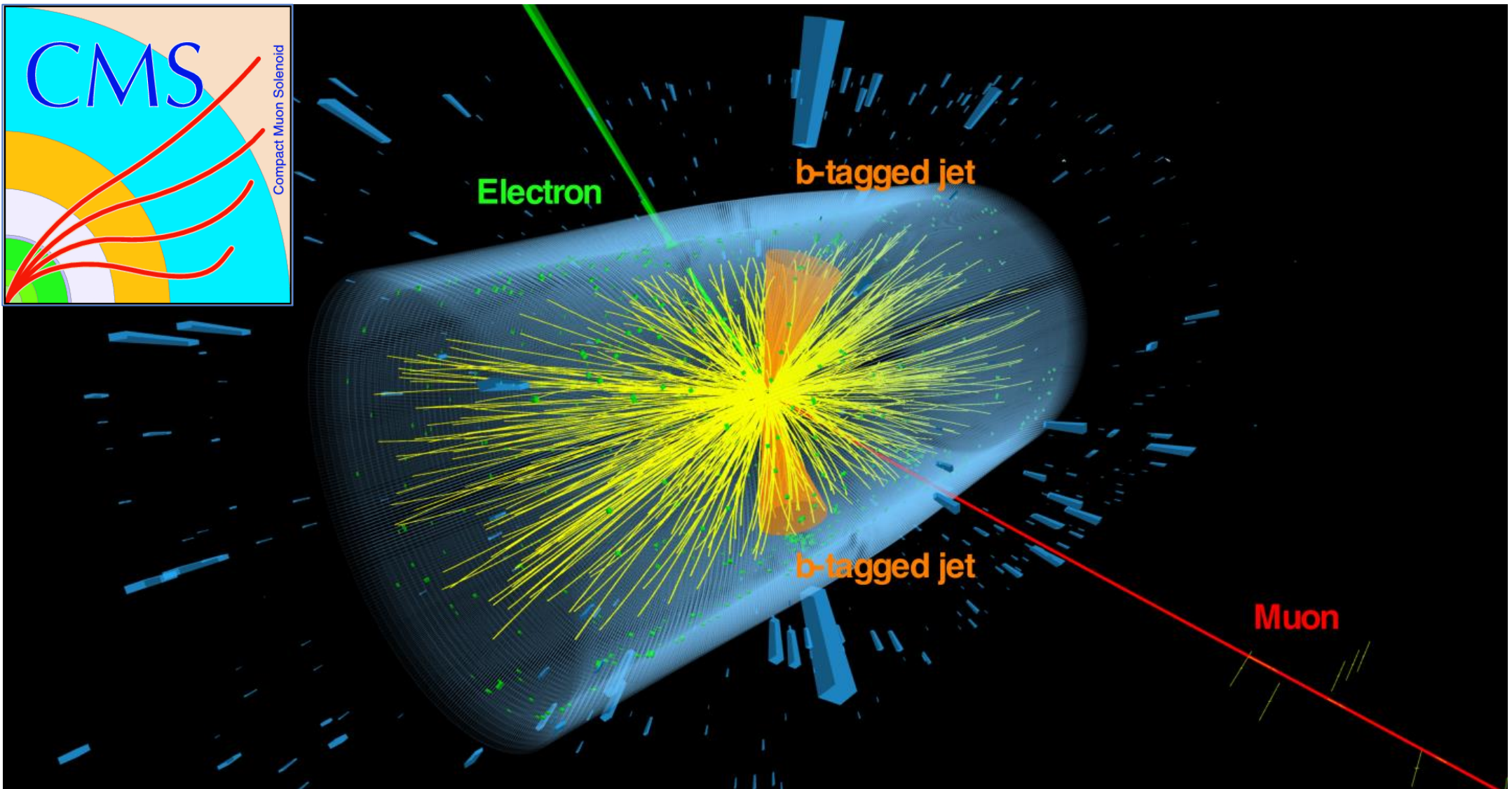


Mass Conditioned & Constrained Normalizing Flows for Particle Cloud Generation.

