

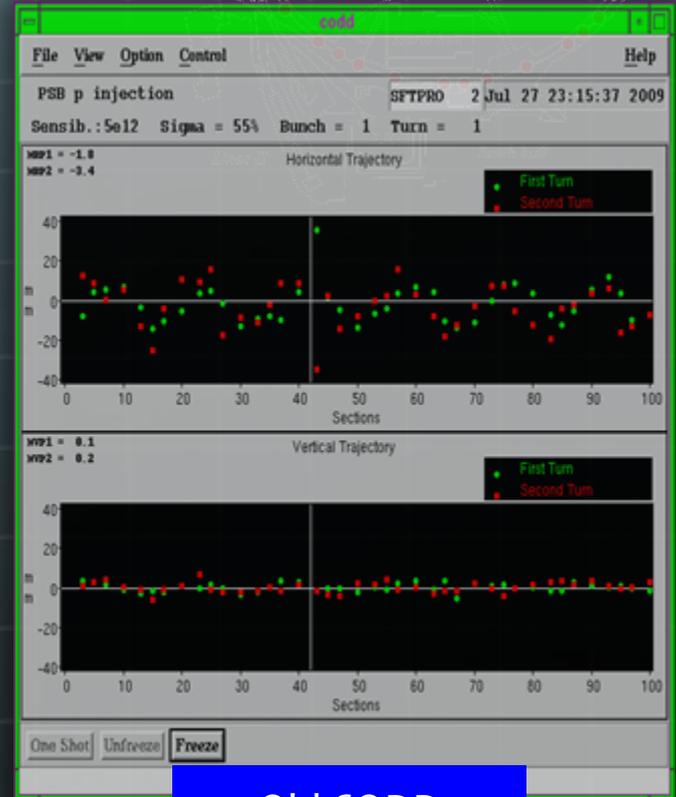
# The 1<sup>st</sup> year of TMS operations

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*BE-BI-SW November 2011*

# Before the TMS

## 🌐 Old PS Orbit (Codd) system

- ✓ Trajectories from the 40 pickups, for max 2 turns and one bunch at a given CTIM
- ✓ Mean Radial Position acquired along the cycle every 5ms



Old CODD  
OP application

# Why a new acquisition system?

- 🌐 Obsolete acquisition hardware
- 🌐 Trajectories retrieved only with CTIM in ms
- 🌐 Critical periods (*injection, transition, extraction, rotation bunch*)
  - ✓ Difficult to analyze with only 2 turns
  - ✓ Important phases at injection already finished after 5 ms
- 🌐 Low level hardware settings (*gate, BLR...*)
  - ✓ To be set manually



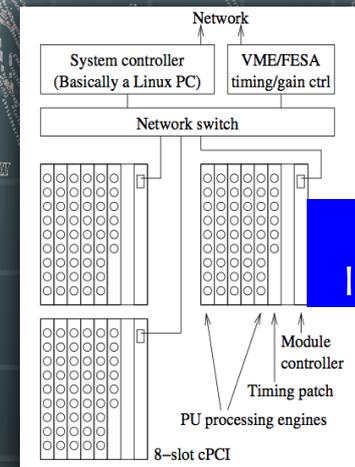
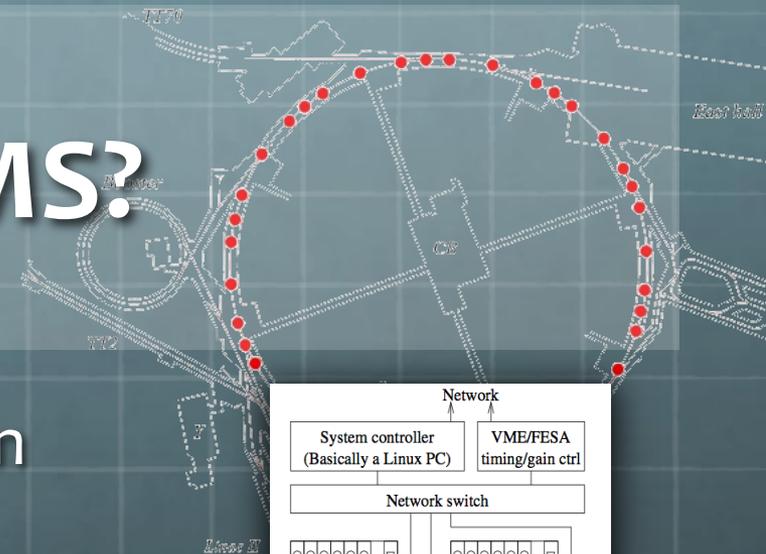
# What is TMS?

