



Status of the Beam Gas Vertex (BGV) Monitor

WP 13.7

Bernadette Kolbinger on behalf of the BGV team (CERN SY-BI-XEI)

Acknowledgements:

BGV team: H. Guerin, J. Storey

With input from: G. Bregglozzi, A. Galloro, D. Hynds, R. Kersevan, R. De Maria, J. Oliveira, R. Plackett, D. Prelicpean, T. Ramos Garcia, B. Salvant, G. Schneider, T. Lefevre, B. Salvant, A. Salzburger, H. Sandberg, R. Veness

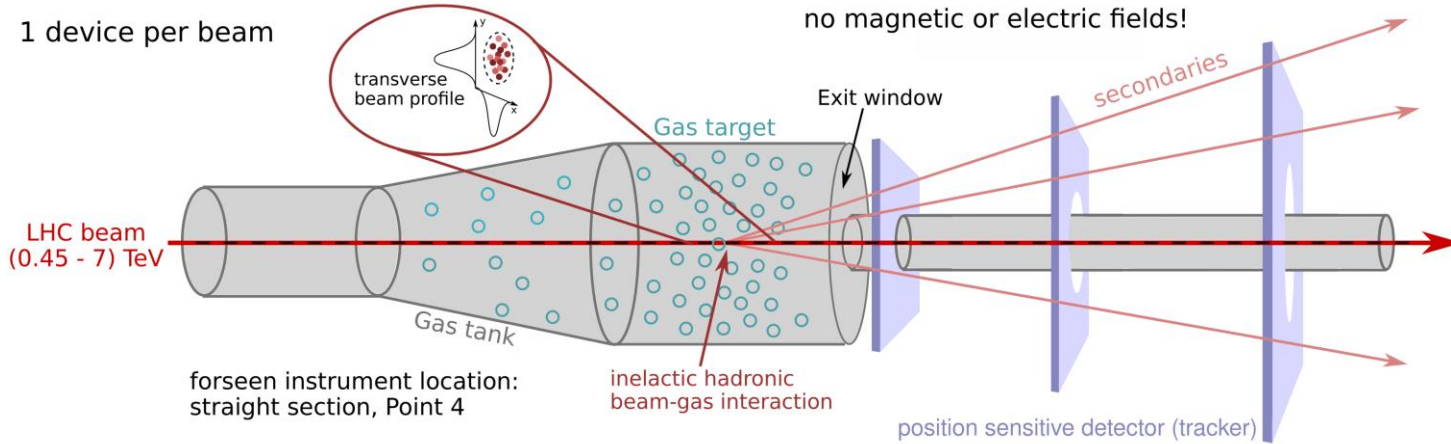


Outline

- ◆ **Introduction**
- ◆ **Simulations**
- ◆ **Status of the new design**
 - ◆ Gas target
 - ◆ Tracking detector
 - ◆ Integration
- ◆ **Expected performance**
- ◆ **Summary & outlook**

Introduction - principle

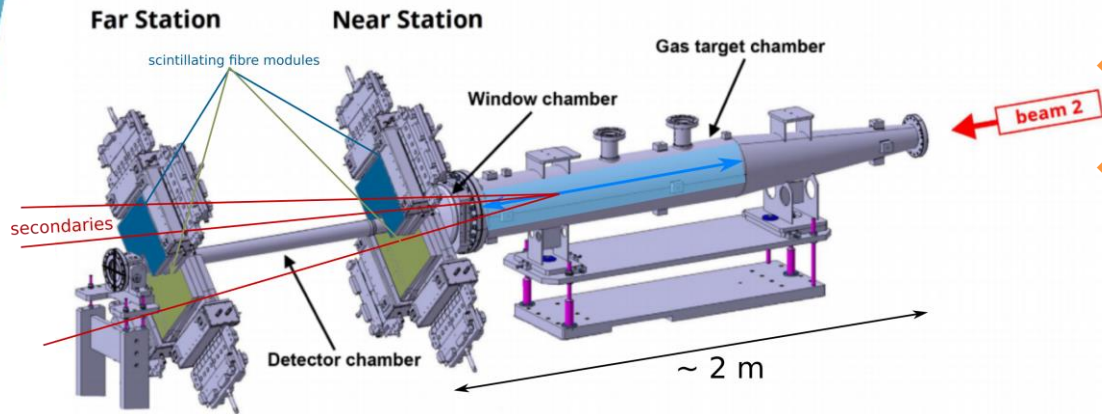
- ◆ **Noninvasive transverse beam profile monitor** based on the reconstruction of vertices of inelastic hadronic beam-gas interactions - **BGV (Beam Gas Vertex)** monitor.
- ◆ Provide **continuous emittance and beam profile measurement** throughout the LHC accelerator cycle (450 GeV to 7 TeV).



- ◆ Consists of: a gas target, a forward tracking detector and computing resources dedicated to event reconstruction.

History – BGV demonstrator

Installed, commissioned and operated in LHC Run 2 ([PhysRevAB](#))



- ◆ Tracking detector based on scintillating fibre stations (LHCb SciFi).
- ◆ Neon gas target of $\sim 1.8\text{m}$ length and 10^{-7} mbar (~ 200 kHz interaction rate).

- ◆ Successful beam size measurements ($200\ \mu\text{m}$ to $800\ \mu\text{m}$), throughout the LHC cycle with required precision. Bunch-by-bunch measurements.
- ◆ Coherent with other beam size measuring devices.
- ◆ Reconstruction of beam-gas interaction vertices not possible \square no beam profile measurement.

Future BGV

- ◆ Beam size review after Run 2 Oct. 2019:

"None of the present instruments provide a bunch-by-bunch profile measurement for the physics beam along the whole cycle. An additional non-invasive measurement device complementary to the WS and BSRT devices is therefore required."

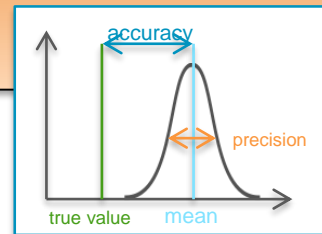
Case for a new device is solid.

- ◆ Work on **new design** - **conceptual design report** will be reviewed in **October 2022**.

Requirements for the future HL-LHC transverse beam profile monitor:

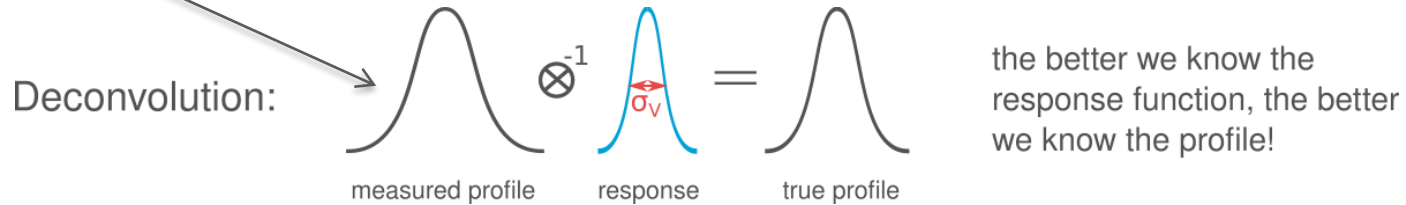
- ◆ Emittance measurement with **accuracy** $\leq 10\%$ (beam size $\leq 5\%$).
- ◆ **Bunch-by-bunch** measurements of **beam size** with $\sim 1\%$ **precision** after ~ 1 min of accumulating data.
- ◆ Provide **transverse profile** measurements.

add. design goals: aim for simplicity, maintainable by small team, minimise R&D: robust technologies.



BGV performance - what's important?

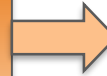
- Method: deduce beam profile from spatial distribution of reconstructed vertices.



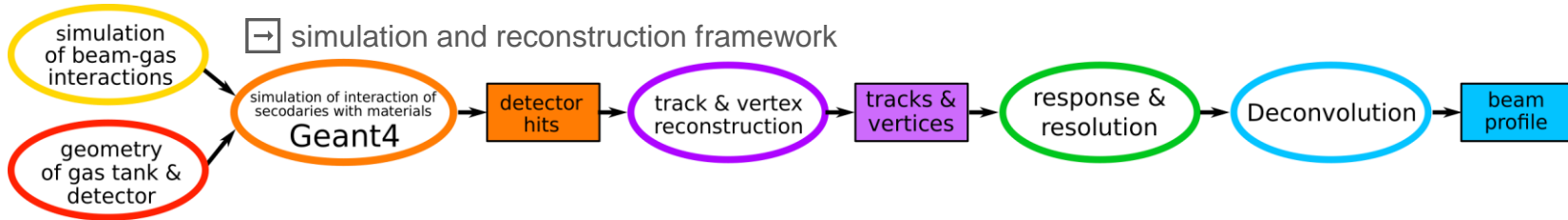
- Key performance measure = response function.** Not easy to determine with high precision - keep its **width (= vertex resolution σ_v)** small!
- What σ_v do we need, to achieve a beam size measurement with accuracy of $\leq 5\%$?**
 - \Rightarrow **Depends on beam size!**
 - Minimum beam size at BGV locations is **235 μm (7 TeV)**. Assume knowledge of σ_v with 10 % accuracy \Rightarrow **$\sigma_v \lesssim 166 \mu\text{m}$** (see [calculation](#)).

Performance study & optimisation

- ◆ What impacts the vertex resolution σ_v ?
- ◆ What are the requirements for BGV gas target and tracker, to:
 - ◆ fulfilling performance specifications,
 - ◆ within the boundary conditions of: feasibility of integrating it into the LHC?

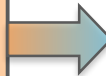


answer with complete simulation study!



Test important **design parameters and their impact on performance:**

- ◆ Detector dimensions, material budget, position resolution etc.
- ◆ Gas target extension, pressure, gas species etc.

