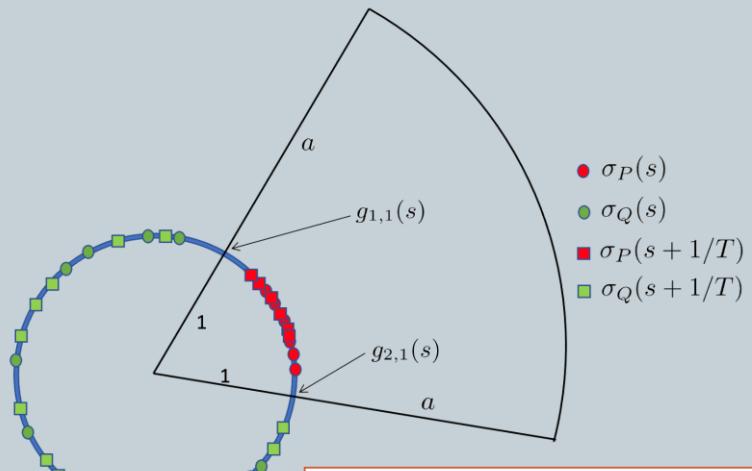


Optimal scaling quantum linear systems solver via discrete adiabatic theorem



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Why do we care?



- Basis for a whole host of new quantum algorithms:

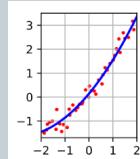
- Machine Learning



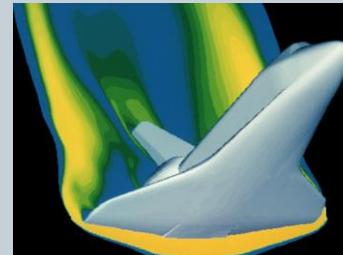
- Data analysis



- Least-squares fitting



- Solution of partial differential equation



Quantum linear systems problem



- Need to solve

$$A\vec{x} = \vec{b}$$

- Initially prepare state

$$|b\rangle = \sum_{j=1}^N b_j |j\rangle$$

- Apply operation A^{-1}

$$|\tilde{x}\rangle \sim A^{-1}|b\rangle$$

Quantum linear systems problem



- Need to solve

$$A\vec{x} = \vec{b}$$

- Initially prepare state

$$|b\rangle = \sum_{j=1}^N b_j |j\rangle$$

- Apply operation A^{-1}

$$|x\rangle \sim A^{-1}|b\rangle$$

- Obtain global properties from sampling $|x\rangle$ (not explicit listing).
- Exponential speedup in N .

Quantum linear systems problem



Optimal Quantum linear System solver

$$\mathcal{O}(\kappa \log(1/\epsilon))$$

κ – condition number

ϵ – allowable error in solution

Year	Reference	Primary innovation	Query Complexity
2008	Harrow, Hassidim, Lloyd PRL 103, 150502 (2009)	first quantum approach	$\mathcal{O}(\kappa^2/\epsilon)$
2012	Ambainis arXiv: 1010.4458	variable-time amplitude amplification	$\mathcal{O}(\kappa(\log(\kappa)/\epsilon)^3)$
2017	Childs, Kothari, Somma SIAM: J. Comput. 46, 1920	Fourier/Chebyshev fitting using LCU	$\mathcal{O}(\kappa \text{polylog}(\kappa/\epsilon))$
2018	Subasi, Somma, Orsucci PRL 122, 060504	adiabatic randomization method	$\mathcal{O}(\kappa \log(\kappa)/\epsilon)$
2019	An, Lin arXiv: 1909.05500	time-optimal adiabatic method	$\mathcal{O}(\kappa \text{polylog}(\kappa/\epsilon))$
2019	Lin, Tong Quantum 4, 361 (2020)	Zeno eigenstate filtering	$\mathcal{O}(\kappa \log(\kappa/\epsilon))$

Outline



Adiabatic Theorems

- Continuous
- Discrete

Continuous vs Discrete

Walk steps evolution + Filtering
(Overhead in κ removed)

