



IBM Quantum Network Hub
at the University of Melbourne



@gregswhitenoise

GREG WHITE

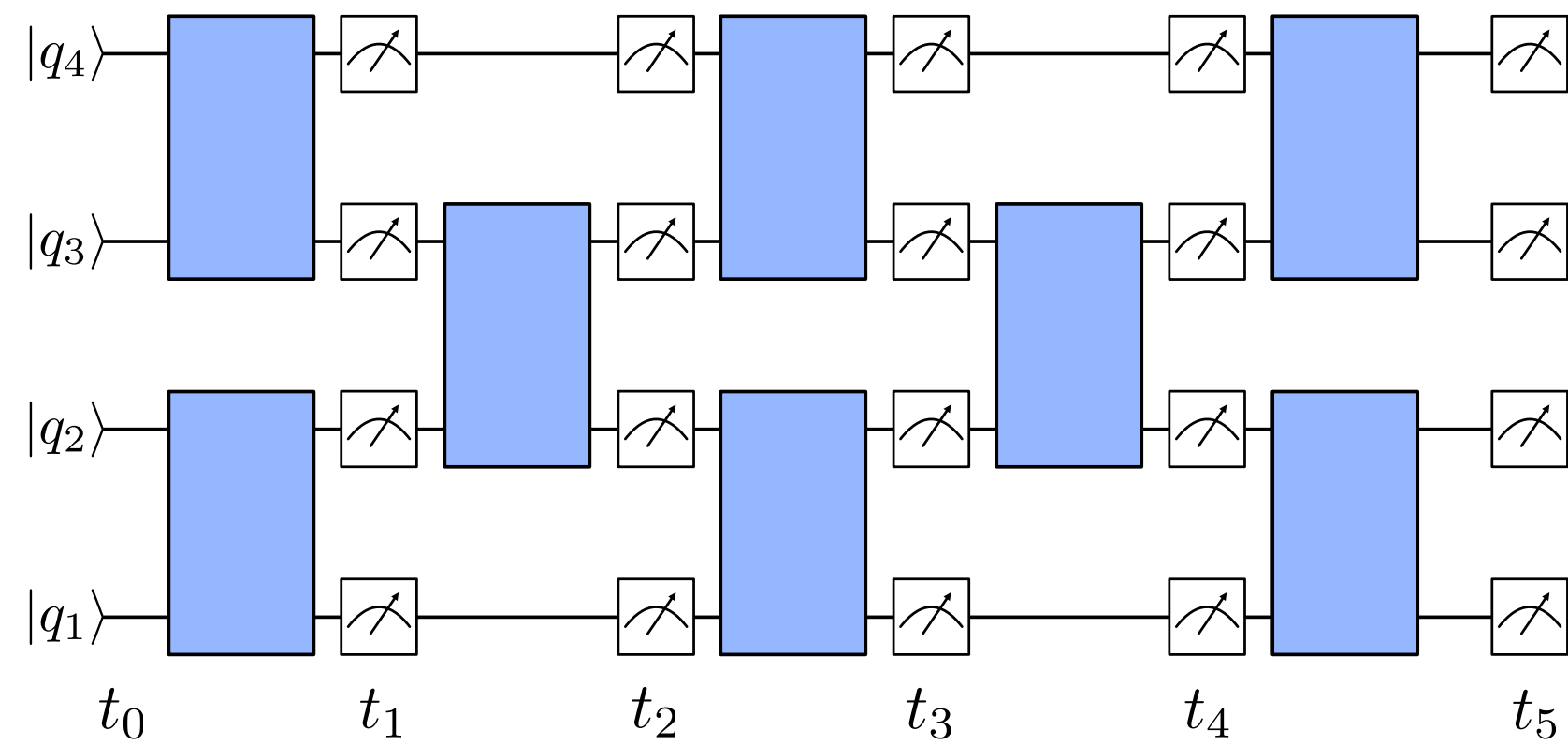
FELIX POLLOCK

LLOYD HOLLENBERG

CHARLES HILL

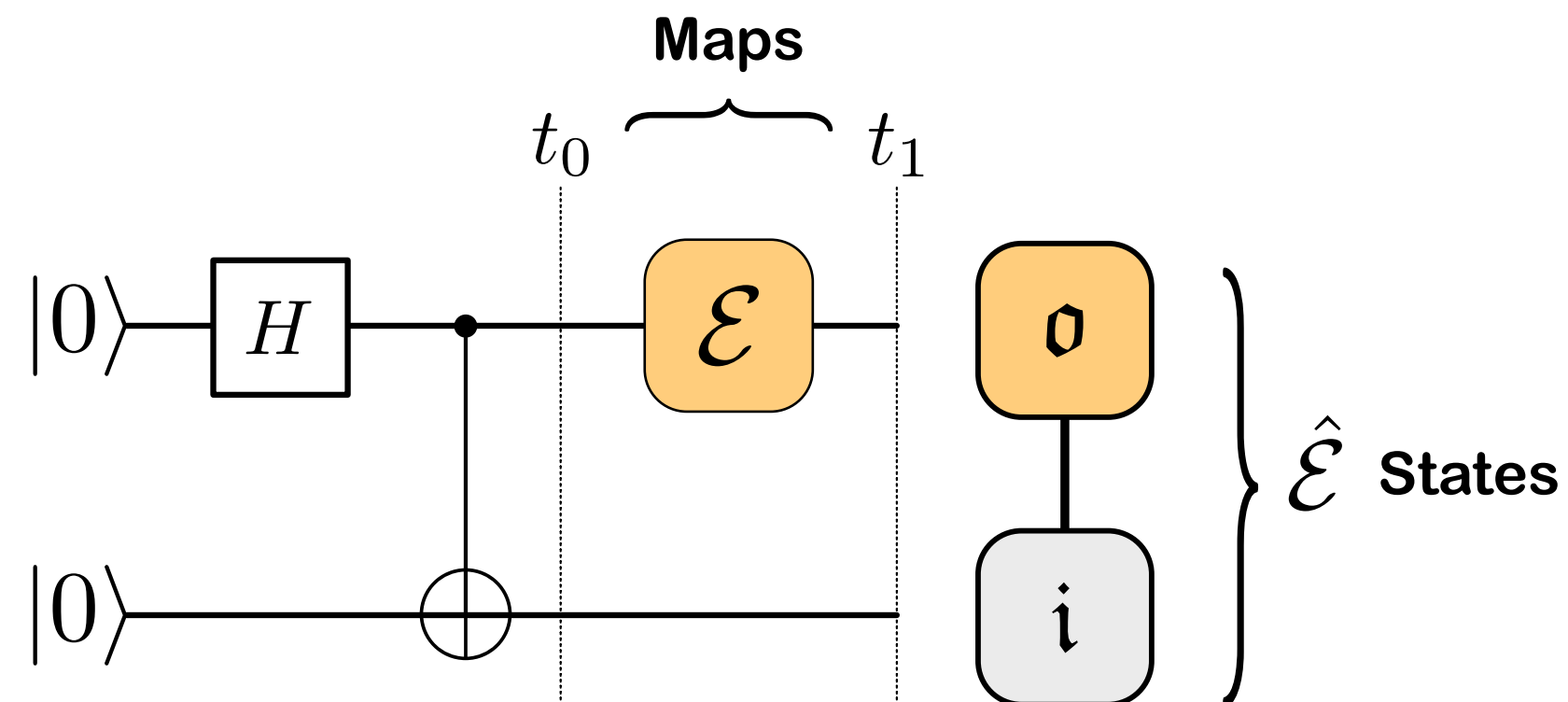
KAVAN MODI

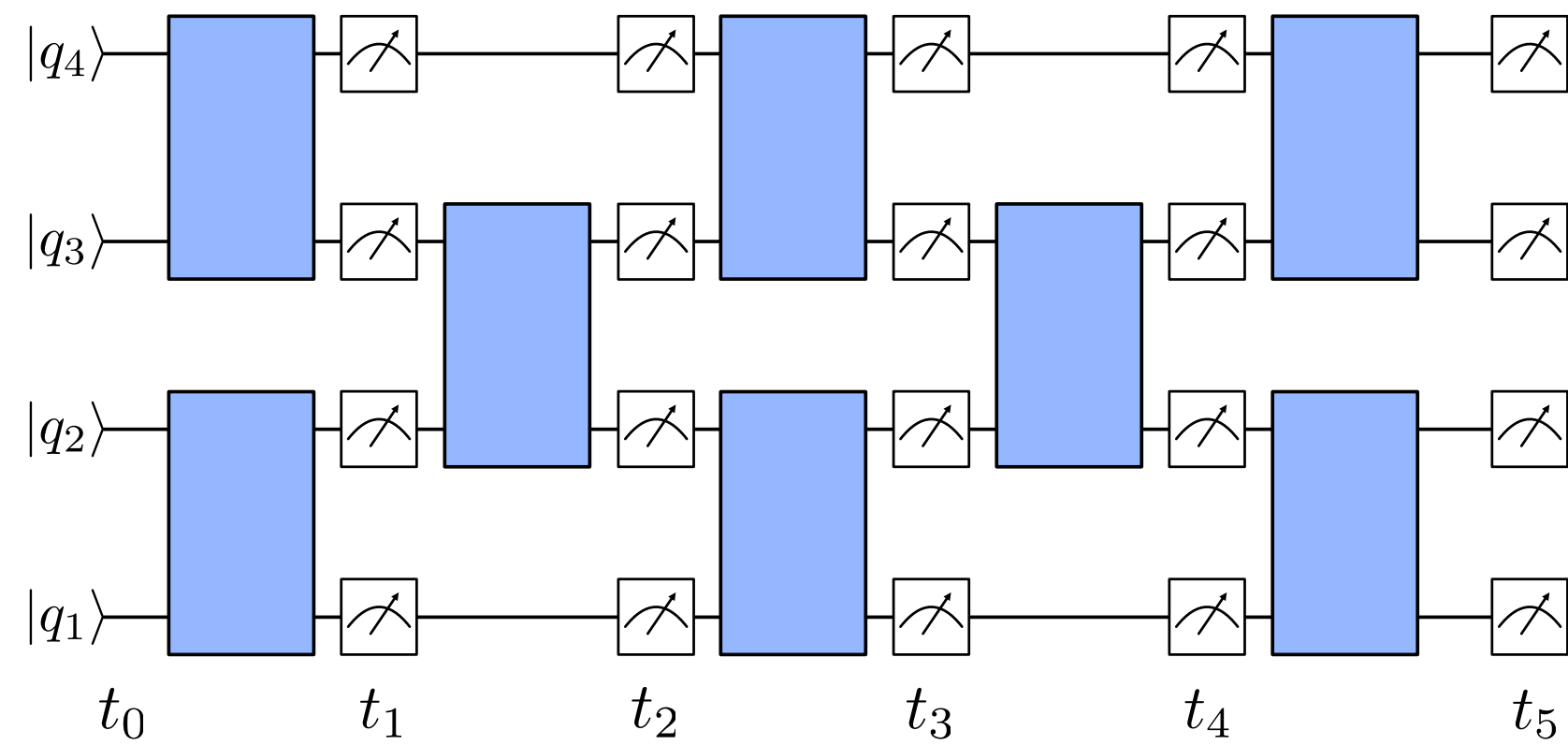
From Many-Body to Many-Time Physics



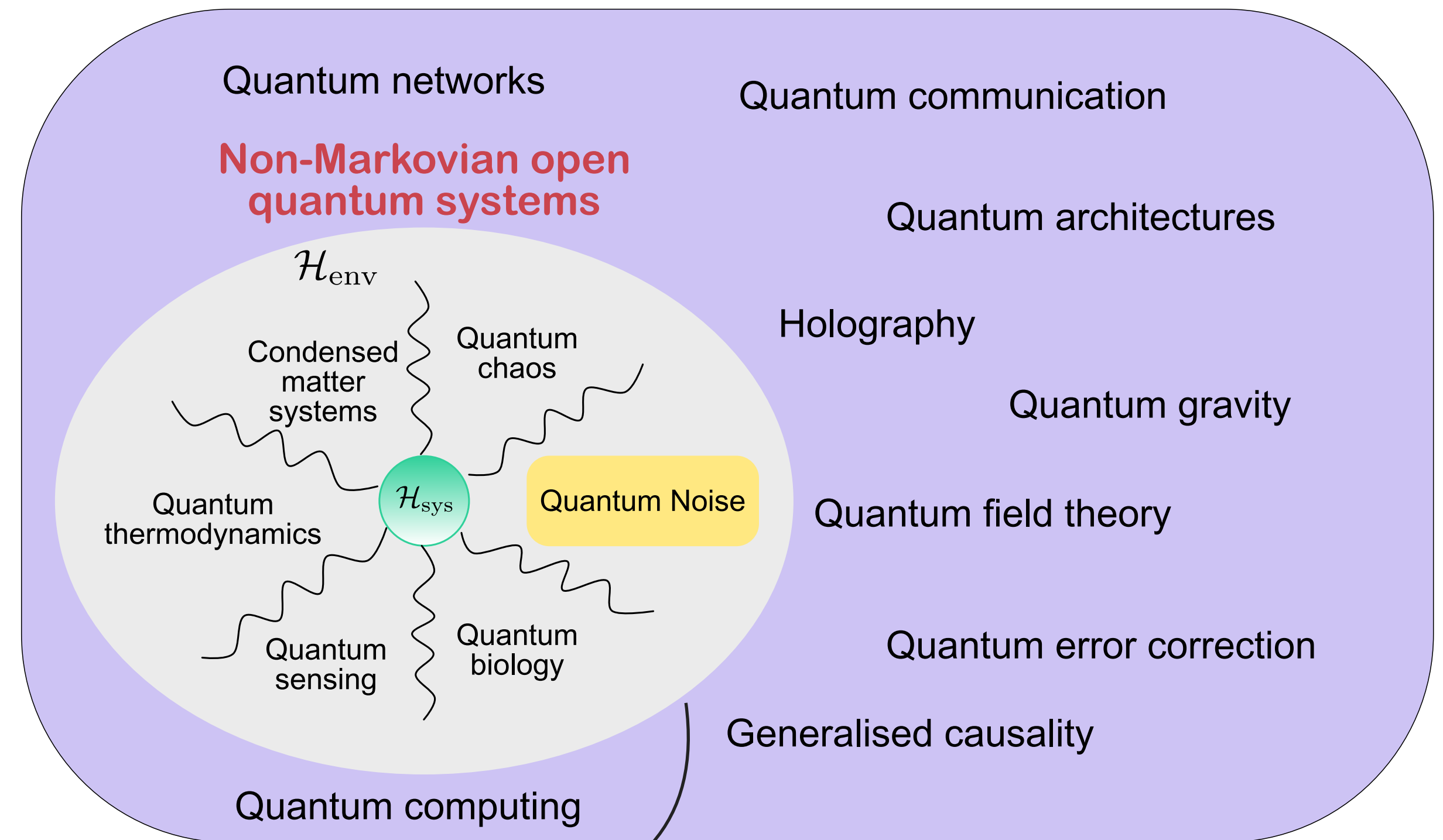
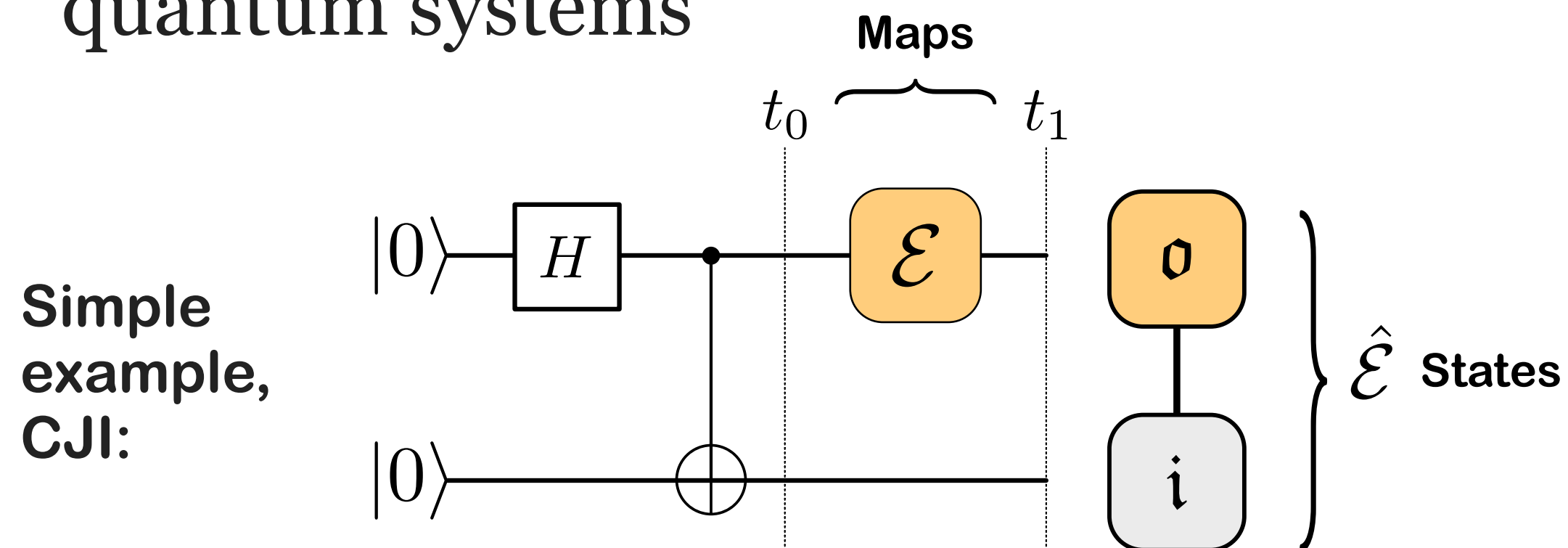
- ▶ Quantum theory has a spacetime structure with curious causal properties

Simple example, CJI:





- ▶ Quantum theory has a spacetime structure with curious causal properties
- ▶ Particularly emerges in the context of open quantum systems



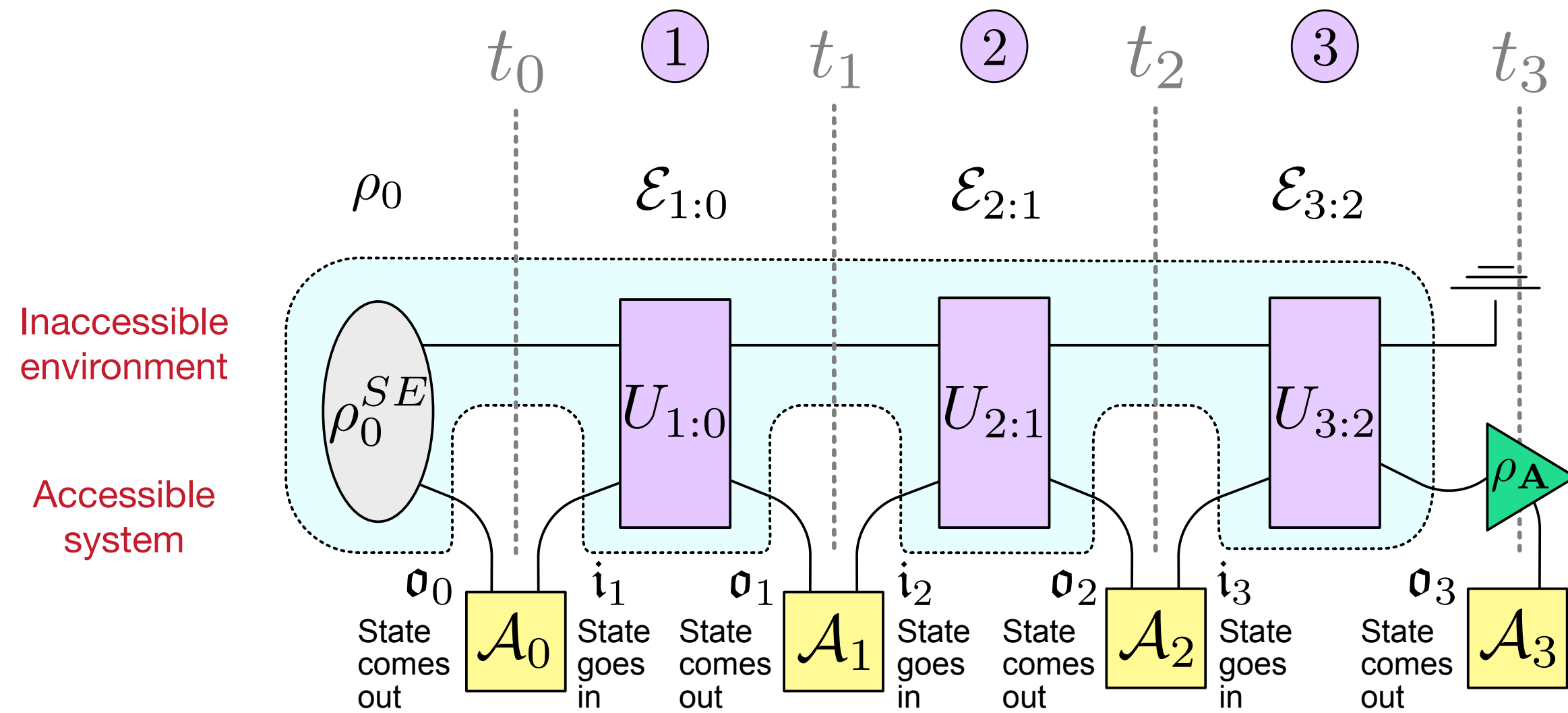
My work:

- What generates spatiotemporal correlations?
- What is their structure?
- How can we access/measure/manipulate them?

- Introduce the process tensor

$$\mathcal{T}_{k:0}[\mathbf{A}_{k-1:0}] = \rho(\mathbf{A}_{k-1:0})$$

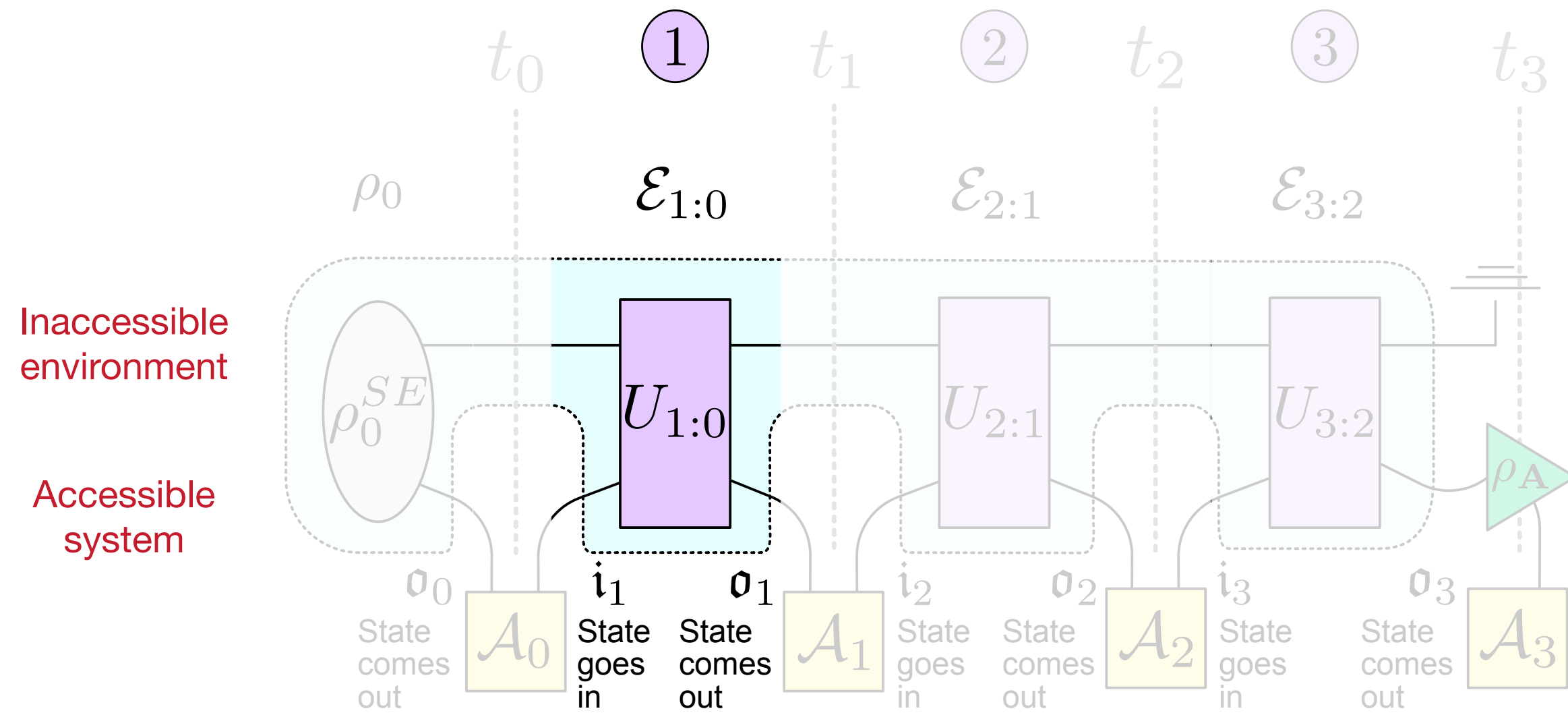
Pollock et al. Phys. Rev. A **97**, 012127 (2018)



