

ISOTDAQ 2023

Trigger/DAQ design:
from test beam to medium size experiments



Roberto Ferrari

INFN - Pavia

Istanbul, June 15th, 2023

Roberto Ferrari

Istituto Nazionale di Fisica Nucleare

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Oh my !

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Istituto Nazionale di Fisica Nucleare

Oh my !

Yet another f...⁽¹⁾ Italian ! ⁽²⁾

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Oh my !

Yet another f...⁽¹⁾ Italian ! ⁽²⁾

(1) fanatic ... fantastic ... ?

(2) about 10 lectures over 29 covered by Italians

ISOTDAQ:

Italian School Of Trigger and Data Acquisition

(Credit: Markus)

But ...

But ...

1) How do Italians communicate?

But ...

1) How do Italians communicate?

2) How can you understand them?

*In Appendix A, you may find
introductory slides for
such demanding environment*

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introductory slides for
such demanding environment*

*(students' homework with brief introduction to Italians'
body language)*

more seriously ...

(1)

→ hope to give you something sensible ←

(2)

→ but, please, don't take anything at face value ←
just aiming at enlightening some critical issues

- not meant to be exhaustive (no way!) -

Trying to move ...

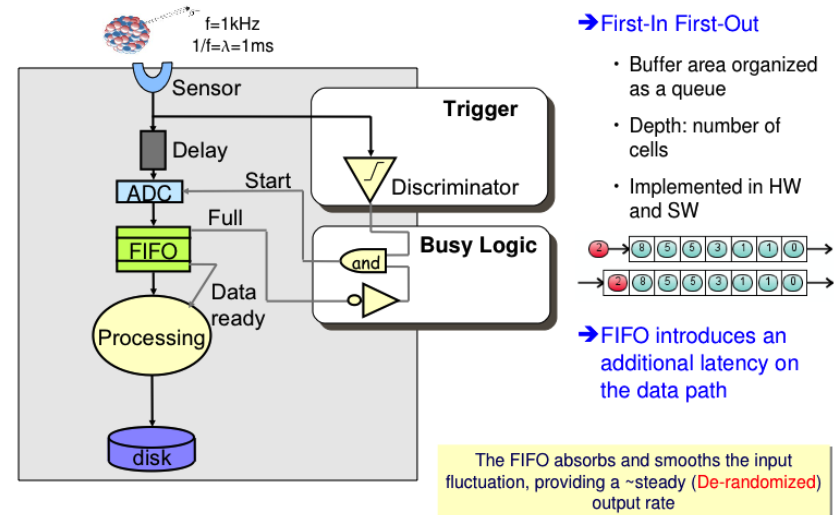
from here:



to here:



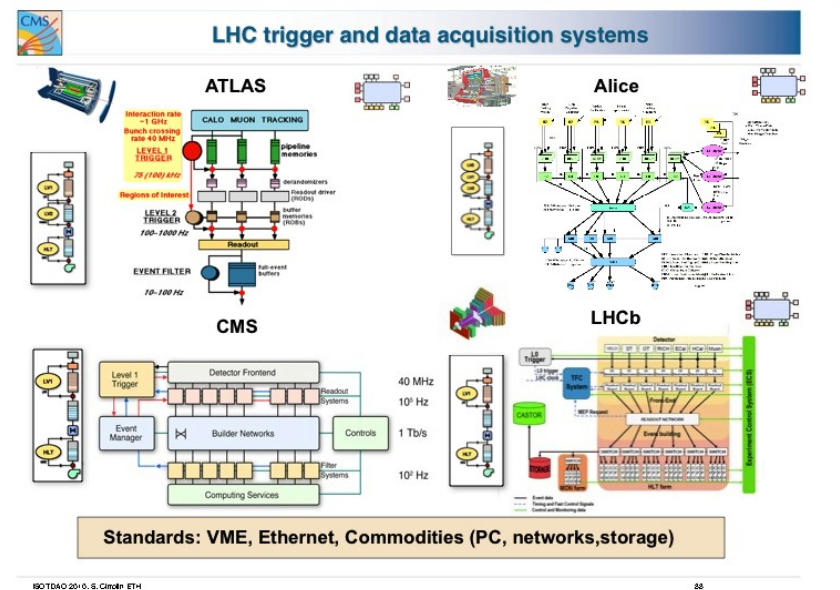
Basic DAQ: De-randomization



February 10th 2011

Introduction to Data Acquisition - W.Vandelli - ISOTDAQ2011

15



ISOTDAQ 2010-6, S. Cincin ET4

25

Friday, 5 February 2010

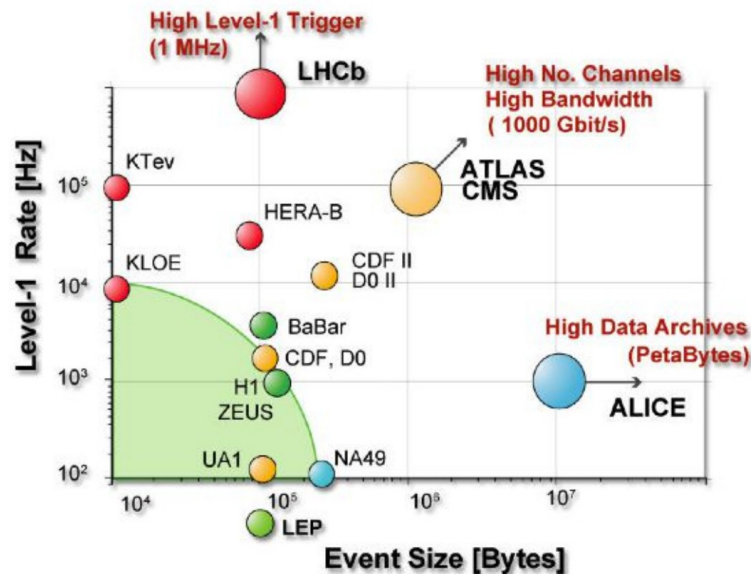
June 15th, 2023

13

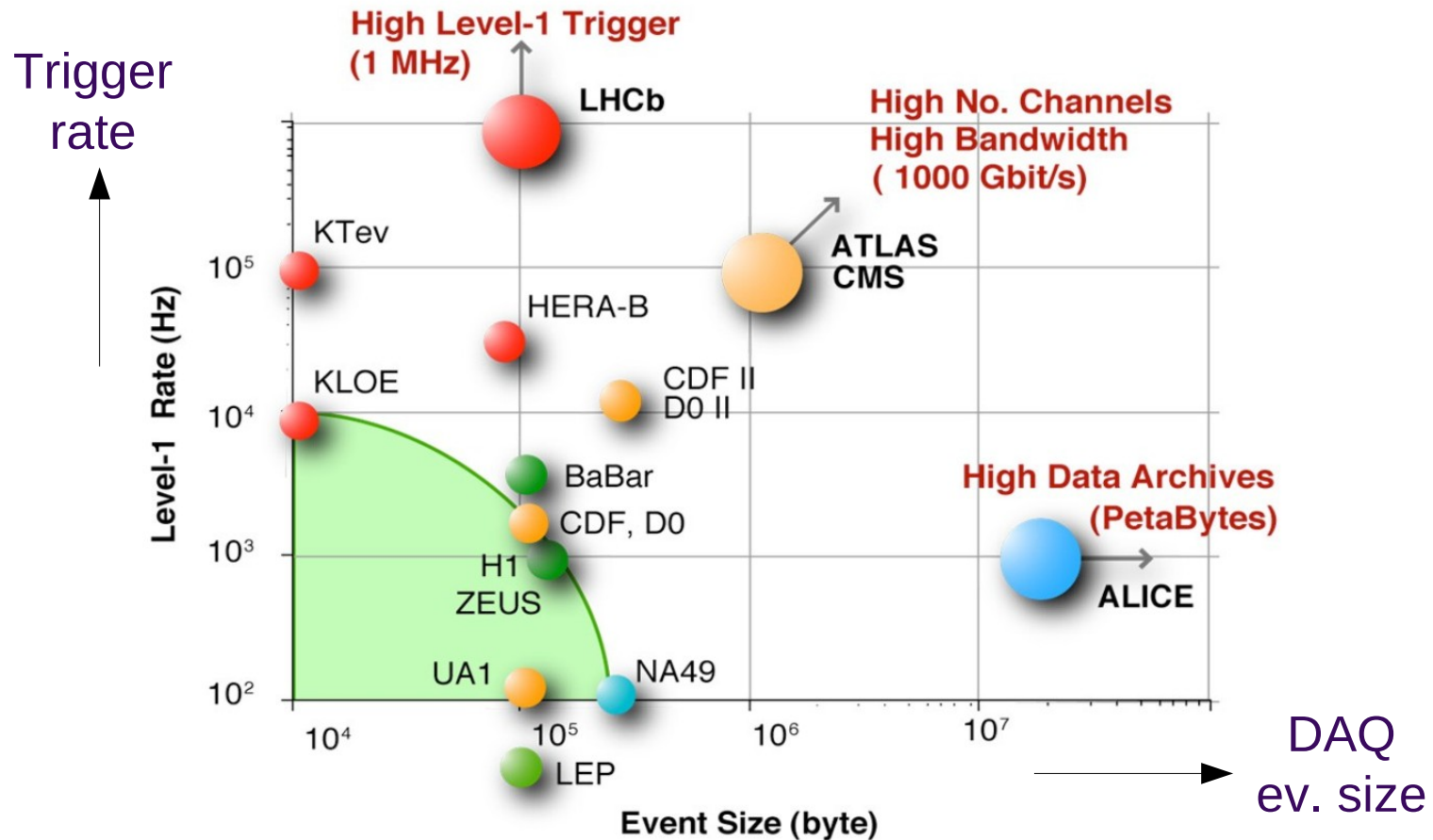
credit to Sergio Ballestrero
most material from his talk at ISOTDAQ 2015