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LHC & MC Simulations

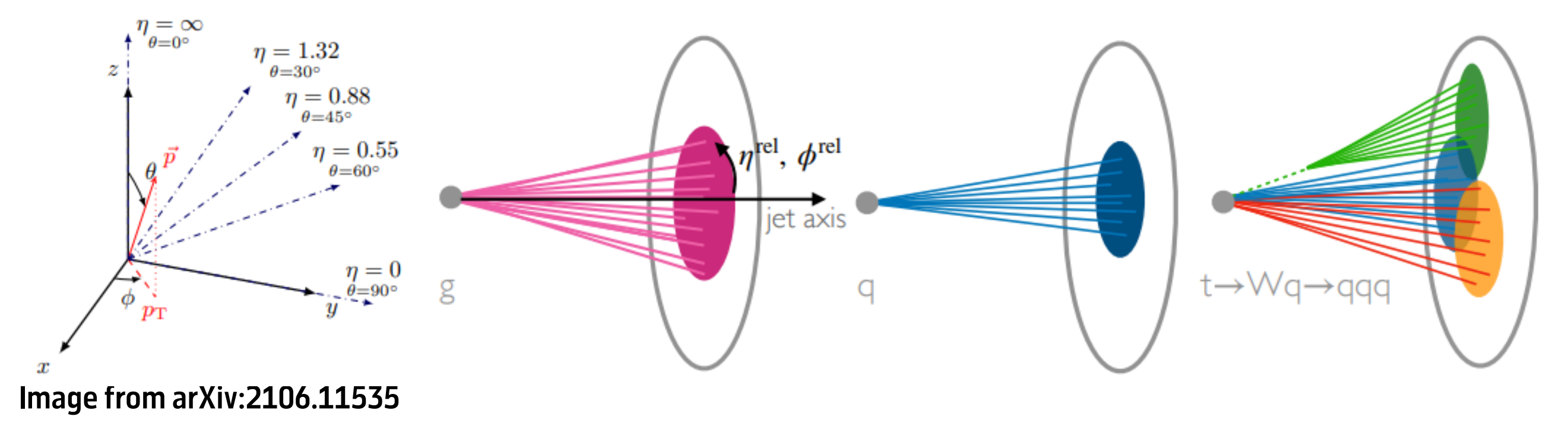
- The Large Hadron collider (LHC) at CERN/Geneva probes fundamental particle physics
- Monte Carlo Simulations needed to test theories
- Uncertainty due to finite MC statistics always relevant for physics analyses
- MC slow ~ 100 s per simulated event \rightarrow previous run ~ 1 billion events were simulated
- Using already $\sim 50\%$ of computing resources
- Future Runs higher Luminosity \rightarrow Even more simulations
- Other ways for simulations needed



Jets

- Jet = narrow cone of particles
- Jets abundant in hadron colliders \rightarrow simulation crucial
- Different mother particles \rightarrow different kinematical properties of constituents
- In this study: gluon, top- and light quark initiated jets
- Jets described by reconstructed momenta of constituents (p_x, p_y, p_z)
- Alternatively more collider friendly variables (η, ϕ, p_T) :
 $p_x = p_T \cos(\phi)$, $p_y = p_T \sin(\phi)$, $p_z = p_T \sinh(\eta)$, $\eta = -\log \frac{\theta}{2}$
- Invariant jet mass, assuming mass of constituents is zero:

$$m^2 = \left(\sum_{part} \sqrt{p_x^2 + p_y^2 + p_z^2} \right)^2 - \left(\sum_{part} p_x \right)^2 - \left(\sum_{part} p_y \right)^2 - \left(\sum_{part} p_z \right)^2$$



Goal

Learn $p_X(x)$ to generate synthetic data

Input/Output Data

- Jets of up to 30 particles (Kansal et al., arXiv/2106.11535)
- Variables relative to jet axis $\rightarrow (\vec{\eta}^{rel}, \vec{\phi}^{rel}, \vec{p}_T^{rel}) = x \in X$
- Each particle tuple $(\eta^{rel}, \phi^{rel}, p_T^{rel}) \rightarrow$ up to 90 features
- Events with fewer particles zero-padded
- Dataset from zenodo.org/record/6302454

ML Challenges

- Particle clouds of variable sizes
- Global features (e.g. jet mass, total transverse momentum,..) crucial for analyses
- No straight-forward performance measure for generated data

Normalizing Flows

- Change of variables for probability distributions:

$$p_X(\vec{x}) = p_Z=f(X)(\vec{z}) \left| \det \frac{\partial \vec{f}}{\partial \vec{x}} \right|$$

