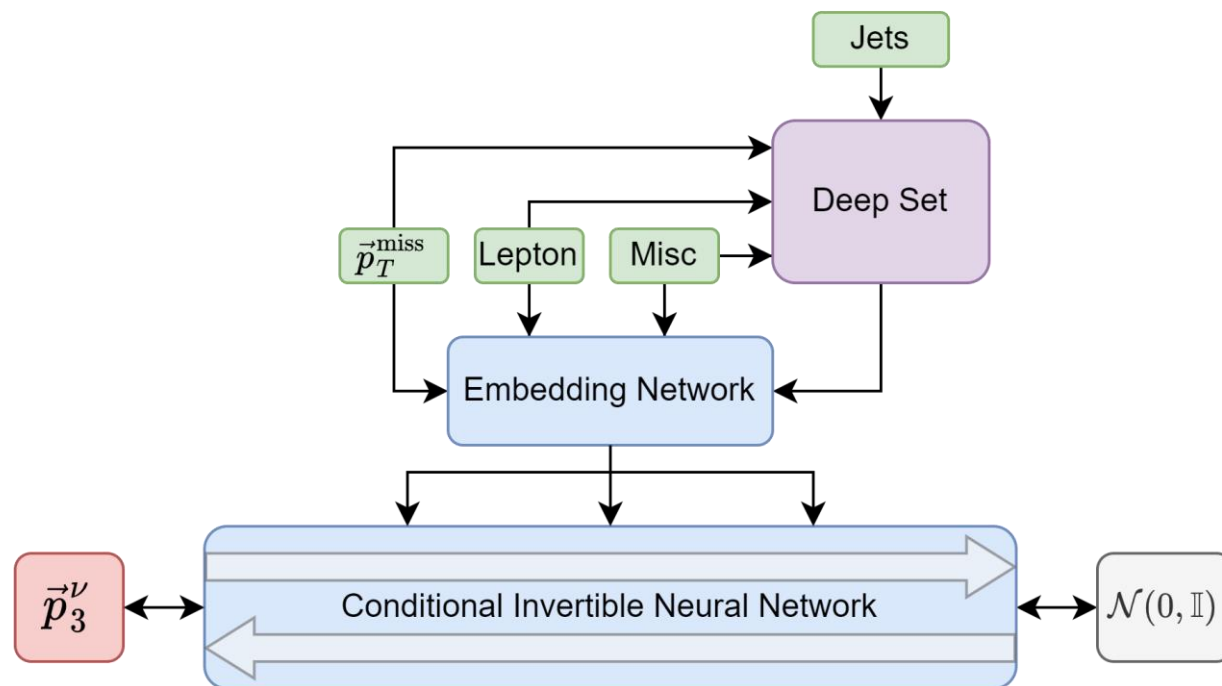


ν -Flows

Conditional Neutrino Regression



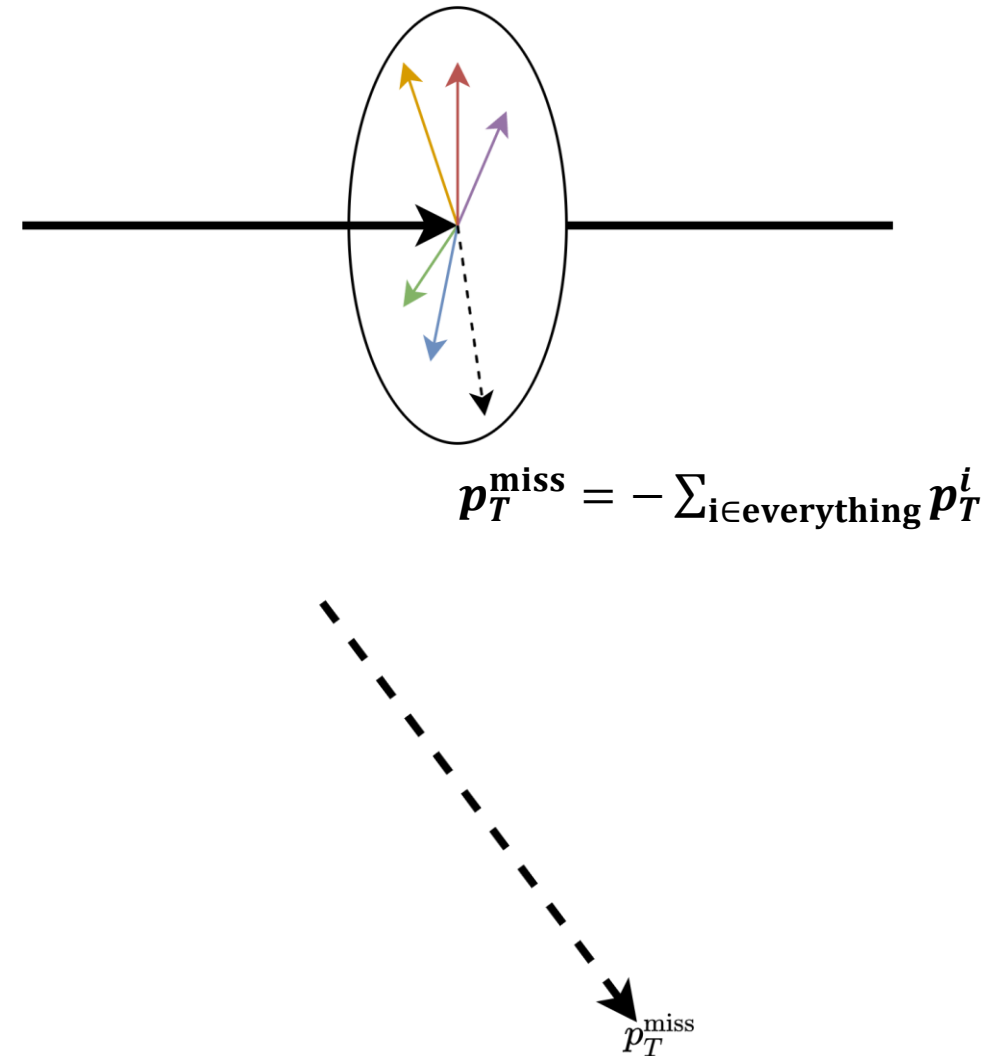
Matthew Leigh Tobias Golling Johnny Raine
ML4Jets 2022

Problem: Neutrino Kinematics

- Neutrinos are not directly observable

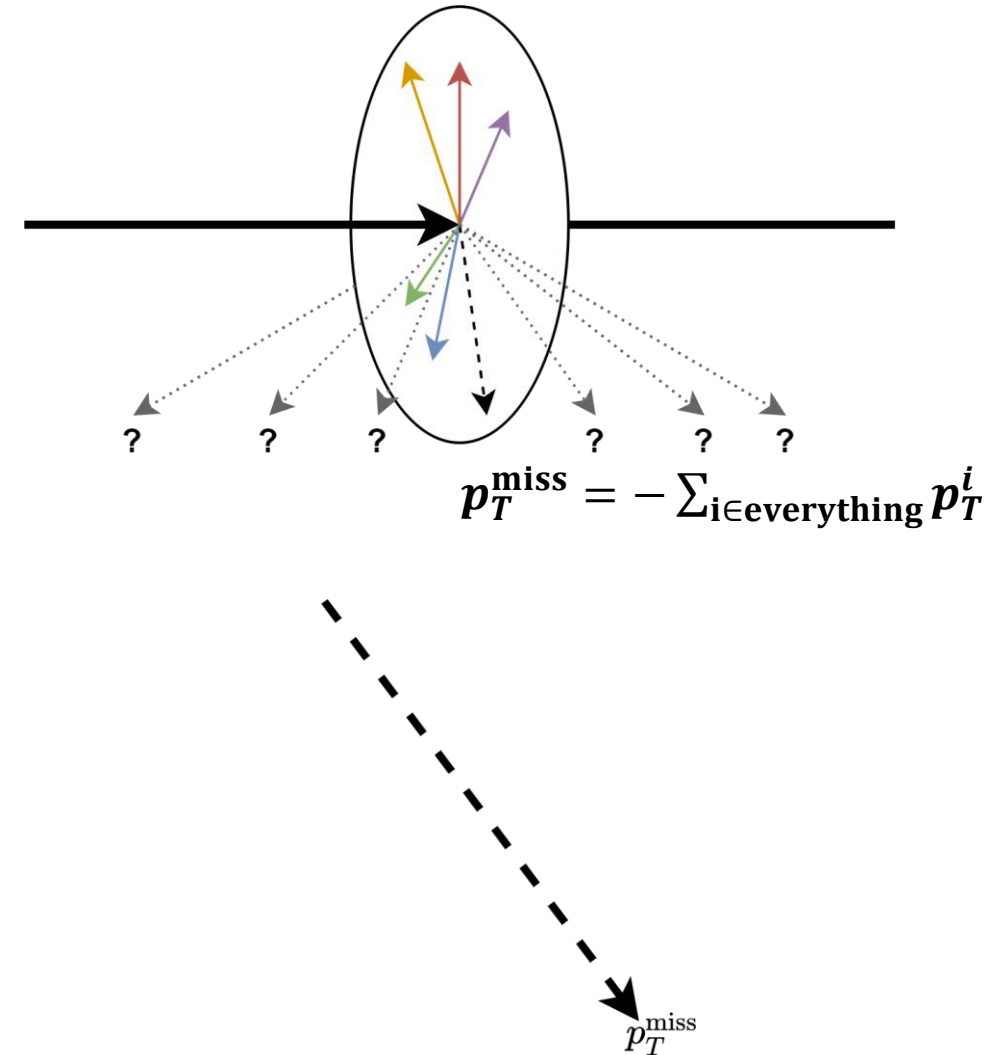
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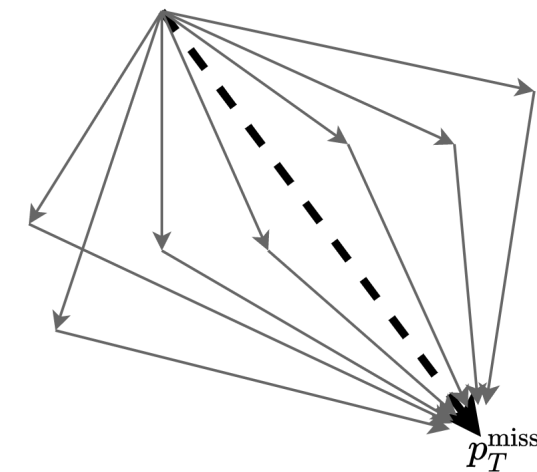
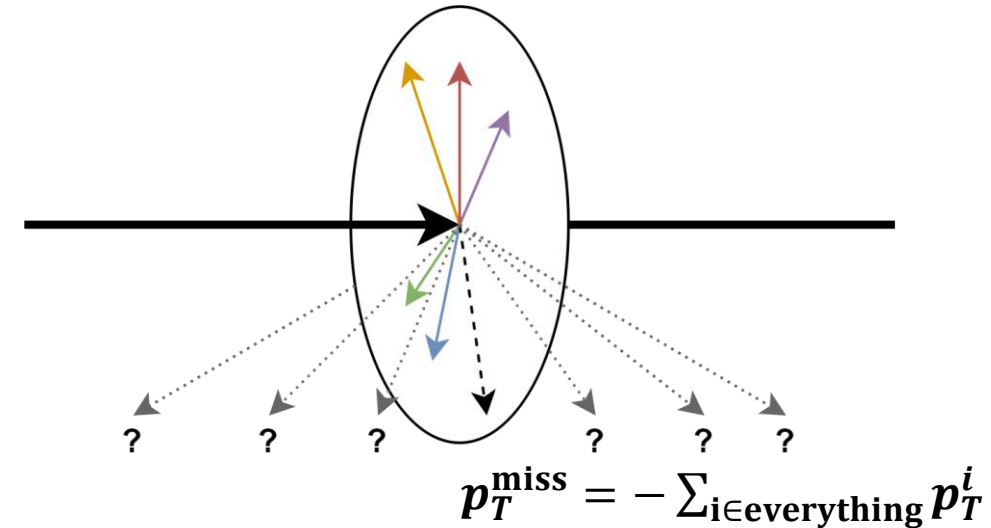
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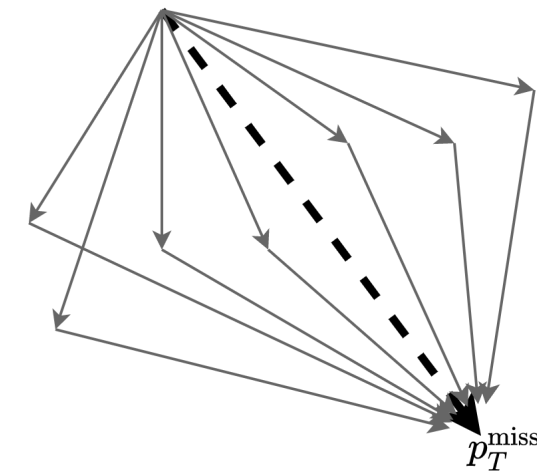
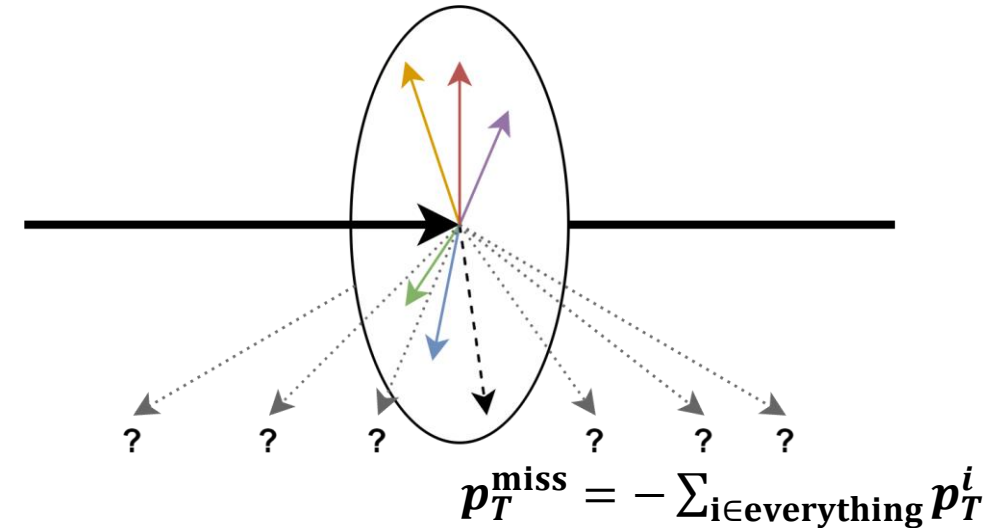
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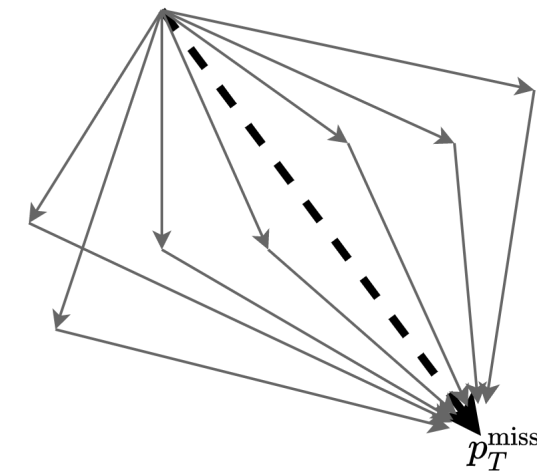
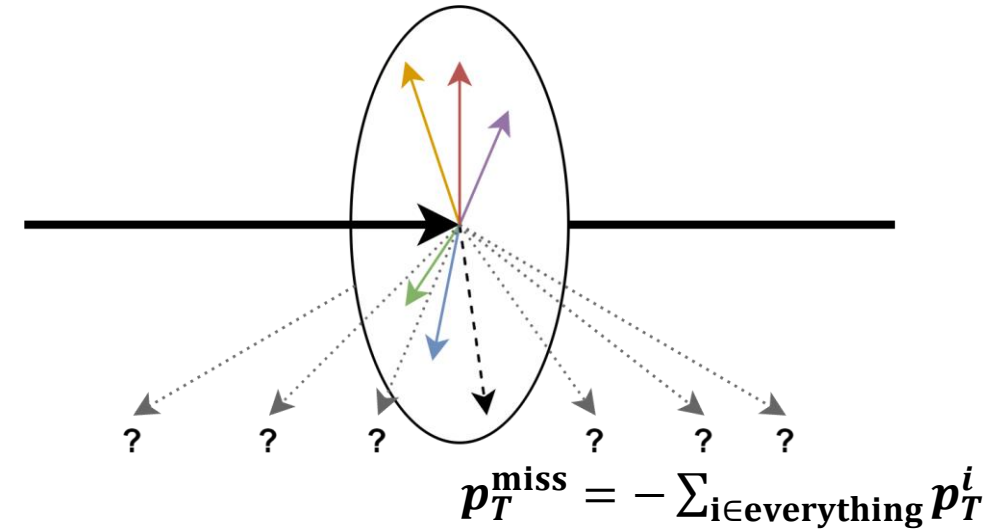
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 - **Transverse** momenta in final states with more than one neutrino are **under-constrained**
- Any indication of the neutrino kinematics could benefit a wide variety of analyses in collider physics