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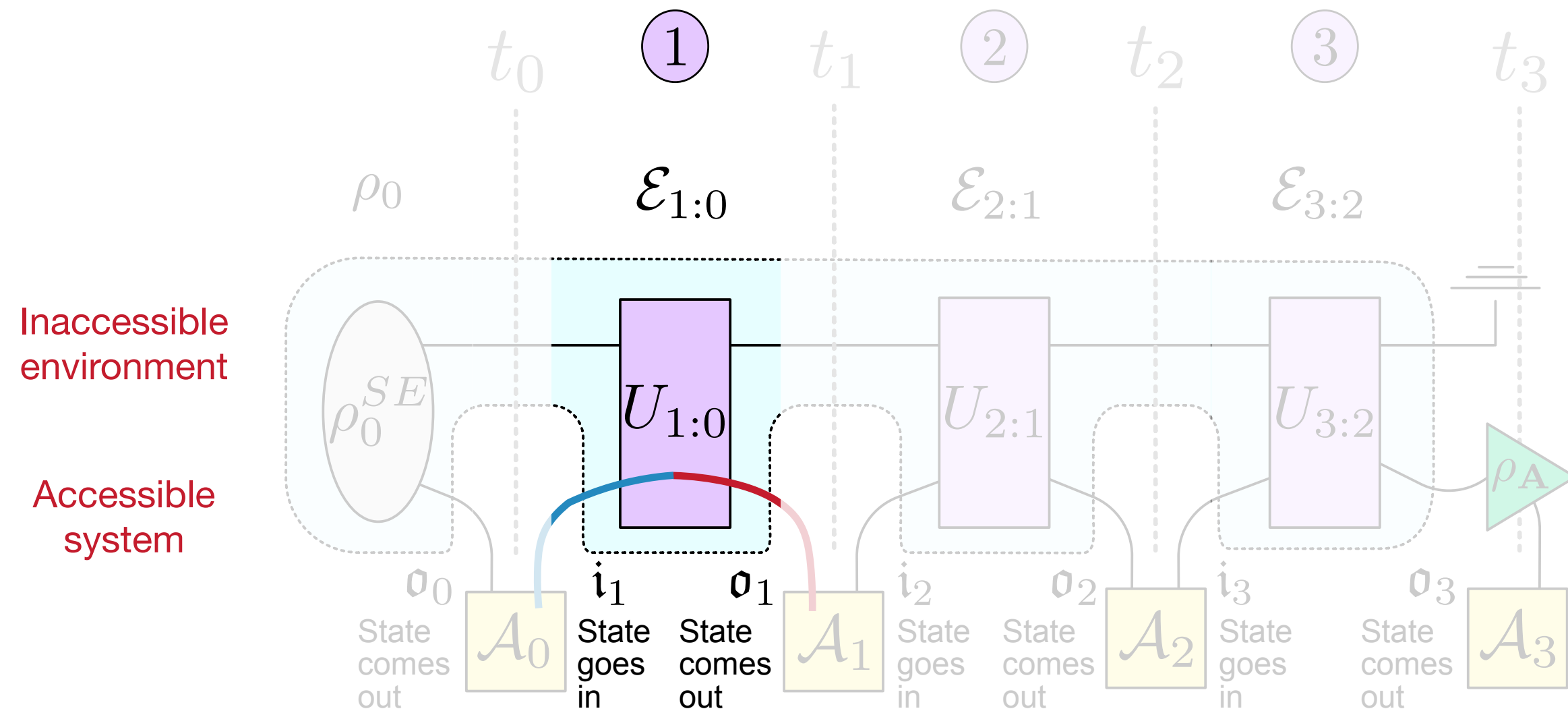
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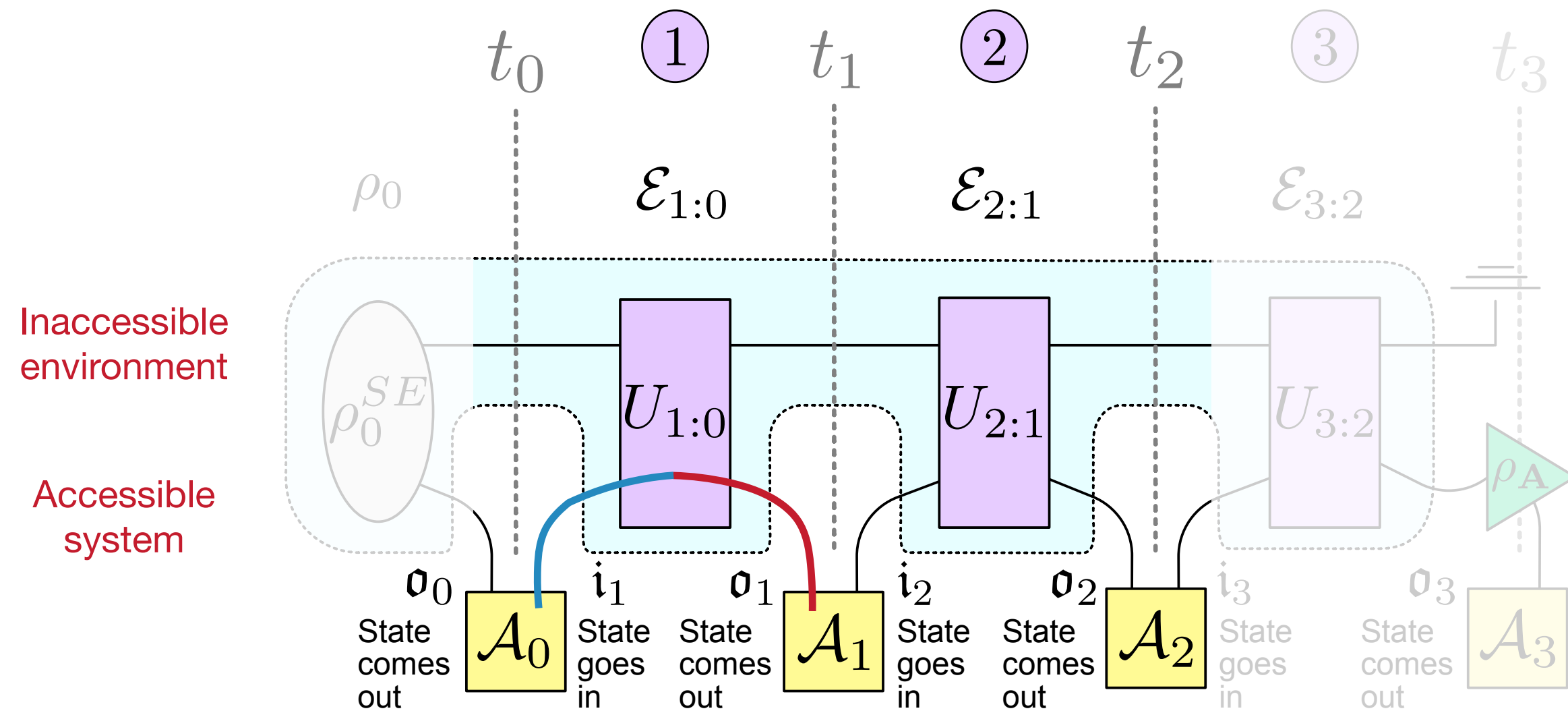
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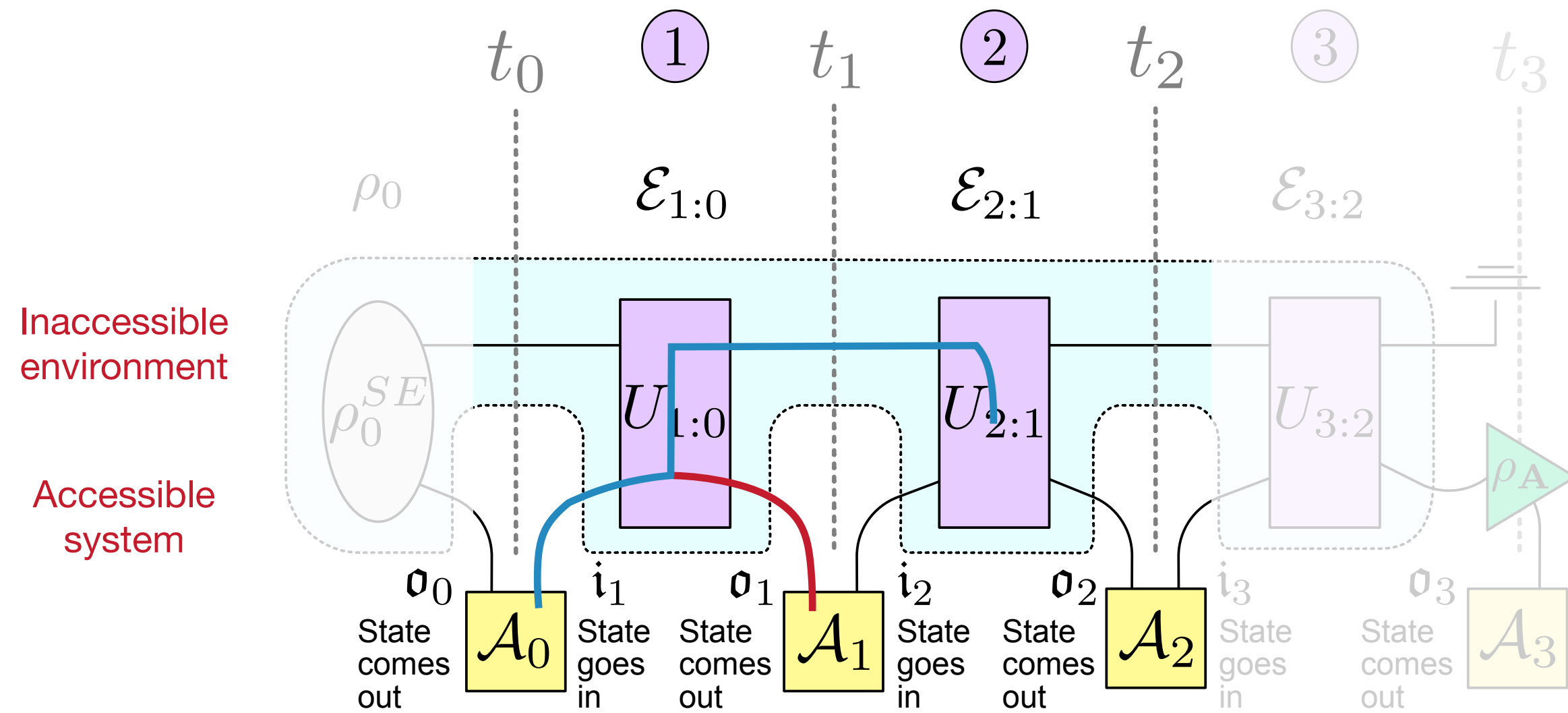
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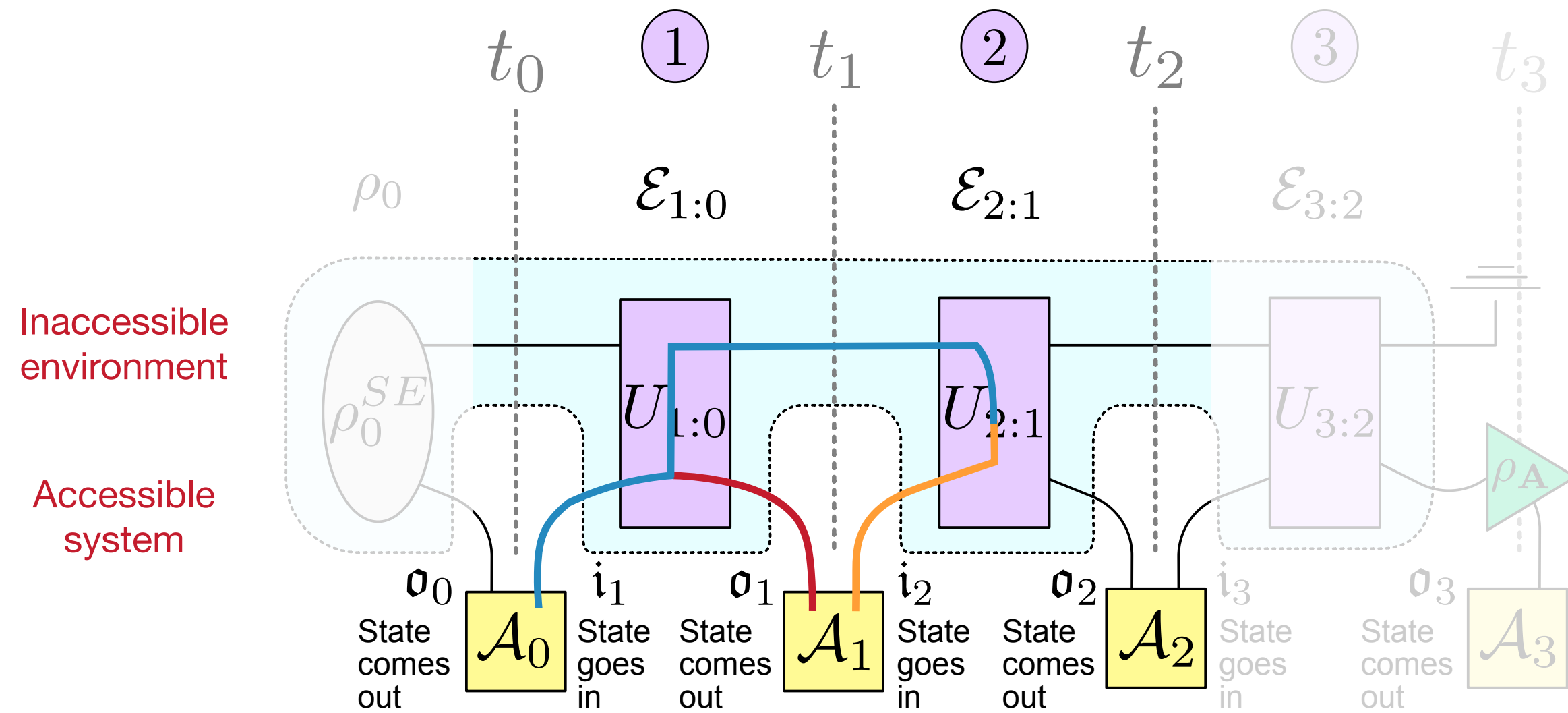
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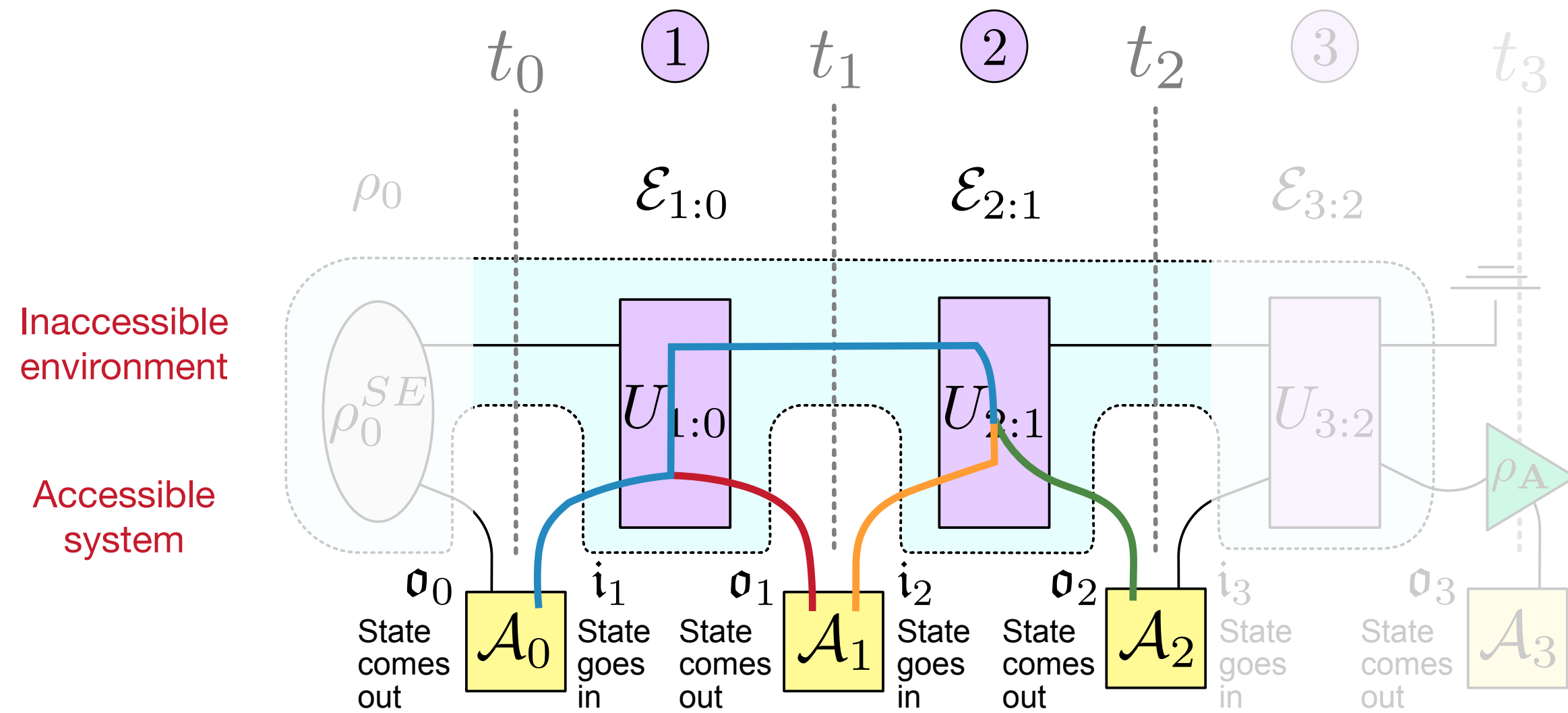
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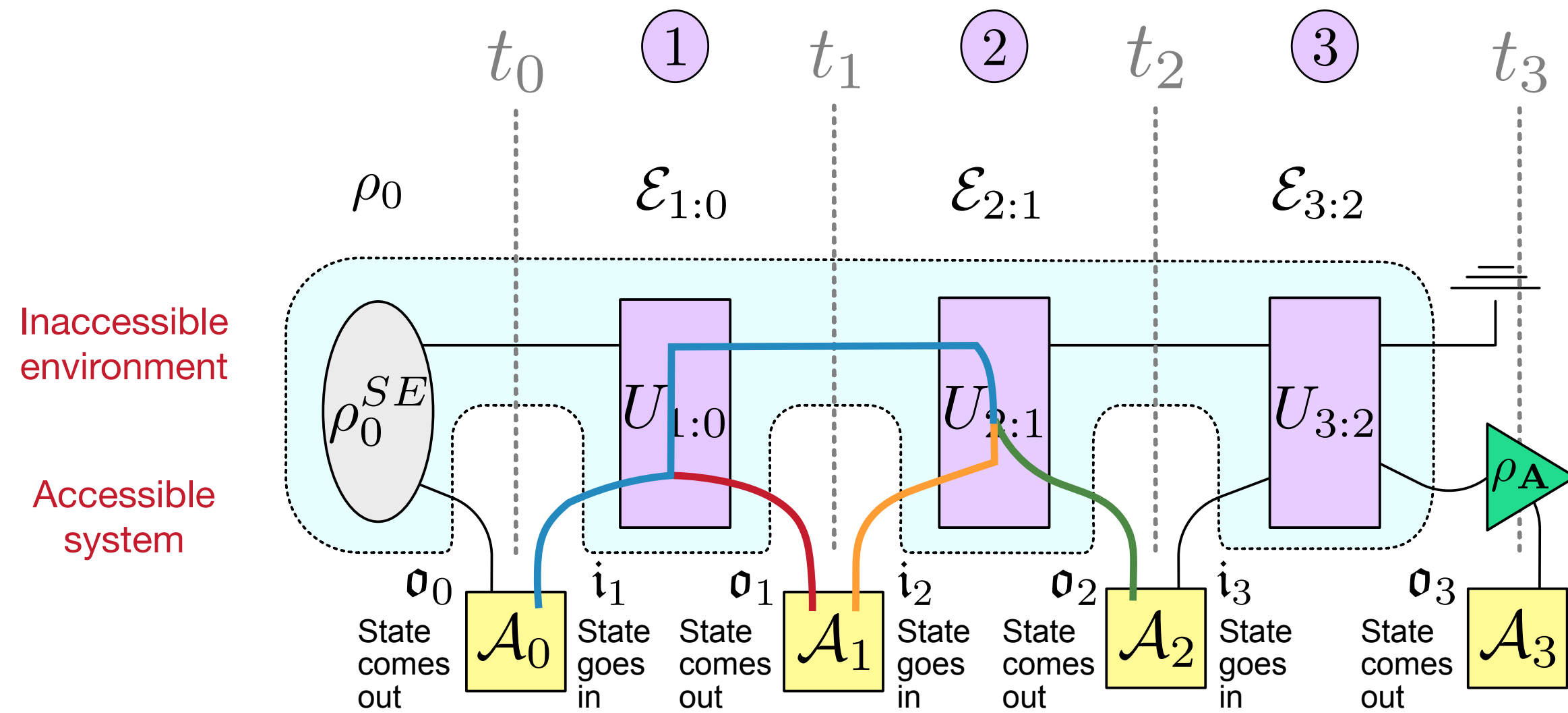
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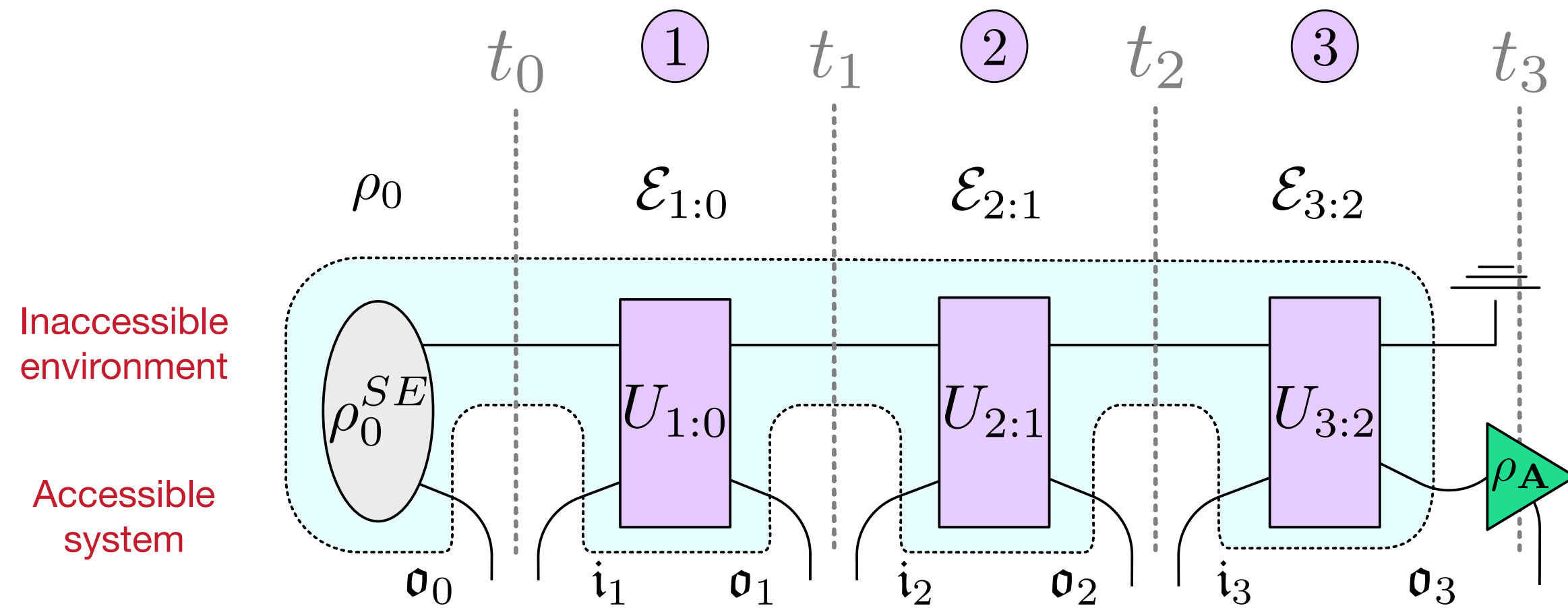
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- ▶ Introduce the process tensor

$$\mathcal{T}_{k:0}[\mathbf{A}_{k-1:0}] = \rho(\mathbf{A}_{k-1:0})$$
- ▶ Propagate a state along *and* account for control
- ▶ Control can manipulate and allow you to learn things
- ▶ Sequences of control operations are observables of the process

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Controls are events we can choose, process exists independently

Controls: deterministic, classical stochastic, quantum stochastic

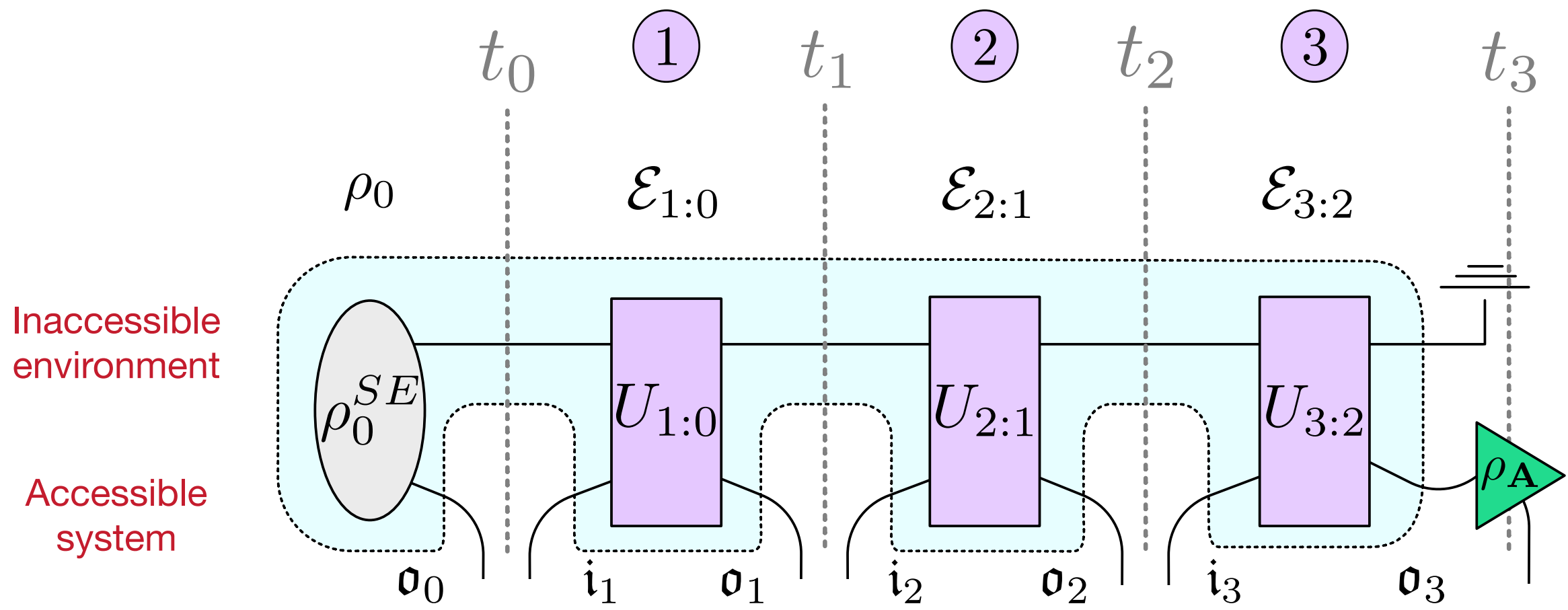
Instruments can click with outcome x_j at time t_j

$$\Pr(x_j, t_j; x_{j-1}, t_{j-1}; \dots; x_0, t_0 | \mathbf{A}_{j:0}).$$

We now have a description of quantum stochastic processes

Milz et al. Quantum 4, 255 (2020)

Pollock et al. Phys. Rev. A **97**, 012127 (2018)



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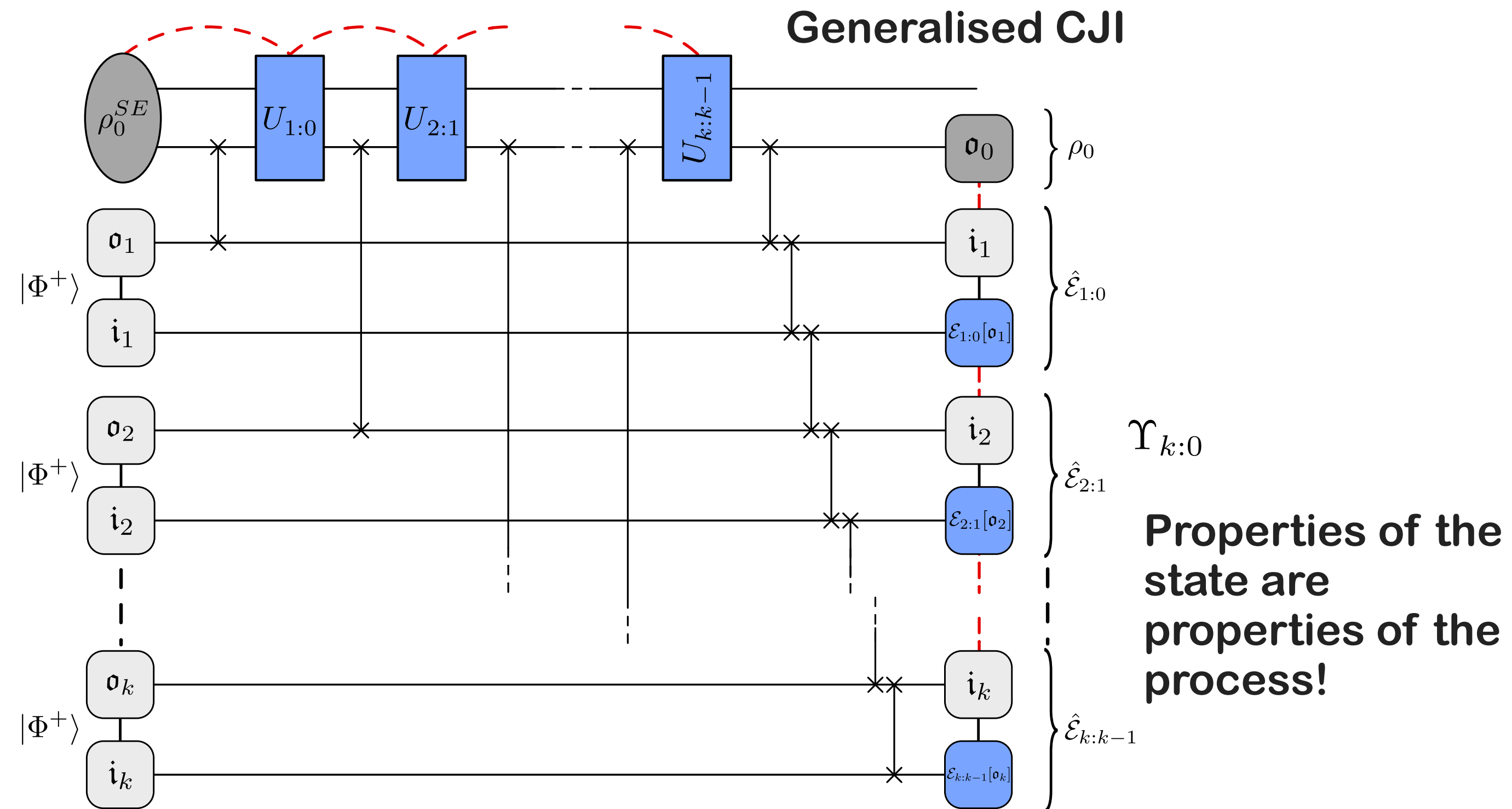
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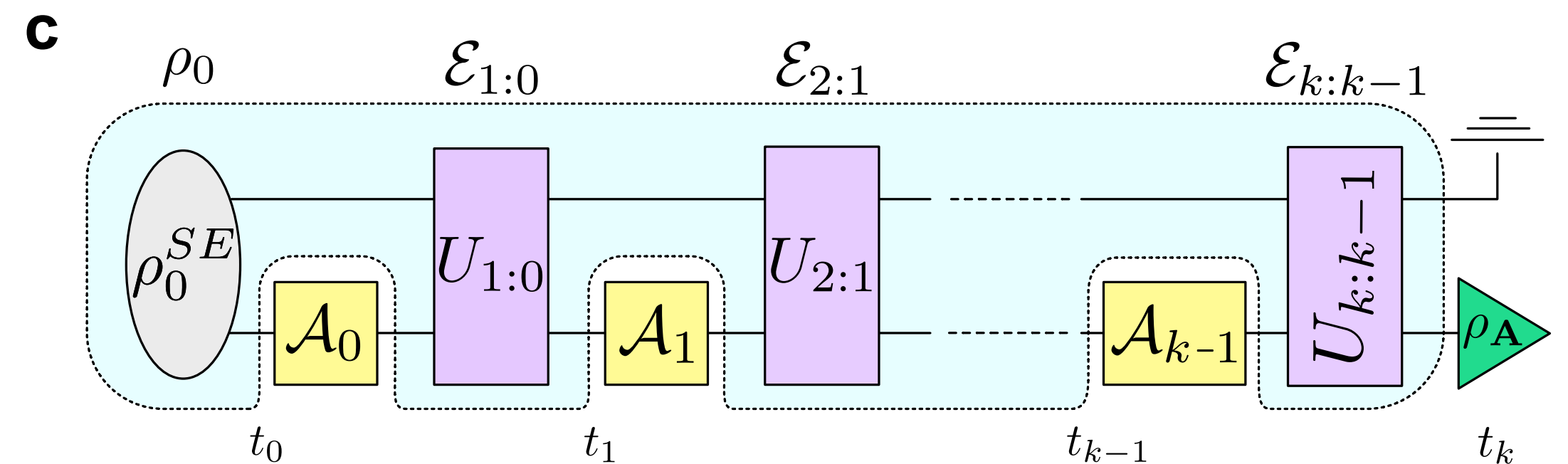
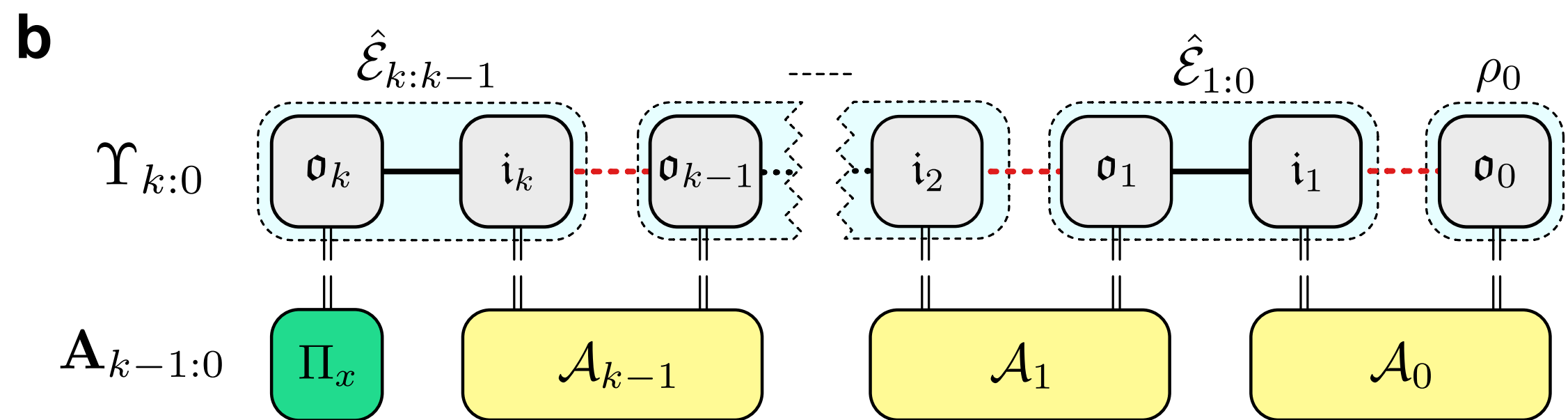
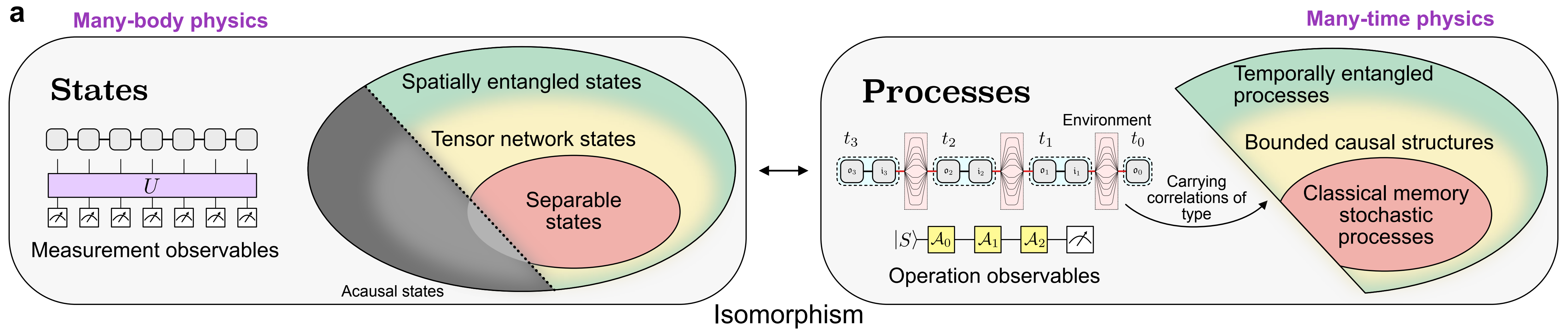
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Milz et al. Quantum 4, 255 (2020)





