Action-Angle formalism for geodesic motion in Kerr spacetime

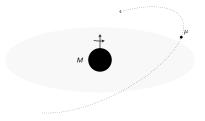
Morteza Kerachian

Astronomical Institute of the CAS Prague, Czech Republic

12th Iberian Gravitational Waves Meeting June 6, 2022

Outline

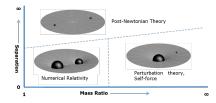
- What is the EMRI?
- Two timescale analysis.
- Action-angle (AA) formalism.
- Canonical perturbation theory.
- Kerr geodesic Hamiltonian in the AA variables.



E つへで 2/16

What is an EMRI? and why EMRI's?

 Extreme mass ratio inspirals (EMRI's): a primary supermassive BH M, and a secondary much lighter compact stellar object μ.



- The mass ratio $q = \frac{\mu}{M} \sim (10^{-7} 10^{-4}).$
- Inspirals occurs slowly, on the time scale $\tau \sim 1/q$.
- Secondary spends $\sim 10^4 10^5$ orbits within LISA band.
- EMRI's are one the most promising sources of gravitational for LISA.
- Detailed map of the supermassive BH.

Modeling the EMRI's

To model an EMRI, we use the two time scale approximation. (T. Hinderer & E E. Flanagan, PRD, 2008)

- The slow time scale: evolution of the constants of motion $\{E, L_z, Q\}$.
- The fast time scale: orbital phases of the secondary.

In the action-angle variables

- Constants of motion $J_i = \{J_t, J_r, J_{\theta}, J_{\phi}\}$
- Fundamental frequencies of geodesic motion $\Omega_r, \Omega_{\theta}, \Omega_{\phi}$.

From canonical perturbation theory, we derived a **closed form** expressions for the actions!

Hamiltonian in action-angle variables

For a bounded motion when the system is integrable, there exist a canonical transformation

$$(\boldsymbol{q}, \boldsymbol{p}) \xrightarrow{\mathsf{CT}} (\boldsymbol{\psi}, \boldsymbol{J}) \implies H(\boldsymbol{q}, \boldsymbol{p}) \to H_{AA}(\boldsymbol{J})$$

where

$$J_i = \frac{1}{2\pi} \oint p_i dq_i$$

From Hamilton equations:

$$\begin{split} \dot{J}_i &= -\frac{\partial H_{AA}}{\partial \psi_i} = 0 \qquad \Longrightarrow \qquad J_i(\lambda) = Const. \\ \dot{\psi}_i &= \frac{\partial H_{AA}}{\partial J_i} = \Omega_i \qquad \Longrightarrow \qquad \psi_i(\lambda) = \Omega_i \lambda + \psi_i(0) \end{split}$$

Geodesic motion in Kerr background in AA variables

Hamiltonian In the Boyer-Lindquist coordinates & Mino time

$$H_{\lambda} = \frac{1}{2} \left(\Delta p_r^2 - \frac{((r^2 + a^2) p_t + aL_z)^2}{\Delta} + r^2 \right) \\ + \frac{1}{2} \left(p_{\theta}^2 + a^2 \cos^2 \theta + \frac{(L_z + a \sin^2 \theta p_t)^2}{\sin^2 \theta} \right)$$

Mino time is applied to separate the radial and angular parts.

$$J_{t} = \frac{1}{2\pi} \oint p_{t} dt = -E$$

$$J_{r} = \frac{1}{2\pi} \oint p_{r} dr =?$$

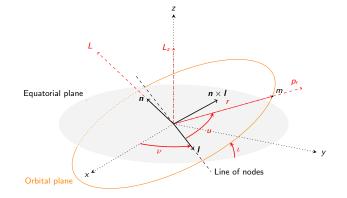
$$J_{\theta} = \frac{1}{2\pi} \oint p_{\theta} d\theta =?$$

$$J_{\phi} = \frac{1}{2\pi} \oint p_{\phi} d\phi = L_{z}$$

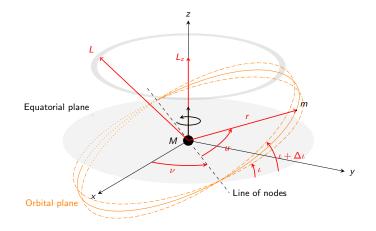
Polar-nodal coordinates

Canonically transformed to polar-nodal coordinate

$$\{r, \theta, \phi, p_r, p_\theta, p_\phi\} \rightarrow \{r, u, \nu, p_r, L, L_z\}$$



Kerr geodesics in polar-nodal coordinates



Canonical perturbation theory

In the Birkhoff normal form theory we assume:

$$H^{(0)}(\psi_i, J_i) = Z_0(J_i) + \sum_{k=1}^N \epsilon^k H_k^{(0)}(\psi_i, J_i),$$

