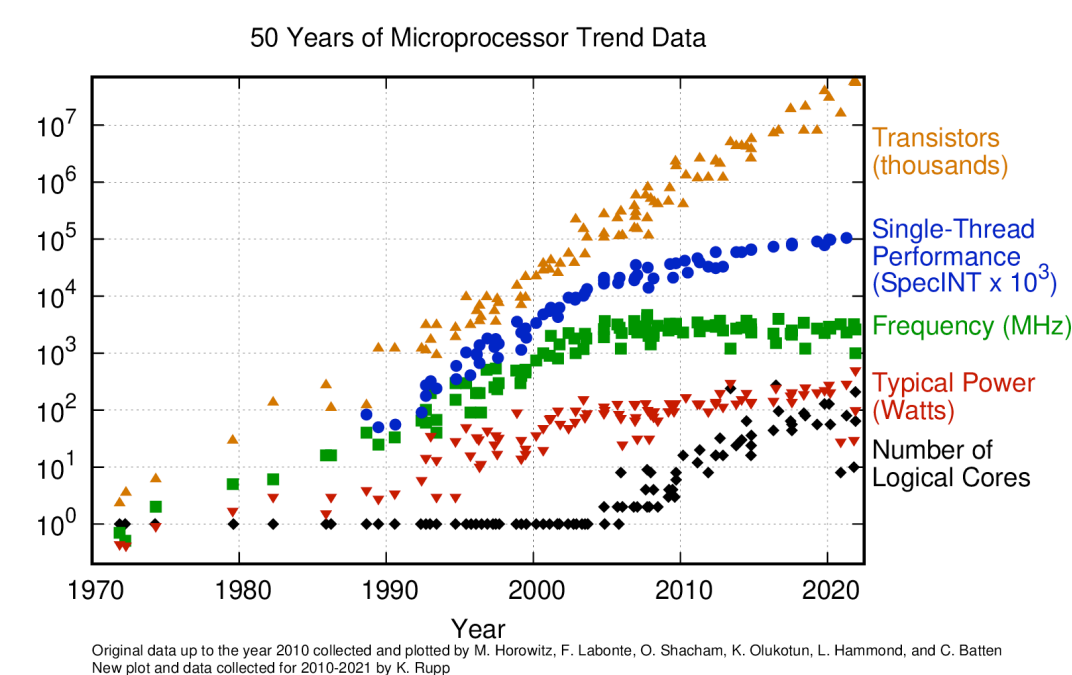


Speeding up the CMS track reconstruction with a parallelized and vectorized Kalman-filter-based algorithm during the LHC Run 3

Emmanouil (Manos) Vourliotis¹ et al.* on behalf of the CMS Collaboration

Motivation for Track Reconstruction Speed-up

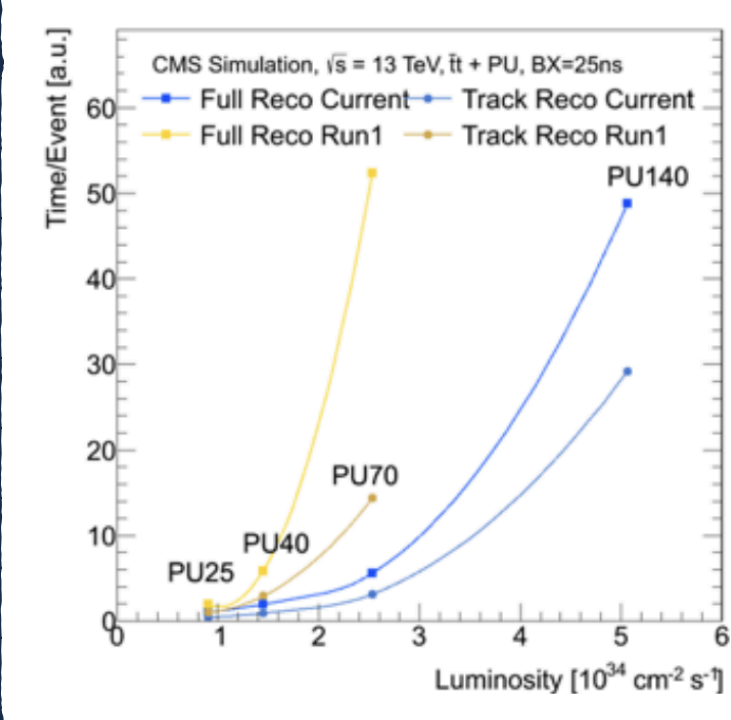
- Exponential growth of CPU time/event at the LHC ⇒ Track reconstruction ~1/2 of event reconstruction.
- Plateau of single thread performance.
- Solution: **Parallelized & vectorized** tracking algorithms.



