

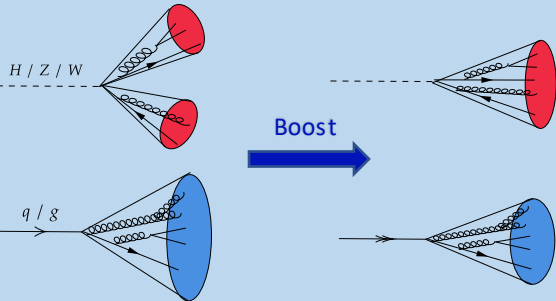
# Boost Invariant Polynomials for Efficient Jet Tagging

We construct highly efficient features invariant under permutations, rotations, and boosts in the jet direction generating a highly flexible and interpretable scheme with SOTA accuracies in supervised and unsupervised approaches using out-of-the-box classifiers with hundreds of parameters. And second, micro-second training and inference times on CPU.

## The problem

DL approaches are the go-to methods for data analysis related to jet-tagging. Specially to tackle the large amount of data generated in particle colliders, from which only some events are physically interesting.

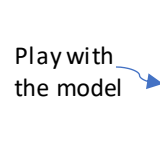
Thus, it is necessary to distinguish events using their substructure. Nevertheless, since the events are highly boosted, most of the times the structure is not accessible from the laboratory frame:



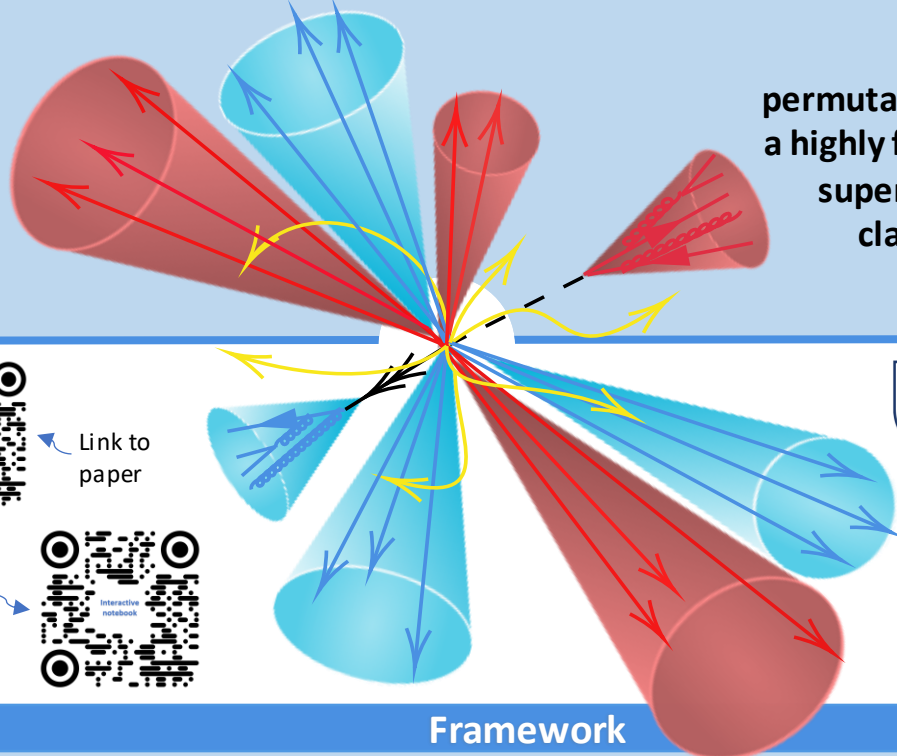
Highest accuracies are currently achieved by models incorporating boost invariance, resulting in computationally costly and complex parametrizations and thus lack interpretability.



Link to paper

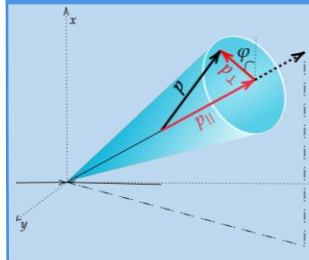


Play with the model



## Framework

The BIP basis composes a complete basis for the jet representation via orthogonal polynomials via:



$$\sum_{\xi} l_{\xi} = \sum_{\xi} k_{\xi} = 0$$

Invariance condition

$$A_{nkl\mu} = \sum_{i=1}^N e^{il\varphi_i} e^{-ky_i} B_n(\tilde{p}_{\perp,i}) \psi_{\mu}(\theta_i)$$

IRC Safe + invariant polynomial

Detected rapidity

Log-normalized transverse momentum

Additional features

Bessel polynomials

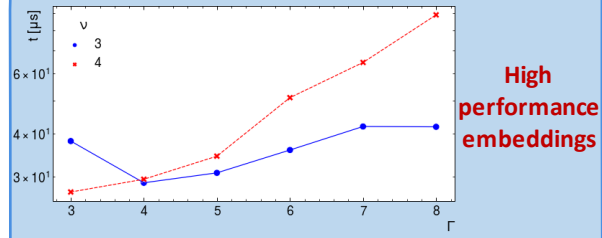
$$A_{lkn\mu} = \prod_{\xi=1}^{\nu} A_{l_{\xi} k_{\xi} n_{\xi} \mu_{\xi}}$$

$\nu \leq \bar{\nu}$  : correlation order

## Outlooks

- Extend geometric deep-learning framework based on our construction.
- Generalization of the BIP embedding generation.
- Application of the framework to further problems in HEP.

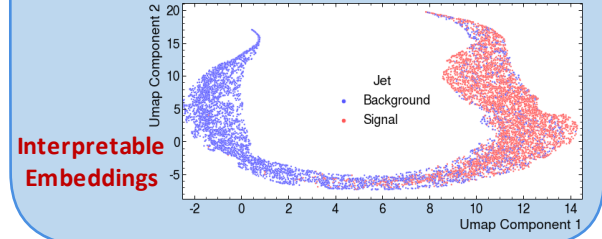
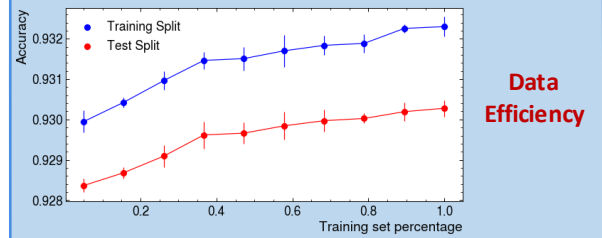
## Results



Architecture	#Param	Accuracy	AUC
Supervised			
BIP(4, 8, XGBoost)	2k	0.931	0.981
BIP(3, 6, LogReg)	120	0.928	0.977
BIP(2, 3, ARD)	71	0.926	0.976
Unsupervised			
BIP(3, 4, UMAP+GMM)	5	0.884	0.864

Model-independent SOTA-range accuracies

Top Tagging Dataset



Interpretable Embeddings