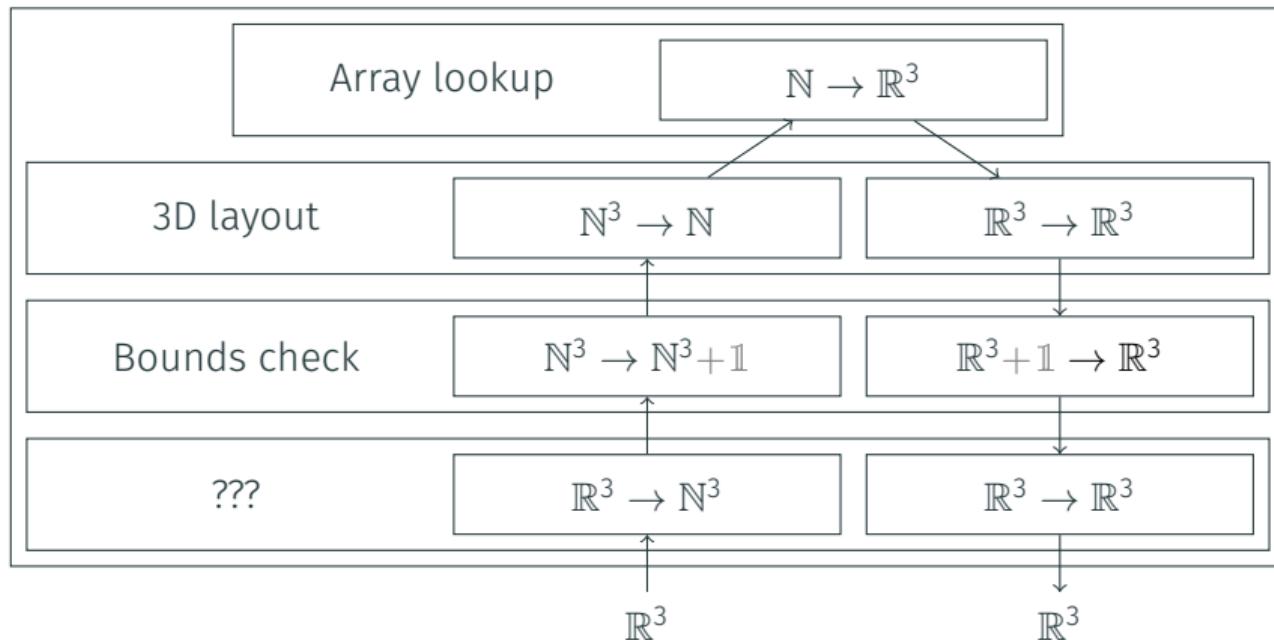
Source: Bartosz Milewski

Bounds Checking

- Let's compose a bounds checking transformer:

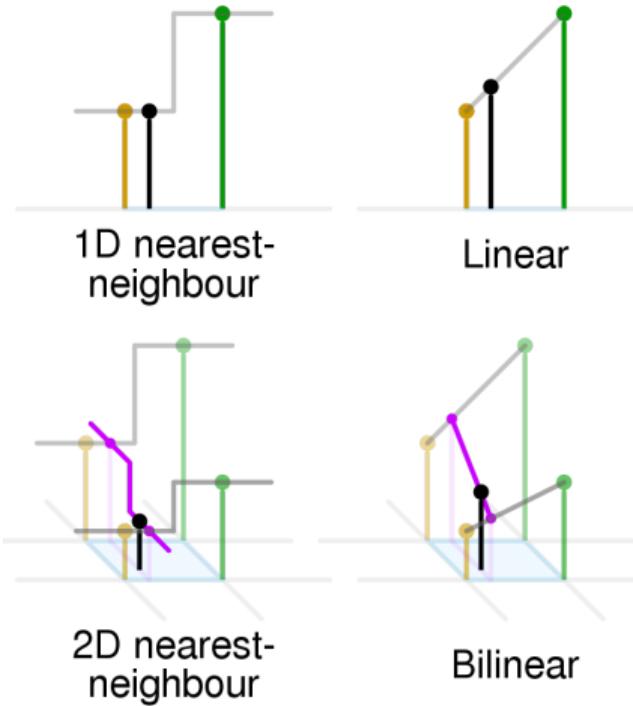
```
1 using field_t = covfie::boundary::def<
2     covfie::layout::morton<
3         ulong2,
4         covfie::storage::array<float2>
5     >
6 >;
```

