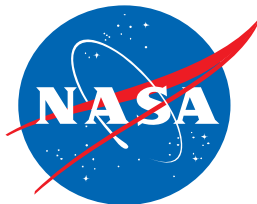


M2Or3J-02

Cryogenic vacuum chamber testing of a conductively-cooled, high temperature superconducting rotor for a 1.4 MW electric machine for aeronautics applications

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Kirsten P. Duffy³, Tysen T. Mulder¹



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³ *University
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Motivation

- Aviation impacts:

Climate

- **CO₂** (dominant), **contrails** ($\sim \frac{1}{2}$ impact of CO₂), **H₂O vapor**, **soot**

Environment

- Air quality – **NO_x** (dominant), **sulfur**
- Noise

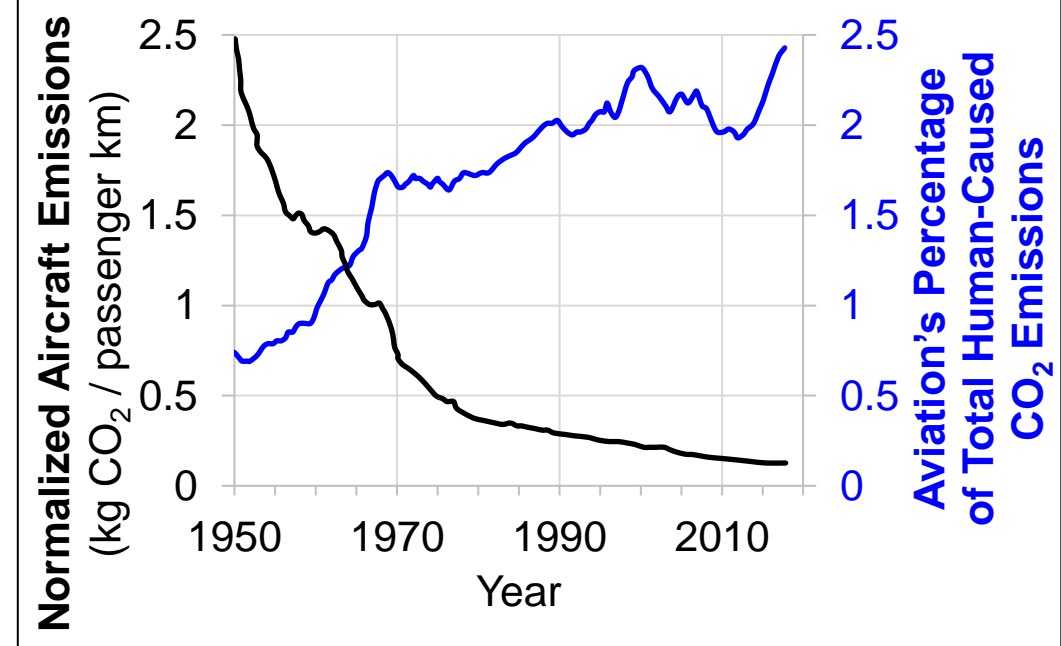
- Despite significant progress in efficiency, global CO₂ emissions from aviation growing at increasing rate

- 2 options:

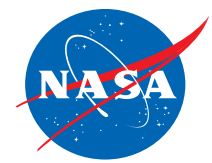
- Change fuel (e.g., jet A → SAF or H₂)
- Electrify

- NASA's High-Efficiency Megawatt Motor (HEMM) sized as generator for NASA's STARC-ABL concept

Global aviation impact on CO₂ (data from [1])

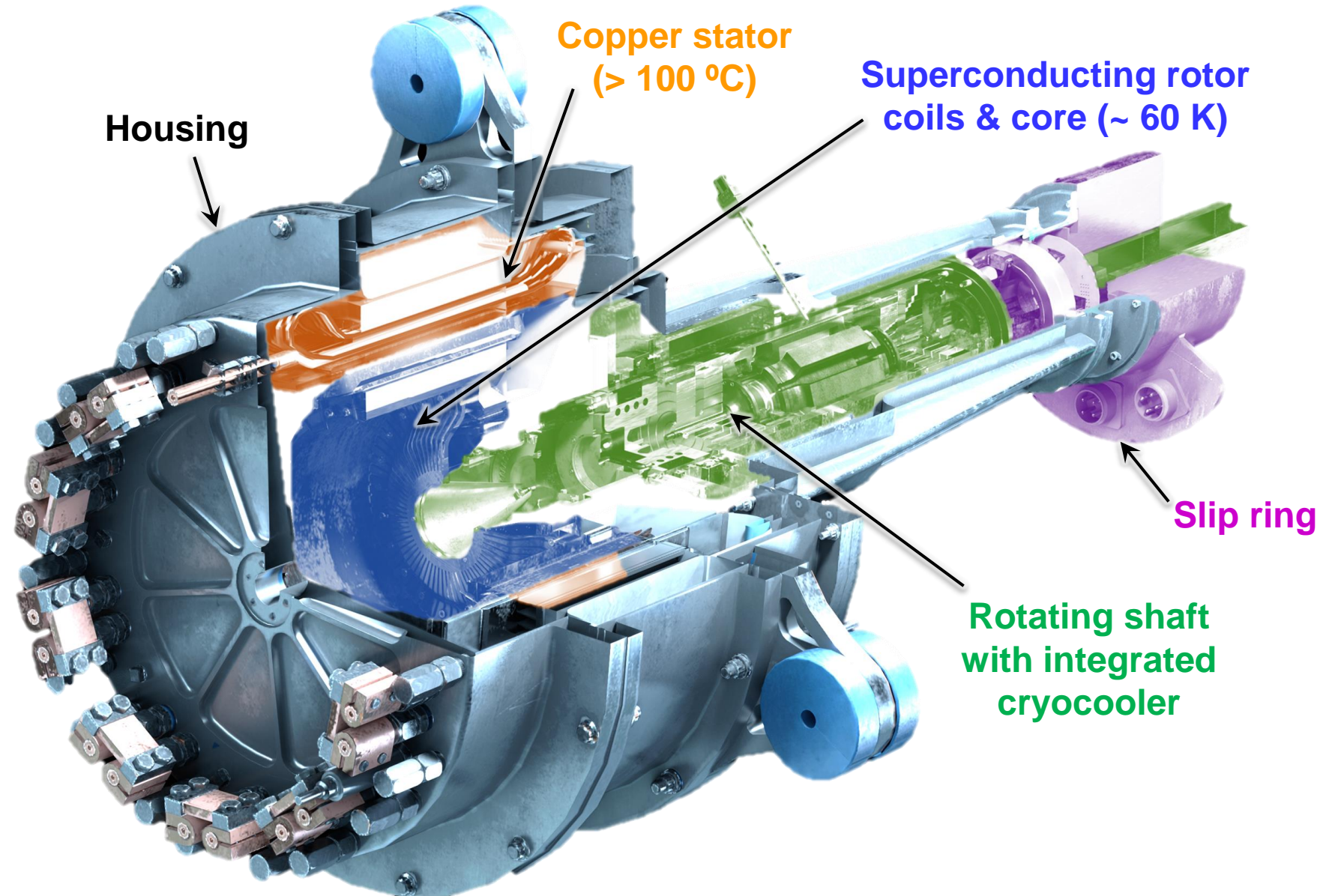


1. Lee, D.S. et al., Atmospheric Environment 244, 117834, 2021.



NASA's High-Efficiency Megawatt Motor (HEMM)

Parameter	Value
Rated continuous power	1.42 MW
Nominal speed	6,800 rpm
Tip speed	107 m/s
Rated torque	2 kNm
Electromagnetic specific power goal	16 kW/kg
Efficiency goal	> 98%





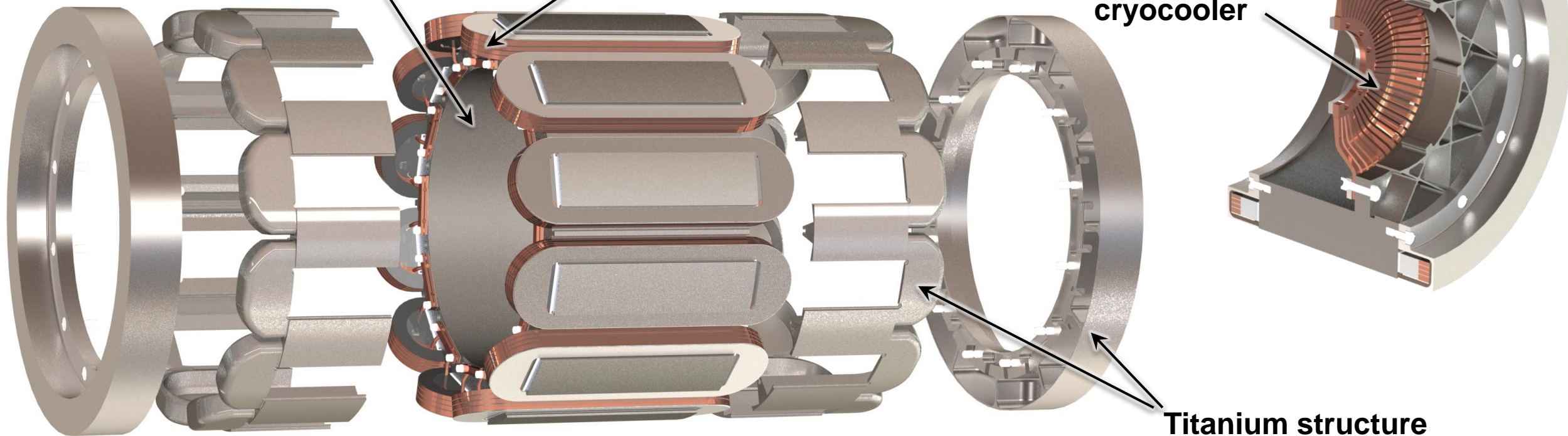
HEMM's Superconducting Rotor

$\text{Fe}_{49.15}\text{Co}_{48.75}\text{V}_2$ rotor core

Superconducting coil

Thermal bridge to cryocooler

Titanium structure



Parameter

Value

Pressure of rotor cavity

< 1e-3 torr

poles (coils)

