



**UNIVERSITÀ
DEGLI STUDI
DI UDINE**

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ATLAS
EXPERIMENT



Third HEP Graduate Workshop

Physics Modeling

May 25, 2022

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Udine & INFN - Gruppo collegato di Udine

Third HEP Graduate Workshop
University of Batna 1, Batna
Algeria, 24-26 May 2022



Observables and averages

An observation in particle physics is

$$\langle O \rangle = \int d\phi_n \frac{d\sigma(A, B \rightarrow n \text{ particles})}{d\phi_n} O(\phi_n)$$

phase space differential cross section value of observable

phase space: sample of all quantum numbers (momentum, flavor...) of particles in scattering final state

differential cross section \approx transition probability to scattering final state

Compare to expectation value in statistics:

$$\langle g \rangle = \int dx f(x) g(x)$$

random variables probability distribution value of function

\Rightarrow Calculate "theory predictions" for O with statistical methods.

Monte-Carlo vs analytic computations

- Dedicated calculations : Evaluate analytic expressions on paper...or very likely a computer. Safe & fast, but only viable for “simple” problems
- Monte Carlo generators : Approximate analytic expressions numerically, by statistical sampling on a computer. Use Monte-Carlo methods to handle complex scattering final states and/or observations.

Integration and averages

Monte-Carlo algorithms are simple enough to have wide applicability, e.g. in integration

$$\int_{x_-}^{x_+} dx f(x) = (x_+ - x_-) \langle f \rangle \approx \frac{(x_+ - x_-)}{N} \sum_{i=1}^N f(x_i)$$

The approximation errors is $\propto \frac{1}{\sqrt{N}}$, independent of number of integrations
($dx \rightarrow dx_1 \cdots dx_n$)

Ideally suited for our types of integrals

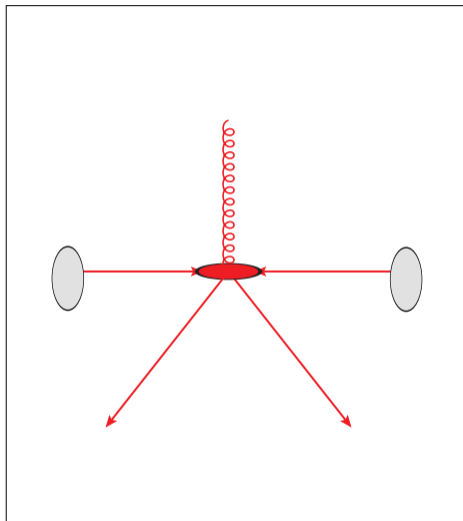
$$\langle O \rangle = \int d\Phi_n \frac{d\sigma_n}{d\Phi_n} O(\Phi_n) \propto \frac{1}{N} \sum_{i=1}^N \frac{d\sigma_n}{d\Phi_n}(\Phi_n^{(i)}) O(\Phi_n^{(i)})$$

May even store the **events** $\Phi_n^{(i)}$ with **event weight** $\frac{d\sigma_n}{d\Phi_n}(\Phi_n^{(i)})$ and evaluate $O(\Phi_n^{(i)})$ later!

NB: Les Houches Event Files are effectively that.

Collisions: a pictorial view

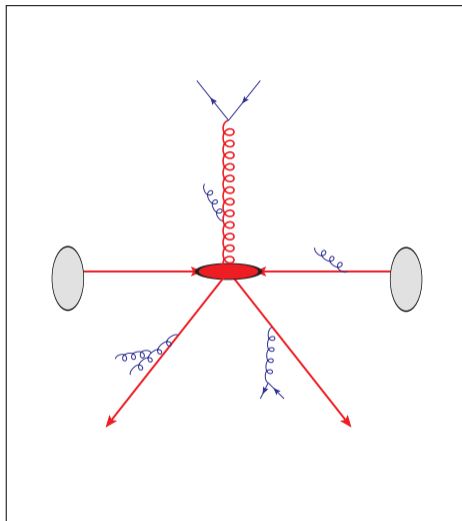
A high-energy scattering breaks the beams apart



Collisions: a pictorial view

A high-energy scattering breaks the beams apart

...which initiates a cascade of radiation in the vacuum.