- mkFit** Matriplex Kalman Fitter tracking algorithm^[1]: Application of this paradigm shift → Goals:

- **Same physics** performance.
- Significant **speed-up**.

Iteration	Seeding	Target track
Initial	pixel quadruplets	prompt, high p _T
LowPQuad	pixel quadruplets	prompt, low p _T
HighPTripel	pixel triplets	prompt, high p _T , recovery
LowPTripel	pixel triplets	prompt, low p _T , recovery
DetachedQuad	pixel quadruplets	displaced-
DetachedTriplet	pixel triplets	displaced-recovery
MixedTriplet	pixel+strip triplets	displaced-
PixelLess	inner strip triplets	displaced+
TopTec	outer strip triplets	displaced+
JetCore	pixel pairs in jets	high-p _T , jets
Muon inside-out	muon-tagged tracks	muon
Muon outside-in	standalone muon	muon



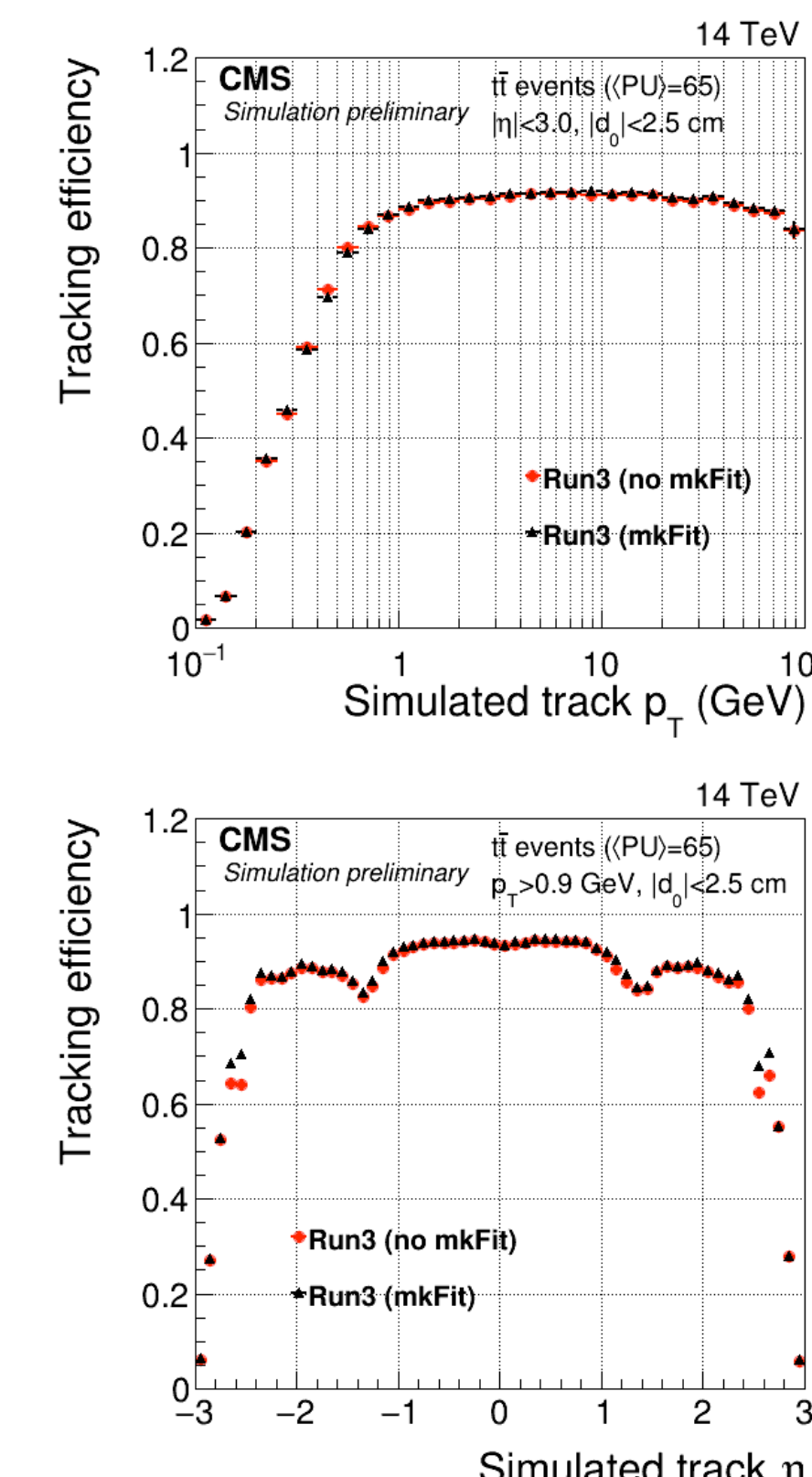
- mkFit in development for 5+ years → Now integrated in central CMS offline track building.