12

Superconductor

2nd generation high temperature superconductor

Parameter

Value

Coil configuration

No-insulation quadruple pancake

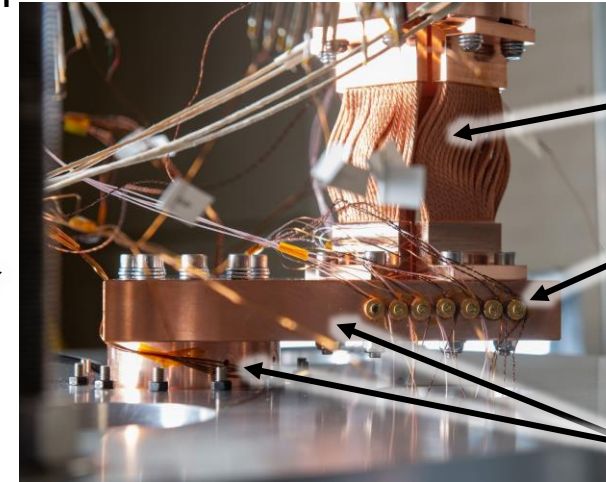
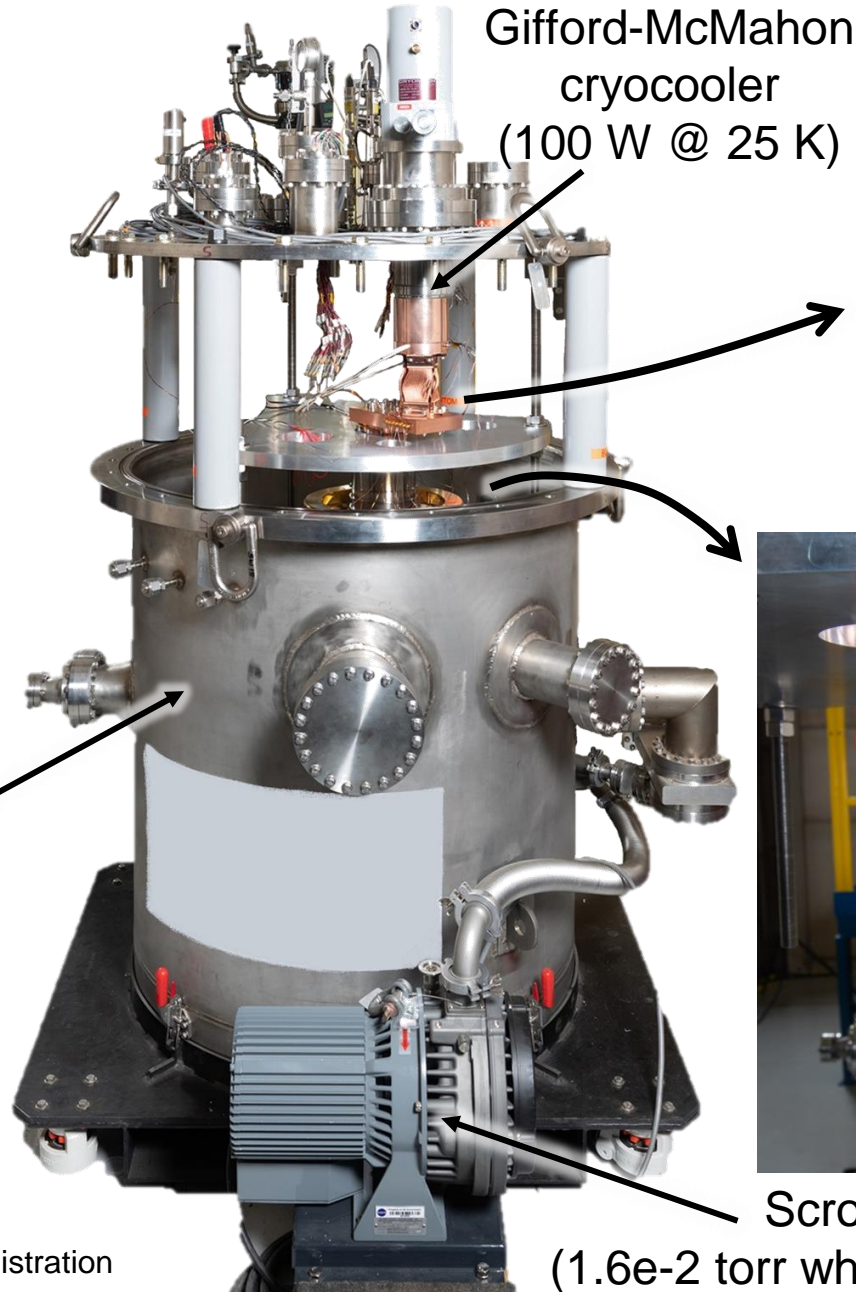
turns per coil

600 (150 per layer)



Experimental Setup – Physical Assembly

- Used NASA Glenn's ICE-Box



4x thermal straps (4.6 W/K total)

Sensor lead wire heat sink bobbins

Cold tip extensions (solid Cu 101)



Support plate (Al 6061)

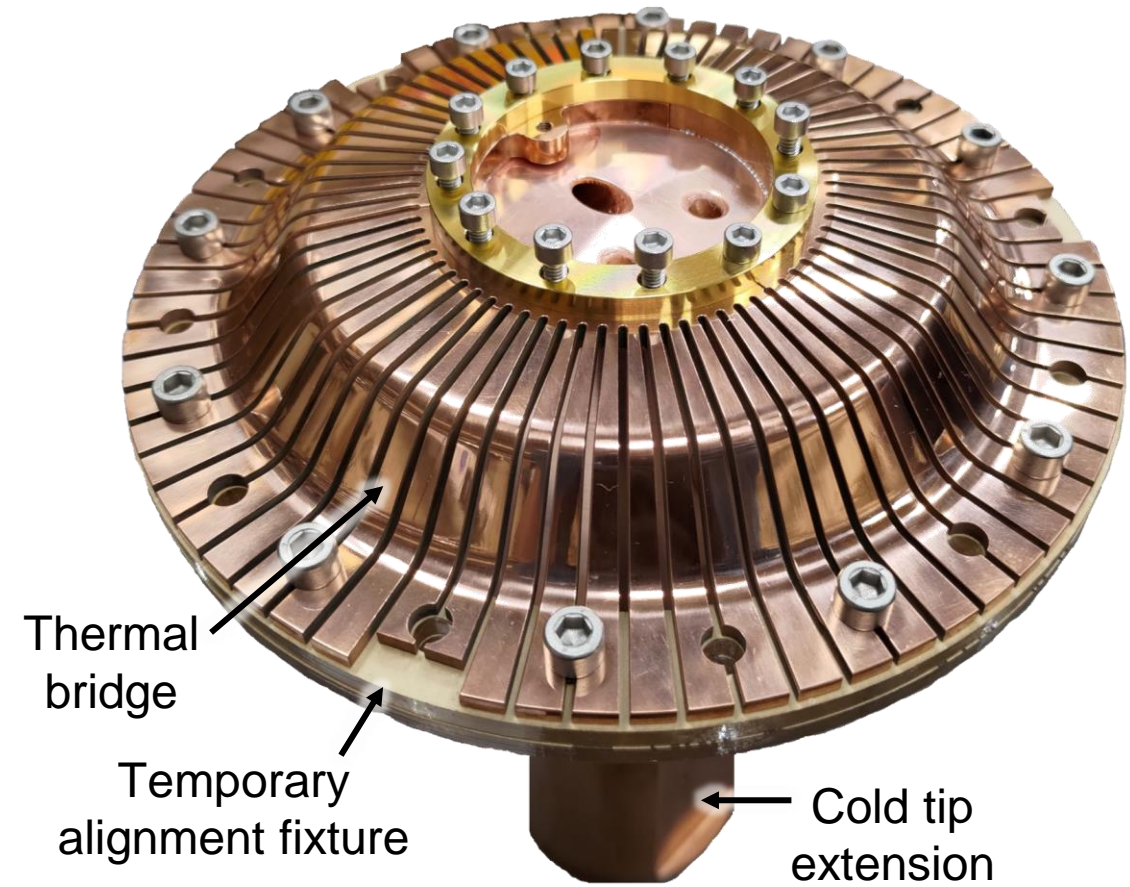
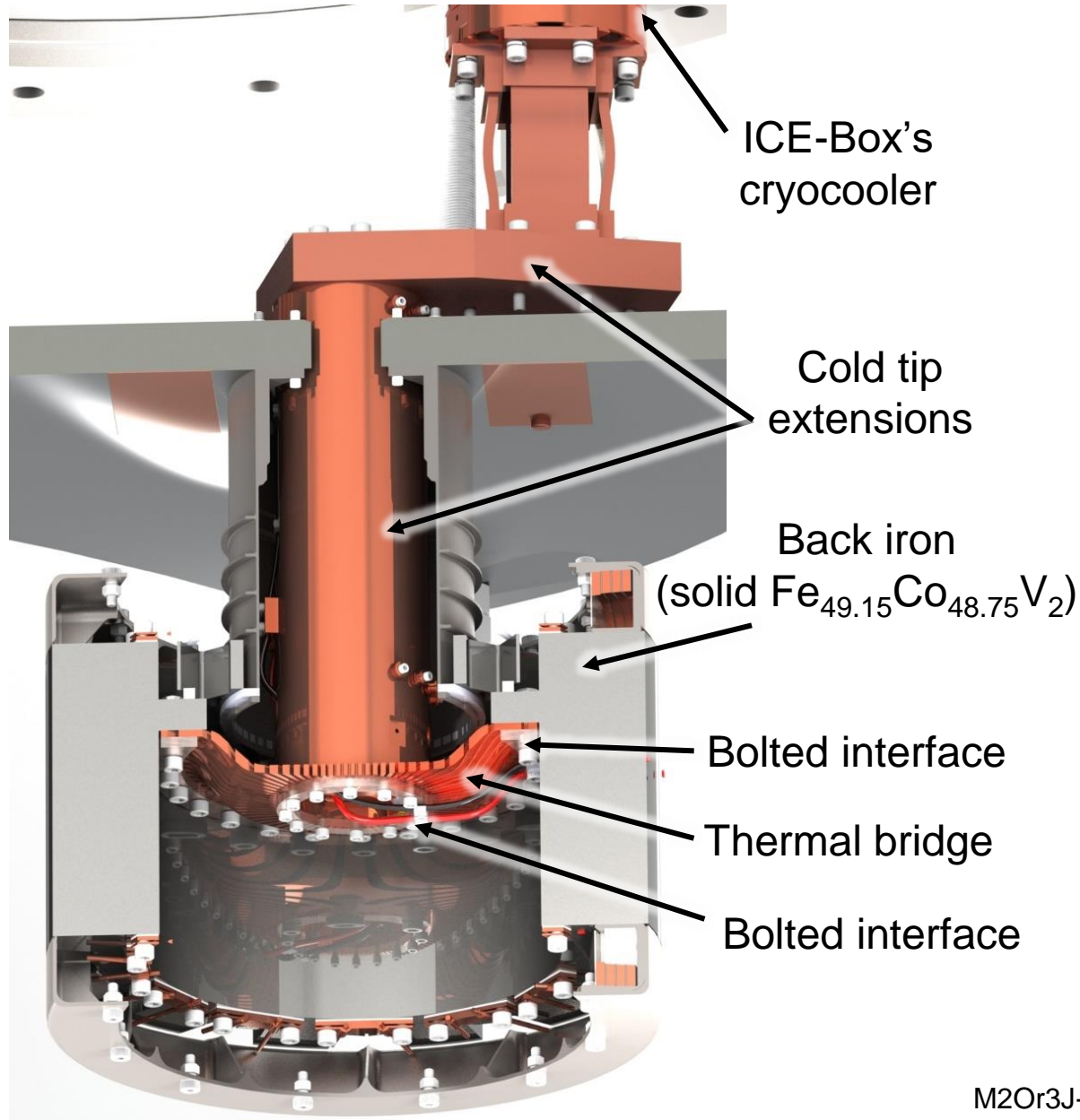
3x support plate heaters

Shaft section (Ti-6Al-4V)