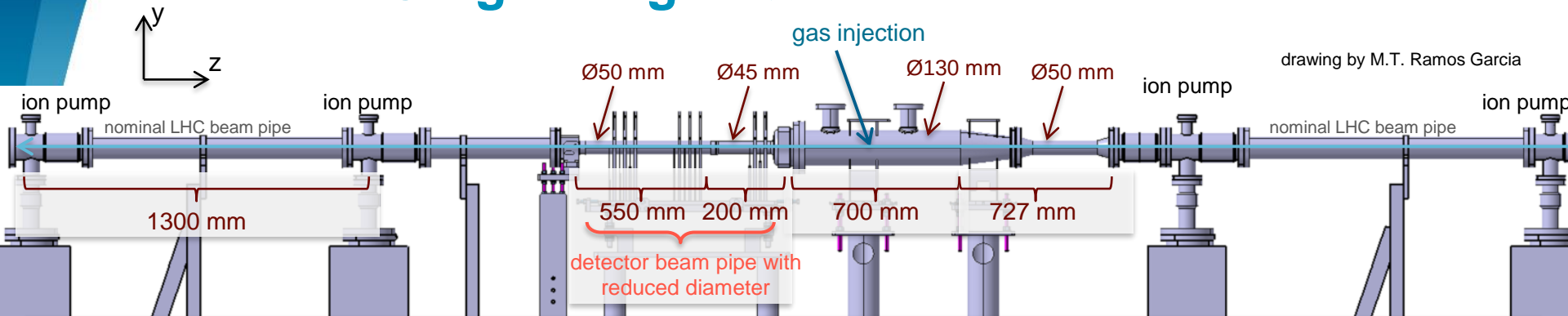


Conclusions

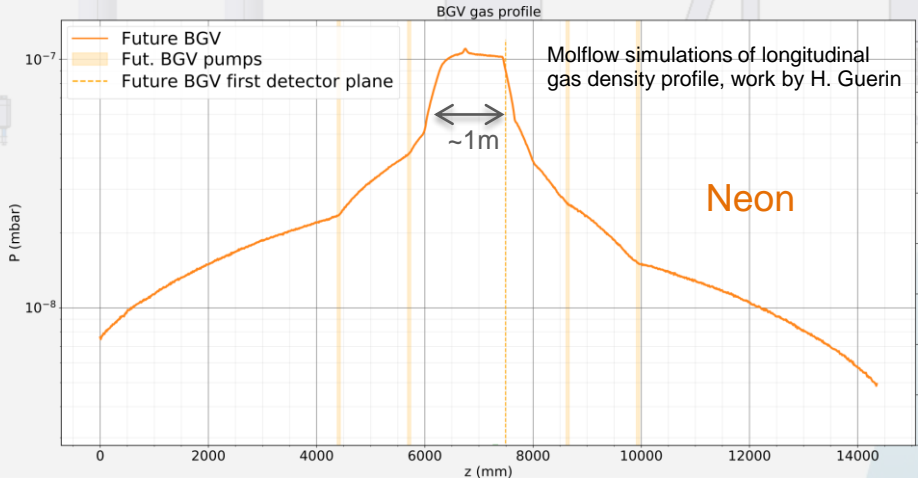
- ◆ Results point towards possibility of **compact tracker with a high spatial resolution.**
- ◆ **Extended gas target** not a show stopper - ~1 m neon, with ~ 10^{-7} mbar.

see: [BGV talk at 2021 Hilumi Collaboration Meeting](#), [IBIC paper 2021](#), or back-up slides.

BGV gas target & chamber



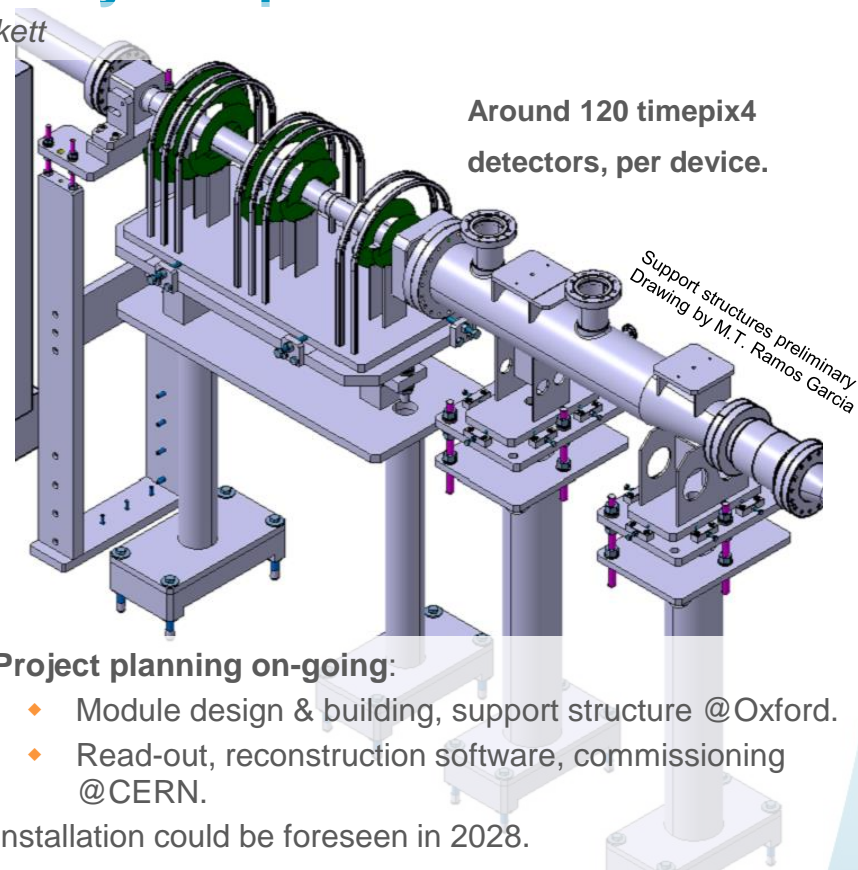
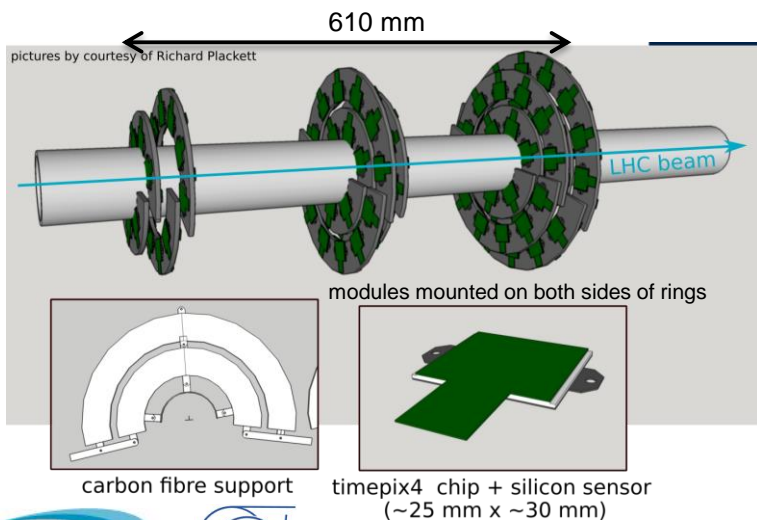
- ◆ Redesign of the demonstrator target - more compact.
- ◆ **Neon gas injected on the tank via a capillary.**
- ◆ **Distributed gas target**, with density plateau $\Delta z \sim 1\text{m}$.
- ◆ 10^{-7} mbar at plateau $\Rightarrow \sim 200$ Hz inelastic collisions per bunch.
- ◆ **Gas tank design**: taking impedance, performance needs and mechanical stability into consideration.
- ◆ **Exit window** (0.9 mm to ~ 2 mm), aluminium alloy.
- ◆ **Potential future upgrade**: gas curtain target.



A BGV tracker based on silicon hybrid pixel detectors

Collaboration with Oxford University: D. Hynds and R. Plackett

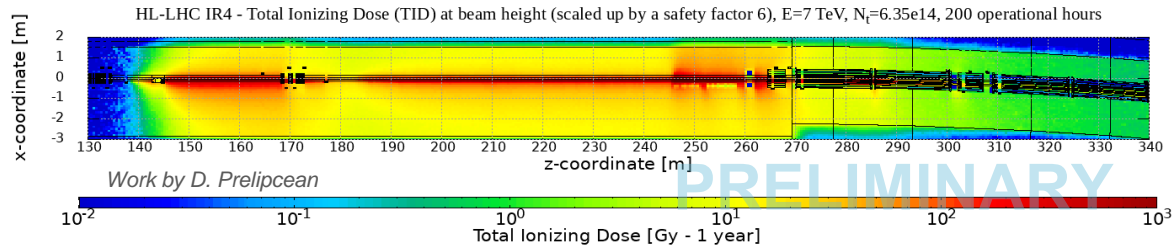
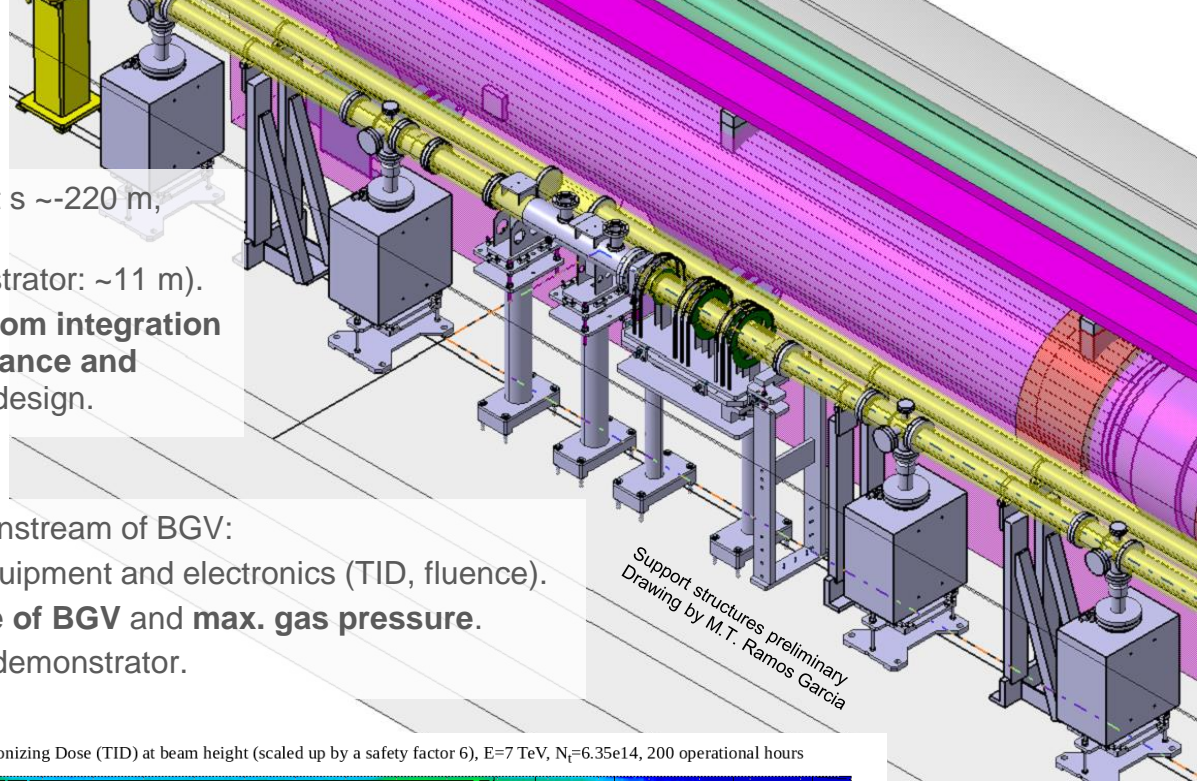
- ◆ Design based on the **ATLAS ITk HiLumi upgrade**.
- ◆ **Timepix technology**: robust and widely used detectors. XP within **Beam Instrumentation** group.
- ◆ **DAQ**:
 - ◆ Read-out system based on BGI read-out.
 - ◆ CPU farm in service tunnel for event reconstruction.



