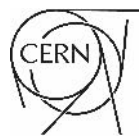


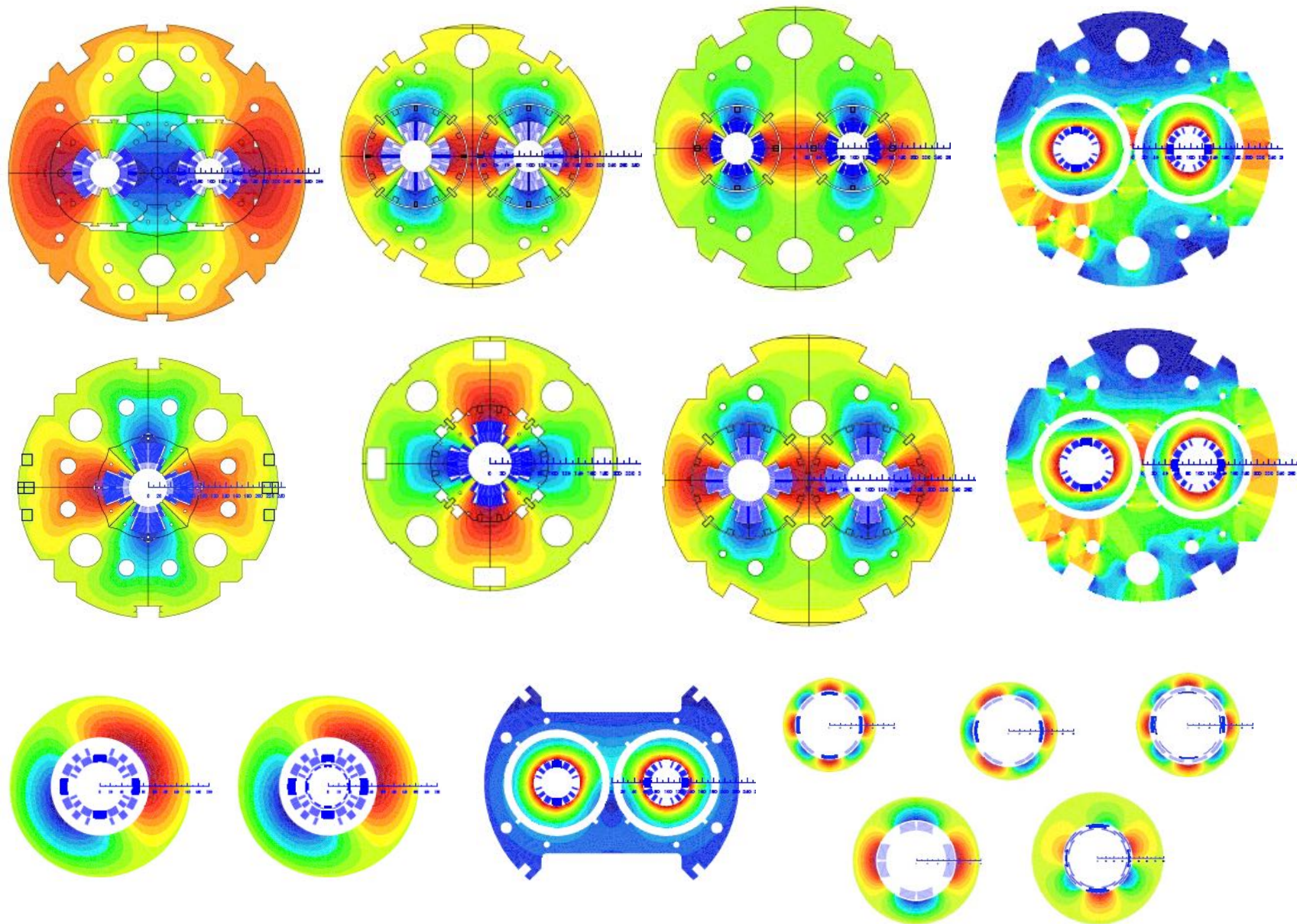
Electromagnetic Design of Accelerator Magnets and ROXIE User's Course

Numerical Field Simulation
FEM / BEM

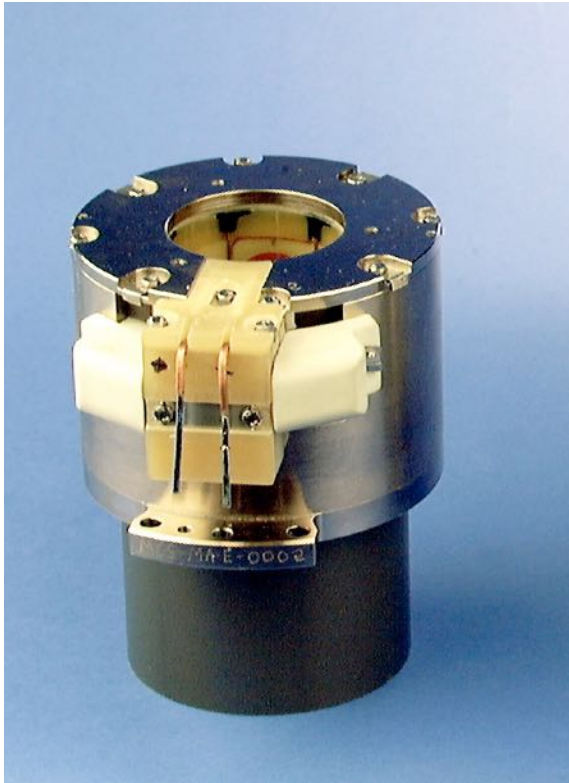
Stephan Russenschuck, CERN, 2022



The LHC Magnet Zoo

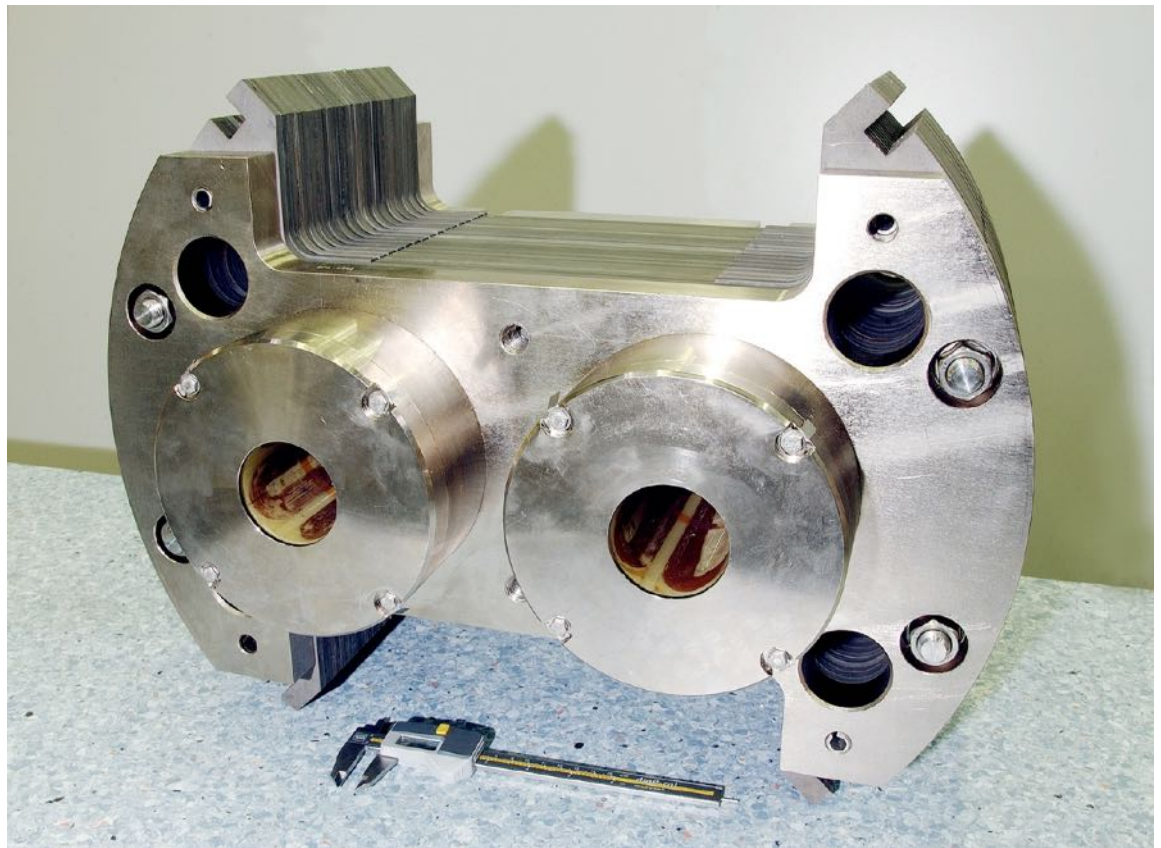


Corrector Magnets

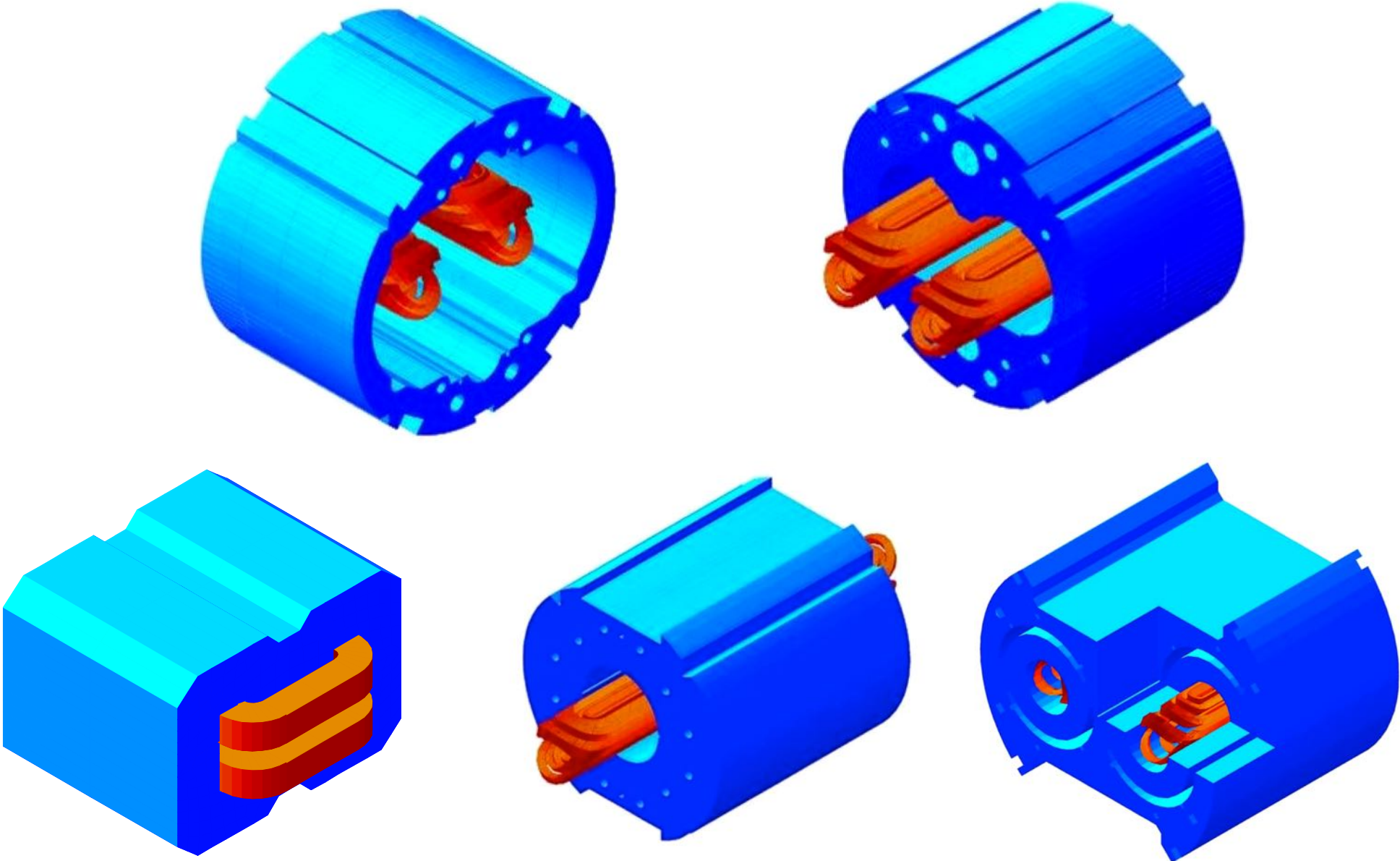


Sextupole-spool pieces

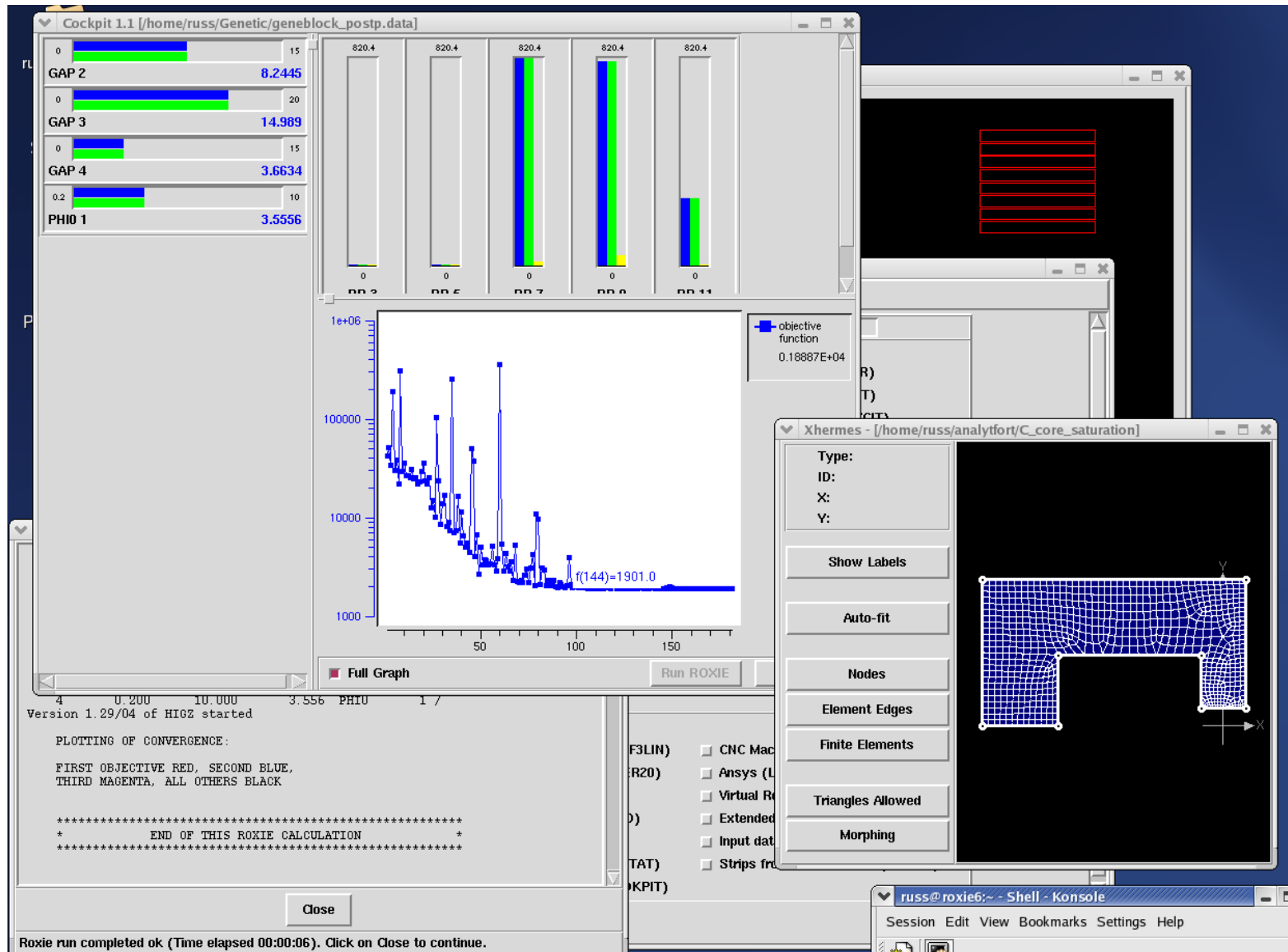
Octupole



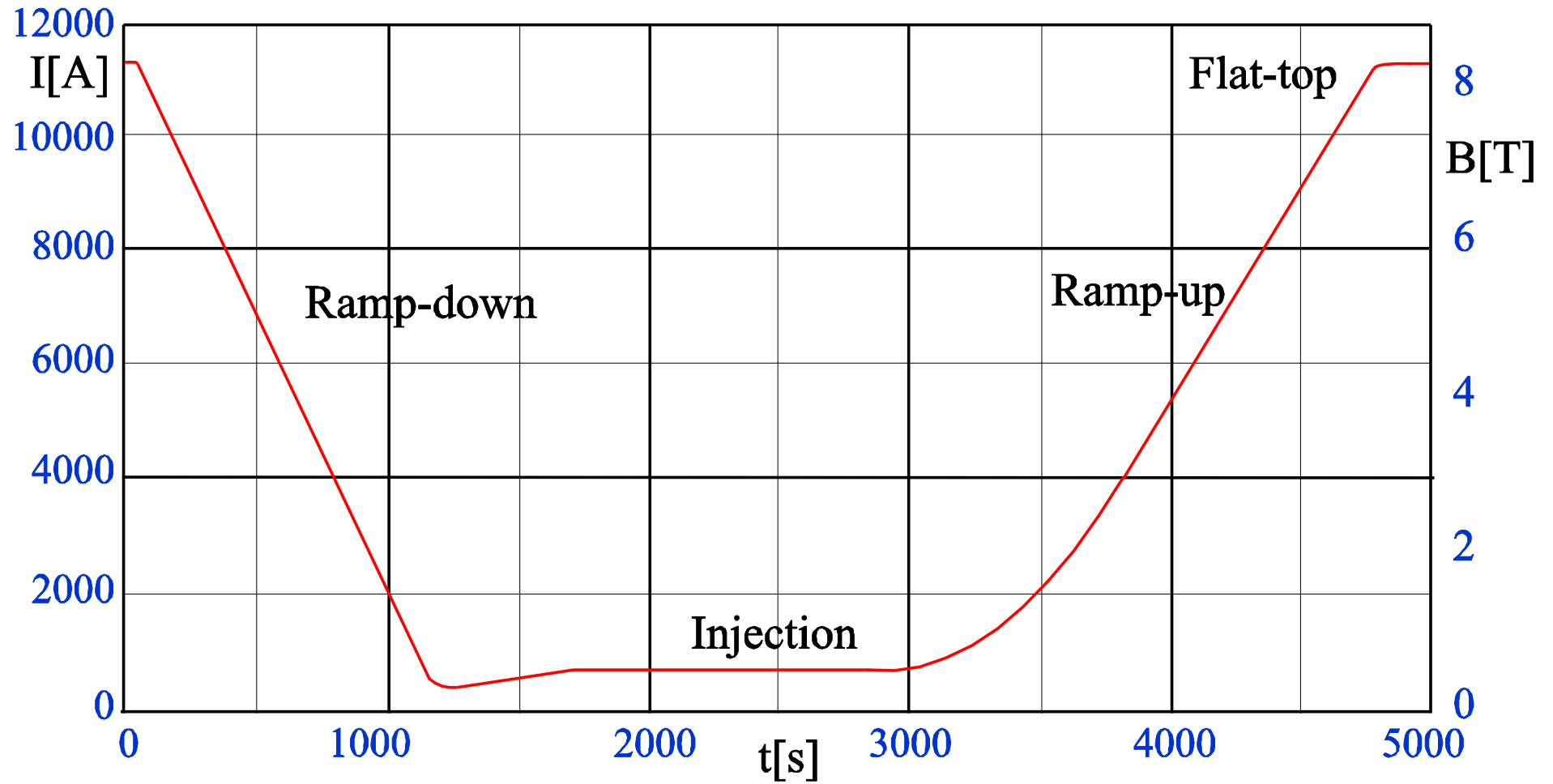
Magnet Extremities



The CERN Field Computation Program ROXIE

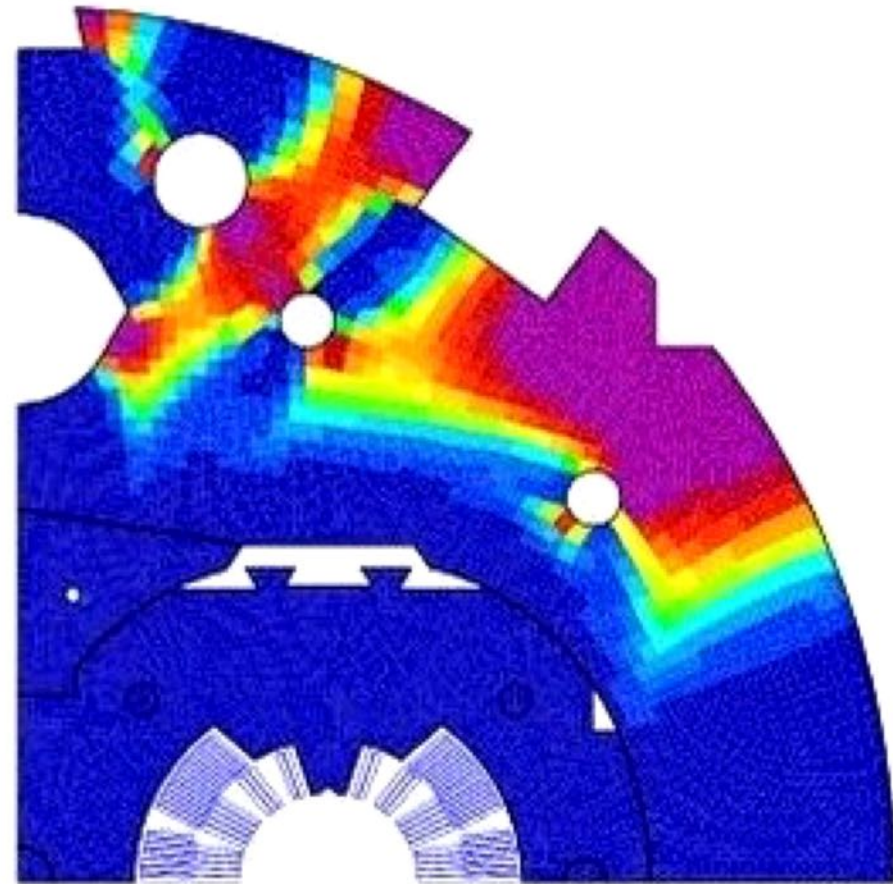
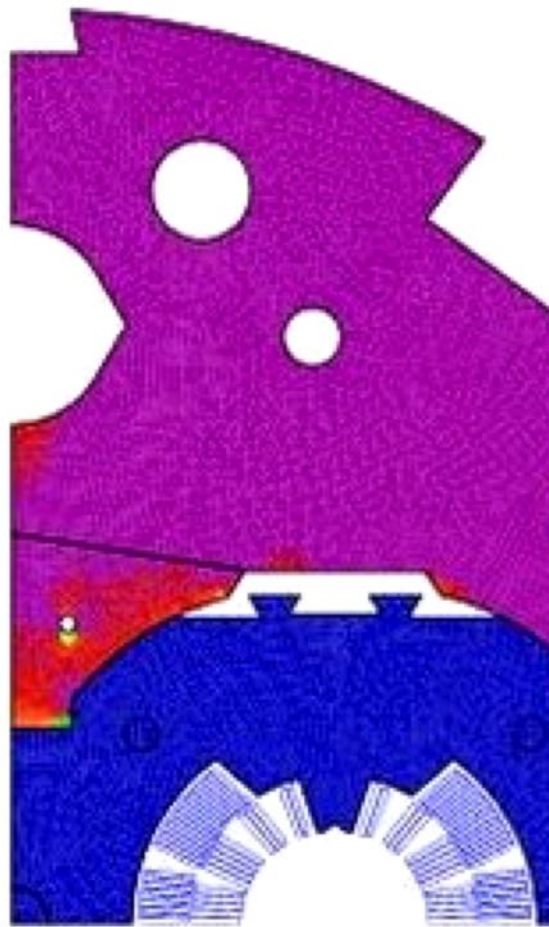
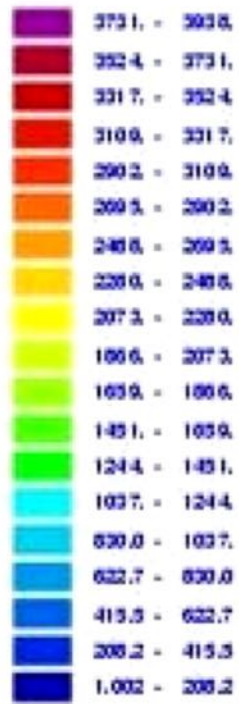