Rotor assembly

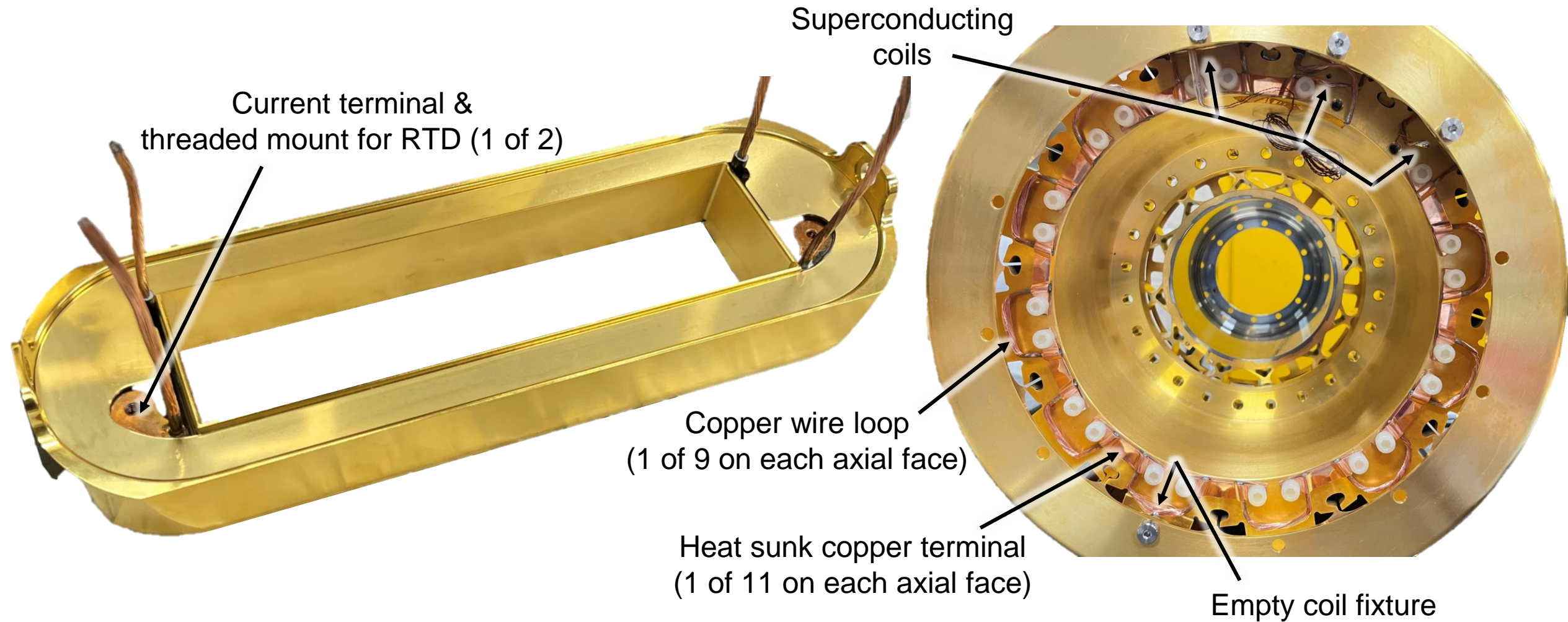


Experimental Setup – Physical Assembly





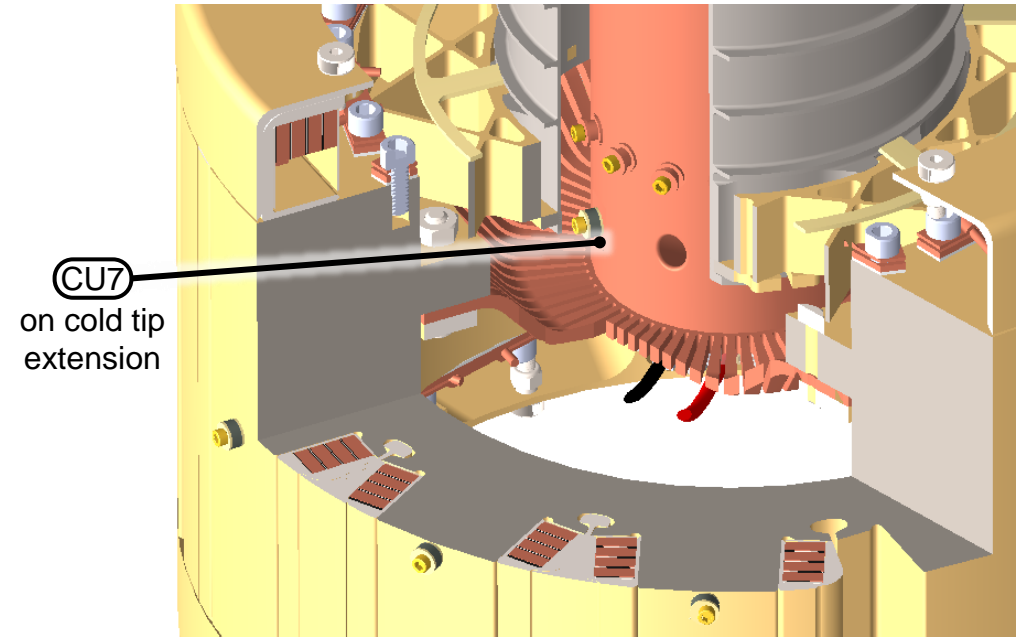
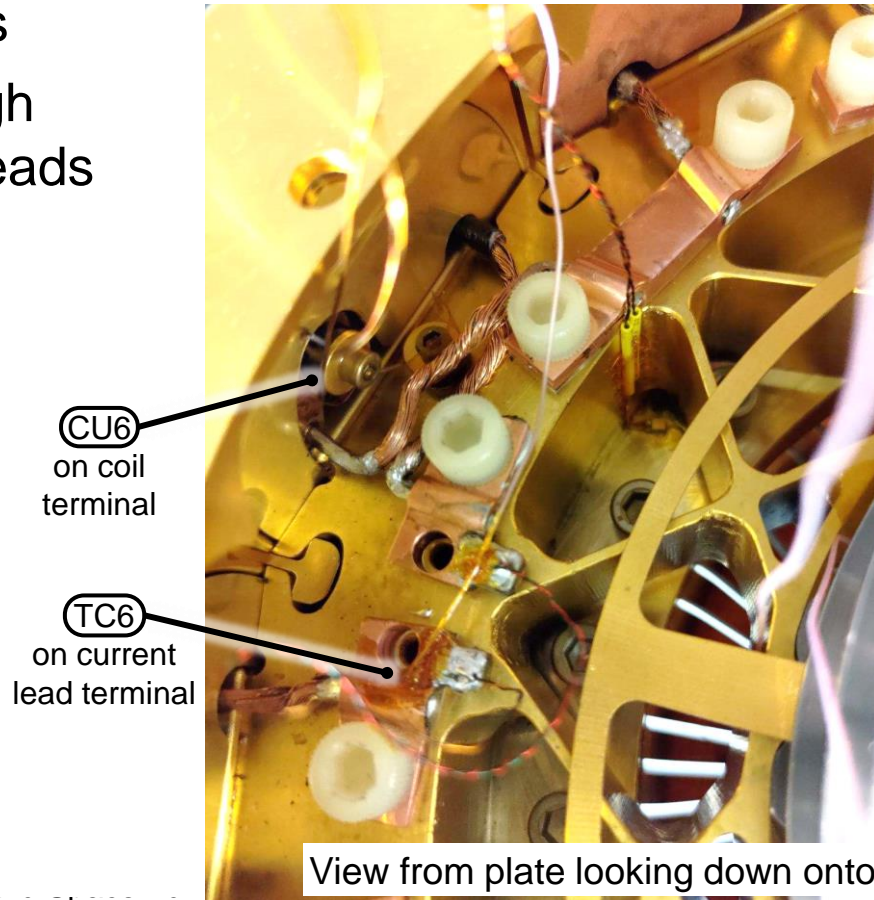
Experimental Setup – Physical Assembly





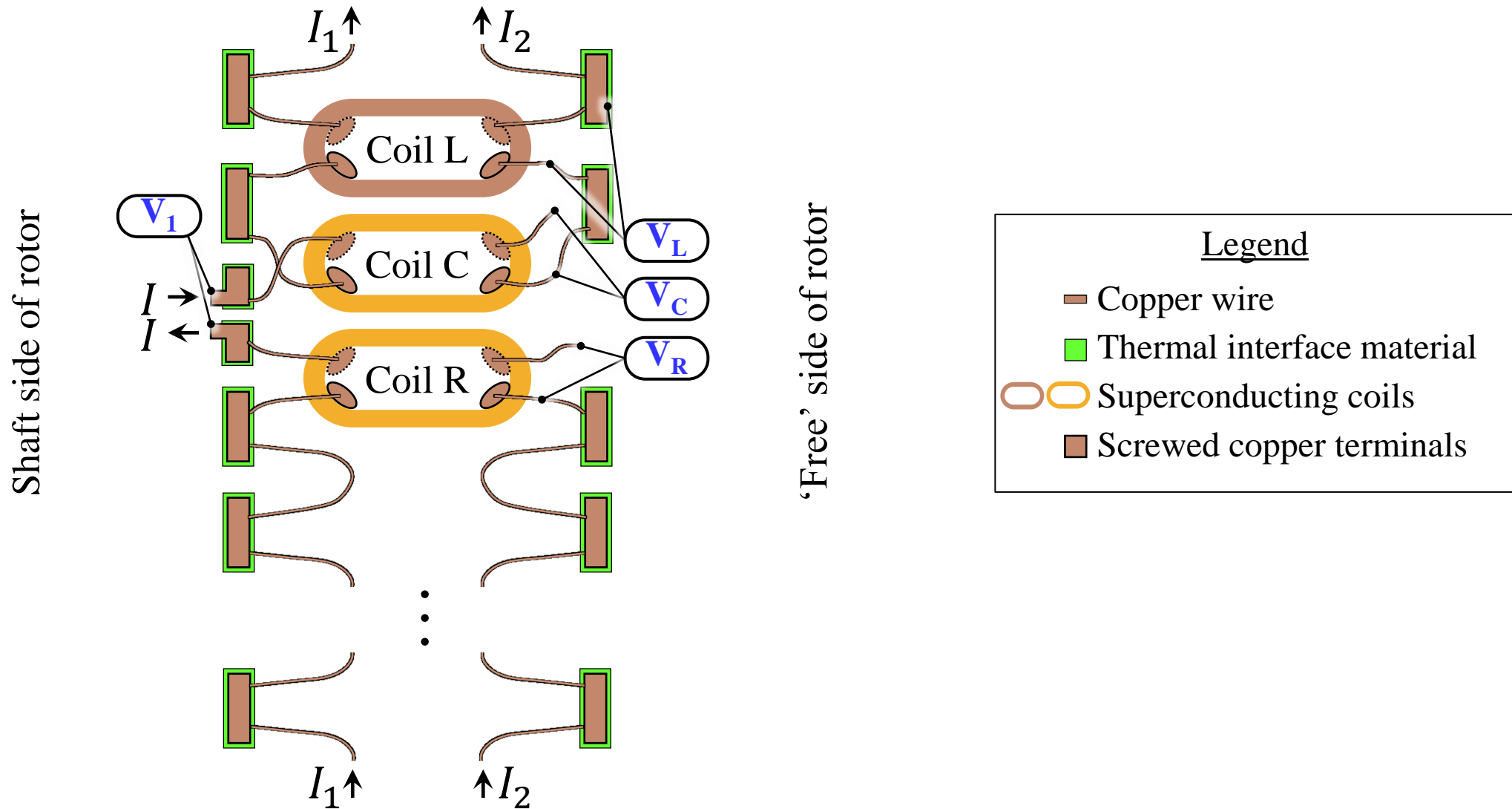
Experimental Setup – Instrumentation

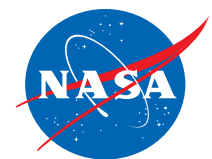
- Vacuum feedthrough channels
 - 15 resistive temperature detectors (RTDs)
 - 9 Type E thermocouples
 - 4 voltage probes
 - 2 heaters
 - 1 pair high current leads





Experimental Setup – Instrumentation





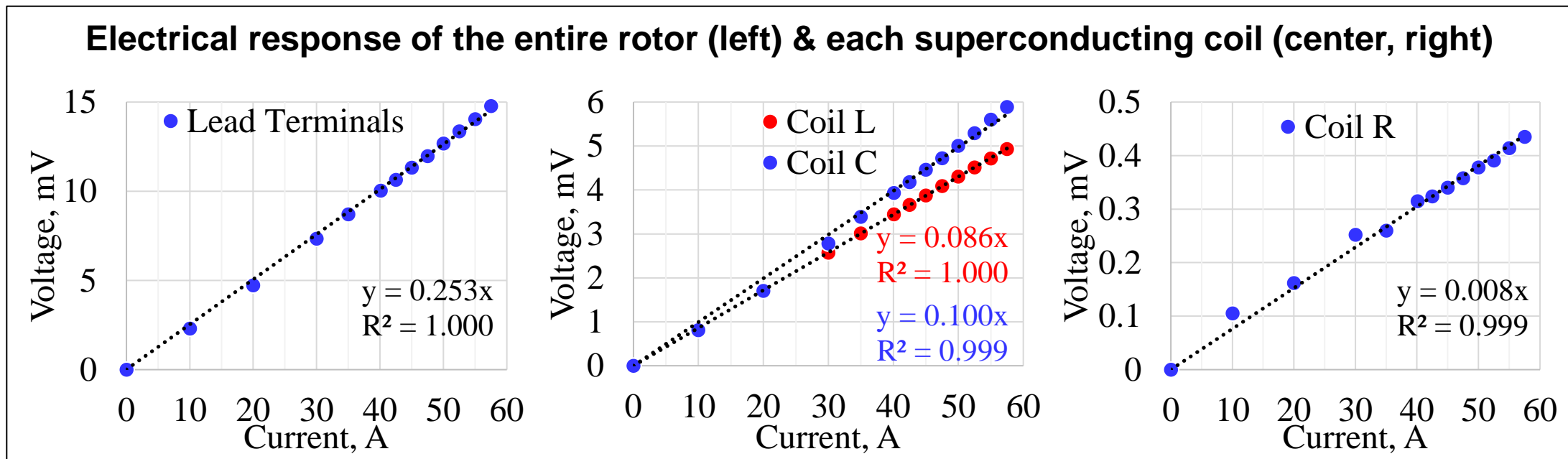
Experimental Results – Electrical

- Current slowly ramped between set points ($\sim 0.5 - 0.7$ A/min) to minimize heating in coils
- Each data point taken after voltage and temperature exhibited little variation (typically 30-45 minutes)
- **1st round of testing**
 1. At 60.5 – 61.0 K
 1. Linear & stable voltage response up to 45 A, then ~ 7 mV jump while stabilizing at 50 A
 2. Linear & stable voltage up to 57.2 A (rated current)
 2. At 57.2 A
 1. Linear & stable voltage from 60.8 K to 62.0 K (rated temperature)