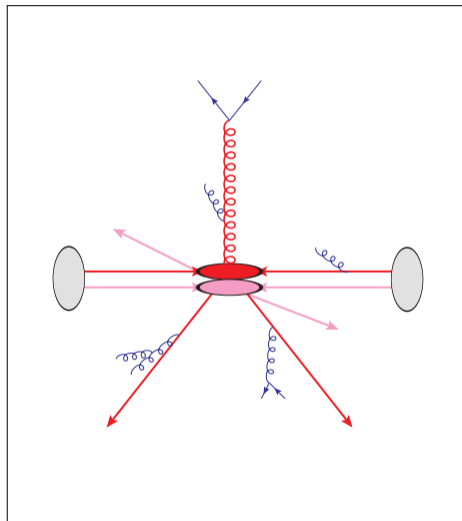


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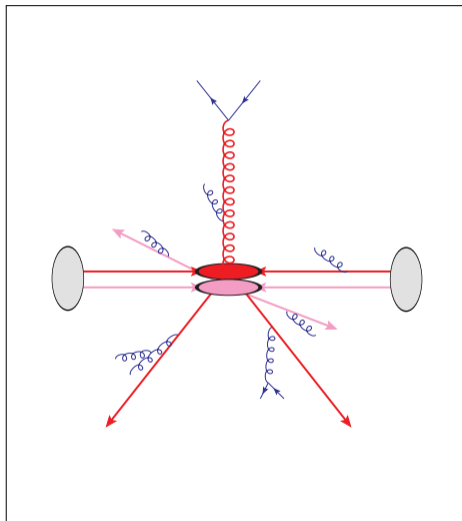
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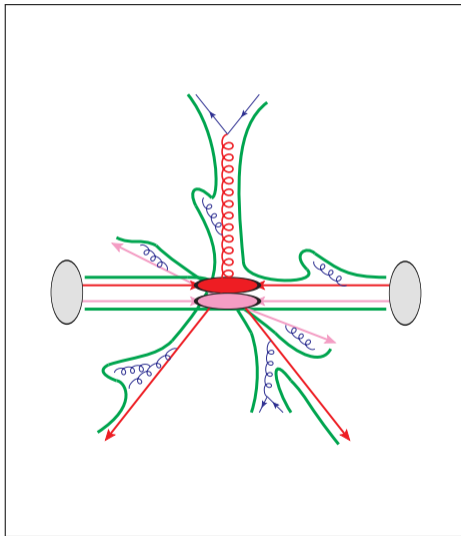
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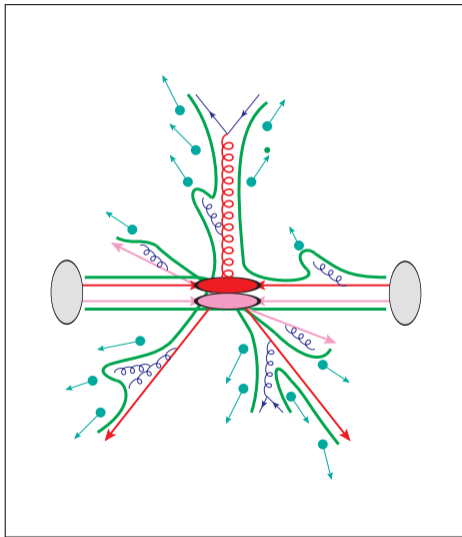
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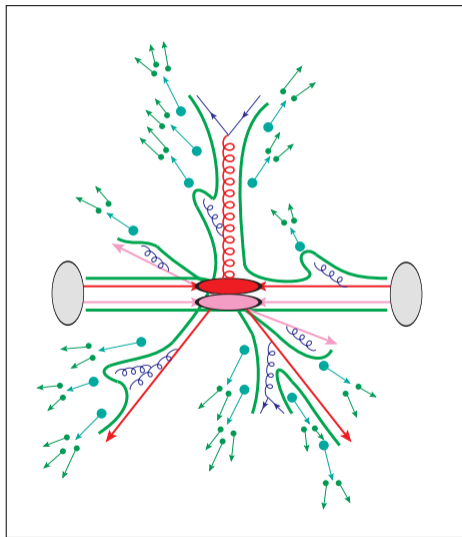
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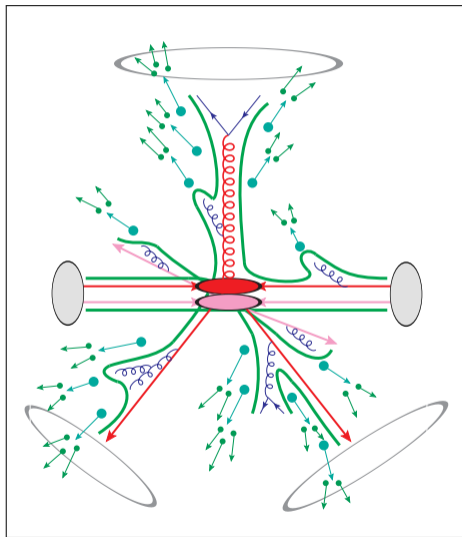
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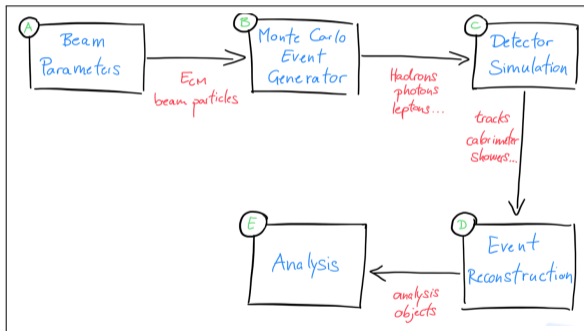
...which decay into stable states.

