Elliptic integrals

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- The simplest Feynman integrals evaluate to multiple polylogarithms
 - all one-loop integrals
 - many of the higher loop integrals we have calculated
- The next-to-simplest Feynman integrals involve an elliptic curve (content of this talk).
- There are even more complicated Feynman integrals (several elliptic curves, Calabi-Yau's, not covered here).

Fantastic Beasts and Where to Find Them

We do not have to go very far to encounter elliptic integrals in precision calculations: The simplest example is the two-loop electorn self-energy in QED:

There are three Feynman diagrams contributing to the two-loop electron self-energy in QED with a single fermion:



All master integrals are (sub-) topologies of the kite graph:



One sub-topology is the sunrise graph with three equal non-zero masses:



(Sabry, '62)

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Where is the elliptic curve?

For the sunrise it's very simple: The second graph polynomial defines an elliptic curve in Feynman parameter space:

$$-p^2 x_1 x_2 x_3 + (x_1 + x_2 + x_3) (x_1 x_2 + x_2 x_3 + x_3 x_1) m^2 = 0.$$

Indications for elliptic Feynman integrals:

- Maximal cut with a square root of a cubic or quartic polynomial
- Irreducible second-order differential operator
- Direct integration: An integration step with a square root of a cubic or quartic polynomial
- A differential equation in dlog form, with algebraic arguments, where not all square roots can be rationalised

Maximal cut:

- The elliptic curve from the maximal cut for the sunrise integral is not isomorphic to the one from Feynman parameters. They are isogenic, meaning one lattice is a sub-lattice of the other.
- Irreducible second-order differential operator:
 - Not every irreducibly second-order differential operator is the Picard-Fuchs operator of an elliptic curve. The ones which are are tabulated. (Movasati and Reiter, '09)

Direct integration/dlog form:

 This does not necessarily imply that the result cannot be expressed in polylogs.

Drell-Yan not rationalisable: Drell-Yan in polylogs: dlog not polylogarithmic:

Besier, Festi, Harrison, Naskrecki, '19; Heller, von Manteuffel, Schabinger, '19; Brown, Duhr, '20

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- Physics is about numbers.
- Best strategy depends on the number of kinematic variables the process depends on.
- For a physical observable we usually only need a few digits for the highest term in perturbation theory.
- For amplitudes we may need quadruple precision in singular limits (soft/collinear).
- For master integrals / special functions we may want O(100) O(1000) digits to use PSLQ.

From many scales / automated to fewer scales / fast evaluations:

- Purely numerical: Sector decomposition, numerical integration in loop momentum space.
- Semi-numerical: Unitarity methods, numerical integration of a differential equation
- Semi-analytical: Expansion in a small parameter
- Analytical: Reduction to standarised special functions

This talk: Reduction to standarised special functions, which we can evaluate fast to O(100) - O(1000) digits.

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Section 1

Algebraic curves of genus zero and one

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- $\bullet \ \, \text{Ground field} \ \, \mathbb{C}$
- Algebraic curve in \mathbb{CP}^2 defined by a homogeneous polynomial P(x, y, z):

$$P(x,y,z) = 0$$

We usually work in the chart z = 1.

 If the curve is smooth and d the degree of P the genus of the curve is given by

$$g = \frac{1}{2}(d-1)(d-2).$$

Definition (Elliptic curve over \mathbb{C})

An algebraic curve in \mathbb{CP}^2 of genus one with one marked point.

Example (Weierstrass normal form)

In the chart z = 1:

$$y^2 = 4x^3 - g_2x - g_3$$

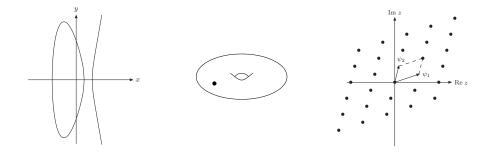
Example (Quartic form)

In the chart z = 1:

$$y^2 = (x-x_1)(x-x_2)(x-x_3)(x-x_4)$$

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Three shades of an elliptic curve



