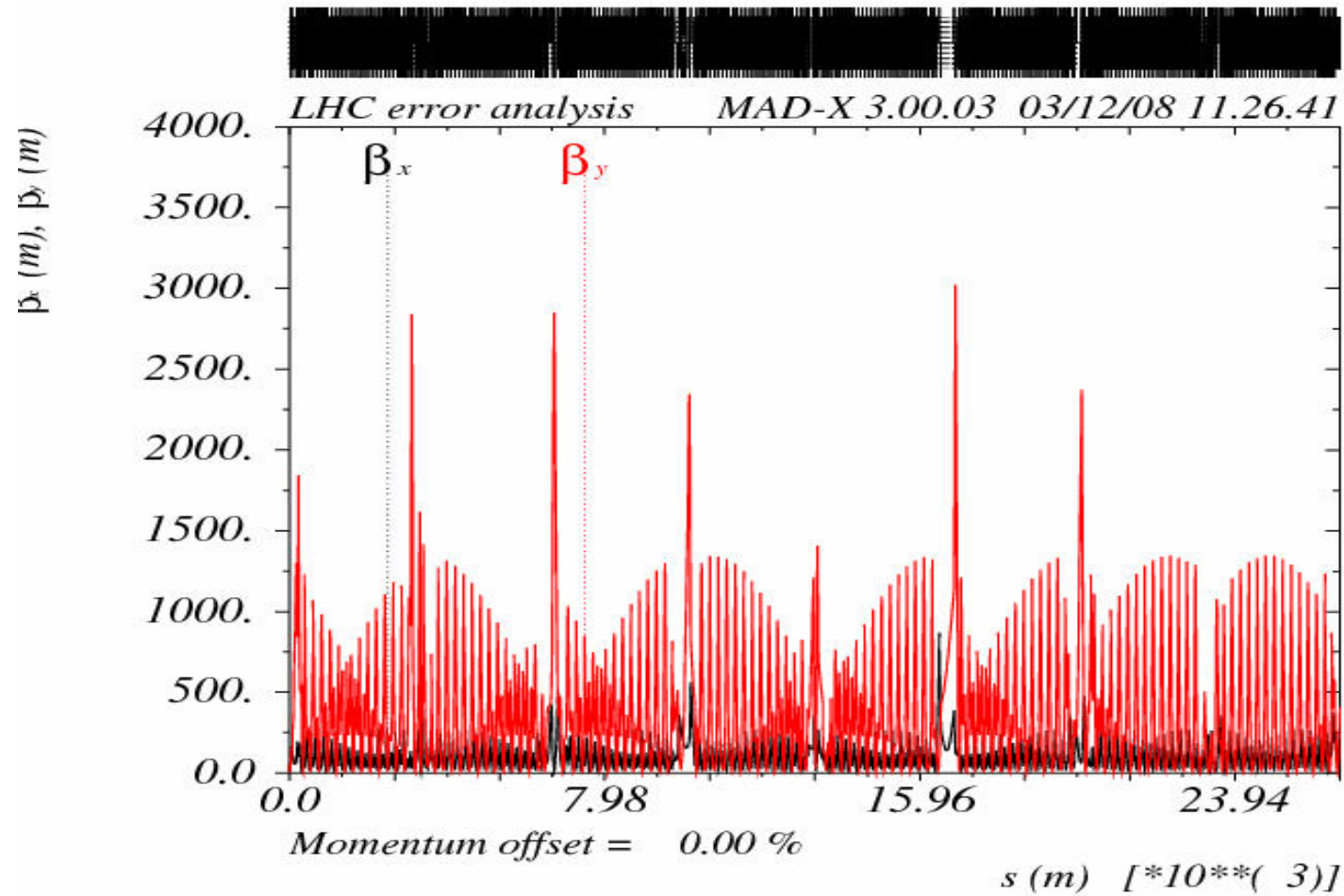


# *Error Analysis for the LHC Beam Optics*

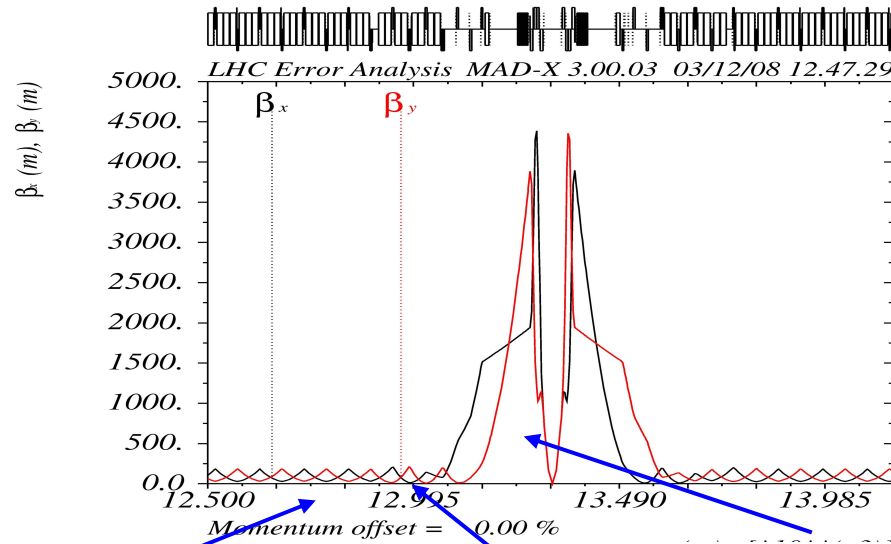
*Bernhard Holzer*

# Quadrupole Error

*... about things that should not happen and still occur from time to time.*

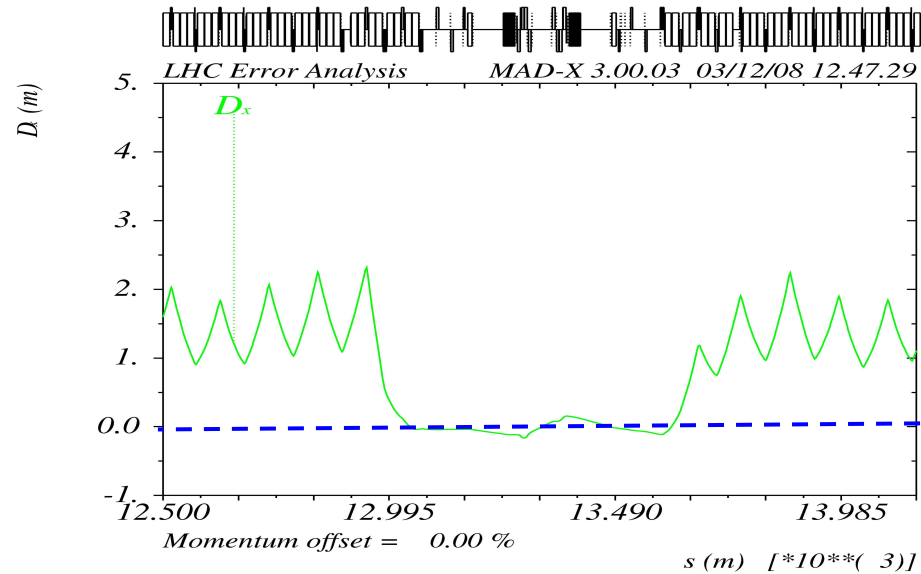


# Basic Layout of the Machine



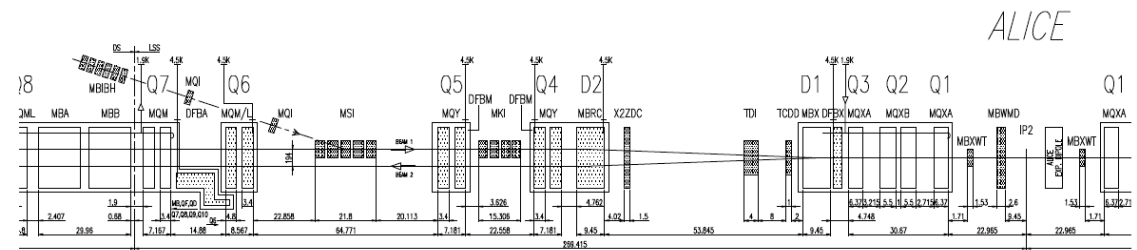
LHC Luminosity Optics in IR\_1 / 5

Arc ... Dispersion Suppressor ... Matching Section ... Triplet



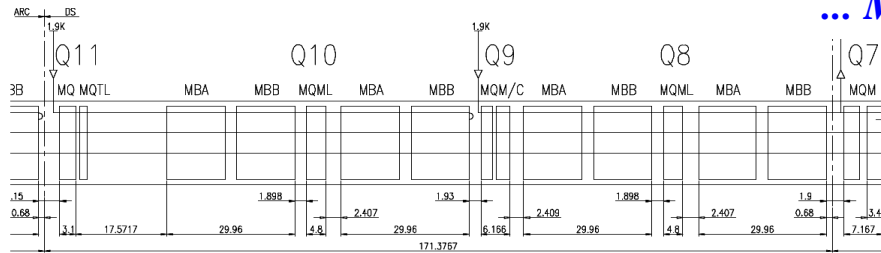
# LHC Lattice Layout

IR layout



... Matching Section

Triplet



Dispersion Suppressor ...

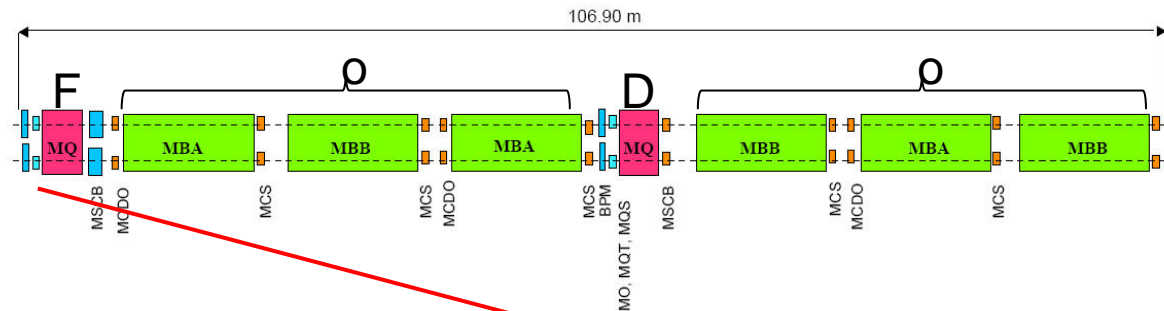


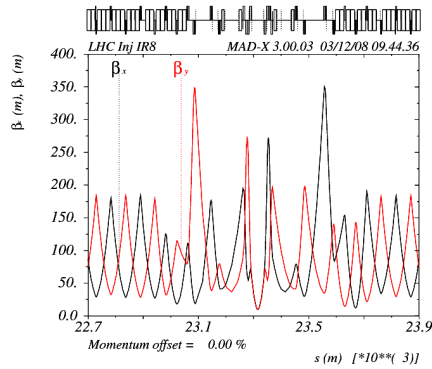
Table 3.3: Magn

	LSS													
