

Machine Learning for Phase Space Sampling

An exploration for LHC simulated event generation with SHERPA

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ACAT 2022

Several slides adapted from Steffen Schumann



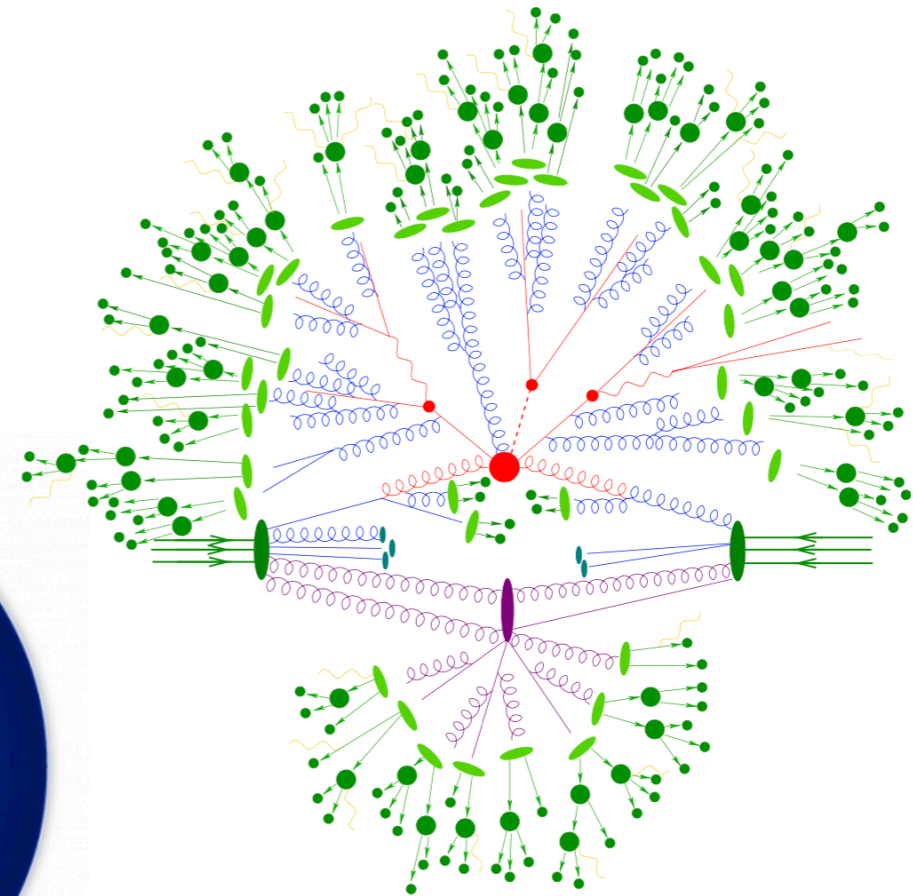
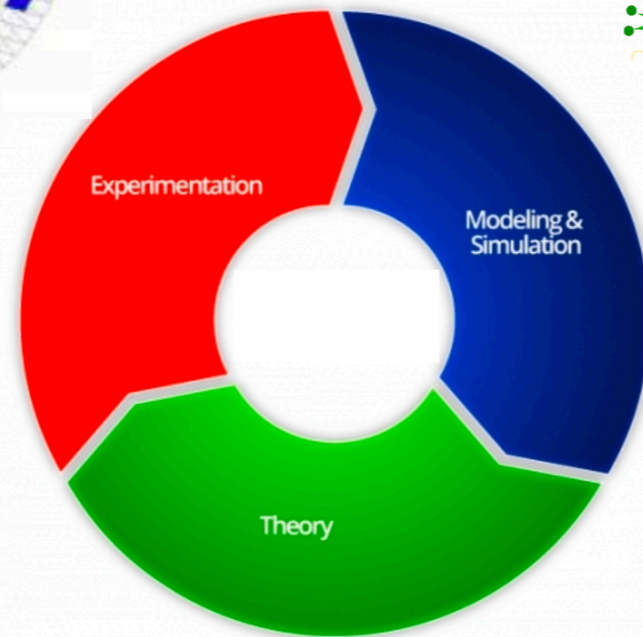
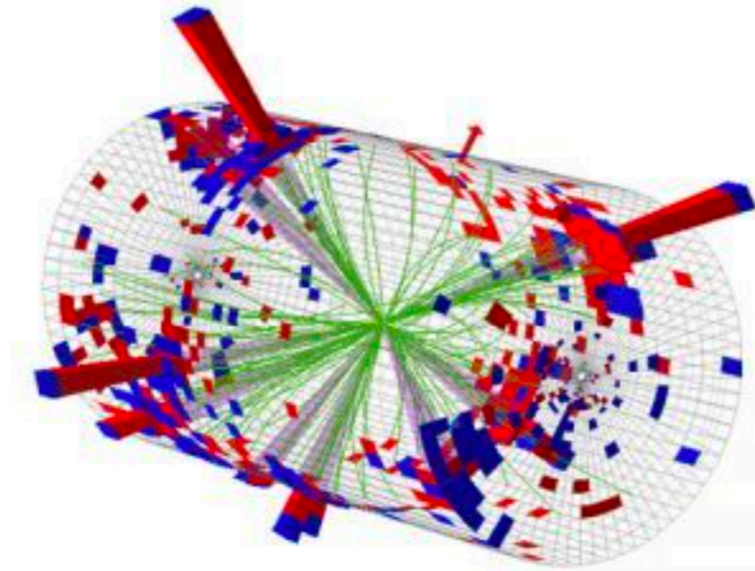
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The High Energy Physics Triad



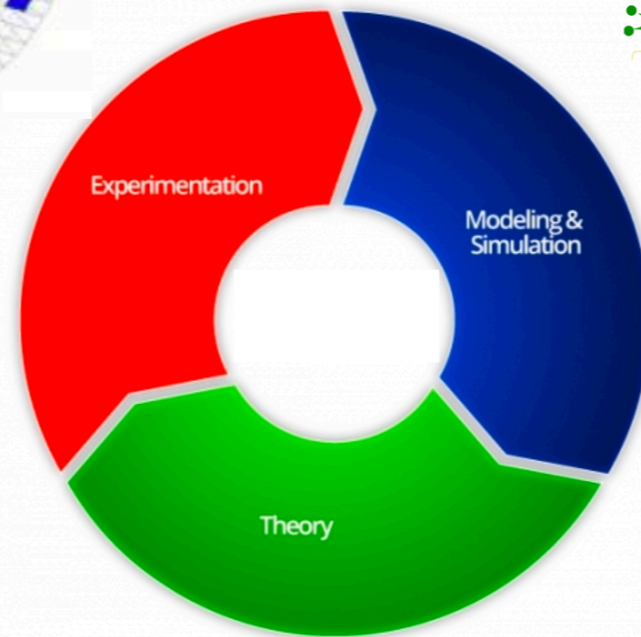
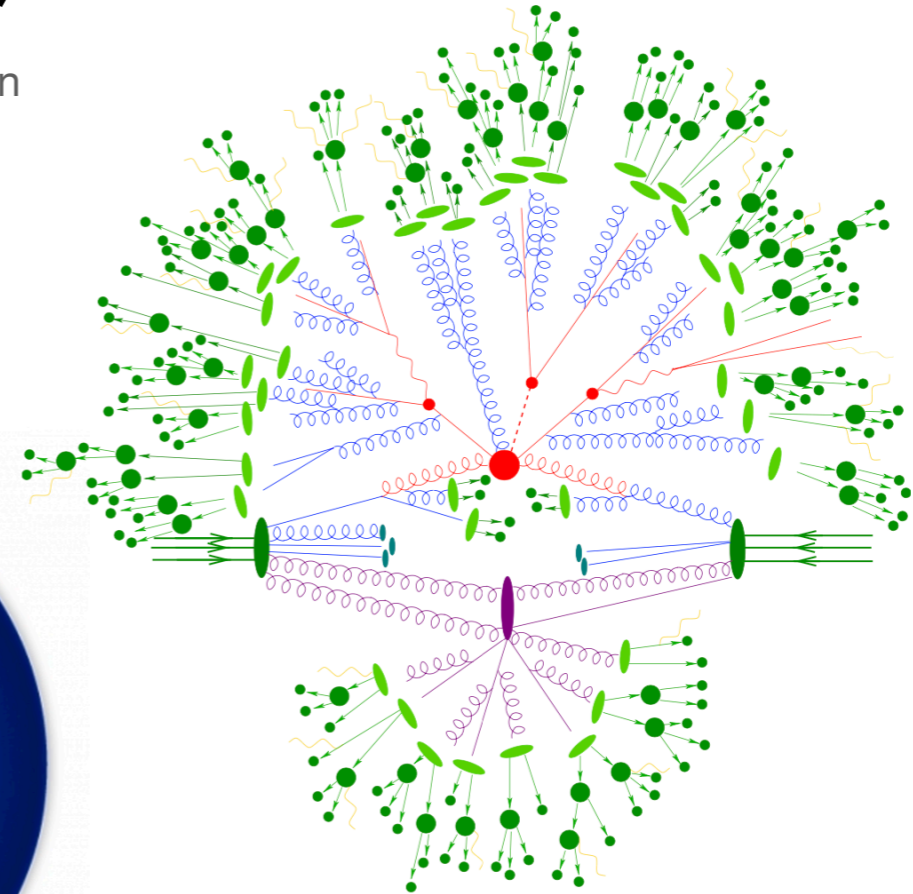
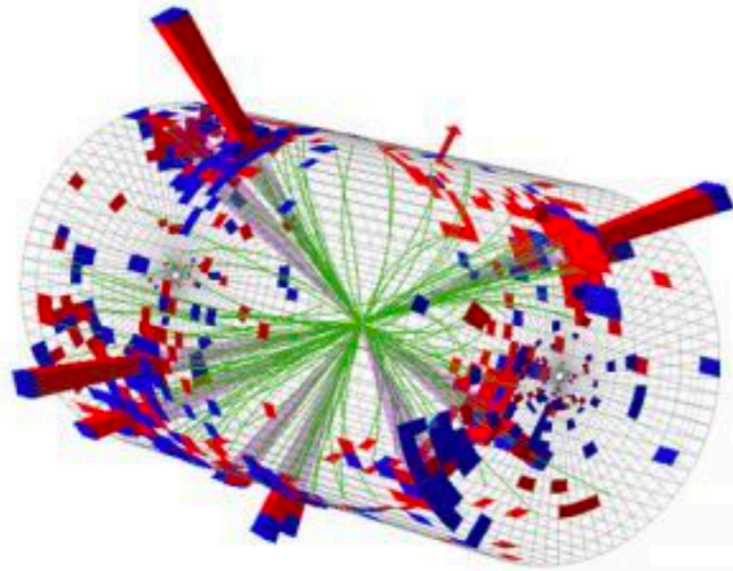
$$\mathcal{L} = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} + i\bar{\psi}\not{D}\psi + h.c.$$