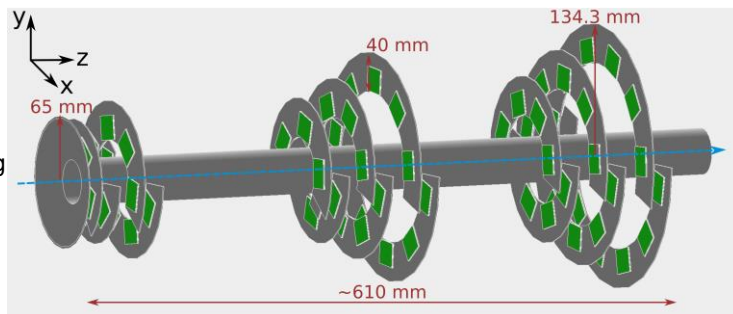
- ◆ **Project planning on-going**:
 - ◆ Module design & building, support structure @Oxford.
 - ◆ Read-out, reconstruction software, commissioning @CERN.
- ◆ Installation could be foreseen in 2028.

Integration aspects

- ◆ **Location: LSS of Point4**, beam 2 device at $s \sim 220$ m, beam 1 device at $s \sim 142$ m.
 - ◆ Total instrument length ~ 6 m (demonstrator: ~ 11 m).
- ◆ Integration study on-going - taking **inputs from integration (WP15), ABP, survey & alignment, impedance and vacuum** teams into account for instrument design.
- ◆ FLUKA study of **radiation environment** downstream of BGV:
- ◆ Impact on magnets (heat loads) and other equipment and electronics (TID, fluence).
- ◆ Caused radiation impacts **total max. up-time of BGV** and **max. gas pressure**.
- ◆ Integrated pressure $\sim 25\%$ less compared to demonstrator.



Expected performance – bunch width precision

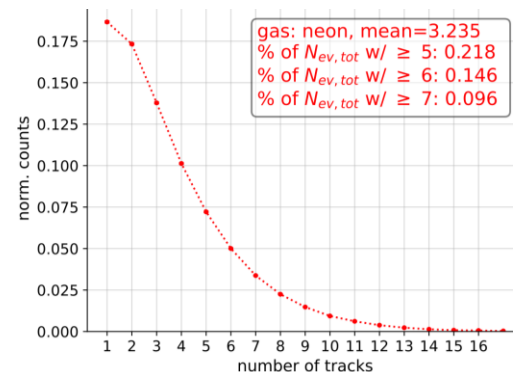
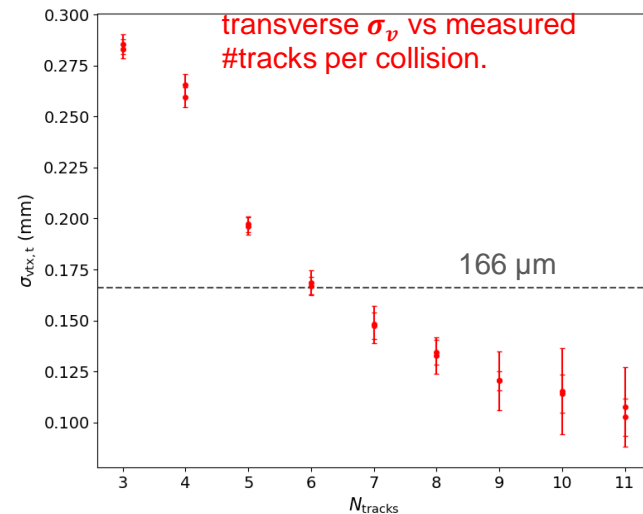


simulation set-up including all important materials.

- ◆ 7 TeV protons (most stringent case).
- ◆ Accept events with $N_{\text{tracks}} \geq 6$ \Rightarrow 14.6 % of total number of collisions.
 - ◆ Cut on N_{tracks} can be relaxed for larger beam sizes.

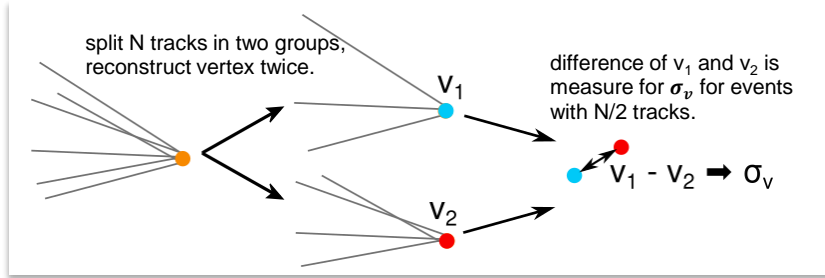
Precision on bunch width:

- ◆ Reminder: bunch-by-bunch measurements with $\sim 1\%$ precision in ~ 1 min.
- ◆ How many interactions in 1 min with $N_{\text{tracks}} \geq 6$?
- ◆ Assume a gas pressure of 10^{-7} mbar.
- ◆ 1740 recorded coll. in 1 min \Rightarrow bunch width relative precision 1.7 %.



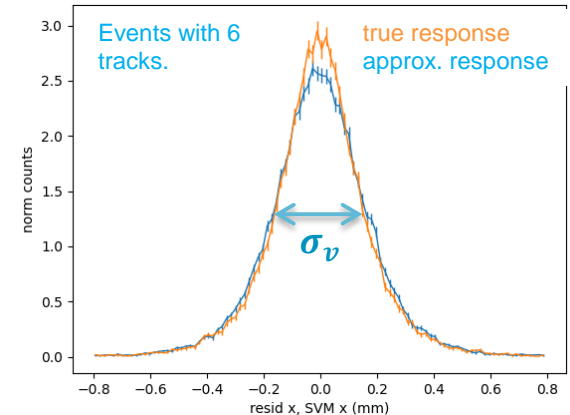
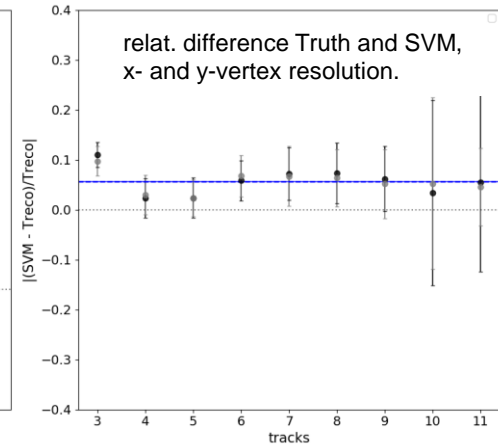
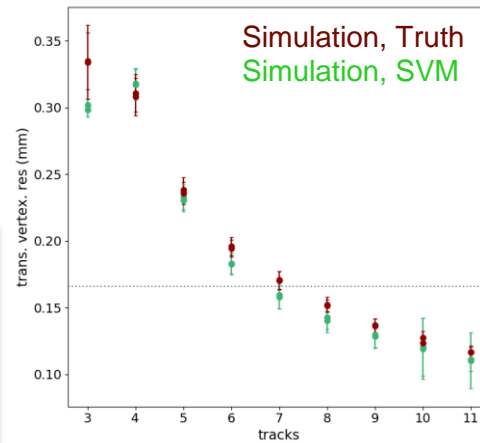
Vertex response and resolution for a profile measurement

- During the measurements - need to determine response and vertex resolution.
- Common method of LHC experiments: **split vertex method (SVM)**.



- Applied to simulation data, SVM shows agreement of $\sim 6\%$ with the true vertex resolution (determined by comparison of reconstructed vertex to generator level).

- Method to determine vertex response during BGV measurements, no need to rely on simulations or additional measurement with known source!



Summary & outlook

- ◆ The BGV is currently being **optimised for the HL-LHC** – work on conceptual design report.
- ◆ **Design is based on extensive performance study** - based on established tools, support from experts.
- ◆ **Gas target baseline: extended neon gas target** with $\sim 1\text{m}$ density plateau of 10^{-7} mbar, via injection of neon into gas chamber.
- ◆ **Compact tracker** based on silicon pixel detectors in collaboration with University of Oxford.
- ◆ **Integration constraints** are taken into account, no showstoppers identified.
- ◆ **Performance study shows promising results in accord with specifications** - bunch width precision 1.7 % in 1 min.
- ◆ **Method of measuring vertex response and resolution** for deconvolution of true profile.
- ◆ On-going: deconvolution, detector alignment, pattern recognition.
- ◆ **Next milestone** - Review of BGV (& BGI) proposal on October 19th 2022.

Thank you for your attention!

BACK UP

Inelastic collisions

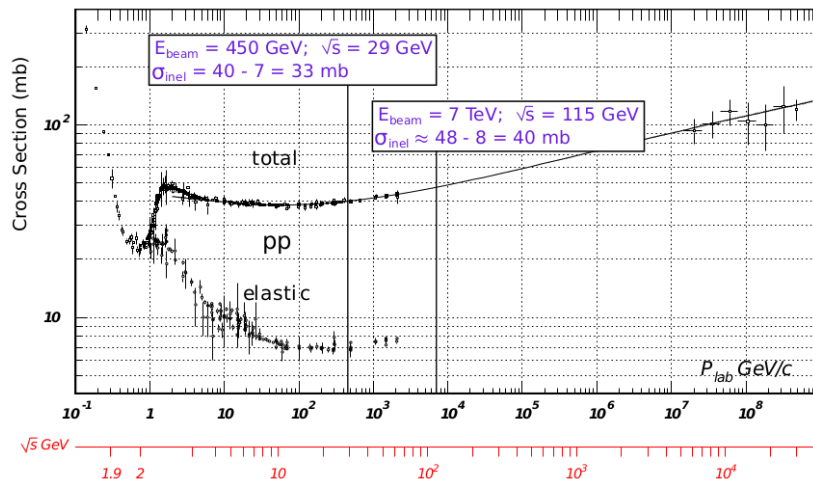
- Inelastic proton-nucleus cross-section

$$\sigma_{pA}(E) \approx \sigma_{pp}(E) \cdot A^{2/3}$$

A – atomic mass

In the case of ^{20}Ne :

- $\sigma_{pNe}(450 \text{ GeV}) = 243 \text{ mb}$
- $\sigma_{pNe}(7 \text{ TeV}) = 295 \text{ mb}$



Data from PDG, plot taken from Plamen Hopchev's presentation (13/11/2013)

- ◆ Rate of inelastic collisions per bunch:

$$R_{\text{inel}} = f_{\text{rev}} N \sigma_{\text{p-gas}}^{\text{inel}} \rho_{\text{gas}} \Delta z$$

- ◆ with the revolution frequency (11245 Hz), the number of protons per bunch N (2.2×10^{11}), the gas density ρ and the gas width Δz .

Beam profile and vertex resolution

- ▶ **Assume:** bunches with Gaussian x- and y- distribution. Known vertex resolution i.e. Gaussian distribution with σ_v .
- ▶ The measured beam distribution is a **convolution** of the "true" beam distribution and the vertex response.
- ▶ De-convolution of the measured beam distribution (Gaussian with σ_{raw}) and **extract the true beam distribution** (Gaussian with σ_{beam}).

- ▶ σ s of two convoluted Gaussians are related via: $\sigma_{\text{raw}}^2 = \sigma_{\text{beam}}^2 + \sigma_v^2 \rightarrow \sigma_{\text{beam}} = \sqrt{\sigma_{\text{raw}}^2 - \sigma_v^2}$.