	low- $\beta$ triplet			MS				DS			arc-cell			
Magnet #	Q1	Q2	Q3	Q4	Q5L	Q5R	Q6	Q7	Q8	Q9	Q10	QT11	QT12	QT13
Type:	XL	X	XL	Y	Y	M	M		ML	M	ML	TL		T
MQ- $L$ [m]	6.3	5.5	6.3	3.4					4.8	3.4 2.4	4.8	1.15	0.32	
$T$ [K]	1.9			4.5				1.9	1.9			1.9		
$B$ [T/m]	215 $\rightarrow$ 220			160				200	200			110	110	
$r$ [mm]	22.2	28.95	27.2	27.2	20.6		22.2	22.2			22.2			
	17.3	24.05	22.3	22.3	15.75		17.3	17.3			17.3			

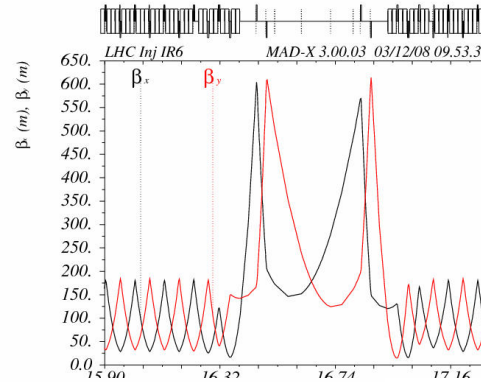
individually powered  
quadrupoles and trims at the  
beginning of the arc structure

# LHC: ... it is a messsss: eight IR's

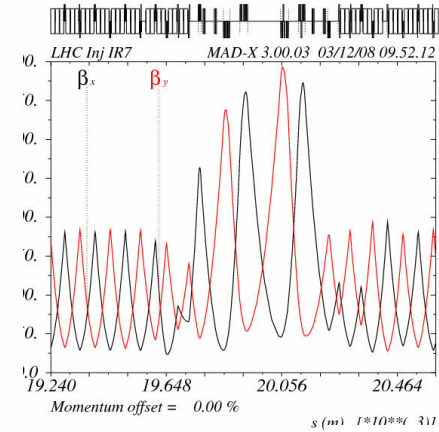
with individual lattices (i.e. quad positions),  
optics (i.e. quad values)  
with individual beat functions



