

Fundamental limits of quantum error mitigation

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NISQ devices

NISQ = Noisy Intermediate-Scale Quantum

Focus on manipulating $O(10)$ – $O(100)$ qubits.

Let's NOT dive into a complicated error correction and see if we can do **anything useful** with it.

Obstacle: noise, of course!!

Error mitigation: run a given NISQ device many times + classical postprocessing

- Trade space resource with time resource (sampling cost)

Zoo of error-mitigation protocols

Various error-mitigation protocols proposed so far.

- Probabilistic error cancellation [Buscemi et al., '13] [Temme et al., PRL '17]
- Noise extrapolation [Temme et al., PRL '17] [Li, Benjamin, PRX '17]
- Virtual distillation [Koczor, PRX '21] [Huggins, PRX '21]
- Symmetry verification [Bonet-Monroig et al., PRA '18]
- ...

What is the ultimate performance shared by all error-mitigation protocols?

General theory for quantum error mitigation?

General quantum error mitigation

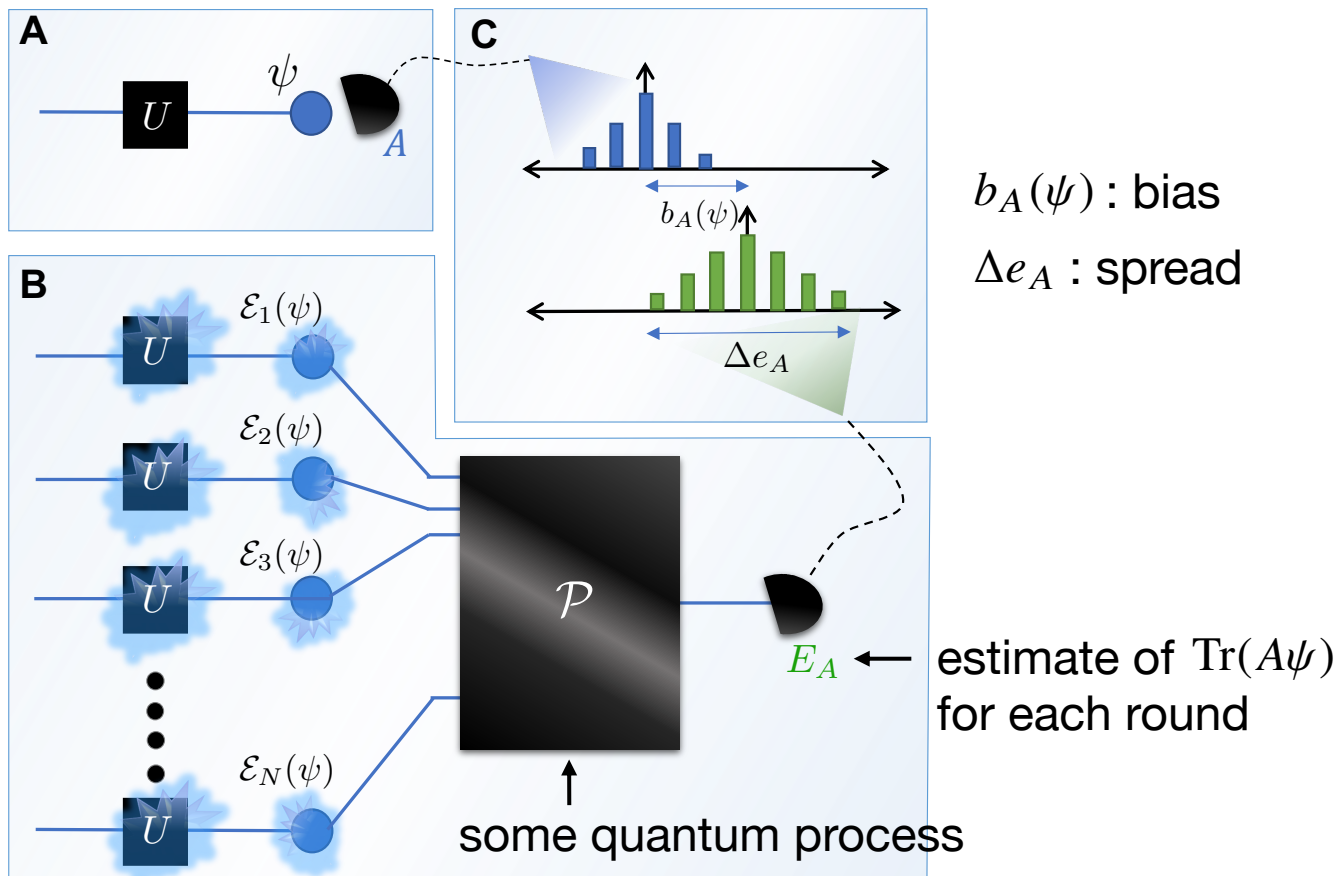
Ideal:

