

Deep Neural Network Algorithms in the CMS Level-1 Trigger

Anthony Vizcaíno Aportela on behalf of the CMS Level-1
trigger group

Basic Idea

- The high-luminosity upgrade of the CMS Level-1 trigger has enabled new capabilities,
 - use of inputs from the outer tracker
 - high-granularity calorimeter
- With richer inputs means more ways of applying machine learning to better discriminate, estimate, and learn the physics of each event.

High Luminosity Upgrade (a Problem)

- Each event produces ~1MB of data
- At 40 MHz, data rate becomes astronomical
- We need data reduction at a microsecond latency
- These are what the triggers are for
- We need to know what signatures correspond to particles, and reduce
- FPGAs provide the latency and flexibility
- ML algos for solving this and have potential improve on algos we have

Phase-II Upgrades of the CMS Detector

Trigger/HLT/DAQ

Level-1 trigger: 12.5 μ s latency, 750kHz out
HLT output: 7.5kHz

New tracker

Increased granularity, coverage to $|\eta| < 4$
40 MHz readout ($p_T > 2$ GeV) outer tracker

Muon systems

Replace DT&CSC FE/BE
RPC coverage from $1.5 < |\eta| < 2.4$

MIP Timing detector

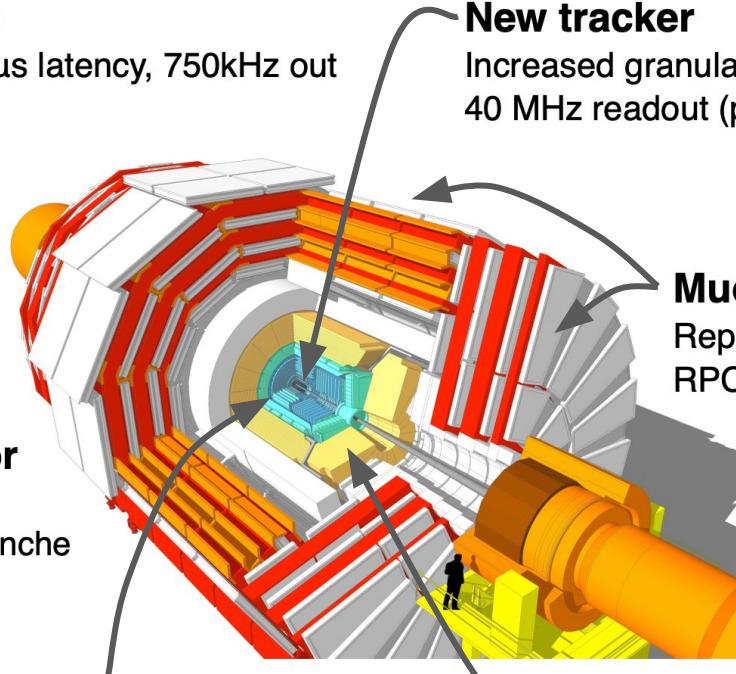
Barrel: Crystal+SiPM
Endcap: Low-gain avalanche diode