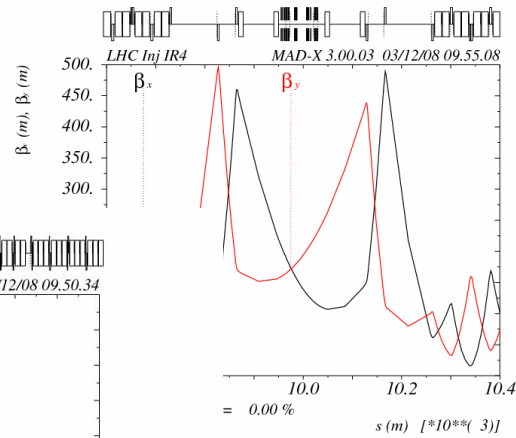
IR\_8



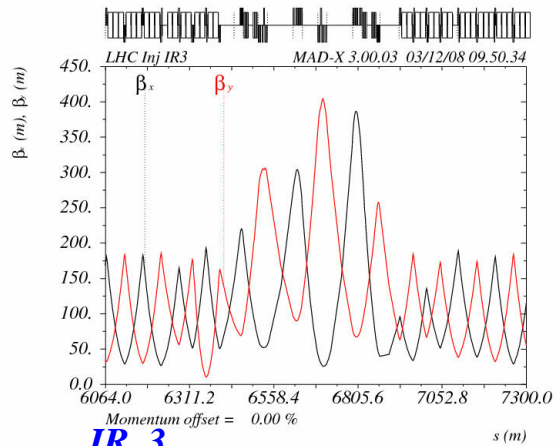
IR\_6



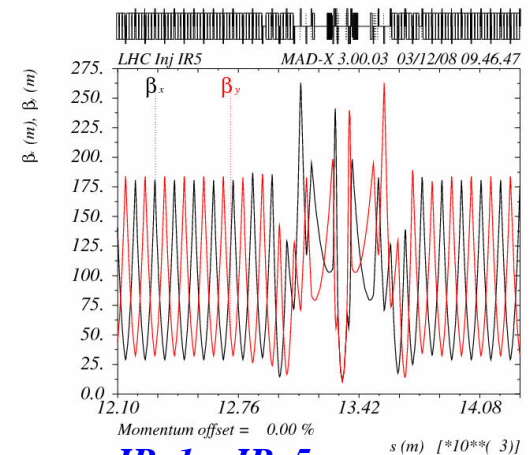
IR\_7



IR\_4



IR\_3

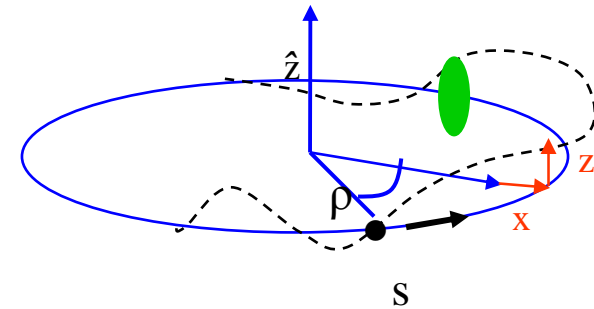


IR\_1 = IR\_5

# Quadrupole Errors

optic *perturbation* described by *thin lens quadrupole*

$$M_{dist} = M_{\Delta k} \cdot M_0 = \underbrace{\begin{pmatrix} 1 & 0 \\ \Delta k ds & 1 \end{pmatrix}}_{\text{quad error}} \cdot \underbrace{\begin{pmatrix} \cos\psi_{turn} + \alpha \sin\psi_{turn} & \beta \sin\psi_{turn} \\ -\gamma \sin\psi_{turn} & \cos\psi_{turn} - \alpha \sin\psi_{turn} \end{pmatrix}}_{\text{ideal storage ring}}$$



$$M_{dist} = \begin{pmatrix} \cos\psi_0 + \alpha \sin\psi_0 & \beta \sin\psi_0 \\ \Delta k ds (\cos\psi_0 + \alpha \sin\psi_0) - \gamma \sin\psi_0 & \Delta k ds \beta \sin\psi_0 + \cos\psi_0 - \alpha \sin\psi_0 \end{pmatrix}$$

*rule for getting the tune*

$$\text{Trace}(M) = 2 \cos \psi = 2 \cos \psi_0 + \Delta k ds \beta \sin \psi_0$$

*Quadrupole error → Tune Shift*

$$\psi = \psi_0 + \Delta\psi \quad \longrightarrow \quad \cos(\psi_0 + \Delta\psi) = \cos\psi_0 + \frac{\Delta k ds \beta \sin\psi_0}{2}$$

*remember the old fashioned trigonometric stuff and assume that the error is small !!!*

$$\underbrace{\cos\psi_0 \cos\Delta\psi}_{\approx 1} - \underbrace{\sin\psi_0 \sin\Delta\psi}_{\approx \Delta\psi} = \cos\psi_0 + \frac{k ds \beta \sin\psi_0}{2}$$

$$\Delta\psi = \frac{k ds \beta}{2}$$

*and referring to Q instead of  $\psi$ :*

$$\psi = 2\pi Q$$

$$\Delta Q = \int_{s_0}^{s_0+l} \frac{\Delta k(s) \beta(s) ds}{4\pi}$$

*the tune shift is proportional*

*! ... to the  $\beta$ -function*

*at the quadrupole :  $\beta \approx 50$  m in the arc*

*$\beta \approx 500$  m in the matching section*

*!! to the number of quadrupoles in series*

*!!! to the strength of the quadrupole*

*... for small errors only !!!*



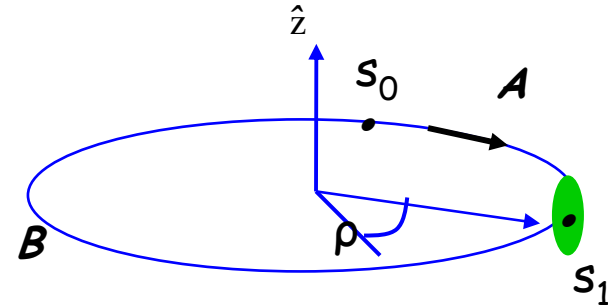


# Quadrupole Errors and Beta Function

*a quadrupole error will not only influence the oscillation frequency ... „tune“  
... but also the amplitude ... „beta function“*

$$M_{turn} = B * A \quad A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$$

$$B = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}$$



$$\text{distorted matrix } M_{dist} = \begin{pmatrix} m_{11}^* & m_{12}^* \\ m_{21}^* & m_{22}^* \end{pmatrix} = B \begin{pmatrix} 1 & 0 \\ -\Delta kds & 1 \end{pmatrix} A$$

$$M_{dist} = B \begin{pmatrix} a_{11} & a_{12} \\ -\Delta kds a_{11} + a_{12} & -\Delta kds a_{12} + a_{22} \end{pmatrix}$$

$$M_{dist} = \begin{pmatrix} \sim & b_{11} a_{12} + b_{12} (-\Delta kds a_{12} + a_{22}) \\ \sim & \sim \end{pmatrix}$$