- ▶ Arbitrary correlations across time, mediated by an environment
- ▶ Formally structured in the same way as spatial many-body correlations
- ▶ What's missing is a way to study these correlations in a practical setting for arbitrary open dynamics

Aharonov et al. Phys. Rev. A **79**, 052110 (2009)

Costa et al. Phys. Rev. A **98**, 012328 (2018)

Ried et al. Nature Physics **11**, 414-420 (2015)

Chiribella et al. Phys. Rev. A **80**, 022339 (2009)

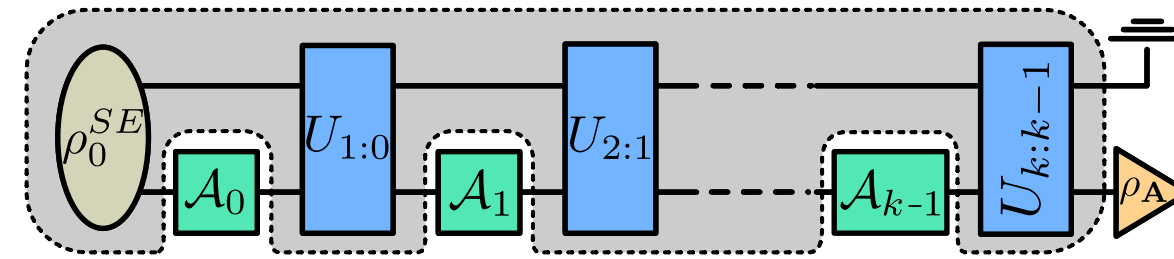
Costa & Shrapnel, New Journal of Physics **18**, 063032 (2016)

Pollock et al. Phys. Rev. A **97**, 012127 (2018)

Milz et al. SciPost Phys. **10**, 141 (2021)

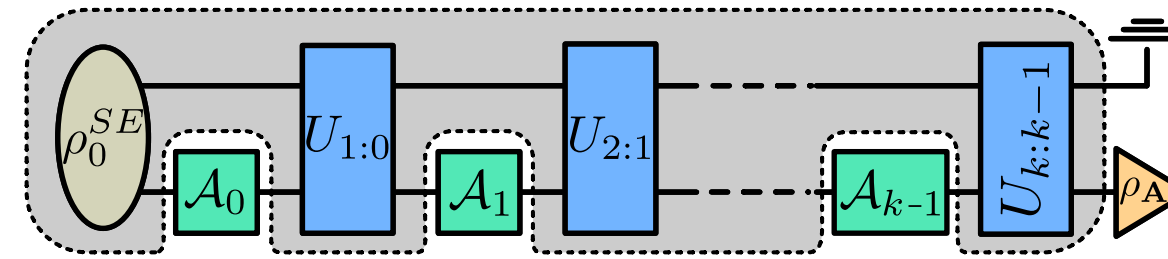
White et al. arXiv:2107.13934 (2021)

$$\mathbf{A}_{k-1:0} = \bigotimes_{j=0}^{k-1} \mathcal{A}_j$$



- ▶ Estimate non-Markovian dynamics
- ▶ Uniquely constrain on a complete basis

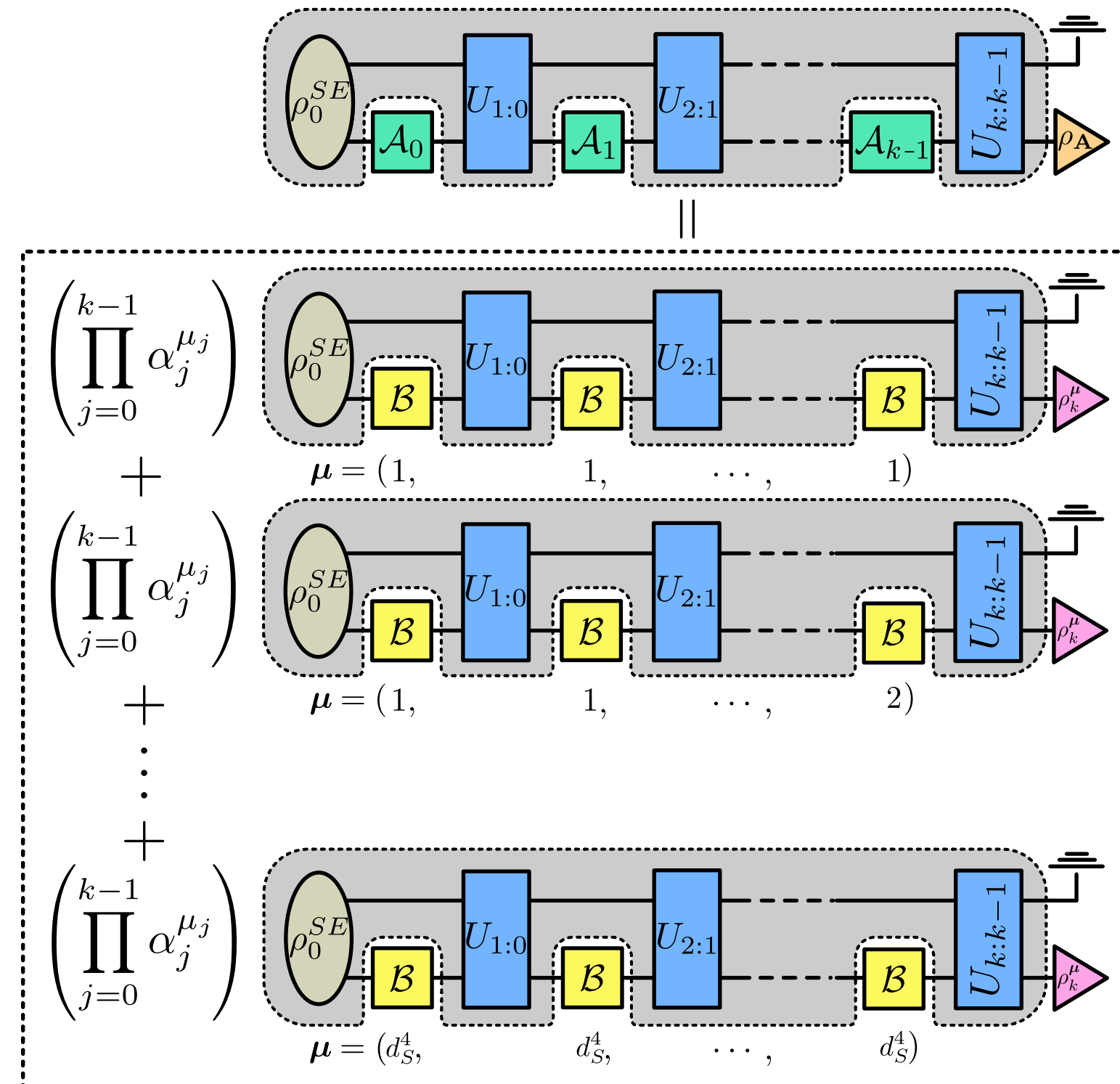
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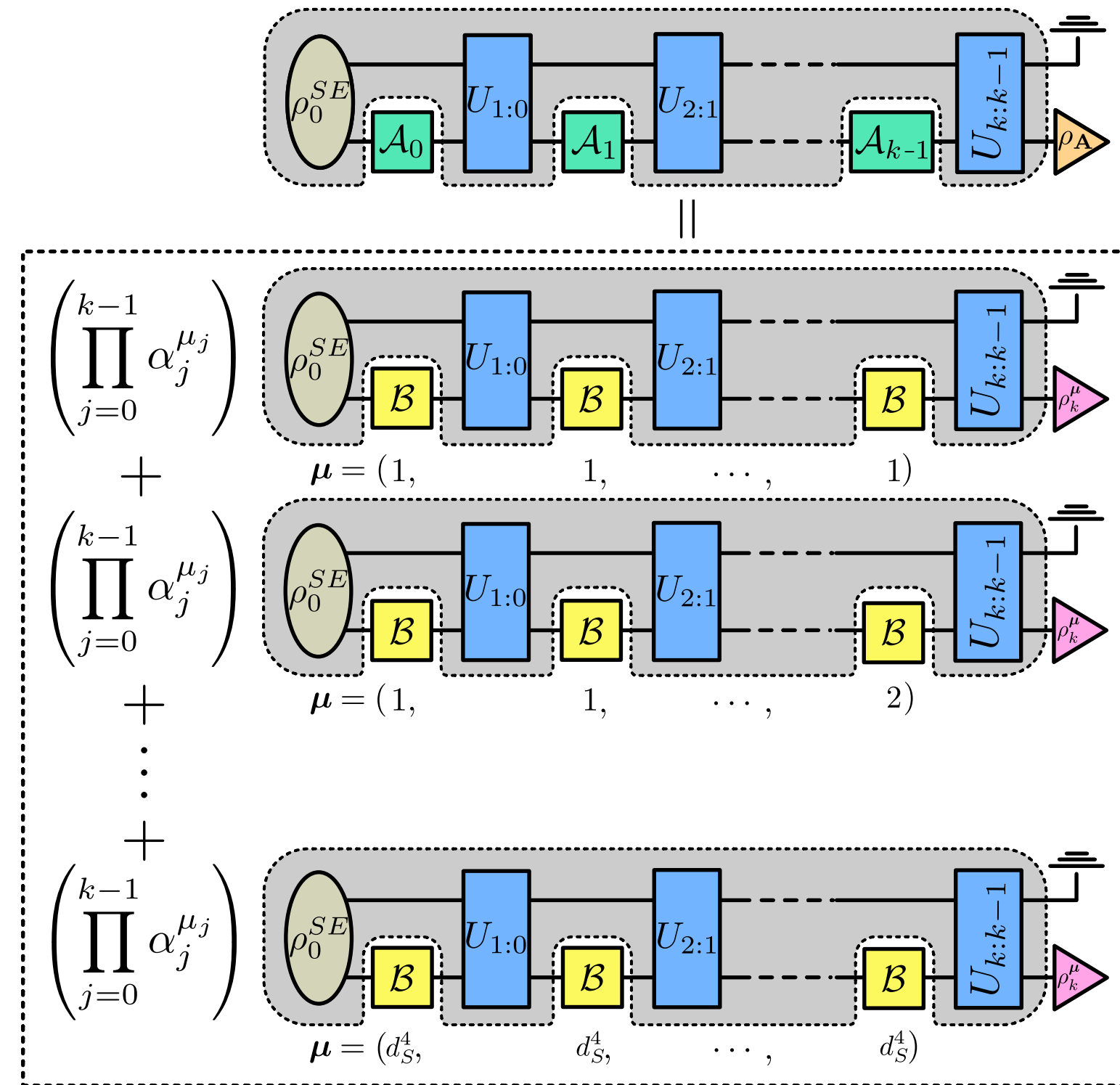
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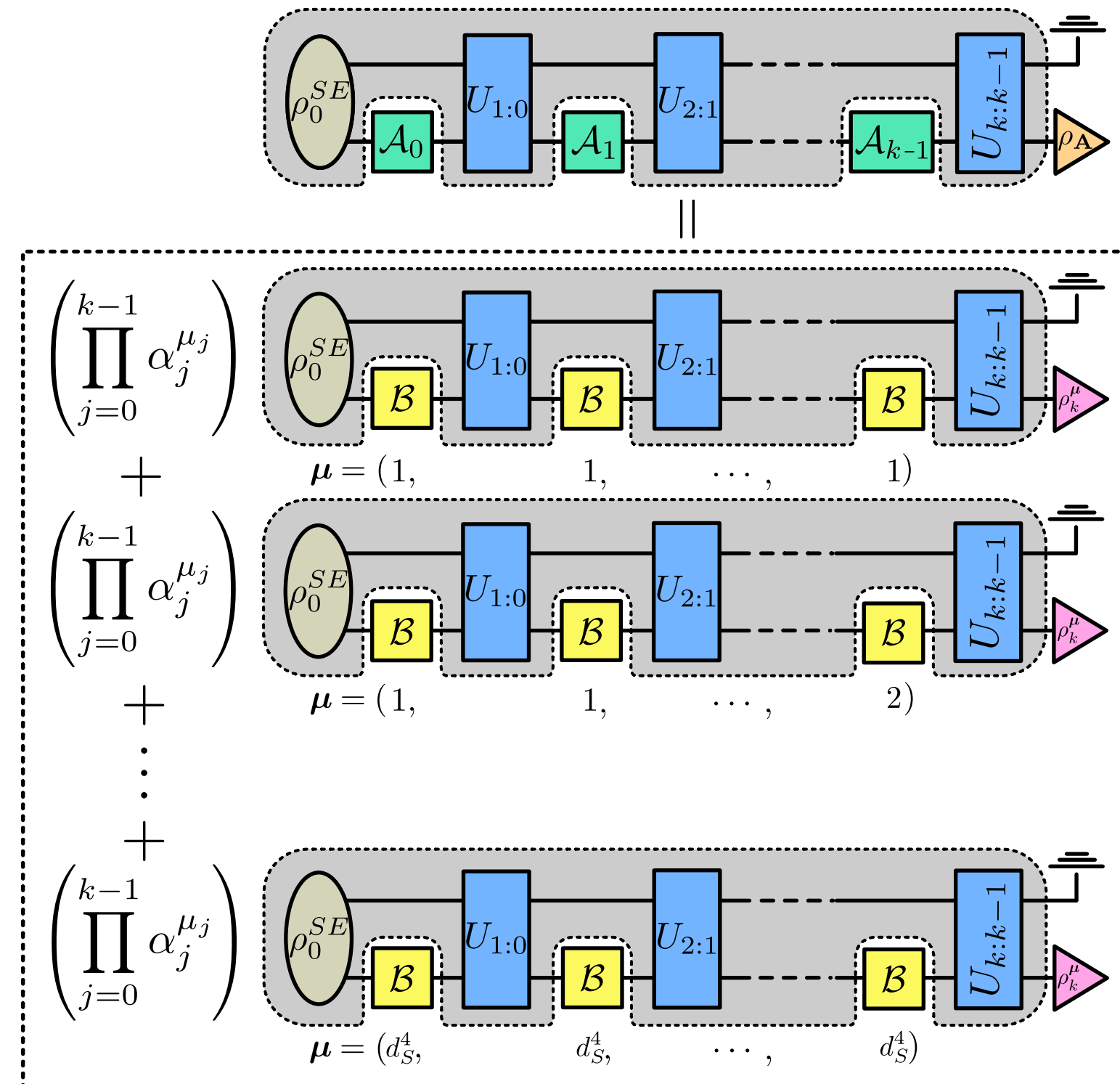
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Predicted state Basis states

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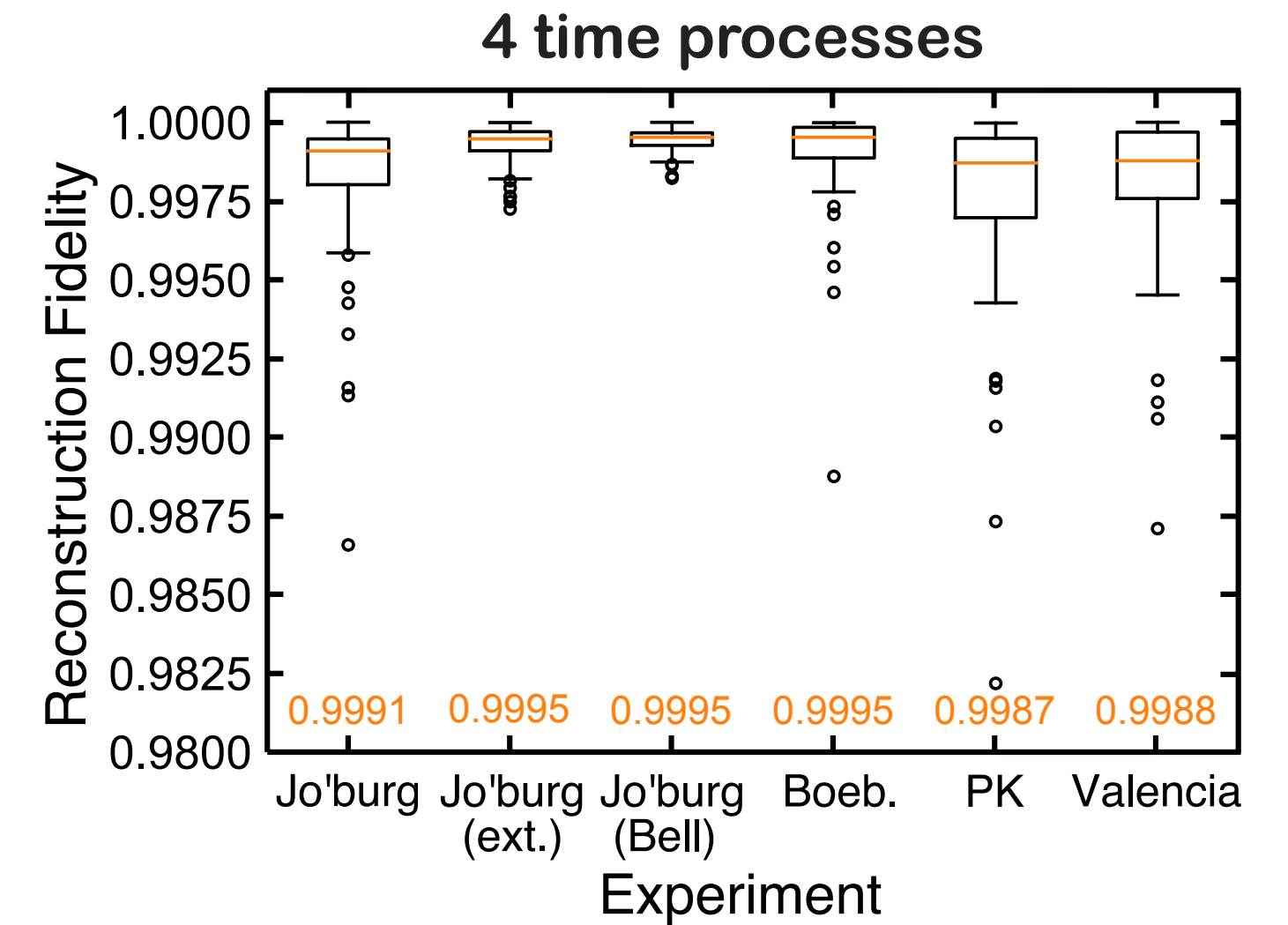
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- ▶ Use the process tensor to predict random sequences
- ▶ Compare how close the two are: ‘reconstruction fidelity’



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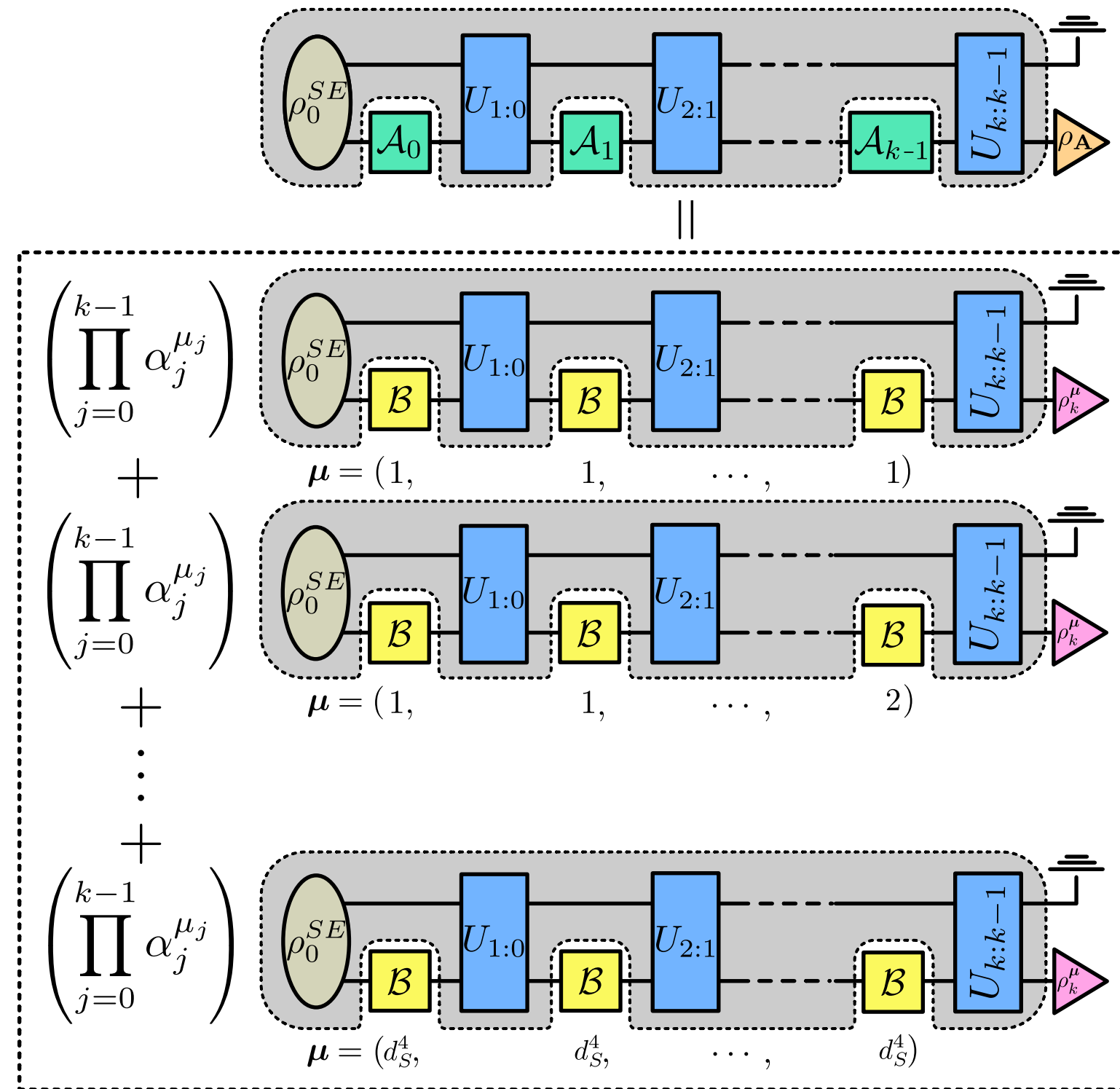
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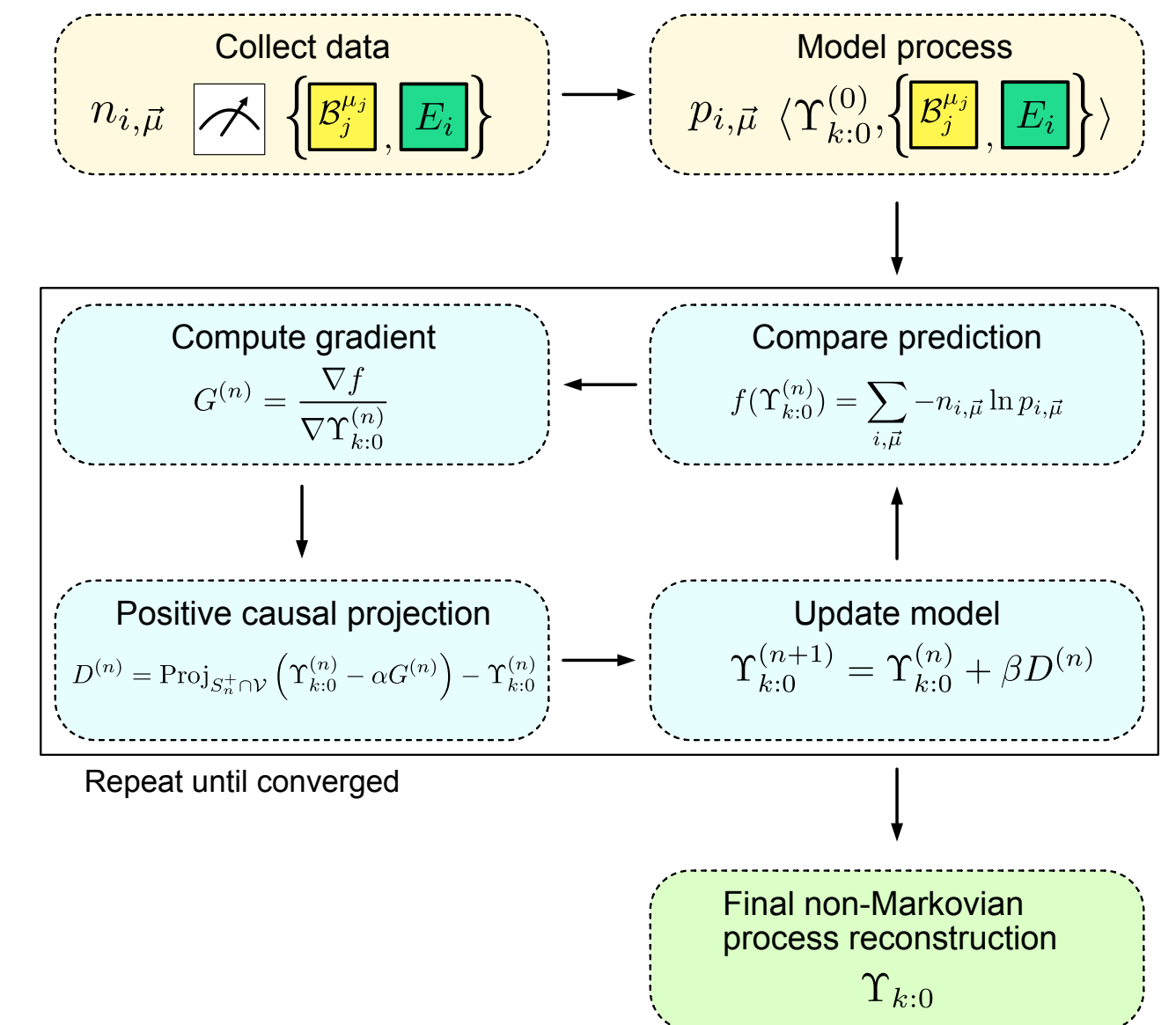
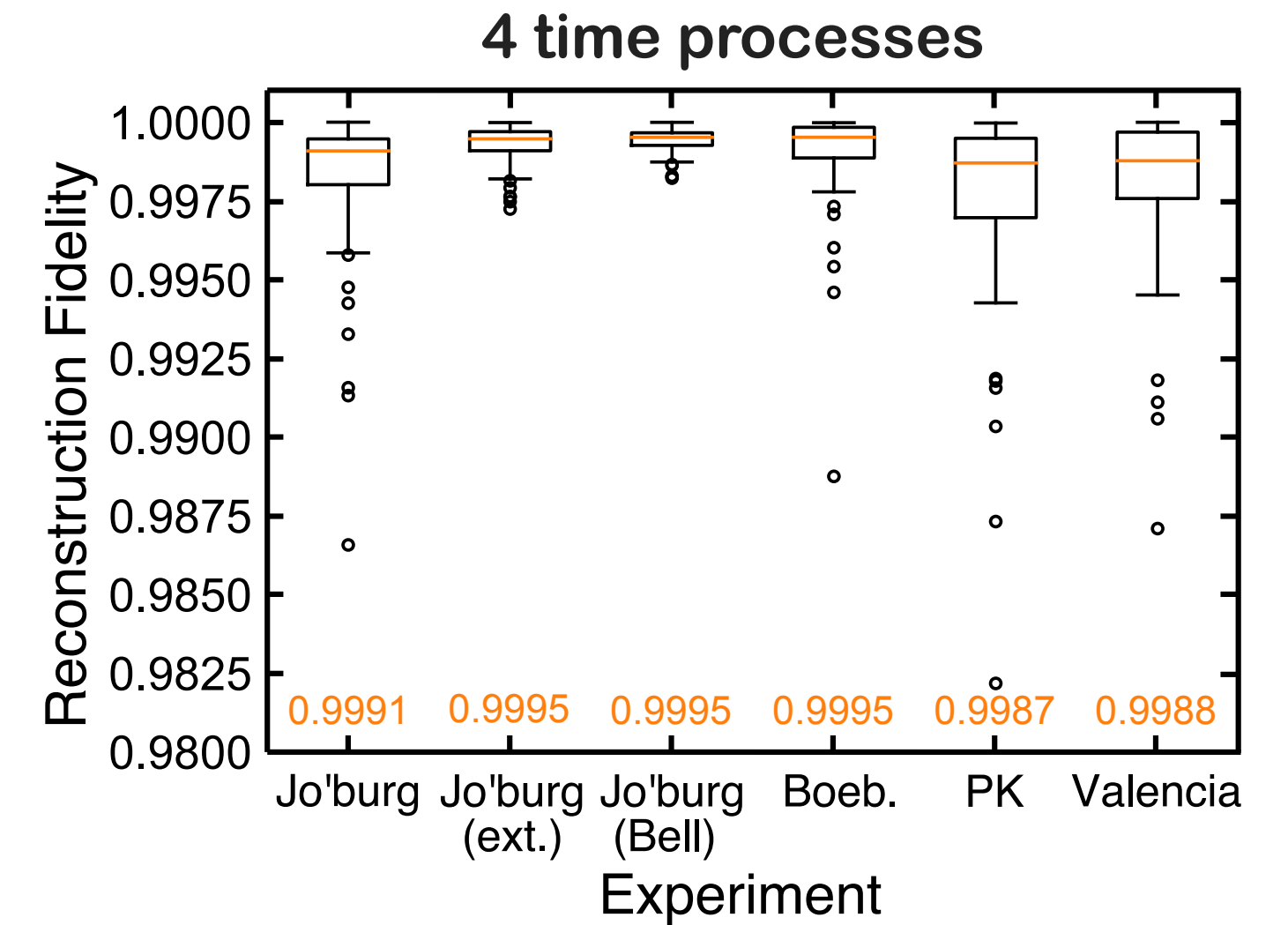
- ▶ Estimate non-Markovian dynamics
- ▶ Uniquely constrain on a complete basis
- ▶ Use the process tensor to predict random sequences
- ▶ Compare how close the two are: ‘reconstruction fidelity’
- ▶ Generalised Born rule connects process tensor to reality
- ▶ Fit a physical, maximum likelihood model



$$\rho_A = \sum_{\mu} \prod_{j=0}^{k-1} \alpha_j^{\mu_j} \rho_k^{\mu}$$

Predicted state Basis states

$$p_{i,\vec{\mu}} = \text{Tr} \left[(\Pi_i \otimes \mathbf{B}_k^{\mu_{k-1}\text{T}} \otimes \dots \otimes \mathbf{B}_0^{\mu_0\text{T}}) \Upsilon_{k:0} \right]$$



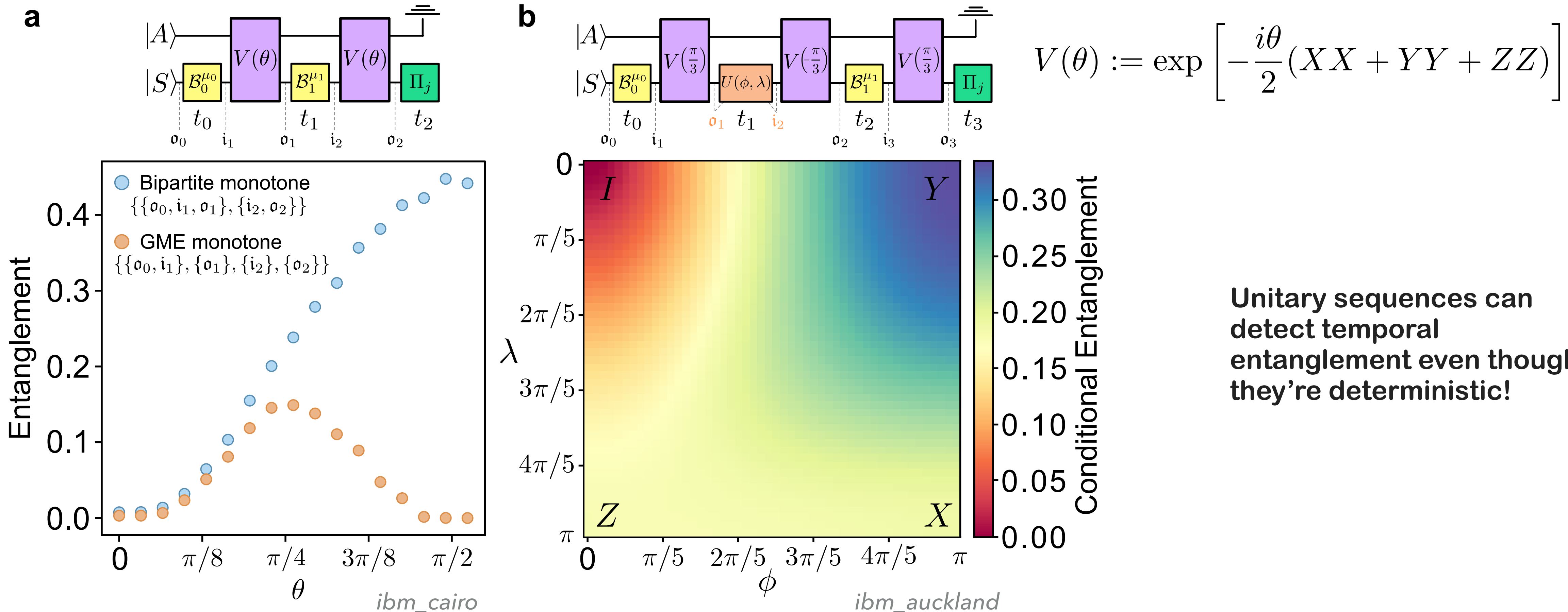
Example: Detecting Temporal Entanglement Structures

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- ▶ If W is constrained to be unitary, can we still measure temporal entanglement?