## Trajectory Measurement System

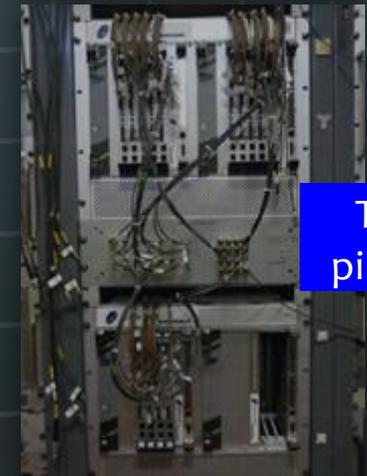
- ✓ Provided by an external company
  - ✓ Analogue signals from 40 BPMs digitized
  - ✓ 14 modules distributed over 3 cPCI crates
  - ✓ Firmware under the responsibility of BE-BI-PI
  - ✓ Setting and continuous acquisition
  - ✓ 3s buffer acquired by a server (*Linux PC*)
- Project leader : J. Belleman

## FESA server (*BPMOPS*) on LynxOs

- ✓ Data published on request
- ✓ Extraction and conversion from the TMS
- ✓ Control of the pickup sensitivities

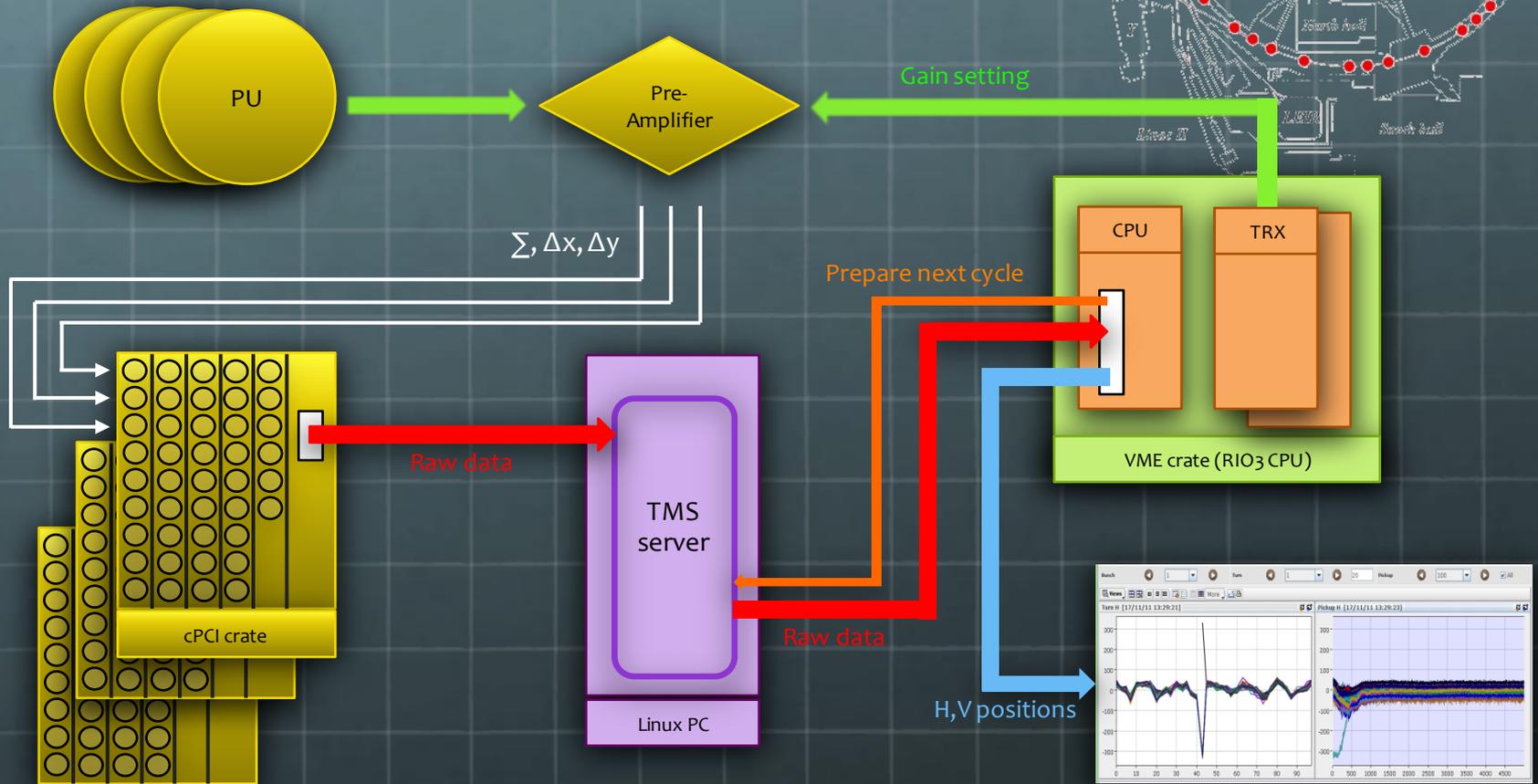


TMS  
layout

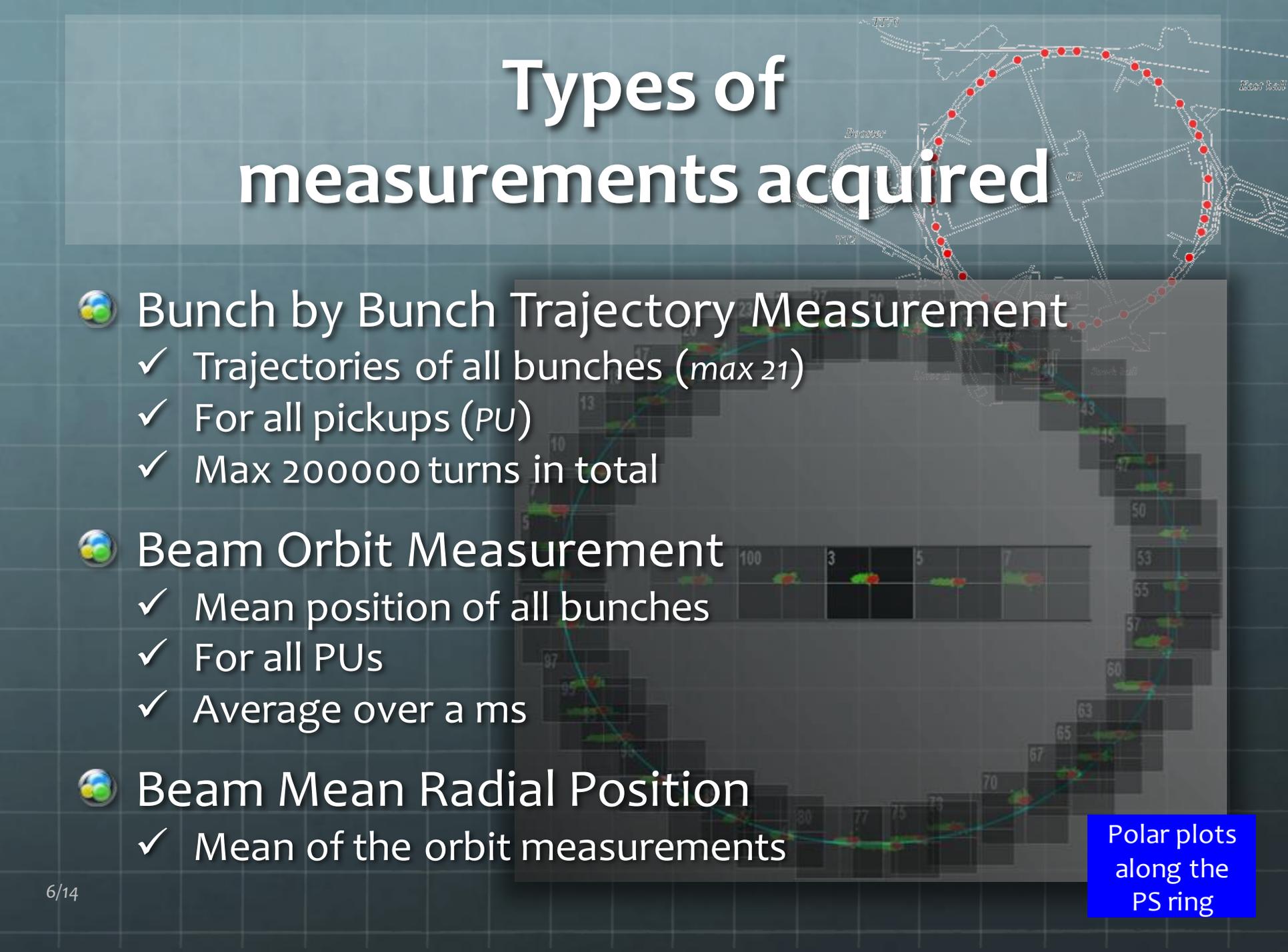


TMS  
picture

# Hardware Installation Layout



# Types of measurements acquired



## Bunch by Bunch Trajectory Measurement

- ✓ Trajectories of all bunches (*max 21*)
- ✓ For all pickups (*PU*)
- ✓ Max 200000 turns in total