The High Energy Physics Triad

Random collision ▶ Detector response ▶ Trigger
▶ Event Reconstruction ▶ Event Sample

Random numbers ▶ Monte Carlo event generator
▶ Detector simulation ▶ Event Reconstruction ▶
Simulated Event Sample

statistical comparison

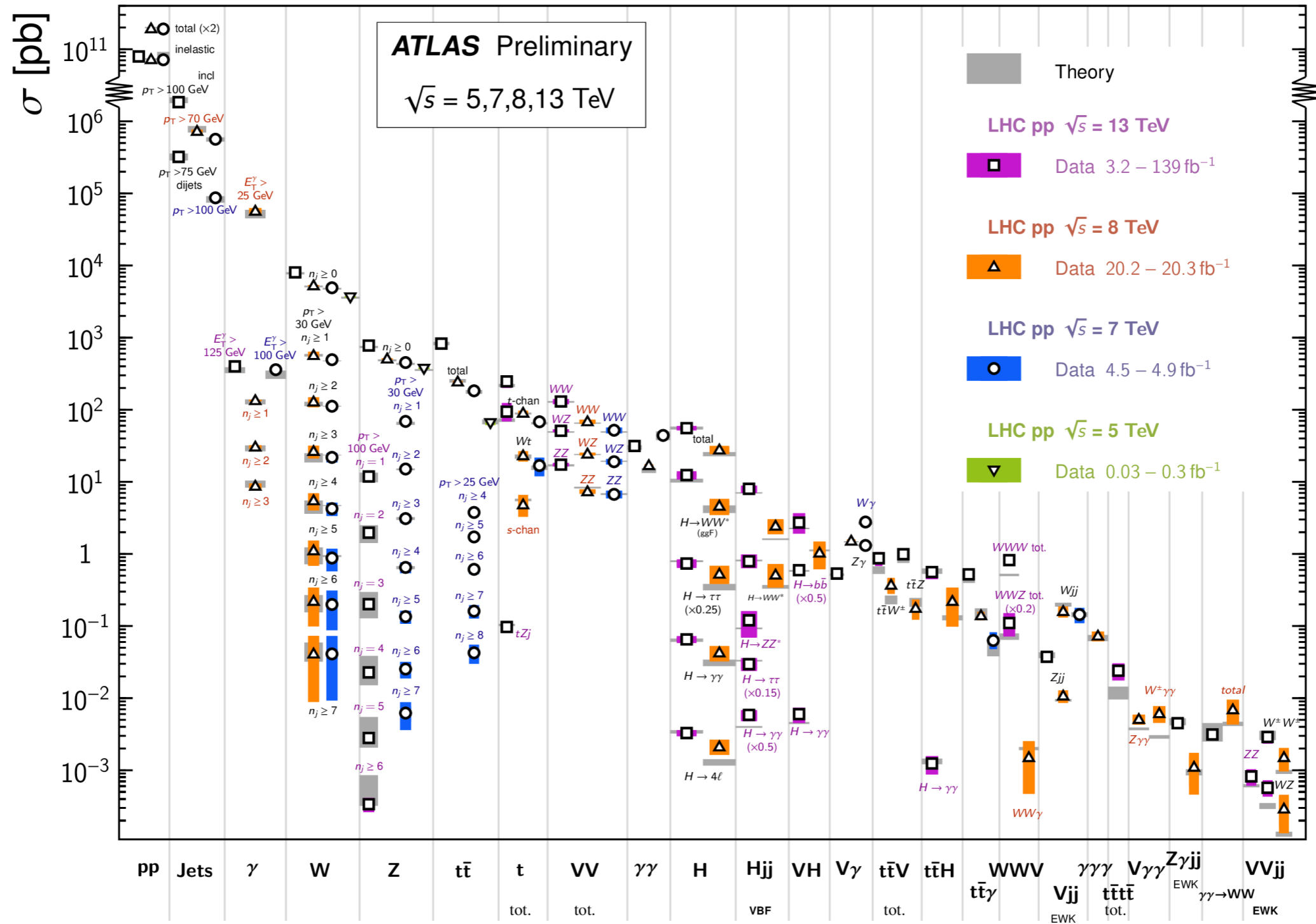


$$\mathcal{L} = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} + i\bar{\psi}\not{D}\psi + h.c.$$

LHC Process Zoo

Standard Model Production Cross Section Measurements

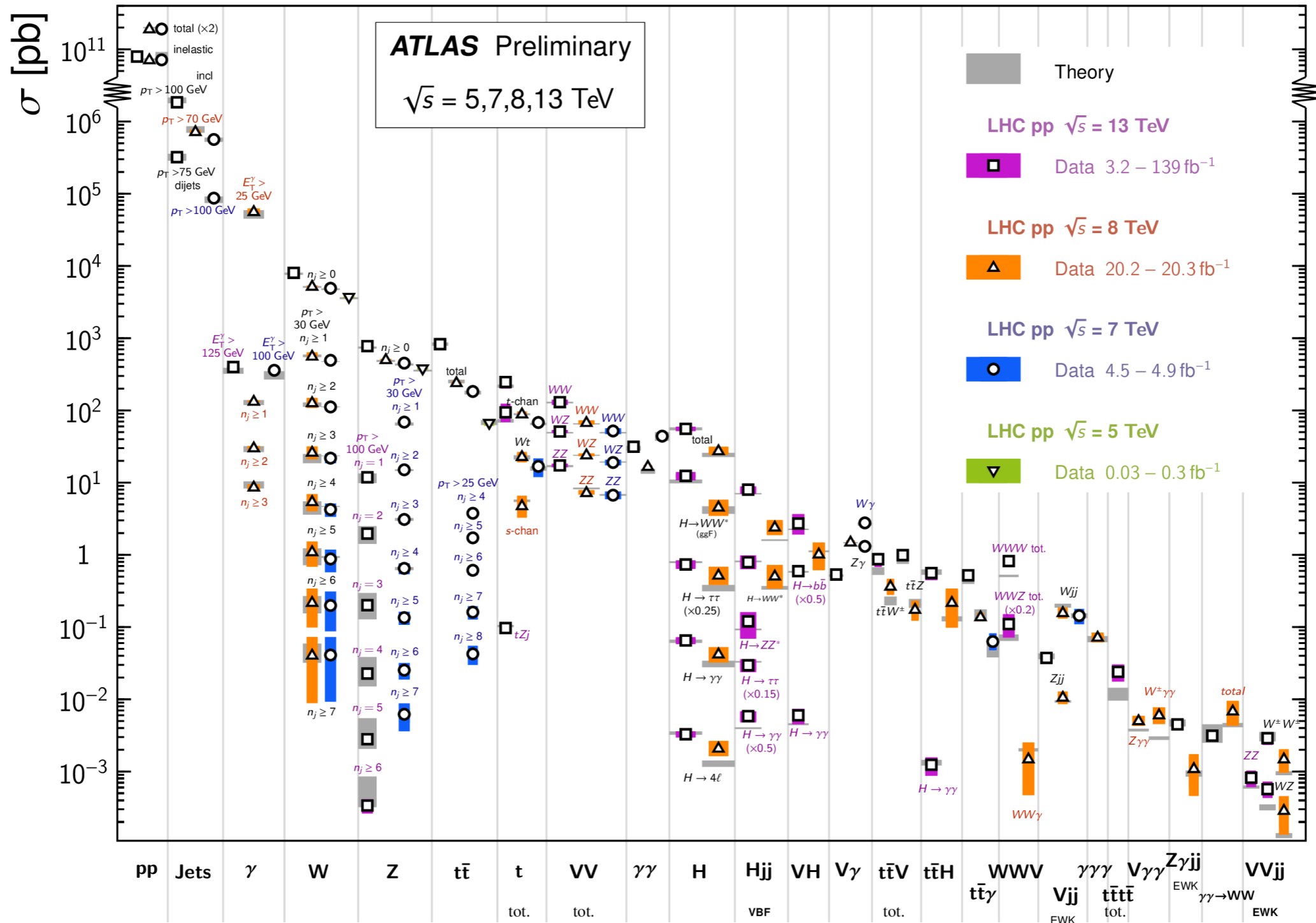
Status: February 2022



LHC Process Zoo

Standard Model Production Cross Section Measurements

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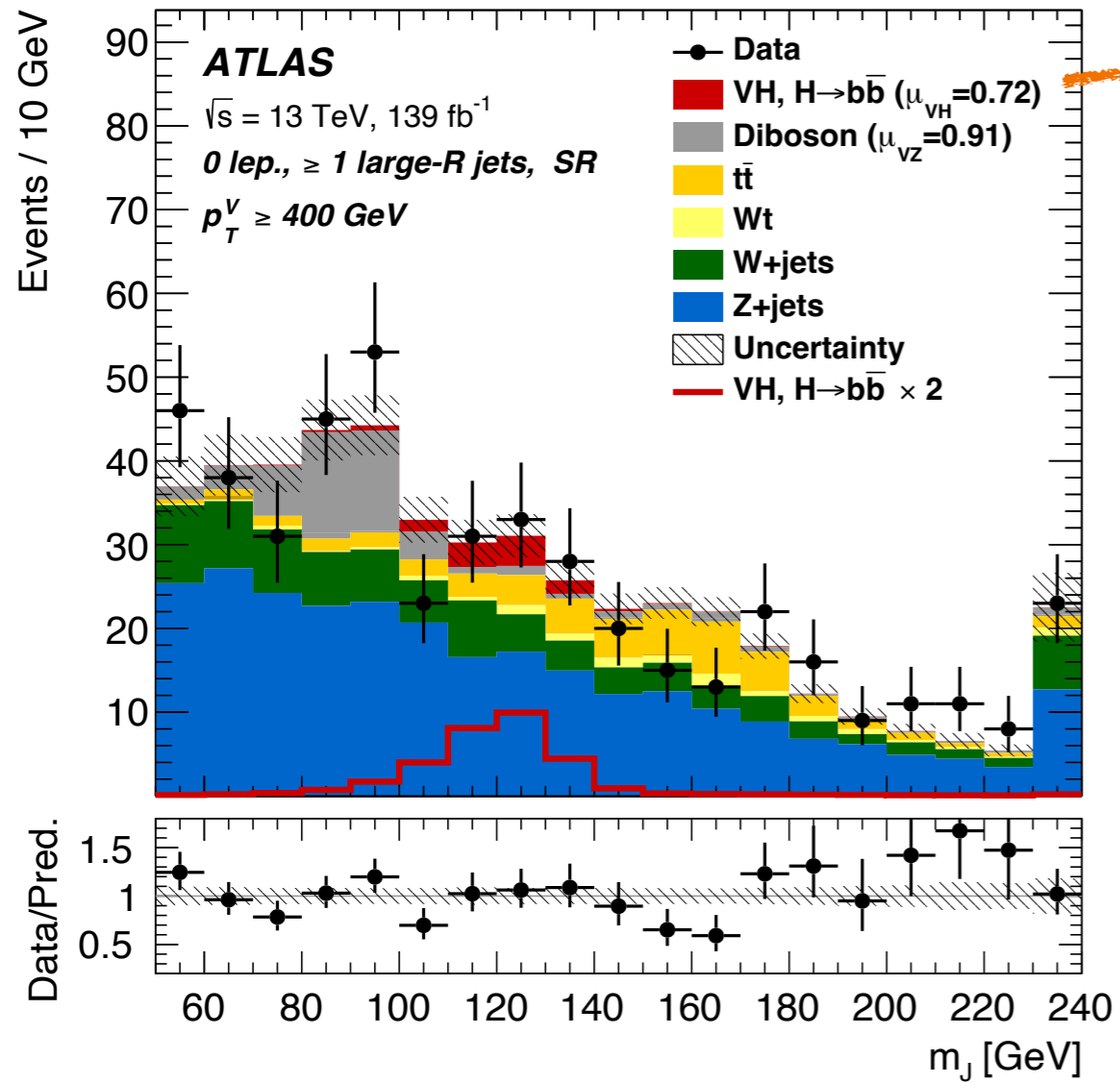


signal processes for SM measurements & BSM searches
 often associated with several jets