\rightarrow Makes Maximum Likelihood training (nLL) viable:

$$L_{nll}(\theta) = -\sum_X \log(p_X(\vec{x})) \stackrel{\text{unknown } \vec{z}=f_\theta(\vec{x})}{=} -\sum_X \log(p_Z(\vec{z})) + \log \left| \det \frac{\partial \vec{f}}{\partial \vec{x}} \right|$$

- p_Z closed form (e.g. Gaussian), f invertible
- Coupling layers candidates for invertible transformations
- Chaining together multiple coupling layers \rightarrow Enhanced expressivity
- Generating: Sample known p_Z and apply inverse transformations
- Add noise $\sim \mathcal{O}(10^{-7})$ to zero-padded particles
- nflows implementation used - github.com/bayesiains/nflows

Conditioning

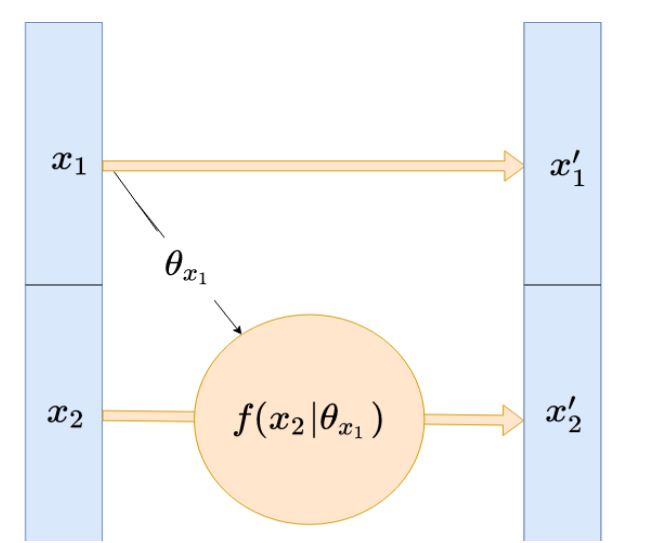
- Additional inputs to neural networks in coupling layers \rightarrow Needed during sampling
- Here: number of particles n , invariant mass m
- Conditioning enhances expressivity of flows and modelling of global features

Coupling Layers

- Coupling layer split features in two sets \rightarrow Parameters for transformation of one set from other
- Simple affine coupling layer:

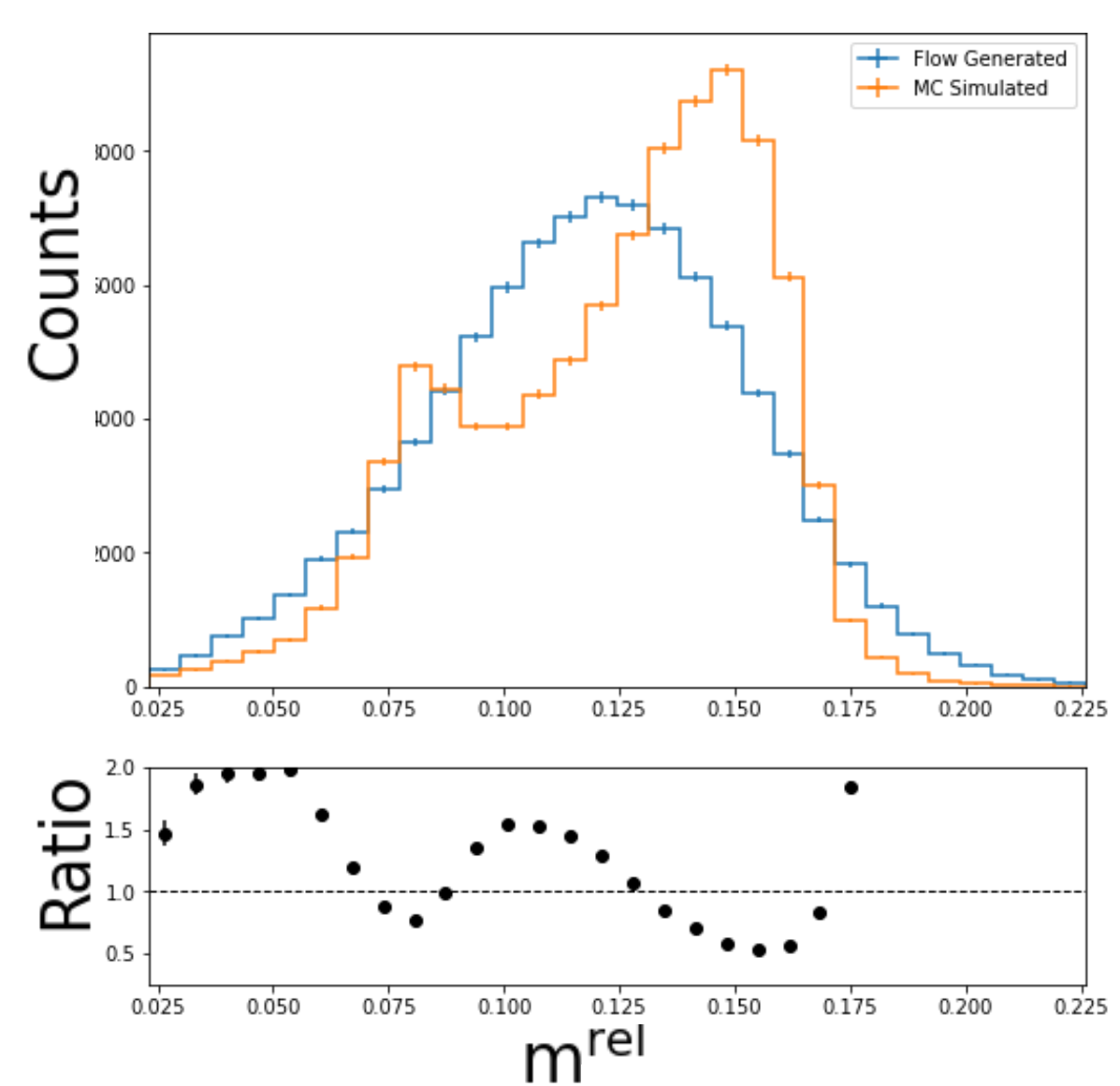
$$f(\vec{x}) = \begin{cases} \vec{x}'_1 = \vec{x}_1 \\ \vec{x}'_2 = \vec{a}(\vec{x}_1) \odot \vec{x}_2 + \vec{b}(\vec{x}_1) \end{cases}$$

