

# SCETlib Updated Level 3 Results.

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in collaboration with  
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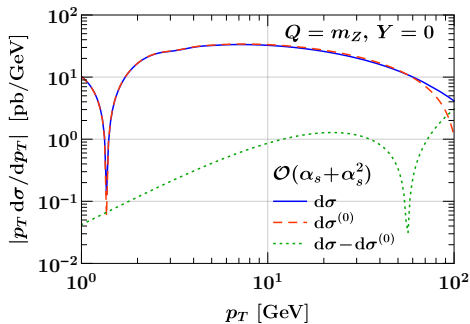
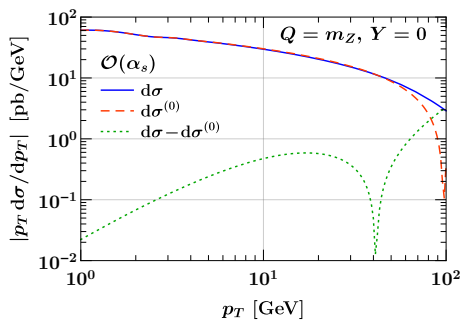


# Matching to Fixed Order.

$$d\sigma = \underbrace{d\sigma^{(0)}(\mu_H, \mu_B, \nu_B, \mu_f, \mu_S, \nu_S)}_{\equiv d\sigma^{\text{resum}}} + \underbrace{[d\sigma^{\text{FO}}(\mu_{\text{FO}}) - d\sigma^{(0)}(\mu_i, \nu_i \equiv \mu_{\text{FO}})]}_{\equiv d\sigma^{\text{nons}}}$$

- $\sigma^{\text{resum}}$  and  $\sigma^{\text{nons}}$  are *separately* scale independent (args show residual dep.)
  - ▶ In particular,  $d\sigma^{\text{nons}}$  *does not* depend on resummation scales and does not affect uncertainties of  $d\sigma^{\text{resum}}$
- For  $p_T \rightarrow Q$ :  $d\sigma^{\text{resum}} \rightarrow d\sigma^{(0)}$ 
  - ▶ Reproduces  $d\sigma^{\text{FO}}$  *exactly* at any given order (i.e. resummation should not induce any rogue higher-order corrections, because in general they would be unphysical and can be arbitrarily large)
  - ▶ Achieved by using profile scales:  $\mu_i(p_T), \nu_i(p_T) \rightarrow \mu_{\text{FO}}$  for  $p_T \rightarrow Q$  which smoothly and intrinsically turn off resummation
- Relation to benchmark levels
  - ▶ Level 1:  $d\sigma^{\text{resum}}$  (canonical scales)
  - ▶ Level 2:  $d\sigma^{\text{resum}}$  (profile scales)
  - ▶ Level 3:  $d\sigma^{\text{resum}}$  (profile scales) +  $d\sigma^{\text{nons}}(\mu_{\text{FO}})$

# Check against FO results from DYTurbo.



- Full  $d\sigma$  from DYTurbo
- Singular  $d\sigma^{(0)}$  from SCETlib
  - ▶  $p_T d\sigma^{(0)}/dp_T \sim \ln^n p_T + \text{const}$  → grows/constant on log-log plot
- Nonsingular  $d\sigma - d\sigma^{(0)}$  is indeed power-suppressed
  - ▶  $p_T d\sigma^{\text{nons}}/dp_T \sim p_T^2$  → must vanish with negative slope on log-log plot
  - ▶ Strong check and best (only) way to identify (small) mismatches