## Beam Orbit Measurement

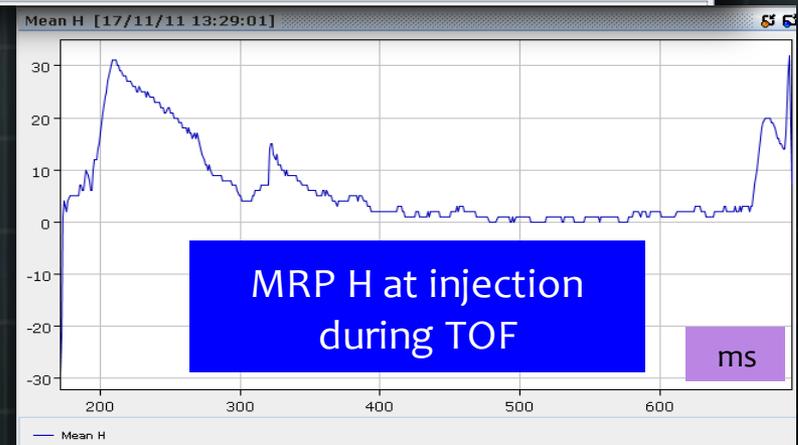
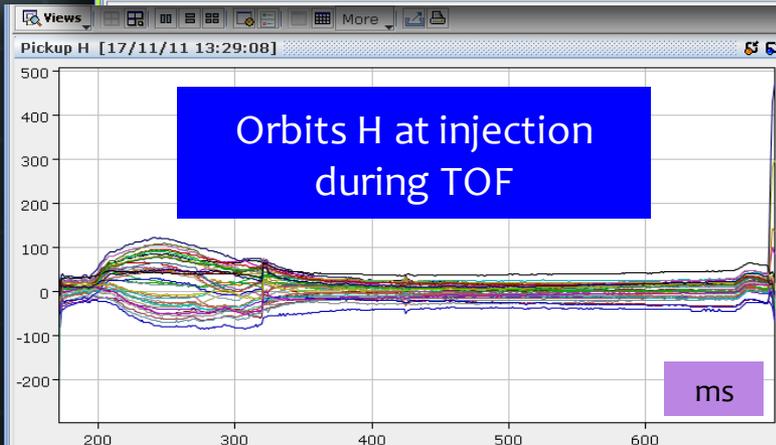
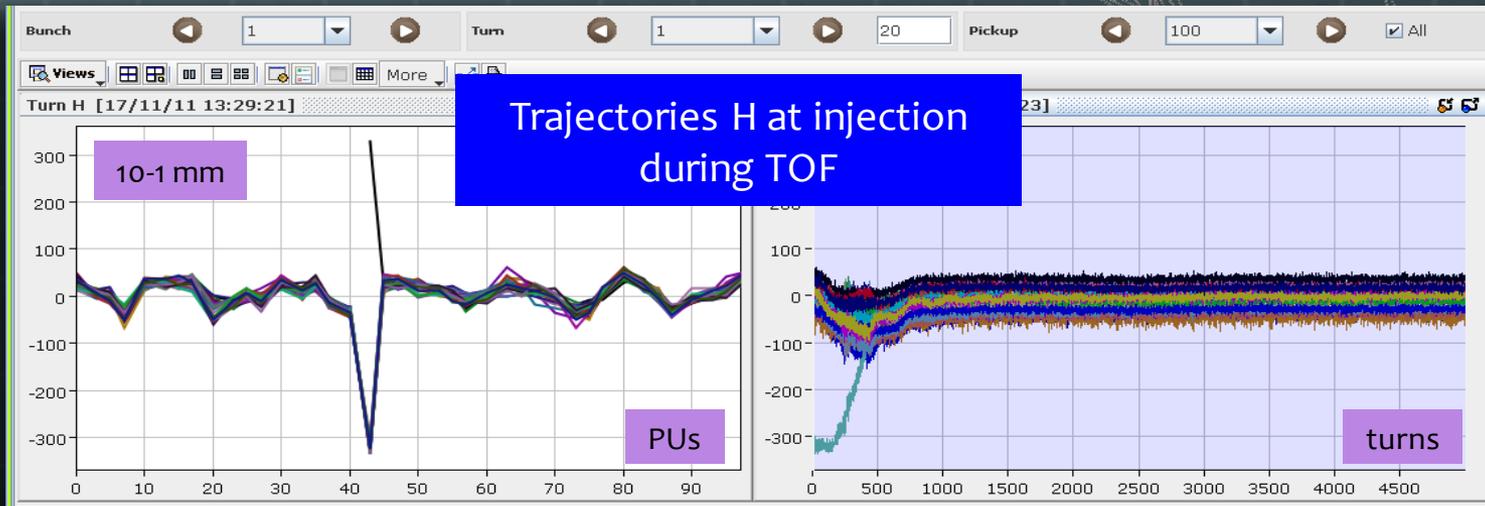
- ✓ Mean position of all bunches
- ✓ For all PUs
- ✓ Average over a ms

