



Machine Learning Platform: Deploying and Managing Models in the CERN Control System

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01/07/2022 – BE Seminar

Summary

- **System overview**
 - Motivation
 - Objectives
 - Workflow
 - Continuous retraining
- **Standalone deployment prototype**
- **MLP in practice**



ML for accelerator controls - motivation

- **Some accelerators / processes difficult to model with means available in CCC
-> no online analytical model available**
 - Space charge dominated dynamics in LINACs
 - Transmission optimization during transition crossing
 - Collimator alignment, septa with many degrees of freedom
 - Multi-turn injection with accumulated intensity diagnostics only
- **Usually solved by trial & error, (semi-)manual scans**
 - Time consuming
 - Depends on experience of operator
- **ML techniques outperform previous techniques and open new doors to automation**
- **But the approach today is ad hoc and heterogeneous**



Finding a compromise

Volatile world of ML

- **Code needs to run once**
- **Bleeding edge technology**
- **Used to own tools and comfort, cloud services**
- **Maintainability is not always the main concern**

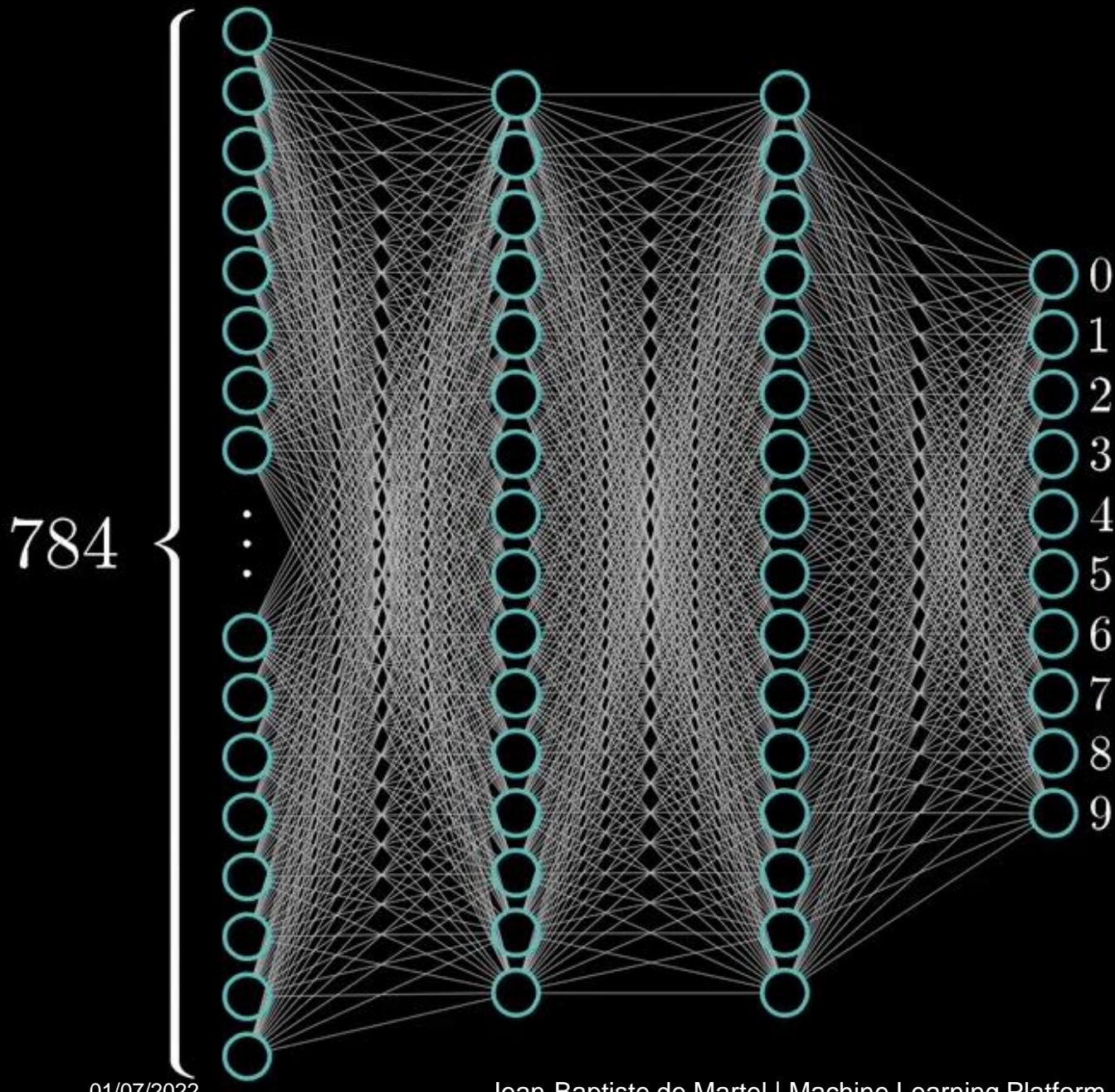
Reliable world of accelerator controls

- **Need to run reliably 24/7/365: need reproducibility, robustness, traceability**
- **Use highly reliable, battle-tested tools**
- **Constraints of the technical network: no internet access, restricted tooling, security precautions**
- **Standardize and unify to minimize maintenance**



Objectives

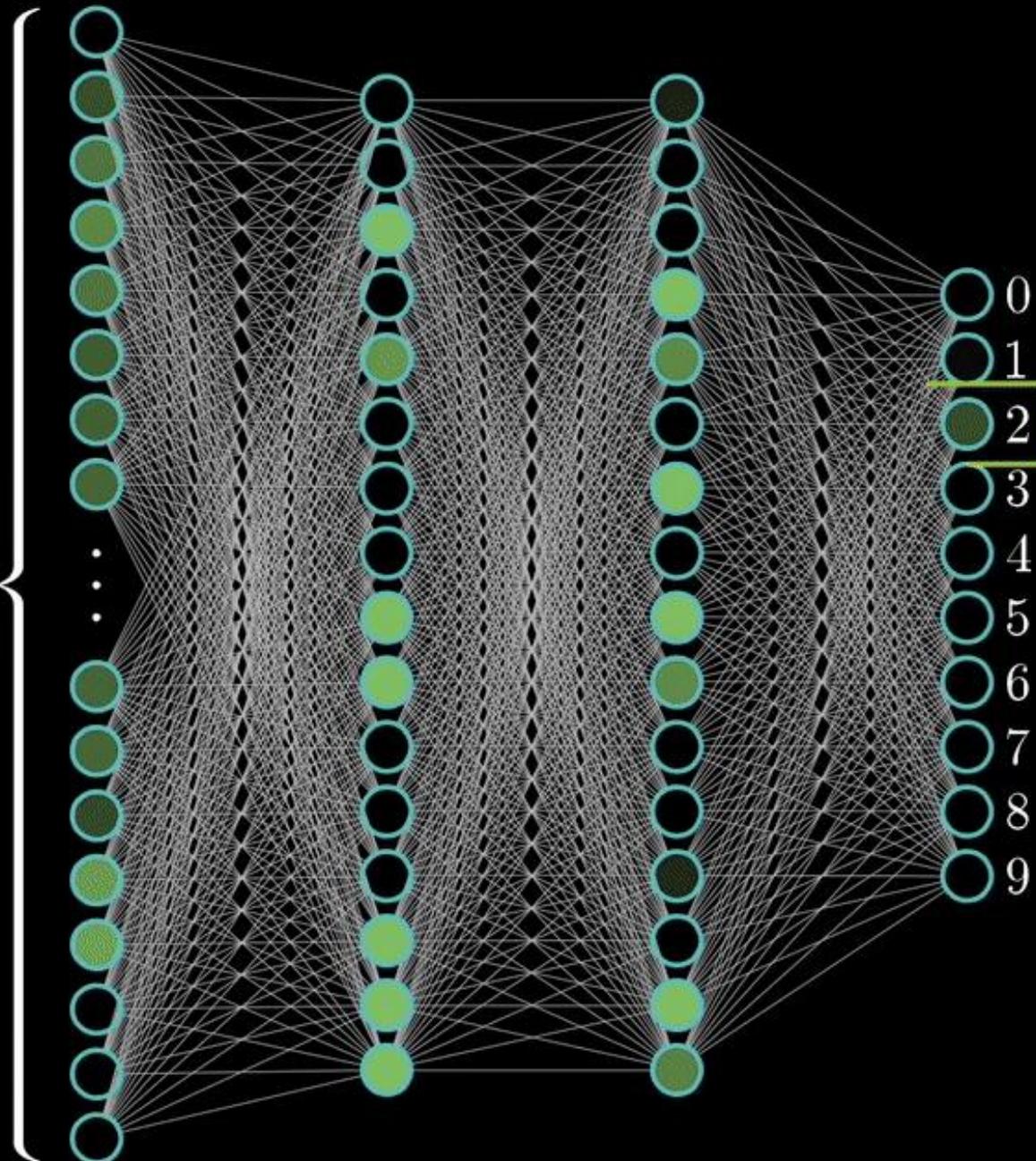
- **Provide a common approach to storage, versioning, deployment and usage of models**
- **Accelerate and simplify the model lifecycle by abstracting infrastructural concerns**
- **Fulfill the specific needs of the accelerator control system**
 - Reliability
 - Traceability
 - Security
 - Standardization
- **Stay out of the user's way**
 - Minimize constraints on model developer's workflow
 - Avoid constraints on choice of tools





Model type:
Layout/architecture
of the neural
network –
i.e., number of
neurons, how they
are connected,
etc...

