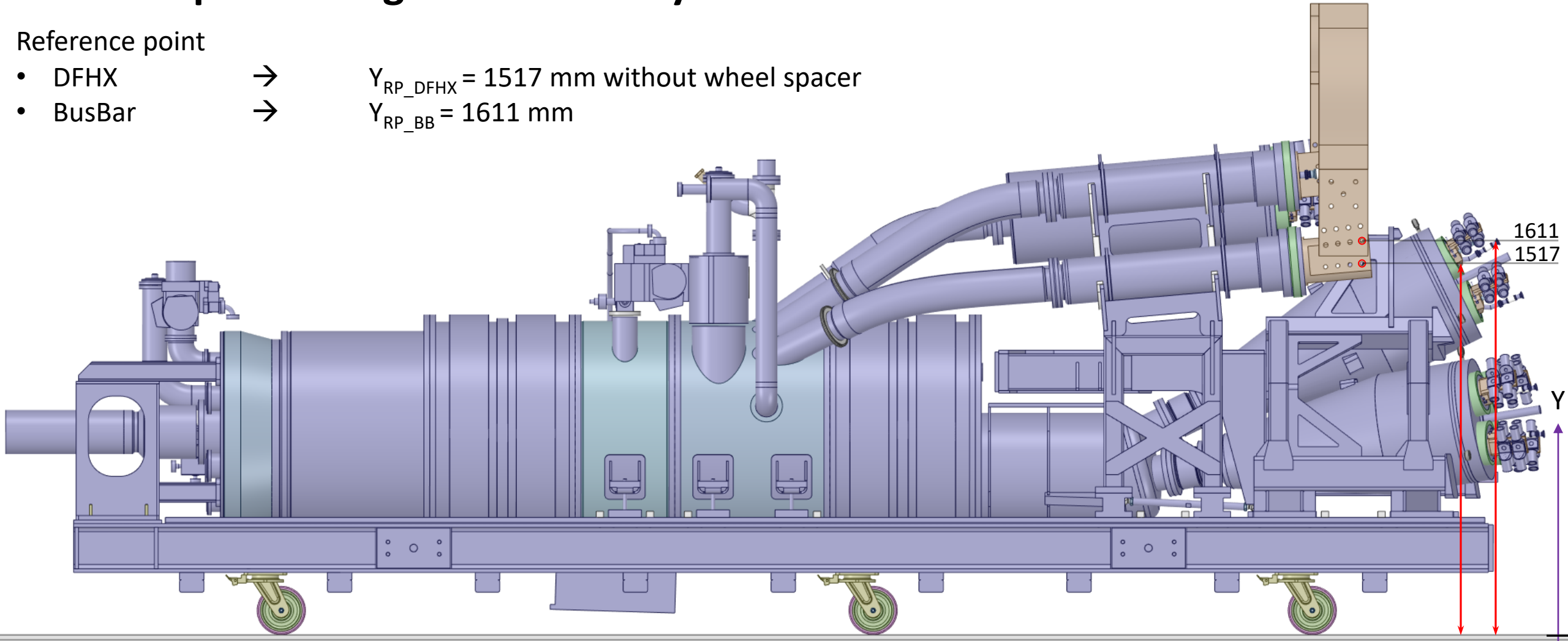


1 – DFHX positioning to horizontally match Busbars

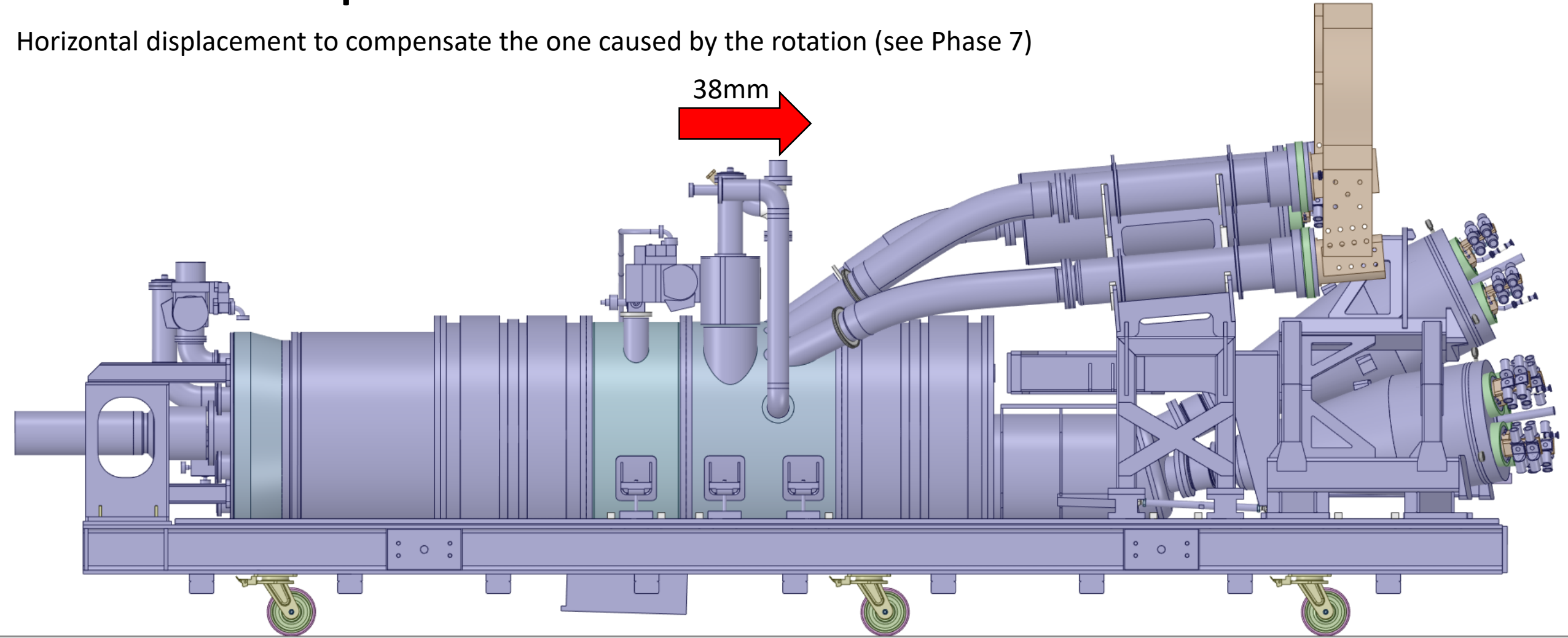
Reference point

- DFHX → $Y_{RP_DFHX} = 1517$ mm without wheel spacer
- BusBar → $Y_{RP_BB} = 1611$ mm