Example: ATLAS



Interpolation

- Our field is currently indexed using natural numbers: not much use for a B-field
- Need an interpolation method to go from real coordinates to natural
 - Nearest neighbour
 - n -linear



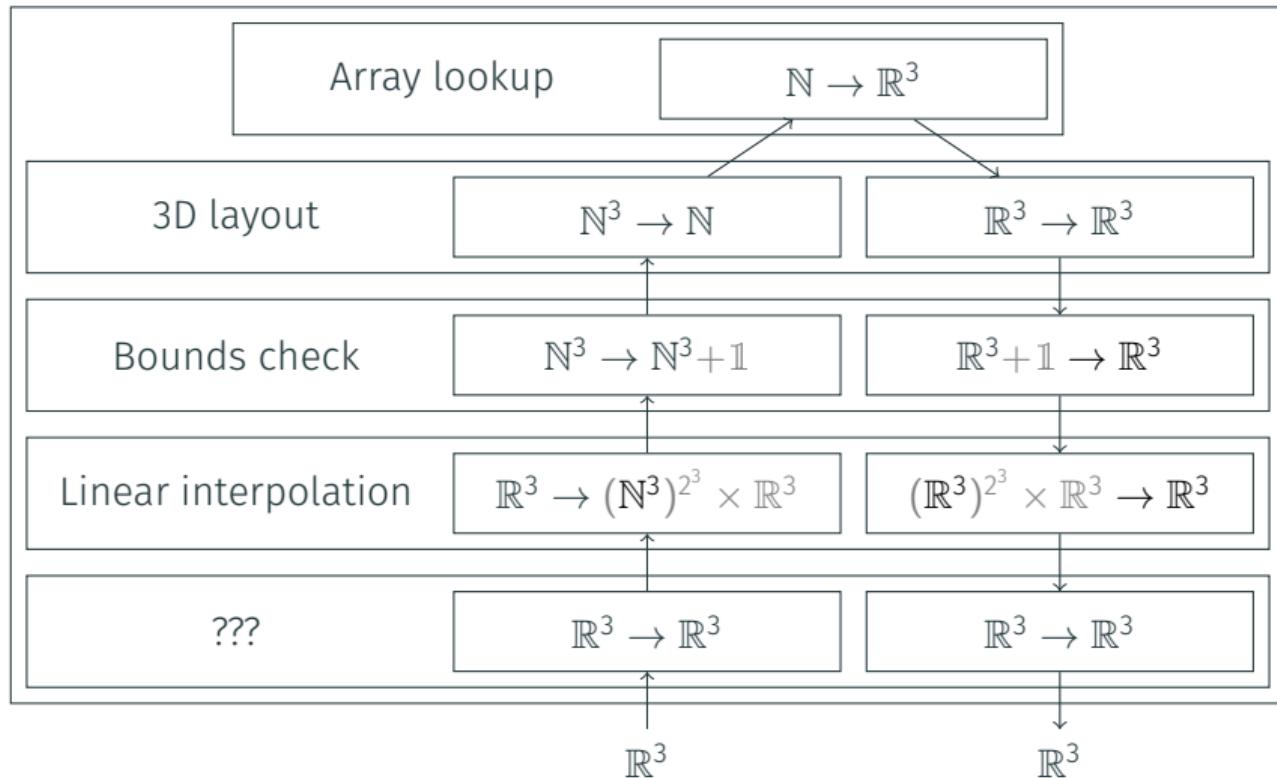
Source: Cmglee

Interpolation

- Let's add a trilinear interpolator to our vector field:

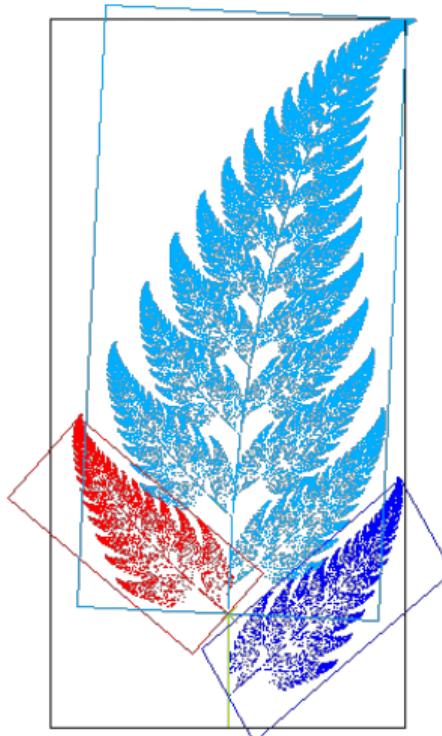
```
1 using field_t = covfie::interpolator::linear<
2     covfie::boundary::def<
3         covfie::layout::morton<
4             ulong2,
5             covfie::storage::array<float2>
6         >
7     >
8 >;
```