Barrel ECal/HCal

Replace FE/BE electronics
ECal single-crystal granularity @40MHz

New endcap calorimeters

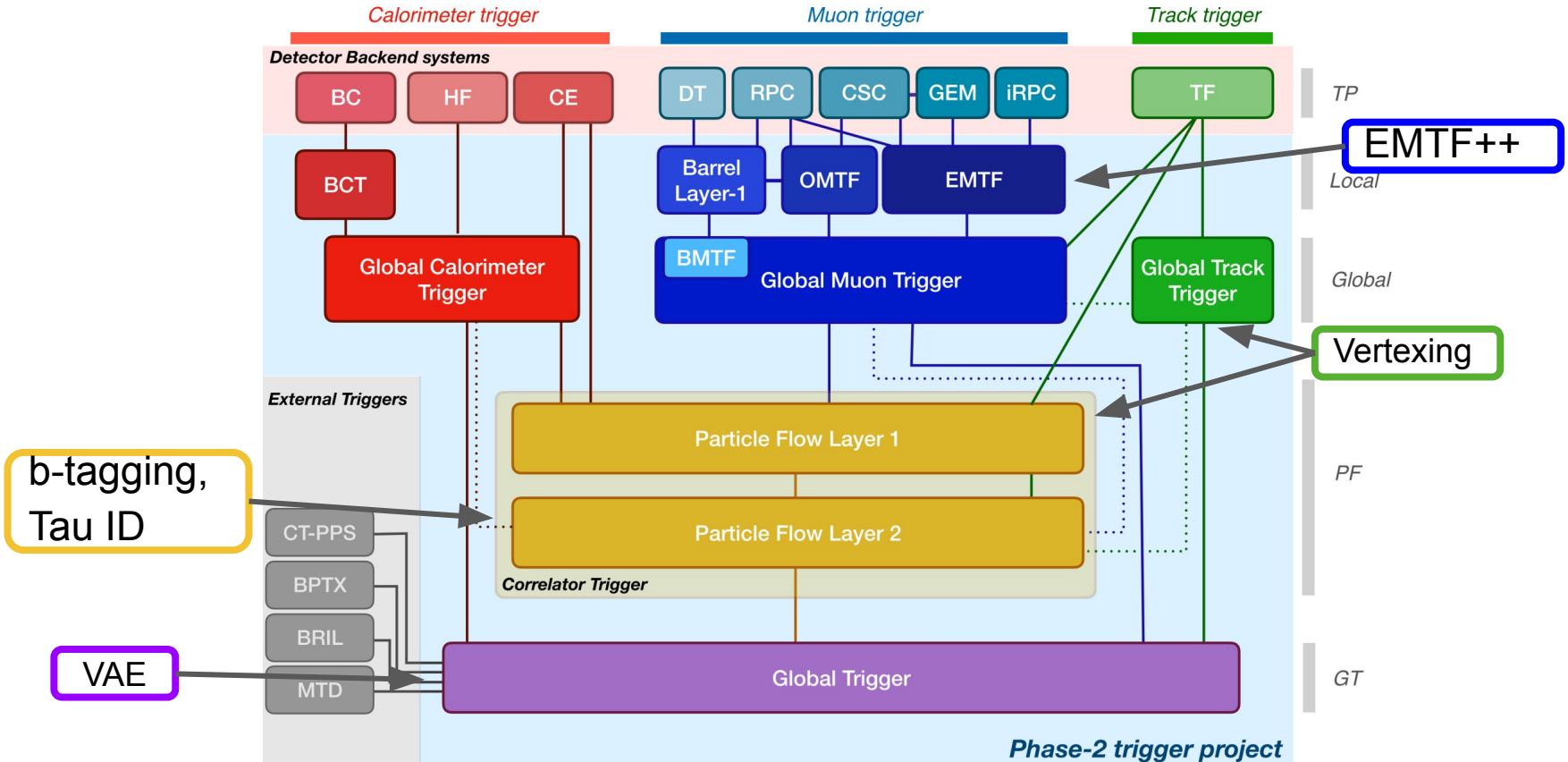
3d showers, precise timing
Si/Scint+SiPM in Pb/W



Recent ML developments CMS

1. Muon Transverse Momentum Estimation
2. b-tagging
3. End-to-End Vertexing NN
4. Tau Identification

Architecture of the Phase-II L1 Trigger



1. Muon Transverse Momentum Estimation

Endcap Muon Track Finder (EMTF)

- Was hard coded into ~1GB LUT (Bad)

Upgrade (EMTF++)

- Utilizing more advanced ML

1. EMTF++



from:

- CSC
- RPC
- GEM
- iRPC
- ME0

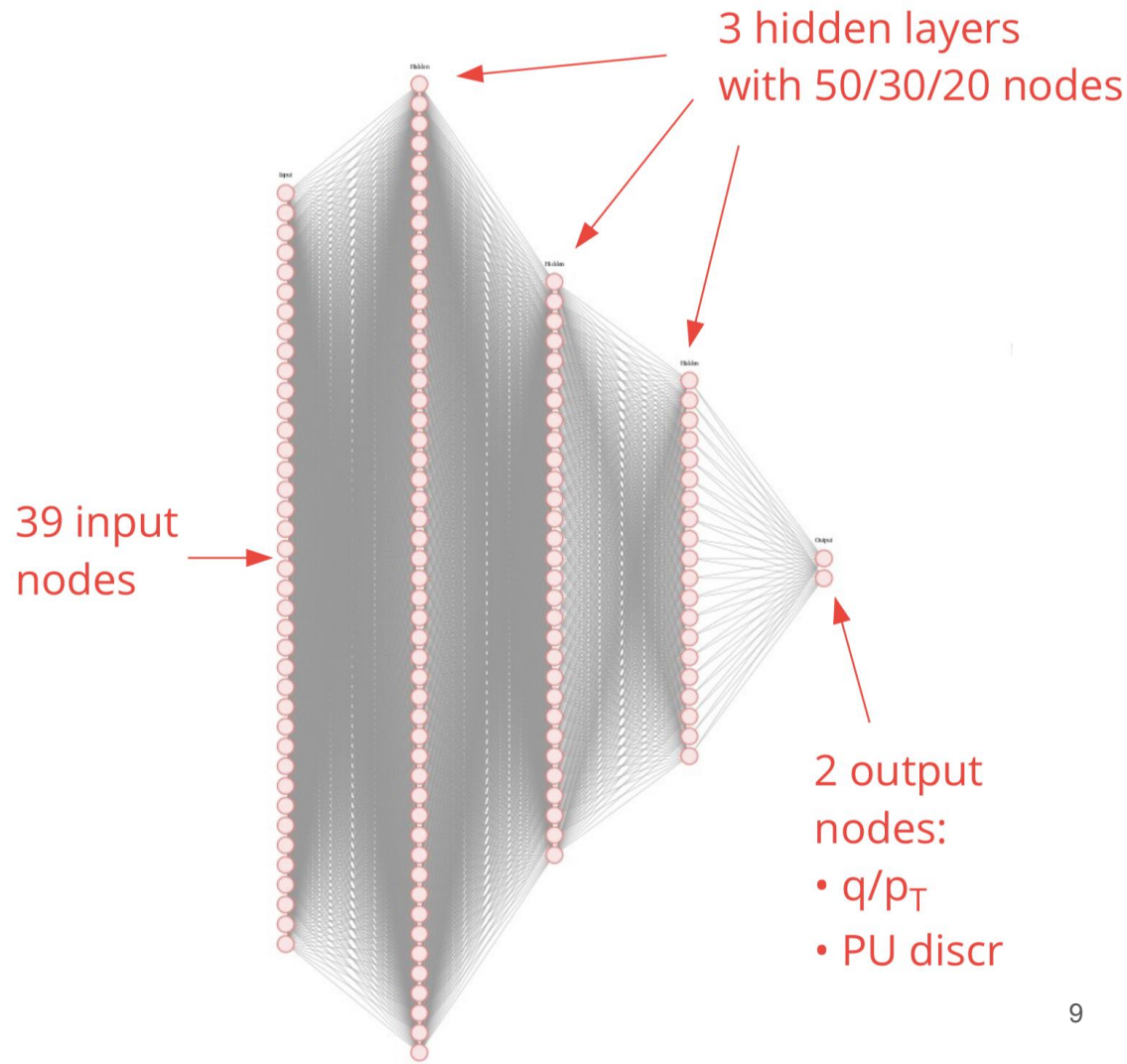
Use patterns to find stubs in stations

Build track candidates by selecting a unique stub from each muon station.

Use ML to determine the p_T from the track candidate

1. EMTF++

- Dense network
- 39 inputs muon system params – phi, bend, etc
- 2 outputs, q/p_T and pileup discriminator



2. b-tagging

- **L1** will include **tracking** and a higher granularity calorimeter (**HGcal**)
- Including **tracking makes it possible** to develop algorithms to identify jets from bottom quarks (**b-tagging**) in the **L1** stage
- Taking advantage of new systems, CMS will implement special versions of PF and PUPPI algorithms in L1.
- The particles reconstructed using the [PUPPI](#) algorithm are used to construct higher level objects, such as jets.
- **Neural network** is implementable on **current trigger hardware**
- Runs on PUPPI particles and **discriminates** between **b-quark jets** and light quark / gluon jets

2. B-tagging algo

Inputs are top ten PUPPI candidates ranked by jet p_T

Input features

$[b_0, b_1, b_2, b_3, b_4, b_5, b_6, b_7]$ Particle type, one-hot encoded
]