Physics Performance^[3]

- mkFit used for almost 90% of all reconstructed signal tracks with p_T > 0.5 GeV.

When using mkFit:

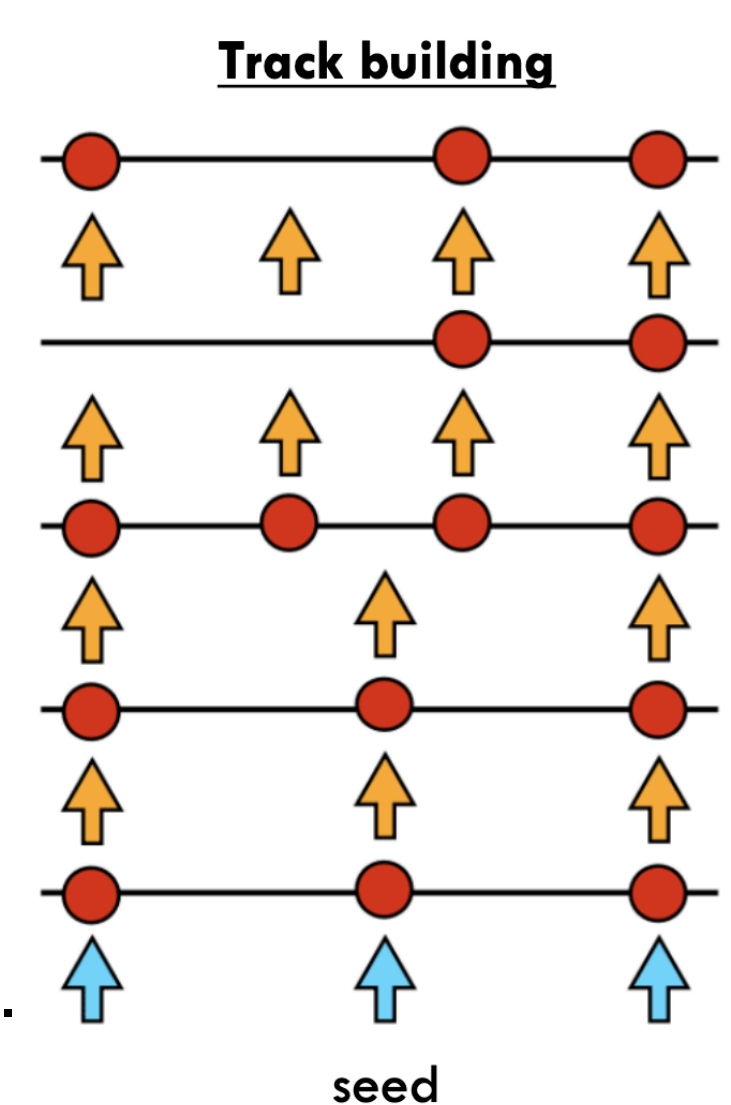
- Tracking **efficiency comparable**:
 - Small gains in endcap (2.4 < |η| < 2.8).
- Tracking **fake rate better** overall:
 - Fake rate reduction with increasing |η|.
 - Better scaling with PU.
- Tracking **duplicate rate slightly increased** overall:
 - Due to parallel nature of the algorithm.
 - Mitigated with dedicated duplicate removal.
 - Performance tuned in p_T and η.