Complex algebraic curve $y^2 = 4x^3 - g_2x - g_3$

Real Riemann surface of genus one with one marked point

Complex plane modulo lattice: \mathbb{C}/Λ

Example

The Legendre form:

$$y^2 = x(x-1)(x-\lambda)$$

The periods are

$$\psi_1 = 2\int_0^\lambda \frac{dx}{y} = 4K\left(\sqrt{\lambda}\right) \qquad \psi_2 = 2\int_1^\lambda \frac{dx}{y} = 4iK\left(\sqrt{1-\lambda}\right)$$

K(x): complete elliptic integral of the first kind

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Notation

Convention: Normalise $(\psi_2,\psi_1) \to (\tau,1),$ where

$$\tau = \frac{\Psi_2}{\Psi_1}$$

and require $\operatorname{Im}(\tau) > 0$.

Definition (The complex upper half-plane)

$$\mathbb{H} = \{\tau \in \mathbb{C} | \operatorname{Im}(\tau) > 0\}$$

Definition (The nome squared)

$$ar{q} = e^{2\pi i au}$$

For $\tau \in \mathbb{H}$ we have $|\bar{q}| < 1$.

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Section 2

Moduli spaces

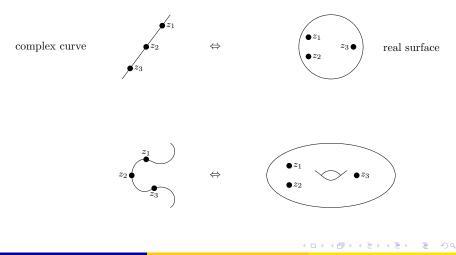
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Moduli spaces

 $\mathcal{M}_{g,n}$: Space of isomorphism classes of smooth (complex, algebraic) curves of genus g with n marked points.



Genus 0: dim $\mathcal{M}_{0,n} = n - 3$. Sphere has a unique shape Use Möbius transformation to fix $z_{n-2} = 1$, $z_{n-1} = \infty$, $z_n = 0$ Coordinates are $(\mathbf{z}_1, ..., \mathbf{z}_{n-3})$

Genus 1: dim
$$\mathcal{M}_{1,n} = n$$
.
One coordinate describes the shape of the torus
Use translation to fix $z_n = 0$
Coordinates are $(\tau, z_1, ..., z_{n-1})$

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Section 3

Iterated integrals

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For $\omega_1, ..., \omega_k$ differential 1-forms on a manifold *M* and $\gamma : [0, 1] \to M$ a path, write for the pull-back of ω_j to the interval [0, 1]

1

$$\gamma_j^*(\lambda) \, d\lambda = \gamma^* \omega_j.$$

The iterated integral is defined by

$$I_{\gamma}(\omega_{1},...,\omega_{k};\lambda) = \int_{0}^{\lambda} d\lambda_{1}f_{1}(\lambda_{1})\int_{0}^{\lambda_{1}} d\lambda_{2}f_{2}(\lambda_{2})...\int_{0}^{\lambda_{k-1}} d\lambda_{k}f_{k}(\lambda_{k}).$$

Chen '77

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- Manifold *M*: kinematic space, coordinates are the kinematic variables.
- γ(0): Boundary point
- $\gamma(1)$: Point, where we would like to evaluate the integral.

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• Defined by giving the ω 's.

• Alternatively, we may specify primitives of the differential one-forms:

$$\omega = d\Omega$$
.

 Ω is related to the symbol.

May do this for genus zero and genus one.

We are interested in differential one-forms, which have only simple poles:

$$\omega^{\mathrm{mpl}}(z_j) = \frac{dy}{y-z_j}.$$

Multiple polylogarithms:

$$G(z_1,...,z_k;y) = \int_0^y \frac{dy_1}{y_1-z_1} \int_0^{y_1} \frac{dy_2}{y_2-z_2} \dots \int_0^{y_{k-1}} \frac{dy_k}{y_k-z_k}, \quad z_k \neq 0$$

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- Coordinates are $(\tau, z_1, ..., z_{n-1})$
- Decompose an arbitrary path along $d\tau$ and dz_i
- Two classes of iterated integrals:
 - Integration along z
 - 2 Integration along τ
- What are the differential one-forms we want to integrate?

