

Introduction to Machine Learning in Astroparticle Physics

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Motivation



Von Banffy - Eigenes Werk, CC BY-SA 3.0,
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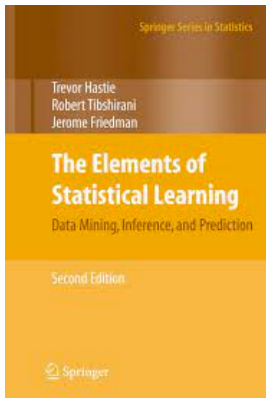
Machine Learning provides tools to accomplish an analysis task faster and more accurately (when used correctly).



Source: Von smial (talk) - Eigenes Werk, FAL,
<https://commons.wikimedia.org/w/index.php?curid=6028669>

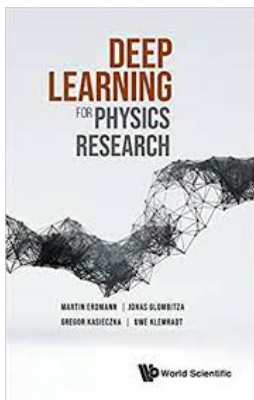


Further Reading



- General Introduction to Statistical Learning
- Good start to get an overview
- A lot of extra material: <https://hastie.su.domains/ElemStatLearn/>
- (I believe you can also download the pdf there...)

Source: <https://hastie.su.domains/ElemStatLearn/>

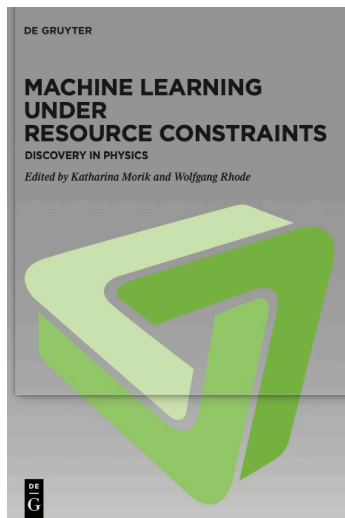


- Focus on Deep Learning and Neural Networks
- Nice pedagogic approach

Source: amazon



Further Reading



- Focus on astroparticle and particle physics
- Contains a lot of topics also covered in this talk
- Open access
- To be published by the end of 2022



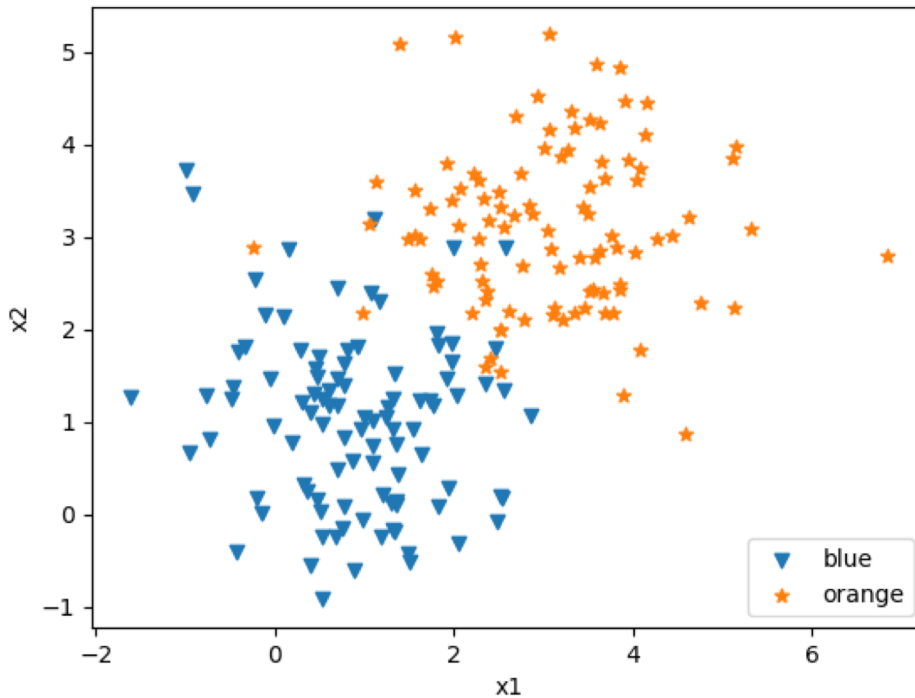
Source: Von The scikit-learn developers - github.com/scikit-learn/scikit-learn/blob/master/doc/logos/scikit-learn-logo.svg, BSD,
<https://commons.wikimedia.org/w/index.php?curid=71445288>

Outline

- Nomenclature and stuff
- Feature Selection
- Selected Algorithms
- Neural Networks and Deep Learning



Nomenclature



N (\vec{X}, y) pairs are referred to as training set
Or annotated data

Events (Examples) are characterized by a feature vector:

$$\vec{X} = (x_1 \dots x_n)$$

In this example

$$\vec{X} = (x_1, x_2)$$

And a class variable

$$y \in [y_1 \dots y_n]$$

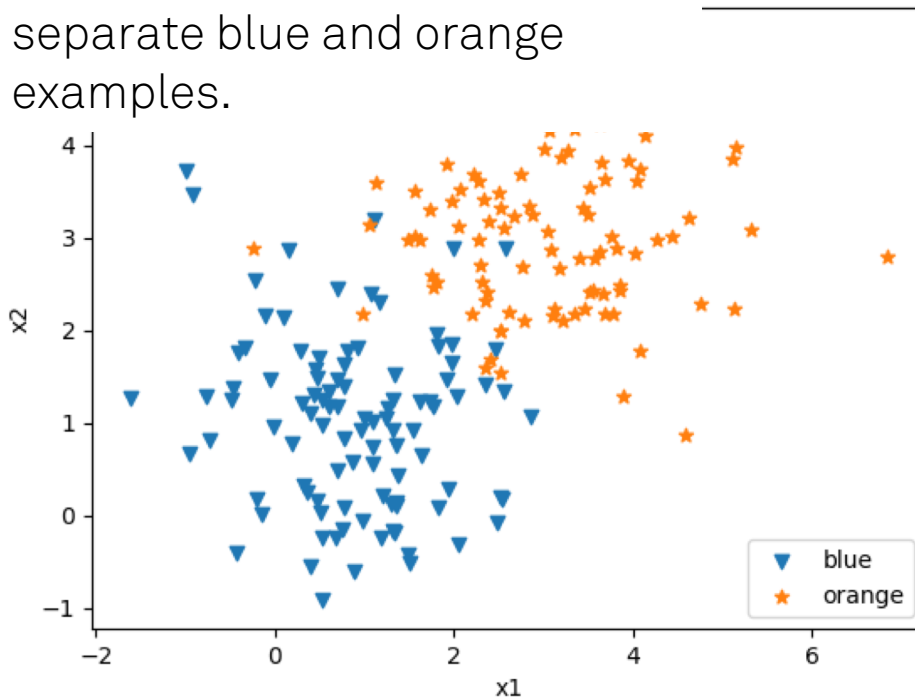
In this example

$$y \in [blue, orange]$$



Nomenclature

Task: Build a model to separate blue and orange examples.



Events (Examples) are characterized by a feature vector:

$$\vec{X} = (x_1 \dots x_n)$$

In this example

$$\vec{X} = (x_1, x_2)$$

And a class variable

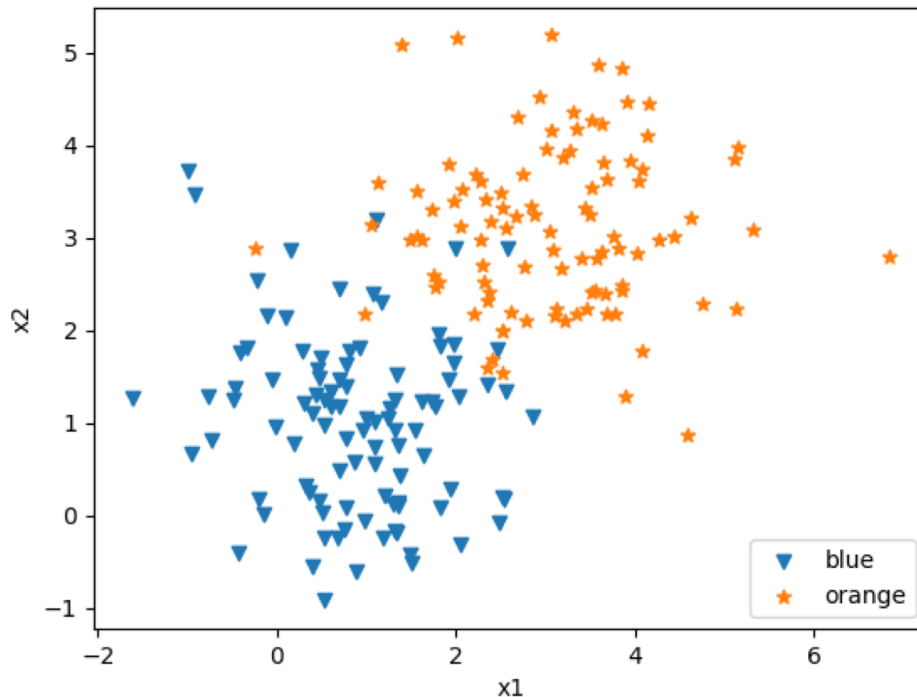
$$y \in [y_1 \dots y_n]$$

In this example

$$y \in [blue, orange]$$



The Linear Model



$$\hat{y} = \beta_0 + \sum_{i=1}^p x_i \beta_i$$

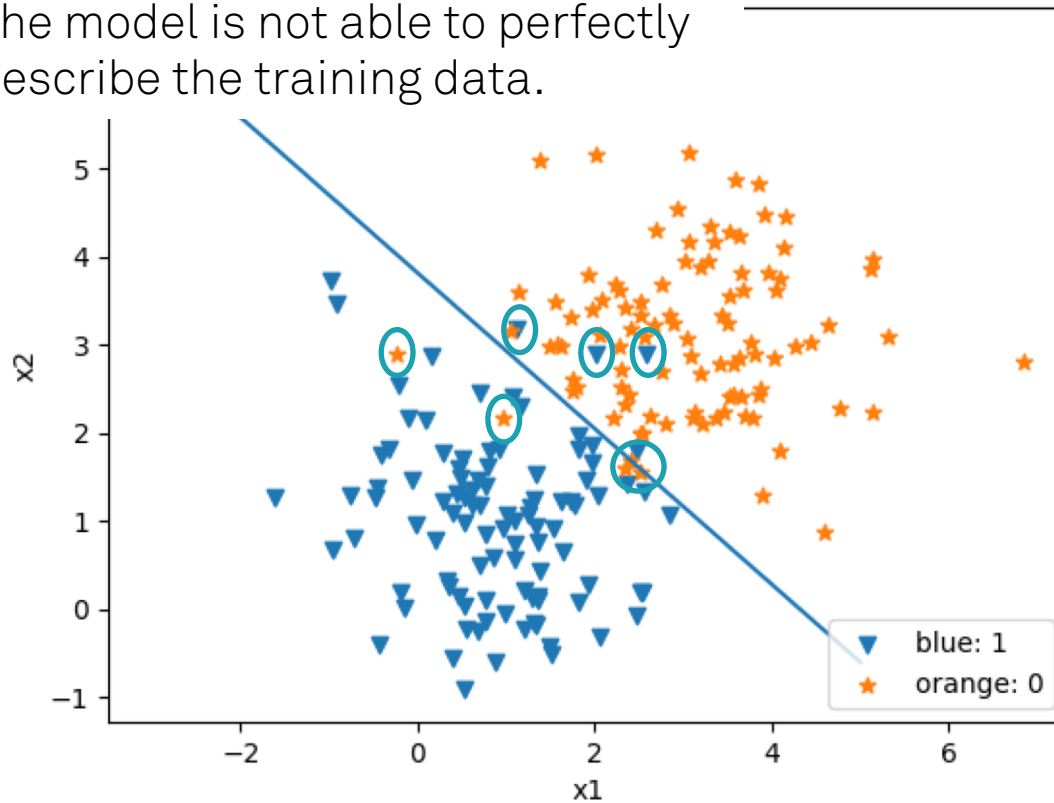
$$\hat{y} = \begin{cases} \text{orange: } 0 \\ \text{blue: } 1 \end{cases}$$

Solve e.g. by least squares fit



The Linear Model: Graphical Representation of the Model

The model is not able to perfectly describe the training data.