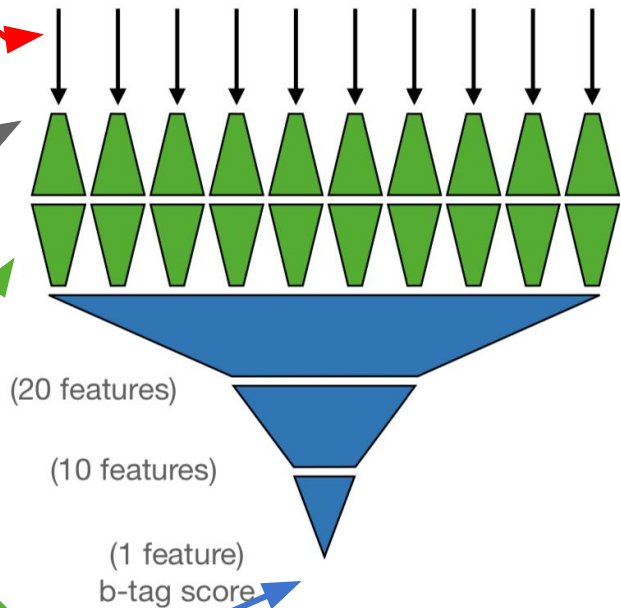
$[p_T, \eta, \phi]$ kinematic information scaled relative to jet

$[z_0, d_0]$ z-position and transverse impact parameter with respect to the primary vertex

Featurizers

Scores close to 1 indicate jets that are likely to have originated from bottom quarks, while scores close to 0 indicate jets that are likely to have originated from light quarks or gluons.

particle 0
particle 1
particle 2
...
particle 9

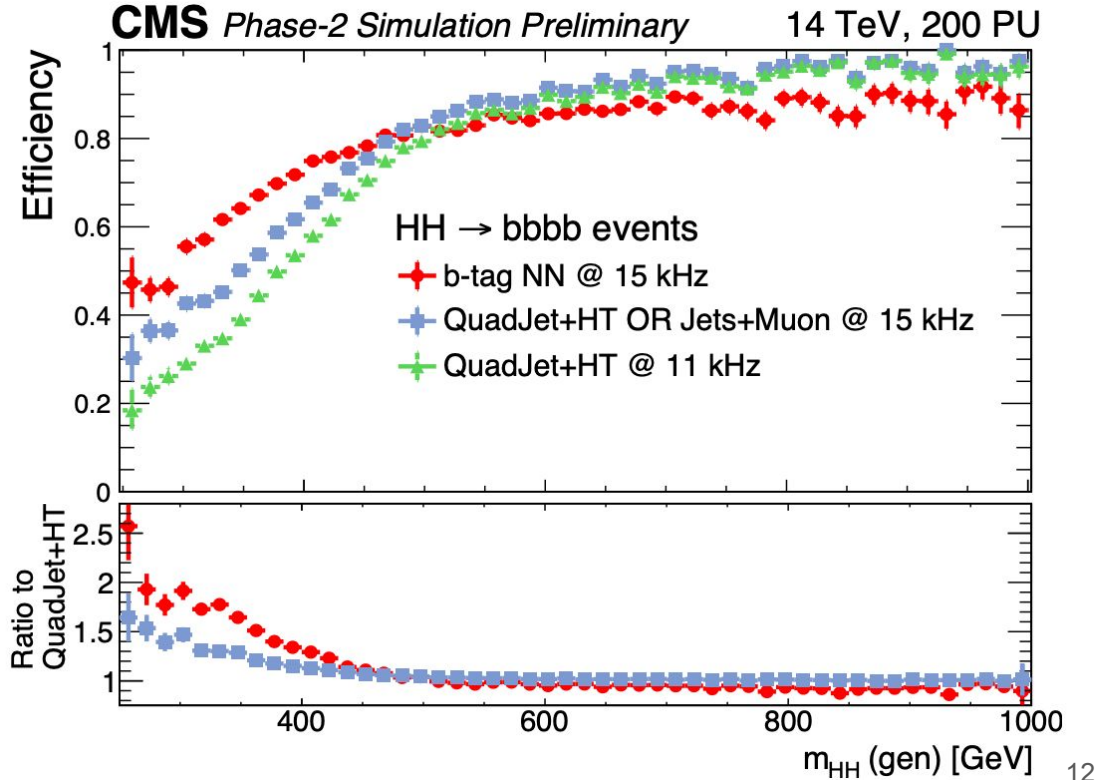


Pointwise convolution
(per particle dense layer)