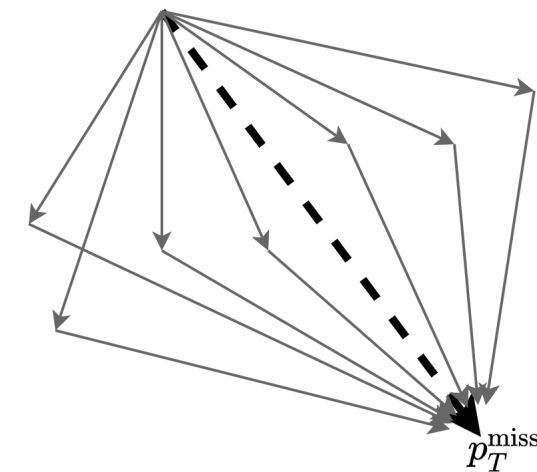
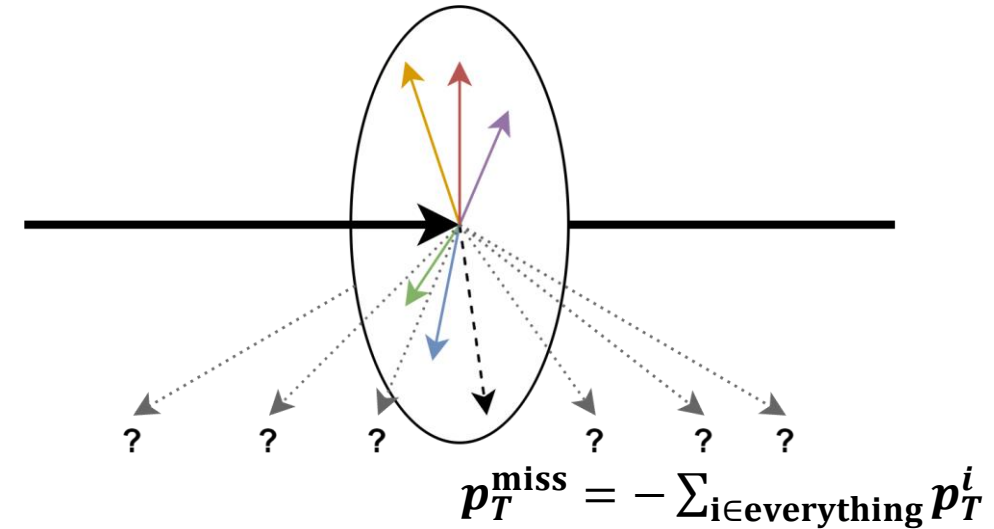
Our Approach

- Many solutions might be **possible** but not equally **likely**
 - **Leverage information** from the event to constrain this likelihood



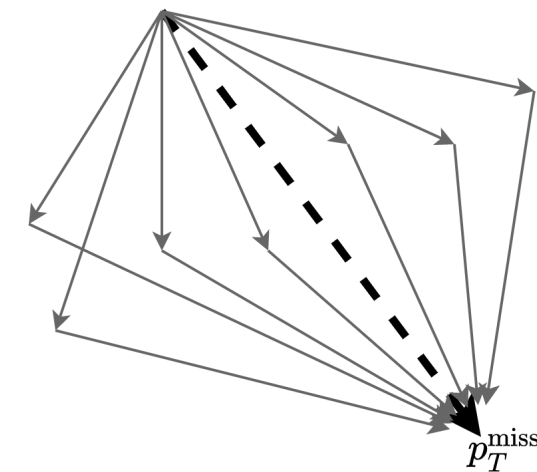
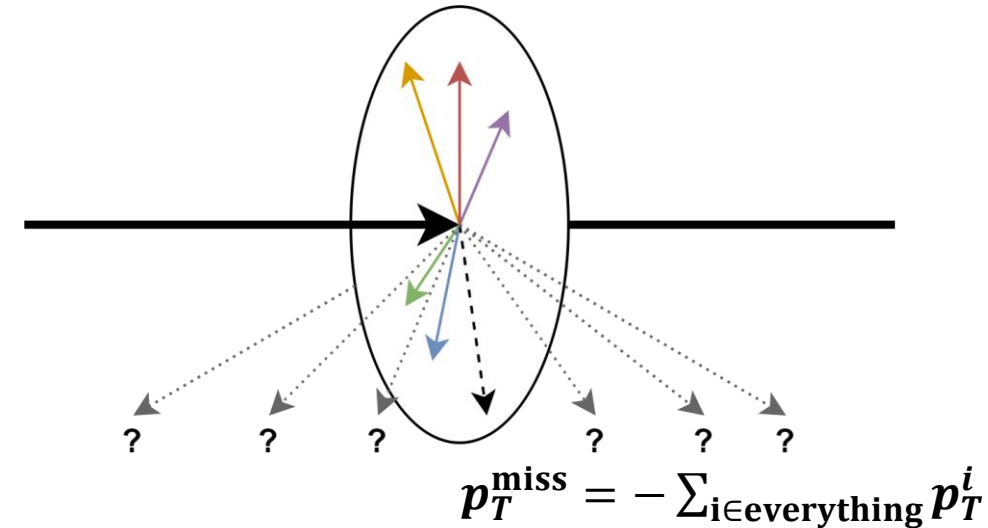
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 - Assume an underlying process



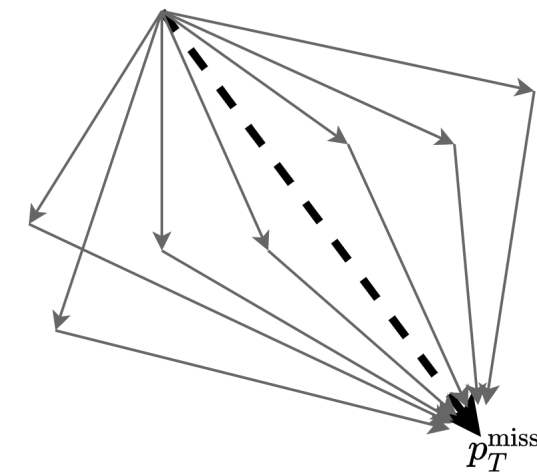
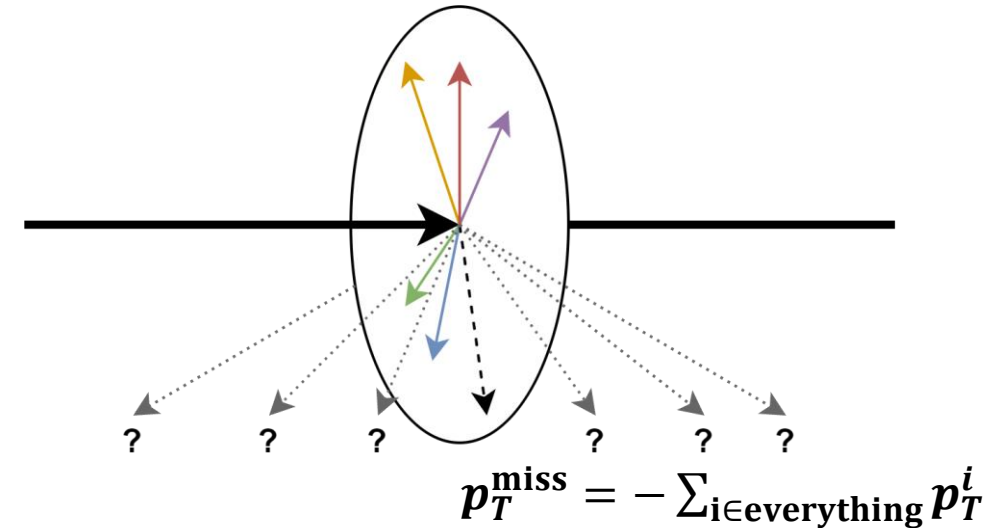
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 - Standard supervised regression methods might not be applicable



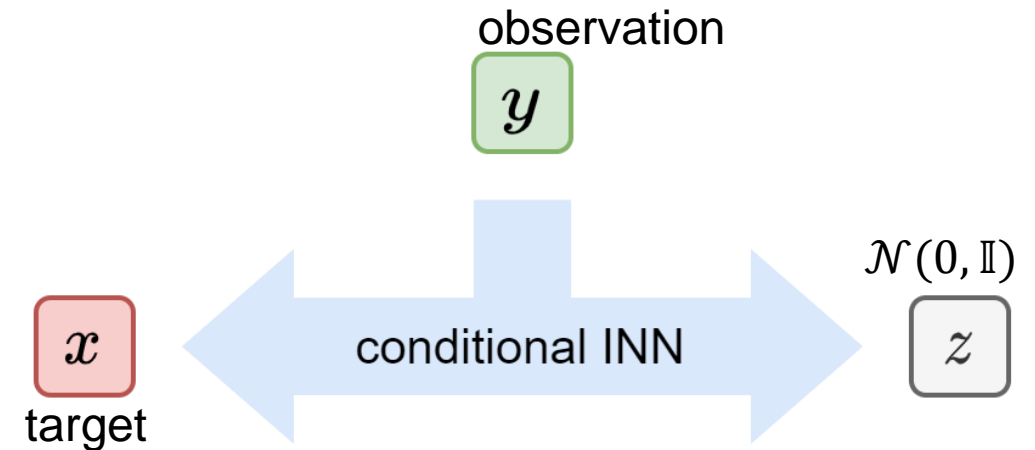
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 - Standard supervised regression methods might not be applicable
- Propose to a **conditional normalizing flow** to learn a **conditional likelihood** over the neutrino momenta