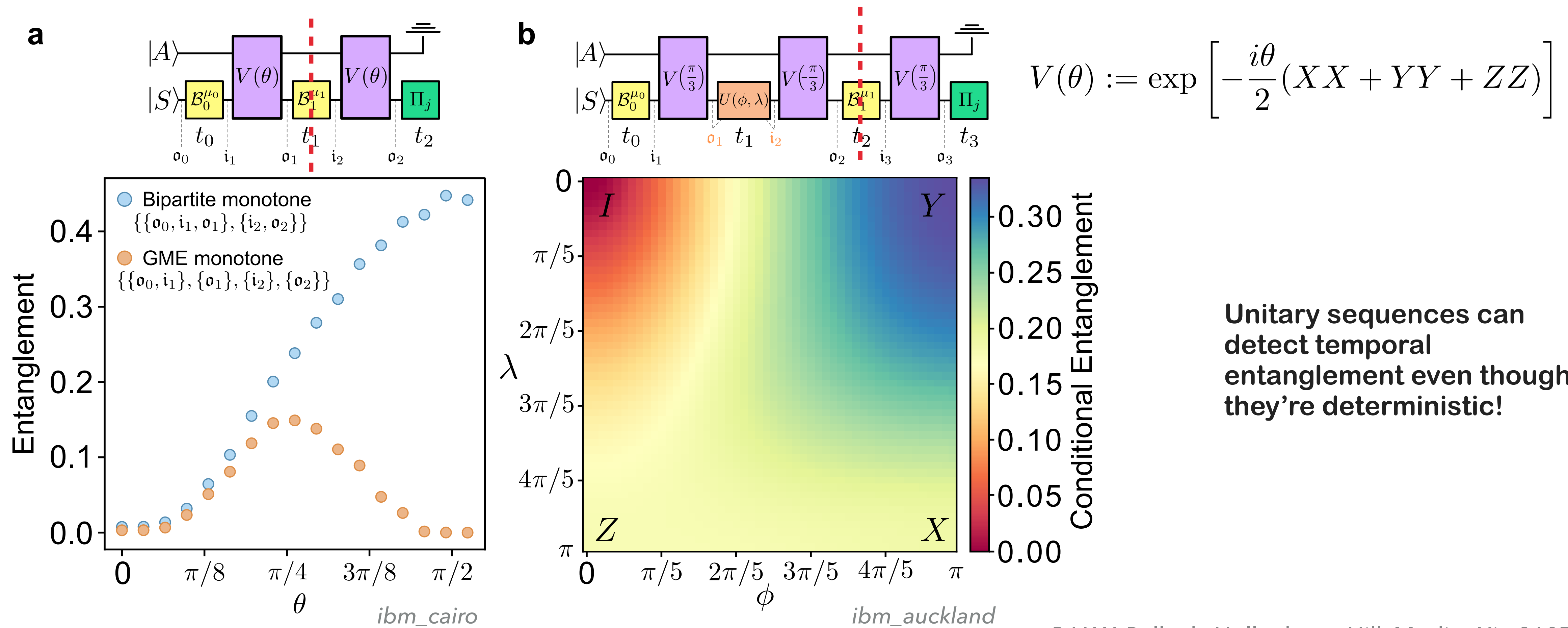
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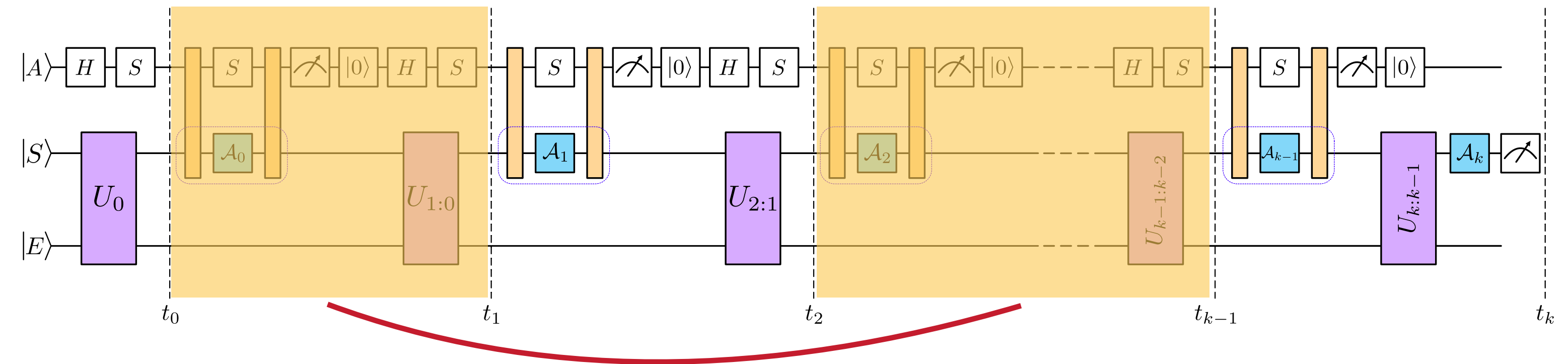
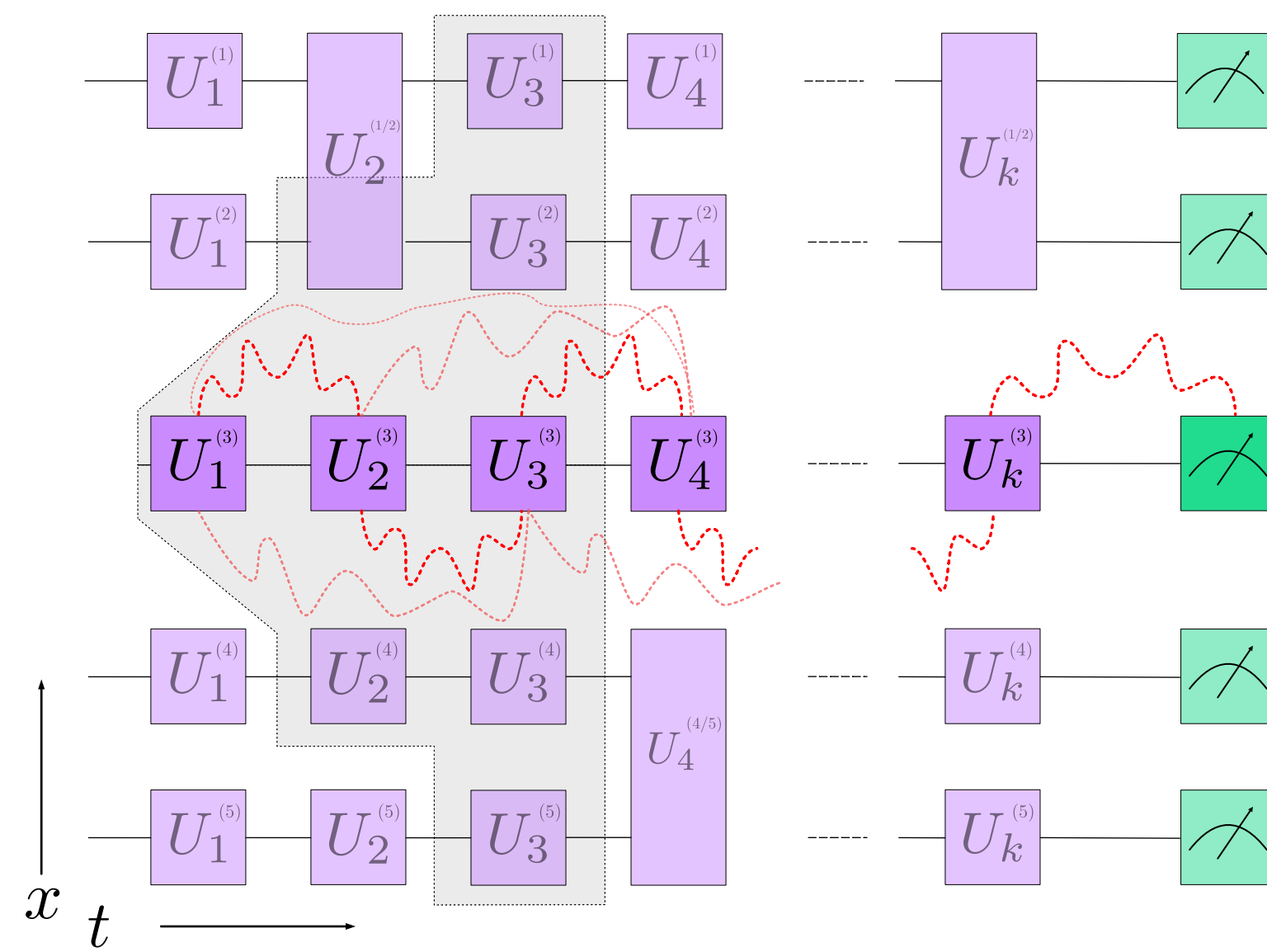


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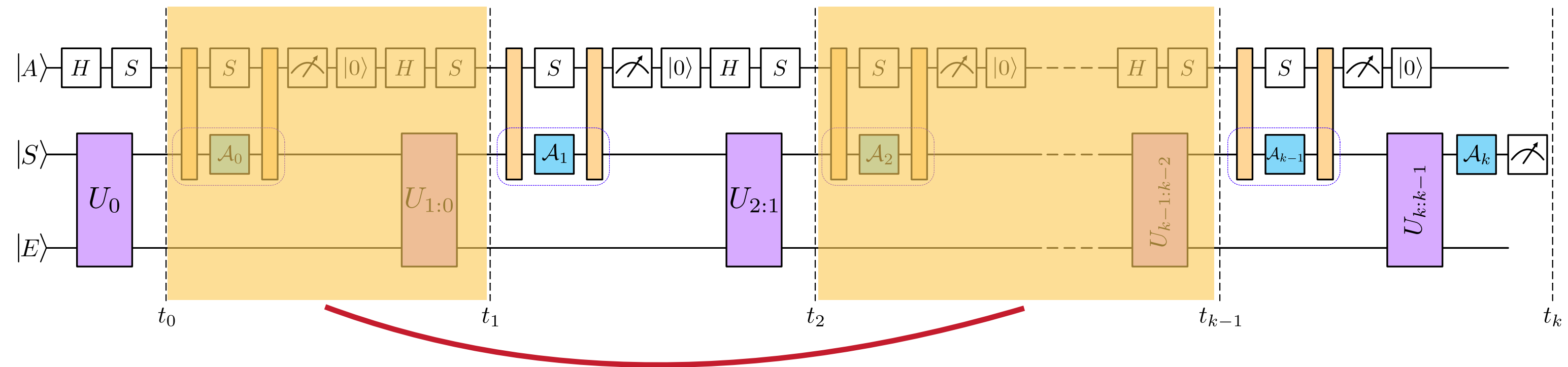
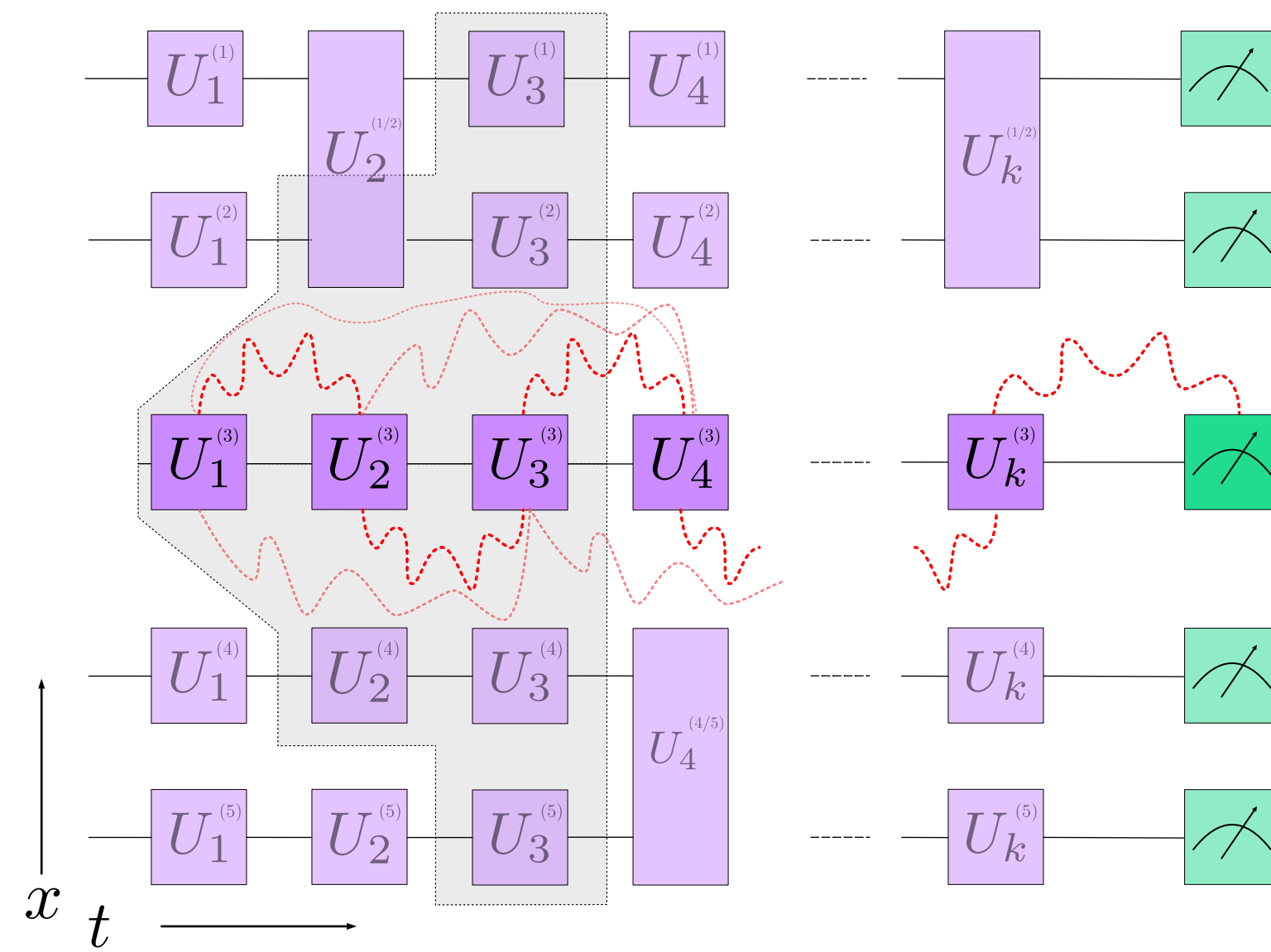
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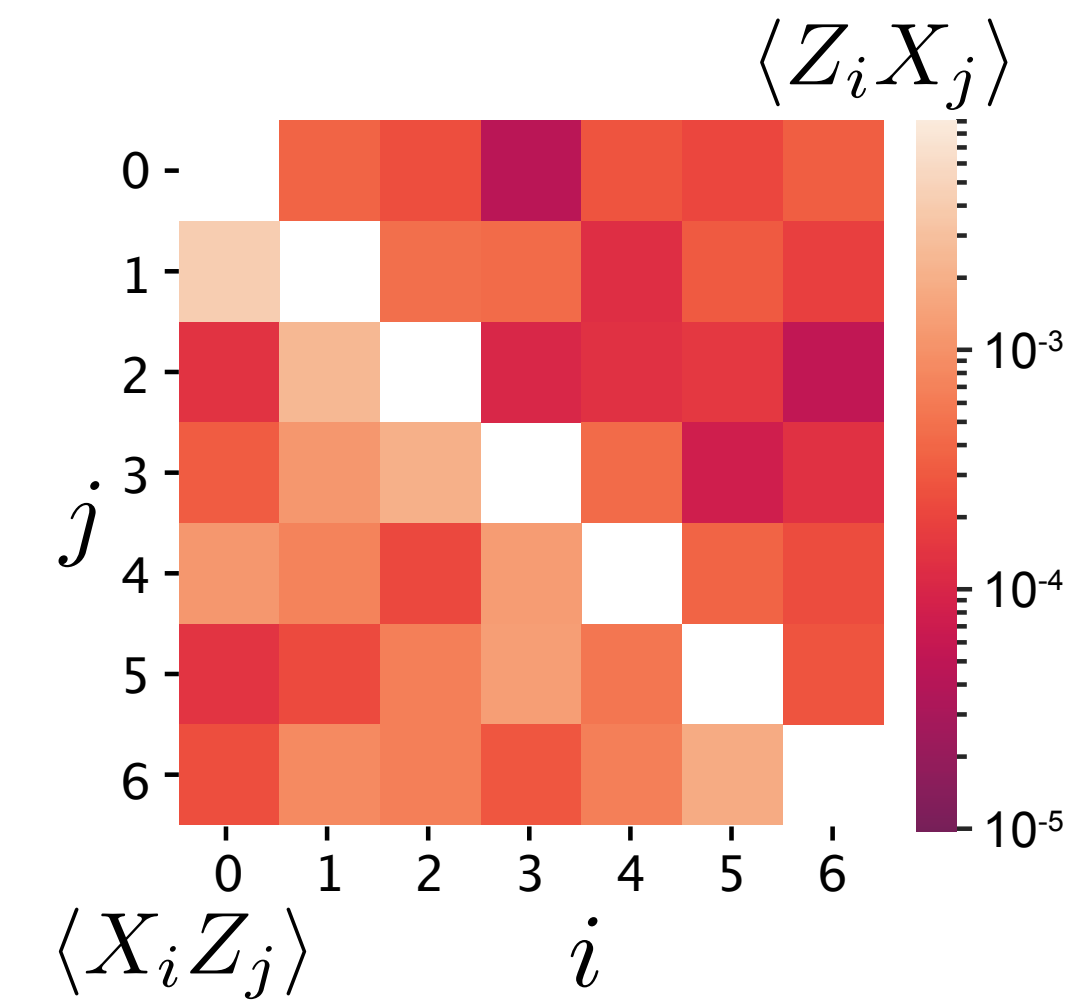
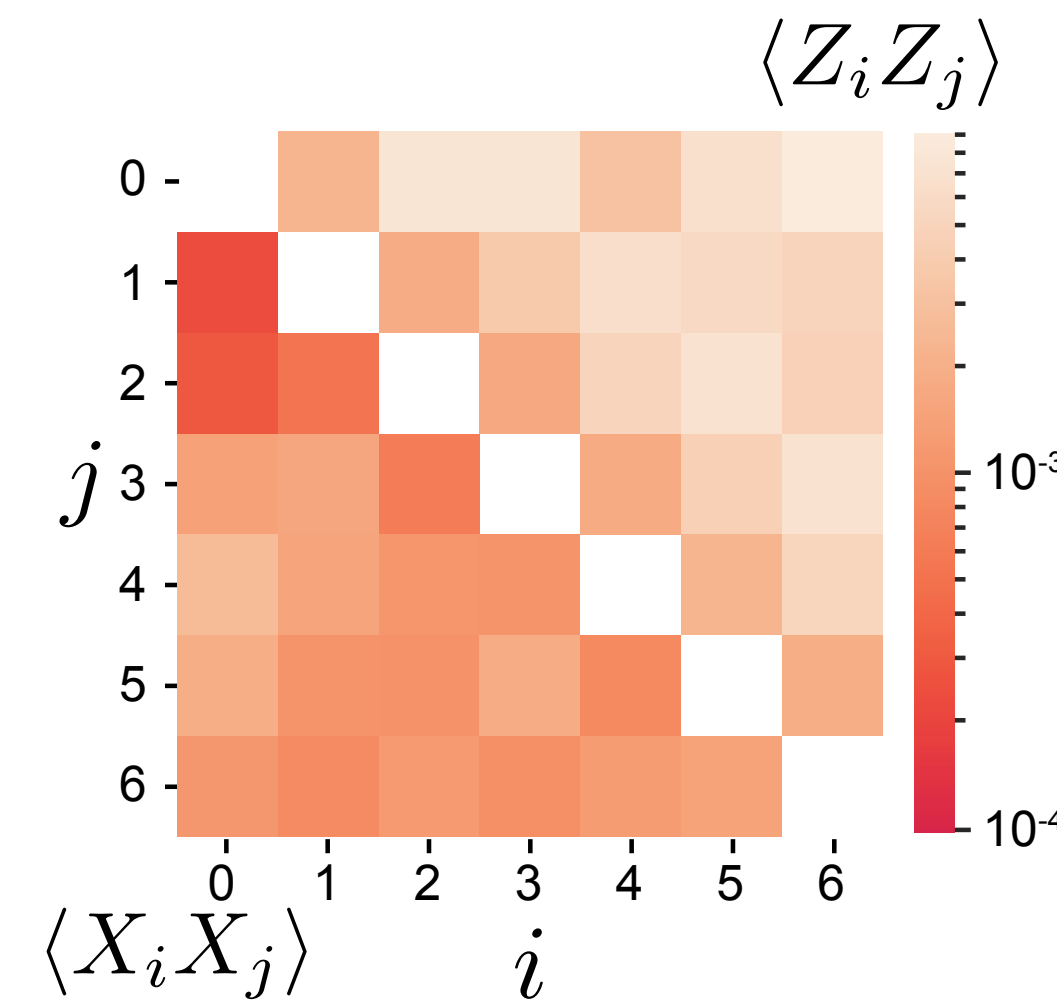
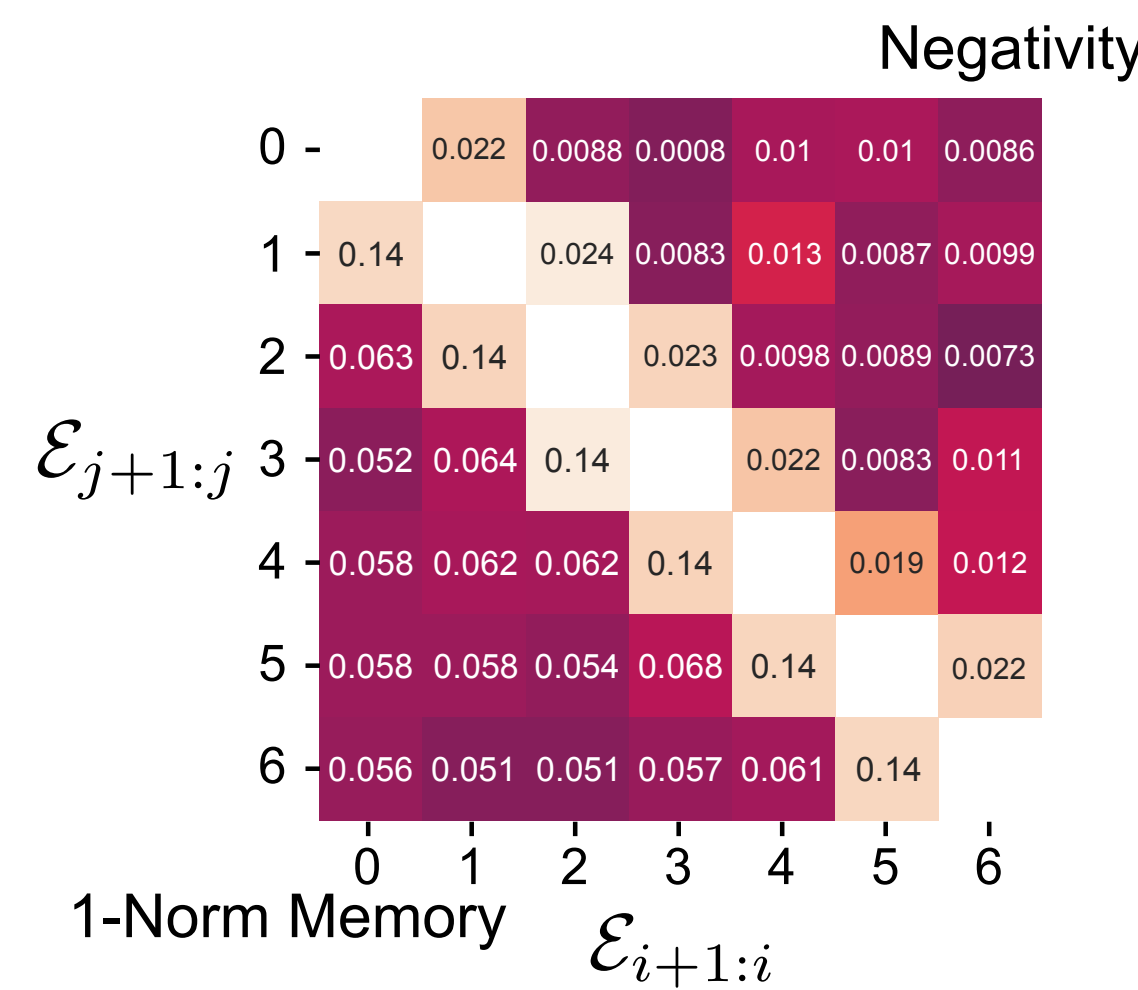
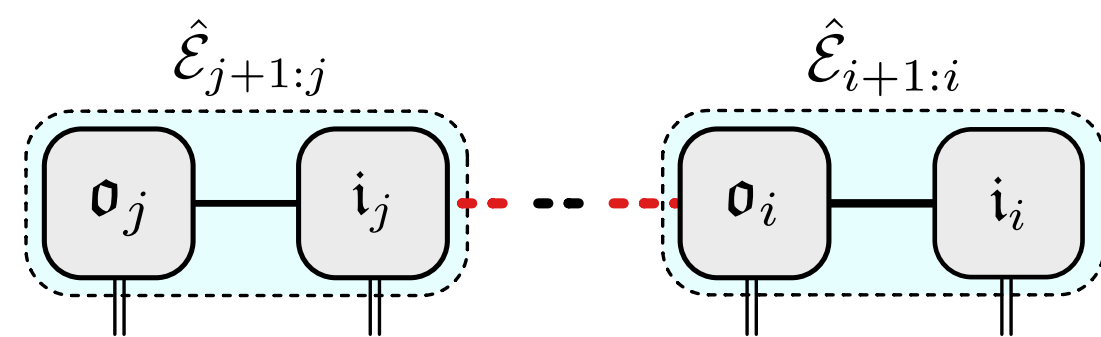
Diagnosing Correlated Noise



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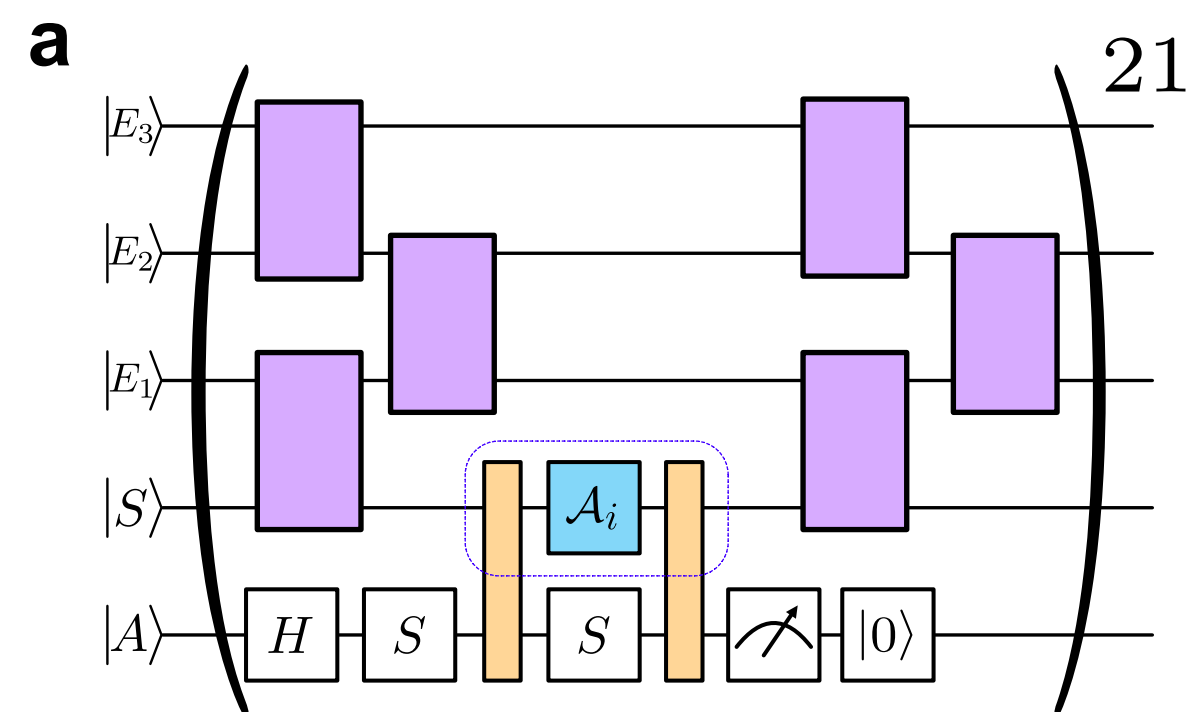


