Machine learning approach for vector boson fusion identification

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Outline



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- 3. Simulation
- 4. ML approach
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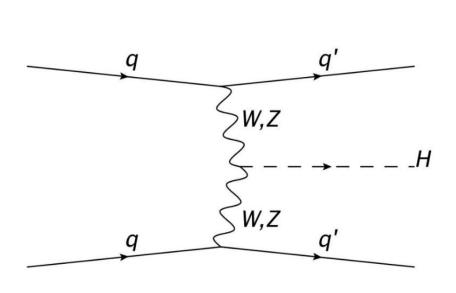
Introduction

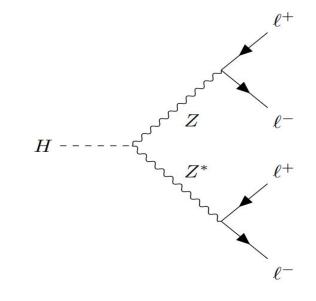


- Vector boson fusion proposed initially as an alternative channel for finding heavy Higgs has now established itself as a crucial search scheme to probe different properties of the Higgs boson or for new physics.
- The emergence of deep learning frameworks, a plethora of machine learning applications have gained immense importance in high-energy physics recently, in collider and neutrino physics.
- Deep learning applications have been widely explored to understand hadronic jets formation and properties, the most common structured object found in any event at LHC.









Higgs production via vector boson fusion

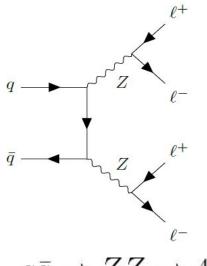
Feynman diagram of the $H \to ZZ^* \to 4\ell$ decay channel





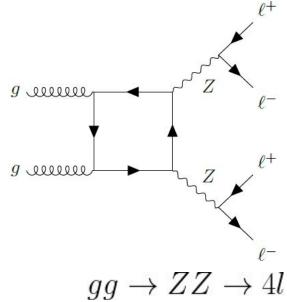
Background

The main background



$$q\bar{q} \to ZZ \to 4l$$

Making up about 80% of all the background



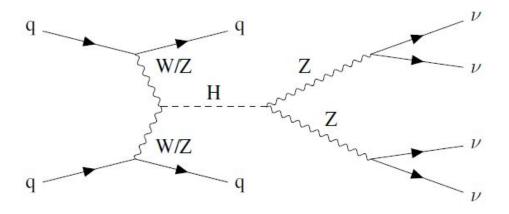
Making up about 3% of all the background





The reference

Machine learning approach towards an improved vector boson fusion selection by *Janna Vischer*



Leading order Feynman diagram of a Higgs created via vector boson fusion and decaying into undetectable particles





In the reference work, three models are proposed.

Network	Learning Rate	AUC-Score	Training Duration	Inference Duration
FullCon-ff	0.0005	0.8591	1 h 35 min	6 min
FullCon-mf	0.0050	0.8757	1 h 40 min	6 min
Particle-Net	0.0050	0.8956	66 h	47 min

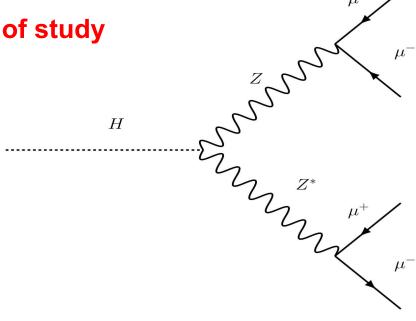
Comparison of the three investigated neural networks in terms of AUC-Score and approximate training and inference duration



VBF (Vector Boson Fusion) and ML







Feynman diagram of the $H \to ZZ^* \to 4\mu$ decay channel



Simulation



Monte Carlo samples

- MADGRAPH5 : Simulates and calculates the effective sections at partonic level
- PYTHIA 8 : Hadronization and Showering processes
- DELPHES 4 : Emulates the detector's response





Input model

34 input features for the model.

```
['missinget_met', 'missinget_phi', 'jet_pt0', 'jet_pt1', 'jet_pt2',
   'jet_pt3', 'jet_eta0', 'jet_eta1', 'jet_eta2', 'jet_eta3',
   'jet_phi0', 'jet_phi1', 'jet_phi2', 'jet_phi3', 'jet_mass0',
   'jet_mass1', 'jet_mass2', 'jet_mass3', 'muon_pt0', 'muon_pt1',
   'muon_pt2', 'muon_pt3', 'muon_eta0', 'muon_eta1', 'muon_eta2',
   'muon_eta3', 'muon_phi0', 'muon_phi1', 'muon_phi2', 'muon_phi3',
   'muon_charge0', 'muon_charge1', 'muon_charge2', 'muon_charge3'],
```





Data processing

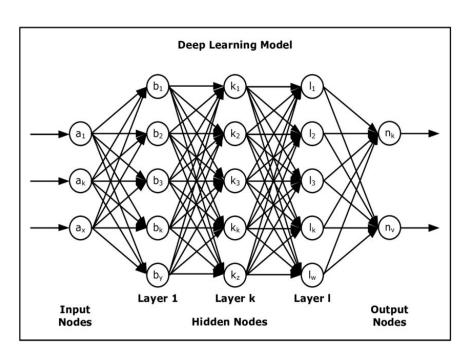
- 1. "n Jet" >= 2
- 2. "Pt Jet" > 30
- 3. The background is bigger that the Signal
- 4. Scalar data with method StandardScaler()
- Resample signal
- 6. 70% train, 30% Val
- 7. Batch_size and epochs are defined depending on the performance of the model.