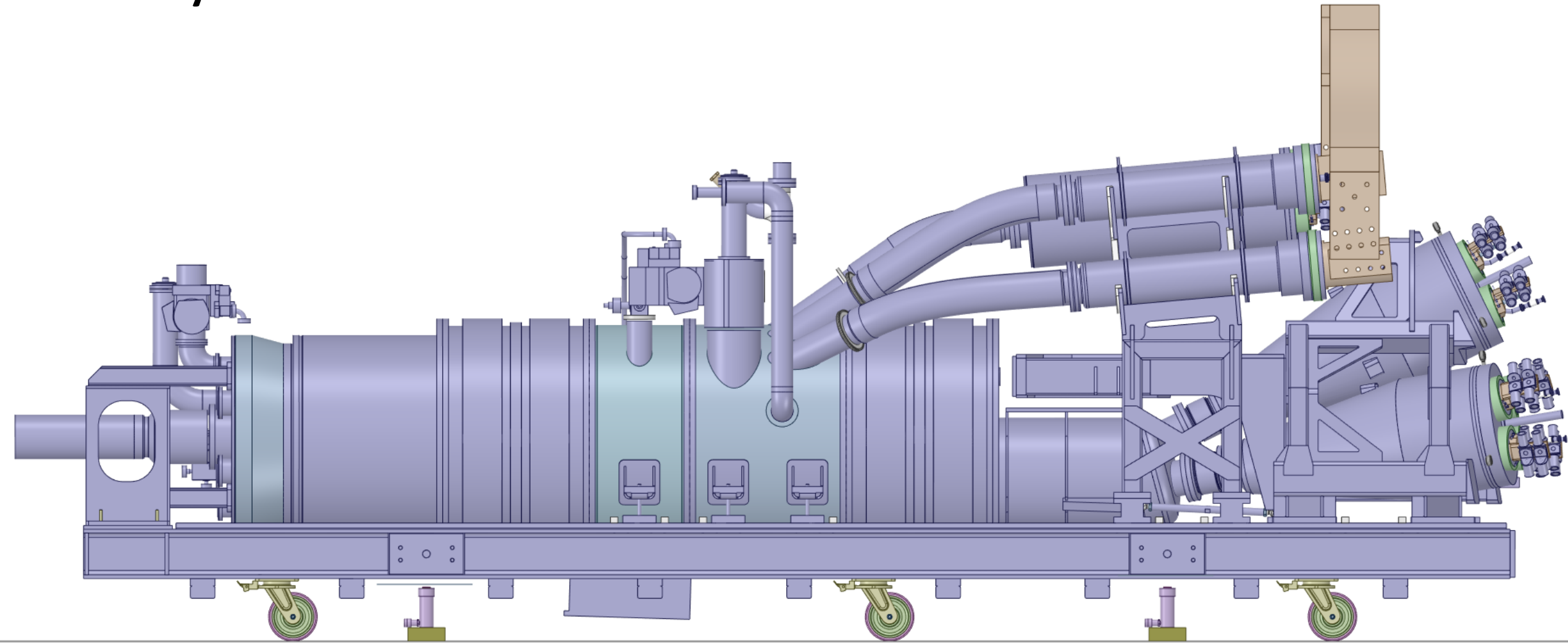


2 – Horizontal displacement

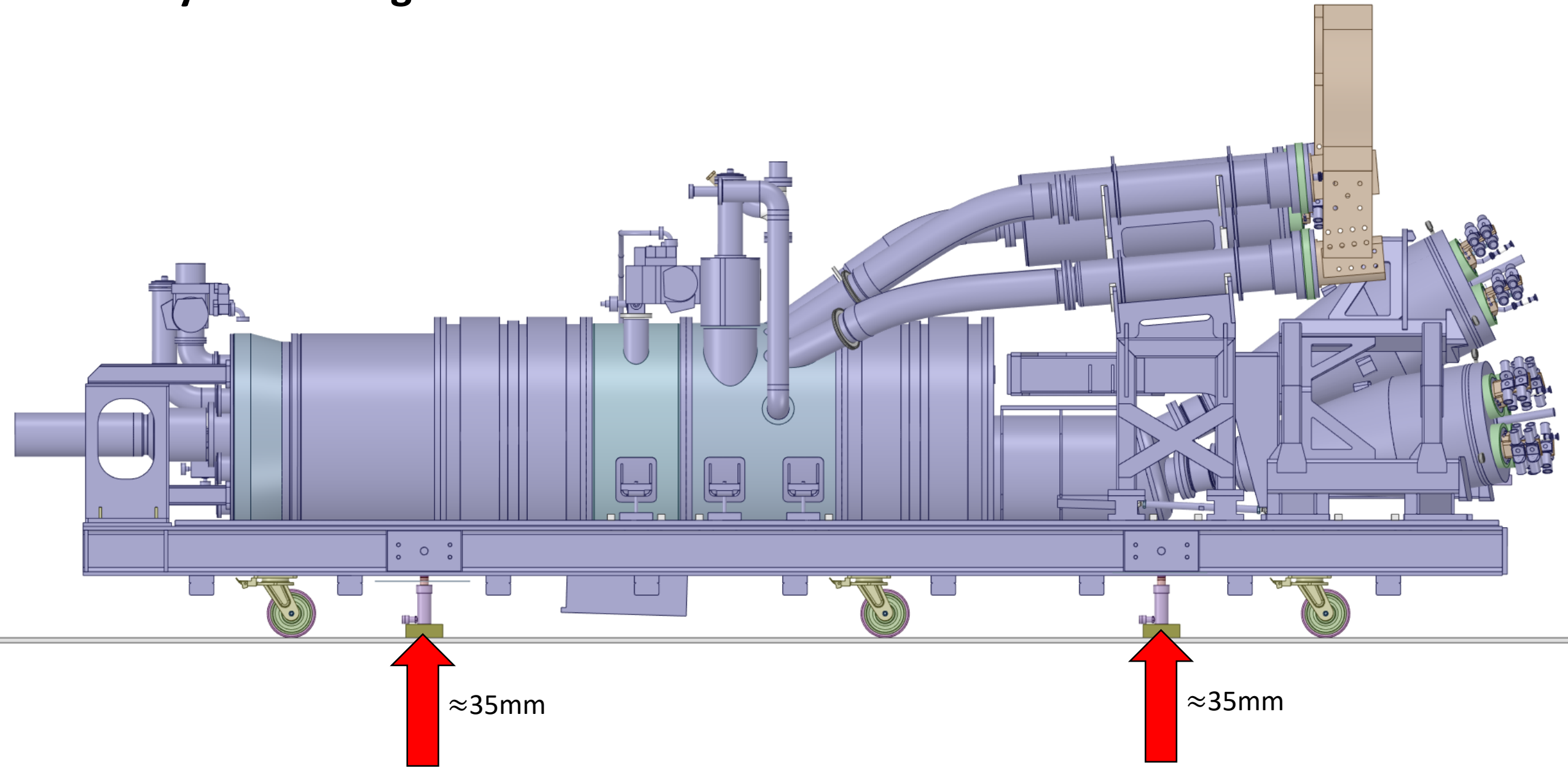
Horizontal displacement to compensate the one caused by the rotation (see Phase 7)