Example: ATLAS



Transformations

- Right now, coordinate $(0, 0, 0)$ is at the top left corner of the field...
- ...not in the center of the detector
- No problem: just compose an affine transformation!
- Takes arbitrary $(n + 1) \times (n + 1)$ transformation matrix



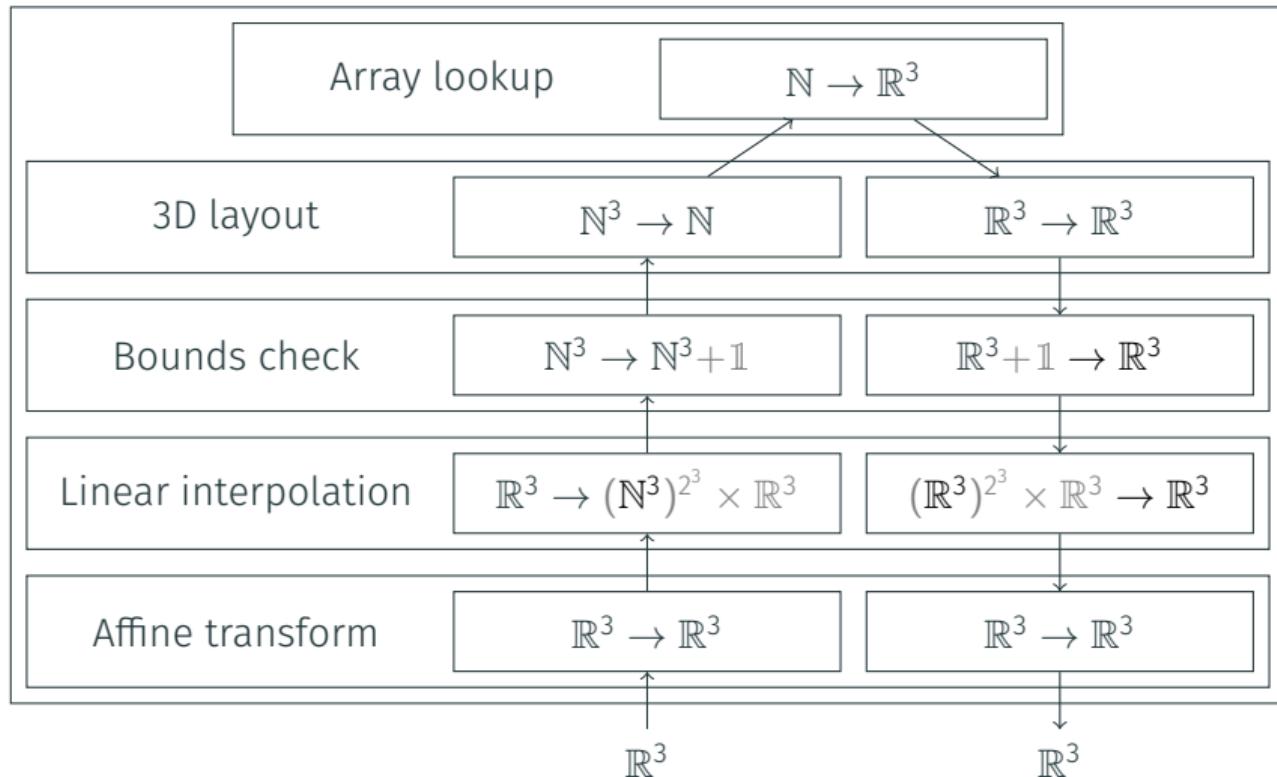
Source: António Miguel de Campos

Interpolation

- Thereby we arrive at our final type:

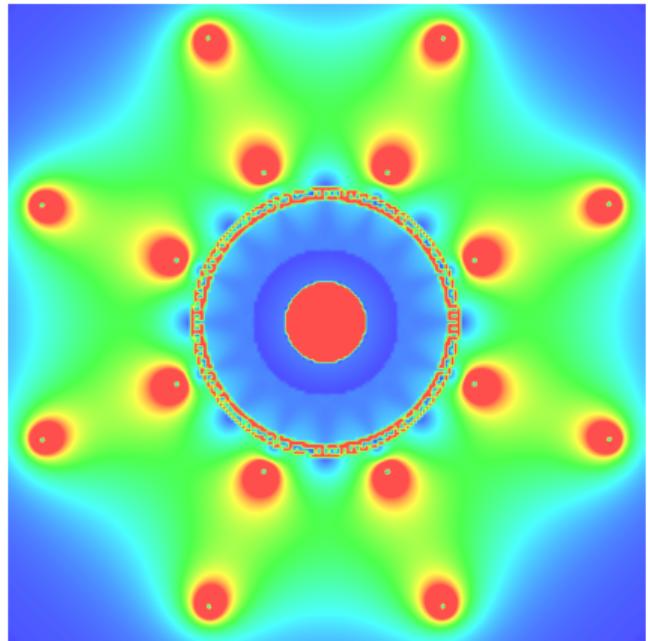
```
1 using field_t = covfie::transformation::affine<
2     covfie::interpolator::linear<
3         covfie::boundary::def<
4             covfie::layout::morton<
5                 ulong2,
6                 covfie::storage::array<float2>
7             >
8         >
9     >
10 >;
```

Example: ATLAS



Rendering

```
1 field_t::view_t fv(f);
2
3 for (std::size_t x = 0; x < im_size[1]; ++x) {
4     for (std::size_t y = 0; y < im_size[0]; ++y) {
5         field_t::view_t::output_t p = fv.at(x, y);
6
7         img[im_size[1] * y + x] = static_cast<char>(
8             255.f *
9             std::min(std::sqrt(mag(p)), 1.0f)
10            );
11    }
12 }
```



List of Primitive Backends

Name	Platform	Field type
ARRAY	CPU	$\prod_{T:\mathcal{V}} \mathbb{N} \rightarrow T$
CUDAARRAY	CUDA	$\prod_{T:\mathcal{V}} \mathbb{N} \rightarrow T$
CUDAPITCH	CUDA	$\prod_{d:[1,3]} \prod_{T:\mathcal{V}} \mathbb{N}^d \rightarrow T$
CUDATEX	CUDA	$\prod_{d:[1,3]} \prod_{d':[1,4]} \mathbb{R}^d \rightarrow \mathbb{R}^{d'}$
ANALYTIC	CPU	$\prod_{S,T:\mathcal{V}} S \rightarrow T$
CONSTANT	Any	$\prod_{S,T:\mathcal{V}} S \rightarrow T$

List of Backend Transformers

Name	Type
PITCHED	$\prod_{n:\mathbb{N}} \prod_{T \text{ Type}} (\mathbb{N}^n \rightarrow \mathbb{N}) \times (T \rightarrow T)$
MORTON	$\prod_{n:\mathbb{N}} \prod_{T \text{ Type}} (\mathbb{N}^n \rightarrow \mathbb{N}) \times (T \rightarrow T)$
HILBERT	$\prod_{T \text{ Type}} (\mathbb{N}^2 \rightarrow \mathbb{N}) \times (T \rightarrow T)$
SHUFFLE	$\prod_{n:\mathbb{N}} \prod_{p:\mathfrak{S}_n} \prod_{S,T \text{ Type}} (S^n \rightarrow S^n) \times (T \rightarrow T)$
DEFAULT	$\prod_{S,T \text{ Type}} (S \rightarrow S + \mathbb{1}) \times (T + \mathbb{1} \rightarrow T)$
WRAP	$\prod_{S,T \text{ Type}} (S \rightarrow S) \times (T \rightarrow T)$
NEAREST	$\prod_{n:\mathbb{N}} \prod_{T \text{ Type}} (\mathbb{R}^n \rightarrow \mathbb{N}^n) \times (T \rightarrow T)$
LINEAR	$\prod_{n:\mathbb{N}} (\mathbb{R}^n \rightarrow (\mathbb{N}^n)^{2^n} \times \mathbb{R}^n) \times ((\mathbb{R}^n)^{2^n} \times \mathbb{R}^3 \rightarrow \mathbb{R}^n)$
AFFINE	$\prod_{n:\mathbb{N}} \prod_{T \text{ Type}} (\mathbb{R}^n \rightarrow \mathbb{R}^n) \times (T \rightarrow T)$

Moving this to a GPU

CPU

```
1 using field_t = covfie::interpolator::linear<
2   covfie::boundary::def<
3     covfie::layout::morton<
4       ulong2,
5       covfie::storage::array<
6         float2
7       >
8     >
9   >
10>;
```

GPU

```
1 using field_t = covfie::interpolator::linear<
2   covfie::boundary::def<
3     covfie::layout::morton<
4       ulong2,
5       covfie::storage::cuda::array<
6         float2
7       >
8     >
9   >
10>;
```