• We apply the Lie series to the Hamiltonian:

$$H^{(1)} = L_{\chi} H^{(0)} = Z_0(J_i) + \epsilon Z_1^{(0)}(J_i) + \epsilon^2 H_2^{(0)}(\psi_i, J_i) + \mathcal{O}(\epsilon^3),$$

where
$$L_{\chi}f = \sum_{k=0}^{\infty} \frac{\epsilon^k}{k!} \mathcal{L}_{\chi}^k f$$
 and $\mathcal{L}_{\chi}f = \{f, \chi\}$.
In a similar fashion, we can apply *n* Lie series:

$$H^{(n)} = L_{\chi_n}^n L_{\chi_{n-1}}^{n-1} \dots L_{\chi_2}^2 L_{\chi} H^{(0)}$$

= $Z_0(J_i) + \epsilon Z_1^{(n)}(J_i) + \dots \epsilon^n Z_n^{(n)}(J_i).$

Why Lie series?

- Lie series is are canonical transformations.
- We can express the old variables in terms of the new variables:

$$\psi_i^{(0)} = L_{\chi_n}^n L_{\chi_{n-1}}^{n-1} \dots L_{\chi_2}^2 L_{\chi} \psi_i^{(n)},$$

$$J_i^{(0)} = L_{\chi_n}^n L_{\chi_{n-1}}^{n-1} \dots L_{\chi_2}^2 L_{\chi} J_i^{(n)},$$

New variables in terms of the old ones:

$$\psi_i^{(n)} = L_{-\chi} L_{-\chi_2}^2 \dots L_{-\chi_{n-1}}^{n-1} L_{-\chi_n}^n \psi_i^{(0)},$$

$$J_i^{(n)} = L_{-\chi} L_{-\chi_2}^2 \dots L_{-\chi_{n-1}}^{n-1} L_{-\chi_n}^n J_i^{(0)}.$$

The resulting relations from the Lie series are in closed form!
 There are simple analytical relations without any integral,
 Hypergeometric function and etc.

Results

- We applied 10 canonical transformation for the radial part and 7 canonical transformation for the angular part.
- We derived the new Hamiltonian in the action-angle variables:

$$H_{AA}(J_i) = C_1 J_t + C_2 J_r + C_3 J_L + C_4 J_z$$

From the Hamilton equations the radial and angular frequencies are obtained:

$$\Omega_r = \frac{\partial H_{AA}}{\partial J_r}, \qquad \Omega_L = \frac{\partial H_{AA}}{\partial J_L}.$$

We derived the relative errors of the new actions and frequencies with their numerical values.

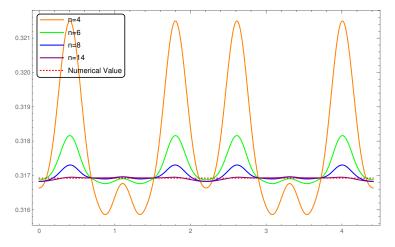


Figure: The radial action J_r in terms of the old variables for different numbers of the CT for a system with a = 0.99, e = 0.4, p = 10, and the initial inclination $\iota_0 = \pi/8$.

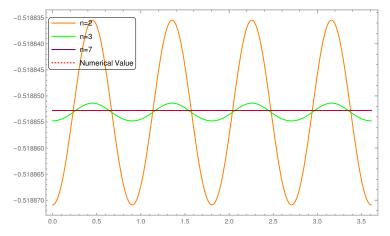


Figure: The angular action J_L in terms of the old variables for different numbers of the CT for a system with a = 0.99, e = 0.4, p = 10, and the initial inclination $\iota_0 = \pi/8$.

<□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Accuracy of the new system

• The relative errors for a system $\{p,\iota_0\}=\{10,\pi/8\}$ for the Kerr parameter $0 < a \leq 0.99$ and the eccentricity $0 < e \leq 0.5$ are

maximum error
$$\implies 0.1 \le e \le 0.5$$

 $\mathcal{O}(\Delta J_r)_{max} \Longrightarrow \{10^{-10}, 10^{-4}\}$
 $\mathcal{O}(\Delta \Omega_r)_{max} \Longrightarrow \{10^{-12}, 10^{-4}\}$
 $\mathcal{O}(\Delta J_L)_{max} \Longrightarrow \{10^{-11}, 10^{-9}\},$
 $\mathcal{O}(\Delta \Omega_L)_{max} \Longrightarrow \{10^{-12}, 10^{-8}\}$

<□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

(phase shift error \times number of cycles) $\sim 0.1 \mathrm{radian}$

Further researches & summary

- EMRI's can be detected by LISA.
- Two timescale approximation provides efficient framework for generation waveforms.
- From Lie series we derived the Hamiltonian in the action variables.
- Our expressions are in closed forms with sufficient accuracy for LISA.

< □ ▶ < □ ▶ < ≧ ▶ < ≧ ▶ ≧ ♪ ○ ○ 15/16

work in progress

- Use Teukolsky equation to generates the fluxes.
- Study the whole inspirals in the LISA band.

Thanks for your attention!

▲□▶ ▲圖▶ ▲ 볼▶ ▲ 볼▶ 볼 · 의 역 · 16/16