[outside MCEG: interactions with the detector material occur, analysis objects are reconstructed]



Divide et impera

The sampling (=event generation) of complicated phase space points $\Phi_n^{(i)}$, and the calculation of $\frac{d\sigma_n}{d\Phi_n}(\Phi_n^{(i)})$ can (with some theory, and some hand-waving) be factorized into smaller problems:



A factorized at LHC, but not for neutrino experiments

C often factorized – but not for decays of long-lived particles

Monte-Carlo generators

The Monte-Carlo generator landscape is rich! Just to name a few:

Neutrino physics:

Genie, GiBUU, NuWro, NEUT...

Cosmic rays:

EPOS, QGSJET and SIBYLL

Heavy ions:

HIJING, AMPT, JEWEL...

LHC physics:

Herwig, Pythia, Sherpa
Madgraph, Whizard, Alpgen...

All of them amazing tools to learn about phenomenology. Focus here \approx LHC-type physics

Exercise: Get together with friends and chat about an event generator in an unfamiliar field.

Split into smaller problems

From a technical viewpoint, this chain of phenomena looks like

$$\begin{aligned} dP(\text{beams} \rightarrow \text{final state}) \\ &= dP(\text{beams} \rightarrow A, B) \\ &\otimes dP(A, B \rightarrow \text{few partons}) \\ &\otimes dP(\text{few parton} \rightarrow \text{many partons}) \\ &\otimes dP(\text{many partons} \rightarrow \text{hadrons}) \\ &\otimes dP(\text{hadrons} \rightarrow \text{stable particles}) \end{aligned}$$

Very high integration dimension. Traditionally, only Monte-Carlo viable
→ Need to learn about numerical methods

Nowadays, deep nets can be used to simulate special cases.

Basic numerical techniques

An overview of some basic numerical techniques gives a feeling about how to tackle event generation.

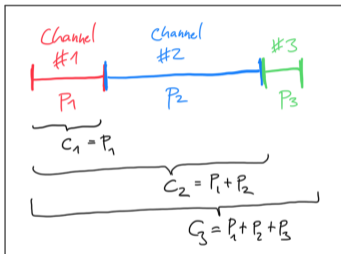
In the following, we'll now look at

- Picking from a probability distribution, a.k.a. inversion sampling
- Hit-or-miss sampling, a.k.a. rejection sampling

...and we'll learn more tricks in the next lectures

Discrete transformation

Imagine several changes to a state could occur, e.g. different particle decays. How do you pick one?



Draw a random number $R \in [0, 1]$. Pick

channel #1 if $0 < RC_3 < C_1$

channel #2 if $C_1 < RC_3 < C_2$

channel #3 if $C_2 < RC_3 < C_3$

Repeat as often as you like.