$$\Rightarrow f^{-1}(\vec{x}') = \begin{cases} \vec{x}_1 = \vec{x}'_1 \\ \vec{x}_2 = \frac{\vec{x}'_2 - \vec{b}(\vec{x}'_1)}{\vec{a}(\vec{x}'_1)} \end{cases}$$



- Parameters a, b output of deep residual network
- Network parameters optimized by gradient descent on nLL
- Features permuted after each coupling layer
- In this study more complicated coupling layers \rightarrow Rational Quadratic Splines

Vanilla Normalizing Flows



Global feature not modelled correctly

Mass Constraint

- Enforce correct mass distribution by adding penalty term

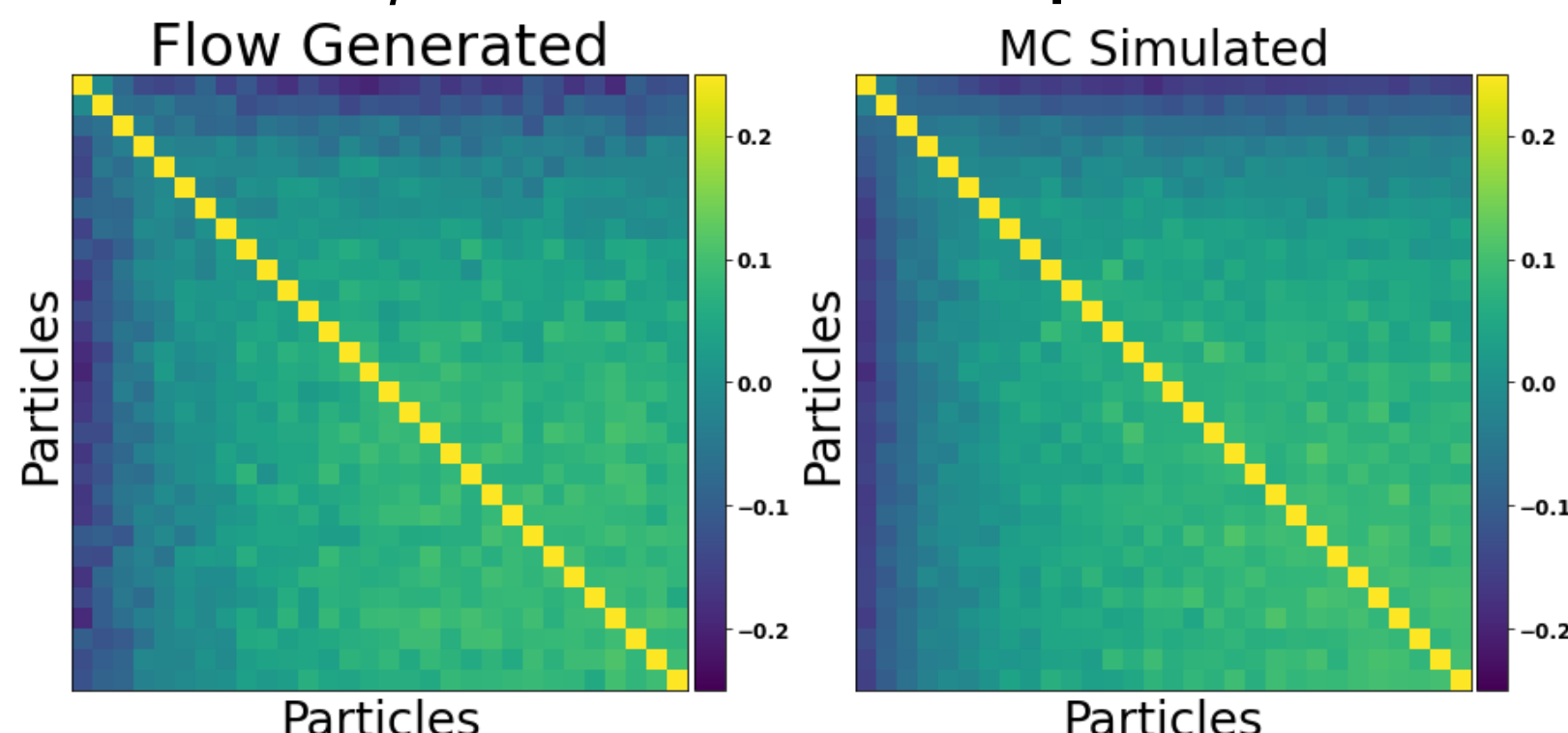
$$L_{mass} = (m_{gen} - m_{cond})^2$$

- Loss from latent space and input space:

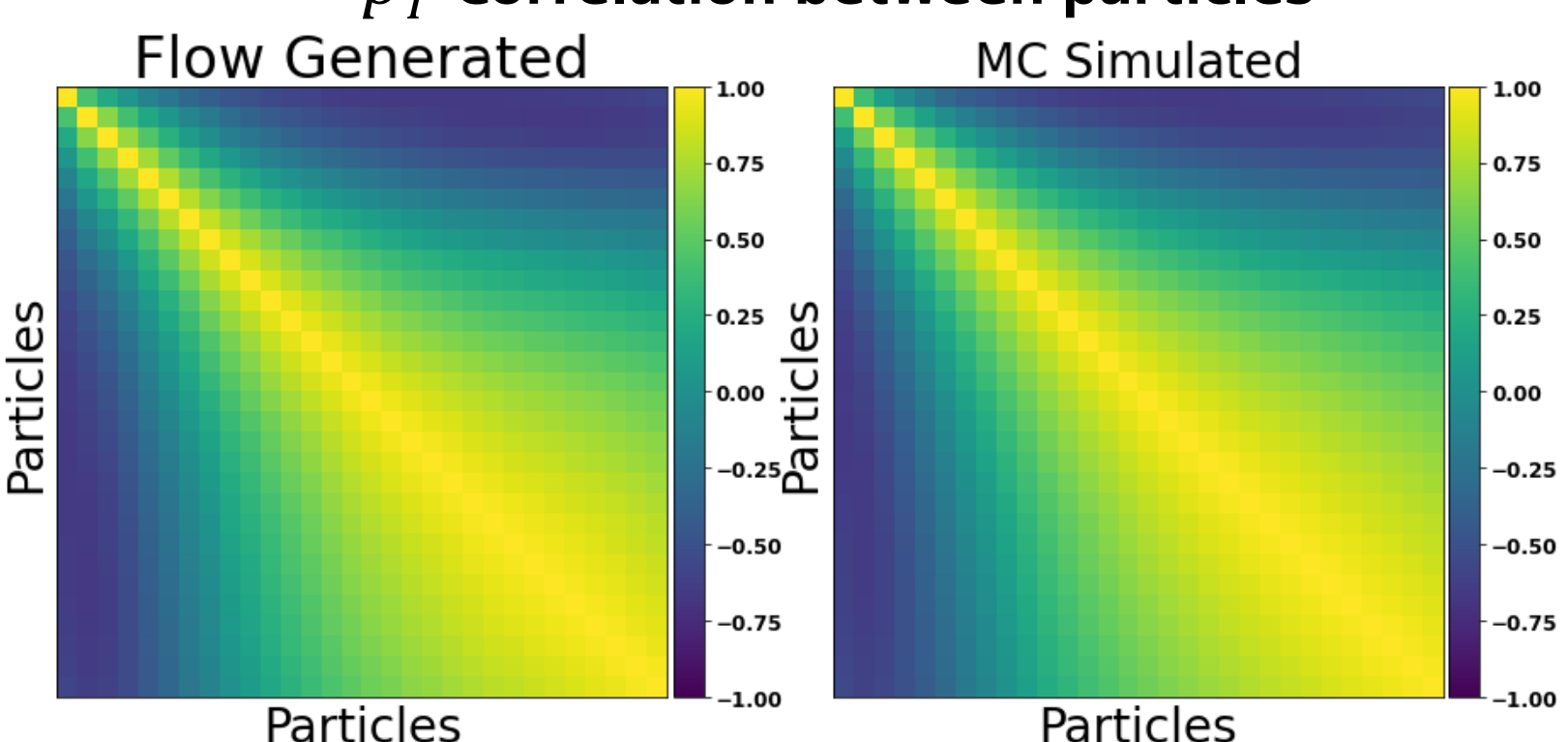
$$L_{Tot} = L_{nll}^{latent\ space} + \lambda \cdot L_{mass}^{input\ space}$$