*the beta function is usually obtained via the matrix element „m12“, which is in Twiss form for the undistorted case*

$$m_{12} = \beta_0 \sin 2\pi Q$$

*and including the error:*

$$m_{12}^* = \underbrace{b_{11}a_{12} + b_{12}a_{22} - b_{12}a_{12}\Delta kds}$$

$$m_{12} = \beta_0 \sin 2\pi Q$$

$$(1) \quad m_{12}^* = \beta_0 \sin 2\pi Q - a_{12}b_{12}\Delta kds$$

*As  $M^*$  is still a matrix for one complete turn we still can express the  $m_{12}$  in twiss form:*

$$(2) \quad m_{12}^* = (\beta_0 + d\beta) * \sin 2\pi(Q + dQ)$$

*Equalising (1) and (2) and assuming a small error*

$$\beta_0 \sin 2\pi Q - a_{12}b_{12}\Delta kds = (\beta_0 + d\beta) * \sin 2\pi(Q + dQ)$$

$$\beta_0 \sin 2\pi Q - a_{12}b_{12}\Delta kds = (\beta_0 + d\beta) * \underbrace{\sin 2\pi Q \cos 2\pi dQ}_{\approx 1} + \underbrace{\cos 2\pi Q \sin 2\pi dQ}_{\approx 2\pi dQ}$$

$$\cancel{\beta_0 \sin 2\pi Q} - a_{12} b_{12} \Delta k ds = \cancel{\beta_0 \sin 2\pi Q} + \beta_0 2\pi dQ \cos 2\pi Q + d\beta_0 \sin 2\pi Q + \cancel{d\beta_0 2\pi dQ \cos 2\pi Q}$$

*ignoring second order terms*

$$- a_{12} b_{12} \Delta k ds = \beta_0 2\pi dQ \cos 2\pi Q + d\beta_0 \sin 2\pi Q$$

*remember: tune shift  $dQ$  due to quadrupole error:  $dQ = \frac{\Delta k \beta_1 ds}{4\pi}$   
(index „1“ refers to location of the error)*

$$- a_{12} b_{12} \Delta k ds = \frac{\beta_0 \Delta k \beta_1 ds}{2} \cos 2\pi Q + d\beta_0 \sin 2\pi Q$$

*solve for  $d\beta$*

$$d\beta_0 = \frac{-1}{2 \sin 2\pi Q} \{2 a_{12} b_{12} + \beta_0 \beta_1 \cos 2\pi Q\} \Delta k ds$$

*express the matrix elements  $a_{12}$ ,  $b_{12}$  in Twiss form*

$$M = \begin{pmatrix} \sqrt{\frac{\beta_s}{\beta_0}} (\cos \psi_s + \alpha_0 \sin \psi_s) & \sqrt{\beta_s \beta_0} \sin \psi_s \\ \frac{(\alpha_0 - \alpha_s) \cos \psi_s - (1 + \alpha_0 \alpha_s) \sin \psi_s}{\sqrt{\beta_s \beta_0}} & \sqrt{\frac{\beta_0}{\beta_s}} (\cos \psi_s - \alpha_s \sin \psi_s) \end{pmatrix}$$

$$d\beta_0 = \frac{-1}{2 \sin 2\pi Q} \{2a_{12}b_{12} + \beta_0\beta_1 \cos 2\pi Q\} \Delta k ds$$

$$a_{12} = \sqrt{\beta_0\beta_1} \sin \Delta \psi_{0 \rightarrow 1}$$

$$b_{12} = \sqrt{\beta_1\beta_0} \sin(2\pi Q - \Delta \psi_{0 \rightarrow 1})$$

$$d\beta_0 = \frac{-\beta_0\beta_1}{2 \sin 2\pi Q} \{2 \sin \Delta \psi_{12} \sin(2\pi Q - \Delta \psi_{12}) + \cos 2\pi Q\} \Delta k ds$$

... after some TLC transformations ... =  $\cos(2\Delta \psi_{01} - 2\pi Q)$

$$\Delta\beta(s_0) = \frac{-\beta_0}{2 \sin 2\pi Q} \int_{s_1}^{s_1+l} \beta(s_1) \Delta k \cos(2(\psi_{s_1} - \psi_{s_0}) - 2\pi Q) ds$$

*Nota bene:*

**!** the beta beat is *proportional to the strength of the error  $\Delta k$*

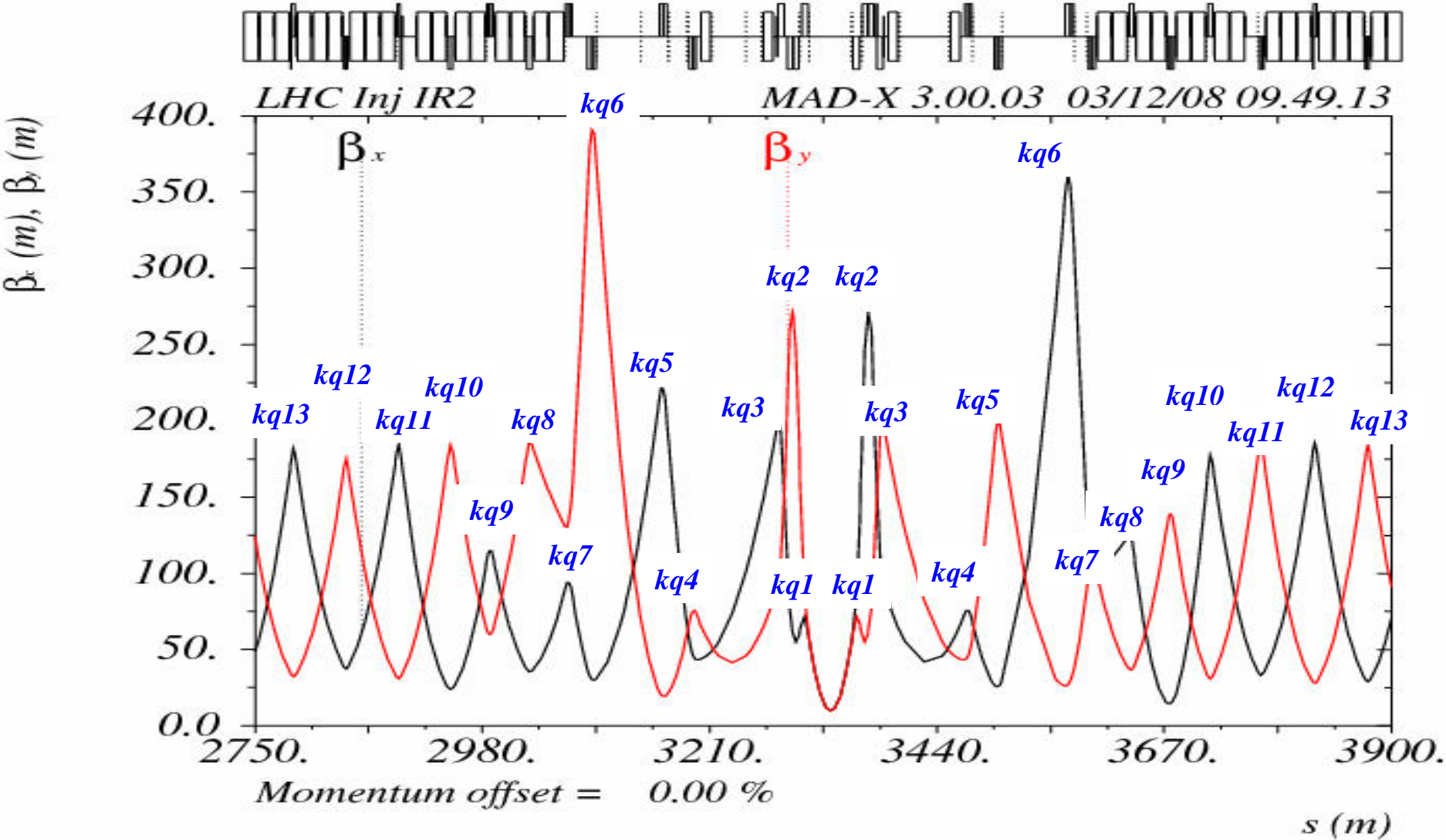
**!!** and to the  *$\beta$  function at the place of the error*,