## Beam Mean Radial Position

- ✓ Mean of the orbit measurements

Polar plots  
along the  
PS ring

# Screenshots



# Some improvements with respect to the old CODD

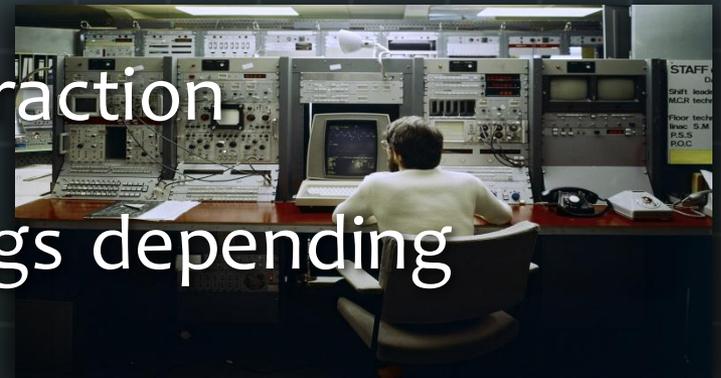
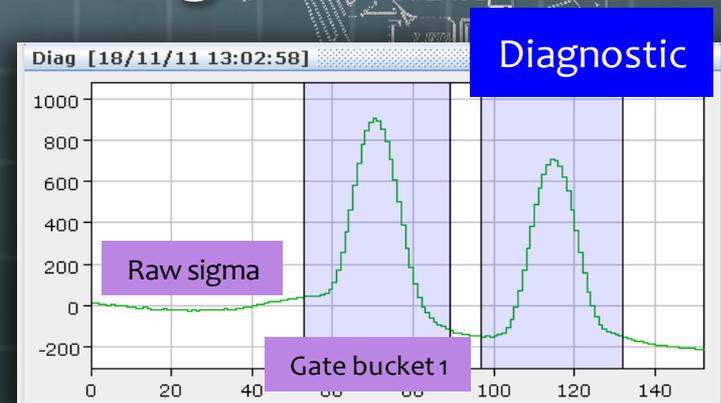
- On-demand oscilloscope-like diagnostic

- Analyze and tuning of the injection

- Bump synchronization more easy

- Bunch behavior before extraction

- Automatic low-level settings depending on the harmonic number



# New types of operation

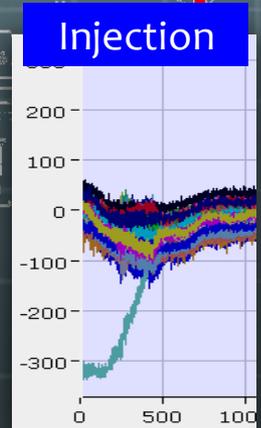
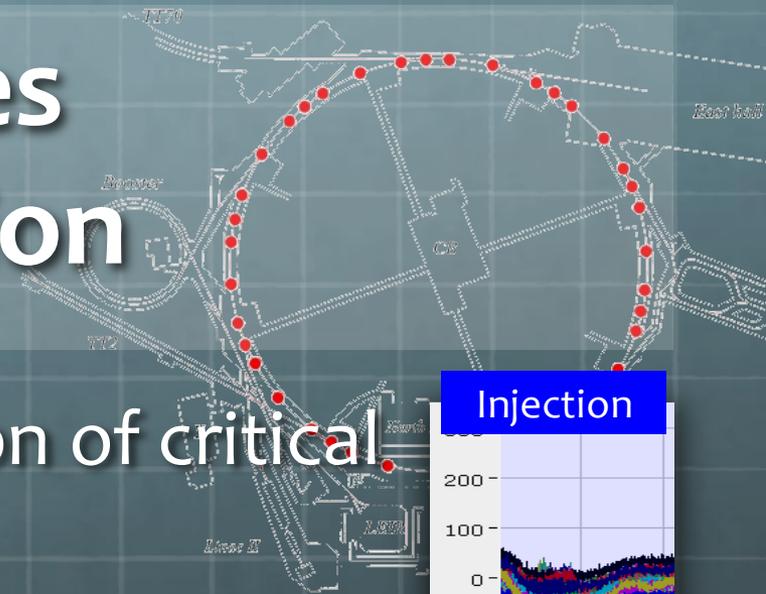
Visualization and optimization of critical processes