► Employ classical shadows to get the 2-map/4-body process marginals

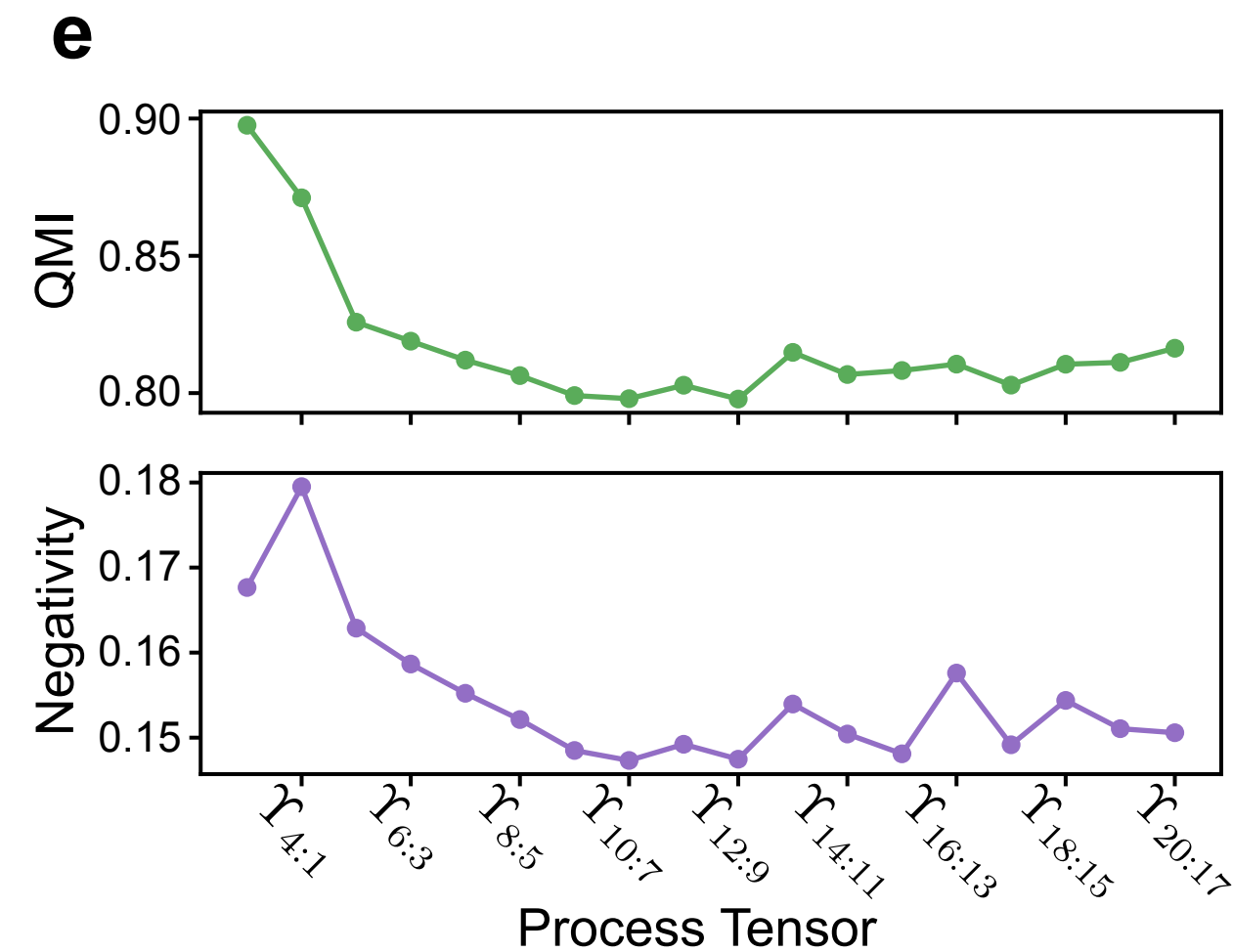
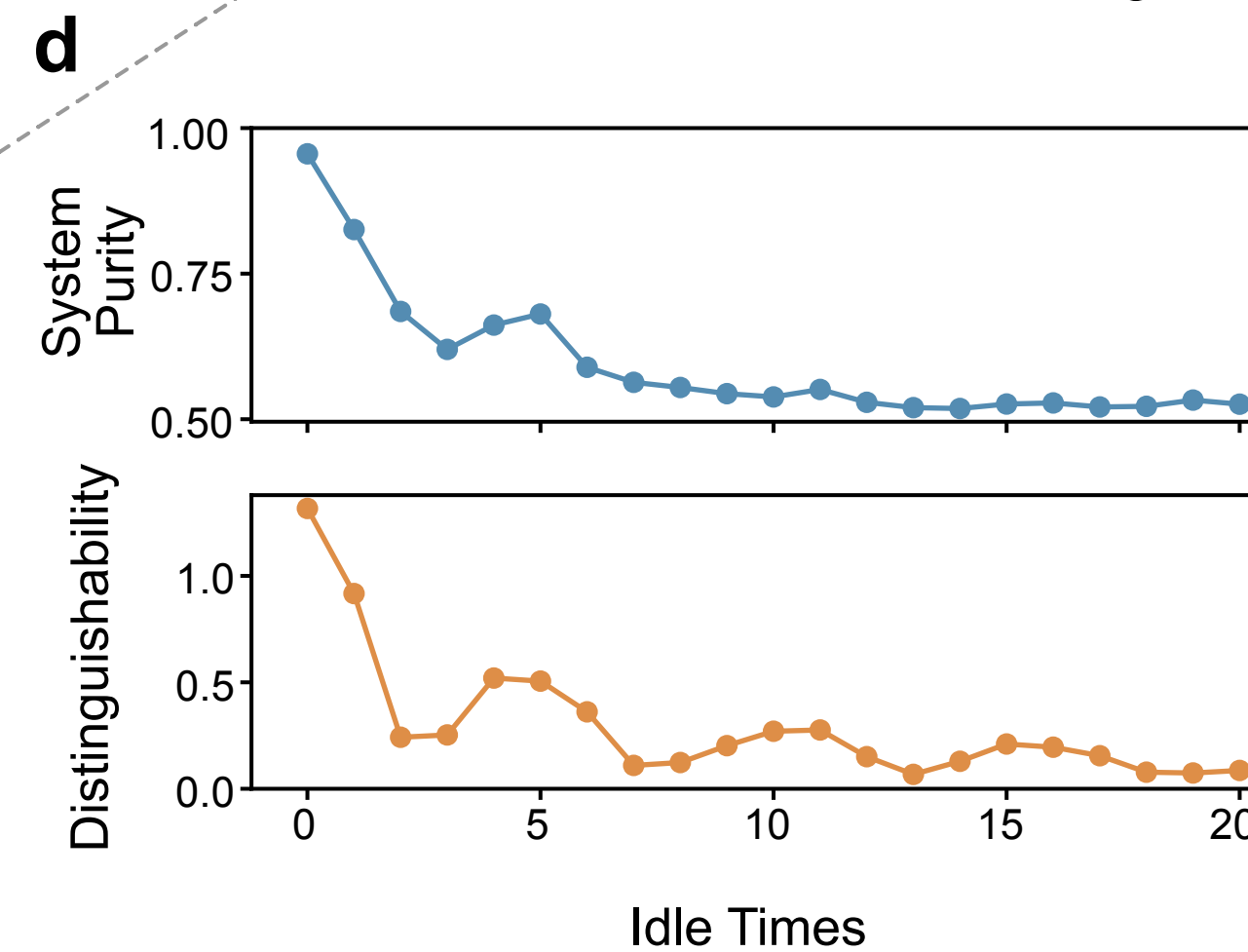
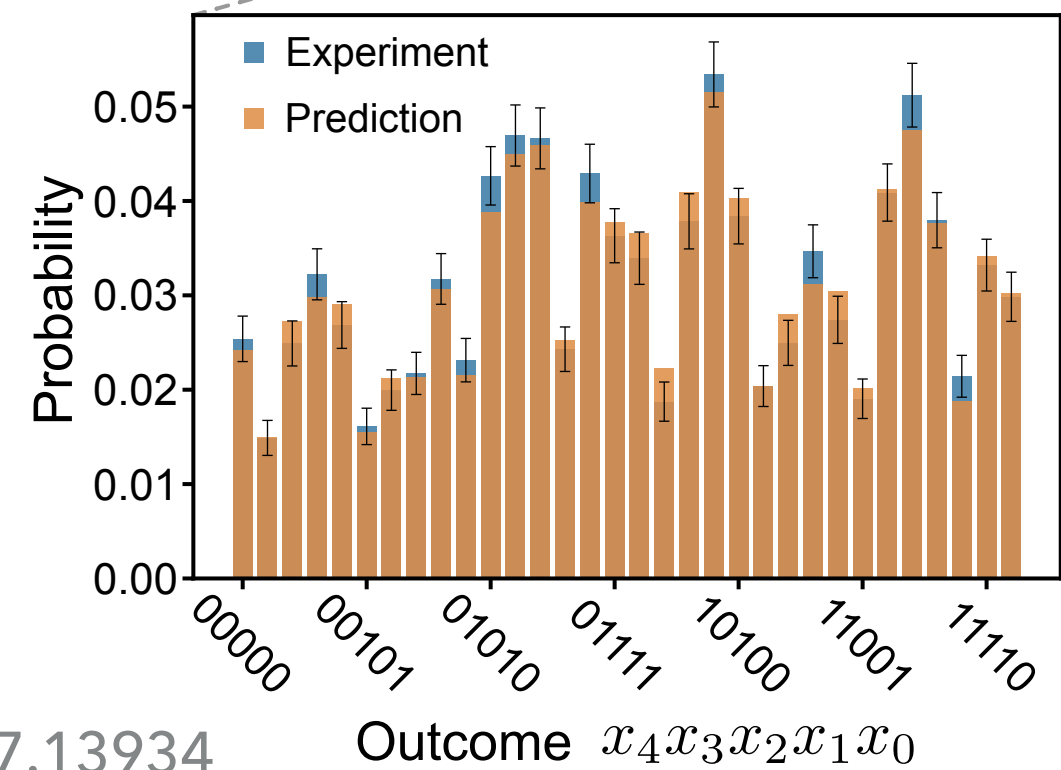
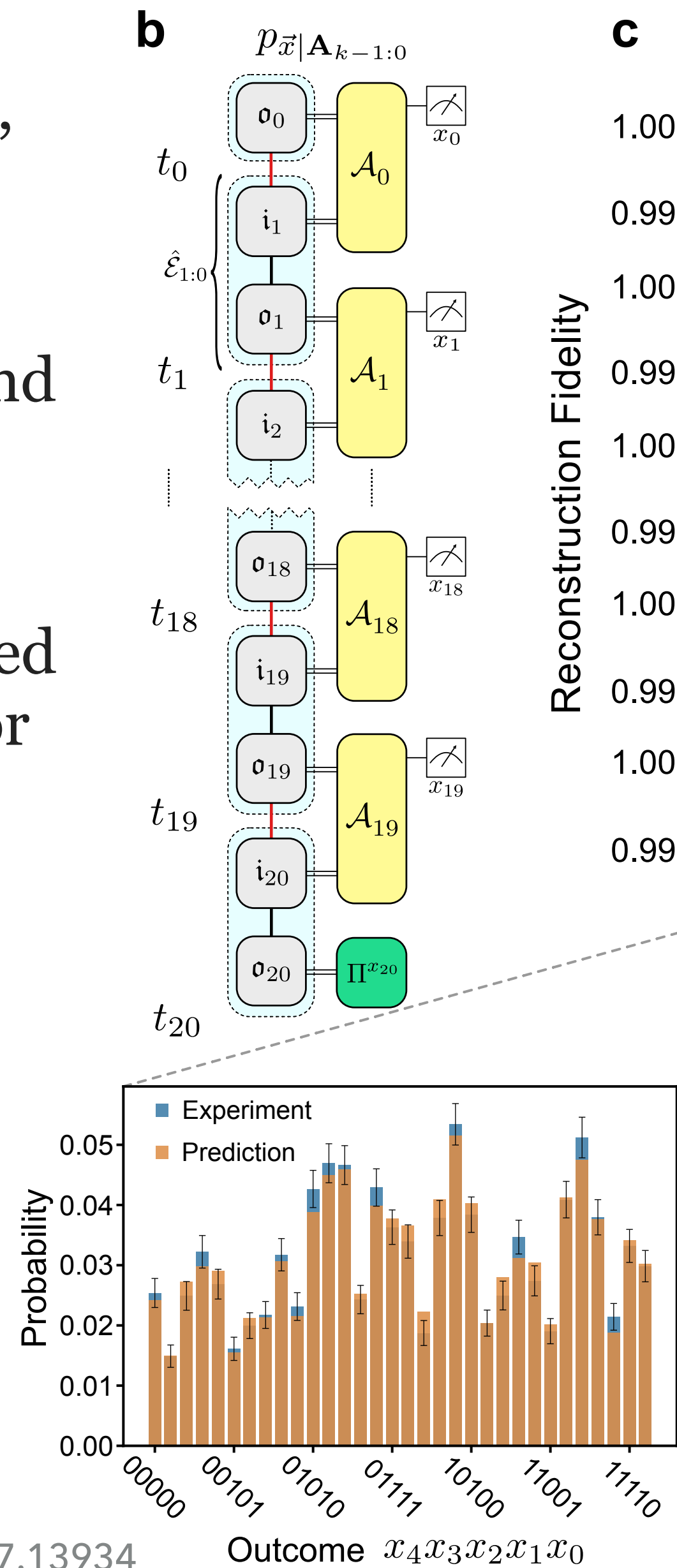
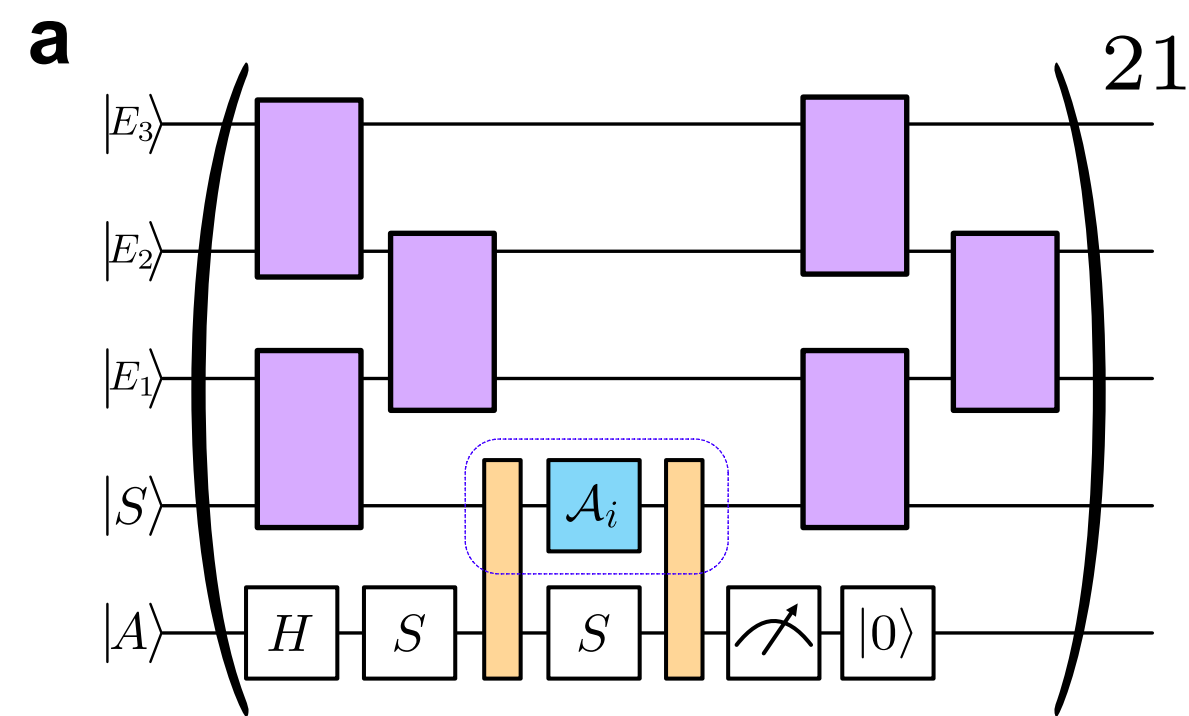


Real noise is genuinely complex across time

- ▶ Applied to simulating OQS, everything you can learn about a process
- ▶ Sampling complexity beyond classical simulability
- ▶ Using randomised control operations, we reconstructed the matrix product operator (MPO) representation of a 20-step process



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Aloisio et al. arXiv:2209.10870
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- ▶ Quantum stochastic processes are the most general description of open quantum dynamics
- ▶ Generalised CJI shows how many-time physics is as rich as many-body physics
- ▶ We develop ‘process tensor tomography’ and its variants to capture different aspects of the many-time physics
- ▶ We make it scalable, deal with device limitations, and self-consistent
- ▶ Estimate contains operational meanings about dynamics
- ▶ Demonstrated tomography and applications on IBM Quantum devices

Thanks for Listening!
Any Questions?

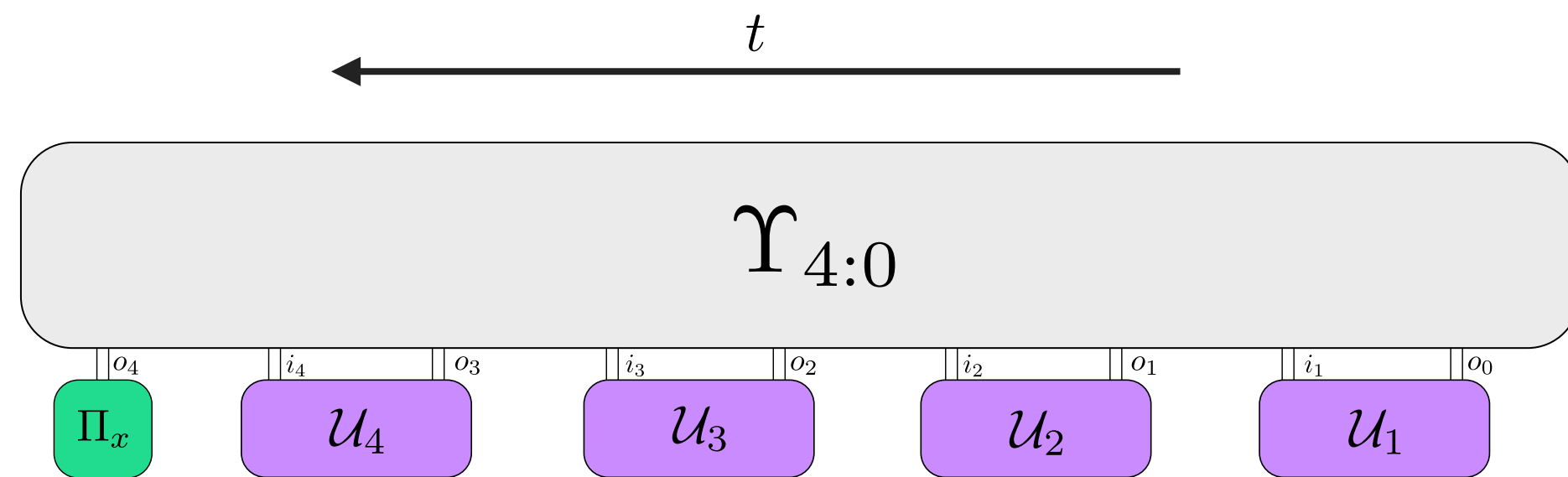
Demonstration – Nature Communications 11 (1), 6301 (2020)

Generalised QPT – PRX Quantum **3**, 020344 (2022)

Many-time physics – arXiv:2107.13934

Complexity of OQS – arXiv:2209.10870

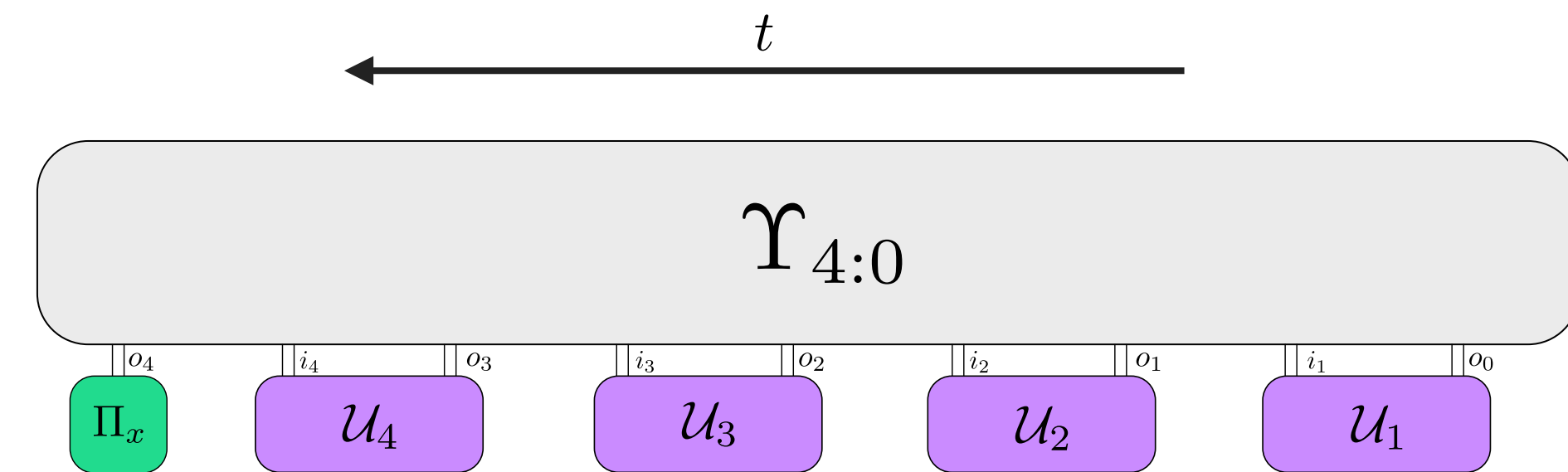
Filtering crosstalk with shadows – arXiv:2210.15333



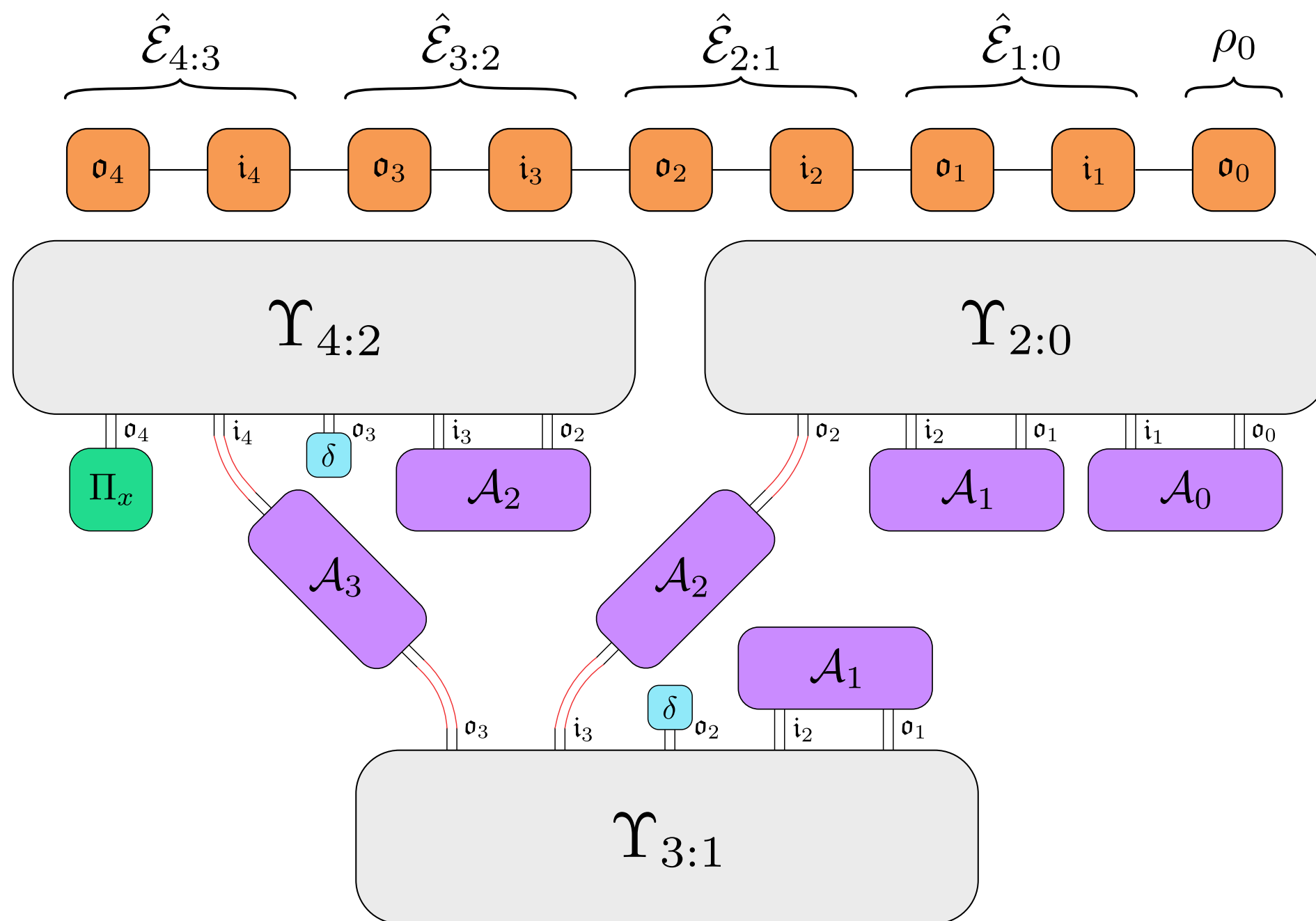
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$$3 \times 10^k = 30\,000$$

- ▶ Full characterisation scales exponentially poorly
- ▶ Markov order: classically, averaging over all but previous l time steps — same statistics at the present
- ▶ No generic extension to quantum
- ▶ Instead, (approximate) *conditional* Markov order



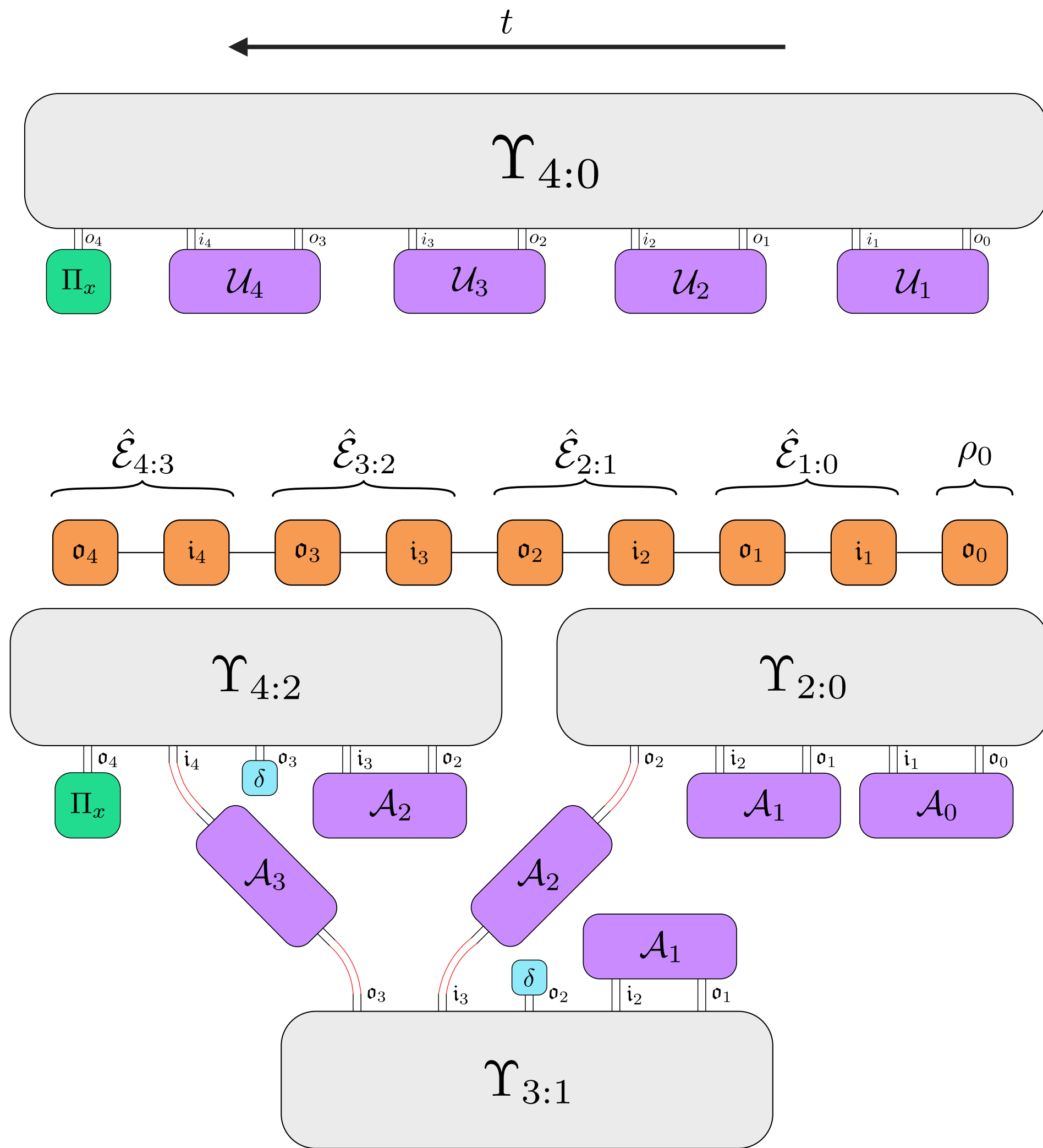
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$k = 4, l = 2$

$(k - l + 1) \times 3 \times 10^l = 900$

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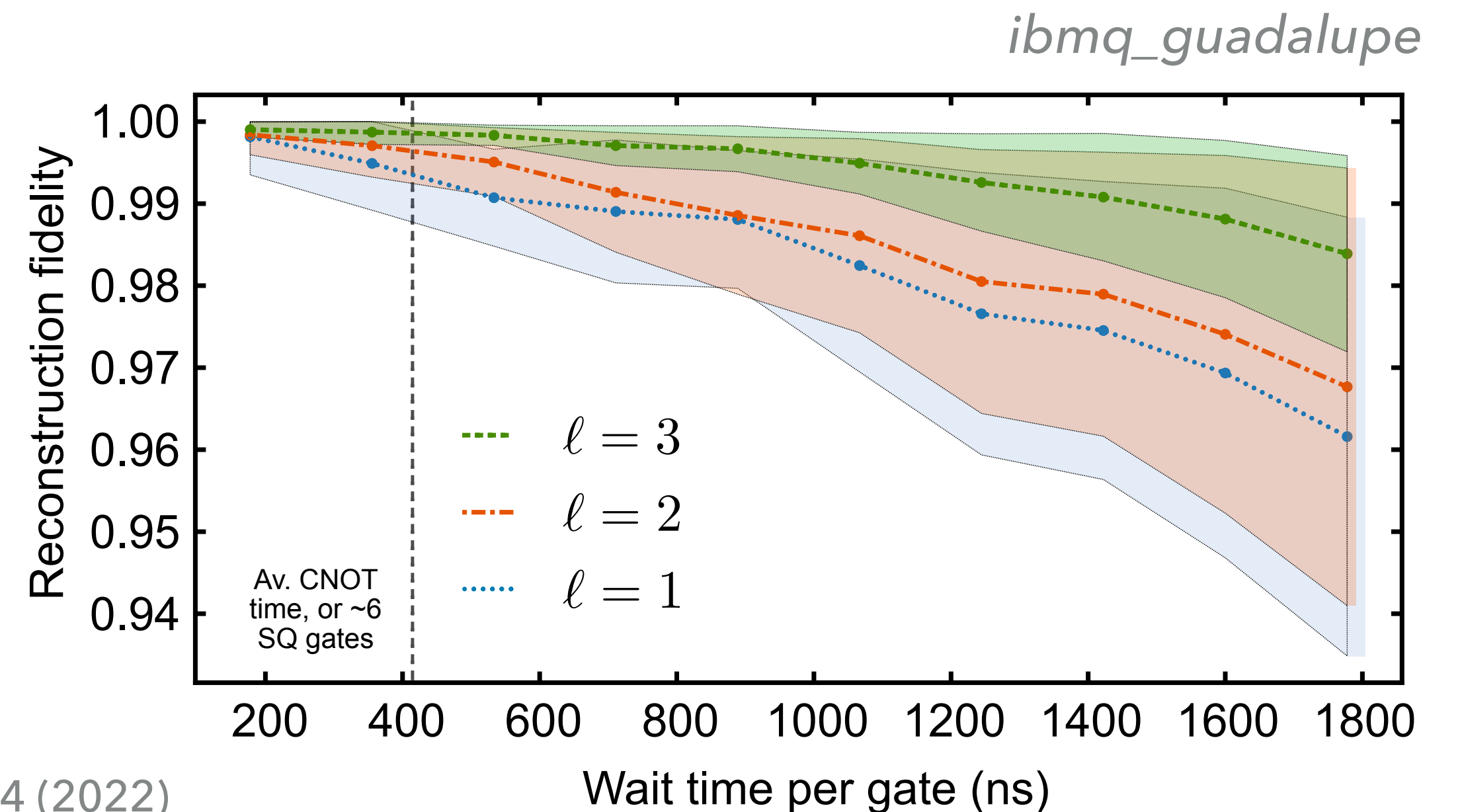