V+jets: background to most other processes & large rates even with several extra jets

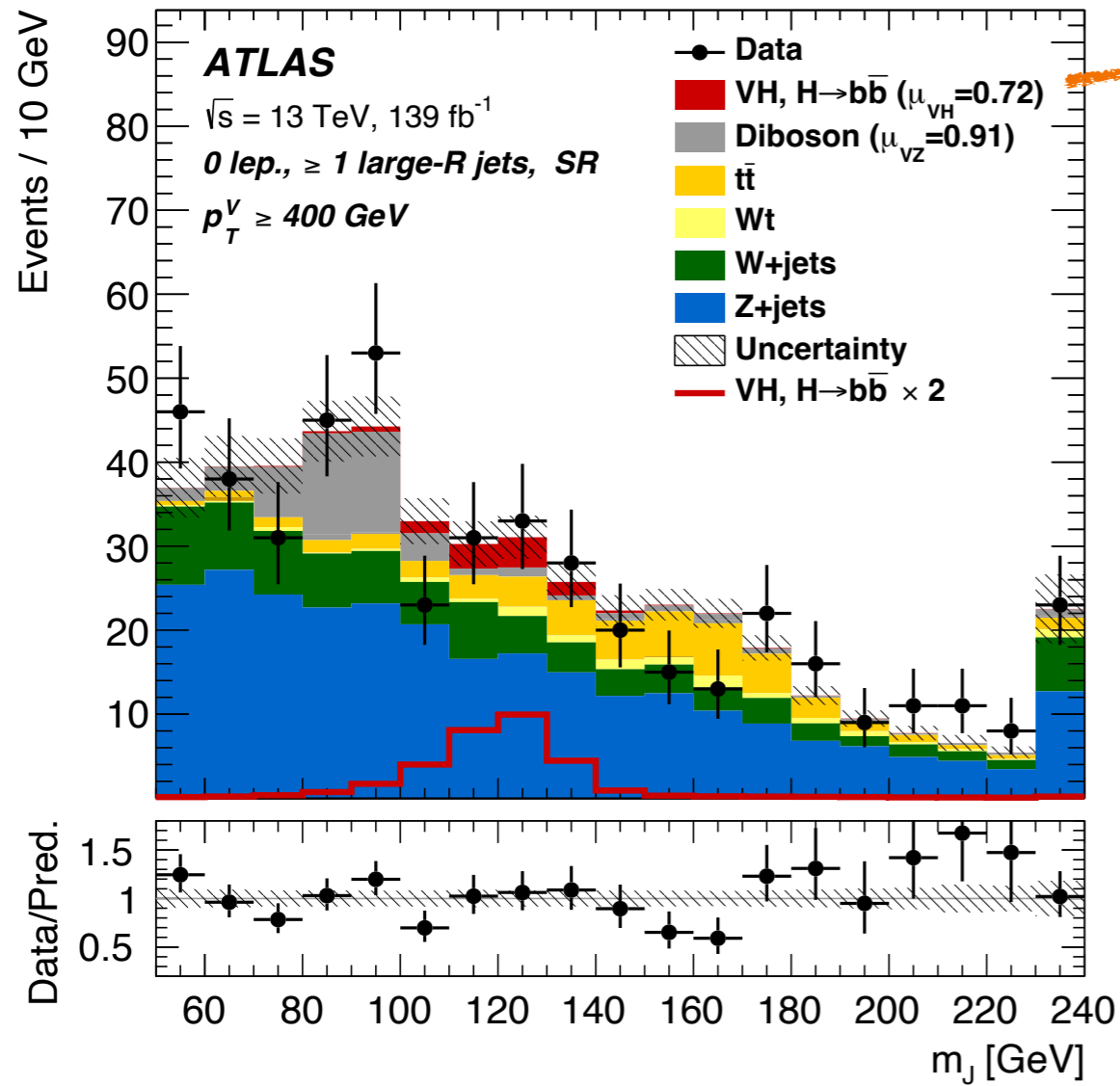
Typical Use Case & Need for Precision

[G. Aad et al. [ATLAS], Phys. Lett. B 816 (2021), 136204]



Typical Use Case & Need for Precision

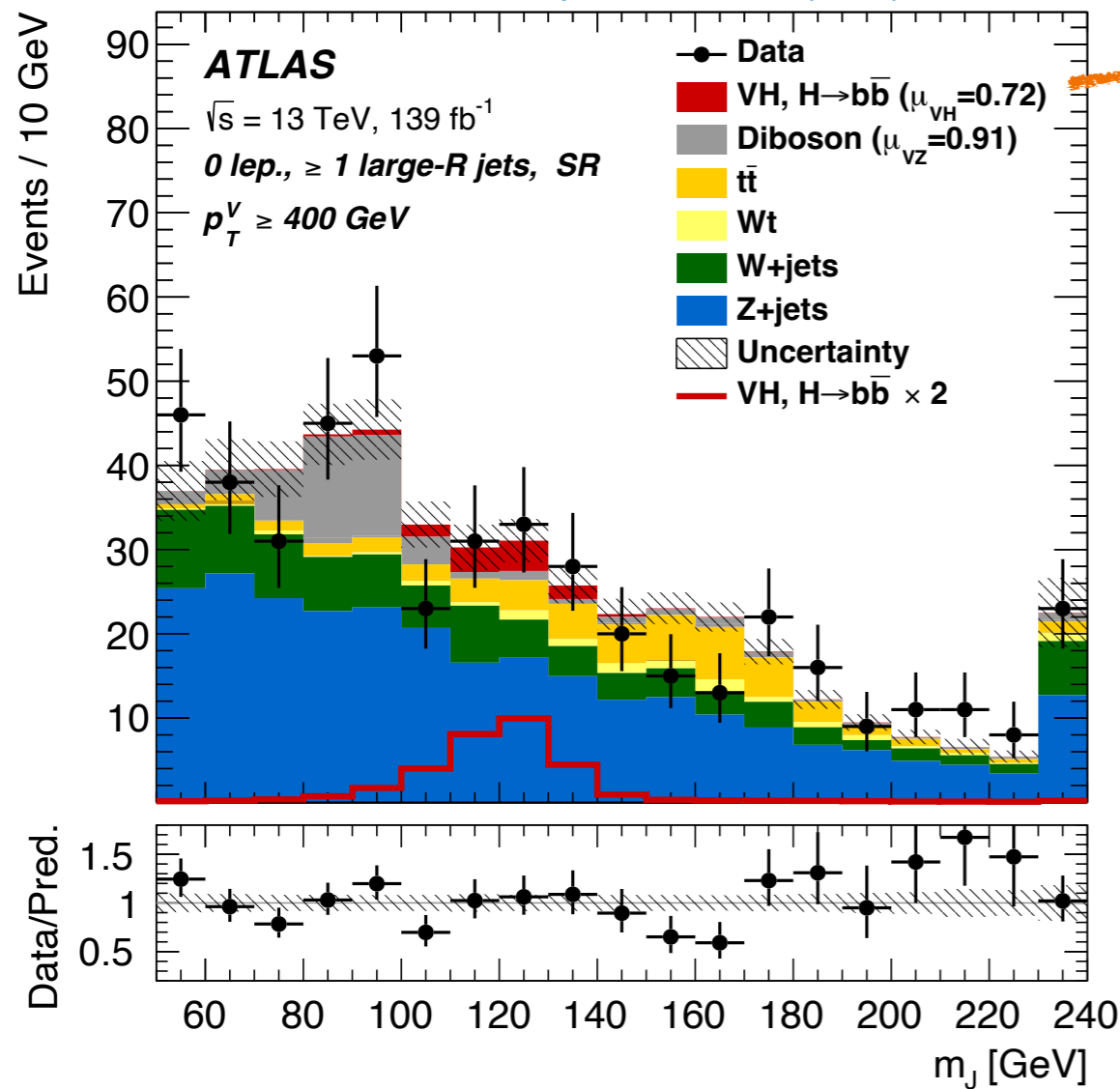
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“measured signal yield to that predicted by the Standard Model, is $0.72^{+0.39}_{-0.36}$ ”

