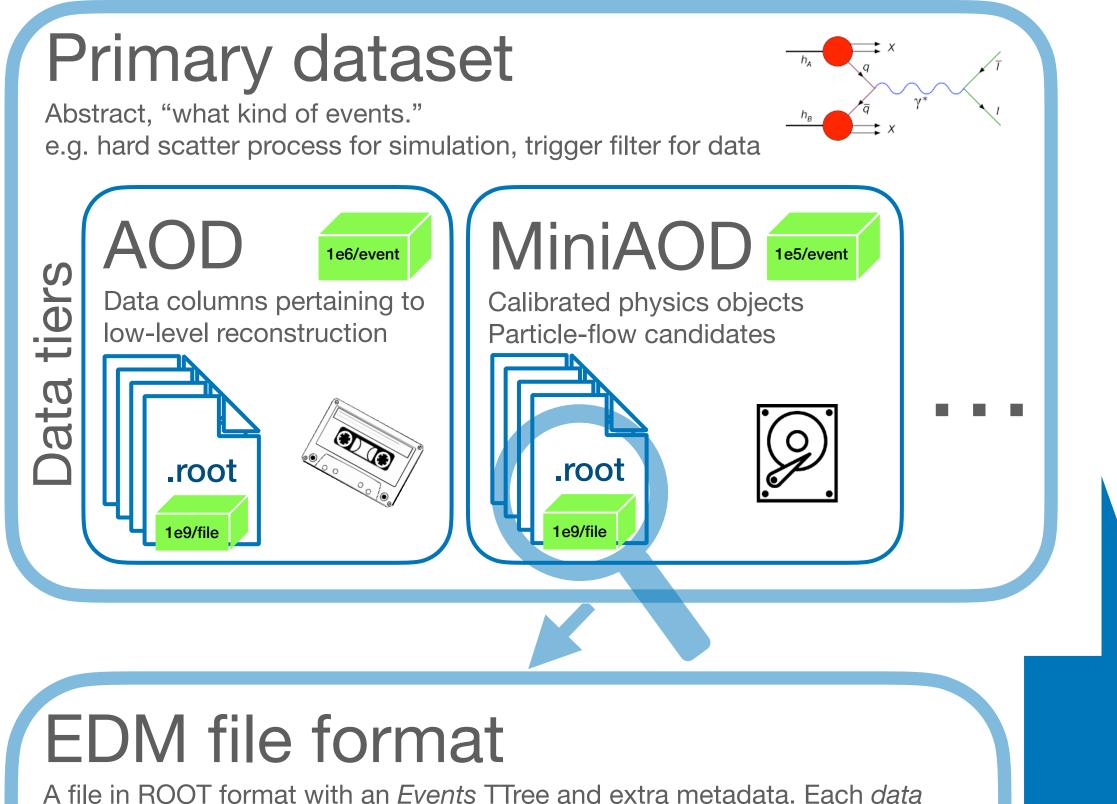


#### **Object Stores for CMS data-**

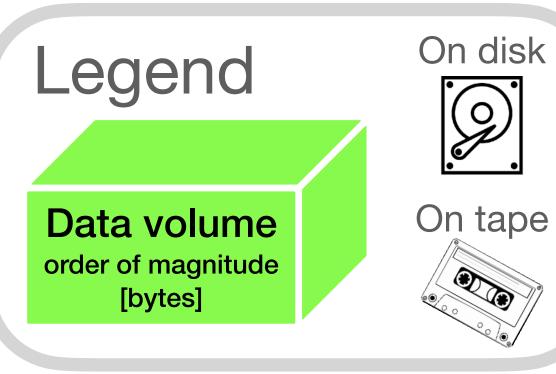
- Object data formats provide new data management capabilities
- Compared to current tier-based EDM file model
- Reduce disk storage requirements for re-processing, obviate the need to define data tiers
- In a prototype framework accessing a Ceph S3 service, I/O performance is excellent
- On-disk data and metadata volume is as expected
- To fully utilize, more software development will be needed
- New data management service requirement: column tracking
- Full data format requires provenance and auxiliary data handling