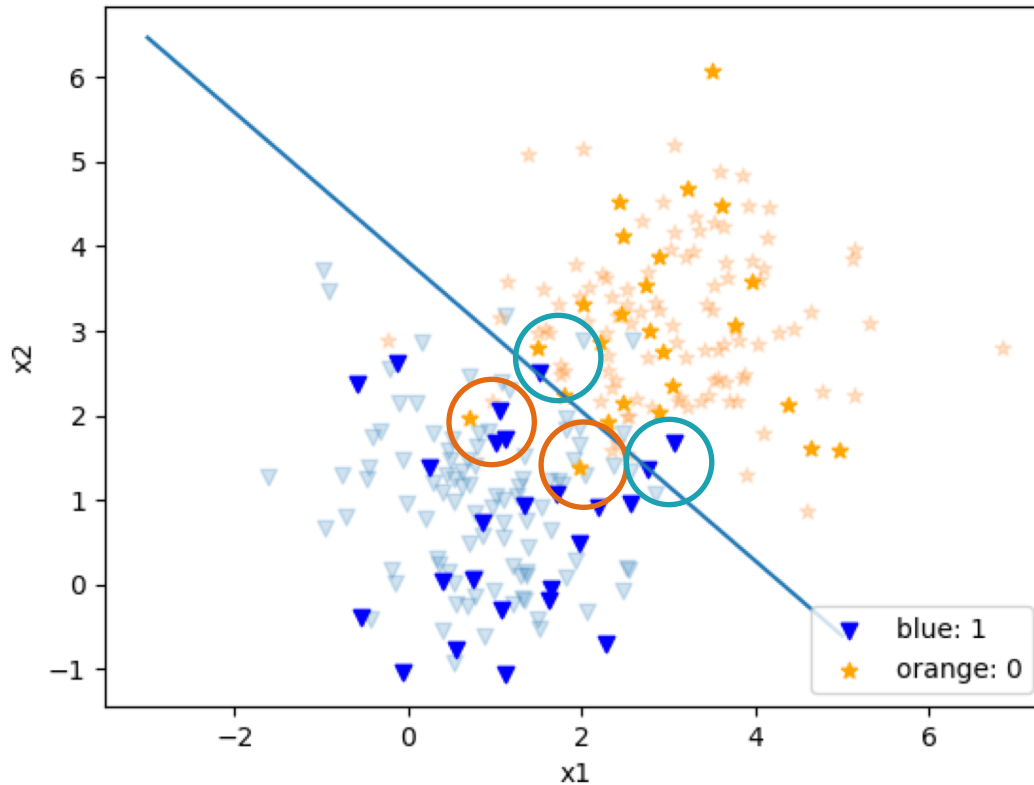


Above line:
Classify as orange

Below line:
Classify as blue



Application to Unseen Data

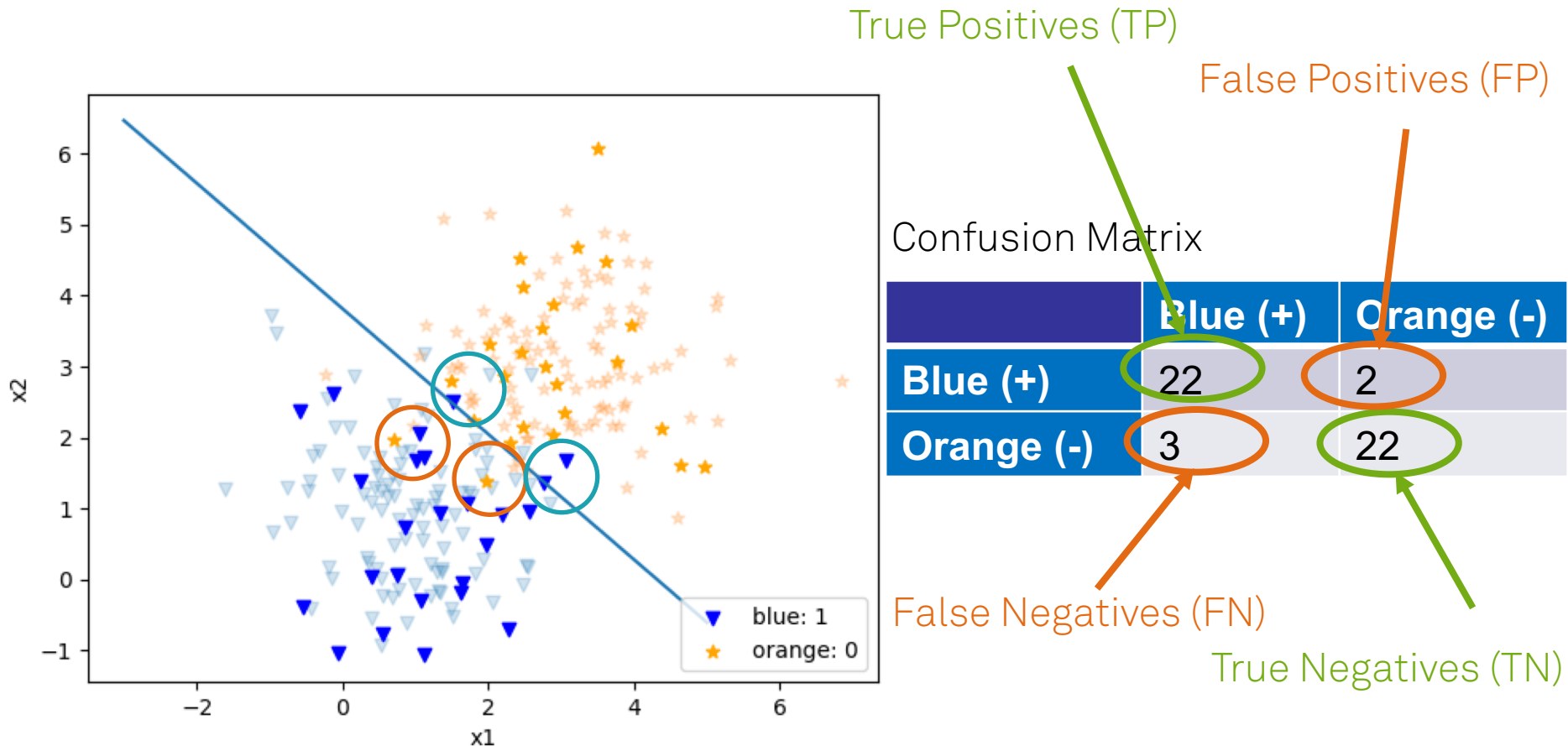


Confusion Matrix

	Blue (+)	Orange (-)
Blue (+)	22	2
Orange (-)	3	22



True and False Negatives and Postives



Quality Measures

Accuracy:

$$ACC = \frac{TP + TN}{P + N} = \frac{TP + TN}{TP + FP + TN + FN}$$

Precision:

$$PREC = \frac{TP}{TP + FP}$$

Recall:

$$REC = \frac{TP}{TP + FN}$$

* These measures can sometimes have different names

True Positives (TP)

False Positives (FP)

Confusion Matrix

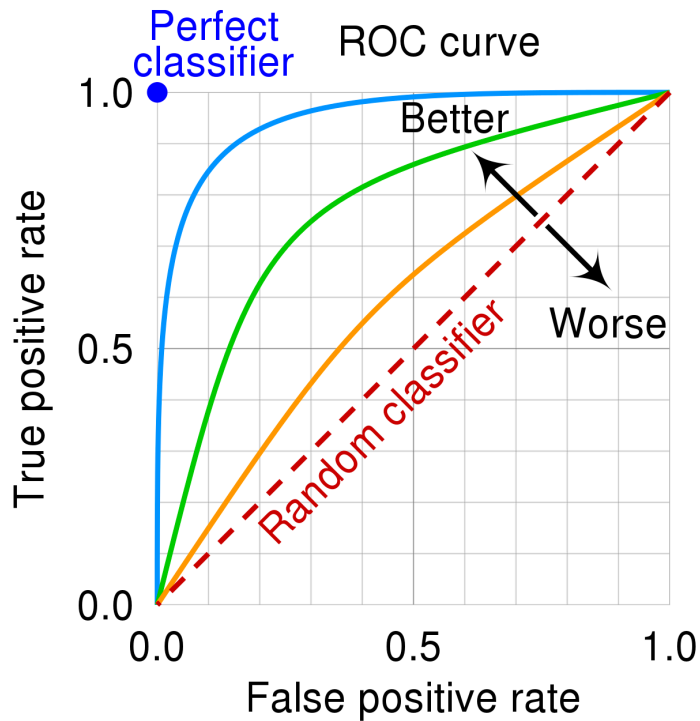
	Blue (+)	Orange (-)
Blue (+)	22	2
Orange (-)	3	22

False Negatives (FN)

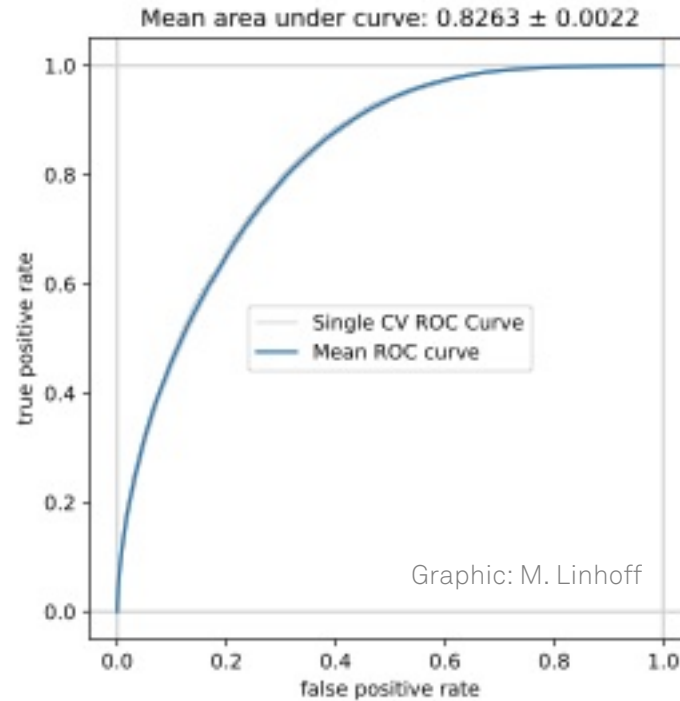
True Negatives (TN)



Area Under Curve



Graphics: M. Linhoff [Learning Under Resource Constraints – Discovery in Physics] (in preparation)

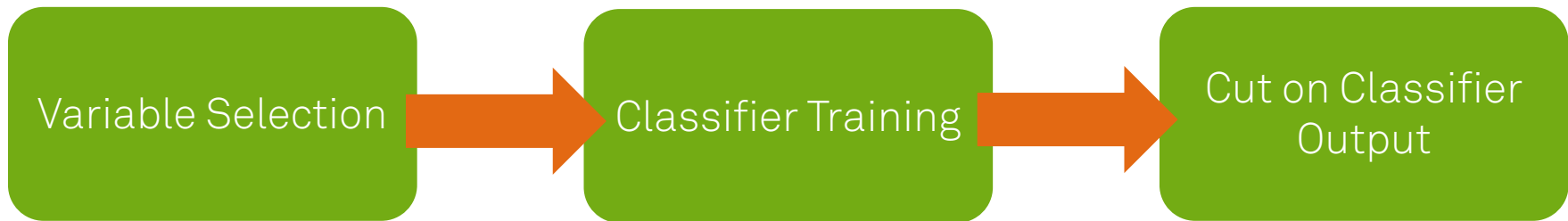


ROC characteristic for the FACT Open Crab data set

Source: By cmglee, MartinThoma - Roc-draft-xkcd-style.svg, CC BY-SA 4.0, <https://commons.wikimedia.org/w/index.php?curid=109730045>