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• From modular forms ($f_k(\tau)$ modular form):

$$\mathfrak{W}_k^{\mathrm{modular}} = 2\pi i f_k(\tau) d\tau$$

Prom the Kronecker function:

$$\omega_{k}^{\text{Kronecker}} = (2\pi i)^{2-k} \left[g^{(k-1)}(z,\tau) \, dz + (k-1) \, g^{(k)}(z,\tau) \, \frac{d\tau}{2\pi i} \right]$$

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A meromorphic function $f : \mathbb{H} \to \mathbb{C}$ is a modular form of modular weight k for $SL_2(\mathbb{Z})$ if

f transforms under modular transformations as

$$f\left(rac{a au+b}{c au+d}
ight)=(c au+d)^k\cdot f(au) \qquad ext{for } \gamma=\left(egin{array}{cc} a & b \ c & d \end{array}
ight)\in \mathrm{SL}_2(\mathbb{Z})$$

- 2) *f* is holomorphic on \mathbb{H} ,
- *f* is holomorphic at $i\infty$.

Modular forms for congruence subgroups: Require transformation properties only for subgroup Γ (plus holomorphicity on \mathbb{H} and at the cusps).

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Define the first Jacobi theta function $\theta_1(z, \bar{q})$ by

$$\theta_1(z,\bar{q}) = -i \sum_{n=-\infty}^{\infty} (-1)^n \bar{q}^{\frac{1}{2}(n+\frac{1}{2})^2} e^{i\pi(2n+1)z}.$$

The Kronecker function $F(z, \alpha, \tau)$:

$$F(z,\alpha,\tau) = \theta'_{1}(0,\bar{q}) \frac{\theta_{1}(z+\alpha,\bar{q})}{\theta_{1}(z,\bar{q})\theta_{1}(\alpha,\bar{q})} = \frac{1}{\alpha} \sum_{k=0}^{\infty} g^{(k)}(z,\tau) \alpha^{k}$$

We are interested in the coefficients $g^{(k)}(z,\tau)$ of the Kronecker function.

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The coefficients $g^{(k)}(z,\tau)$ of the Kronecker function

 \bar{q} -expansion:

$$\begin{split} g^{(0)}(z,\tau) &= 1, \\ g^{(1)}(z,\tau) &= -2\pi i \left[\frac{1+\bar{w}}{2(1-\bar{w})} + \overline{E}_{0,0}(\bar{w};1;\bar{q}) \right], \\ g^{(k)}(z,\tau) &= -\frac{(2\pi i)^k}{(k-1)!} \left[-\frac{B_k}{k} + \overline{E}_{0,1-k}(\bar{w};1;\bar{q}) \right], \qquad k > 1, \end{split}$$

where $\bar{w} = \exp(2\pi i z)$, B_k denotes the k-th Bernoulli number and

$$\overline{\mathrm{E}}_{n;m}(\bar{w};\bar{v};\bar{q}) = \mathrm{ELi}_{n;m}(\bar{w};\bar{v};\bar{q}) - (-1)^{n+m} \mathrm{ELi}_{n;m}(\bar{w}^{-1};\bar{v}^{-1};\bar{q})$$
$$\mathrm{ELi}_{n;m}(\bar{w};\bar{v};\bar{q}) = \sum_{j=1}^{\infty} \sum_{k=1}^{\infty} \frac{\bar{w}^{j}}{j^{n}} \frac{\bar{v}^{k}}{k^{m}} \bar{q}^{jk}$$

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Iterated integrals on $\mathcal{M}_{1,n}$: Integration along z

Differential one-forms:

$$\omega_k^{\text{Kronecker},z}(z_j,\tau) = (2\pi i)^{2-k} g^{(k-1)}(z-z_j,\tau) dz$$

Elliptic multiple polylogarithms:

$$\widetilde{\Gamma}\begin{pmatrix}n_{1} & \dots & n_{r} \\ z_{1} & \dots & z_{r} \\ \vdots & z_{r} \\ \vdots & z_{r} \\ \vdots \\ z_{1} \\ \vdots \\ z_{r} \\$$

Broedel, Duhr, Dulat, Tancredi, '17

• $\tau = const$

- meromorphic version, only simple poles
- not double periodic!