Conditional Normalising Flows

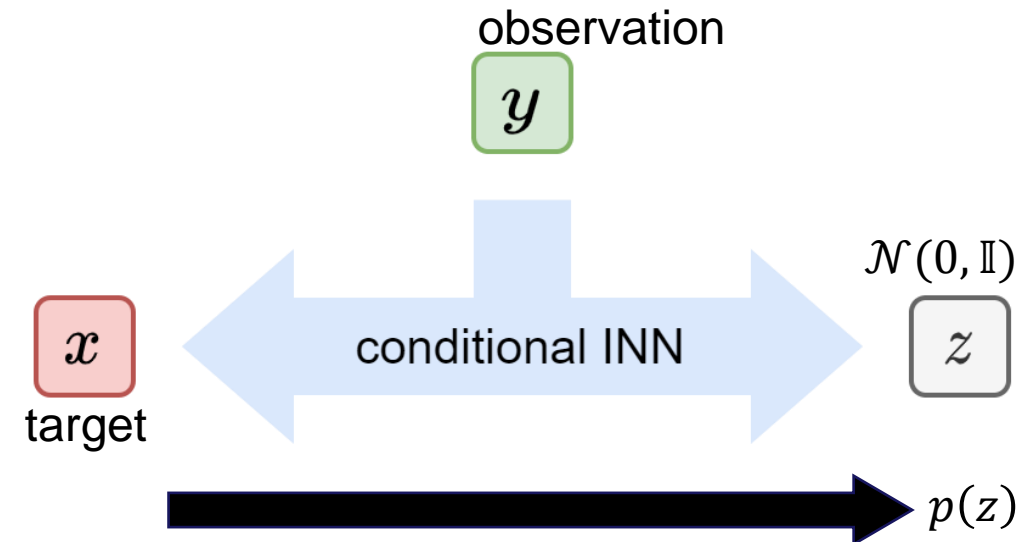
- **Conditional normalising flows** parameterise an invertible map from x to z given y as **conditioning** inputs
 - (y, x) can be seen as **input/target** training pair



Conditional Normalising Flows

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 - (y, x) can be seen as **input/target** training pair
- **Training:** Model runs forward for **maximum likelihood** objective

$$\begin{aligned}
 \text{Loss}(y, x) &= -\log(p_X(x|y)) \\
 &= -\log\left(p_Z(f_\theta(x|y))\right) - \log|\det(J(x|y))|
 \end{aligned}$$

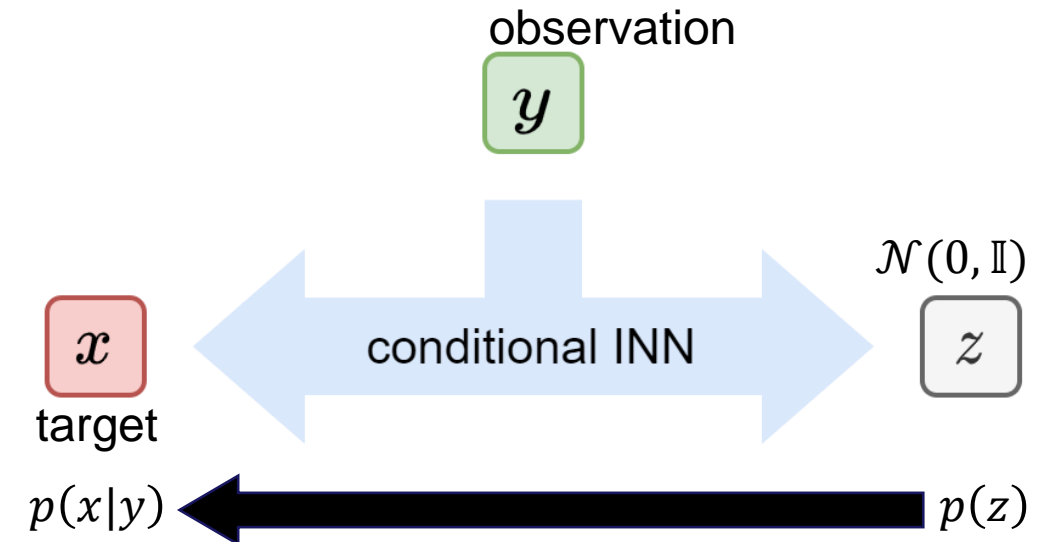


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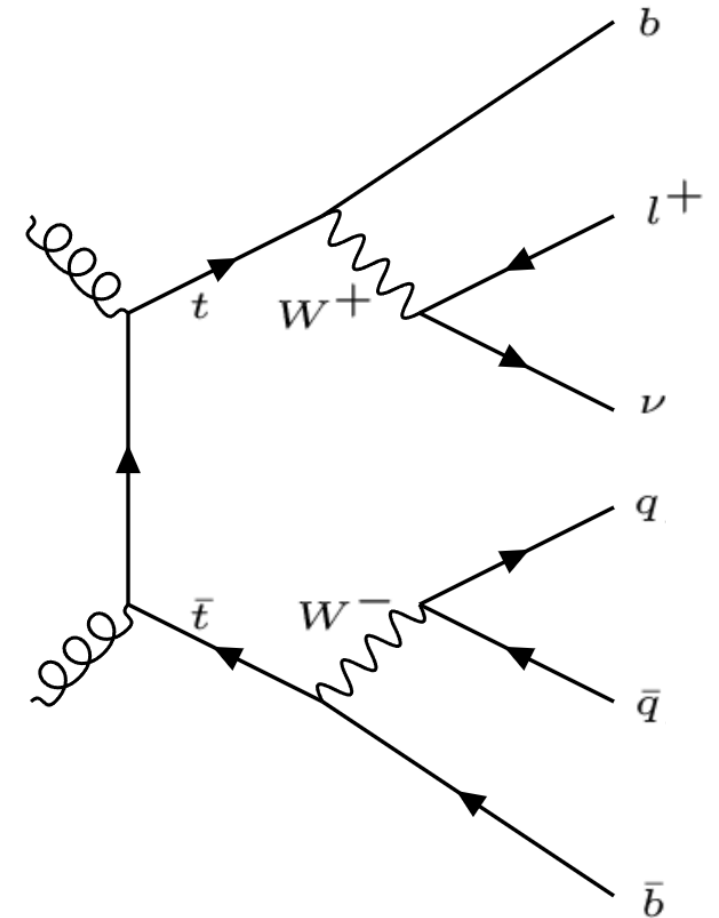
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- **Sampling:** Model runs in reverse giving $p(x|y)$



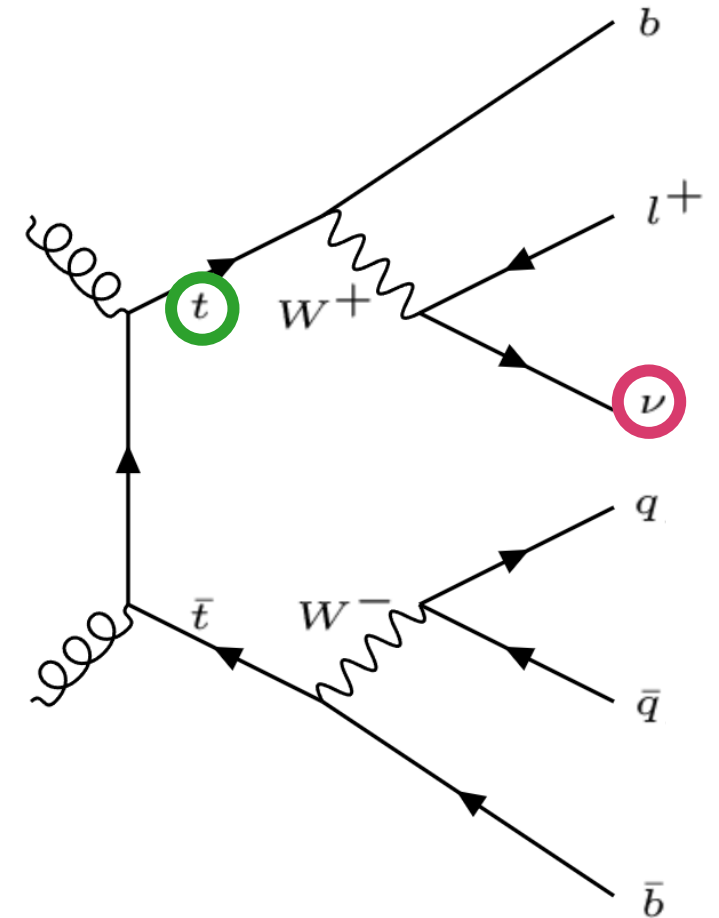
Case Study: Single Leptonic $t\bar{t}$

- Commonly studied process is the **single leptonic $t\bar{t}$** decay



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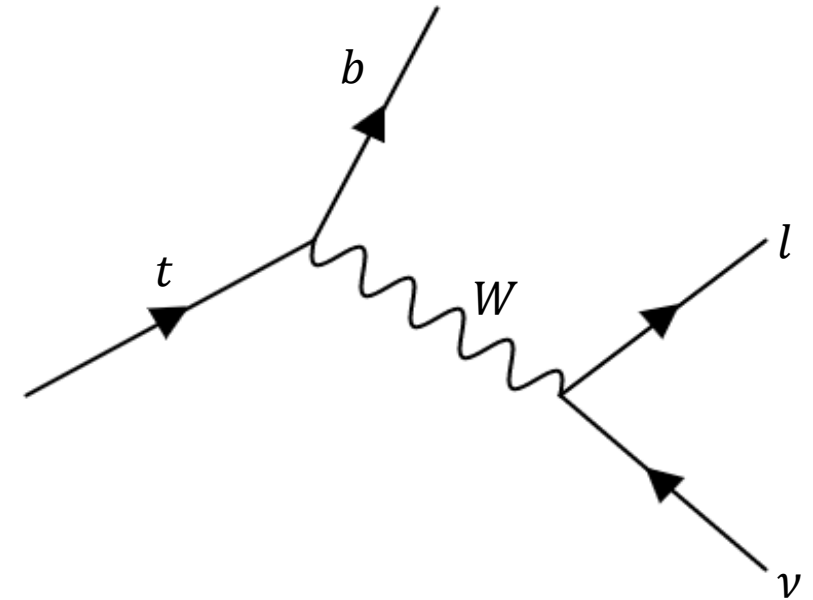
- Commonly studied process is the **single leptonic $t\bar{t}$** decay
- Full properties of **leptonic top** not directly measurable due to the unknown **longitudinal momentum of the neutrino** in the final state



Kinematic Solution: $W \rightarrow l\nu$

- If we **assume** that
 - $(p_x^\nu, p_y^\nu) = (p_x^{\text{miss}}, p_y^{\text{miss}})$
 - $m_W = 80.38 \text{ GeV}$
- Can **solve** for neutrino's **longitudinal** momentum:

$$p_z^\nu = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$



$$a = (p_z^\ell)^2 - (E^\ell)^2,$$

$$b = \alpha p_z^\ell,$$

$$c = \frac{\alpha^2}{4} - (E^\ell)^2 (p_T^\nu)^2,$$

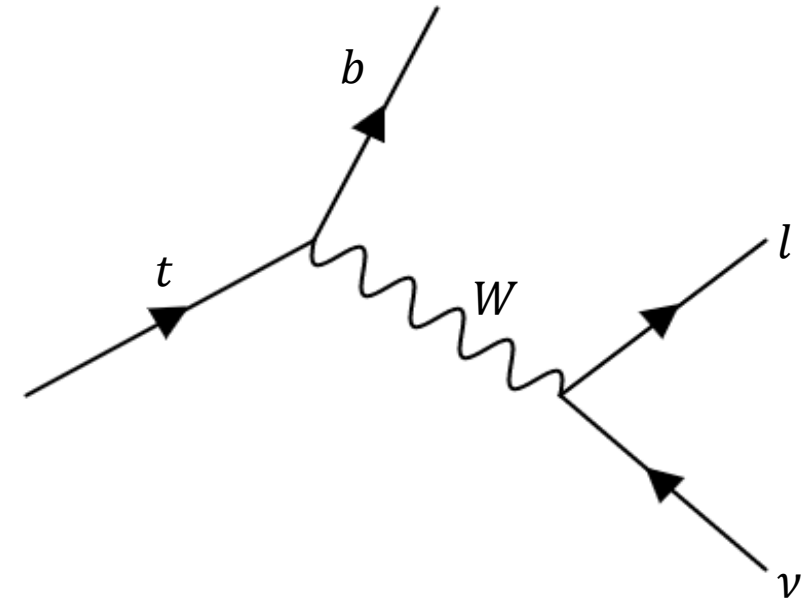
$$\alpha = m_W^2 - m_\ell^2 + 2(p_x^\ell p_x^\nu + p_y^\ell p_y^\nu).$$

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 - Take the estimate **closer to zero**
 - Consider **both possibilities** in any downstream tasks



