

Performance study of the CLUE algorithm with the alpaka library

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High Luminosity LHC



Discovering new physics and performing more accurate measurements due to the improved sensitivity level...







The CMS Phase-2 challenge









The software reconstruction challenge

Software reconstruction: digital signals in each detector must be processed to provide information about particles produced in the proton-proton collisions and successive decays and interaction with the absorber material.

- In the PU200 scenario, such a task becomes much harder
 - > Massive amount of computing resources required
 - Advent of heterogeneous computing!







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The heterogeneous computing scenario

Modern computing farms and data centers rely on *heterogeneous architectures*

- CPU
- GPUs → hardware accelerators
- > HEP approach: offloading part of the reconstruction to GPUs for parallel execution
- ♦ Many vendors → many programming languages → many versions of the same code!!!



Performance portability with alpaka

Performance portability libraries have become an interesting solution

- Write code once
- Compile for different backends
- Execute on target platform
- ≻Not all the technologies provide close-to-native backend performance
- Portable code can be *easily maintained* and support new accelerators

CMS choice for Run 3:



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alsaka



Alpaka

Abstraction Library for Parallel Kernel Acceleration









- Developed and maintained at HZDR (Helmholtz-Zentrum-Dresden-Rossendorf) and CASUS (Center for Advanced Systems Understanding)
- C++ header-only library (currently on C++17)
- Supports a wide range of compilers (g++, clang, ...)
- Several backends supported
 - CPU serial and parallel execution (std::thread or TBB)
 - NVIDIA GPU (CUDA)
 - AMD GPU (HIP/ROCm)
 - Intel GPU and FPGAs (SYCL) under development
- For more information, check Jan Stephan's poster "Performance portability with alpaka" on Thursday







A real application: the CLUE algorithm

CLUstering of Energy (CLUE): fast 2D clustering algorithm developed for the future CMS-HGCAL detector

- Based on energy density
- Builds small clusters (~10 RecHits)
- Fully ported to GPU (CUDA)
- Uses a tiled data structure that fully exploits the detector granularity and allows fast querying of neighbor cells





M. Rovere, Z. Chen, A. Di Pilato, F. Pantaleo, C. Seez, CLUE: A Fast Parallel Clustering Algorithm for High Granularity Calorimeters in High Energy Physics, Frontiers in Big Data, 3, 2020.







CLUE procedure



Step 0: arrange input data in "tiles" (spatial indexing)

- *a.* calculate local energy density
- **b.** find nearest higher and calculate its distance
- *c. find seeds and outliers*
- d. assign cluster indices

Each of these steps can be written as a function (or kernel) and perform the same operation on each point



M. Rovere, Z. Chen, A. Di Pilato, F. Pantaleo, C. Seez, CLUE: A Fast Parallel Clustering Algorithm for High Granularity Calorimeters in High Energy Physics, Frontiers in Big Data, 3, 2020.



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Porting CLUE from CUDA to Alpaka - 1

class CLUEAlgoCUDA {

public:

// constructor

CLUEAlgoCUDA() = delete;

explicit CLUEAlgoCUDA(float const &dc, float const &rhoc, float const &outlierDeltaFactor, cudaStream_t stream)
 : d_points{stream}, dc_{dc}, rhoc_{rhoc}, outlierDeltaFactor_{outlierDeltaFactor}, stream_{stream} {
 init_device();

}

~CLUEAlgoCUDA() = default;

void makeClusters(PointsCloud const &host_pc);

PointsCloudCUDA d_points;

LayerTilesCUDA *hist_; cms::cuda::VecArray<int, maxNSeeds> *seeds_; cms::cuda::VecArray<int, maxNFollowers> *followers_;

private:

float dc_;
float rhoc_;
float outlierDeltaFactor_;
cudaStream_t stream_ = nullptr;
cms::cuda::device::unique_ptr<LayerTilesCUDA[]> d_hist;
cms::cuda::device::unique_ptr<cms::cuda::VecArray<int, maxNSeeds>> d_seeds;
cms::cuda::device::unique_ptr<cms::cuda::VecArray<int, maxNFollowers>[]> d_followers;

