POINT CLOUD DEEP LEARNING METHODS FOR PION RECONSTRUCTION IN THE ATLAS DETECTOR



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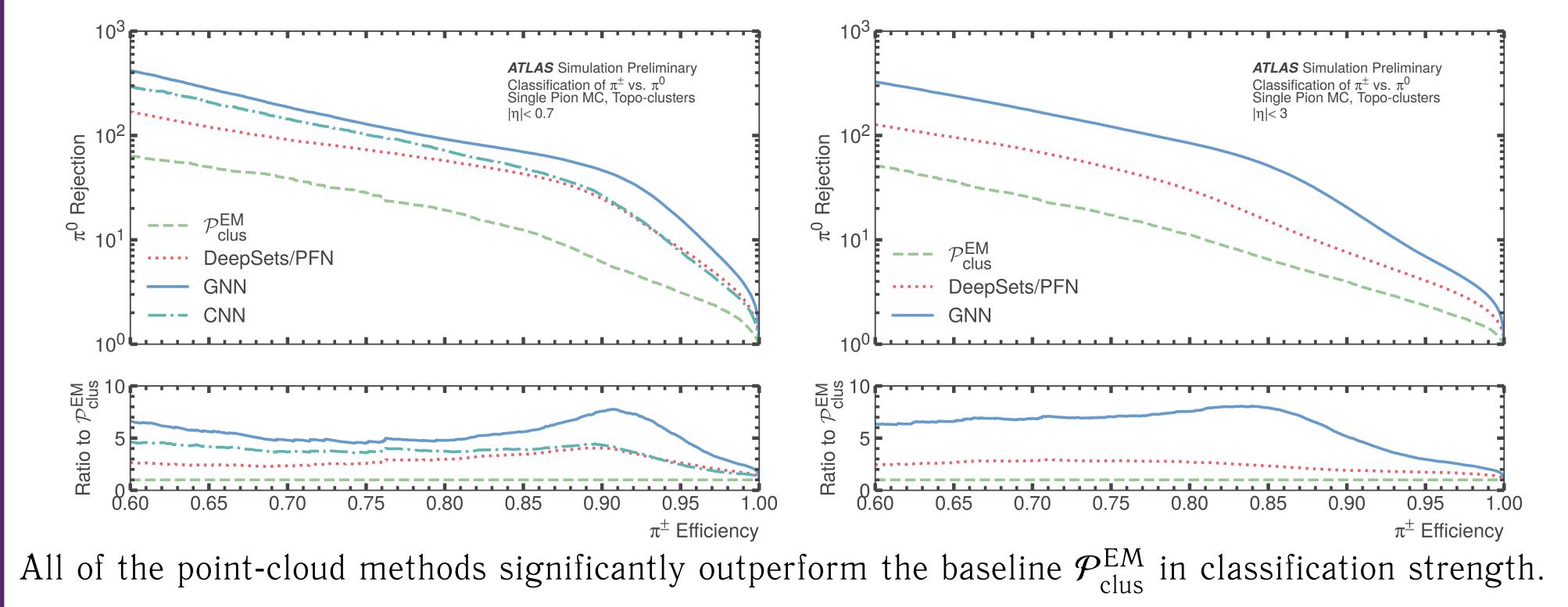
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Overview

The reconstruction and calibration of hadronic final states in the ATLAS detector present complex experimental challenges. One important aspect of the reconstruction chain is the identification and calibration of energy deposited in the calorimeters by charged and neutral pions, to account for the calorimeter systems' different responses to electromagnetic (EM) and hadronic showers. Building on previous work with neural networks [1], we present results from using point cloud-based methods - specifically Graph Neural Networks (GNNs), Deep Sets and *Transformer* methods – to identify and calibrate energy deposits, as alternatives to the existing Local Cell Weighting (LCW) method [2]. These point cloud methods are also presented in a corresponding note [3].

Classification Performance

Here, we show charged vs. neutral pion classification performance, using only cluster (calorimeter) information. The CNN shown in the left figure corresponds to results from Ref. [1].



