

# **Machine Learning in High Energy Physics**

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**QCD School 2024**

# Enfrainch



# **ML-powered anomaly detection exercise on CMS Open Data**

#### ML Exercise: Anomaly detection in high energy physics

In this notebook we will demonstrate how to design a tiny autoencoder (AE) that we will use for anomaly detection in particle physics. More specifically, we will demonstrate how we can use autoencoders to select potentially New Physics enhanced proton collision events in a more unbiased way!

We will train the autoencoder to learn to compress and decompress data, assuming that for highly anomalous events, the AE will fail.

#### **Dataset**

As a dataset, we will use the CMS Open data that you have been made familiar with already. Our dataset will be represented as an array of missing transverse energy (MET) up to 4 electrons, up to 4 muons and 10 jets each described by pT, η, φ and particle ID (just from knowing whether it is a muon/electron/jet)--recid 63168 --protocol xrootd. The particles are ordered by pT. If fewer objects are present, the event is zero padded.

We will train on a QCD MC dataset (we could also train directly on data), and evaluate the AE performance on a New Physics simulated sample: A Bulk graviton decaying to two vector bosons:  $G(M=2 \text{ TeV}) \rightarrow WW$ 

We'll train using background data only and test using both background and the Graviton sample. Let's fetch them! The background data are available here (recid = 63168) and the signal data here (recid = 33703). The signal consists of 1,37M events and the background 19,279M events. We will use roughly 500K for each process.

We will use the docker client to print all the file names. You can then use this list to concatenate data from all the files.



When: Today at 17:00 Material: github.com/thaarres/qcd\_school\_ml



("machine learning" or "deep learning" or neural) and (hep-ex or hep-ph or hep-th)

# Date of paper







CERN Summer student 2012







#### learning would have required the collection of about four times as  $\mathbb{R}$ **We were using ML for discovery very early on**

field-specific knowledge to engineer to engineer to engineer to engineer to extract the features of the featu

data that are expected to be the most useful for a given measurement. The most useful for a given measurement measurement. The most useful for a given measurement of a given measurement of a given measurement. The most use





tonnes of liquid argon, detects neutrinos sent from the booster neu-











T1037 / 6vr4 90.7 GDT (RNA polymerase domain) T1049 / 6y4f 93.3 GDT (adhesin tip)

Experimental result

Computational prediction

sequence-the structure prediction component of the 'protein folding problem'<sup>8</sup>-has been an important open research problem for more than 50 years<sup>9</sup>. Despite recent









T1037 / 6vr4 90.7 GDT (RNA polymerase domain) T1049 / 6y4f 93.3 GDT (adhesin tip)

Experimental result

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sequence-the structure prediction component of the 'protein folding problem'<sup>8</sup>-has been an important open research problem for more than 50 years<sup>9</sup>. Despite recent







#### 1,800,000,000,000 (1.6% of neurons in your brain)



#### 175,000,000,000 (0.16% of neurons in your brain)

# GPT-3 GPT-4 (MoE)

#### [semianalysis](https://www.semianalysis.com/p/gpt-4-architecture-infrastructure) 2023



#### **Train (GPT-4):**

- **• 2.1525 floating point operations**
- **• ~25,000 A100 GPUs**
- **• 90-100 days**
- **• \$63 million**
- **• Trained on 13 trillion tokens**

ChatGPT 4o  $\vee$ 

֍

are mosquitoes in Finland known to be more aggressive than Swiss mosquitos?

Mosquitoes in Finland are often perceived as more aggressive compared to those in Switzerland. There are several reasons behind this perception:

1. Species and Density: Finland, especially in its northern parts, is home to a high density of mosquitoes during the summer months. The country's extensive wetlands and numerous lakes create ideal breeding grounds for mosquitoes. In contrast, Switzerland has fewer mosquito-prone areas.