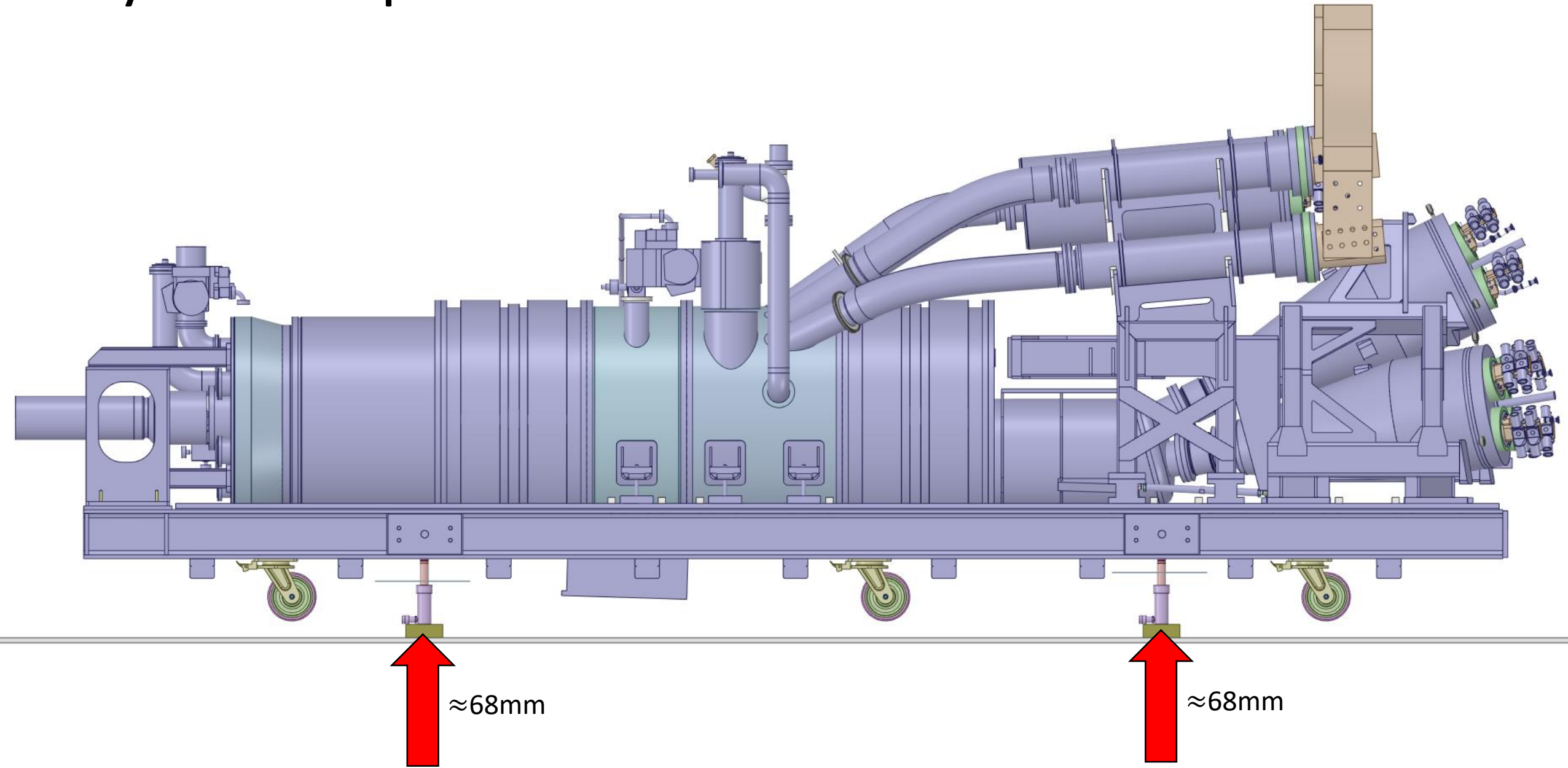
3 – Jack system installation