# Profile Scales and Perturbative Uncertainties.

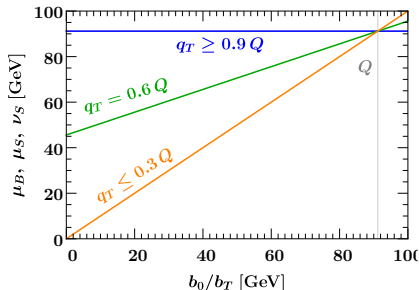
$$\mu_H = \nu_B = \mu_{\text{FO}} = Q$$

$$\mu_B, \mu_S, \nu_S = \mu_{\text{FO}} f_{\text{prof}} \left[ \frac{p_T}{Q}, \frac{1}{Q} \mu_* \left( \frac{b_0}{b_T}, \mu_i^{\text{min}} \right) \right] \begin{cases} = b_0/b_T & p_T \ll Q \\ \rightarrow \mu_{\text{FO}} \equiv \mu_R & p_T \rightarrow Q \end{cases}$$

$$\mu_f = \mu_F f_{\text{run}} \left[ \frac{p_T}{Q}, \frac{1}{Q} \mu_* \left( \frac{b_0}{b_T}, \mu_f^{\text{min}} \right) \right] \begin{cases} = b_0/b_T & p_T \ll Q \\ \rightarrow \mu_F & p_T \rightarrow Q \end{cases}$$

$f_{\text{prof}}$  steers transition from resummation on  $\rightarrow$  resummation off

- Turn-off for  $p_T \rightarrow Q$  does not alter canonical res. at  $p_T \ll Q$ 
  - ▶ Transition driven by  $p_T/Q$   
( $b_T$  is just means to an end, we want to predict physical  $p_T$  spectrum not the  $b_T$  spectrum)
  - ▶ Transition points are based on relative size of leading-power vs. nonsingular (power) corrections
  - ▶ Their variation yields  $\Delta_{\text{match}}$



# Profile Scales and Perturbative Uncertainties.

$$\mu_H = \nu_B = \mu_{FO} = Q$$

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$$\mu_f = \mu_F f_{\text{run}} \left[ \frac{p_T}{Q}, \frac{1}{Q} \mu_* \left( \frac{b_0}{b_T}, \mu_f^{\text{min}} \right) \right] \begin{cases} = b_0/b_T & p_T \ll Q \\ \rightarrow \mu_F & p_T \rightarrow Q \end{cases}$$

Nonpert. cutoff prescription for  $b_0/b_T \lesssim 1 \text{ GeV}$  (freeze-out, local  $b^*$ , global  $b^*$ )

- New: Dedicated  $\mu_*$  prescription

- ▶ Similar to local  $b^*$  except each scale has its own cutoff

$$\begin{aligned} \mu_B^{\text{min}} = \mu_S^{\text{min}} &= 1 \text{ GeV} && \text{(min scale appearing in } \alpha_s \text{),} \\ \nu_S^{\text{min}} &= 0 && \text{(no cutoff needed for rapidity scale),} \\ \mu_f^{\text{min}} &= 1.65 \text{ GeV} && \text{(min scale of PDF, use } Q_0 \text{ of NNPDF3.1)} \end{aligned}$$

- ▶ And cutoffs are maintained (kept unchanged) under any scale variations

# Profile Scales and Perturbative Uncertainties.

$$\mu_H = \nu_B = \mu_{FO} = Q$$

$$\mu_B, \mu_S, \nu_S = \mu_{FO} f_{\text{prof}} \left[ \frac{p_T}{Q}, \frac{1}{Q} \mu_* \left( \frac{b_0}{b_T}, \mu_i^{\text{min}} \right) \right] \begin{cases} = b_0/b_T & p_T \ll Q \\ \rightarrow \mu_{FO} \equiv \mu_R & p_T \rightarrow Q \end{cases}$$

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## Perturbative uncertainties via scale variations

- "Fixed-order"  $\Delta_{FO}$ : Max envelope of varying  $\mu_{FO}$  by factor of 2
  - ▶ Keeps all resummed scale ratios invariant, hence the name
  - ▶ Transitions into  $\mu_R$  variation for  $p_T \rightarrow Q$
- "Resummation"  $\Delta_{\text{resum}}$ : Max envelope of varying  $\mu_B, \nu_B, \mu_S, \nu_S$ 
  - ▶ 36 combinations that all possible scale ratios get probed and changed by factor 2 (but not 4) for  $p_T \ll Q$  without changing  $p_T \rightarrow Q$