2. Climate and Activity: The short but intense summer season in

#### **Inference (GPT-4): • Multiple clusters of 128 GPUs**

- 
- **• Model carefully mapped onto hardware**





#### **AI and Memory Wall**



#### **Computer vision: 10–100M trainable parameters (1018 –1019 floating point operations for training) LLMs: 100M to 100Bs trainable parameters (1020–1023 floating point operations for training)**

# **• innovations in network structures**

**What is deep learning? • strategies to train them • dedicated hardware**



#### **PFN** P-CNN ParticleNet **ParT**

ParT (plain)





*["Particle Transformer For Jet Tagging" H. Qu, C. Li, S. Qian](https://arxiv.org/abs/2202.03772)* 





*100 million jets for training*

[Krizhevsky et al. \[2012\]](https://proceedings.neurips.cc/paper/2012/file/c399862d3b9d6b76c8436e924a68c45b-Paper.pdf):

Artificial Neural Network with a **simple structure** (known for >20 years [\[LeCun et al., 1989\]](http://yann.lecun.com/exdb/publis/pdf/lecun-89e.pdf)), Beat complex SOTA image recognition methods by huge margin **How? x100 larger and trained on a data set x100 larger**

# **TPU**



## **What has changed?**

[Krizhevsky et al. \[2012\]](https://proceedings.neurips.cc/paper/2012/file/c399862d3b9d6b76c8436e924a68c45b-Paper.pdf):

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Made possible due to

Graphical Processing Units (GPUs) Data, data and data!

# **TPU**



## **What has changed?**

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Made possible due to

Graphical Processing Units (GPUs) Data, data and data!

Deep Learning:

innovations in network structures, strategies to train them, and dedicated hardware

Exponential increase in size and quantity of training data [Sevilla et al., 2022]!





## **What has changed?**

# GPT-4(omni?)





?

CMS Experiment at the LHC, CERN J. Run / Event: 151076 1405





- ֍ Machine learning has the potential to make significant contributions within high-energy physics in various areas. Here are some of the key areas where machine learning can have a substantial impact:
	- Data Analysis and Event Classification: High-energy physics experiments generate massive amounts of data, and sifting through this data to identify interesting events and classify them is a challenging task. Machine learning algorithms can help automate this process by efficiently identifying and categorizing particle collisions, reducing the workload on physicists.
	- 2. Anomaly Detection: Machine learning can be used to detect anomalies or rare events in experimental data. This is crucial for identifying unexpected or new physics phenomena that may deviate from existing theories. Algorithms like autoencoders and anomaly detection models can help in this regard.
	- 3. Particle Tracking and Reconstruction: Accurate reconstruction of particle trajectories and interactions is essential in high-energy physics experiments. Machine learning can improve the precision and efficiency of particle tracking, helping physicists better understand the paths and properties of particles.
	- Simulation and Generative Models: Generative models like Generative Adversarial Networks (GANs) and Variational Autoencoders (VAEs) can be used to simulate highenergy physics events and particle interactions. These models can generate synthetic data that can be compared with experimental data, aiding in background estimation and calibration.
	- 5. Detector Calibration and Optimization: Machine learning can assist in calibrating and optimizing particle detectors. Algorithms can automatically adjust detector parameters to improve the accuracy of measurements and reduce systematic errors.
	- 6. Rare Signal Searches: High-energy physics experiments often involve searching for rare signals amidst a vast amount of background noise. Machine learning techniques, including advanced statistical analysis and deep learning, can enhance the sensitivity of these searches.
- 7. **Data Compression:** Storing and transmitting large datasets from particle collisions can be resource-intensive. Machine learning can be used for data compression techniques, allowing for more efficient storage and transmission of experimental data.
- Dark Matter and Beyond the Standard Model Physics: Machine learning can help in the search for dark matter and other particles beyond the Standard Model. Advanced algorithms can assist in designing experiments, analyzing data, and identifying potential signatures of new physics.
- 9. Optimizing Experimental Design: Machine learning can assist in optimizing the design of high-energy physics experiments. It can help determine the most informative configurations and setups for detectors, accelerators, and data collection strategies.
- Reducing Human Bias: Machine learning can help reduce human bias in data analysis by providing automated and unbiased methods for data interpretation.

It's important to note that the application of machine learning in high-energy physics often requires collaboration between physicists and machine learning experts to develop specialized algorithms and models tailored to the unique challenges of the field. Additionally, the interpretation of results and the validation of machine learning techniques remain crucial aspects of ensuring the reliability of the findings in high-energy physics experiments.

