

FLAVOUR TAGGING WITH THE ATLAS DETECTOR AT THE HL-LHC

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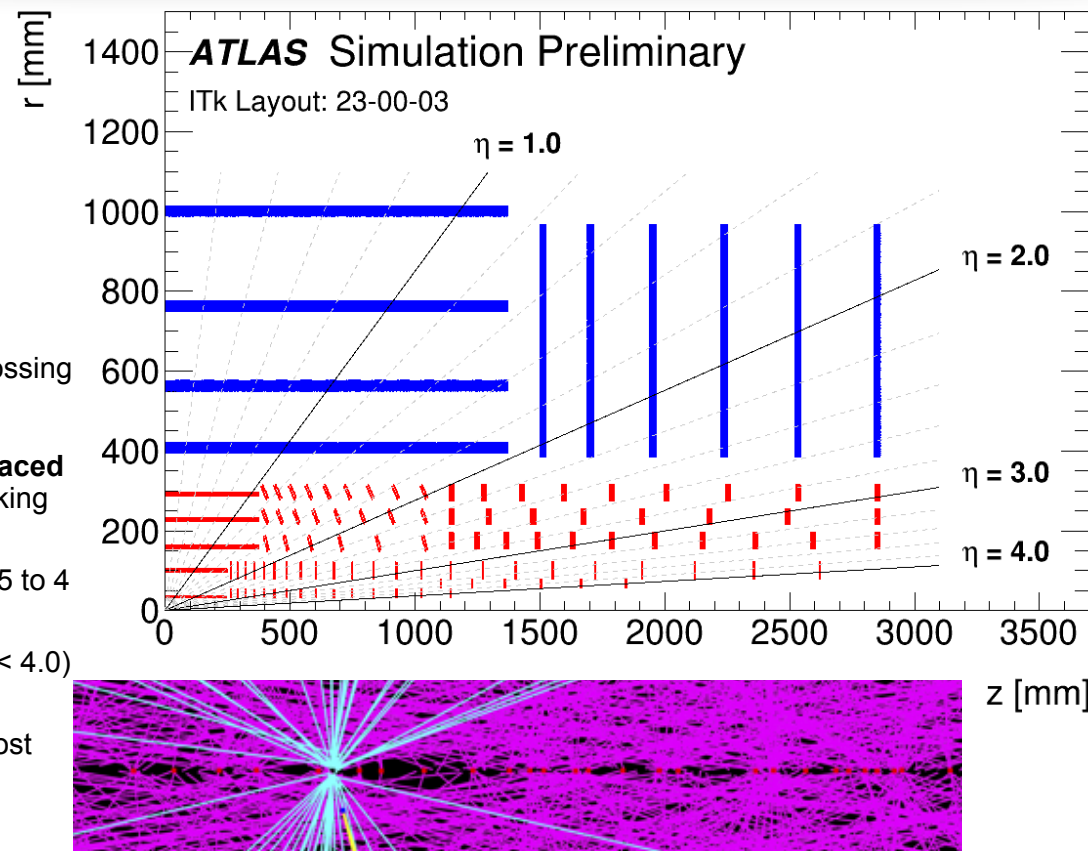
High-Luminosity Large Hadron Collider (HL-LHC)

Benefits and Challenges

- ✓ Increased instantaneous luminosity up to $7.5 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$
- ✓ Larger integrated luminosity; 10x more data than what is collected during Run 1-3
- ✗ More pile-up; ~200 interactions per bunch crossing