**!!!** and to the  *$\beta$  function at the observation point*,

**!!!!** *proceeds as double the phase advance*

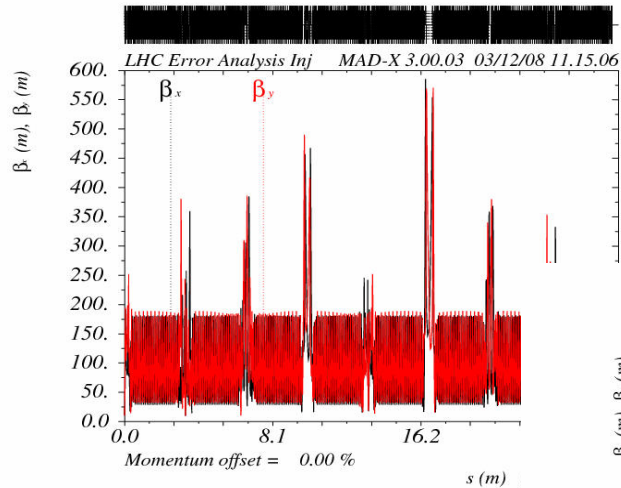
**!!!!** *there is a resonance denominator*

en detail: *LHC Injection Optics IR\_2*

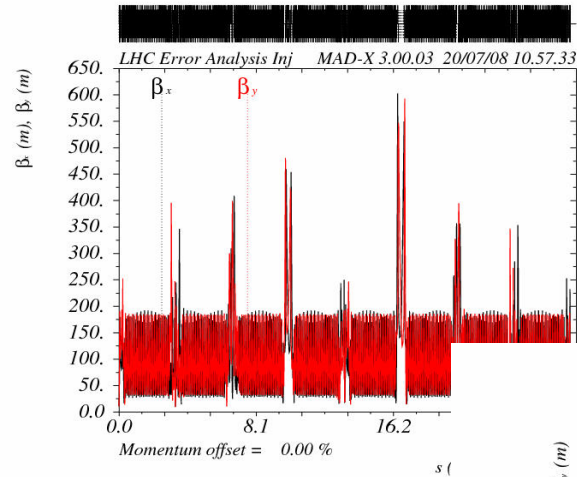


# Absolute Beta function

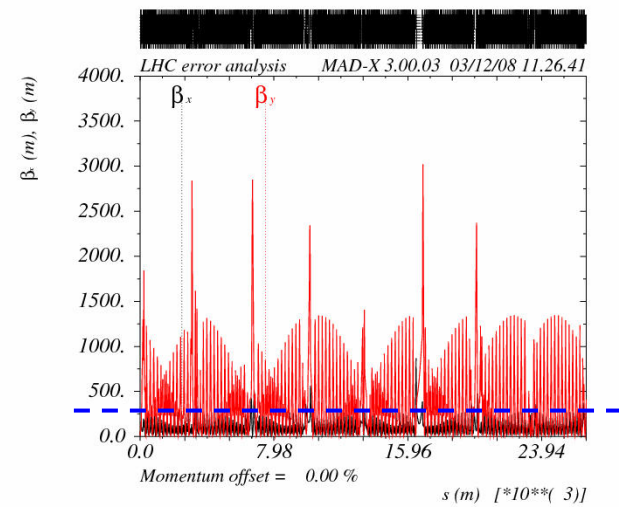
after trip of different quadrupoles in IR\_2



**kqt12 0.6 / 2.4 %**



**kqt12 12 / 2.4 %**



**kq 5 52 / 650 %**

## Cross Check with analytical formula:

Example: IR 2 ... Inj. Optics

kqtl11.r2.b1

$$\Delta\beta(s_0) = \frac{-\beta_0}{2 \sin 2\pi Q} \int_{s_1}^{s_1+l} \beta(s_1) \Delta k \underbrace{\cos(2(\psi_{s_1} - \psi_{s_0}) - 2\pi Q)}_{\approx 1} ds$$

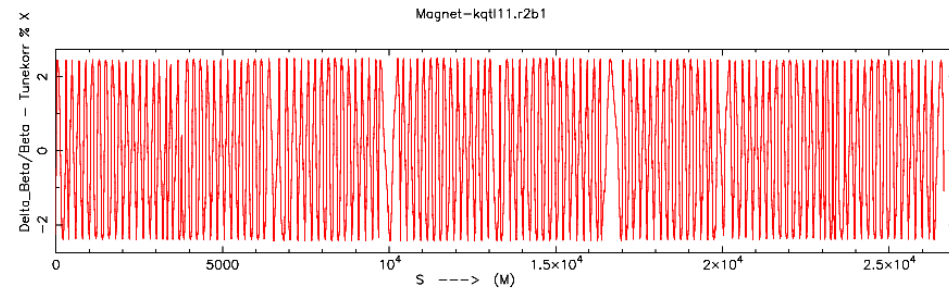
$$Q_x \approx 64.31$$

$$Q_y \approx 59.32$$

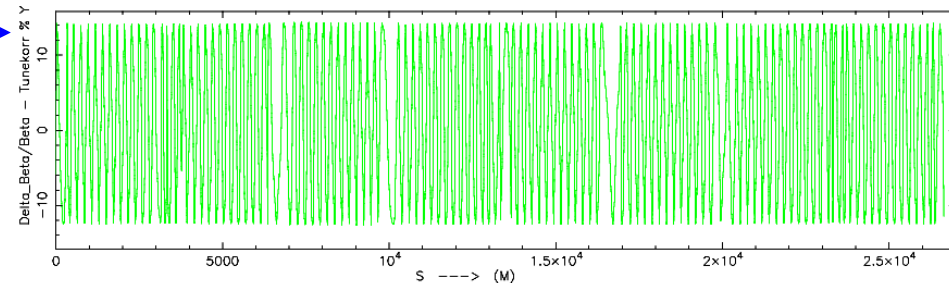
$$\frac{\Delta\beta}{\beta} \approx \frac{1}{2 \sin 2\pi Q} \beta_Q \Delta k * l_Q \approx 1$$