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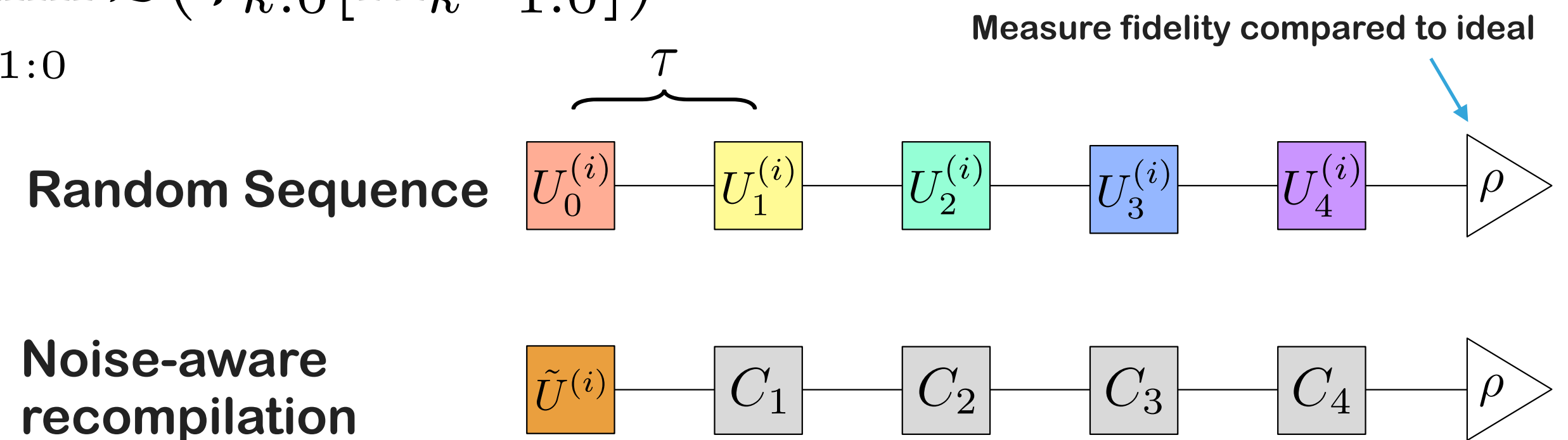
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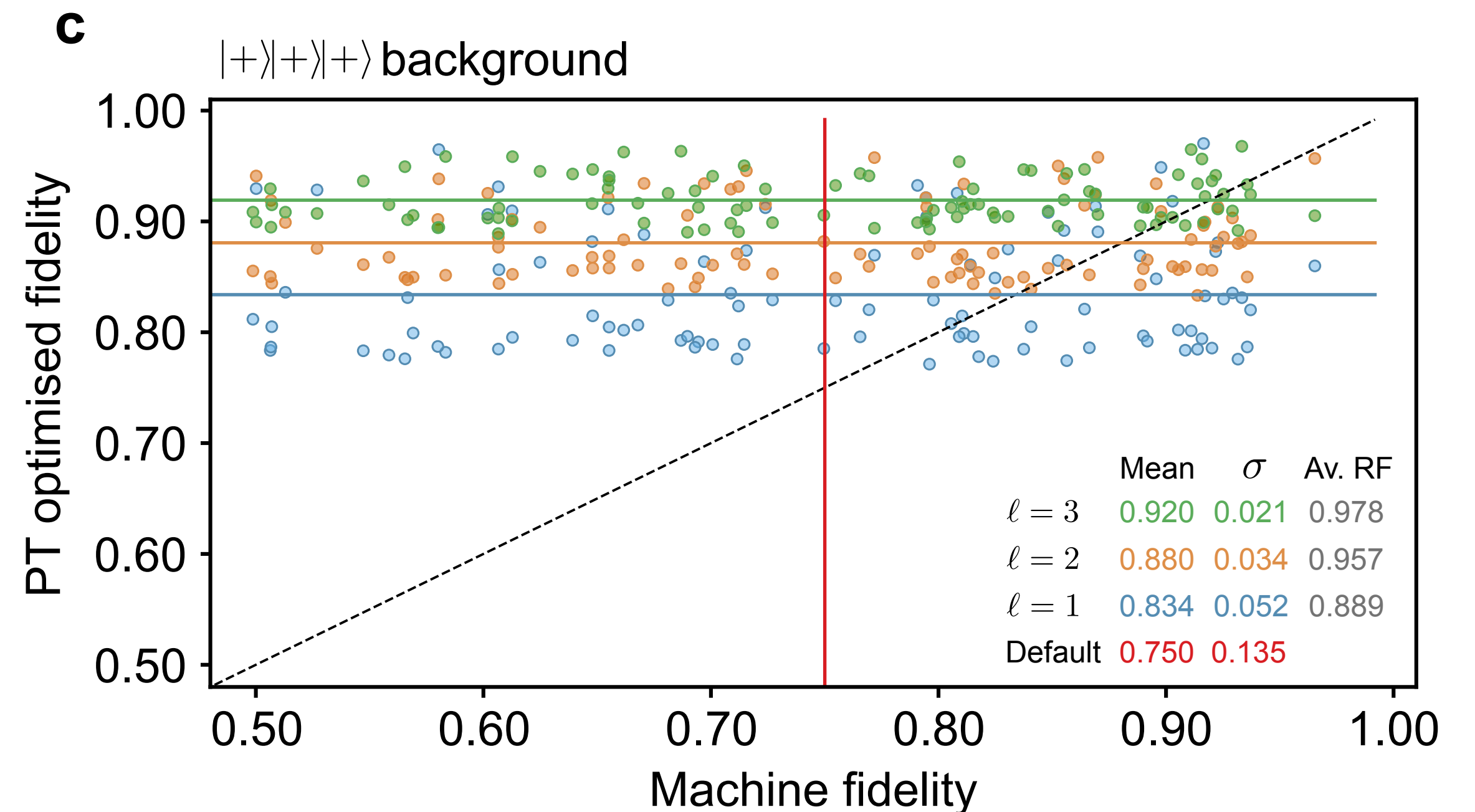
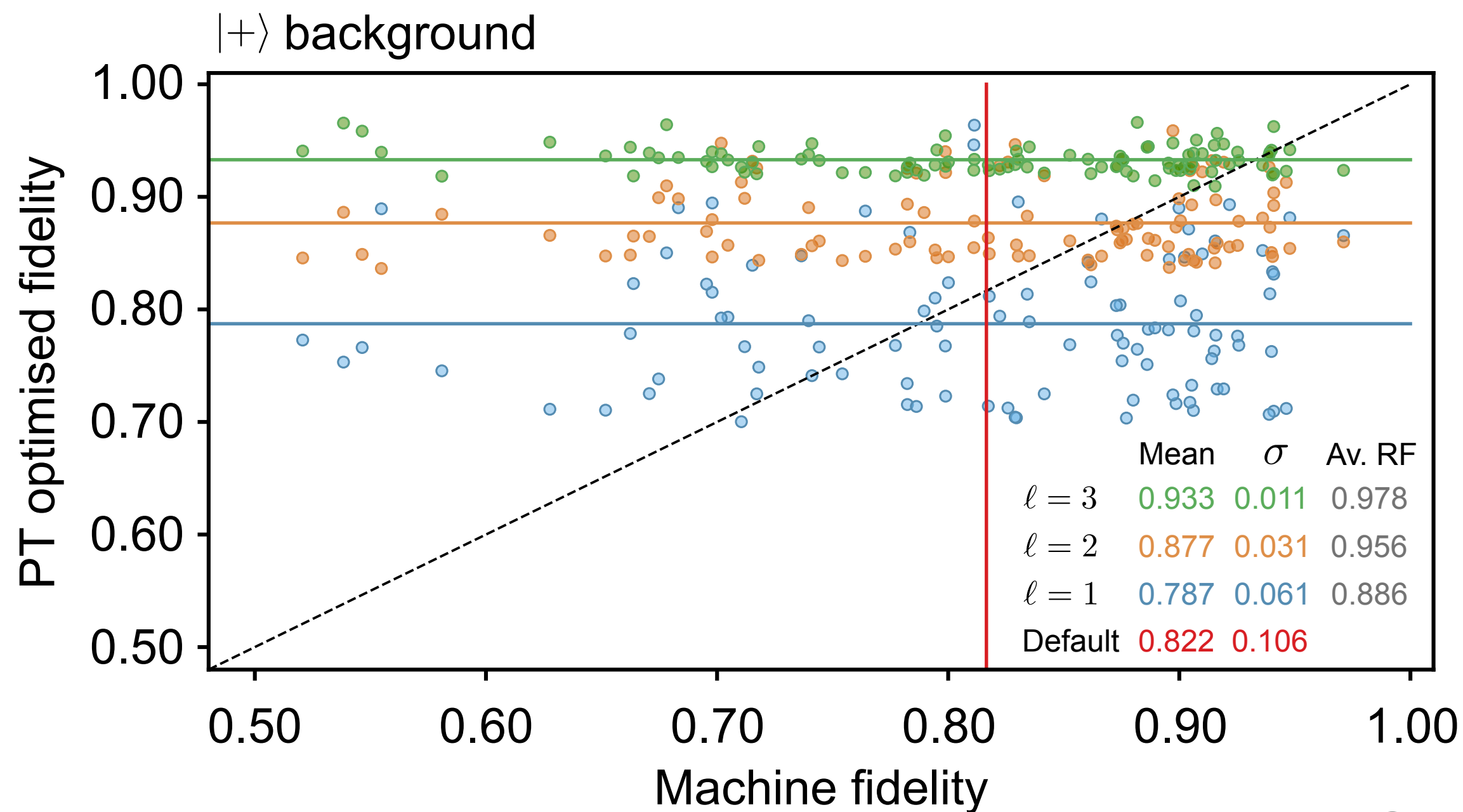
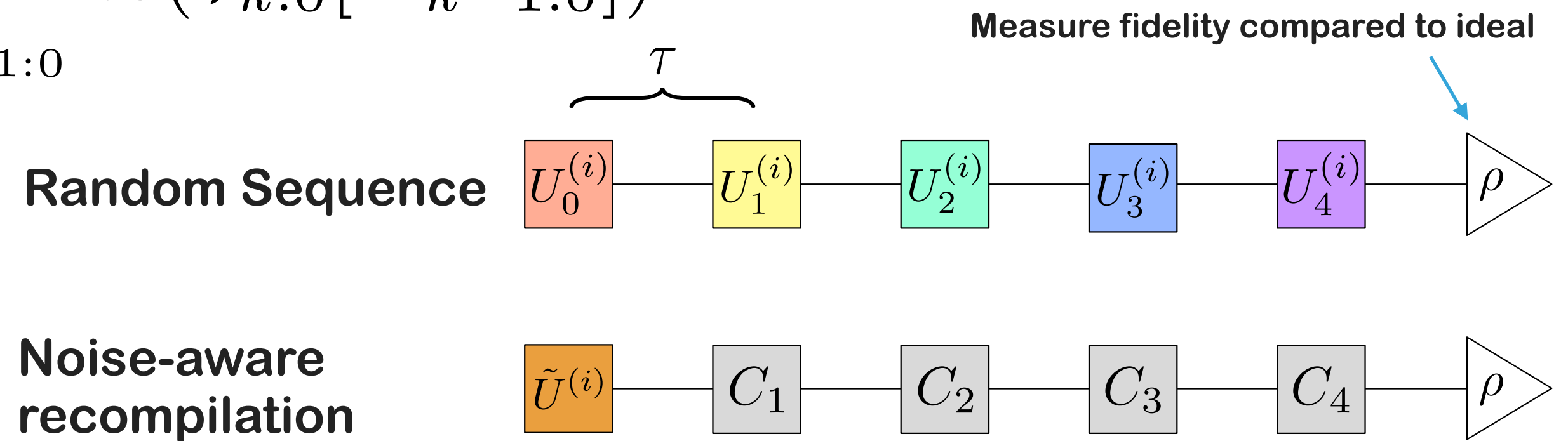
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- ▶ Characterised five-step process with 1.2 microsecond wait time – different Markov orders
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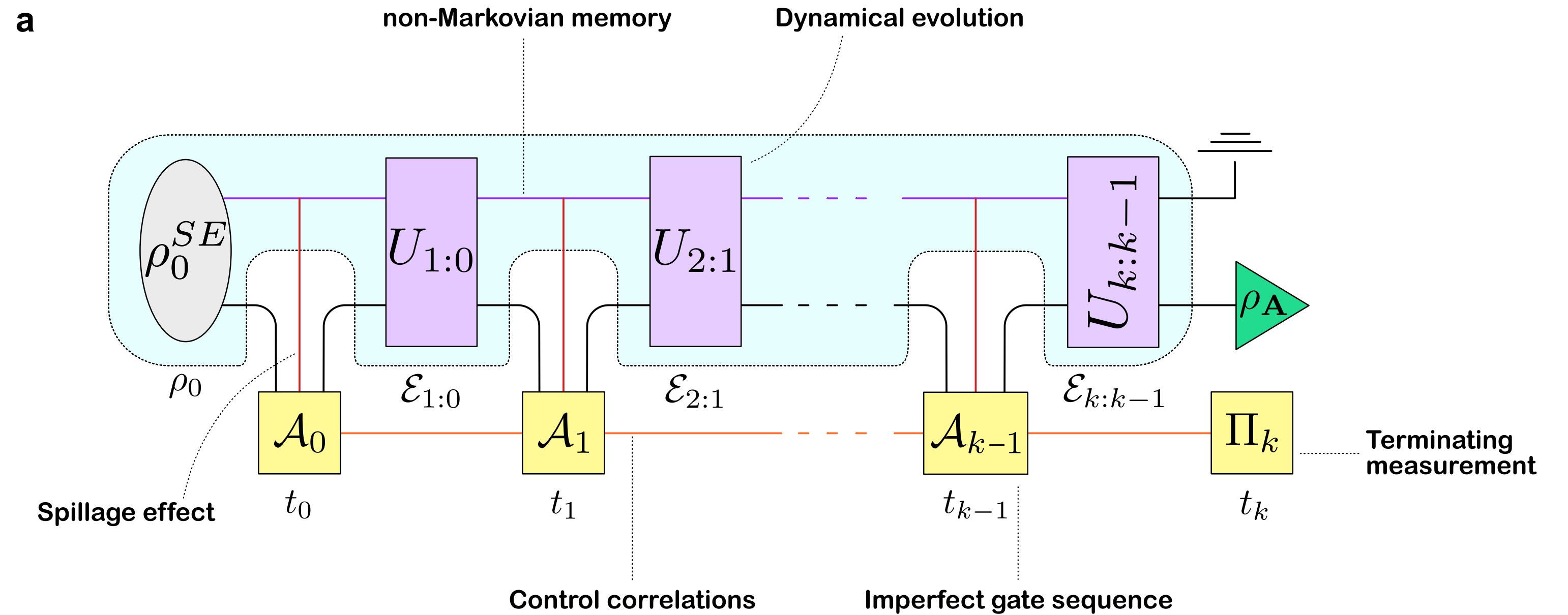
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- ▶ PTT generically expensive and relies on known controls
- ▶ Universally model control process, and interplay of control and process
- ▶ Use locally purified tensor networks to model both process and control
- ▶ Estimate¹ the process tensors and controls

¹Torlai et al. arXiv:2006.02424



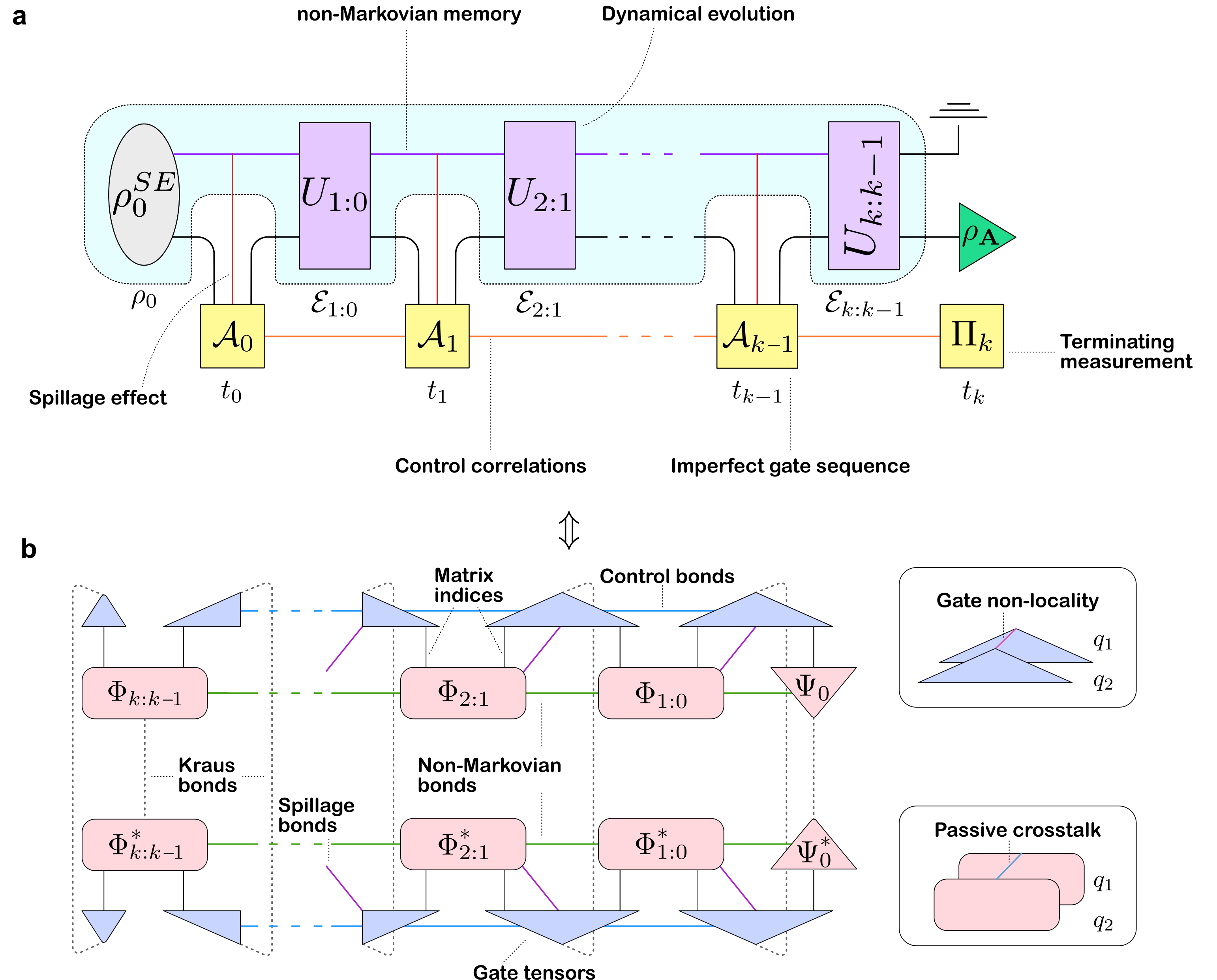
- ▶ PTT generically expensive and relies on known controls
- ▶ Universally model control process, and interplay of control and process
- ▶ Use locally purified tensor networks to model both process and control
- ▶ Estimate¹ the process tensors and controls

¹Torlai et al. arXiv:2006.02424

Simultaneously model, e.g.:

- imperfect gates
- frequency collisions
- gate degradation
- correlated coherent error
- SPAM
- correlated instruments — “testers”

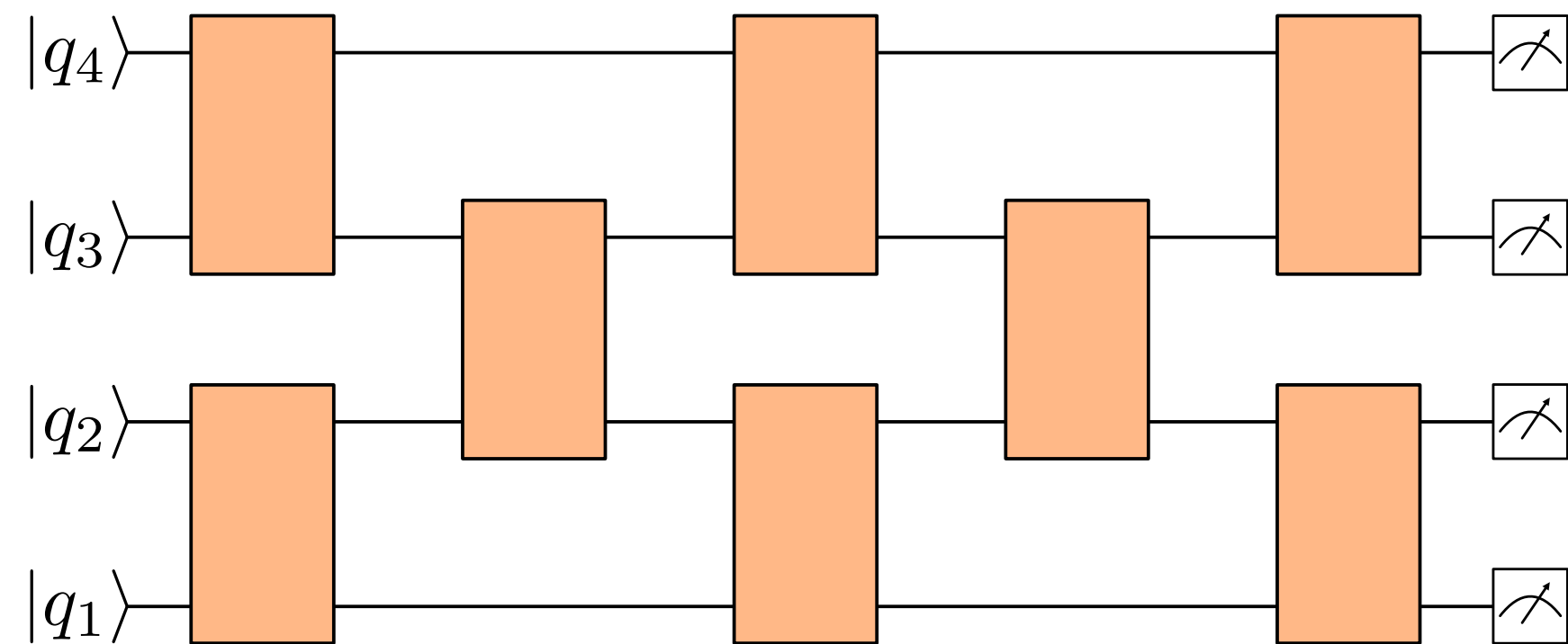
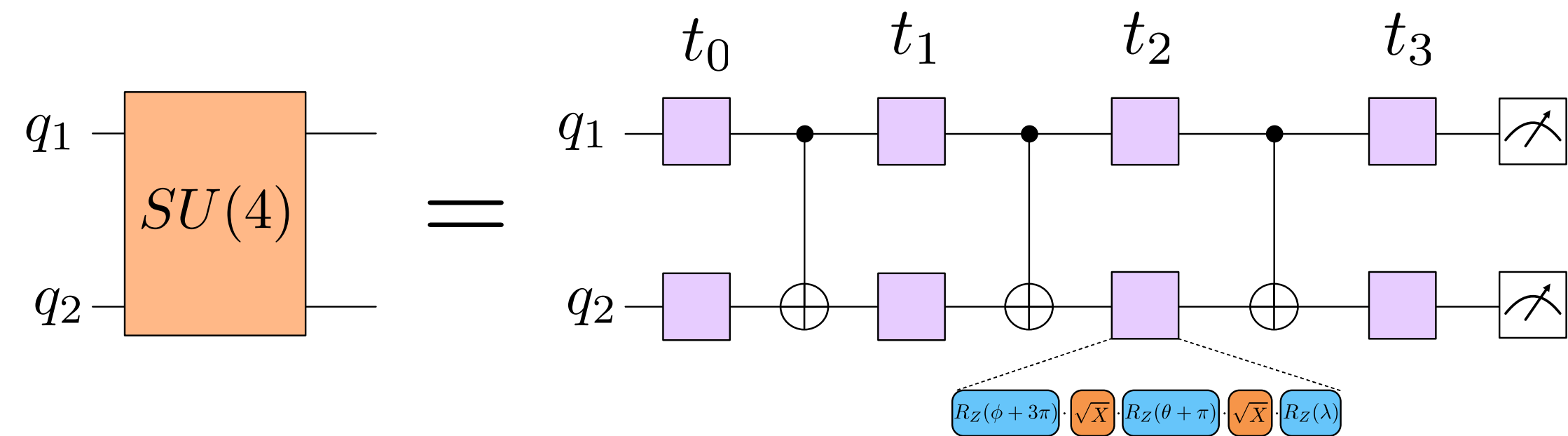
(Please suggest more!)



- ▶ Design around IBM hardware
- ▶ e.g. SU4 gate

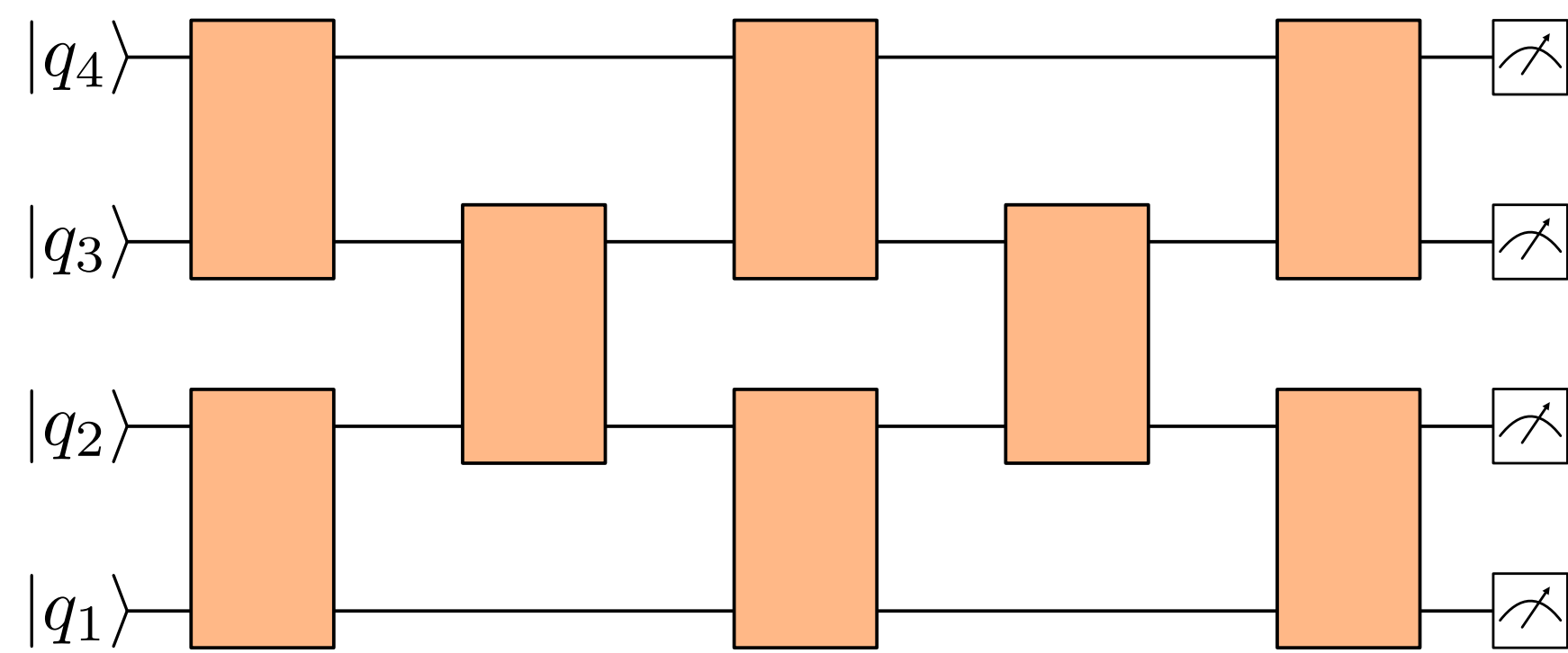
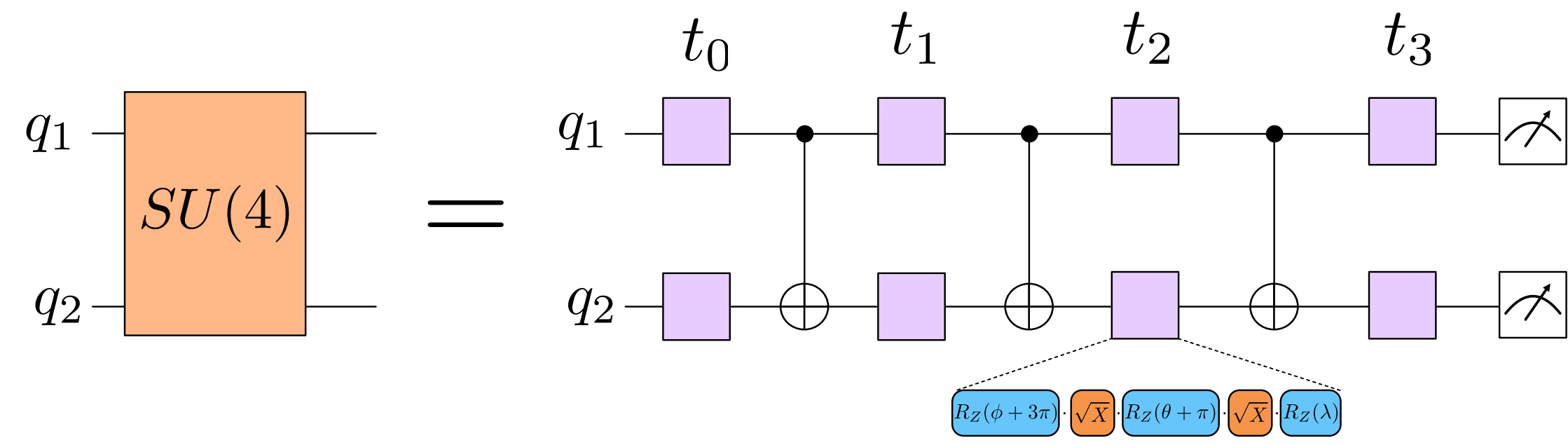
$$\Upsilon_{k:0} \quad \{ \mathbf{A}_{k-1:0} \} \quad \{ \Pi_x \}$$

$$U(\theta, \phi, \lambda) = R_Z(\phi + 3\pi) \cdot \sqrt{X} \cdot R_Z(\theta + \pi) \cdot \sqrt{X} \cdot R_Z(\lambda)$$