784



Model parameters:
“Trained weights”
- values assigned
to the neurons and
connections after
training

Model:
Combination of a
model type and
model parameters

ARTIFICIAL INTELLIGENCE

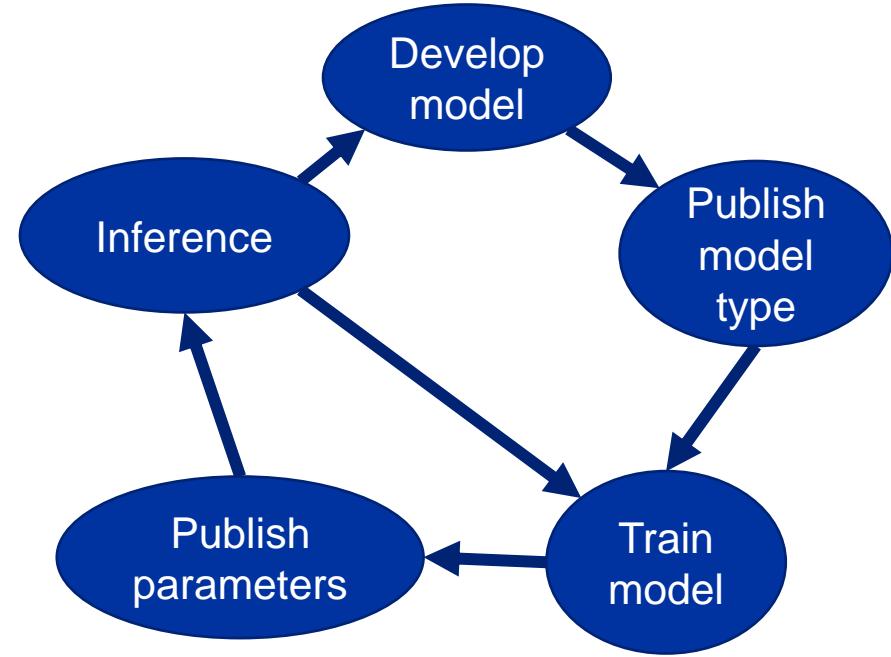
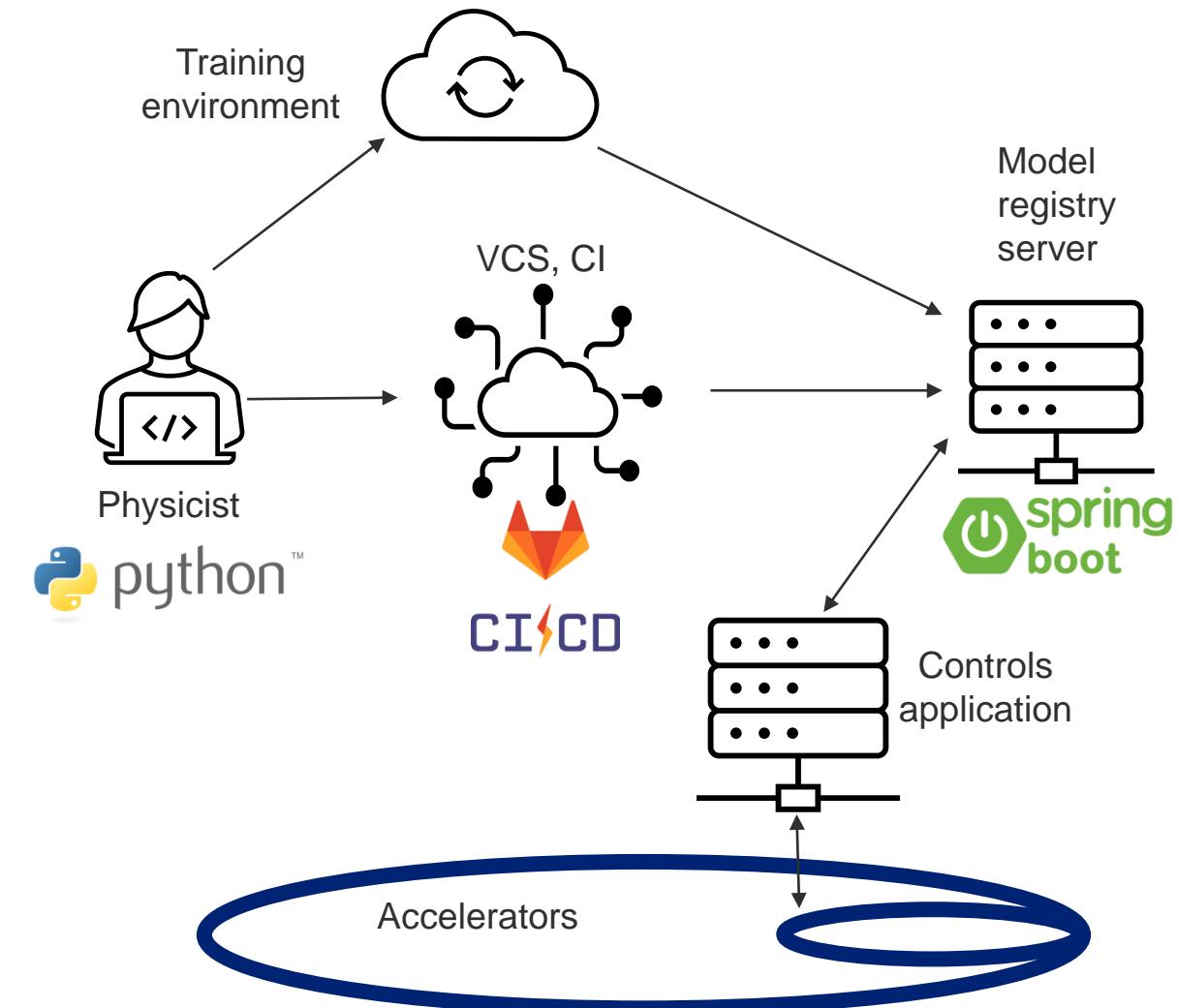
MACHINE LEARNING

dozens of
different ML
methods

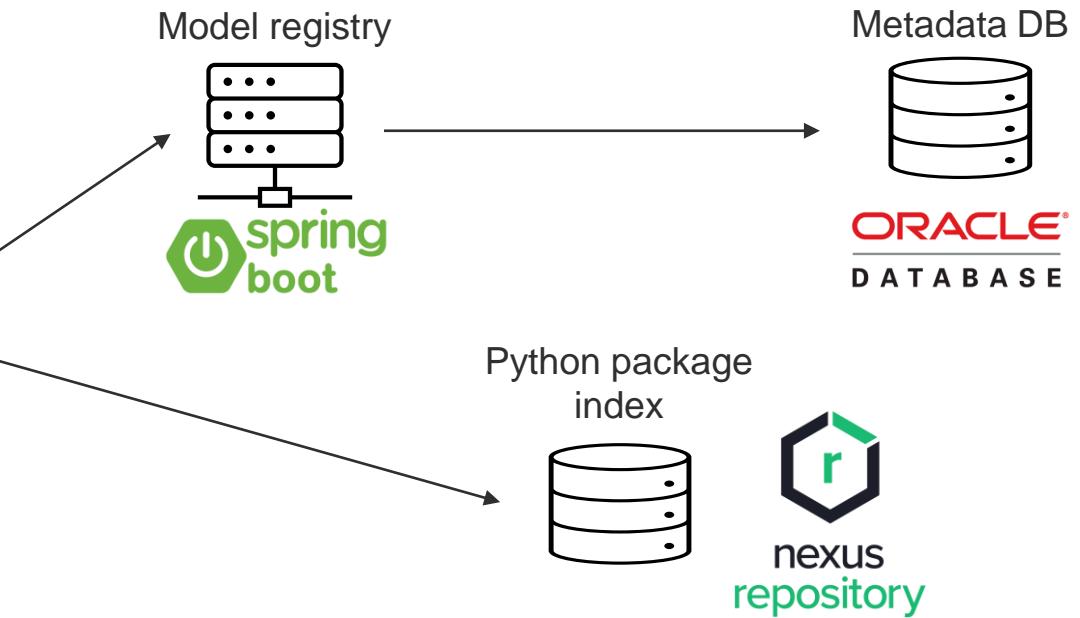
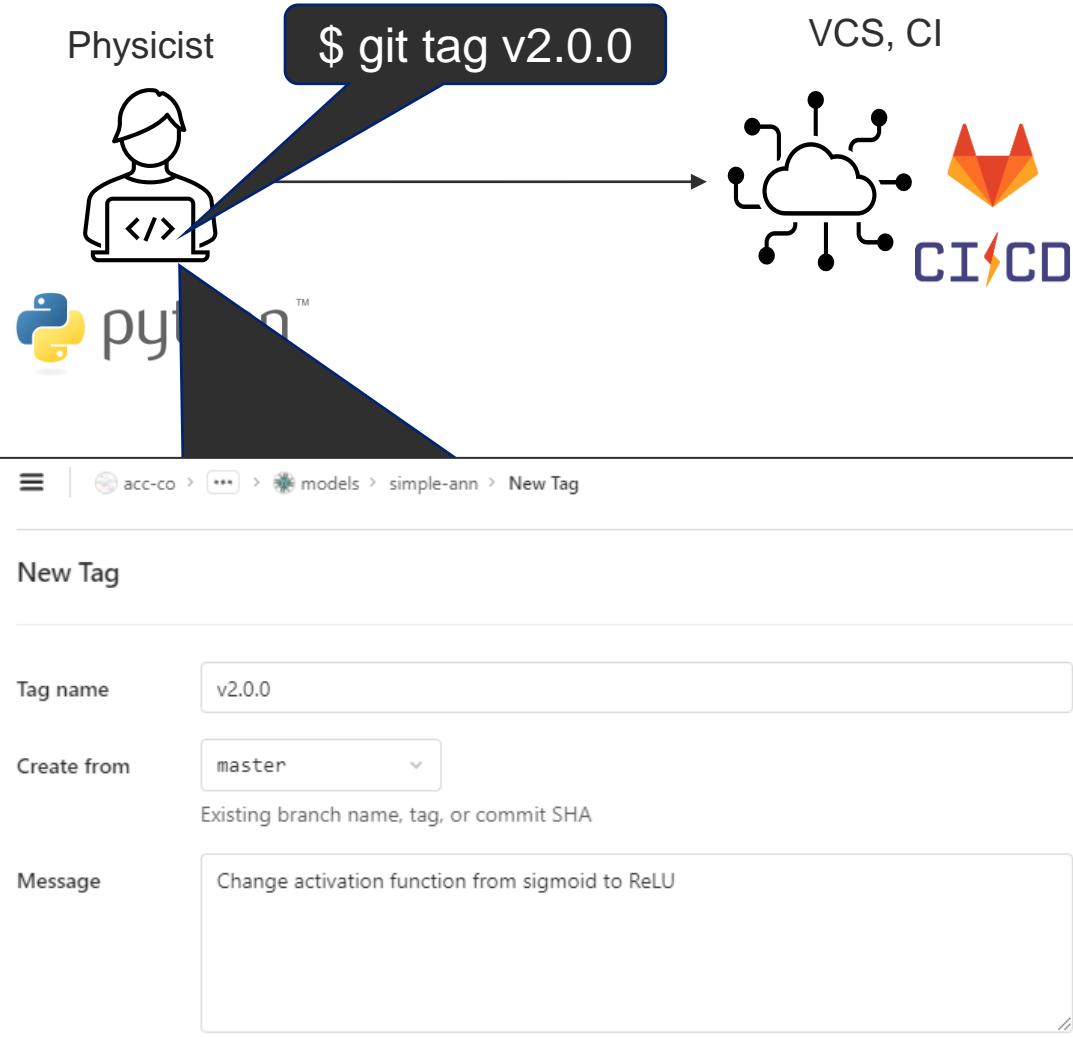
NEURAL NETS