# Profile Scales and Perturbative Uncertainties.

$$\mu_H = \nu_B = \mu_{FO} = Q$$

$$\mu_B, \mu_S, \nu_S = \mu_{FO} f_{\text{prof}} \left[ \frac{p_T}{Q}, \frac{1}{Q} \mu_* \left( \frac{b_0}{b_T}, \mu_i^{\min} \right) \right] \begin{cases} = b_0/b_T & p_T \ll Q \\ \rightarrow \mu_{FO} \equiv \mu_R & p_T \rightarrow Q \end{cases}$$

$$\mu_f = \mu_F f_{\text{run}} \left[ \frac{p_T}{Q}, \frac{1}{Q} \mu_* \left( \frac{b_0}{b_T}, \mu_f^{\min} \right) \right] \begin{cases} = b_0/b_T & p_T \ll Q \\ \rightarrow \mu_F & p_T \rightarrow Q \end{cases}$$

## Perturbative uncertainties via scale variations

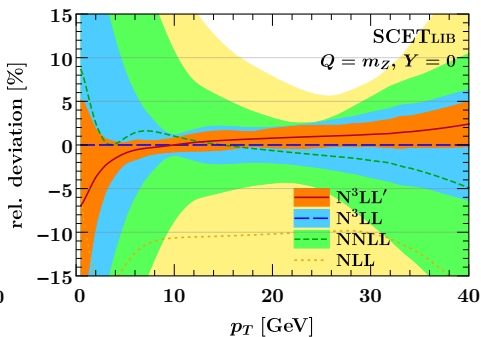
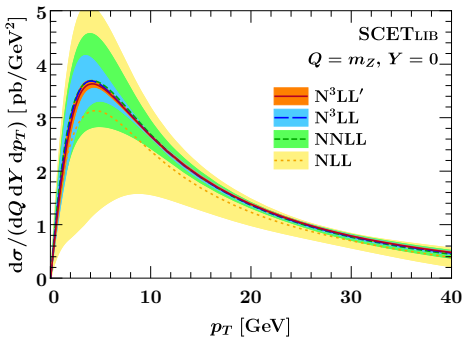
- “PDF/DGLAP”  $\Delta_f$ : Max envelope of varying  $\mu_f$  by factor of 2
  - ▶ Probes unc. due to universal DGLAP evolution (at actual PDF scale)
  - ▶ Explicitly separated out now (was previously tied to  $\mu_B$ )
    - Together with  $\mu_f^{\min}$  largely avoids previously seen unphysical oscillations
  - ▶ Transitions into  $\mu_F$  variation for  $p_T \rightarrow Q$
  - ▶ Note: This leads to adding in quadrature separate max-envelopes of  $\mu_F$  and  $\mu_R$  variations also in FO limit
    - Actually the more sensible thing to do than usual envelope of 7-point variations



# Nonperturbative Uncertainties (preliminary).

- Previously: Via simple cutoff variations, crude and not ideal
  - ▶ Relies on size of leftover, unresummed perturbative logs
  - ▶ Directly depends on perturbative order
- New: Use a basic nonperturbative model
  - ▶ Switch to quartic  $\mu_*$  prescription  $\mu_*(\mu, \mu_{\min}) = (\mu^4 + \mu_{\min}^4)^{1/4}$ 
    - Avoids inducing artificial quadratic OPE coefficient
    - [see e.g. Scimemi, Vladimirov arXiv:1609.06047; Ebert, Michel, Stewart, Sun arXiv:2201.07237]
  - ▶ Otherwise current central-value predictions are not affected (i.e. model is turned off at central parameter values)
  - ▶ Use reasonably generous model parameter variations to estimate  $\Delta_{\text{np}}$