G





#### **What makes particle physics special?**

 $dP_d^n$  $\sum_{data}^{n} = |M_S + M_B|^2 dp_1 dp_2 ... dp_n$ 



 $M_S M_B^* + M_B M_S^*$ 



**Dijet invariant mass**

#### **It's against physical law to annotate our data!**

**Dijet invariant mass**



 $M_S M_B^* + M_B M_S^*$ 











# **Monte Carlo Simulation** *Dimensions*  $O(10)$   $O(10^3)$  $O(10^{10})$  $O(10^3)$  and  $O(10^{10})$  $10^{-18}$ m  $10^{-15}$ m  $10^{-6}$ m *Perturbative QCD Markov model Hadronization Detection*Ceoperate  $\boldsymbol{o}$  $\Omega$  $\sim$ **POPT** ╱

#### **~40 quadrillion collisions recorded at LHC (1 fb-1 ~ 100 trillion collisions)**

#### *CMSOfflineComputingResults*   $\underline{CMSOffline Computing Results}$











#### We are also very keen on using this!





#### We have a lot of high quality simulated data that we want to use

We are also very keen on using this!





#### We have a lot of high quality simulated data that we want to use



#### We have a lot of high quality simulated data that we want to use





 $\boldsymbol{n}$ 



 $\mathcal{L}_{\mathcal{A}}$ 





 $0.4 -$ 



*?*







Fig. 1.: An example jet image of a Lorentz boosted top quark jet after *[arXiv:1511.05190](https://arxiv.org/abs/1511.05190)* 

 $N = N \cdot N$ ages have notable di↵erences with respect to typical natural images in CV. **But… inhomogeneous geometry, high sparsity**



#### Fig. 1.: An example jet image of a Lorentz boosted top quark jet after *[arXiv:1511.05190](https://arxiv.org/abs/1511.05190)*





#### **But... permutation-invariance**




 $\blacksquare$ 

 $\mathcal{L}_{\mathcal{A}}$ 

 $\mathcal{L}_{\mathcal{A}}$ 



While designed to take advantage of advances in computer vision, jet im-



recurrent neural network (RNN), e.g., GRU/LSTM; 1D CNNs; etc.







![](_page_39_Picture_1.jpeg)

![](_page_39_Picture_2.jpeg)

![](_page_40_Picture_1.jpeg)

Properties of physics data:

- Measurements distributed in space (and time) **irregularly**
- **Sparse** (most detector channels are empty), but pockets of density
- Complex **interdependencies** between measurements
- Physics "objects" composed of **multiple measurements**
- Inherent **symmetries** (Lorentz boosts, rotational)

Graph (or point cloud) embedding of the data can handle these properties!

![](_page_41_Picture_8.jpeg)

# **Graph Neural Networks**

![](_page_42_Picture_0.jpeg)

![](_page_42_Picture_1.jpeg)

![](_page_42_Picture_3.jpeg)

• Node features : particle 4-momentum

• Edge features : pseudoangular distance

• Graph (global) features : jet mass

Δ*R* = Δ*η*<sup>2</sup> + Δ*ϕ*<sup>2</sup>

![](_page_43_Picture_1.jpeg)

![](_page_43_Picture_2.jpeg)

*<sup>m</sup>* <sup>=</sup> <sup>∑</sup>

**Node, edge, graph features (e.g. jet)**

# **Graph Neural Networks**

• Node features : particle 4-momentum

• Edge features : pseudoangular distance

# **Graph Neural Networks** Efficient N<br>Effects DSPS (used for multiplication)

 $e'_{1\rightarrow5} = \sqrt{\text{LP}(\vec{v}_1)}$ 

 $v'_1$ 

 $n_1' =$ 

Efficient NN design: compression *70% compression ~ 70% fewer DSPs (max DSP use) m* in the *m* in the V<br>J<br>- $\mathbf{v}_{s_k}, \mathbf{u}$ <br>*i*  $\mathbf{u}' = \phi^u (\mathbf{e}', \mathbf{v}', \mathbf{u})$ 

- Greate a new represent the graph **u** the graph *Fully parallelized*  • Create a new representation for each part of
	- These"updates" are usually DNNs!