## ACAT 2022

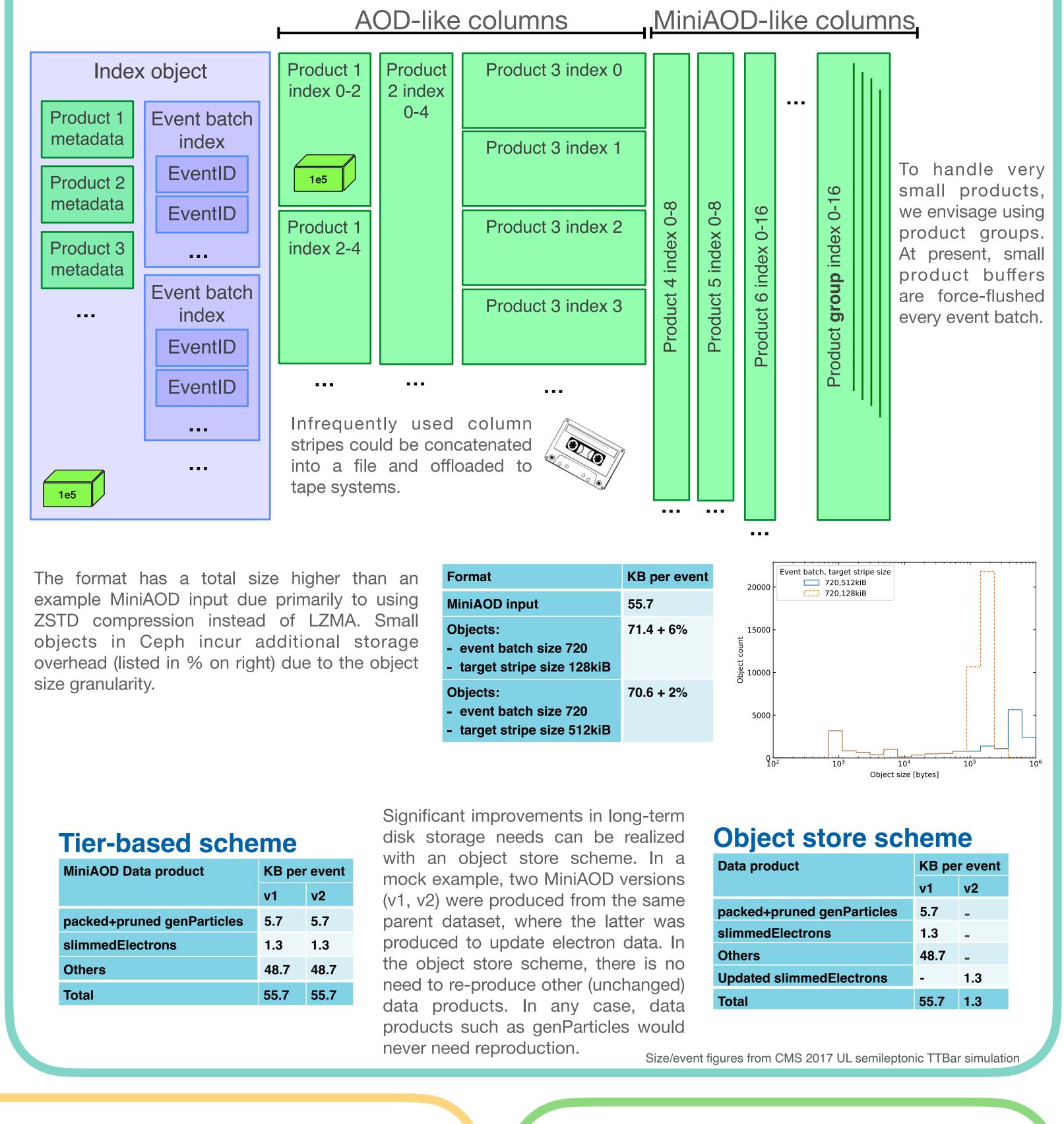
Nick Smith, Bo Jayatilaka, David Mason, Oliver Gutsche, Alison Peisker, Robert Illingworth, Chris Jones (FNAL)

