Beam Emittance by 3 Screen Method

Task: Measure the Emittance of the Laser Beam

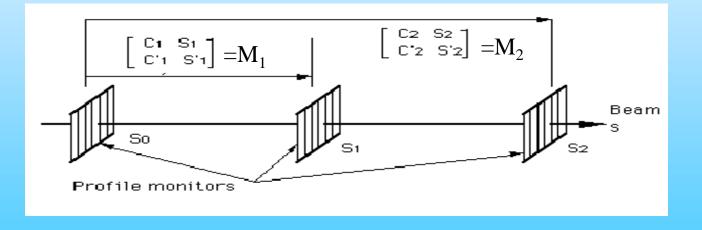
Your tasks in green frames

Three screen method:

If β is known unambiguously as in a circular machine, then a single profile measurement determines ϵ by

 $\sigma_y^2 = \epsilon \beta_y$.

But it is not easy to be sure in a transfer line which β to use, or rather, whether the beam that has been measured is matched to the β -values used for the line. This problem can be resolved by using three monitors (see Fig. 1), i.e. the three width measurement determines the three unknown α , β and ε of the incoming beam.



Introduction of σ -Matrix (see for example: K. Wille; Physik der Teilchenbeschleuniger, Teubner)

$$\sigma = \begin{pmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{pmatrix} = \begin{pmatrix} \sigma_{y}^{2} & \sigma_{yy'} \\ \sigma_{yy'} & \sigma_{y'}^{2} \end{pmatrix} = \varepsilon_{rms} \begin{pmatrix} \beta & -\alpha \\ -\alpha & \gamma \end{pmatrix} = \sigma \text{ matrix}$$

$$rms = \sqrt{\det \sigma} = \sqrt{\sigma_{11}\sigma_{22} - \sigma_{12}^{2}} \qquad (\beta\gamma - \alpha^{2} = 1)$$

Beam width_{rms} of measured profile = $\sigma_y \not\in \sigma_{11} = \sqrt{\beta(s) \cdot \varepsilon}$

Transformation of σ -Matrix through the elements of an accelerator:

$$\sigma_{s1} = M \cdot \sigma_{s0} \cdot M^{t} \qquad M = \begin{pmatrix} M_{11} & M_{12} \\ M_{21} & M_{22} \end{pmatrix}; M^{t} = \begin{pmatrix} M_{11} & M_{21} \\ M_{12} & M_{22} \end{pmatrix}$$

 L_1 , L_2 = distances between screens or from Quadrupole to screen and Quadrupole field strength are given, therefore the transport matrix M is known. Applying the transport matrix gives:

$$\sigma_{s_{1}} = M \cdot \sigma_{s_{0}} \cdot M'$$

$$= \begin{pmatrix} M_{11} & M_{12} \\ M_{21} & M_{22} \end{pmatrix} \cdot \begin{pmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{pmatrix}_{s_{0}} \cdot \begin{pmatrix} M_{11} & M_{21} \\ M_{12} & M_{22} \end{pmatrix} = \sigma^{measured} = \begin{pmatrix} \sigma_{y}^{2} & \sigma_{yy} \\ \sigma_{y'y} & \sigma_{y'}^{2} \end{pmatrix}_{s_{1}}^{measured} = \varepsilon_{rms} \begin{pmatrix} \beta & -\alpha \\ -\alpha & \gamma \end{pmatrix}$$

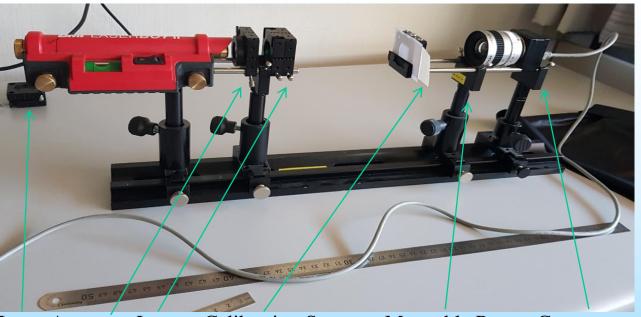
$$= \begin{pmatrix} M_{11} & M_{12} \\ M_{21} & M_{22} \end{pmatrix} \cdot \begin{pmatrix} \sigma_{11}M_{11} + \sigma_{12}M_{12} & \sigma_{11}M_{21} + \sigma_{12}M_{22} \\ \sigma_{21}M_{11} + \sigma_{22}M_{12} & \sigma_{12}M_{21} + \sigma_{22}M_{22} \end{pmatrix}$$

