



Beam Loading effects in Traveling-Wave structures and its integration in particle tracking

CLIC Beam Physics meeting

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14.07.2022

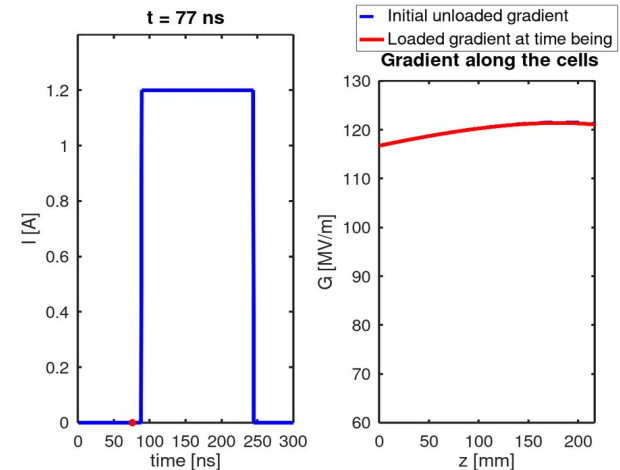
Objectives

- **PART I:** Understand the beam loading effect
 - Derive a **general PDE** describing energy flow
- **PART II:** Design of a **numerical method** to implement such effect in **RF-Track**
 - General ideas
- **PART III:** **Assess** the BL collective effect **performance** in RF-Track
 - Concrete examples (CLIC main linac, PETS, HPCI)

PART I: Beam Loading effect description

I. Beam loading effect

- **What:** **Reduction** of available accelerating **gradient**
- **Origin:** Beam – **Cavity** interaction
 - 1st bunches affect following bunches
- **Consequences:** **Transient** response
 - Not all **bunches** gain/lose same energy



[1] A. Grudiev, A. Lunin, V. Yakovlev. *Analytical solutions for transient and steady state beam loading in arbitrary travelling wave accelerating structures*. Phys. Rev. Special topics **14**, 052001 (2011)

> Theoretical analysis of beam loading effect based on CLIC's main linac [1]

I. Electric field description: Synchronism

- **Motivation:** Study of **energy** conservation → Interest in V_{acc}
- Electric field phasorial description [2]:

$$E_z(z, t) = \text{Re} \left[\tilde{E}_z(z) e^{j\omega t} \right]$$

- Accelerating voltage [3,4]:

$$V_{acc} = \int_0^L \underbrace{\text{Re} \left[\tilde{E}_z(z) e^{j\omega \frac{z}{c}} \right]}_{\text{Effective electric field seen by the particle}} dz \rightarrow \text{Time of flight for an ultrarelativistic particle}$$

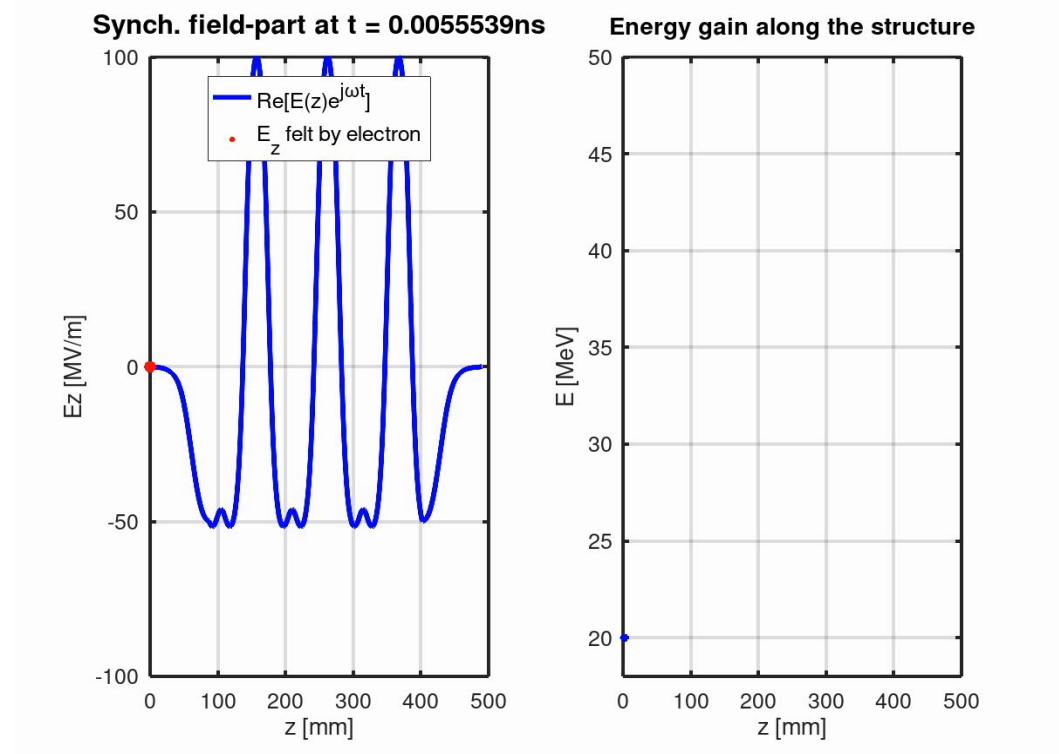
[2] Jackson, J. D. (1999). *Classical electrodynamics*.

[3] P. Lapostolle. *Linear Accelerators*. North Holland Publishing Company, 1970 (Amsterdam, Holland)

[4] Thomas P. Wangler. *RF linear accelerators*. Wiley-VCH 2008 (Amsterdam, Holland)

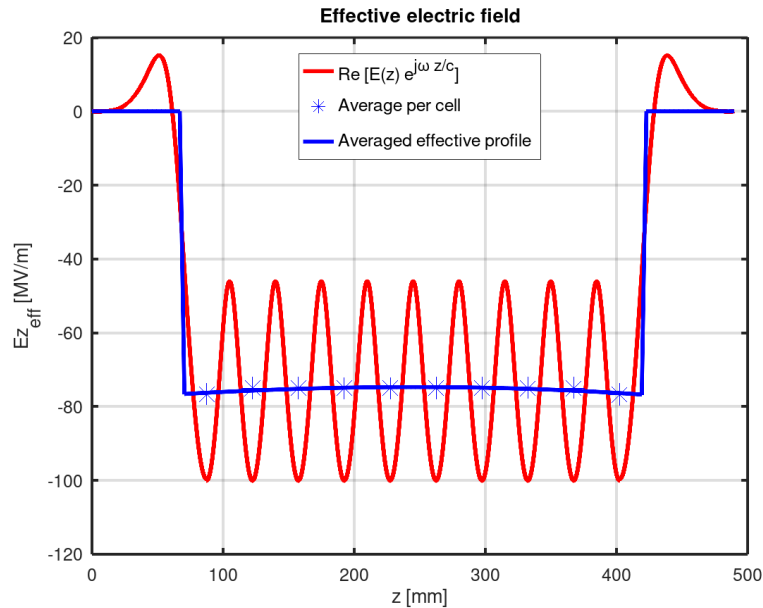
I. Electric field description: Synchronism

- From E_z to $E_{z,\text{eff}}$
 - Example
 - $f = 2.856$ GHz
 - $\langle G \rangle = 77$ MV/m
 - 9 TW cells + 2 x $\frac{1}{2}$
 - 2 SW couplers