Trigger/DAQ design:
from test beam
to medium size experiments

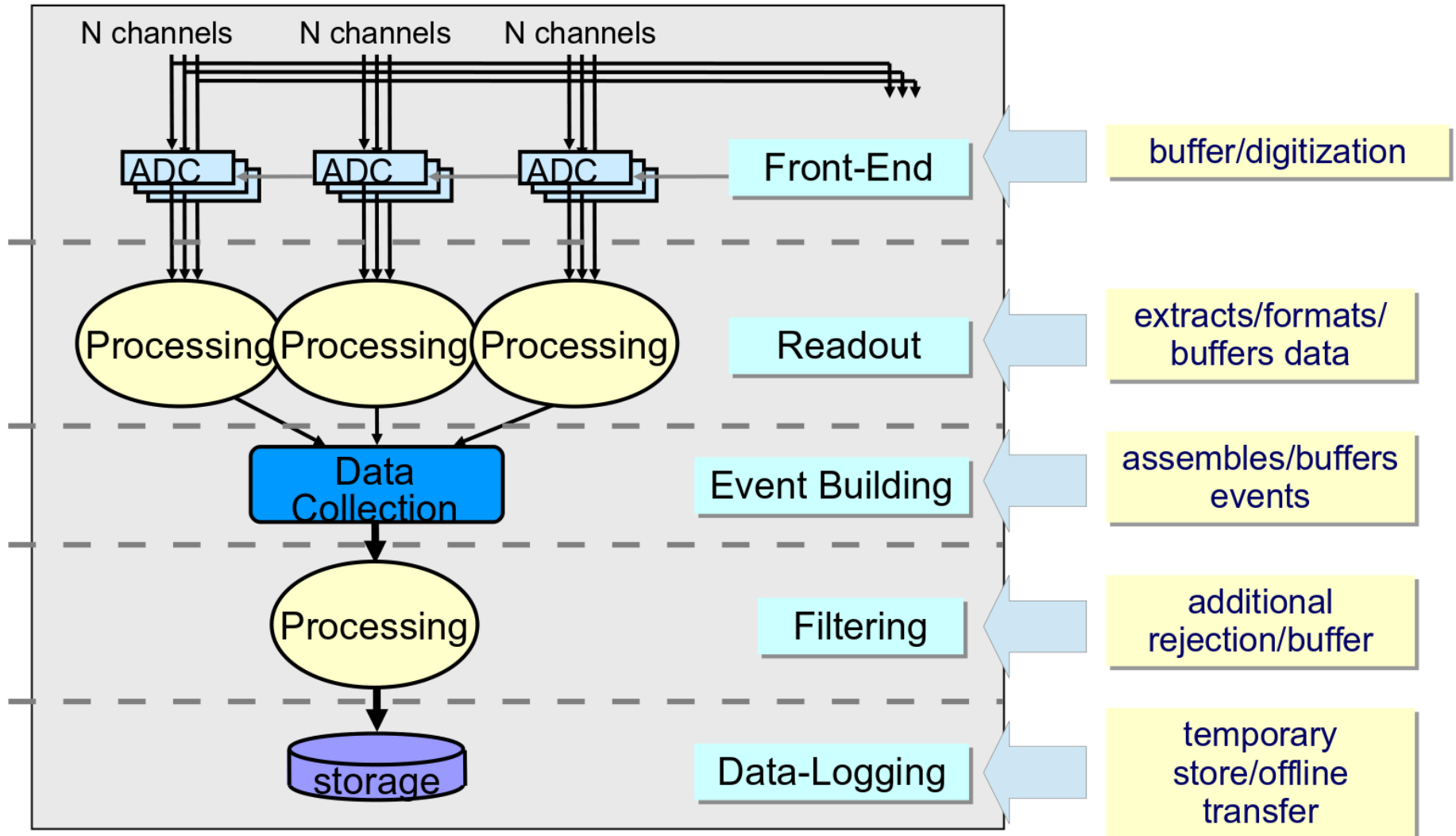


Trigger & DAQ in HEP



different issues → different solutions
no magic, unique solution for all cases

medium/large DAQ: constituents



breakdown into 5 steps ...

- Step 1: Increasing rate
- Step 2: Increasing sensors
- Step 3: Multiple front-ends
- Step 4: Multi-level trigger
- Step 5: Data-flow control

back to square one

A minimal system: what do we need ?

back to square one

Do we really need a trigger ?

back to square one

Do we really need a trigger ?

not obvious ... triggerless DAQ systems do exist

back to square one

Do we really need a trigger ?

not obvious ... triggerless DAQ systems do exist

even in HEP experiments

back to square one

Do we really need a trigger ?

not obvious ... triggerless DAQ systems do exist

even in HEP experiments

e.g.:

a) LHCb upgrade: 40 MHz readout

b) DUNE: LAr TPC 2 MHz readout

*however, in most cases,
triggering is crucial !*

how trigger is born

how trigger is born

Walther Bothe (1924-1929):

offline → online coincidence (logic **AND**) of 2 signals

Bruno Rossi (Nature, 1930):

"Method of Registering Multiple Simultaneous Impulses of Several Geiger Counters"

→ online coincidence of 3 signals (scalable)!

first modern trigger

Coincidence circuit [wikipedia]:

“Rossi coincidence circuit was rapidly adopted by experimenters around the world. It was the first practical AND circuit, precursor of the AND logic circuits of electronic computers”

Geiger-Muller
counters

Rossi's circuit: coincidence of
signals of 3 Geiger-Muller
counters

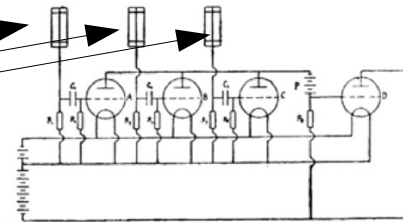


Fig. 17 – Il circuito di Rossi per rivelare coincidenze di raggi cosmici che arrivano sui contatori Geiger (i rettangoli in alto dello schema)¹⁹.

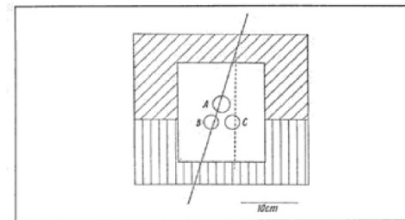


Fig. 18 – L'uso del circuito di Rossi per rivelare una coincidenza tripla che, nella disposizione in figura dei tre contatori, mostra la produzione di una radiazione secondaria (linea tratteggiata) da parte della radiazione primaria (linea continua)²⁰.

simplest case: 2-signal
coincidence

a simple trigger system

Gokhan's talk:

$$N1 = s1 \cdot s2 \cdot \overline{s3}$$

Veto (anti-coincidence)

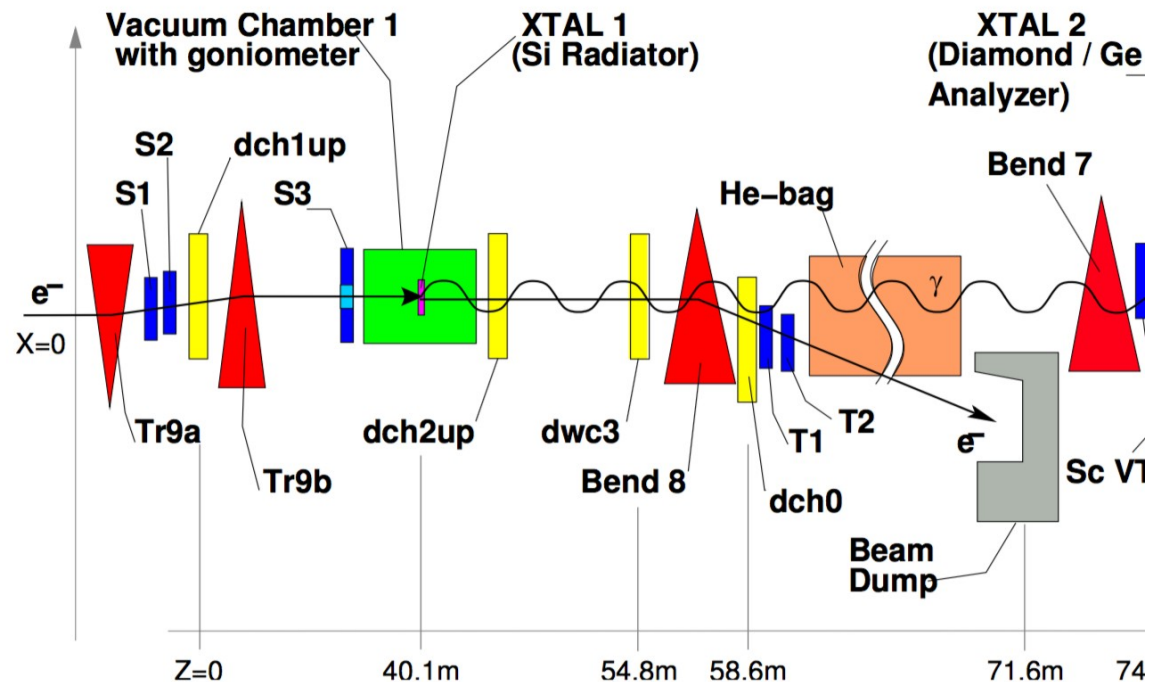
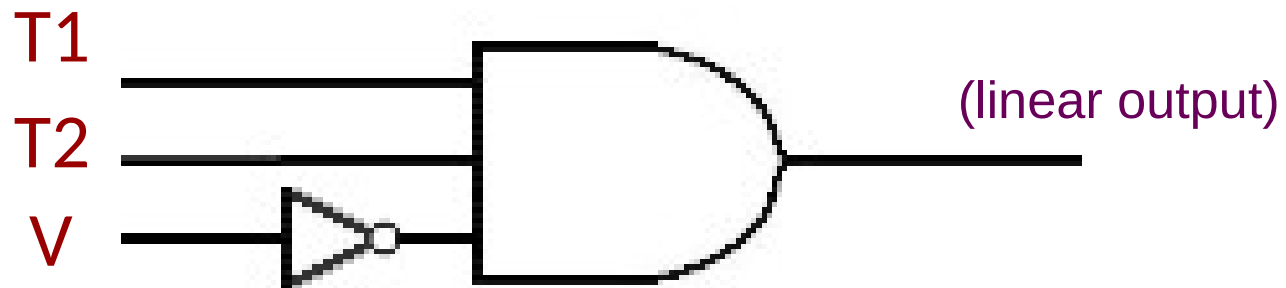


Fig. 1. Setup of the Na59 Experiment

any issue ?

any issue ?

T1, T2, V : logic pulses (“0/1” values)

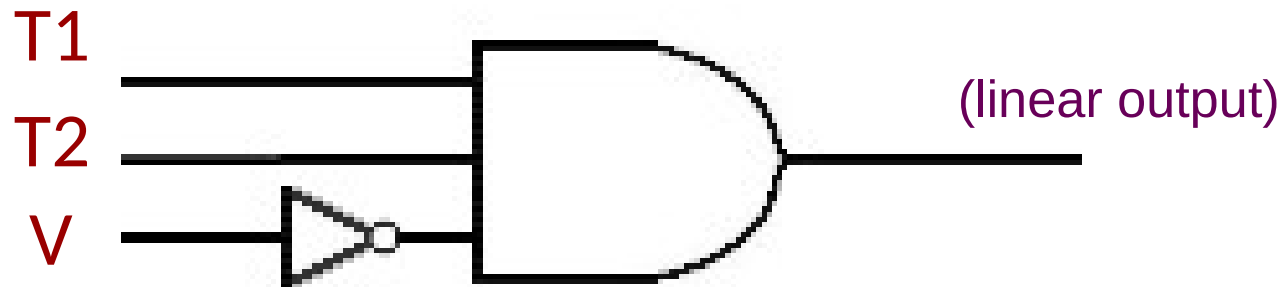


(anti-)coincidence with veto

→ easy !

any issue ?