- Type conversion includes movement of the data to or from the GPU

Rendering on a GPU

- Field types are convertible
- Simply put one into your CUDA kernel: no hassle!

```
1 __global__ void render(
2     typename field_t::view_t vf, char * out,
3     uint width, uint height, float z
4 ) {
5     int x = blockDim.x * blockIdx.x + threadIdx.x;
6     int y = blockDim.y * blockIdx.y + threadIdx.y;
7
8     if (x < width && y < height) {
9         float fx = x / static_cast<float>(width);
10        float fy = y / static_cast<float>(height);
11
12        typename field_t::output_t p = vf.at(fx, fy, z);
13        out[height * x + y] = static_cast<char>(
14            255.f *
15            std::min(mag(p), 1.0f)
16        );
17    }
18 }
```

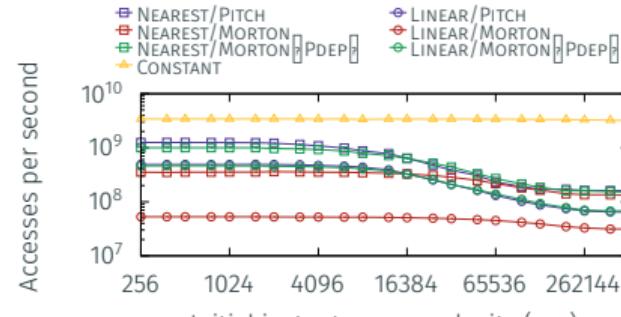
Texture “Memory”

- Primitive backends need not be as simple as an array
- GPUs support special texture “memory”
 - It’s just global memory with storage layouts, separate caching, and hardware acceleration
- In some cases, may provide performance benefits
- Entirely encapsulated as primitive COVIE backend

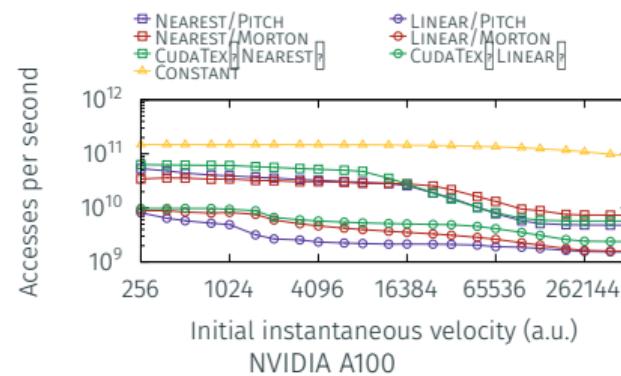


Benchmarking

- covFIE also comes with a benchmark suite
- Set of mini-apps with different access patterns
- Includes RK1 and RK4 propagation of agents
- Fun results for depth-first RK4 propagation of 65 536 agents



Intel Xeon E5-2630 v3 (2 sockets, 32 threads)



Conclusions

- covFIE is available right now to try!
- Header-only, documented, and easy to use
- <https://github.com/acts-project/covfie>
- Please get in contact
stephen.nicholas.swatman@cern.ch!

The screenshot shows the GitHub repository page for `acts-project/covfie`. The repository is public and has 219 commits. The main branch is `main`, and there is 1 branch. The repository has 3 logs. The commit history shows various contributions from `stephenswat`, including updates to GitHub workflows, benchmarks, cmake, doxygen, examples, extra layers, lib, tests, clang-format, gignore, CMakeLists.txt, LICENSE, and README.md. The repository is licensed under MPL-2.0 and has 4 stars. It is being watched by 1 user and has 0 forks. The repository is associated with the `acts` project. The GitHub interface includes sections for About, Releases, Packages, and Languages.

About
A library for storing interpolable vector fields on co-processors

Releases
Create a new release

Packages
No packages published
Publish your first package

Languages
C++ 90.3%
CMake 6.0%
Cuda 2.0%
Haskell 1.7%

covfie

Build Tests [Succeeded](#) Code Checks [Passed](#) Docs [Passed](#) License [MPL-2.0](#) Issues [0 open](#) Pull Requests [0 open](#)

Commit activity [1 week](#) Contributors [2](#) Last commit [Aug 2023](#)

covfie (pronounced coffee) is a co-processor vector field library. covfie consists of two main components; the first is the header-only C++ library, which can be used by scientific applications using CUDA or other programming platforms. The second is a set of benchmarks which can be used to quantify the computational performance of all the different vector field implementations covfie provides. Arguably, the test suite constitutes a third component.