Exemplary Data Analysis Pipeline



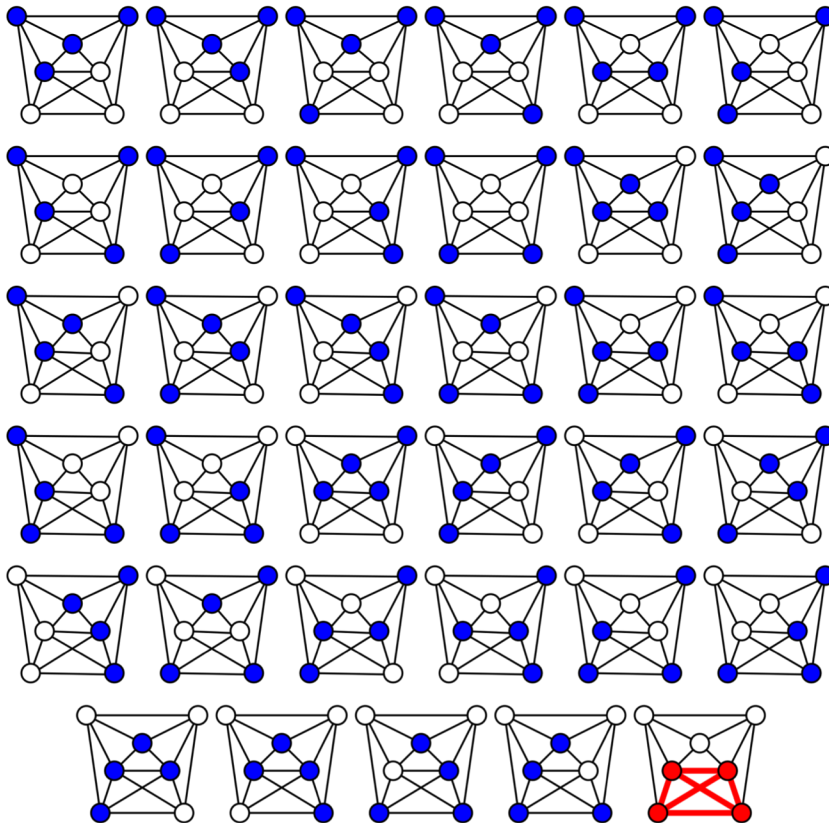
Source: <https://www.pinterest.com/pin/550354016946043419/>



Picture: CC BY-SA 3.0,
<https://commons.wikimedia.org/w/index.php?curid=14260>



Variable Selection: Try possible combinations

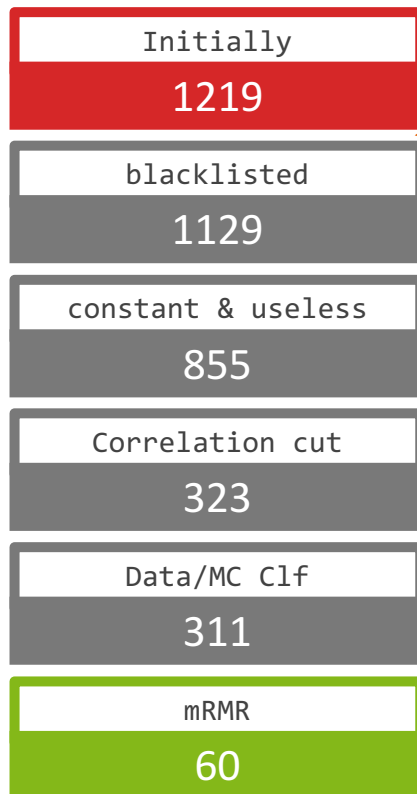


Yes, but...



Source: By Thore Husfeldt at English Wikipedia, CC BY-SA 3.0, <https://commons.wikimedia.org/w/index.php?curid=31823619>

Feature Selection

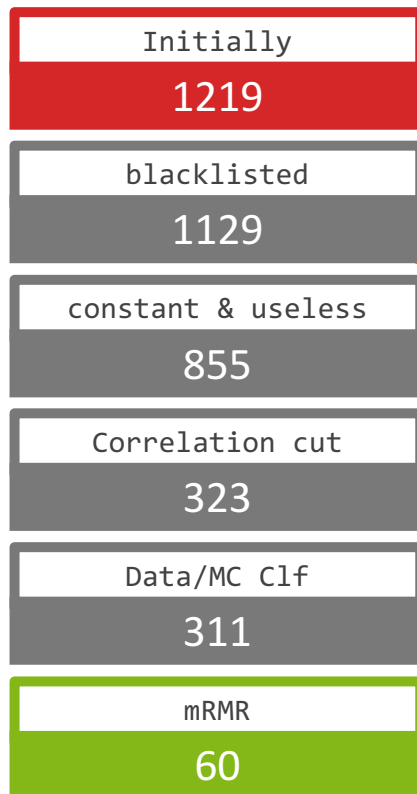


Exclude features that either bias the selection or are only present in simulation.

M. Börner, PhD thesis (2018)



Feature Selection



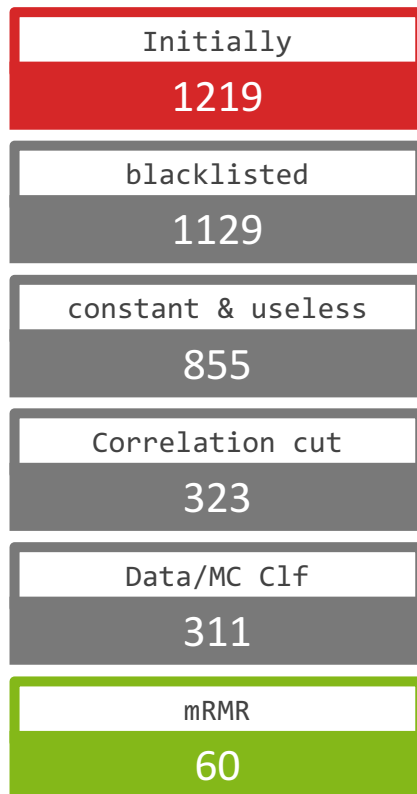
Exclude features that either bias the selection or are only present in simulation.

Constant features do not carry information.

M. Börner, PhD thesis (2018)



Feature Selection



Exclude features that either bias the selection or are only present in simulation.

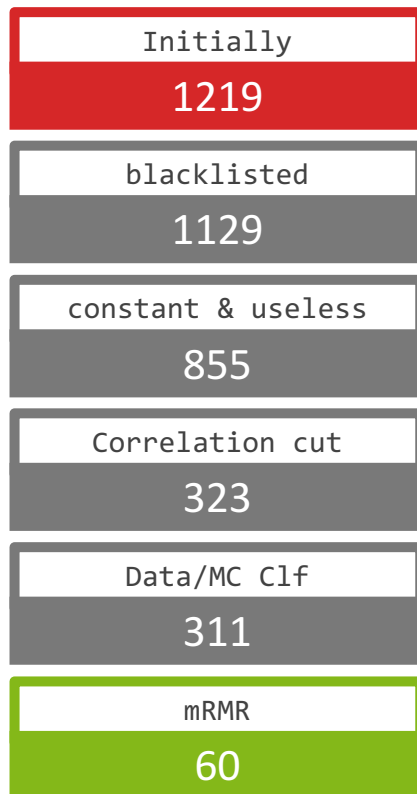
Constant features do not carry information.

Strongly correlated features do not contain new information (or only very little)

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Feature Selection



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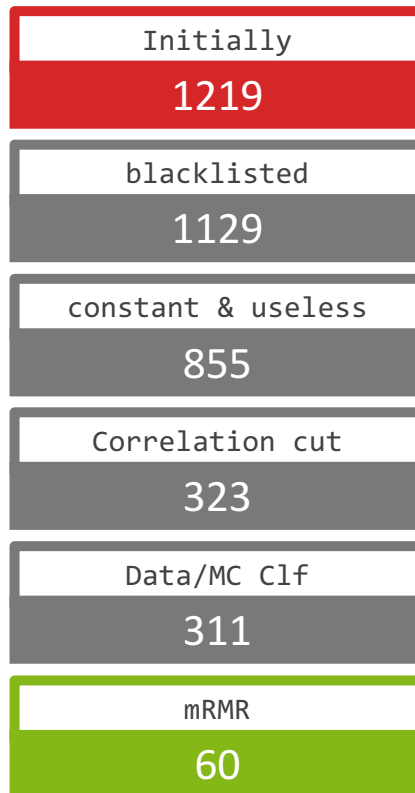
Strongly correlated features do not contain new information (or only very little)

Simulated and experimental data should agree to not bias the result.

M. Börner, PhD thesis (2018)



Feature Selection



M. Börner, PhD thesis (2018)

Exclude features that either bias the selection or are only present in simulation.

Constant features do not carry information.

Strongly correlated features do not contain new information (or only very little)

Simulated and experimental data should agree to not bias the result.

Automated selection by a feature selection algorithm.



Minimum Redundancy Maximum Relevance

Initially	1219
blacklisted	1129
constant & useless	855
Correlation cut	323
Data/MC Clf	311
mRMR	60

- Select features according to relevance and redundancy
- Feature set is built by iteratively adding features that fulfill the following criterion

$$\max_{x_j \in X - S_{m-1}} \left[I(x_j, c) - \frac{1}{m-1} \sum_{x_i \in S_{m-1}} I(x_i, x_j) \right]$$

Peng, H.C., Long, F., and Ding, C., IEEE Transactions on Pattern Analysis and Machine Intelligence, Vol. 27, No. 8, pp. 1226–1238, 2005.