Typical Use Case & Need for Precision

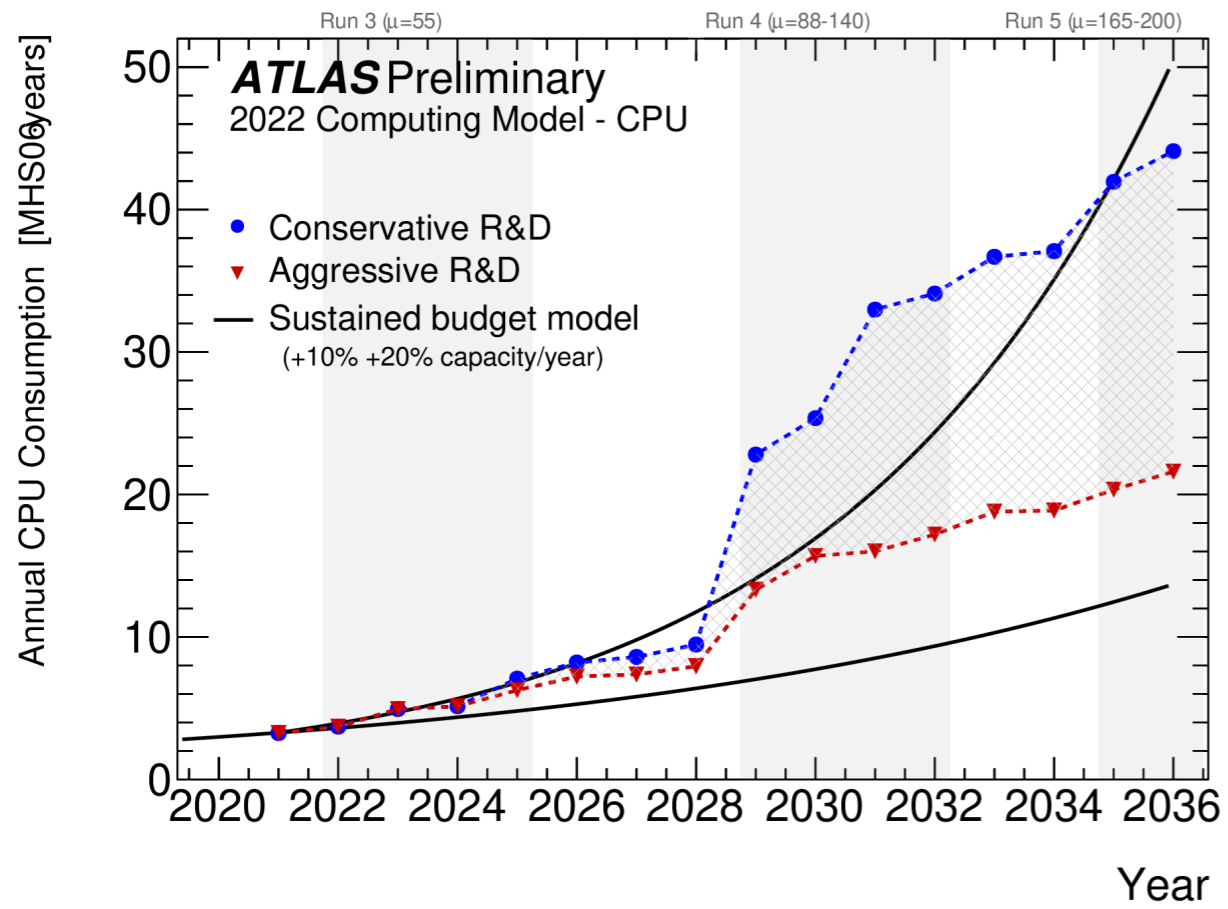
[G. Aad et al. [ATLAS], Phys. Lett. B 816 (2021), 136204]



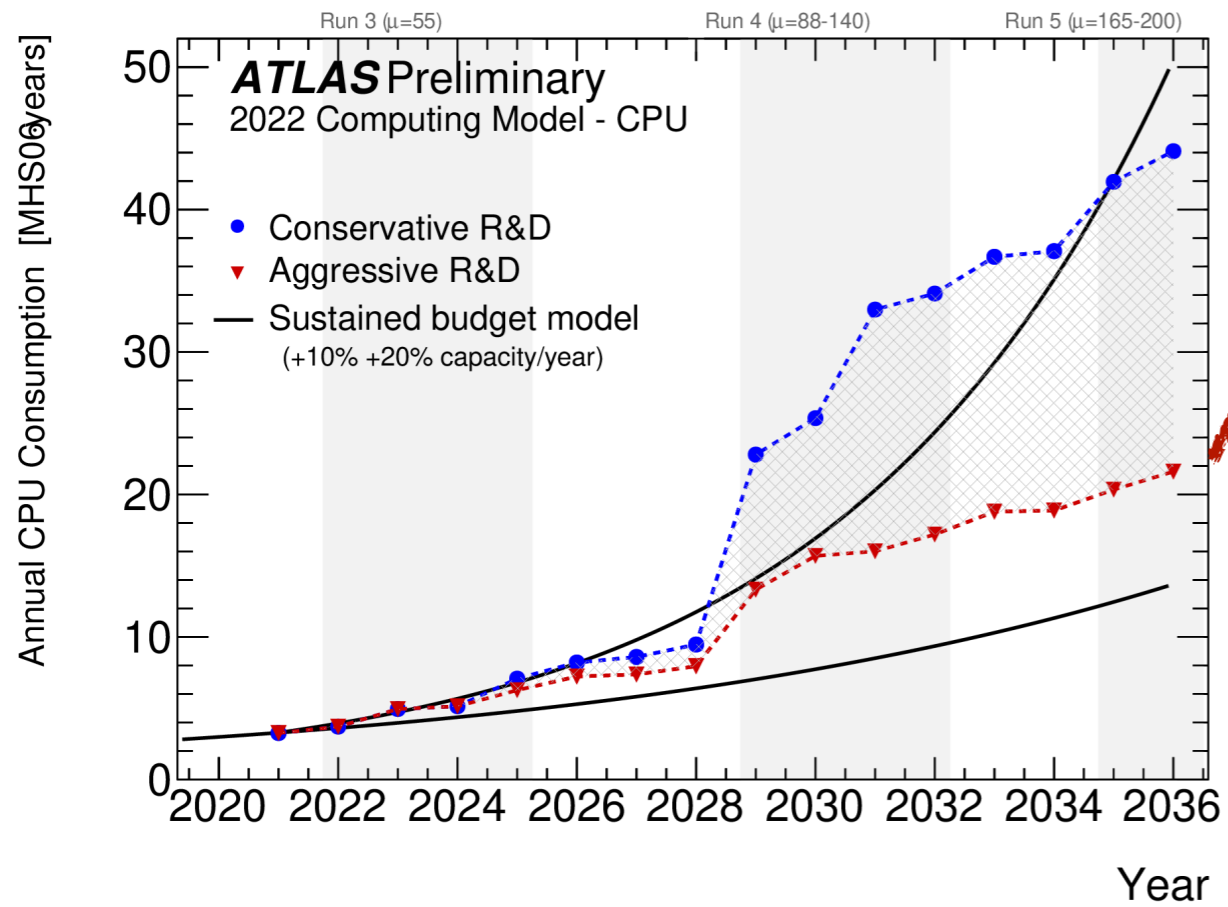
“measured signal yield to that predicted by the Standard Model, is $0.72^{+0.39}_{-0.36}$ ”

- results like this need (automated) first-principle forward simulation for all relevant processes
 - accuracy in perturbative expansion: (N)NLO QCD, (N)LO EW, NLL etc.
 - multi-jet predictions
 - quantifiable uncertainties for model parameters, perturbation theory, etc.
- ➡ MCEG provide this
- ➡ but precision simulations are expensive

Event generation computing challenge

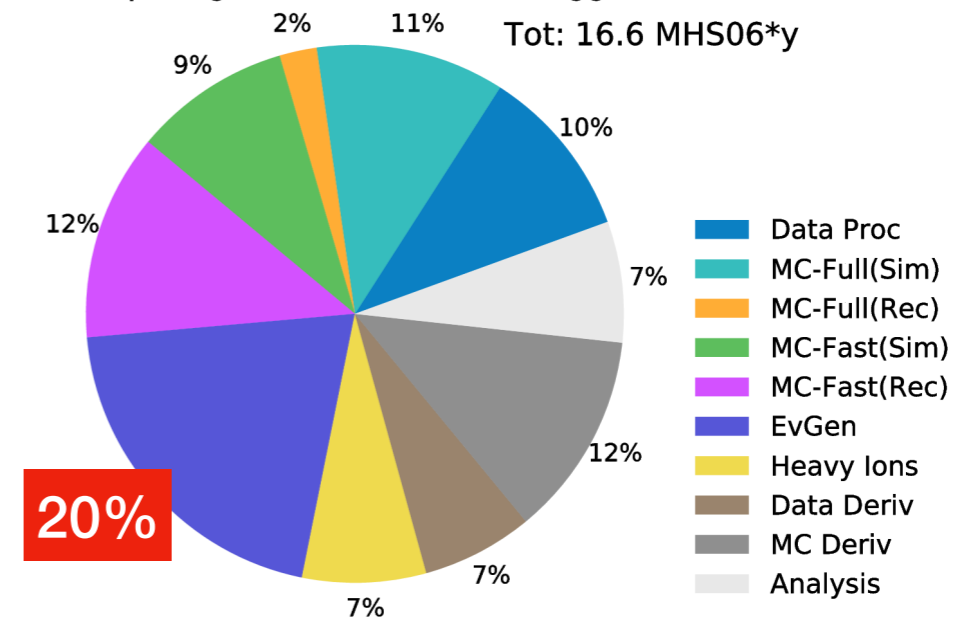


Event generation computing challenge

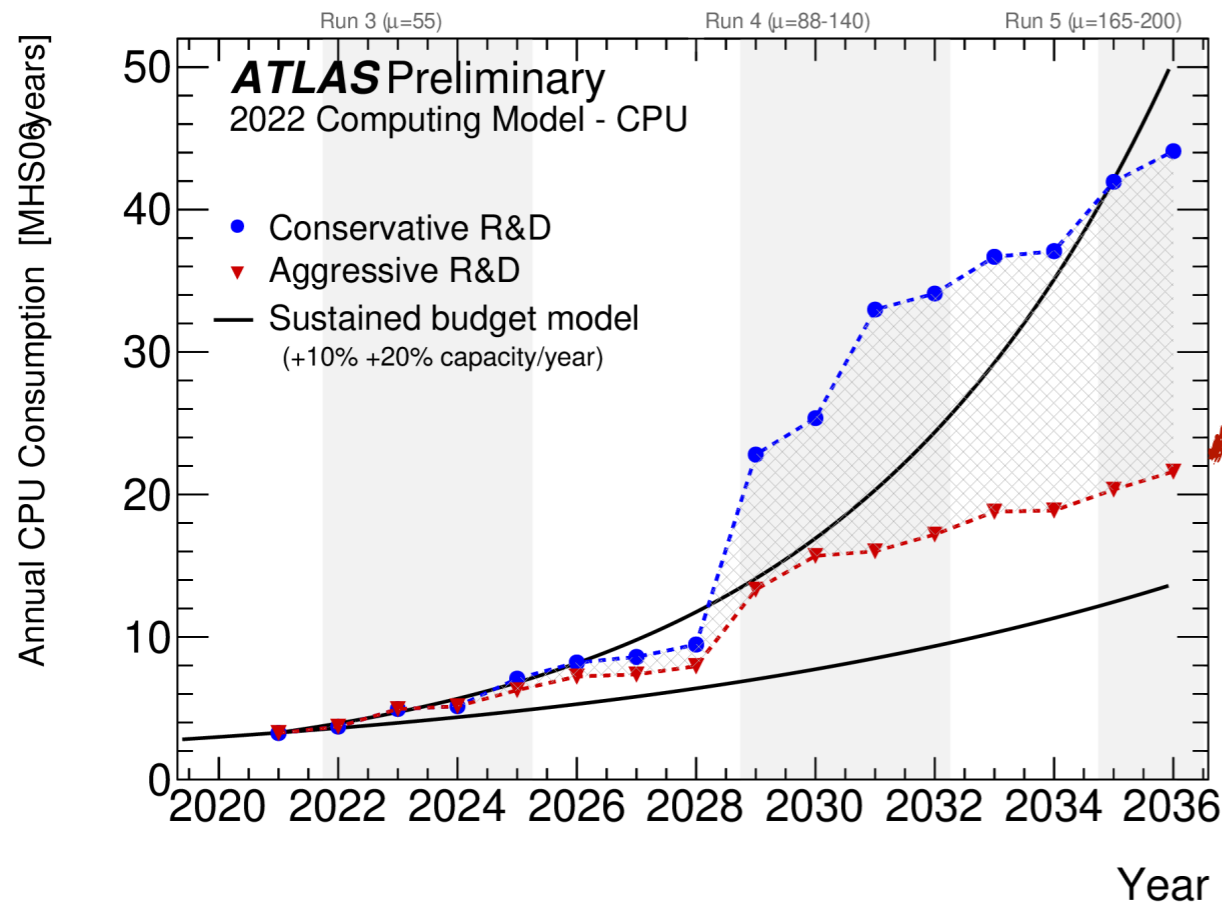


composed of ...