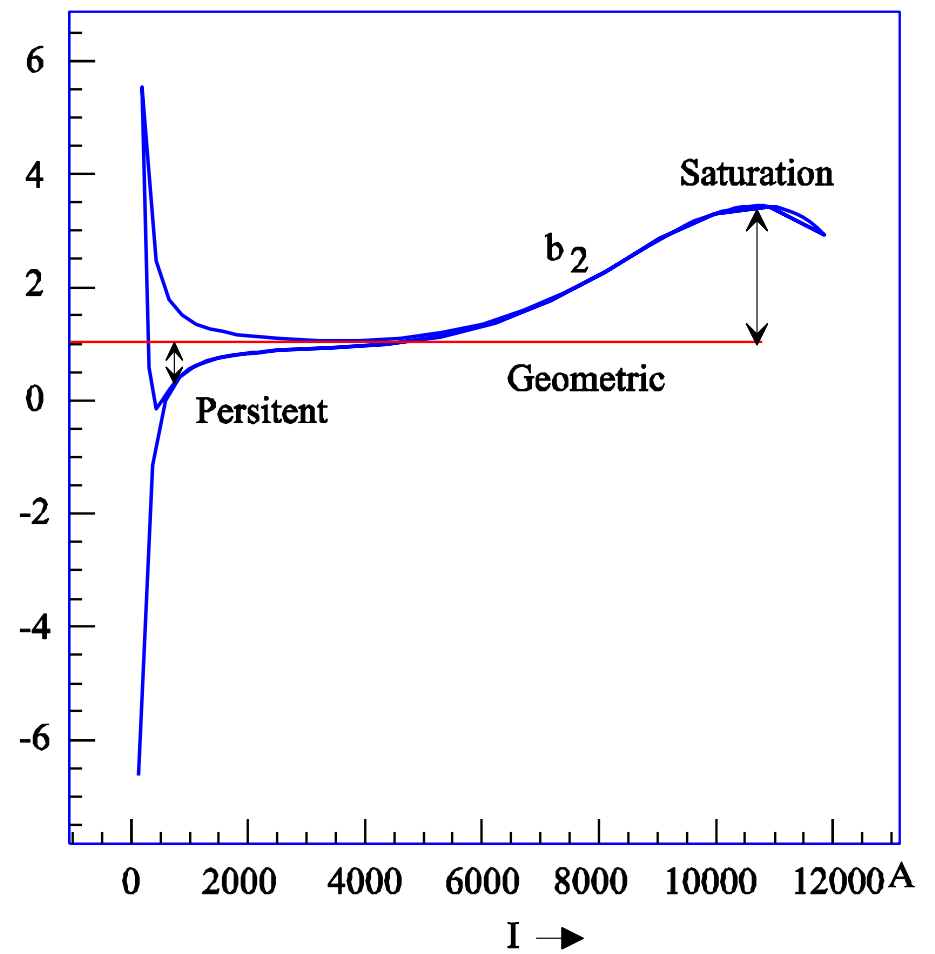
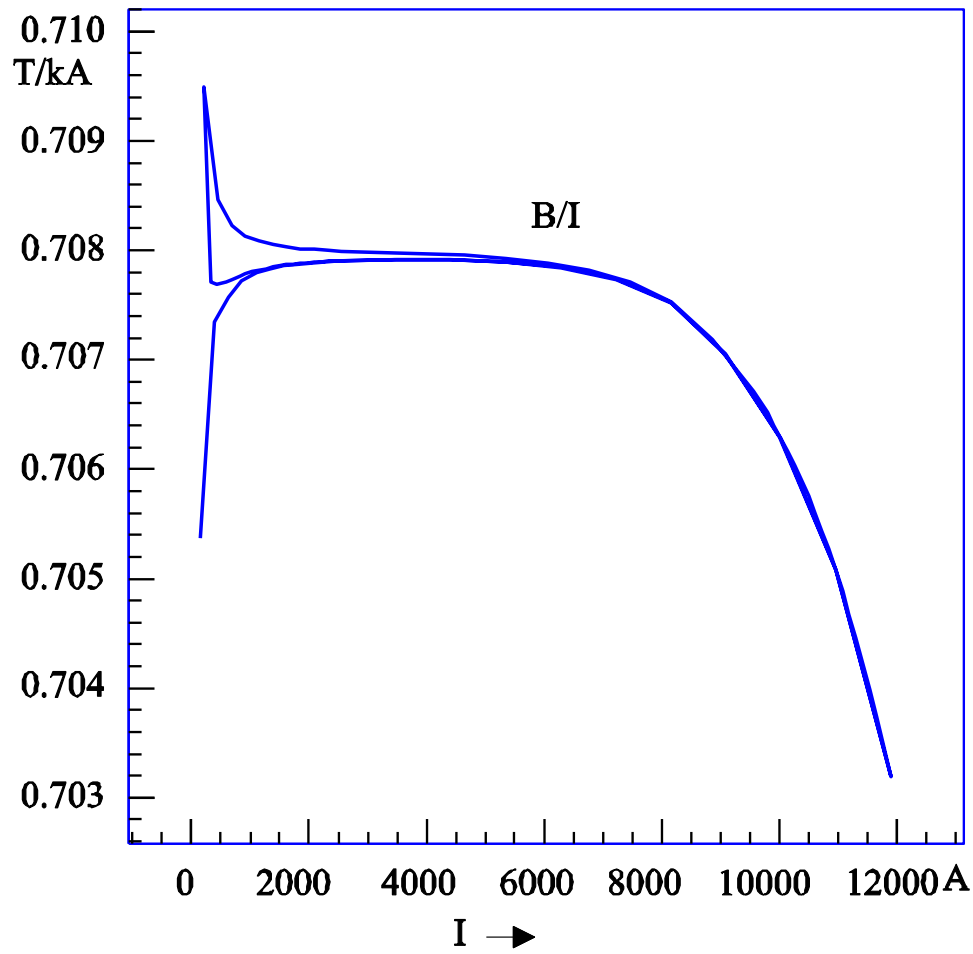
Excitation Cycle



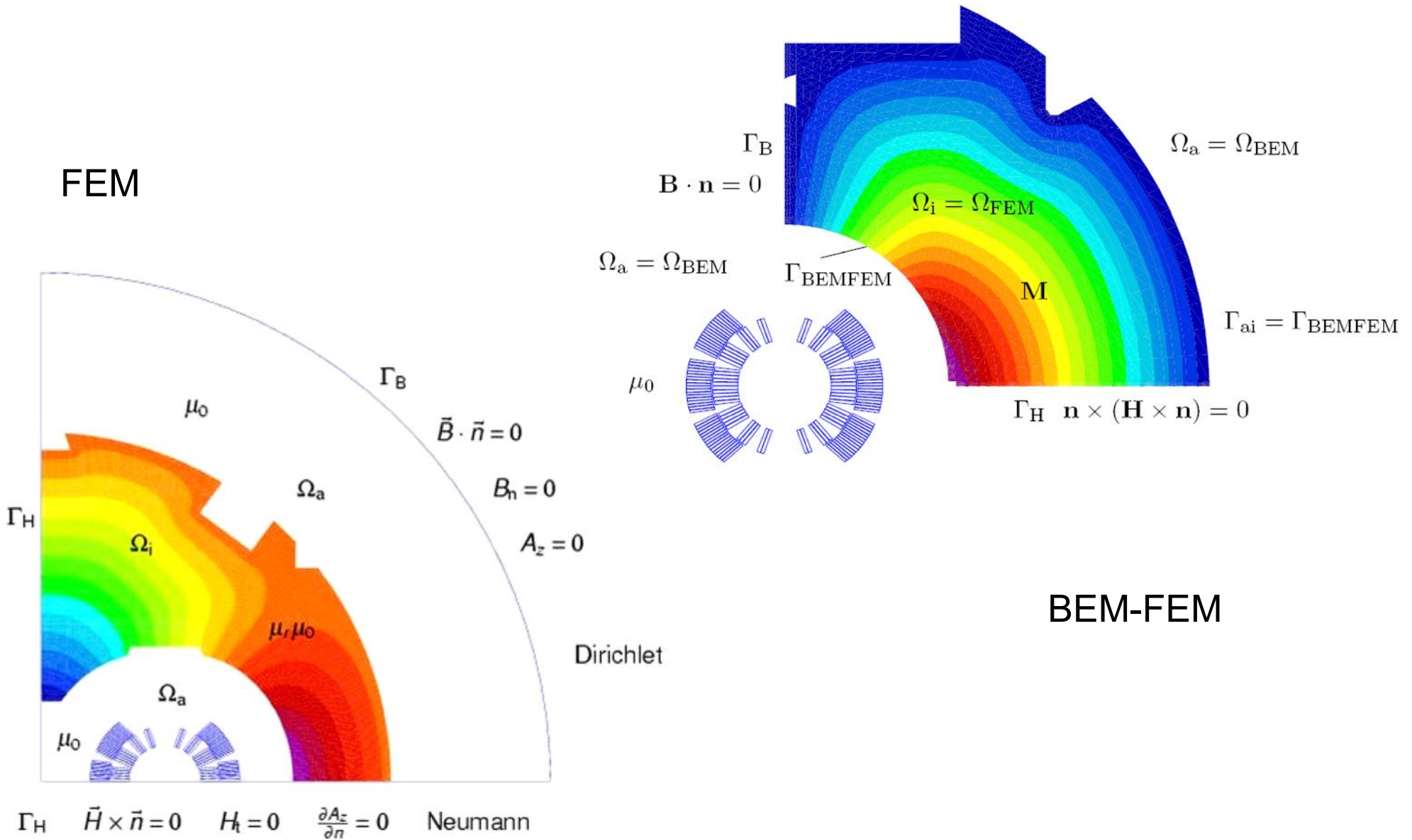
Saturation Effects in the Dipole Iron Yoke

HL7





The Problem Domain



The Model Problem (1-D)

$$\frac{d^2 u(x)}{dx^2} = f(x), \quad x \in \Omega$$

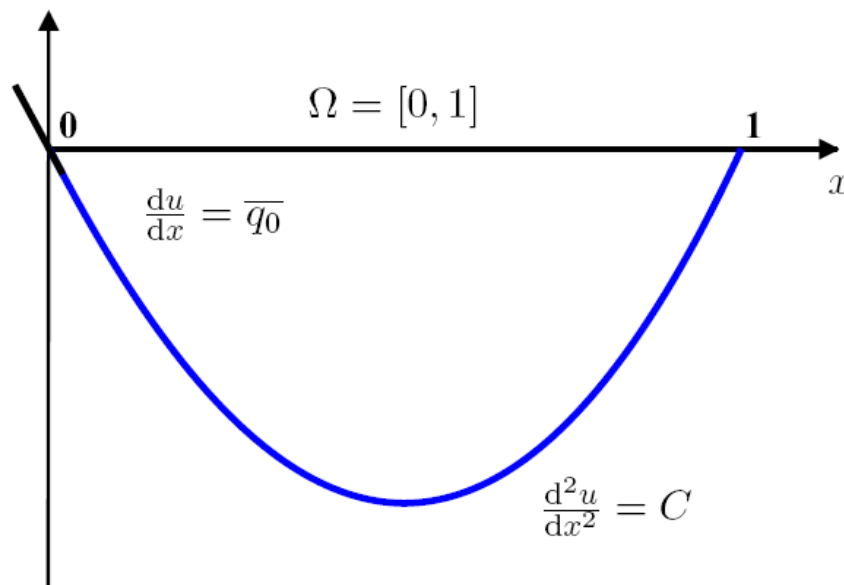
$$u(x)|_{x=0} = u_0,$$

$$u(x)|_{x=1} = u_1,$$

or

$$\left. \frac{du}{dx} \right|_{x=0} = q_0,$$

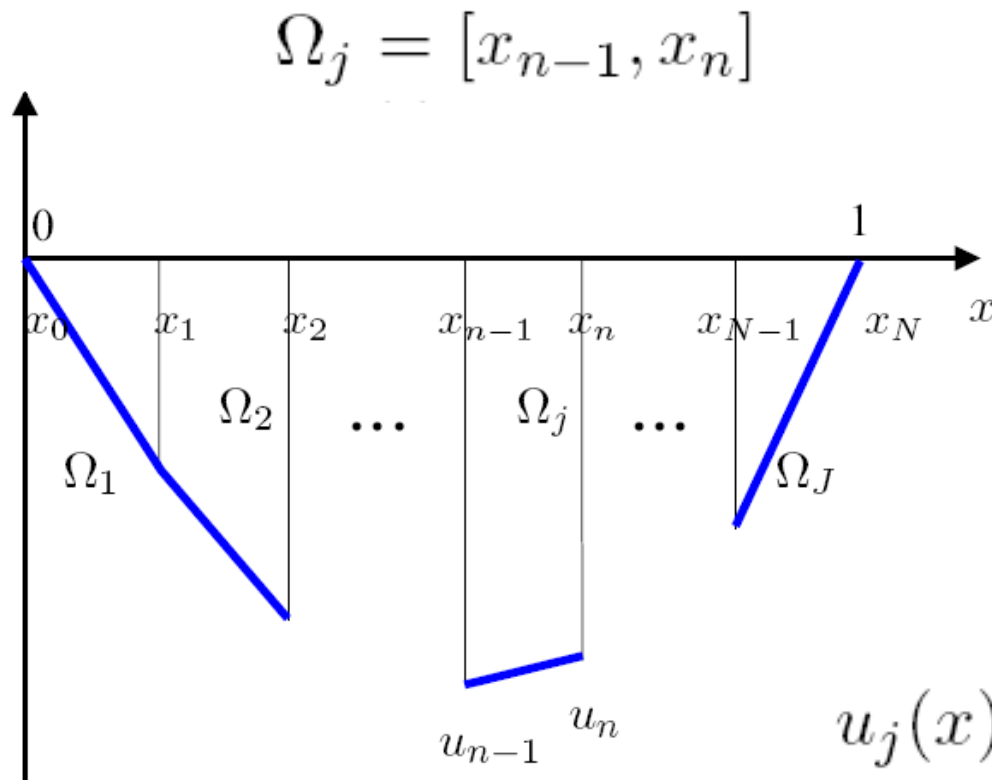
$$\left. \frac{du}{dx} \right|_{x=1} = q_1.$$



Constant heat source C and
 $u(x) = 0$ at $x=0$ and $x=1$

$$u(x) = \frac{C}{2} (x^2 - x)$$

Shape Functions



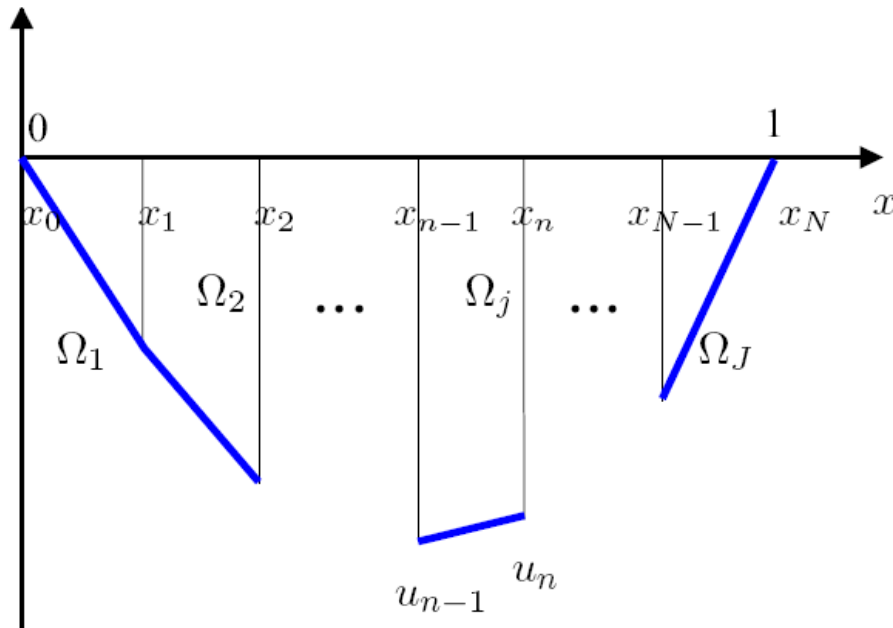
$$\Omega = \bigcup_{j=1}^J \Omega_j$$

$$u_j(x) = \alpha_{j1} + \alpha_{j2}x \quad x \in \Omega_j$$

$$u_{n-1} = \alpha_{j1} + \alpha_{j2}x_{n-1}$$

$$u_n = \alpha_{j1} + \alpha_{j2}x_n$$

Shape Functions



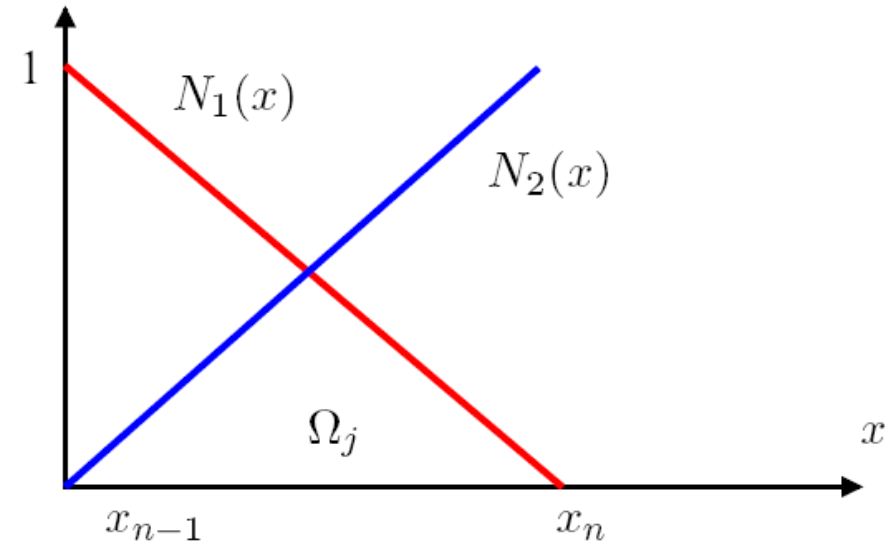
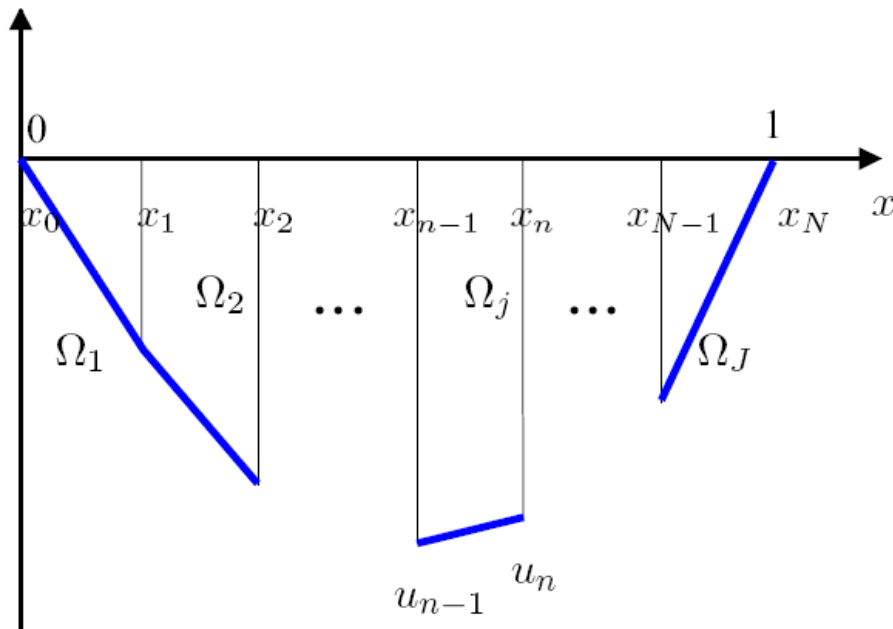
$$\alpha_{j1} = \frac{\begin{vmatrix} u_{n-1} & x_{n-1} \\ u_n & x_n \end{vmatrix}}{\begin{vmatrix} 1 & x_{n-1} \\ 1 & x_n \end{vmatrix}} \quad \text{Cramer's rule}$$

$$\alpha_{j1} = \frac{x_n u_{n-1} - x_{n-1} u_n}{x_n - x_{n-1}}$$

$$\alpha_{j2} = \frac{u_n - u_{n-1}}{x_n - x_{n-1}}$$

$$u_j(x) = \alpha_{j1} + \alpha_{j2}x = \frac{x_n - x}{x_n - x_{n-1}} u_{n-1} + \frac{-x_{n-1} + x}{x_n - x_{n-1}} u_n$$

Shape Functions



$$N_{j1}(x) = \frac{x_n - x}{x_n - x_{n-1}}$$

$$N_{j2}(x) = \frac{-x_{n-1} + x}{x_n - x_{n-1}}$$

What have we won? We can express the field in the element as a function of the node potentials using known polynomials in the spatial coordinates

The Weighted Residual

$$R(x) := \frac{d^2 u(x)}{dx^2} - f(x)$$

Integration by parts

$$\int_{\Omega} w(x) R(x) d\Omega = \int_{\Omega} w(x) \frac{d^2 u(x)}{dx^2} d\Omega - \int_{\Omega} w(x) f(x) d\Omega = 0$$

$$\int_a^b \phi \psi' dx = [\phi \psi]_a^b - \int_a^b \phi' \psi dx \quad w(x) = \phi \quad \frac{du(x)}{dx} = \psi$$

$$- \int_{\Omega} \frac{dw(x)}{dx} \frac{du(x)}{dx} d\Omega + \left[w(x) \frac{du(x)}{dx} \right]_0^1 - \int_{\Omega} w(x) f(x) d\Omega = 0$$

What have we won? Removal of the second derivative, a way to incorporate Neumann boundary conditions

$$\int_{\Omega} \frac{dw(x)}{dx} \frac{du(x)}{dx} d\Omega = - \int_{\Omega} w(x) f(x) d\Omega$$

$$\int_{\Omega_j} \frac{dw_l(x)}{dx} \sum_{k=1,2} \frac{dN_{jk}(x)}{dx} u^{(k)} d\Omega_j = - \int_{\Omega_j} w_l(x) f(x) d\Omega_j, \quad l = 1, 2.$$

$$\int_{\Omega_j} \frac{dN_{jl}(x)}{dx} \sum_{k=1,2} \frac{dN_{jk}(x)}{dx} u^{(k)} d\Omega_j = - \int_{\Omega_j} N_{jk}(x) f(x) d\Omega_j, \quad l = 1, 2$$

$$\int_{x_{n-1}}^{x_n} \left(\frac{dN_{j1}}{dx} \frac{dN_{j1}}{dx} u_{n-1} + \frac{dN_{j1}}{dx} \frac{dN_{j2}}{dx} u_n \right) dx = - \int_{x_{n-1}}^{x_n} N_{j1} f(x) dx$$

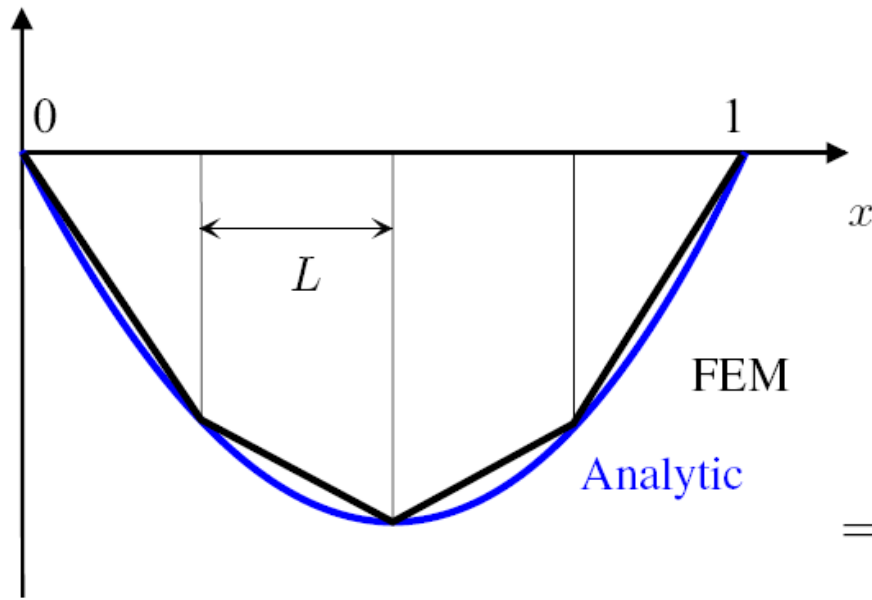
$$\int_{x_{n-1}}^{x_n} \left(\frac{dN_{j2}}{dx} \frac{dN_{j1}}{dx} u_{n-1} + \frac{dN_{j2}}{dx} \frac{dN_{j2}}{dx} u_n \right) dx = - \int_{x_{n-1}}^{x_n} N_{j2} f(x) dx$$

$$[k_j] \{u_j\} = \{f_j\}$$

Linear equation system for the node potentials

Numerical Example

4 finite elements $\Omega_j, j = 1, \dots, 4$ of equidistant length L



$$[k_j] = \int_{x_{n-1}}^{x_n} \begin{pmatrix} \frac{dN_{j1}}{dx} & \frac{dN_{j1}}{dx} & \frac{dN_{j1}}{dx} & \frac{dN_{j2}}{dx} \\ \frac{dN_{j2}}{dx} & \frac{dN_{j1}}{dx} & \frac{dN_{j2}}{dx} & \frac{dN_{j2}}{dx} \end{pmatrix} dx$$