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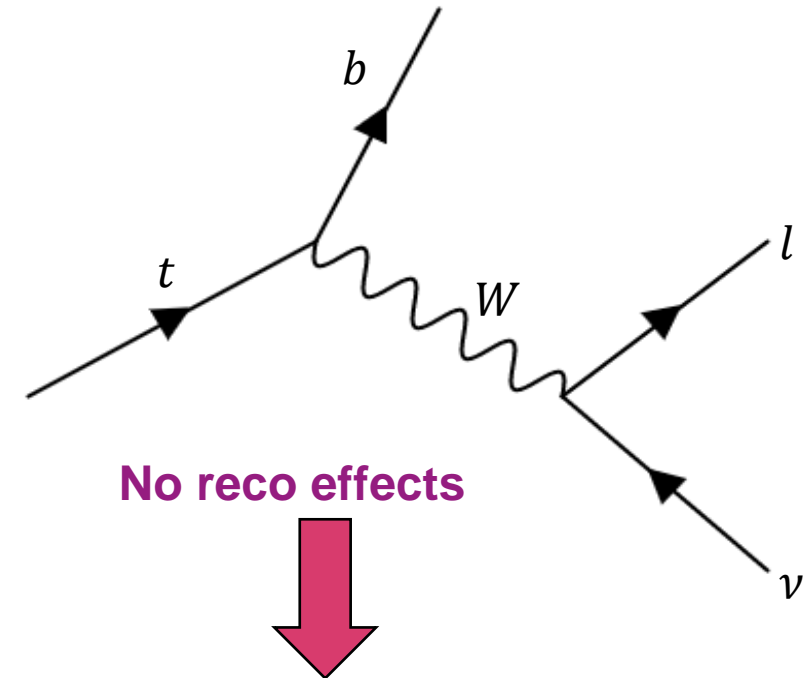
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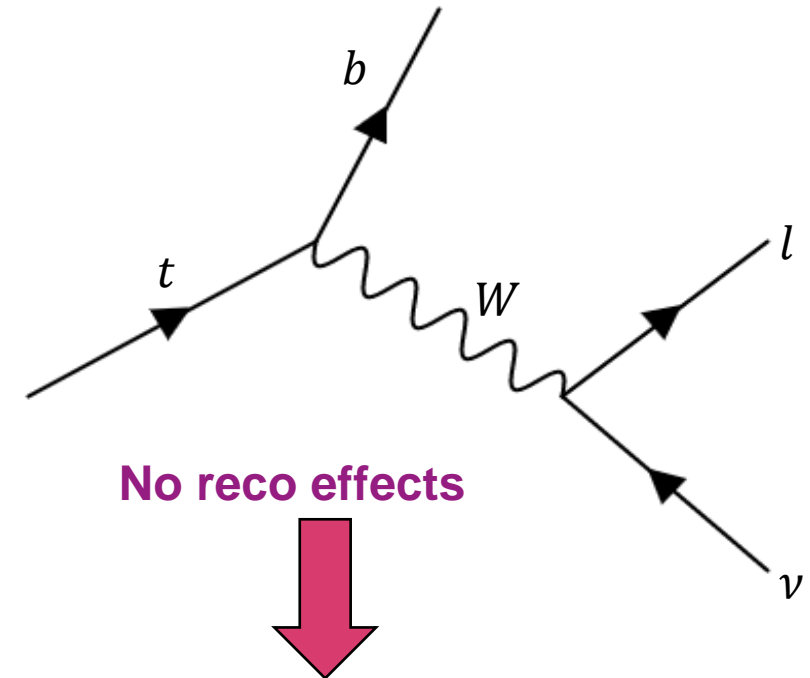
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← **No off-shell
No reco effects**
- Can **solve** for neutrino's **longitudinal** momentum:

$$p_z^\nu = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

← **Sometimes lead to
no real solutions!**
- Gives two solutions** with no preference
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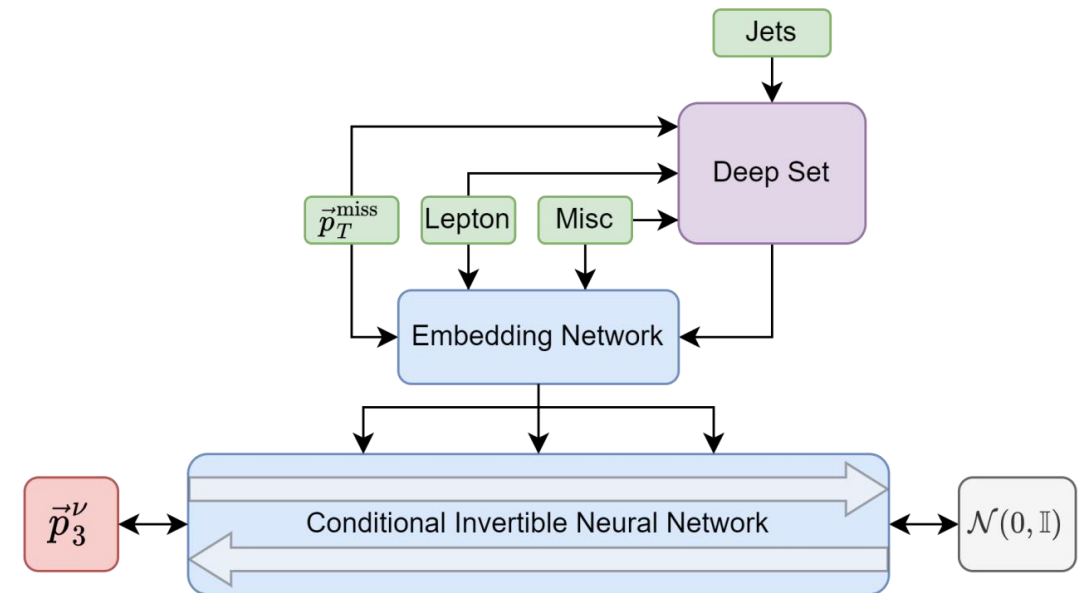
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ν -Flow Overview

- Trained using simulated single leptonic $t\bar{t}$
<https://doi.org/10.5281/zenodo.6782987>

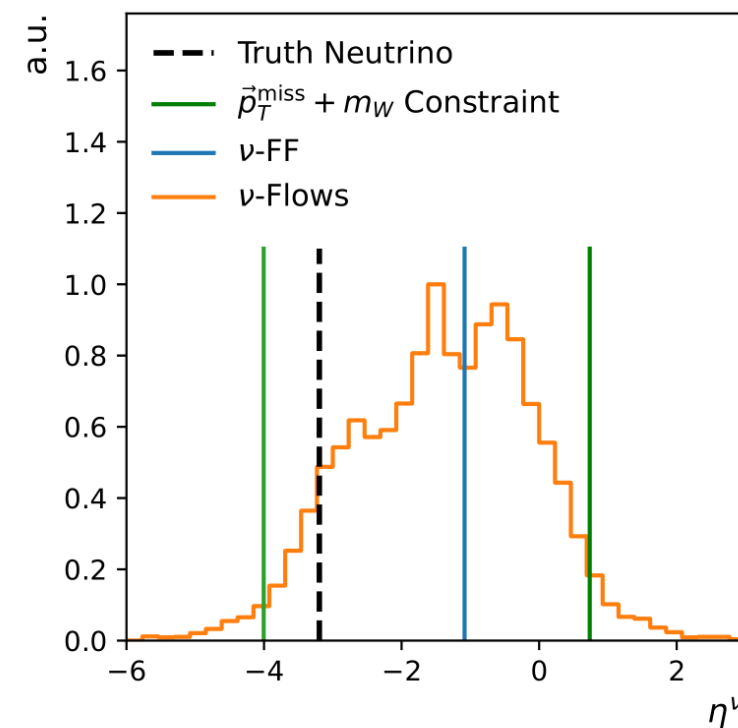
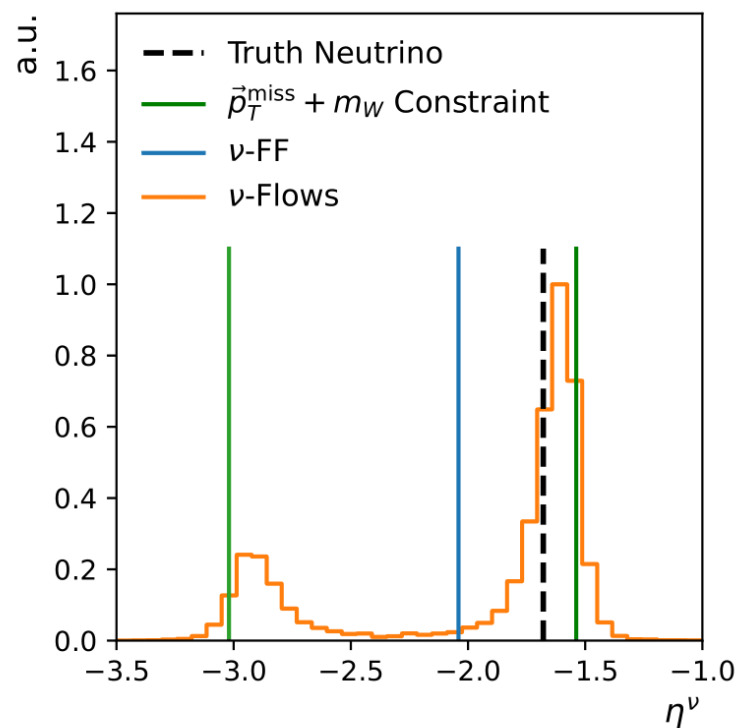
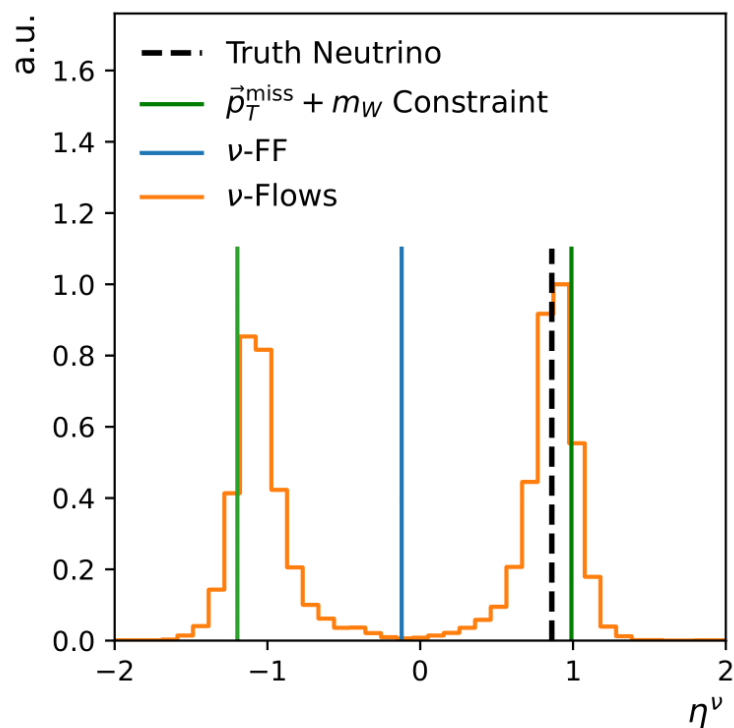
Category	Variables	Description
	\vec{p}_T^{miss}	$p_x^{\text{miss}}, p_y^{\text{miss}}$ Missing transverse momentum 2-vector
Lepton	$p_x^\ell, p_y^\ell, \eta^\ell, \log E^\ell$ ℓ^{flav}	Lepton momentum 4-vector Whether lepton is an electron or muon
Jets	$p_x^j, p_y^j, \eta^j, \log E^j$ isB	Jet momentum 4-vector If jet met b -tagging criteria
Misc	$N_{\text{jets}}, N_{\text{bjets}}$	Jet and b -jet multiplicities in the event



- Combines observations + assumptions in fully probabilistic way
- Can scale to multiple neutrinos