DEEP
LEARNING

Development workflow



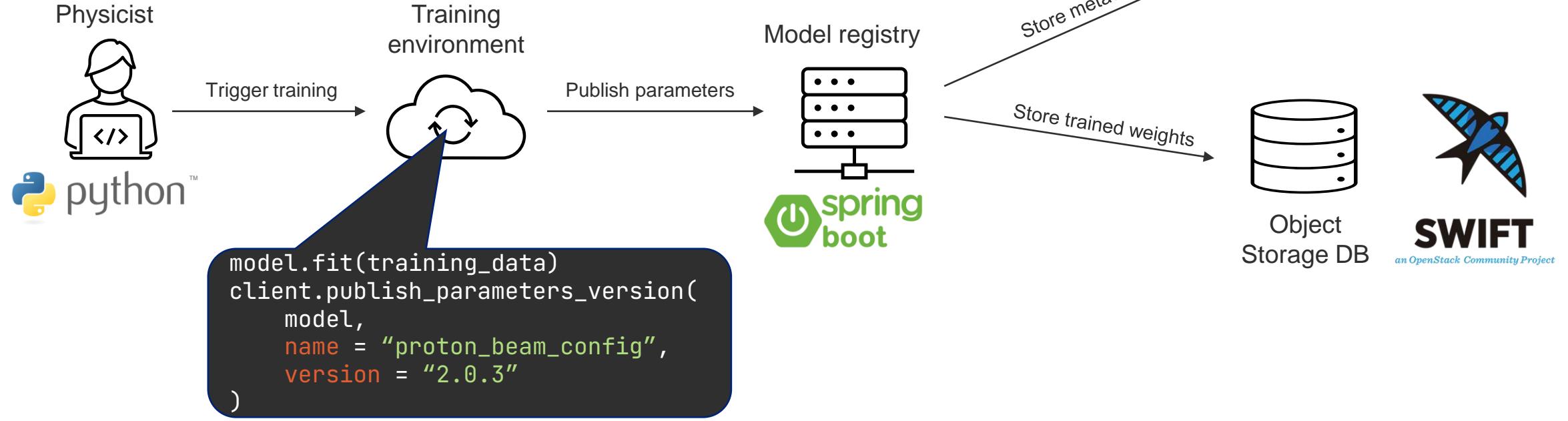
Publishing model types



Advantages

- **Access control and traceability for model types**
- **Quick & easy, no need to learn new tools, complexity is hidden**

Publishing model parameters



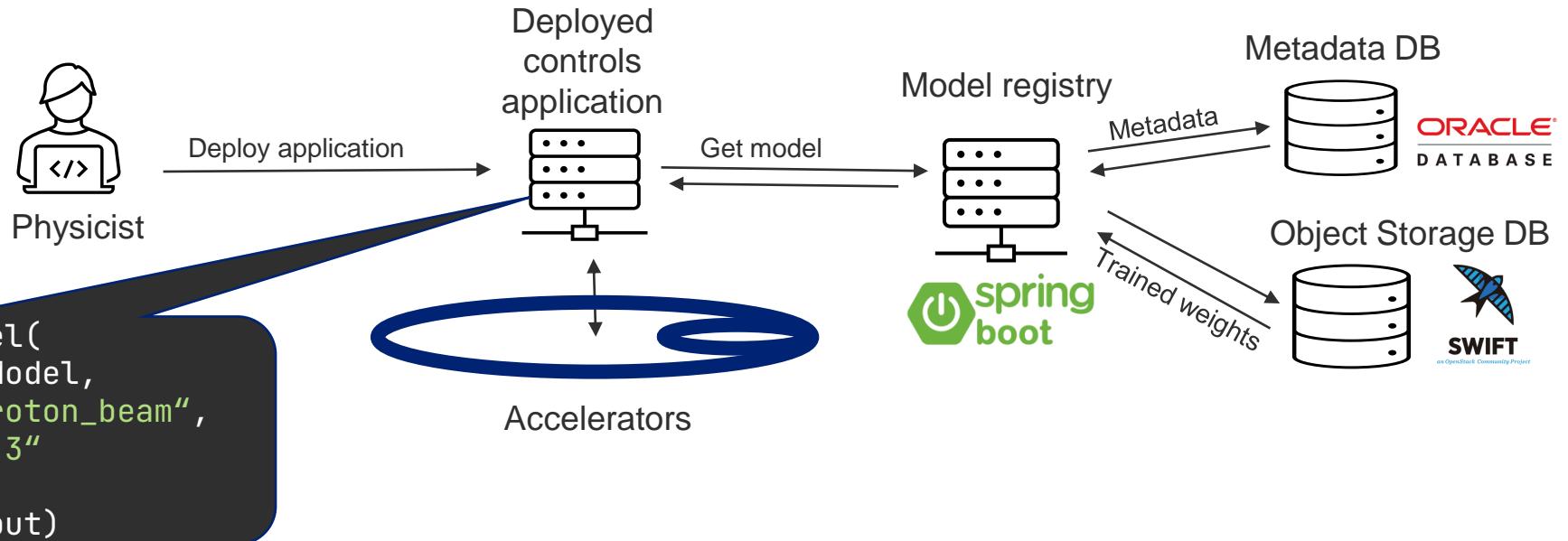
Usage

- Choose parameters name and version
- Use the client library to publish

Advantages

- All parameters stored centrally and reliably
- Compatibility is fully managed

Inference



Usage

- Use the MLP client library to instantiate the model
- Provide model type, parameters name and version