Dense layer₁₁

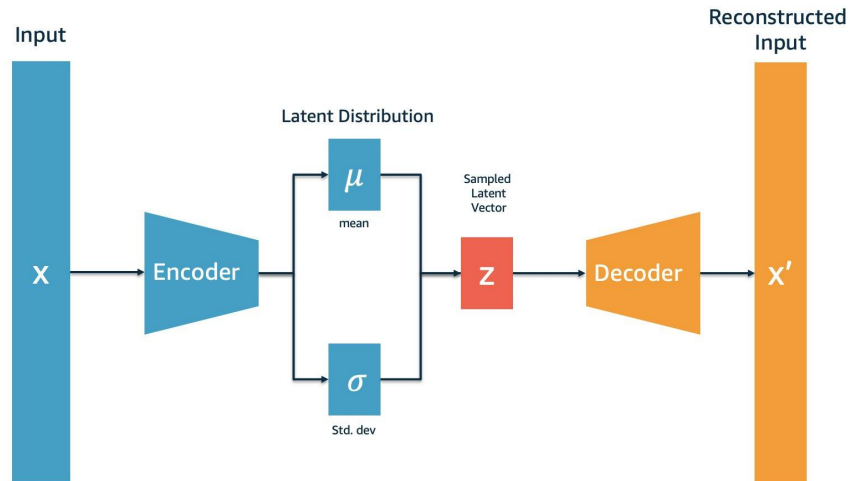
2. Prelim b-tagging results

A b-tag CNN can recover inefficiencies at low m_{HH} seen by conventional strategies



3. Autoencoder for Anomaly Detection

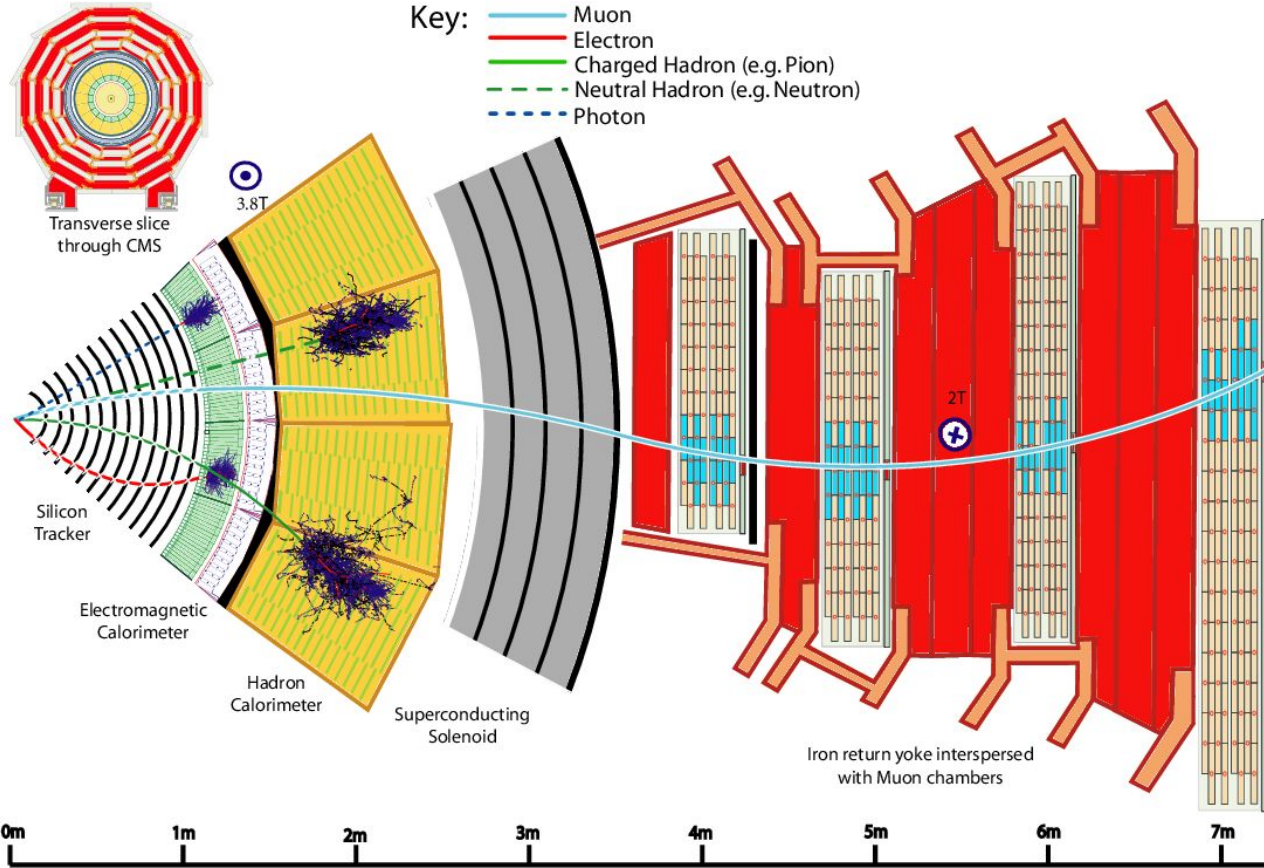
- Possible that new physics events, if any, are systematically rejected by the CMS trigger system
- Requires departure from the usual fully supervised search scheme
- A strategy would be to pose as an anomaly detection task in real time