// private methods void init_device();

void setup(PointsCloud const &host_pc);

mespace ALPAKA_ACCELERATOR_NAMESPACE {	User-defined	namespace that contain all
class CLUEAlgoAlpaka {	the needed su	mbols (Platform Device
public:		
// constructor	Queue, Buffe	rType)
CLUEAlgoAlpaka() = delete;		
explicit CLUEAlgoAlpaka(float const &	dc,	
float const &	rhoc,	
float const &	outlierDeltaFactor,	
Queue stream,		
uint32_t cons	t &numberOfPoints)	
: d_points{stream, numberOfPoints;	ł,	
queue_{std::move(stream)},		
dc_{dc},		
<pre>rhoc_{rhoc},</pre>		
outlierDeltaFactor_{outlierDelta	aFactor} {	
<pre>init_device();</pre>		
}		
~CLUEAlgoAlpaka() = default;		
void makeClusters(PointsCloud const &	host_pc);	
PointsCloudAlpaka d_points;		
LayerTilesAlpaka <acc1d> *hist_;</acc1d>		Pointers to device memory
cms::alpakatools::VecArray <int, maxns<="" th=""><th>eeds> *seeds_;</th><th></th></int,>	eeds> *seeds_;	
cms::alpakatools::VecArray <int, maxnfg<="" th=""><th>ollowers> *followers_;</th><th>passed to kernels</th></int,>	ollowers> *followers_;	passed to kernels
private:		
Executes the	task (similar to	cudaStream)
float then t		
float outlierDeltaFaster :		
loat outlielbeltaractor_,		
stdontional comsalmakatoolsdevice	e buffercDevice LaverTi	lesalnakazacc1Ds[]>> d hist.
std::optional coms::alpakatools::device	buffercDevice cms::al	nakatoole::Vectoravint maxNSeedesss d seeder
std::optionalcoms::alpakatools::device	<pre>buffer<device, cms::al<="" pre=""></device,></pre>	nakatools::VecArraysint, maxNoccdassi d_secds,
alpaka buffers	don't have a d	efault constructor
// private methods		oradit corrotractor
void init device():		
void setup(PointsCloud const &bost pc):	
}:		
// namespace ALPAKA ACCELERATOR NAMESP	ACE	

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Performance study of the CLUE algorithm with the alpaka library

Porting CLUE from CUDA to Alpaka - 2

alpaka::memcpy(stream, view_d, view_h);



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Copy view from host to device

