



# 4D tracking with thin Resistive Silicon Detectors (RSD2): recent performance studies and future potentials

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# State of the art of 4D-tracking with RSD (FBK)



## What is an RSD? Resistive read-out AC-LGAD Silicon Detector

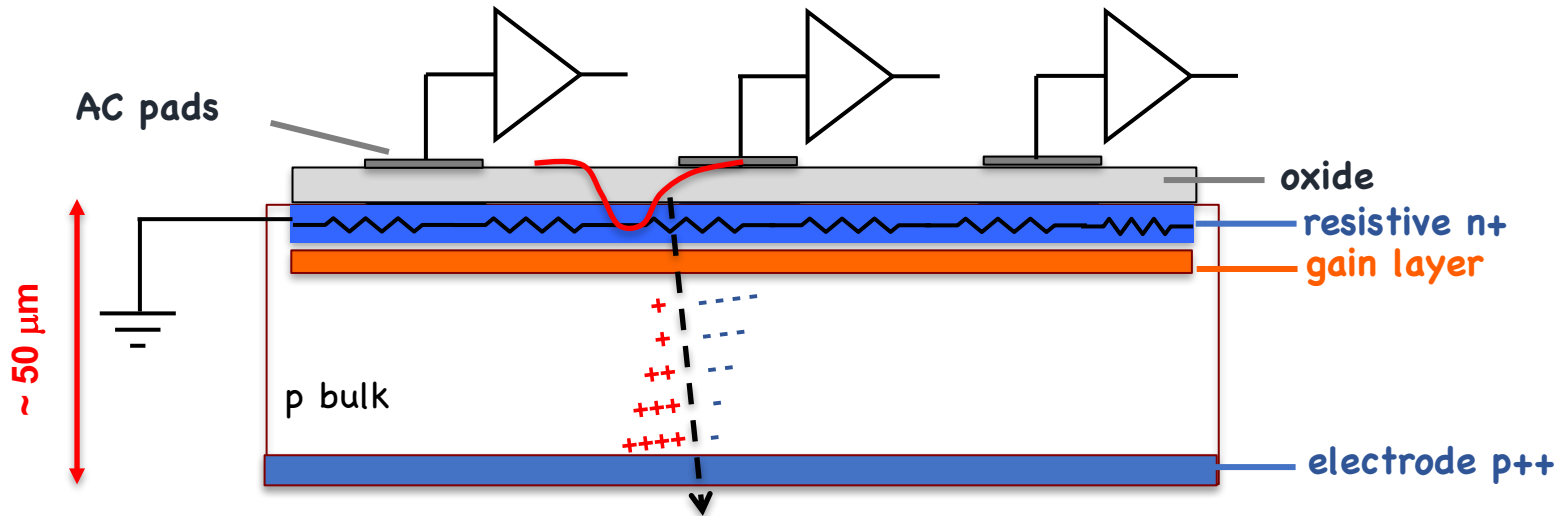
- ⇒ Thin LGAD with a resistive read-out AC-coupled, where the **design of the read-out pads** (shape and segmentation) **defines the segmentation** and can easily adapt to many geometries
- ⇒ **100% Fill Factor** (continuous gain), reduced material budget and **enhanced timing performance** by design
- ⇒ **spatial resolutions better than**  $\sigma_x = k \frac{\text{pitch}}{\sqrt{12}}$ ,  $k \sim 0.5 - 1$



# Reminder: resistive AC-LGAD devices

Intrinsic signal sharing is realized thanks to a resistive read-out, AC-coupled

- Charge is induced on the n+ layer ==> very fast process (1 ns)

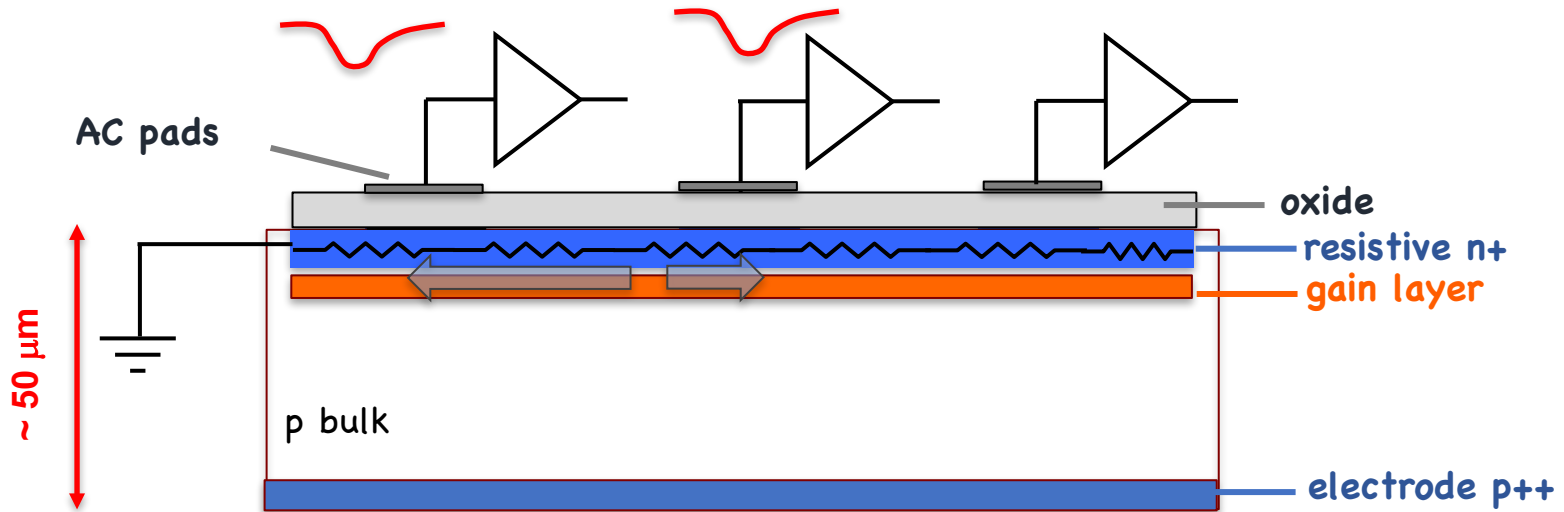




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- This generates signals on the near-by AC pads (fast component – capacitive coupling)



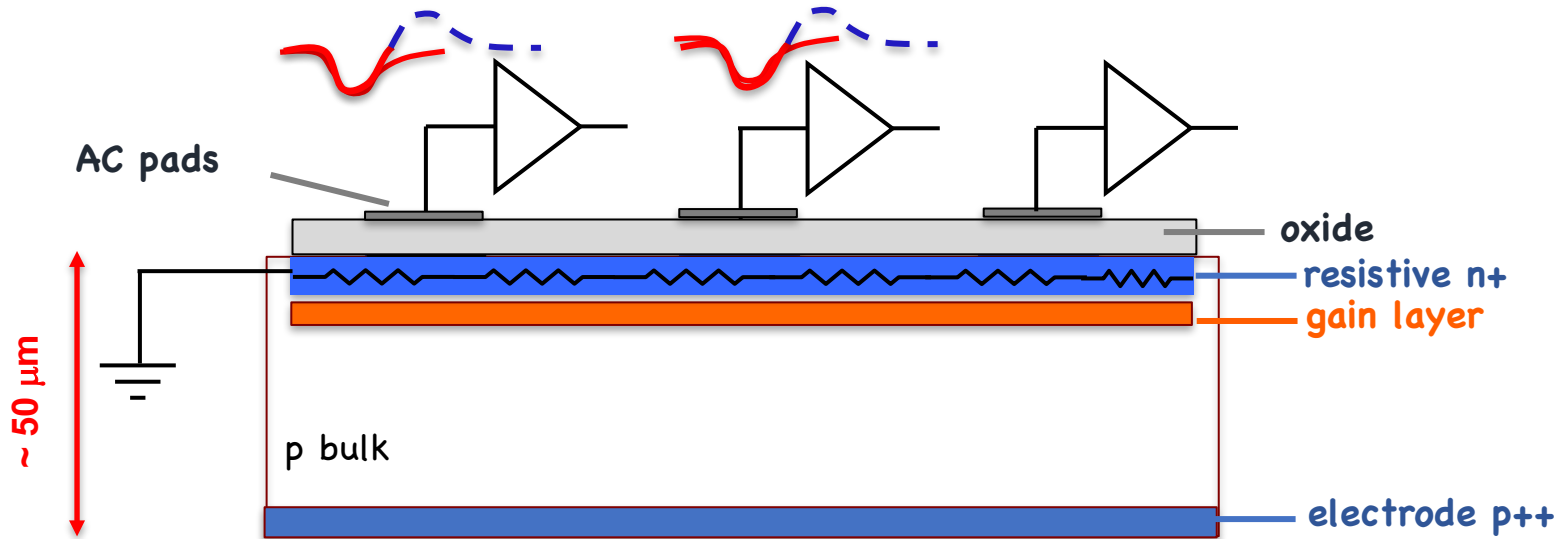




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- The charge flows to ground (slow component)