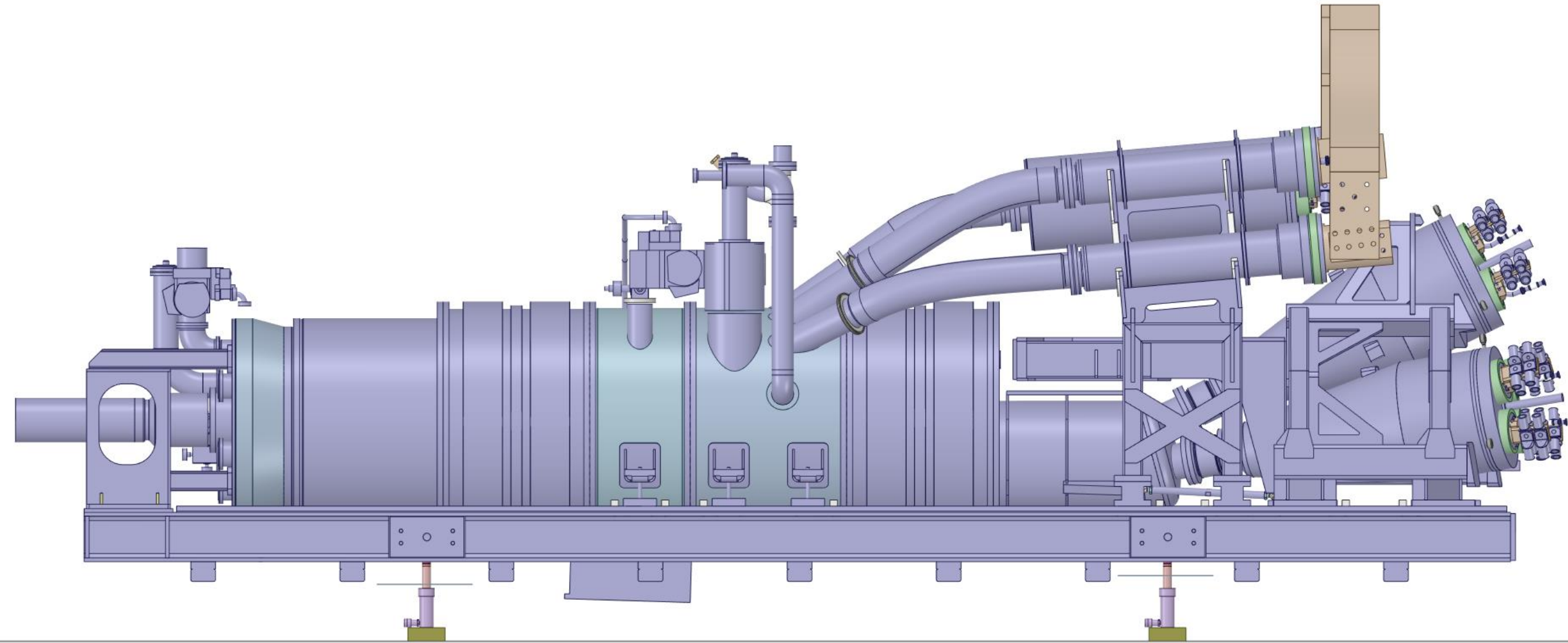
4 – Jack system brought to contact with the frame