I. Electric field description: Synchronism

- From $E_{z,\text{eff}}$ to G



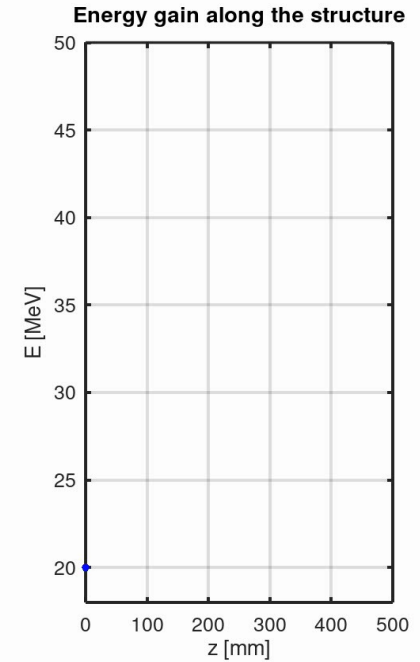
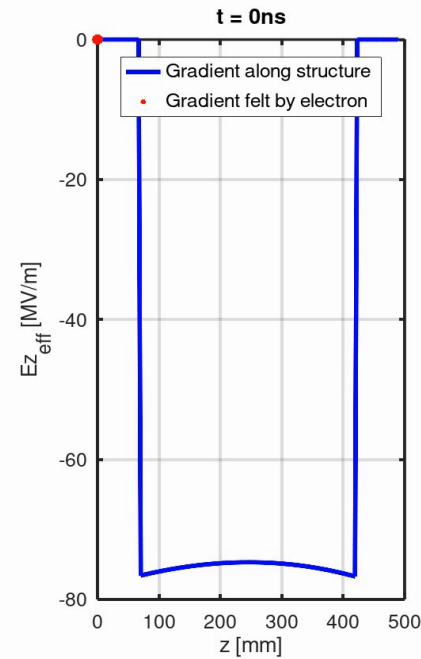
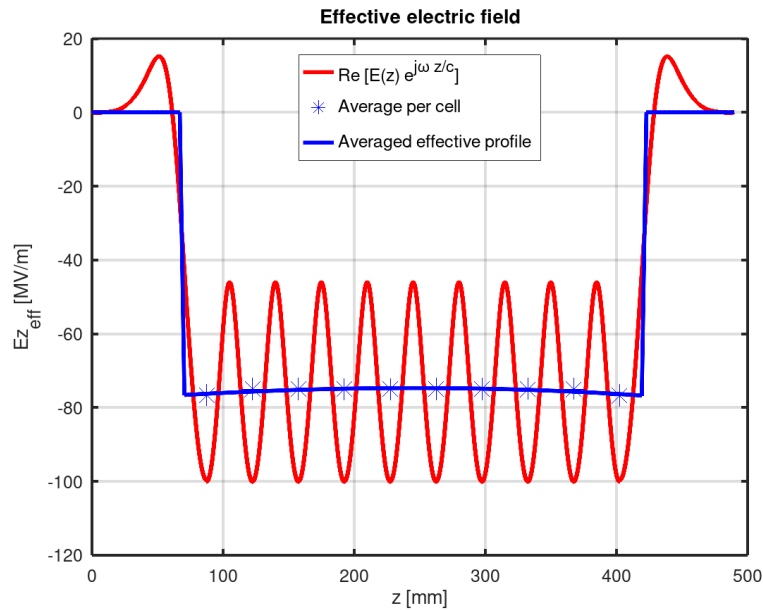
- **Gradient:** **Averaged** electric field *seen* by the particle

- Equivalent tracked energy gain

- Suitable for tracking!

I. Electric field description: Synchronism

- From $E_{z,\text{eff}}$ to G



I. Electric field description: Synchronism

- **Move to:** Transient + Relativistic
- Electric field **quasi-static** phasorial description [5]:

$$E_z(z, t) = \text{Re} \left[\tilde{E}_z(z, t) e^{j\omega t} \right]$$

Transient quasi-static:
RF variation \gg Amplitude variation

- Accelerating voltage:

$$V_{\text{acc}}(k, t, t_0, \beta_0) = \int_{z_k}^{z_{k+1}} \text{Re} \left[\tilde{E}(z, t) e^{j\omega t_q(z, t, t_0, \beta_0)} \right] dz$$

Time of flight of a
relativistic particle

- **Effective** Gradient

$$G_{\text{eff}}(k, t, t_0, \beta_0) = \frac{V_{\text{acc}}(k, t, t_0, \beta_0)}{L}$$

[5] Venkatasubramanian, V. (1994). Tools for dynamic analysis of the general large power system using time-varying phasors. *International Journal of Electrical Power & Energy Systems*, 16(6), 365-376.

I. Electric field description: Synchronism

- A bit more on synchronism and transient regime
- Time of flight:

$$t_q(z, t_0, \beta(z, t, t_0, \beta_0)) = t_0 + \int_0^z \frac{d\zeta}{\beta(\zeta, t, t_0, \beta_0)c}$$

Related to energy gain

- Note that:

$$E_z|_{\text{eff}}(z, t, t_0, \beta) = \text{Re} \left[\tilde{E}_z(z, t) e^{j\omega t_q(z, t_0, \beta(z, t, t_0, \beta_0))} \right]$$

Use this for simplicity in maths

\neq

$$E_z|_{\text{seen}}(z, t, t_0, \beta) = \text{Re} \left[\tilde{E}_z(z, t_q(z, t, t_0, \beta_0)) e^{j\omega t_q(z, t, t_0, \beta(z, t_0, \beta_0))} \right]$$

Consistent with the **quasi-static** assumption

I. Energy flow PDE

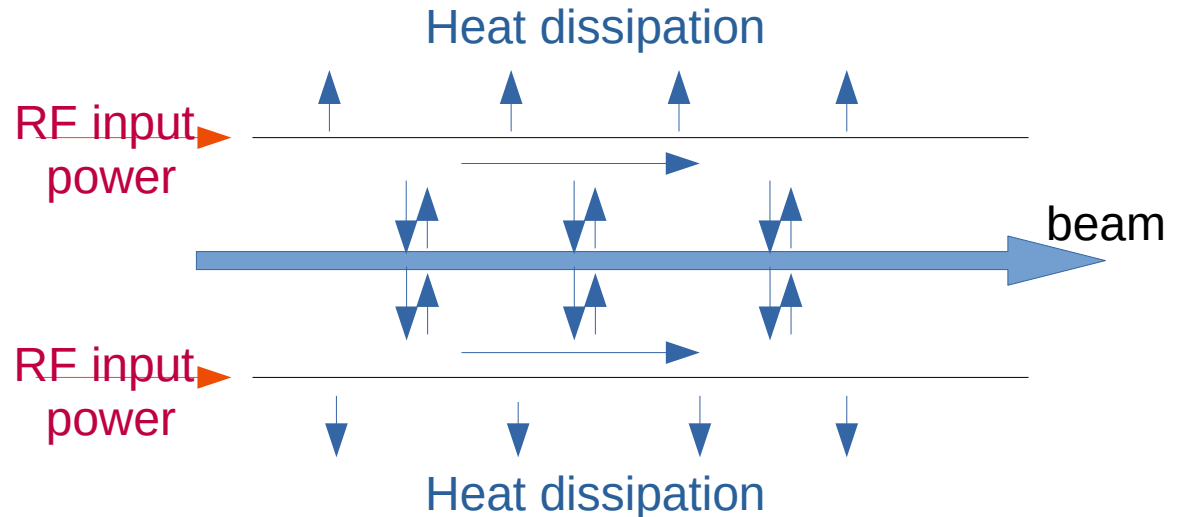
- Starting point: **Poynting theorem**

$$-\frac{\partial u(\vec{r}, t)}{\partial t} = \vec{\nabla} \cdot \vec{S}(\vec{r}, t) + \vec{E}(\vec{r}, t) \cdot \vec{J}(\vec{r}, t)$$

Source term: Field – beam interaction

Stored E.M.energy
density variation

Power flow & loss



> Energy balance schematic for a TW accelerating cavity.

I. Energy flow PDE

- We want: **PDE** for (**G**) in the variables z, t .
- We need: **Figures of merit**

- Effective shunt impedance per unit length
- Quality factor
- Group velocity

$$\left. \begin{aligned} r_e &= \frac{G_{\text{eff}}^2}{p_{\text{diss}}} [\Omega/\text{m}] \\ Q &= \omega_{\text{RF}} \frac{w}{p_{\text{diss}}} \end{aligned} \right\} \rho_e = \frac{r_e}{Q} [\Omega/\text{m}]$$

$$v_g = \frac{P_{\text{flow}}}{w} [\text{m/s}]$$

+ E.M. quantities (p_{diss} , w , P_{flow}) defined at [2,4,6]

[6] CAS Proceedings. *Fifth General Accelerator Physics Course*. (Jyväskylä, Finland) 1992.