$$\frac{\Delta\beta}{\beta} \approx \frac{1}{2 \sin (2\pi * 0.31)} 180m * 1.06 * 10^{-3} \frac{1}{m^2} :$$

$$\frac{\Delta\beta}{\beta} \approx 13 \%$$



$$\frac{\Delta\beta}{\beta} \approx 12 \%$$

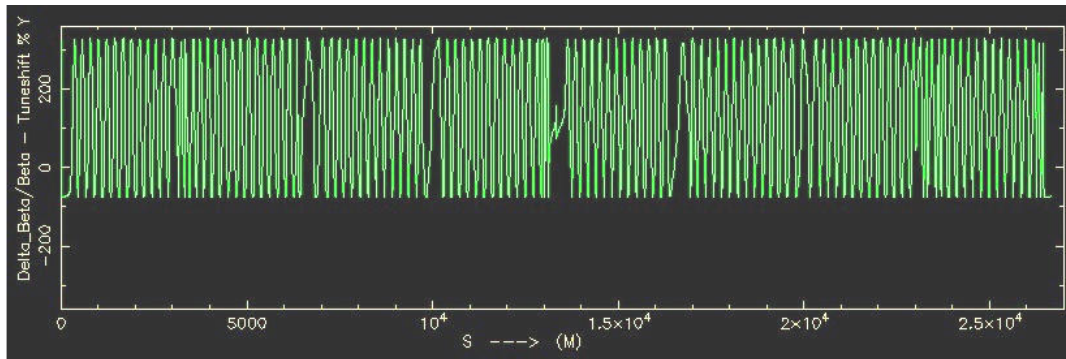


# Tune Problem:

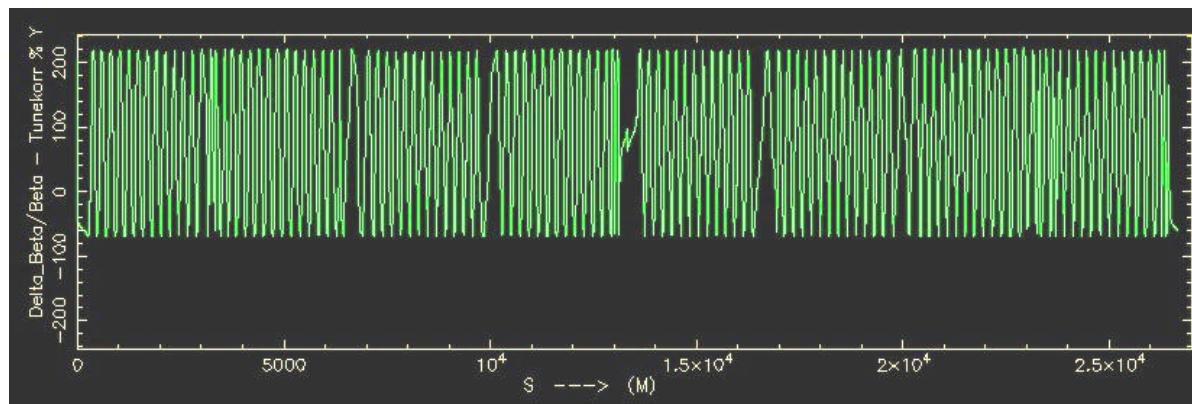
*tune shift can increase the beta beat "ad infinitum"*

$$\Delta\beta(s_0) = \frac{\beta_0}{2 \sin 2\pi Q} \int_{s_1}^{s_1+l} \beta(s_1) \Delta K \cos(2|\psi_{s_1} - \psi_{s_0}| - 2\pi Q) ds$$

$$\Delta Q = \int_{s_0}^{s_0+l} \frac{\Delta k(s) \beta(s) ds}{4\pi}$$



*beta beat  $\Delta\beta / \beta \approx 350\%$   
without tune correction*

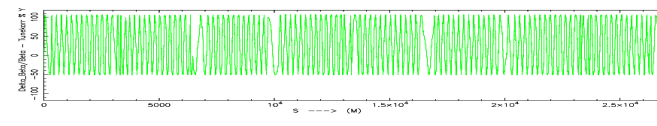
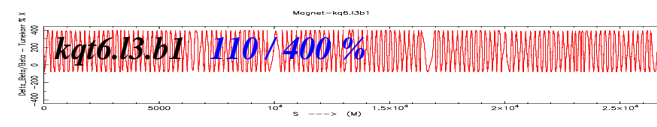
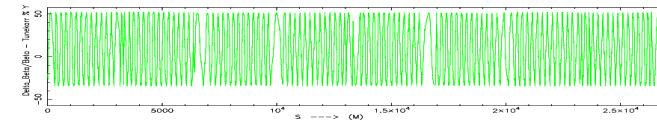
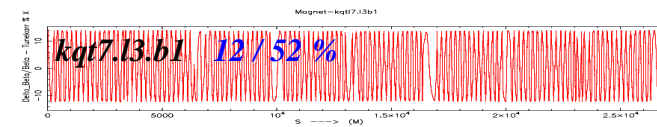
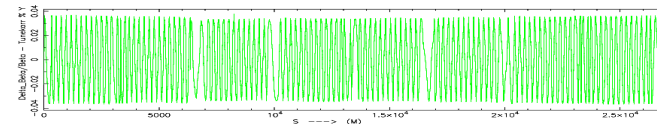
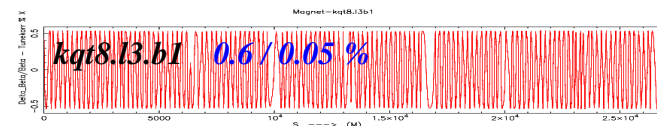
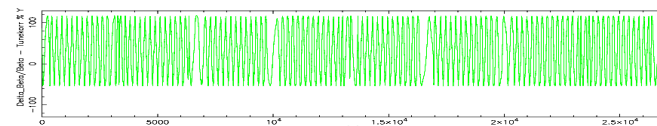
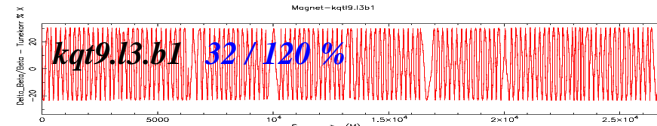
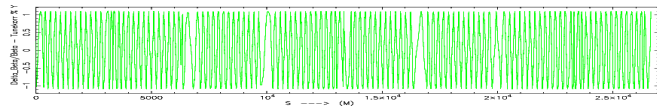
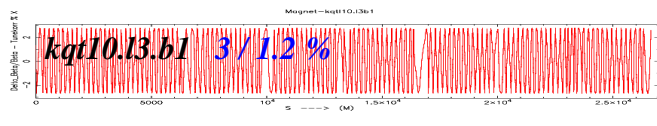
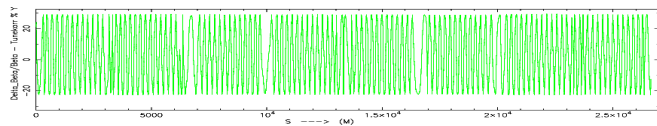
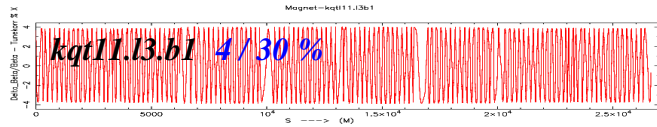
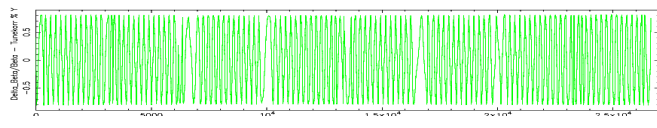
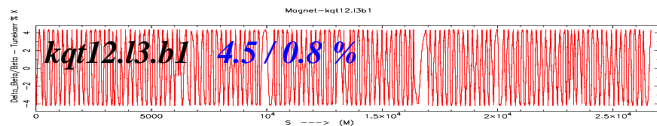
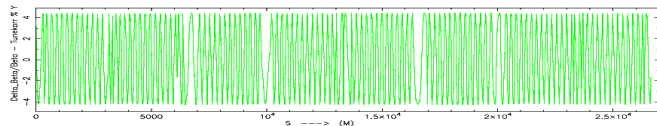
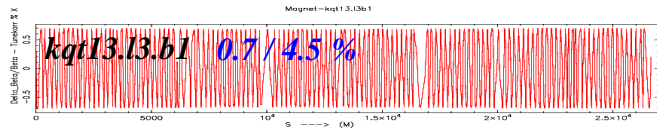