Q: Why go through the hassle?

A: Now, the rate of channel # i is given by its **population in the sample**, and no longer by an “event weight”. Every “event” has identical weight (C_3).

This is the discrete transformation method. It may be used to pick between different hard scattering processes, decay channels, or for **unweighting**.

Inversion sampling

The same algorithm applies when picking a continuous “index” y , i.e. **picking a random variable according to a distribution** (e.g. a phase-space point)

The cumulative distribution becomes

$$C(y) = \int_{-\infty}^y dx p(x) \quad \text{with} \quad \int_{-\infty}^{\infty} dx p(x) = 1$$

which allows using $R \in [0, 1]$ and

$$C(y) = R \quad \Rightarrow \quad y = C^{-1}(R)$$

This is called inversion sampling.

Often, we're not so lucky that a uniquely **invertible primitive function** C^{-1} exists ...but we can often still use this method as part of a more flexible algorithm.

Exercise: Generate random variables $x > 0$ with distribution $f(x) = e^{-x}$

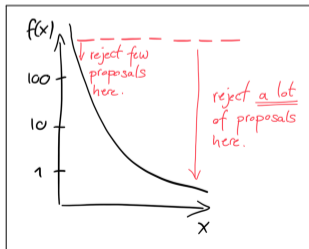
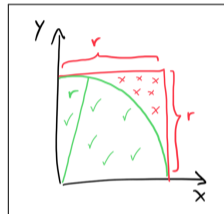
Rejection sampling

We can circumvent the issue with rejection sampling (a.k.a. hit-or-miss).

Basic idea: Use a simple distribution to pick x from, adjust rate once x is generated.

Example: Calculate π by random sampling:

- Draw $x, y \in [0, r]$
- Accept pair if $x^2 + y^2 < r^2$
- (fraction of accepted pairs) will be $\propto \pi/4$



In practise, “uniform sampling” often not sufficient – efficiency very bad!

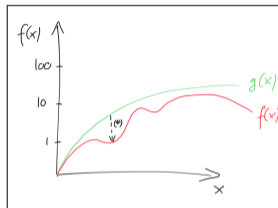
Combining the two

Rejection sampling will be much more efficient if combined with inversion sampling:

- Assume a simple distribution $g(x) > f(x)$, i.e.

$$f(x) = g(x) \underbrace{\frac{f(x)}{g(x)}}_{<1}$$

- Use inversion sampling to draw x from $g(x)$.
- Draw $R \in [0, 1]$. Reject x if $\frac{f(x)}{g(x)} < R$



\Rightarrow Accepted x now distributed according to $f(x)$. This algorithm is excessively used in Monte Carlo generators.

Comparison: Uniform sampling

$$\text{var}(f)_{MC} \approx \frac{\text{var}(f)}{\sqrt{N}}$$

error worse in regions of large variance...

Importance sampling

$$\int dx g(x) \frac{f(x)}{g(x)} \approx \left\langle \frac{f}{g} \right\rangle \pm \sqrt{\frac{\langle f^2/g^2 \rangle - \langle f/g \rangle^2}{N}}$$

Exercise: Generate random variables $0 < z < 1 - \epsilon$ with distribution $P(z) = \frac{1+z^2}{1-z}$. Hint: Use a simpler [numerator](#) to get a simple $g(z)$...

Measurements

Let's get back to physics for a bit :)
The measurement of an observable is

$$\langle O \rangle = \int d\phi_n \frac{d\sigma(A, B \rightarrow n \text{ particles})}{d\phi_n} O(\phi_n)$$

phase space differential cross section value of observable

...so we have to worry about

- sampling phase space points Φ_n
- calculating the differential cross section $\frac{d\sigma_n}{d\Phi_n}$
- evaluating the observable

Sampling factorization

When sampling phase space,

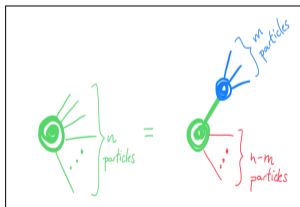
avoid large event weight fluctuations

avoid excessive rejection rate

⇒ Phase space generation separates enthusiasts from experts.

$$d\Phi_n = \left[\prod_{i=1}^n \frac{d\vec{p}_i}{(2\pi)^3 2E_i} \right] \delta(p_A + p_B - \sum_1^n p_i)$$

This $(3n - 4)$ dimensional integration can be sampled in factorized steps:



$$d\Phi_n = d\Phi_{n-m+1} \frac{ds_{1m}}{2\pi} d\Phi_m$$

...we can continue until only simple integrations ($d\Phi_2, d\Phi_3$) remain, and then find a **clever parameterization** for those.