Electrical Results – Voltage Response

- 2nd round of testing
 - At 60.9 – 61.1 K
 - Linear & stable voltage up to ≥ 47.5 A on 4 separate occasions over 2 weeks

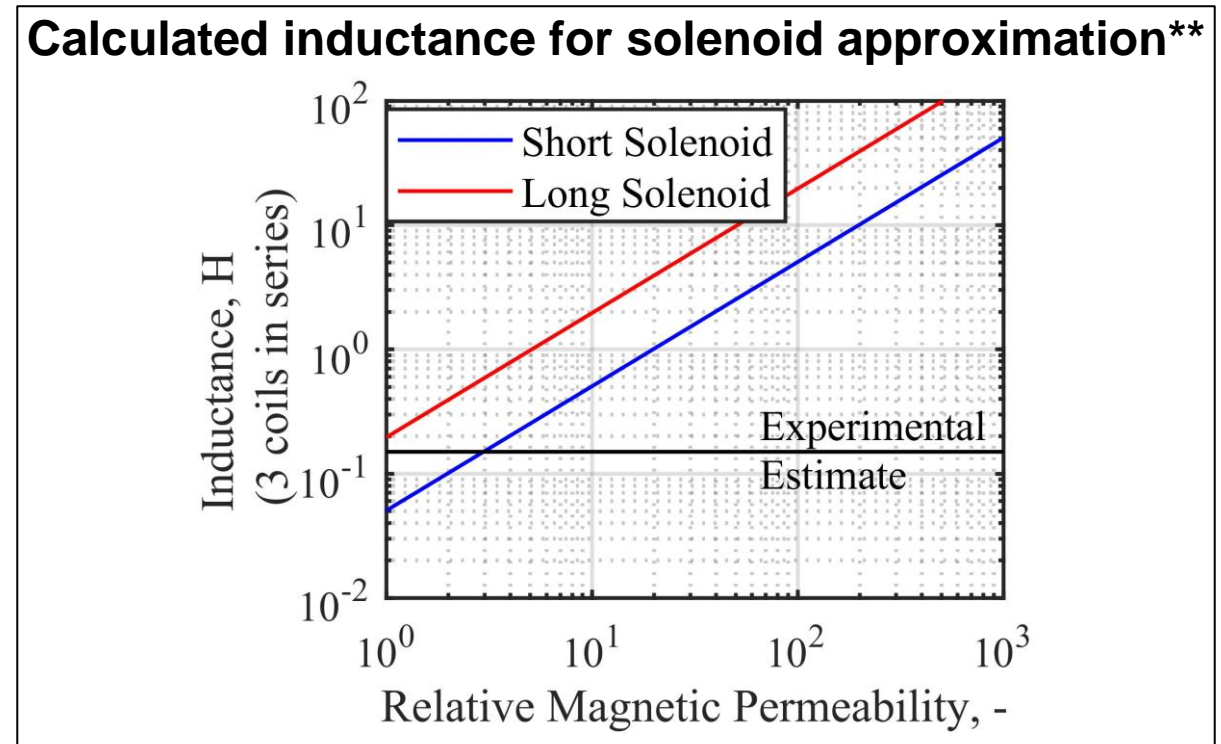
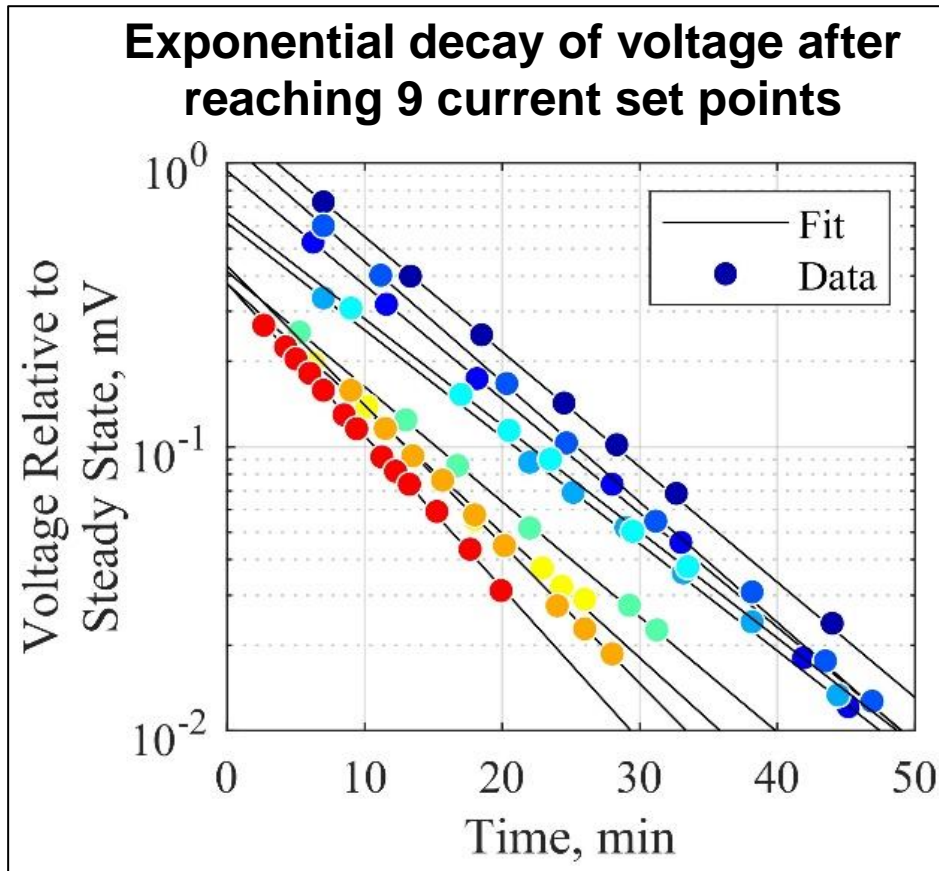


	Entire rotor	Coil L	Coil C	Coil R
Measured Resistance R, mOhm	0.253	0.086	0.100	0.008



Electrical Results – Inductance

- 2nd round of testing
 - At 60.9 – 61.1 K
 - Measured exponential time constant (τ): average: 10.2 min | standard deviation: 1.2 min
 - **Estimated inductance = 0.15 H** (series L - R circuit: $L=\tau R$)



** Long solenoid: $L = \frac{\mu N^2 A}{l}$ Short solenoid: $L = \frac{\mu N^2 A \{\sqrt{a^2 - l^2} - a\}}{l^2}$

$N = \#$ of turns = 600 | $A =$ cross-sectional area = $\frac{\pi}{4} (50.8)^2 \text{ mm}^2$ (mean diameter of end turns = 50.8 mm) | $a =$ radius of turn = $\frac{50.8}{2} \text{ mm}$ | $l =$ length = 14 mm



Electrical Results – Inductance

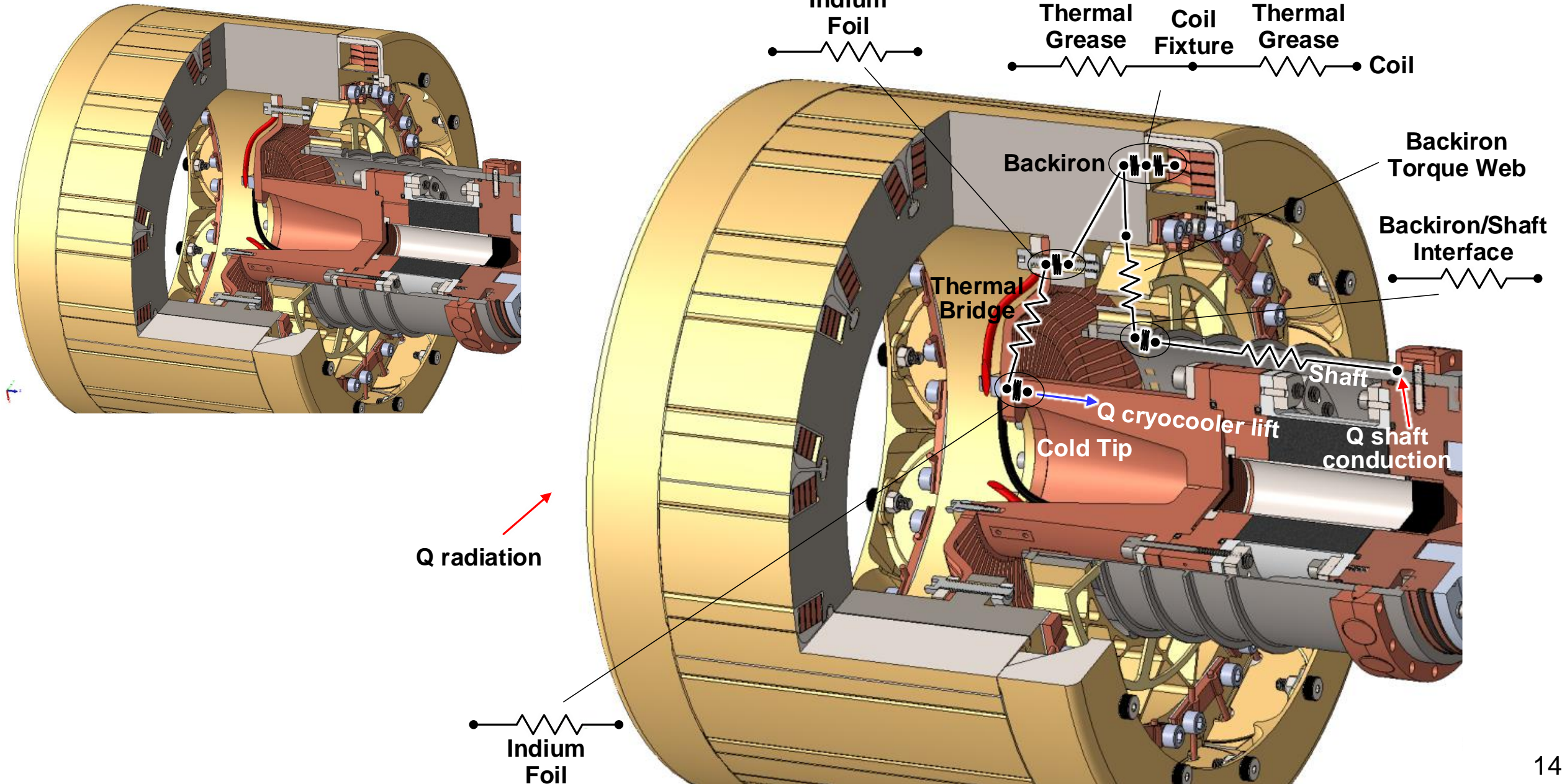
- 2nd round of testing

Voltage response to quasi-step 10 A decrease in current

Coil temperatures, K	Measured time constant, s	Measured resistance, mOhm	Estimated inductance, mH
55.8 to 57.4	628	0.253	159
104.3 to 105.6	< 0.2	0.680	< 0.1
300	< 0.2	0.557	< 0.1