T1, T2, V : logic pulses (“0/1” values)



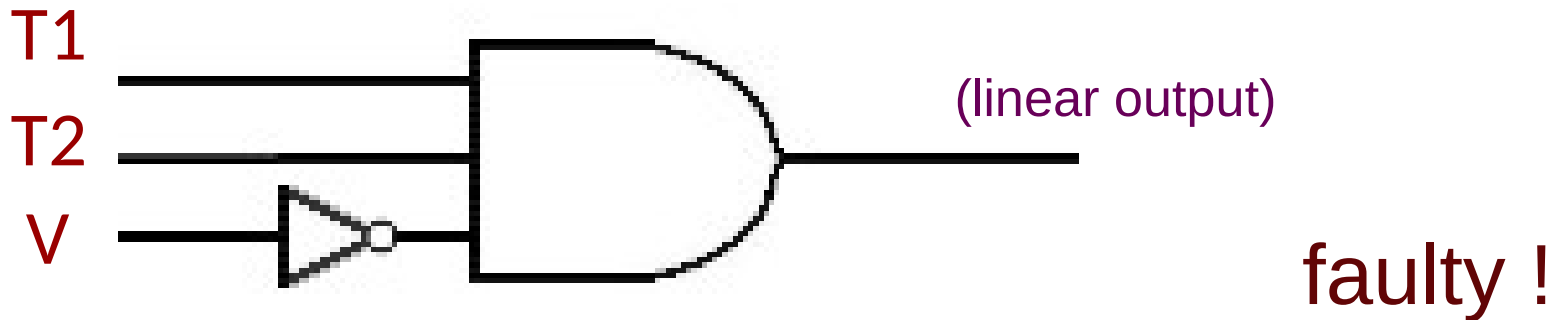
(anti-)coincidence with veto

→ easy !

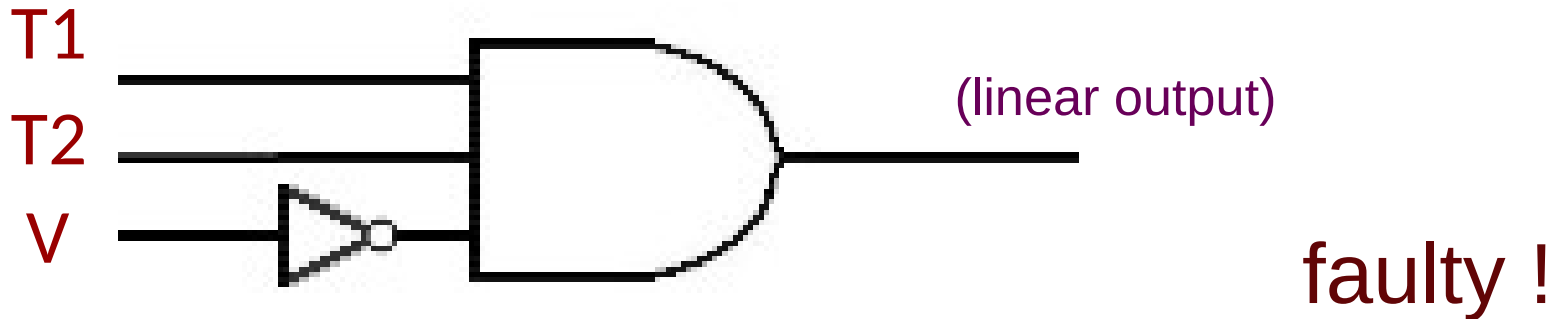
sure it works ?

uh !

(anti-)coincidence with veto



(anti-)coincidence with veto

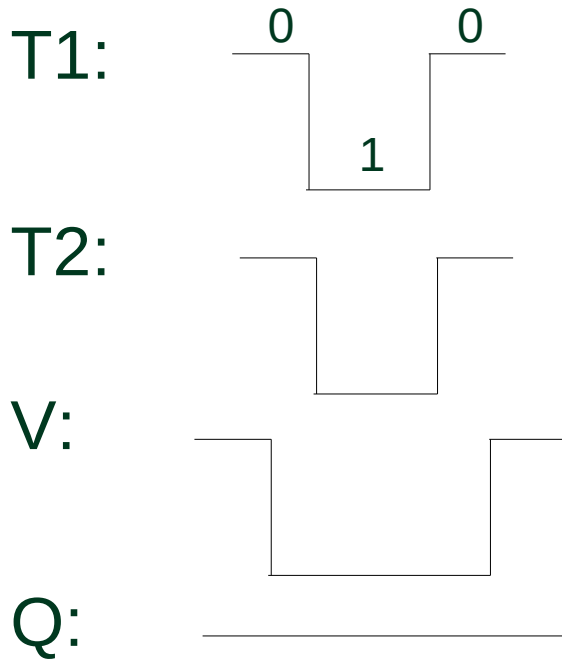


output signal does:

- a) jitter
- b) fluctuate in duration

why ?

(good) in-time signals



NIM signals:

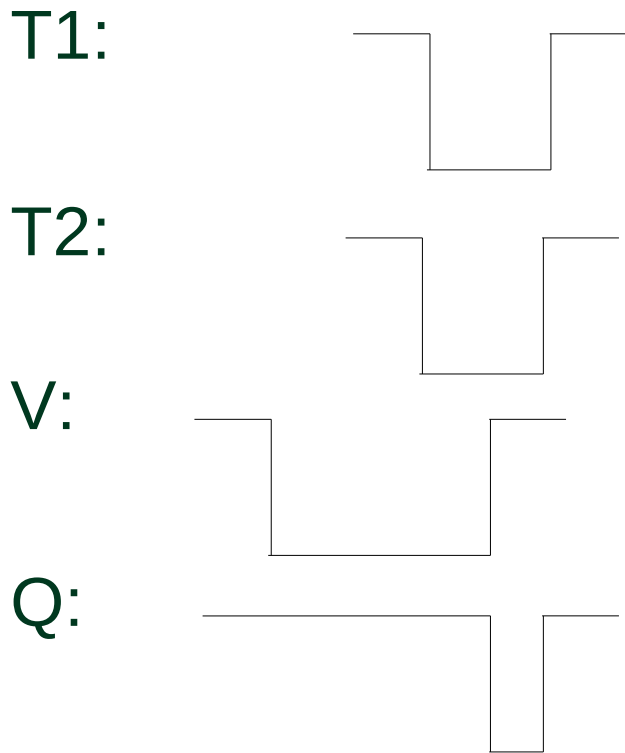
0 \Leftrightarrow 0 V

1 \Leftrightarrow - 800 mV

1) T1 and T2 (almost) perfectly in time

2) In case it is present, V totally covers in time T1 and T2

(bad) out-of-time signals

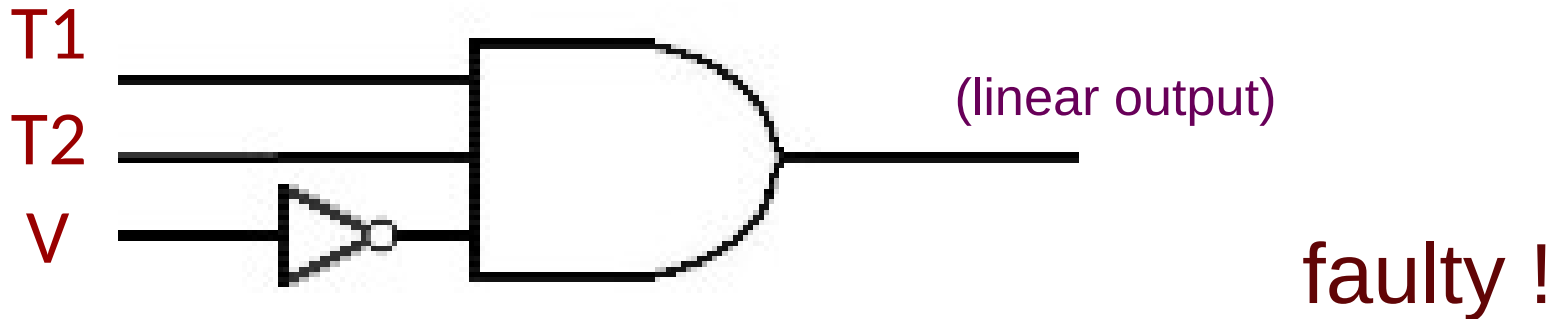


in some cases:

wrong transition time or **wrong** duration or **both**

(anti-)coincidence with veto

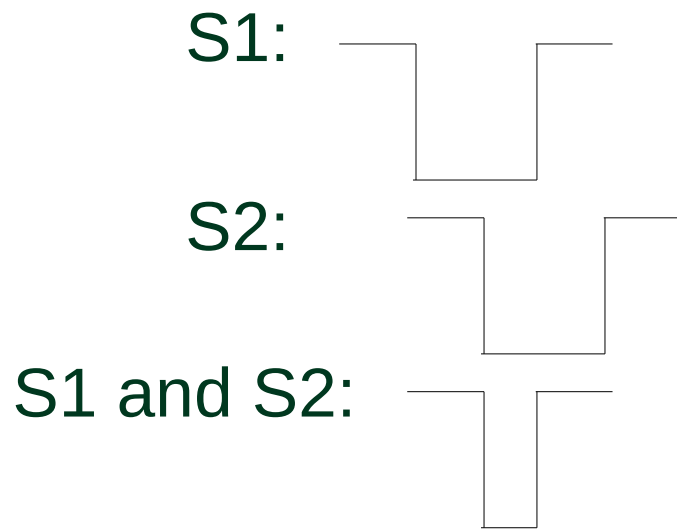
combinatorial logic



output signal will:

- a) jitter
- b) fluctuate in duration

because of independent signals from T1, T2, V



independent → uncorrelated (e.g. random) signals

→ even without veto, output needs to be formed

Shit!

S...!

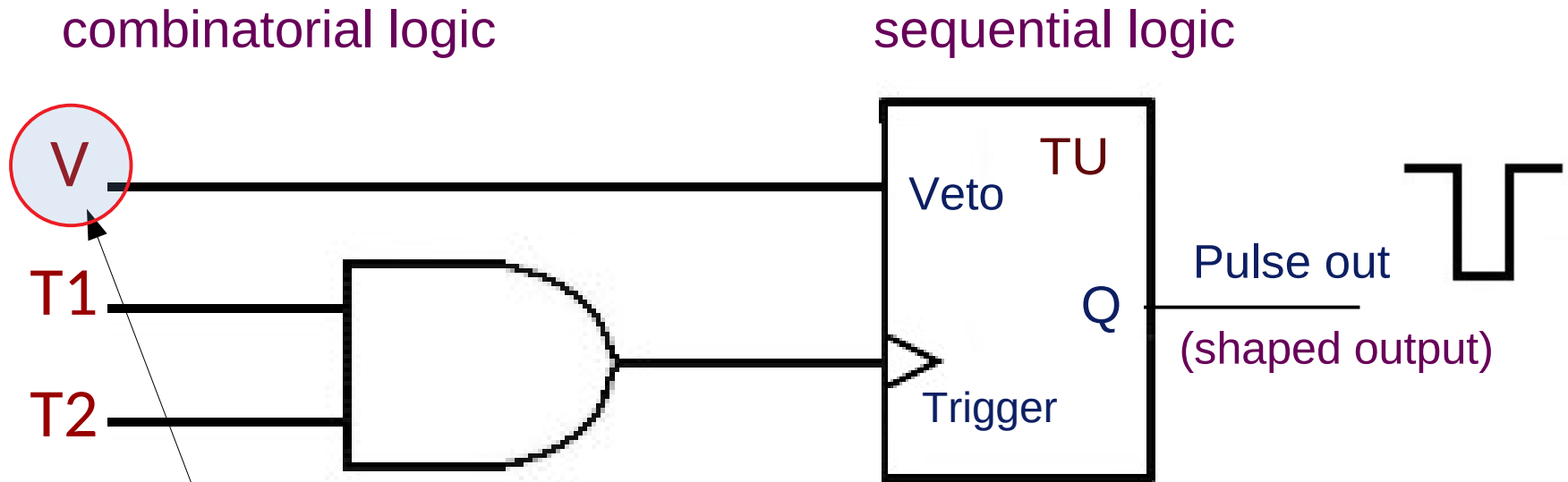
*You designed a "perfect" trigger
but simple random coincidences are
sufficient to break it*

S...!