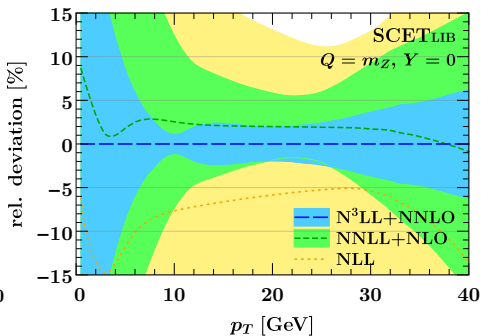
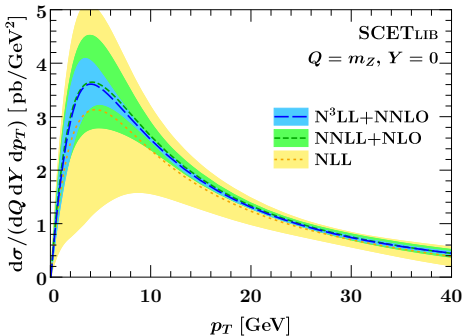
## Level 2



- Excellent coverage/convergence (except in pure FO region)

- Here: Total uncertainty =  $\sqrt{\Delta_{\text{FO}}^2 + \Delta_f^2 + \Delta_{\text{resum}}^2 + \Delta_{\text{match}}^2}$

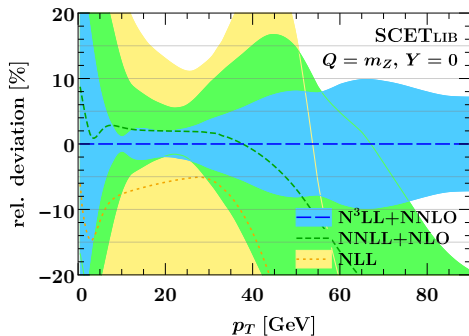
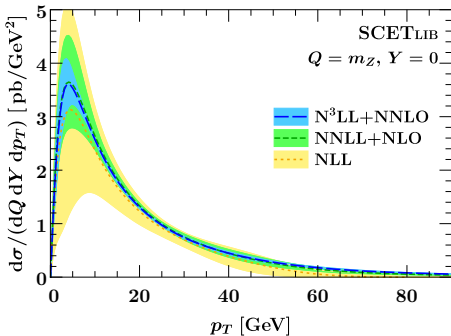
## Level 3



- Excellent coverage/convergence (except in pure FO region)

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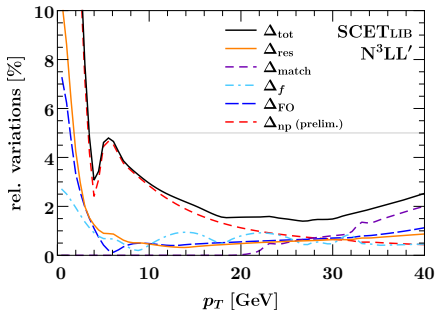
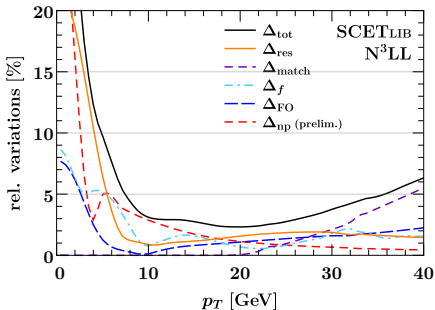
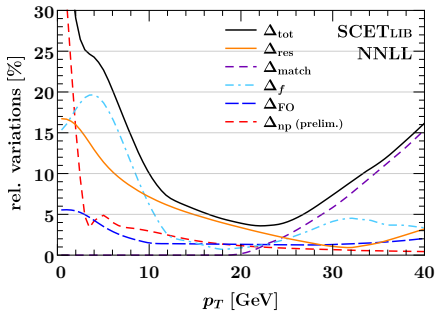
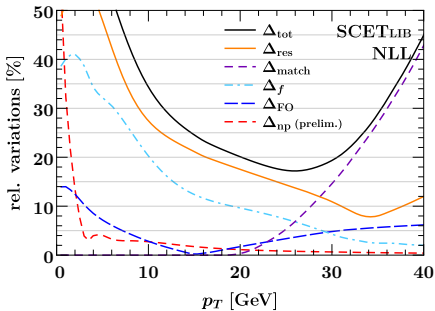
## Level 3 (wide)