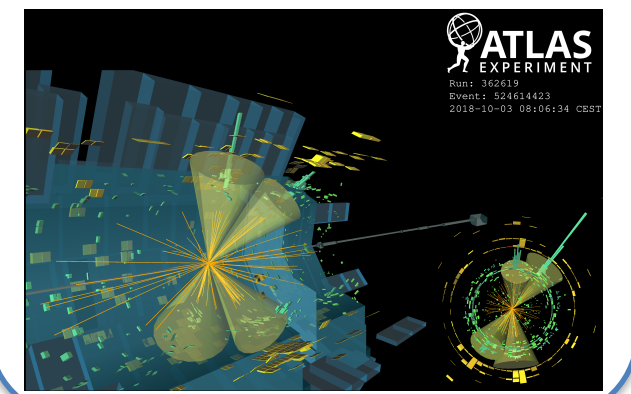
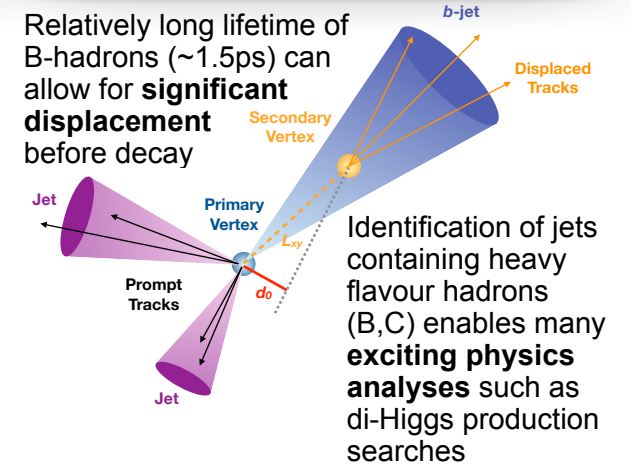
Inner Tracker (ITk) Upgrade

- Current ATLAS Inner Detector (ID) will be **replaced by a new Inner Tracker (ITk)** to maintain tracking performance in harsh HL-LHC conditions
- Extended forward pseudo-rapidity ($|\eta|$) from 2.5 to 4 provides **increased tracking acceptance**
- All-silicon design consisting of inner **pixel** ($|\eta| < 4.0$) and outer **strip** ($|\eta| < 2.7$) sub-detectors
- Latest ITk layout design 23-00-03 with innermost pixel layer closer to beam pipe ($R = 34\text{mm}$)



Flavour Tagging

Relatively long lifetime of B-hadrons (~1.5ps) can allow for **significant displacement** before decay