ATLAS Preliminary
2022 Computing Model - CPU: 2031, Aggressive R&D
Tot: 16.6 MHS06*y

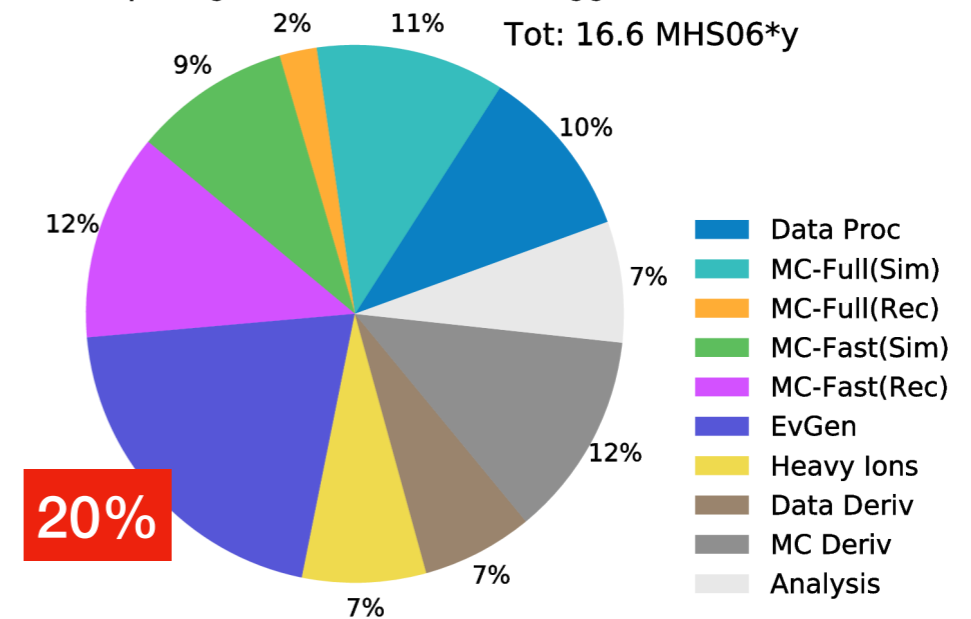


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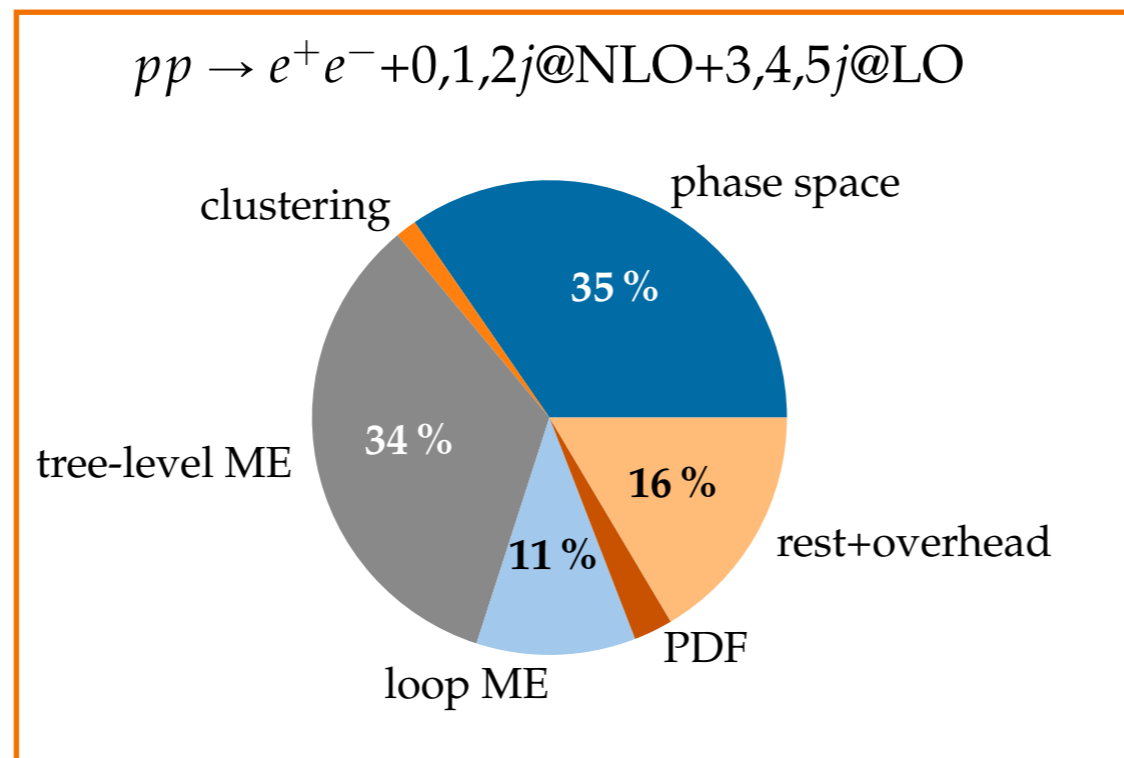


- Run-III & HL-LHC CPU requirements spark renewed interest in efficiency
[ATLAS HL-LHC Computing CDR, Valassi et al Challenges in MCEG software for HL-LHC arXiv:2004.13687]
- Event Generators is significant consumer of CPU hours
- Beyond addressing this important issue ...
 - ... faster simulation also enables physics: better accuracy, higher jet multiplicity, etc.

Event Generation Bottlenecks

Our job is to sample this integral:

$$\sigma_{pp \rightarrow X_n} = \sum_{ab} \int dx_a dx_b d\Phi_n f_a(x_a, \mu_F^2) f_b(x_b, \mu_F^2) |\mathcal{M}_{ab \rightarrow X_n}|^2 \Theta_n(p_1, \dots, p_n)$$



relative CPU time usage
for a typical ATLAS
V+jets setup with SHERPA

(after series of optimisations
which give a ~40x speed-up,
thus ticking off one of the major
HSF generator WG milestones)

[EB et al. 2209.00843]
[Talk by C. Gutschow]

- ➔ relevant remaining bottleneck: phase-space & matrix elements $|\mathcal{M}|^2$ (ME)
- better phase-space sampling directly reduces number of ME evaluations

When expensive integrands meet poor sampling efficiencies

Our job is to sample this integral:

$$\sigma_{pp \rightarrow X_n} = \sum_{ab} \int dx_a dx_b d\Phi_n f_a(x_a, \mu_F^2) f_b(x_b, \mu_F^2) |\mathcal{M}_{ab \rightarrow X_n}|^2 \Theta_n(p_1, \dots, p_n)$$

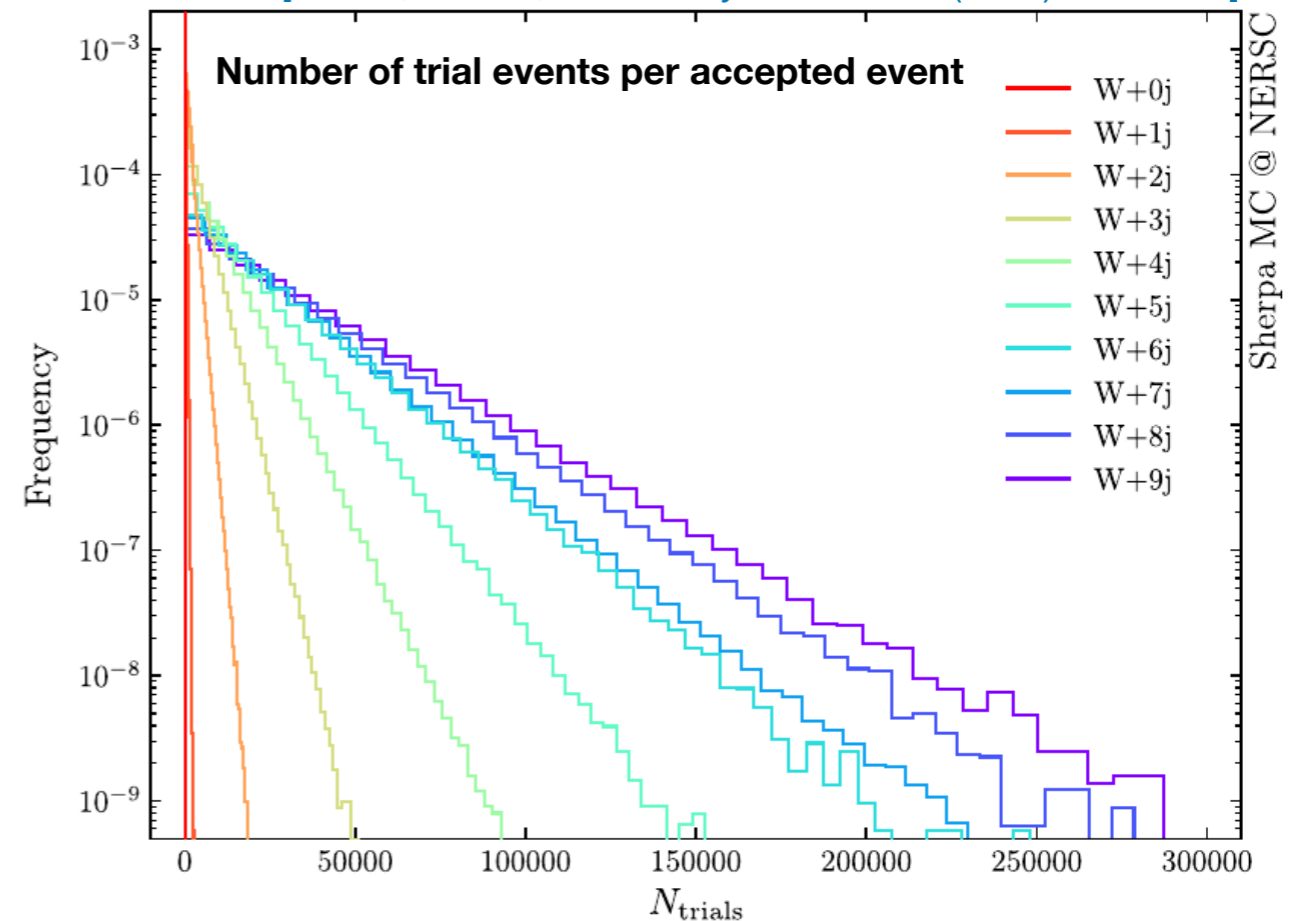
First figure of merit:

$$\epsilon = \frac{1}{\langle N_{\text{trials}} \rangle}$$

(rejection sampling efficiency)

- Low sampling efficiency ϵ , why?
 - multi-modal, wildly fluctuating target distribution $f_a f_b |\mathcal{M}|^2$
 - subject to non-trivial acceptance cuts Θ_n
 - high dimensionality $\dim[\Phi_n] = 3n - 4$
- Good news: Fairly generic sampling/integration problem

[Höche, Prestel, Schulz *Phys.Rev.D* 100 (2019) 1, 014024]



Can we use ML/NN as a remedy without compromising on precision requirements?