Algorithm Logic and Challenges

- CMS tracking^[2] → Combinatorial Kalman Filter:

- Start from track seeds.
- Iteratively accumulate compatible hits to build tracks.
- ⇒ The most time consuming part of track reconstruction.

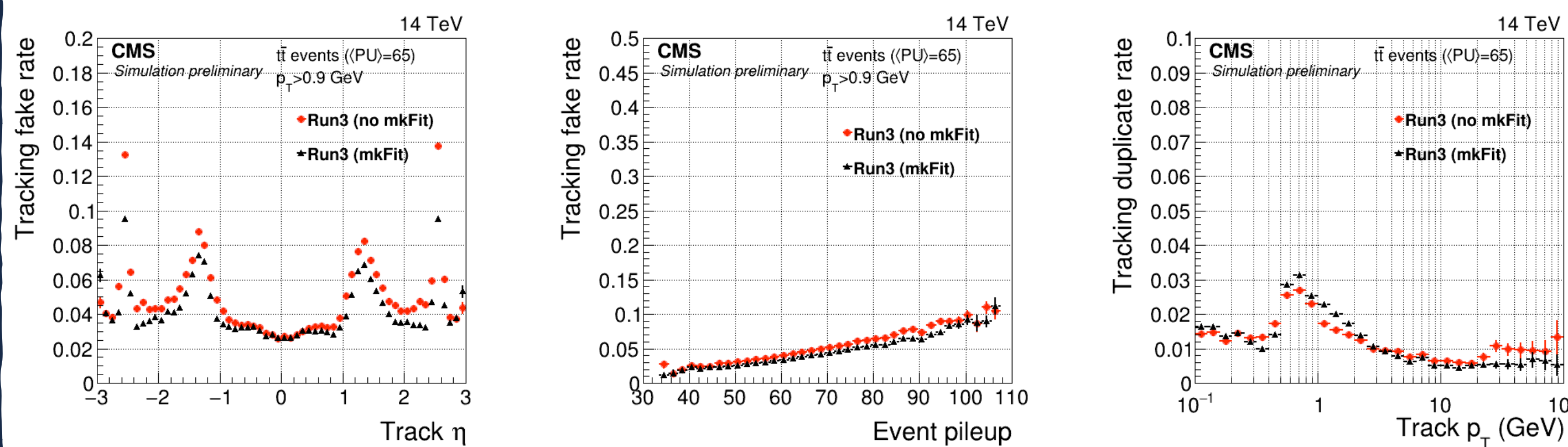


- Improve by:

- **Vectorization**: Same Instruction, Multiple Data (SIMD).
- **Multithreading**: Different Instructions, Different Data.

- Requirements:

- **Minimization of algorithm branching** for vector operations.
- **Load balancing** among threads.
- **Minimization** of memory usage and **optimisation of memory** accesses.



Timing Performance^[3]