![](_page_44_Picture_5.jpeg)

DSPs (used for multiplication) are often

limiting resource

maximum use when fully parallelized

 DSPs have a max size for input (e.g.  $27<sup>18</sup>$ multiplication changes with precision

compression

hls4ml tutorial – 4th IML Workshop

19th October 2020

Efficient NN design: compression NN de

limiting resource

maximum use when fully parallelized

 $1, \overrightarrow{V}$ ∫<br>│

 DSPs have a max size for input (e.g. 27x18 bits), so number of DSPs per multiplication changes with precision

compression of the compression o

*70% compression ~ 70% fewer DSPs*

•

limiting resource

maximum use when fully parallelized

 DSPs have a max size for input (e.g. 27x18 bits), so number of DSPs per multiplication changes with precision

*Fully parallelized (max DSP use)*

a<br>K

 $f'$ **5** $(e_1$  → 5, …,  $e_6$  → 5)

∫<br>∫

*70% compression ~ 70% fewer DSPs*

Number of DSPs available

 $\mathcal{L}$ 

*v*′

 $\frac{2}{5}$ <br> $\frac{1}{5}$ <br> $\frac{1}{5}$  $\frac{1}{2}$ Number of DSPs available Want to create "new features" on the nodes, edges, or the full graph with multiple iterations:

⃗

![](_page_45_Picture_0.jpeg)

![](_page_46_Figure_0.jpeg)

![](_page_47_Picture_0.jpeg)

# **Transformers and (self-)attention**

# (Self-)Attention

- Allows inputs to interact with each other ("self") and find out who they should pay more attention to ("attention").
- Outputs: aggregates of interactions and attention scores

![](_page_48_Figure_6.jpeg)

![](_page_48_Picture_56.jpeg)

![](_page_48_Picture_8.jpeg)

![](_page_49_Picture_6.jpeg)

$$
y_i = \sum_j w_{ij} x_j
$$

Weight (how related inputs are):

$$
w_{ij}' = x_i^T x_j
$$

Map to [0,1]:<br> $w_{\bf ij} = \frac{\exp w'_{\bf ij}}{\sum_{\bf j} \exp w'_{\bf ij}}$ 

# (Self-)Attention

- Allows inputs to interact with each other ("self") and find out who they should pay more attention to ("attention").
- Outputs: aggregates of interactions and attention scores

![](_page_50_Picture_6.jpeg)

![](_page_50_Figure_8.jpeg)

Weight (how related inputs are):

![](_page_50_Picture_10.jpeg)

$$
\boldsymbol{w}_{ij}^{\prime} = \boldsymbol{x}_i^{\mathsf{T}} \boldsymbol{x}_j
$$

Map to [0,1]:<br> $w_{ij} = \frac{\exp w'_{ij}}{\sum_j \exp w'_{ij}}$ 

# (Self-)Attention

- Allows inputs to interact with each other ("self") and find out who they should pay more attention to ("attention").
- Outputs: aggregates of interactions and attention scores

![](_page_51_Picture_12.jpeg)

 $y_i = \sum_i w_{ij} x_j$ 

Weight (how related inputs are):

![](_page_51_Picture_16.jpeg)

 $w'_{ii} = x_i^{\top} x_j$ 

Map to [0,1]:<br> $w_{\bf ij} = \frac{\exp w'_{\bf ij}}{\sum_{\bf j} \exp w'_{\bf ij}}$ 

## (Self-)Attention

- Allows inputs to interact with each other ("self") and find out who they should pay more attention to ("attention").
- Outputs: aggregates of interactions and attention scores

### Attention weights: weighted importance between each pair of particles

- Determine relationship between all particles of point cloud
- Jet features become parameters of the model
- Several attention layers  $\rightarrow$  different important features (multi-head attention)

![](_page_52_Picture_14.jpeg)

 $y_i = \sum_i w_{ij} x_j$ 

Weight (how related inputs are):

![](_page_52_Picture_18.jpeg)

 $w'_{ii} = x_i^{\dagger} x_j$ 

Map to [0,1]:<br> $w_{\bf ij} = \frac{\exp w'_{\bf ij}}{\sum_{\bf j} \exp w'_{\bf ij}}$ 

## (Self-)Attention

- Allows inputs to interact with each other ("self") and find out who they should pay more attention to ("attention").
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### Attention weights: weighted importance between each pair of particles

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### Transformer:

• Only set of interaction between units is self-attention!