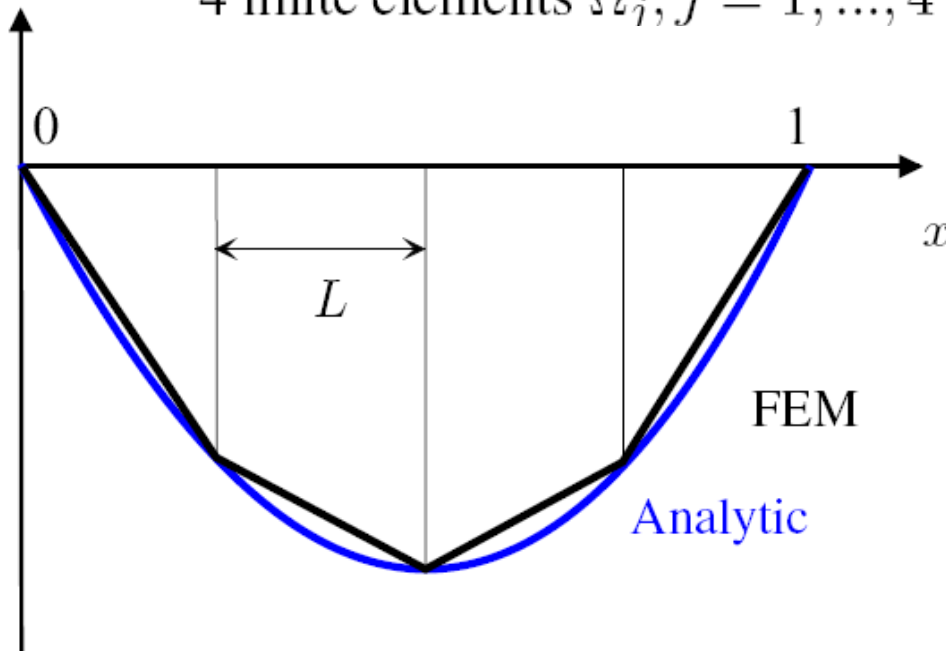
$$= \int_{x_{n-1}}^{x_n} \begin{pmatrix} \frac{1}{(x_n - x_{n-1})^2} & \frac{-1}{(x_n - x_{n-1})^2} \\ \frac{-1}{(x_n - x_{n-1})^2} & \frac{1}{(x_n - x_{n-1})^2} \end{pmatrix} dx = \begin{pmatrix} \frac{1}{L} & \frac{-1}{L} \\ \frac{-1}{L} & \frac{1}{L} \end{pmatrix}$$

$$\{f_j\} = - \int_{x_{n-1}}^{x_n} \begin{pmatrix} N_{j1} \\ N_{j2} \end{pmatrix} C dx = -C \int_{x_{n-1}}^{x_n} \begin{pmatrix} \frac{x_n - x}{x_n - x_{n-1}} \\ \frac{-x_{n-1} + x}{x_n - x_{n-1}} \end{pmatrix} dx$$

$$= -\frac{C}{2L} \begin{pmatrix} 2x_n x - x^2 \\ -2x_{n-1} x + x^2 \end{pmatrix} \Big|_{x_{n-1}}^{x_n} = -\frac{C}{2L} \begin{pmatrix} (x_n - x_{n-1})^2 \\ (x_{n-1} - x_n)^2 \end{pmatrix} = - \begin{pmatrix} 0.5 CL \\ 0.5 CL \end{pmatrix}$$

Numerical Example

4 finite elements $\Omega_j, j = 1, \dots, 4$ of equidistant length L



S (Stiffness matrix)

$$\begin{pmatrix} \frac{1}{L} & -\frac{1}{L} & 0 & 0 & 0 \\ \frac{1}{L} & \frac{2}{L} & -\frac{1}{L} & 0 & 0 \\ 0 & -\frac{1}{L} & \frac{2}{L} & -\frac{1}{L} & 0 \\ 0 & 0 & -\frac{1}{L} & \frac{2}{L} & -\frac{1}{L} \\ 0 & 0 & 0 & -\frac{1}{L} & \frac{1}{L} \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \end{pmatrix} = - \begin{pmatrix} 0.5CL \\ CL \\ CL \\ CL \\ 0.5CL \end{pmatrix}$$

Essential boundary conditions (Dirichlet)

S^{-1}

$$\begin{pmatrix} u_2 \\ u_3 \\ u_4 \end{pmatrix} = - \begin{pmatrix} \frac{3L}{4} & \frac{L}{2} & \frac{L}{4} \\ \frac{L}{2} & L & \frac{L}{2} \\ \frac{L}{4} & \frac{L}{2} & \frac{2L}{4} \end{pmatrix} \begin{pmatrix} CL \\ CL \\ CL \end{pmatrix} = \begin{pmatrix} -0.375 \\ -0.5 \\ -0.375 \end{pmatrix}$$

Higher order elements

$$u^{(1)} = \alpha_{j1} + \alpha_{j2}x_1 + \alpha_{j3}x_1^2$$

$$u^{(2)} = \alpha_{j1} + \alpha_{j2}x_2 + \alpha_{j3}x_2^2$$

$$u^{(3)} = \alpha_{j1} + \alpha_{j2}x_3 + \alpha_{j3}x_3^2$$

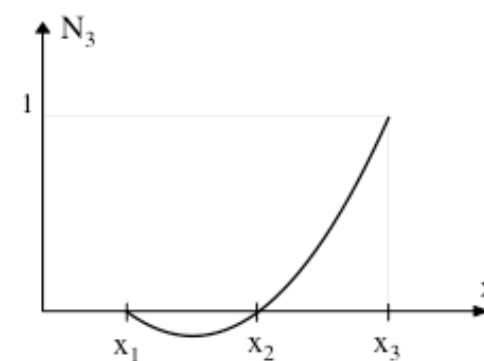
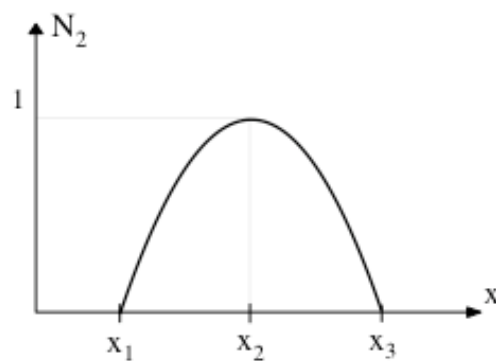
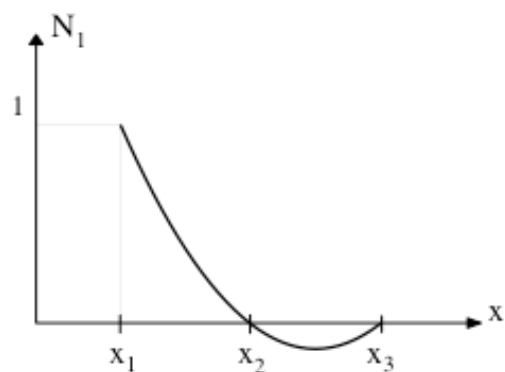
$$u_j(x) = \sum_{k=1}^3 N_{jk}(x)u^{(k)}$$

$$N_{j1}(x) = \frac{(x - x_2)(x - x_3)}{(x_1 - x_2)(x_1 - x_3)},$$

$$N_{j2}(x) = \frac{(x - x_1)(x - x_3)}{(x_2 - x_1)(x_2 - x_3)}$$

$$N_{j3}(x) = \frac{(x - x_1)(x - x_2)}{(x_3 - x_1)(x_3 - x_2)}.$$

h-refinement
Versus
p-refinement



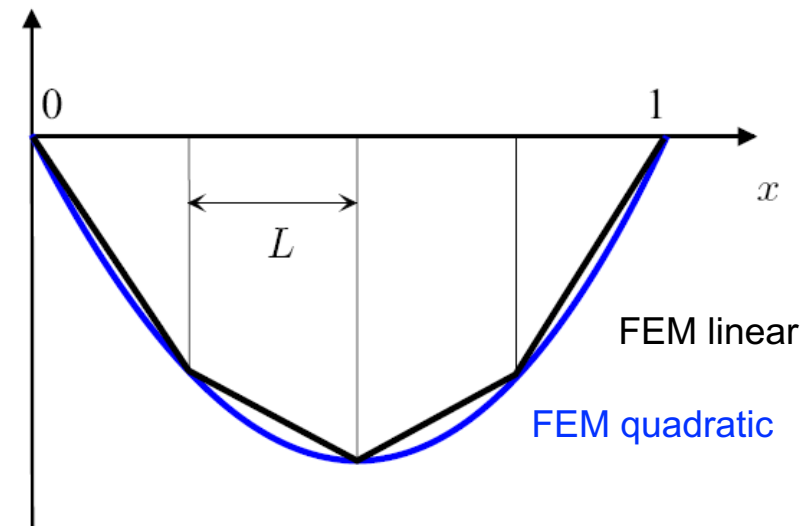
Two Quadratic Elements

$$[k_j] = \int_{x_1}^{x_3} \begin{pmatrix} \frac{dN_{j1}}{dx} \frac{dN_{j1}}{dx} & \frac{dN_{j1}}{dx} \frac{dN_{j2}}{dx} & \frac{dN_{j1}}{dx} \frac{dN_{j3}}{dx} \\ \frac{dN_{j2}}{dx} \frac{dN_{j1}}{dx} & \frac{dN_{j2}}{dx} \frac{dN_{j2}}{dx} & \frac{dN_{j2}}{dx} \frac{dN_{j3}}{dx} \\ \frac{dN_{j3}}{dx} \frac{dN_{j1}}{dx} & \frac{dN_{j3}}{dx} \frac{dN_{j2}}{dx} & \frac{dN_{j3}}{dx} \frac{dN_{j3}}{dx} \end{pmatrix} dx \quad [k_j] = \begin{pmatrix} \frac{7}{6l} & \frac{-8}{6l} & \frac{1}{6l} \\ \frac{-8}{6l} & \frac{16}{6l} & \frac{-8}{6l} \\ \frac{1}{6l} & \frac{-8}{6l} & \frac{7}{6l} \end{pmatrix}$$

$$\{f_j\} = - \int_{x_1}^{x_3} \begin{pmatrix} N_{j1} \\ N_{j2} \\ N_{j3} \end{pmatrix} f(x) dx \quad \{f_j\} = -\frac{1}{3}c \begin{pmatrix} l \\ 4l \\ l \end{pmatrix}$$

$$\begin{pmatrix} \frac{16}{6l} & \frac{-8}{6l} & 0 \\ \frac{-8}{6l} & \frac{14}{6l} & \frac{-8}{6l} \\ 0 & \frac{-8}{6l} & \frac{16}{6l} \end{pmatrix} \begin{pmatrix} u_2 \\ u_3 \\ u_4 \end{pmatrix} = -\frac{1}{3} \begin{pmatrix} 4cl \\ 2cl \\ 4cl \end{pmatrix}$$

$$\begin{pmatrix} u_2 \\ u_3 \\ u_4 \end{pmatrix} = - \begin{pmatrix} \frac{3l}{4} & \frac{1}{2} & \frac{l}{4} \\ \frac{l}{2} & l & \frac{l}{2} \\ \frac{l}{4} & \frac{l}{2} & \frac{3l}{4} \end{pmatrix} \begin{pmatrix} cl \\ cl \\ cl \end{pmatrix} = \begin{pmatrix} -0.375 \\ -0.5 \\ -0.375 \end{pmatrix}$$

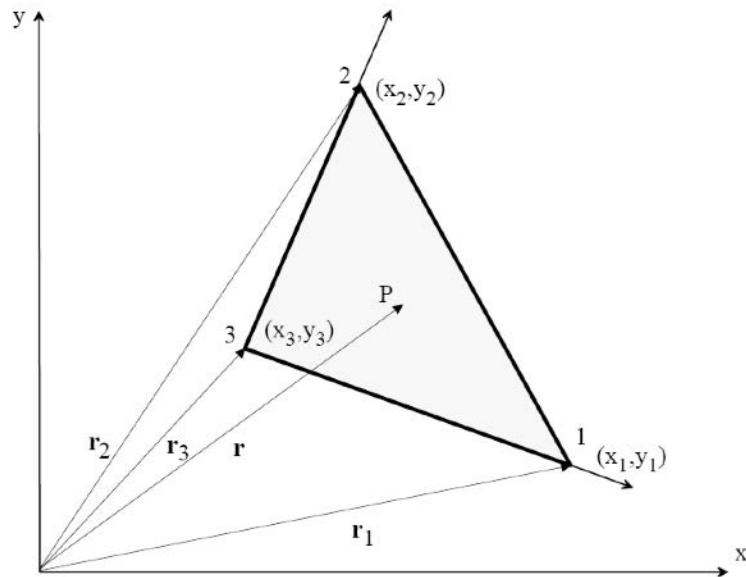


Shape Functions

$$A_j(\mathbf{x}) = \alpha_1 + \alpha_2 x + \alpha_3 y,$$

$$\mathbf{x} \in \Omega_j$$

$$A_j(\mathbf{x}) = A_{z_j}(x, y)$$



$$A^{(1)} = \alpha_1 + \alpha_2 x_1 + \alpha_3 y_1$$

$$A^{(2)} = \alpha_1 + \alpha_2 x_2 + \alpha_3 y_2$$

$$A^{(3)} = \alpha_1 + \alpha_2 x_3 + \alpha_3 y_3$$

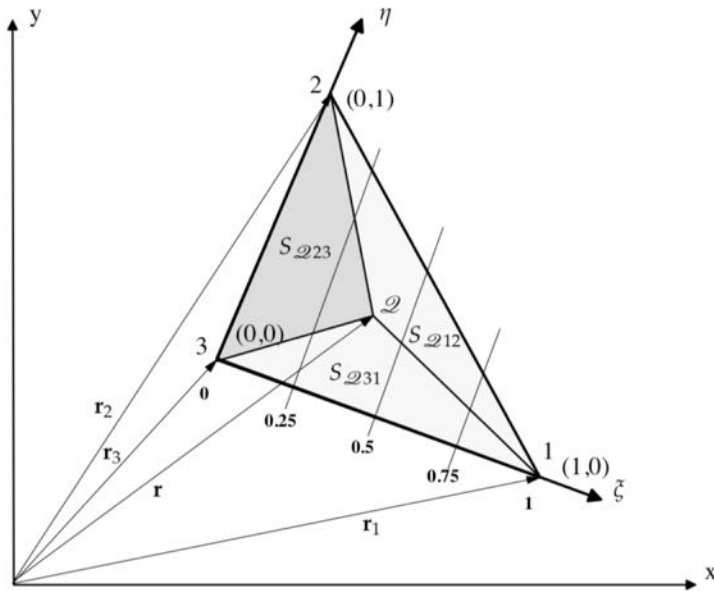
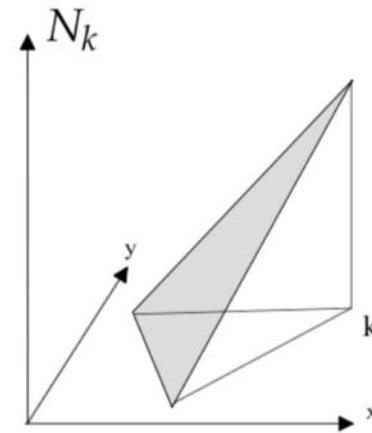
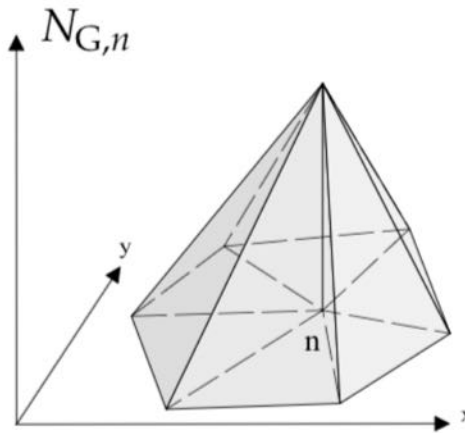
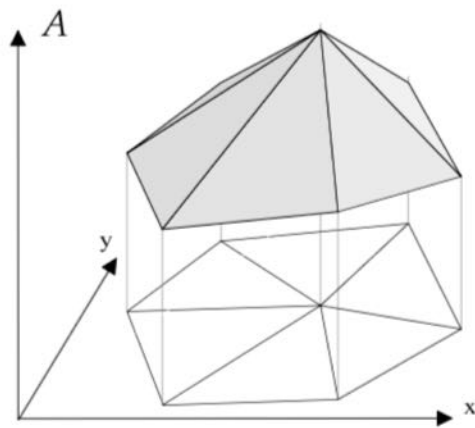
$$\begin{pmatrix} A^{(1)} \\ A^{(2)} \\ A^{(3)} \end{pmatrix} = \begin{pmatrix} 1 & x_1 & y_1 \\ 1 & x_2 & y_2 \\ 1 & x_3 & y_3 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix}$$

$$\{A\} = [C]\{\alpha\}$$

$$\{\alpha\} = [C]^{-1}\{A\}$$

$$N_k(\mathbf{r}) = \frac{a_k + b_k x + c_k y}{a_k + b_k x_k + c_k y_k}, \quad k = 1, 2, 3.$$

Finite Element Shape Functions and Barycentric Coordinates



$$x = \lambda_1 x_1 + \lambda_2 x_2 + \lambda_3 x_3,$$

$$y = \lambda_1 y_1 + \lambda_2 y_2 + \lambda_3 y_3,$$

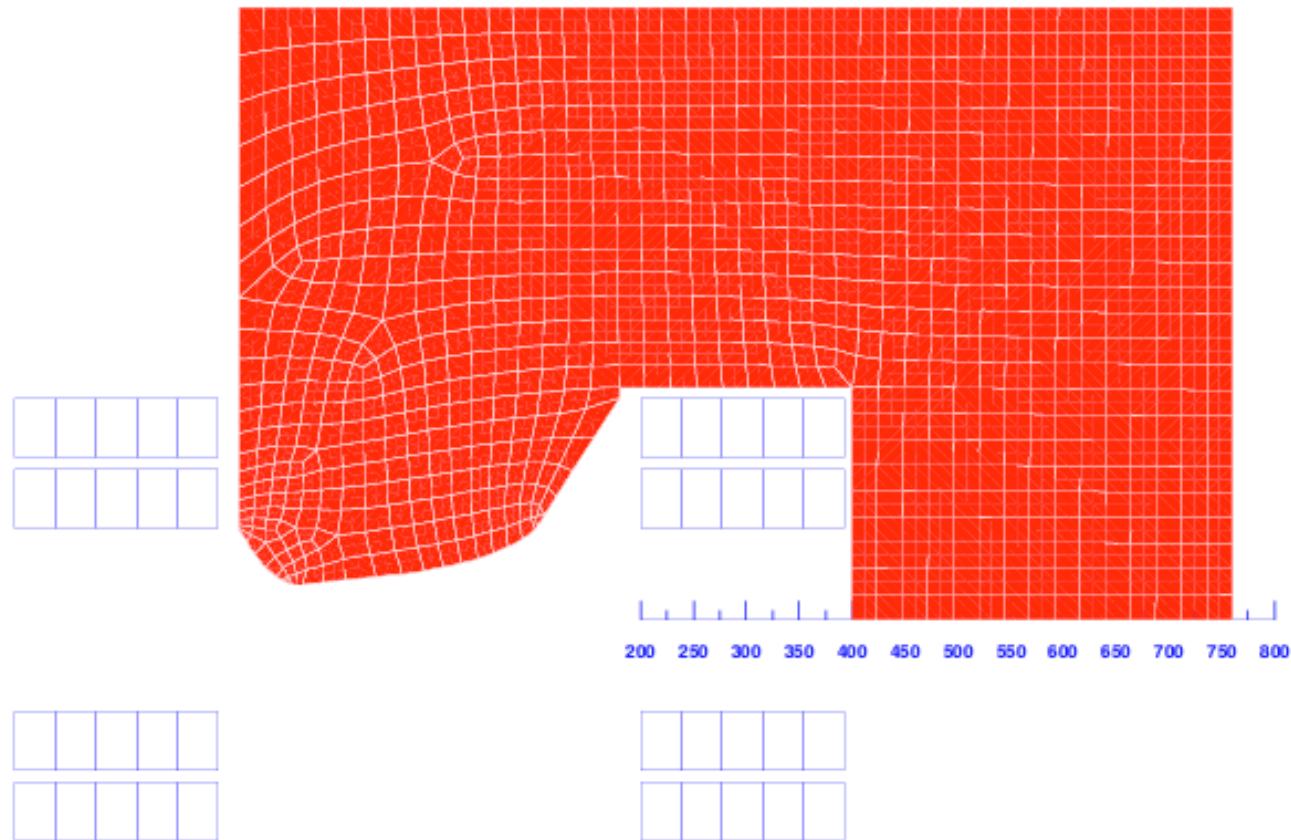
$$1 = \lambda_1 + \lambda_2 + \lambda_3.$$

$$\lambda_1 = \frac{S_{Q23}}{S_{123}},$$

$$\lambda_2 = \frac{S_{Q31}}{S_{123}},$$

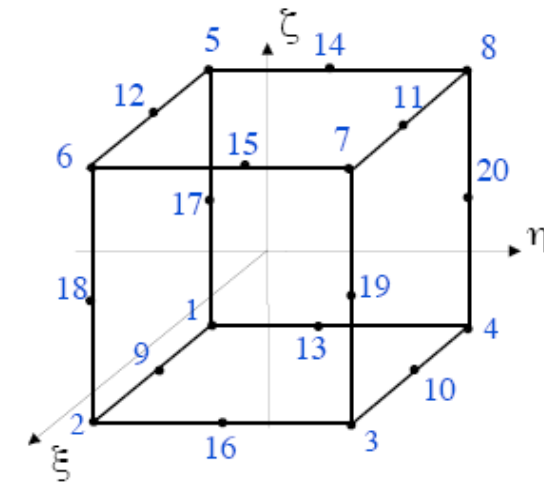
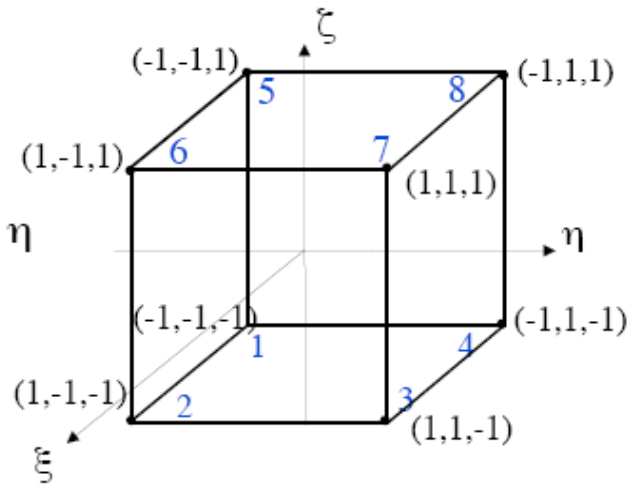
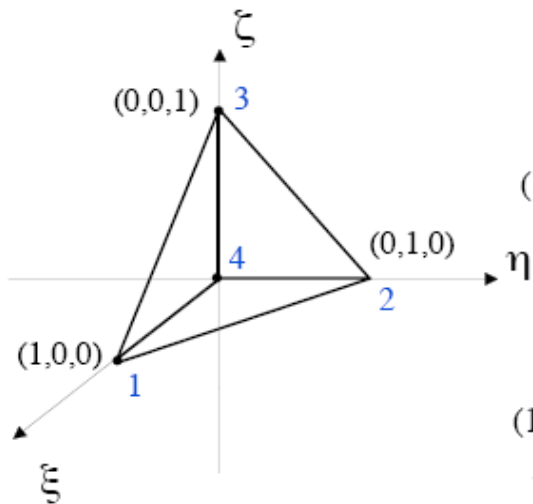
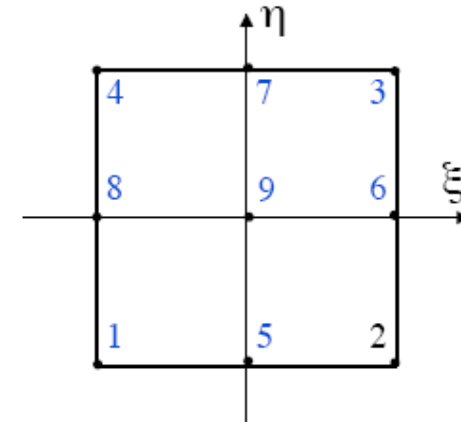
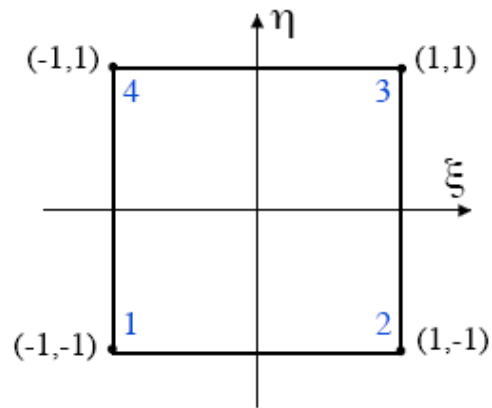
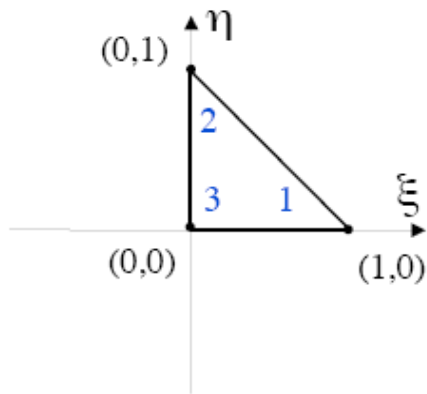
$$\lambda_3 = \frac{S_{Q12}}{S_{123}}$$