$$\psi \longrightarrow \text{Tr}(A\psi)$$

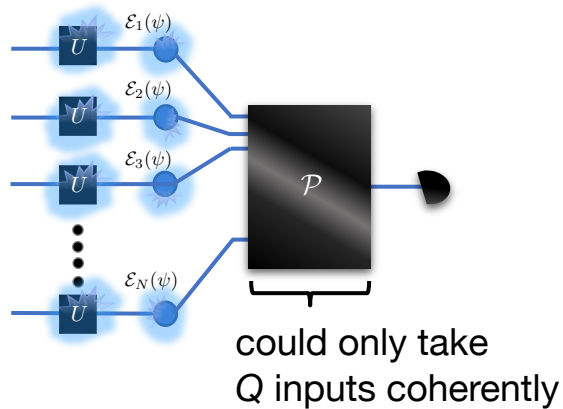
Real:

$$\mathcal{E}_1(\psi), \dots, \mathcal{E}_N(\psi)$$

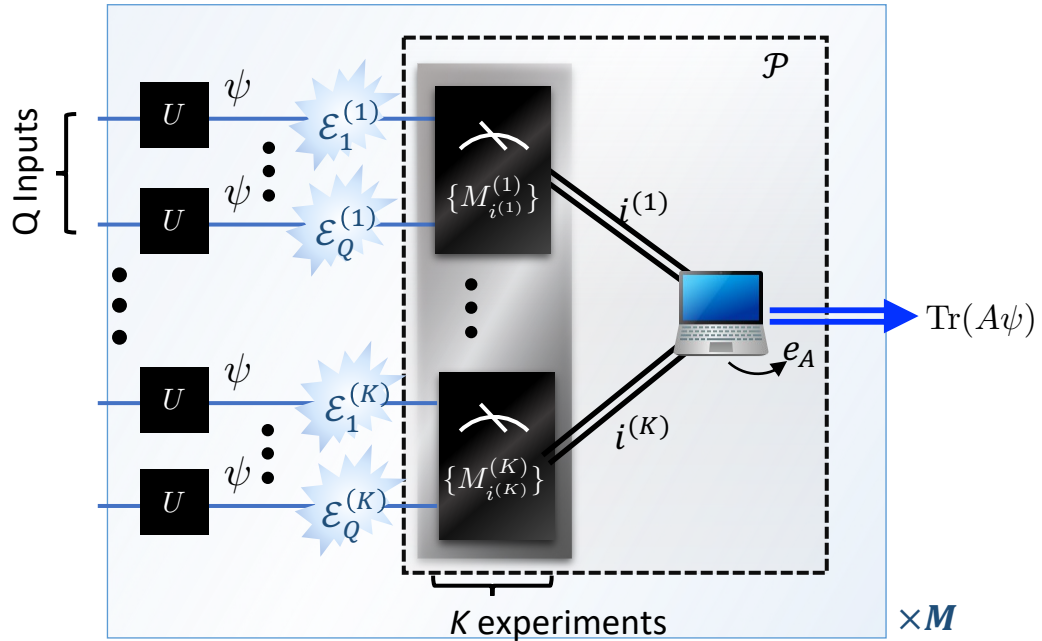
$$\longrightarrow \text{Tr}(A\psi)$$



General quantum error mitigation



(Q,K)-error mitigation

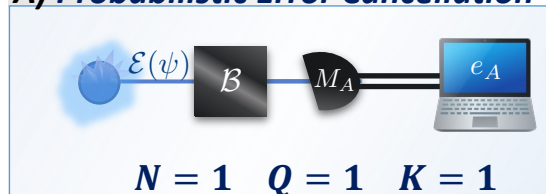


Repeat M rounds to get estimate $e_A(i^{(1)}, \dots, i^{(K)}) = e_{A,m}$ for each $m=1, \dots, M$

$$\bar{E}_A^{(M)} = \frac{1}{M} \sum_{m=1}^M e_{A,m} : \text{estimate of } \text{Tr}(A\psi)$$