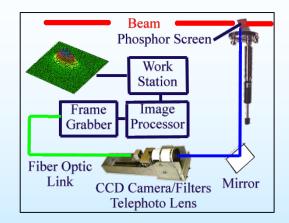
$$= \begin{pmatrix} M_{11}(\sigma_{11}M_{11} + \sigma_{12}M_{12}) + M_{12}(\sigma_{21}M_{11} + \sigma_{22}M_{12}) & \cdots \\ \cdots & \cdots & \cdots \end{pmatrix}$$

$$\sigma(s_{n})_{1})^{new} = \sigma^{2}(s_{n})_{y}^{new} = M_{11}^{2}\sigma(s_{0})_{11} + 2M_{11}M_{12}\sigma(s_{0})_{12} + M_{12}^{2}\sigma(s_{0})_{22} \quad (\sigma_{12} = \sigma_{21}) \quad (1)$$
transferred beam width at s_{n} measured beam width at s_{0} unknown
Solving $\sigma(s_{n})_{1} \sigma(s_{0})_{12}$ and $\sigma(s_{0})_{22}$ while Matrix elements are known: Needs minimum of three

Solving $\sigma(s_n)_{11} \sigma(s_0)_{12}$ and $\sigma(s_0)_{22}$ while Matrix elements are known: <u>Needs minimum of three</u> (n=0,1,2) different measurements, either three screens or three different Quadrupole settings with different field strength.

$$\varepsilon_{rms} = \sqrt{\det \sigma} = \sqrt{\sigma_{11}\sigma_{22} - \sigma_{12}^2} \quad (2)$$





Laser Aperture Lense Calibration Screen Moveable Part Camera

By moving screen (together with the camera) one can take pictures from three positions (avoid the focus due to limited resolution of the optic system). The distance of the lens to various screen positions can be measured by a simple ruler. The camera is connected to a Computer where the readout software is installed. The pictures (.jpg) can be saved and can be loaded into a free software called "ImageJ" where a profile of an area can be displayed and the curser position and the value is displayed (8 bit). The σ of the profile have to be found for each screen position and the emittance have to be calculated.

Your tasks in green frames

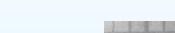
Calibration

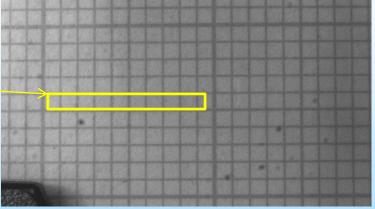
Use mm-grid to calibrate the readout setup.

Select ROI (where beam image will appear), plot profile, use cursor and enter measurement into pre-prepared Excel sheet "Laser emittance.xlsx"

> Plot of calibration 787.93x108.03 pixels (530x255); 8-bit; 132K 180 160 **Gray Value** 140 120 100 200 400 600 Distance (pixels) List Save... More » Live

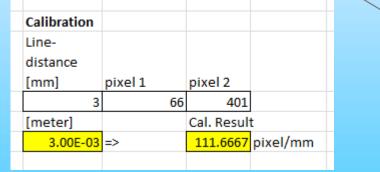
All yellow cells will be calculated automatically