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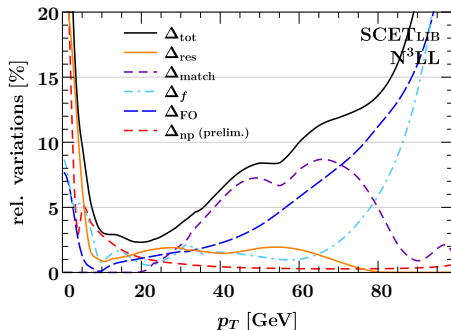
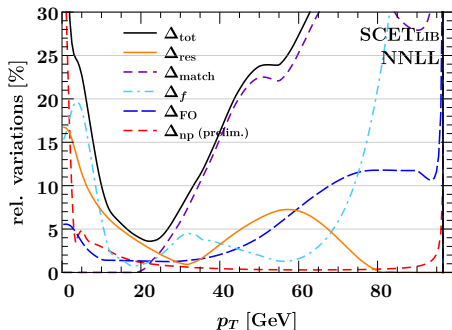
- Here: Total uncertainty =  $\sqrt{\Delta_{\text{FO}}^2 + \Delta_f^2 + \Delta_{\text{resum}}^2 + \Delta_{\text{match}}^2}$

# Breakdown of Uncertainties: Level 2.



# Breakdown of Uncertainties: Level 2 $\rightarrow$ Level 3.

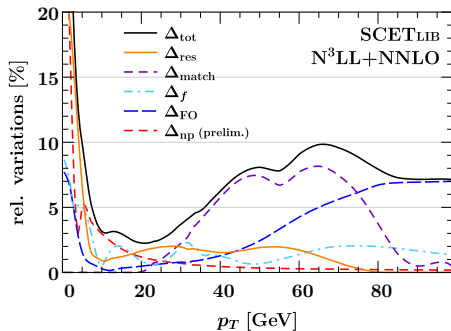
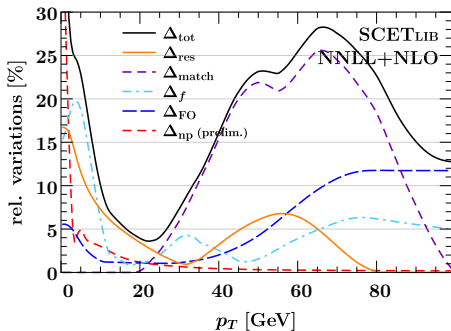
## Level 2 (wide)



- Matching only affects uncertainties beyond  $p_T \gtrsim 50$  GeV (as it should)

# Breakdown of Uncertainties: Level 2 $\rightarrow$ Level 3.

## Level 3 (wide)



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Additional Slides



# Factorization and Resummation at Leading Power.

Leading-power terms factorize into **hard**, **collinear**, and **soft** contributions