- ▶ Using **error propagation**, arrive at: $\sigma_{\text{beam}}^2 \delta \sigma_{\text{beam}}^2 = \sigma_{\text{raw}}^2 \delta \sigma_{\text{raw}}^2 + \sigma_v^2 \delta \sigma_v^2$.

- ▶ Assuming a **negligible measurement uncertainty** i.e. $\delta \sigma_{\text{raw}} \rightarrow 0$.

- ▶ Arrive at:
$$\frac{\delta \sigma_{\text{beam}}}{\sigma_{\text{beam}}} = \frac{\sigma_v^2}{\sigma_{\text{beam}}^2} \frac{\delta \sigma_v}{\sigma_v}$$

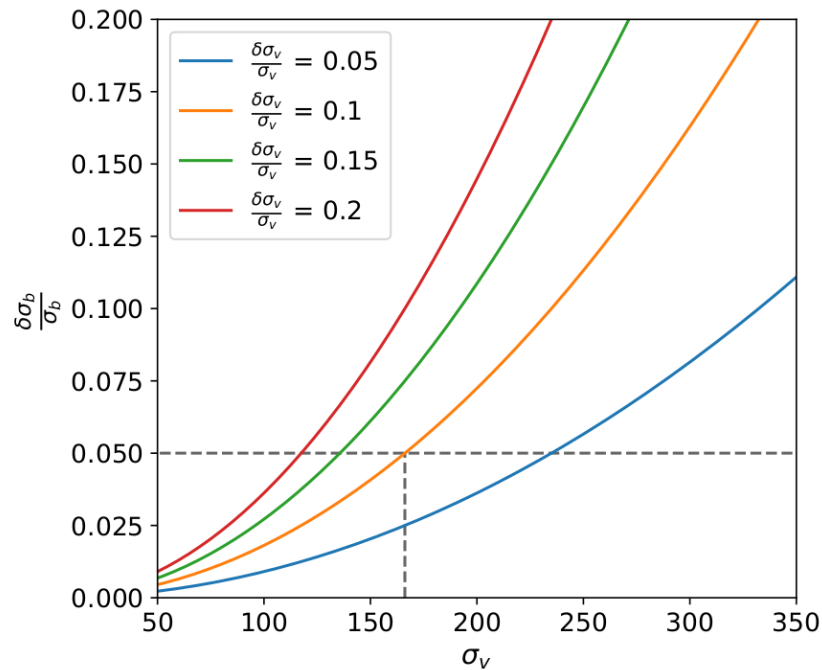
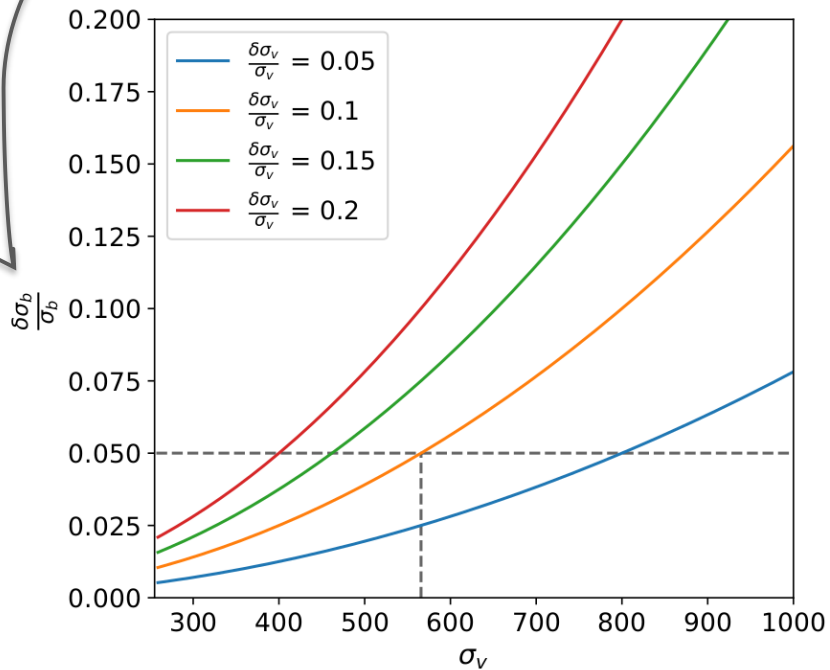
- ▶ **Estimate** required vertex resolution:
$$\frac{\delta \sigma_{\text{beam}}}{\sigma_{\text{beam}}} = \frac{\sigma_v^2}{\sigma_{\text{beam}}^2} \frac{\delta \sigma_v}{\sigma_v}$$

- ▶ → **Small σ_v relative to beam size σ_{beam} .**

- ▶ → **Know σ_v precisely.**

- ▶ For $\frac{\delta \sigma_{\text{beam}}}{\sigma_{\text{beam}}} \lesssim 0.05$ and $\frac{\delta \sigma_v}{\sigma_v} \lesssim 0.1 \rightarrow$ for $\sigma_{\text{beam}} = 200 \mu\text{m}$, get: $\sigma_v \lesssim 140 \mu\text{m}$

$$\frac{\delta\sigma_{\text{beam}}}{\sigma_{\text{beam}}} = \frac{\sigma_v^2}{\sigma_{\text{beam}}^2} \frac{\delta\sigma_v}{\sigma_v}$$



Emittance growth (negligible)

- ◆ Consider beam particles scattered elastically within BGV gas target.
- ◆ Emittance growth budget should be below 10 to 15 %.
- ◆ Emittance growth per turn of gas target with length L [Ref]:

$$\Delta\varepsilon = \frac{1}{2} q_p^2 \left(\frac{13.6 \text{ MeV}}{p\beta_r} \right)^2 \overline{\beta_x} \frac{L}{L_{rad}}$$

- ◆ q_p is the charge of the projectile, p the momentum, β_r the relat. velocity, $\overline{\beta_x}$ the average transverse beta-function along the gas targets length L. L_{rad} is the radiation length of neon.

Table 2: Elastic Scattering Emittance Growth.

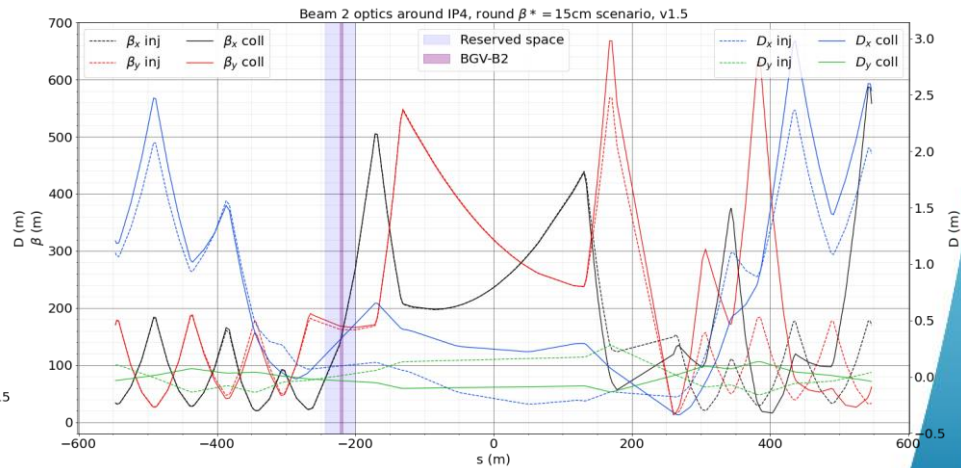
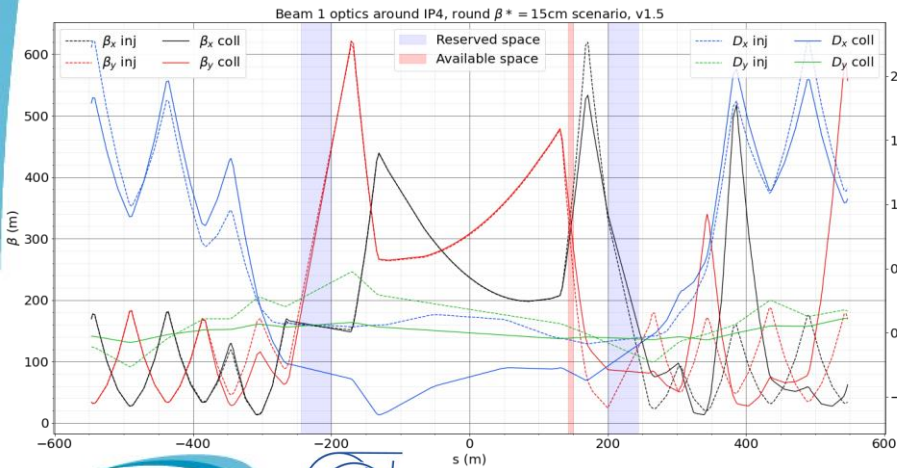
Beam and Energy	$\Delta\varepsilon$ (π rad m)	$\Delta\varepsilon_n$ ($\mu\text{m h}^{-1}$)
Beam 1, 450 MeV	1.9×10^{-19}	3.2×10^{-3}
Beam 1, 7000 MeV	7.7×10^{-22}	2.0×10^{-4}
Beam 2, 450 MeV	9.3×10^{-20}	1.6×10^{-3}
Beam 2, 7000 MeV	3.8×10^{-22}	1.0×10^{-4}

from latest IBIC paper by H. Guerin et al.

- ◆ For running the BGV 2h per fill: 0.16 % (beam 1) and 0.08 % (beam 2).

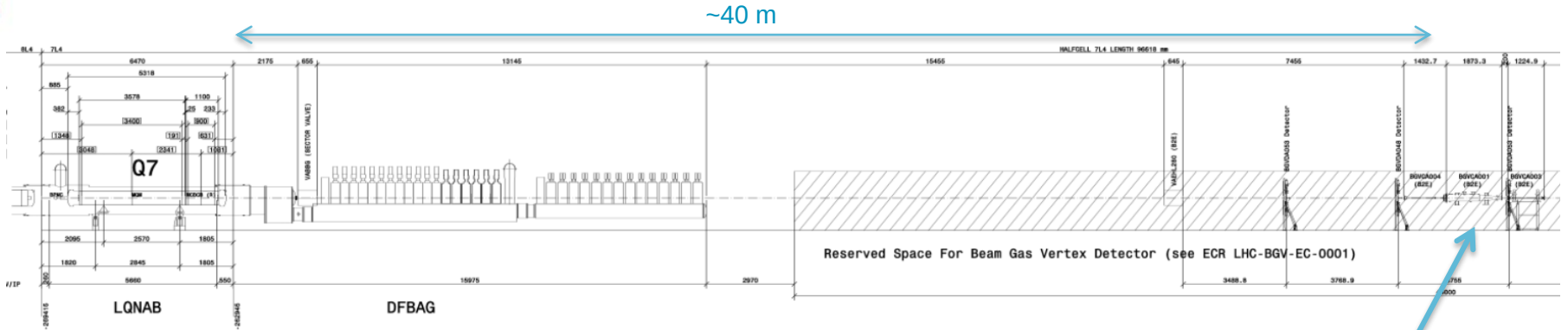
Location and space reservations

- Initial space reservation from [LHC-BGV-EC-0001](#)
- **B2-BGV** is foreseen to be installed where the demonstrator is on left of IP4, with space reservation **[-244, -200]m**
- ([9753.081, 9797.081]m DCUM) w.r.t IP4 centre
- The initially foreseen location for B1-BGV was symmetric to IP4 centre **[200, 244]m** but now shows too demanding beam optics for instrument vertex resolution.
- The new foreseen location is now **[141.052, 148.572]m** ([10138.133, 10145.653]m DCUM) w.r.t IP4 centre for **B1-BGV**.
- Possibly additional 1.2m on each side of this location, currently occupied by disconnected BQKH&V (confirmed by Thibaut).



