Inverse Stability Problem in Beam Dynamics

Alexey Burov

Fermilab

HB Workshop, 10/10/2023 CERN



Inverse Stability Problem in Beam Dynamics

PHYSICAL REVIEW ACCELERATORS AND BEAMS

Highlights

Recent

Accepted

Special Editions

Authors

Referees

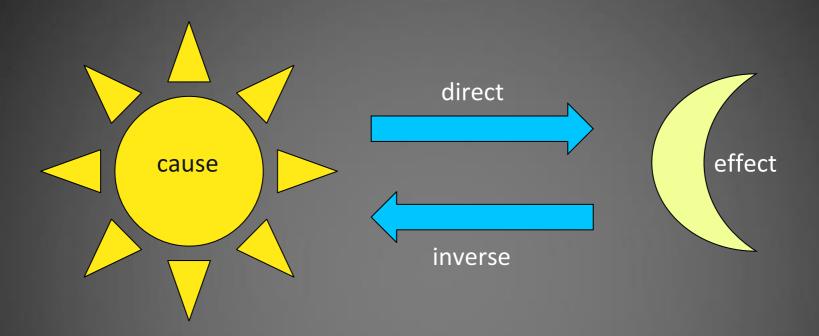
Sponsors

Open Access

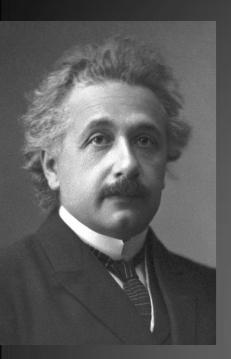
Inverse stability problem in beam dynamics

Alexey Burov

Phys. Rev. Accel. Beams 26, 082801 – Published 17 August 2023



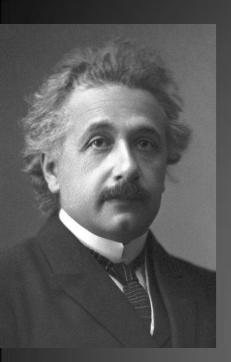




1879-1955

How a simplest unified description for gravity and inertia could look like?

1907-1915

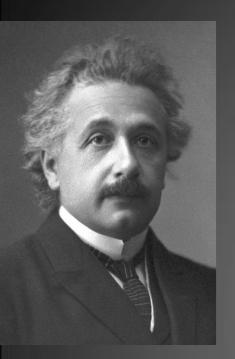


1879-1955

Inverse

How a simplest unified description for gravity and inertia could look like?

1907-1915



1879-1955

Inverse

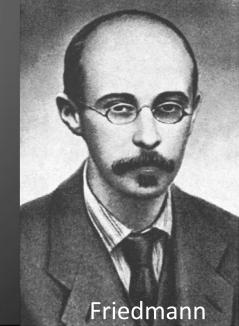
How a simplest unified description for gravity and inertia could look like?

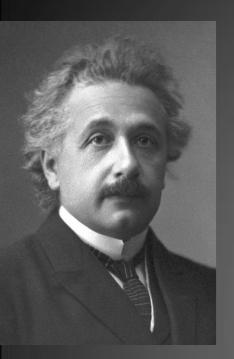
1907-1915

1888-1925

What could be a fate of the Universe, according to GR?

1922-1924





1879-1955

Inverse

How a simplest unified description for gravity and inertia could look like?

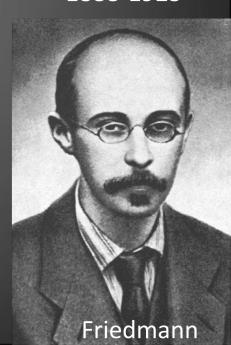
1907-1915

Direct

What could be a fate of the Universe, according to GR?