Multi-channel importance sampling

- Consider generic integral over target function $f(x)$, $x \in V \subseteq \mathbb{R}^d$
- Choose variable mapping $y : V \rightarrow U \subseteq \mathbb{R}^d$

$$I = \int_V d^d x f(x) = \int_U d^d y \frac{f(x)}{g(x)} \Big|_{x \equiv x(y)} \quad \text{with} \quad \left| \frac{\partial y(x)}{\partial x} \right| = g(x)$$

Second figure of merit:

$$\text{Var} \approx \frac{\langle w^2 \rangle - \langle w \rangle^2}{N}$$

(Monte-Carlo variance)

↪ reduce **variance of MC estimate** through suitable $g(x)$, such that $w = f/g \approx \text{const}$.

↪ for multi-modal target use multi-channel $g(x) = \sum_i \beta_i g_i(x)$ with $\sum_i \beta_i = 1$

$$I = \int_V d^d x f(x) = \sum_i \int_V d^d x \beta_i g_i(x) \frac{f(x)}{g(x)} = \sum_i \int_{U_i} d^d y_i \beta_i \frac{f(x)}{g(x)} \Big|_{x \equiv x(y_i)}$$

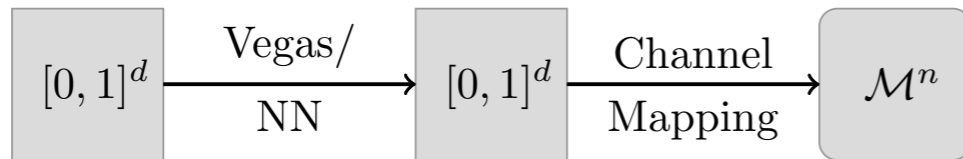
↪ ME generators use physics knowledge about $f_a f_b | \mathcal{M} |^2$ to construct channels, mapping out prominent features/singularities, but not all features are known

**We can embed ML into this for additional optimisation of $y(x)$.
But we need to (i) guarantee phase-space coverage and (ii) cheap evaluation.**

Neural Importance Sampling (Normalising Flows)

[Bothmann et al., SciPost Phys. 8 (2020) no.4, 069], [Gao et al., Phys. Rev. D 101 (2020) no.7, 076002]

- Further generic optimisation of random number mapping entering phase-space channels $g(x)$



- Chain of **bijective** maps, called coupling layers ℓ

$$\left. \begin{array}{l} x^A \rightarrow y^A := x^A \\ x^B \rightarrow y^B := C(x^B; m(x^A)) \end{array} \right\} J = \left| \begin{pmatrix} \text{diag}(1) & 0 \\ \frac{\partial C}{\partial m} \frac{\partial m}{\partial x^A} & \frac{\partial C}{\partial x^B} \end{pmatrix} \right| = \left| \frac{\partial C}{\partial x^B} \right|$$

- C invertible+separable yields cheap Jacobian $\sim \mathcal{O}(d)$
- m arbitrary function \rightarrow use DNN
- C piecewise quadratic \rightarrow „Neural Importance Sampling“
first applied to ray tracing in 3D scenes
[\[Müller et al. arXiv:1808.03856\]](#)
- very expressive+cheap non-linear variable transformations (non-factorisable!)

Illustration: Linear VEGAS grid

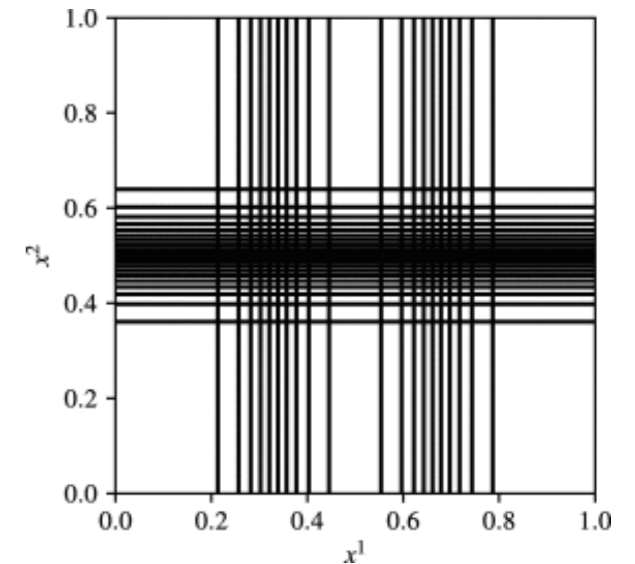
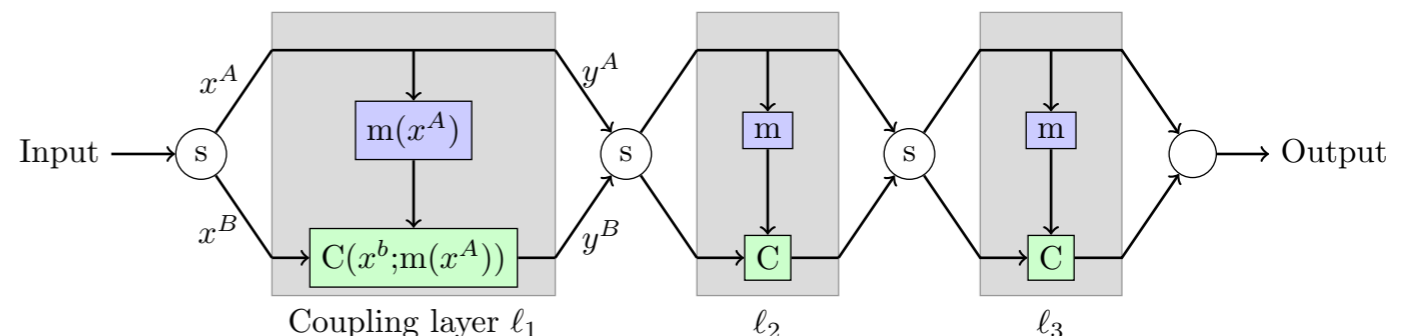
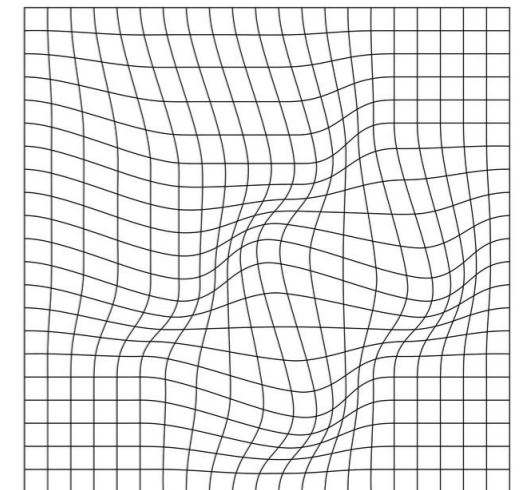
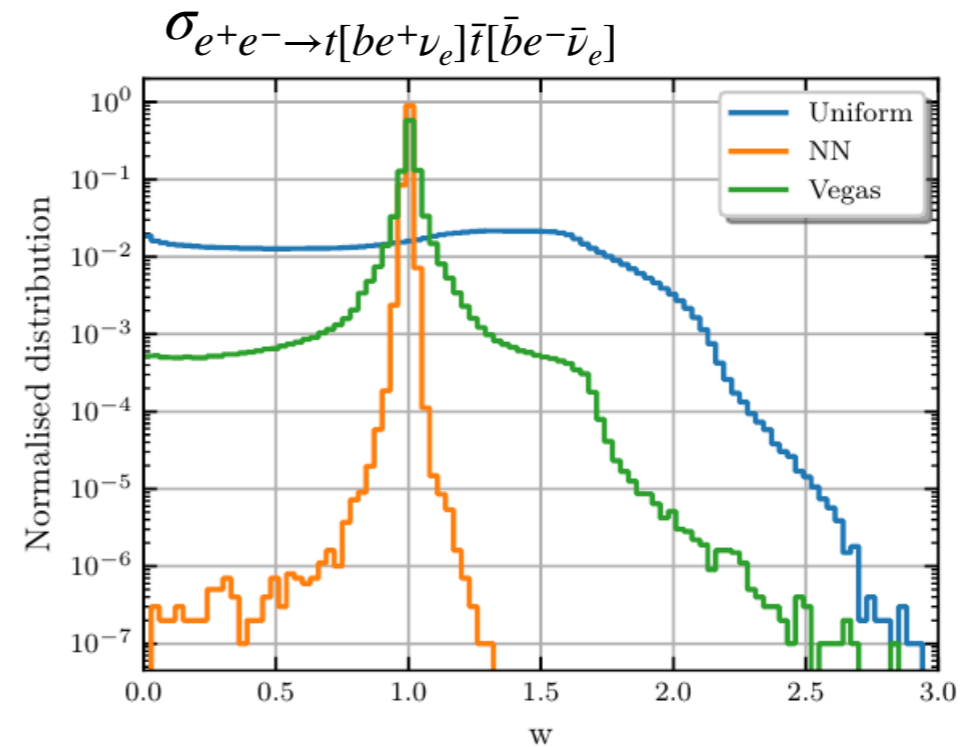
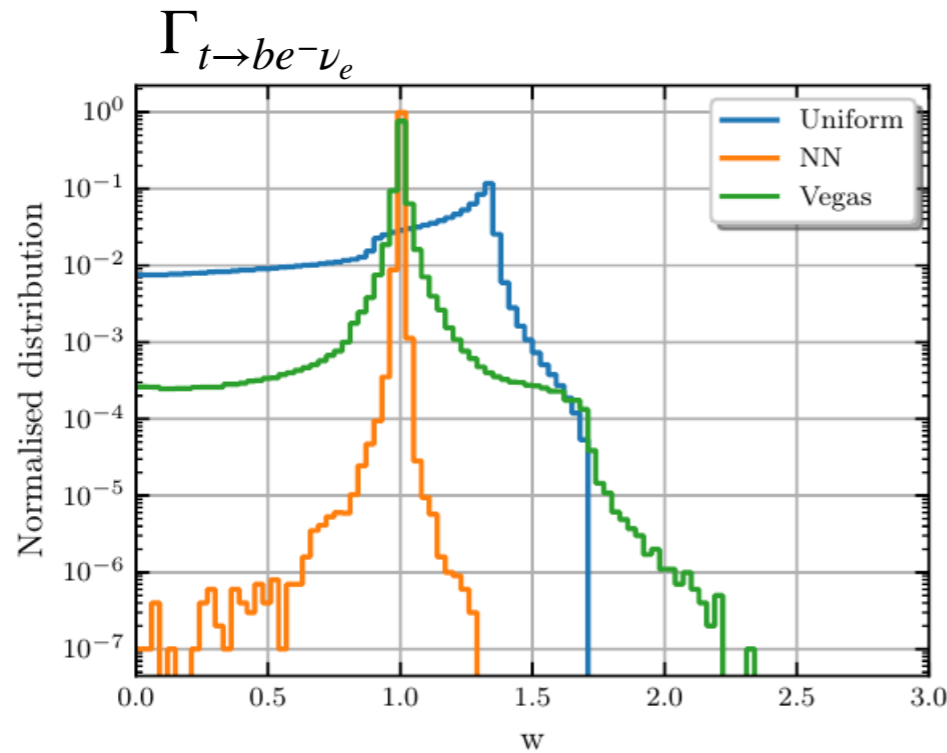