Example

“Clever” parameterizations need knowledge about $d\sigma$.

Example: Sampling of $d\Phi_2$ stemming from decay of resonance V :

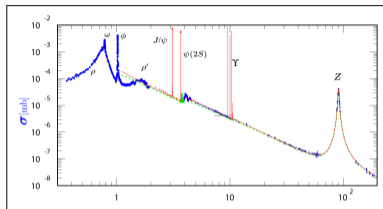
$$\frac{d\sigma_n}{d\Phi_n} \propto \frac{M_V \Gamma_V}{\left(\underbrace{(p_1 + p_2)^2}_{=\hat{s}} - M_V^2 \right)^2 + M_V^2 \Gamma_V^2}$$

The cumulative function is

$$\begin{aligned} C(\hat{s}_{min}, \hat{s}_{max}) &\propto I(\hat{s}_{max}) - I(\hat{s}_{min}) \\ &= \frac{1}{M_V \Gamma_V} \left[\text{atan} \left(\frac{\hat{s}_{max} - M_V^2}{M_V \Gamma_V} \right) - \text{atan} \left(\frac{\hat{s}_{min} - M_V^2}{M_V \Gamma_V} \right) \right] \end{aligned}$$

Finding the inverse, and using $R \in [0, 1]$, we may draw \hat{s} according to

$$\hat{s} = M_V^2 + M_V \Gamma_V \tan (M_V \Gamma_V [I(\hat{s}_{max}) - RC(\hat{s}_{min}, \hat{s}_{max})])$$



Basic thought: know your integrand & generate variables more often close to peaks.

Multichannel sampling

$$\left| \text{Diagram} \right|^2 = \left| \text{Diagram } P_1 \right|^2 + \left| \text{Diagram } P_2 \right|^2 + \text{interference}$$
$$f = g_1 + g_2$$

enhanced for $(P_1+P_2)^2 \rightarrow 0$ *enhanced for $(P_2+P_3)^2 \rightarrow 0$*

Differential cross sections have a rich structure. In that case, importance sampling can be **combined** with the discrete transformation method into multichannel sampling:

- Use $f(x) \leq g_1(x) + g_2(x)$
- Choose index $i \in \{1, 2\}$ [using $P_i = \int dx g_i(x)$]
- Draw x from $g_i(x)$. Overall, x is now distributed according to $g_1 + g_2$
- Draw $R \in [0, 1]$, and accept if (i, x) pair if $\frac{f(x)}{g_1(x)+g_2(x)} > R$. Else reject & restart.

NB: also heavily used in parton showers.

Exercise: Draw x from the distribution $f(x) = \frac{1}{\sqrt{x(1-x)}}$ using two integration channels.

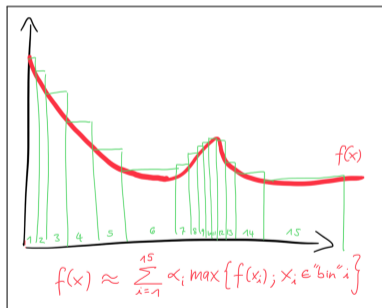
All of these methods require (analytical) knowledge of the differential cross section – which is often hard to come by.

Another way of “generating variables in integration regions where they matter most” is stratified sampling:

- Multichannel with $g_i \propto \max\{f\}$ in small integration region (=bin).
- Put more bins where variance of $f(x)$ is large.

This is the construction principle of VEGAS.

NB: Need to evaluate the function very often to learn good “integration grids”.



Phase-space integrators in MCs are a mix of all of these methods, and recently also more modern machine learning techniques.

Hands on: session I

Worksheet link