	Tamespace ALFARA_ACCELERATOR_NAMESFACE {
lass PointsCloudCUDA {	
ublic:	class PointsCloudAlpaka {
<pre>PointsCloudCUDA() = delete;</pre>	public:
<pre>explicit PointsCloudCUDA(cudaStream_t stream, int nPoints)</pre>	PointsCloudAlpaka() = delete;
// input variables	explicit PointsCloudAlpaka(Queue stream, int nPoints)
: x{cms::cuda::make_device_unique< <mark>float</mark> []>(nPoints, stream)},	//input variables Allocate memory for alpaka buffers
y{cms::cuda::make_device_unique< <mark>float</mark> []>(nPoints, stream)},	: x{cms::alpakatools::make_device_buffer <float[]>(stream, nPoints)},</float[]>
layer{cms::cuda::make_device_unique< <mark>int</mark> []>(nPoints, stream)},	y{cms::alpakatools::make_device_buffer <float[]>(stream, nPoints)},</float[]>
weight{cms::cuda::make_device_unique< <mark>float</mark> []>(nPoints, stream)},	layer{cms::alpakatools::make_device_buffer< <mark>int</mark> []>(stream, nPoints)},
// result variables	weight{cms::alpakatools::make_device_buffer <f<mark>loat[]>(stream, nPoints)},</f<mark>
rho{cms::cuda::make_device_unique <f<mark>loat[]>(nPoints, stream)},</f<mark>	//result variables
delta{cms::cuda::make_device_unique< <mark>float</mark> []>(nPoints, stream)},	rho{cms::alpakatools::make_device_buffer< <mark>float</mark> []>(stream, nPoints)},
nearestHigher{cms::cuda::make_device_unique <int[]>(nPoints, stream)},</int[]>	delta{cms::alpakatools::make_device_buffer< <mark>float</mark> []>(stream, nPoints)},
clusterIndex{cms::cuda::make_device_unique< <mark>int</mark> []>(nPoints, stream)},	nearestHigher{cms::alpakatools::make_device_buffer< <mark>int</mark> []>(stream, nPoints)},
isSeed{cms::cuda::make_device_unique< <mark>int</mark> []>(nPoints, stream)},	clusterIndex{cms::alpakatools::make_device_buffer< <mark>int</mark> []>(stream, nPoints)},
view_d{cms::cuda::make_device_unique <pointscloudcudaview>(stream)} {</pointscloudcudaview>	isSeed{cms::alpakatools::make_device_buffer< <mark>int</mark> []>(stream, nPoints)},
<pre>auto view_h = cms::cuda::make_host_unique<pointscloudcudaview>(stream);</pointscloudcudaview></pre>	view_d{cms::alpakatools::make_device_buffer <pointscloudalpakaview>(stream)} {</pointscloudalpakaview>
<pre>view_h->x = x.get();</pre>	<pre>auto view_h = cms::alpakatools::make_host_buffer<pointscloudalpakaview>(stream);</pointscloudalpakaview></pre>
<pre>view_h->y = y.get();</pre>	<pre>view_h->x = x.data();</pre>
view_h->layer = layer.get();	view_h->y = y.data(); Allocate memory for host view
view_h->weight = weight.get();	view_h->layer = layer.data();
<pre>view_h->rho = rho.get();</pre>	<pre>view_h->weight = weight.data();</pre>
view_h->delta = delta.get();	view_h->rho = rho.data();
view_h->nearestHigher = nearestHigher.get();	view h->delta = delta.data():
<pre>view_h->clusterIndex = clusterIndex.get();</pre>	view h->nearestHigher = nearestHigher.data():
view_h->isSeed = isSeed.get();	view h->clusterIndex = clusterIndex.data():
	view h->isSeed = isSeed.data():
cudaMemcpyAsync(view_d.get(), view_h.get(), <pre>sizeof(PointsCloudCUDAView), cudaMemcpyHostToDevice, stream);</pre>	

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Porting CLUE from CUDA to Alpaka - 3

void KernelComputeHistogram(std::array<LayerTilesSerial, NLAYERS> &d_hist, PointsCloudSerial &points) { for (unsigned int i = 0; i < points.n; i++) {</pre> // push index of points into tiles d_hist[points.layer[i]].fill(points.x[i], points.y[i], i); _global__ void kernel_compute_histogram(LayerTilesCUDA* d_hist, pointsView* d_points, int numberOfPoints) { int i = blockIdx.x * blockDim.x + threadIdx.x; if (i < numberOfPoints) {</pre> // push index of points into tiles d_hist[d_points->layer[i]].fill(d_points->x[i], d_points->y[i], i); kernel struct KernelComputeHistogram { template <typename TAcc> Called when launching the kernel ALPAKA_FN_ACC void operator()(const TAcc &acc, LayerTilesAlpaka<Acc1D> *d_hist, pointsView *d_points, CUDA uint32_t const &numberOfPoints) const { // push index of points into tiles cms::alpakatools::for_each_element_in_grid(acc, numberOfPoints, [&](uint32_t i) { d_hist[d_points->layer[i]].fill(d_points->x[i], d_points->y[i], i); });