*You designed a "perfect" trigger
but simple random coincidences are
sufficient to break it*

*can't even blame high rate, pileup, ...,
locusts*

(anti-)coincidence with veto



can also be a busy
signal → busy logic

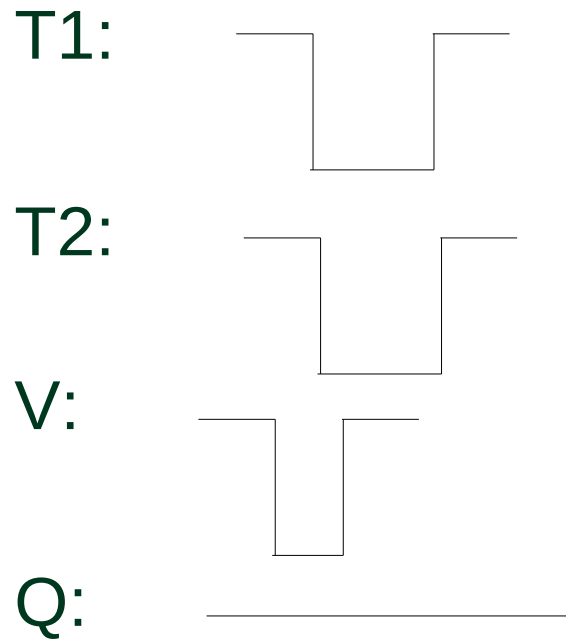
TU = Timing Unit

aka Monostable Multivibrator

aka One-Shot Pulse Generator

much better !

now



1) V only covers transition region ($0 \rightarrow 1$) of T1 and T2

2) lower dead time

T1 and T2 → transition time

TU → duration time

T1 and T2 → transition time

TU → duration time

Q: What the relevant information?

first lesson(s)

trigger signal:

1) should be formed!

→ pulse with predefined duration

2) veto/busy should block pulse generation

3) need both combinatorial (AND, OR, NOT)
and sequential logic (TU, FF)

step one: increase rate

Many issues:

- trigger latency
- readout latency
- throughput
- rate fluctuations (trigger bursts)
- throughput fluctuations
(correlated noise, ...)

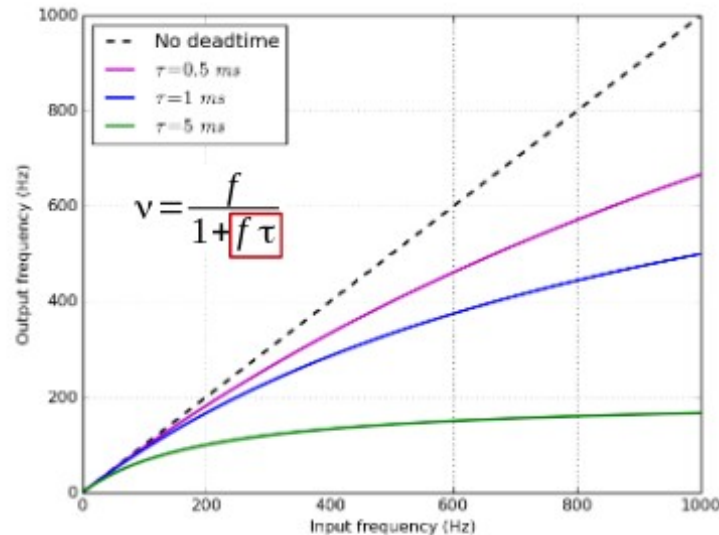
step one: increase rate

Many issues:

- trigger latency
- readout latency
- throughput
- rate fluctuations (trigger bursts)
- throughput fluctuations
(correlated noise, ...)
- dead-time

deadtime (from Andrea's introduction)

Deadtime and efficiency

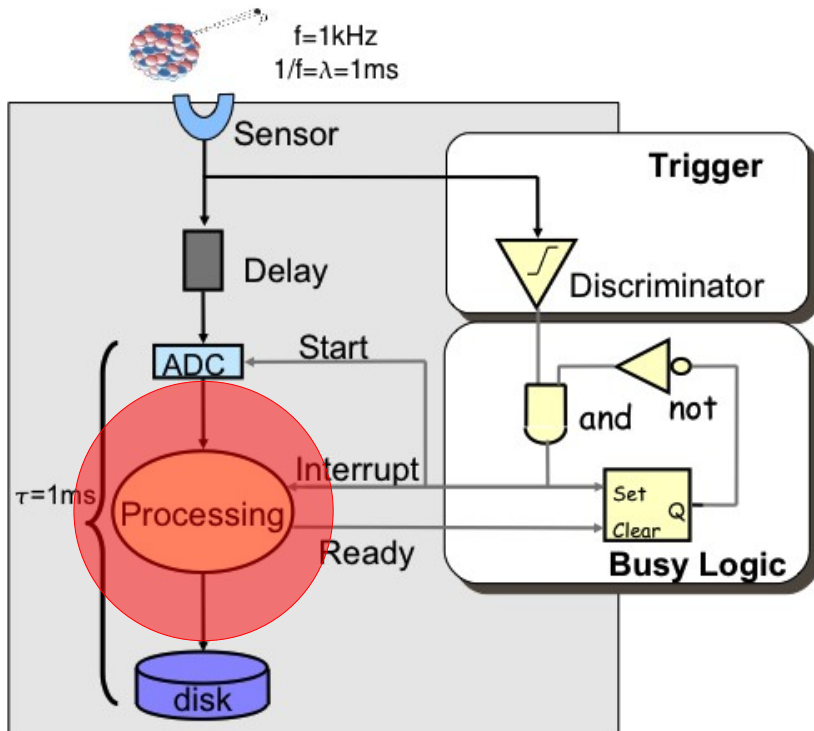


- In order to obtain $\varepsilon \sim 100\%$ (i.e.: $v \sim f$) $\rightarrow f\tau \ll 1 \rightarrow \tau \ll \lambda$
 - E.g.: $\varepsilon \sim 99\%$ for $f = 1 \text{ kHz}$ $\rightarrow \tau < 0.01 \text{ ms} \rightarrow 1/\tau > 100 \text{ kHz}$
 - To cope with the input signal fluctuations, we have to **over-design** our DAQ system by **a factor 100**
- How can we mitigate this effect?



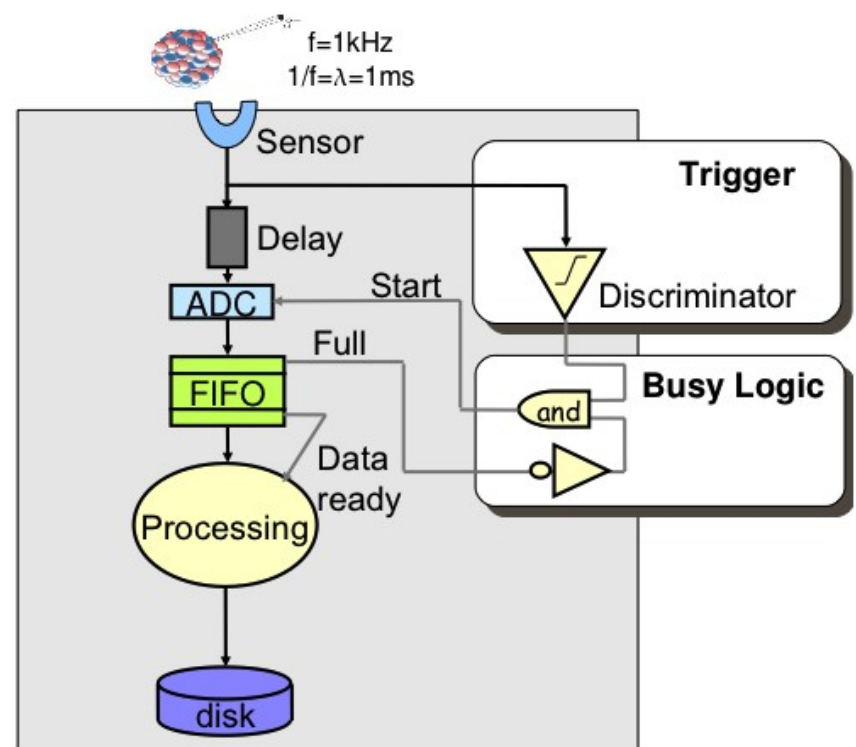
deadtime → de-randomise

- Processing → bottleneck ?



$(f \cdot \tau) \sim 1 \rightarrow \text{deadtime} \sim 50\%$

- Buffering → decouple problems



What the impact ?

$(f \cdot \tau) \sim 1 \rightarrow \text{deadtime?}$

FIFO

First-In First-Out memory:

- 1) independent read/write (sequential) access
- 2) may be hardware or over RAM

if RAM better Dual-Port RAM

buffering solve all problems ?