Inputs & Point Clouds

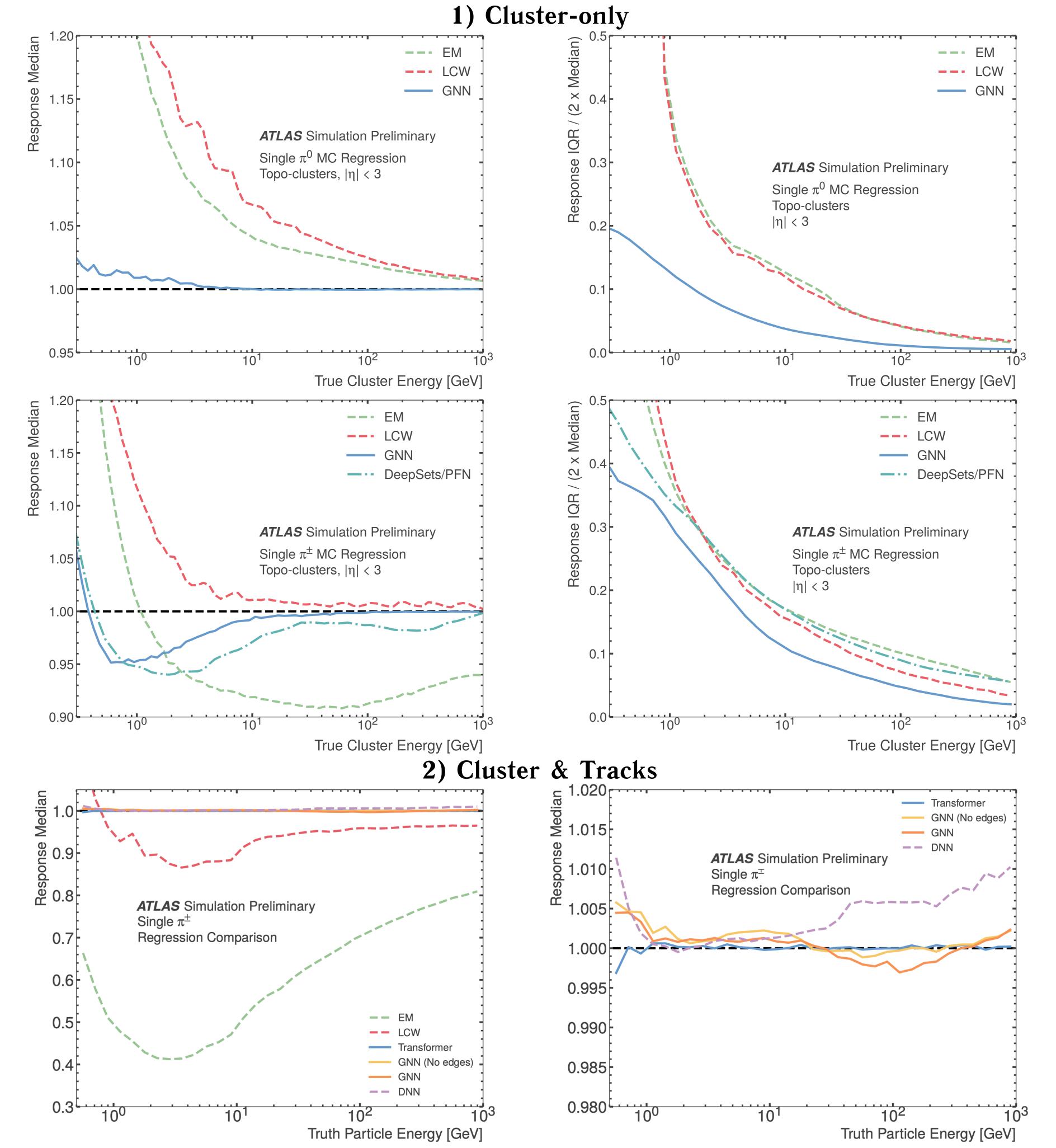
These methods use *topo-clusters* and *tracks* as inputs. Topo-clusters are clusters of calorimeter cells seeded and built using signal significance thresholds, and tracks are reconstructed from hits recorded in the silicon tracker.

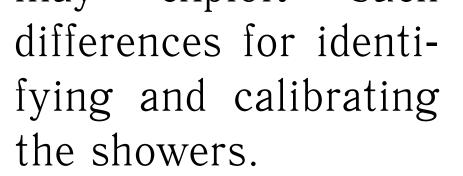
hadronic EM and typically showers differ in shape, and may produce multiple such clusters. These methods, which operate on cell-level data, may exploit such

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			0				
	0	0	2	0	0		
	0	2	2	2	0		
	0	2	4	2	0	0	
	0	2	2	2	2	0	
	0	0	0	0	0	0	

Calibration Performance

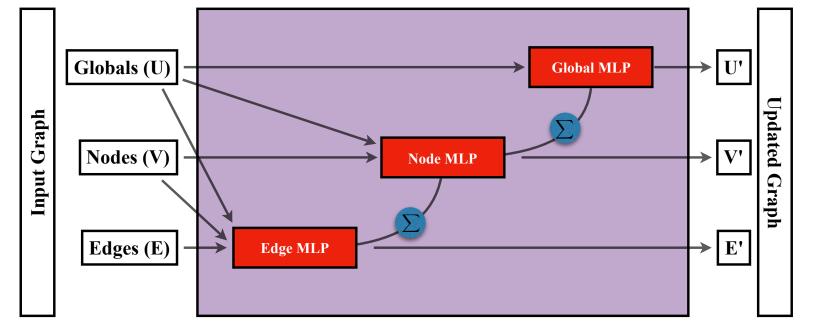
Here, we show energy calibration performance, for charged and neutral pions – a separate instance of each network is trained for each of the two types – for networks using only cluster information, as well as those using both clusters and tracks as input.





Network Designs

GNN: Each topo-cluster is represented as a graph whose nodes correspond to its calorimeter cells. Multi-layer perceptrons act separately on edge, node, and global features to update the graph from one layer to the next.



Deep Sets: An implementation of the *Deep* Sets framework [4], the Particle Flow Networks (PFNs) [5] can generalize any permutationinvariant observable as

 $O\left(\{p_1,\ldots,p_M\}\right)=F\left(\sum_{i=1}^M\Phi\left(p_i\right)\right)$

with Φ and F parametrized by neural networks. **Transformer:** The transformer acts on graphs topo-cluster cells that are updated via the *self-attention* mechanism [6], allowing the model to learn the mutual importance of calorimeter cells for predicting calibrated topo-cluster energy.

The GNN and PFN studied here are used for simultaneous cluster classification and energy calibration, whereas the transformer is only used for energy calibration.

All the point cloud methods outperform LCW in reconstructing the median cluster (or pion) energy, as well as achieving a smaller spread in energy response, showing that deep learning techniques are promising tools for low-level hadronic reconstruction.

References

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