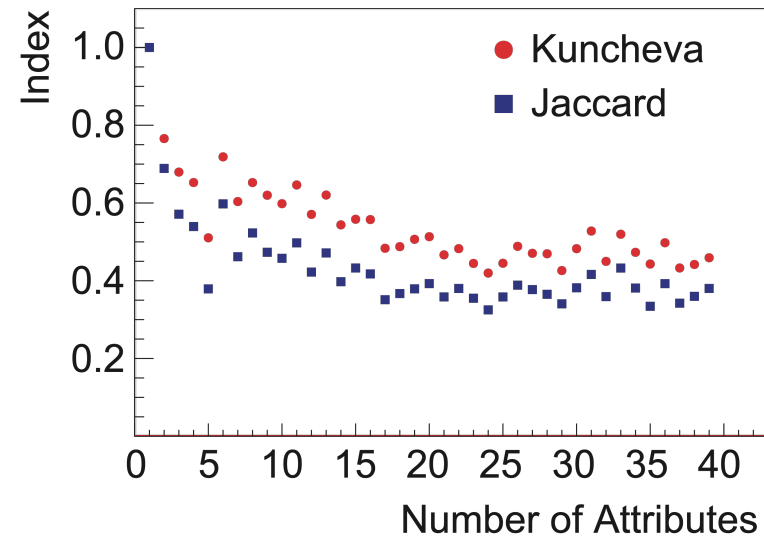
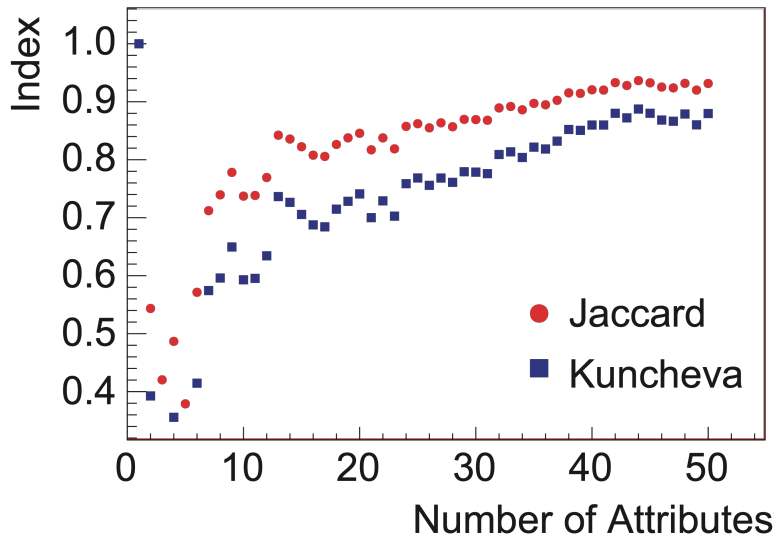
Ding, C., & Peng, H., *Journal of bioinformatics and computational biology*, 3(02), 185-205. (2005)

M. Börner, PhD thesis (2018)



Feature Selection Stability

Ludmila I. Kuncheva: A STABILITY INDEX FOR FEATURE SELECTION



$$J(A, B) = \frac{|A \cap B|}{|A \cup B|}$$

$$I_C(A, B) = \frac{rn - k^2}{k(n - k)}$$

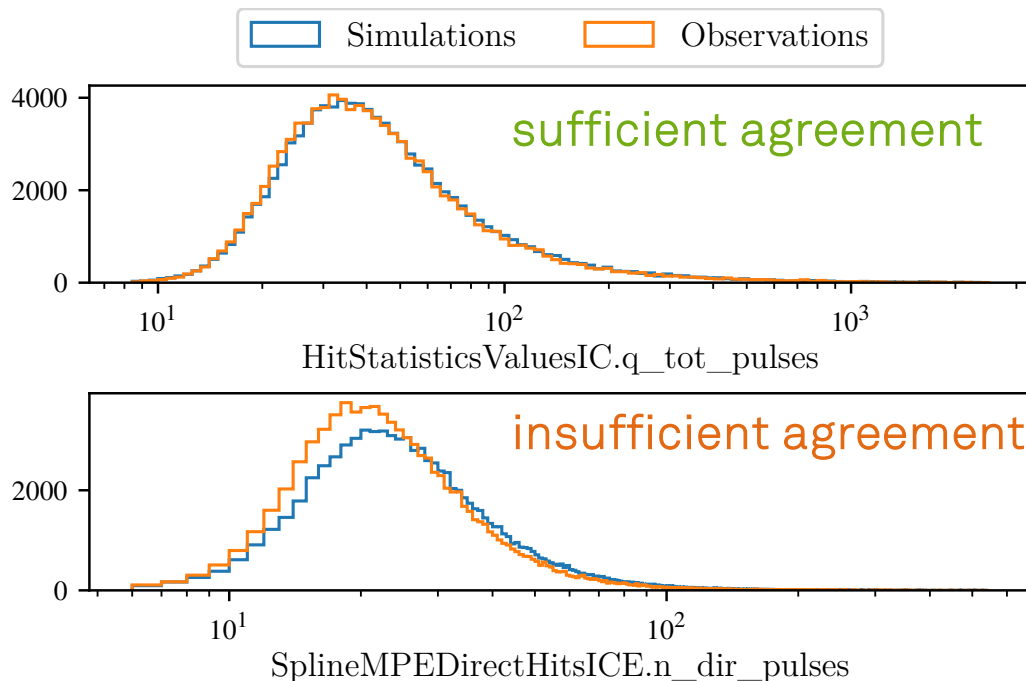
$$k = |A| = |B|$$

$$r = |A \cap B|$$

n : number of features



Detection of Data/Simulation Disagreements



Graphics: M. Linhoff [Learning Under Resource Constraints – Discovery in Physics] (in preparation)

Challenges when inspecting distributions by eye:

- only looking at one-dimensional distributions
- Systematic errors in simulation will also affect correlations between features
- Which metric ???
- Which threshold ???



Detection of Data/Simulation Disagreements

Random Forest Feature Importance



Graphics: M. Linhoff [Learning Under Resource Constraints – Discovery in Physics] (in preparation)

General Idea:

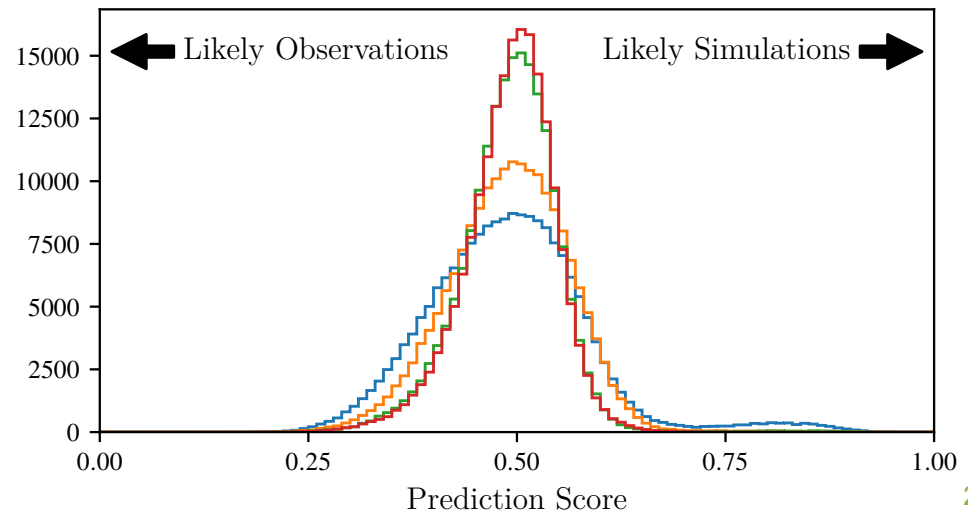
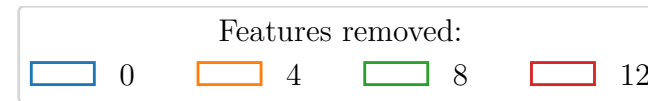
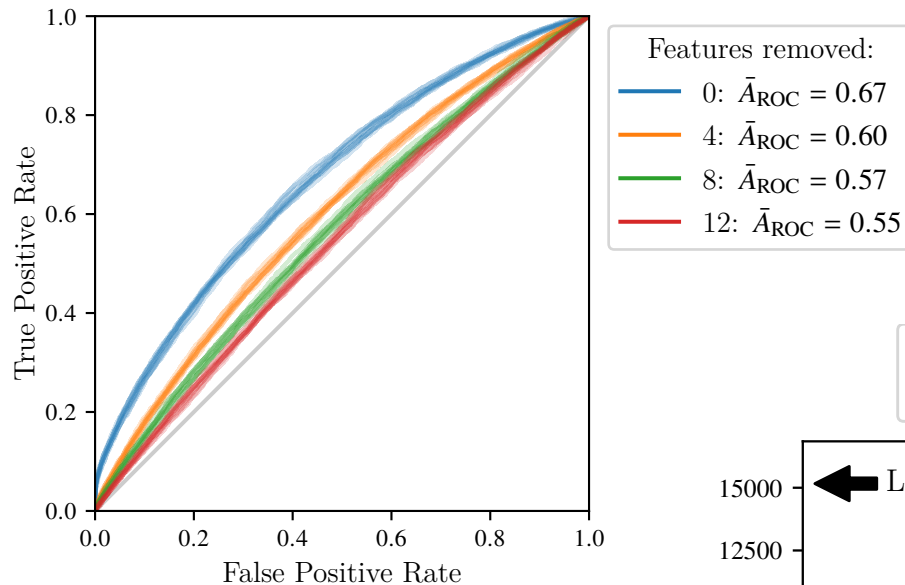
- Train classifier to distinguish simulated and experimental data
- Hard to impossible for a perfect agreement
- Sort features according to their importance
- Discard top n features
- Advantage: Extent to which mismatches can be tolerated is set by the classifier



Detection of Data/Simulation Disagreements

Graphics: M. Linhoff [Learning Under Resource Constraints – Discovery in Physics] (in preparation)

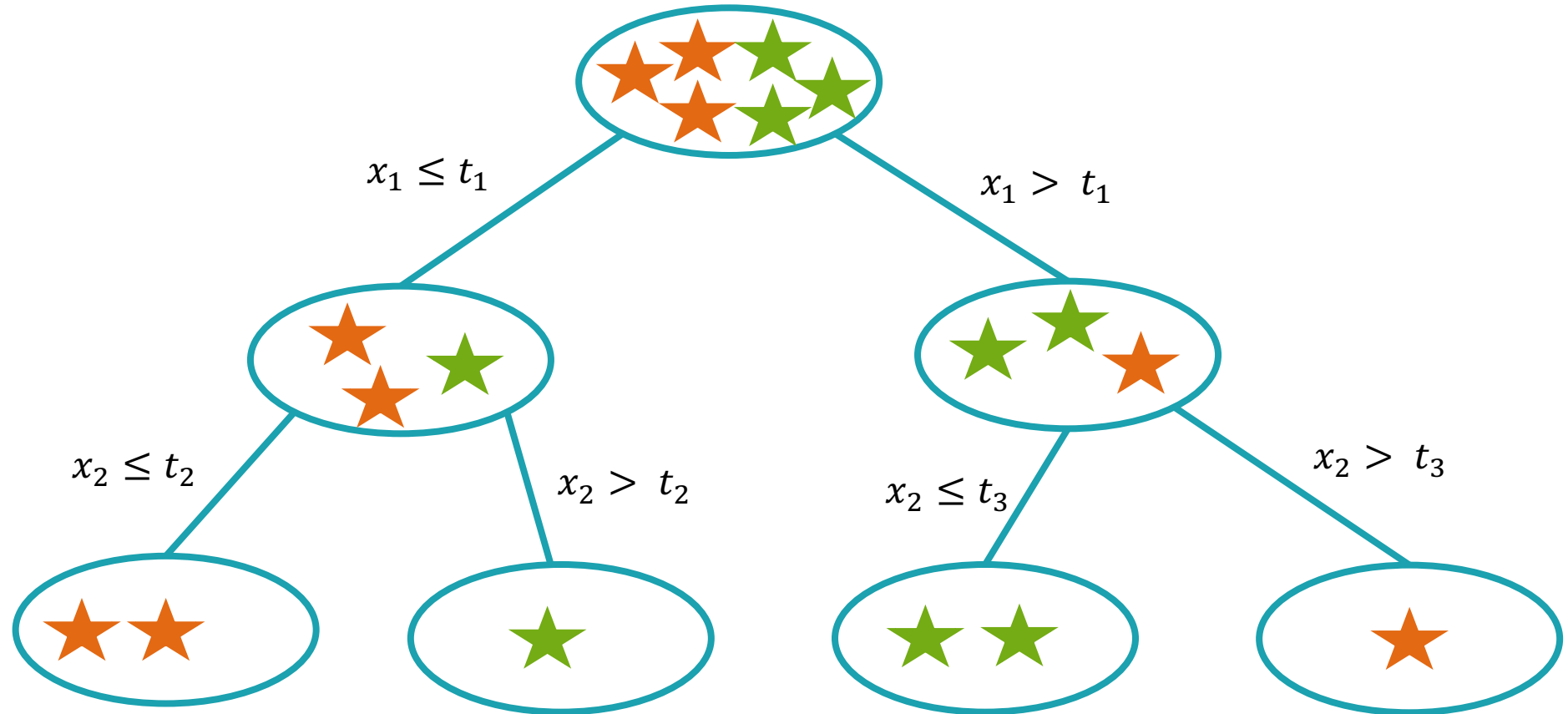
Area under Curve is close to 0.5 (close to random guess).