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### Object data format

One index object holds metadata for an entire primary dataset. For each *data product*, or column of data, a *stripe* of events is written as an object in an S3 bucket. Each event data product is serialized with standard ROOT IO. The stripe size is chosen on first write, once the compressed output buffer reaches a target size (100k-1MB) and the number of events evenly divides the event batch size. The index object may eventually be replaced by a database, to more easily add and remove products. The metadata volume grows as (N products) + (M events) despite the N\*M growth of the number of stripes.



*product* is a TBranch in the TTree. Some data product branch elements are further split into smaller columns for improved compression, but a product is accessed as one unit within the CMS offline software framework. TBranch objects reference several TBaskets, which contain serialized data products for a range of events.

In the diagram to the right, each TBasket accessed by a CMS workflow reading MiniAOD is represented as a rectangle, where the height 3 8 is the number of events and  $\frac{1}{2}$  100 width is proportional to the <sup>1/20</sup> compressed bytes. The top 140 6 largest MiniAOD products 160 represent half of the file size. 180-Unfilled rectangles represent baskets that were not accessed.

20.0

17.5

<u></u> 15.0 ·

0 12.5 ·

- 10.0

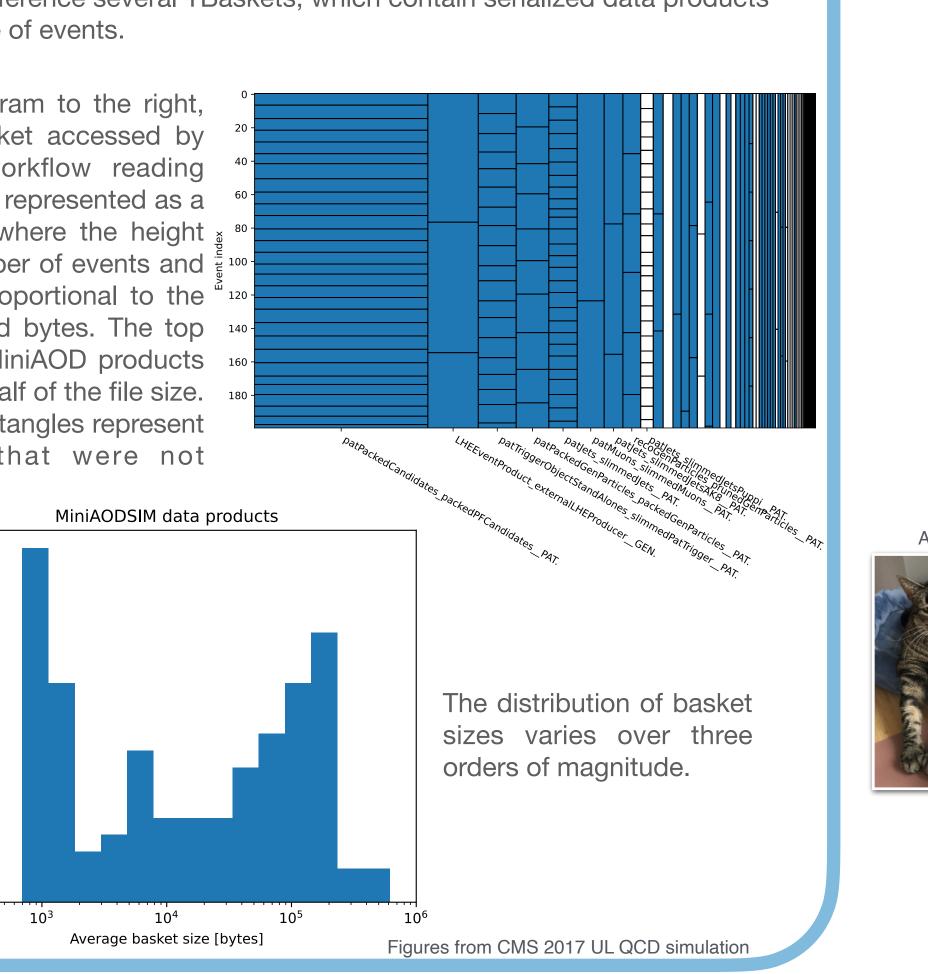
<sup>L</sup>n<sub>N</sub> 7.5 -

5.0

2.5 -

0.0

10<sup>2</sup>



# S3 I/O software prototype

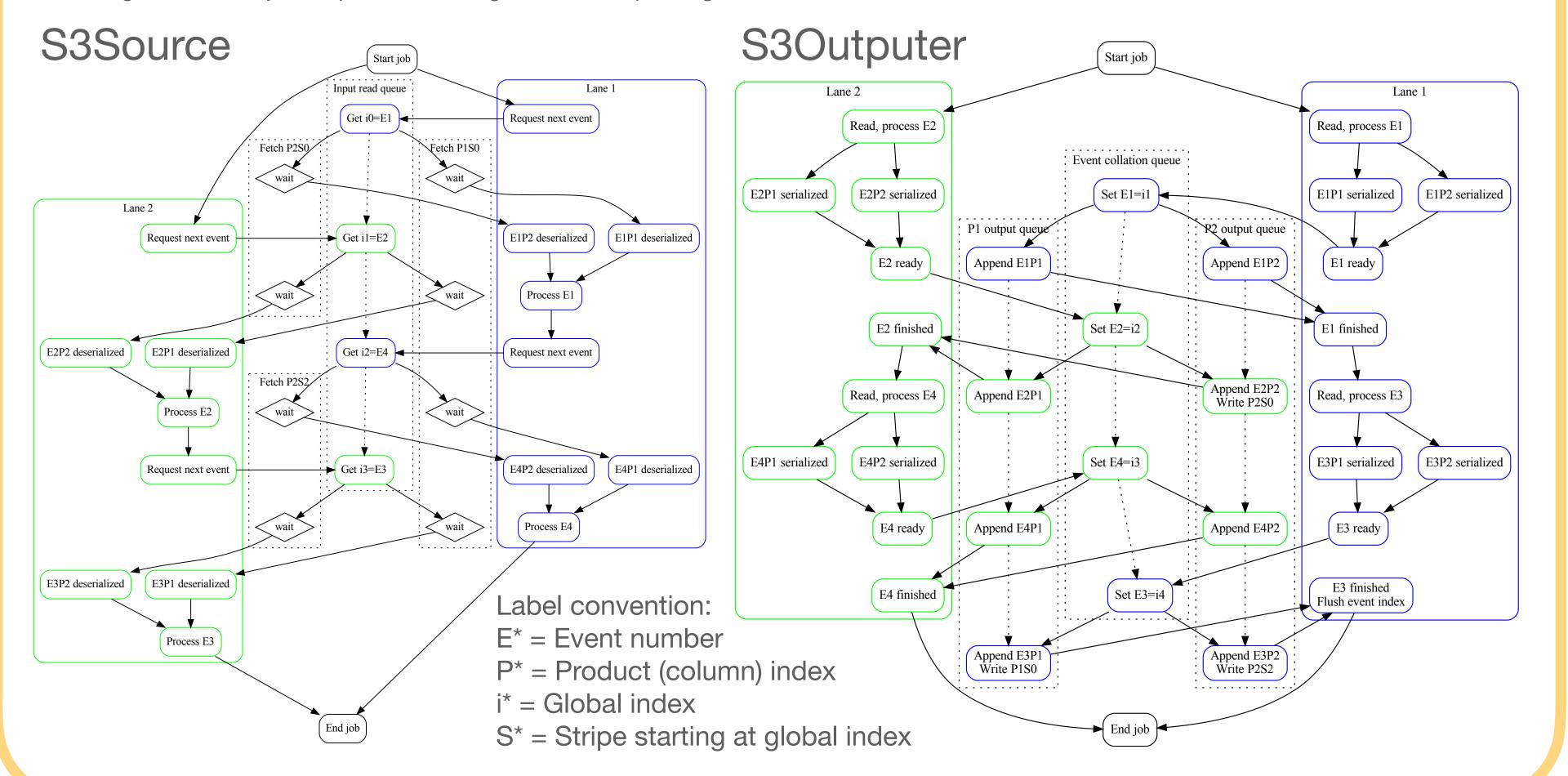
The HEP-CCE root\_serialization project provides a C++ framework for performance experiments with various I/O packages from