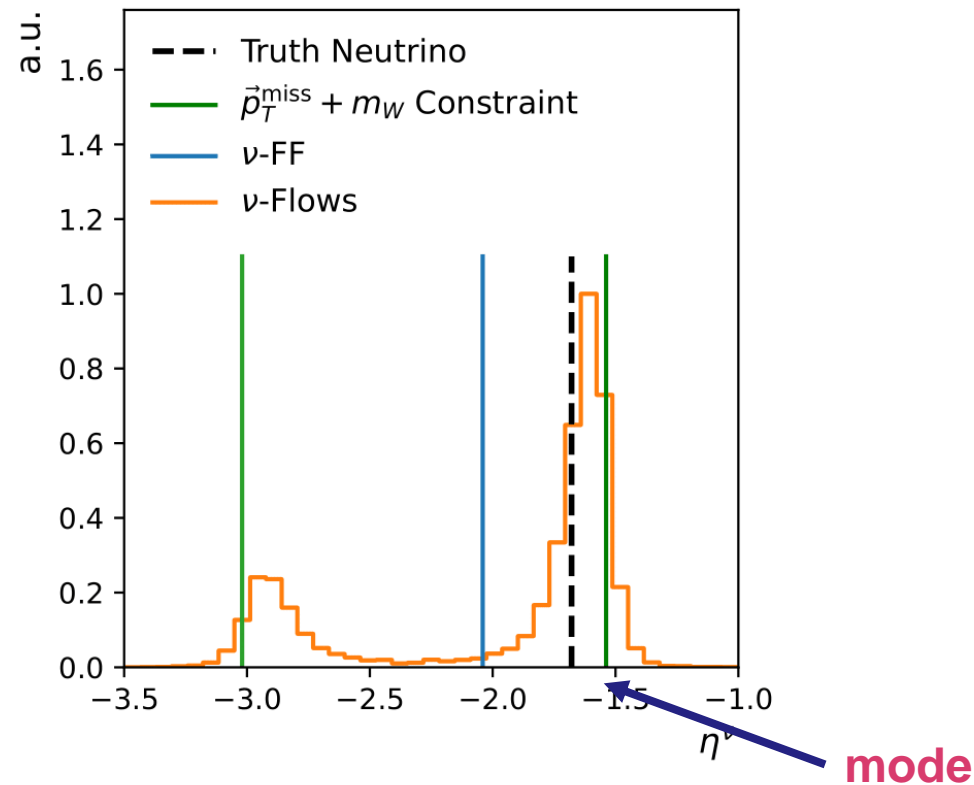
Inference on Individual Events

Cherry picked representative examples



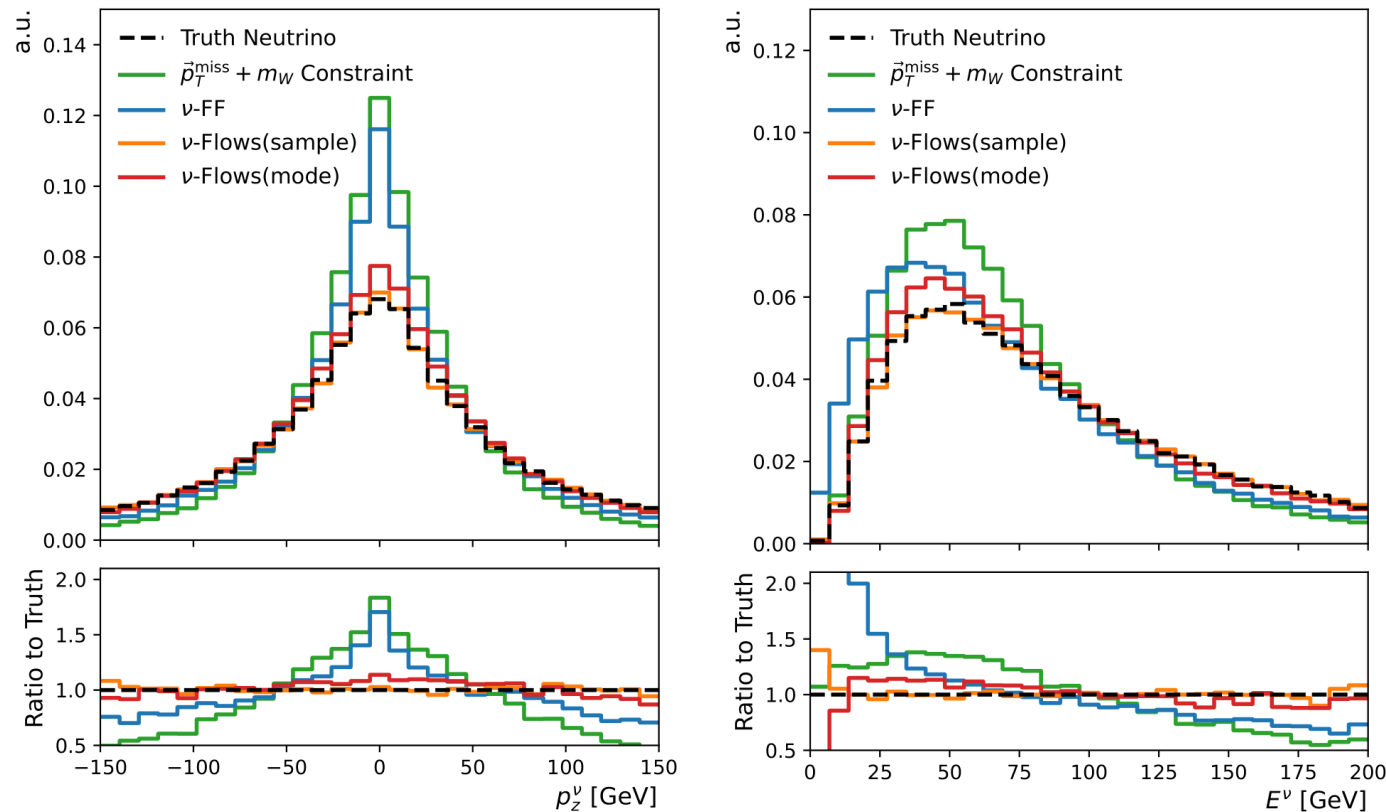
Results: Neutrino Kinematics

- Neutrino kinematic distributions for different methods of generation
 - **ν -Flows(sample)**: Take **one sample** from $p(x|y)$
 - **ν -Flows(mode)**: Take **1024 samples** keep one with **highest likelihood under flow**



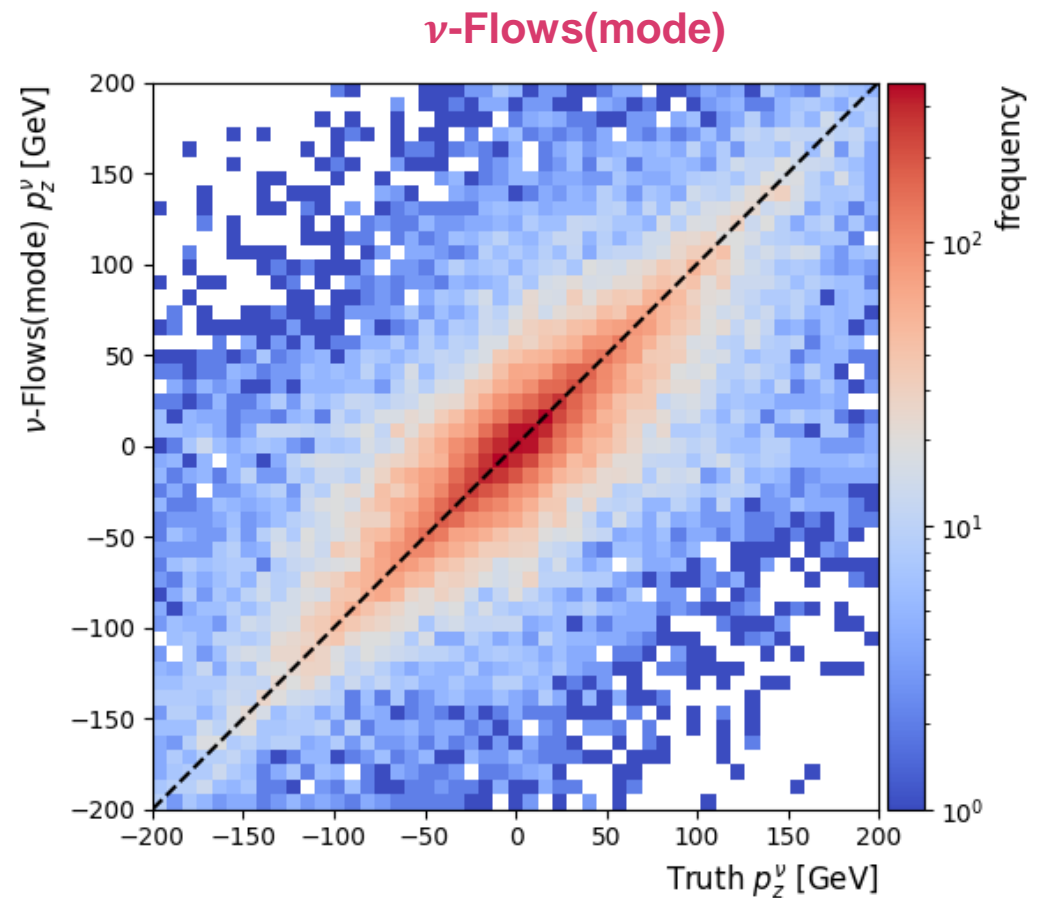
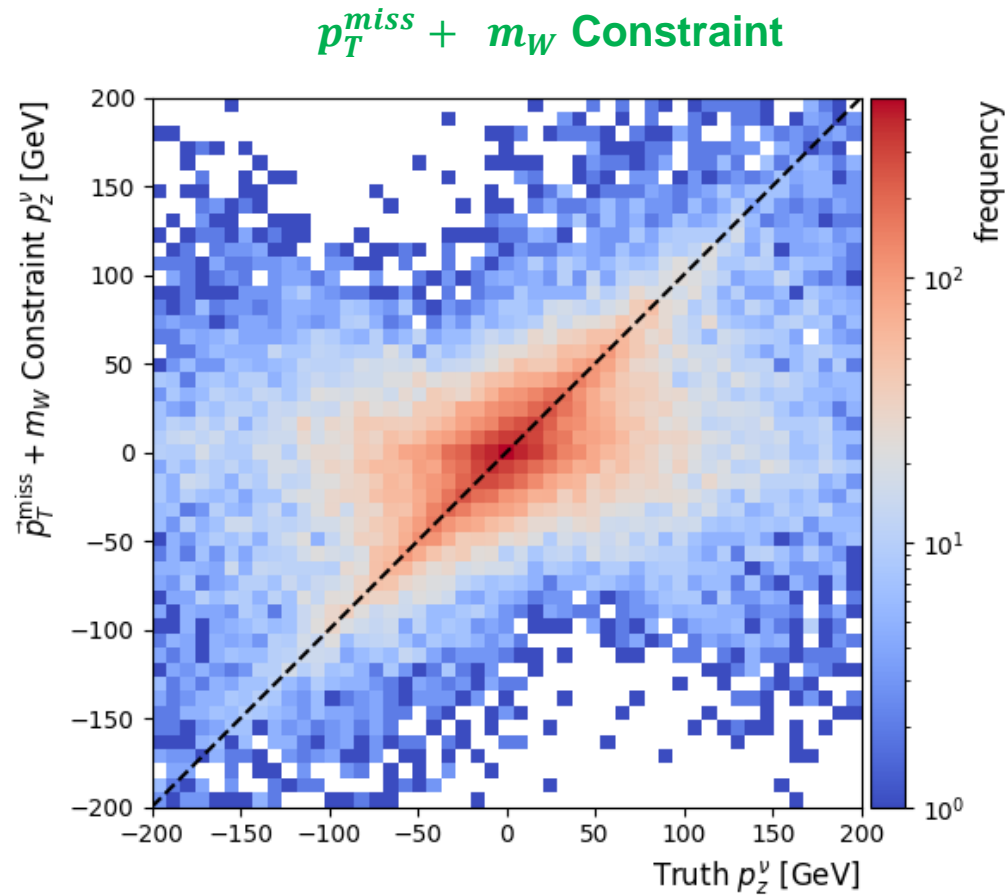
Results: Neutrino Kinematics

- Neutrino kinematic distributions for different methods of generation
 - ν -Flows(sample): Take **one sample** from $p(x|y)$
 - ν -Flows(mode): Take **256 samples** keep one with **highest likelihood under flow**



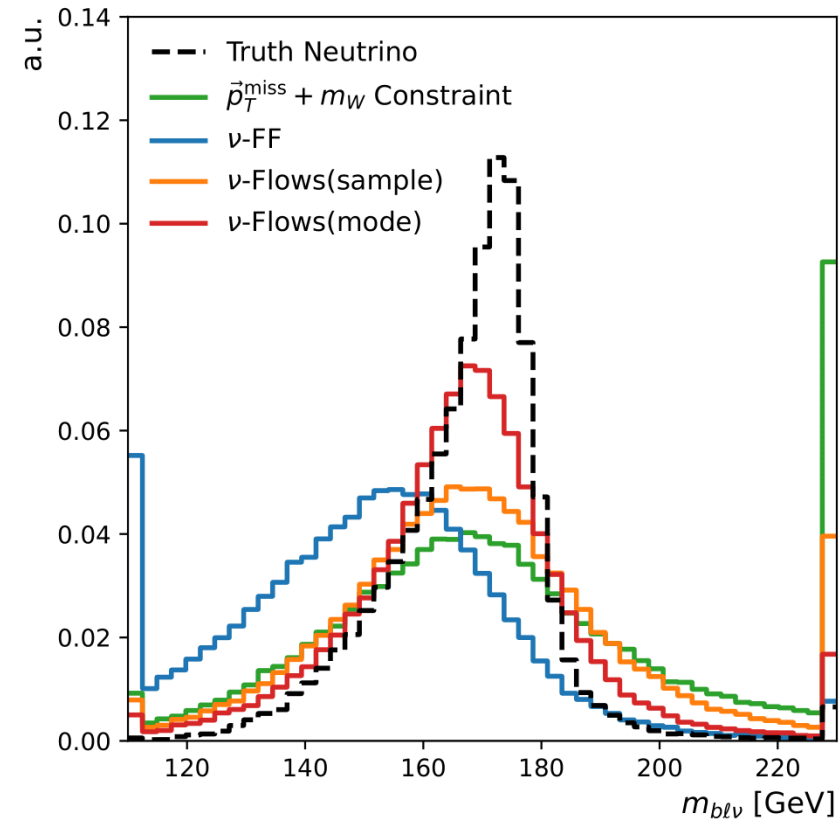
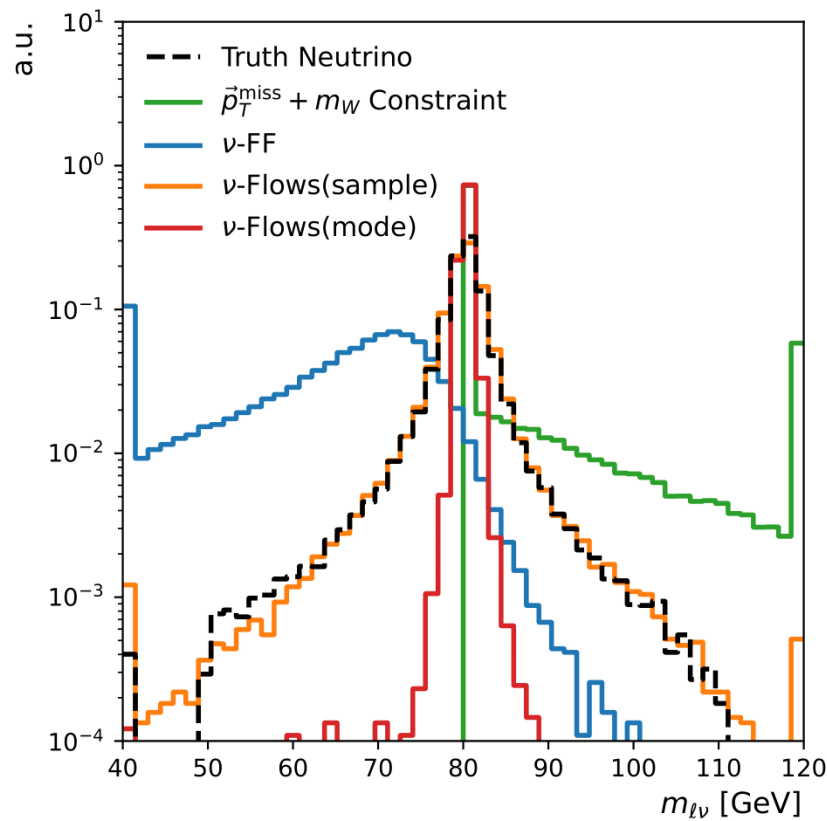
Results: Neutrino Kinematics