I. Energy flow PDE

- Starting point: **Poynting theorem**
- Manipulation:
 - Time-Average over RF-period → Measurability
 - Integration over arbitrary volume
 - Hypothesis: Paraxial, continuity

$$-\frac{\partial G}{\partial t} = v_g \frac{\partial G}{\partial z} + \left(-\frac{1}{\rho_e} \frac{\partial \rho_e}{\partial \beta} \frac{\partial \beta}{\partial t} - \frac{v_g}{\rho_e} \frac{\partial \rho_e}{\partial z} + \frac{\omega}{Q} + \frac{\partial v_g}{\partial z} \right) \frac{G}{2} + \frac{\omega \rho_e \tilde{I}}{2}$$

- Linear non-homogeneous PDE → **Superposition**

I. Energy flow PDE

- **Ultrarelativistic case:** Most common in TW

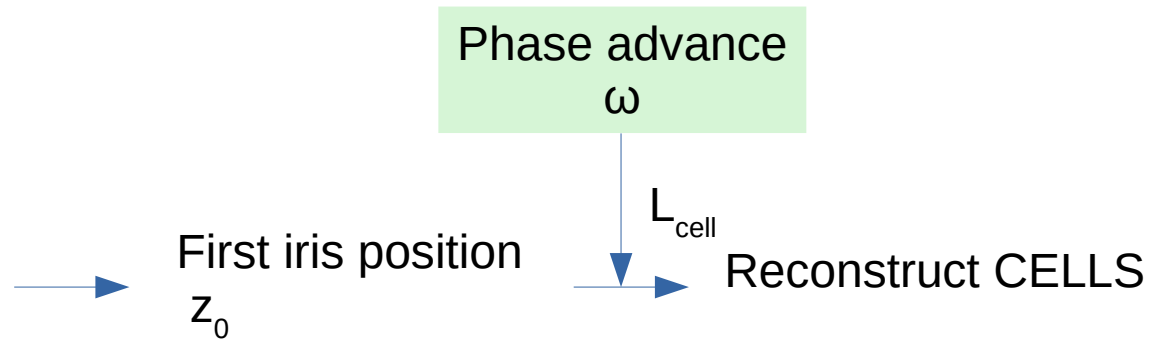
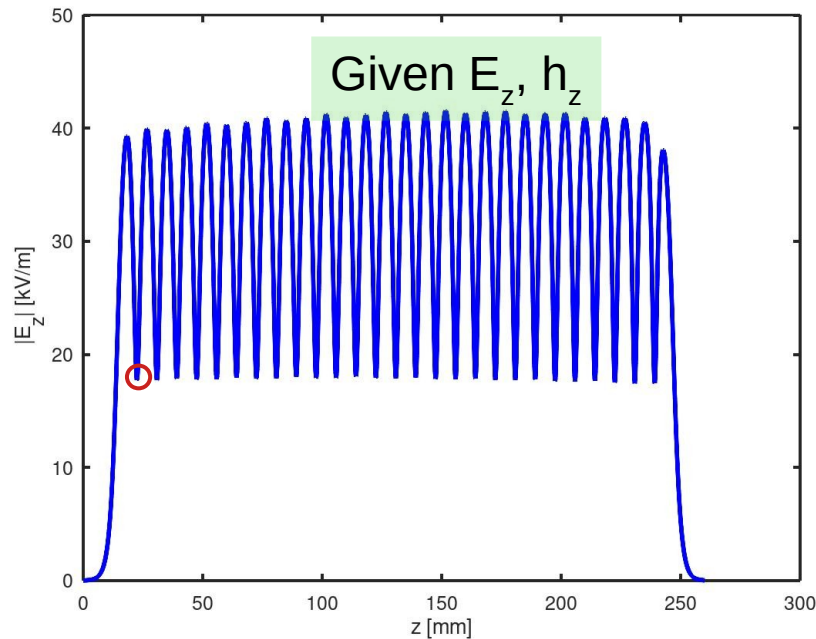
$$-\frac{\partial G}{\partial t} = v_g \frac{\partial G}{\partial z} + \left(-\frac{v_g}{\rho} \frac{\partial \rho}{\partial z} + \frac{\omega}{Q} + \frac{\partial v_g}{\partial z} \right) \frac{G}{2} + \frac{\omega \rho \tilde{I}}{2}$$

- Matching with [1]

PART II: Numerical implementation

II. PDE resolution algorithm

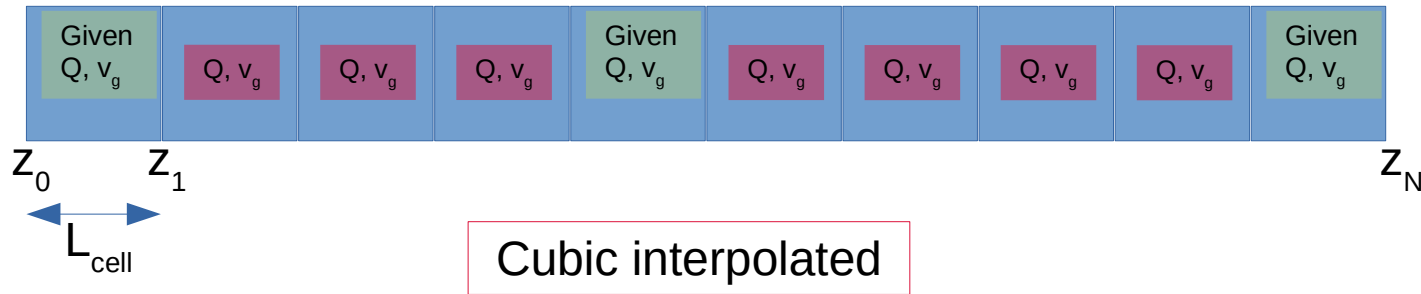
- Finite difference method – Require **space** and **time discretization**
- **SPACE**: Mesh with $N+1$ points – N CELLS



> Proposed *unscaled* fieldmap for CLIC's main linac [1].
Courtesy of A. Grudiev.

II. PDE resolution algorithm

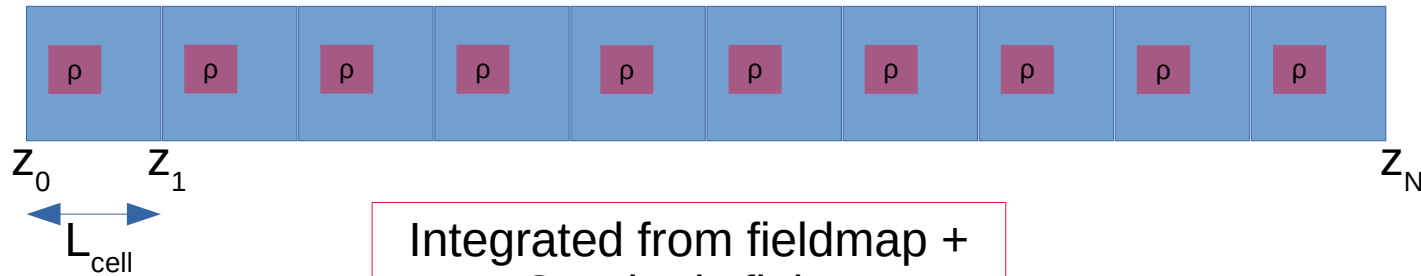
- Finite difference method – Require **space** and **time discretization**
- **SPACE**: Mesh with $N+1$ points – N CELLS



*If ρ is provided, the similar strategy can be applied.