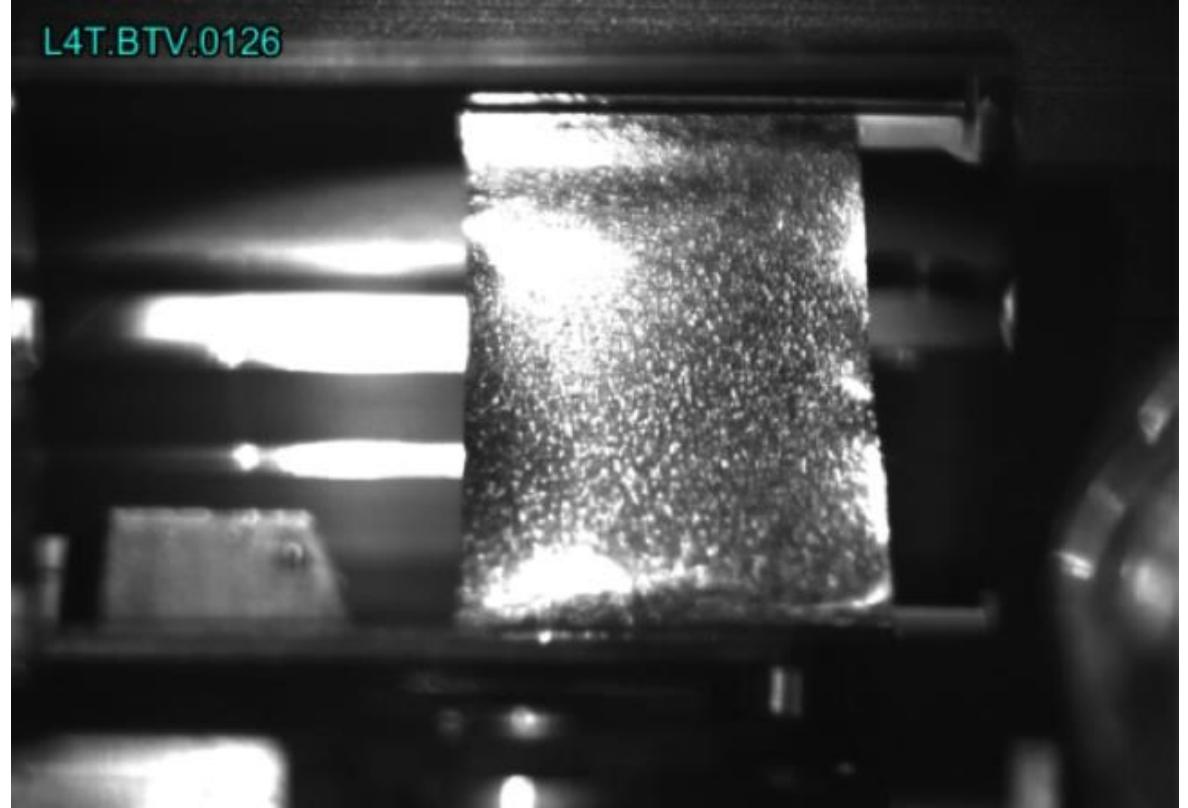
Advantages

- Parameters retrieved and loaded transparently
- Parameter traceability

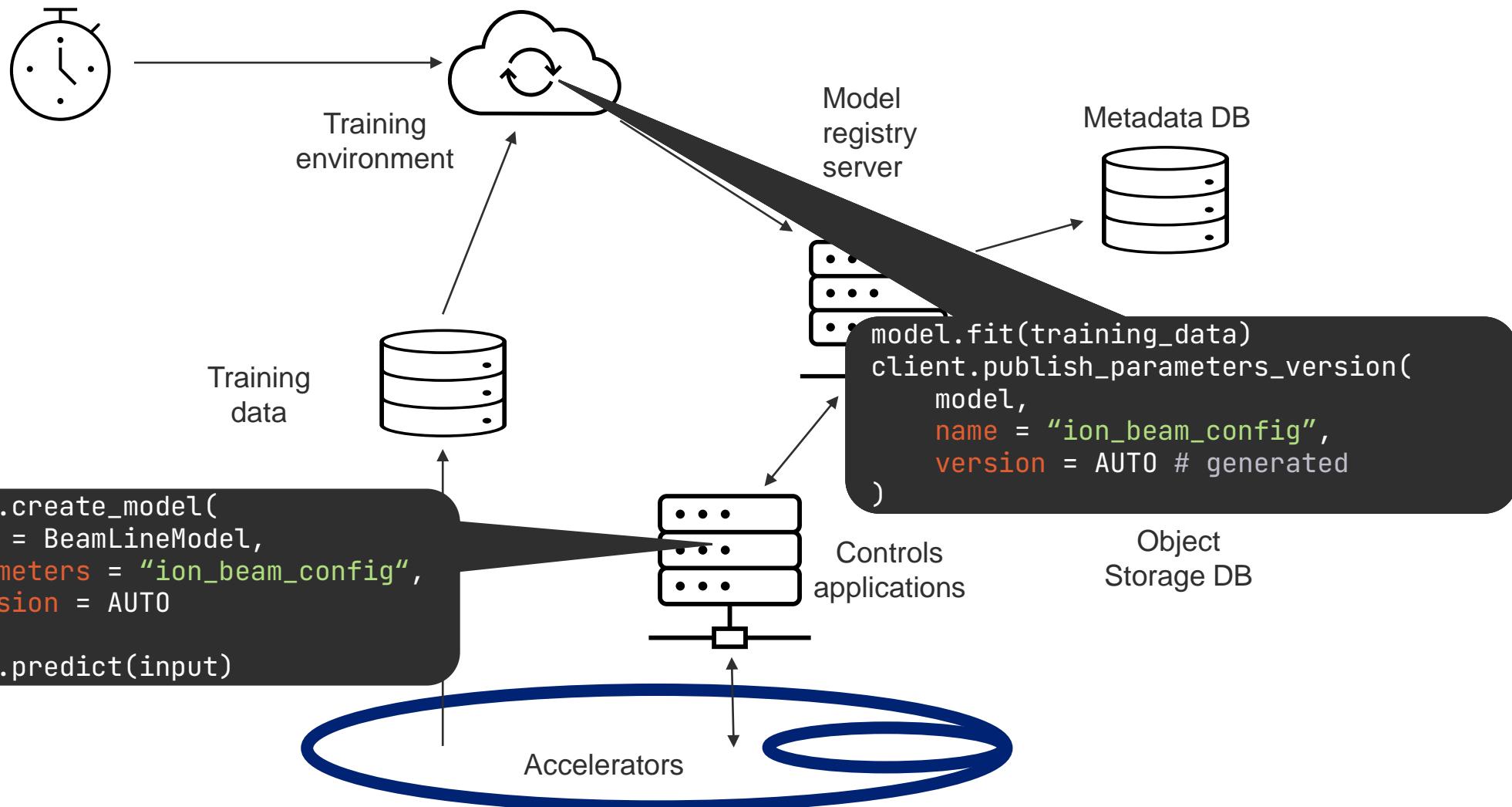
Continuous retraining - motivation

Example: stripper foil degradation

- The stripper foil is an essential component of our linacs
 - It degrades over time and is replaced regularly
 - Beam characteristics vary
 - Machine parameters need to adapt
- > need to re-train model continuously to keep it up to date



Continuous retraining - implementation



Standalone deployment prototype

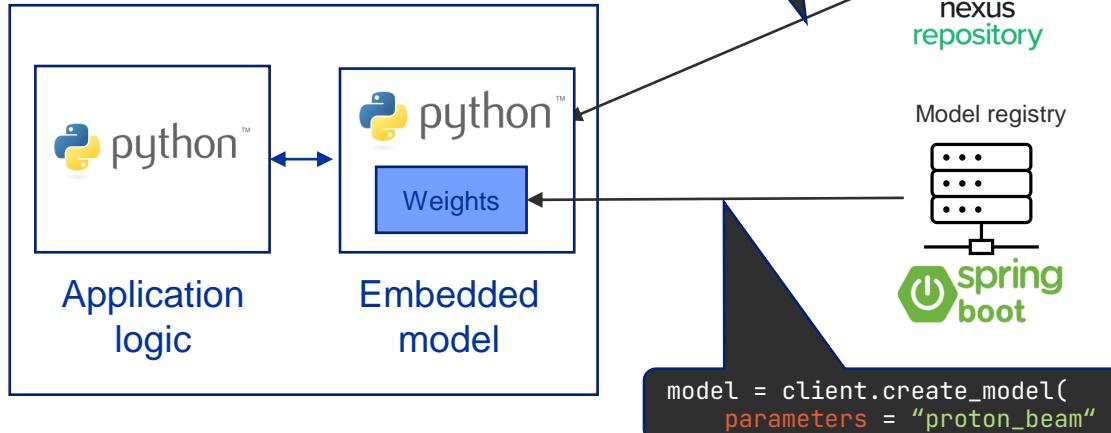
Calling models remotely from any language



Inference - Embedded vs standalone

Embedded

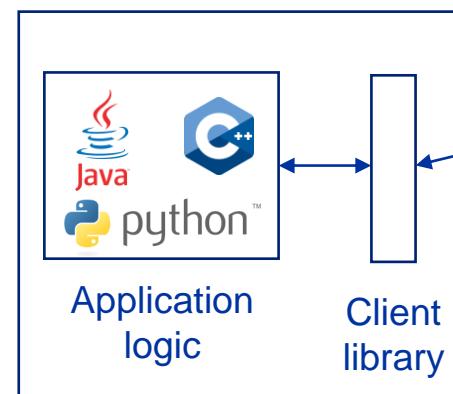
Controls application



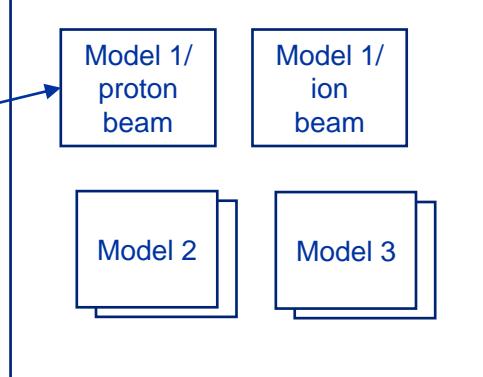
- **Python only**
- **Model type must be installed**
- **Parameters retrieved then stored locally**

Standalone

Controls application

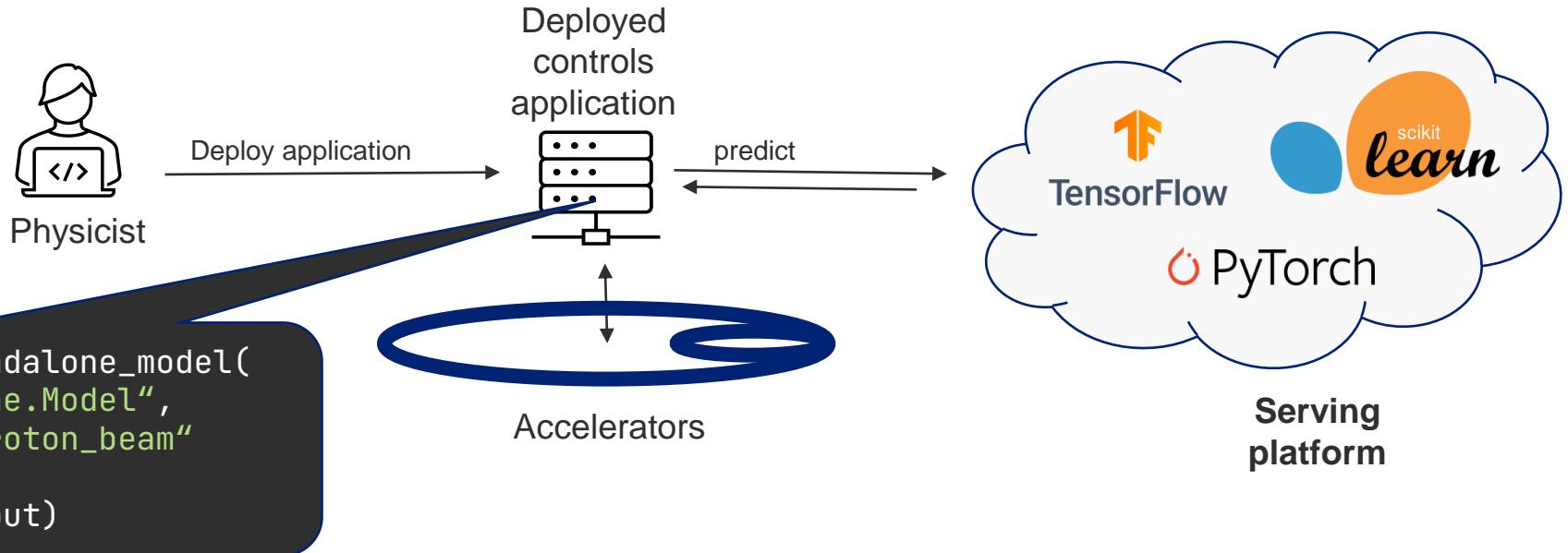


Standalone serving cluster



- **Language-agnostic approach**
- **No local model installation needed**
- **Everything happens remotely**

Inference (Standalone)



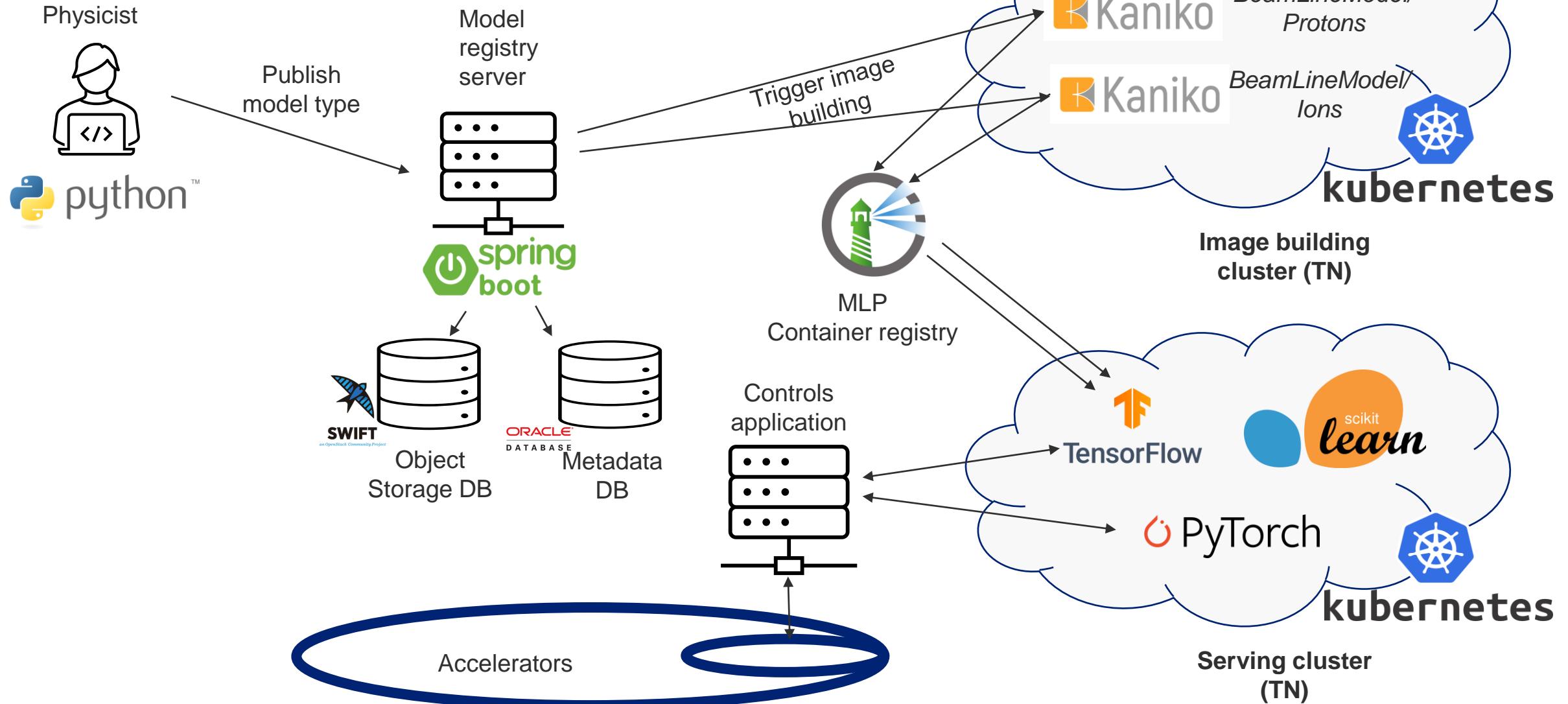
Usage

- Use the MLP client library to instantiate the model
- Provide model type and parameters name