- Reconstructed p_z vs Truth p_z



Results: Invariant Mass Reconstruction

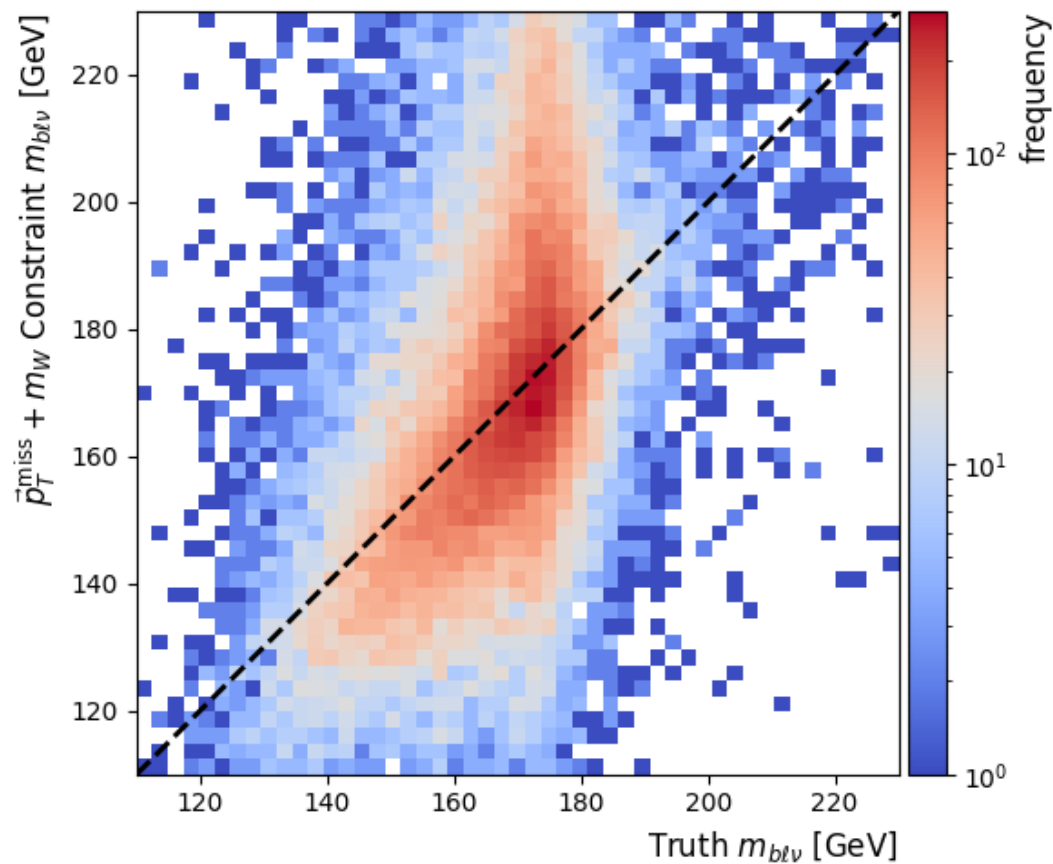
- **Invariant mass reconstruction of the leptonic W and leptonic t**
 - t is reconstructed **using the correct b-jet** (not guaranteed in data)



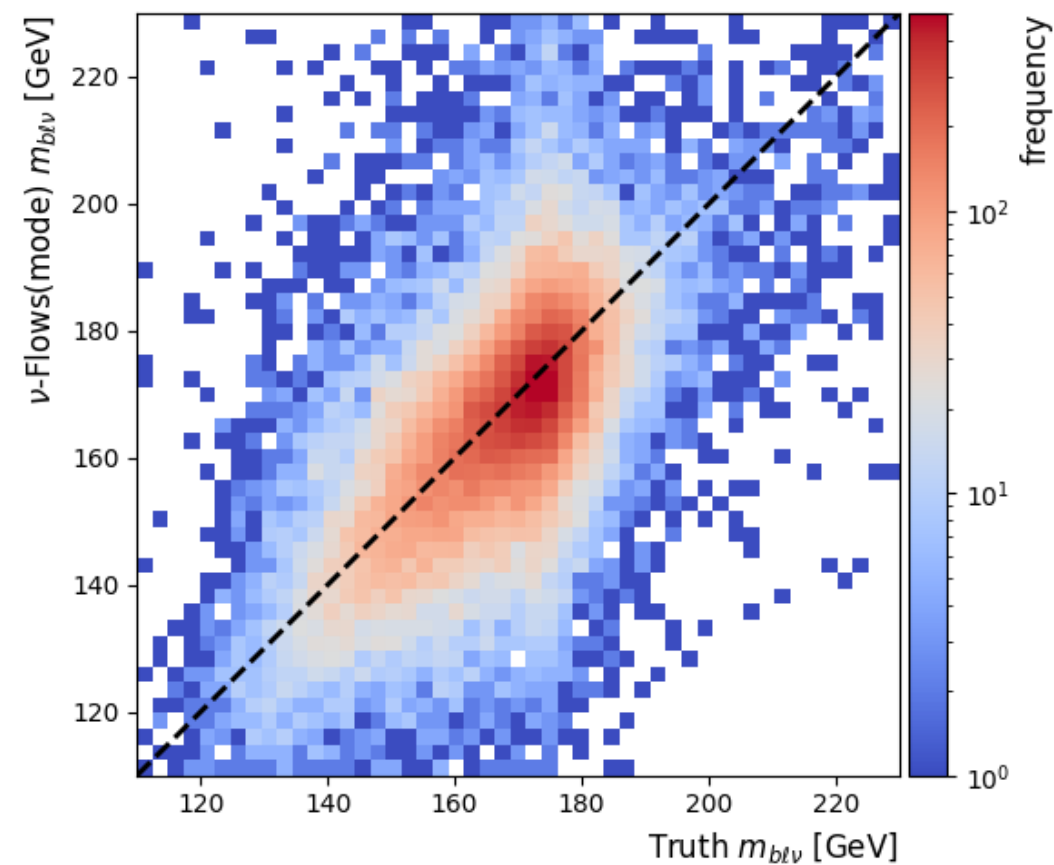
Results: Invariant Mass Reconstruction

- Reconstructed m_t vs Truth m_t

$p_T^{miss} + m_W$ Constraint



ν -Flows(mode)



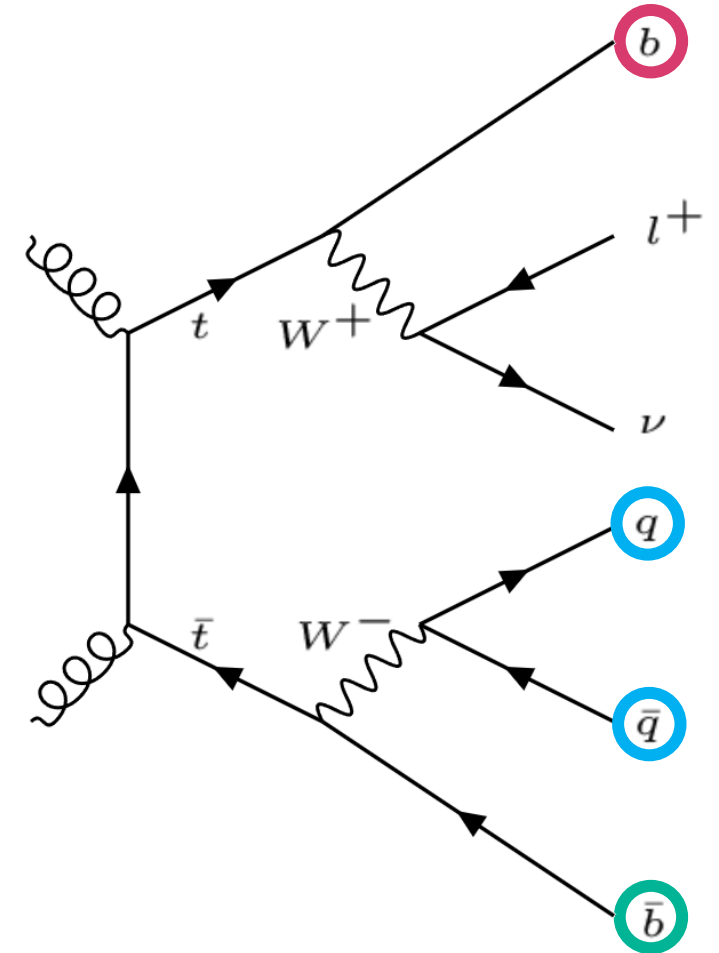
χ^2 : Downstream Task Example

- Don't know which of our reconstructed jets correspond to the b_{lep} , b_{had} , q_1 , or q_2
 - Up to 9 reconstructed jets

- Test **all possible jet permutations**
- Take permutation with **smallest χ^2**

$$\chi^2 = \frac{(m_W - m_{l\nu})^2}{\sigma_{l\nu}} + \frac{(m_W - m_{qq})^2}{\sigma_{qq}} + \frac{(m_t - m_{bl\nu})^2}{\sigma_{bl\nu}} + \frac{(m_t - m_{bqq})^2}{\sigma_{bqq}}$$

- Example of a method used in many combinatoric solving approaches (χ^2 , KLFitter, etc)



χ^2 : Association Results

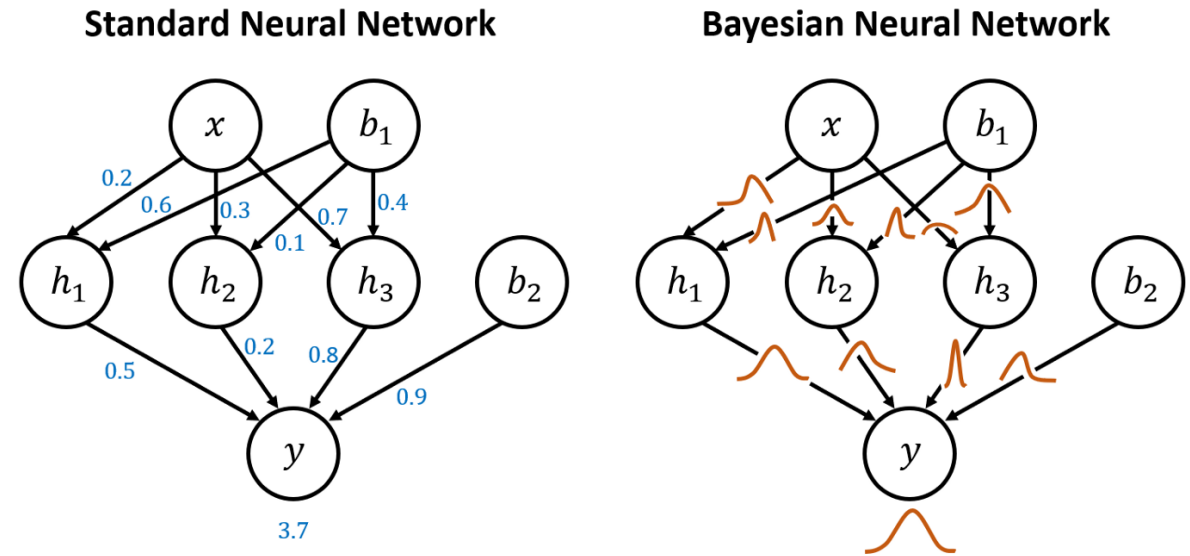
- **Association accuracy** of the b_{lep} verses the **number of jets**
 - Parton with highest dependance on neutrino in χ^2 fit
- Events where the **4 signal jets** were reconstructed

Neutrino Type	Number of Jets					
	4	5	6	7	8	9
Truth Neutrino	0.864	0.753	0.686	0.641	0.611	0.587
\vec{p}_T^{miss} and m_W Constraint	0.790	0.576	0.476	0.398	0.366	0.286
ν -FF	0.754	0.533	0.410	0.353	0.300	0.302
ν -Flows(sample)	0.803	0.624	0.515	0.457	0.391	0.357
ν -Flows(mode)	0.813	0.664	0.575	0.508	0.481	0.405