II. PDE resolution algorithm

- Finite difference method – Require **space** and **time discretization**
- **SPACE**: Mesh with N+1 points – N CELLS



Integrated from fieldmap +
Quadratic fitting

Extra info from Ez:
Initial t_0
Initial ϕ
 P_{actual}

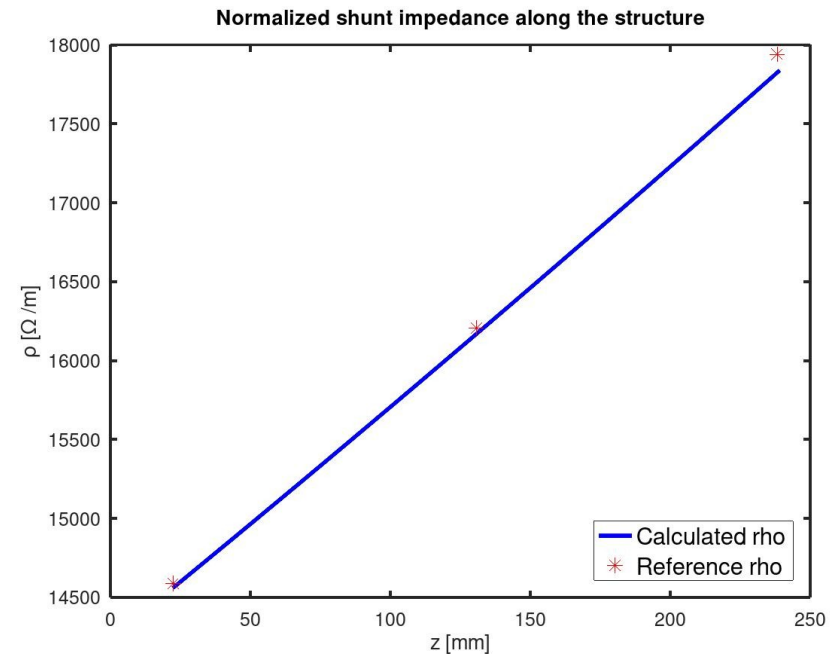
$$\left. \begin{array}{l} \text{From } E_z \rightarrow G^2 \\ \text{From } [1,2,6] \rightarrow w \end{array} \right\} \rho = \frac{G^2}{\omega w}$$

II. PDE resolution algorithm

- Finite difference method – Require **space** and **time discretization**
- **SPACE**: Mesh with N+1 points – N CELLS

Max. deviation $\delta = 0.63\%$

> Shunt impedance comparison for CLIC's main linac.
Data obtained from [1].



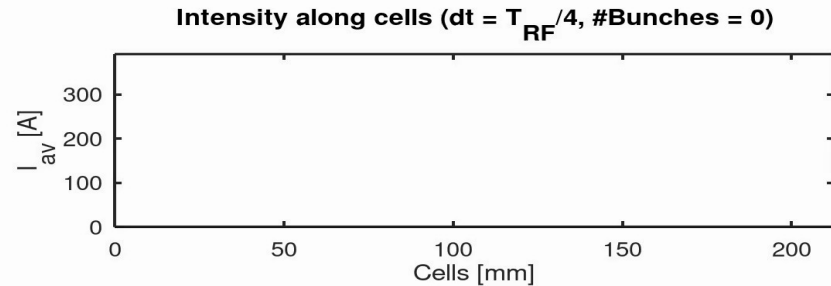
II. PDE resolution algorithm

- Finite difference method – Require **space** and **time discretization**
- **TIME:** Mesh with M points

$$\tilde{I}(z, t, t_0) = \frac{q}{T} \chi(z, t - t_q(z, t_0)) \quad \chi(n, t) = \begin{cases} 1 & \text{if } n\text{th bunch contained in } [t, t+T] \\ 0 & \text{otherwise} \end{cases}$$

Bunch info as input:

-q
-f_b
-N_{bunches}



II. From PDE to tracking

1) Mesh Characterization (Initialize)

- SPACE (N cells): **Interp** & **fitting** routines $\longrightarrow v_g(n), \rho(n), Q(n)$
- TIME (M steps): $\tilde{I}(n, m)$

A priori:
Precomputed **before**
tracking

2) PDE resolution (Compute)

Initial conditions set to 0

$$\longrightarrow E|_{\text{eff}}(n, m)_{N+1 \times M}$$

3) Tracking

$$E = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & e^{-j\omega dt} & 0 & .. & 0 \\ 0 & 0 & e^{-j\omega 2dt} & .. & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & e^{-j\omega Ndt} \end{bmatrix}_{N+1 \times N+1}$$

$$\cdot E|_{\text{eff}} \longrightarrow F_z = q\text{Re} \left[\underbrace{E(z_{\text{part}}, t_{\text{part}})}_{\text{Cubic interp from } E_{N+1 \times M}} e^{j\omega t_{\text{part}}} \right]$$

Cubic interp from $E_{N+1 \times M}$

II. Beam Loading in RF-Track

- **Workflow**

- 1) Analytic calculation
- 2) Extensive tests in Octave
- 3) **C++** implementation in RF-Track

- About **RF-Track** [7]:

- Beam **tracking** in field map including **space-charge** effects, **wakefields** ...
- **Multiple species** (arbitrary q and m)
- Parallel **C++**, interface with user via **Octave** and **Python**

[7] A. Latina. *RF-Track Reference Manual*. CERN, Geneva, Switzerland, June 2020

II. Beam Loading in RF-Track

- **Example:** RF field + BL effect

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
%% Load RF Track  
RF_Track  
  
%% Create BL constructor from input data (If given fieldmap)  
BL = BeamLoading(Ez, hz, Pactual, f0, VG, QQ, initialt0, initialphi, phaseadvance, q, fb);  
  
%% Create RF-Field  
RF = RF_FieldMap_1d_CINT(Ez, hz/1000, -1, f0, +1, Pmap, Pactual);  
  
%% Add collective effect as an additional kick  
RF.add_collective_effect(BL);  
RF.set_cfx_nsteps(30);  
  
%% Define bunch  
X0 = XP = Y0 = YP = zeros(1000,1);  
T = 12 / (fb / 1e3)* c + randn(1000,1); % [mm/c]  
P = 2400 * ones(1000,1); % [MeV]  
  
B0 = Bunch6d(RF_Track.electronmass, charge, -1, [X0 XP Y0 YP T P]);  
  
%% Lattice  
L = Lattice();  
L.append(RF)  
  
%% Perform Tracking  
B1 = L.track(B0);  
  