Higher Order Elements

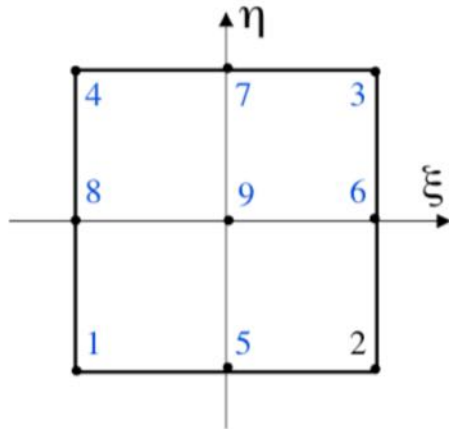


Higher accuracy of the field solution, but also better modeling of the iron contour

Parent Elements



Pascal Triangle



$$N_{1,2,3,4} = \frac{1}{4}(1 + \zeta\bar{\zeta}_k)(1 + \eta\eta_k)(\zeta\bar{\zeta}_k + \eta\eta_k - 1),$$

$$N_{5,7} = \frac{1}{2}(1 - \zeta^2)(1 + \eta\eta_k),$$

$$N_{6,8} = \frac{1}{2}(1 + \zeta\bar{\zeta}_k)(1 - \eta^2).$$

$$N_9 = (1 - \zeta^2)(1 - \eta^2).$$

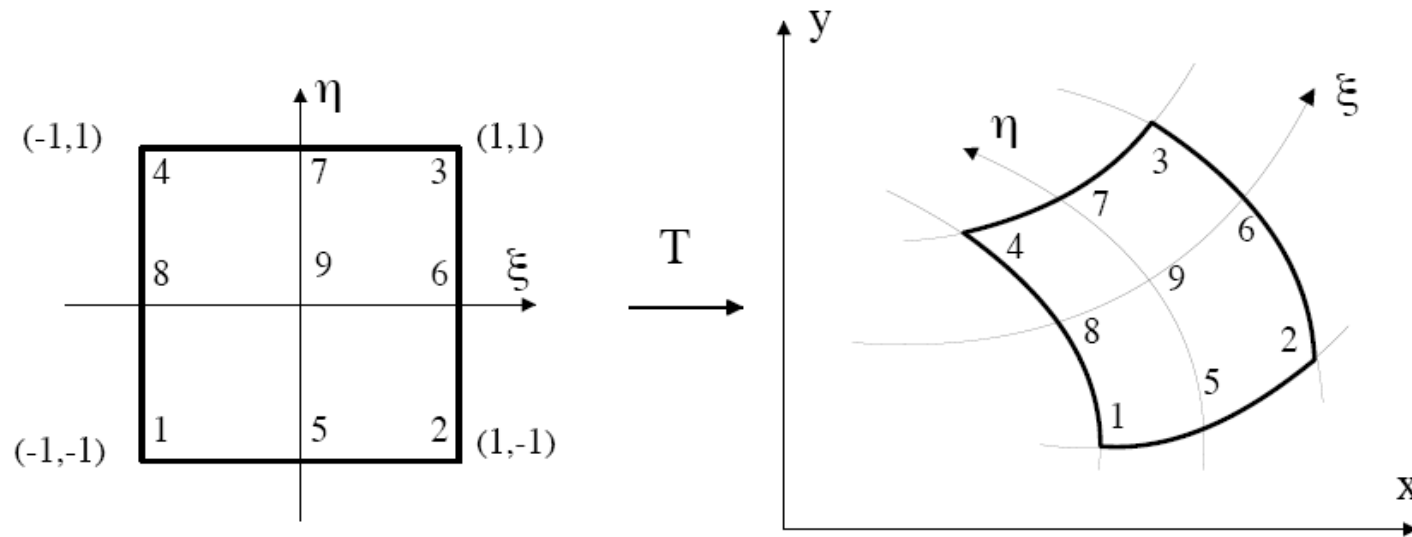
					1					
			ζ^2	ζ	$2\zeta\eta$	η	η^2			
	ζ^4	ζ^3	$4\zeta^3\eta$	$3\zeta^2\eta$	$6\zeta^2\eta^2$	$3\zeta\eta^2$	η^3			
ζ^5		$5\zeta^4\eta$		$10\zeta^3\eta^2$		$10\zeta^2\eta^3$	$4\zeta\eta^3$	$5\zeta\eta^4$	η^4	
									η^5	

Mapped Elements

$$x = x(\xi, \eta, \zeta),$$

$$y = y(\xi, \eta, \zeta),$$

$$z = z(\xi, \eta, \zeta)$$



$$A_j(\xi) = \sum_{k=1}^K N_k(\xi) A^{(k)}$$

$$x_j(\xi) = \sum_{k=1}^K N_k(\xi) x^{(k)}$$

$$y_j(\xi) = \sum_{k=1}^K N_k(\xi) y^{(k)}$$

Use of the same shape functions for the transformation of the elements

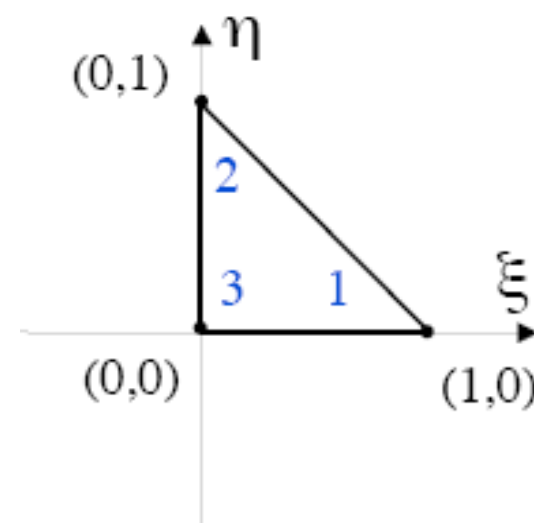
Transformation of Differential Operators

$$\frac{\partial N_k}{\partial x} = \frac{\partial N_k}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial N_k}{\partial \eta} \frac{\partial \eta}{\partial x}$$

Complicated

Easy

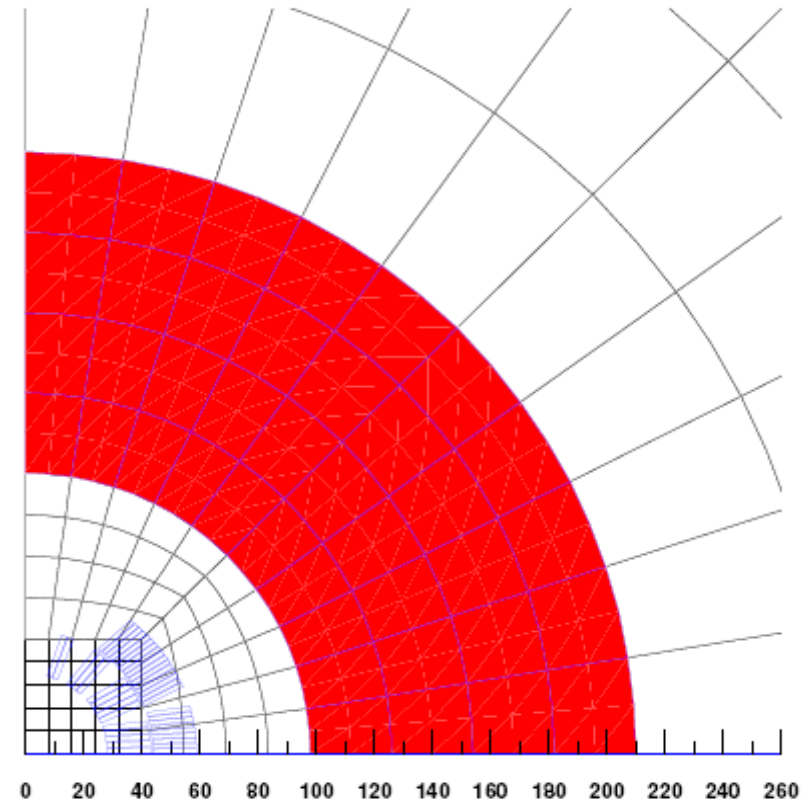
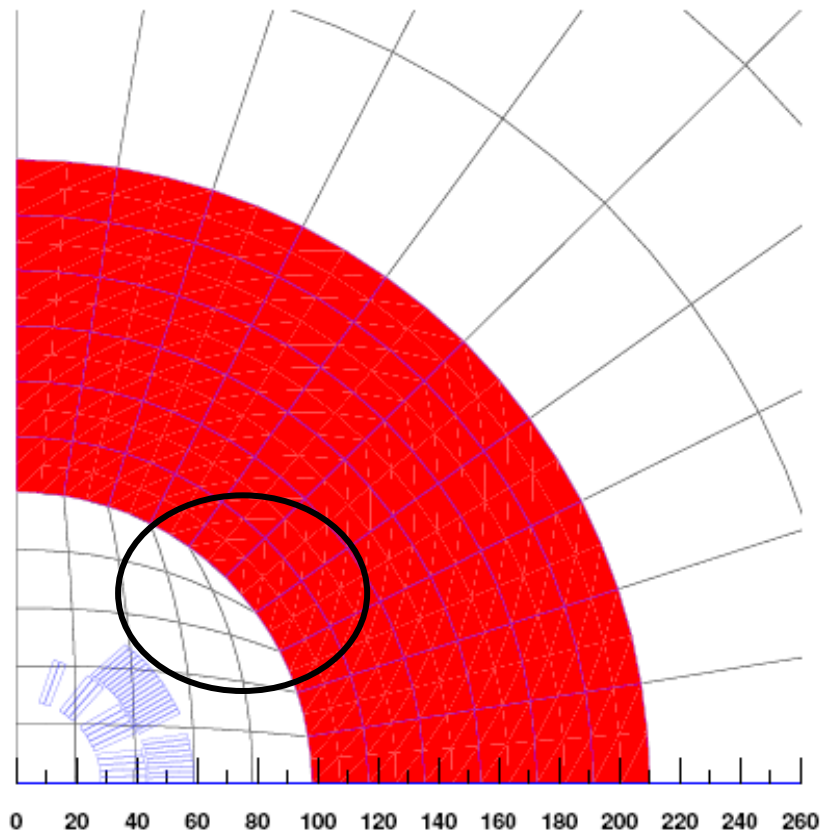
$$\begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix} N_k = \begin{pmatrix} \frac{\partial \xi}{\partial x} & \frac{\partial \eta}{\partial x} \\ \frac{\partial \xi}{\partial y} & \frac{\partial \eta}{\partial y} \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial \xi} \\ \frac{\partial}{\partial \eta} \end{pmatrix} N_k = [J]_{T^{-1}} \begin{pmatrix} \frac{\partial}{\partial \xi} \\ \frac{\partial}{\partial \eta} \end{pmatrix} N_k$$



$$[J]_{T^{-1}} = \begin{pmatrix} \frac{\partial \xi}{\partial x} & \frac{\partial \eta}{\partial x} \\ \frac{\partial \xi}{\partial y} & \frac{\partial \eta}{\partial y} \end{pmatrix} = \begin{pmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{pmatrix}^{-1} = [J]_T^{-1}$$

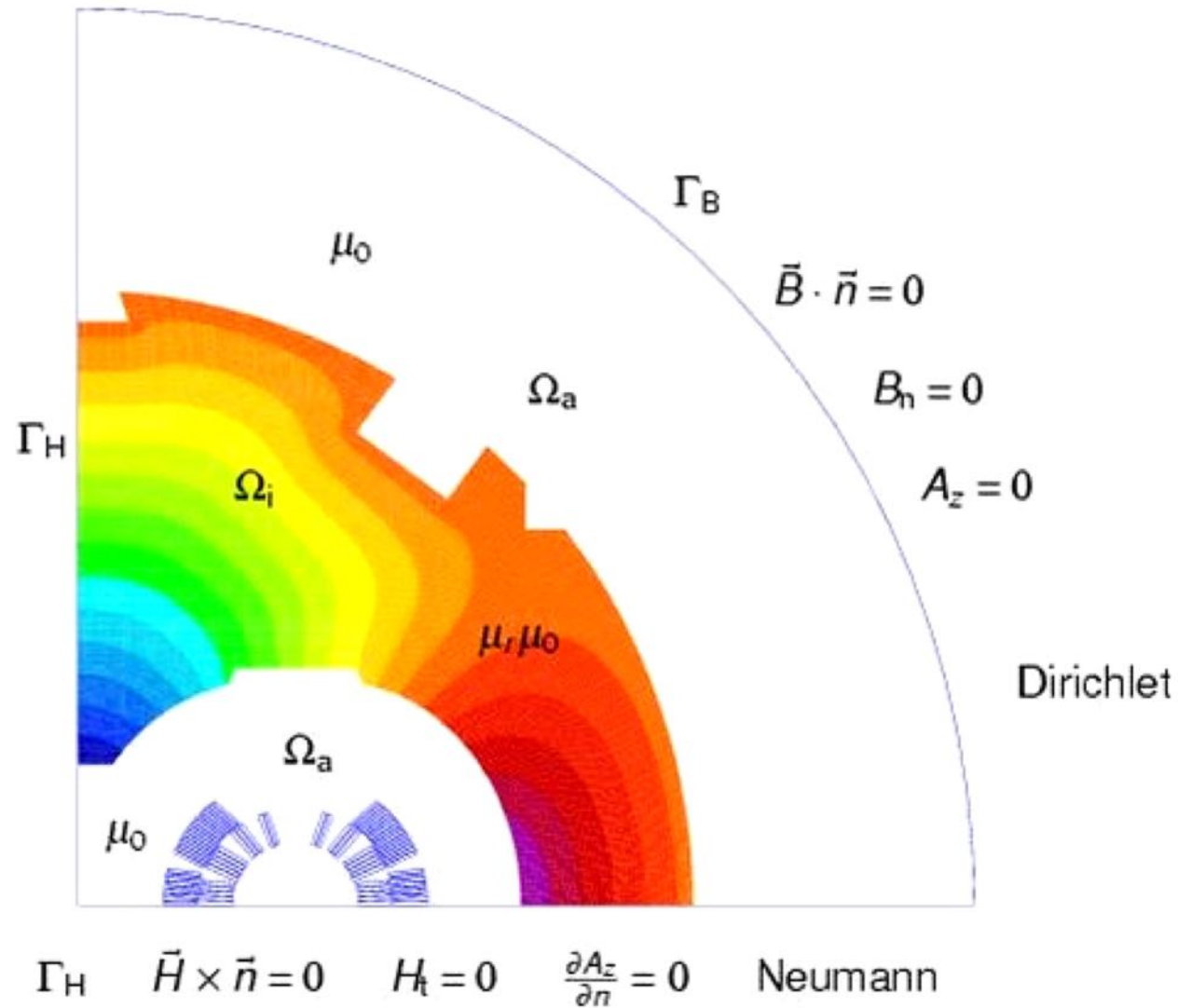
$$[J]_T = \begin{pmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{pmatrix} = \begin{pmatrix} \sum_{k=1}^K \frac{\partial N_k}{\partial \xi} x^{(k)} & \sum_{k=1}^K \frac{\partial N_k}{\partial \xi} y^{(k)} \\ \sum_{k=1}^K \frac{\partial N_k}{\partial \eta} x^{(k)} & \sum_{k=1}^K \frac{\partial N_k}{\partial \eta} y^{(k)} \end{pmatrix} = \begin{pmatrix} \frac{\partial N_1}{\partial \xi} & \frac{\partial N_2}{\partial \xi} & \dots & \frac{\partial N_K}{\partial \xi} \\ \frac{\partial N_1}{\partial \eta} & \frac{\partial N_2}{\partial \eta} & \dots & \frac{\partial N_K}{\partial \eta} \end{pmatrix} \begin{pmatrix} x_1 & y_1 \\ x_2 & y_2 \\ \vdots & \vdots \\ x_k & u_k \end{pmatrix}$$

Collinear Sides yield Singular Jacobi Matrices



Note: Bad meshing is not a trivial offence

The Problem Domain



Curl-Curl Equation

$$\mathbf{B} = \text{curl } \mathbf{A} \quad \text{in } \Omega$$

$$\text{curl } \frac{1}{\mu} \text{curl } \mathbf{A} = \mathbf{J} \quad \text{in } \Omega$$

$$\mathbf{H}_t = \mathbf{0} \quad \rightarrow \quad \frac{1}{\mu} (\text{curl } \mathbf{A}) \times \mathbf{n} = \mathbf{0} \quad \text{on } \Gamma_H$$

$$B_n = 0 \quad \rightarrow \quad \mathbf{B} \cdot \mathbf{n} = \text{curl } \mathbf{A} \cdot \mathbf{n} = 0 \quad \text{on } \Gamma_B$$

$$\left[\frac{1}{\mu} (\text{curl } \mathbf{A}) \times \mathbf{n} \right]_{\text{ai}} = \mathbf{0} \quad \text{on } \Gamma_{\text{ai}}$$

$$[\mathbf{A}]_{\text{ai}} = \mathbf{0} \quad \text{on } \Gamma_{\text{ai}}$$

Problem in 3-D: Gauging

$$\mathbf{A} \rightarrow \mathbf{A}' : \mathbf{A}' = \mathbf{A} + \text{grad } \psi$$

$$\text{div } \mathbf{A}' = q$$

$$q = \text{div } \mathbf{A} + \nabla^2 \psi$$

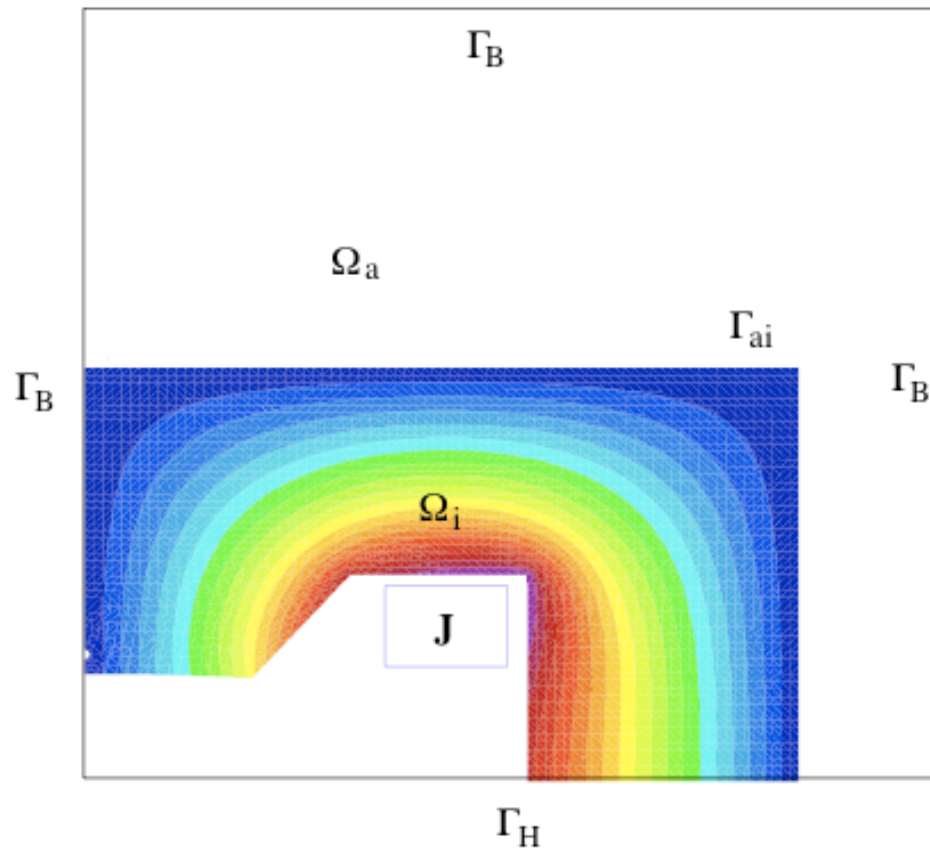
$$\frac{1}{\mu} \text{div } \mathbf{A} = 0 \quad \text{in } \Omega$$

$$\mathbf{A} \cdot \mathbf{n} = 0 \quad \text{on } \Gamma_H$$

$$\text{curl } \frac{1}{\mu} \text{curl } \mathbf{A} - \text{grad } \frac{1}{\mu} \text{div } \mathbf{A} = \mathbf{J} \quad \text{in } \Omega$$

Weak Form in the FEM Problem

$$\operatorname{curl} \frac{1}{\mu} \operatorname{curl} \mathbf{A} - \operatorname{grad} \frac{1}{\mu} \operatorname{div} \mathbf{A} = \mathbf{J} \quad \text{in } \Omega$$



$$\begin{aligned} \mathbf{A} \cdot \mathbf{n} &= 0 && \text{on } \Gamma_H, \\ \frac{1}{\mu} \operatorname{div} \mathbf{A} &= 0 && \text{on } \Gamma_B, \\ \mathbf{n} \times (\mathbf{A} \times \mathbf{n}) &= \mathbf{0} && \text{on } \Gamma_B, \\ \mathbf{n} \times \left(\frac{1}{\mu} (\operatorname{curl} \mathbf{A}) \times \mathbf{n} \right) &= \mathbf{0} && \text{on } \Gamma_H, \\ \left[\frac{1}{\mu} \operatorname{div} \mathbf{A} \right]_{\text{ai}} &= 0 && \text{on } \Gamma_{\text{ai}}, \\ \left[\frac{1}{\mu} (\operatorname{curl} \mathbf{A}) \times \mathbf{n} \right]_{\text{ai}} &= \mathbf{0} && \text{on } \Gamma_{\text{ai}}, \\ [\mathbf{A}]_{\text{ai}} &= \mathbf{0} && \text{on } \Gamma_{\text{ai}}. \end{aligned}$$

Weak Form in the FEM Problem

$$\operatorname{curl} \frac{1}{\mu} \operatorname{curl} \mathbf{A} - \operatorname{grad} \frac{1}{\mu} \operatorname{div} \mathbf{A} = \mathbf{J} \quad \text{in } \Omega$$

$$\operatorname{curl} \frac{1}{\mu} \operatorname{curl} \mathbf{A} - \operatorname{grad} \frac{1}{\mu} \operatorname{div} \mathbf{A} - \mathbf{J} = \mathbf{R}$$

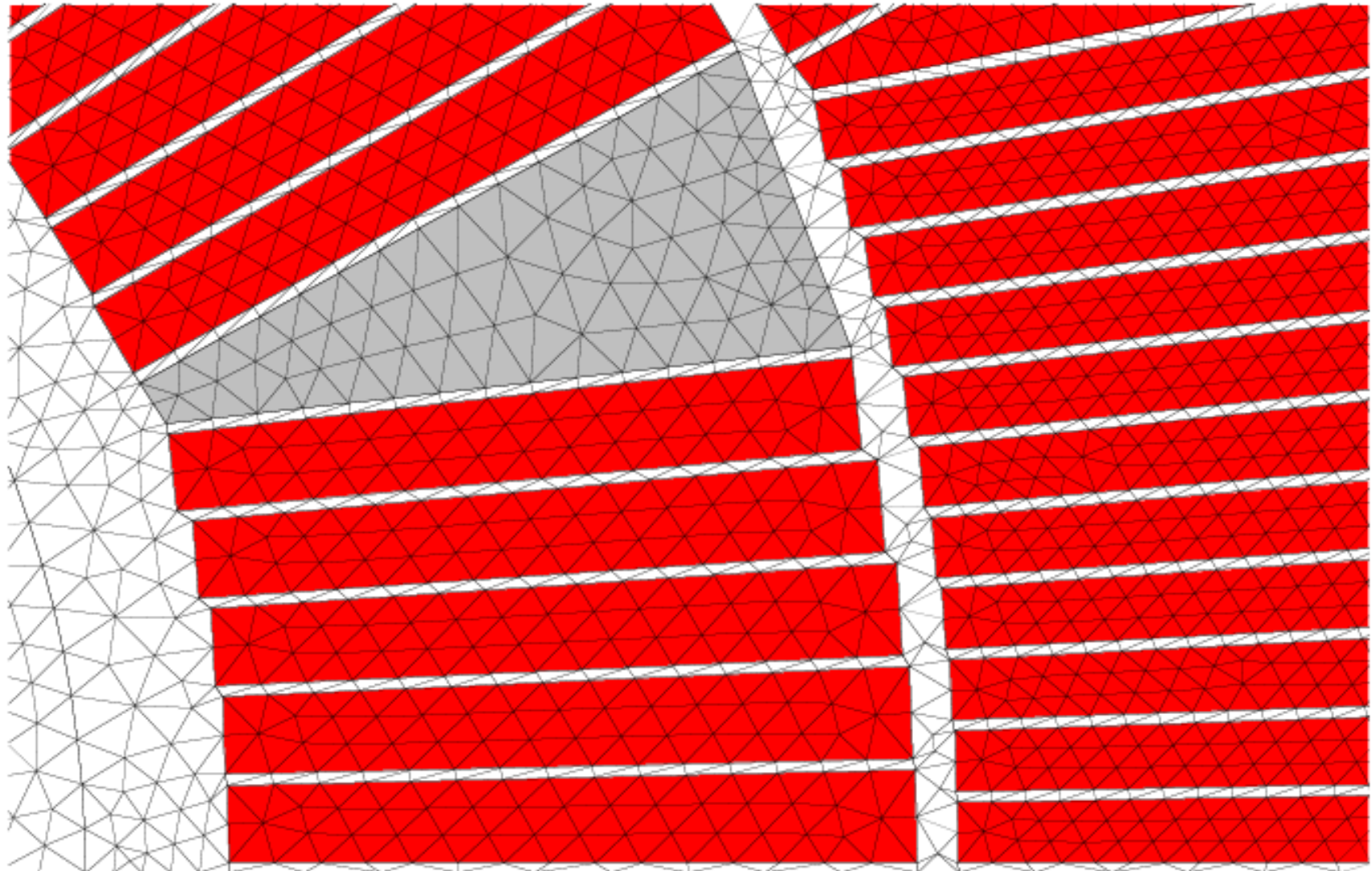
$$\int_{\Omega} \mathbf{w}_a \cdot \left(\operatorname{curl} \frac{1}{\mu} \operatorname{curl} \mathbf{A} - \operatorname{grad} \frac{1}{\mu} \operatorname{div} \mathbf{A} \right) d\Omega = \int_{\Omega} \mathbf{w}_a \cdot \mathbf{J} d\Omega, \quad a = 1, 2, 3.$$