HEMM – Thermal Design





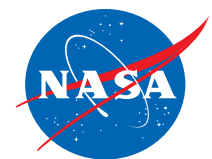
Steady-State Thermal Results

- Steady state: >90% of temperature sensors changing at rate < 0.2 K/hr
- Most tests: cold tip held at 45 K rather than 50 K (HEMM's nominal)
- **Allowable ΔT from cold tip to coils: 12 K**

Test Point	Rotor Current (A)	Support Plate Heater Enabled?	HEMM's Cold Tip Temp. (K)	Coil Temp. (K)		ΔT , Cold Tip to Coils (K)	
				Average	Peak	Average	Peak
A	0	Yes	48.2	59.6	60.2	11.3	12.0
B	0	No	26.3	39.1	40.1	12.9	13.8
C	0	No	45.0	55.9	56.6	10.9	11.6
D	0	No	45.0	55.2	55.9	10.2	10.9
E	47.5	No	45.0	55.8	56.7	10.8	11.7
F	0	Yes	45.0	56.6	57.3	11.6	12.3

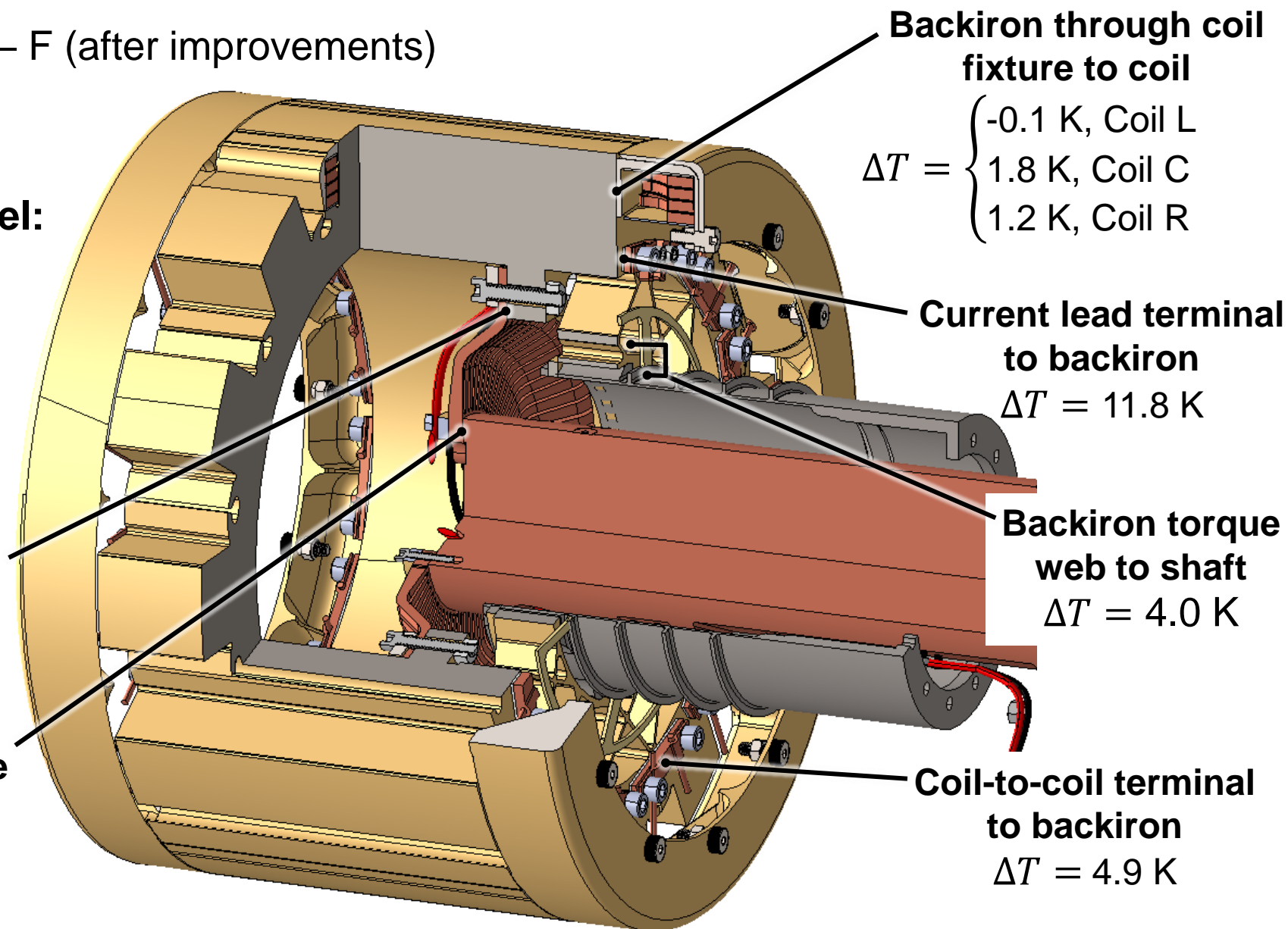
After improvements
(to cleanliness, clamping force, instrumentation)

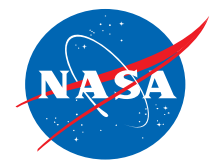
Measured peak ΔT from cold tip to coils (10.9 to 12.3 K) is acceptable, but with no margin



Steady-State Temperature Gradients Across Interfaces

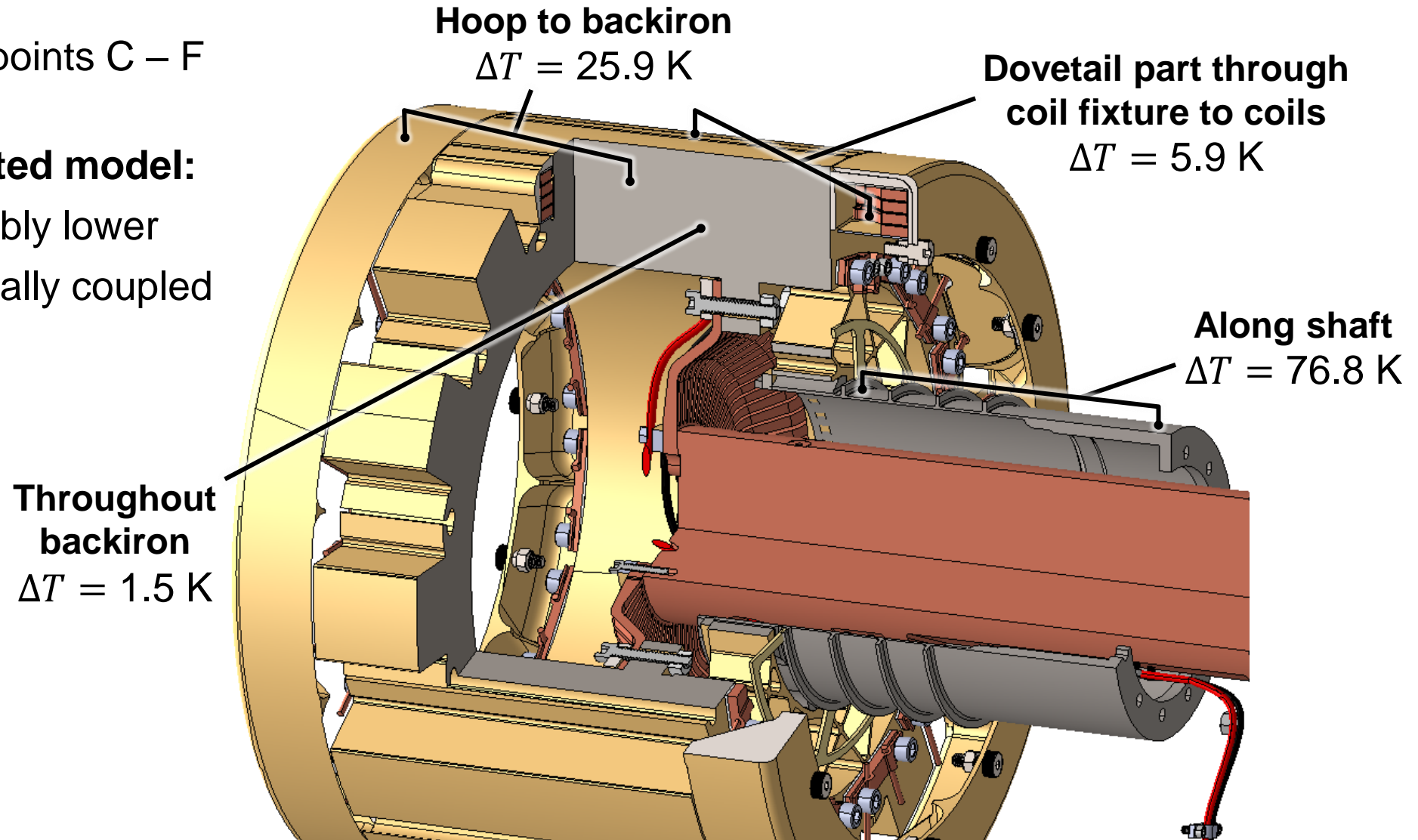
- Values shown for test points C – F (after improvements)
- In most cases, ΔT varied by < 0.6 K between test points
- **Relative to uncorrelated model:**
 - Current terminals hotter
 - Other interfaces similar





Steady-State Temperature Differences Between Parts

- Values shown for test points C – F (after improvements)
- **Relative to uncorrelated model:**
 - Shaft ΔT considerably lower
 - Dovetail part thermally coupled
 - Hoop less coupled



ΔT from cold tip to coils driven by elevated conduction from shaft & current leads

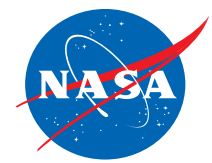


Conclusions

- Thermal & electromagnetic differences between HEMM & ICE-Box experiment are acceptably small [1]
- **Sustained 6 thermal cycles from 293 K to < 50 K throughout test campaign**
- Despite lack of magnetic sensors, **good confidence that superconducting coils operated as intended**
 - Linear & stable operation up to ≥ 45 A in 6 separate tests
 - Estimated inductance of rotor (0.15 H) had reasonable magnitude & went to ~ 0 above HTS transition temperature
- **ΔT from HEMM's cold tip to coils acceptable but with no margin**
 - Identified opportunities to reduce ΔT

Stable operation of rotor at rated current (57.2 A) and rated temperature (62.0 K) demonstrated while conductively cooled with acceptable ΔT

1st ever demonstration of superconducting rotor cooled conductively without a cryogen

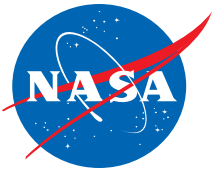


Acknowledgements

This work was funded by

- NASA's Advanced Air Transport Technology (AATT) Project
 - Electrified Aircraft Powertrain Technologies Subproject