%% Retrieve information  
M1 = B1.get_phase_space();
```

BL Constructor: Mesh prep + precomputation

Can be added on top of :

- **Drift** spaces (Pure BL effect)
- **Analytic TW structures**
- 1D, 2D, 3D **field maps**

* Possibility for a **simpler constructor** if ρ is given

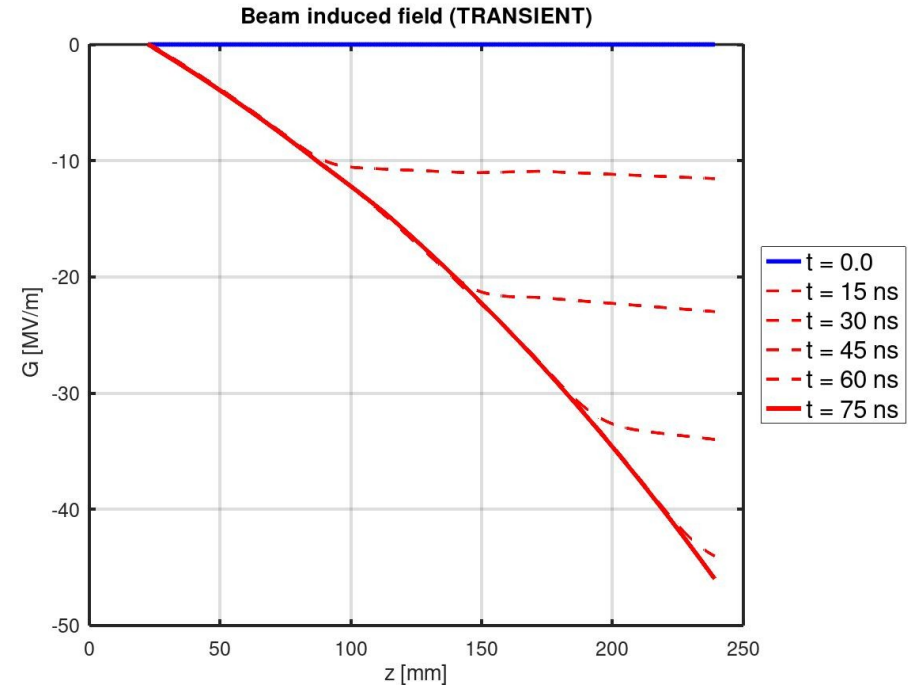
PART III: Results

III. CLIC main linac

- Check of **field calculation** ($t_{\text{own}} = 0.73 \text{ s}$, $t_{\text{RF-Track}} = 0.15 \text{ s}$)

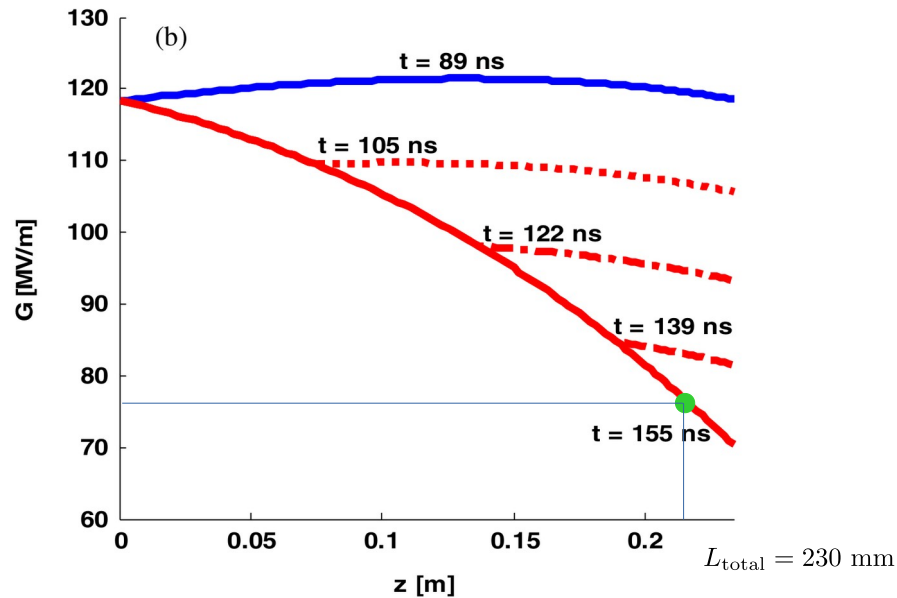
Frequency [GHz]	12
Rf advance / cell	$2\pi/3$
V_g (1st, middle, last cell) [%c]	(1.65, 1.2, 0.83)
Q (1st, middle, last cell)	(5536, 5635, 5738)
Number of cells	26
T fill [ns]	66.7
Mean I [A]	1.2
f_inj [GHz]	2

> Design parameters for CLIC main linac [1].

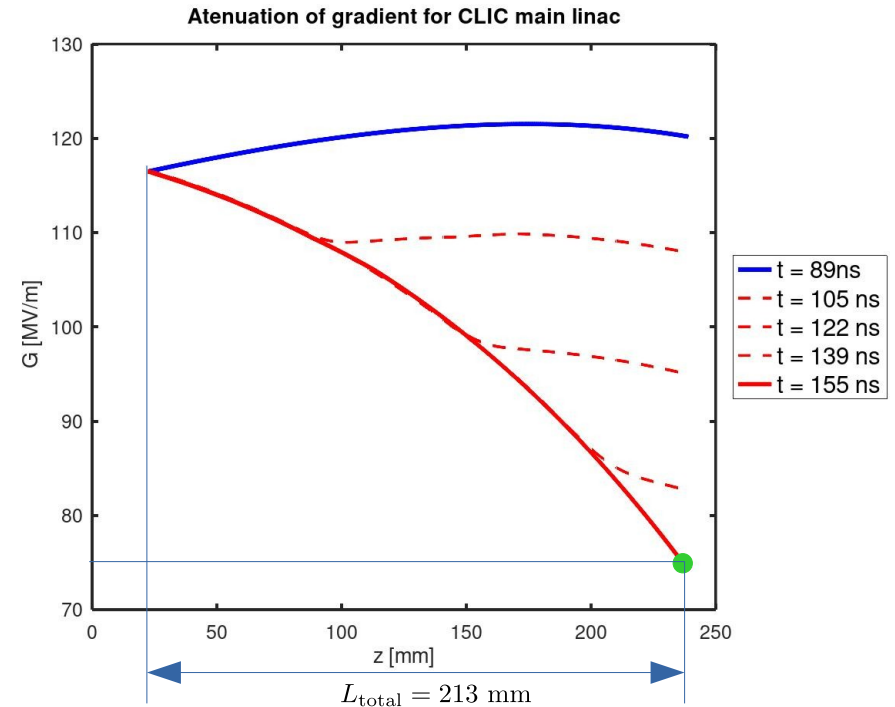


III. CLIC main linac

- Comparison for **superposed gradient** ($P_0 = 61.3 \text{ MW}$, $t_{inj} = 89 \text{ ns}$)



> Theoretical evolution of the gradient for CLIC main linac [1].



III. PETS

- **Passive** cavity providing **deceleration** due to BL effect

– $t_{\text{own}} = 1.3 \text{ s}$, $t_{\text{RF-Track}} = 8.7 \times 10^{-3} \text{ s}$

Norm shunt imp [Ω/m]	2294
Rf advance / cell	$\pi/2$
V_g [%c]	45.3
Q	7200
N cells	34
T fill [ns]	1.63

```
% Create BL constructor from input data
BL = BeamLoading(N0, f0, VG, QQ, RHO, phaseadvance, charge, fb, Nbunches);

% Create Drift
D = Drift( Ltotal / 1000 );