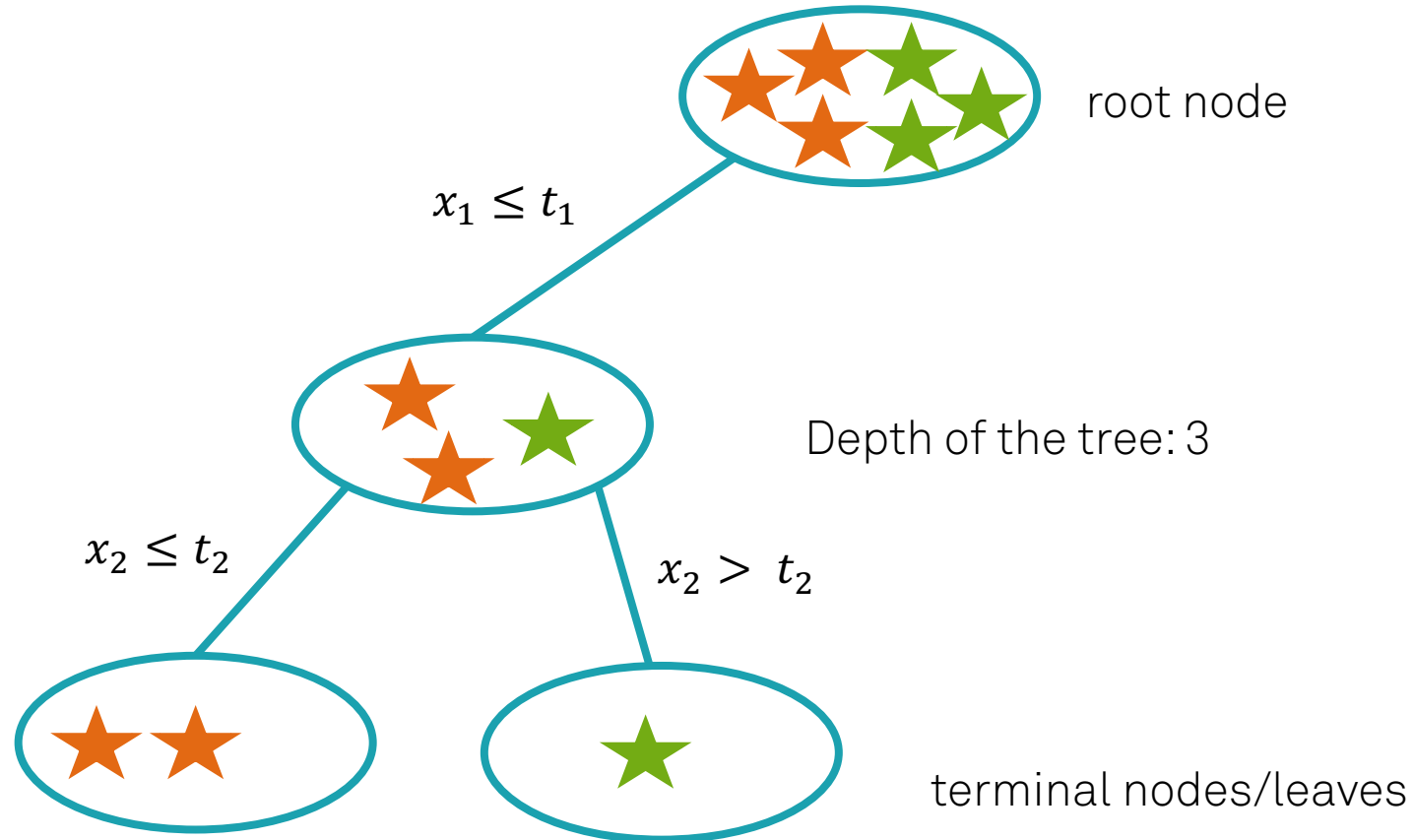
Prediction score centered around 0.5 (close to random guess).



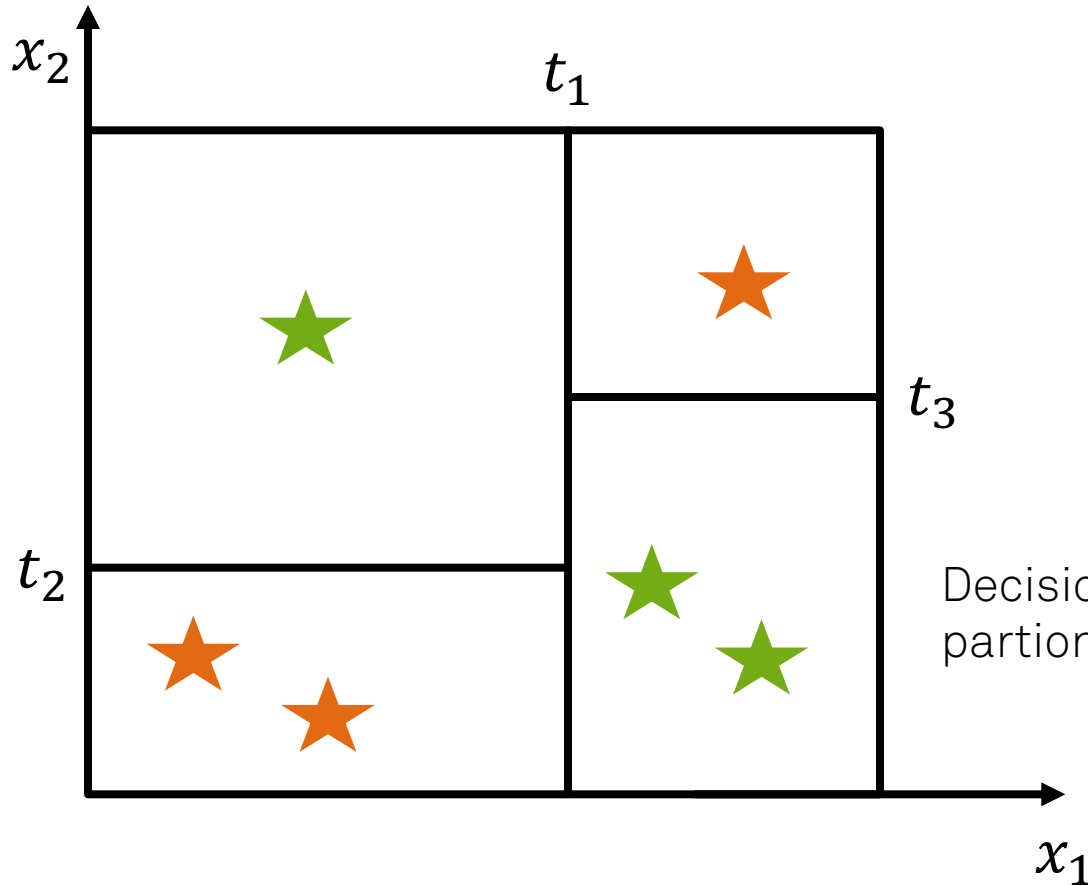
Decision Trees



Decision Trees Nomenclature



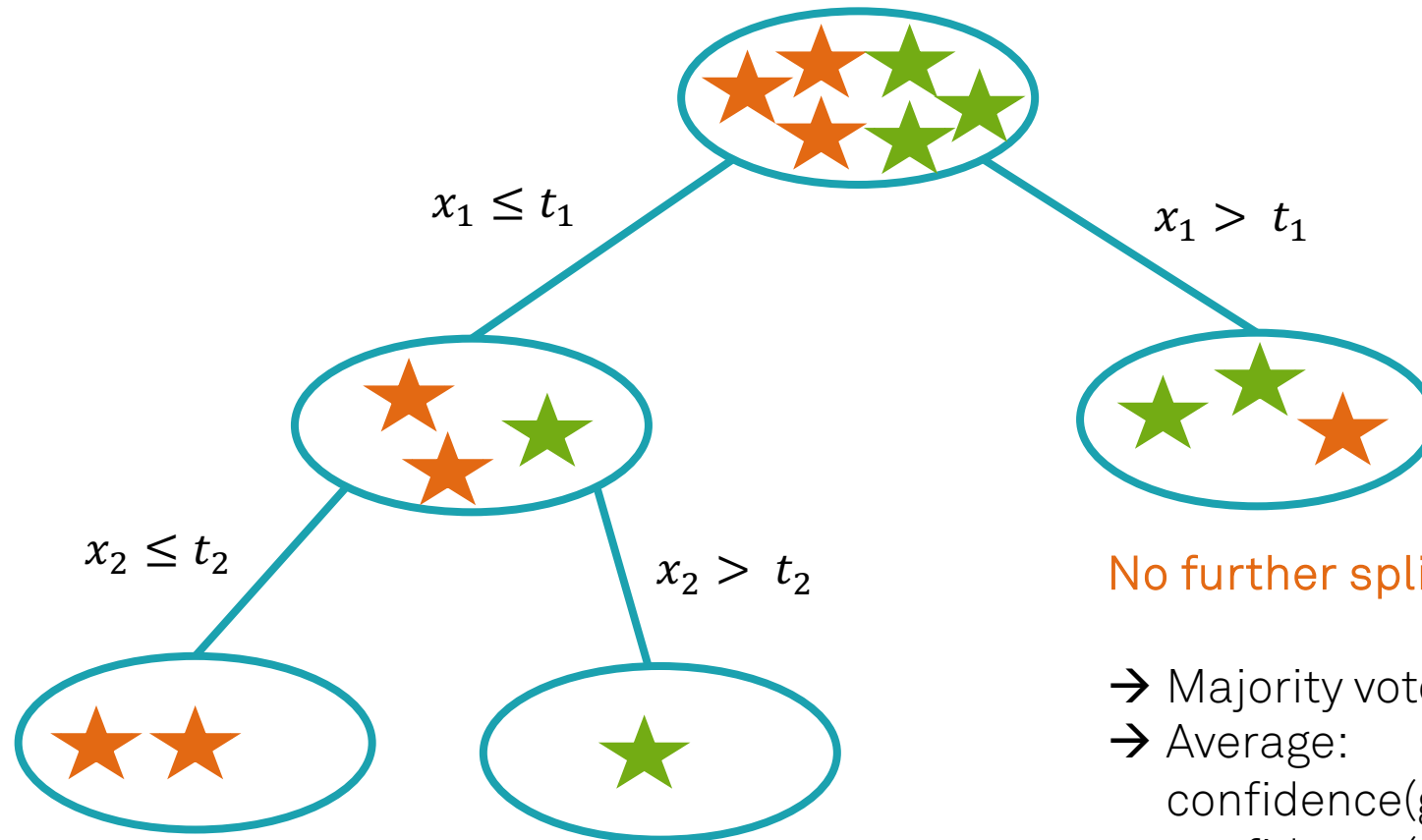
Decision Trees



Decision Trees achieve a binary partitioning of the feature space.