1922-1924

1888-1925



$$\dot{a}_k + i\Delta\omega_k a_k = -ig\bar{a}$$



$$\dot{a}_k + i\Delta\omega_k a_k = -ig\bar{a}$$

$$a_k \propto \exp(-i\nu t)$$



$$\dot{a}_k + i\Delta\omega_k a_k = -ig\bar{a}$$

$$a_k \propto \exp(-i\nu t)$$

$$a_k = \frac{g}{\nu - \Delta\omega_k} \bar{a}$$

$$\dot{a}_k + i\Delta\omega_k a_k = -ig\bar{a}$$

$$a_k \propto \exp(-i\nu t)$$

$$a_k = \frac{g}{\nu - \Delta\omega_k}\bar{a}$$

$$\left| \frac{g}{N} \sum_{k} \frac{1}{\nu - \Delta \omega_k} = 1 \right|$$

$$\dot{a}_k + i\Delta\omega_k a_k = -ig\bar{a}$$

$$a_k \propto \exp(-i\nu t)$$

$$a_k = \frac{g}{\nu - \Delta\omega_k}\bar{a}$$

$$\left| \frac{g}{N} \sum_{k} \frac{1}{\nu - \Delta \omega_k} = 1 \right|$$

$$-\left[\int \int dJ_x dJ_y \frac{J_x \frac{\partial F}{\partial J_x}}{\nu - \Delta\omega(J_x, J_y) + io}\right]^{-1} = g$$

1D, octupoles, Gaussian

alien nonlinearity

$$\Delta\omega(J_x,J_y)=kJ_y$$
 \Longrightarrow $\left[\int \mathrm{d}J_y rac{F_y(J_y)}{
u-J_y+io}
ight]^{-1}=g$



1D, octupoles, Gaussian

alien nonlinearity

$$\Delta\omega(J_x,J_y)=kJ_y$$
 \Longrightarrow $\left[\int \mathrm{d}J_y \frac{F_y(J_y)}{\nu-J_y+io}\right]^{-1}=g$

own nonlinearity

$$\Delta\omega(J_x,J_y) = kJ_x \longrightarrow F_y \rightarrow -J_x \frac{\partial F_x}{\partial J_x}$$

$$F_y \to -J_x \frac{\partial F_x}{\partial J_x}$$

Hereward rule



1D, octupoles, Gaussian

alien nonlinearity

$$\Delta\omega(J_x, J_y) = kJ_y$$

alien nonlinearity
$$k=1$$

$$\Delta\omega(J_x,J_y)=kJ_y \qquad \longmapsto \qquad \left[\int \mathrm{d}J_y \frac{F_y(J_y)}{\nu-J_y+io}\right]^{-1}=g$$

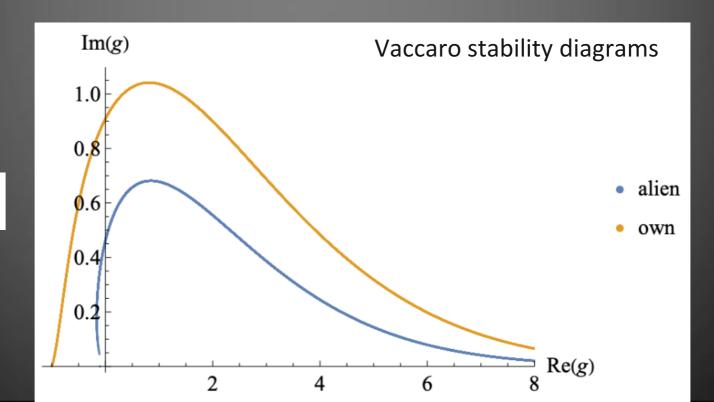
own nonlinearity

$$\Delta\omega(J_x,J_y) = kJ_x$$

$$F_{\mathcal{Y}} \to -J_{\mathcal{X}} \frac{\partial F_{\mathcal{X}}}{\partial J_{\mathcal{X}}}$$