ν -Flow (mode) improves
upon kinematic solution by
factor of **1.03 to 1.41**

Bayesian Normalising Flows

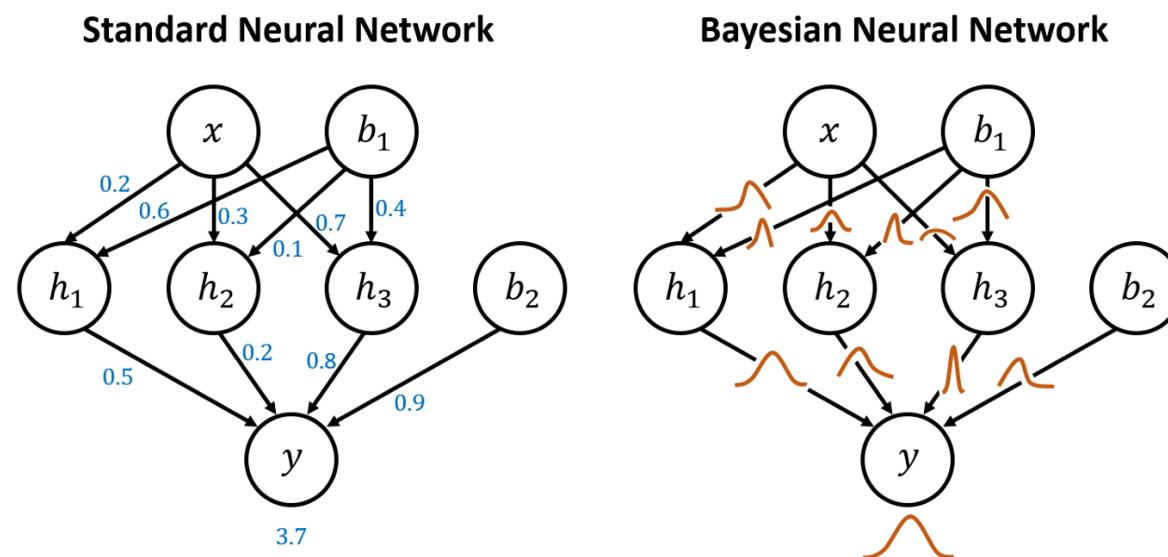
- **Bayesian** networks account for uncertainty in the network's parameters θ



<https://towardsdatascience.com/why-you-should-use-bayesian-neural-network-aaf76732c150>

Bayesian Normalising Flows

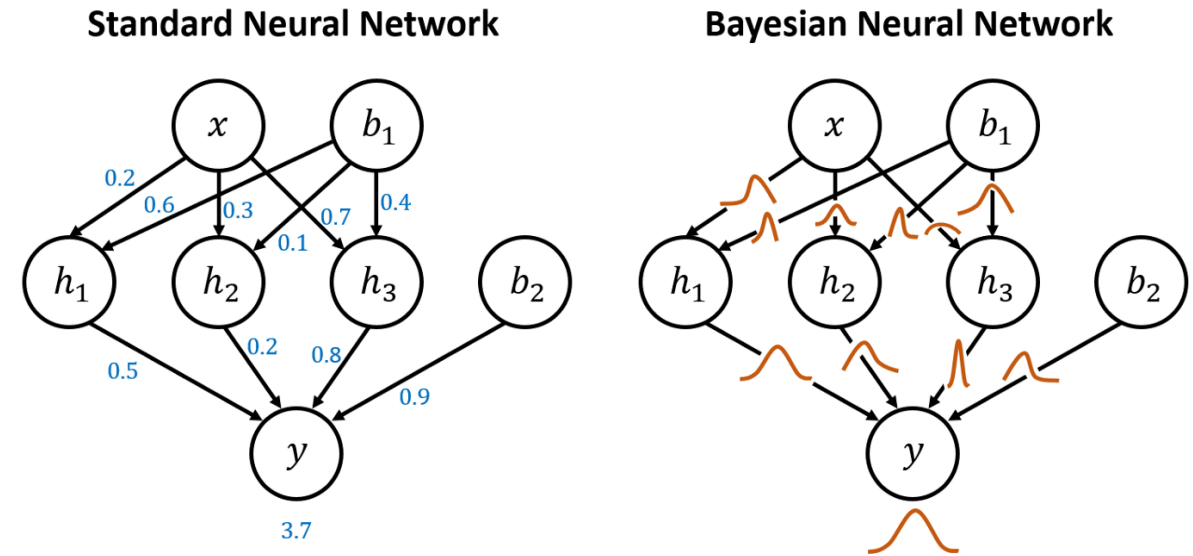
- **Bayesian** networks account for uncertainty in the network's parameters θ
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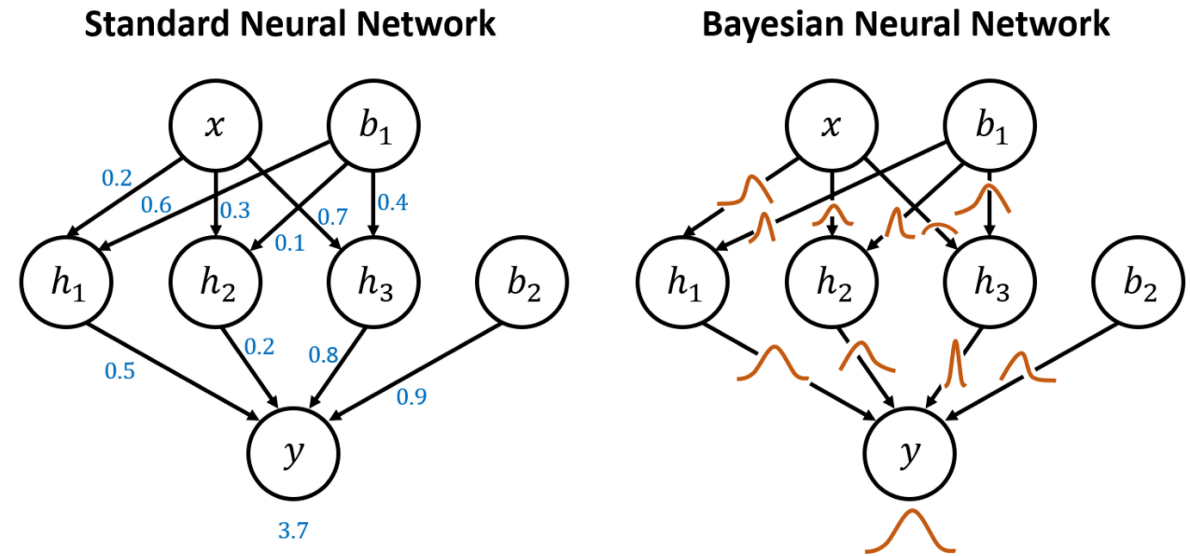
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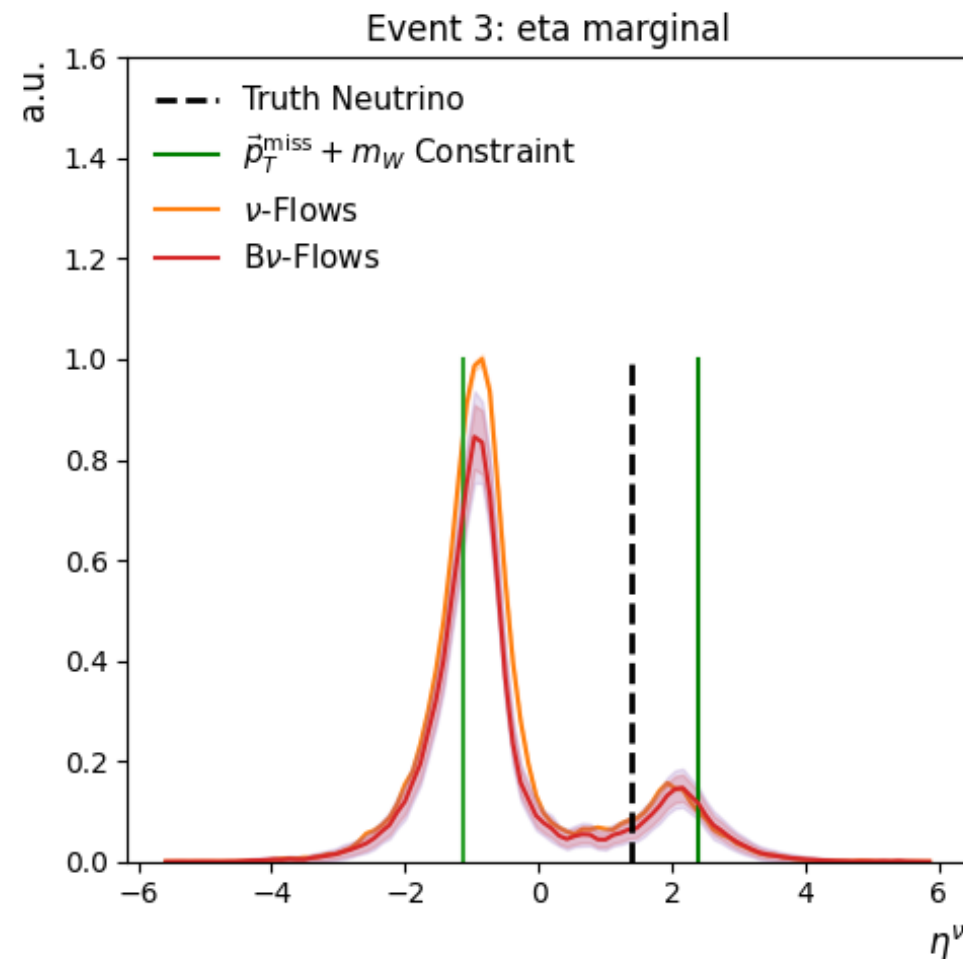


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$$Loss(y, x) = -\log \left(p_z(f_\theta(x|y)) \right) - \log |\det(J(x|y))| + \text{KL}(q_\phi(\theta) | p(\theta))$$

Bayesian Flow Inference

- Allows us to sample under the base distribution **AND** under the network parameters
- Gives variance of the network's predictions
- Uncertainty from missing data
- Can signify the stability of the flow

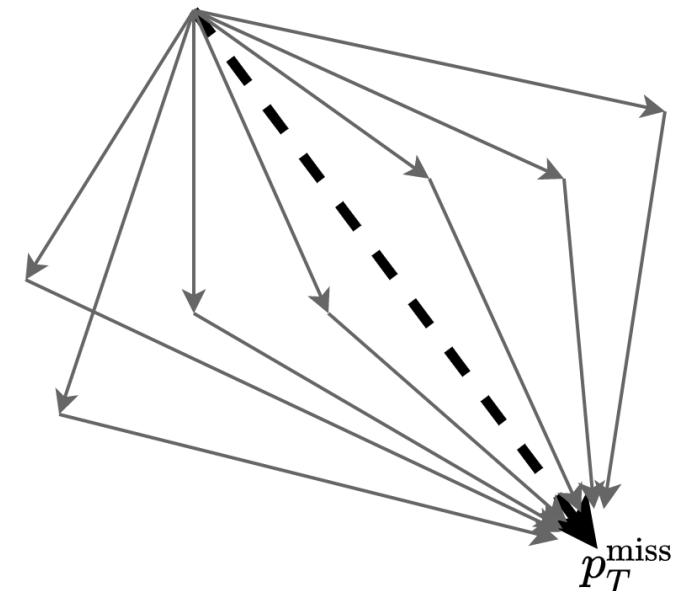


Conclusions

- Demonstrated an approach of using normalizing flow for neutrino momentum regression
- Reconstruction with the flow yields better distributions for p_z^ν , m_{lv} , and m_{blv}
- Demonstrated benefits in example downstream task of jet association
- ArXiv pre-print available:
 - <https://arxiv.org/abs/2207.00664v2>