Vector form of Greens theorem and integration by parts rule

$$\begin{aligned} & \int_{\Omega} \frac{1}{\mu} \operatorname{curl} \mathbf{A} \cdot \operatorname{curl} \mathbf{w}_a d\Omega - \int_{\Gamma_H} \frac{1}{\mu} (\operatorname{curl} \mathbf{A} \times \mathbf{n}) \cdot \mathbf{w}_a d\Gamma_H + \int_{\Omega} \frac{1}{\mu} \operatorname{div} \mathbf{A} \operatorname{div} \mathbf{w}_a d\Omega - \\ & \int_{\Gamma_B} \frac{1}{\mu} \operatorname{div} \mathbf{A} (\mathbf{n} \cdot \mathbf{w}_a) d\Gamma_B - \int_{\Gamma_{ai}} \left(\frac{1}{\mu} \operatorname{div} \mathbf{A}_i (\mathbf{n}_i \cdot \mathbf{w}_a) + \frac{1}{\mu_0} \operatorname{div} \mathbf{A}_a (\mathbf{n}_a \cdot \mathbf{w}_a) \right) d\Gamma_{ai} - \\ & \int_{\Gamma_{ai}} \left(\frac{1}{\mu} (\operatorname{curl} \mathbf{A}_i \times \mathbf{n}_i) + \frac{1}{\mu_0} (\operatorname{curl} \mathbf{A}_a \times \mathbf{n}_a) \right) \cdot \mathbf{w}_a d\Gamma_{ai} = \int_{\Omega} \mathbf{w}_a \cdot \mathbf{J} d\Omega, \end{aligned}$$

$$\int_{\Omega} \frac{1}{\mu} \operatorname{curl} \mathbf{w}_a \cdot \operatorname{curl} \mathbf{A} d\Omega + \int_{\Omega} \frac{1}{\mu} \operatorname{div} \mathbf{w}_a \operatorname{div} \mathbf{A} d\Omega = \int_{\Omega} \mathbf{w}_a \cdot \mathbf{J} d\Omega$$

Meshing the Coil



Reduced Vector Potential Formulation

$$\mathbf{A} = \mathbf{A}_S + \mathbf{A}_R$$

$$\mathbf{B} = \mu_0 \mathbf{H}_S + \text{curl } \mathbf{A}_R$$

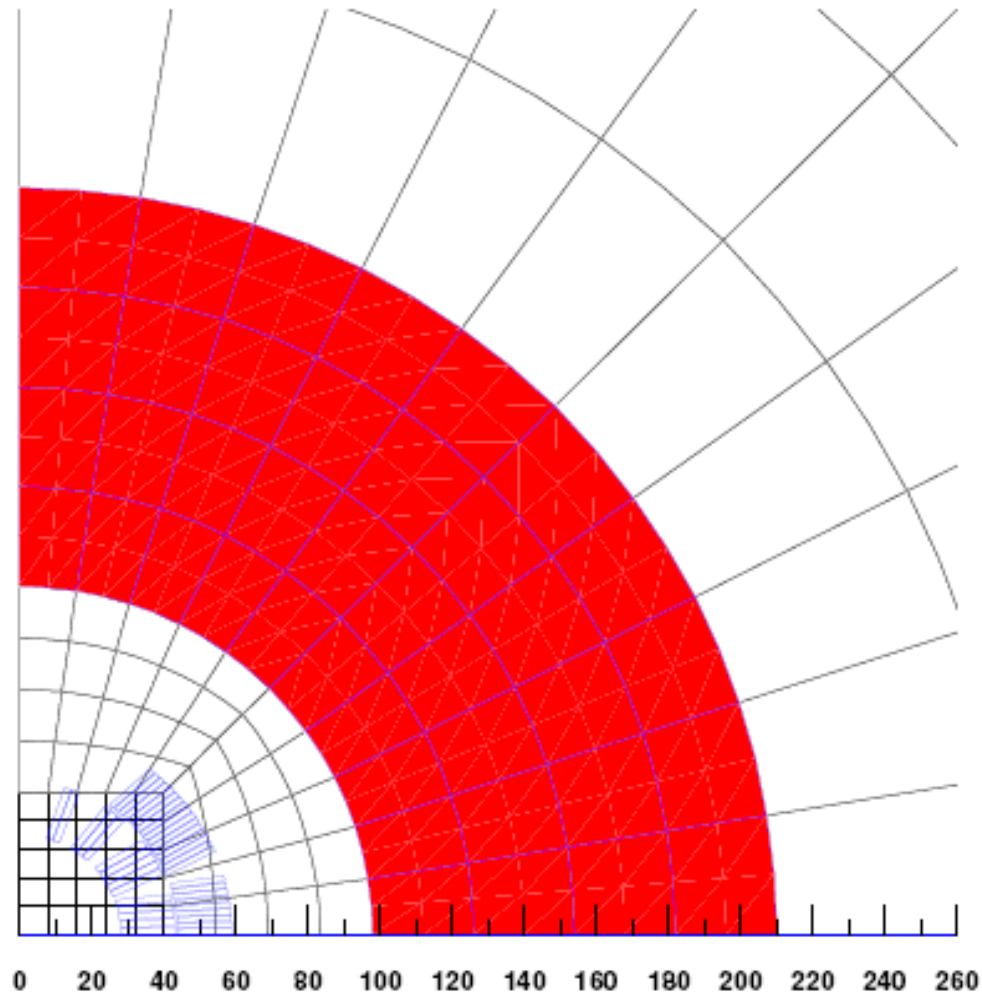
$$\text{curl } \frac{1}{\mu} \text{curl} (\mathbf{A}_R + \mathbf{A}_S) - \text{grad } \frac{1}{\mu} \text{div} (\mathbf{A}_R + \mathbf{A}_S) = \mathbf{J}$$

$$\begin{aligned} \text{curl } \frac{1}{\mu} \text{curl } \mathbf{A}_R - \text{grad } \frac{1}{\mu} \text{div } \mathbf{A}_R &= \mathbf{J} - \text{curl } \frac{1}{\mu} \text{curl } \mathbf{A}_S \\ &= \text{curl } \mathbf{H}_S - \text{curl } \frac{\mu_0}{\mu} \mathbf{H}_S \\ &= \text{curl} \left(\mathbf{H}_S - \frac{\mu_0}{\mu} \mathbf{H}_S \right) \end{aligned}$$

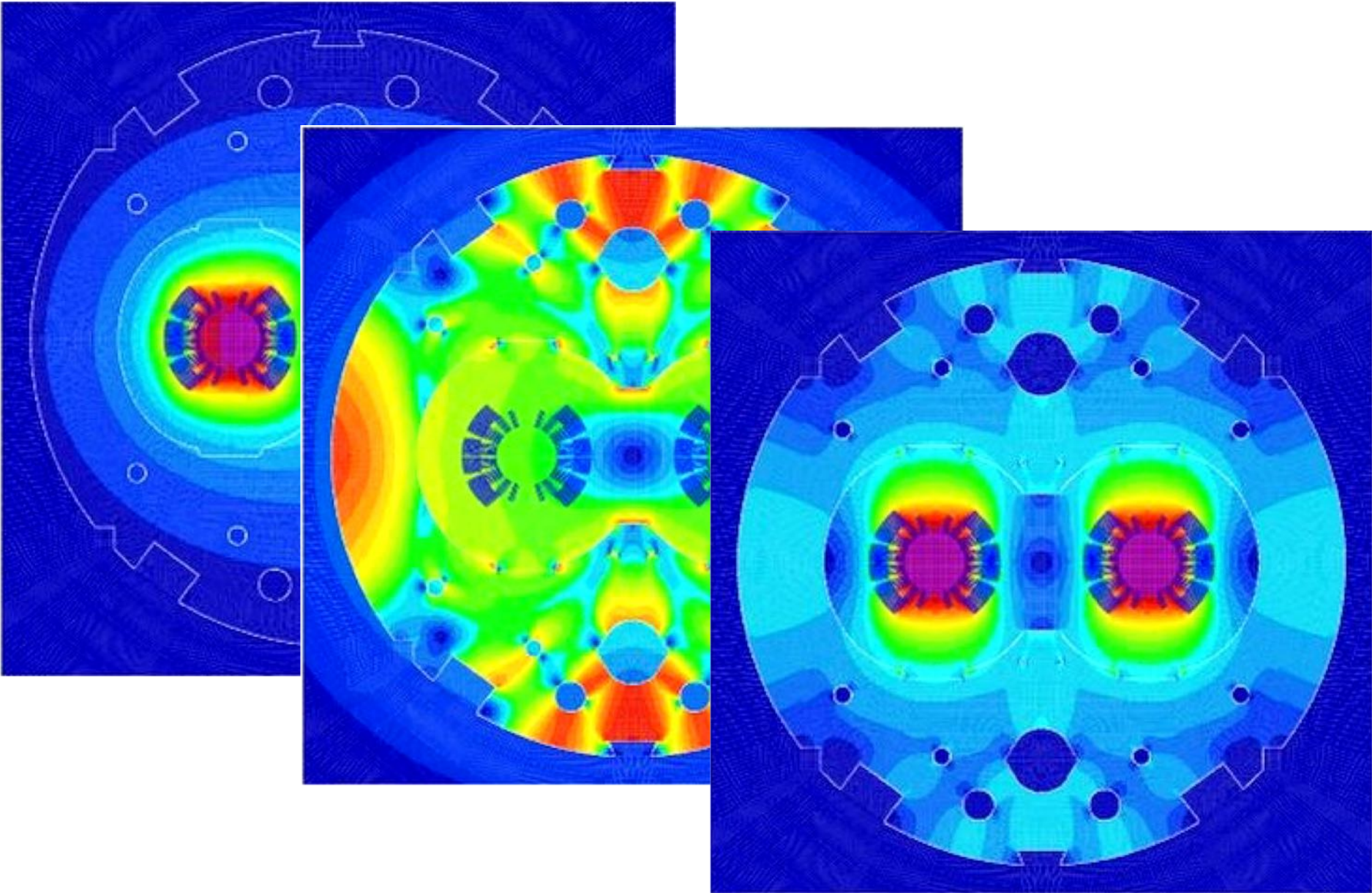
Weak form

$$\int_{\Omega} \text{curl } \mathbf{w}_a \cdot \frac{1}{\mu} \text{curl } \mathbf{A}_R \, d\Omega + \int_{\Omega} \text{div } \mathbf{w}_a \cdot \frac{1}{\mu} \text{div } \mathbf{A}_R \, d\Omega = \int_{\Omega} \text{curl } \mathbf{w}_a \cdot \left(\mathbf{H}_S - \frac{\mu_0}{\mu} \mathbf{H}_S \right) \, d\Omega$$

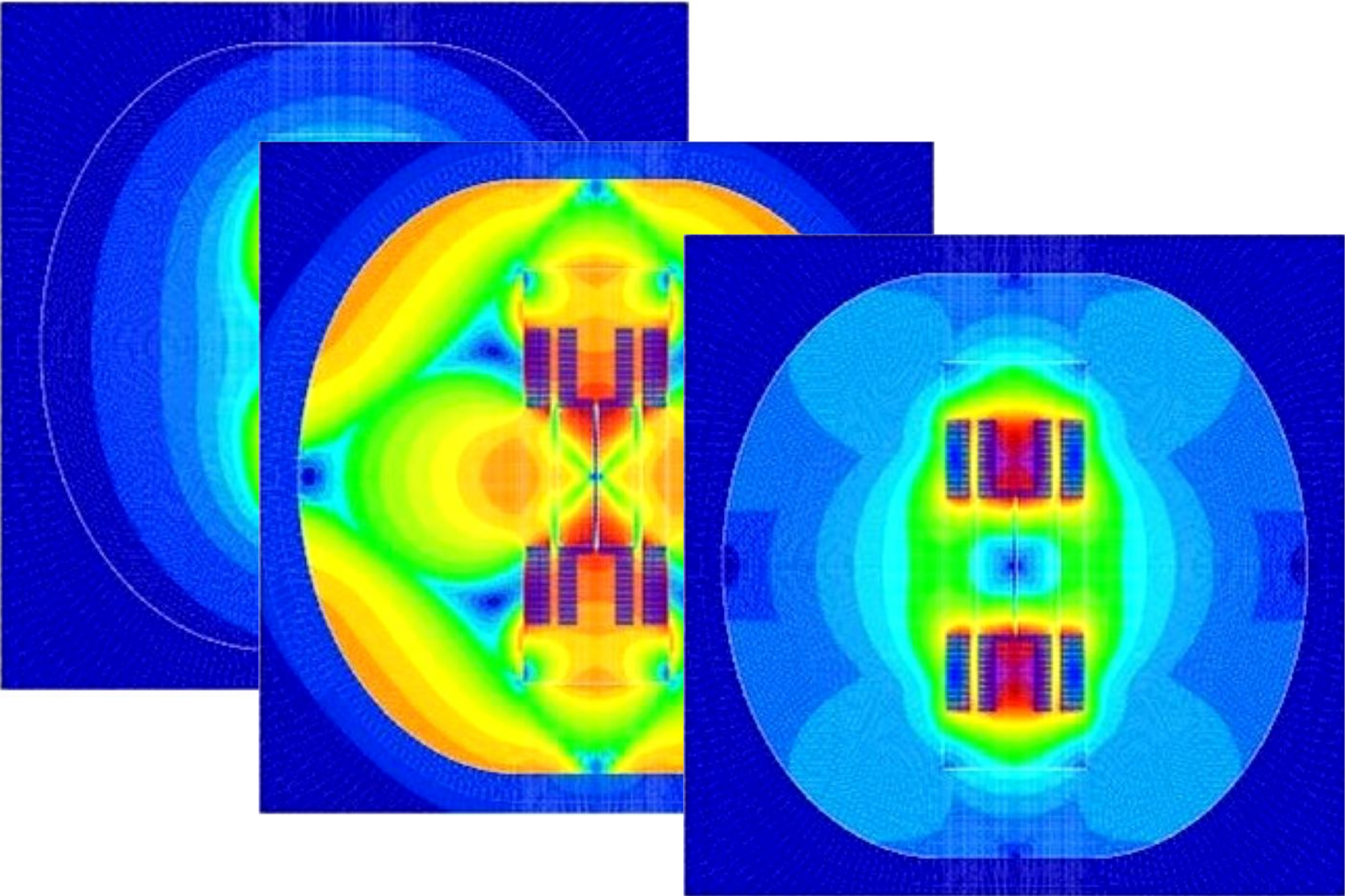
FEM Mesh for Reduced Vector Potential Formulation



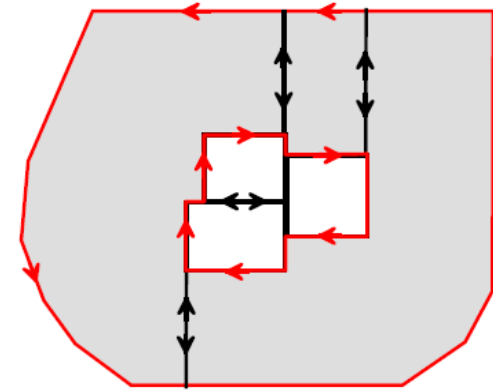
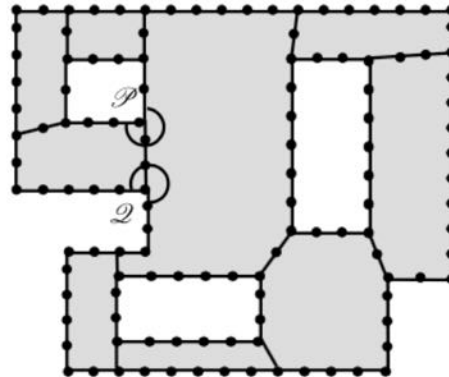
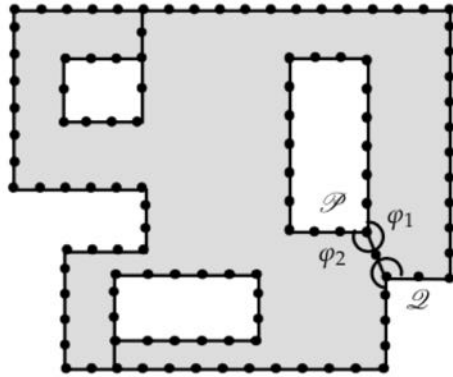
Source, Reduced, Total Field



Source, Reduced, Total Field



Topology Decomposition



$$\Gamma := \mathcal{P} + t(\mathcal{Q} - \tilde{\mathcal{P}})$$

$$\min\{f(\Gamma)\} = \min \{ \lambda_1 g_1(\Gamma) + \lambda_2 g_2(\Gamma) + \lambda_3 g_3(\Gamma) \}$$

$$g_1(\Gamma) := 4\pi - \varphi_1(\mathcal{P}) - \varphi_2(\mathcal{P}) - \varphi_1(\mathcal{Q}) - \varphi_2(\mathcal{Q}),$$

$$g_2(\Gamma) := \sum_{i=1}^2 \min \left\{ \varphi_i(\mathcal{P}) - \frac{\pi}{2}, \varphi_i(\mathcal{P}) - \pi, \varphi_i(\mathcal{P}) - \frac{3\pi}{2} \right\} \\ + \sum_{i=1}^2 \min \left\{ \varphi_i(\mathcal{Q}) - \frac{\pi}{2}, \varphi_i(\mathcal{Q}) - \pi, \varphi_i(\mathcal{Q}) - \frac{3\pi}{2} \right\}$$

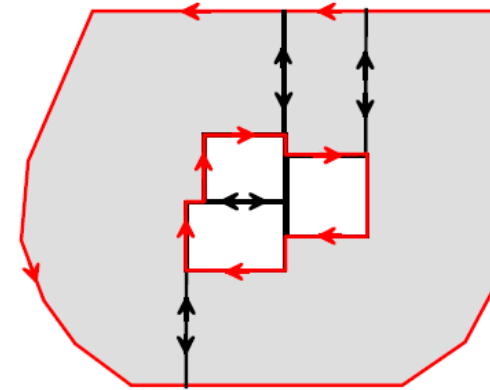
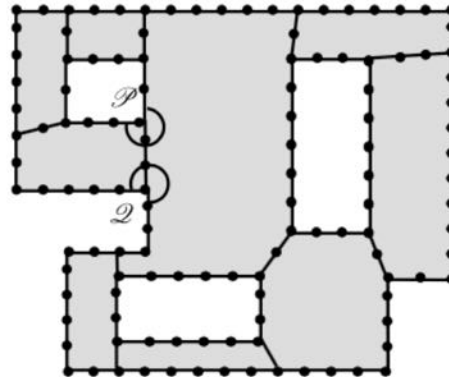
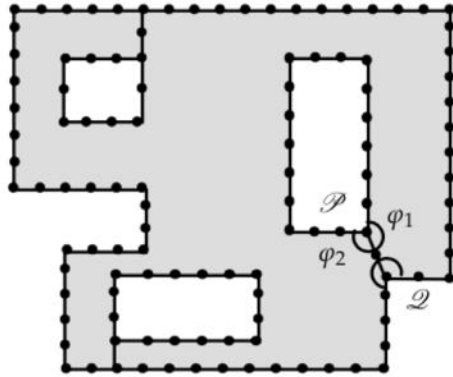
$$g_3(\Gamma) := L,$$

Max inner angle

Right angles between cutting edge and boundary

Minimum length

Topology Decomposition



$$\min\{f(\Gamma)\} = \min \{ \lambda_1 g_1(\Gamma) + \lambda_2 g_2(\Gamma) + \lambda_3 g_3(\Gamma) + \lambda_4 g_4(\Gamma) \}$$

$$g_1(\Gamma) := 4\pi - \varphi_1(\mathcal{P}) - \varphi_2(\mathcal{P}) - \varphi_1(\mathcal{Q}) - \varphi_2(\mathcal{Q}),$$

$$g_2(\Gamma) := \sum_{i=1}^2 \min \left\{ \varphi_i(\mathcal{P}) - \frac{\pi}{2}, \varphi_i(\mathcal{P}) - \pi, \varphi_i(\mathcal{P}) - \frac{3\pi}{2} \right\} \\ + \sum_{i=1}^2 \min \left\{ \varphi_i(\mathcal{Q}) - \frac{\pi}{2}, \varphi_i(\mathcal{Q}) - \pi, \varphi_i(\mathcal{Q}) - \frac{3\pi}{2} \right\}$$

$$g_3(\Gamma) := \frac{L^2}{\min\{a_1, a_2\}},$$

$$g_4(\Gamma) := \frac{L}{\min\{C_1, C_2\}}$$

$$\Gamma := \mathcal{P} + t(\mathcal{Q} - \tilde{\mathcal{P}})$$

Max inner angle

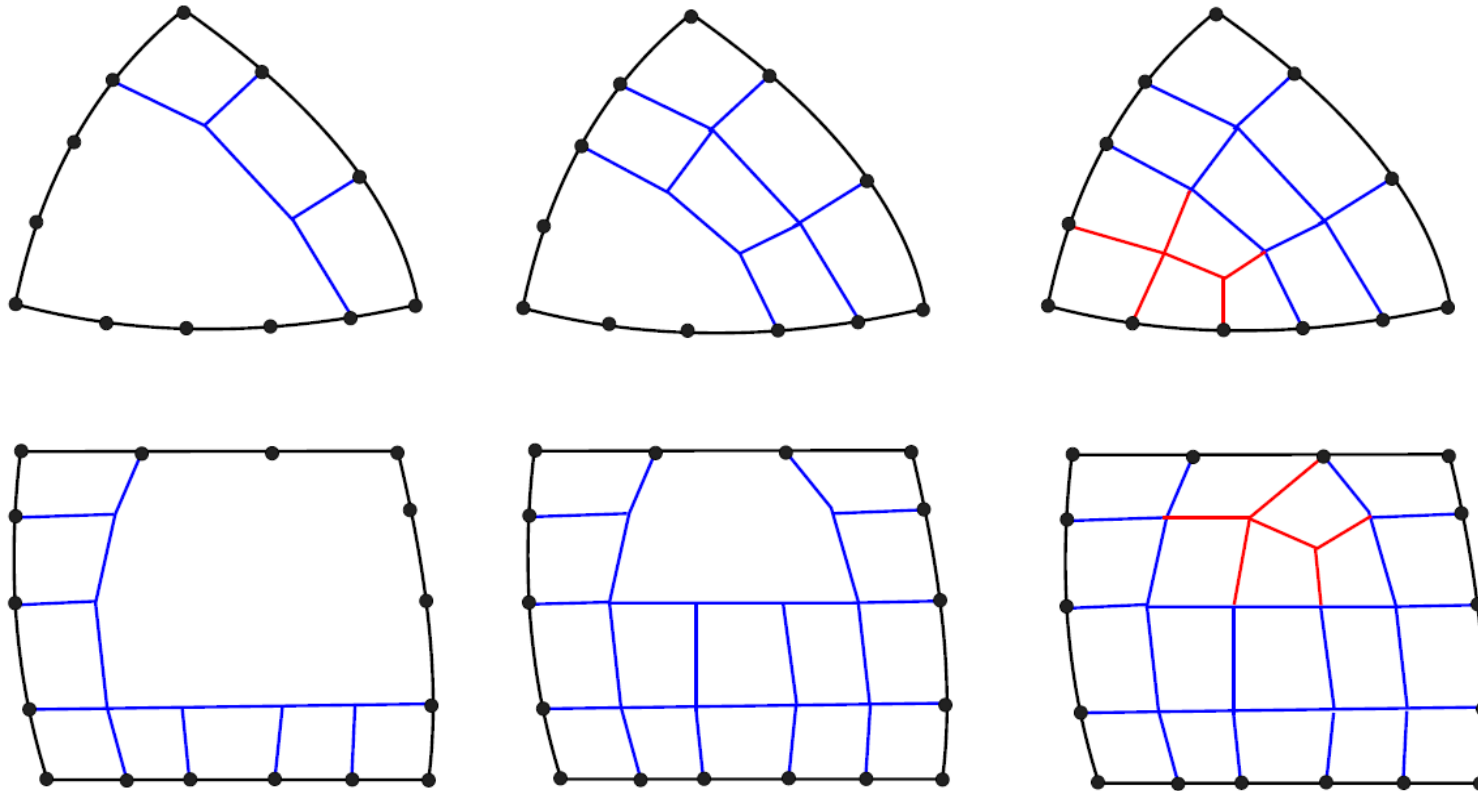
Right angles between cutting edge and boundary