*beta beat  $\Delta\beta / \beta \approx 220\%$   
with tune correction*



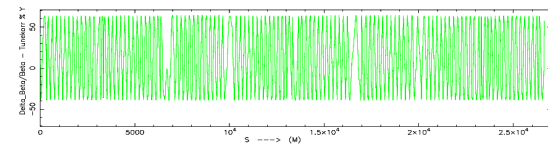
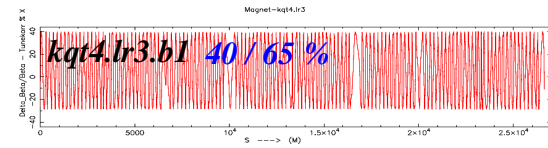
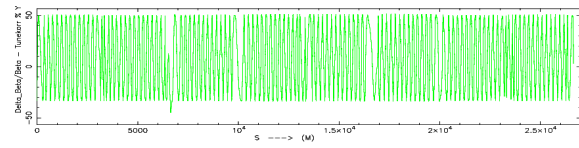
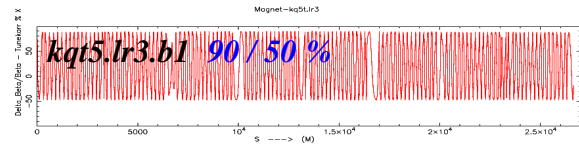
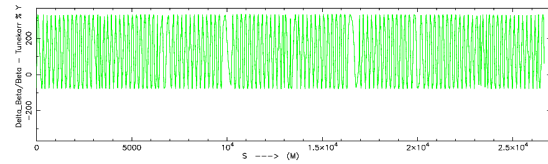
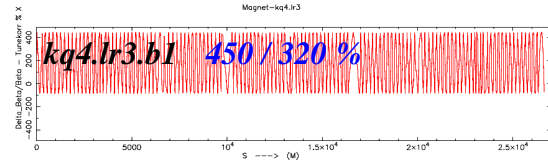
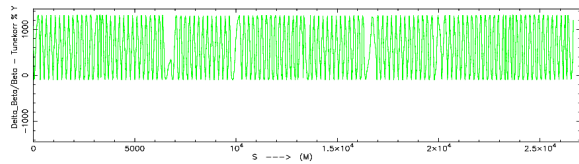
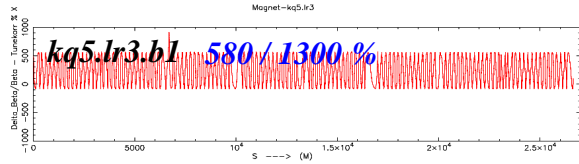
# Example: IR\_3

$\Delta\beta / \beta \dots$  in %



# Example: IR\_3

$\Delta\beta / \beta \dots$  in %



## Résumé:

### beta beat $\Delta\beta/\beta$ for the horizontal / vertical plane

#### IR\_8

<i>kqt</i> 13.r8.b1	1 / 6	%	<i>kqt</i> 13.l8.b1	1.4 / 0.3	%
<i>kqt</i> 12.r8.b1	1.4 / 10	%	<i>kqt</i> 12.l8.b1	1.1 / 7.2	%
<i>kqt</i> l11.r8.b1	6 / 33	%	<i>kqt</i> l11.l8.b1	7.5 / 1.3	%
<i>kq</i> 10.r8.b1	600 / 50	%	<i>kq</i> 10.l8.b1	52 / 520	%
<i>kq</i> 9.r8.b1	28 / 600	%	<i>kq</i> 9.l8.b1	420 / 85	%
<i>kq</i> 8.r8.b1	420 / 27	%	<i>kq</i> 8.l8.b1	22 / 210	%
<i>kq</i> 7.r8.b1	290 / 550	%	<i>kq</i> 7.l8.b1	410 / 85	%
<i>kq</i> 6.r8.b1	1000 / 70	%	<i>kq</i> 6.l8.b1	50 / 1400	%
<i>kq</i> 5.r8.b1	60 / 600	%	<i>kq</i> 5.l8.b1	600 / 100	%
<i>kq</i> 4.r8.b1	210 / 105	%	<i>kq</i> 4.l8.b1	85 / 190	%

#### IR\_7

<i>kqt</i> 13.r7.b1	9 / 1.9	%	<i>kqt</i> 13.l7.b1	0.3 / 1.4	%
<i>kqt</i> 12.r7.b1	1.3 / 6.4	%	<i>kqt</i> 12.l7.b1	0.6 / 0.1	%
<i>kqt</i> l11.r7.b1	6.2 / 1	%	<i>kqt</i> l11.l7.b1	2.0 / 12	%
<i>kqtl</i> 10.r7.b1	0.05 / 0.3	%	<i>kqtl</i> 10.l7.b1	50 / 11	%
<i>kqtl</i> 9.r7.b1	25 / 14	%	<i>kqtl</i> 9.l7.b1	0.3 / 2.0	%
<i>kqtl</i> 8.r7.b1	8 / 48	%	<i>kqtl</i> 8.l7.b1	8 / 7	%
<i>kqtl</i> 7.r7.b1	6.5 / 5	%	<i>kqtl</i> 7.l7.b1	4 / 8	%
<i>kq</i> 6.r7.b1	75 / 330	%	<i>kq</i> 6.l7.b1	620 / 80	%
<i>kq</i> 5.l7.b1	1000 / 1250	%	<i>kq</i> 4.l7.b1	1100 / 1200	%
<i>kqt</i> 5.l7.b1	2 / 1.6	%	<i>kqt</i> 4.l7.b1	19 / 21	%