Advantages

- Call models from any language
- Seamless model updates

Behind the scenes



MLP in practice



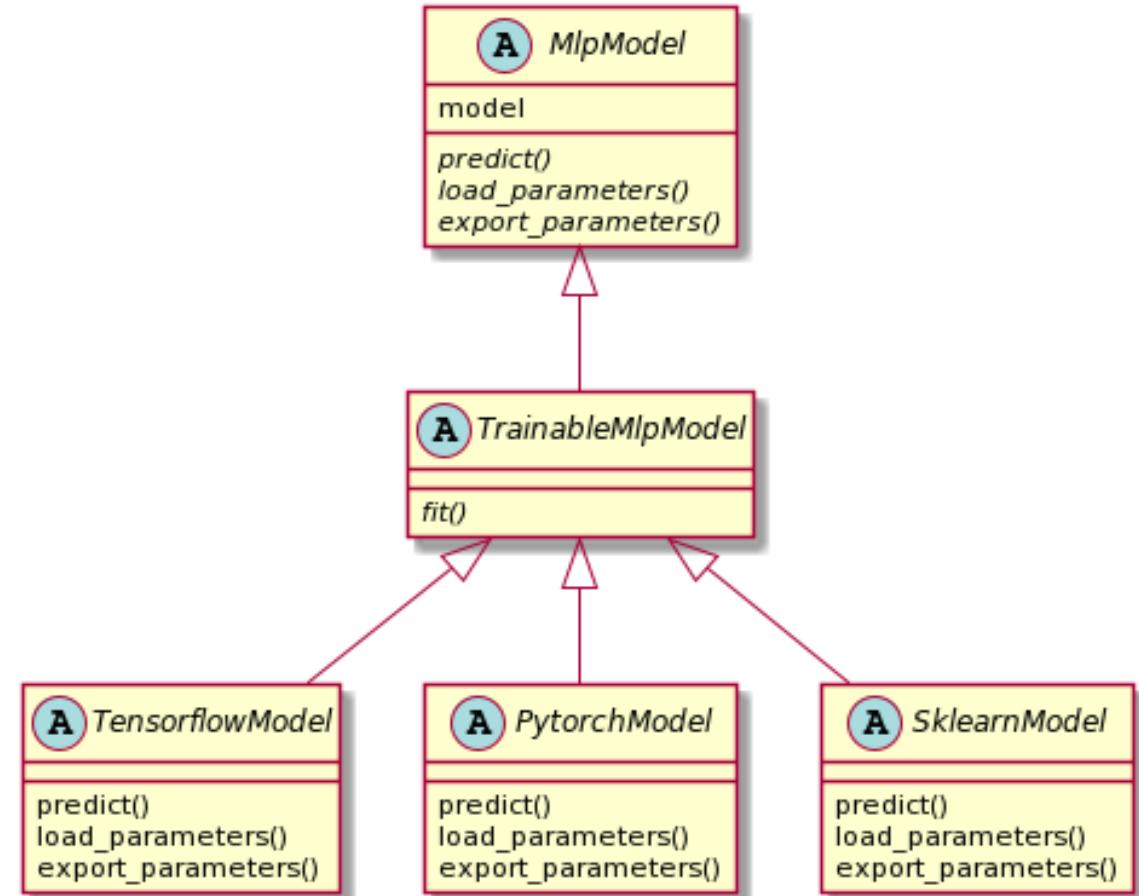
MLP in Practice

- **Adapting a model**
 - Implementing the model interface
 - Model declaration
 - CI template
- **Using a model**
 - Publishing trained parameters
 - Loading parameters
 - Standalone prediction

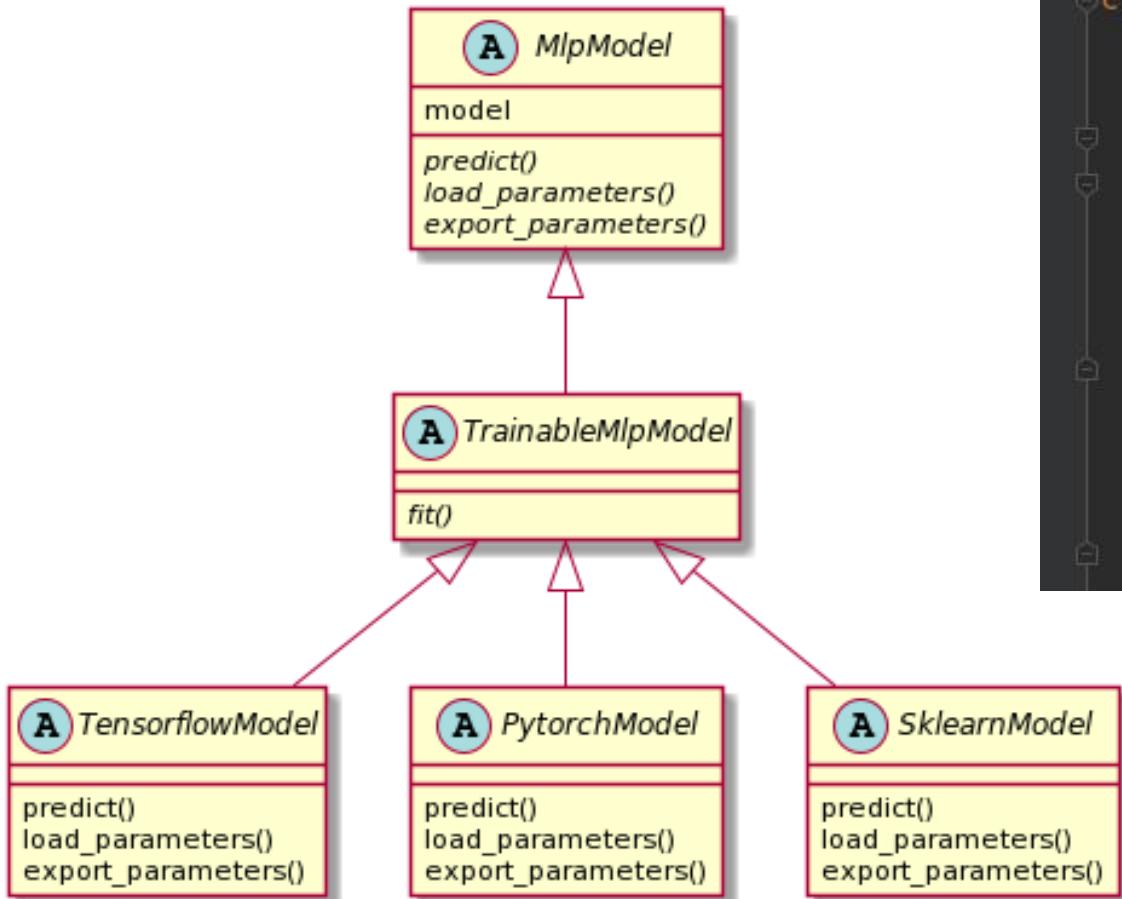


MLP in practice: Implementing a model

- We define a common API for all controls models
 - shared abstraction layer
- Interface defines 4 methods:
 - *Fit* – train the model on the provided data
 - *Export parameters* – extract current values of all model parameters
 - *Load parameters* – configure the model using the provided parameters
 - *Predict* – return a prediction from the input data
- Default extensible implementations for common frameworks



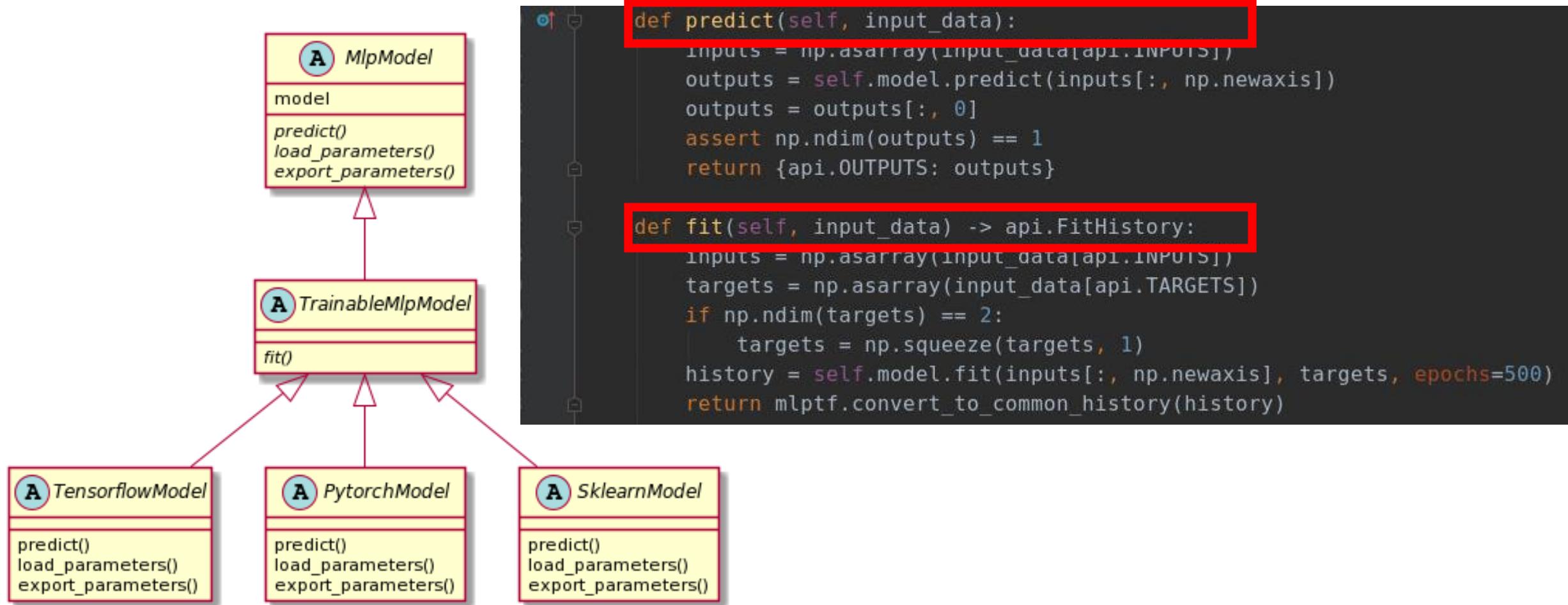
MLP in practice: Implementing a model



```
class Model(mlptf.TensorFlowModel):
    """ANN that fits a sine function."""

    def __init__(self):
        model: tf.keras.Model = tf.keras.models.Sequential([
            tf.keras.layers.Dense(16, activation="relu"),
            tf.keras.layers.Dense(16, activation="relu"),
            tf.keras.layers.Dense(1)
        ])
        model.compile(loss='mean_squared_error',
                      optimizer=tf.keras.optimizers.Adam(0.01))
        model.build(input_shape=self.input_shape)
        super().__init__(model)
```