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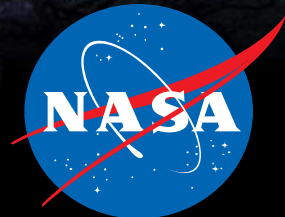
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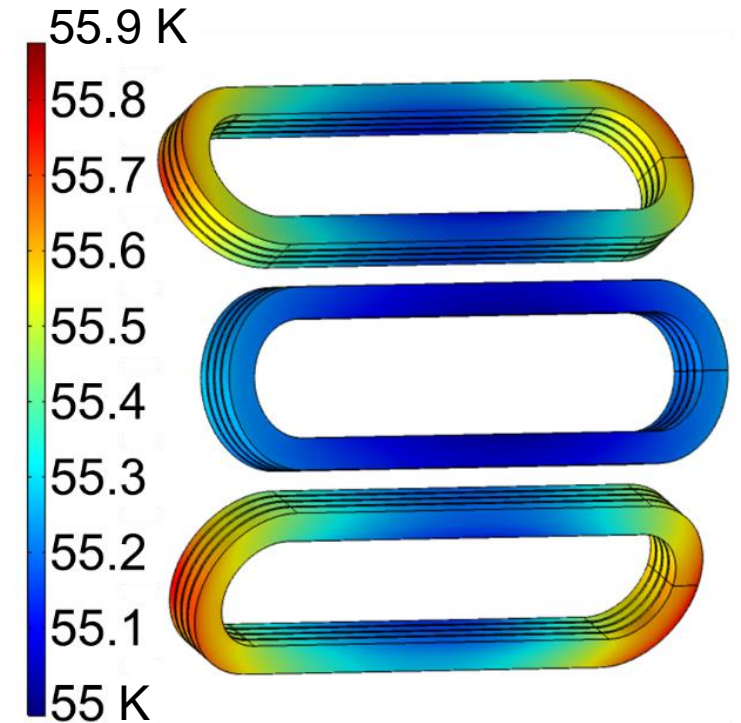
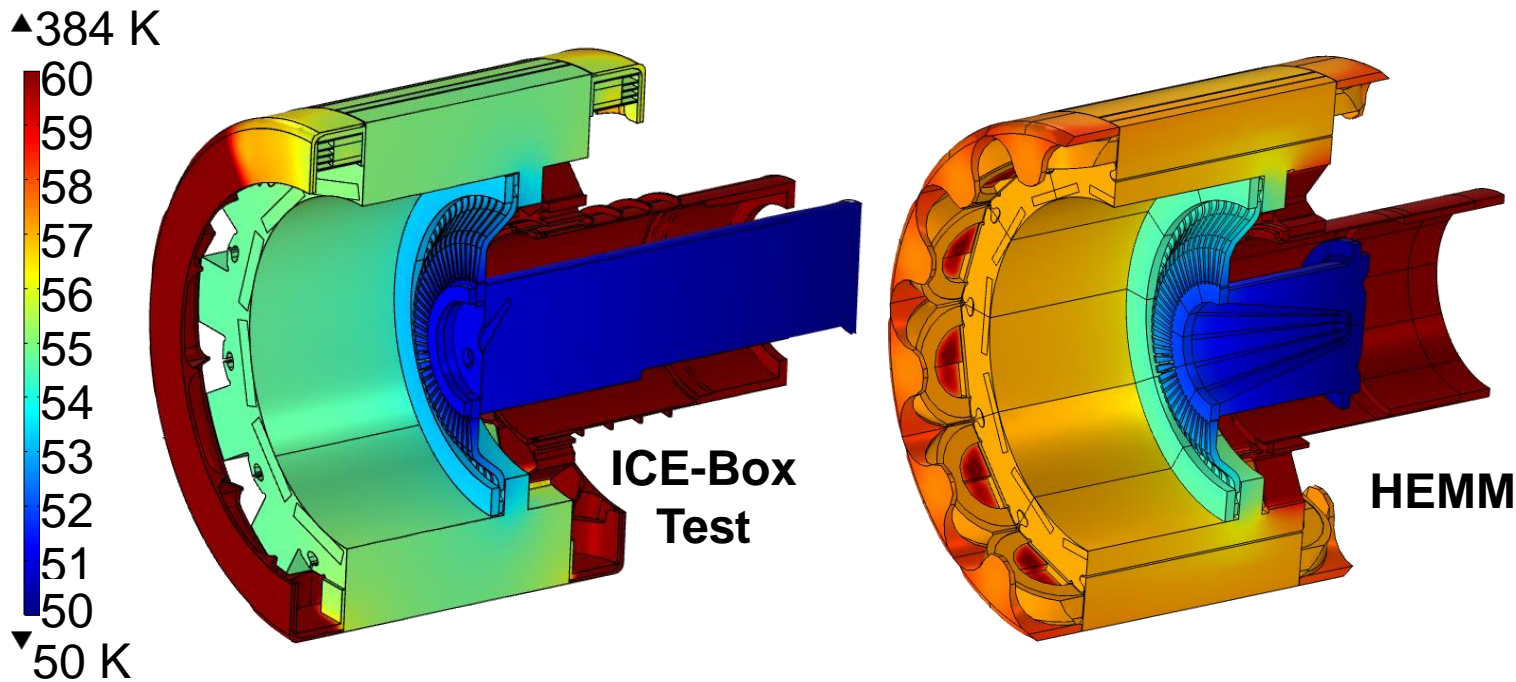
THANK YOU





Simulated Thermal Response

- Radiation, conductive, and resistive heating loads are applied to ICE-Box model
- 4 W lower heat load in experiment due to lack of windage
 - Thus, generally lower temperatures in experiment
- End winding hoops operate at up to ~100 K due to missing coils



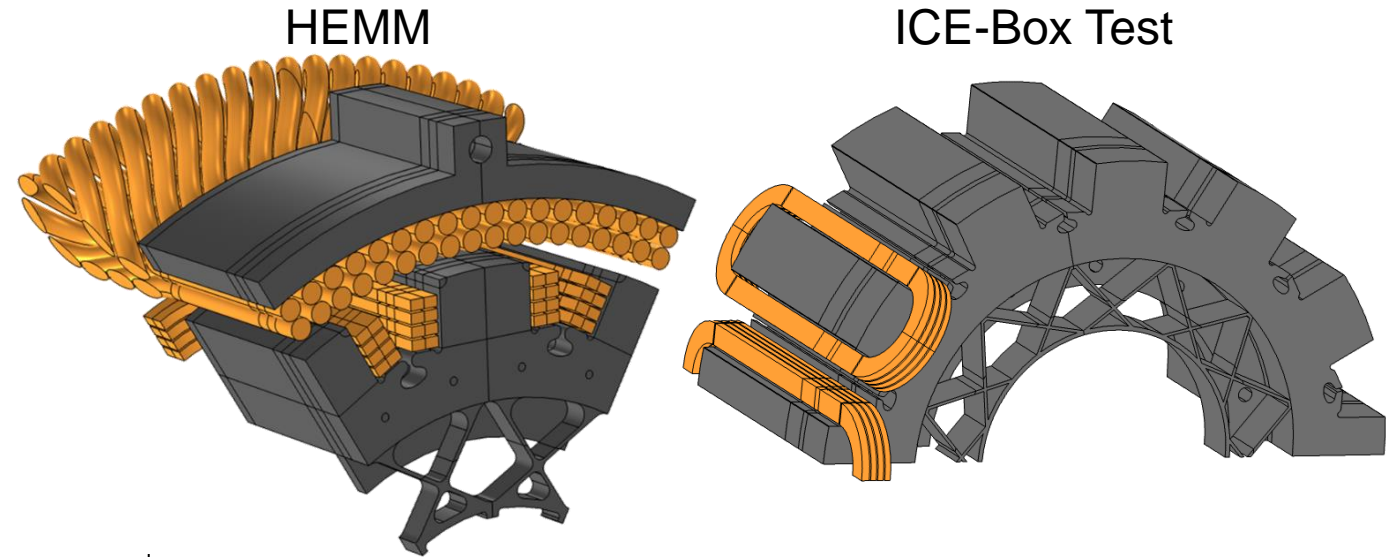
Predicted coil temperatures

	ICE-Box Test	HEMM
Maximum	55.9 K	57.4 K
Average	55.3 K	57.2 K

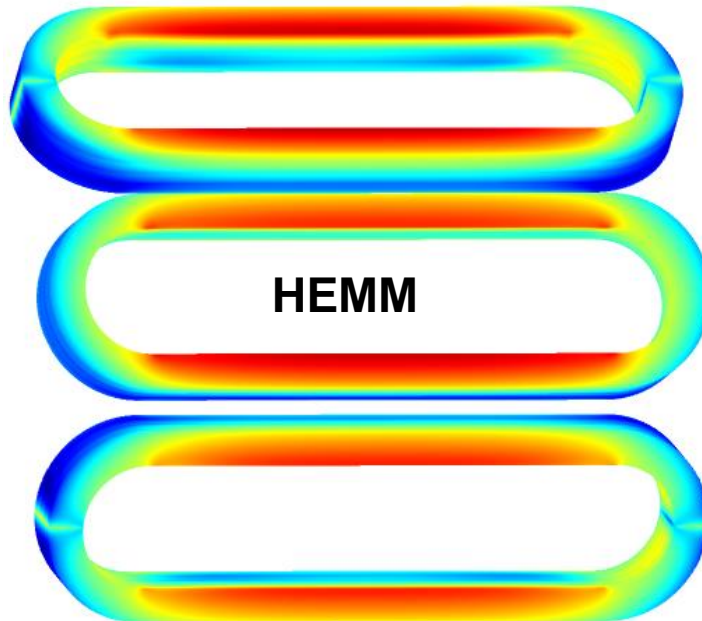
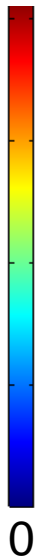


Simulated Electromagnetic Response

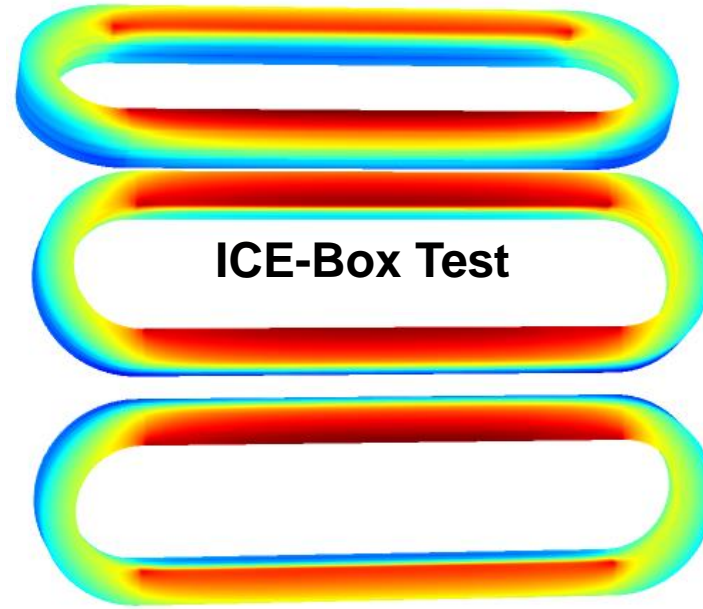
- Rotor current & # turns same in both models
- Nonlinearity considered
- Using HEMM design method, critical current in ICE-Box test 2.1 A less than in HEMM