Short edge / large surfaces

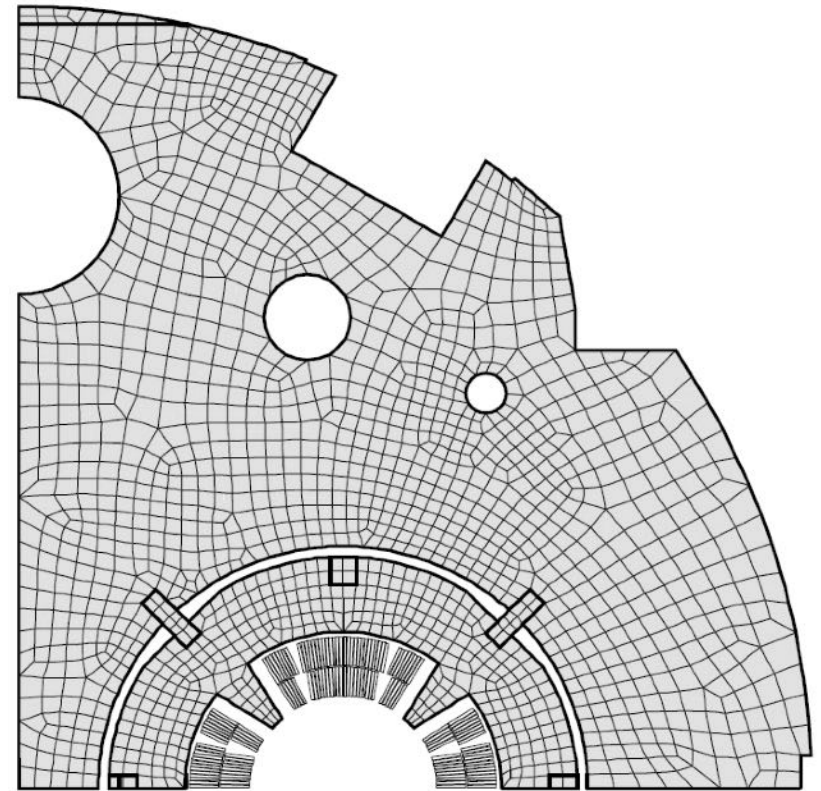
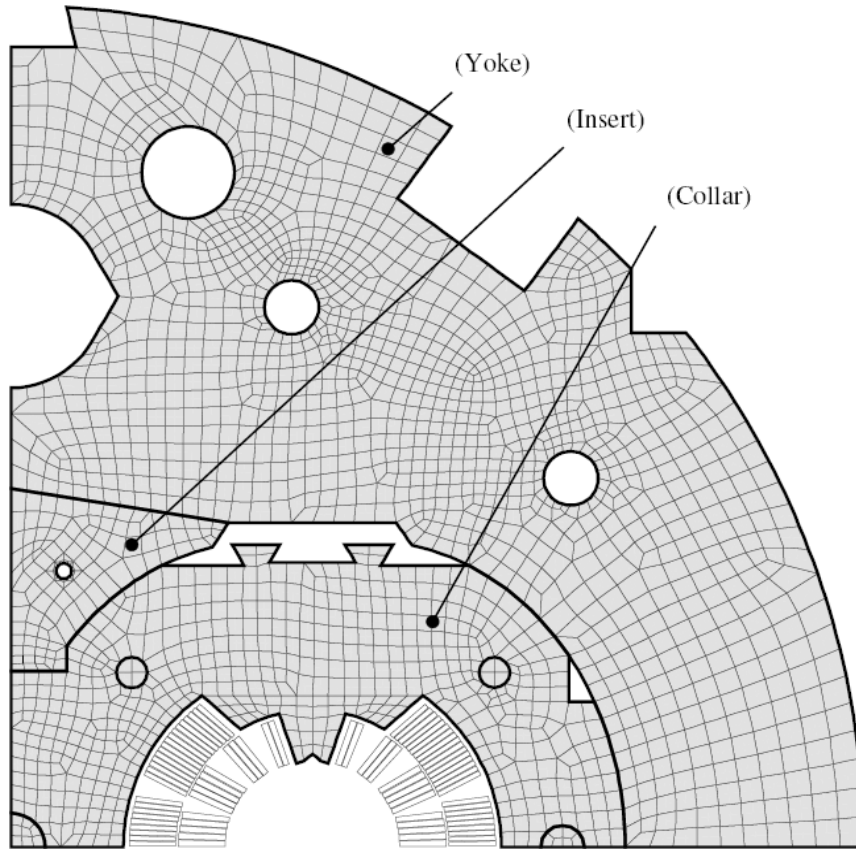
Short edge / large surface boundary

Paving and Mesh Closing in Simple Domains

- The number of nodes is less than 6
- The domain does not contain “bottlenecks”, i.e., C^2/a approaches 4π
- The biggest inner angle is less than π
- For triangles: $a+b < c$



Examples for FEM Meshes



Point-Based Morphing



Source: [steven.codes / Face Morphing](#)

25-35 yrs

35-45 yrs

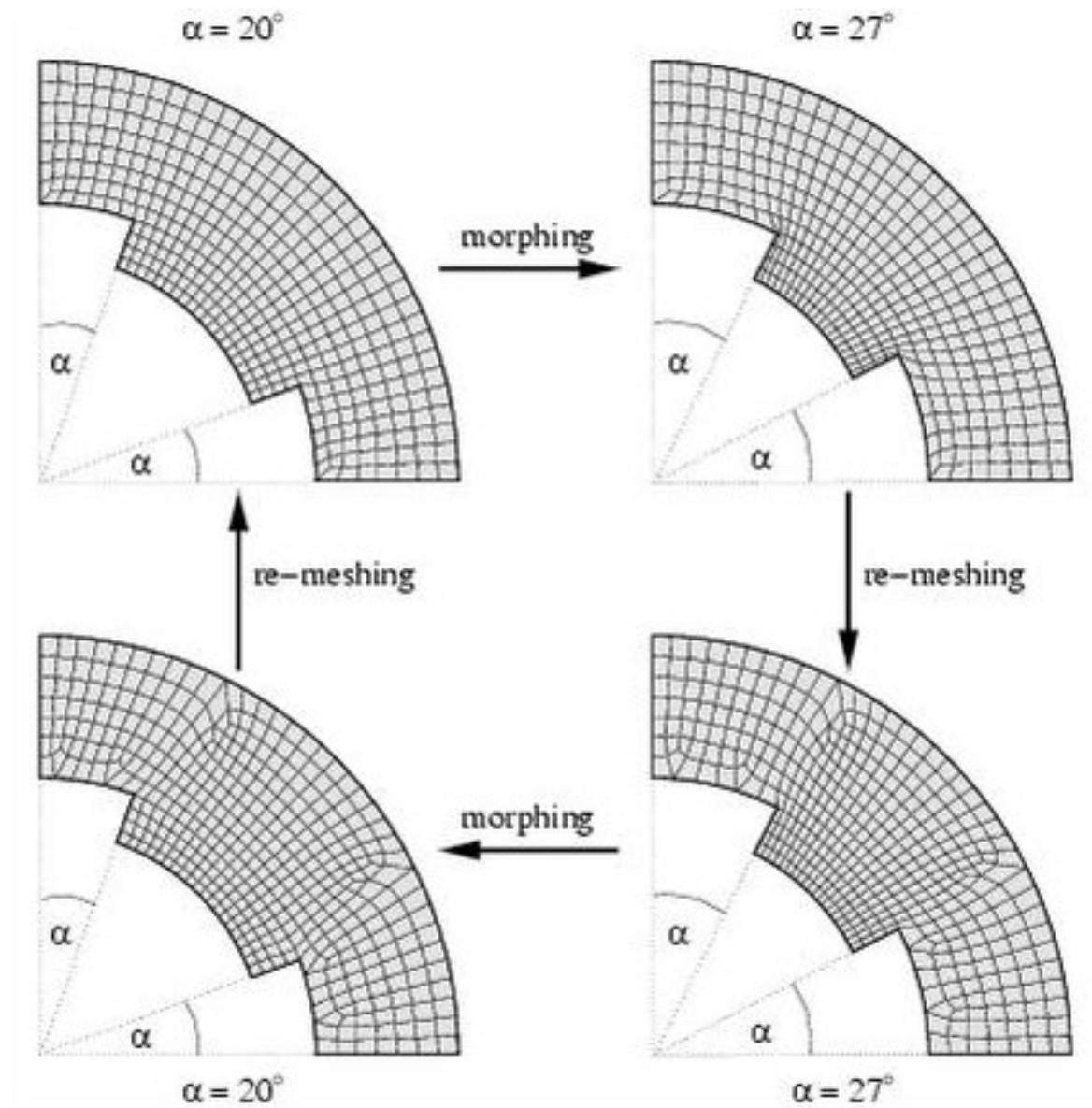
45-55 yrs

55-65 yrs

65-75 yrs

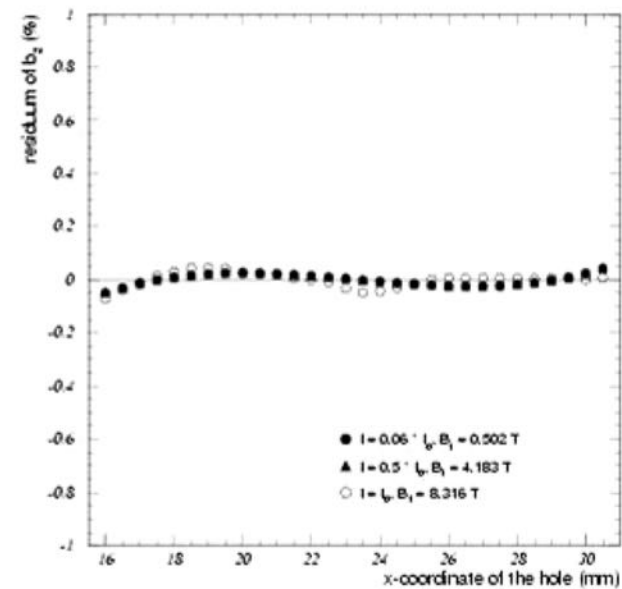
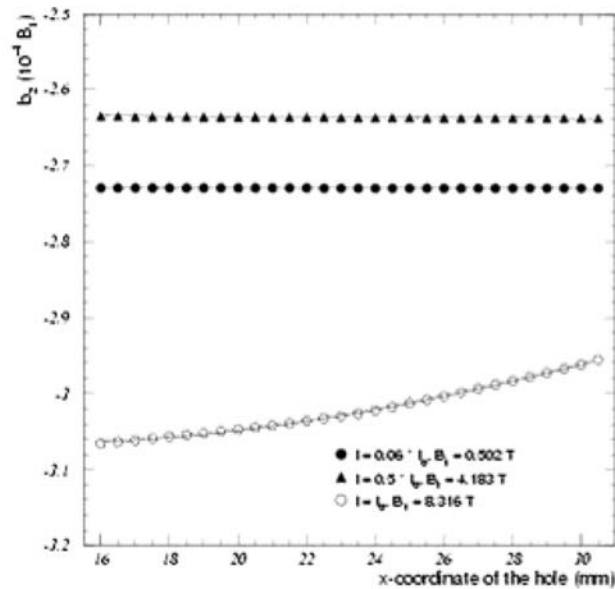
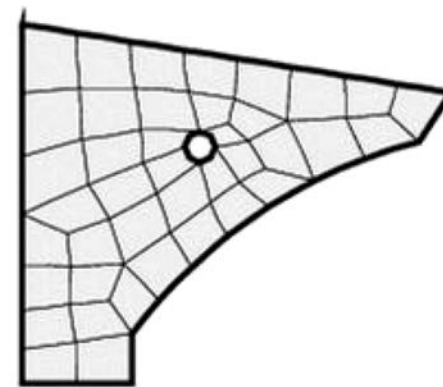
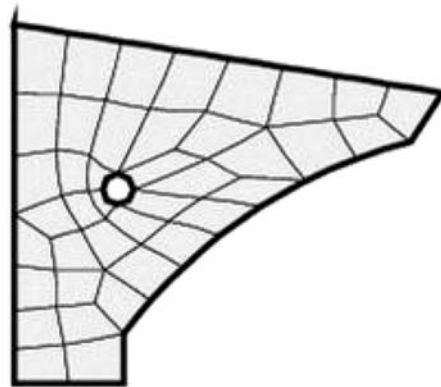


Point Based Morphing

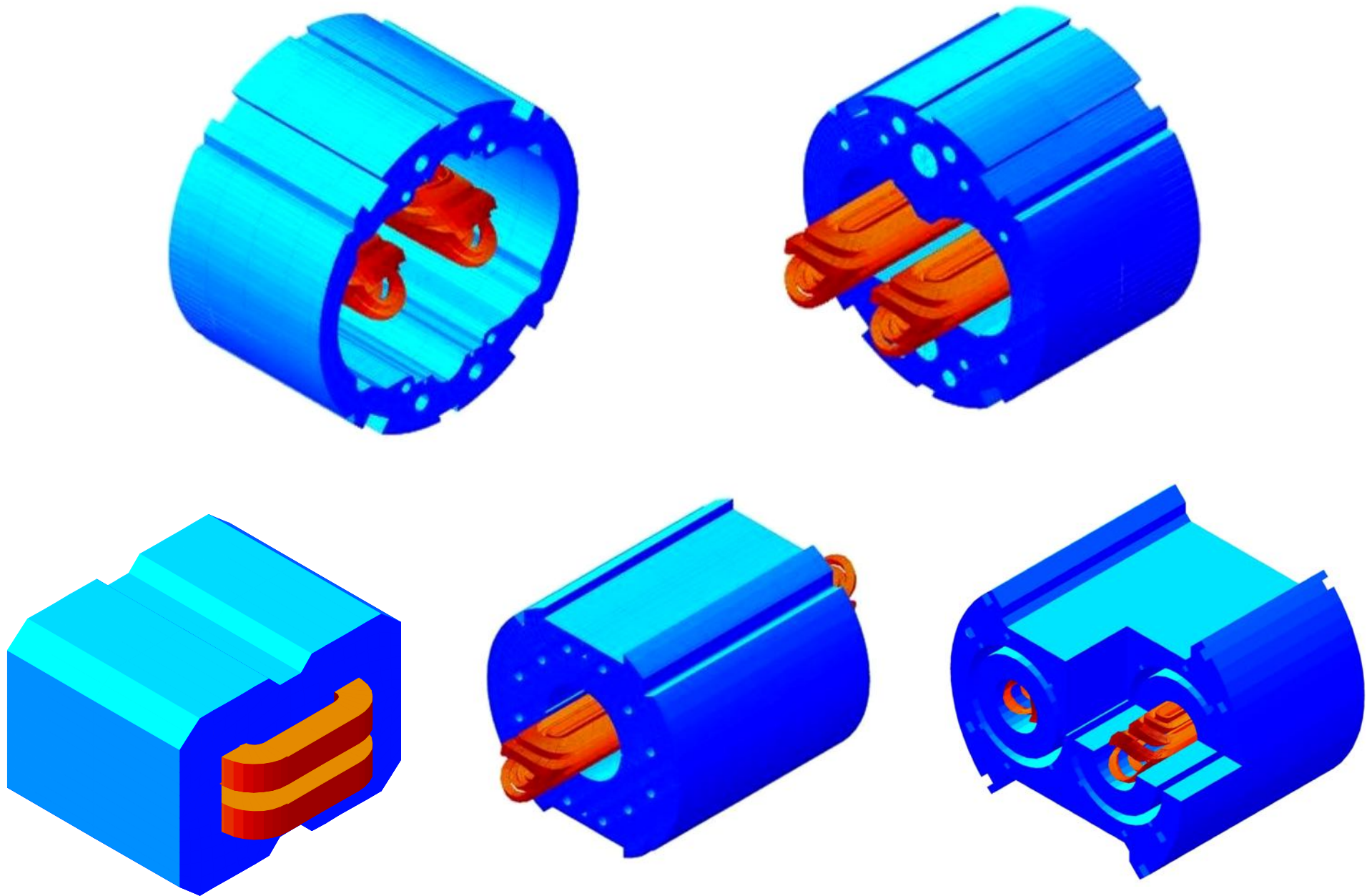


Point Based Morphing

$$\vec{s}(Q) = \sum_{i=1}^n \frac{\vec{s}(P_i) \cdot w_i}{|\vec{r}(Q) - \vec{r}(P_i)|} \left(\sum_{i=1}^n \frac{w_i}{|\vec{r}(Q) - \vec{r}(P_i)|} \right)^{-1}$$



Magnet Extremities



$$\text{curl } \mathbf{H} = 0$$

$$\mathbf{H} = -\text{grad } \phi_m \quad \text{in } \Omega, \mathbf{J} = 0$$

$$\text{div} (\mu \text{grad } \phi_m) = 0 \quad \text{in } \Omega, \mathbf{J} = 0$$

$$\mu_0 \text{div grad } \phi_m = 0 \quad \text{in } \Omega_a, \mathbf{J} = 0$$

$$\nabla^2 \phi_m = 0 \quad \text{in } \Omega_a, \mathbf{J} = 0$$

$$\mathbf{H}_t = \mathbf{0} \quad \rightarrow \quad \mathbf{n} \times (\text{grad } \phi_m \times \mathbf{n}) = \mathbf{0} \quad \text{on } \Gamma_H$$

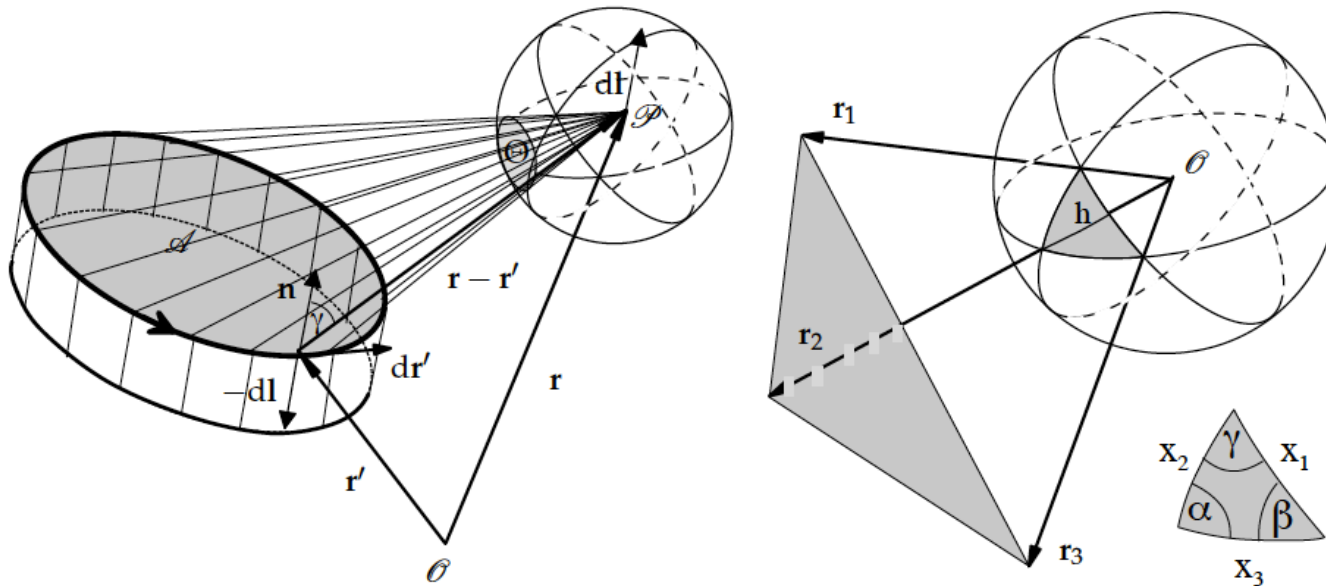
$$B_n = 0 \quad \rightarrow \quad \mu \mathbf{n} \cdot \text{grad } \phi_m = 0 \quad \text{on } \Gamma_B$$

$$[\mu \mathbf{n} \cdot \text{grad } \phi_m]_{ai} = 0 \quad \text{on } \Gamma_{ai}$$

$$[\text{grad } \phi_m \times \mathbf{n}]_{ai} = \mathbf{0} \quad \text{on } \Gamma_{ai}$$

Solid Angle and Magnetic Scalar Potential

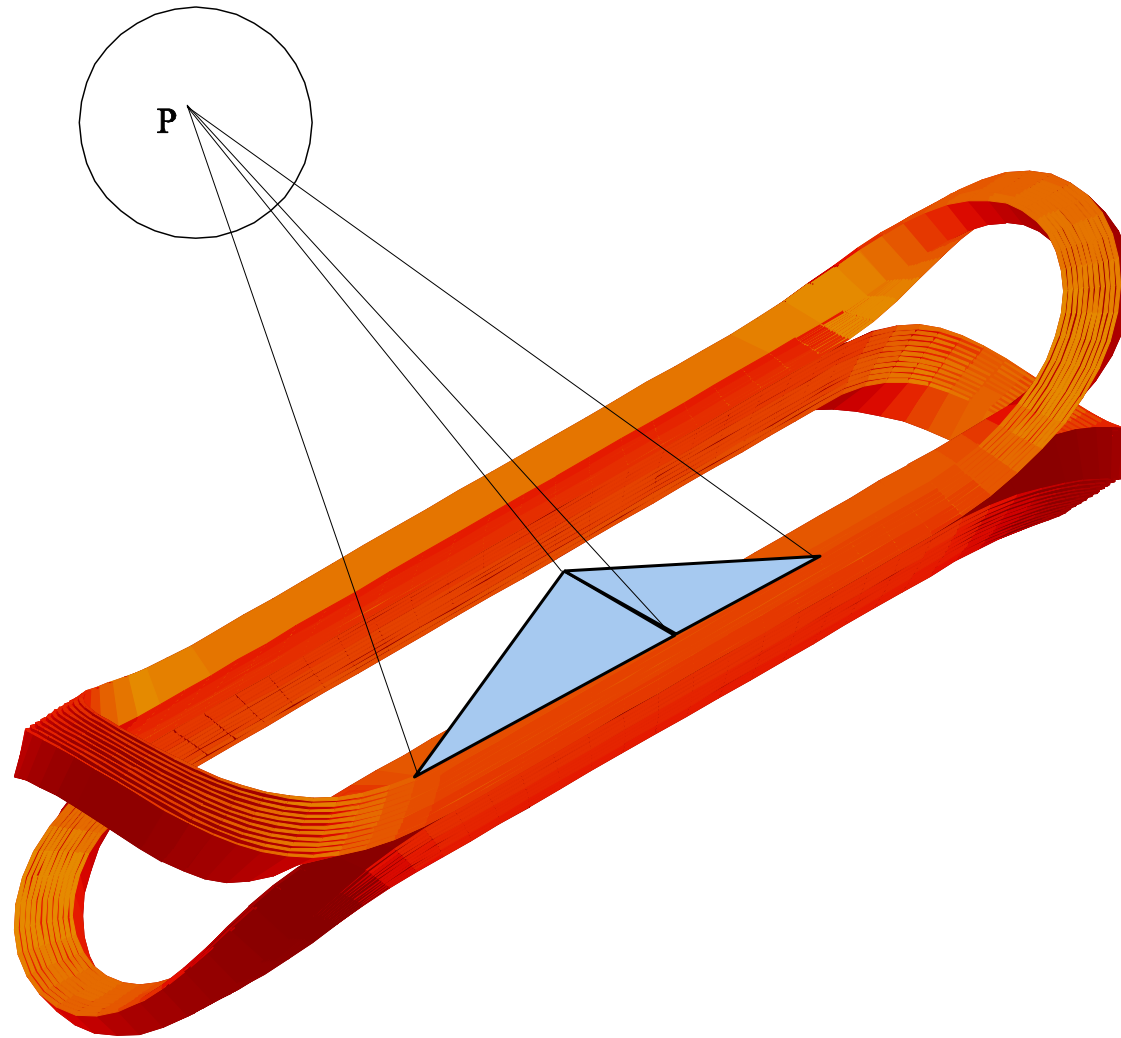
Solid angle (easy to compute) gives the magnetic scalar potential of a current loop