Illustration: Nonlinear NIS grid



Neural Importance Sampling – Results

remember: aim for $w = f/g \approx 1$, i.e. peaked distribution of w



Sample	top decays		top-pair production		$gg \rightarrow 3g$		$gg \rightarrow 4g$	
	ϵ_{uw}	E_N [GeV]	ϵ_{uw}	E_N [fb]	ϵ_{uw}	E_N [fb]	ϵ_{uw}	E_N [fb]
Uniform	59 %	0.1679(2)	35 %	1.5254(8)	3.0 %	24806(55)	2.7 %	9869(20)
Vegas	50 %	0.16782(4)	40 %	1.5251(1)	27.7 %	24813(23)	31.8 %	9868(10)
NN	84 %	0.167865(5)	78 %	1.52531(2)	64.3 %	24847(21)	48.9 %	9859(10)

- Smaller impact for more complicated (multi-channel) processes, similar in [\[Gao et al., Phys. Rev. D 101 \(2020\) no.7, 076002\]](#)
- GPU evaluation of MEs desirable for efficient training cf. talks by M. Knobbe, R. Wang and A. Valassi
- Alternative to ML-assisted phase space sampling: directly learn target distribution using autoregressive flows, GANs, VAEs [\[Stienen and Verheyen SciPost Phys. 10, 038 \(2021\)\]](#), [\[Butter, Plehn and Winterhalder, SciPost Phys. 7 \(6\), 075 \(2019\)\]](#), [\[Sipio et al. JHEP 08, 110 \(2019\)\]](#), [\[Otten et al. Nature Commun. 12 \(1\), 2985 \(2021\)\]](#), [\[Choi and Lim, J. Korean Phys. Soc. 78 \(6\), 482 \(2021\)\]](#)
 - if no surjectivity guarantee \rightarrow might miss tails of distributions and get small bias in overall integration result

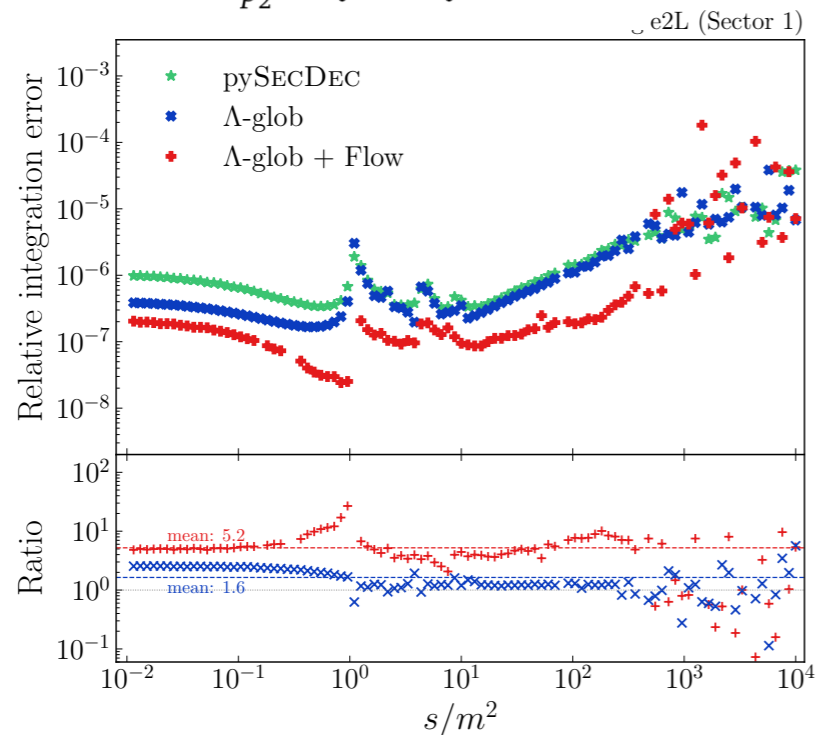
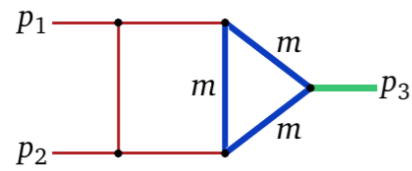
Neural Importance Sampling – Spin-Offs

Aim: Improve numerical evaluation of integral over Feynman parameters in multi-loop diagrams.

Method: Use Neural Importance Sampling to improve sampling

2-loop, one massive

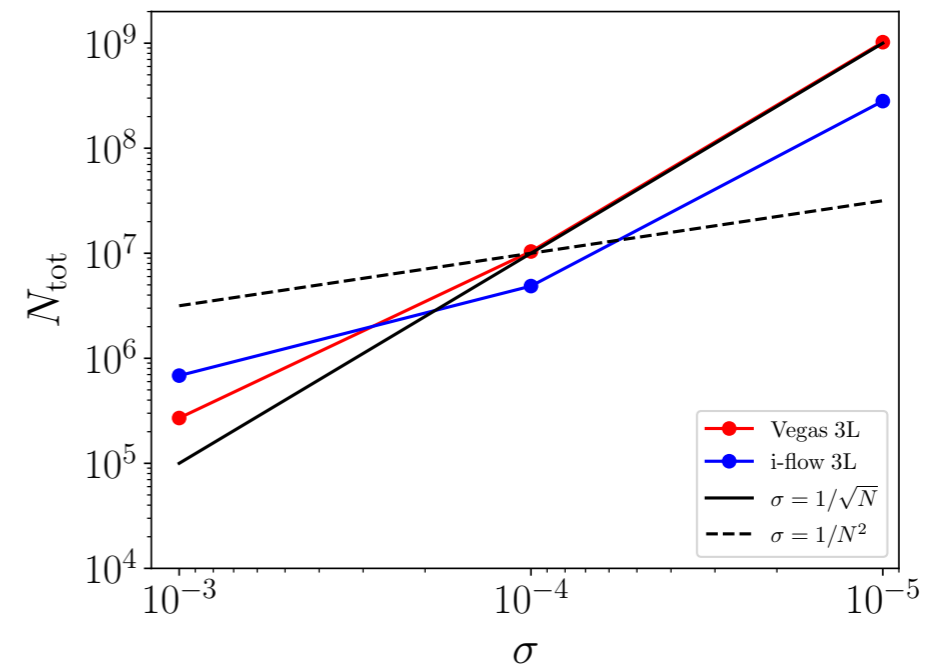
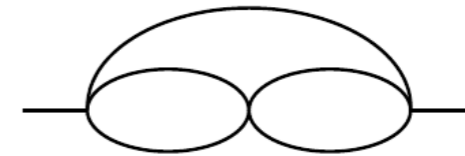
[Winterhalder et al., “Targeting multi-loop integrals with neural networks”, arXiv:2112.09145 [hep-ph]]



- 6 dimensions
- Achieve reduction of numerical uncertainties by 2–10x

1,2,3-loop binary dynamics in GR

[Jinno, Kälin, Liu and Rubira: “Machine Learning Post-Minkowskian Integrals”, arXiv:2209.01091 [hep-th]]



- 9 dimensions
- training phase included here
- Achieve precision target with less evaluations compared to VEGAS 2–3x

NN integration of multi-loop integrals

[Talk by D. Maître]

Related: application of Normalising Flows in Lattice Field Theory

[Talk by A. Singha]

More on integrating loops

[Plenary Talk by S. Badger, Talks by E. de Doncker, A. Butter]

Exploring Phase Space with Nested Sampling

[Yallup, Janßen, Schumann and Handley, Eur. Phys. J. C 82 (2022), 8]

- Transfer Bayesian inference algorithm to our sampling problem
 - applications in cosmology, statistical thermodynamics, material science
 - wide range of existing tools, e.g. PolyChord [Handley, Hobson and Lasenby]
- Consider uniform prior, posteriori matching target distribution
- aim: optimise rejection sampling efficiency ϵ , example $gg \rightarrow ng$:

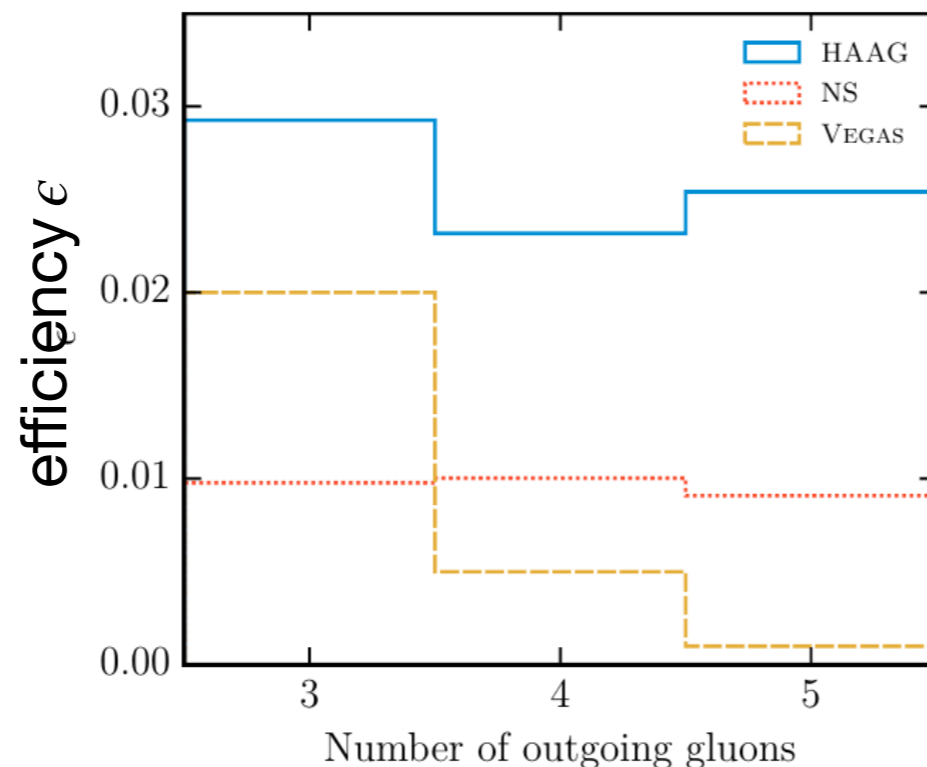
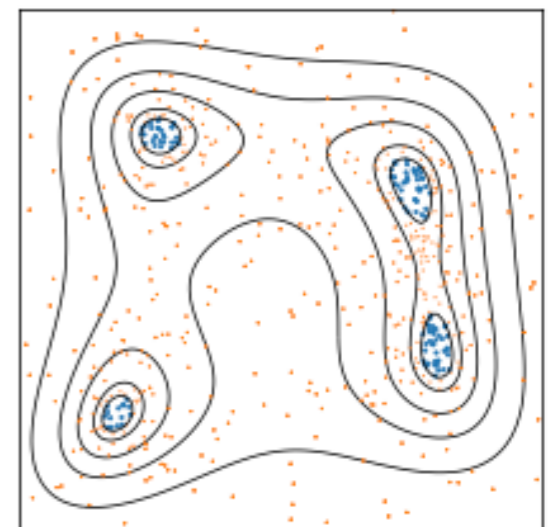
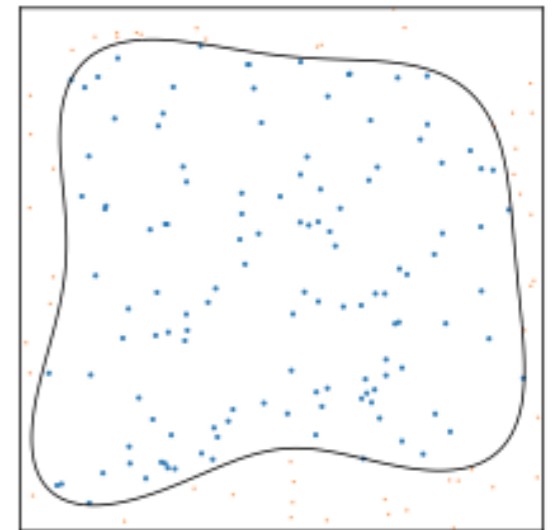
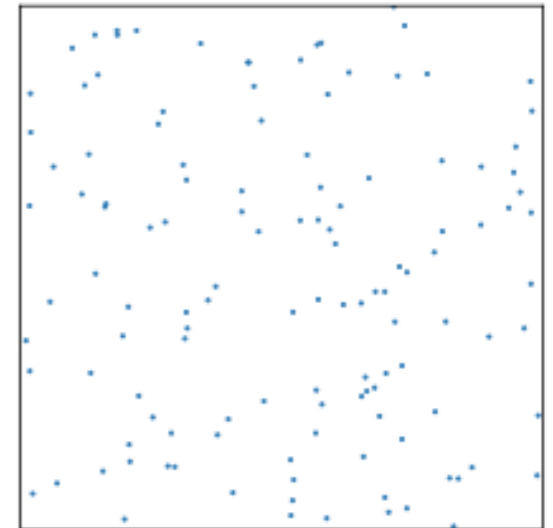


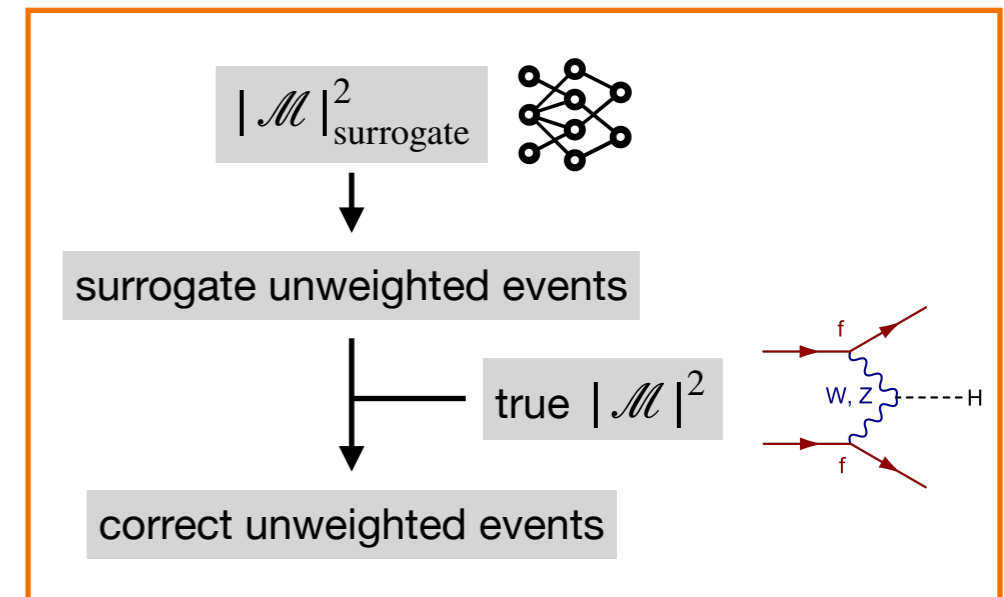
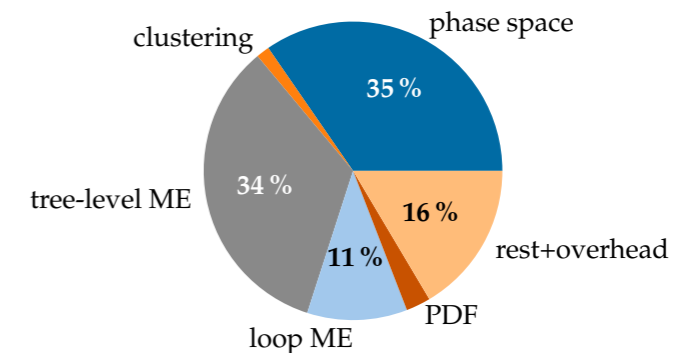
Illustration of Algorithm:



Active research on alternative approaches

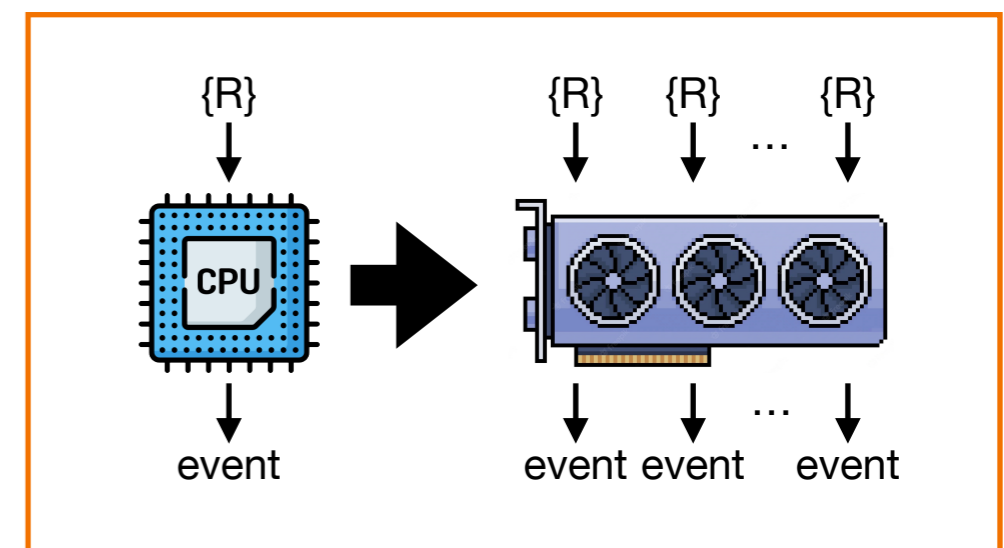
- live with low phase-space efficiency, but make $|\mathcal{M}|^2$ evaluation much faster
 - surrogate unweighting**
[Danziger et al. 2109.11964], [Talk by T. Janßen]
 - use integrand emulator for trial events
 - correct accepted events later to exact result by 2nd rejection step
 - emulation must be close to the real thing, but failure to do so only reduces gain factor
 - proof-of-concept: simple DNN gives **effective gain factors between 2 and 10**
 - provides use case for more sophisticated ME emulators
[Maître and Truong, JHEP 11 (2021), 066], [Aylett-Bullock, Badger and Moodie, JHEP 08 (2021), 066], [Badger et al., arXiv:2206.14831 [hep-ph]], [Janßen, Maître, Schumann, Siegert and Truong, *tbp soon*]

$$pp \rightarrow e^+e^- + 0,1,2j @ \text{NLO} + 3,4,5j @ \text{LO}$$



- Accelerated $|\mathcal{M}|^2$: GPU, Vector Engines, ...**

- madgraph4gpu
[Talk by A. Valassi]
- BlockGen
[Talks by M. Knobbe, T. Childers]



Conclusions

- **The Problem**

- LHC physics programme & computing demands efficient event generation, for signal and background processes
- Main event generator bottleneck identified:
 - Expensive (N)NLO ME and many-jets LO ME evaluations
 - Combined with inefficient phase-space sampling

- **Solutions** (active & explorative research!)

- Development and implementation of novel sampling algorithms
Neural Importance Sampling, Nested Sampling, ...
- Beyond toy examples, traditional approaches not so easy to beat
- Many more ideas (see previous slide)
surrogate NN models, faster (GPU-accelerated) ME, ...

- **Interdisciplinary relevance**

for range of integration/sampling problems

- Cross talk to many other fields
ML, Lattice FT, cosmo, industry, ...