Weight (how related inputs are):

![](_page_53_Picture_21.jpeg)

 $w'_{ii} = x_i^{\dagger} x_j$ 

Map to [0,1]:<br> $w_{ij} = \frac{\exp w'_{ij}}{\sum_j \exp w'_{ij}}$ 

![](_page_53_Picture_27.jpeg)

## (Self-)Attention

- Allows inputs to interact with each other ("self") and find out who they should pay more attention to ("attention").
- Outputs: aggregates of interactions and attention scores

### Attention weights: weighted importance between each pair of particles

- Determine relationship between all particles of point cloud
- Jet features become parameters of the model
- Several attention layers  $\rightarrow$  different important features (multi-head attention)

### Transformer:

• Only set of interaction between units is self-attention!

### Example prompt

Rigor [adj.] Something for scientists to aspire to, a state of mind that would not be required if scientists could be trusted to do their job.

**View next definition** 

### GPT-3's output: 1 of 10

The Literature [noun] A name given to other people's published papers, referred to by scientists without actually reading them.

Gwern.net

Query, Key and Value: How self-attention is implemented

- •**The query**: dog I'm looking for verbs, adjectives related to me
- •**The key**: every word in the sentence! I'm a noun, an adjective or a verb (What am I? What features do I posses in relation to the sentence?)
- •**The value:** the meaning of this word in general not specifically for this sentence (What are my embeddings? What's the semantic information I posses?)

![](_page_54_Figure_5.jpeg)

![](_page_54_Picture_6.jpeg)

# **Transformers**

### Query, Key and Value: How self-attention is implemented

- •**The query**: dog
- I'm looking for verbs, adjectives related to me
- •**The key**: every word in the sentence! I'm a noun, an adjective or a verb (What am I? What features do I posses in relation to the sentence?)
- •**The value:** the meaning of this word in general not specifically for this sentence (What're my embeddings? What's the semantic information I posses?)

### Self-Attention for word dog:

- •**Dog (Query Vector):** Multiplied with all other words (Keys) to get Attention Map
- •**Attention Map:** represent importance of every other word related to Dog
- •This attention map will be multiplied by the Embeddings of the Sentence words (Values), and produce a weighted sum of the embeddings based on the relevancy of the words

![](_page_55_Figure_10.jpeg)

![](_page_55_Picture_11.jpeg)

# **Transformers**

### ABCNet:

Pixel intensity = particle importance w.r.t most energetic particle in jet, from attention weights No substructure information given, learned through attention layers! +1 0 1110 1110 (1011 g|1011, counted the  $\overline{5}$ <sup>−</sup><sup>5</sup> 10 −0.000 m joq nom allondon worgi

### −−<br>−− −−<br>−

![](_page_56_Figure_1.jpeg)

![](_page_56_Picture_4.jpeg)

**Symmetry in Deep Learning**

![](_page_57_Figure_3.jpeg)

Symmetries is an extremely important concept, also in Machine Learning.

• If there is a symmetry in your system, integrate it into your model, and it can do more with less!

*Walters, IAIFI School 2023*

# **Symmetries**

![](_page_58_Figure_2.jpeg)

# Equivariance

*E.g CNNs & GNNs (see later)! Invariances are usually obtained through weight sharing*

# *Result changes in "the same way" as the input Result doesn't change when you change the input*

![](_page_58_Figure_5.jpeg)

# **Symmetries**

- 
- Conservation of mass, momentum, energy Conservation of mass, momentum, energy
- $\bullet$  In many cases, we also have approximate models that can predict the system behaviour

![](_page_59_Figure_5.jpeg)

![](_page_59_Picture_7.jpeg)

![](_page_59_Picture_8.jpeg)

### • Other than observed data, we know the invariances that govern physical phenomena More and more work in HPE try to utilise symmetries when designing DNNs, e .g invariant under Lorentz symmetries! • Other than observed data, we know the invariances that govern physical phenomena