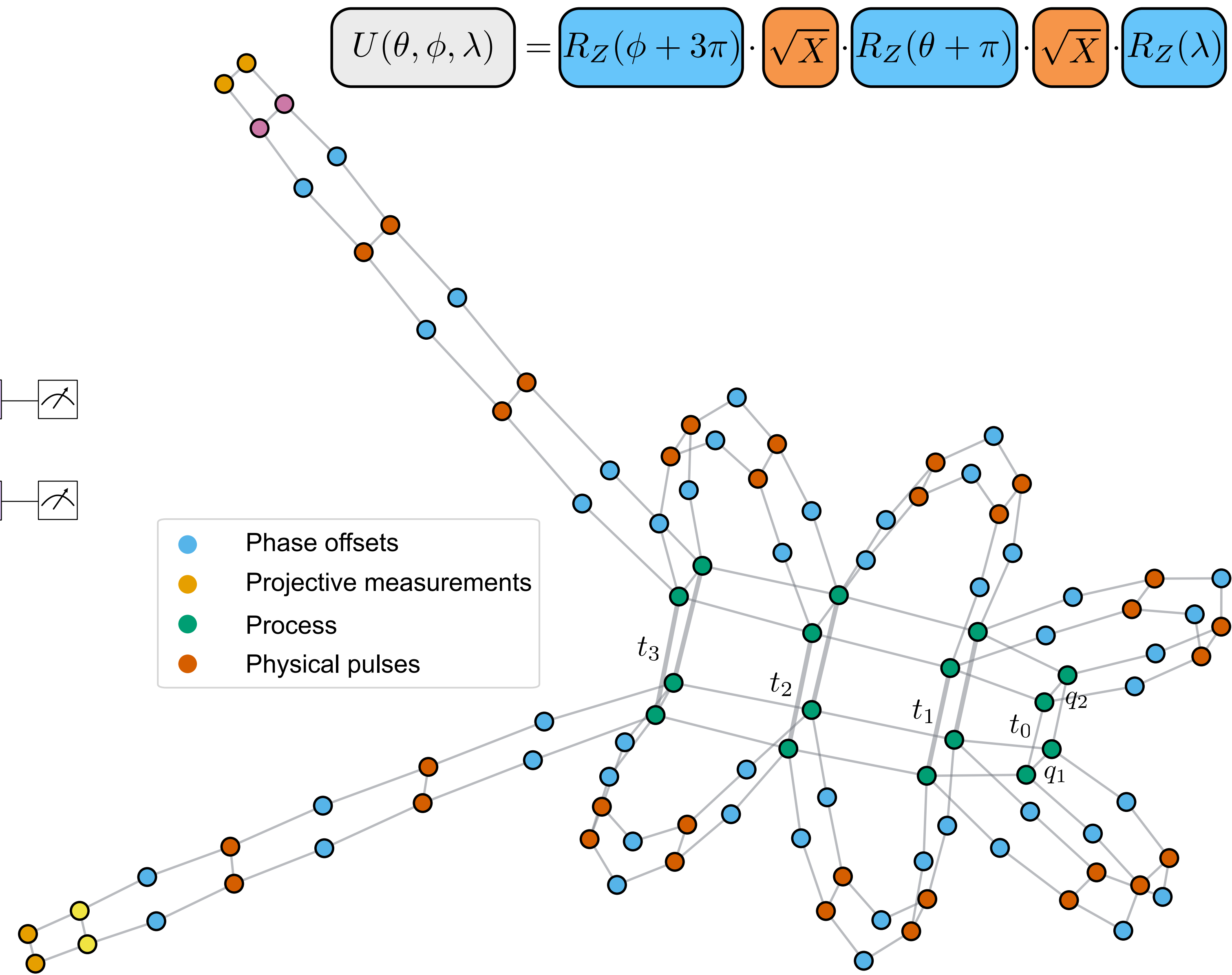


- ▶ Design around IBM hardware
- ▶ e.g. SU4 gate

$$\Upsilon_{k:0} \quad \{ \mathbf{A}_{k-1:0} \} \quad \{ \Pi_x \}$$



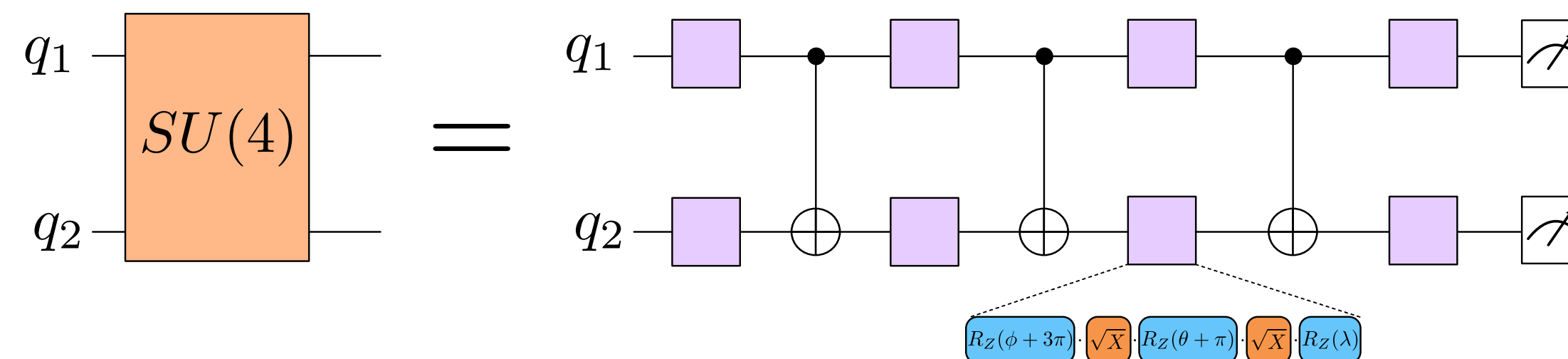
$$U(\theta, \phi, \lambda) = R_Z(\phi + 3\pi) \cdot \sqrt{X} \cdot R_Z(\theta + \pi) \cdot \sqrt{X} \cdot R_Z(\lambda)$$



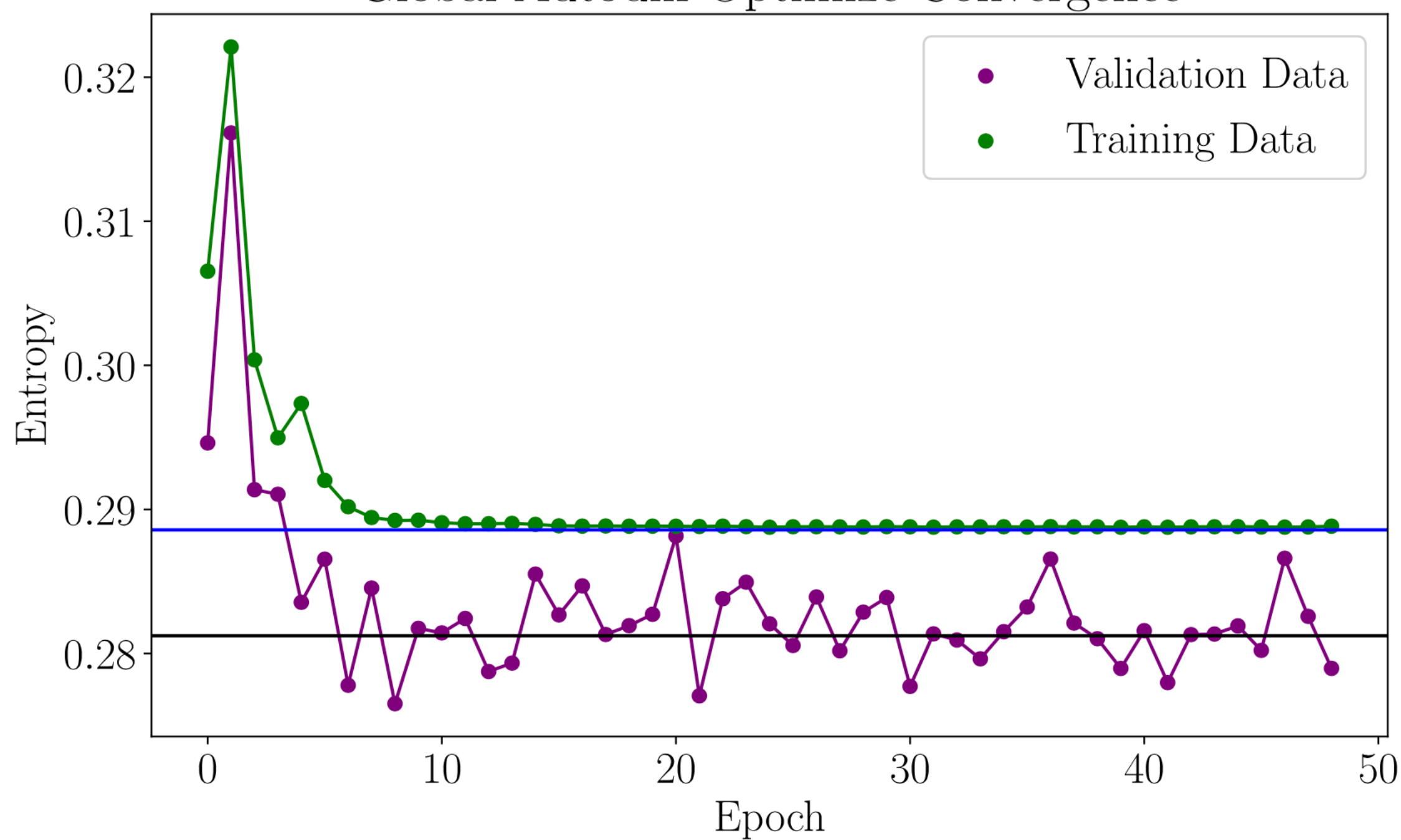
Example Results

One example from a bunch of sets of IBM experiments

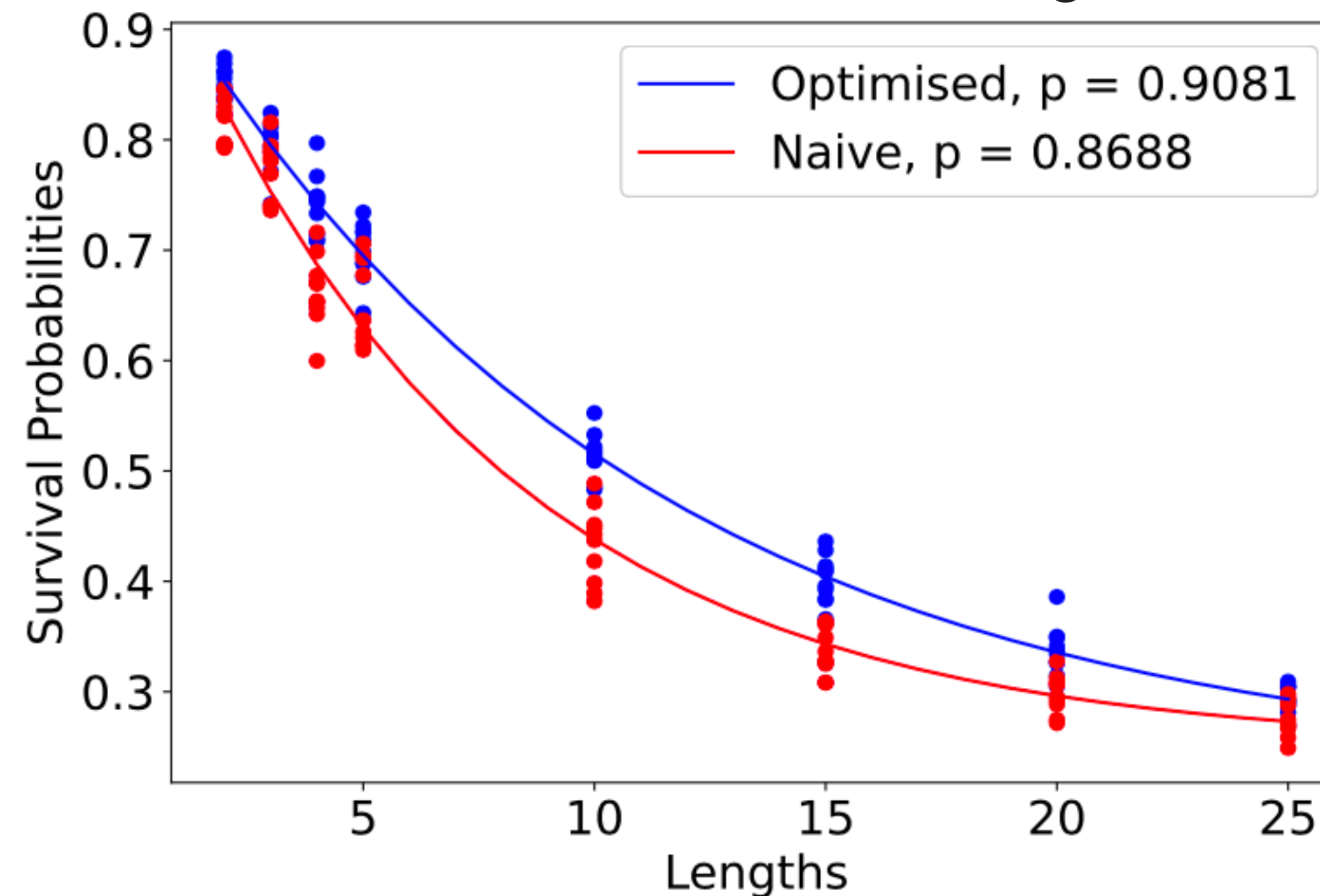
2 qubits, 3 steps, ibmq_guadalupe



Global Autodiff Optimize Convergence

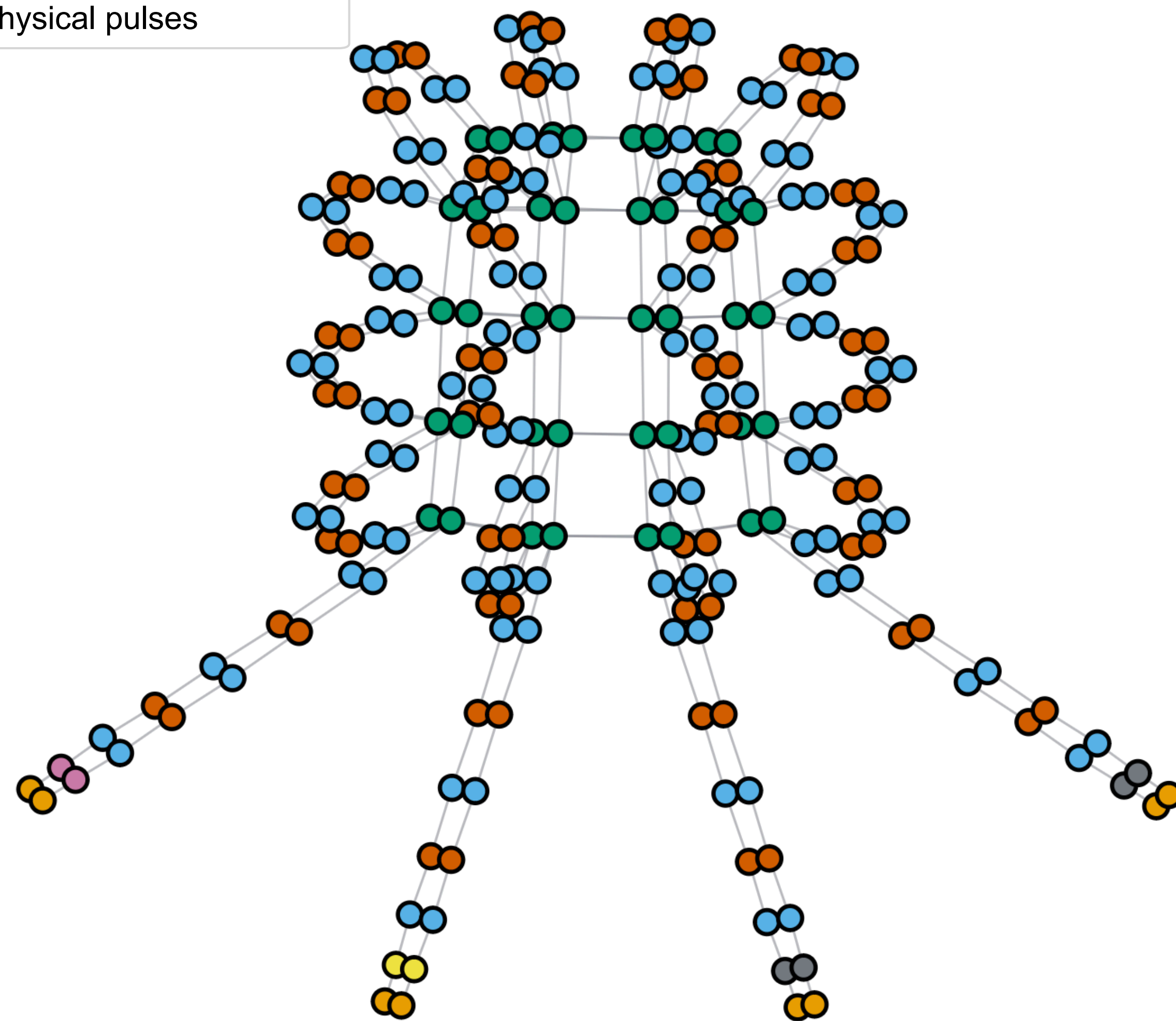
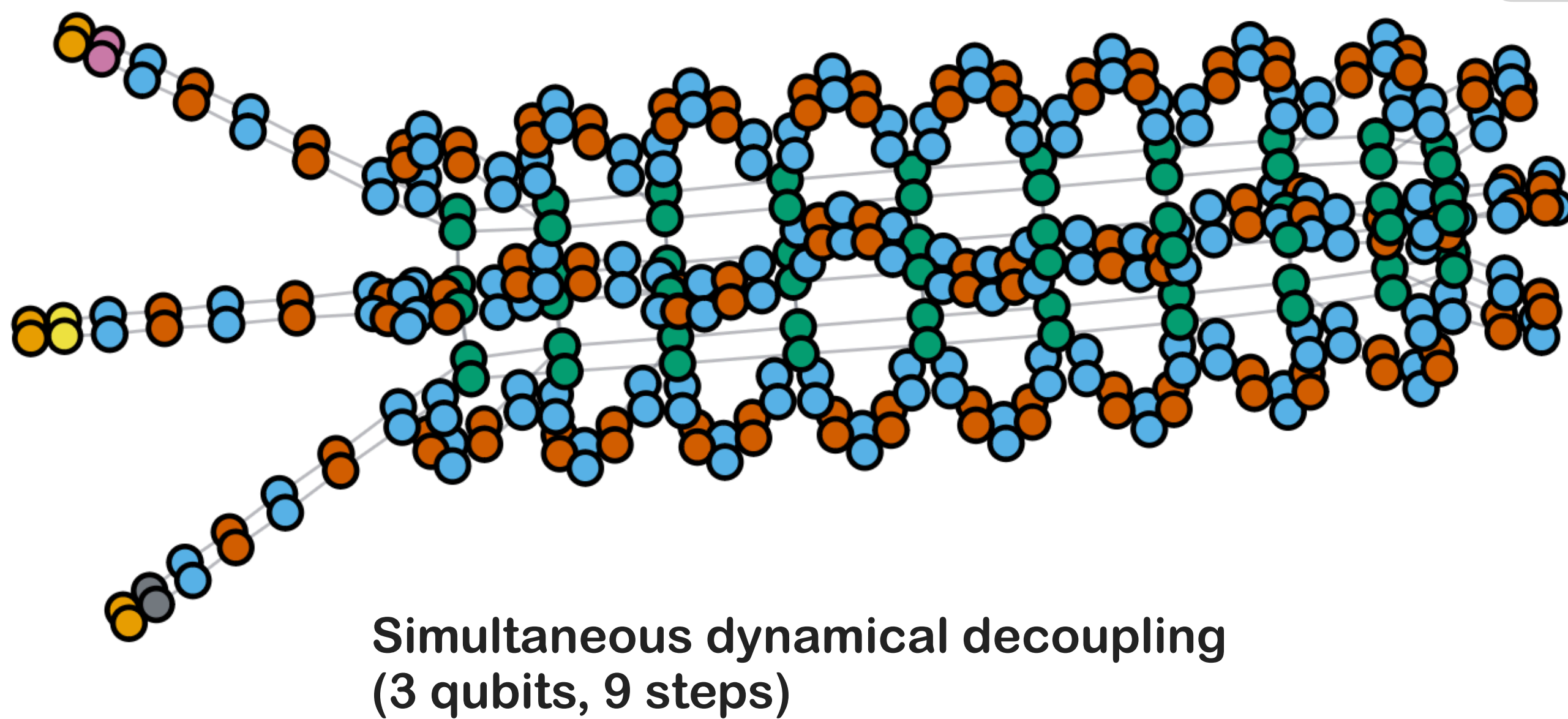
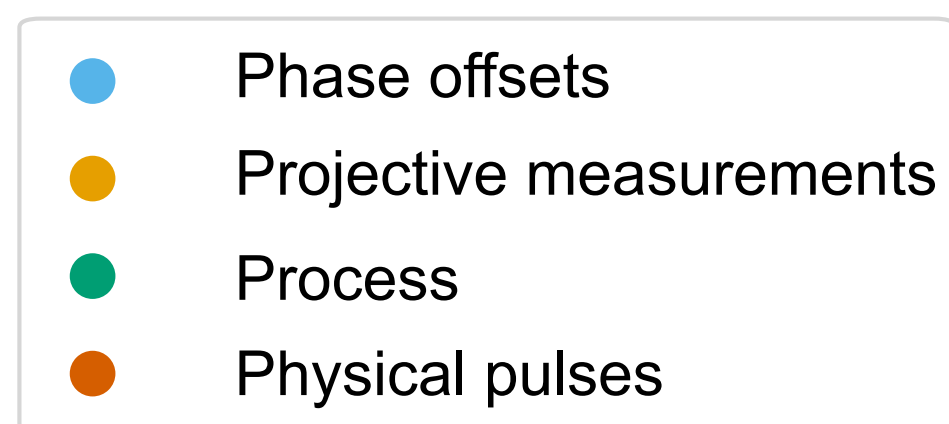


Randomised benchmarking



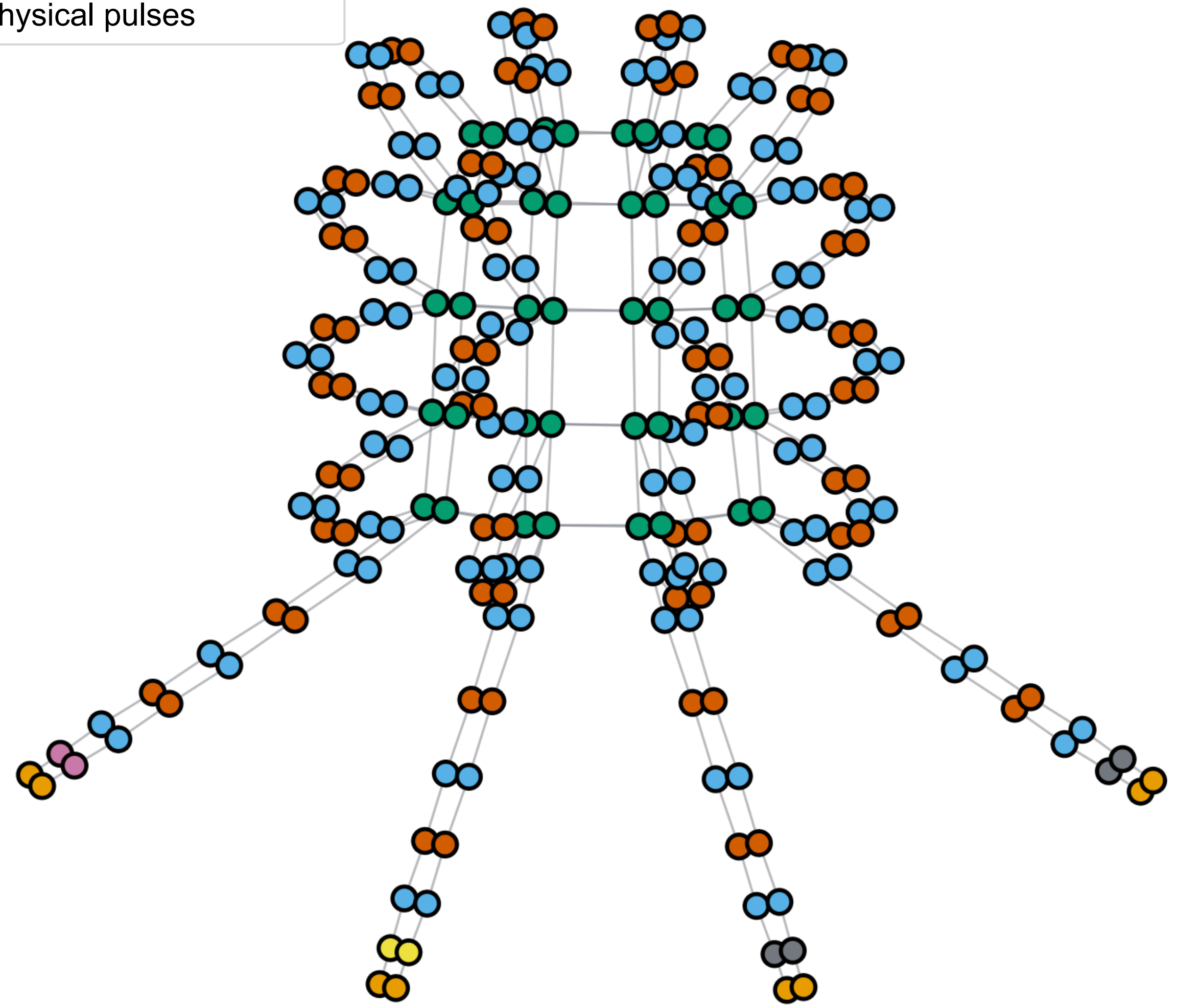
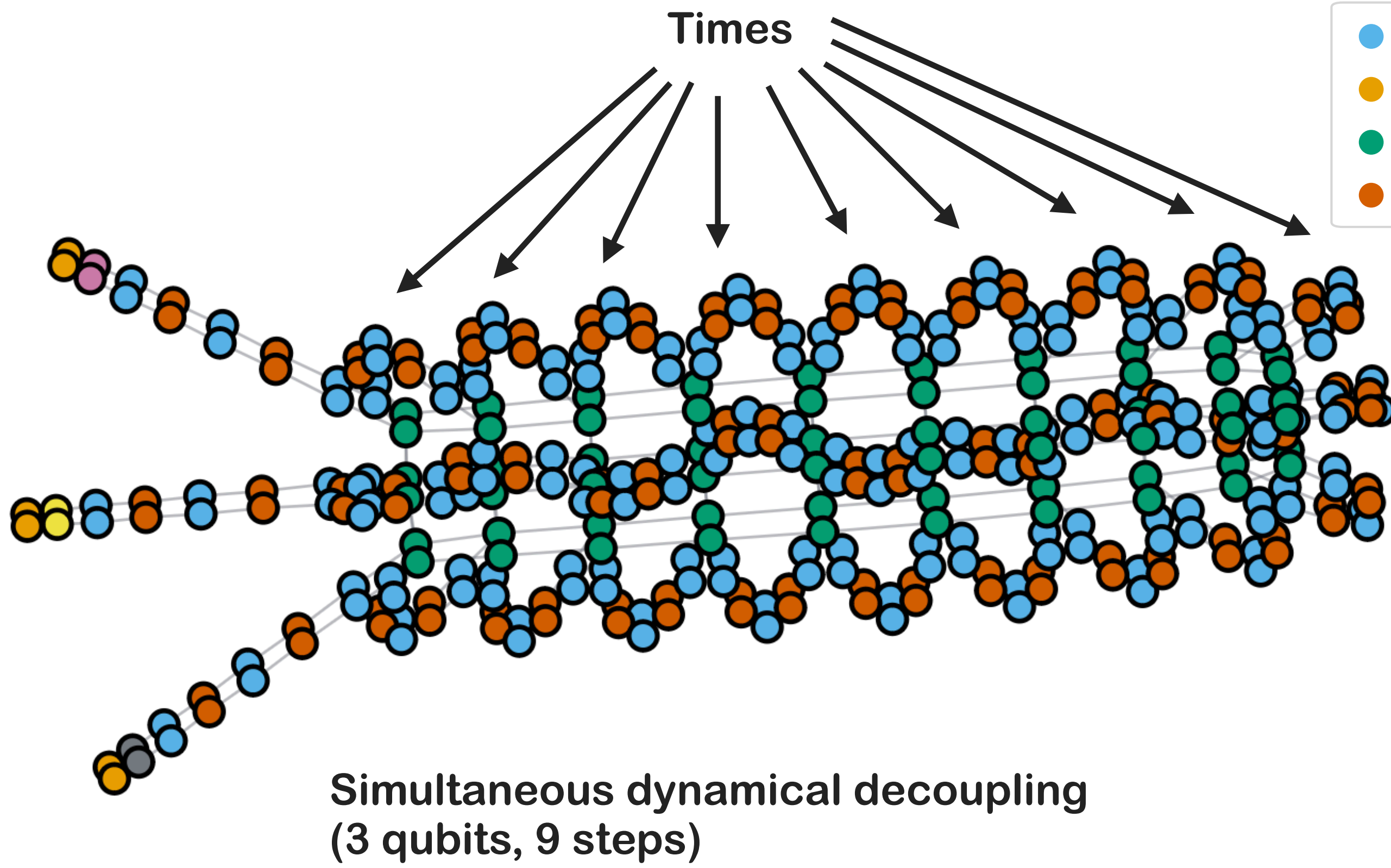
Absolute predictive difference: $\text{minmax}=(1.8775463e-06, 0.027240574)$, $\text{mean}=0.006607343$

Predictive fidelity: $\text{minmax}=(0.9977334332133879, 0.9999972379788054)$, $\text{mean}=0.999675008101766$