CPU serial: loops over all the points

GPU CUDA: each thread execute the same instruction with a different point

CPU/GPU alpaka: same as CUDA, with a user-defined helper function that accounts for an additional "*elements"* abstraction layer

 Work division organized in Grids-Blocks-Threads-Elements







CLUE - Performance plot



- Alpaka with the serial backend scales
 linearly with the number of threads
 (concurrent events), the same way as the
 native serial implementation
- Alpaka with the cuda backend has the same scaling of the native cuda
 implementation. Two points are under investigation:
 - Other applications **do not show** that alpaka is faster than cuda
 - It seems that I/O operations and the computing capability of the GPU are limiting the scaling for threads > 4

CLUE 3D (WIP)

- 3D version of the CLUE algorithm to reconstruct particle showers in multi-layer high granularity calorimeters
- Builds 3D objects *starting from clusters* built with CLUE 2D
- Serial implementation currently used by the HGCAL reconstruction framework (TICL) in CMSSW
- Ported to alpaka and can run on GPU now!
- For more information, check Wahid Redjeb's poster
 "The TICL reconstruction at the CMS Phase-2
 High Granularity Calorimeter Endcap" on Thursday









CLUE 3D – Performance plot



- Alpaka with the serial backend scales
 linearly with the number of threads
 (concurrent events) the same way as the
 native serial implementation
- Alpaka with the cuda backend provides a a high throughput of ~200 events/second
 - Compared with serial and the same number of threads (i.e. 2), throughput is more than 20 times higher
 - Also for CLUE 3D, throughput on GPU seems limited by I/O operations

Work in progress and future plans

- CLUE has been ported to another performance portability library:
 - SYCL/oneAPI (credits to Luca Ferragina and Juan Jose Olivera Loyola)
 - Performance under study
 - CLUE 3D expected to be ported as well
 - For more information, check Aurora Perego's poster "Experience in SYCL/oneAPI for event reconstruction at the CMS experiment" on Tuesday
- * A python library named **CLUEstering** (credits to **Simone Balducci** and

Alessandro Mancini) has been developed

- Generalization of CLUE to N dimensions
- Python binding to C++ serial implementation
- Expected binding to C++ alpaka implementation in future







Conclusions

- The alpaka performance portability library is an interesting solution in the era of heterogeneous computing
 - Write the code once, compile it, and run it on different backends!
 - Performance close to native implementations
 - New backends are planned and/or in development (i.e. SYCL)
- CLUE represents a useful testbed for performance portability solutions
 - Simple application
 - Tests have been made with both alpaka and SYCL/oneAPI
- CLUE 3D is the first algorithm, within the HGCAL-TICL reconstruction
 - framework, that has been **ported directly from serial C++ to alpaka**
 - Optimizations still ongoing



Thanks for your attention

CLUE repository: <u>heterogeneous-clue</u> CLUE original paper: <u>CLUE</u> email: <u>cms-patatrack@cern.ch</u>









Backup



Porting to Alpaka: what to know

- Programming strategy inspired by CUDA
 - Easy porting CUDA-to-alpaka
 - Same way of organizing the work division Grids-Blocks-Threads + additional abstraction layer *Elements* that can be exploited for vectorization
- Performance is close to the native backend
 - No overhead with respect to native CUDA or HIP/ROCm
- Alpaka objects behave like shared_ptrs \rightarrow must be passed by value or const reference
- native buffers (vectors, arrays, ...) must be ported to alpaka buffers, which don't have a default constructor



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Kernel launch comparison

kernel_compute_histogram<<<gridSize, blockSize, 0, stream_>>>(d_hist.get(), d_points.view(), host_pc.x.size());

auto WorkDiv1D = cms::alpakatools::make_workdiv<Acc1D>(gridSize, blockSize);

alpaka::enqueue(

queue_,
alpaka::createTaskKernel<Acc1D>(WorkDiv1D, KernelComputeHistogram(), hist_, d_points.view(), d_points.n));

alpaka: kernels are enqueued in task objects

CUDA baseline

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