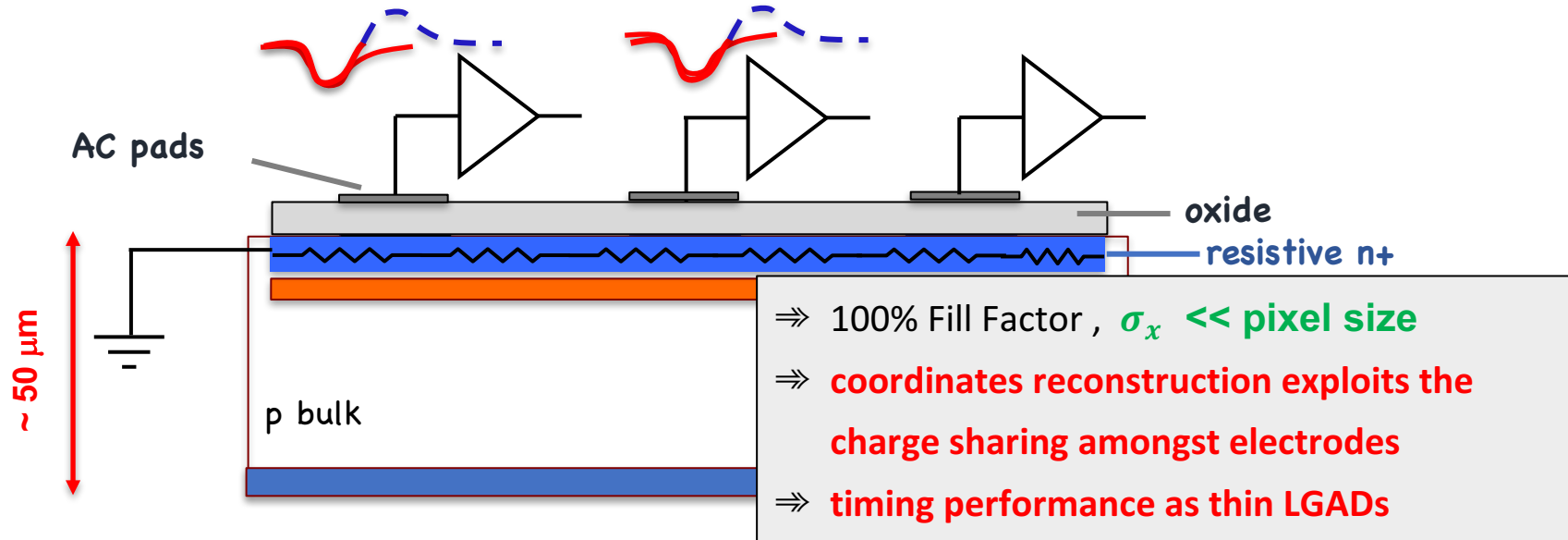




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# RSD productions at FBK



- **RSD1 production (2019) demonstrated the soundness of the idea. Several lessons learned:**
  - *reconstruction is biased when the sharing involves too many pads*
  - *variable number of pads compromises the uniformity of the response*
  - *metal of read-out pads should be minimized*
  - *leakage current collected by the DC contact at the periphery of the device may create baseline fluctuation in large devices*

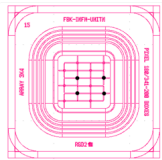


# RSD productions at FBK

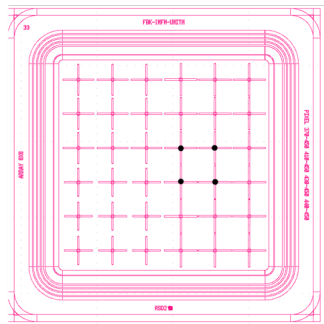


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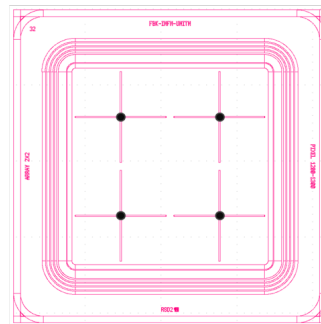
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- RSD2 production (2021) optimized the design (parameters that drive the sharing) and improved performance: **various non-conventional electrodes shapes implemented**



200 x 340  $\mu\text{m}^2$



Pitch = 450  $\mu\text{m}$



Pitch = 1300  $\mu\text{m}$

Our best so far (and most recent) results **have been obtained with the crosses.**

# RSD2 with crosses: Lab and testbeam studies



Signal formation and performance studied in the lab using a TCT-setup with **picosecond laser** (spot  $\sim 8 \mu\text{m}$ ; Intensity 1-3 MIPs), mounted on a movable x-y stage ( $\sigma_{x-\text{laser}} \sim 2 \mu\text{m}$ ).

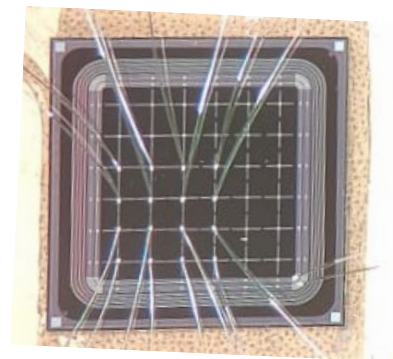
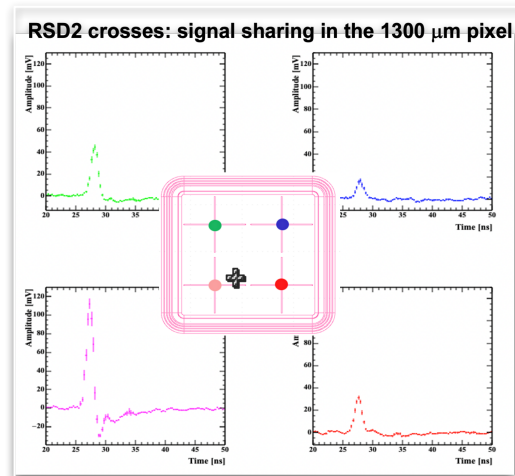
16 electrodes read out (FNAL read-out board + digitizer)

Typically signals from 4 adjacent electrodes are used in the reconstruction.

**Position and time coordinates are reconstructed with the methods briefly described in the following.**

More details in this paper <http://arxiv.org/abs/2211.13809>

**A few devices have been tested at DESY (3-6 GeV electrons), on testbeam lines equipped with a EUDET pixel telescope (2-15 micron of spatial resolution) -> analysis ongoing. Today some preliminary results**



# Parametrization of the resolutions

## SPACE

$$\sigma_{hit\ pos}^2 = \sigma_{jitter}^2 + \sigma_{rec}^2 + \sigma_{setup}^2 + \sigma_{sensor}^2$$

- ***jitter term***: related to the variation of signal amplitude induced by the electronic noise (this biases the space-amplitude correlation)  
**Noise/(dV/dx)**
- $\sigma_{rec}$  : accuracy of the reconstruction method used, which might have a position-dependent systematic offset
- $\sigma_{setup}$  : related to changes in the relative signal sharing due to the experimental set-up.
- $\sigma_{sensor}$  : all sensor imperfections contributing to an uneven signal sharing among pads

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- $\sigma_{sensor}$  : all sensor imperfections contributing to an uneven signal sharing among pads

## TIME

$$\sigma_{hit\ time}^2 = \sigma_{jitter}^2 + \sigma_{Landau}^2 + \sigma_{delay}^2$$

### ***Uncertainty on hit time seen by a single pad***

- ***jitter term***: due to the electronics  
**~Noise/(dV/dt)**
- ***Landau term***: due to non-uniform ionization, about ~30 ps for a 50  $\mu\text{m}$  thick sensor
- $\sigma_{delay}$  : the delay, due to the propagation time to the read-out pad, has an uncertainty induced by the hit position reconstruction.