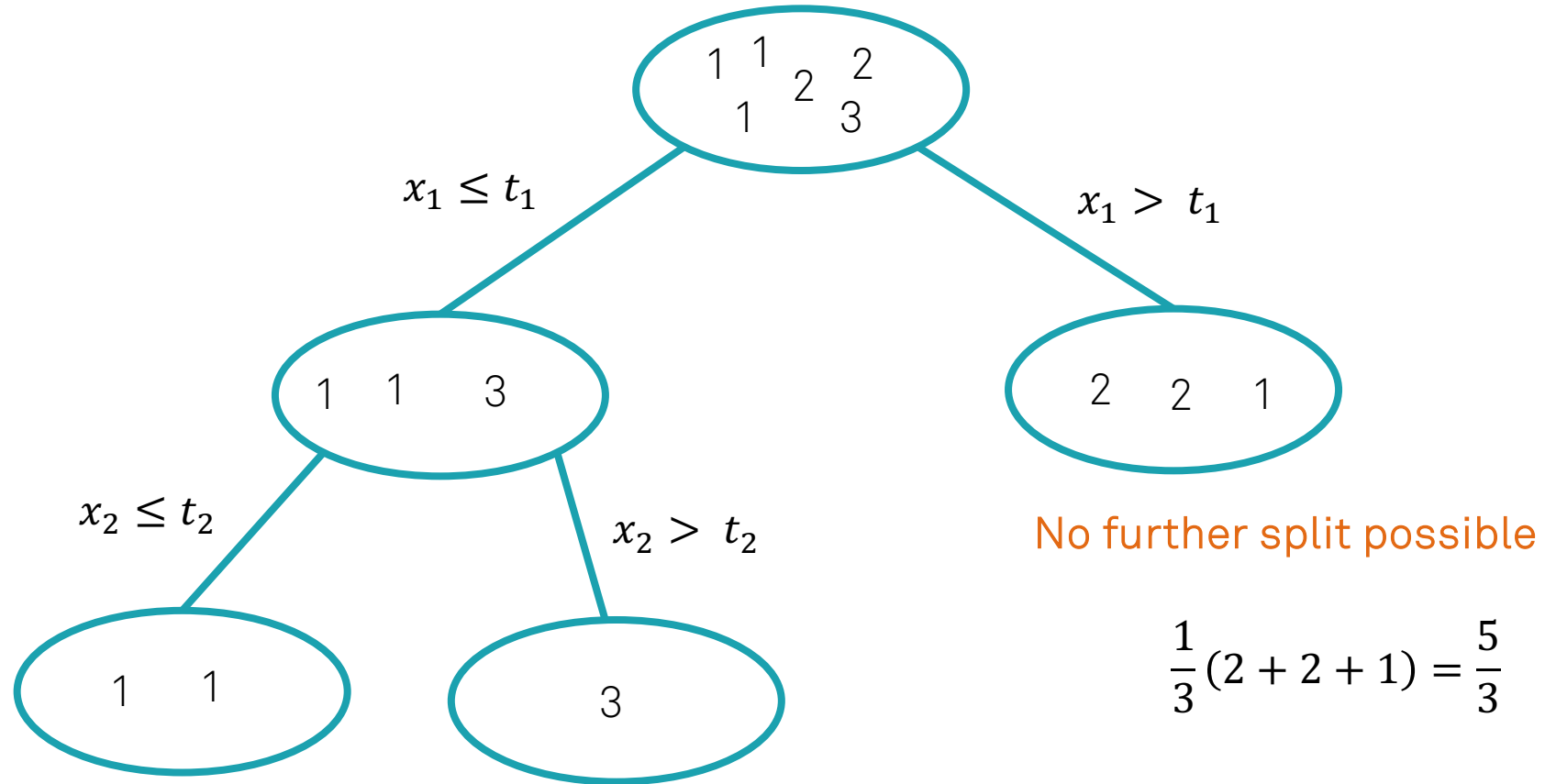
Decision Trees



- Majority vote: green
- Average:
confidence(green) = $2/3$,
confidence(orange) = $1/3$



Decision Trees for Regression



How to decide where to split?

Impurity Measures:

Cross entropy:

$$i(N) = - \sum_{j=1}^K P(\omega_j) \log_2(\omega_j)$$

Gini Impurity:

$$i(N) = \sum_{i \neq j} P(\omega_i) P(\omega_j) = \frac{1}{2} \left[1 - \sum_j P^2(\omega_j) \right]$$

$P(\omega_j)$: Fraction of patterns at
node N in class ω_j



How to decide where to split?

Misclassification impurity:

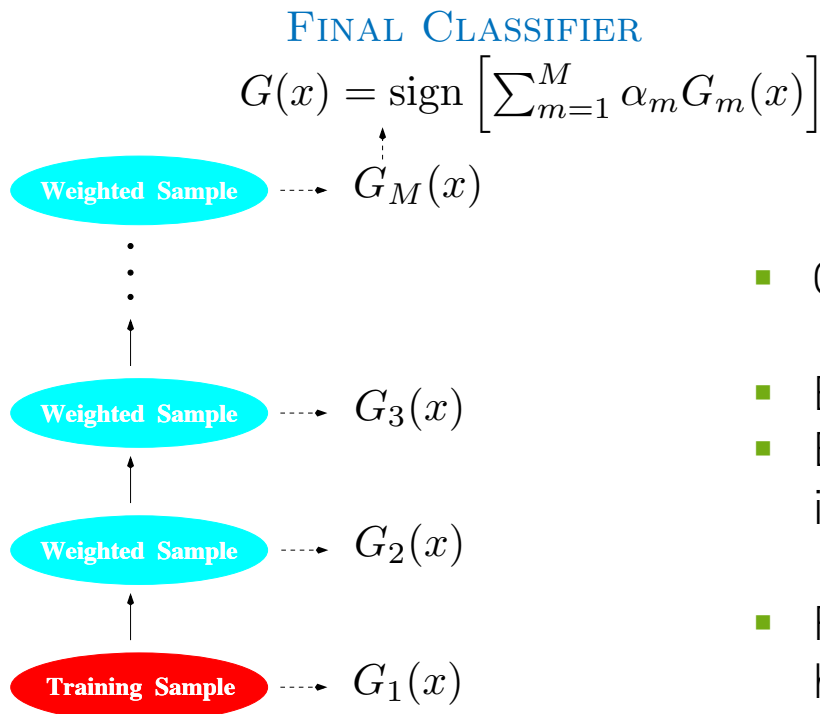
$$i(N) = 1 - \max_j P(\omega_j)$$

To determine the optimal split consider the decrease in impurity:

$$\Delta i(N) = i(N) - P_L \cdot i(N_L) - (1 - P_L) \cdot i(N_R)$$



Boosted Decision Trees



- Classifiers are weighted by

$$\alpha_m = \log((1 - \text{err}_m)/\text{err}_m)$$
- Better classifiers obtain higher weights
- Example weights are updated in every iteration

$$w_i \leftarrow w_i \cdot \exp(\alpha_m \cdot I(y_i \neq G(x_i)))$$
- Falsely classified examples obtain higher weights in the next iteration

Source: Elements of Statistical Learning, Figure 10.1



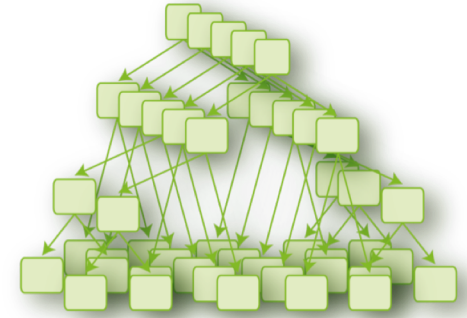
Random Forest

$$x_1 \leq t_1$$



Random subset features to determine the optimal split

Random subset of examples to build each tree.



Random forests utilize an ensemble of independent weak classifiers (decision trees) to obtain a better classification.

Final classification is achieved via:

$$c_j = \frac{1}{n_{trees}} \sum_{i=1}^{n_{trees}} c_{ij}$$

c_{ij} : Classification for example j by tree i



Validation



- In order to not optimize on statistical fluctuations in the test set it is advisable to use cross validation for parameter optimization
- It can also be useful to have an additional validation set to validate the performance of the optimized parameter settings



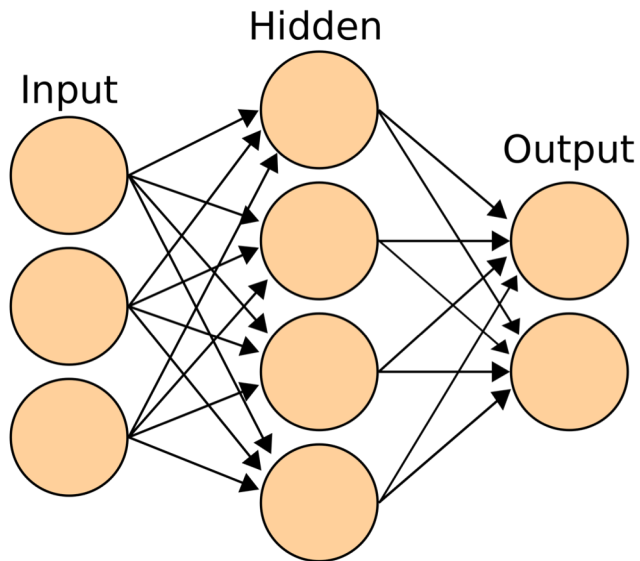
Use for training



Use for testing



Neural Networks



Source: By Alvesgaspar - Top left: File:Cat August 2010-4.jpg by AlvesgasparTop middle: File:Gustav chocolate.jpg by Martin BahmannTop right: File:Orange tabby cat sitting on fallen leaves-Hisashi-01A.jpg by HisashiBottom left: File:Siam lilacpoint.jpg by Martin BahmannBottom middle: File:Felis catus-cat on snow.jpg by Von.grzankaBottom right: File:Sheba1.JPG by Dovenetel, CC BY-SA 3.0, <https://commons.wikimedia.org/w/index.php?curid=17960205>

- Highly successful, e.g in image classification
- Hyped

Source: By en:User:Cburnett - This W3C-unspecified vector image was created with Inkscape., CC BY-SA 3.0, <https://commons.wikimedia.org/w/index.php?curid=1496812>



Reasons for Using Neural Networks (in IceCube)

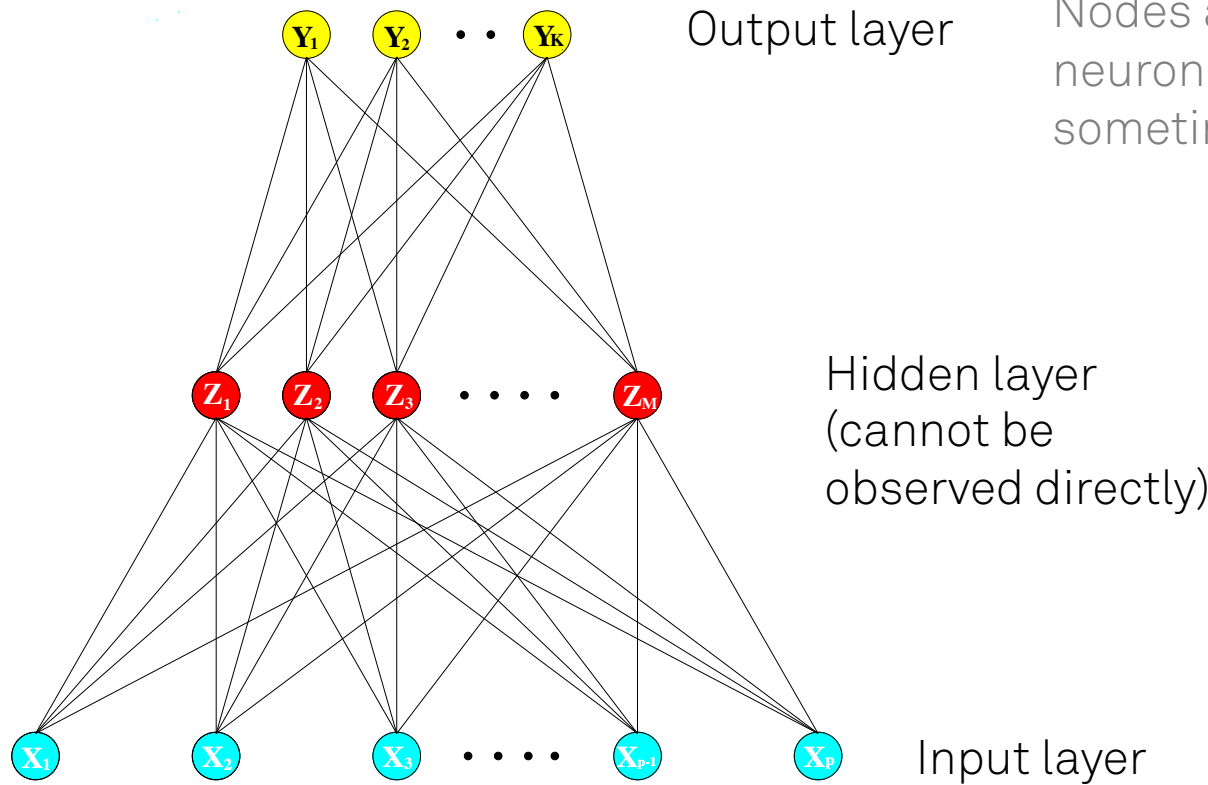
- Improved reconstruction methods will lead to increased sensitivity for the detection of sources
- Hardware limitations at the South Pole
- Events need to be processed in a given time frame to prevent pileup
- Limitations call for robust method that can handle raw data in constant time
- Neural networks are computationally inexpensive once the network is trained
- Fixed amount of operations, runtime is (largely) independent of the input
- Translational invariance (position of the classified object does not impact the class)
- Physics of neutrino interaction is invariant in time and space