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Comments on elliptic multiple polylogarithms

- There exist non-equivalent definitions of elliptic multiple polylogarithms.
- Desirable properties are
 - double periodic
 - meromorphic
 - only simple poles
- It is not possible to have all three properties.
 - double periodic + meromorphic Levin. Racinet. '07
 - double periodic + only simple poles Brown, Levin, '11
 - meromorphic + only simple poles
 Broedel, Duhr, Dulat, Tancredi, '17

More variants of elliptic polylogarithms

Some authors consider iterated integrals of the form

$$\int_{0}^{y_0} dy f(y) G(z_1,\ldots,z_{k-1};y),$$

where only the outermost integration is non-polylogarithmic, for example

$$f(y) = \frac{1}{\sqrt{(y-z_1)(y-z_2)(y-z_3)(y-z_4)}}$$

Can be reduced to $\widetilde{\Gamma}({}^{n_1}_{z_1} \dots {}^{n_r}_{z_r}; z; \tau)$.

Remiddi, Tancredi, '17; Bourjaily, McLeod, Spradlin, von Hippel, Wilhelm, '17; Hidding, Moriello, '17;

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Iterated integrals on $\mathcal{M}_{1,n}$: Integration along τ

Differential one-forms:

$$\begin{split} \omega_k^{\text{Kronecker},\tau}(z_j) &= \frac{(k-1)}{\left(2\pi i\right)^{k-2}}g^{(k)}\left(z_j,\tau\right)\frac{d\tau}{2\pi i}\\ &= \frac{(k-1)}{\left(2\pi i\right)^k}g^{(k)}\left(z_j,\tau\right)\frac{d\bar{q}}{\bar{q}} \end{split}$$

Integrate in q

- No poles in $0 < |\bar{q}| < 1$.
- Possibly a simple pole at $\bar{q} = 0$ ("trailing zero")

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- It is advantageous to integrate in τ:
 - Analytic expressions shorter
 - Easier to evaluate numerically
- Boundary condition at $\tau = i\infty$:
 - Elliptic curve degenerates, geometric genus equals zero
 - Feynman integrals expressible in terms of multiple polylogarithms

Section 4

Modular transformations

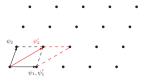
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Modular transformations

Let's assume we choose as periods (ψ_2, ψ_1) , while somebody else made the choice (ψ_2', ψ_1') .



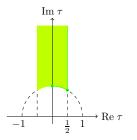
The two choices are related by a (2 \times 2)-matrix γ :

$$\left(\begin{array}{c} \psi_2' \\ \psi_1' \end{array} \right) \ = \ \gamma \left(\begin{array}{c} \psi_2 \\ \psi_1 \end{array} \right)$$

This is called a modular transformation.

Transformation should be invertible: $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(\mathbb{Z})$

Modular transformations



By a modular transformation we may map τ to the fundamental domain, resulting in

$$|ar{q}|~\leq~e^{-\pi\sqrt{3}}pprox$$
 0.0043

resulting in a fast converging series.

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Let us now consider the transformation on $\mathcal{M}_{1,n}$

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Modular transformations

Let f be a modular form of modular weight k for a congruence subgroup of level N and consider the coordinate transformation

$$au ~=~ \gamma^{-1}\left(au'
ight) ~=~ rac{a au'+b}{c au'+d}, \qquad \gamma^{-1}~\in~ \Gamma.$$

We have

$$\begin{array}{lll} (f;\tau) & = & 2\pi i \int\limits_{i\infty}^{\tau} f\left(\tilde{\tau}\right) d\tilde{\tau} \\ & = & 2\pi i \int\limits_{\gamma(i\infty)}^{\gamma(\tau)} \left(c\tilde{\tau}'+d\right)^{k-2} \underbrace{\left(f|_{k}\gamma^{-1}\right)(\tilde{\tau}')}_{\in \mathcal{M}_{k}(\Gamma_{N})} d\tilde{\tau}'. \end{array}$$

For $k \neq 2$ we pick up a power of the automorphic factor $(c\tilde{\tau}' + d)$ and leave the space of iterated integrals of modular forms!