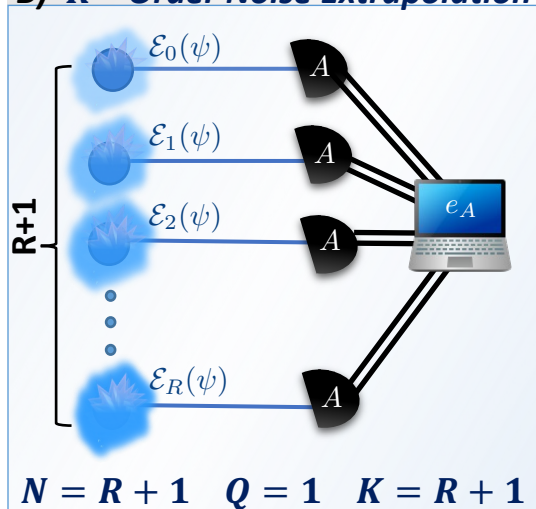
Examples

A) Probabilistic Error Cancellation



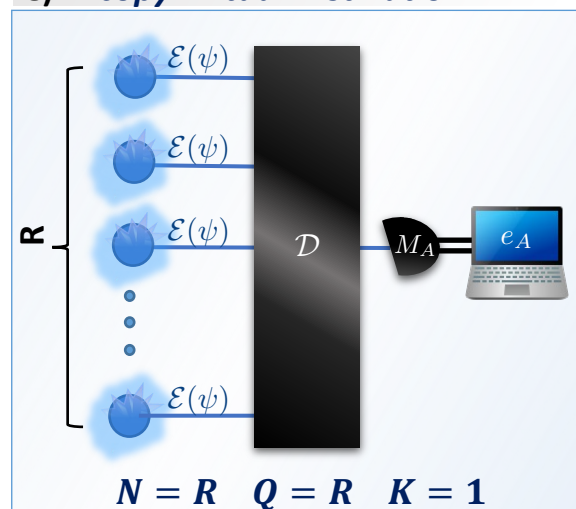
[Temme et al., PRL '17]

B) R^{th} Order Noise Extrapolation



[Temme et al., PRL '17] [Li, Benjamin, PRX '17]

C) R -copy Virtual Distillation



[Koczor, PRX '21] [Huggins, PRX '21]

Quantifying performance

- Bias $b_A(\psi) = \langle E_A \rangle - \text{Tr}(A\psi)$ E_A : random variable for each estimate

- Statistical Error $|\bar{E}_A^{(M)} - \langle E_A \rangle|$

$$\bar{E}_A^{(M)} = \frac{1}{M} \sum_{m=1}^M e_{A,m} : \text{estimate of } \text{Tr}(A\psi)$$

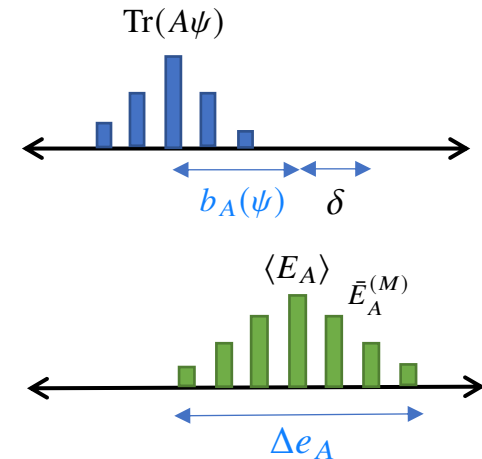
How many round number M ensures the statistical error δ ?