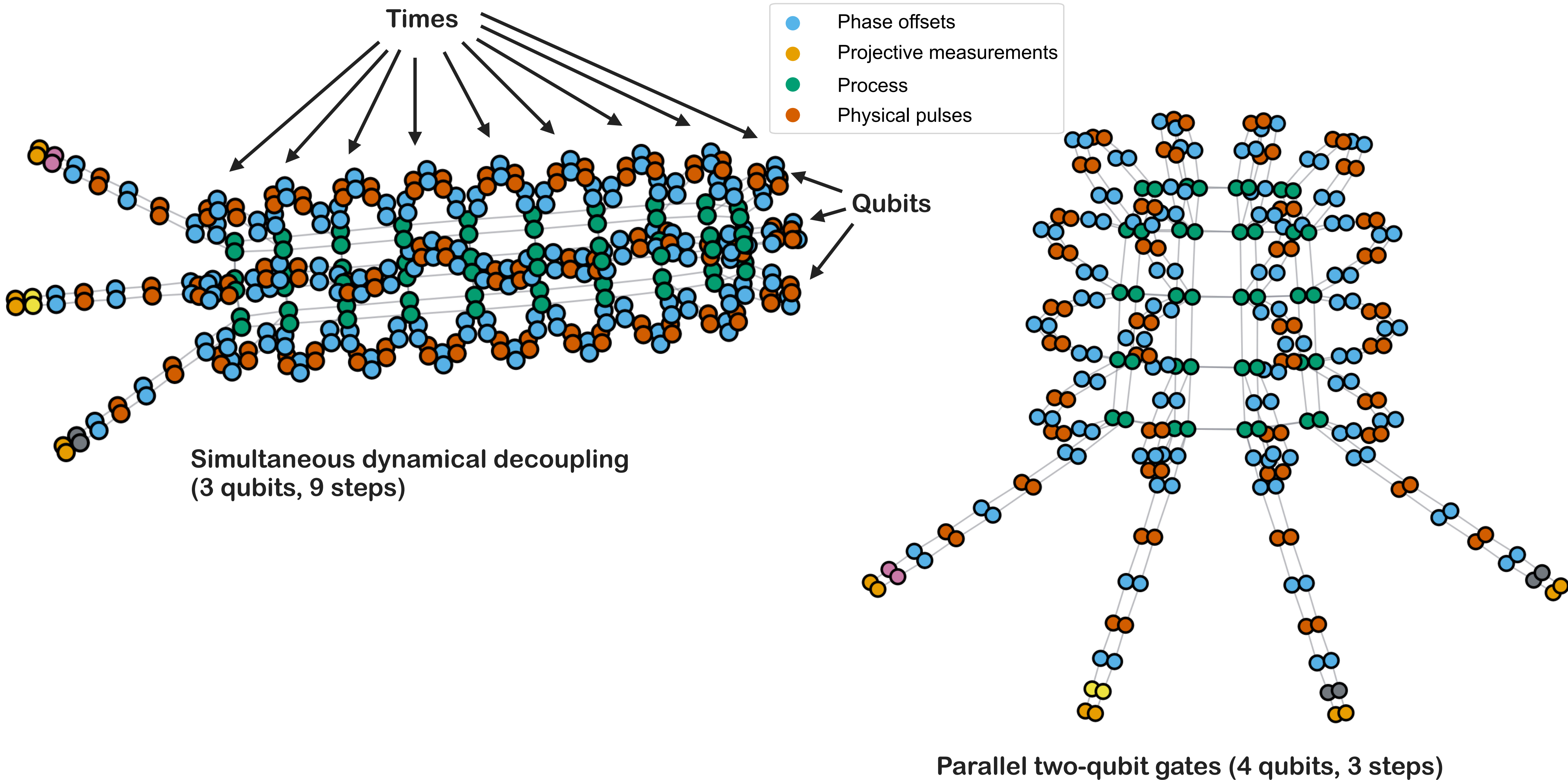
Parallel two-qubit gates (4 qubits, 3 steps)

Can Also Go Bigger and Better

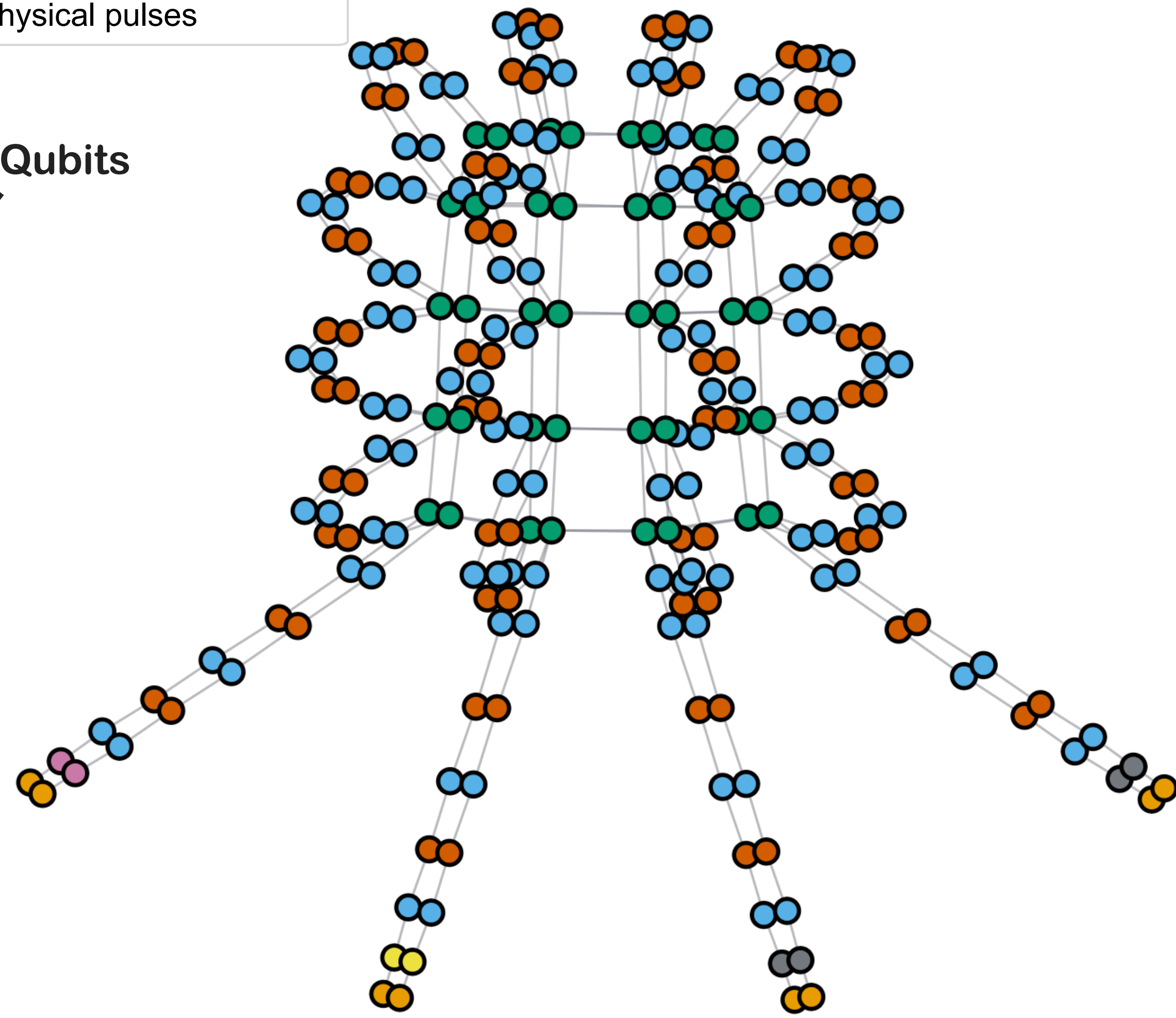
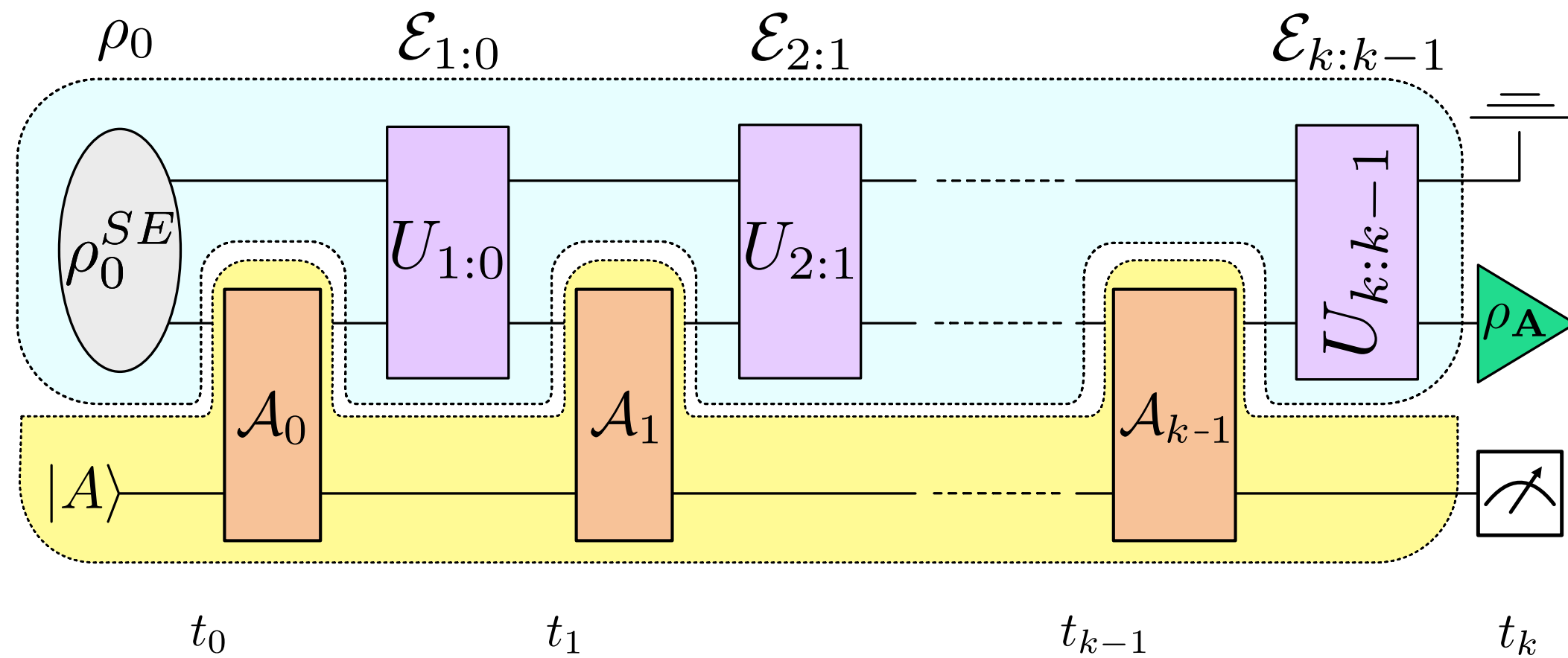
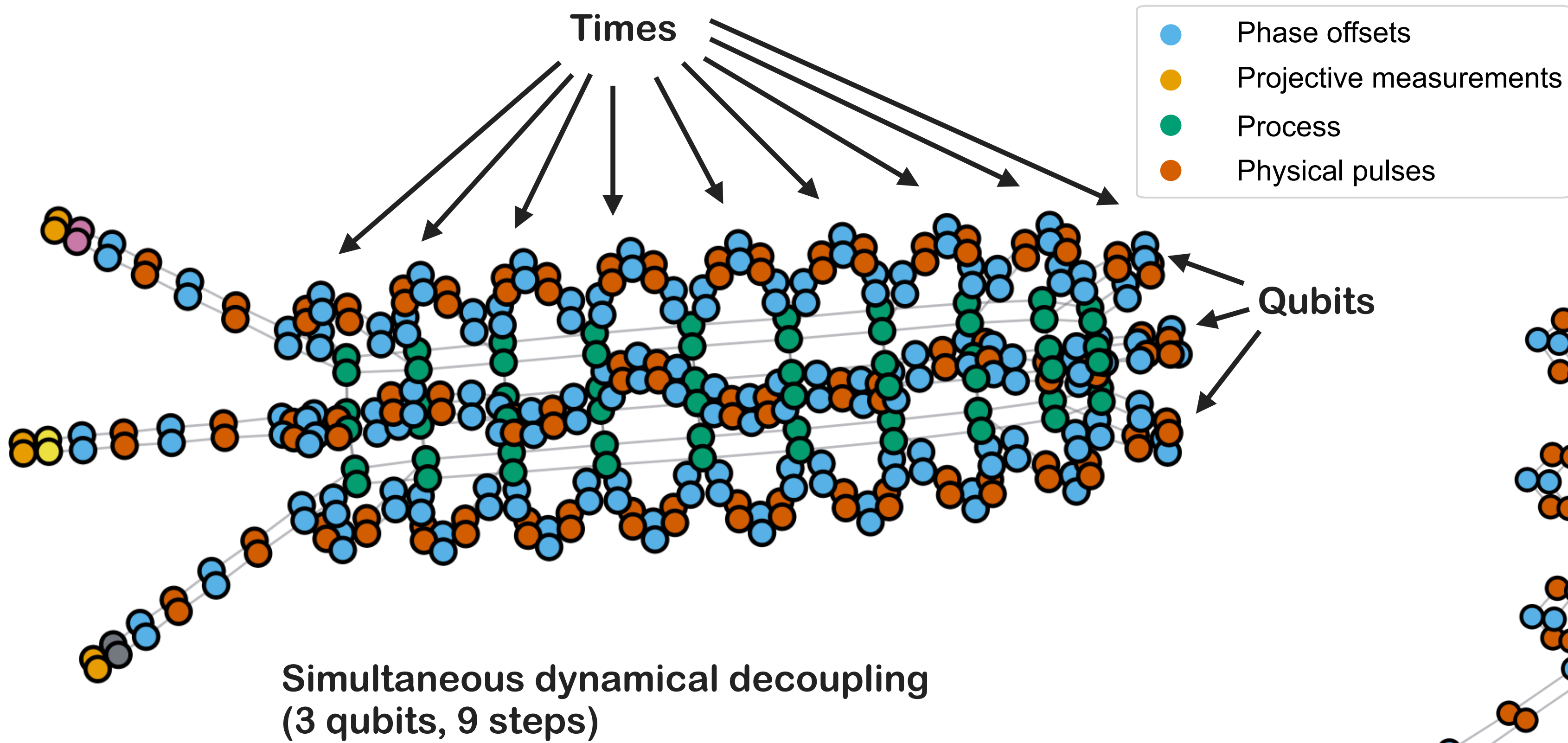


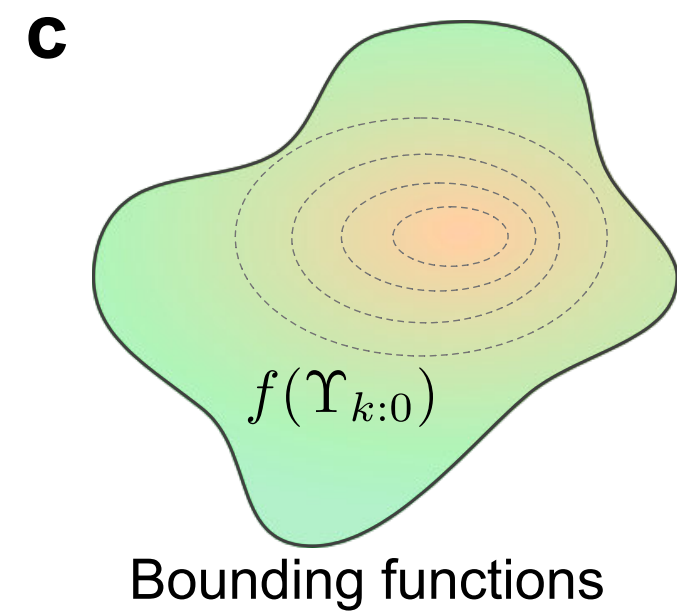
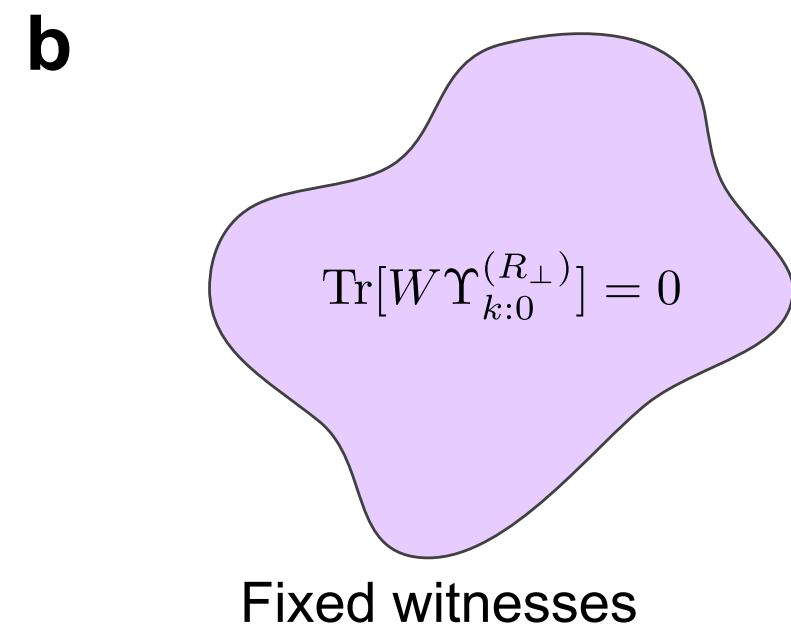
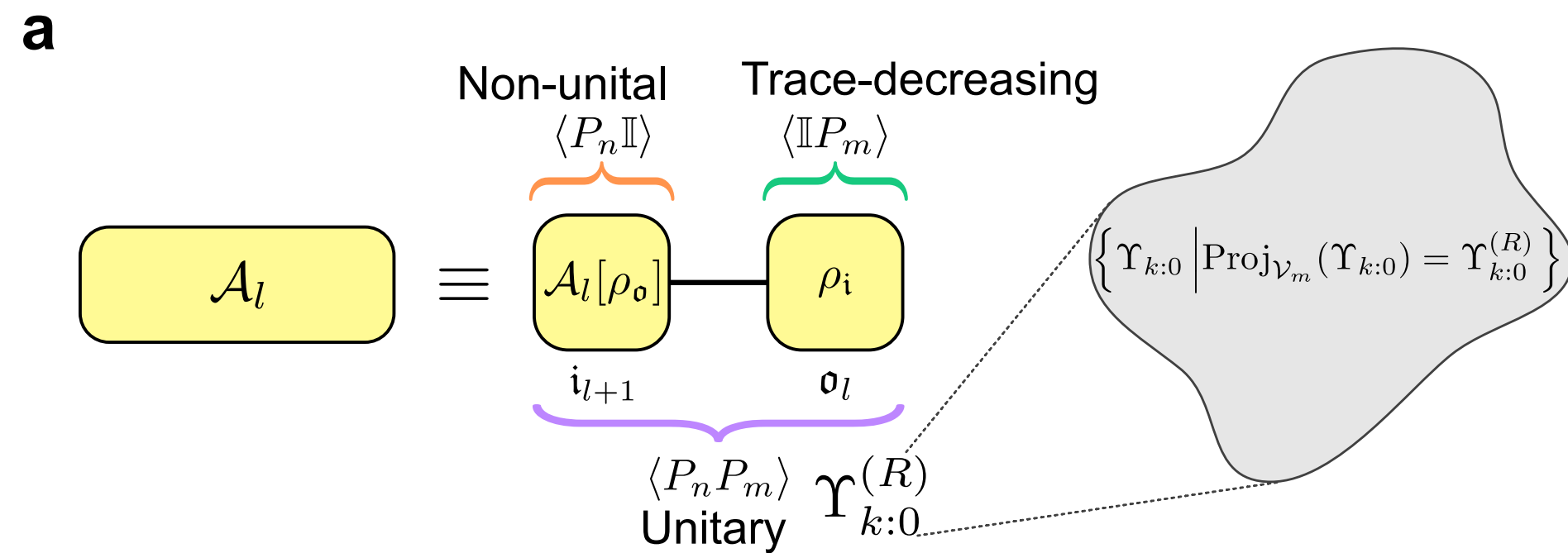
Parallel two-qubit gates (4 qubits, 3 steps)

Can Also Go Bigger and Better



Can Also Go Bigger and Better





$$\mathcal{O} = \sum_{i, \vec{\mu}} \alpha_{i, \vec{\mu}} P_i \otimes \bigotimes_{j=0}^k P_{\mu_j}, \quad \text{where}$$

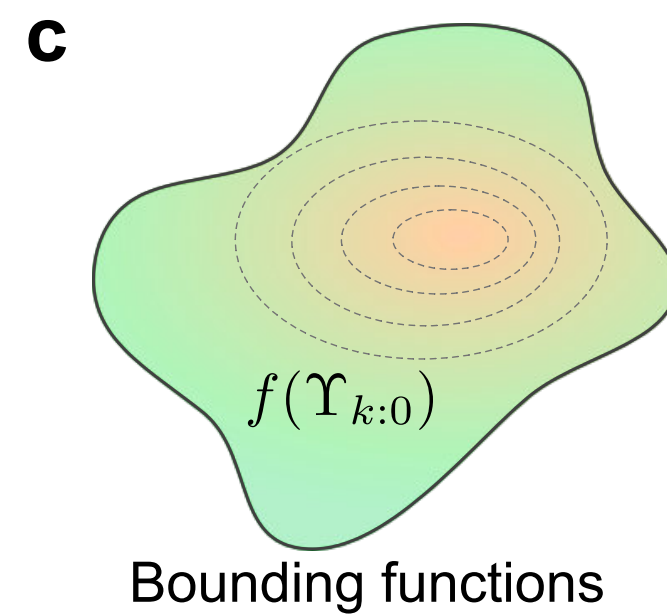
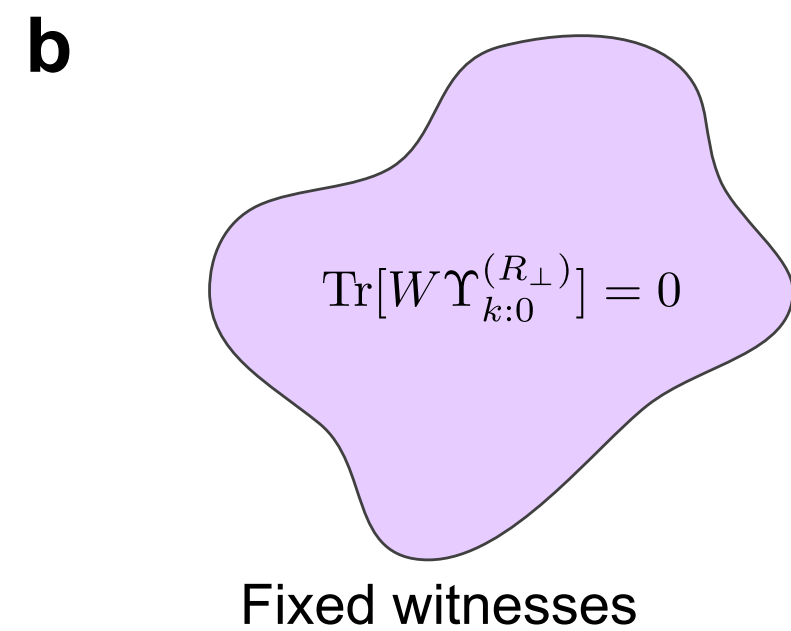
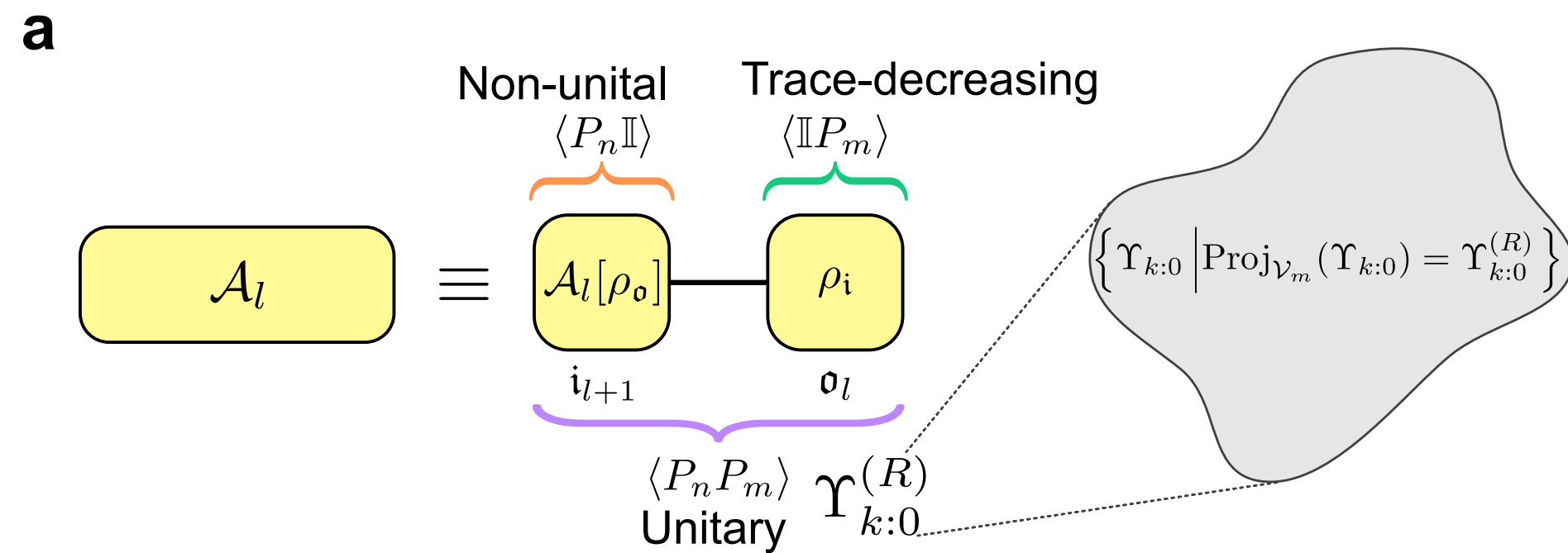
$$\alpha_{i, \vec{\mu}} \in \mathbb{R},$$

$$P_i \in \{\mathbb{I}, X, Y, Z\},$$

$$P_{\mu_j} \in \{\mathbb{I}\} \cup \{X, Y, Z\} \otimes \{X, Y, Z\}$$

$$\min_{W \in \mathcal{W}} \text{Tr}[W \Upsilon_{k:0}],$$

$$\mathcal{W} = \{W \mid \forall M : \exists P_M, Q_M \succcurlyeq 0 : W = P_M + Q_M^{\Gamma_M}, \text{Tr}[W] = 1, W \in \mathfrak{A}\}.$$



$$\mathcal{O} = \sum_{i, \vec{\mu}} \alpha_{i, \vec{\mu}} P_i \otimes \bigotimes_{j=0}^k P_{\mu_j}, \quad \text{where}$$

$$\alpha_{i, \vec{\mu}} \in \mathbb{R},$$

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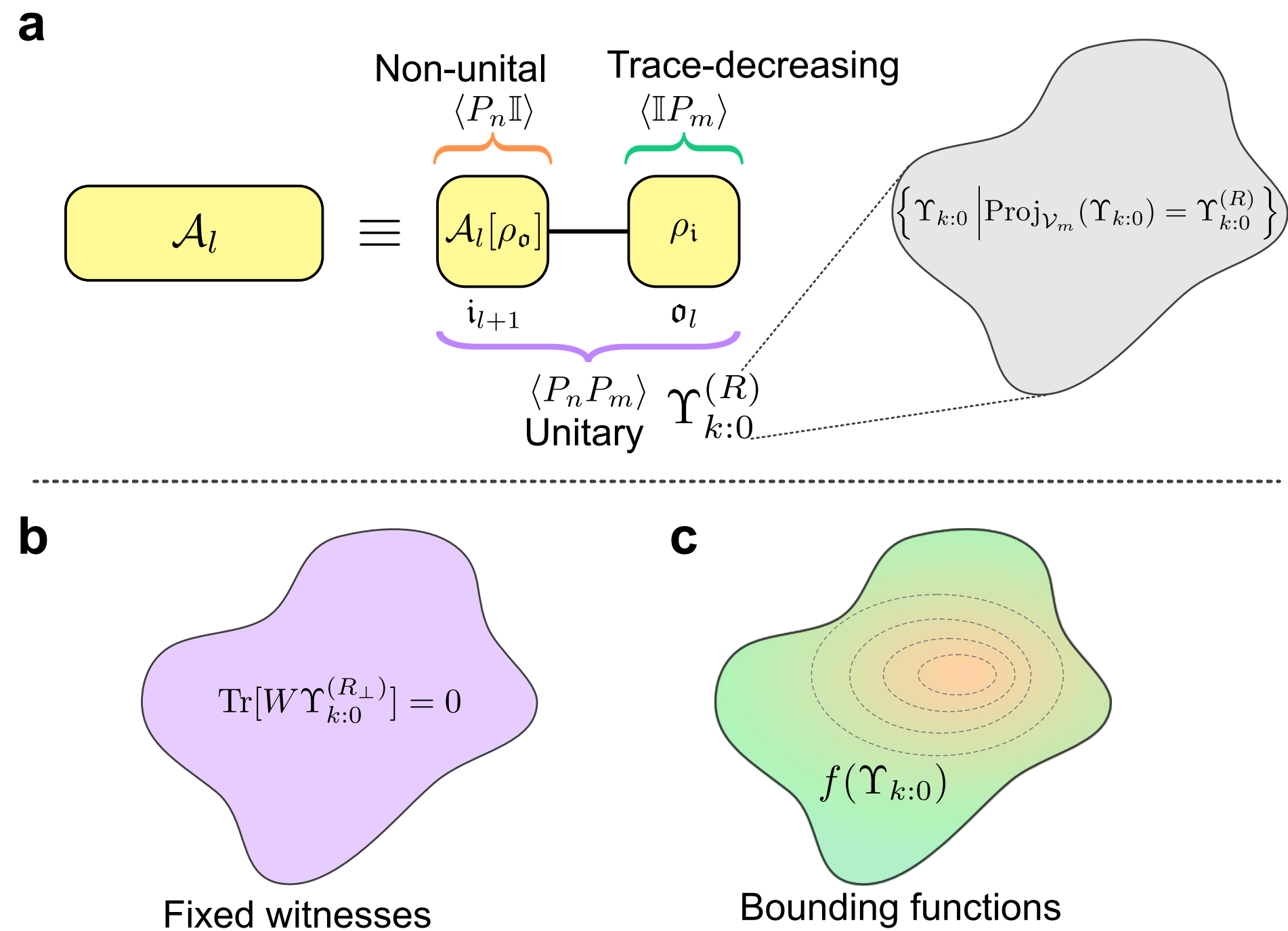
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$$\mathcal{W} = \{W \mid \forall M : \exists P_M, Q_M \succcurlyeq 0 : W = P_M + Q_M^{\Gamma_M}, \text{Tr}[W] = 1, W \in \mathfrak{A}\}.$$

$$\Upsilon = \Upsilon^{(R)} + \Upsilon^{(R_\perp)}$$

↑
Fixed

↑
Non-unique



$$\mathcal{O} = \sum_{i, \vec{\mu}} \alpha_{i, \vec{\mu}} P_i \otimes \bigotimes_{j=0}^k P_{\mu_j}, \quad \text{where}$$

$$\alpha_{i, \vec{\mu}} \in \mathbb{R},$$

$$P_i \in \{\mathbb{I}, X, Y, Z\},$$

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$$\min_{W \in \mathcal{W}} \text{Tr}[W \Upsilon_{k:0}],$$

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$$\Upsilon = \underbrace{\Upsilon^{(R)}}_{\text{Fixed}} + \underbrace{\Upsilon^{(R_\perp)}}_{\text{Non-unique}}$$

► Also look at 3-step/7-body processes with different backgrounds

Setup	QMI (min, max)	Negativity	Purity	Fidelity
#1. System Alone	(0.298, 0.304)	(0.0179, 0.0181)	(0.8900, 0.8904)	(0.9423, 0.9427)
#2. $ +\rangle$ Nearest Neighbours (NN)	(0.363, 0.369)	(0.0255, 0.0259)	(0.7476, 0.7485)	(0.7239, 0.7244)
#3. Periodic CNOTs on NNs in $ +\rangle$	(0.348, 0.358)	(0.0240, 0.0246)	(0.7796, 0.7811)	(0.7264, 0.7272)
#4. $ 0\rangle$ NNs with QDD	(0.358, 0.373)	(0.0205, 0.0210)	(0.8592, 0.8612)	(0.8034, 0.8045)
#5. $ +\rangle$ Long-range Neighbours	(0.329, 0.339)	(0.0209, 0.0214)	(0.8594, 0.8608)	(0.9252, 0.9260)
#6. $ +\rangle$ NN, delay, $ +\rangle$ next-to-NN	(0.322, 0.329)	(0.0209, 0.0213)	(0.8534, 0.8549)	(0.9077, 0.9083)