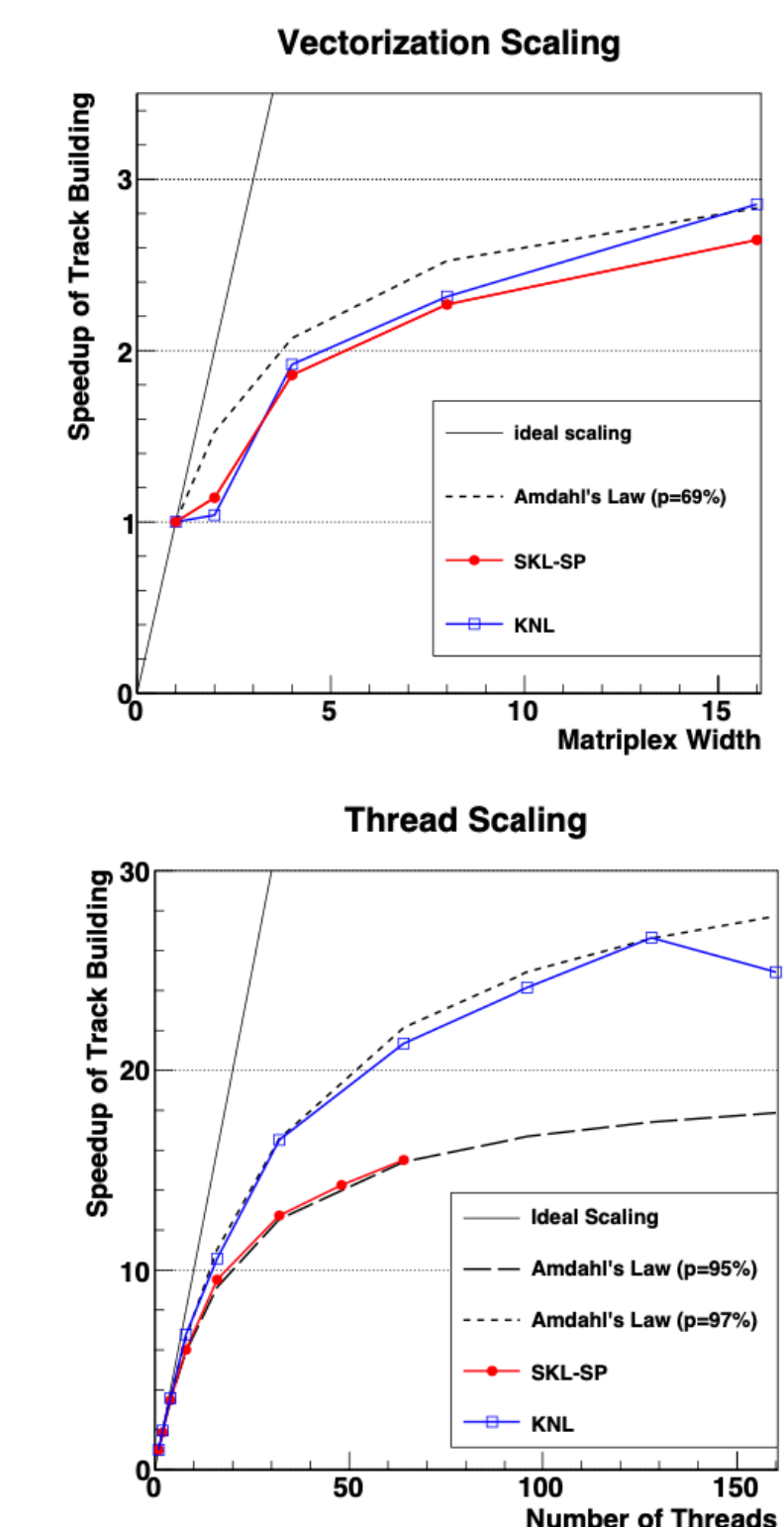
- mkFit vectorization & multithreading performance → According to Amdahl's Law:

- ~70% of operations effectively **vectorized**.
- >95% of code effectively **parallelized**.

When using mkFit:

- **Individual mkFit** iterations: Up to **6.7x** building time reduction.
- **Sum of mkFit** iterations: ~**3.5x** building time reduction.
- **Sum of all iterations**: ~**1.7x** building time reduction ⇒ **25% reduction of total tracking time**.

- Event throughput increase by 10-15%** in Run3.