% Attach BL effect
D.add_collective_effect(BL);
D.set_cfx_nsteps(N0);
```

> Design parameters for CLIC PETS [8].

[8] *A Multi-TeV linear collider based on CLIC technology: CLIC Conceptual Design Report*, edited by M. Aicheler, P. Burrows, M. Draper, T. Garvey, P. Lebrun, K. Peach, N. Phinney, H. Schmickler, D. Schulte and N. Toge, CERN-2012-007

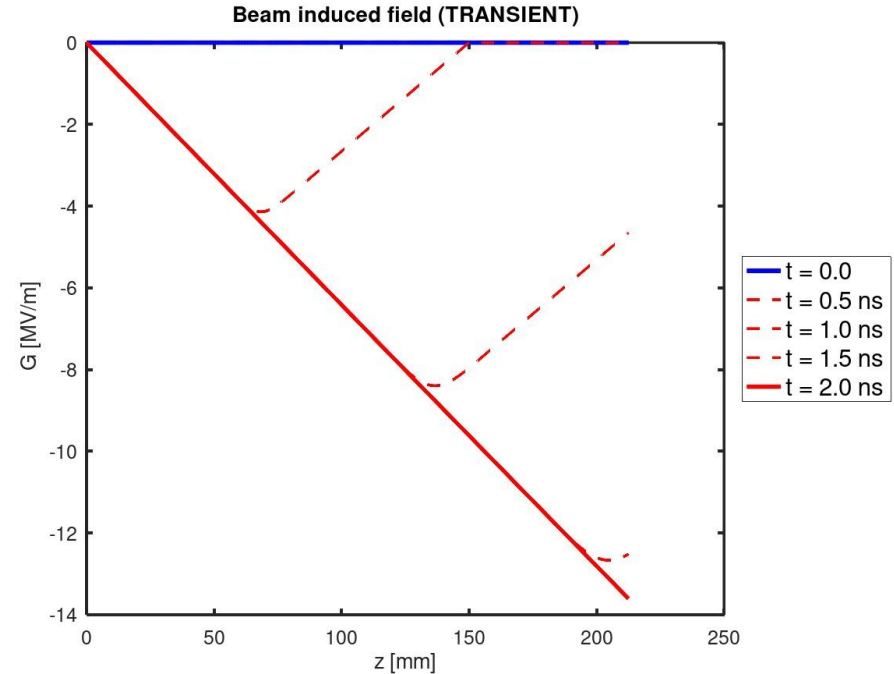
III. PETS

- **Passive** cavity providing **deceleration** due to BL effect

– $t_{\text{own}} = 1.3 \text{ s}$, $t_{\text{RF-Track}} = 8.7 \times 10^{-3} \text{ s}$

Norm shunt imp [Ω/m]	2294
Rf advance / cell	$\pi/2$
V_g [%c]	45.3
Q	7200
N cells	34
T fill [ns]	1.63

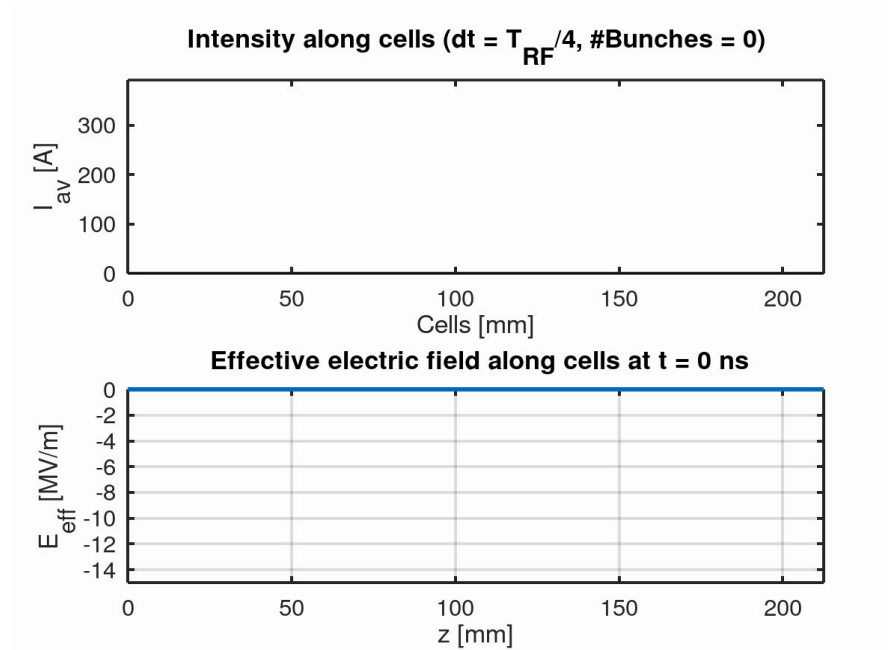
> Design parameters for CLIC PETS [8].



[8] *A Multi-TeV linear collider based on CLIC technology: CLIC Conceptual Design Report*, edited by M. Aicheler, P. Burrows, M. Draper, T. Garvey, P. Lebrun, K. Peach, N. Phinney, H. Schmickler, D. Schulte and N. Toge, CERN-2012-007

III. PETS

- **Passive** cavity providing **deceleration** due to BL effect



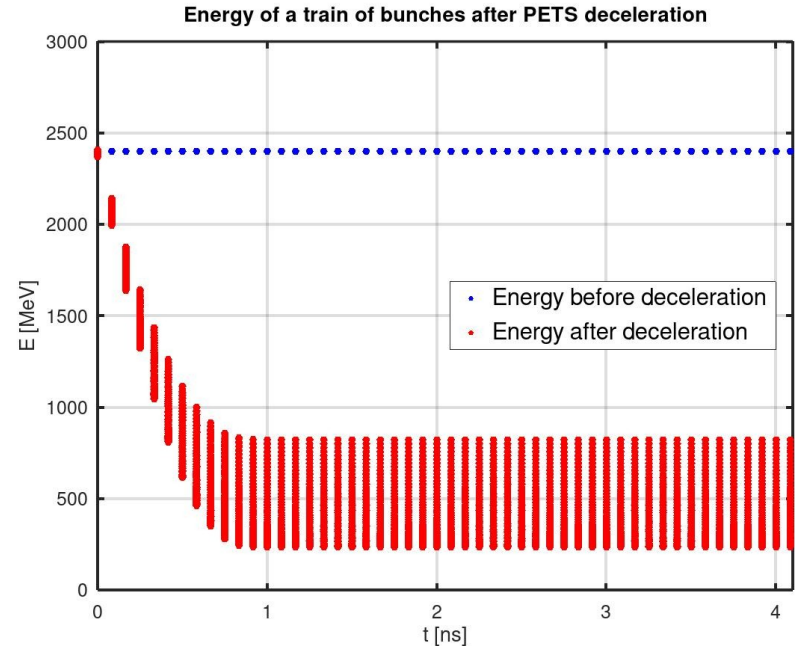
III. PETS

- **Assess tracking** along 1492 structures

- $t_{\text{own}} = 62\text{s}$, $t_{\text{RF-Track}} = 3.2 \times 10^{-1} \text{ s}$

f_injection [GHz]	11.99
Averaged intensity [A]	101.0
σ [mm/c]	1.000
Nbunches	2928
Macropart/bunch	10000
E0 [MeV]	2400

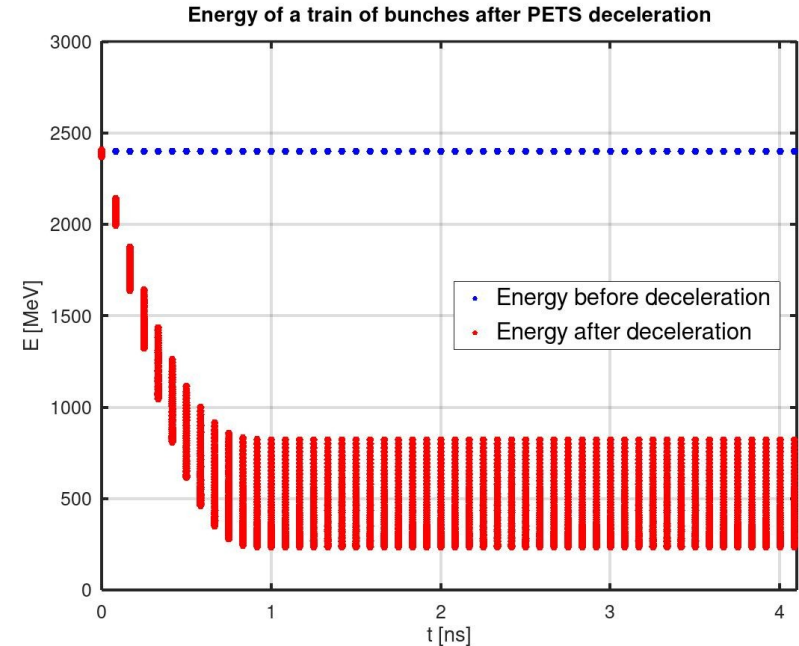
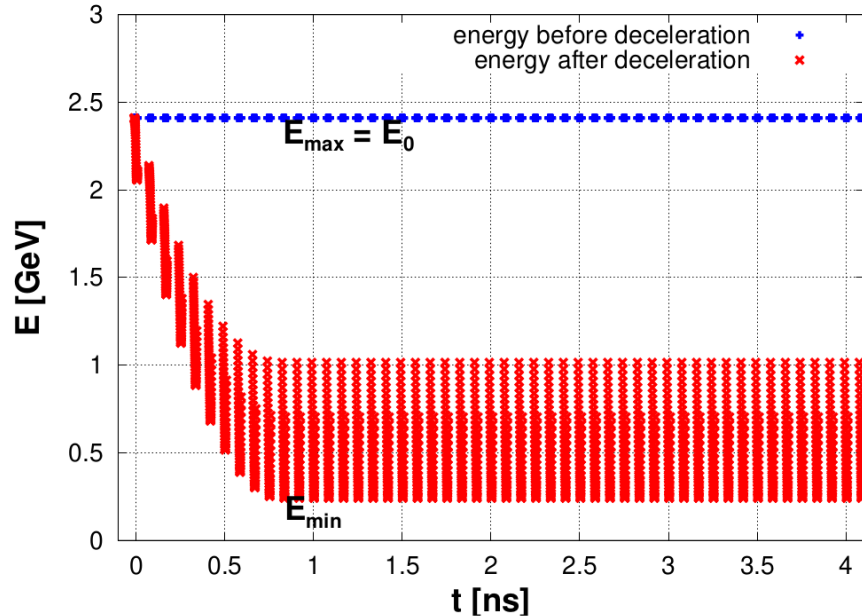
> Bunch train parameters for the drive beam at PETS [9].



[9] Erik Adli (2009). *A Study of the Beam Physics in the CLIC Drive Beam Decelerator*. CERN Geneva. PhD Thesis.

III. PETS

- Assess tracking along 1492 structures



> Energy distribution of the electrons in a train of bunches injected with $E_0 = 2.4$ GeV in CLIC's PETS. Simulated results from Erik's Adli's thesis [9].

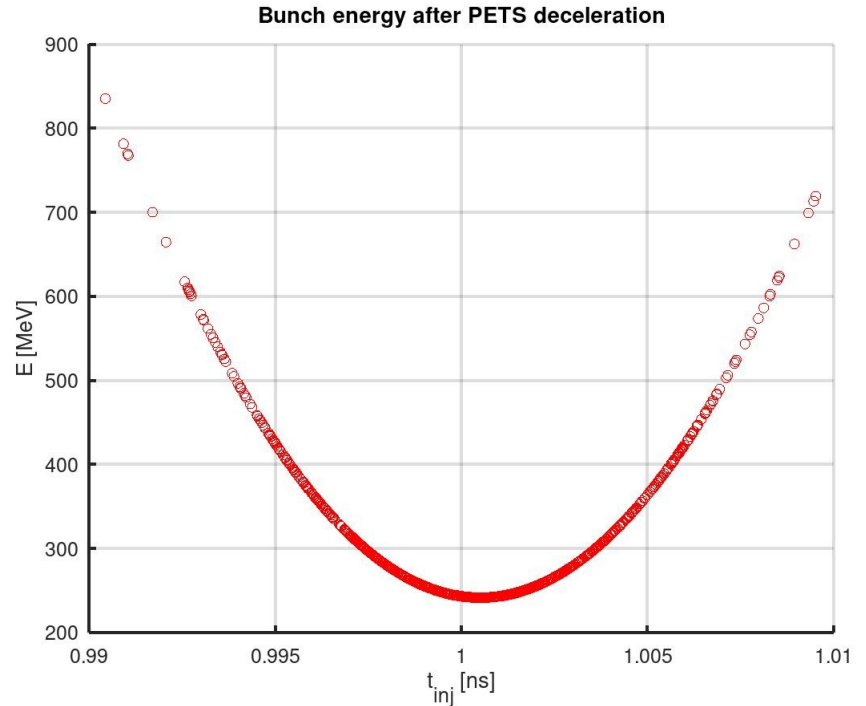
III. PETS

- **Tracking** along 1492 structures
 - $t_{\text{own}} = 40\text{s}$, $t_{\text{RF-Track}} = 1.3 \times 10^{-2} \text{ s}$

$$\eta = \frac{E_0 - E_{\text{min}}}{E_0}$$

$$\eta_{\text{PLACET}} = 90\%$$

E_0 [MeV]	E_{min} [MeV]	η_{min} [%]	δ_E [%]
2400	241.6	89.7	0.67



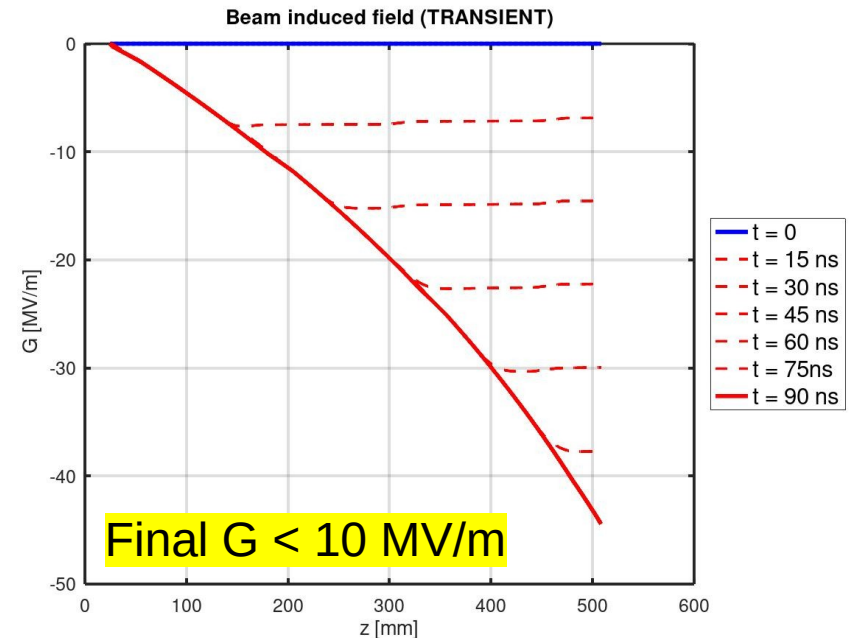
III. High Pulse-Current Injector

- **Chosen model:** Constant gradient structure (~ 54 MV/m)

– $t_{\text{own}} = 3.4$ s, $t_{\text{RF-Track}} = 8.1 \times 10^{-1}$ s

Frequency [GHz]	11.9934
Rf advance / cell	$2\pi/3$
V_g (1st, last cell) [%c]	(2.90, 1.06)
Q (1st, last cell)	(6710, 6670)