Flavour Tagging Algorithms

Jet Input

p_T
 η

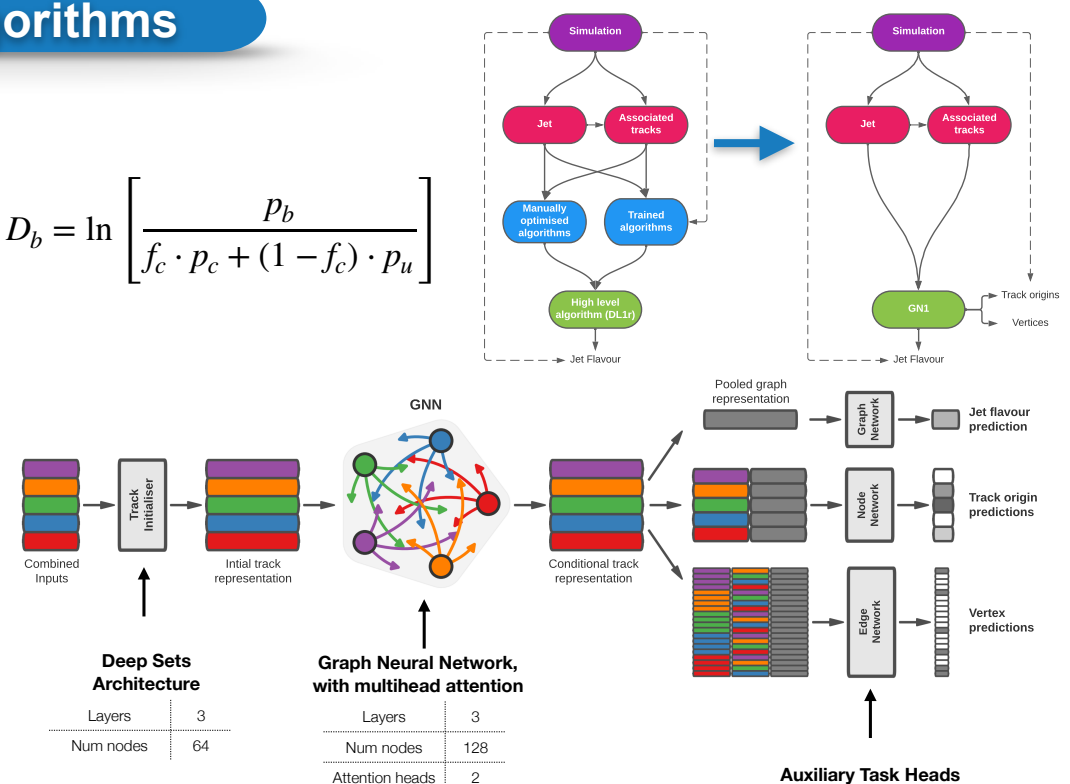
Track Input

q/p
 $d\eta$
 $d\phi$
 d_0
 $z_0 \sin \theta$
 $\sigma(q/p)$
 $\sigma(\theta)$
 $\sigma(\phi)$
 $s(d_0)$
 $s(z_0 \sin \theta)$
nPixHits
nStripHits
nInnermostPixHits
nNextToInnermostPixHits
nInnermostPixShared
nInnermostPixSplit
nPixShared
nPixSplit
nStripShared
nPixHoles
nStripHoles

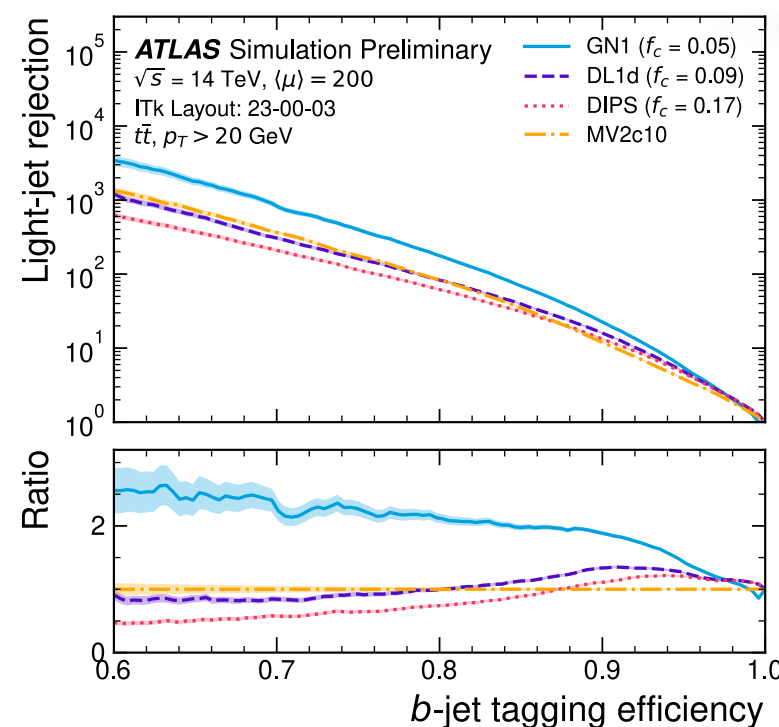
- Previous flavour tagging algorithms relied on “two-tiered” approach, where the outputs from manually optimised low-level taggers were fed into high-level taggers
- New approach based on graph neural networks (GNNs): **no need for manually optimised low-level algorithms!**
- GN1 trains jet flavour, vertexing, and track origin tasks **simultaneously**
- Single algorithm is easy to maintain and tune for specific use-cases, e.g. high- p_T flavour tagging
- Naturally suited for variable number of unordered input tracks