Results

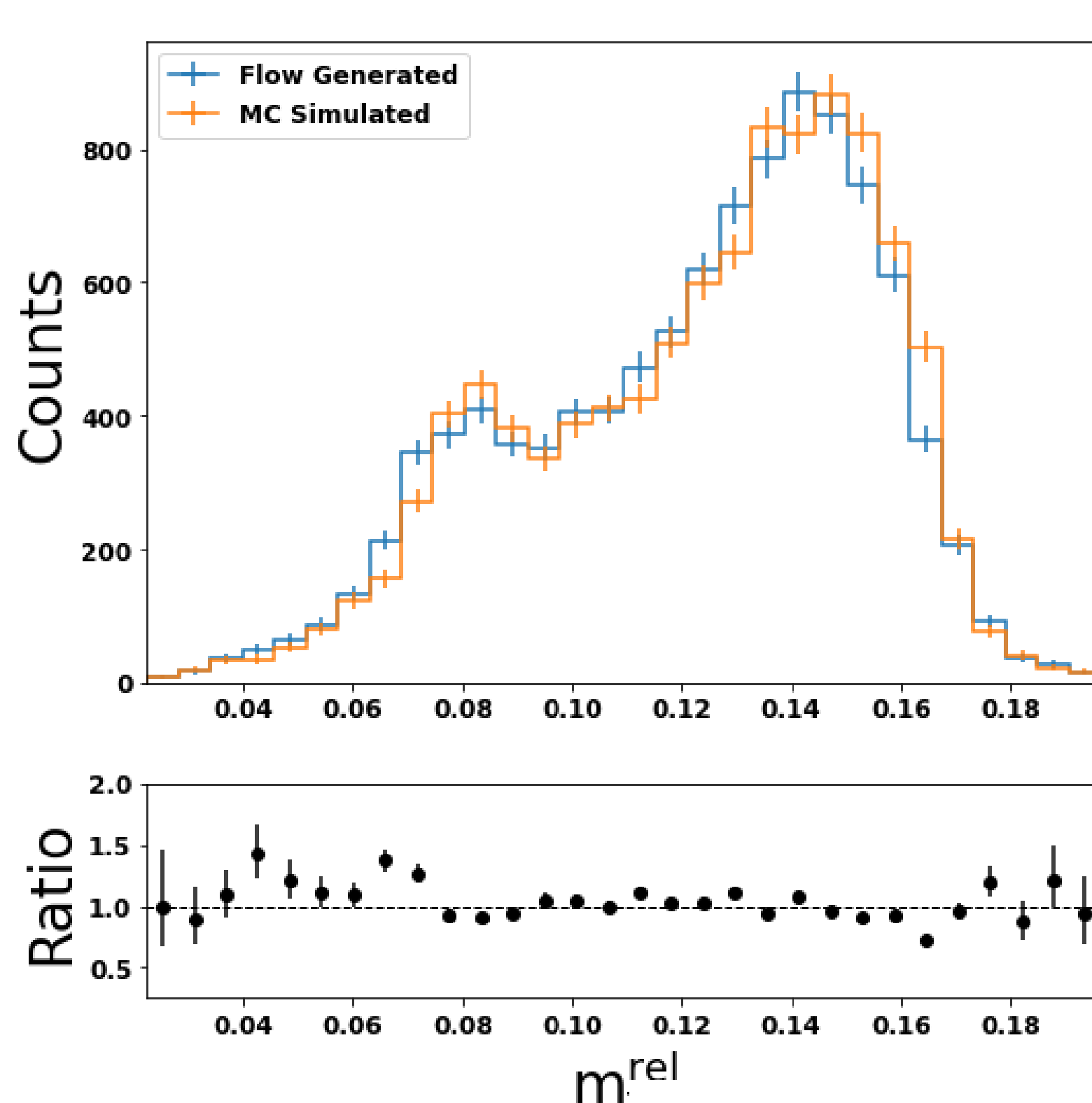
ϕ Correlation between particles



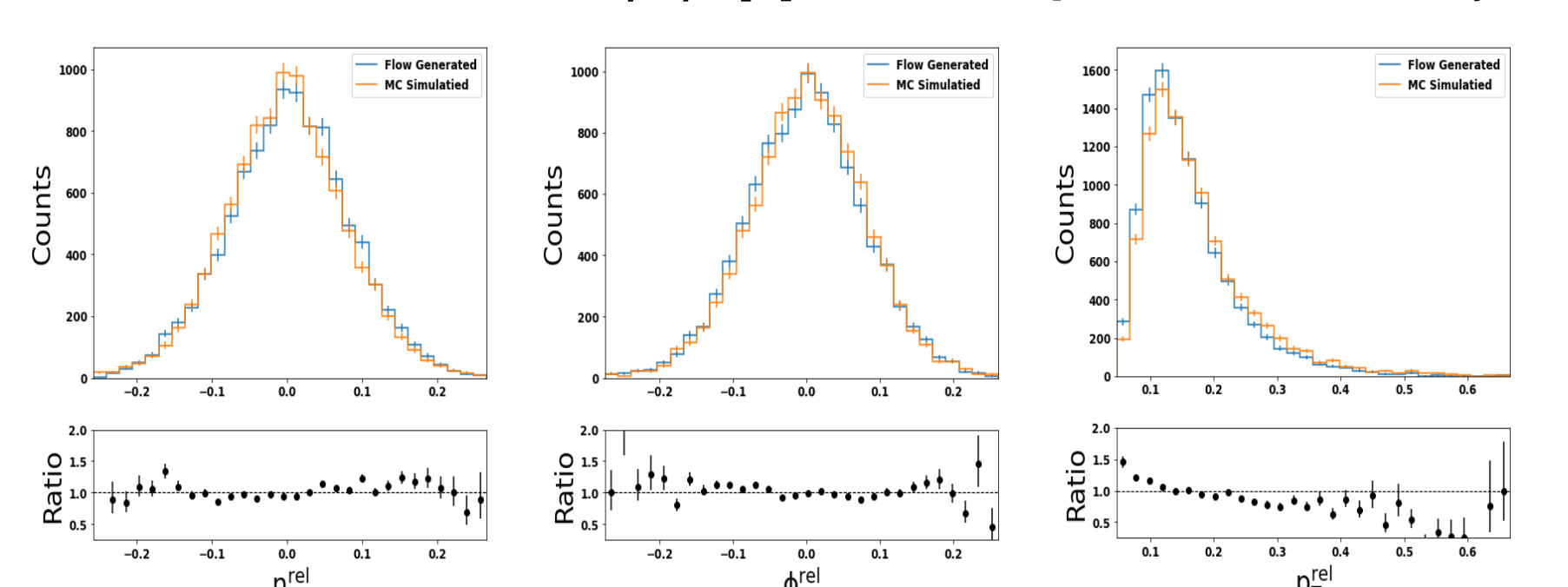
p_T Correlation between particles



Jet Mass Distribution modelled correctly



Inclusive Distributions (η, ϕ, p_T) over all particles and all jets



(η, ϕ, p_T) Distribution of particle with highest p_T