BGV2 foreseen location

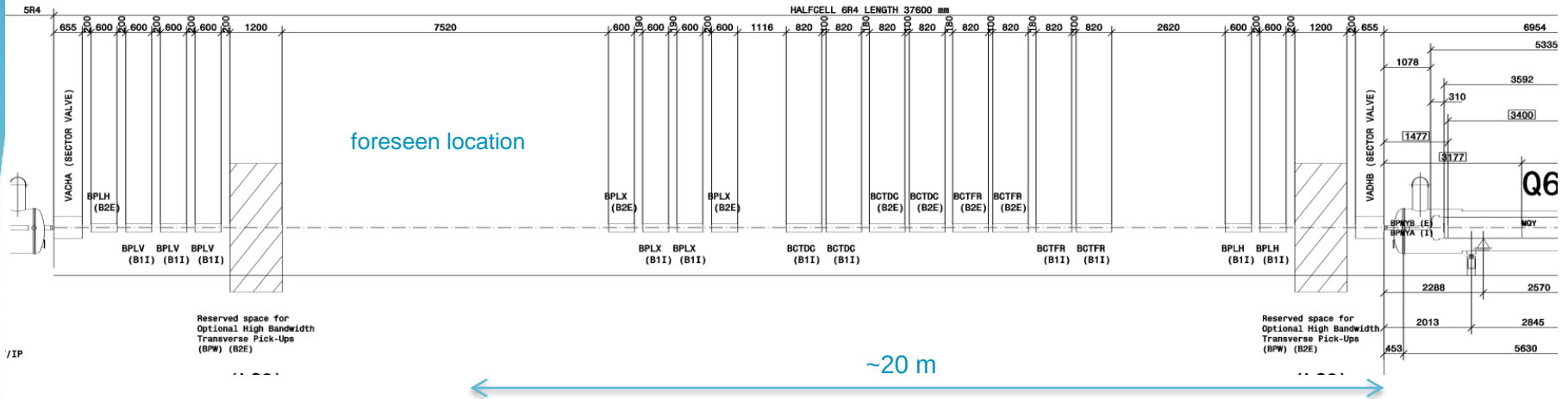
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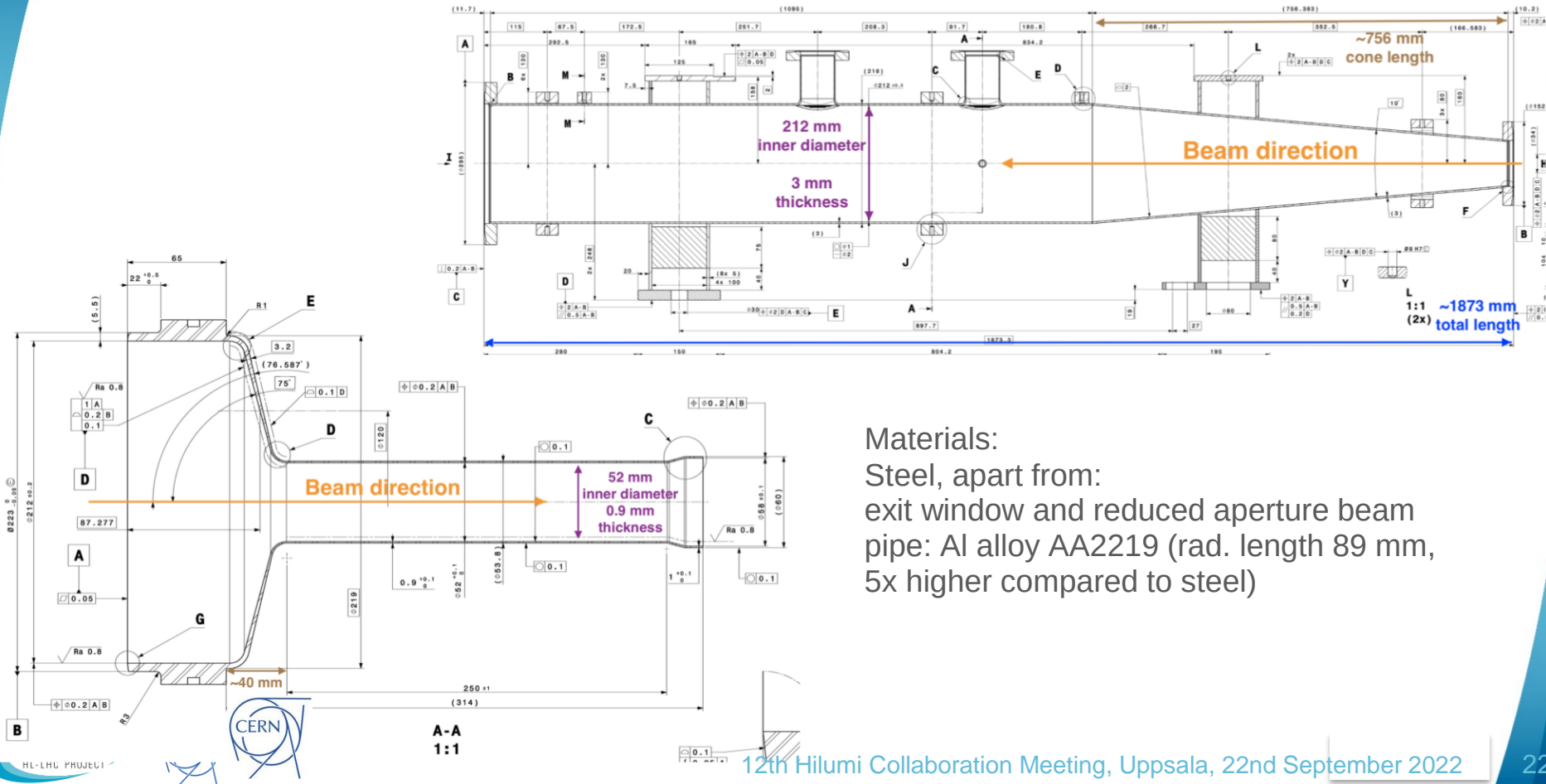
BGV demonstrator location

BGV1 foreseen location

<https://edms.cern.ch/document/1395360/0>



Demonstrator tank



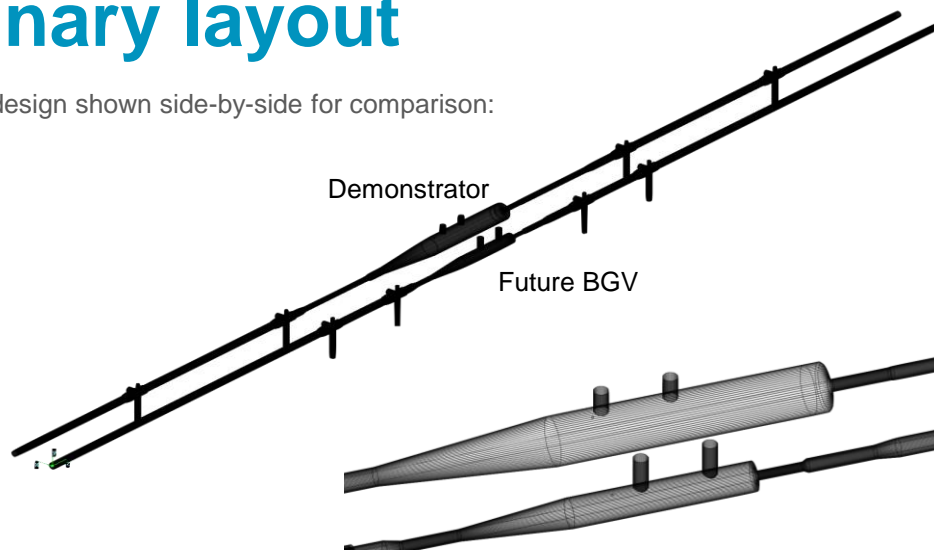
Materials:
Steel, apart from:
exit window and reduced aperture beam pipe: Al alloy AA2219 (rad. length 89 mm, 5x higher compared to steel)

Preliminary layout

The beam chamber layout has been modified compared to the demonstrator device:

- **Smaller aperture of the downstream small radius beam pipe** to maximise track acceptance
- **Smaller gas tank diameter** to reduce beam-coupling impedance
- **Shorter total length (upstream taper, distance between pumps)**, to fit into the new B1-BGV location and reduce the radiations due to the longitudinal gas density profile tails.

Old and new design shown side-by-side for comparison:

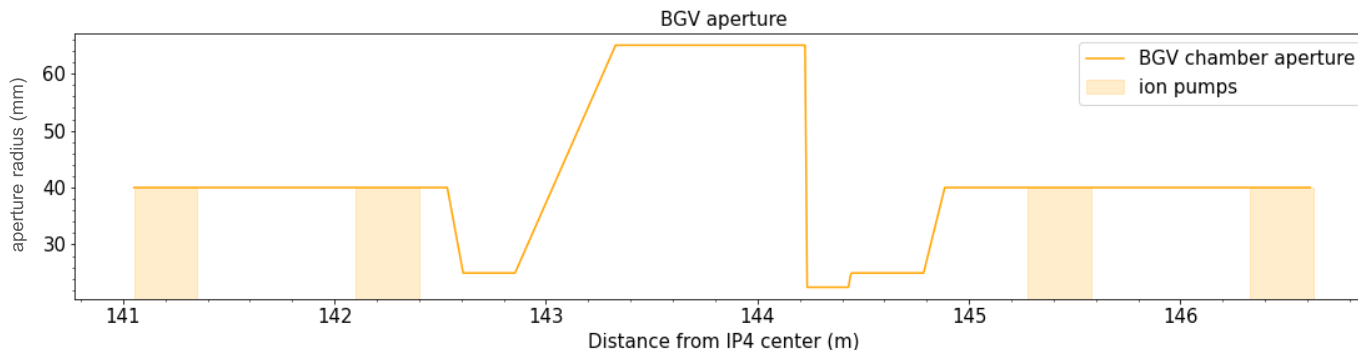


		Cone 1	Upstream chamber	Upstream taper	Tank cylinder	Exit window	Detectors beam pipe	Cone 2	Transition beam pipe	Cone 3
Demonstrator	ID (mm)		52		212		52		58	
	length (mm)	48	1108	815	1185	50	251	12	988	44
Future BGV	ID (mm)		50		130		45		50	
	length (mm)	50	250	477	700	11	200	12	350	100