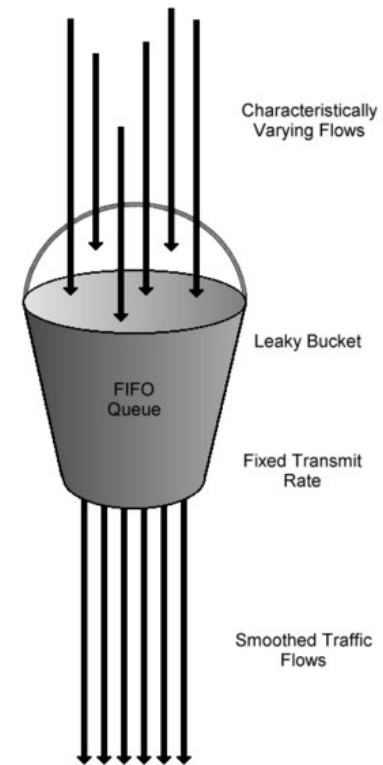
- FIFO (front-end buffers)

1) filling at very variable input flow

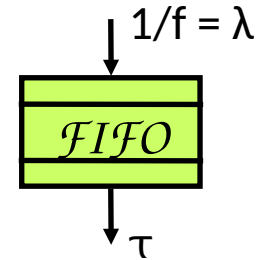
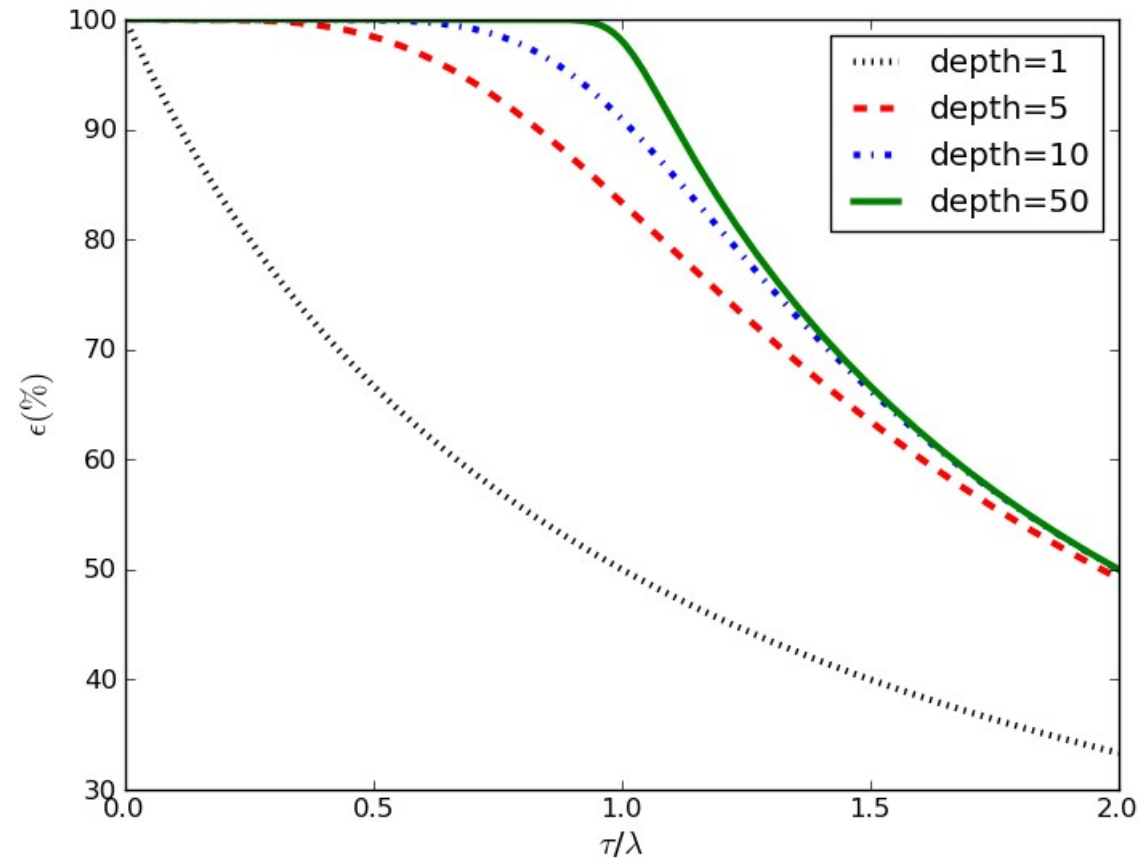
2) emptying at smoothed output flow

→ the Leaky-Bucket problem

Q: how often may overflow?



de-randomisation



- DAQ $\epsilon \sim 100\%$ with:
 - $\tau \sim 1/f$
 - “moderate” buffer size
- Two degrees of freedom to play with
- This deadtime often managed by trigger system itself (“complex deadtime”)

deadtime in trigger system

1) Simple deadtime: avoid overlapping (conflicting) readout window

2) Complex deadtime: avoid overflow in front-end buffers (protection against trigger bursts)

→ different subdetector & different front-end elx

→ different algorithm/parameters

ATLAS deadtime @ end of run 2

1) Simple deadtime: 4 LHC BC [i.e. 100 ns] after any LVL-1 trigger

2) Complex deadtime:

2.a) four leaky-bucket algorithms

[two params: bucket size S (in number of events), readout time R (in BC units)]

1) 15 / 370 for LVL-1 Calorimeter and CSC readout

2) 42 / 384 for TRT readout

3) 9 / 351 for LAr readout

4) 14 / 260 for LVL-1 Topo readout

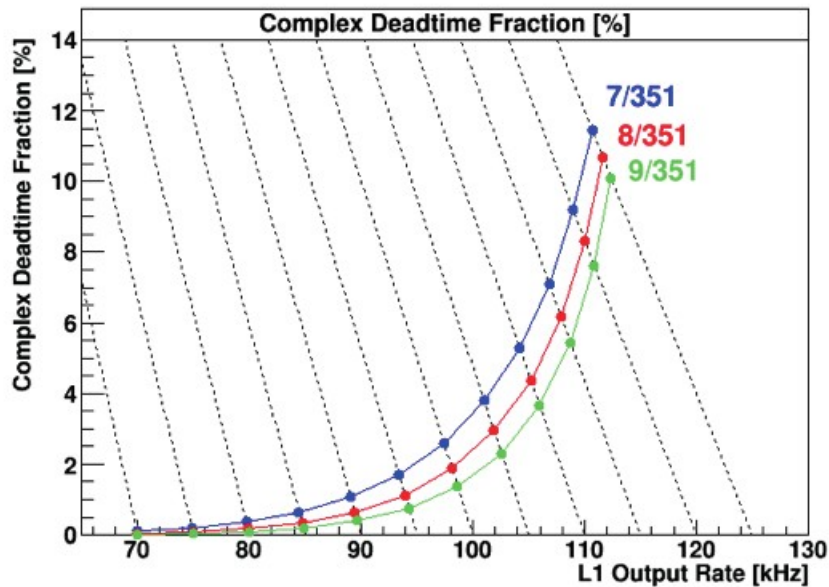
2.b) one sliding-window algorithm

< 16 LVL-1 signals in any 3600 BC sliding window

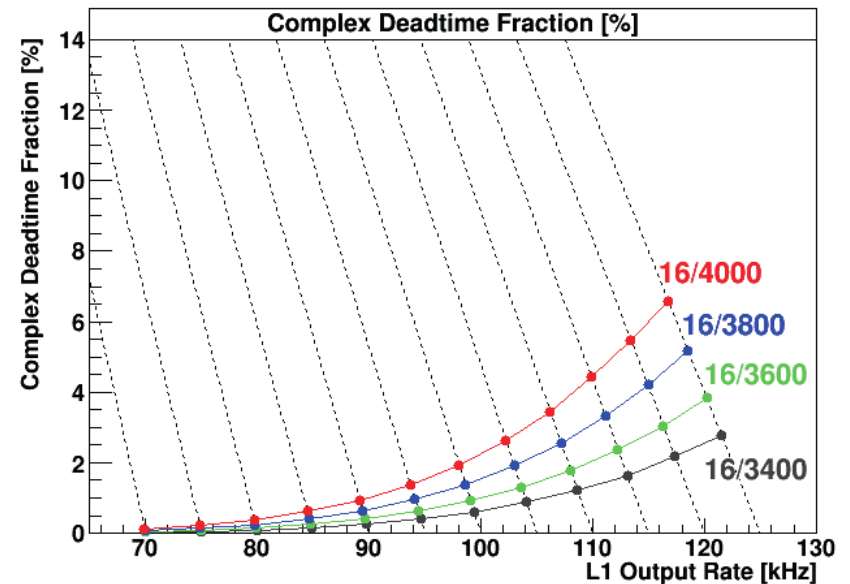
ATLAS deadtime @ end of run 2

Total deadtime @ 90 kHz trigger rate < 2%

Leaky bucket (LAr readout)

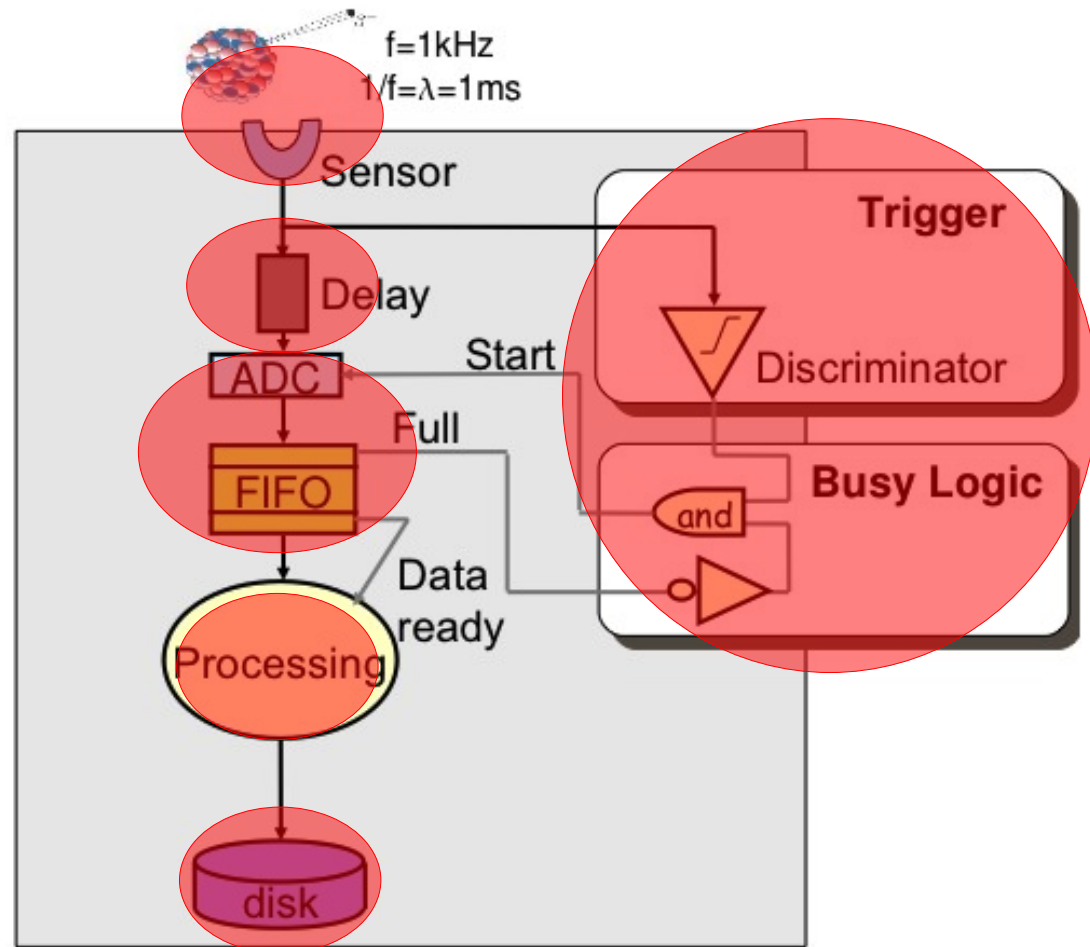


Sliding window (SCT readout)