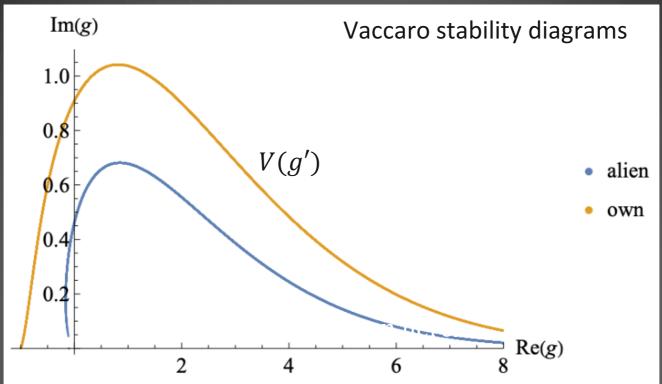
Hereward rule







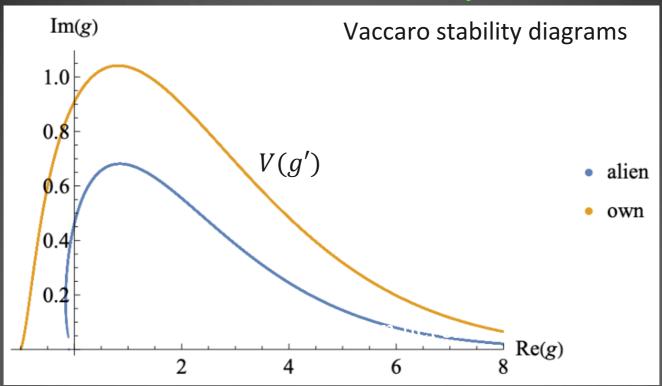
Direct and Inverse Stability Problems



Direct problem: $F(J) \rightarrow V(g')$

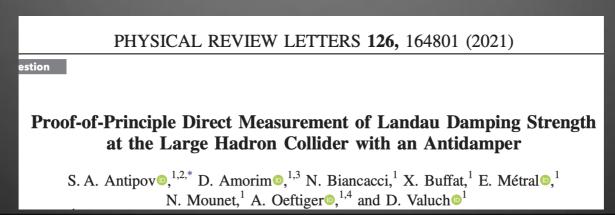
Inverse problem: $V(g') \rightarrow F(J)$

Direct and Inverse Stability Problems



Direct problem: $F(J) \rightarrow V(g')$

Inverse problem: $V(g') \to F(J)$; a pair of nonlinear integral equations.



Tails: easy

$$\int dJ_y \frac{F_y(J_y)}{\nu - J_y + io} \simeq \frac{1}{\nu} - \pi i \, F_y(\nu)$$

$$\Re g \simeq \nu; \ \Im g \simeq \pi \nu^2 F_y(\nu)$$

$$F_y(
u) \simeq \frac{\Im g(
u)}{\pi
u^2}$$

Core: fitting approach

$$A = \Delta \Re g_{
m FWHM} / \max \Im g$$

aspect ratio for V

$$F(J) \propto \left(1 - \frac{J}{J_0}\right)^n$$

 $nJ_0 > 0$

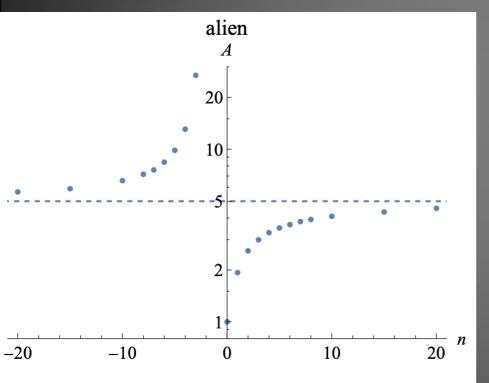


FIG. 2. Aspect ratio A of 1D stability diagram, the alien case, versus the power n of the binomial distribution function $\propto (1 - J/J_0)^n$, $nJ_0 > 0$. Note that $\lim_{n \to -2} A = \infty$. The dashed line marks the asymptote, $F(J) = J_0^{-1} e^{-J/J_0}$, $J_0 > 0$.

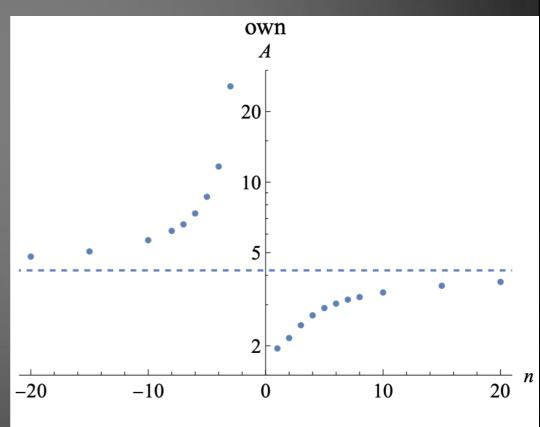


FIG. 3. The same as Fig. 2 for the own case. Here $\lim_{n\to-2}A=\infty$ as well.