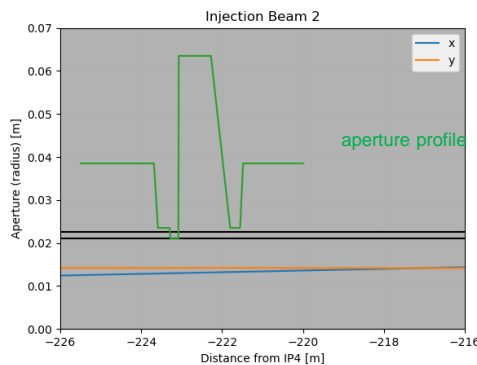
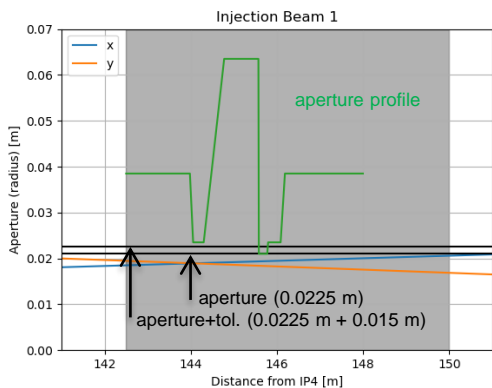
+ 500mm beam pipes at each pump connection + **750mm** between pumps for the future instrument (vs. 2000mm demonstrator) -> total length **~5.5m** (vs. ~10m total demonstrator length)

Aperture profile

- Preliminary aperture profile of B1-BGV (position can be shifted along z), total length ~6 m:



- Reduced-diameter beam pipe placement - as close to beta x/y crossing point as possible.



- Plots by Riccardo de Maria (BE-ABP-LNO).
- **Tolerance budget: 1.5 mm** (estimation from demonstrator page 6: [LHC-BGV-EC-0002](#)).
- Smallest aperture size: 22.5 mm (inner radius).
- Ok from ABP (if tol. can be guaranteed).
- See: [initial discussion](#) (2020), [WP2 meeting](#) (2022) and recent [follow-up](#) discussion.

Gas target system

- ▶ Gas target requirement for an **unbiased beam profile measurement**: **Transverse gas density profile homogeneity**, over the time scale of ≈ 1 min (integration time).
- ▶ Gas target parameters impacting the performance:
 - ▶ Gas species \Rightarrow number of tracks per interaction
 - ▶ Pressure \Rightarrow interaction rate \Rightarrow number of events with sufficient number of tracks in a given time interval

2 gas target options are considered:

Gas injection system: (demonstrator target [4])

extended pressure bump: $\Delta z \approx 1 - 2$ m

10^{-7} mbar \Rightarrow 200 Hz inelastic interaction rate per bunch

\Rightarrow decrease instrument complexity

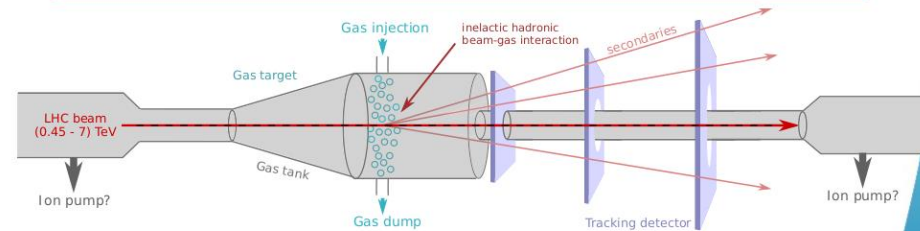
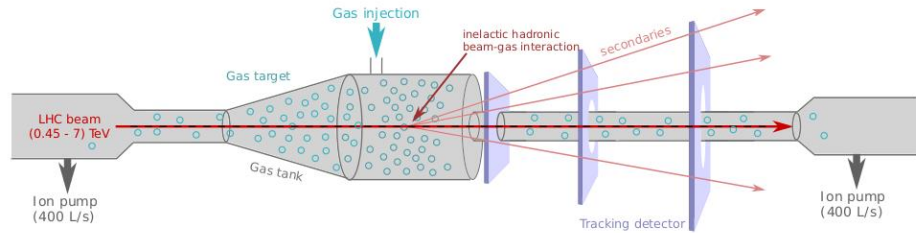
Gas curtain target: BGC target [5]

localised pressure bump: $\Delta z \approx$ few mm

\Rightarrow similar interaction rate

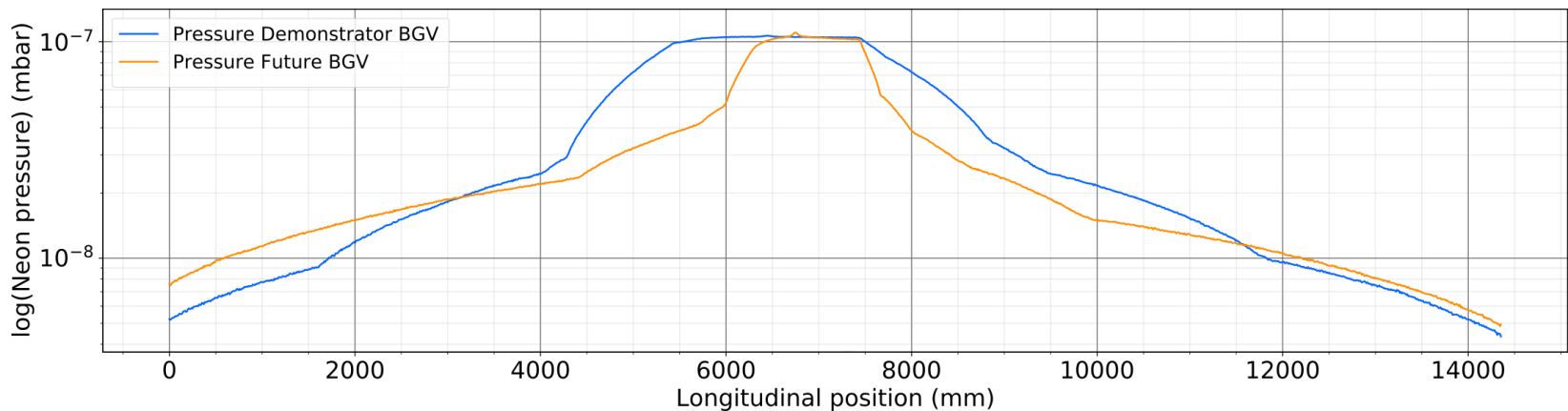
\Rightarrow easier identification of tracks from the interaction vertex.

\Rightarrow improves vertex resolution due to z constraint.



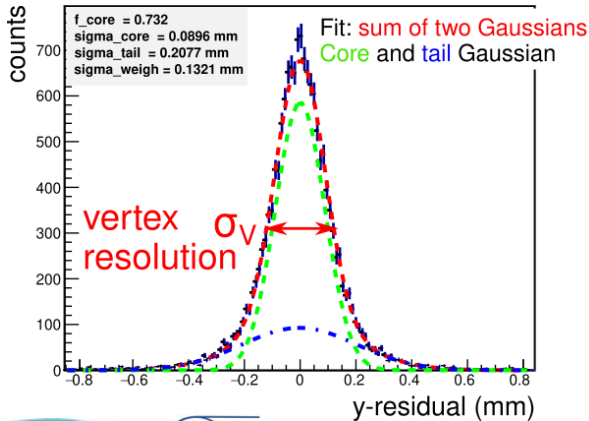
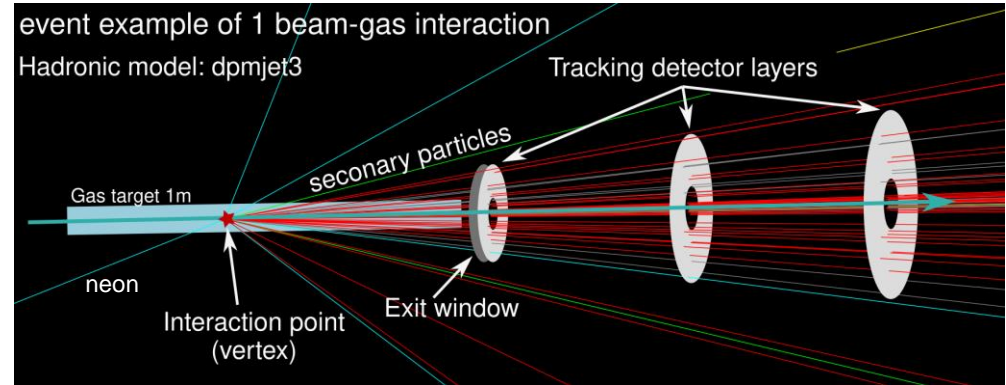
Longitudinal gas profile comparison

Molflow simulations by H. Guerin, with input from R. Kersevan



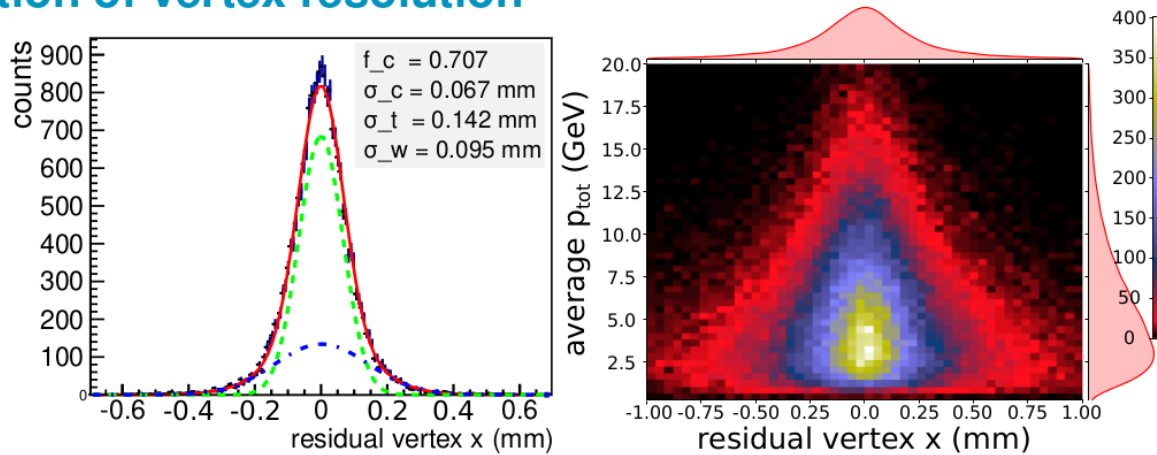
Performance study - overview

- ◆ **Initially: generic BGV** setup to ease navigation of extensive parameter space.
- ◆ **Goal:** efficiently identify impact of design parameters and provide first estimates of promising setup's dimensions etc.



- ◆ detector parameters studied:
- ◆ material budget, size, separation, spatial resolution.
- ◆ extended gas target of 1 m in z.
- ◆ **Evaluation of performance:**
- ◆ compare reconstructed vertices to generator level vertices.
- ◆ determine response and vertex resolution.