Number of cells	58
Peak input power [MW]	24.9
T fill [ns]	81.4

> Preliminary design parameters for a HPCI.
Obtained from internal communication with A. Grudiev
and A.Latina

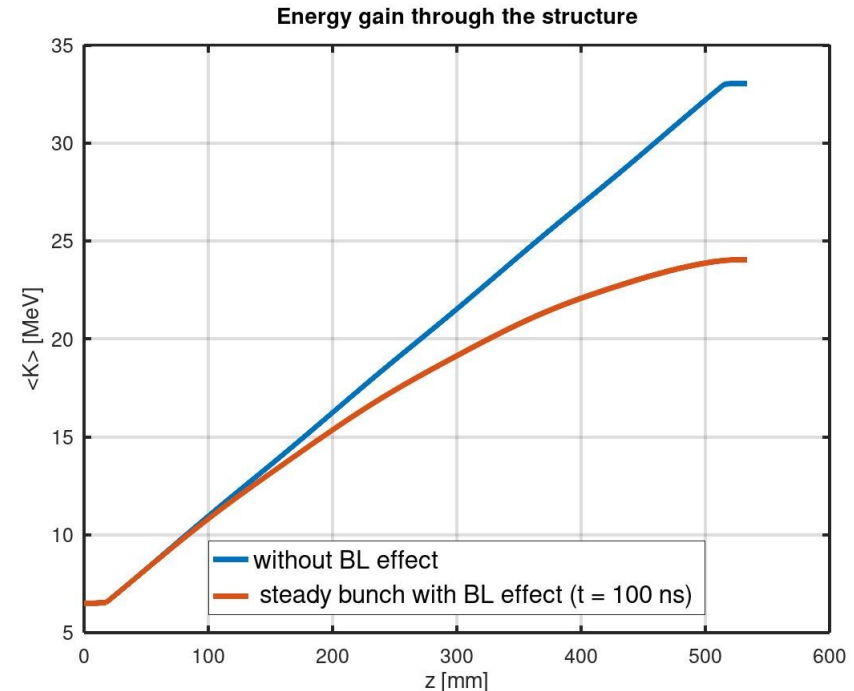


III. High Pulse-Current Injector

- **Chosen model:** Constant gradient structure (~ 54 MV/m)

f_injection [GHz]	2
Bunch charge [pC]	500
σ [mm/c]	0.299
Nbunches	312
E0 [MeV]	7

> Preliminary design parameters for a HPCI.
Obtained from internal communication with A. Grudiev
and A.Latina

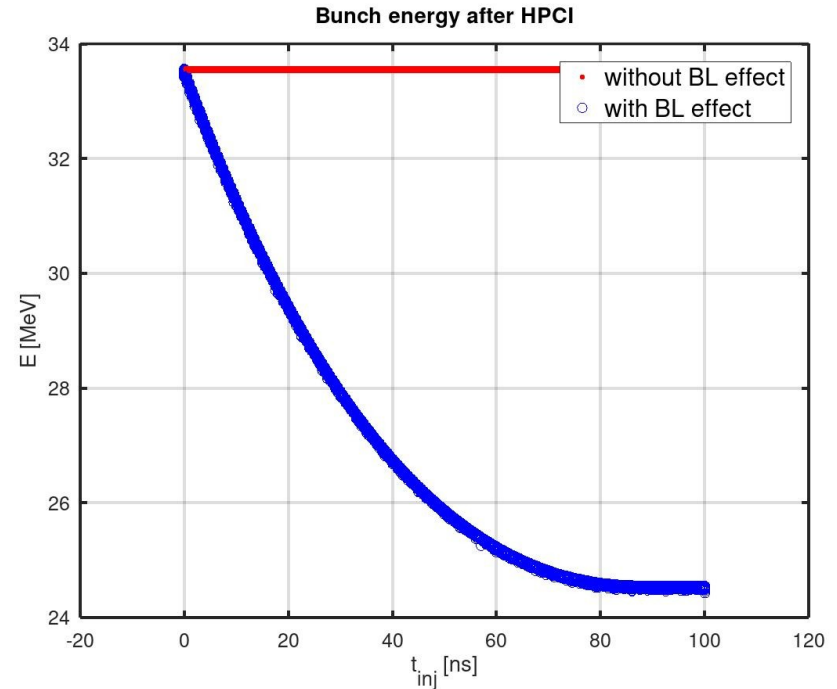


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f_injection [GHz]	2
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σ [mm/c]	0.299
Nbunches	312
E0 [MeV]	7

> Preliminary design parameters for a HPCI.
Obtained from internal communication with A. Grudiev
and A.Latina



Conclusions

- **Beam loading** = Additional **excitation** interacting with the beam
 - **Decrease** of accelerating **gradient**
 - **Transient** response → **Steady** state
 - Bunches **gain different energy** depending on their **injection time**
 - Geometry and beam dependent – Beam cavity interaction
 - Crucial in high-intensity machines
- Implementation in **RF-Track** (fast!)
 - Fully self-consistent model
 - Successful reproduction of previous results: CLIC, PETS, HPCI

Next steps

- **SW for injector guns**
 - Relativistic!
 - CLEAR perfect test-bench for BL effects

Possible applications

- ERL
- Positron sources
- Beam loading compensation studies ?

Acknowledgments

- **Supervision, guidance and trust:**
 - Andrea Latina (CERN, BE-ABP-LAF)
 - Nuria Fuster, Benito Gimeno, Daniel Esperante (UV – Spain, IFIC - CSIC)

- **Useful material & discussions:**
 - Alexej Grudiev, Hermann Pommerenke (CERN, SY-RF-MKS)

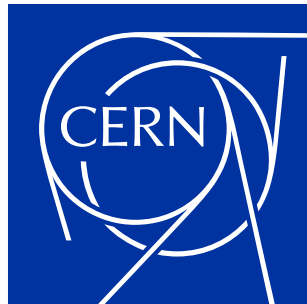
References

- **[1]** A. Grudiev, A. Lunin, V. Yakovlev. *Analytical solutions for transient and steady state beam loading in arbitrary travelling wave accelerating structures*. Phys. Rev. Special topics **14**, 052001 (2011)
- **[2]** P. Lapostolle. *Linear Accelerators*. North Holland Publishing Company, 1970 (Amsterdam, Holland)
- **[3]** Jackson, J. D. (1999). *Classical electrodynamics*.
- **[4]** Thomas P. Wangler. *RF linear accelerators*. Wiley-VCH 2008 (Amsterdam, Holland)
- **[5]** Venkatasubramanian, V. (1994). Tools for dynamic analysis of the general large power system using time-varying phasors. *International Journal of Electrical Power & Energy Systems*, 16(6), 365-376.