# Reconstruction method for the position (1)

## SPACE RESOLUTION

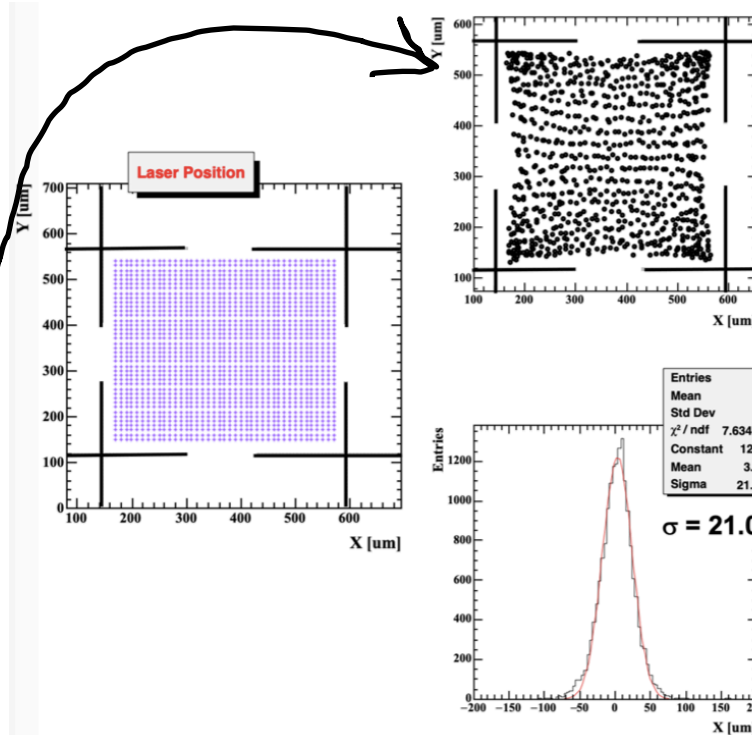
x-y coordinates reconstructed using only **4 neighboring electrodes with the larger signals.**

Method: "charge asymmetry"

$$x_i = x_{center} + k_x \frac{pitch}{2} * \frac{Q_3 + Q_4 - (Q_1 + Q_2)}{Q_{tot}}$$

$$y_i = y_{center} + k_y \frac{pitch}{2} * \frac{Q_1 + Q_3 - (Q_2 + Q_4)}{Q_{tot}}$$

$$\sigma_x \sim \frac{pitch}{\sqrt{12}} \sim 130 \text{ micron}$$



reconstructed positions for the  $450 \times 450 \mu\text{m}^2$





# Reconstruction method for the position (2)

## SPACE RESOLUTION

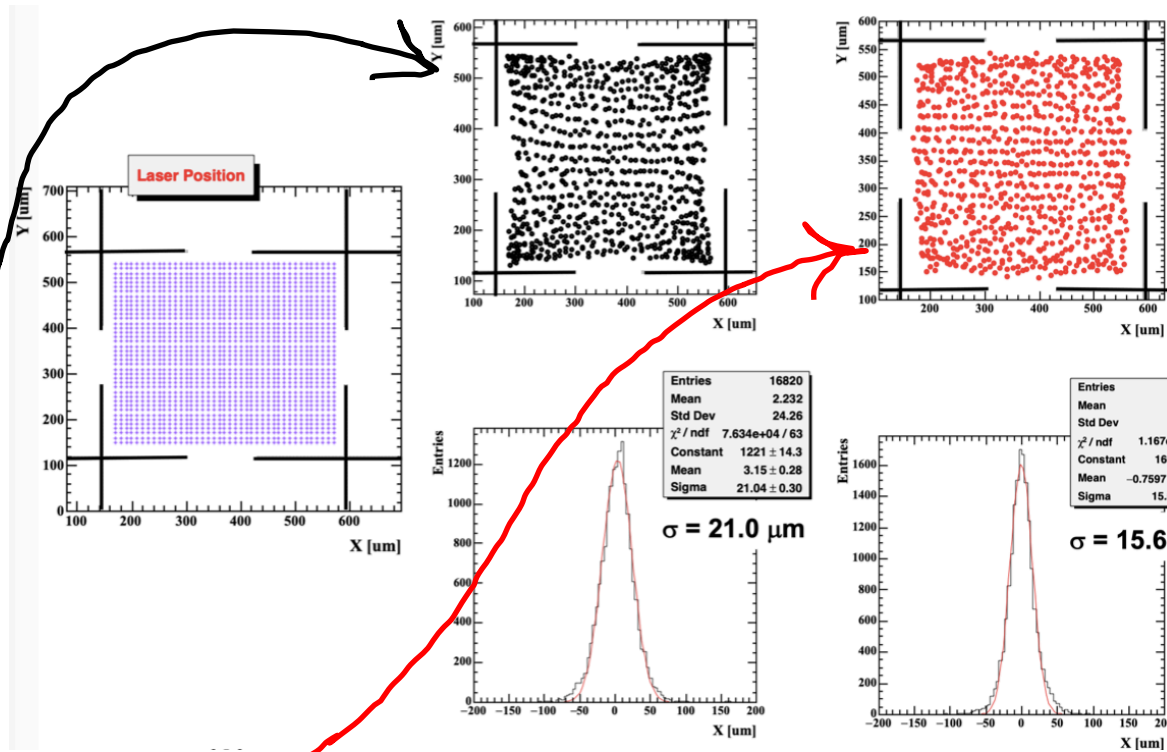
x-y coordinates reconstructed  
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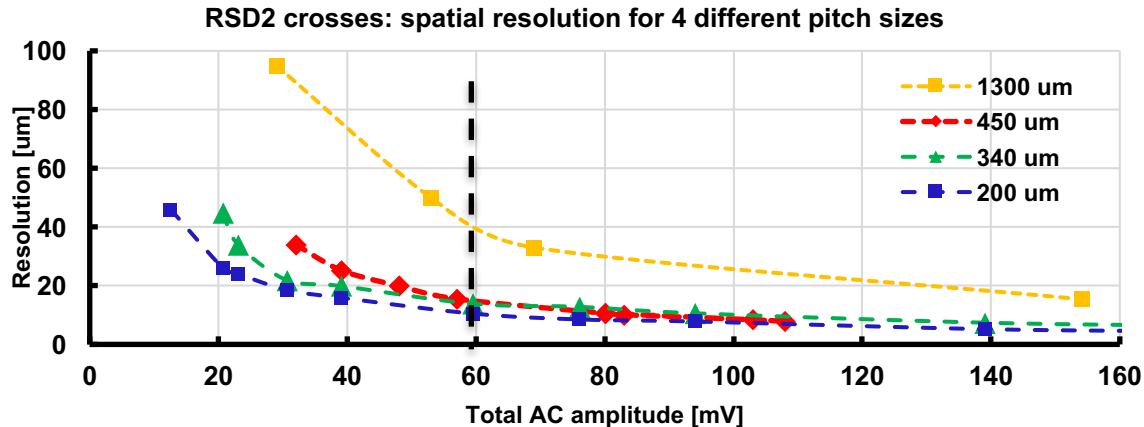
The coordinates are then **corrected**  
using a migration matrix (measured  
always with the laser setup –  
independent set of data)