✓ 5000 turns per cycle in one shot

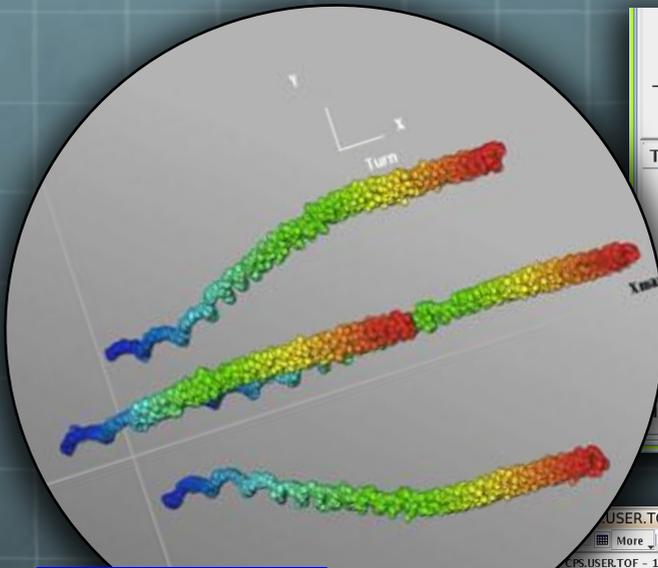
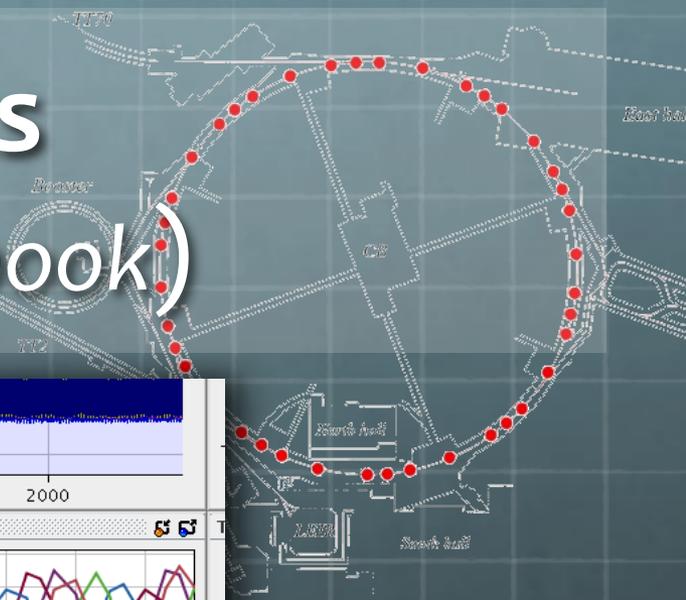
Beam steering (YASP) using 20 first turn trajectories

New MTE observation types

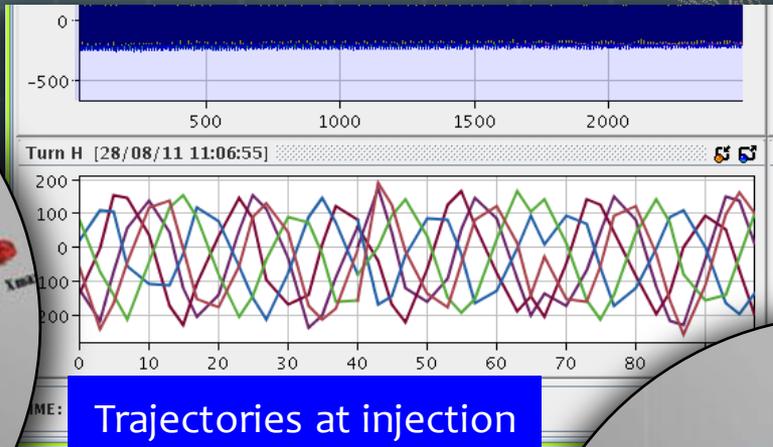
✓ Evolution of the islands



# Screenshots (from cpsop elogbook)

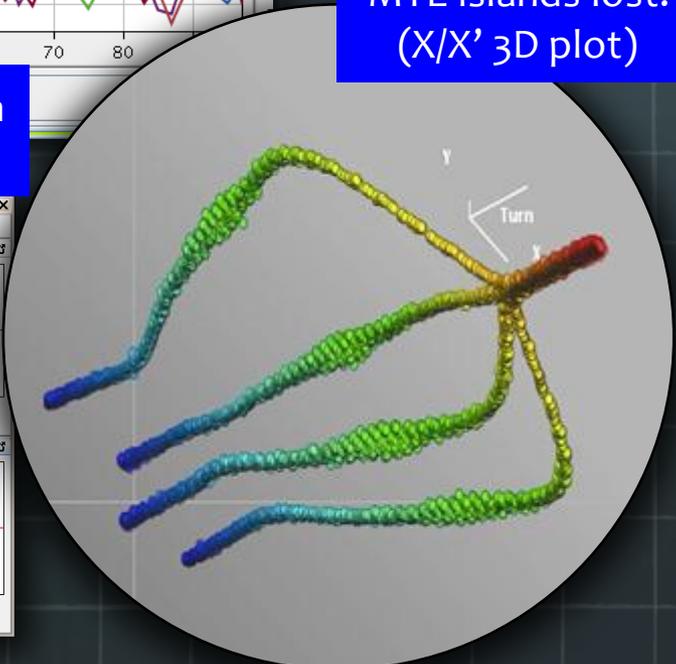


MTE islands  
(X/X' 3D plot)