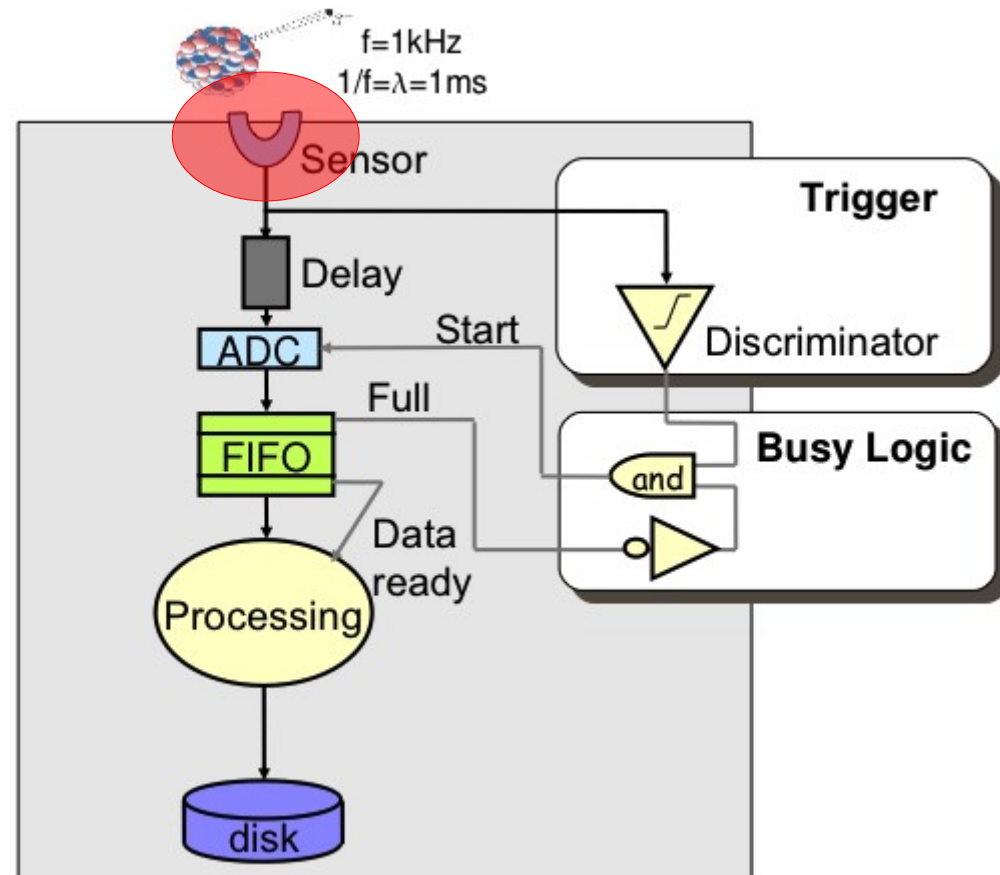
game over ?

many other possible
limits even in a simple
DAQ



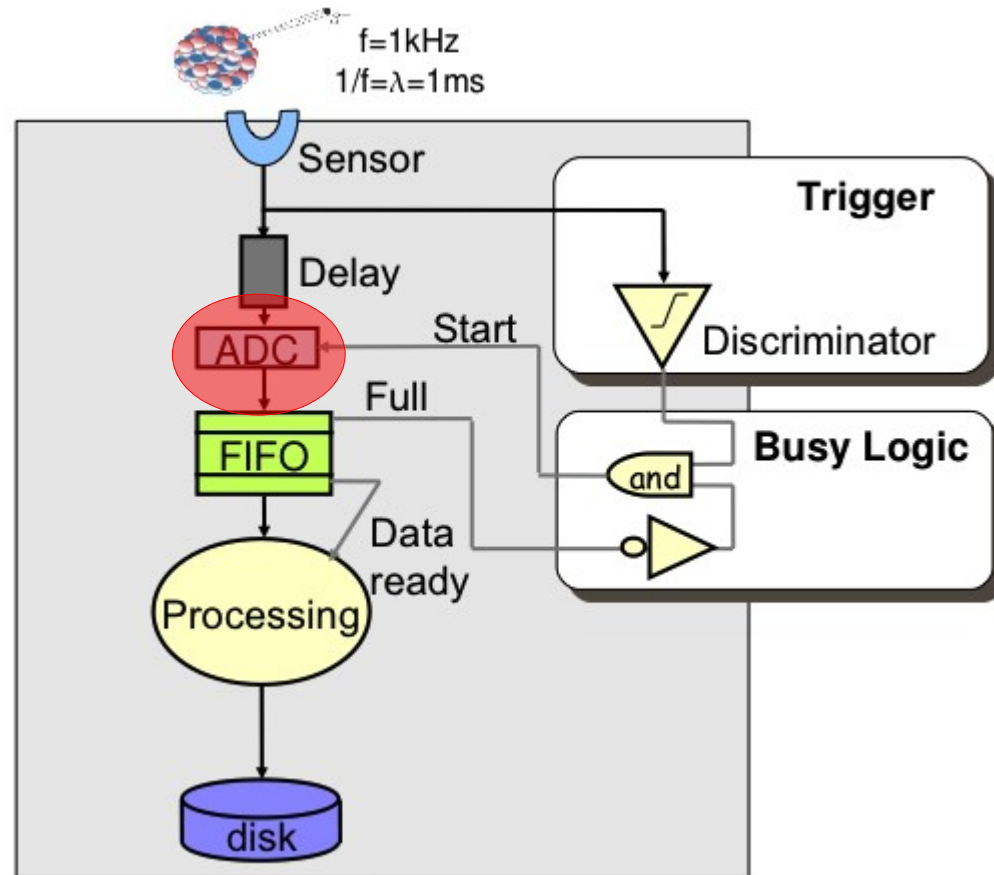
→ sensor

- Sensors limited by physical processes such as:
 - drift times in gases
 - charge collection in Si
- (possibly) choose fast processes
- analog FE imposes limits as well
- split sensors, each gets less rate:
“increase granularity”



→ ADC

- A/D conversion also limited
- Fast ADC
 - # of bits (resolution)
 - power consumption
- Alternatives:
 - analog buffers
 - (e.g. switched capacitor arrays)
- You may need integration (or sampling) over quite some time

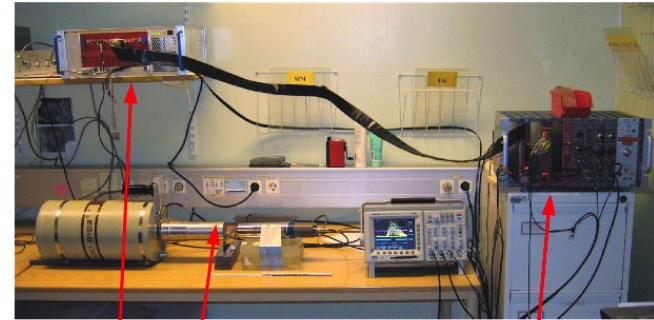


an example

- HPGe + NaI Scintillator
High res spectroscopy and beta+ decay identification
- minimal trigger with busy logic
- Peak ADC with buffering, zero suppression
- VME SBC with local storage
- Root for monitor & storage
- Rate limit ~14 kHz
 - HPGe signal shaping for charge collection
 - PADC conversion time



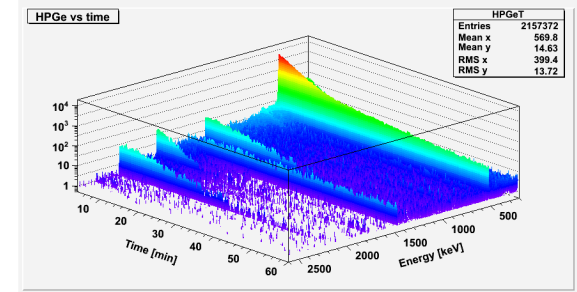
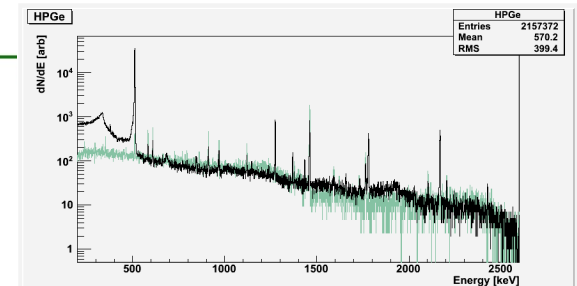
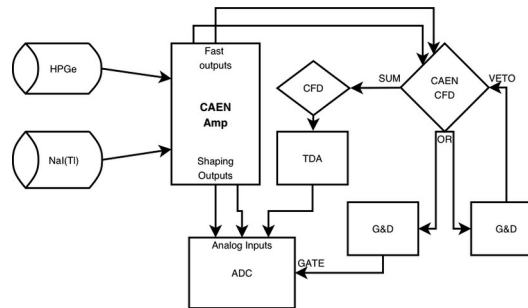
Ge crystal for isotope identification



Crystal HPGe

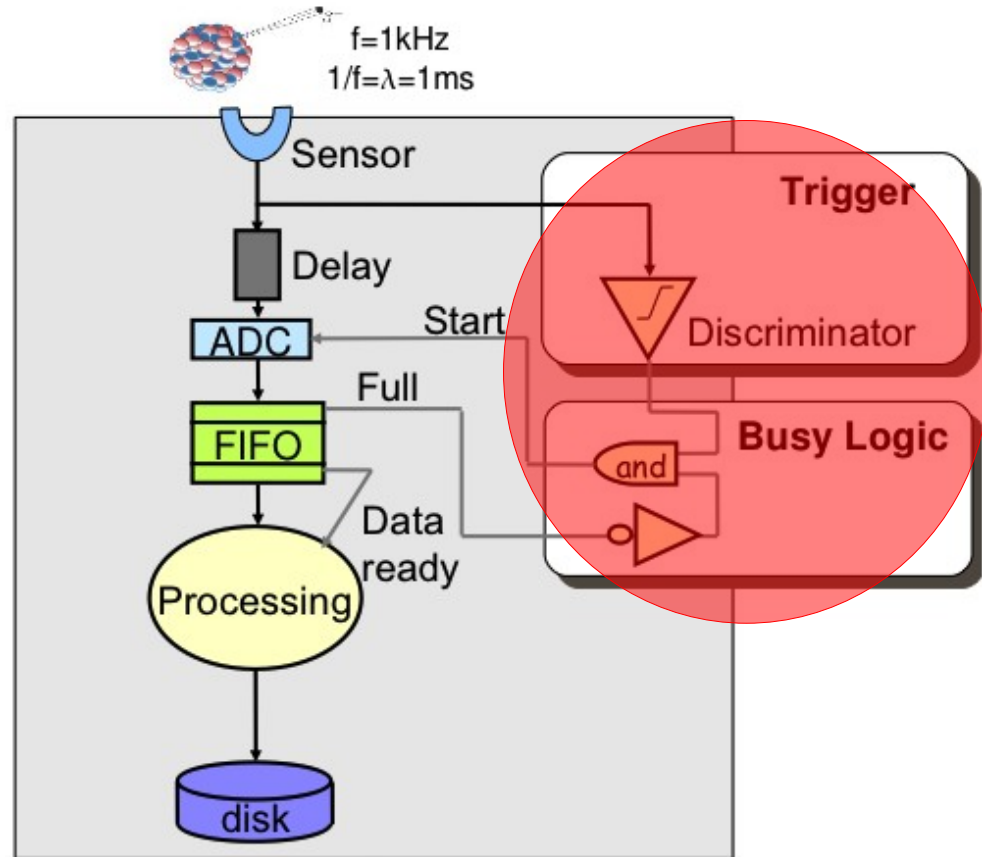
Readout (ADC)