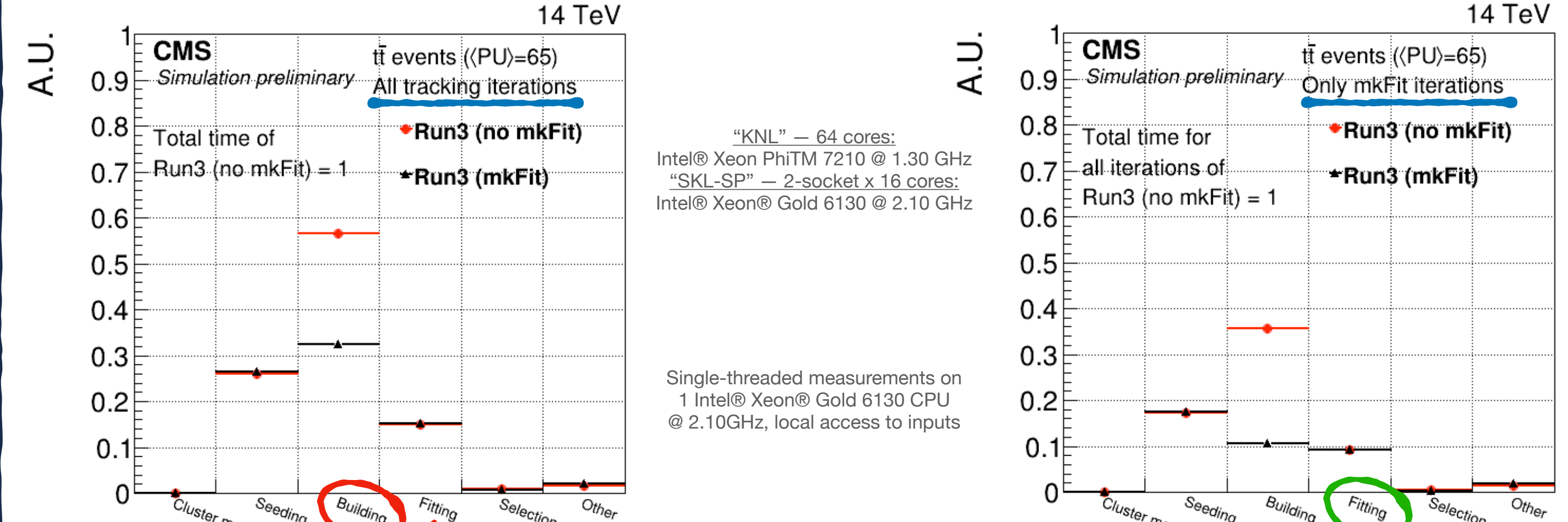
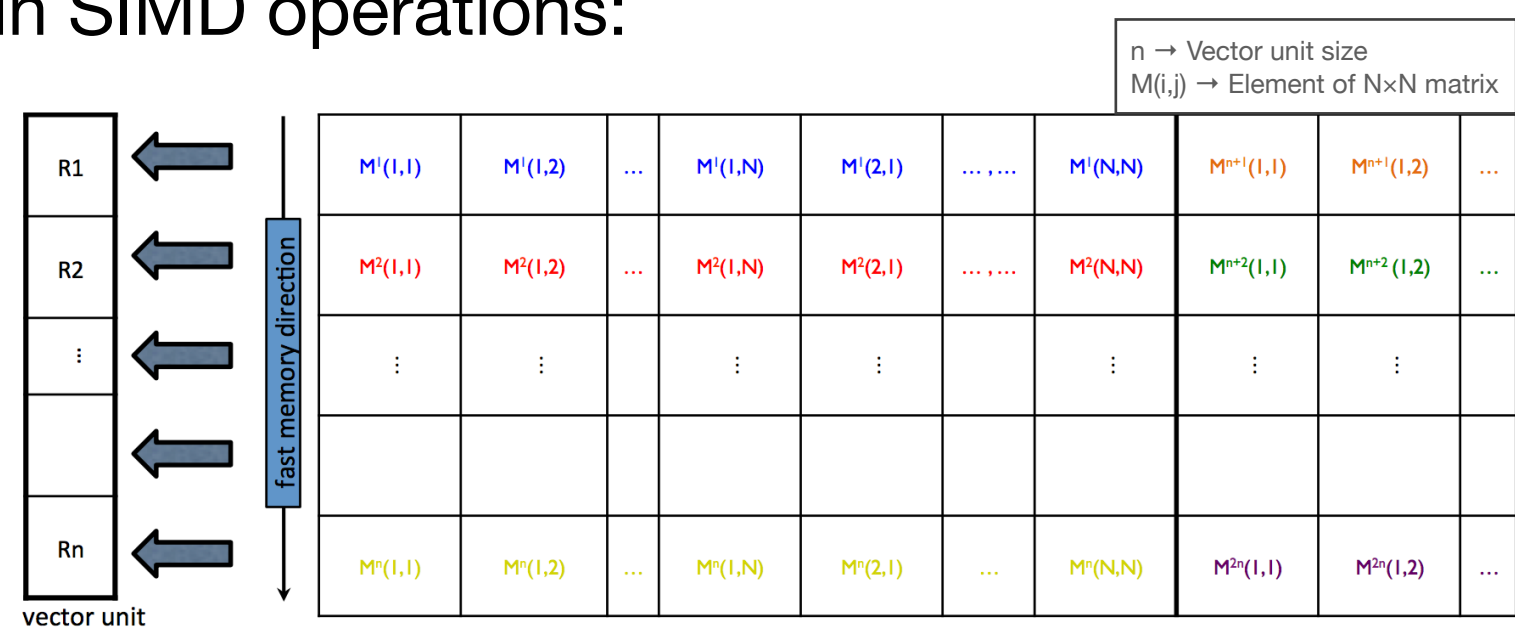
Parallelisation Strategy

- Multiple levels of **multithread parallelization**:
 - ↳ Loop over different **events**.
 - ↳ Loop over different **η-regions**.
 - ↳ Loop over z-/r- and φ-sorted groups of seeds.