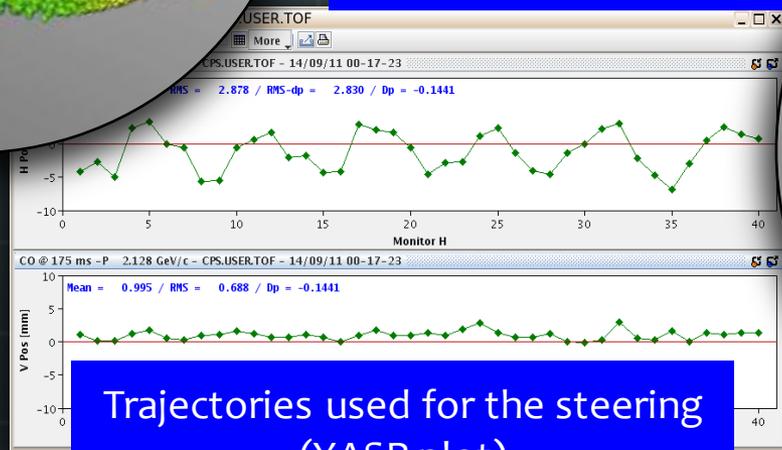


Trajectories at injection  
There is a problem...

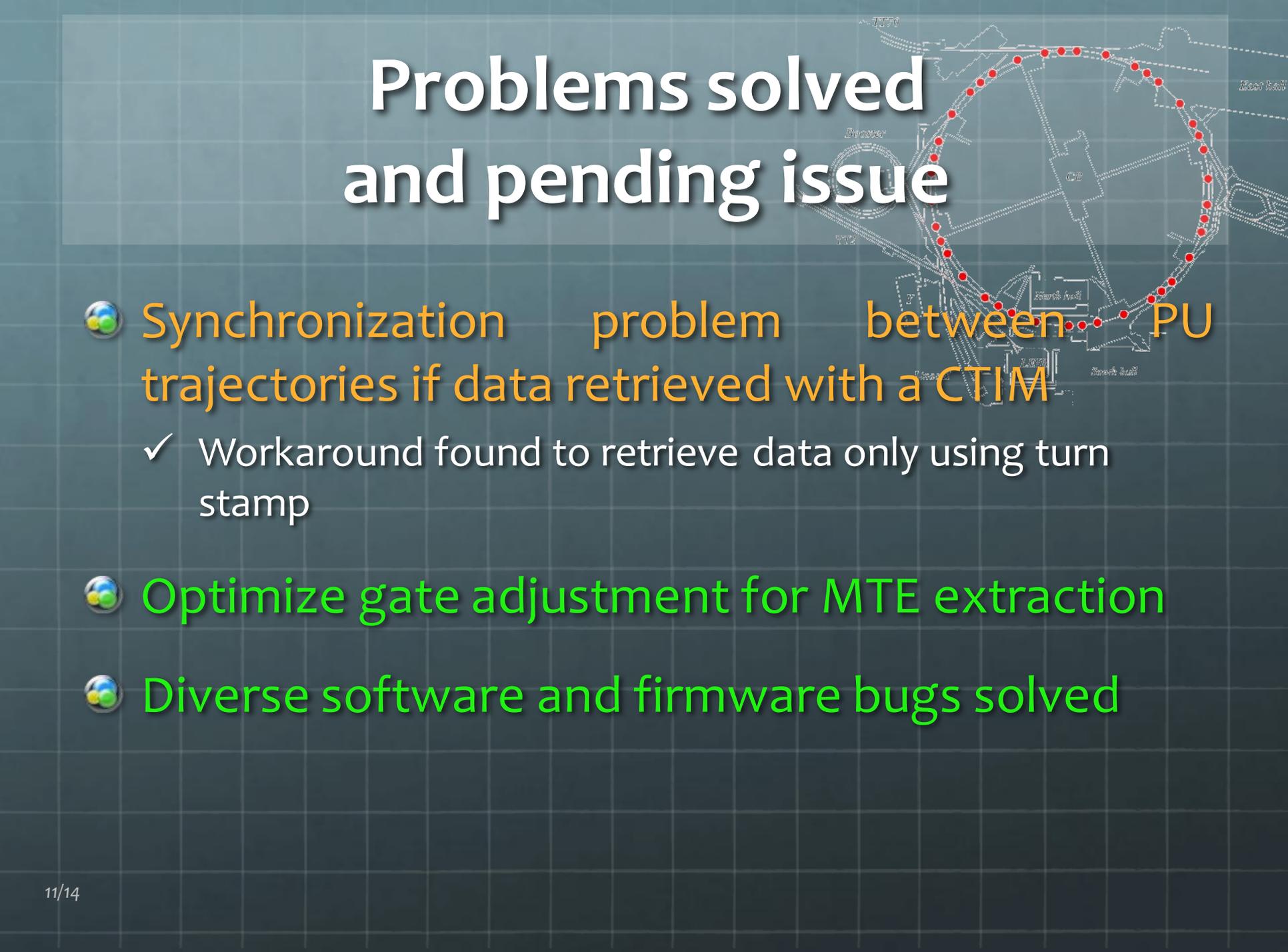
MTE islands lost!  
(X/X' 3D plot)



