# Inverse Stability Problem in Beam Dynamics 

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HB Workshop, 10/10/2023 CERN

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## Direct and Inverse Problems



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How a simplest unified description
for gravity and inertia could look like?

1907-1915

1879-1955

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## Direct

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Harmonic oscillators with an antidamper

$$
\dot{a}_{k}+i \Delta \omega_{k} a_{k}=-i g \bar{a}
$$

Harmonic oscillators with antidamper

$$
\begin{gathered}
\dot{a}_{k}+i \Delta \omega_{k} a_{k}=-i g \bar{a} \\
a_{k} \propto \exp (-i \nu t)
\end{gathered}
$$

Harmonic oscillators with antidamper

$$
\dot{a}_{k}+i \Delta \omega_{k} a_{k}=-i g \bar{a}
$$

$$
a_{k} \propto \exp (-i \nu t)
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$$
a_{k}=\frac{g}{\nu-\Delta \omega_{k}} \bar{a}
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Harmonic oscillators with antidamper


## Harmonic oscillators with antidamper

$$
\dot{a}_{k}+i \Delta \omega_{k} a_{k}=-i g \bar{a}
$$

$$
a_{k} \propto \exp (-i \nu t)
$$

$$
a_{k}=\frac{g}{\nu-\Delta \omega_{k}} \bar{a}
$$

$$
\frac{g}{N} \sum_{k} \frac{1}{\nu-\Delta \omega_{k}}=1
$$

$$
-\left[\iint \mathrm{d} J_{x} \mathrm{~d} J_{y} \frac{J_{x} \frac{\partial F}{\partial J_{x}}}{\nu-\Delta \omega\left(J_{x}, J_{y}\right)+i o}\right]^{-1}=g
$$

## 1D, octupoles, Gaussian

alien nonlinearity
$\Delta \omega\left(J_{x}, J_{y}\right)=k J_{y}$

$$
\left[\int \mathrm{d} J_{y} \frac{F_{y}\left(J_{y}\right)}{\nu-J_{y}+i o}\right]^{-1}=g
$$

## 1D, octupoles, Gaussian

alien nonlinearity
$\Delta \omega\left(J_{x}, J_{y}\right)=k J_{y}$
$\longmapsto$

$$
\left[\int \mathrm{d} J_{y} \frac{F_{y}\left(J_{y}\right)}{\nu-J_{y}+i o}\right]^{-1}=g
$$

own nonlinearity
$\Delta \omega\left(J_{x}, J_{y}\right)=k J_{x} \longleftrightarrow$

$$
F_{y} \rightarrow-J_{x} \frac{\partial F_{x}}{\partial J_{x}}
$$

Hereward rule

## 1D, octupoles, Gaussian

$$
\Delta \omega\left(J_{x}, J_{y}\right)=k J_{y} \stackrel{k=1}{\square}
$$

$$
\left[\int \mathrm{d} J_{y} \frac{F_{y}\left(J_{y}\right)}{\nu-J_{y}+i o}\right]^{-1}=g
$$

own nonlinearity
$\Delta \omega\left(J_{x}, J_{y}\right)=k J_{x} \square$

$$
F_{y} \rightarrow-J_{x} \frac{\partial F_{x}}{\partial J_{x}}
$$



## Direct and Inverse Stability Problems



Direct problem: $F(J) \rightarrow V\left(g^{\prime}\right)$
Inverse problem: $V\left(g^{\prime}\right) \rightarrow F(J)$

## Direct and Inverse Stability Problems



Direct problem: $F(J) \rightarrow V\left(g^{\prime}\right)$
Inverse problem: $V\left(g^{\prime}\right) \rightarrow F(J)$; a pair of nonlinear integral equations.

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Proof-of-Principle Direct Measurement of Landau Damping Strength at the Large Hadron Collider with an Antidamper
S. A. Antipov©,\(^{1,2, *}\) D. Amorim \(\odot,{ }^{1,3}\) N. Biancacci, \({ }^{1}\) X. Buffat, \({ }^{1}\) E. Métral \({ }^{\circ},^{1}\)

\section*{Tails: easy}
\[
\int \mathrm{d} J_{y} \frac{F_{y}\left(J_{y}\right)}{\nu-J_{y}+i o} \simeq \frac{1}{\nu}-\pi i F_{y}(\nu)
\]
\[
\Re g \simeq \nu ; \Im g \simeq \pi \nu^{2} F_{y}(\nu)
\]

\section*{\(F_{y}(\nu) \simeq \frac{\Im g(\nu)}{\pi \nu^{2}}\)}

\section*{Core: fitting approach}

\section*{\(A=\Delta \Re g_{\text {FWHM }} / \max \Im g \quad\) aspect ratio for \(V\)}

\[
n J_{0}>0
\]



FIG. 2. Aspect ratio \(A\) of 1D stability diagram, the alien case, versus the power \(n\) of the binomial distribution function \(\propto\left(1-J / J_{0}\right)^{n}, n J_{0}>0\). Note that \(\lim _{n \rightarrow-2} A=\infty\). The dashed line marks the asymptote, \(F(J)=J_{0}^{-1} e^{-J / J_{0}}, J_{0}>0\).

FIG. 3. The same as Fig. 2 for the own case. Here \(\lim _{n \rightarrow-2} A=\infty\) as well.

\section*{Core: iterative 4-leg walk}
1. Compute integrals with your initial guess \(F(J)\);
2. With that, make tables \(g^{\prime}(v) ; g^{\prime \prime}(v)\);
3. Update your guess as \(F(v)=-\pi^{-1} \widetilde{\Im} g^{-1}(v)\);
4. Normalize the updated \(F(J)\) and go back to 1.

\section*{Convergency Limitation}


FIG. 4. An example of the iteration convergence for the alien case, \(\nu_{\min }=0.7\). Here "true" means the distribution responsible for the "measured diagram"; "0" means the initial guess of the distribution, while " 1 " and " 2 " stand for the output distributions after the first and second four-leg moves of the algorithm. The latter is clearly very fast, but it becomes unstable at small actions, \(J \lesssim 0.5\), for a slightly smaller border \(\nu_{\text {min }}\).


FIG. 7. Vaccaro diagrams calculated for a Gaussian bunch at the LHC top energy for 550A of the octupole current, yielding \(k_{x}=1.0 \cdot 10^{-4}, k_{y}=0.7 \cdot 10^{-4}\) for the normalized rms emittances \(2.5 \mathrm{~mm} \cdot \mathrm{mrad}\); for more details see Ref. [5]. Gaussian normalized rms emittances for each curve are shown.

Positive tune shifts mostly correspond to \(x\), negative - to \(y\). The problem is effectively factorized, reducing to 1D case.

\section*{Chromaticity effects}

If \(|g| \ll \omega_{s}\) then the gain is distributed between the headtail modes:
\[
g \rightarrow g_{l}=g K_{l}(\zeta) \quad \text { with } \zeta=\text { rms HT phase }
\]
```

K
K

```
\(\sum_{l=-\infty}^{\infty} K_{l}=1\)

If \(|g| \gg \omega_{S},|\zeta| \omega_{S}, \quad\) the single rigid-bunch mode is formed, taking the entire gain.

Many thanke!```