reconstructed positions for the  $450 \times 450 \mu\text{m}^2$

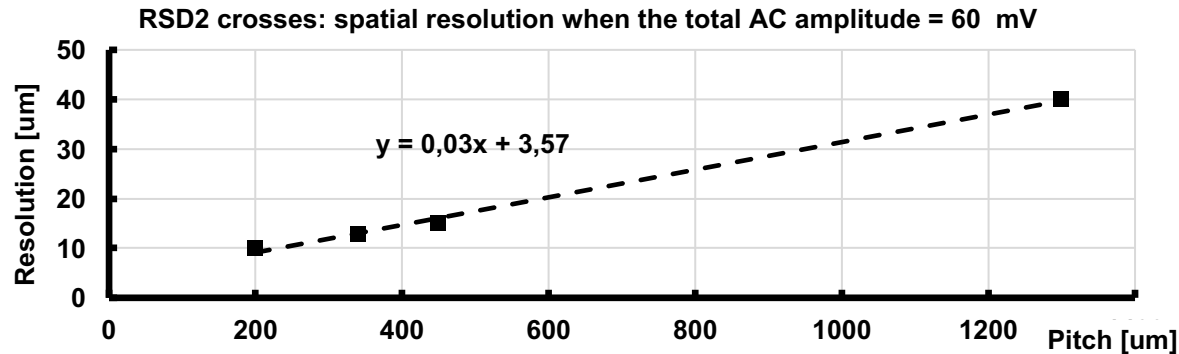
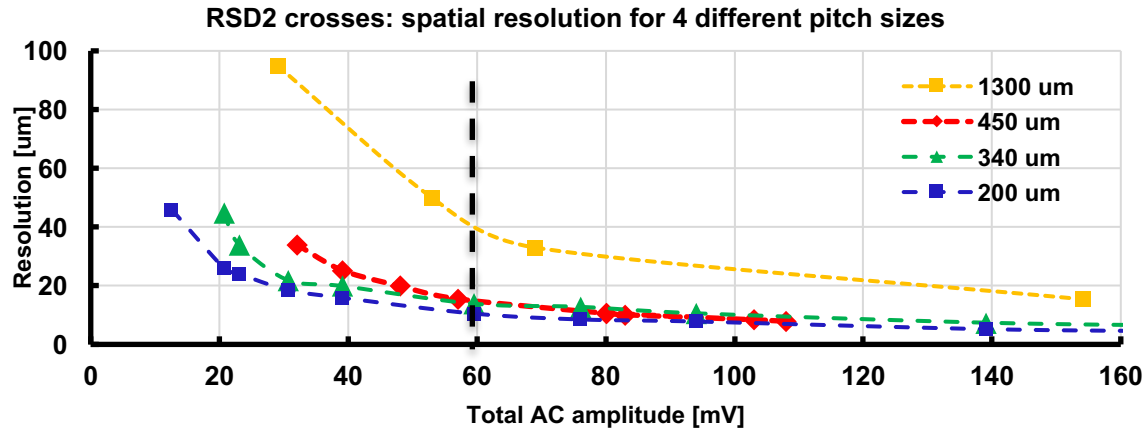


# Spatial resolution from the TCT measurements





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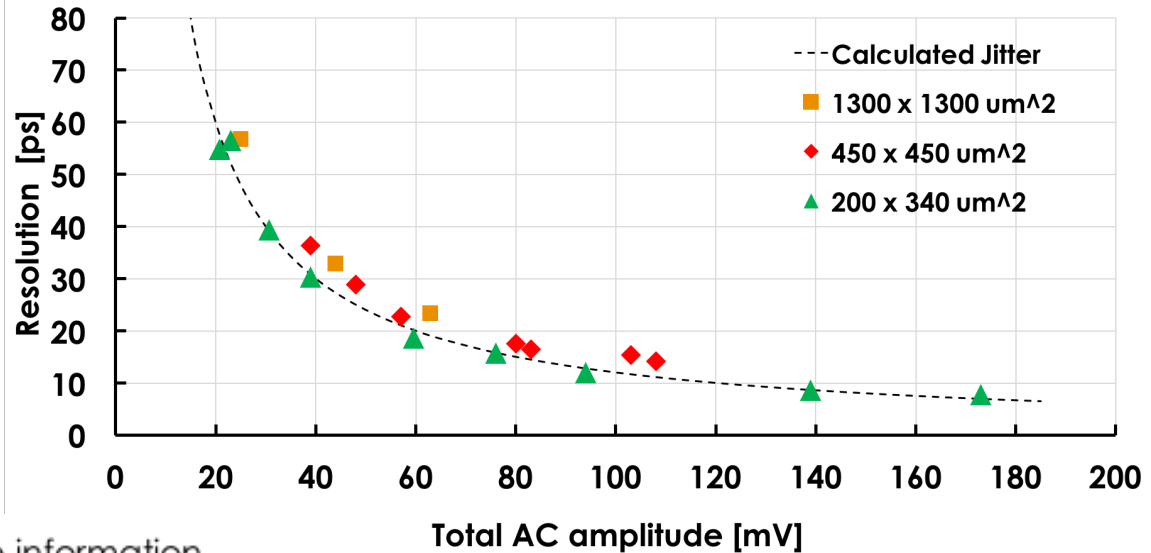
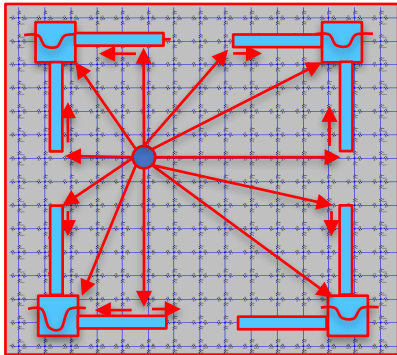


Spatial resolution versus pitch size when the total AC amplitude equals 60 mV.

At a fixed amplitude, the resolution depends linearly on the pixel size (terms  $\sigma_{\text{setup}}$ ,  $\sigma_{\text{sensor}}$  are zero)



# Time resolution from the TCT measurements



The time is obtained combining the information from the 4 read-out pads, minimizing the chi 2

$$t_{rec} = \frac{\sum_i^4 t_{rec}^i * A_i^2}{\sum_i^4 A_i^2}$$

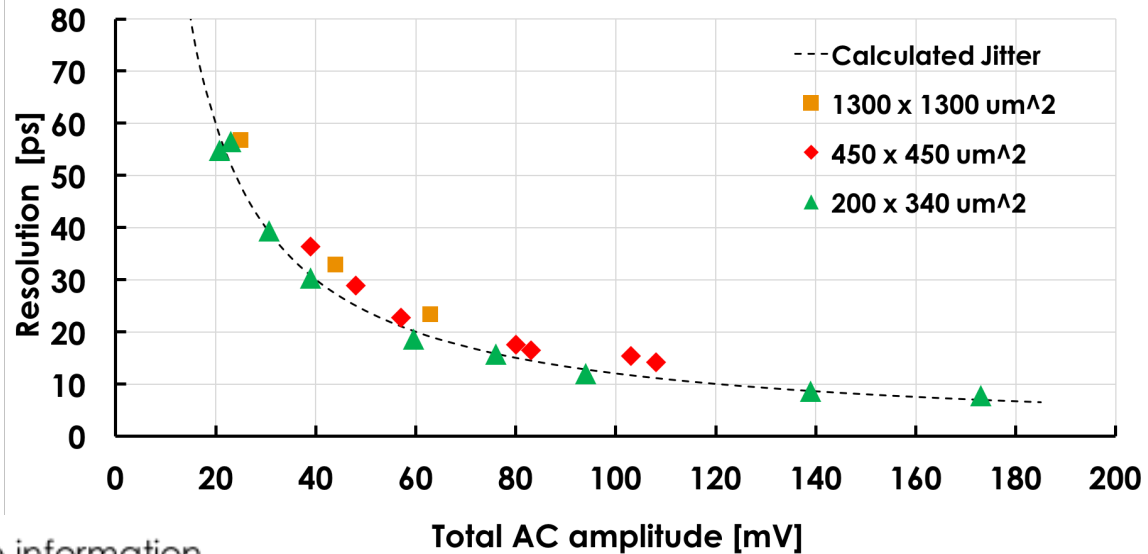
where  $t_{rec}^i = t_{meas}^i + t_{delay}^i$



# Time resolution from the TCT measurements



Landau fluctuations  
not present in this  
measurement



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where  $t_{rec}^i = t_{meas}^i + t_{delay}^i$