Next steps

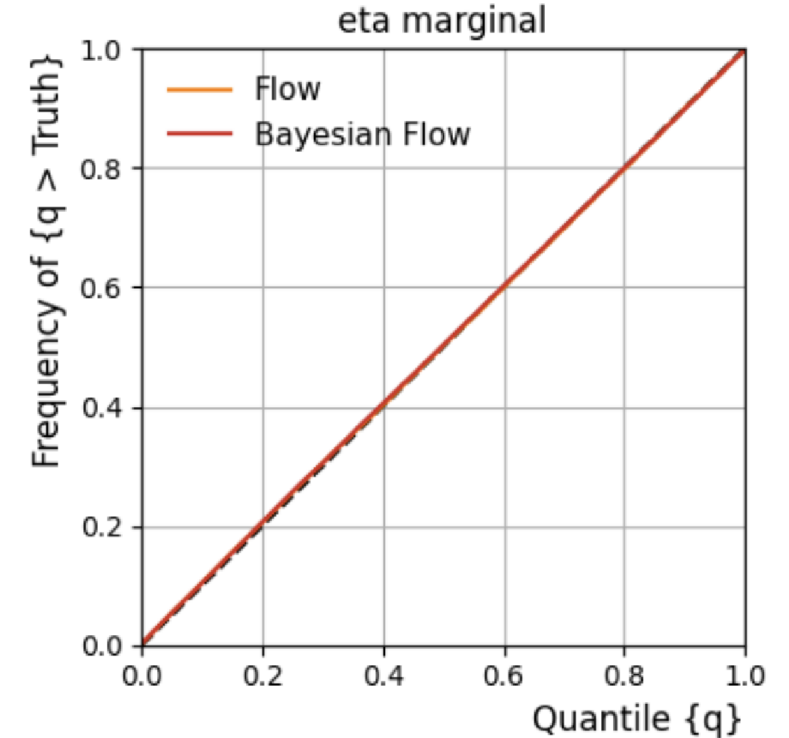
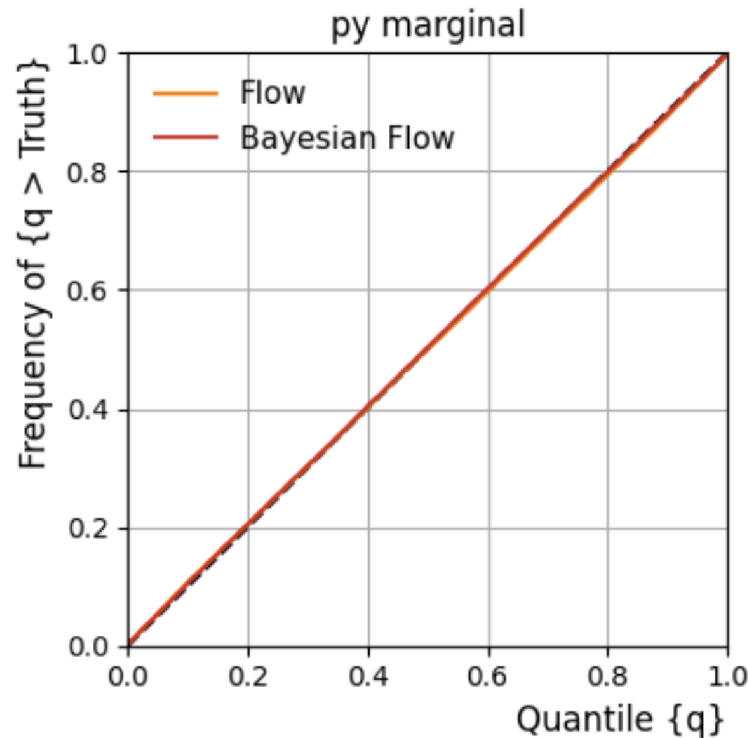
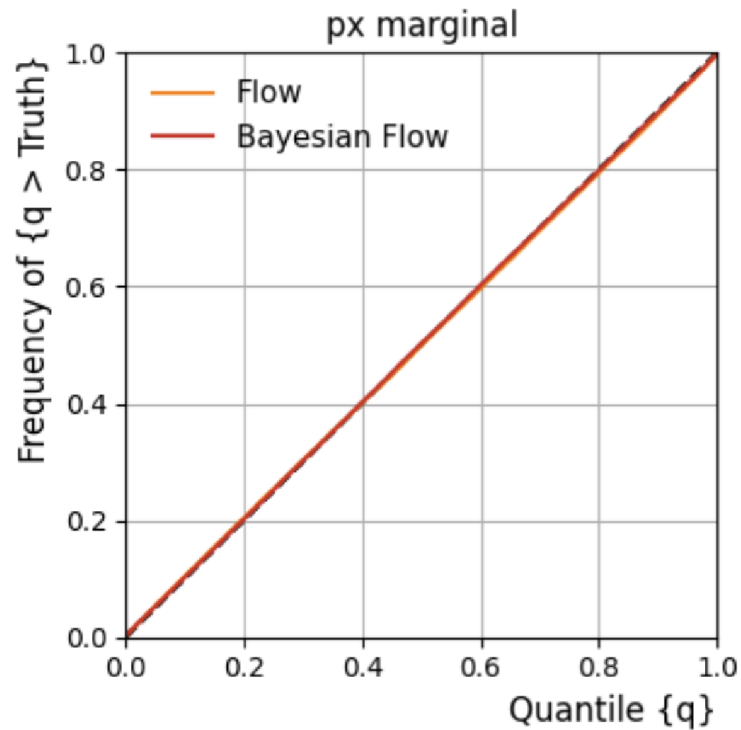
- Move to two neutrino case
- Use the flow / Bayesian flow as an event filter



Thank You

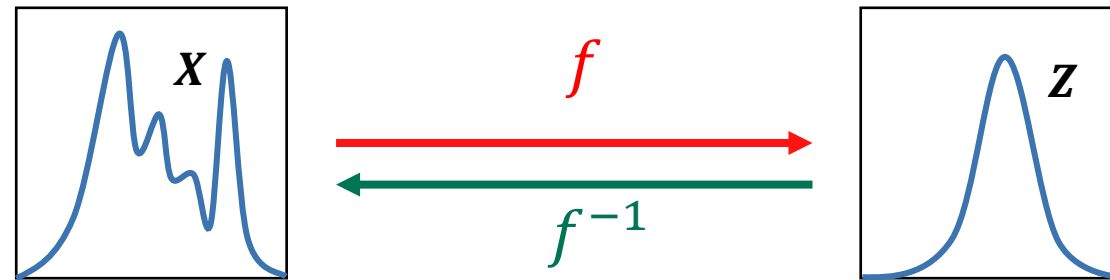
Interpretable Uncertainty

- The distribution of the flow does seem to correspond to real world accuracy!
- **Observed Accuracy** verses **Predicted Confidence**



Normalizing Flows

- A normalising flow is a transformation that typically maps a **complex distribution** $p_X(x)$ into a **simple distribution** $p_Z(z)$
 - $Z = f(X)$ with an **invertible** and **differentiable** $f(x)$



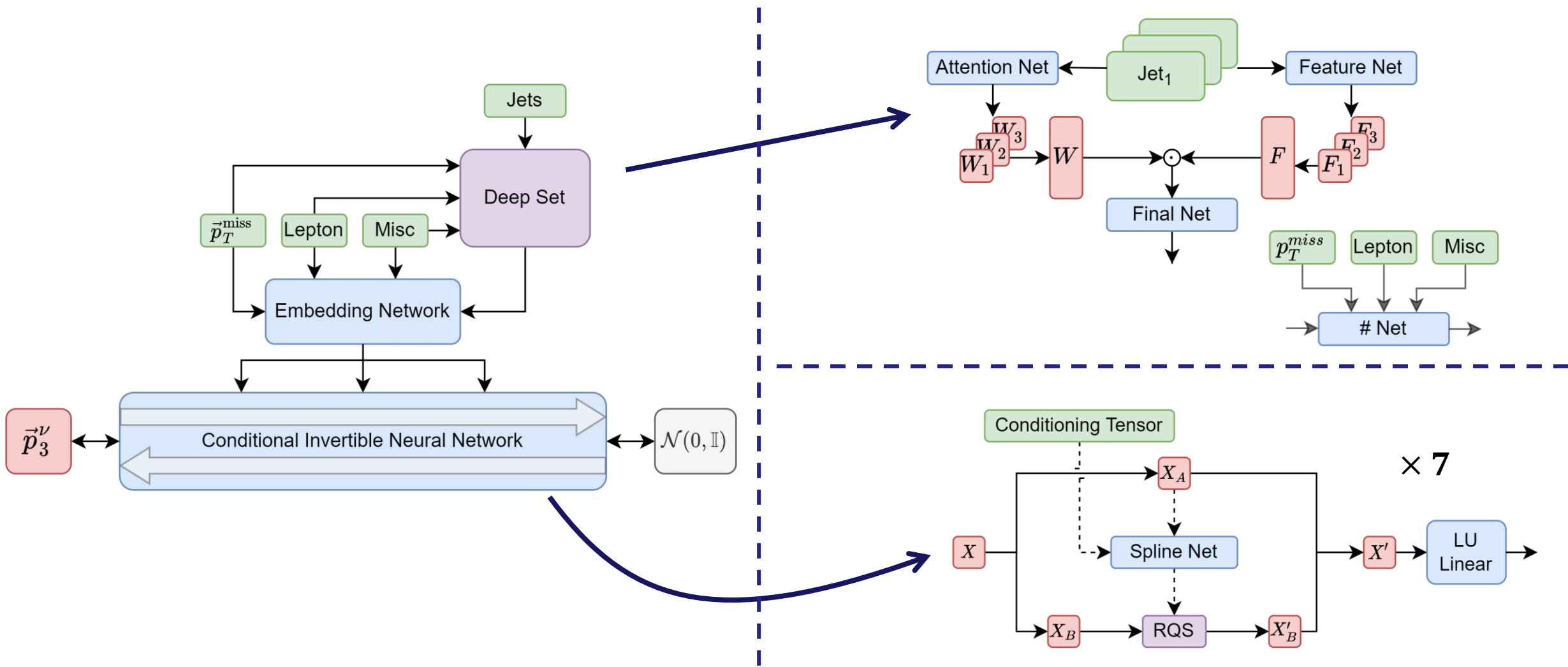
“diffeomorphism”

- Taking $p_X(x)$ to be the complex distribution over **our data**
 - Can perform exact density estimation: $p_X(x) = p_Z(f(x))|\det(J(x))|$
 - Can generate new data by sampling p_X : Sample $p_Z(\cdot)$, compute $f^{-1}(z)$
- In practice we use an **invertible neural network (INN)** to parameterise f_θ
- Usually train with INNs for generation using **maximum likelihood objective** for observed data:

INN layers need to be invertible and have a Jacobian that is easy to calculate

$$Loss(x) = -\log(p_X(x)) = -\log(p_Z(f_\theta(x))) - \log(|\det(J(x))|)$$

ν -Flow Structure



Network Hyperparameters

DeepSet: Feature Network

- 5(11)->Linear->LeakyReLU->LayerNorm->64
- 64->Linear->LeakyReLU->LayerNorm->64
- 64->Linear->8

DeepSet: Attention Network

- 5(11)->Linear->LeakyReLU->LayerNorm->32
- 32->Linear->LeakyReLU->LayerNorm->32
- 32->Linear->1

DeepSet: Final Network

- 8(11)->Linear->LeakyReLU->LayerNorm->64
- 64->Linear->LeakyReLU->LayerNorm->64
- 64->Linear->8

Each row is a layer showing:
Inputs(conditional inputs) -> operations -> outputs(residual)

Embedding Network

- 19->Linear->LeakyReLU->LayerNorm->64
- 64->Linear->LeakyReLU->LayerNorm->64(add)
- 64->Linear->32

Spline Network

- 2(32)->Linear->LeakyReLU->LayerNorm->64
- 64(32)->Linear->LeakyReLU->LayerNorm->64(add)
- 64->Linear->LeakyReLU->LayerNorm->64(add)
- 64->Linear->29

Network Training

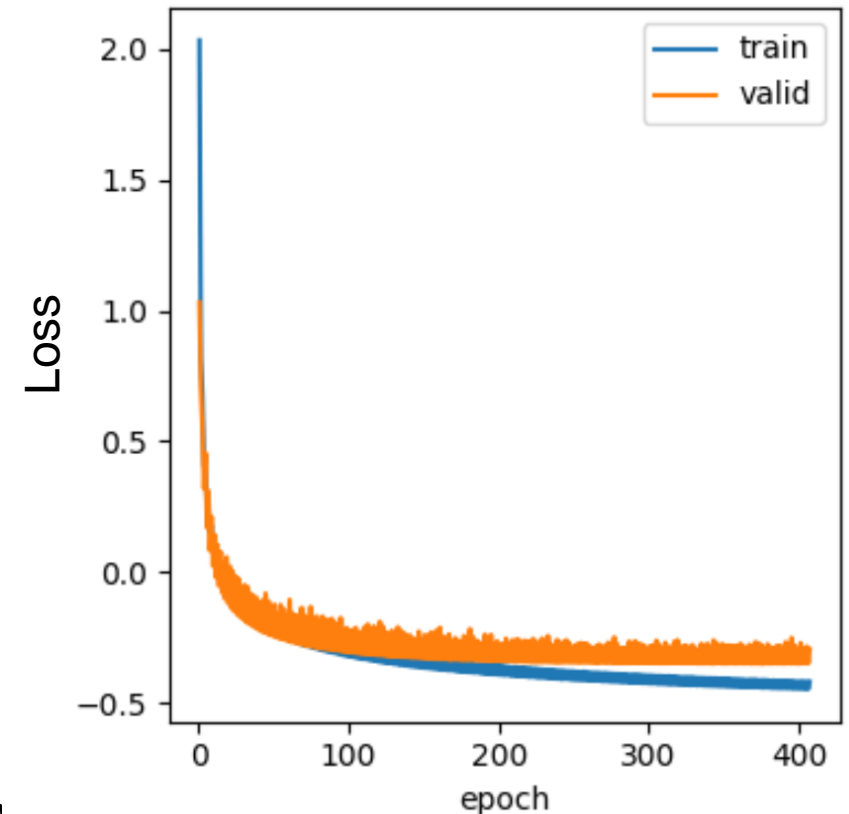
Training was done using the **negative log likelihood** as the loss function using the **Adam optimizer** with **early stopping** performed on a **10% holdout** validation set.

- Training set size: 528921
- Validation set size: 58768

Other training parameters:

- Batch size = 256
- Gradient norm clipping = 5
- Early stopping patience = 30

The learning rate followed a **cyclic asymmetrical cosine schedule** with a period of two epochs. Each cycle the learning rate would be ramped up from 0 to $5e-4$ and then back down to 0. The fraction of the cycle used for warmup(cooldown) was set to 0.3(0.7).



χ^2 : Masses

- Looking at the invariant mass of $bl\nu$ using the b selected by the χ^2 fit
 - Idealised** refers to the truth neutrino and the correct b_{lep}
 - Shaded regions are subset of events where χ^2 yielded correct b_{lep}