# *The label of a jet should be invariant under any transformation of the input jet, right?*

![](_page_59_Picture_10.jpeg)

![](_page_60_Figure_0.jpeg)

![](_page_61_Figure_1.jpeg)

# Train on simulation, test on data **Train on simulation, test on data**

If data and simulation differ, this is **sub-optimal**! **If data and simulation differ, this is sub-optimal!**

![](_page_61_Figure_3.jpeg)

Unsupervised/SSL • No labels, completely data driven

# We are also very keen on using this!

![](_page_62_Picture_6.jpeg)

Mostly (SM )background samples, small signal datasets

![](_page_62_Figure_2.jpeg)

# Simulation != test data

# **The scientific method**

![](_page_63_Figure_1.jpeg)

# **Searches at LHC**

- assuming Standard Model
- and some signal hypothesis

# Searches at LHC (almost) always start with by

### No longer learn from observation

• Blind analysis only way we perform searches

![](_page_64_Picture_7.jpeg)

![](_page_64_Figure_1.jpeg)

# Searches at L **Searches at LHC**

### his is fine when you know what This is fine when you know what you are looking for

- **2** ditul start in die given the dry substantial subst • Tailor search to a given theory
- Motivated by belief/disbelief
- e MULIVALEU DY DELIEI/UISDELIEI howered, but annived to model • Powerful, but limited to model of choice

![](_page_65_Figure_5.jpeg)

![](_page_66_Figure_0.jpeg)

![](_page_67_Picture_0.jpeg)

![](_page_68_Figure_0.jpeg)

What are "normal" data and what are "outliers" (and what is noise)?

# **Learning from data**

![](_page_69_Figure_3.jpeg)

**LEARN THIS FROM DATA**

![](_page_70_Picture_2.jpeg)

# **Anomaly detection for New Physics searches**

# **Types of anomaly detection**

### **Outlier detection Detecting overdensities** [1807.10261, 1808.08979, 1808.08992, 1811.10276, 1903.02032, 1912.10625, 2004.09360, 2006.05432,

Find (resonant) overdensities in distributions 2106.1001.1020986, 2110084, 2109.10919, 2110.01094<br>Expediantly victimization in also humanois

**Find (non-resonant) out-of-distribution datapoints Find (resonant) overdensities in distributions** Two Types of Anomaly Detection

![](_page_71_Figure_3.jpeg)

![](_page_71_Figure_6.jpeg)
# **Types of anomaly detection**

#### Outlier d  $\mathbf{H} = \mathbf{H} \mathbf{H} = \mathbf{H} \mathbf{$ etection





#### Non-resonant, tail of distributions

- Often (variational) auto-encoders
- et alisaful for trinnering/"selecting"| et al: 2102.08380, Finke et al: 2104.09051, Govorkova et al: 2108.03986, Collins: 2109.10919, **Fraser et al:**  • Useful for triggering/"selecting"!

### **Detecting overdensities**

#### Resonant, similar to a bump hunt

- Density estimation methods
- Useful for offline analysis

# **Outlier detection**

Compressed representation of x. Latent space  $\mathbf{\mathfrak{R}}^k$ , k < m $\times$ n prevents memorisation of input, must learn



# **Outlier detection**





 $\mathscr L(\mathbf x, \hat{\mathbf x})$  is Mean Squared E  $\mathscr{L}(\mathbf{x}, \hat{\mathbf{x}})$  is Mean Squared Error $(\mathbf{x}, \hat{\mathbf{x}})$ , "high error events" proxy for "degree of abnormality"  $\mathscr L(\mathbf x, \hat{\mathbf x})$  is Mean Squared

# **Outlier detection**

*n* × *m*





#### SciPost Physics

 $\mathbb{R}^k$ 



Figure 2: Distribution of reconstruction error computed with a CNN autoencoder on test samples of  $\begin{bmatrix} \text{S} & \text{SimpW} & \text{ISE} & \text{ISE} \\ \text{ISE} & \text{ISE} & \text{ISE} & \text{ISE} \end{bmatrix}$ napping is not easily invertible we do not use it for the autoencoder. Instead, 4-vectors by another component containing the invariant mass, Ve allow for  $M = 10$  trainable linear combinations. These combined 4-vectors can <sub>tii</sub>on on the hadronically decaying massive particles. In the original LOLA appro the momenta  $k_j$  onto observable Lorentz scalars and related observables [13].