**The resolution (jitter + delay term)** depends mostly upon the signal size and **weakly on the pixel size**

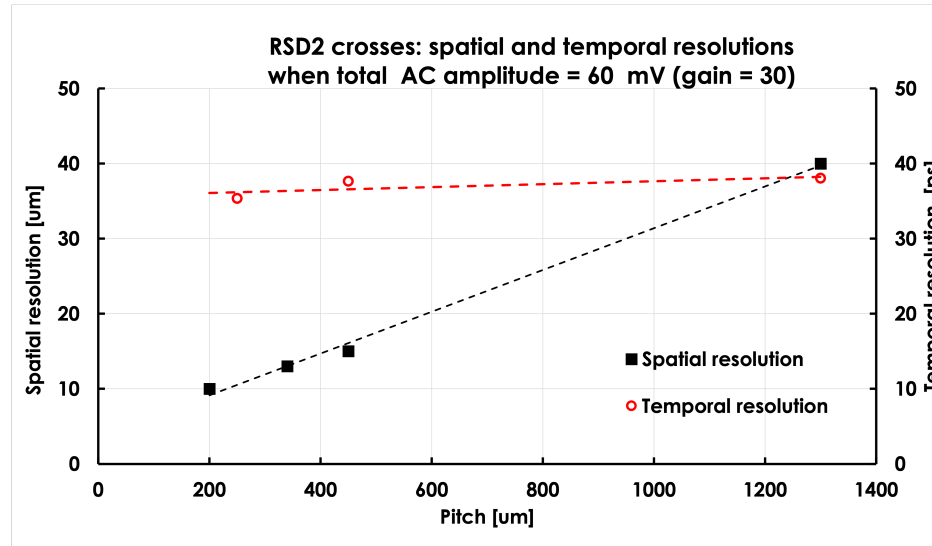
$\sigma_{delay}$  is very small

RSD2 crosses at gain = 30 achieve a time jitter of 20 ps



# RSD2 extrapolated performance

- Extrapolated resolutions for the determination of the position and time coordinates
- **time resolution**: computed by adding the Landau noise term ( $\sigma_{\text{Landau noise}} = 30$  ps)
- **spatial resolution**: computed adding  $\sigma_{\text{setup}} + \sigma_{\text{sensor}} = 5$   $\mu\text{m}$  in quadrature



Spatial resolution is about 3% of the pixel size

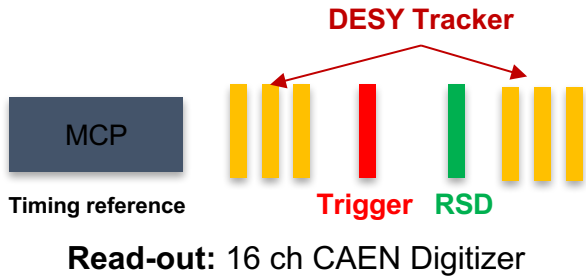
Time resolution is fairly constant at about 38 ps as a function of the pixel size



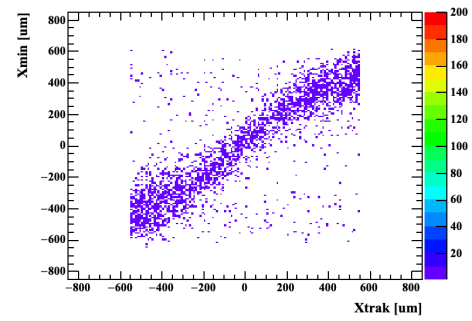
# Test beam @ DESY, 1.3 x 1.3 mm<sup>2</sup> crosses



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Correlation x\_tracker and x\_RSD

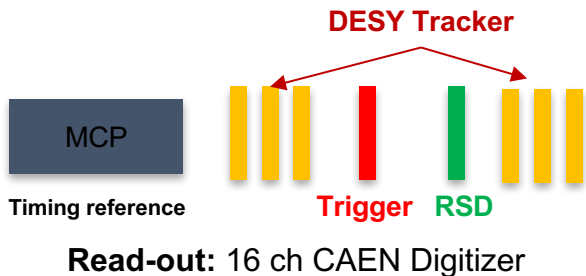


*very preliminary*

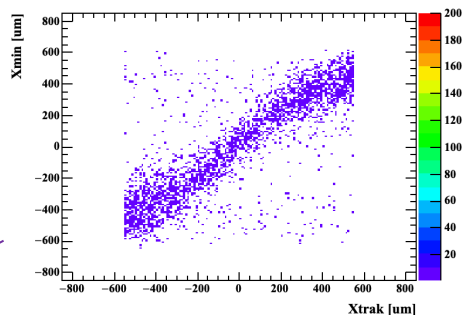
Hit position reconstructed using the method explained (with correction)



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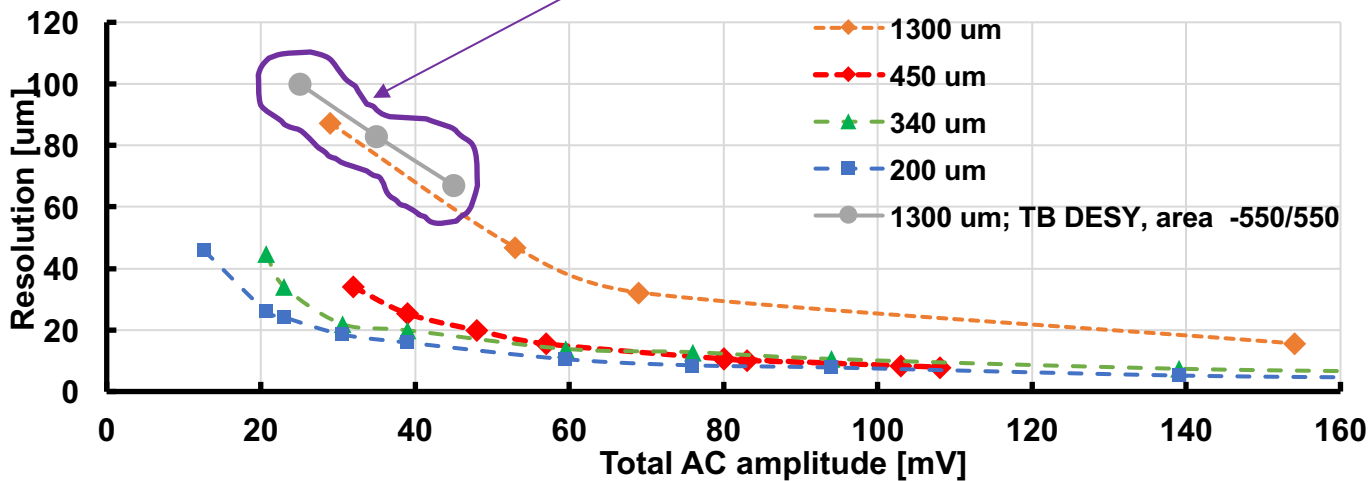


Correlation x\_tracker and x\_RSD



*very preliminary*

Hit position reconstructed using the method explained (with correction)



- max gain obtained with this device ~15
- using high part of Landau distribution
- **work just started...**



# Next step: DC-coupled resistive LGAD

## DC-RSDs

- studies started within the Italian project PRIN 2017 (2017L2XKTJ – 4DinSiDe)
- now supported by INFN CSN5 project 4DSHARE
- **see Tommaso Croci's talk** "A two-prong approach to the simulation of DC-RSD: TCAD and Spice"