Adiabatic approach to QLSP

Adiabatic Theorems

Continuous Adiabatic Theorem

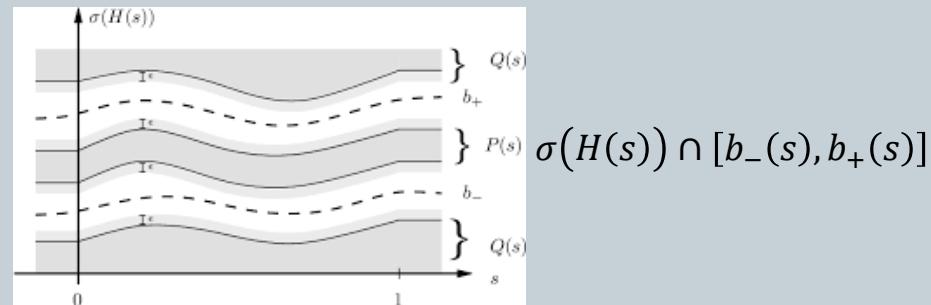


- **Adiabatic Hamiltonian**

$$H_T^A(s) := H(s) + \frac{i}{T} [\dot{P}(s), P(s)], \quad s \in [0,1]$$

Associated with

$$P(s) = \frac{1}{2\pi i} \oint_{\Gamma(s)} (H(s) - z)^{-1} dz$$



$$Q(s) = I - P(s)$$

Discrete Adiabatic Theorem

- **Adiabatic Walk**

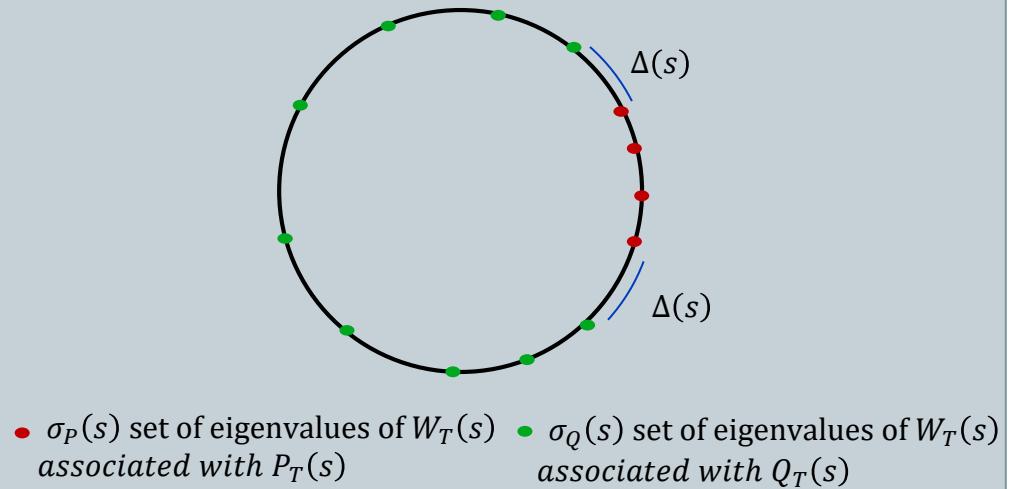
$$W_T^A(s) := V_T(s)W_T(s)$$

where V_T is associated with

$$P_T(s) = \frac{1}{2\pi i} \oint_{\Gamma_T(s)} (W_T(s) - zI)^{-1} dz$$



- Eigenvalues on a circle in complex plane



Discrete Adiabatic Theorem



- The goal is

$$\|U_T(s) - U_T^A(s)\| = \|U_T^{A\dagger}(s)U_T(s) - I\| = \|\Omega_T(s) - I\|$$

where

$$U_T(s) = \prod_{n=0}^{sT-1} W_T(n/T)$$

- **Adiabatic Theorem (DKS)**, Given $T \in \mathbb{N}$, let $W_T(n)$ be operators satisfying conditions $DW_T(s) = W_T(s + 1/T) - W_T(s) \approx \mathcal{O}(1/T)$, then for any time s , s.t., $sT \in \mathbb{N}$ we have

$$\|\Omega_T(s) - I\| = \mathcal{O}(1/T)$$

Discrete Adiabatic Theorem



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$$\|U_T(s) - U_T^A(s)\| = \|U_T^{A\dagger}(s)U_T(s) - I\| = \|\Omega_T(s) - I\|$$

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- **Adiabatic Theorem (DKS)**, Given $T \in \mathbb{N}$, let $W_T(n)$ be operators satisfying conditions $DW_T(s) = W_T(s + 1/T) - W_T(s) \approx \mathcal{O}(1/T)$, then for any time s , s.t., $sT \in \mathbb{N}$ we have