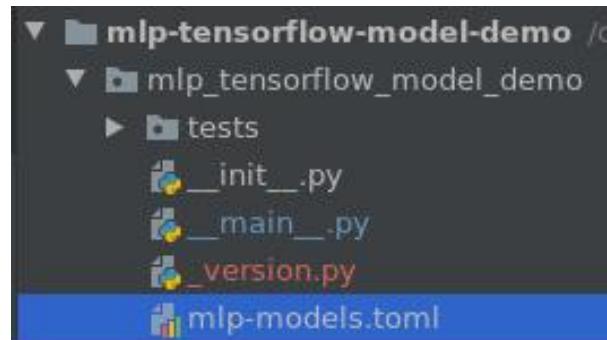
MLP in practice: Implementing a model



MLP in practice: Implementing a model

Model declaration

- *mlp-models.toml*



```
mlp-tensorflow-model-demo
  mlp_tensorflow_model_demo
    tests
    __init__.py
    __main__.py
    __version__.py
  mlp-models.toml
```

```
[[model]]
name = "mlp_tensorflow_model_demo:Model"
standalone = false

[[model]]
name = "mlp_tensorflow_model_demo:SecondModel"
standalone = false
```

CI configuration

- *gitlab-ci.yml*

```
include:
  - project: acc-co/machine-learning-platform/mlp-ci
    file: pipeline-templates/mlp-model-gitlab-ci-template.yml

variables:
  project_name: mlp tensorflow model demo

#
# --- Custom CI jobs ---
#
# Full installation, tested with pytest.
test_install:
  extends: .acc_py_full_test

# Development installation, tested with pytest.
test_dev:
  extends: .acc_py_dev_test
```

MLP in practice: Using a model

Publish trained parameters

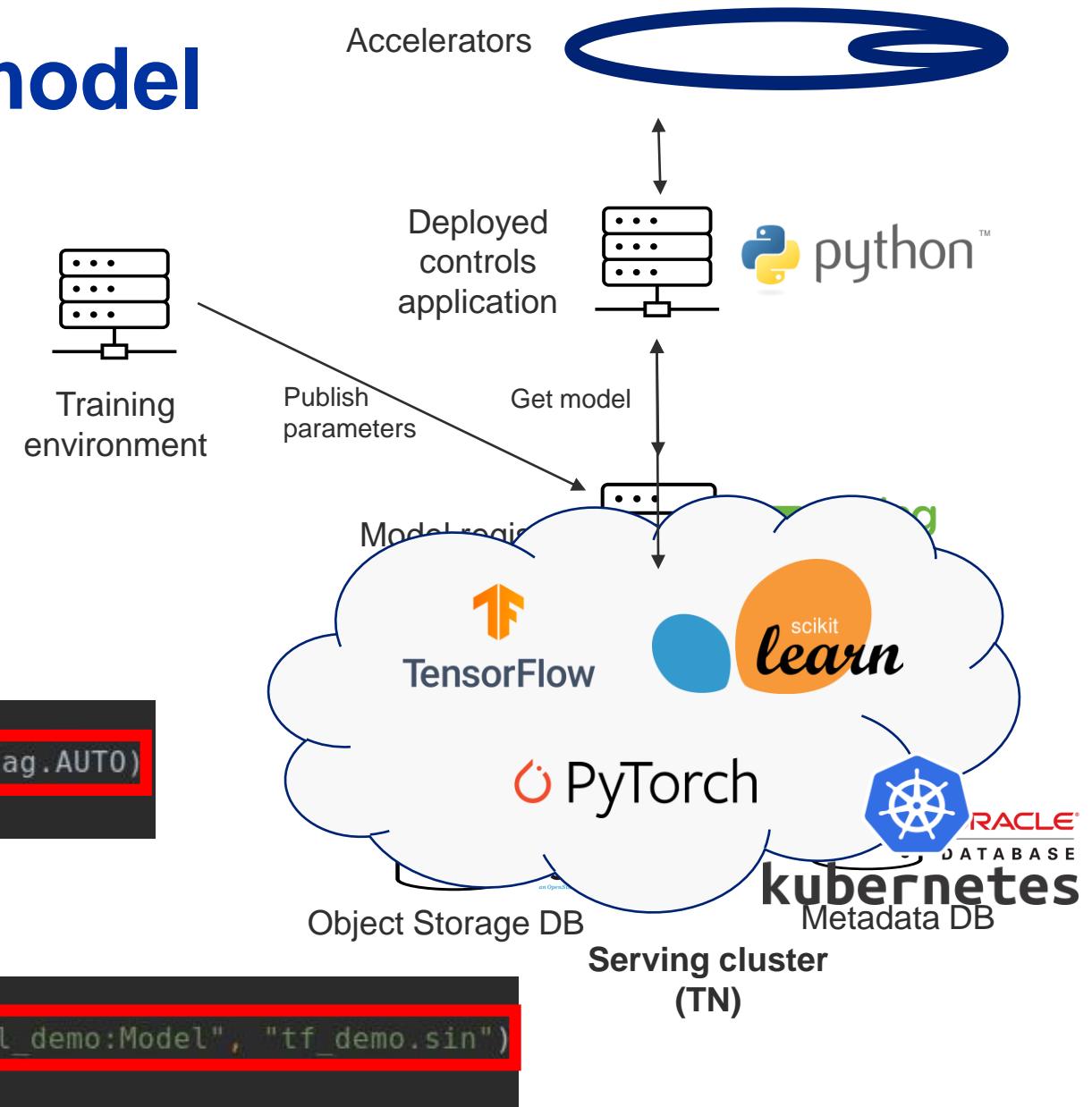
```
model = Model()  
history = model.fit(dict(inputs=inputs, targets=targets))  
  
client = Client(Profile.DEV)  
mpv = client.publish_model_parameters_version(  
    model, name="tf_demo.tanh", version=AUTO)
```

Load remote parameters

```
client = Client(Profile.DEV)  
model = client.create_model(Model, "tf_demo.sin", VersionFlag.AUTO)  
preds = model.predict(dict(inputs=inputs))["outputs"]
```

Call standalone model (prototype)

```
client = Client(Profile.DEV)  
model = client.create_standalone_model("mlp_tensorflow_model_demo:Model", "tf_demo.sin")  
preds = model.predict(dict(inputs=inputs))["outputs"]
```