3. Autoencoder for Anomaly Detection

- The input features consist of (p_T, f) of PUPPI E_{miss} , PUPPI H_T , and (p_T, h, f) of 5 PUPPI jets, for a total of 18 input variables
- The AE is constructed as a multilayer perceptron (MLP) consisting of 8 layers
- Each layer uses ReLU activation function
- objective function is norm_1 distance
- Simple functions for use on FPGAs

3. End-to-End Vertexing NN



3. End-to-End Vertexing NN

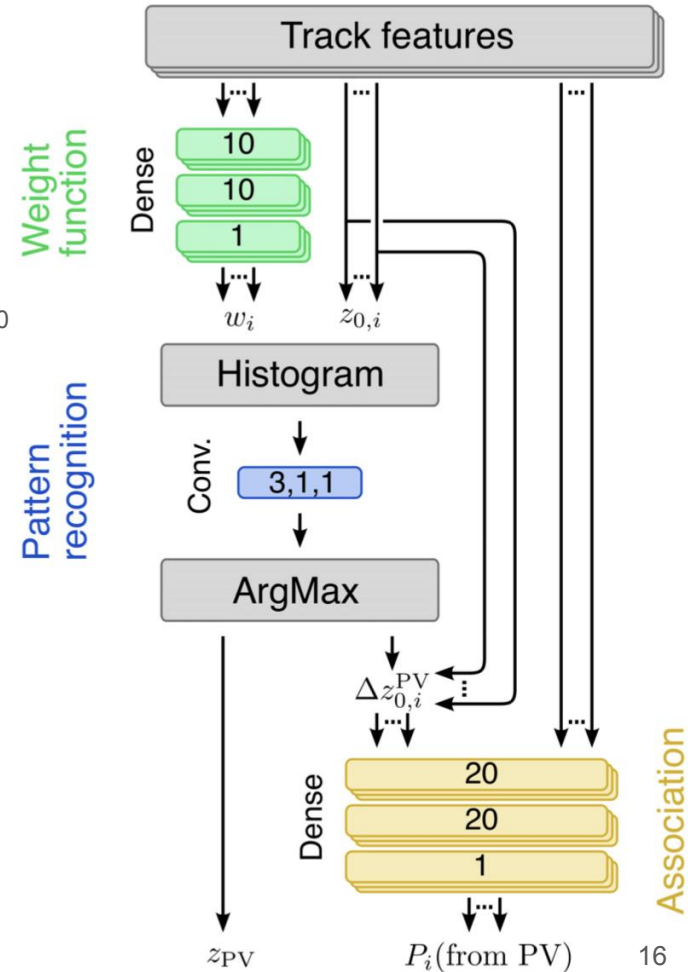
1. Filtering input tracks
2. binning them on z axis
3. performing regression on the histogram to reconstruct vertex z_0 position
4. and finally to associate tracks to the vertex

are combined using “end-to-end ML” as a potential improvement to the vertexing performance.