Trajectories used for the steering  
(YASP plot)



# Problems solved and pending issue

The background features a technical diagram of a power system. It includes a network of lines and nodes, with a prominent red trajectory path winding through the system. Labels such as 'TI1', 'TI2', 'TI3', 'TI4', 'TI5', 'TI6', 'TI7', 'TI8', 'TI9', 'TI10', 'TI11', 'TI12', 'TI13', 'TI14', 'TI15', 'TI16', 'TI17', 'TI18', 'TI19', 'TI20', 'TI21', 'TI22', 'TI23', 'TI24', 'TI25', 'TI26', 'TI27', 'TI28', 'TI29', 'TI30', 'TI31', 'TI32', 'TI33', 'TI34', 'TI35', 'TI36', 'TI37', 'TI38', 'TI39', 'TI40', 'TI41', 'TI42', 'TI43', 'TI44', 'TI45', 'TI46', 'TI47', 'TI48', 'TI49', 'TI50' are scattered throughout the diagram. The text 'Problems solved and pending issue' is overlaid on the top left of the diagram.

🌐 Synchronization problem between PU trajectories if data retrieved with a CTIM

✓ Workaround found to retrieve data only using turn stamp

🌐 Optimize gate adjustment for MTE extraction

🌐 Diverse software and firmware bugs solved

# What is missing?

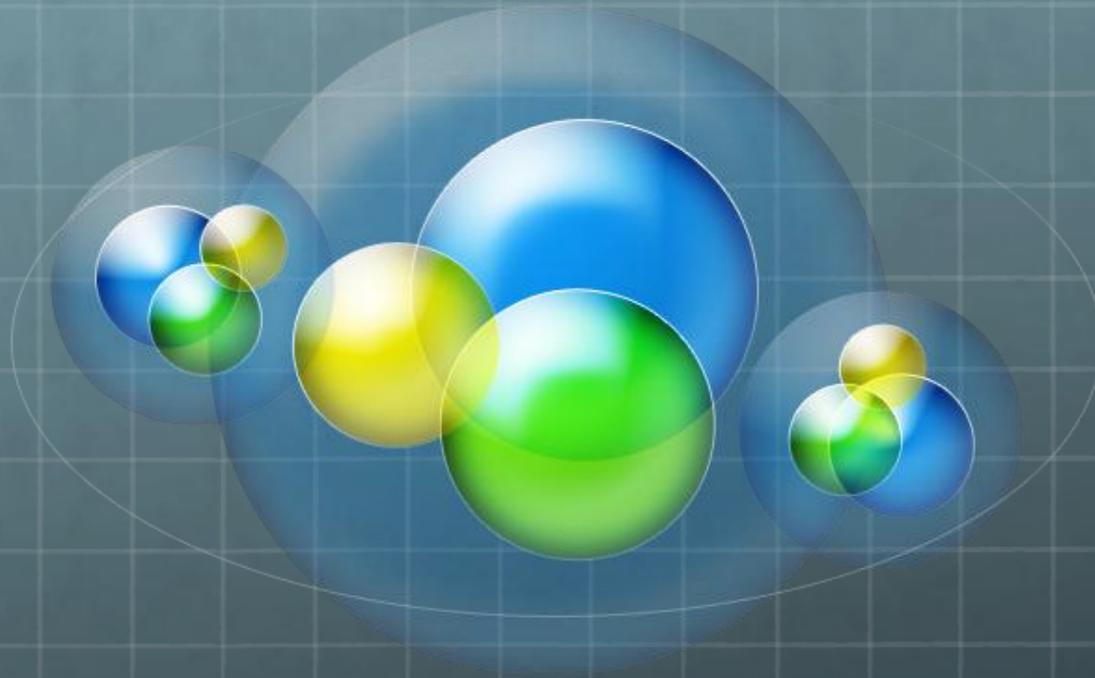


- Fast diagnostic of the gain setting
- More trajectories to acquire
  - ✓ Need to analyze trajectories during a period longer than 10ms
  - ✓ Study to calculate the tune over the whole cycle and with all PUs
- Linux based PC/VME card in order to increase performances
  - ✓ Acquisition server implemented
  - ✓ Gain control hardware to be tested

# Conclusions



- 🌐 Successful project
  - ✓ Very good collaboration inside BE
  - ✓ Interesting partnership with an external company
- 🌐 System that will be re-used in another injector (*ex : PSB*)
- 🌐 Firmware has given lots of worries
  - ✓ Firmware specialist (*fellow*) left CERN
  - ✓ Huge efforts for J. Belleman to correct bugs



**Thank you!**