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In the case of multiple polylogarithms

$$G(z_1,\ldots,z_k;y)$$

the transformations

$$y' = 1 - y, \quad y' = \frac{1}{y}, \quad y' = \frac{1}{1 - y}, \quad y' = \frac{1 - y}{1 + y},$$

don't leave the space of multiple polylogarithms.

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Let $J = (J_1, J_2, ...)$ denote a basis of master integrals of uniform weight. The definition of *J* may depend on the choice of the periods.

Solution:

In order not to leave the space of iterated integrals on $\mathcal{M}_{1,n}$ a base transformation

$$\tau' = \gamma(\tau), \qquad z'_j = \frac{z_j}{c\tau+d},$$

needs to be accompanied by a fibre transformation

$$J' = UJ.$$

S.W., '20

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Drawback:

As a modular transformation is always accompanied by a fibre transformation, there is no black-box numerical evaluation algorithm just for iterated integrals of $\omega^{modular}$ and $\omega^{Kronecker}$.

Feynman integrals are linear combinations of iterated integrals of $\omega^{modular}$ and $\omega^{Kronecker}$.

Feynman integrals transform nicely, individual iterated integrals not.

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Section 5

Numerics

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GiNaC

GiNaC was initiated in 1999 by Ch. Bauer, A. Frink and R. Kreckel at the University of Mainz.



Despite it's name, it is a computer algebra system. Allows symbolic calculations in C++.

Shipped with major linux distributions (Ubuntu, Debian, Fedora, ...).

```
Available at http://www.ginac.de.
```

GiNaC contains a sub-package to evaluate multiple polylogarithms and elliptic multiple polylogarithms with arbitrary precision.

J. Vollinga, S.W., (2004); M. Walden, S.W., (2020)

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ginsh - GiNaC Interactive Shell (GiNaC V1.8.0)
__, _____ Copyright (C) 1999-2020 Johannes Gutenberg University Mainz,
(__) * | Germany. This is free software with ABSOLUTELY NO WARRANTY.
._) i N a C | You are welcome to redistribute it under certain conditions.
<------' For details type `warranty;'.</pre>

```
Type ?? for a list of help topics.
> Digits=50;
50
> evalf(G({0,0,1},1));
-1.202056903159594285399738161511449990764986292340498881794
```

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Elliptic integration kernels

• Kernels related to $g^{(k)}(z,\tau)$:

Kronecker_dtau_kernel(k, z_j); Kronecker_dz_kernel(k, z_j, tau);

• Kernels related to modular forms:

Eisenstein_kernel(k, a, b, K); modular_form_kernel(k, P, qbar);

• Kernels related to ELi-functions:

ELi_kernel(n, m, x, y); Ebar_kernel(n, m, x, y);

• User-defined kernels:

```
user_defined_kernel(f, y);
```

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```
Digits = 50;
ex tau = 10*I;
ex qbar = evalf(exp(2*Pi*I*tau));
ex z = 0.9;
ex g_2 = Kronecker_dtau_kernel(2,z);
ex g_3 = Kronecker_dtau_kernel(3,z);
```

std::cout << iterated_integral(lst{g_3,g_2},qbar).evalf() << std::endl;</pre>

```
3.2253571394850843286565907071596312651610339124775388346726E-27
-4.370890856300573854123107098377978052316020623730771456153E-85*I
```

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Section 6

Conclusions

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High precision numerical values for elliptic Feynman integrals:

- Standarised special functions: Iterated integrals of $\omega_k^{\text{modular}}$ and $\omega_k^{\text{Kronecker}}$ on the moduli space $\mathcal{M}_{1,n}$.
- Choose an integration path, that first stays on the hypersurface $\bar{q} = 0$ and then integrate for $z_j = \text{const}$ in \bar{q} .
 - Integration on the hypersurface $\bar{q} = 0$ gives multiple polylogarithms.
 - Integration along τ (or \bar{q}) gives elliptic iterated integrals.
- Advantages:
 - There are no poles along the integration path for the \bar{q} -integration, except possibly at $\bar{q} = 0$ ("trailing zero").
 - By a modular transformation we can always achieve $|\bar{q}| \le 0.0043$. This gives a very fast converging series expansion.