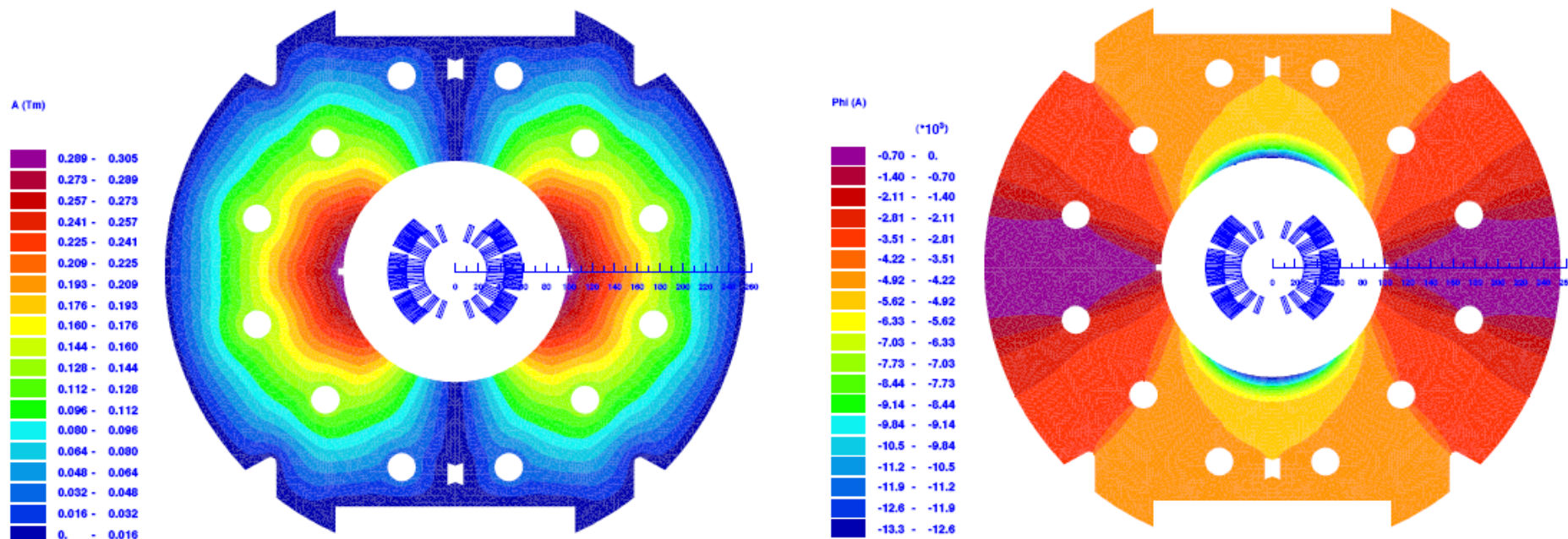
$$\phi_m(\mathbf{r}) = \frac{I}{4\pi} \Theta.$$

$$\tan\left(\frac{\Theta}{2}\right) = \frac{\mathbf{r}_1 \cdot (\mathbf{r}_2 \times \mathbf{r}_3)}{r_1 r_2 r_3 + (\mathbf{r}_1 \cdot \mathbf{r}_2) r_3 + (\mathbf{r}_1 \cdot \mathbf{r}_3) r_2 + (\mathbf{r}_2 \cdot \mathbf{r}_3) r_1}.$$

Total Magnetic Scalar Potential

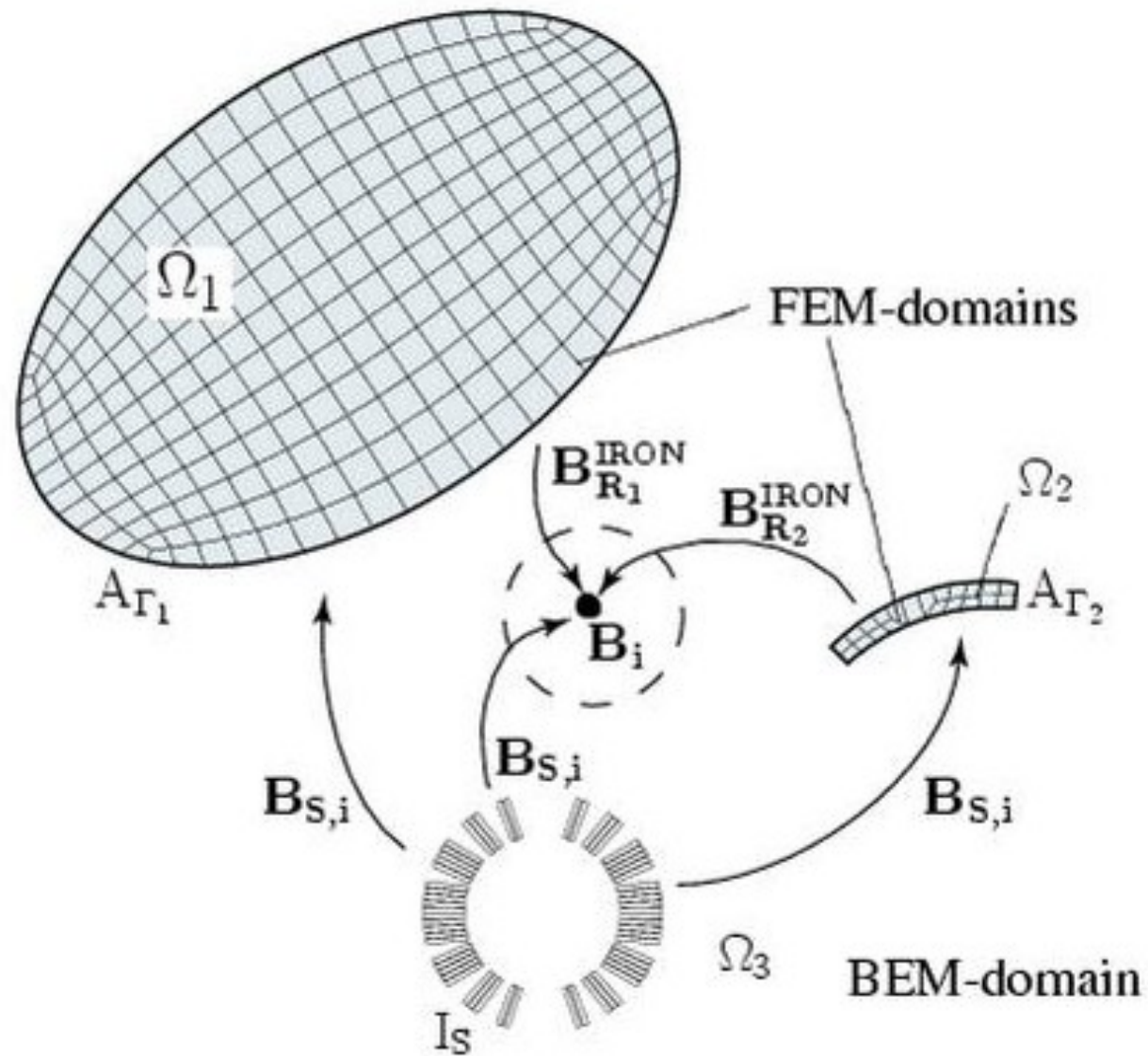


Vector Potential and Total Scalar Potential



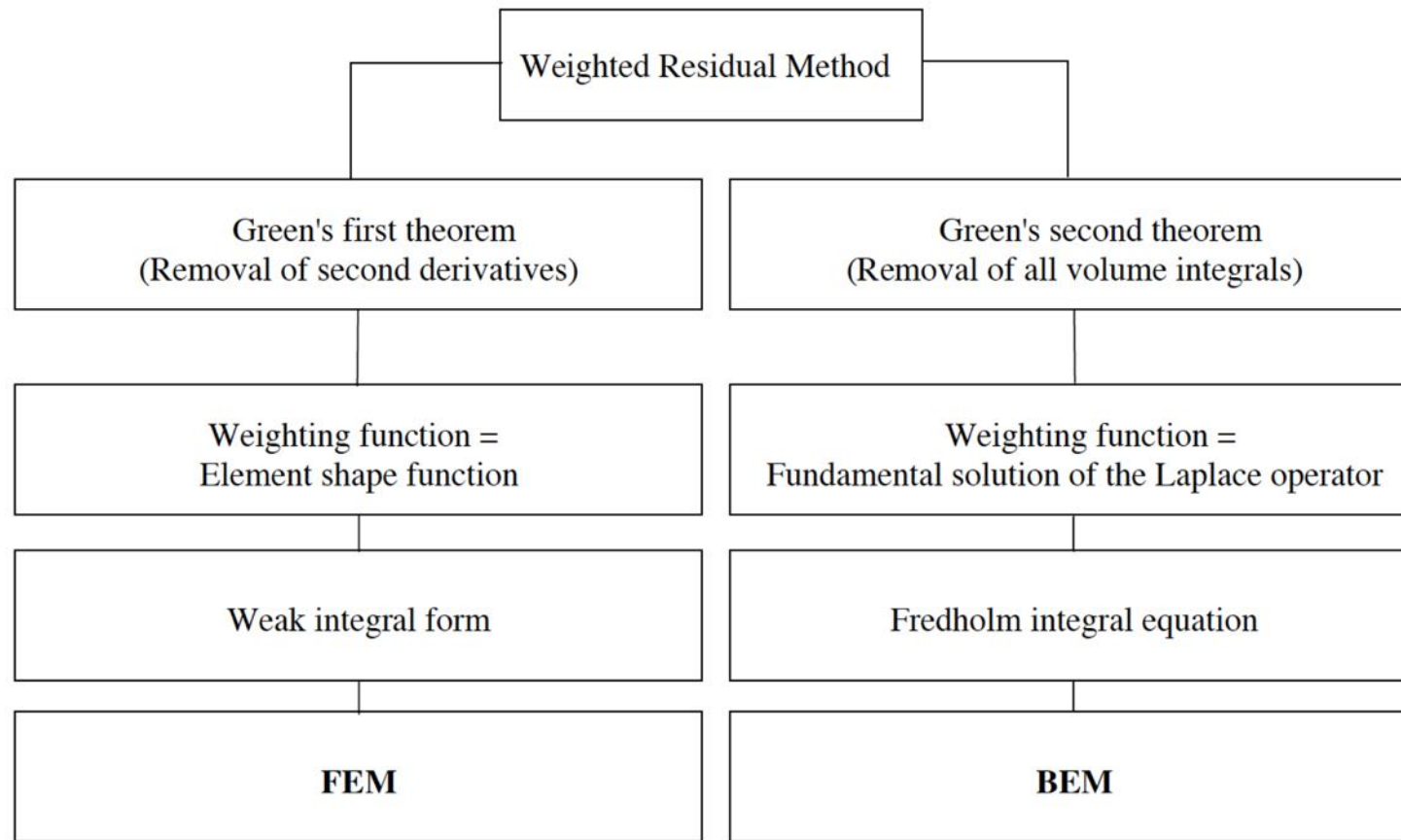
Number of finite elements	60	178	449	787	2799	6233
Total scalar potential	65.8	72.1	13.0	5.0	3.8	15.7
Vector potential	-40.5	-27.4	-7.4	-4.8	-3.8	25.0

BEM-FEM Coupling (Elementary Model Problem)



Green's First and Second Identities in FEM and BEM

$$\int_{\Omega} (\text{grad } \phi \cdot \text{grad } \psi + \phi \nabla^2 \psi) dV = \int_{\Gamma} \phi \text{grad } \psi \cdot \mathbf{n} da,$$



$$\int_{\Omega} (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dV = \int_{\Gamma} (\phi \partial_{\mathbf{n}} \psi - \psi \partial_{\mathbf{n}} \phi) da,$$

The FEM Part (Vector Laplace Equation)

$$-\frac{1}{\mu_0} \nabla^2 \mathbf{A} = \mathbf{J} + \text{curl } \mathbf{M}$$

in Ω_i ,

$$\mathbf{A} \cdot \mathbf{n} = 0$$

on Γ_H ,

$$\frac{1}{\mu_0} \text{div } \mathbf{A} = 0$$

on Γ_B ,

$$\mathbf{n} \times (\mathbf{A} \times \mathbf{n}) = \mathbf{0}$$

on Γ_B ,

$$\frac{1}{\mu} (\text{curl } \mathbf{A}) \times \mathbf{n} = \mathbf{0}$$

on Γ_H ,

$$\left[\frac{1}{\mu_0} \text{div } \mathbf{A}_a \right]_{\text{ai}} = 0$$

on Γ_{ai} ,

$$\frac{1}{\mu_0} (\text{curl } \mathbf{A}_i - \mu_0 \mathbf{M}) \times \mathbf{n}_i + \frac{1}{\mu_0} (\text{curl } \mathbf{A}_a) \times \mathbf{n}_a = \mathbf{0}$$

on Γ_{ai} ,

$$[\mathbf{A}]_{\text{ai}} = \mathbf{0}$$

on Γ_{ai} .

$$\frac{1}{\mu_0} \int_{\Omega_i} \text{grad}(\mathbf{A} \cdot \mathbf{e}_a) \cdot \text{grad} w_a d\Omega_i - \frac{1}{\mu_0} \oint_{\Gamma_{ai}} \left(\frac{\partial \mathbf{A}}{\partial n_i} - (\mu_0 \mathbf{M} \times \mathbf{n}_i) \right) \cdot \mathbf{w}_a d\Gamma_{ai} = \int_{\Omega_i} \mathbf{M} \cdot \text{curl} \mathbf{w}_a d\Omega_i$$

$$\frac{\partial \mathbf{A}_i^{\text{FEM}}}{\partial n_i} - (\mu_0 \mathbf{M} \times \mathbf{n}_i) + \frac{\partial \mathbf{A}_a^{\text{BEM}}}{\partial n_a} = \mathbf{0} \quad \text{on } \Gamma_{ai}$$

$$\frac{1}{\mu_0} \int_{\Omega_i} \text{grad}(\mathbf{A} \cdot \mathbf{e}_a) \cdot \text{grad} w_a d\Omega_i - \frac{1}{\mu_0} \oint_{\Gamma_{ai}} \mathbf{Q}_{\Gamma_{ai}} \cdot \mathbf{w}_a d\Gamma_{ai} = \int_{\Omega_i} \mathbf{M} \cdot \text{curl} \mathbf{w}_a d\Omega_i$$

$$[K] \{A\} - [T] \{Q\} = \{F(\mathbf{M})\}$$

Vector Laplace

$$\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}, \quad \text{in } \Omega_a$$

Weighted Residual (x 3 in Cartesian coordinates)

$$\int_{\Omega_a} \nabla^2 A w \, d\Omega_a = - \int_{\Omega_a} \mu_0 J w \, d\Omega_a$$

Kirchhoff theorem: From Green's second theorem and setting the using the free-space Green function of the Laplace operator as weighting function

$$C A(\mathbf{r}) + \int_{\Gamma} -\partial_{\mathbf{n}_a} A(\mathbf{r}') u^*(\mathbf{r}, \mathbf{r}') \, da' + \int_{\Gamma} A(\mathbf{r}') \partial_{\mathbf{n}_a} u^*(\mathbf{r}, \mathbf{r}') \, da' = \int_{\Omega_a} \mu_0 J u^*(\mathbf{r}, \mathbf{r}') \, dV'$$

	$u^*(\mathbf{r}, \mathbf{r}')$	$q^*(\mathbf{r}, \mathbf{r}') := \partial_{\mathbf{n}_a} u^*(\mathbf{r}, \mathbf{r}')$	C
2D	$-\frac{1}{2\pi} \ln \mathbf{r} - \mathbf{r}' $	$-\frac{(\mathbf{r} - \mathbf{r}') \cdot \mathbf{n}_a}{2\pi \mathbf{r} - \mathbf{r}' ^2}$	$\frac{\beta}{2}$
3D	$\frac{1}{4\pi \mathbf{r} - \mathbf{r}' }$	$-\frac{(\mathbf{r} - \mathbf{r}') \cdot \mathbf{n}_a}{4\pi \mathbf{r} - \mathbf{r}' ^3}$	$\frac{\Theta}{4\pi}$

$$\nabla^2 w = -\delta(|\mathbf{r} - \mathbf{r}'|)$$

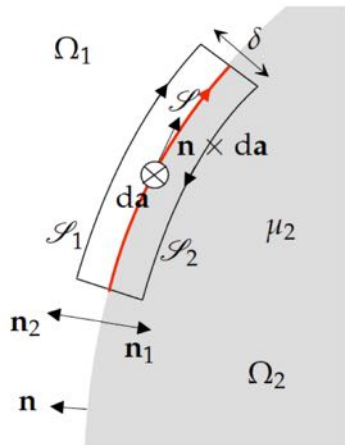
Representation Formula (Fredholm Integral Equation)

$$C A(\mathbf{r}) + \int_{\Gamma} -\partial_{\mathbf{n}_a} A(\mathbf{r}') u^*(\mathbf{r}, \mathbf{r}') da' + \int_{\Gamma} A(\mathbf{r}') \partial_{\mathbf{n}_a} u^*(\mathbf{r}, \mathbf{r}') da' = \int_{\Omega_a} \mu_0 J u^*(\mathbf{r}, \mathbf{r}') dV',$$

Single-layer potential

$$\boldsymbol{\alpha}(\mathbf{r}') := -\frac{1}{\mu} \partial_{\mathbf{n}_a} A(\mathbf{r}')$$

$$[\boldsymbol{\alpha}] = 1 \text{ A m}^{-1}$$

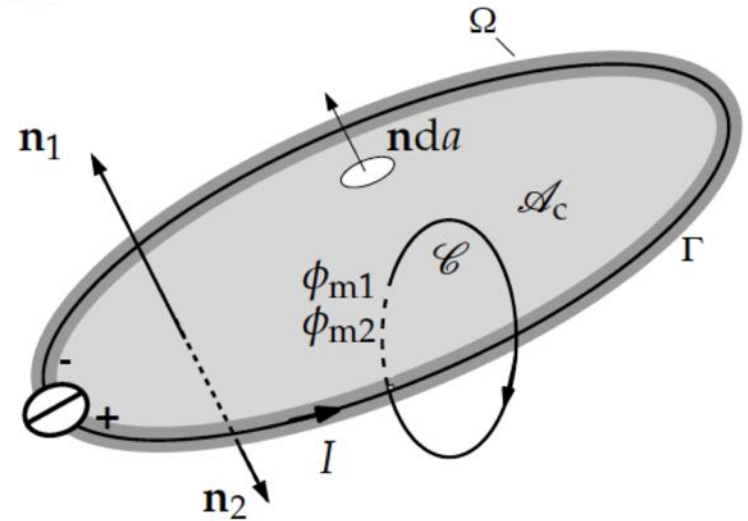


$$\boldsymbol{\alpha} = \mathbf{n} \times (\mathbf{H}_1 - \mathbf{H}_2)$$

Double-layer potential

$$\boldsymbol{\tau}(\mathbf{r}') := \frac{1}{\mu} A(\mathbf{r}')$$

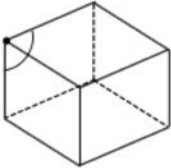
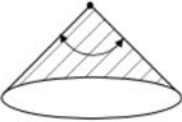

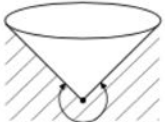
$$[\boldsymbol{\tau}] = 1 \text{ A}$$

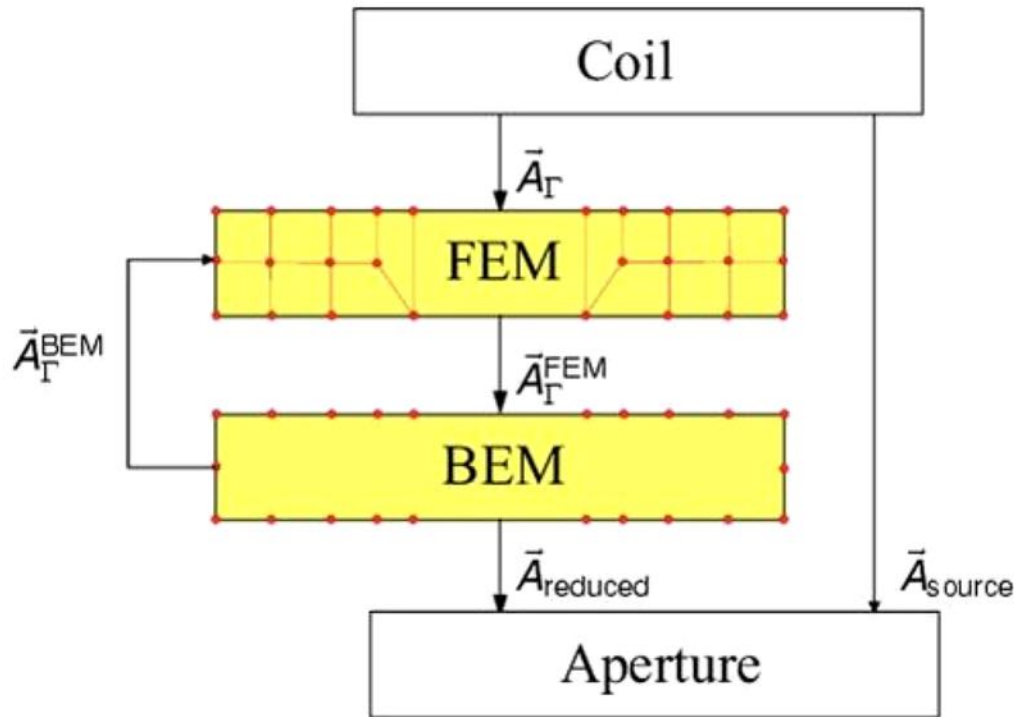


Point-Collocation (Compute One from the Other)

$$Q(\mathbf{r}') := \partial_{\mathbf{n}_a} A(\mathbf{r}') \quad \text{and} \quad q^*(\mathbf{r}, \mathbf{r}') := \partial_{\mathbf{n}_a} u^*(\mathbf{r}, \mathbf{r}')$$

$$C(\mathbf{r}_p)A(\mathbf{r}_p) + \sum_{e=1}^E \int_{\Gamma_e} Q(\mathbf{r}) u^*(\mathbf{r}, \mathbf{r}_p) da + \sum_{e=1}^E \int_{\Gamma_e} A(\mathbf{r}) q^*(\mathbf{r}, \mathbf{r}_p) da = A_s(\mathbf{r}_p).$$

Ω_a				
	90° Corner	90° Cone inner	Half-space	90° Cone outer
Θ	$\frac{1}{2} \pi$	$(2 - \sqrt{2}) \pi$	2π	$(2 + \sqrt{2}) \pi$
$\frac{\Theta}{4\pi}$	$\frac{1}{8}$	$\frac{2 - \sqrt{2}}{4}$	$\frac{1}{2}$	$\frac{2 + \sqrt{2}}{4}$