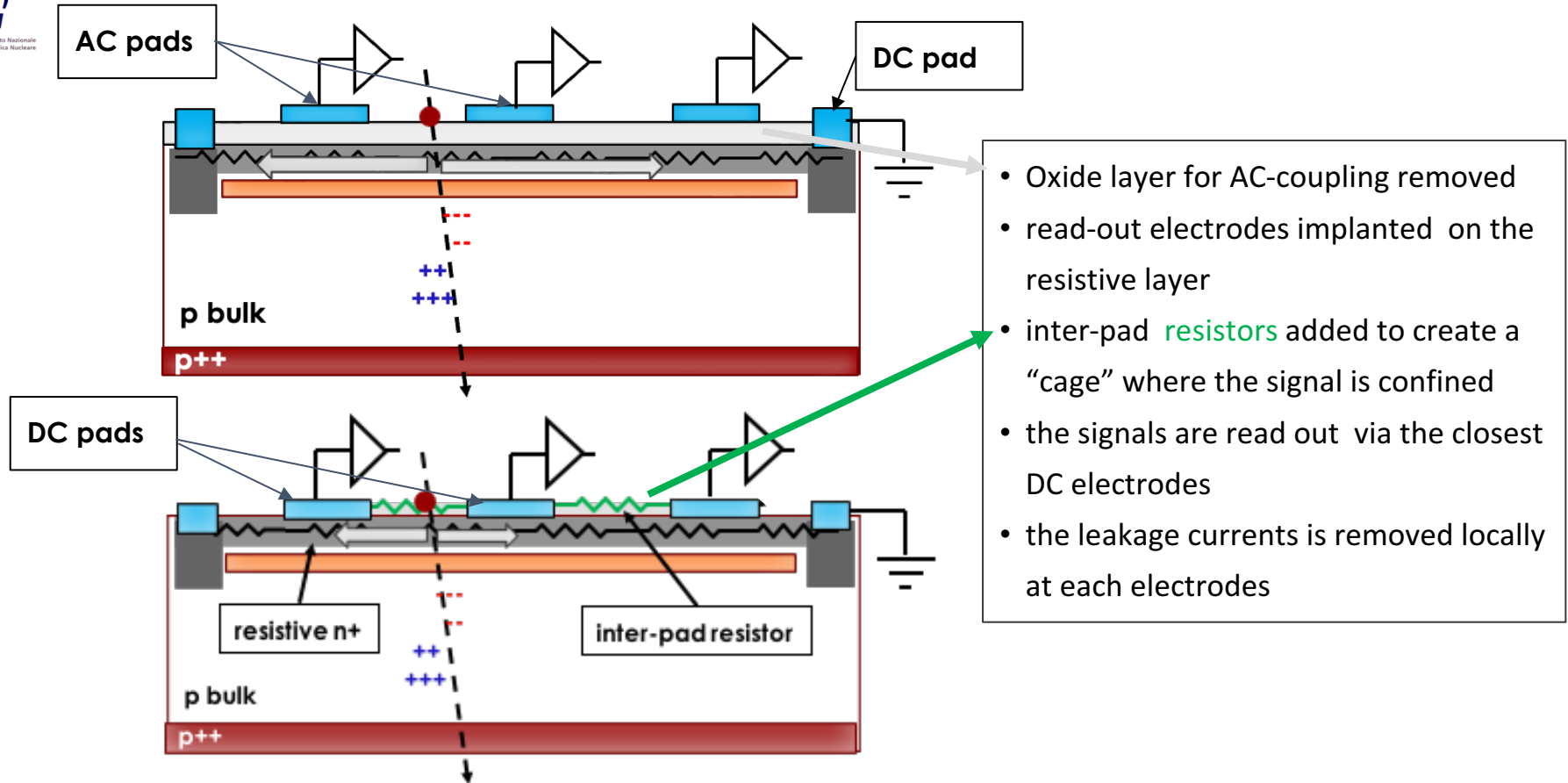
main objectives for the DC-coupled resistive read-out LGADs

➤ **overcome the limitations or drawbacks** observed studying the resistive AC-LGADS

**key points:**

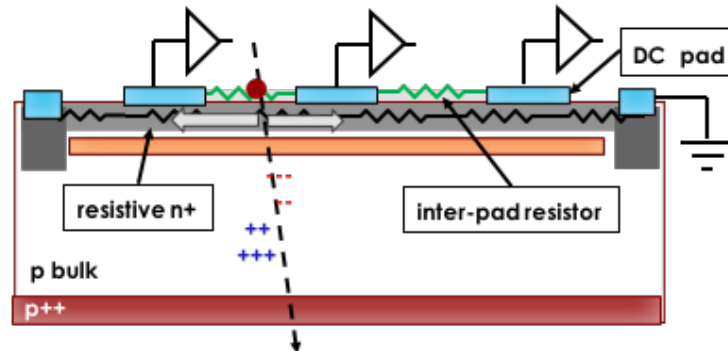
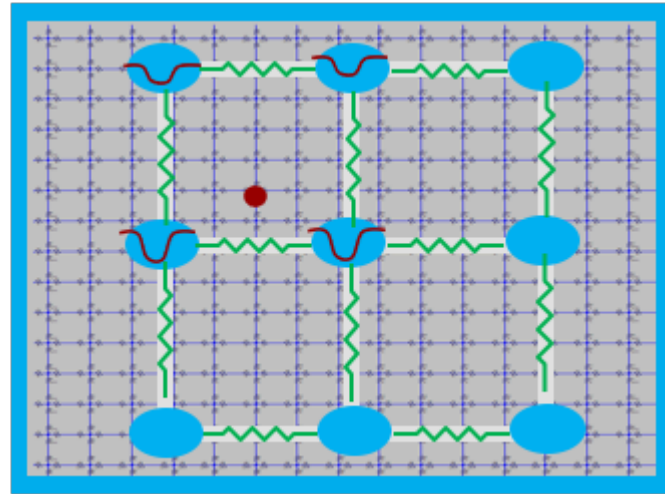
- **obtain intrinsic controlled signal sharing**, in a predetermined (not too large) number of pads
- **avoid** the collection of the **leakage current only at the periphery** of the sensor

# From AC to DC-coupled LGAD: what's new

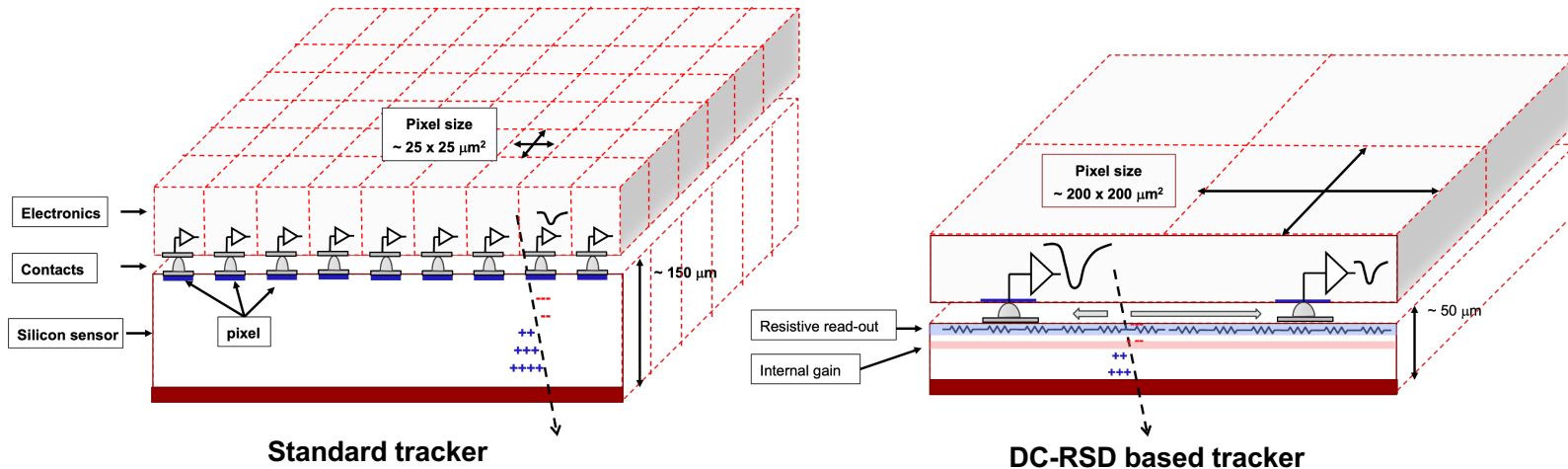




# DC-RSD from above



# A look at the next generation 4D-trackers?



## The design of a tracker based on RSD:

- Delivers ~ 30 ps time resolution
- Can easily deliver position resolution of a few microns, but with much larger pixels (number of pixel is reduced by 50-100)
- The electronic circuitry can be easily accomodated (power consumption ~ 0.1-0.2 W/cm²)
- The sensors can be really thin



# Thanks for your attention





# Acknowledgments



We kindly acknowledge the following funding agencies, collaborations:

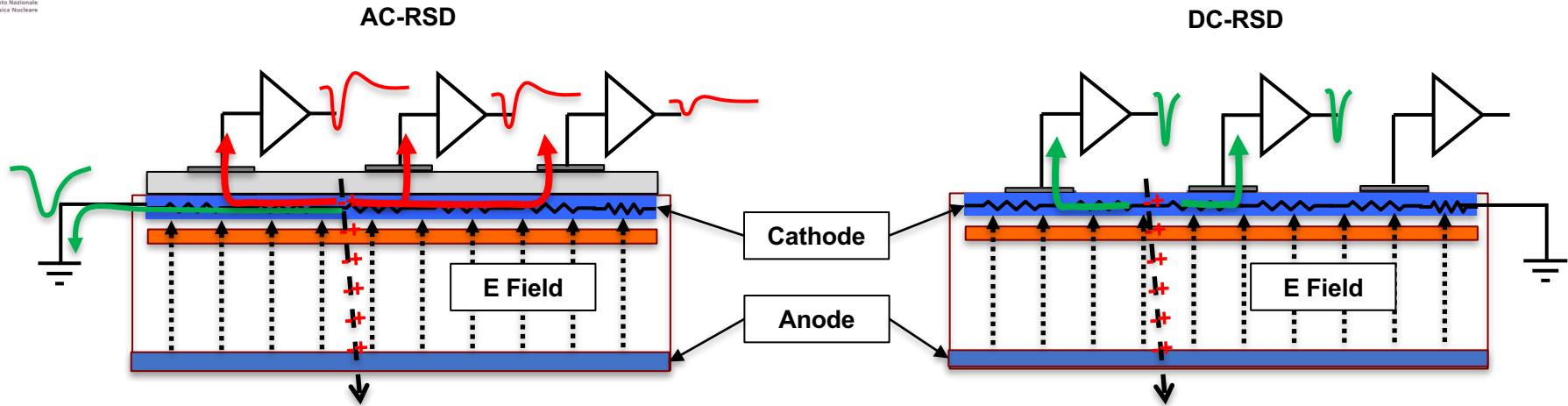
- INFN - Gruppo V RSD
- H2020 project AIDA-2020, GA no. 654168
- Dipartimenti di Eccellenza, Univ. of Torino (ex L. 232/2016, art. 1, cc. 314, 337)
- Ministero della Ricerca, Italia , PRIN 2017, progetto 2017L2XKTJ – 4DinSiDe
- RD50 Collaboration, CERN
- INFN - Gruppo V 4DSHARE
- Compagnia San Paolo, Bando TRAPEZIO 21



# BACK-UP



# From RSD to DC-RSD



DC-RSD wants to improve the RSD design:

- Move to DC-coupled read-out
  - DC signal
  - Remove the leakage current at each node and not at the periphery
- Limit the signal sharing to the closest neighboring pads
- Improve reconstruction accuracy



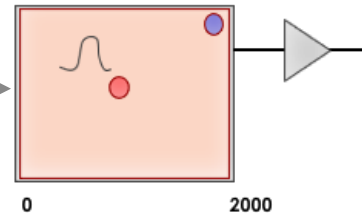


# Study of the propagation on the resistive layer

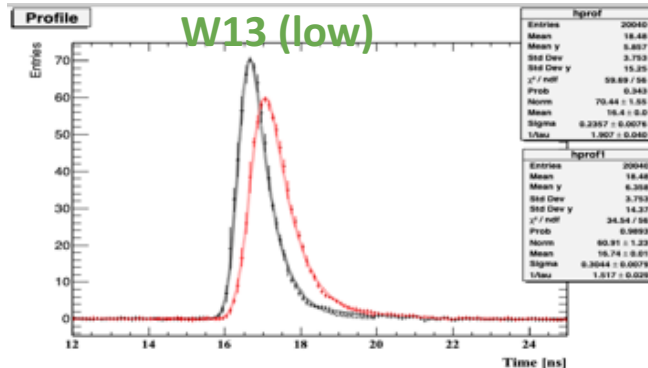
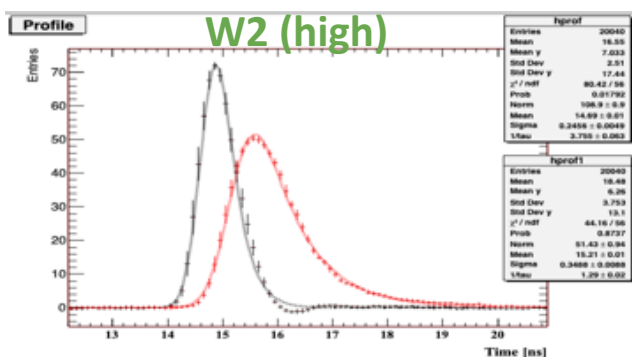


In RSD1 there is a device without electrodes, ideal for this study:

an area  $2 \times 2 \text{ mm}^2$  read out only at the DC contact only



Study of the signal (laser induced) propagation/deformation as a function of position on the surface, for wafers with different resistivities



Read= shot in the center  
Blue = shot on one side

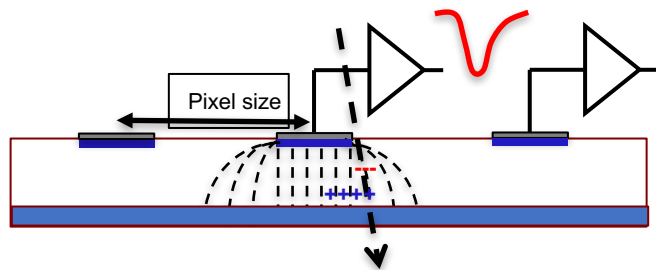
Even a propagation over a large pixel ( $O(\text{mm})$ ), and on the most resistive  $n+$  surface, does not degrade the signal significantly → key point to pursue the DC-RSD idea --> this device represent well one DC-RSD pixel



# Position measurement: Single and Multi Pixels Read-out

## Single pixel

where the signal is induced on one pixel

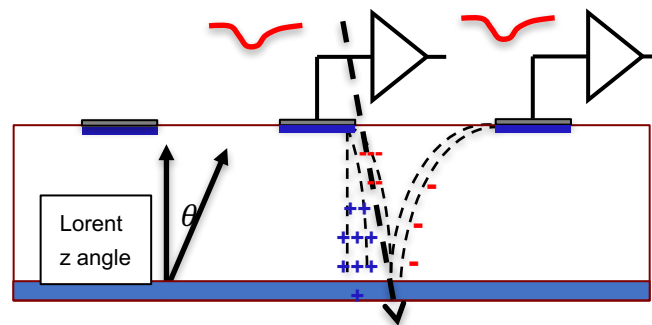


$$\sigma_x = k \frac{\text{pitch}}{\sqrt{12}}, k \sim 0.5 - 1$$

- $\sigma_x$  depend on the pixel size  
pixel = 100  $\mu\text{m}$   $\rightarrow$   $\sigma_x = 20 \mu\text{m}$