$$\|\Omega_T(s) - I\| = \mathcal{O}(1/T)$$

**They showed that the walk is asymptotically accurate,
But nothing about the gap dependence!**

Discrete Adiabatic Theorem



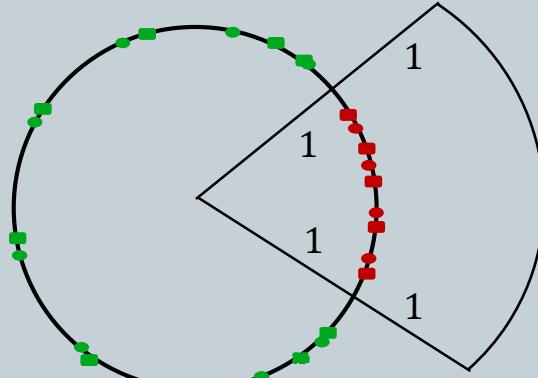
- In order to get a discrete adiabatic theorem with **strict bounds** we replace the general order scaling $DW_T(s)$ with an upper bound with explicit schedule dependence

$$\|DW_T(s)\| \leq \frac{c(s)}{T}$$

More general

$$\|D^{(k)}W_T(s)\| \leq \frac{c_k(s)}{T^k}$$

- Bound on difference of projectors needs contour threaded between eigenvalues for multiple steps.



$$\|DP_T(s)\| \leq \frac{2c_1(s)}{T\Delta_1(s)}$$

Discrete Adiabatic Theorem



- **Adiabatic Theorem**

$$\begin{aligned} \|U_T(s) - U_T^A(s)\| \leq & \frac{12\hat{c}_1(0)}{T\bar{\Delta}(0)^2} + \frac{12\hat{c}_1(s)}{T\bar{\Delta}(s)^2} + \frac{6\hat{c}_1(s)}{T\bar{\Delta}(s)} \\ & + 305 \sum_{n=1}^{sT-1} \frac{\hat{c}_1(n/T)^2}{T^2\bar{\Delta}(n/T)^3} + 44 \sum_{n=0}^{sT-1} \frac{\hat{c}_1(n/T)^2}{T^2\bar{\Delta}(n/T)^2} + 32 \sum_{n=1}^{sT-1} \frac{\hat{c}_2(n/T)}{T^2\bar{\Delta}(n/T)^2} \end{aligned}$$

$$\bar{\Delta}(s) = \min(\Delta(s - 1/T), \Delta(s), \Delta(s + 1/T)) \quad \hat{c}_k(s) = \max_{s' \in \{s-1/T, s, s+1/T\} \cup [0, 1-k/T]} c_k(s')$$

- \hat{c}_1 – analogous to first derivative in continuous adiabatic theorem
- \hat{c}_2 – analogous to second derivative in continuous adiabatic theorem

Discrete Adiabatic Theorem



- **Adiabatic Theorem**

$$\|U_T(s) - U_T^A(s)\| \leq \frac{12\hat{c}_1(0)}{T\bar{\Delta}(0)^2} + \frac{12\hat{c}_1(s)}{T\bar{\Delta}(s)^2} + \frac{6\hat{c}_1(s)}{T\bar{\Delta}(s)} \\ + 305 \sum_{n=1}^{sT-1} \frac{\hat{c}_1(n/T)^2}{T^2 \bar{\Delta}(n/T)^3} + 44 \sum_{n=0}^{sT-1} \frac{\hat{c}_1(n/T)^2}{T^2 \bar{\Delta}(n/T)^2} + 32 \sum_{n=1}^{sT-1} \frac{\hat{c}_2(n/T)}{T^2 \bar{\Delta}(n/T)^2}$$

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- \hat{c}_1 – analogous to first derivative in continuous adiabatic theorem
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$$\frac{1}{T} \frac{\|H^{(1)}(0)\|}{g^2(0)} + \frac{1}{T} \frac{\|H^{(1)}(s)\|}{g^2(s)} + \frac{1}{T} \int_0^s ds' \left(\frac{\|H^{(1)}(s')\|^2}{g^3(s')} + \frac{\|H^{(2)}(s')\|}{g^2(s')} \right)$$

Continuous vs Discrete

Continuous vs Discrete



- **Continuous**

$$U(t_0, t_0 + T) = \tau \exp \left(-i \int_{t_0}^{t_0+T} dt' H(t') \right)$$

M. Kieferová, A. Scherer, and D. W. Berry, PRA **99**, 042314 (2019); 1805.00582.
G. H. Low and N. Wiebe, arXiv:1805.00675 (2018).