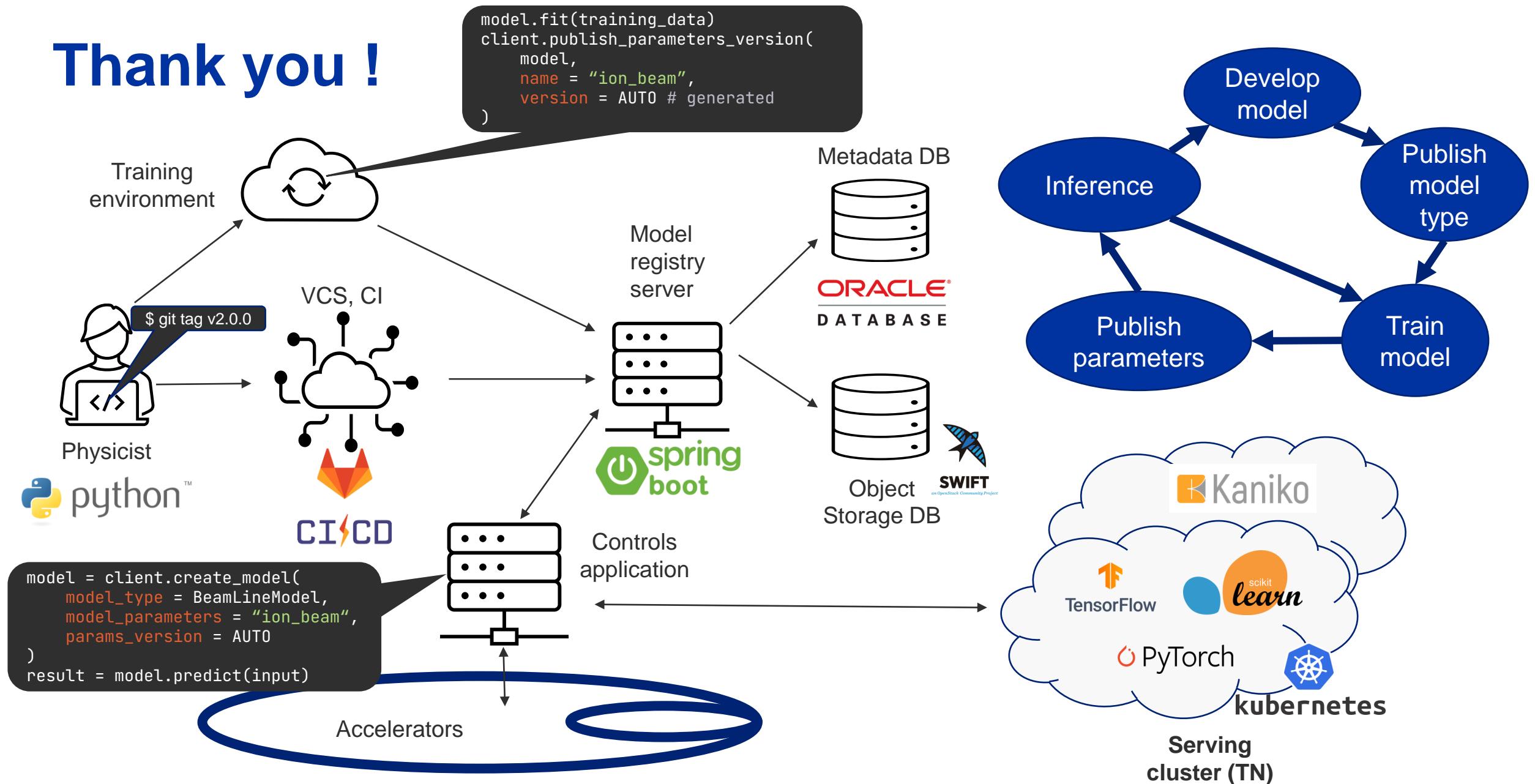


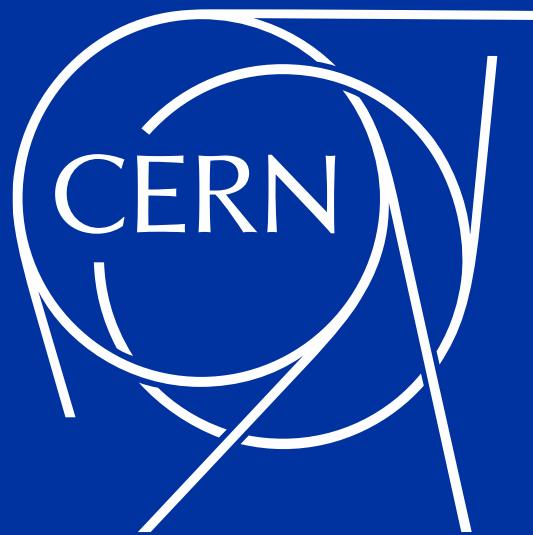
Conclusion

- We want to help physicists develop models faster and unburden them from infrastructural concerns while minimizing constraints
- We also want to apply software engineering best practices to ensure reliability and maintainability of the control system
- MLP provides a basis to achieve these goals and is ready for production (standalone deployment in beta)
- Could not cover everything, simplified a lot – please contact us offline!
 - [MLP Wikis](#) - [ICALEPCS paper](#) – machine-learning-platform-support@cern.ch
 - jean-baptiste.de.martel@cern.ch
 - nico.madysa@cern.ch
 - roman.gorbonosov@cern.ch



Thank you !