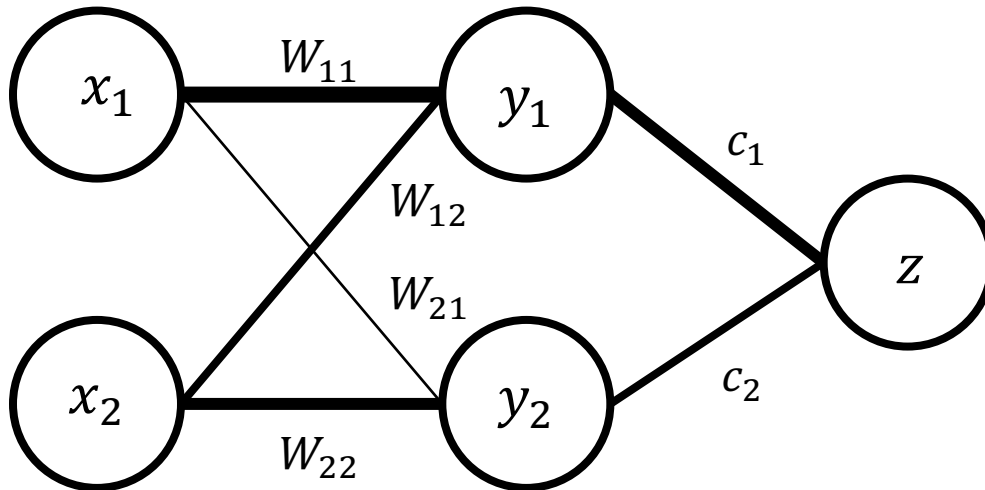
General Idea of Neural Networks

Originally developed to mimic the human brain.

Nodes are sometimes called neurons, and connections are sometimes called synapses.



General Idea of Neural Networks



Nodes are linear combinations of nodes from previous layers.

The task is to optimize the weights such that the estimated label z matches the true label \hat{z} .

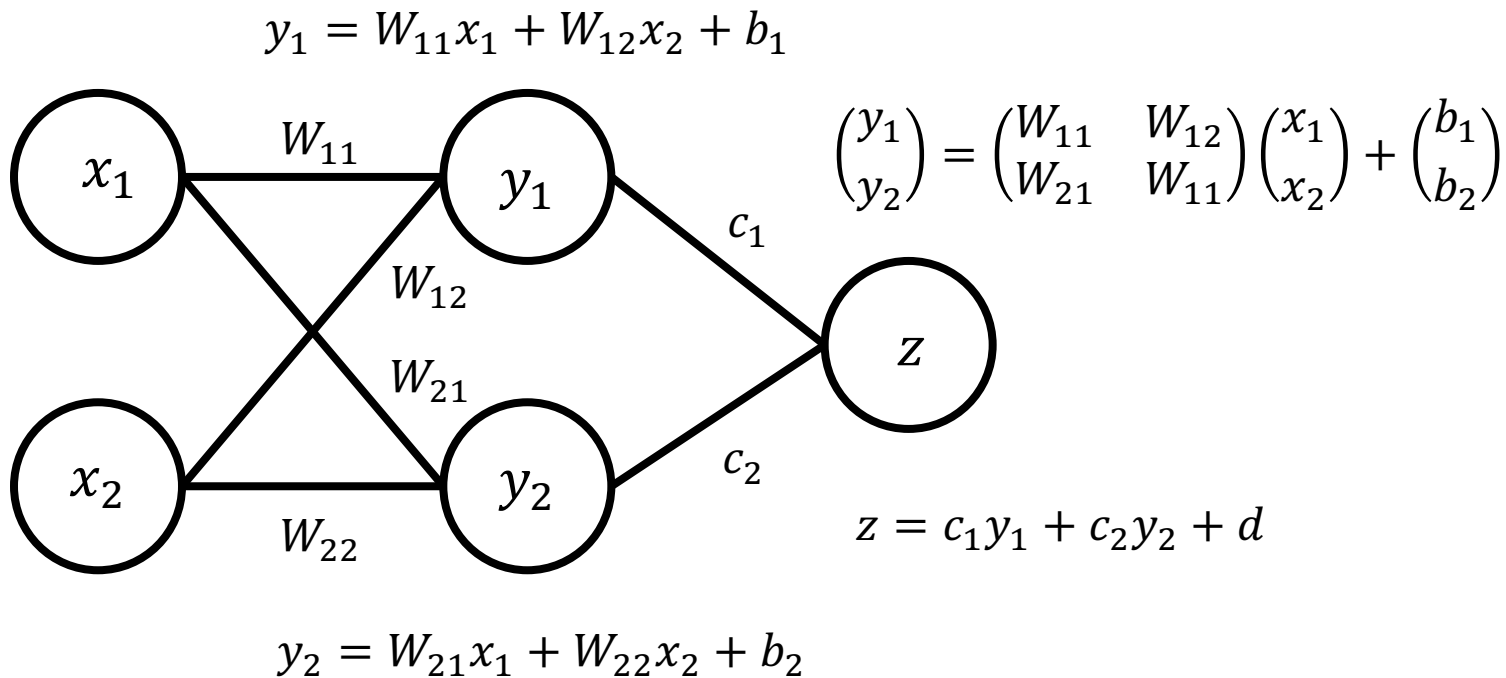
A feed-forward neural network with linear output and at least one hidden layer with a finite number of nodes can approximate any of the above* functions with arbitrary precision**.

*Continuous functions on closed bounded subsets of the Euclidean space \mathbb{R}^n .