Continuous vs Discrete

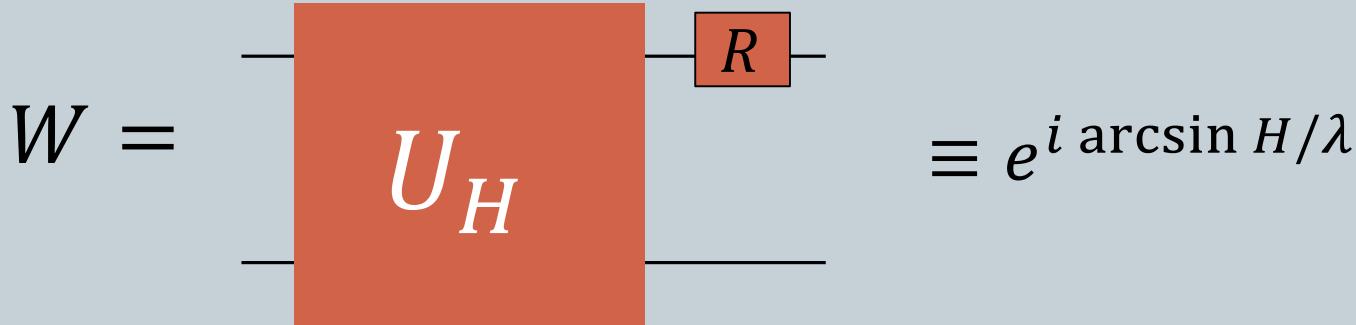


- **Continuous**

$$U(t_0, t_0 + T) = \tau \exp \left(-i \int_{t_0}^{t_0+T} dt' H(t') \right)$$

- **Discrete:** Qubitisation

Construct quantum walk using reflection



Adiabatic approach to QLSP

Adiabatic approach to QLSP



- Initial and final Hamiltonians with $Q_b = I_N - |b\rangle\langle b|$

$$H_0 = \begin{pmatrix} 0 & Q_b \\ Q_b & 0 \end{pmatrix} \quad H_1 = \begin{pmatrix} 0 & A Q_b \\ Q_b A & 0 \end{pmatrix}$$
$$\begin{pmatrix} b \\ 0 \end{pmatrix} \quad \begin{pmatrix} A^{-1}b \\ 0 \end{pmatrix}$$

Adiabatic approach to QLSP



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- For $H(s) = (1 - f(s))H_0 + f(s)H_1$ gap is

$$\boxed{\Delta_0(s) = 1 - f(s) + f(s)/\kappa}$$

- Schedule is chosen as

$$\dot{f}(s) = d_p \Delta_0^p(s), \quad d_p = \int_0^1 \Delta_0^{-p}(u) du$$

- Solution is

$$f(s) = \frac{\kappa}{\kappa-1} \left[1 - (1 + s(\kappa^{p-1} - 1))^{\frac{1}{1-p}} \right]$$

$$1 < p \leq 2$$

Adiabatic approach to QLSP

- **Theorem for $p = 1.5$**

Overall inequality

$$\|U_T(s) - U_T^A(s)\| \leq 5632 \frac{\kappa}{T} + O\left(\frac{\sqrt{\kappa}}{T}\right)$$

The discrete adiabatic evolution removes the $\log(\kappa/\epsilon)$ overhead for adiabatic solution of QLSP.

Adiabatic approach to QLSP

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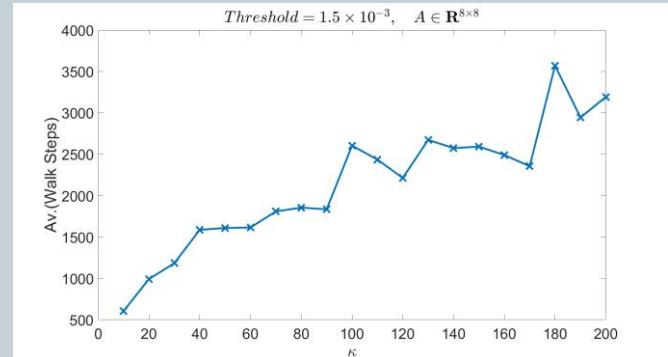
- **Numerical testing for constant factor**

Numerically test with the complete discrete adiabatic theorem.

About 9 times better than theorem.

The discrete adiabatic evolution removes the $\log(\kappa/\epsilon)$ overhead for adiabatic solution of QLSP.

Numerical testing for examples
matrices A for $p=1.4$



Conclusions



- Fastest possible quantum algorithm for the quantum linear systems problem in terms of κ and ϵ (we don't consider sparsity d).
- Lower bound of Kothari and Harrow is $\Omega(\sqrt{d}\kappa \log(1/\epsilon))$.
- Our discrete adiabatic algorithm with qubitisation gives speedup for all adiabatic algorithms too.
- Method for LCU with two ancilla qubits can be used generally.

Future work:

- There could be scope for improving constant factors.
- How to achieve optimal scaling in d at the same time is open problem.