*in order to define a QCD-jet* 

๏ *Based on image and physics-*







# **Outlier detection in analysis**

E.g







Variational Autoencoder: Decorrelation fr[om](https://cds.cern.ch/record/2892677?ln=en) dijet mass E.g



# **Outlier detection in analysis**





# **Outlier detection in analysis**



# **Example for semi-visible jets**



### Normalizedautoencoders [:](https://indico.nikhef.nl/event/4875/contributions/20467/attachments/8294/11858/EBGAEs.pdf) Lund Graph autoencoders







## **Finding overdensities** • CURTAINS: Train an invertible [Raine et al: 2203.09470]





**Dijet invariant mass**



# **Weak classification without labels (CWoLa)**

**Dijet invariant mass**



### [Classification Without Labels](https://arxiv.org/abs/1708.02949)

• Lemma: "Given mixed S+B samples SB and SR, optimal classifier trained to distinguish SB and SR is also optimal for distinguishing S from B"

# **Weak classification without labels (CWoLa)**



Dijet invariant mass

**CWola hunting in ATLAS** 









#### Alternative approach: End-to-end DNN search

- How do we get around defining a signal hypothesis?
- What is alternate hypothesis to test reference?

Idea: Assume alternate model n(x|w) can be parametrised in terms of reference model n(x|R)

• [Let DNN parametrise alternative model](https://arxiv.org/pdf/1806.02350.pdf)

## **DNN likelihood**

**\**

$$
n(x | \overrightarrow{w}) = n(x | R)e^{f(x; \overrightarrow{w})}
$$
 Set of real f

$$
f(x; \overrightarrow{w}) = NN
$$

unctions

#### Alternative approach: End-to-end DNN search

- How do we get around defining a signal hypothesis?
- What is alternate hypothesis to test reference?

Idea: Assume alternate model n(x|w) can be parametrised in terms of reference model n(x|R)

• [Let DNN parametrise alternative model](https://arxiv.org/pdf/1806.02350.pdf)

## **DNN likelihood**

$$
n(x | \overrightarrow{w}) = n(x | R)e^{f(x; \overrightarrow{w})}
$$
 Set of real f

• Formulate loss as log likelihood. → Trained DNN **is** the maximum likelihood fit to data and reference log-ratio  $\rightarrow$  best approximate of true data distribution  $\alpha$  data and reference tog-ratio.<br> $\alpha$  hest annroximate of true data distribution parametrization, of the true underlying data distribution *n*(*x|*T)

$$
f(x; \overrightarrow{w}) = NN
$$

$$
f(x, \hat{\mathbf{w}}) \simeq \log \left[ \frac{n(x|\mathbf{T})}{n(x|\mathbf{R})} \right]
$$
 - True underlying data distribution

unctions

**\**

-tobs and  $f(x; \hat{w})$ 

**DNN loss function! Can be used to build Can be used to build** hypothesis test + p-value Data  $\rightarrow$  toys under R, repeat



### **OUTPUTS**

### **INPUTS**  - any high level features



 $f(x,\widehat{\mathbf{w}})$  $\widehat{\mathbf{w}}$  )  $\simeq$  log  $\left[\frac{n(x|T)}{n(x|R)}\right]$ *a* in the underlying data distribution. MC distribution True underlying data distribution  $\lceil n/(n|\mathbf{T}) \rceil$  and  $\lceil n/2 \rceil$ 

### **Hybrid approaches - NoVa**



#### *[Aurisano et al](https://iopscience.iop.org/article/10.1088/1748-0221/11/09/P09001)  [K. Sachdev](https://s3.cern.ch/inspire-prod-files-9/9e56e739150f481676c6b72ec6c08a59)*





### **Hybrid approaches - NoVa**



Efficiency of selecting electron neutrinos improved by 40%







## **Hybrid approaches - NoVa**

Efficiency of selecting electron neutrinos improved by 40%



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 $(c)$  A simulated electron is inserted in place of the muon to make an MRE event.