(with  $Q \equiv \sqrt{q^2}$  and  $x_{a,b} \equiv (Q/E_{\text{cm}})e^{\pm Y}$ )

$$\frac{d\sigma^{(0)}}{dQ dY dp_T^2} = \sum_{a,b} H_{ab}(Q^2, \mu) \times [B_a B_b S](Q^2, x_a, x_b, \vec{p}_T, \mu)$$

$$[B_a B_b S] = \int d^2\vec{k}_a d^2\vec{k}_b d^2\vec{k}_s \delta^{(2)}(\vec{p}_T - \vec{k}_a - \vec{k}_b - \vec{k}_s) \\ \times B_a(x_a, \vec{k}_a, \mu, \nu/Q) B_b(x_b, \vec{k}_b, \mu, \nu/Q) S(\vec{k}_s, \mu, \nu)$$

- Most general forms with no hard-coded choices yet (and completely equivalent)

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$$\begin{aligned} [B_a B_b S] &= \int d^2\vec{k}_a d^2\vec{k}_b d^2\vec{k}_s \delta^{(2)}(\vec{p}_T - \vec{k}_a - \vec{k}_b - \vec{k}_s) \\ &\quad \times B_a(x_a, \vec{k}_a, \mu, \nu/Q) B_b(x_b, \vec{k}_b, \mu, \nu/Q) S(\vec{k}_s, \mu, \nu) \\ &\equiv \int \frac{d^2\vec{b}_T}{(2\pi)^2} e^{i\vec{b}_T \cdot \vec{p}_T} \tilde{B}_a(x_a, b_T, \mu, \nu/Q) \tilde{B}_b(x_b, b_T, \mu, \nu/Q) \tilde{S}(b_T, \mu, \nu) \\ &\equiv \int \frac{d^2\vec{b}_T}{(2\pi)^2} e^{i\vec{b}_T \cdot \vec{p}_T} \tilde{f}_a(x_a, b_T, \mu, \zeta_a) \tilde{f}_b(x_b, b_T, \mu, \zeta_b) \end{aligned}$$

(where  $\zeta_{a,b} \propto \omega_{a,b}^2$  with  $\zeta_a \zeta_b = Q^4$  plays the role of  $\nu$ )

- Most general forms with no hard-coded choices yet (and completely equivalent)

# Schematic Resummation Structure.

$$d\sigma^{(0)} = H(Q, \mu) \times B(p_T, \mu, \nu/Q)^2 \otimes S(p_T, \mu, \nu/p_T)$$

$$\ln^2 \frac{p_T}{Q} = 2 \ln^2 \frac{Q}{\mu} + 2 \ln \frac{p_T}{\mu} \ln \frac{\nu}{Q} + \ln \frac{p_T}{\mu} \ln \frac{\mu p_T}{\nu^2}$$

- For generic  $\mu, \nu$ , each function contains (potentially large) logs
- Resummation follows from solving RGEs, and evolving each function from some starting scales  $\mu_i, \nu_i$  to common arbitrary  $\mu, \nu$

$$H(\mu) = H(\mu_H) \times U_H(\mu_H, \mu)$$

$$B(\mu, \nu) = B(\mu_B, \nu_B) \otimes U_B(\mu_B, \nu_B; \mu, \nu)$$

$$S(\mu, \nu) = S(\mu_S, \nu_S) \otimes U_B(\mu_S, \nu_S; \mu, \nu)$$

- ▶ Dependence on overall arbitrary  $\mu, \nu$  cancels *exactly at each order* (it must do so = RGE consistency or path independence)
- ▶ This is *not* SCET specific, it is exactly how CSS formula arises from solution of Collins-Soper equation

# Schematic Resummation Structure.

$$d\sigma^{(0)} = H(\mu_H) \times U_H(\mu_H, \mu) \times [B(\mu_B, \nu_B) \otimes U_B(\mu_B, \nu_B; \mu, \nu)]^2 \\ \otimes S(\mu_S, \nu_S) \otimes U_B(\mu_S, \nu_S; \mu, \nu)$$