A pilot cluster has been assembled to gain experience in managing a Ceph installation. Nine servers provide 2 PB of HDD, and two servers provide 20 TB of NVMe for metadata. All machines have 10 to 100Gbps networking. The cluster supports filesystem and S3 object access mechanisms. An xrootd server exposes the filesystem to hosts within the Fermilab network.

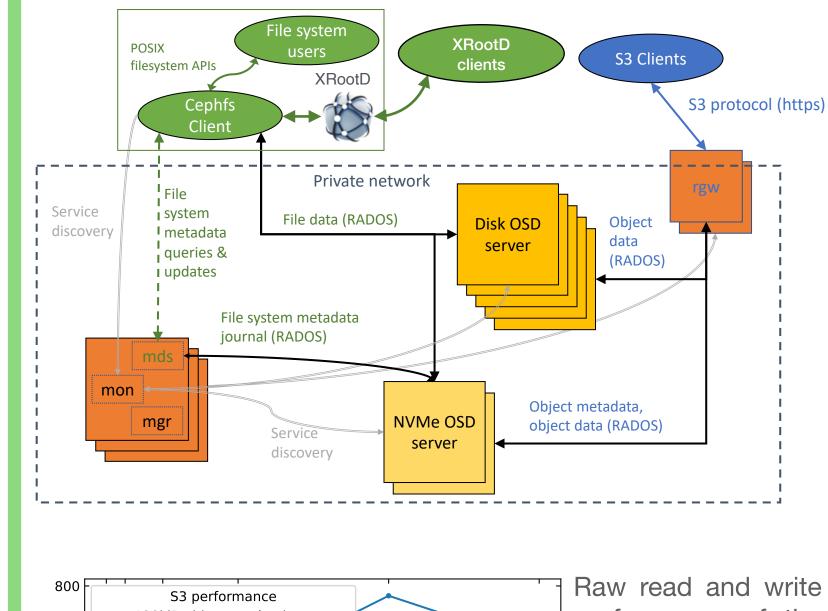
Test cluster

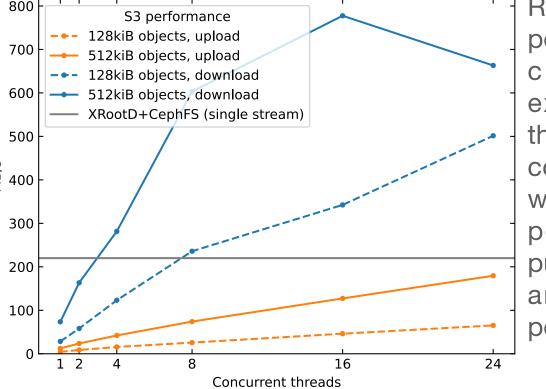
within a multi-threaded program. The program mimics behaviors common for HEP data processing frameworks. Within this framework, the S3Source and S3Outputer modules have been developed to read from and write to S3 buckets, respectively. This allows to explore the performance and parallelization behavior of writing to an Ceph S3 service in comparison to local files with ROOT or other formats.