Requirements	Pseudorapidity interval		
	$ \eta < 2.0$	$2.0 < \eta < 2.6$	$2.6 < \eta < 4.0$
pixel + strip hits	≥ 9	≥ 8	≥ 7
pixel hits	≥ 1	≥ 1	≥ 1
pixel + strip holes	≤ 2	≤ 2	≤ 2
p_T [MeV]	> 900	> 500	> 500
$ d_0 $ [mm]	≤ 2.0	≤ 2.0	≤ 3.5
$ z_0 \sin \theta $ [mm]	≤ 5.0	≤ 5.0	≤ 5.0

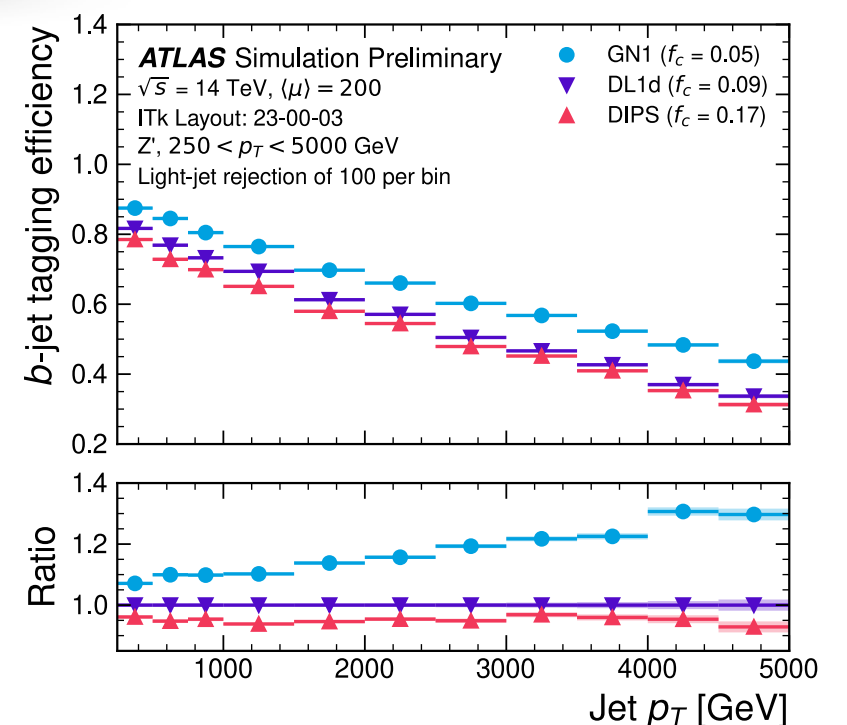
$$D_b = \ln \left[\frac{p_b}{f_c \cdot p_c + (1 - f_c) \cdot p_u} \right]$$



Expected Performance



- Previous generation of taggers used for comparison: MV2c10 (Boosted Decision Tree), DIPS (Deep Sets), DL1d (Deep Neural Network)
- GN1 all-in-one tagger **outperforms current taggers** over a broad range of phase space and provides excellent performance in the harsh HL-LHC environment
- Limited statistics for HL-LHC training (4M jets vs. 30M jets used for baseline model); **expect further improvements** with enlarged training dataset
- 2x improvement in light-jet rejection for the 70% $t\bar{t}$ working point compared to previous taggers
- GN1 improves flavour tagging performance in all regions of phase space, including the high p_T regime



Summary & Outlook

- GN1 flavour tagging algorithm provides excellent flavour tagging performance in the harsh HL-LHC environment
- Training procedure used for current detector configuration easily adapted to ITk geometry and increased tracking acceptance
- Next generation of flavour tagging algorithms will include updated architecture, optimized training, and enlarged training dataset

References



- [ATL-PHYS-PUB-2022-027](#)
- [ATL-PHYS-PUB-2022-047](#)
- [TRIG-2018-08](#)
- [ATLAS-CONF-2022-035](#)