BEM

$$\{Q\} = -[G]^{-1}[H]\{A\} + [G]^{-1}\{A_s\}$$

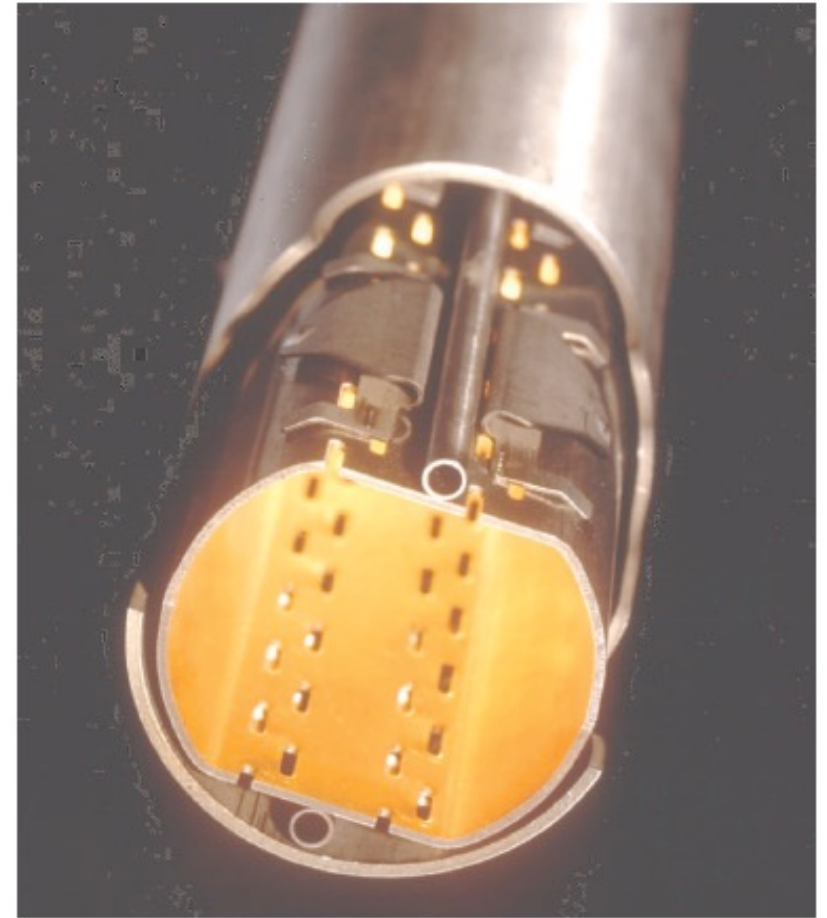
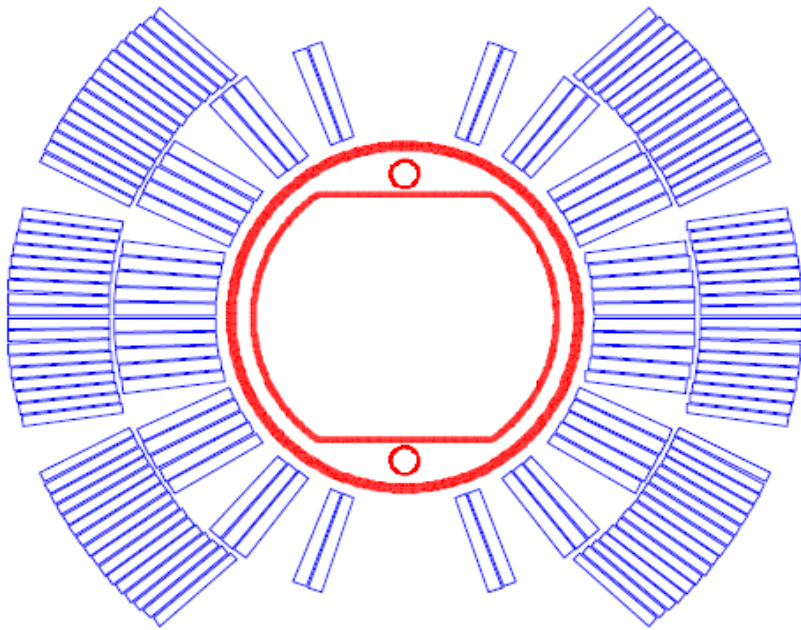
FEM

$$[K]\{A\} - [T]\{Q\} = \{F(\mathbf{M})\}$$

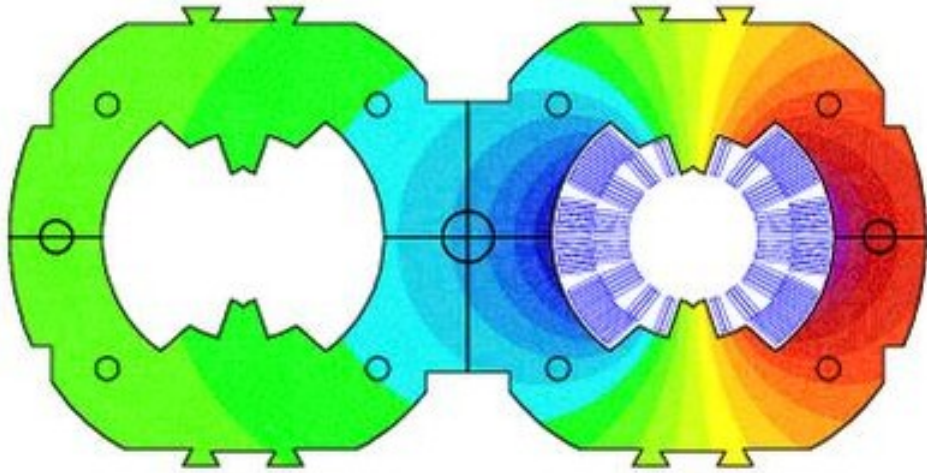
$$\left([K] + [T][G]^{-1}[H] \right) \{A\} = \{F(\mathbf{M})\} + [T][G]^{-1}\{A_s\}$$

$$[\bar{K}]\{A\} = \{\bar{F}(A_s, \mathbf{M})\}$$

LHC Beam Screen



Open Boundary Problem (2)

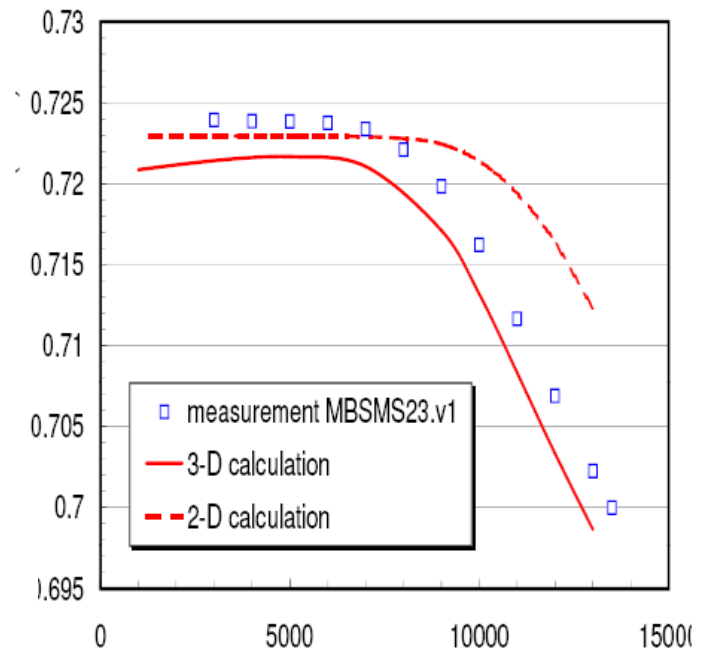
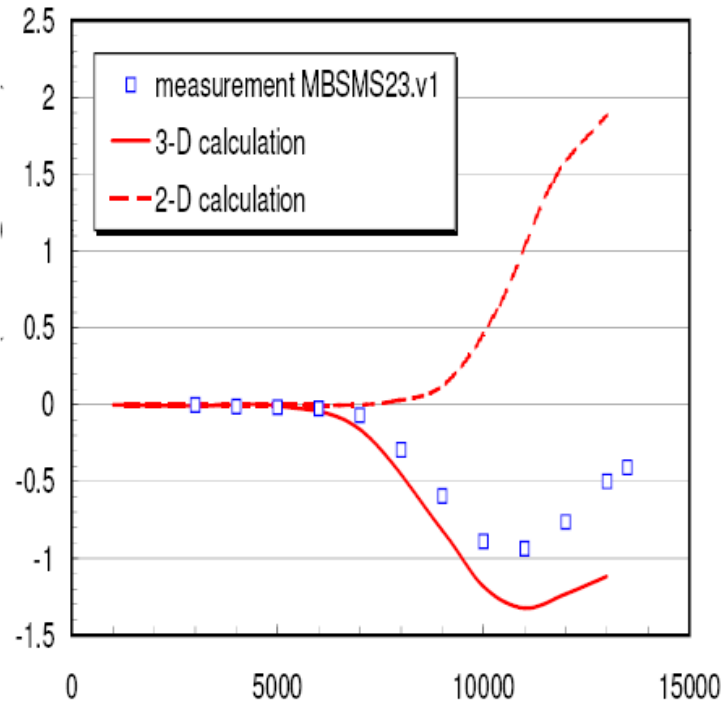
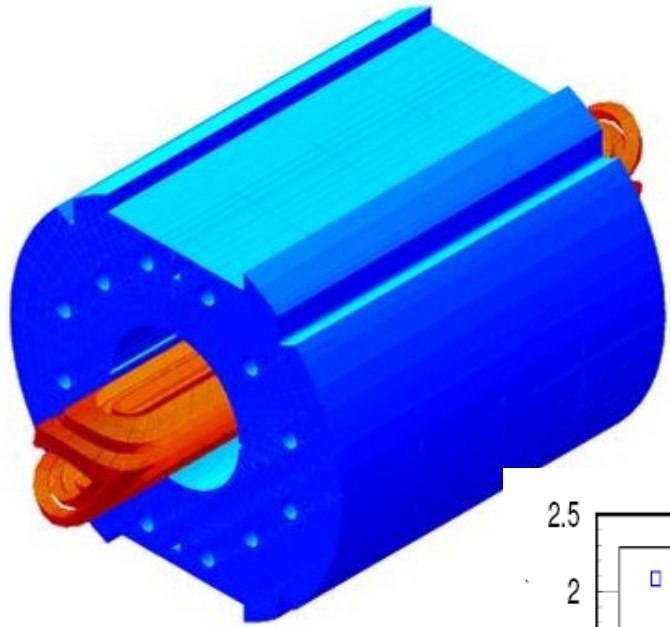


Collared Coil
Field Problem

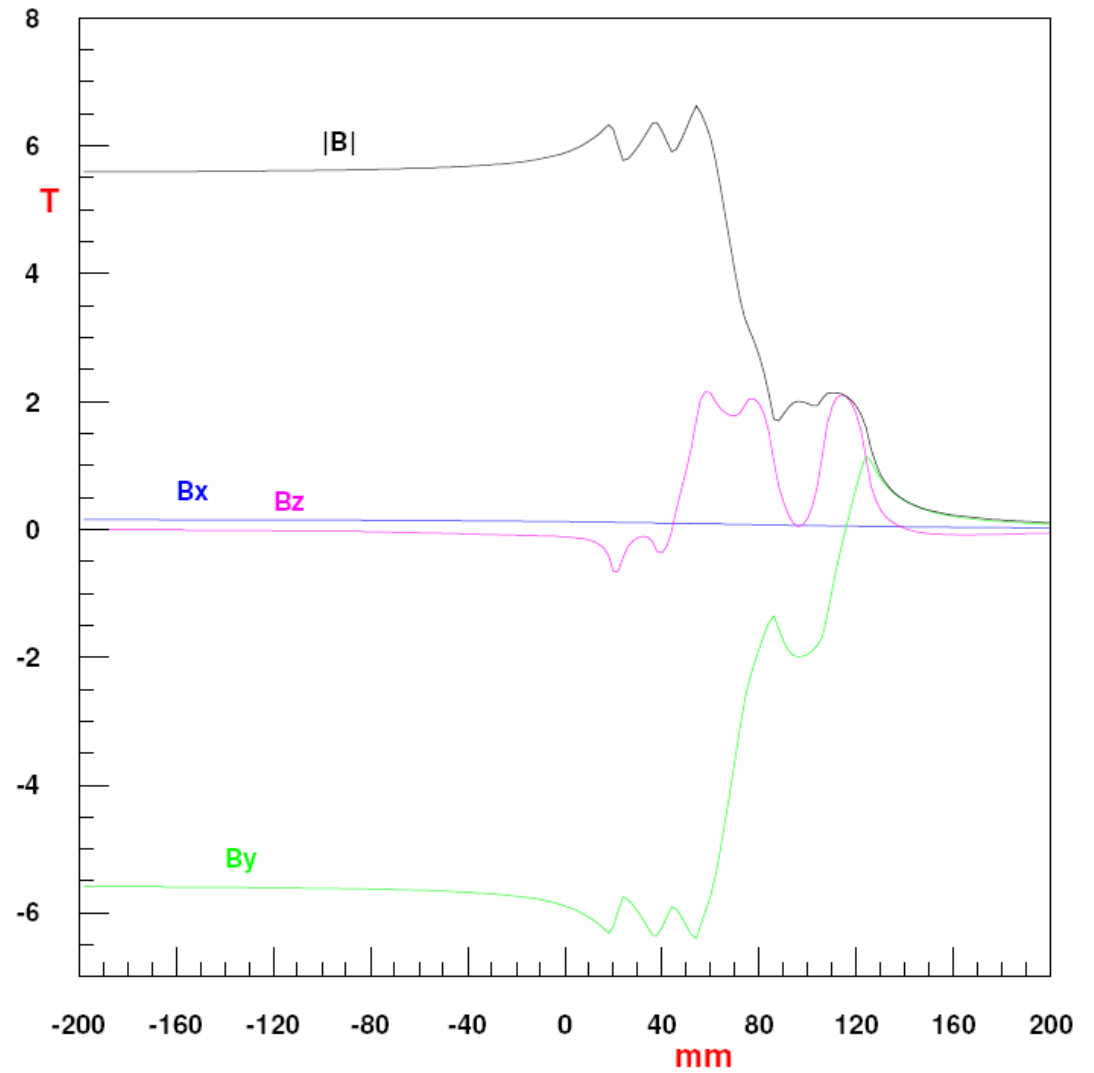
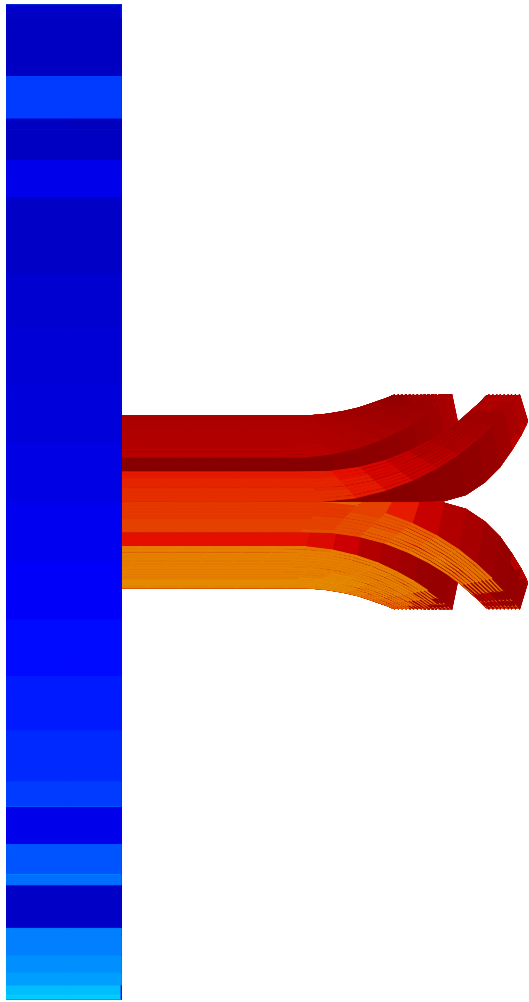


Collared Coil
Measurements in
Industry

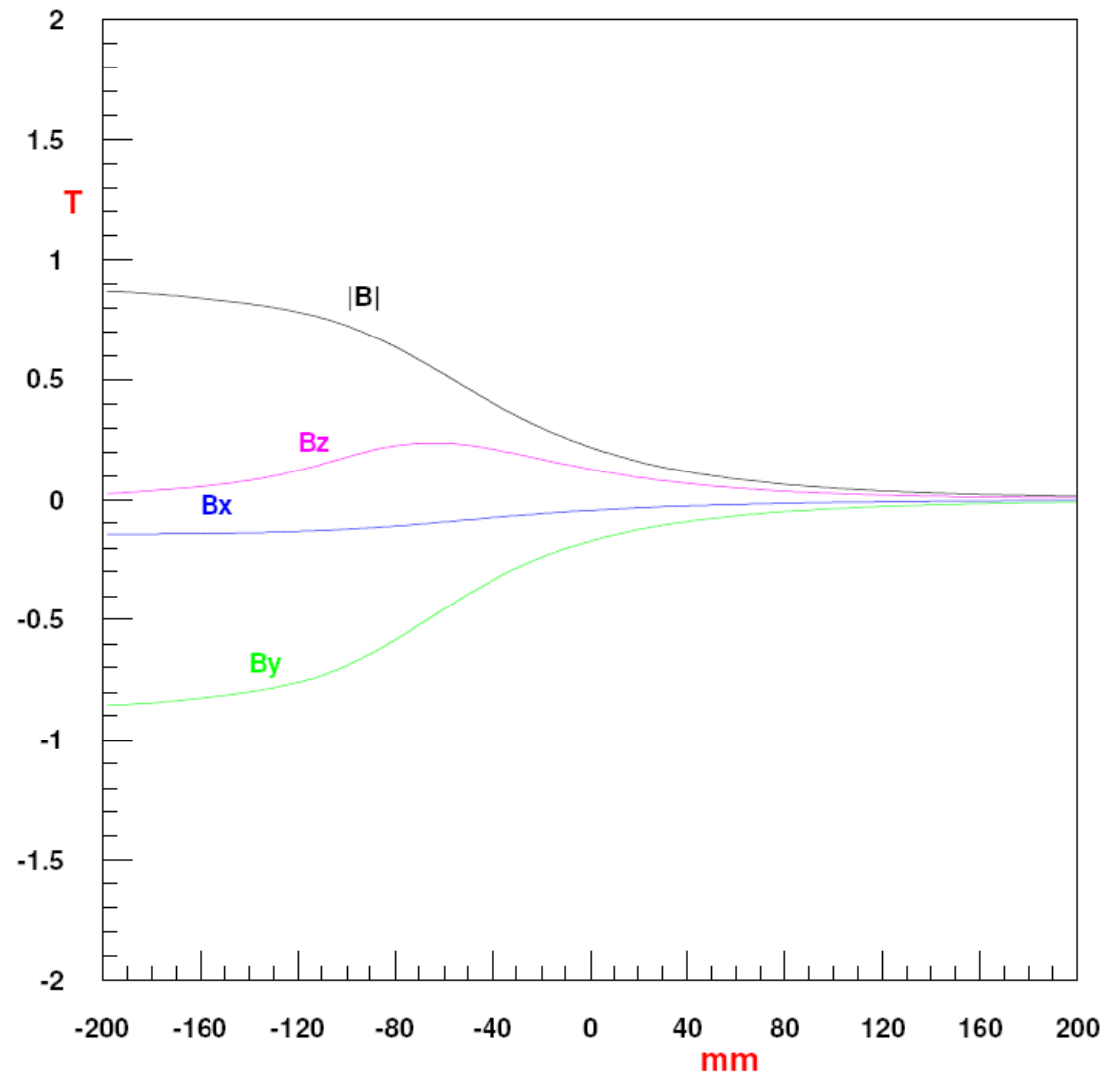
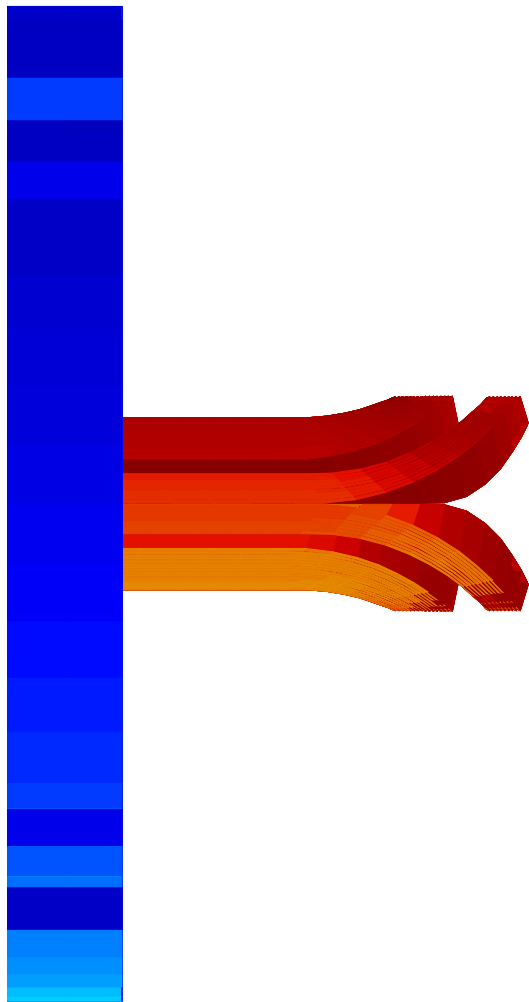
Transfer Function of CTF



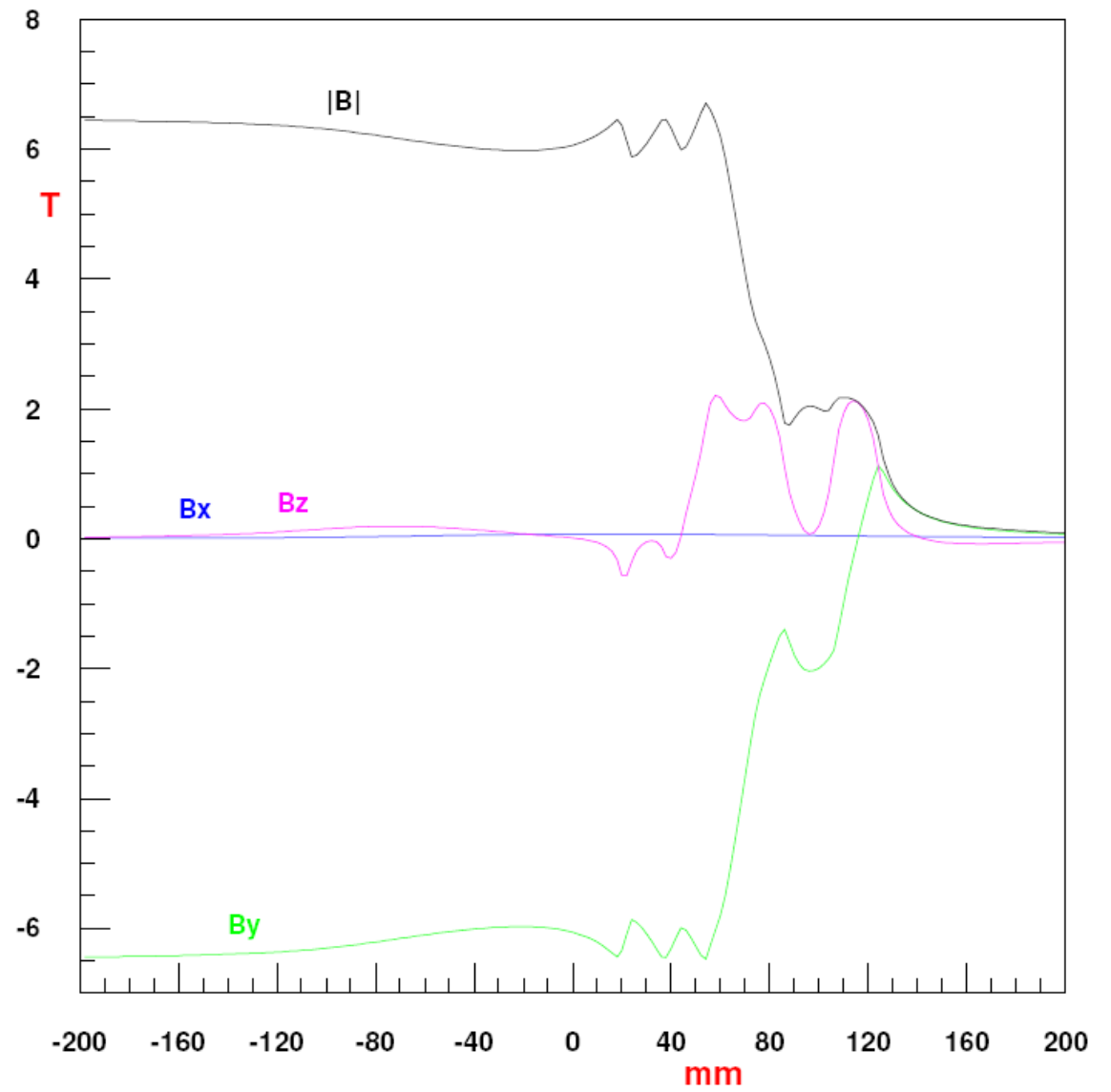
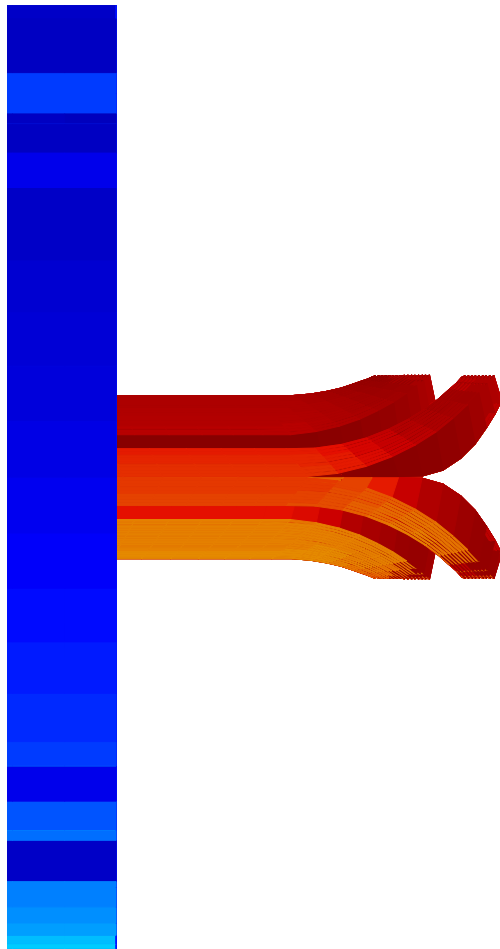
Source Field



Reduced Field



Total Field



Forces (N) in the Connection Ends of the LHC Main Dipole

I	F _x	F _y	F _z
1	-39.7	-44.0	-45.4
2	-6.5	3.7	-41.7
3	-6.1	88.3	-38.2
4	1.25	3.9	-28.5
5	48.1	-46.7	-48.5
Sum	-2.95	5.2	-202.3