Uses a 1D CNN to

1. weight input tracks
2. accumulate tracks in histogram

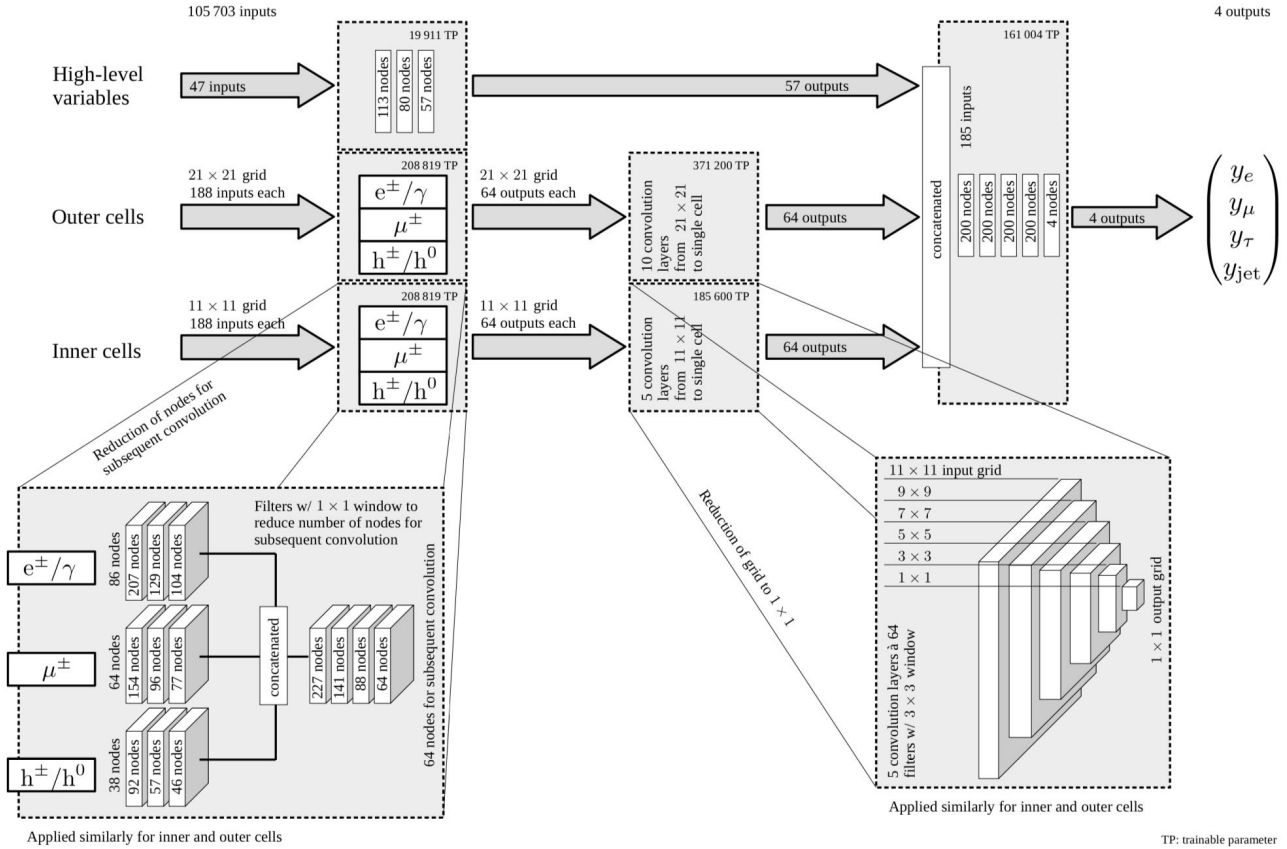
and use another set of convolutional layers to perform peak finding within the histogram



4. Tau ID

- Particle Flow based algorithm
- Iteratively seed from the highest-pT charged particles that have $dR > 0.4$ from each other.
- For each particle, take all particle-flow or PUPPI candidates within $dR < 0.4$.
- Of these candidates, take the 10 highest-pT candidates within the cone, compute pT , $d_{\eta_{seed}}$, $d_{\phi_{seed}}$, and particle ID (40 inputs total), and input these variables into a dense neural network.
- For all candidates within $dR < 0.1$ of the seed, assign them to the tau candidate to compute its four-vector

4. Tau ID



At a Glance

Talked about ML techniques in the trigger

1. Muon Transverse Momentum Estimation: In Muon trigger system
2. B-tagging: In Correlator
3. Autoencoder for Anomaly Detection: In global trigger
4. End-to-End Vertexing NN: In correlator and global track trigger
5. Tau Identification: In Correlator