Core: iterative 4-leg walk

- 1. Compute integrals with your initial guess F(J);
- 2. With that, make tables g'(v); g''(v);
- 3. Update your guess as $F(v) = -\pi^{-1}\Im g^{-1}(v)$;
- 4. Normalize the updated F(J) and go back to 1.

Convergency Limitation

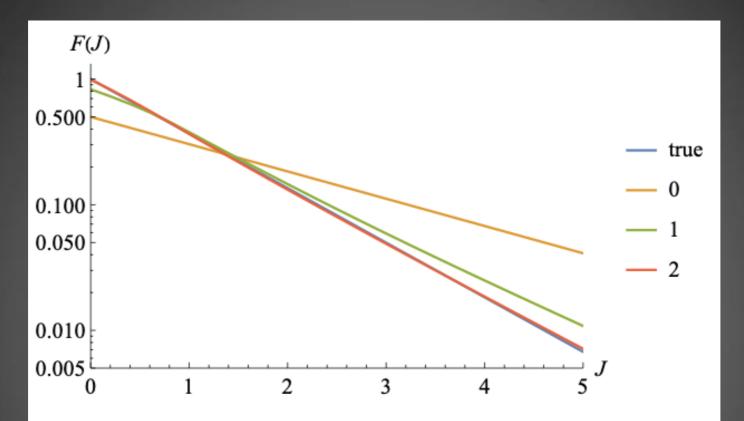


FIG. 4. An example of the iteration convergence for the alien case, $\nu_{\rm min}=0.7$. Here "true" means the distribution responsible for the "measured diagram"; "0" means the initial guess of the distribution, while "1" and "2" stand for the output distributions after the first and second four-leg moves of the algorithm. The latter is clearly very fast, but it becomes unstable at small actions, $J\lesssim 0.5$, for a slightly smaller border $\nu_{\rm min}$.

2D case $\Delta\omega(J_x,J_y)=k_xJ_x-k_yJ_y$

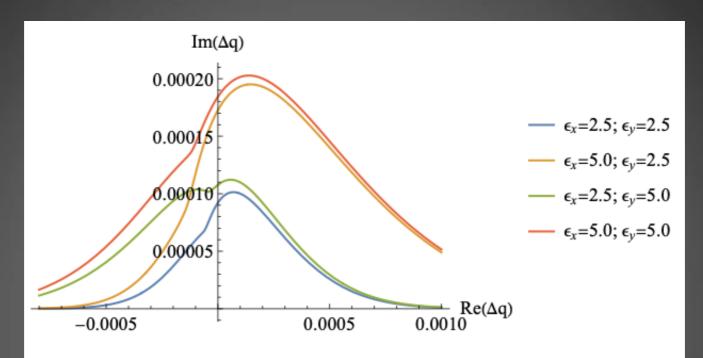


FIG. 7. Vaccaro diagrams calculated for a Gaussian bunch at the LHC top energy for 550A of the octupole current, yielding $k_x = 1.0 \cdot 10^{-4}$, $k_y = 0.7 \cdot 10^{-4}$ for the normalized rms emittances 2.5mm·mrad; for more details see Ref. [5]. Gaussian normalized rms emittances for each curve are shown.

Positive tune shifts mostly correspond to x, negative — to y. The problem is effectively factorized, reducing to 1D case.

Chromaticity effects

If $|g| \ll \omega_s$ then the gain is distributed between the headtail modes:

$$g \rightarrow g_l = g K_l(\zeta)$$
 with ζ = rms HT phase

$$K_l(\zeta) = \exp(-\zeta^2) \mathrm{I}_l(\zeta^2)$$
 for the longitudinally Gaussian case

$$K_l = \int_0^\infty \mathrm{J}_l^2(\zeta r) f(r) r \mathrm{d}r$$
 in general

$$\sum_{l=-\infty}^{\infty} K_l = 1$$

If $|g| \gg \omega_s$, $|\zeta|\omega_s$, the single rigid-bunch mode is formed, taking the entire gain.

Many thanks!