The S3 protocol is implemented with libs3. Requests are run asynchronously in a separate thread from the Intel Thread Building Blocks (TBB) thread pool that is used for all other tasks. Network errors are handled with an exponential backoff retry mechanism. The task graphs below illustrate module behavior for a configuration with two lanes, effectively TBB task groups (blue and green nodes.) The same number of lanes, threads, and task groups is used in all tests. In this example, product 1 has stripes written every 4 events, while product two has stripes written every two events. Tasks in queues are run sequentially, with dashed arrows indicating the order. Object stripe read events gather a set of pending tasks that are released once the data has been received.







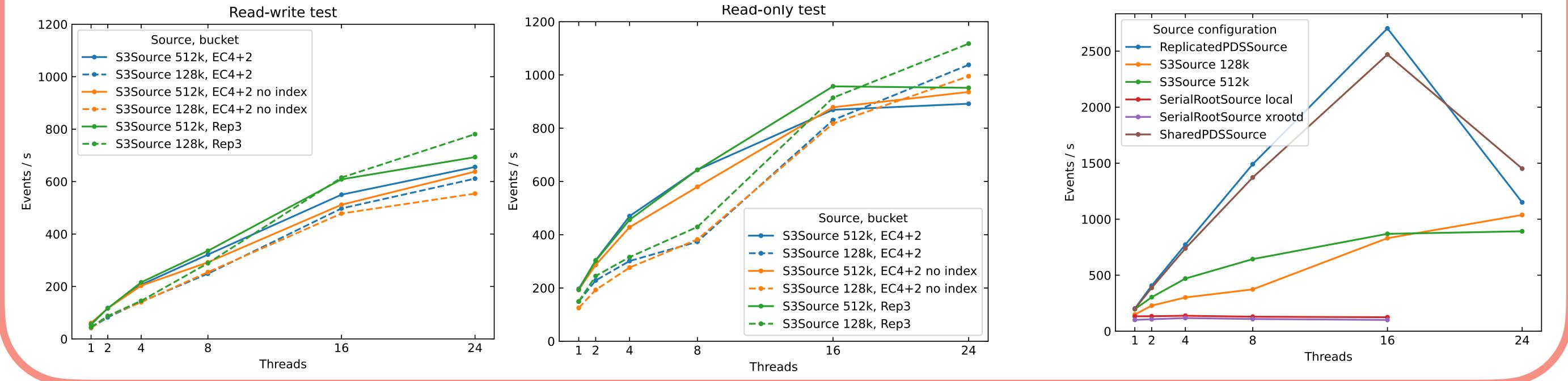


performance of the cluster is within expectation given the current hardware configuration. Here we are testing the performance of a pure-I/O workload to an erasure-coded pool

#### Performance tests

A set of tests where all data products in the MiniAOD tier are read and written as fast as possible was performed. The executable's thread scaling properties are probed, with the metric being the events processed per second. In the full chain test, events are: read, decompressed, deserialized, serialized, compressed, and written. For the read-only chain, only the first three steps are performed. Tests were run on a 24-core machine with 10Gbps network connection to the Ceph cluster. These tests show good scaling behavior with increased thread count.

The tests are performed for two configurations of event batch size and target stripe size. For each, the source and output modules target one of three S3 buckets with different Ceph pool configurations: an erasure coded configuration with 4 data blocks (4kiB) and 2 parity blocks (EC4+2), the same configuration with the bucket index disabled (about 300b metadata per object stored in 3x replicated NVMe pool), and a triple-replicated pool (Rep3).



Comparison to an input source similar to that used in a CMSSW grid job, where the input is read (either on-site or remotely) via xrootd. The xrootd server has CephFS mounted and is accessing a pool with the same erasure coding setup as the S3 source. In addition, a PDS source (file format with concatenated serialized events) is compared. For this test, data is read and discarded.