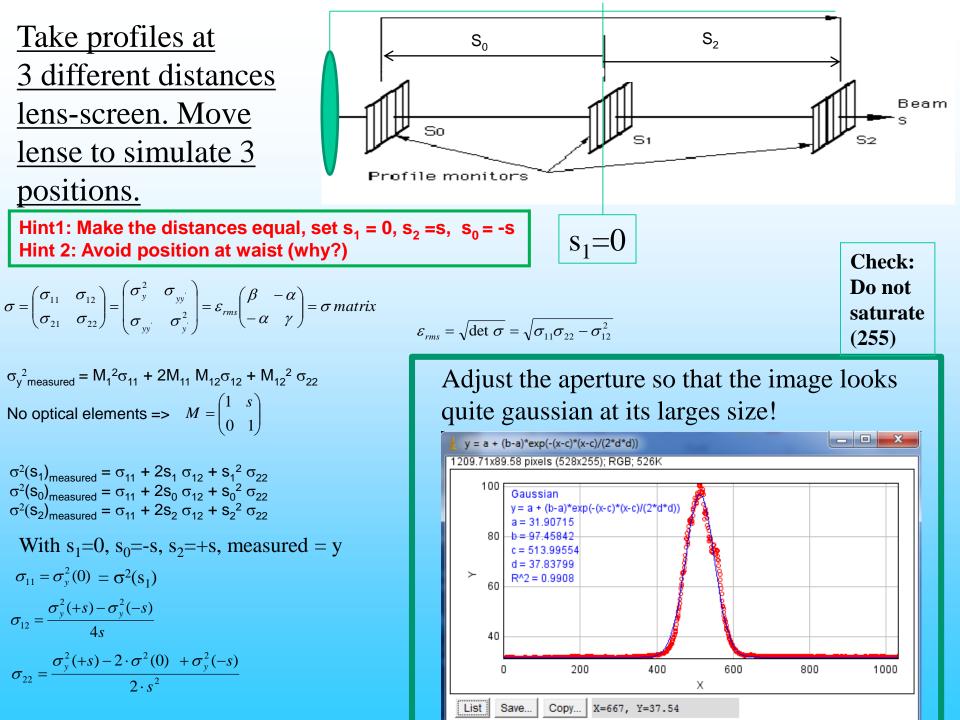


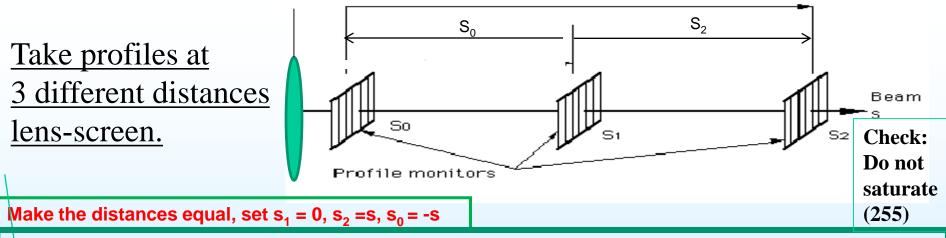


Check: Do not saturate

(255)

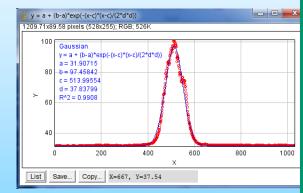


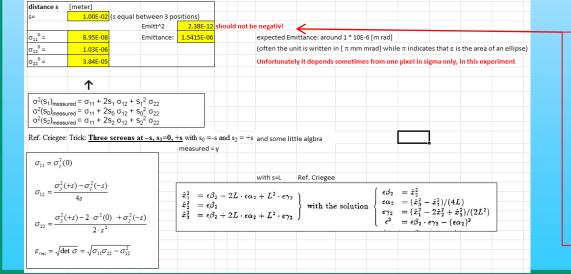




Enter the screen positons +s, 0, -s and the measured σ from fits (in pixel) at +s, 0 and -s into the Excel sheet:

				sigma [p]	sigma(s) [m]
$\boldsymbol{\Lambda}$						
V	So	-1,00E-02		37.8	3.38E-04	Take FWHM/2.36 if not Gaussian!
			1,00E-02			
	S1=0	0,00E+00		33.5	2.99E-04	Take FWHM/2.36 if not Gaussian!
			1,00E-02			
	s.	1,00E-02		30.2	2.70E-04	Take FWHM/2.36 if not Gaussian!
		,				

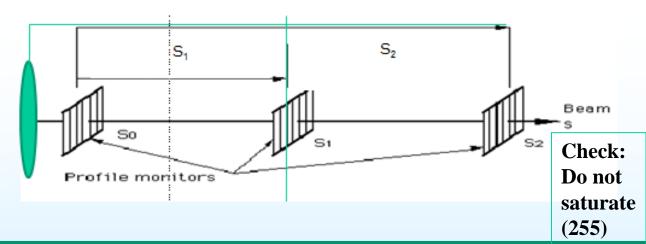




The emittance is calculated by the formulas.

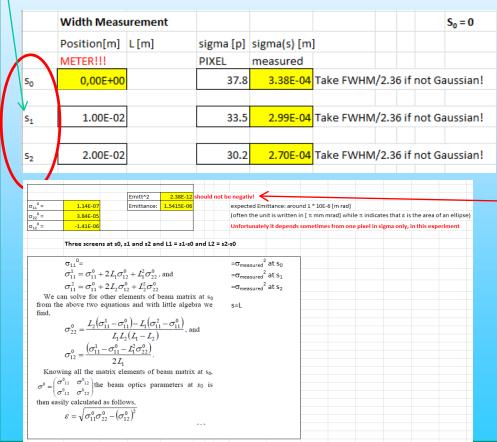
Since the Laser is not gaussian, vary a little(!) the fitted widths. Note how sensitive the emittance behave. => Need of **good resolution** and good fits. Without equal distances:

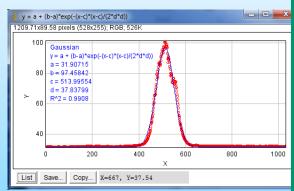
<u>Take profiles at</u> <u>3 different distances</u> <u>lens-screen.</u>



Set $s_1 = L_1$, $s_2 = L_2$, $s_0 = 0$

Enter the screen positons 0, s_1 , s_2 and the measured σ from fits (in pixel) at 0, s_1 , s_2 into the Excel sheet:





The emittance is calculated by the formulas.

Since the Laser is not gaussian, vary a little(!) the fitted widths. Note how sensitive the emittance behave. => Need of **good resolution** and good fits.