Trigger & front-end



→ trigger latency

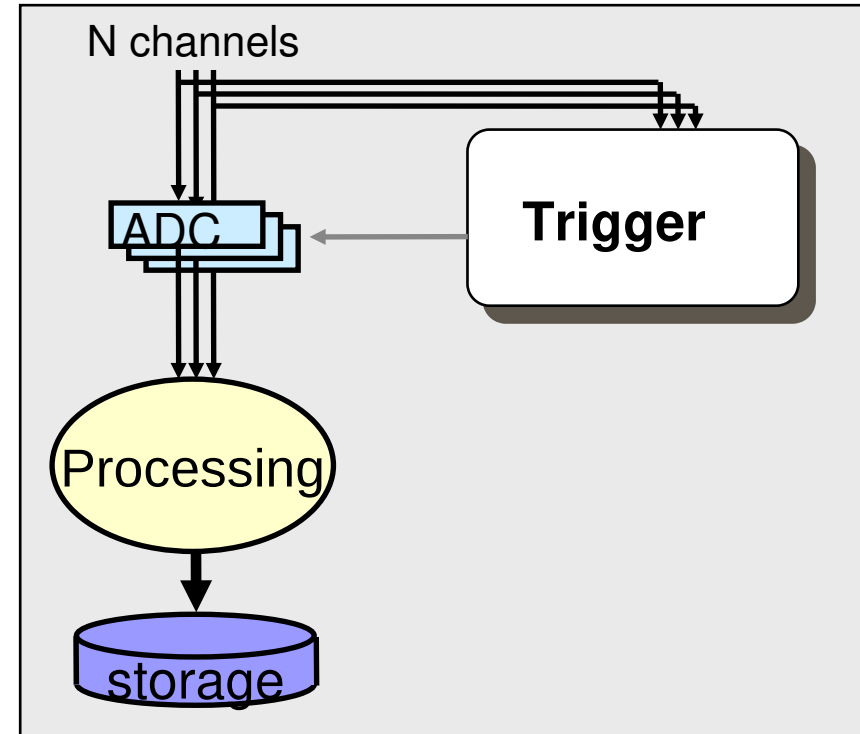
- simple trigger: ~fast
- complex trigger logic: not obvious [even when all in hw]
- some trigger detectors may be far away / slow → latency
- trigger signal is one: all information at a single point
 - in one step:
too many cables
 - in many steps:
delays



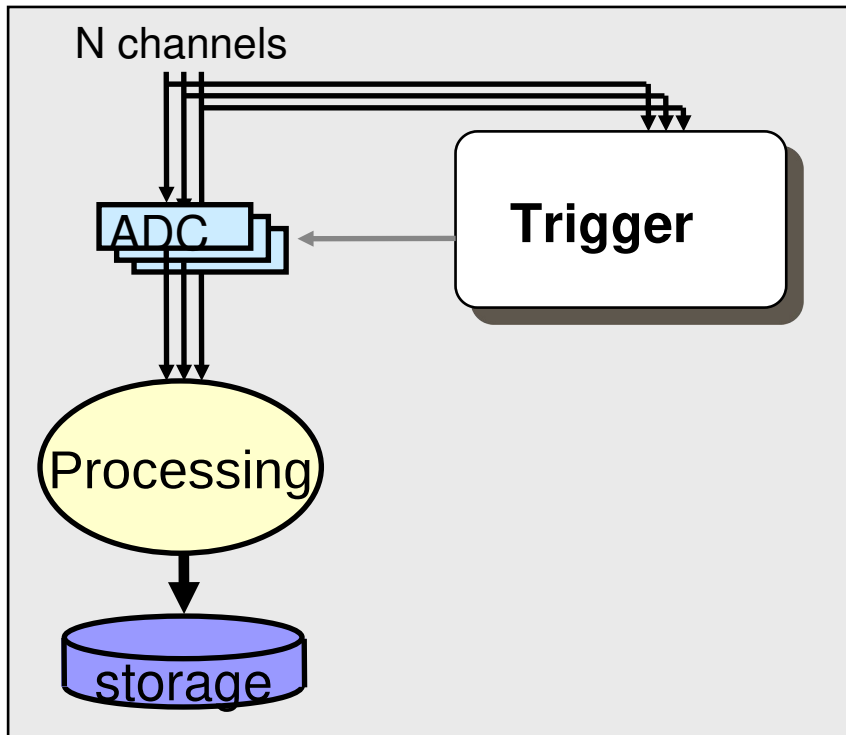
→ discrete modules: ~ 5-10 ns delay → tot. latency $\geq 20\text{-}30\text{ ns}$ ←

step two: increase # of sensors

- More granularity at the physical level
- Multiple channels (usually with FIFOs)
- Single, all-HW trigger
- Single processing unit
- Single I/O

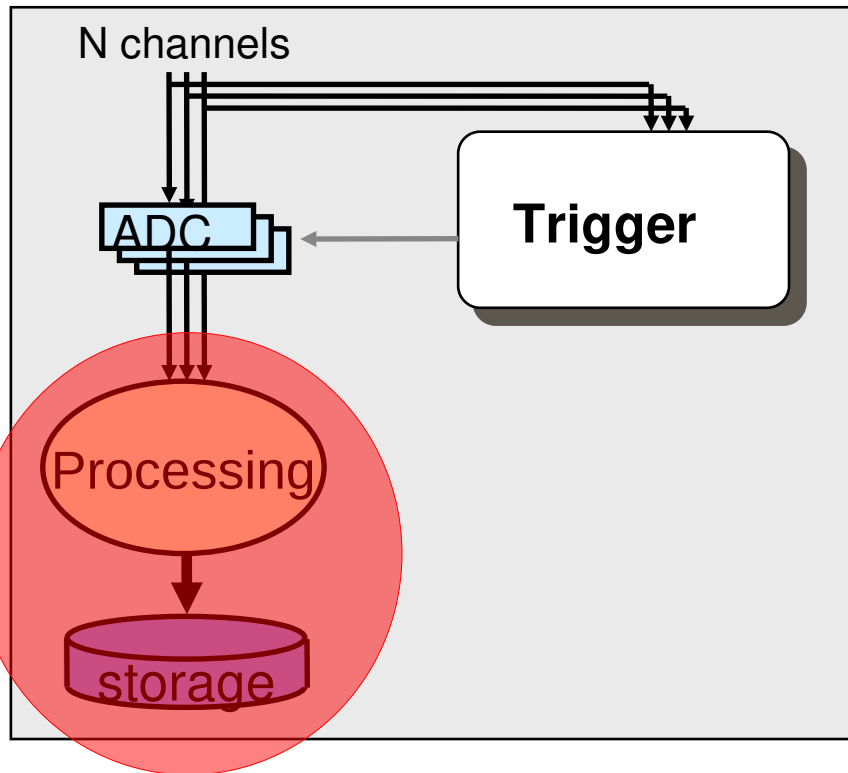


multi-channel, single-PU system



- common architecture in test beams and small experiments
- often rate limited by (interesting) physics itself, not TDAQ system
- or by the sensors

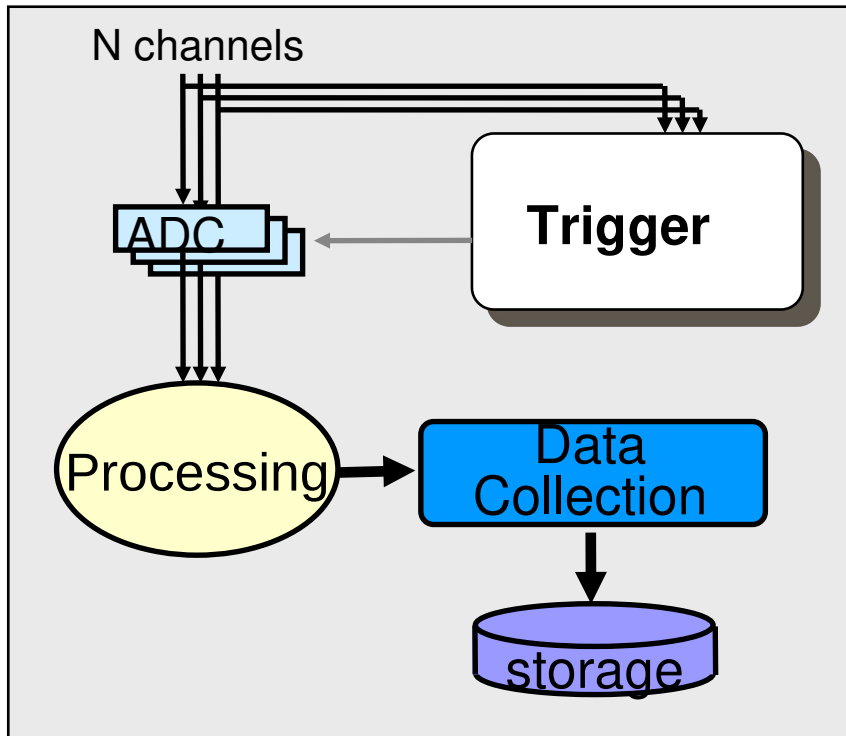
bottlenecks: PU and storage



- a single PU can be a limit
 - collect / reformat / compress data can be heavy
 - simultaneously writing storage
- final storage too:
 - VME up to 50MB/s
 - 1TB in 6h
 - too many disks in a week!