 $-200$ 



#### The New York Times

How the A.I. Race Began One Year of ChatGPT Key Figures in A.I. How A.I. Could Be Regulated A.I. and Chatbots >

#### **THE SHIFT**

### Maybe We Will Finally Learn More **About How A.I. Works**

Stanford researchers have ranked 10 major A.I. models on how openly they operate.

### Al Explainer: Foundation models and the 2 next era of Al

Published March 23, 2023



Figure 5: Representative sample of companies that have publicly stated that they are using, building, or enabling











• **Who:** No registration is required. All are welcome to attend!

### **Foundation Models**



### Heterogeneous detector Multi-modal input!







 $x = (x_1, x_2, \ldots, )$ 





NN

# **Too many models, too little learning?**

# **Discrimination**



### NN Something New

# **Metric Learning**

### NN Something New





# **Neural embedding**





NN Something New

## What if we really try to focus on this space



# **Neural embedding**

# Learning the space







•By looking at data, we can learn a lot

- Go over input piece by piece
- Analyze every aspect
- Compare every feature
- •Find distinctive style of the input
	- can be done e.g by looking for a deviation





# **Learning the space**

# Cat A



# Dog A



# Cat A



# Dog A



### **Augmented Cat A**



# Augmented Dog A





## Cat A



# Dog A



### Augmented Cat A



### **Augmented Dog A**









# Dog A



### **Augmented Cat A**



## **Augmented Dog A**



# **Physically motivated augmentations?**

• Minimizing and maximizing distances learns a space


### **Augmented Cat A**



### Cat A



### Cat B  $\dot{\mathcal{L}}$







## No class labels used in training! How do we augment detector data?

# **Physically motivated augmentations?**



## No class labels used in training! How do we augment detector data?



# **Physically motivated augmentations?**



Embedded Space can use any NN to embed

## **QM foundation models**



gluon

quark

H

 $\rightarrow$  embedding quantum mechanics into AI algorithm





 $x = (x_1, x_2, \ldots, x_n)$ 

## **Training 2: Fine tune for specific task (fast, small dataset, simulation)**

## Theorists N-D Space



## Capture Physics



NN

## **Capture** Physics

## (Graph) NN N-D Space

## We can replace the QCD theorist with a NN (And it works better)

# **Masked language modelling**

### **Next-token-prediction**

The model is given a sequence of words with the goal of predicting the next word.

Example: Hannah is a \_\_\_

Hannah is a sister Hannah is a *friend* Hannah is a marketer Hannah is a comedian

# **Self-supervised pre-training**

### Masked-languagemodeling

The model is given a sequence of words with the goal of predicting a 'masked' word in the middle.

Example Jacob [mask] reading

Jacob fears reading Jacob loves reading Jacob enjoys reading Jacob hates reading

# **Masked particle modelling**

 $-4$ 

 $-2$ 

0

2





# **Part2: ML in HEP**





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**QCD School 2024**

# Enfizürich

### *[CMS Offline Computing Results](https://twiki.cern.ch/twiki/bin/view/CMSPublic/CMSOfflineComputingResults)*



HL-LHC, Simulation of CMS HGCAL with 140 PU

# **ML for simulation**



### **CMS** Public Total CPU HL-LHC (2031/No R&D Improvements) fractions<br>2022 Estimates



### *[CMS Offline Computing Results](https://twiki.cern.ch/twiki/bin/view/CMSPublic/CMSOfflineComputingResults)*















Particle reconstruction from

Energy deposits→digital Energy deposits→digital signals→reconstructed by signals→reconstructed by the reconstruction software the reconstruction software  $\mathcal{H}(\mathcal{A})$  and  $\mathcal{H}(\mathcal{A})$  and  $\mathcal{H}(\mathcal{A})$  and  $\mathcal{H}(\mathcal{A})$ [Hard & Slow]

detector response

simulation [Hard & Slow]

Trajectory simulation

81%

### **DIGI+RECO**



Particle reconstruction from









### $\int f(x)g(x)dx$ **Diffusion models**















### *https://arxiv.org/pdf/2303.05376.pdf*



vibrant portrait painting of Salvador Dalí with a robotic half face

### *Dall-e 2 Dall-e 2*