- Exploit **Intel TBB** for task scheduling ⇒ Dynamic task stealing to balance workloads.

- Vectorisation of track candidate processing → Custom matrix library, **MATRIPLEX** ⇒ Optimized for vector loading in SIMD operations:

- **"Matrix-major"** representation designed to fill a vector unit with **n** matrices in sync.



Simplified Detector Description

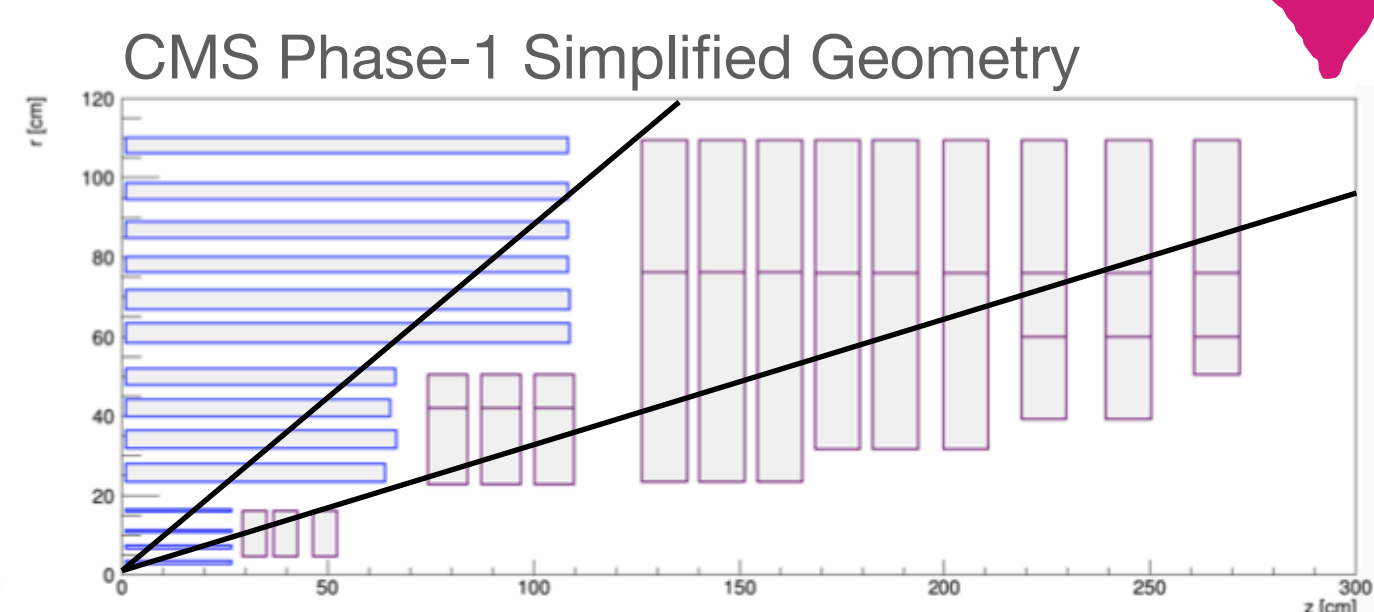
- Use highly configurable **tracker layer** data structures ⇒ Detector details in 2D (r/z, phi) bins instead of individual modules:

- **Reduction of memory** usage.
- Instruction **overhead minimization**.

- 2-step propagation**:

- Track → Average r or z ⇒ Create compatibility window.
- Track → Each hit in window ⇒ Selection based on χ².

