<span id="page-0-0"></span>Evaluation of A Digital Tracking Calorimeter for In-Situ Range Verification during Particle Therapy

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# Particle Therapy

- Cancer is one of the leading causes of death
- Tumors can be treated with photons or ions (protons, carbon, ...)



Particle therapy can be done by passive scattering or pencil beam scanning



- Treatment planning provides expected locations for the Bragg peak of individual spots
- Many things can go wrong
	- Movement through breathing and other organ activity
	- Patient anatomy changes between imaging and treatment
	- Patient alignment on the treatment table

#### Range verification

- Goal: Predict Bragg peak location with  $\leq 1$  mm error
- How do we know the Bragg peak is at the expected location?
	- $\rightarrow$  Positron emission tomography (PET), e.g. Parodi et al., 2000 [\[3\]](#page-13-2)
	- $\rightarrow$  Prompt gamma (PG) detection, e.g. Kurosawa et al., 2012 [\[4\]](#page-13-3)
	- $\rightarrow$  Charged secondary particles?

# Range Verification

- Heavier ions (e.g. carbon) produce fast secondary ions
	- $\rightarrow$  Range verification with charged particles in carbon therapy: Gwosch et al., 2013 [\[5\]](#page-13-4)
- Range verification with charged secondaries has not been done in proton therapy
- Protons only produce neutral secondaries leaving the patient
- Neutral particles interact with matter in the detector  $\rightarrow$  tertiary charged particles



# Digital Tracking Calorimeter

- Conventional CT is done with photons
	- Uncertainties when using an x-ray CT for particle treatment planning
	- $\rightarrow$  Imaging with protons: proton CT (pCT)

- Bergen pCT collaboration is developing a digital tracking calorimeter (DTC) for pCT [\[6\]](#page-13-5)
- 2 tracker layers
- 41 detector-absorber layers (calorimeter)
- Per layer: 108 ALPIDE [\[7\]](#page-13-6) chips (monolithic active pixel sensor)



- **1** Can the DTC be used for range verification during particle therapy?
- **2** How accurate is range verification with the DTC for carbon ions?
- **8** Is readout yield sufficient for proton range verification within 1 mm?
- Simulate treatment with protons & carbon
- DTC is modeled in GATE Monte Carlo simulation
- Phantom: water cuboid, thickness: 160 200 mm
- 3.11 $\cdot$  10<sup>7</sup> protons per simulation
- 3.11  $\cdot$  10<sup>5</sup> carbon ions per simulation
- Beam energies are set to medically relevant values
	- Protons: 60.13 150.35 MeV in 3 mm range intervals (43 energies from matRad [\[8\]](#page-13-7))
	- Carbon:  $115.23 279.97$  MeV/u in 2 mm range intervals (61 energies from matRad [\[8\]](#page-13-7))
- 213 proton samples, 305 carbon samples Protons at 69.4 MeV, 160 mm water



### Machine Learning Models

- 29 base features:
	- Water phantom thickness
	- Total number of active pixels
	- Total number of pixel clusters (hits)
	- Aggregate properties of cluster sizes
	- Different fits of aggregate properties over detector layer
- Features with ground truth range from matRad used with models:
	- Linear regression (OLS)
	- Automatic relevance determination (ARD)
	- Kernel regression
	- Gaussian process (GP)
	- Deep neural network (DNN)
- For Kernel regression, GP, and DNN, the feature set is reduced to different subsets



- Carbon works better than protons despite 100 times fewer primaries
- GP performs best in both cases
- Sub-mm error even for protons
- The detector has shown potential for range verification
- ... but it is optimized for pCT through Monte Carlo simulations
- Extremely low yield requires too many simulations to do the same for range verification
- $\rightarrow$  Differentiated MC simulation (GATE/Geant4)
- Then we can optimize some properties
	- Existence and thickness of converter materials
	- Replace empirical with analytical models to predict range
	- Improved uncertainty quantification

The Bergen pCT collaboration's DTC is the first detector shown to be capable of in-situ range verification through charged particles in proton therapy

What's next?

- More realistic data (pediatric head simulation)
- Replace manual feature engineering with graph neural network of raw data
- As soon as differentiated physics simulation is available: detector design optimization

# The Bergen pCT Collaboration and SIVERT Research Training Group

- University of Bergen, Norway
- Helse Bergen, Norway
- Western Norway University of Applied Science, Bergen, Norway
- Wigner Research Center for Physics, Budapest, Hungary
- DKFZ, Heidelberg, Germany
- Saint Petersburg State University, Saint Petersburg, Russia
- Utrecht University, **Netherlands**
- RPE LTU, Kharkiv, Ukraine
- Suranaree University of Technology, Nakhon Ratchasima, Thailand
- China Three Gorges University, Yichang, China
- University of Applied Sciences Worms, Germany
- University of Oslo, Norway
- Eötvös Loránd University, Budapest, Hungary
- Technical University TU Kaiserslautern, Germany





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29 base features:

- Water phantom thickness
- Total number of active pixels
- Total number of pixel clusters (hits)
- Number of clusters over threshold (5, 20 pixels)
- Mean and standard deviation of cluster sizes
- Linear and cubic fit for active pixels over layer
- Linear and cubic fit for hits over layer
- Linear and cubic fit for deposited energy over layer
- Exponential fit and its mean squared residuals for active pixels over layer

#### Gaussian Process

- Features: Phantom thickness, clusters, mean cluster size, linear fit for pixels over layer
- Kernel: const ∗ RBF + const ∗ RBF
- MAE: 0.33



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#### <span id="page-16-0"></span>Deep Neural Network

- Features: Fits for clusters over layer and energy deposition over layer are removed
- Fully-connected network with 2 hidden layers (256 and 128 units, sigmoid, 5% dropout)
- MC dropout raises MAE to  $>1$  mm



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