**Figure and definition adopted from Erdmann et al.



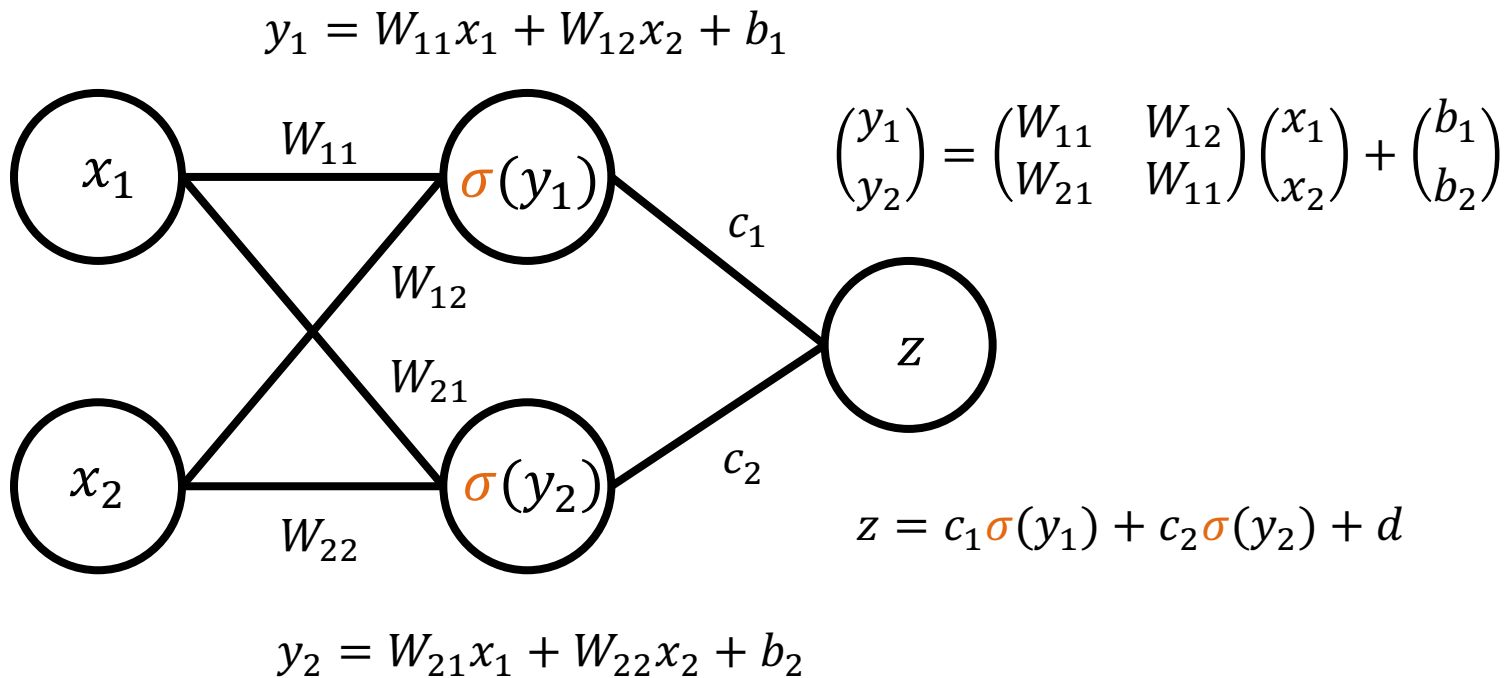
More mathematically speaking



**Figure adopted from Erdmann et al.



Adding non-linearity

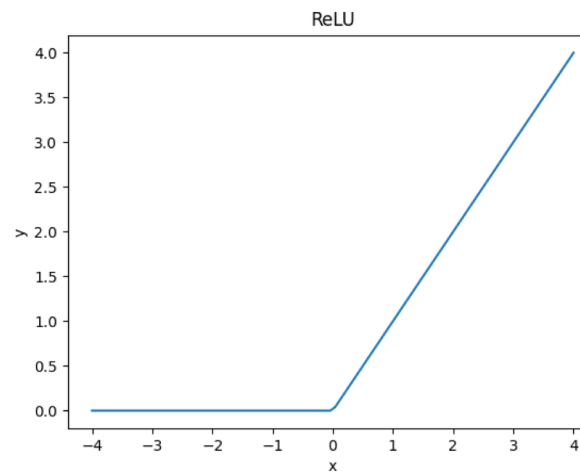
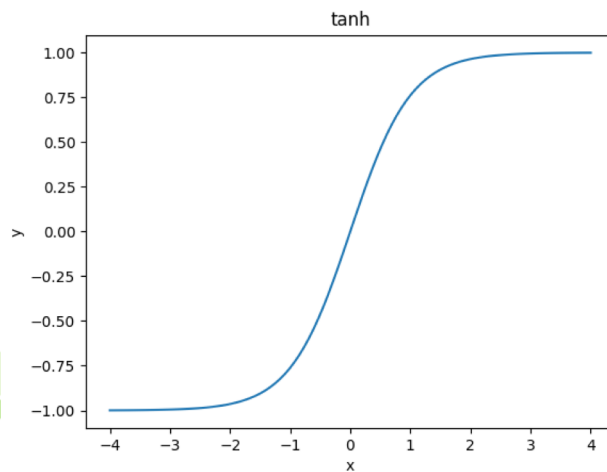
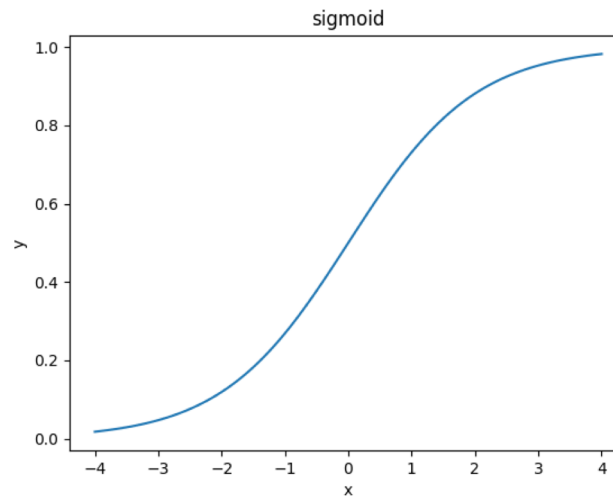
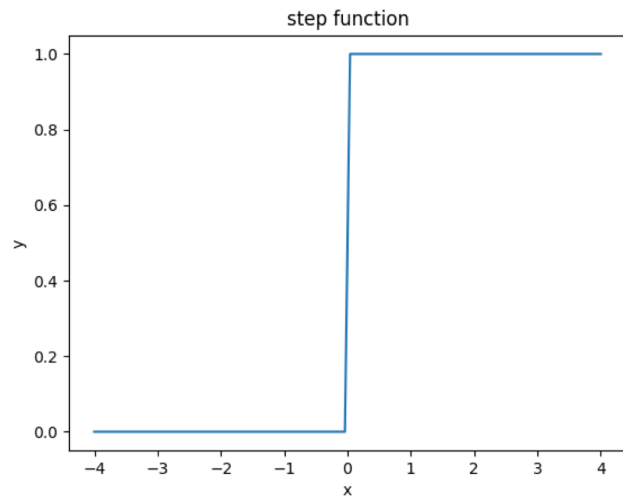


σ is generally referred to as the activation function.

**Figure adopted from Erdmann et al.



Popular choices for σ



Input Preparation

- **Zero-centered:** ReLU changes drastically around 0, $x_i - \langle x_i \rangle$ to include positive and negative values
- **Order of magnitude:** Large variables could be preferred in the network training $x'_i = \frac{x_i - \langle x_i \rangle}{\sigma_i}$
- **Logarithm** to achieve more evenly distributed data
- **Decorrelation:** highly correlated variables should be decorrelated

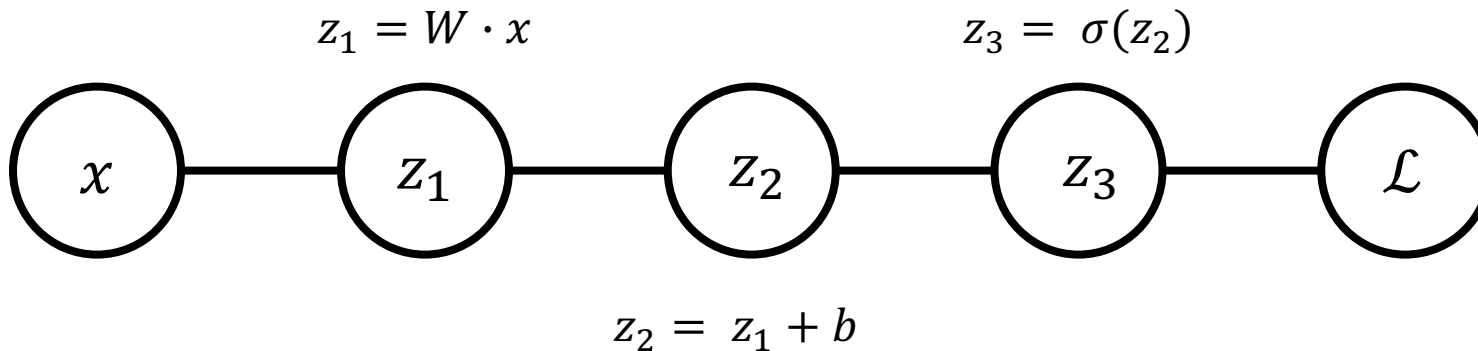


Epoch and (mini)batch

- **Minibatch, Batch:** Using all examples can be infeasible in case many parameters need to be optimized, instead random subsets (batches) of examples are used. The optimal size of the batch depends on the problem to be solved. Popular choices are 2^k
- **Epoch:** Complete use of all examples.



Weight Updates



$$\frac{\partial \mathcal{L}}{\partial W} = \frac{\partial \mathcal{L}}{\partial z_3} \cdot \frac{\partial z_3}{\partial z_2} \cdot \frac{\partial z_2}{\partial z_1} \cdot \frac{\partial z_1}{\partial W}$$

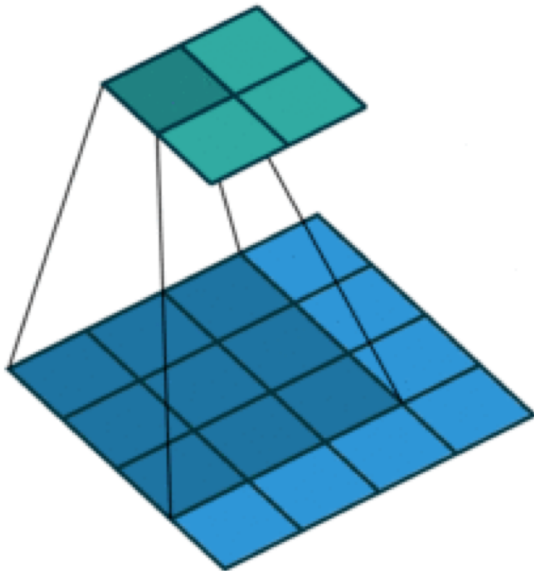
$$W_{t+1} = W_t - \alpha \mathbb{E} \left[\frac{\partial \mathcal{L}}{\partial W} \right]_t$$

$$\mathbb{E} \left[\frac{\partial \mathcal{L}}{\partial W} \right] = \frac{1}{k} \sum_{i=1}^k \left(\frac{\partial \mathcal{L}}{\partial W} \right)_i$$

This is the basic idea, this will most likely be handled by an optimizer.



Convolutional Layers

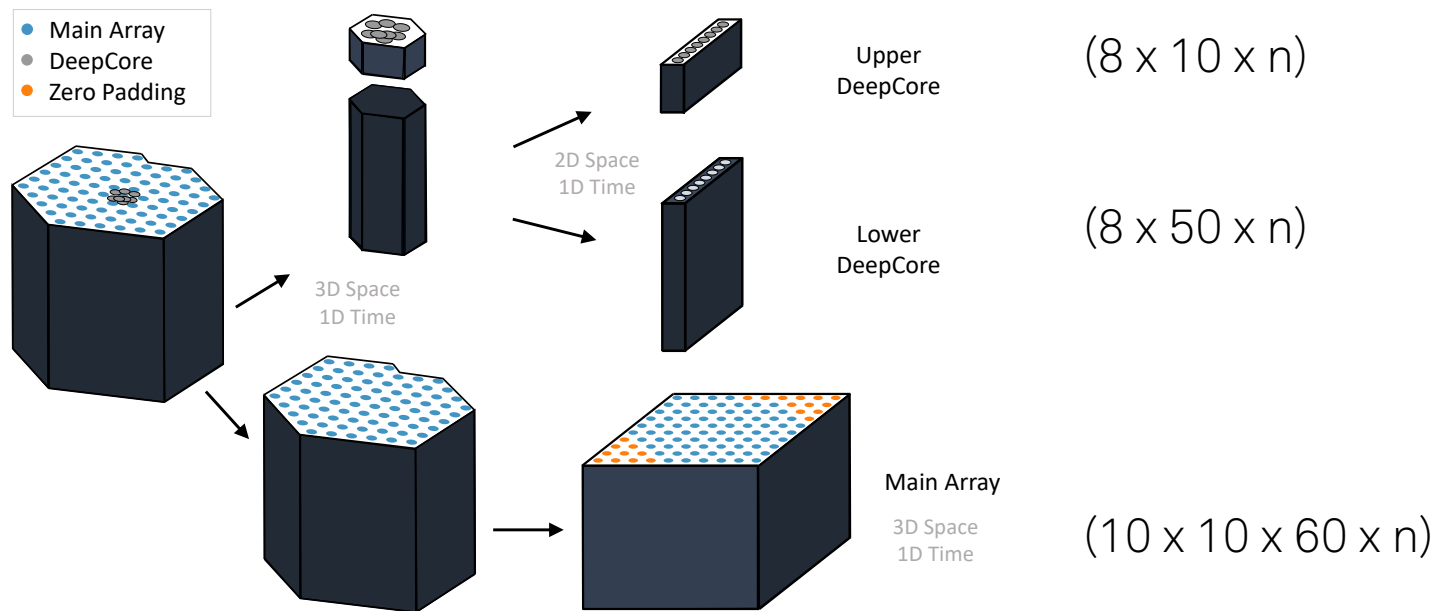


- Considering all pixels in an image in a fully connected network, results in too many parameters to be optimized
- The position of an object in an image should not alter the prediction (translational invariance)
- The convolutional operation exploits the neighbourhood of each pixel

Source: By Vincent Dumoulin, Francesco Visin -
https://github.com/vdumoulin/conv_arithmetic, MIT,
<https://commons.wikimedia.org/w/index.php?curid=78003423>



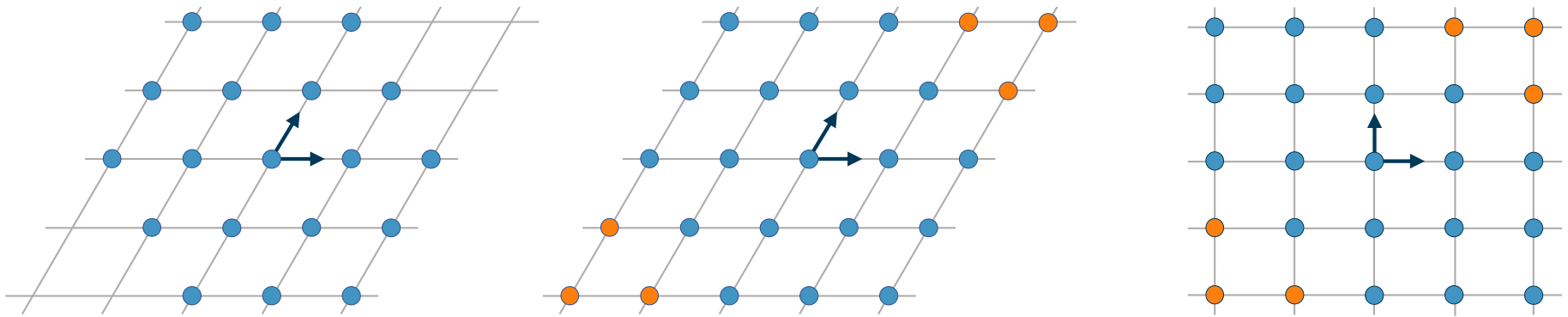
Hexagonal Input Data



Abbasi et al., JINST, 16 (7) (2004).



Hexagonal Kernels



Abbasi et al., JINST, 16 (7) (2004).



Take-Away Messages

- Machine Learning and esp. Deep Learning is not magic
- Machine Learning and Deep Learning are tools that will help you to accomplish an analysis task faster and more accurately (when used correctly)
- The preprocessing of data is part of machine learning (and very important)
- Not every classifier is suited for every problem (consider runtime)
- If something fast and simple does the job: use it
- Make sure simulated and experimental data agree
- ...