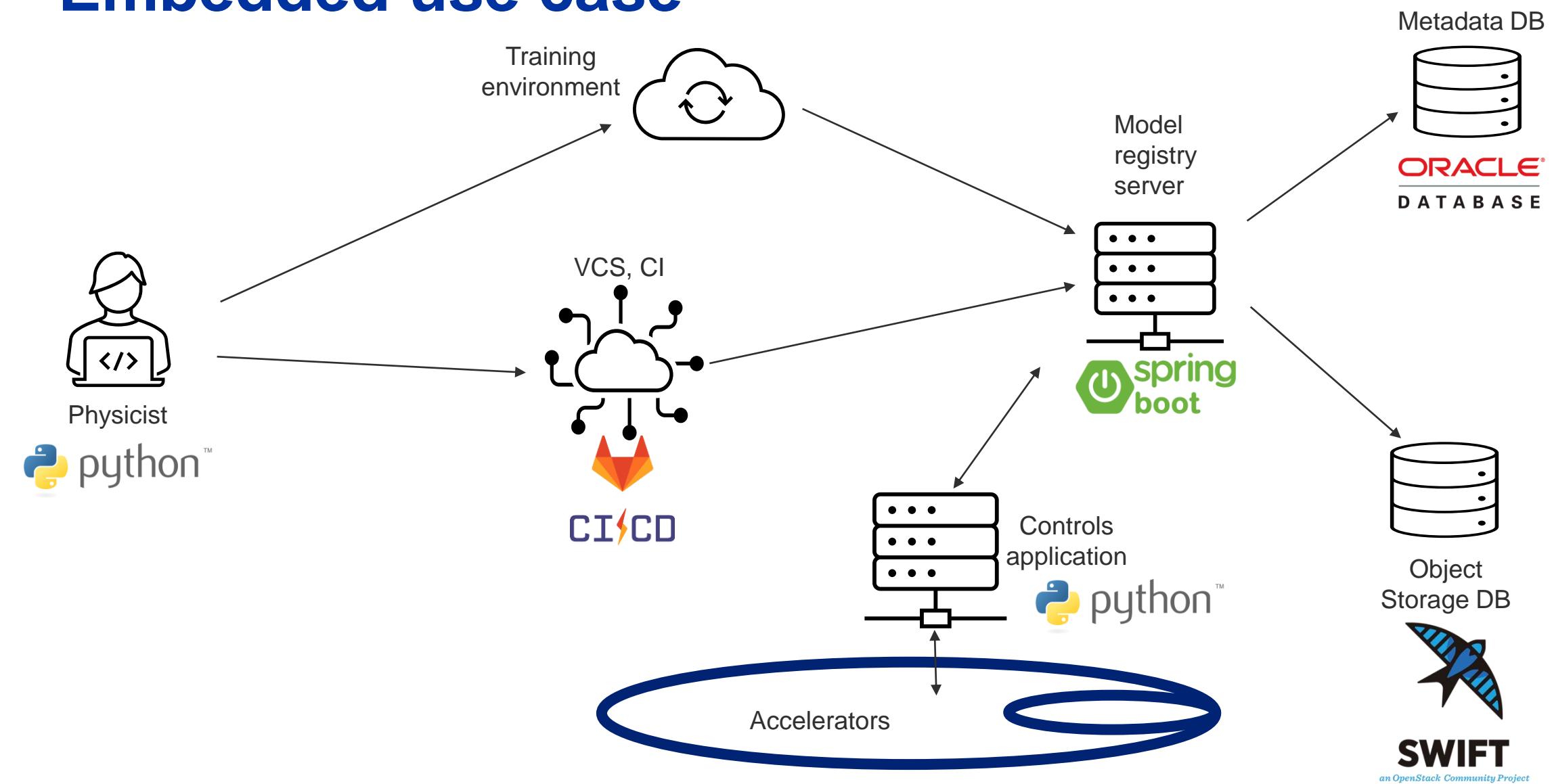
Reserve slides



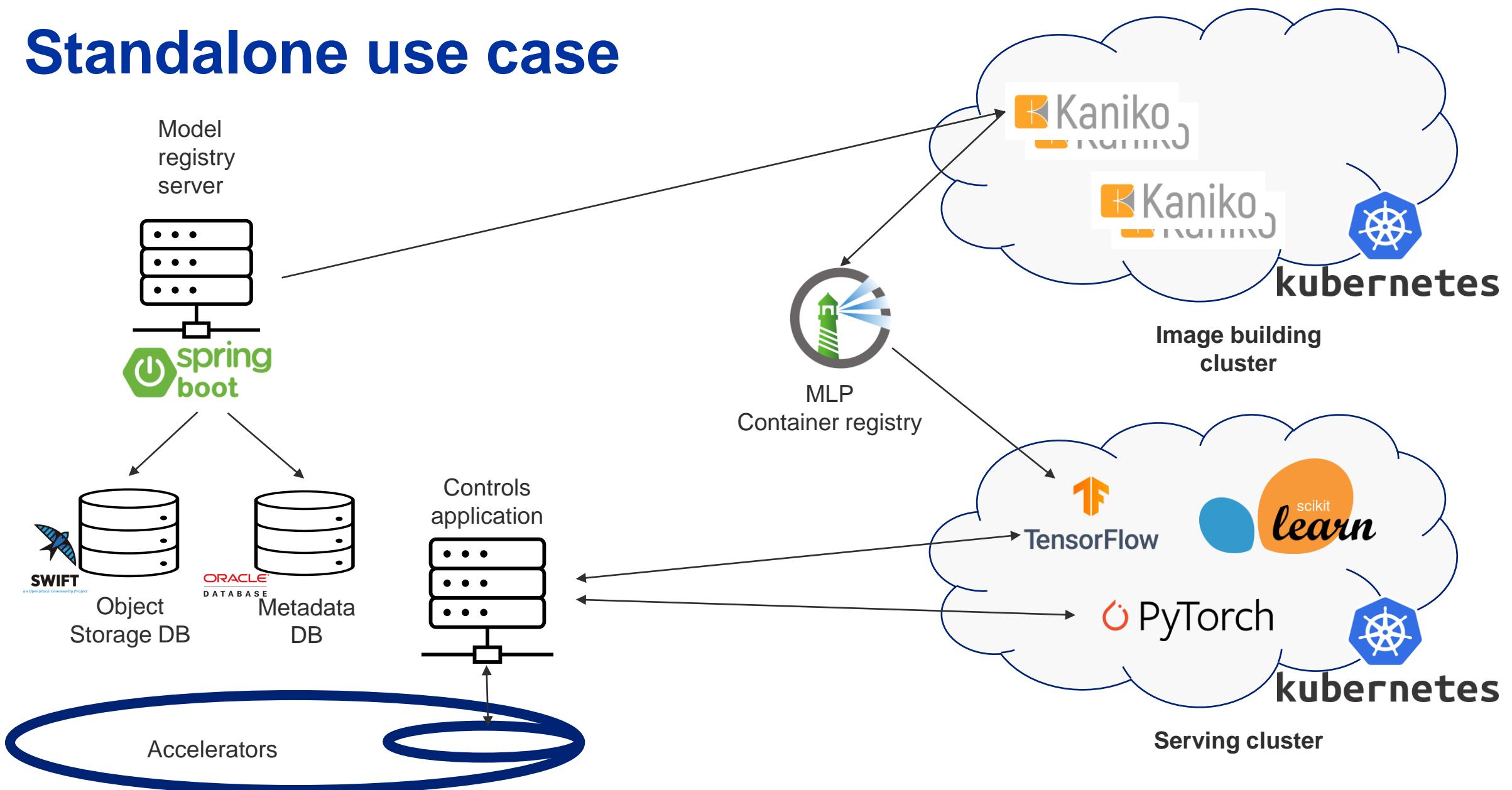
Use cases

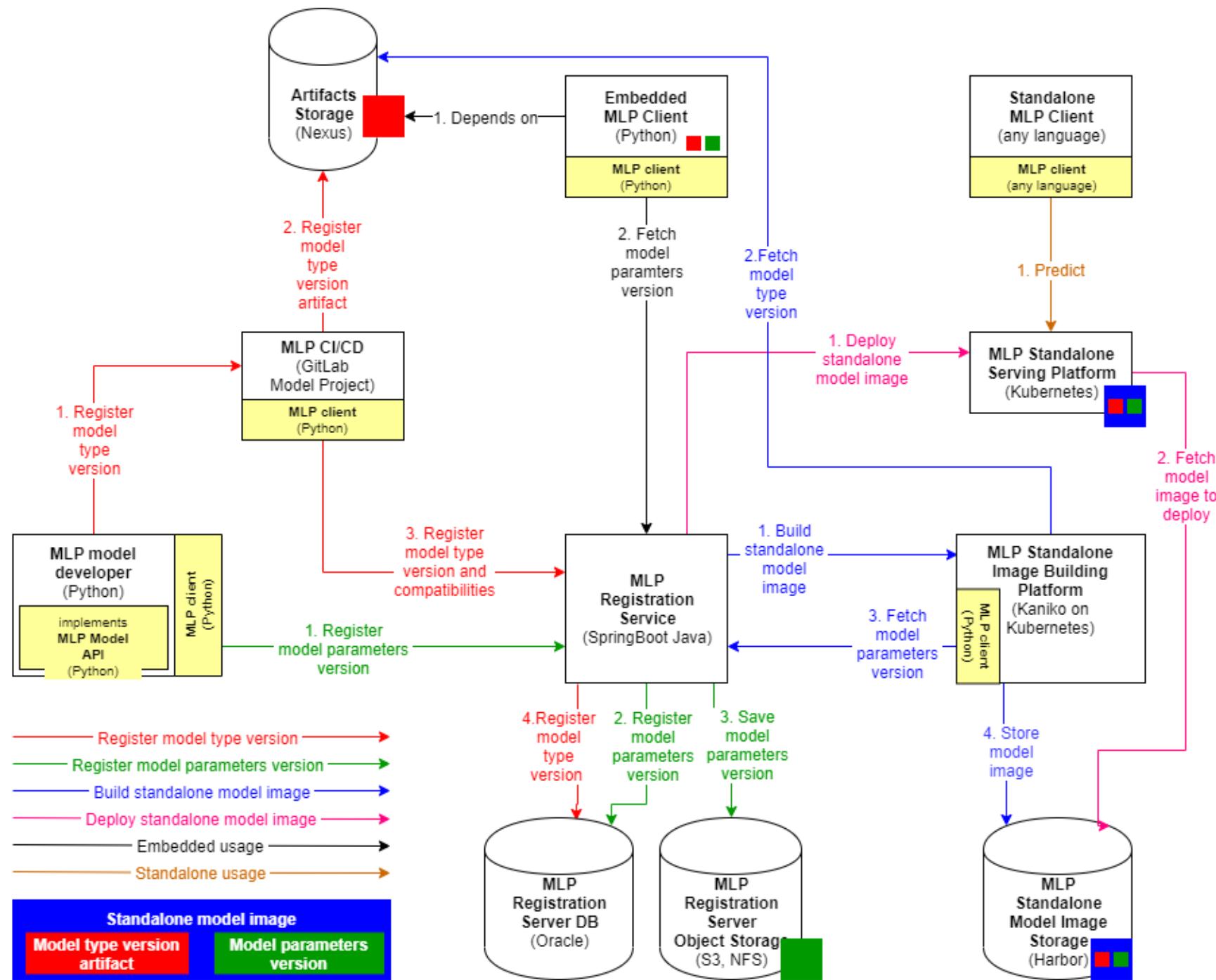
- **SPS eddy current effect – V. Kain**
- **SPS deep hysteresis compensation – N. Madysa**
- **LEIR Schottky computer vision – N. Madysa**
- **SPS MKD dump pattern analysis – F. M. Velotti**
- **Awake auto-matching - F. M. Velotti**

Embedded use case

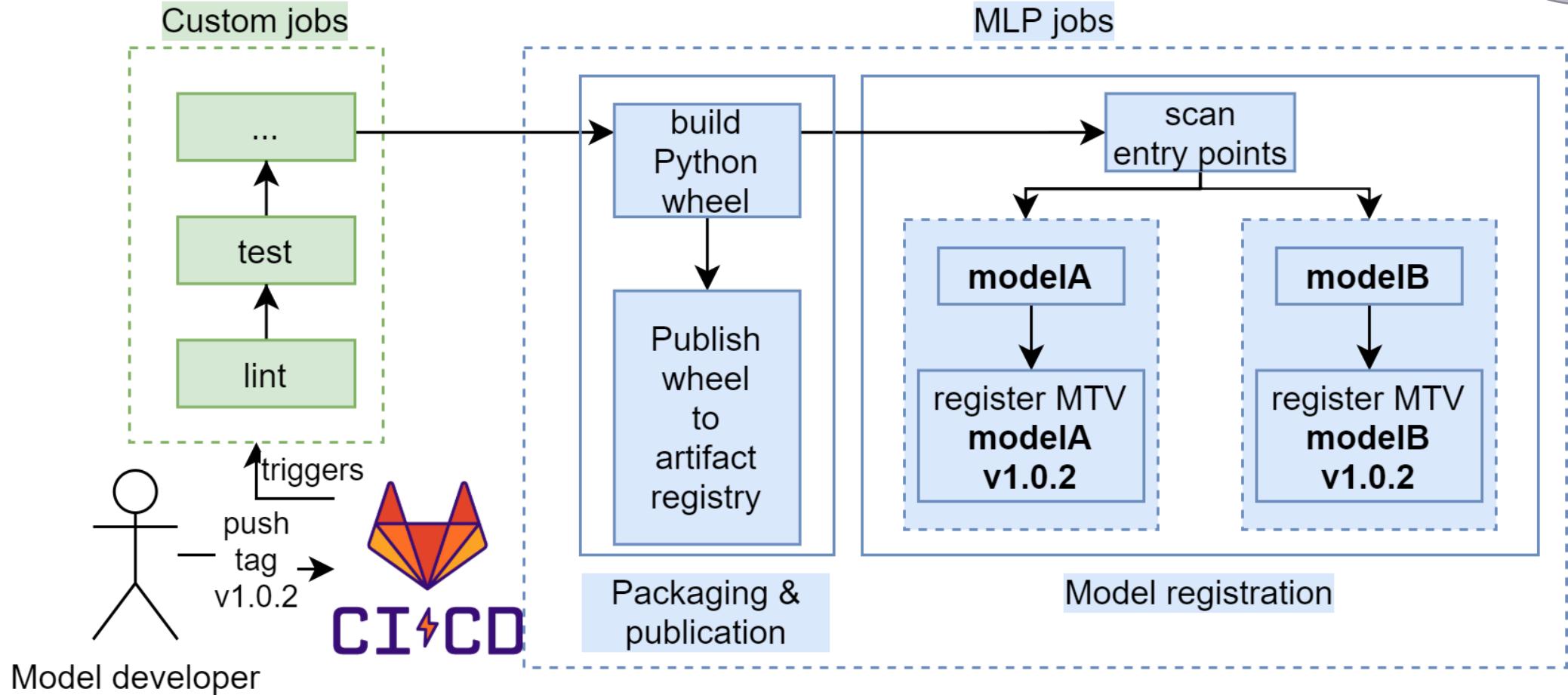
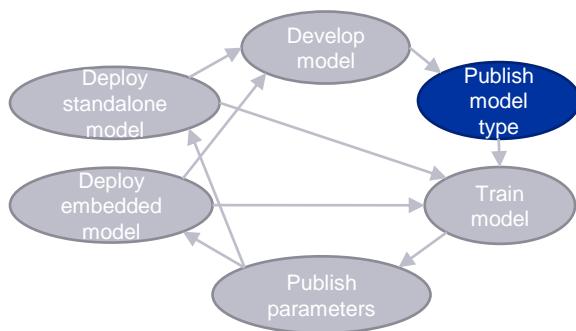


Standalone use case





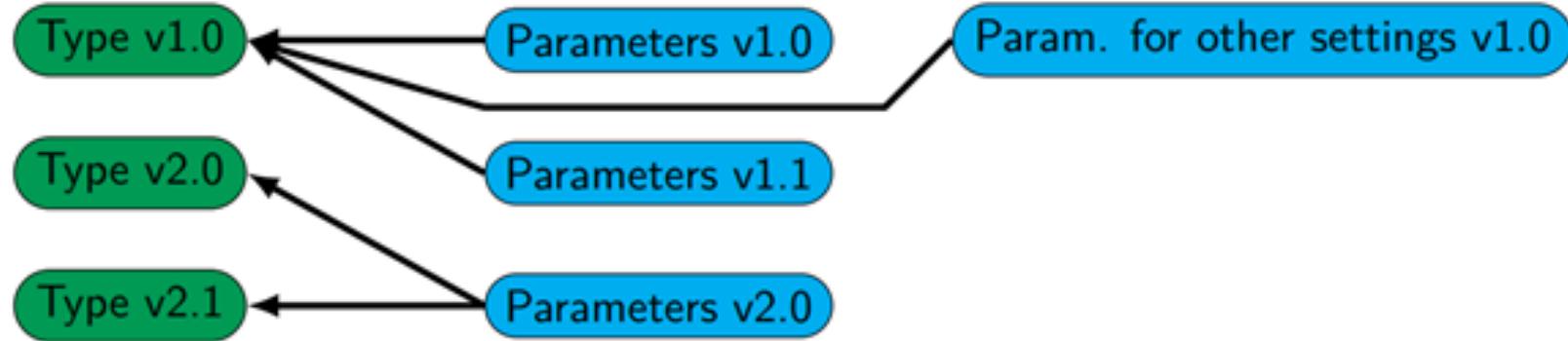
Publishing model types



Model parameters version number generation

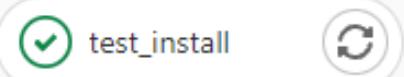
Model type version	Highest existing parameters version	->	Generated parameters version
1.0.0	None exist yet	->	1.0
1.0.0	1.0	->	1.1
1.6.0	1.1	->	1.2
2.0.0	1.2	->	2.0
3.3.0	4.0 (no 3.x)	->	ambiguity
3.3.0	4.0 (3.3 exists)	->	3.4

Compatibility

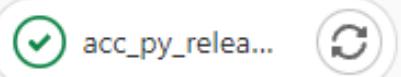


Standalone deployment CI

Test



Deploy



Register



Standalone



Downstream



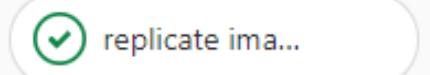
Downstream



Build



Replicate to acc registry



Deploy