- Hoeffding inequality

M samples ensure error $|\bar{E}_A^{(M)} - \langle E_A \rangle| < \delta$ with probability $1 - \varepsilon$ when

$$M > \frac{2 \Delta e_A^2 \log(2/\varepsilon)}{\delta^2}$$

- Maximum bias $b_{\max} = \max_{-I/2 \leq A \leq I/2} \max_{\psi} b_A(\psi)$
- Maximum spread $\Delta e_{\max} = \max_{-I/2 \leq A \leq I/2} \Delta e_A$



Lower bounds for maximum spread

What is the unavoidable maximum spread for a given maximum bias?

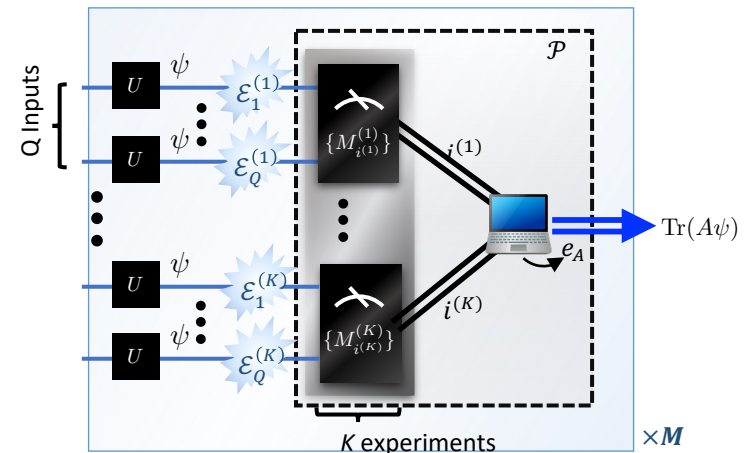
For an arbitrary (Q,K) -mitigation protocol,

$$\Delta e_{\max} \geq \max_{\psi, \phi} \frac{D_{\text{tr}}(\psi, \phi) - 2b_{\max}}{D_{\text{LM}}(\tilde{\psi}_Q^{(K)}, \tilde{\phi}_Q^{(K)})}$$

$$\tilde{\psi}_Q^{(K)} := \otimes_{k=1}^K \otimes_{q=1}^Q [\mathcal{E}_q^{(k)}(\psi)] \quad \tilde{\phi}_Q^{(K)} := \otimes_{k=1}^K \otimes_{q=1}^Q [\mathcal{E}_q^{(k)}(\phi)]$$

Maximum bias $b_{\max} = \max_{-1/2 \leq A \leq 1/2} \max_{\psi} b_A(\psi)$

Maximum spread $\Delta e_{\max} = \max_{-1/2 \leq A \leq 1/2} \Delta e_A$



$D_{\text{tr}}(\rho, \sigma)$: trace distance (= distinguishability using any measurement)

$D_{\text{LM}}(\rho, \sigma)$: local distinguishability (= distinguishability using local measurements)

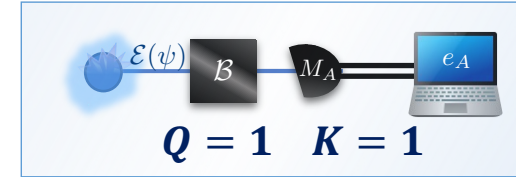
Connecting error-mitigation performance with information-theoretic measures.

Application: protocol benchmarking

Probabilistic error cancellation: (1,1)-protocol. ($Q=K=1$)

$$\mathcal{E}^{-1} = \sum_j c_j \mathcal{B}_j, \quad c_j \in \mathbb{R} \quad \gamma := \sum_j |c_j|$$

γ_{opt} : minimum γ over all feasible $\{\mathcal{B}_j\}_j$



$\Delta e_{\text{max}}^{\text{PEC}} = \gamma_{\text{opt}}$ characterizes the sampling cost for this protocol. [Takagi, PRR '21]
[Regula, Takagi, Gu, Quantum '21]

e.g.) Local dephasing noise $\mathcal{Z}_\epsilon^{\otimes n}$

$$\mathcal{Z}_\epsilon(\rho) = (1 - \epsilon)\rho + \epsilon Z\rho Z$$

$$\Delta e_{\text{max}}^{\text{PEC}} = \gamma_{\text{opt}} = \frac{1}{(1 - 2\epsilon)^n}$$