$max(B)$



HEMM



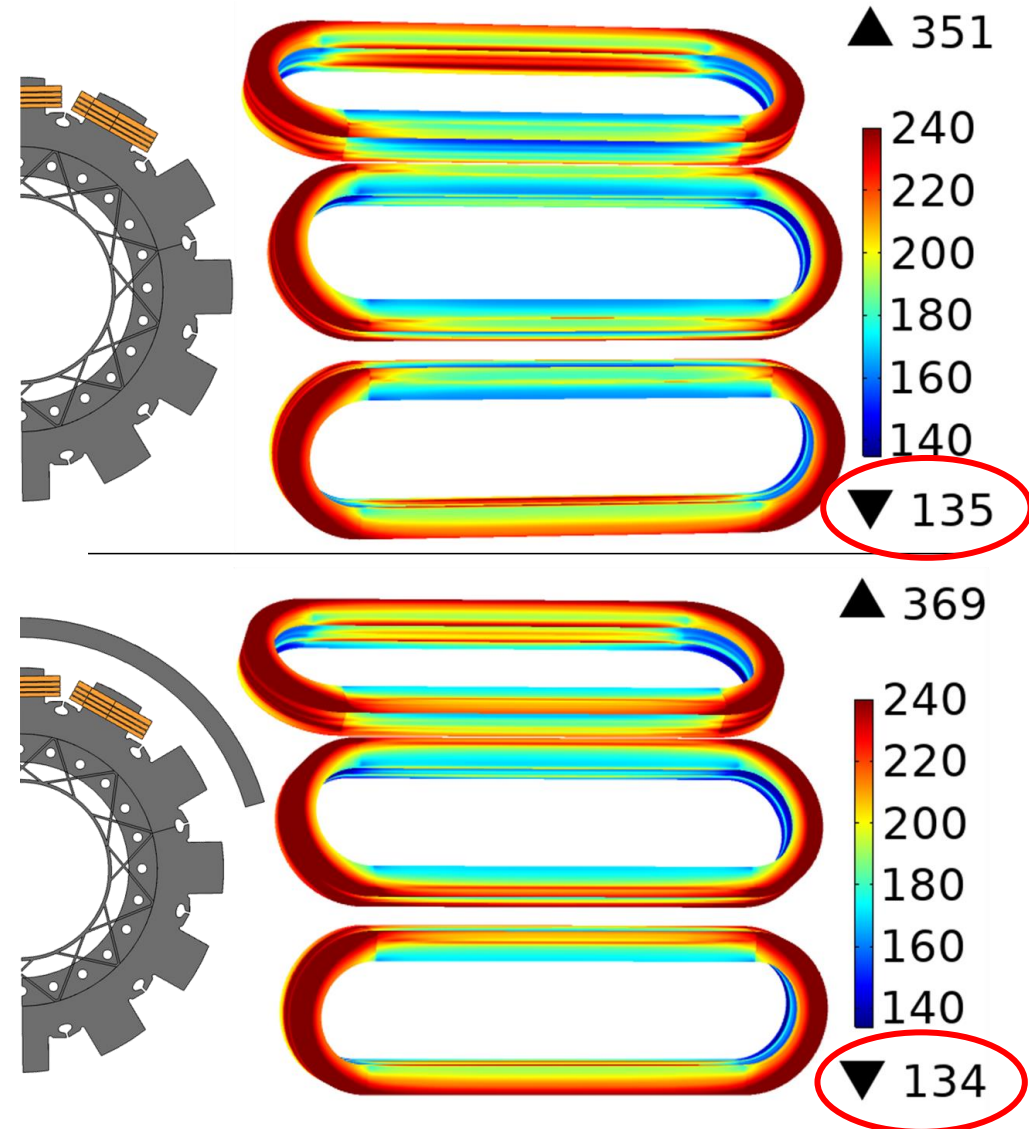
ICE-Box Test



Simulated Electromagnetic Response

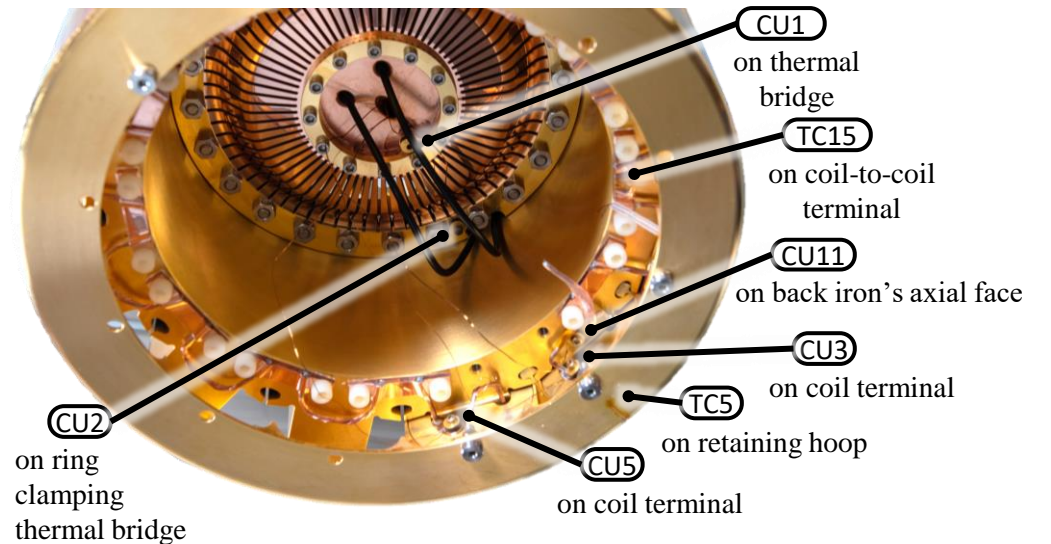
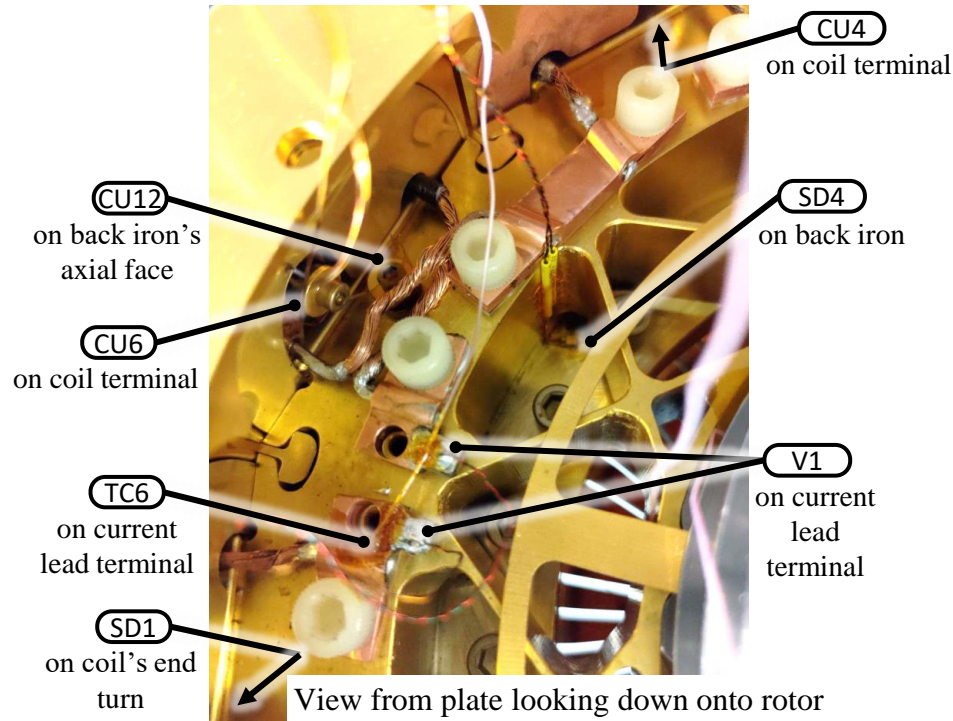
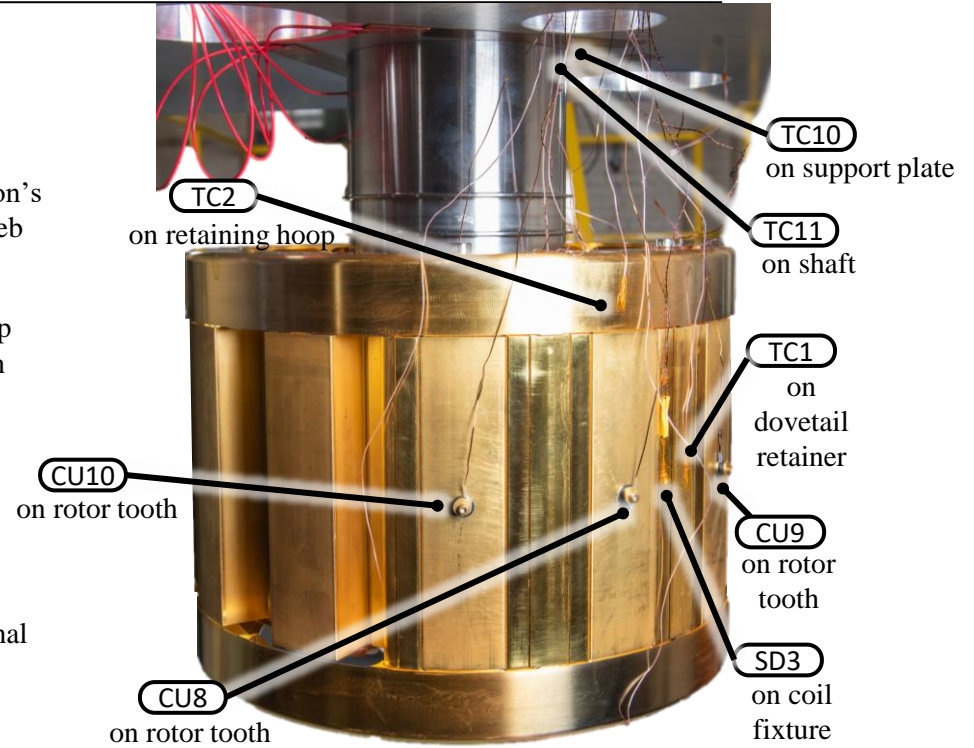
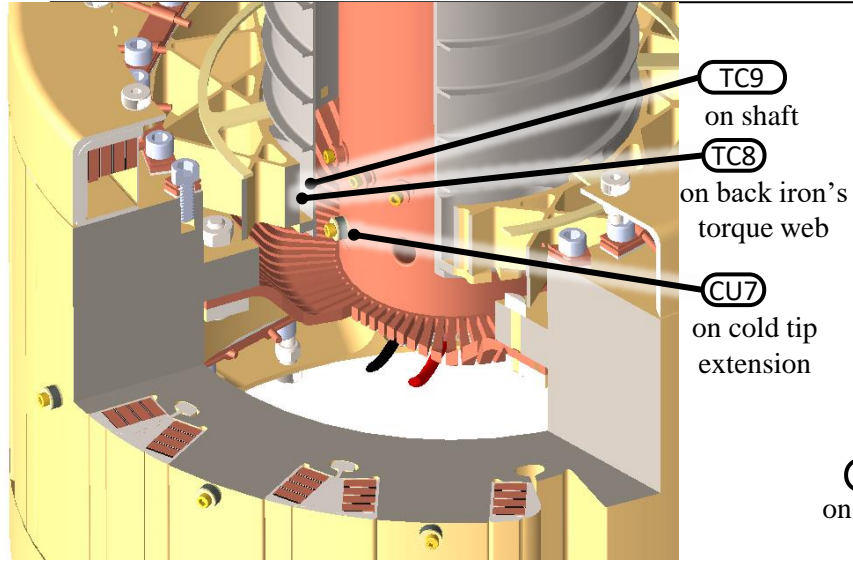
- Critical current calculation considers:
 - Temperature from previous slide
 - $I_c(77 K, s.f.)$ of conductor used to make each layer
- Stator back iron not added to experiment

Predicted critical current (I_c) distribution (units: A) with & without stator back iron