# Résumé

## IR\_6

<i>kqt</i> 13.r6.b1	1 / 1	%	<i>kqt</i> 13.l6.b1	1 / 1	%
<i>kqt</i> 12.r6.b1	16 / 3	%	<i>kqt</i> 12.l6.b1	0.8 / 6	%
<i>kqt</i> l11.r6.b1	3 / 16	%	<i>kqt</i> l11.l6.b1	10 / 1.8	%
<i>kq</i> 10.r6.b1	500 / 110	%	<i>kq</i> 10.l6.b1	42 / 500	%
<i>kq</i> 9.r6.b1	32 / 600	%	<i>kq</i> 9.l6.b1	420 / 120	%
<i>kq</i> 8.r6.b1	230 / 25	%	<i>kq</i> 8.l6.b1	14 / 200	%
<i>kq</i> 5.r6.b1	280 / 1400	%	<i>kq</i> 5.l6.b1	850 / 220	%
<i>kq</i> 4.r6.b1	900 / 300	%	<i>kq</i> 4.l6.b1	----- / ----	%

## IR\_5 & IR\_1

<i>kqt</i> 13.r5.b1	6.5 / 1.7	%	<i>kqt</i> 13.l5.b1	1.4 / 11	%
<i>kqt</i> 12.r5.b1	1.4 / 6.0	%	<i>kqt</i> 12.l5.b1	3 / 0.5	%
<i>kqt</i> l11.r5.b1	2.2 / 0.4	%	<i>kqt</i> l11.l5.b1	3.1 / 0.5	%
<i>kq</i> 10.r5.b1	55 / 650	%	<i>kq</i> 10.l5.b1	600 / 56	%
<i>kq</i> 9.r5.b1	500 / 34	%	<i>kq</i> 9.l5.b1	33 / 520	%
<i>kq</i> 8.r5.b1	32 / 380	%	<i>kq</i> 8.l5.b1	360 / 33	%
<i>kq</i> 7.r5.b1	320 / 210	%	<i>kq</i> 7.l5.b1	170 / 350	%
<i>kq</i> 6.r5.b1	30 / 650	%	<i>kq</i> 6.l5.b1	620 / 140	%
<i>kq</i> 5.r5.b1	420 / 240	%	<i>kq</i> 5.l5.b1	260 / 450	%
<i>kq</i> 4.r5.b1	80 / 220	%	<i>kqt</i> 4.l5.b1	220 / 85	%

# Résumé

## IR\_4

<i>kqt</i> 13.r4.b1	1 / 1	%	<i>kqt</i> 13.l4.b1	1 / 1	%
<i>kqt</i> 12.r4.b1	12 / 2	%	<i>kqt</i> 12.l4.b1	0.2 / 1.5	%
<i>kqt</i> l11.r4.b1	2 / 10	%	<i>kqt</i> l11.l4.b1	4 / 0.8	%
<i>kq</i> 10.r4.b1	510 / 100	%	<i>kq</i> 10.l4.b1	55 / 520	%
<i>kq</i> 9.r4.b1	30 / 480	%	<i>kq</i> 9.l4.b1	430 / 75	%
<i>kq</i> 8.r4.b1	310 / 70	%	<i>kq</i> 8.l4.b1	28 / 280	%
<i>kq</i> 7.r4.b1	90 / 140	%	<i>kq</i> 7.l4.b1	280 / 80	%
<i>kq</i> 6.r4.b1	900 / 180	%	<i>kq</i> 6.l4.b1	210 / 990	%
<i>kq</i> 5.r4.b1	200 / 700	%	<i>kq</i> 5.l4.b1	700 / 240	%

## IR\_3

<i>kqt</i> 13.r3.b1	13 / 3	%	<i>kqt</i> 13.l3.b1	0.7 / 4.5	%
<i>kqt</i> 12.r3.b1	3 / 12	%	<i>kqt</i> 12.l3.b1	4.5 / 0.8	%
<i>kqt</i> l11.r3.b1	60 / 13	%	<i>kqt</i> l11.l3.b1	4 / 30	%
<i>kqtl</i> 10.r3.b1	11 / 36	%	<i>kqtl</i> 10.l3.b1	3 / 1.2	%
<i>kqtl</i> 9.r3.b1	4.5 / 2.7	%	<i>kqtl</i> 9.l3.b1	32 / 120	%
<i>kqtl</i> 8.r3.b1	6 / 35	%	<i>kqtl</i> 8.l3.b1	0.6 / 0.05	%
<i>kqtl</i> 7.r3.b1	2.4 / 2	%	<i>kqtl</i> 7.l3.b1	12 / 52	%
<i>kq</i> 6.r3.b1	52 / 480	%	<i>kq</i> 6.l3.b1	110 / 400	%
<i>kq</i> 5.lr3.b1	580 / 1300	%	<i>kq</i> 4.lr3.b1	450 / 320	%
<i>kqt</i> 5.lr3.b1	90 / 50	%	<i>kqt</i> 4.lr3.b1	40 / 65	%

# Résumé

## IR\_2

<i>kqt</i> 13.r2.b1	1.2 / 9	%
<i>kqt</i> 12.r2.b1	9 / 1.4	%
<i>kqt</i> l11.r2.b1	2.5 / 12	%
<i>kq</i> 10.r2.b1	580 / 72	%
<i>kq</i> 9.r2.b1	25 / 400	%
<i>kq</i> 8.r2.b1	270 / 70	%
<i>kq</i> 7.r2.b1	380 / 420	%
<i>kq</i> 6.r2.b1	1250 / 70	%
<i>kq</i> 5.r2.b1	52 / 650	%
<i>kq</i> 4.r2.b1	200 / 110	%

<i>kqt</i> 13.l2.b1	12 / 2.4	%
<i>kqt</i> 12.l2.b1	0.6 / 2.4	%
<i>kqt</i> l11.l2.b1	0.6 / 0.2	%
<i>kq</i> 10.l2.b1	38 / 450	%
<i>kq</i> 9.l2.b1	350 / 150	%
<i>kq</i> 8.l2.b1	38 / 290	%
<i>kq</i> 7.l2.b1	310 / 480	%
<i>kq</i> 6.l2.b1	63 / 1400	%
<i>kq</i> 5.l2.b1	650 / 40	%
<i>kq</i> 4.l2.b1	120 / 230	%