Proposed model architecture

- Input layer with 34 input features.
- Dense layer with 200 neurons, reluativation function.
- Dense layer with 100 neurons, reluativation function.
- Dense layer with 50 neurons, reluation activation.
- Dense layer with 25 neurons, reluativation function.
- Dense layer with 1 neurons, sigmoid activation function.
- Output with VBF identification score



Model architecture

<u>Preliminary</u>



Conclusions



- A new ML architecture for VBF identification is proposed, it is expected to be more efficient in execution time and performance.
- The methodology for the VBF identification with machine learning is defined.
- ❖ Different sources that apply ML models for VBF were studied, the performance of these models in AUC-Score is greater than 0.85.





Thank you!!



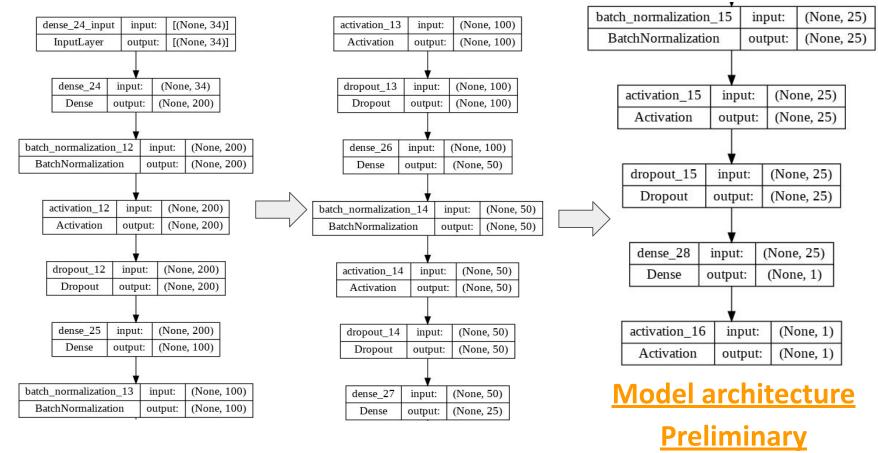


Backup

December 1st 2022, UdeA









BACKGROUND



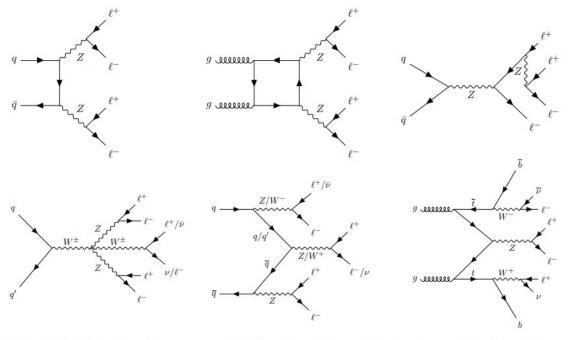


Figure 62: Irreducible background contributions to the 4ℓ signal selection. $q\bar{q}ZZ$ (top left) contributes the most. Next is ggZZ (top middle) and single resonant $Z \to 4\ell$ (top right). Triboson (ZZW,WWZ,ZZZ) (bottom left and middle) and $V+t\bar{t}$ all-leptonic (bottom right) are minor irreducible backgrounds.



Model architecture - Preliminary



```
def MODEL VBF(n features):
   model = Sequential()
   model.add(Dense(200, input shape=(n features,), kernel initializer="glorot normal"))
   model.add(BatchNormalization())
   model.add(Activation("relu"))
   model.add(Dropout(0.5))
   model.add(Dense(100, kernel initializer="glorot normal", use bias=False))
   model.add(BatchNormalization())
   model.add(Activation("relu"))
   model.add(Dropout(0.25))
   model.add(Dense(50, kernel initializer="glorot normal", use bias=False))
   model.add(BatchNormalization())
   model.add(Activation("relu"))
   model.add(Dropout(0.15))
   model.add(Dense(25, kernel initializer="glorot normal", use bias=False))
   model.add(BatchNormalization())
   model.add(Activation("relu"))
   model.add(Dropout(0.1))
   model.add(Dense(1, activation="sigmoid"))
   model.compile(loss="binary_crossentropy", optimizer="adam", metrics=["accuracy"])
    return model
```