- Boundary conditions  $H(\mu_H)$ ,  $B(\mu_B, \nu_B)$ ,  $S(\mu_S, \nu_S)$  can (must) be calculated in (log-free) fixed order, so at

$$\mu_H \sim Q$$

$$\mu_B \sim p_T, \quad \nu_B \sim Q$$

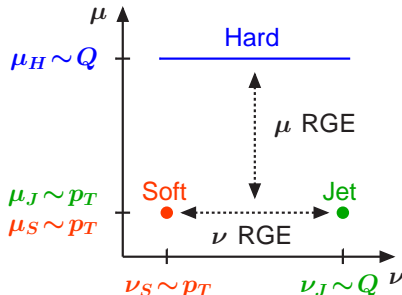
$$\mu_S \sim p_T, \quad \nu_S \sim p_T$$

- RGE then really sums logs of ratios

$$\ln \frac{\mu_B}{\mu_H} \sim \ln \frac{\mu_S}{\mu_H} \sim \ln \frac{\nu_S}{\nu_B} \sim \ln \frac{p_T}{Q}$$

- Choice of boundary scales does matter

- ▶ Determine precise form of resummed logarithms (“resummation” scales)
- ▶ Their dependence *only cancels to the fixed order* of the boundary conditions



- Solving the complete RGE system for  $p_T$  distribution is (surprisingly) difficult
  - ▶ Exact distributional solution in  $\vec{p}_T$  space is equivalent (up to different boundary terms) to solving RGE in  $b_T$  space with *canonical*  $b_T$  scales ( $b_0 = 2e^{-\gamma_E}$ )

$$\mu_H = Q, \quad \mu_B = b_0/b_T, \quad \nu_B = Q, \quad \mu_S = \mu_\nu = \nu_S = b_0/b_T$$

- ▶ Quite nontrivial statement, proven in [Ebert, FT; 1611.08610]
- ▶ This corresponds to canonical logs (level 1)
- Once canonical scales are inserted, the dependence on  $\mu_i, \nu_i$  “disappears”
  - ▶ But important to remember that this was a choice
  - ▶ Typical CSS implementations are (roughly) equivalent to only retaining  $\mu_H$  dependence  
(In addition,  $\mu_R$  is reintroduced by reexpanding  $\alpha_s(\mu_H)$  in terms of  $\alpha_s(\mu_R)$ , which typically leads to violating RGE consistency unless  $\mu_H = \mu_R$ )

# Complete RGE System.

In virtuality scale  $\mu$

$$\mu \frac{dH(Q, \mu)}{d\mu} = \gamma_H(Q, \mu) H(Q, \mu)$$

$$\mu \frac{dB(\vec{p}_T, \mu, \nu)}{d\mu} = \gamma_B(\mu, \nu) B(\vec{p}_T, \mu, \nu)$$

$$\mu \frac{dS(\vec{p}_T, \mu, \nu)}{d\mu} = \gamma_S(\mu, \nu) S(\vec{p}_T, \mu, \nu)$$

and rapidity scale  $\nu$

$$\nu \frac{dB(\vec{p}_T, \mu, \nu)}{d\nu} = -\frac{1}{2} \int d^2\vec{k}_T \gamma_\nu(\vec{k}_T, \mu) B(\vec{p}_T - \vec{k}_T, \mu, \nu)$$

$$\nu \frac{dS(\vec{p}_T, \mu, \nu)}{d\nu} = \int d^2\vec{k}_T \gamma_\nu(\vec{k}_T, \mu) S(\vec{p}_T - \vec{k}_T, \mu, \nu)$$

$$\mu \frac{d}{d\mu} \gamma_\nu(\vec{k}_T, \mu) = \nu \frac{d}{d\nu} \gamma_S(\mu, \nu) \delta(\vec{k}_T) = -4\Gamma_{\text{cusp}}[\alpha_s(\mu)] \delta(\vec{k}_T)$$

- plus evolution equations for  $\alpha_s(\mu)$  and PDFs( $\mu$ )
- plus consistency relations between different anomalous dimensions  $\gamma_i$  which encode RGE consistency