Instrumentation

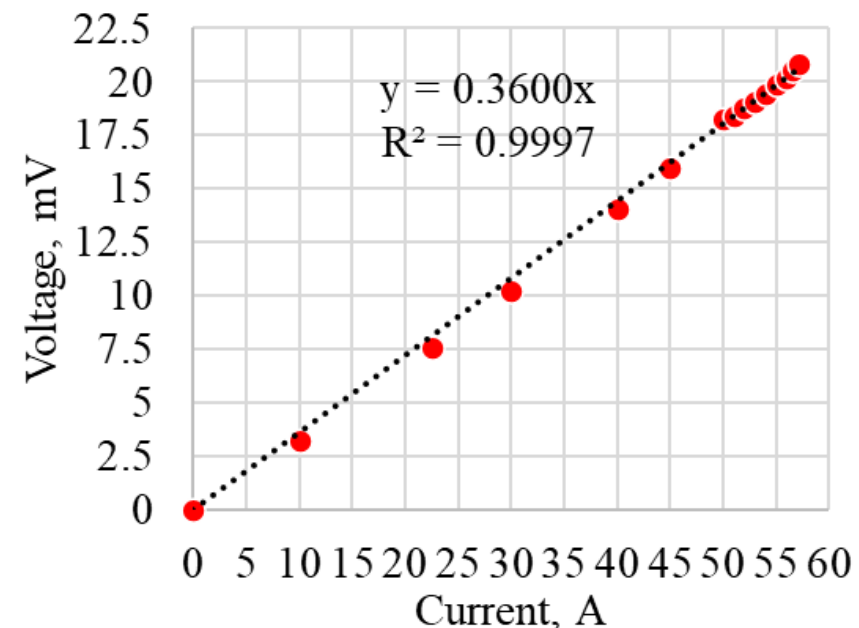
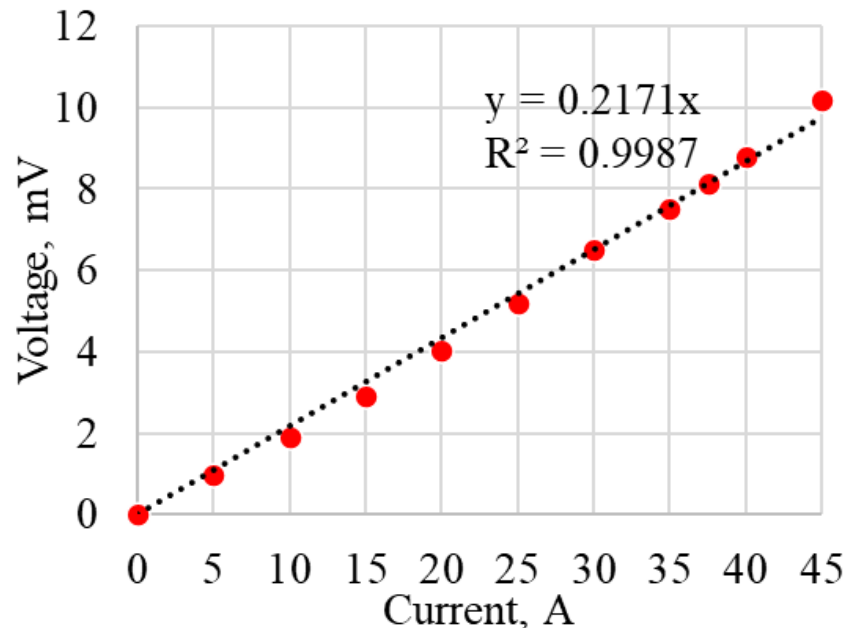




Experimental Results – Electrical

- Current very slowly ramped between set points (about 0.5-0.7 A/min) to minimize heating in coils
- Each data point taken after voltage and temperature exhibited little variation (typically 30-45 minutes)
- Highest temperature in coils controlled to 60.5 to 61.0 K
- ~7 mV voltage jump occurred during 1st attempt at constant 50 A as temperature increased to 61.2 K
- 2nd characterization shows higher resistance but stable at the design current while conductively cooled

Electrical characterization of the entire rotor before (left) & after (right) voltage jump

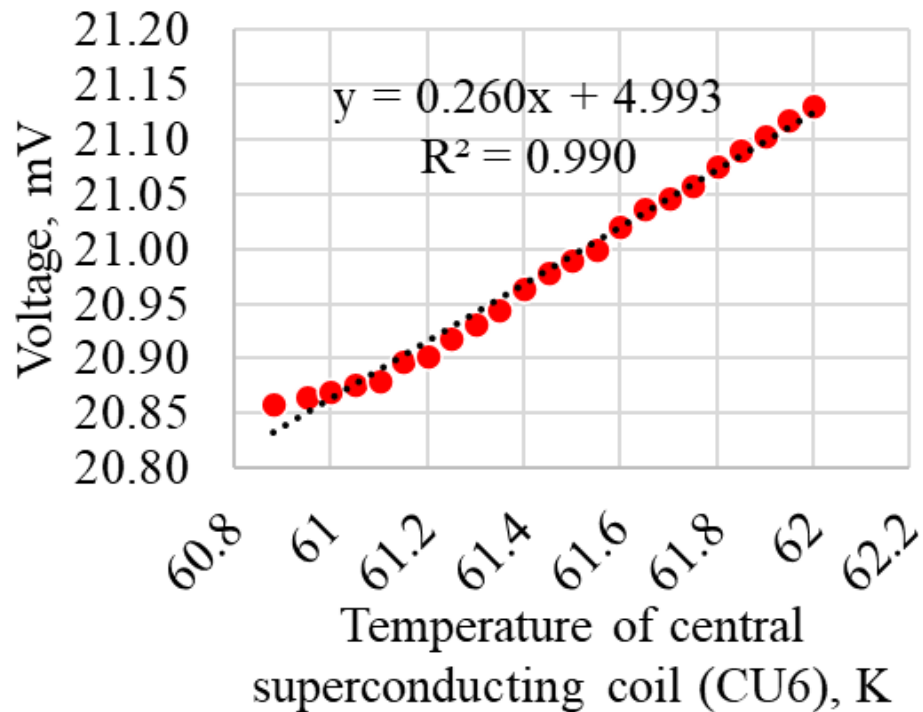




Experimental Results – Electrical

- After stably operating at 57.2 A and 60.9 K, current held fixed, and temperature slowly raised in increments to 62.0 K
- Linear response & increase in voltage (1.40%) suggest superconductivity maintained to 62.0 K (HEMM design limit)

Voltage across the superconducting rotor during a temperature excursion at 57.2 A

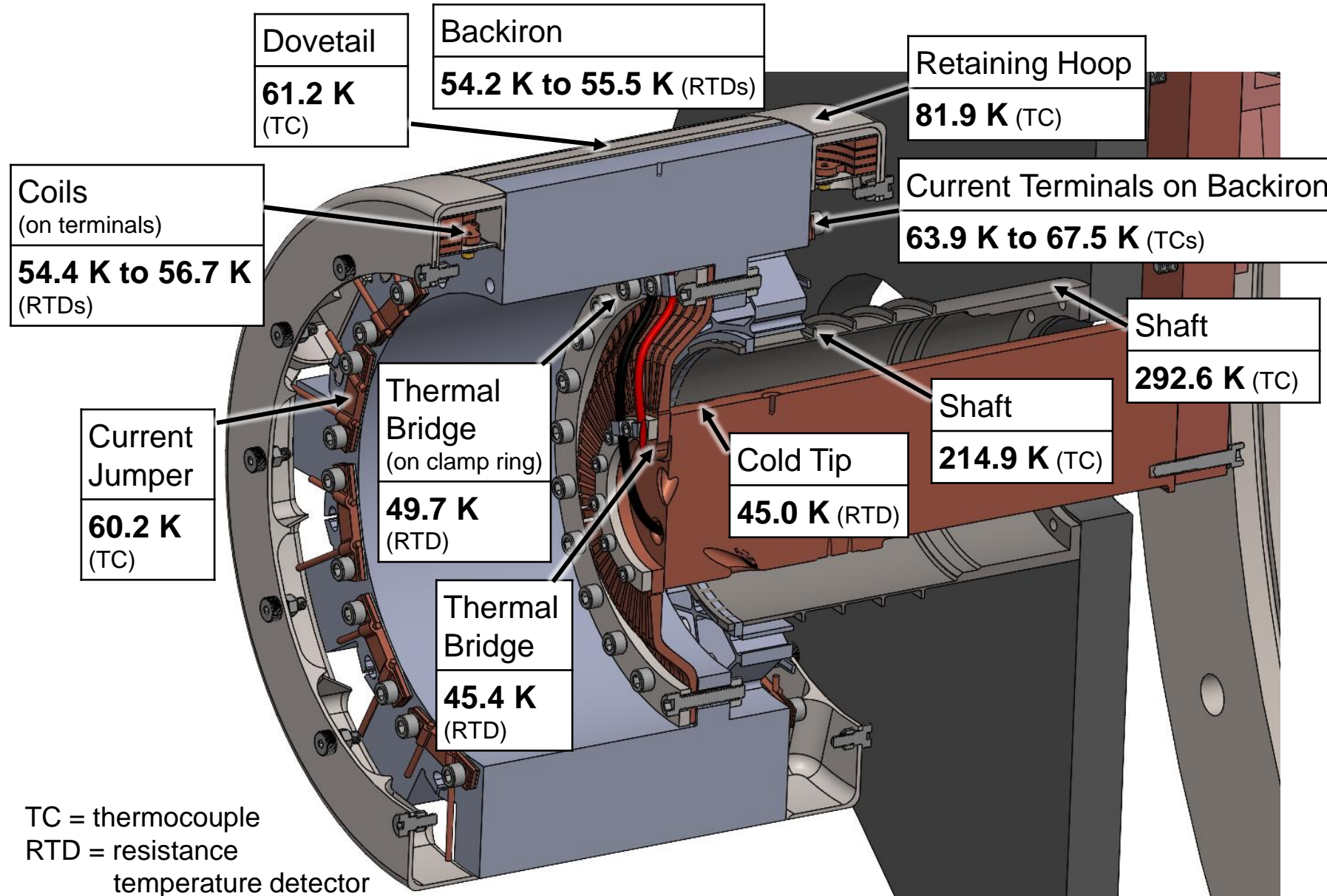


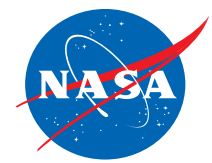
Predicted increase in resistance (thus voltage) per linear interpolation of cryogenic data

Material	Change in resistance (& voltage)
Cu (very high purity)	5.53%
OFHC copper (annealed)	3.88%
OFHC copper (60% cold work)	3.54%
Less pure Cu wire	< 3.5%



Steady-State Thermal Results – Test Point E





Steady-State Thermal Results

Notable temperature differences at each test point (location 1 minus location 2)

Location 1		Location 2		Test Point						Uncorrelated model (test point E)
				A	B	C	D	E	F	
Cold tip at cold tip/bridge interface		ICE-Box cryocooler cold tip (facility)		12.77	8.77	10.79	10.12	11.01	11.72	–
Thermal bridge at cold tip/bridge interface		Cold tip at cold tip/bridge interface		0.43	0.36	0.41	0.38	0.41	0.45	0.06
Thermal bridge (clamp ring) at bridge/backiron interface		Thermal bridge at cold tip/bridge interface		4.54	4.44	4.28	3.93	4.29	4.53	1.36
Large support plate, near heater		Shaft near interface with Al support plate		65.58	-15.85	-14.79	-17.02	-16.04	59.53	6.54
Shaft near interface with Al support plate		Shaft at shaft/backiron interface		173.18	151.18	86.28	78.79	77.71	60.62	202 (A-B config.) 167 (C-F config.)
Shaft at shaft/backiron interface		Backiron at shaft/backiron interface		26.09	22.04	33.66	4.22	2.44	4.47	3.96
Backiron at shaft/backiron interface				37.60	86.47	118.63	155.97	158.22	176.16	16.80
Current lead	terminal A	Backiron axial face, coil C	shaft end	33.63	45.54	8.56	8.80	9.61	13.33	0.23
	terminal B		free end	–	–	10.53	12.42	13.31	15.12	0.27
Coil-to-coil terminal, coil L, free end				9.52	22.28	4.53	5.06	4.73	4.84	-0.07
Coil terminal	coil C	free end		1.36	1.11	1.13	1.18	1.22	1.29	0.46
			coil C	1.78	1.71	1.74	1.74	1.75	1.87	0.62
	coil L	shaft end	Backiron pole OD	0.32	-0.50	-0.16	-0.15	-0.25	0.39	0.46
	coil R	free end	coil L	1.20	1.17	1.14	1.17	1.08	1.23	0.45
			coil R							
	coil C	free end		12.01	13.71	11.60	10.90	11.69	12.30	3.42
	coil L	shaft end	Cold tip at cold tip/bridge interface	10.31	11.12	9.48	8.97	9.39	10.73	3.36
	coil R	free end		11.71	13.80	11.62	10.63	11.33	11.90	3.39
	coil C	free end		7.03	8.91	6.90	6.59	6.99	7.32	2.00
	coil L	shaft end	Thermal bridge (clamp ring) at bridge/backiron interface	5.34	6.32	4.78	4.65	4.69	5.75	1.94
coil R	free end		6.73	9.00	6.92	6.32	6.63	6.92	1.97	



Predicted Performance of HEMM's Cryocooler