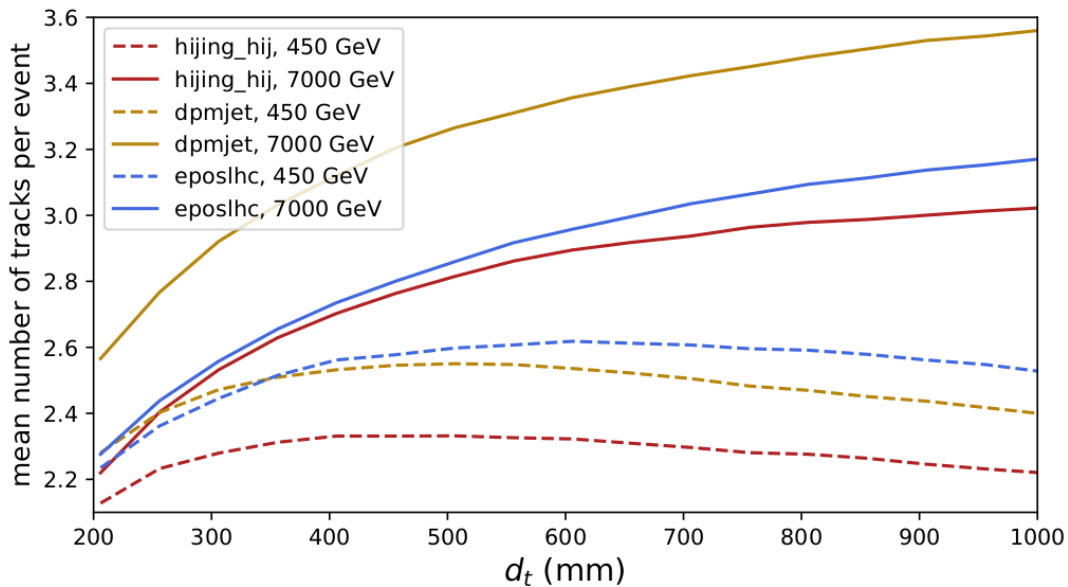
Determination of vertex resolution



Residual r_x ($N_{tr} = 5$). Red line: fit with sum of two Gaussians. Green and blue dashed lines: core and tail Gaussians. Right: two-dimensional histogram of the r_x ($N_{tr} \geq 2$) vs average total momentum of the tracks stemming from the vertex.

- ▶ Compute residuals $r_i = v_{i,fit} - v_{i,true}$ with $i = \{x, y, z\}$.
- ▶ **Fit residuals with a sum of two Gaussians** (core and tail Gaussian [9]) with widths σ_c and σ_t .
- ▶ The vertex resolution can then be calculated as the weighted average $\sigma_v = \sqrt{f_c \sigma_c^2 + f_t \sigma_t^2}$
- ▶ where f_c and f_t are core and tail fractions, calculated via: $f_t = \frac{\rho_t \sigma_c}{\rho_c \sigma_c + \rho_t \sigma_t}$, where ρ denotes the amplitudes and σ the widths of the Gaussians.

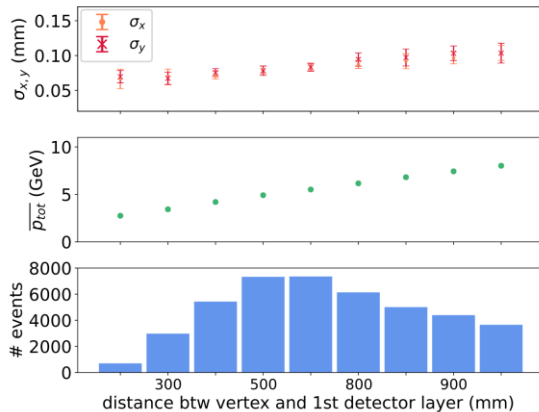
Distance source-detector vs mean #tracks per event



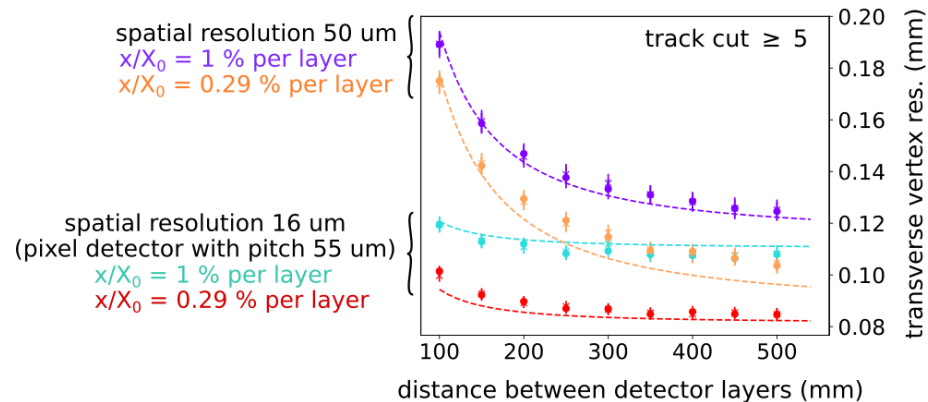
Results and conclusions of generic BGV study

- Distance between vertices and first detector layer that showed highest average number of tracks is **550 mm**.
- Extended gas target is no show stopper.
- Performance results point towards a **compact tracker with a high spatial resolution**.

vertex resolution vs distance between interaction and detector:



vertex resolution vs distance between detector layers:



- Eliminates any x/y hit association issues (demonstrator BGV).
- Promising candidate: compact Si pixel tracker with detector layer ~ 250 mm apart.
- Fits within space between the LHC beam pipes.

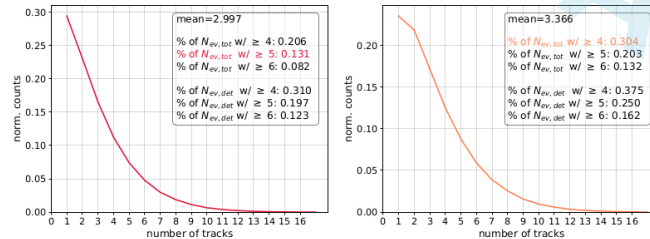
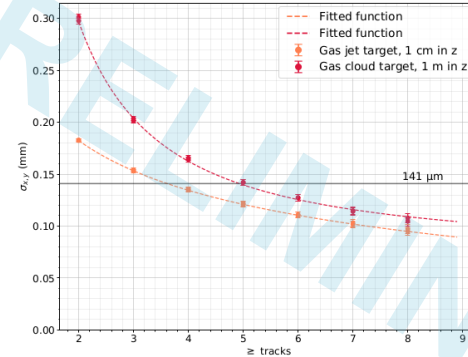
Gas curtain target - performance

slide from: [BI/TB Meeting, March 2022](#)

Performance results - gas injection and gas jet (7 TeV)

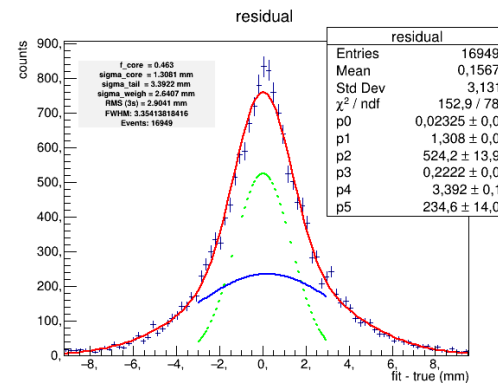
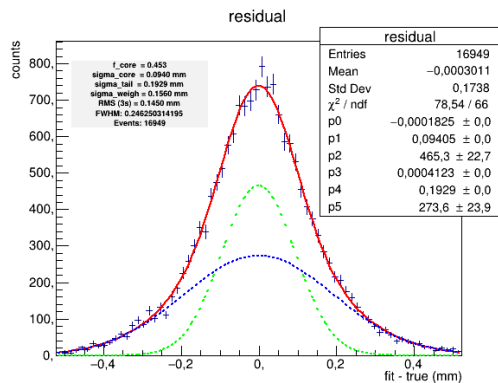
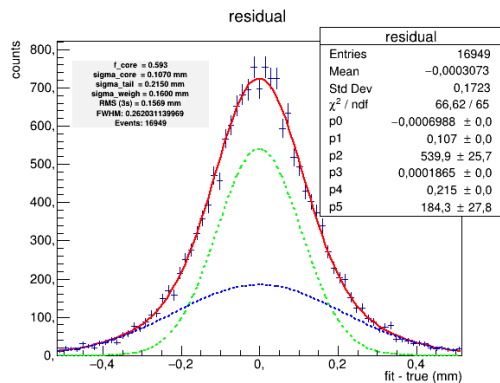
- ▶ 7 TeV, same number of initial beam-gas interactions.
- ▶ Vertex resolution vs registered number of tracks per event.
- ▶ Performance goal reached with:
 - ▶ **Extended gas target:** events with ≥ 5 tracks \Rightarrow 13 % of total beam-gas collisions.
 - ▶ **Gas jet:** events with ≥ 4 tracks \Rightarrow 30 % of total beam-gas collisions.
- ▶ Localised pressure bump \rightarrow larger fraction of the total collisions can be accepted. Lower integrated pressure is necessary.
- ▶ Width < 1 cm no large impact on performance

▶▶ back-up slide



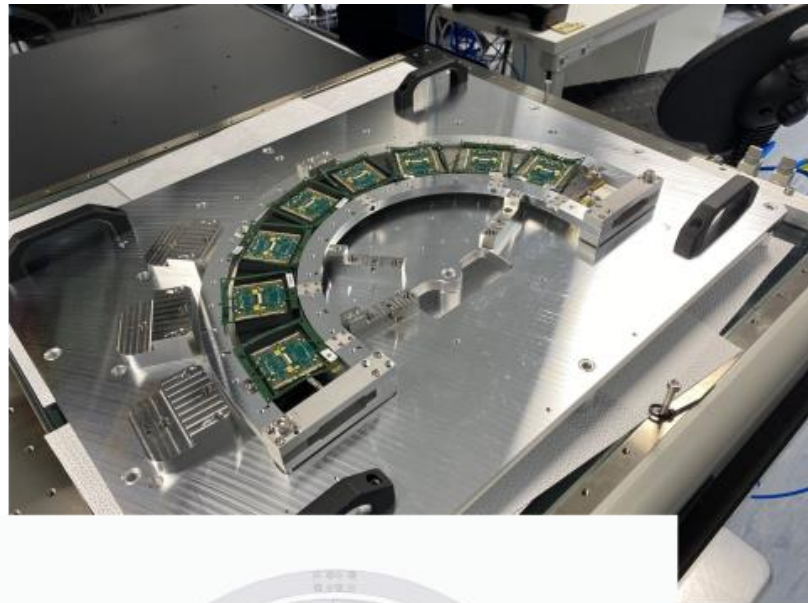
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Vertex residuals examples (x, y, z)