References

- **[6]** CAS Proceedings. *Fifth General Accelerator Physics Course*. (Jyväskylä, Finland) 1992.
- **[7]** A. Latina. *RF-Track Reference Manual*. CERN, Geneva, Switzerland, June 2020 DOI: 10.5281/zenodo.3887085
- **[8]** *A Multi-TeV linear collider based on CLIC technology: CLIC Conceptual Design Report*, edited by M. Aicheler, P. Burrows, M. Draper, T. Garvey, P. Lebrun, K. Peach, N. Phinney, H. Schmickler, D. Schulte and N. Toge, CERN-2012-007
- **[9]** Erik Adli (2009). *A Study of the Beam Physics in the CLIC Drive Beam Decelerator*. PhD Thesis.

Thanks for your attention



Additional slide: Finite difference method (I)

- Discretization of quantities for a given $N \times M$ mesh

$$G(z, t) \rightarrow G(z_n, t_m) := G(n, m)$$

$$v_g(z) \rightarrow v_{g,n}$$

$$\frac{\partial G(z, t)}{\partial t} \simeq \frac{G(n, m) - G(n, m - 1)}{dt}$$

$$Q(z) \rightarrow Q_n$$

$$\frac{\partial G(z, t)}{\partial z} \simeq \frac{G(n, m) - G(n - 1, m)}{L}$$

$$\rho(z) \rightarrow \rho_n$$

$$\tilde{I}(z, t) \rightarrow \tilde{I}(n, m)$$

Here **N** is **not** the number of cells necessarily

Additional slide: Finite difference method (II)

- Then the PDE remains:

$$G(n, m + 1) = dt(B(n)G(n, m) + \frac{v_g(n)}{L}G(n - 1, m)) - C(n, m)$$

- With:

$$B(n) = \frac{1}{2} \left. \frac{dv_g}{dz} \right|_n + \frac{d\rho}{dz} \frac{v_g(n)}{2\rho(n)} - \frac{\omega}{2Q(n)} - \frac{v_g(n)}{L} + \frac{1}{dt}$$

$$C(n, m) = \frac{\omega\rho(n)\tilde{I}(n, m)}{2}$$

Additional slide: Finite difference method (III)

- Initialize G for calculation with initial conditions (**no RF**, unloaded)

$$G = \begin{bmatrix} G_{un}(1) & G_{un}(1) & \dots & G_{un}(1) \\ G_{un}(2) & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots \\ G_{un}(N) & 0 & \dots & 0 \end{bmatrix}_{(N \times M)}$$

$$G_{un}(i) = 0 \quad \forall i = 1..N$$

- At each time step **dt**, the gradient along the cells is obtained as:

$$\begin{bmatrix} G(2, m+1) \\ G(3, m+1) \\ \vdots \\ G(N, m+1) \end{bmatrix}_{(N-1) \times 1} = \begin{bmatrix} \frac{v_g(2)}{L} & dt \cdot B(2) & 0 & \dots & 0 \\ 0 & \frac{v_g(3)}{L} & dt \cdot B(3) & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & \frac{v_g(N)}{L} & dt \cdot B(N) \end{bmatrix}_{(N-1)} \cdot \begin{bmatrix} G(1, m) \\ G(2, m) \\ G(3, m) \\ \vdots \\ G(N, m) \end{bmatrix}_{N \times 1} + \begin{bmatrix} C(2, m) \\ C(3, m) \\ \vdots \\ C(N, m) \end{bmatrix}_{(N-1) \times 1}$$