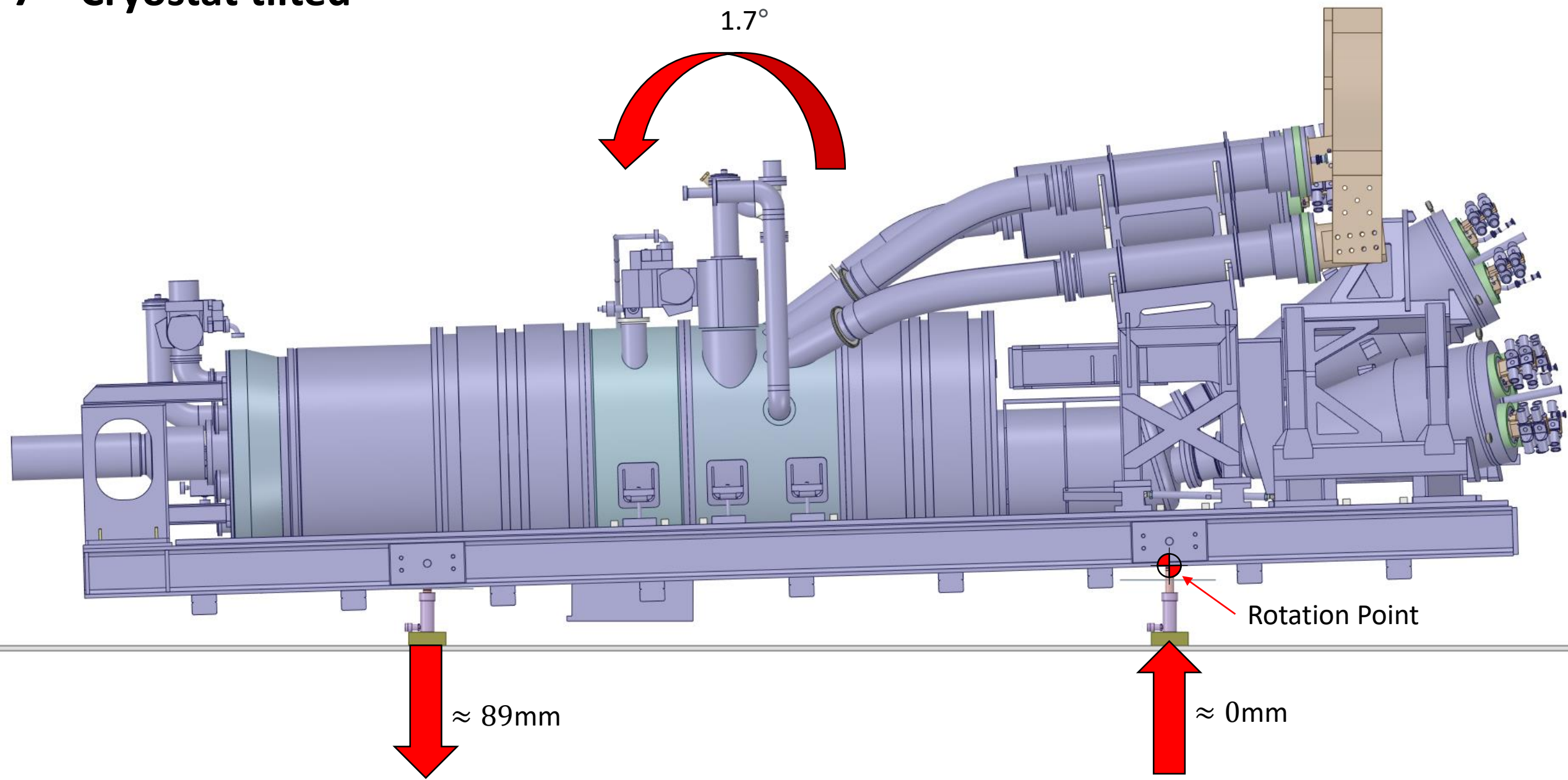
5 – Cryostat lifted up



6 – Wheels removal

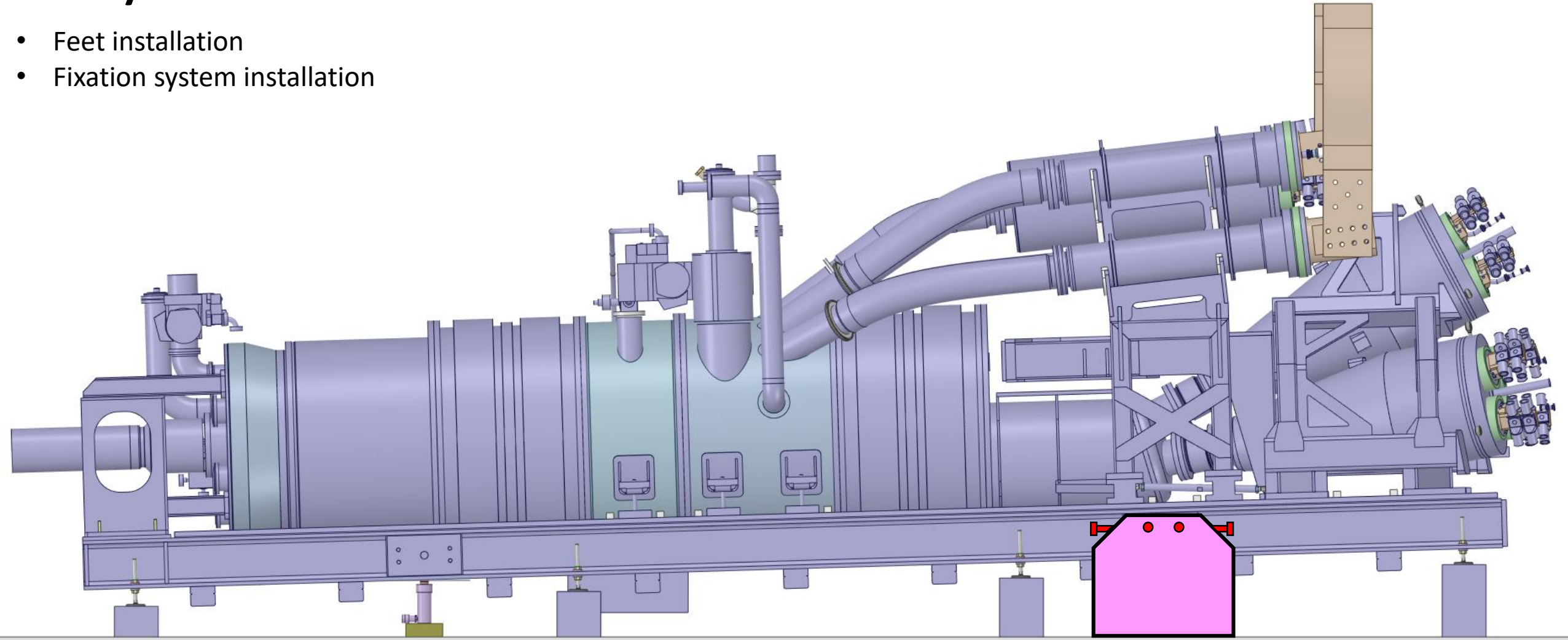


7 – Cryostat tilted

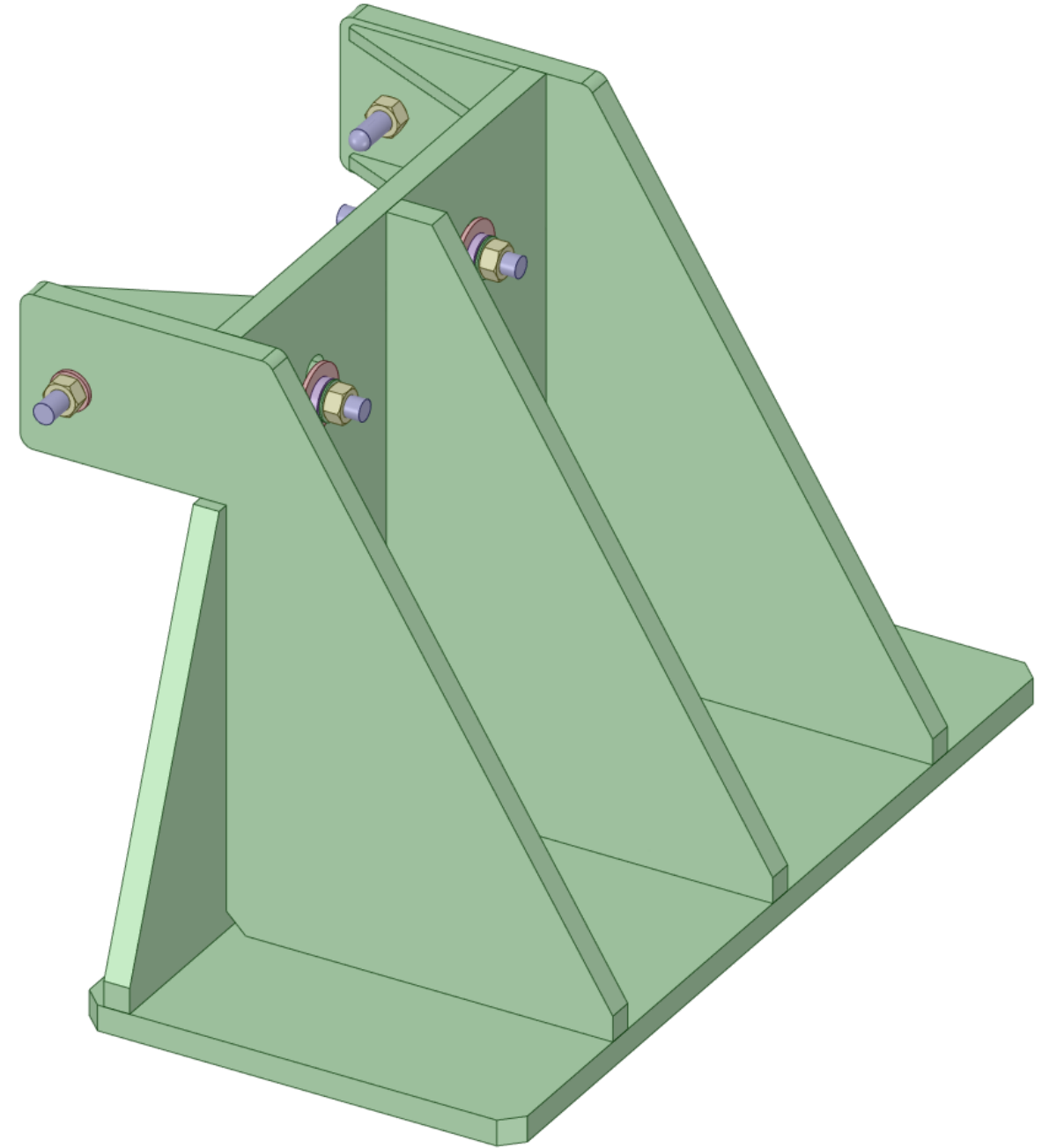
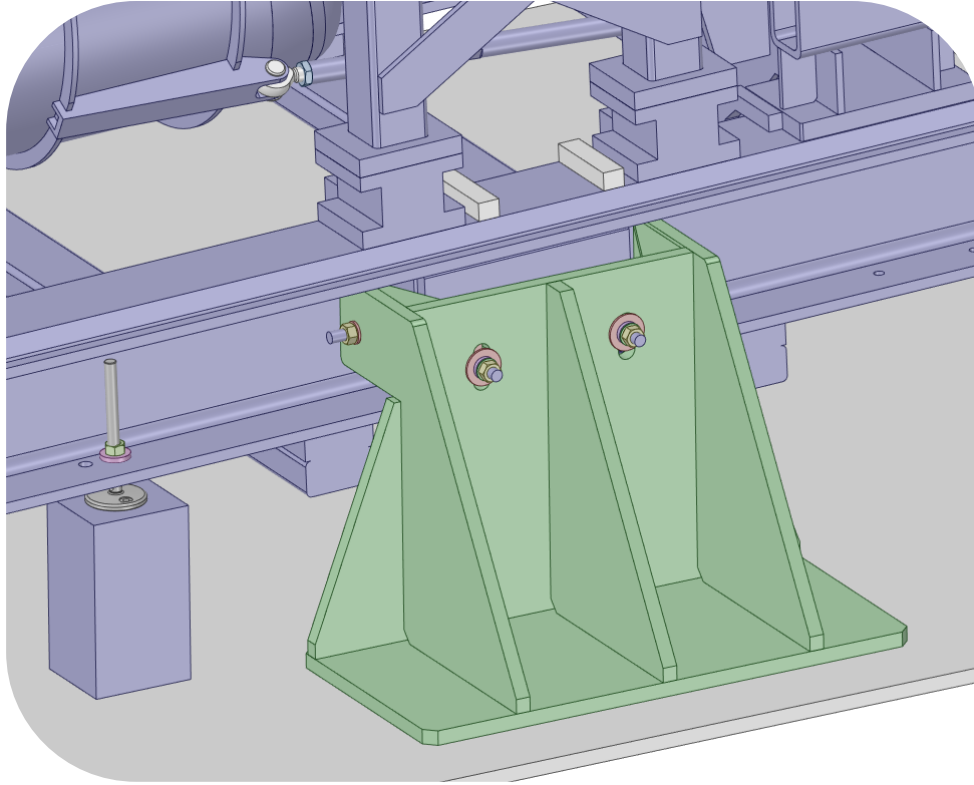


8 – Cryostat secured to the floor

- Feet installation
- Fixation system installation



Fixation Bracket Model



Equipment

- Hydraulic cylinder → Enerpac RC55, 4.9-ton Capacity, 5.00" Stroke + Tilt saddle to absorb the inclination
- Wheel → Blicke LS-GTH 202K-RI4, $\varnothing = 200\text{mm}$, Height = 255, Capacity (static) = 4-ton
- Feet → elesa+Ganter GN 23 Stainless Steel-Levelling feet

[Enerpac RC55 + Tilt Saddle](#)



[Blicke LS-GTH 202K-RI4](#)



[GN 23 Stainless Steel-Levelling feet](#)