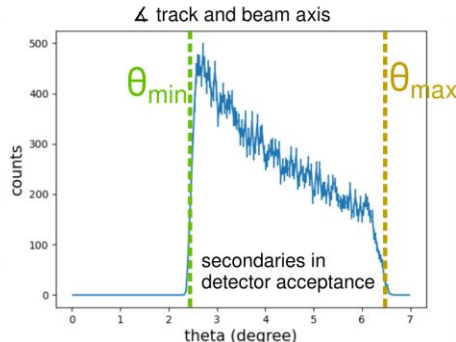
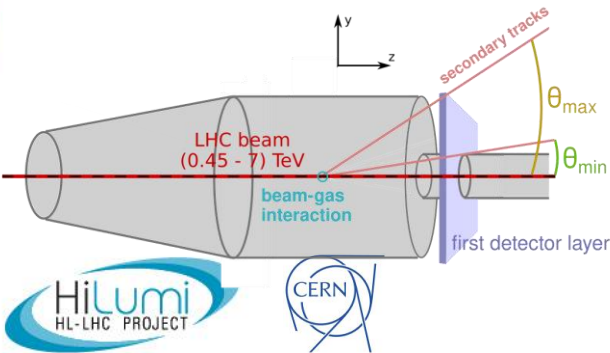
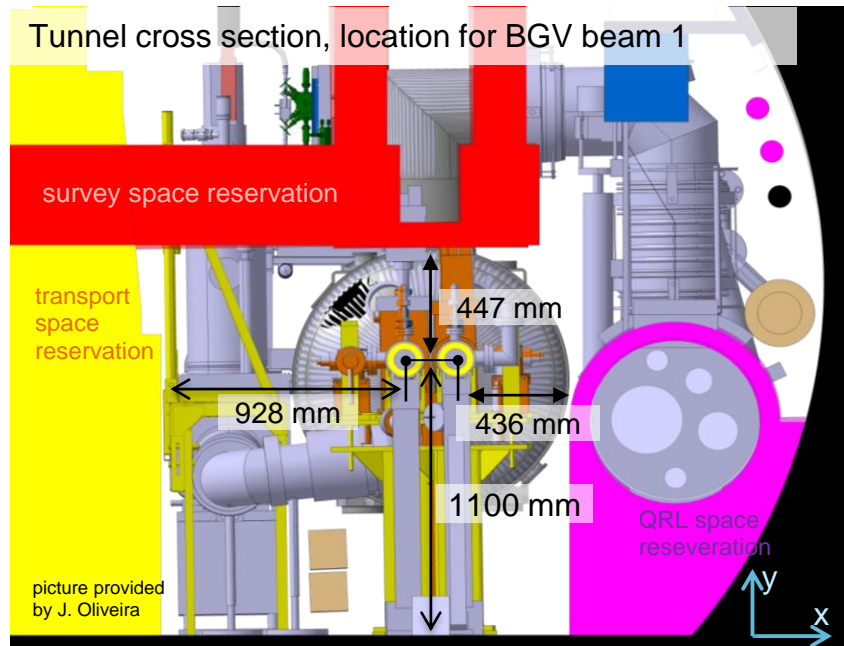
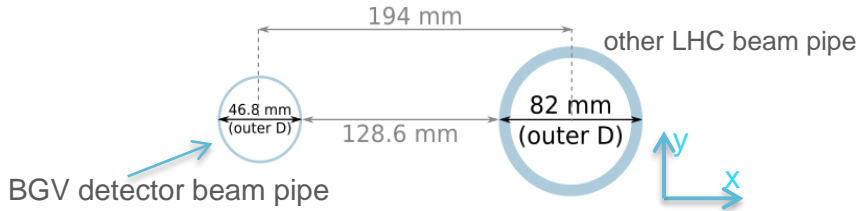
A glimpse in the future? - ATLAS iTk prototype

pictures by courtesy of D. Hynds



Detector space and placement

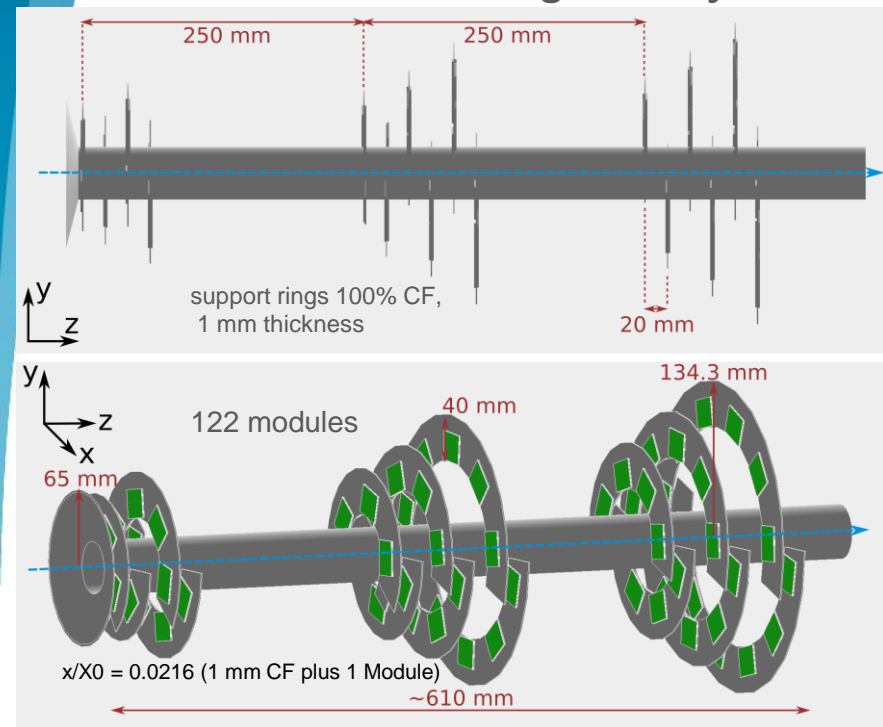
- ◆ Integrational space constraints (reserved areas in tunnel).
- ◆ **Allow access to beam pipes** for e.g. baking prior to runs. Take into account for detector support.
- ◆ **Space constraint transversally** due to **second beam pipe**:



- ◆ Place detector layers **transversally** as **close to beam axis** as possible.
- ◆ Size of 1st detector layer is determined by diameter of gas tank.

Details of updated geometry

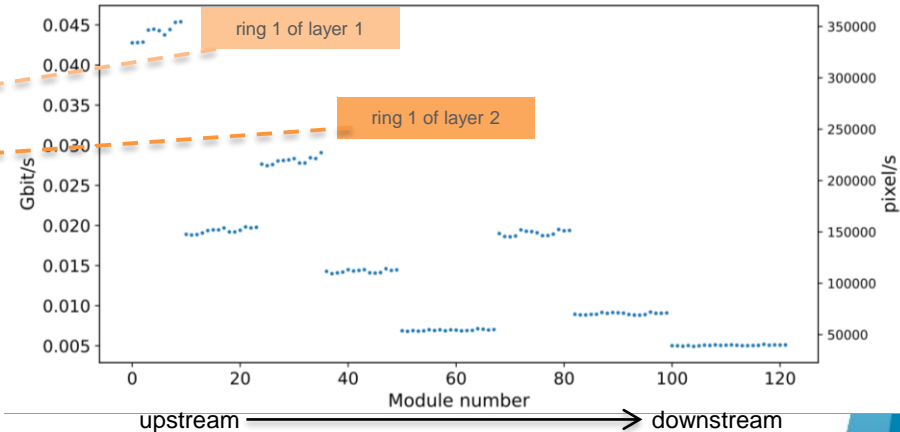
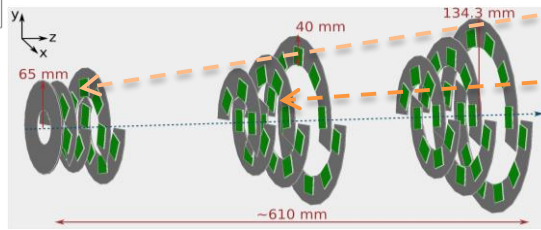
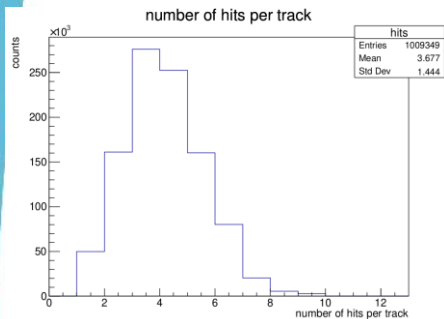
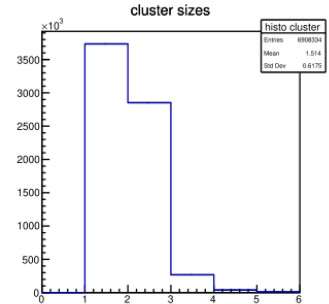
Tracker simulation geometry



- ◆ Dimensions based on generic BGV dimensions.
- ◆ **Module:**
 - ◆ Material: Sensor 300 μm Si, Timepix 700 μm Si, Flex cable: 8 μm Cu, 170 μm Kapton, 300 μm C, Glue.
 - ◆ Transverse size: 24.7 mm x 29.96 mm.
- ◆ **Support half rings:** dz = 1 mm carbon fibre.
- ◆ **122 modules in total.**
- ◆ **Reconstruction analysis:**
 - ◆ Gaussian smearing $\sigma = 55\mu\text{m}/\sqrt{12}$ of hits (spatial resolution).
 - ◆ Track and vertex fitting.
 - ◆ To be added: digitisation, clustering, track finding.
 - ◆ 3D track info of timepix4 not yet included in analysis.

Hit and event rate estimation for DAQ via G4 simulations

- Collision rate 6×10^5 Hz, (7 TeV & gas pressure of 10^{-7} mbar).
- Total number of secondaries traversing all detector modules:**
 8.96×10^6 per sec.
- Geometric digitisation - average pixel cluster size is 1.5 pixels. **1.35×10^7 activated pixels/s.**
- Assume event size of 128 bit (64 bit plus padding). **Total amount of 1.72 Gbit/s data.**
- Better estimation: Allpix2 and inclusion of background sources.



- Data amount of “interesting” events ($N_{\text{tracks}} \geq 6$).**
- ~45 average activated pixels per event.
- Total event rate of $N_{\text{tracks}} \geq 6$: 53 kHz, 2.37×10^6 pixels/s.
- 0.3 Gbit/s.**

- Processing time** for reconstruction per recorded collision: ~6 ms (rough conservative estimate).
- with 100 CPUs - 16.7 kHz.

Detector read-out

- ♦ **Read-out system mock-up** based on Beam Gas Ionisation monitor (BGI) by H. Sandberg.
- ♦ Around 120 timepix4 modules.
- ♦ **Frontend:** Low Power Giga Bit Transceiver (lpGBT) + an optical link module for data transmission (VTRx+) + DC/DC power supply.
- ♦ **Backend:** Based around a system-on-chip (SoC) from Xilinx: contains both programmable logic (FPGA) and processors.
- ♦ Flexibility to process data in both gateway and software on Zynq - **possibility to do some steps of the analysis on backend.**
- ♦ Analyse selected events with **reconstruction software on CPU farm** similar to demonstrator (~100 CPUs).