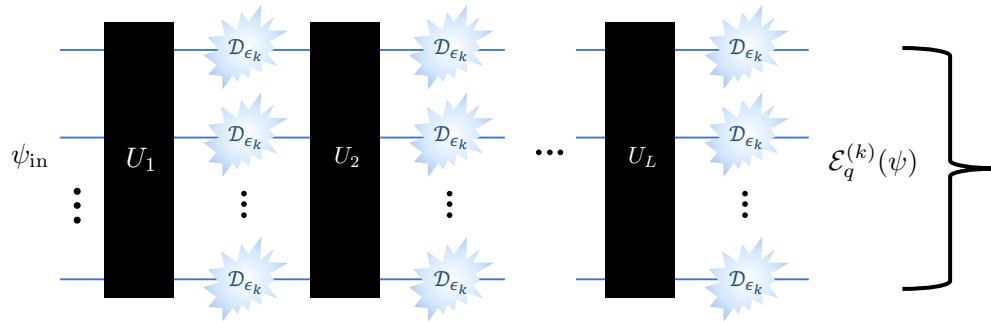
Our bound implies that any unbiased (1,1)-protocol satisfies

$$\Delta e_{\text{max}} \geq \max_{\psi, \phi} \frac{D_{\text{tr}}(\psi, \phi)}{D_{\text{tr}}(\mathcal{Z}_\epsilon^{\otimes n}(\psi), \mathcal{Z}_\epsilon^{\otimes n}(\phi))} \geq \frac{1}{(1 - 2\epsilon)^n}$$

Lower bound achieved!

Probabilistic error cancellation is optimal for this noise.

Application: error-mitigating layered circuits

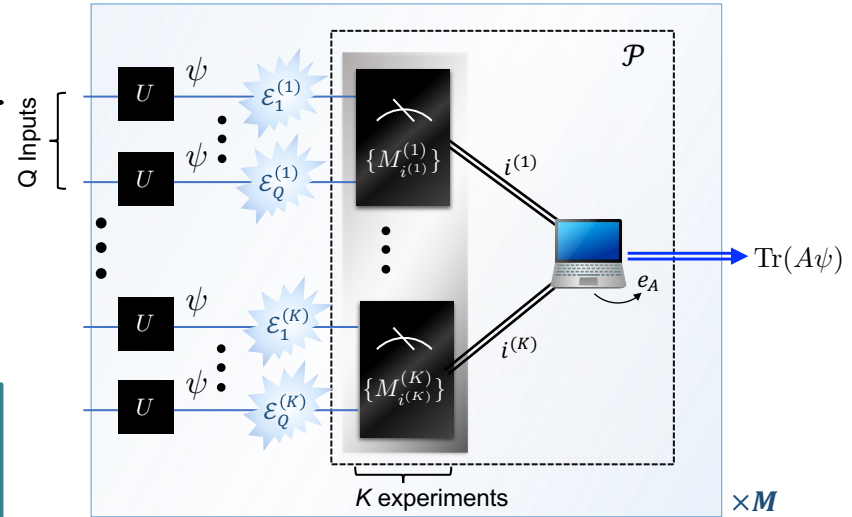


$\mathcal{D}_{\epsilon_k}(\rho) = (1 - \epsilon_k)\rho + \epsilon_k\mathbb{I}/2$: local depolarizing noise

For an arbitrary (Q, K) -mitigation protocol,

$$\Delta e_{\text{max}} \geq \frac{1 - 2b_{\text{max}}}{\sqrt{2 \ln 2} \sqrt{n} Q K} \left(\frac{1}{1 - \epsilon_{\text{min}}} \right)^L$$

$\epsilon_{\text{min}} := \min_k \epsilon_k$



Exponential error spread w.r.t. circuit depth L !

Summary

- Introduced a general framework for quantum error mitigation.
- Established a general lower bound for the maximum spread.
- Showed the optimality of probabilistic error cancellation for the local dephasing noise in terms of the maximum spread.
- Showed that mitigating errors in layered circuits requires exponentially large maximum spread.
- Sampling lower bounds? See our follow-up work
“Universal sample lower bounds for quantum error mitigation”, arXiv:2208.09178