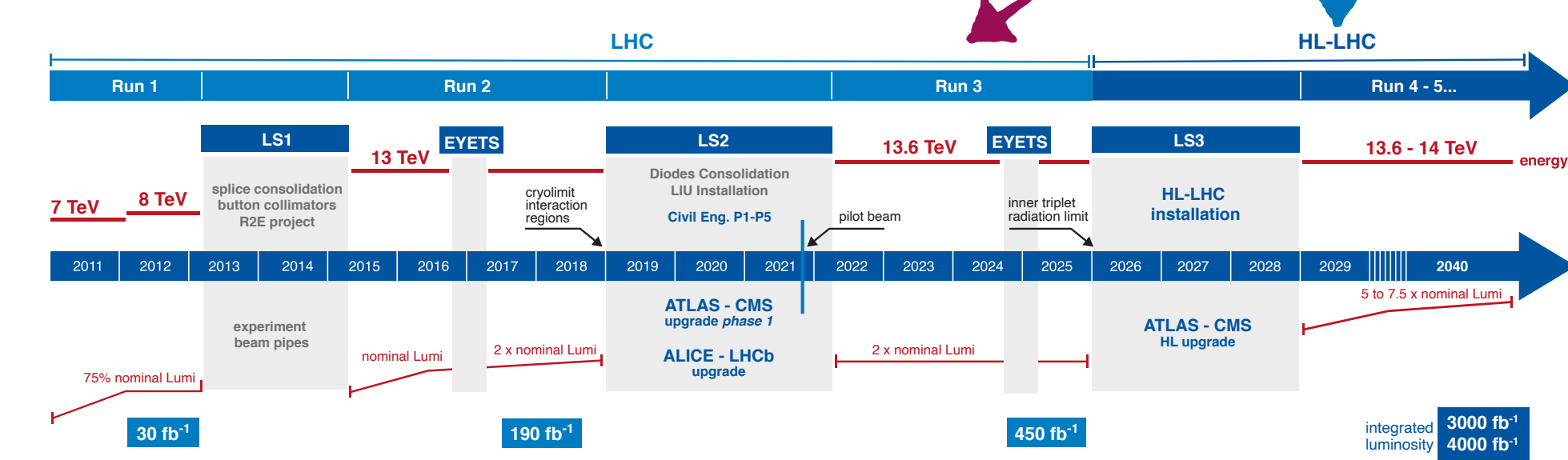
- Multiple scattering & energy loss** effects included.



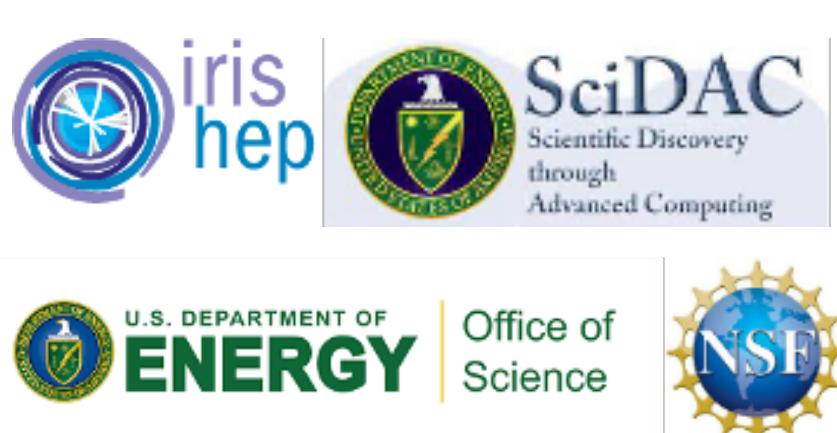
Outlook

- Plans for mkFit paradigm extension to more applications:

- Extend to **more track building iterations** ⇒ Further speed-up.
- Apply to **track fitting** → Its timing now comparable to track building.
- Build tracks for **High Level Trigger**, already during Run3 → Global SiStrip RAW data unpacking needed, can now be on GPU.
- Modify for **Phase-2 geometry and configuration**
 - Optimization and tuning.
 - Synergies with other algorithms.



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[1] S. Lantz et al., "Speeding up particle track reconstruction using a parallel Kalman filter algorithm", arXiv:2006.00071, DOI:10.1088/1748-0221/15/09/P09030, JINST 15 (2020) 09, P09030
 [2] CMS Collaboration, "Description and performance of track and primary-vertex reconstruction with the CMS tracker", arXiv:1405.6569, DOI:10.1088/1748-0221/9/10/P10009, JINST 9 (2014) 10, P10009
 [3] CMS Collaboration, "Performance of Run 3 track reconstruction with the mkFit algorithm", CMS-DP-2022/018