## Multi pixels

where the signal is induced on a few pixels



$$x = \frac{\sum_i x_i A_i}{\sum_i A_i}$$

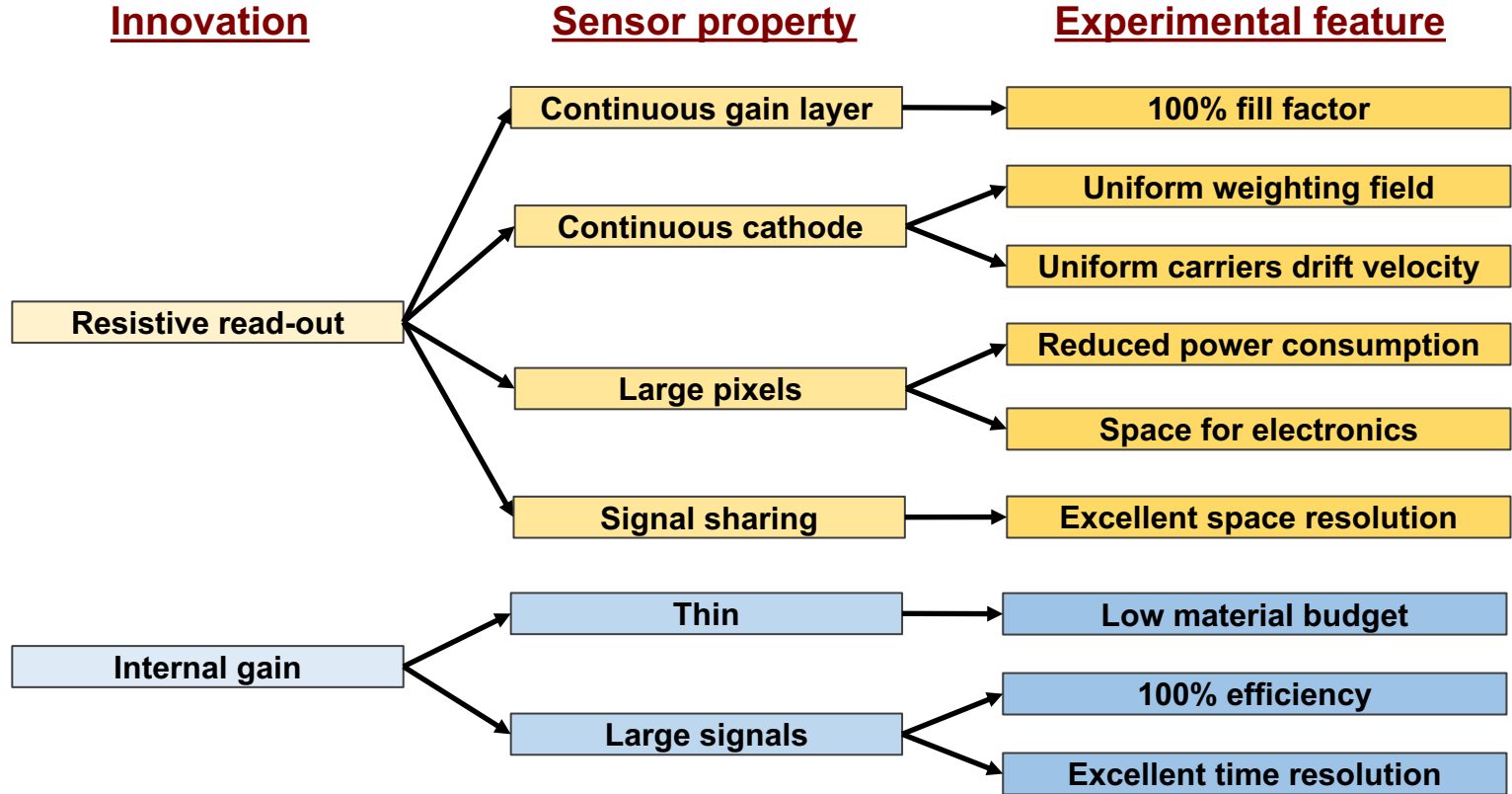
- $\sigma_x \ll$  pixel size
- Same  $\sigma_x$  can be obtained with larger pixels



# Properties of optimized RSDs

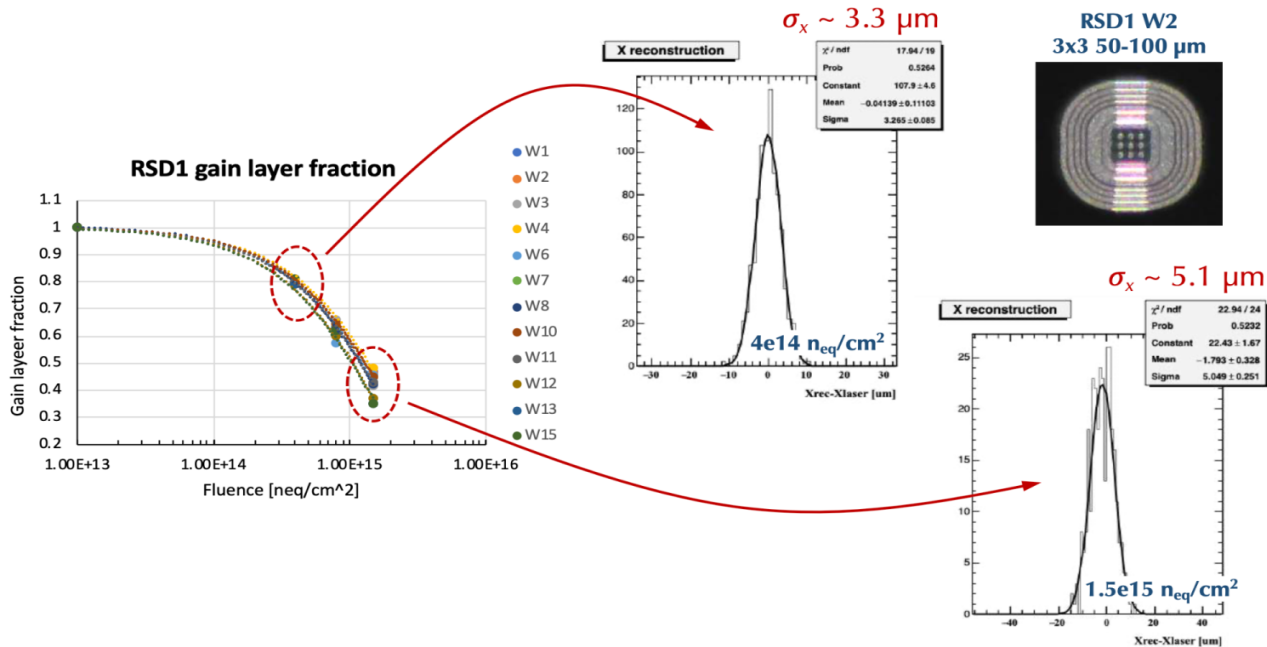


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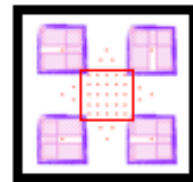
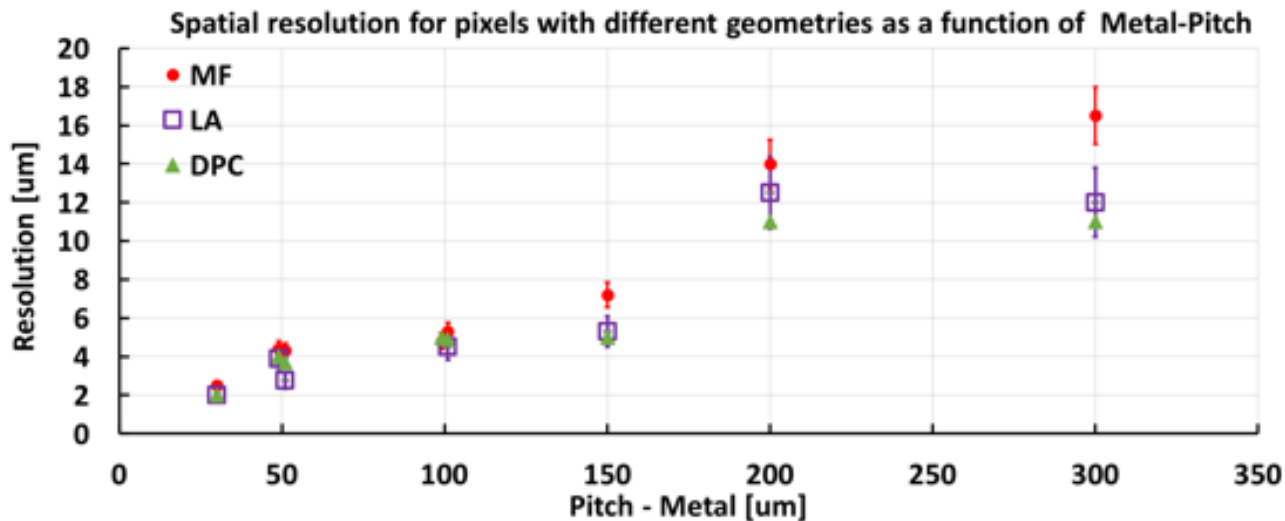
# RSD1 radiation resistance



- The radiation resistance of RSD1 is similar to that of standard LGAD
- The space and time resolutions decrease due to the signal being smaller
- No “RSD specific” effects have been found, **resistive read-out is not sensitive to radiation damage up to 1E15 n/cm<sup>2</sup> → Study to be extended to check the limits**



# RSD1- position resolution



- In RSD1 Position resolution (within the red square) is about 5% of the distance between electrodes