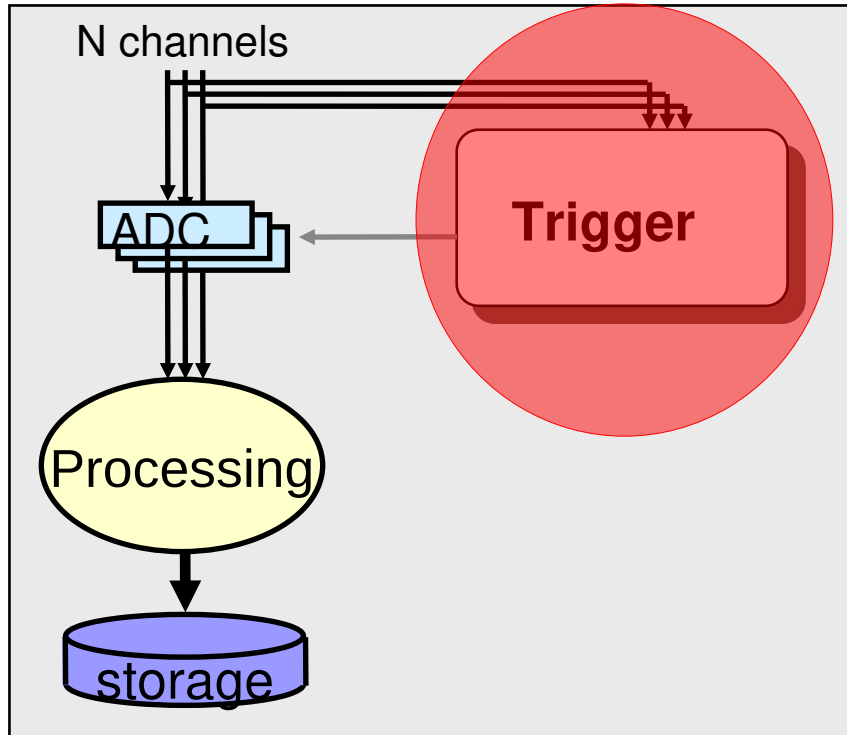
Laptop SATA disk: ~ 100 MB/s
USB2: ~ 60 MB/s

→ decouple storage from PU



- data transfer data → dedicated “Data Collection” unit to format, compress and store
- more room for smarter processing or decreased deadtime on non-buffered ADCs

bottlenecks: trigger



- to reduce data rates
(to avoid storage issues)
→ non-trivial trigger
- complexity may already hit
manageability limits for discrete
logic (latency!)
- integrated, programmable logic
came to rescue (FPGA)
→ latency may go down to
O(few ns)

DREAM/RD52 (2006→): a testbeam case

R&D on dual-readout calorimetry, setup:

- Crystals
- Scintillating/cherenkov fibers in lead/copper matrices
- Scintillator arrays as shower leakage counters
- Trigger/veto/muon counters
- Precision chamber hodoscope → Si beam telescope

... always evolving

acquiring: waveforms, total charge, time information

DREAM/RD52 (2006→): a testbeam case

R&D on dual-readout calorimetry, setup:

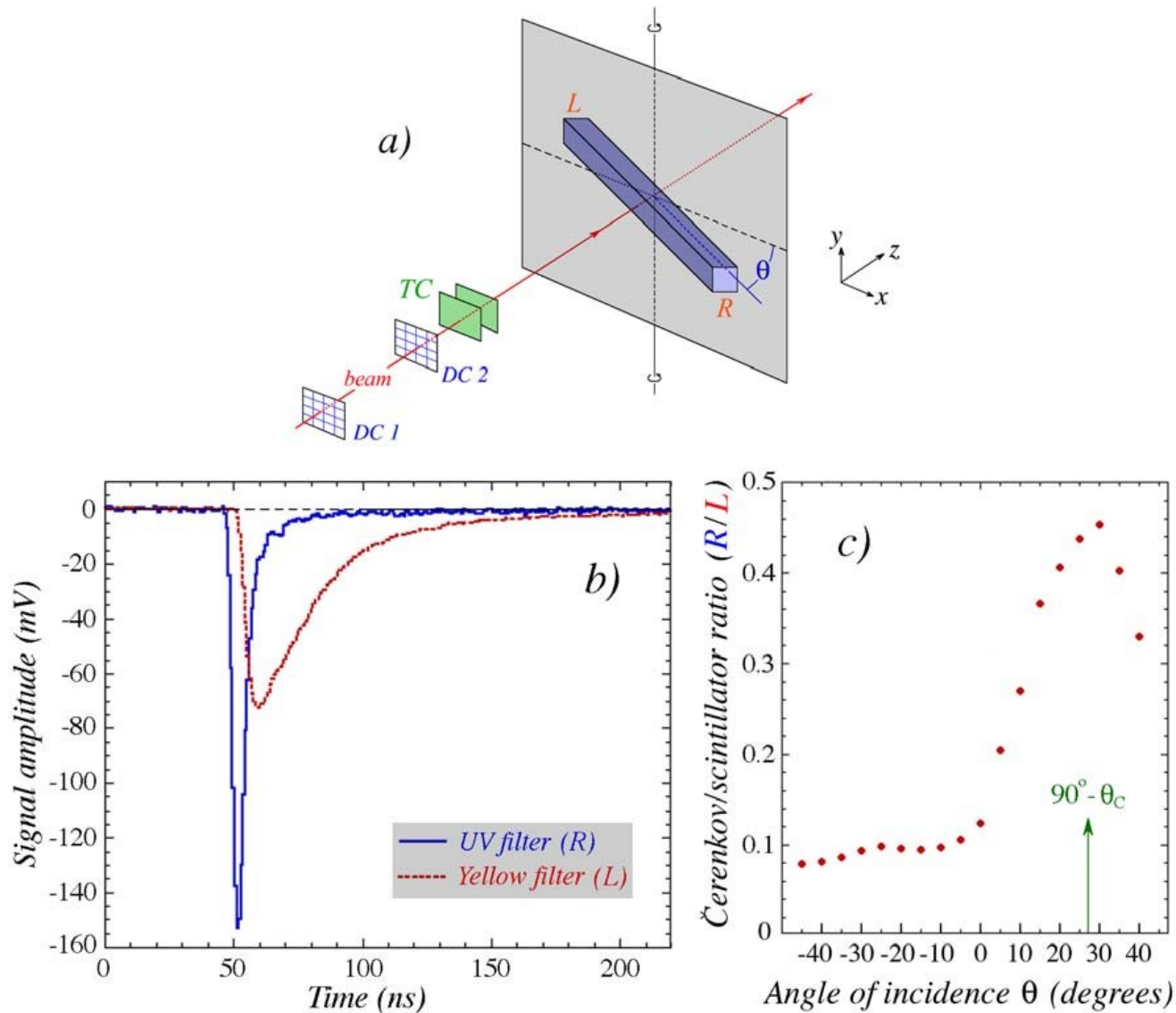
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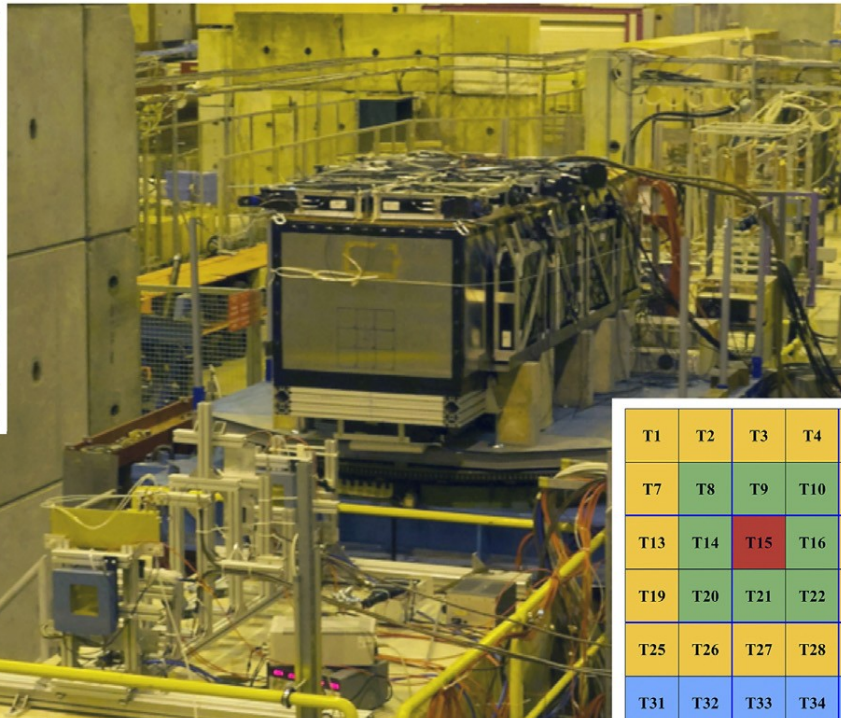
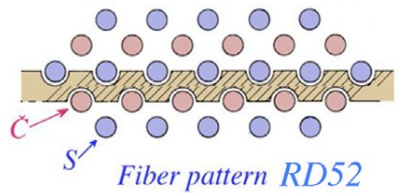
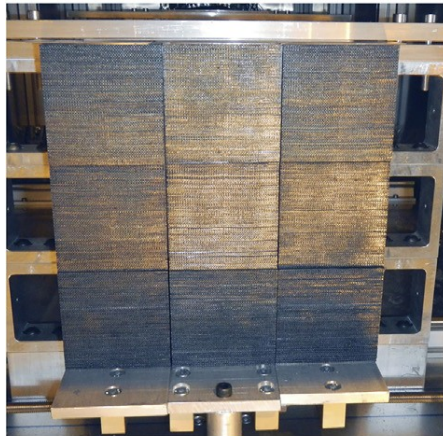
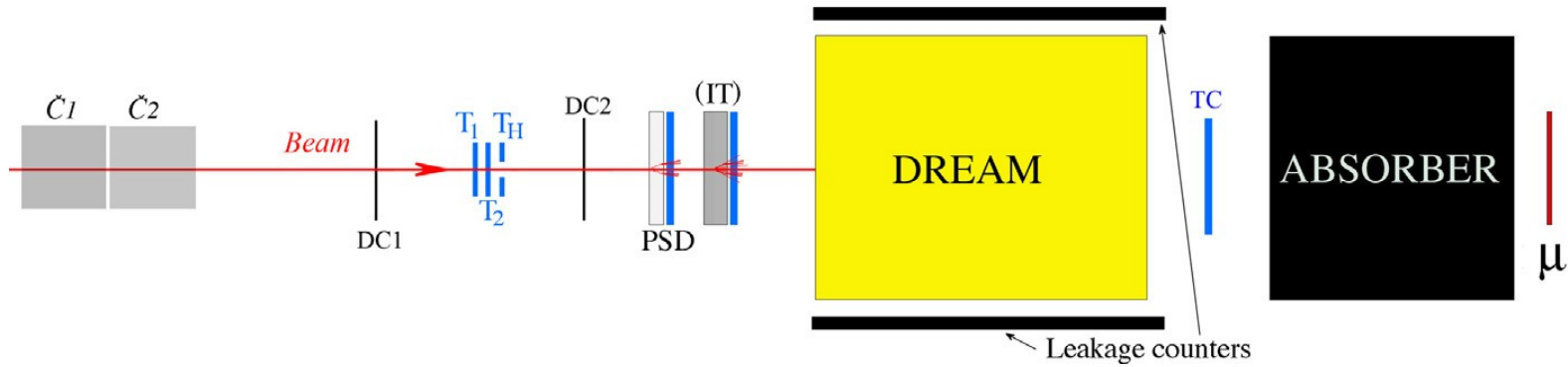
sometime running with 2 or even 3 independent DAQ systems

- trigger and busy signals used for DAQs' synchronisation
- offline event building

DREAM/RD52: crystal prototype



DREAM/RD52: fibre-sampling prototype



T1	T2	T3	T4	T5	T6
T7	T8	T9	T10	T11	T12
T13	T14	T15	T16	T17	T18
T19	T20	T21	T22	T23	T24
T25	T26	T27	T28	T29	T30
T31	T32	T33	T34	T35	T36
Ring 1	Ring 2	Ring 3			

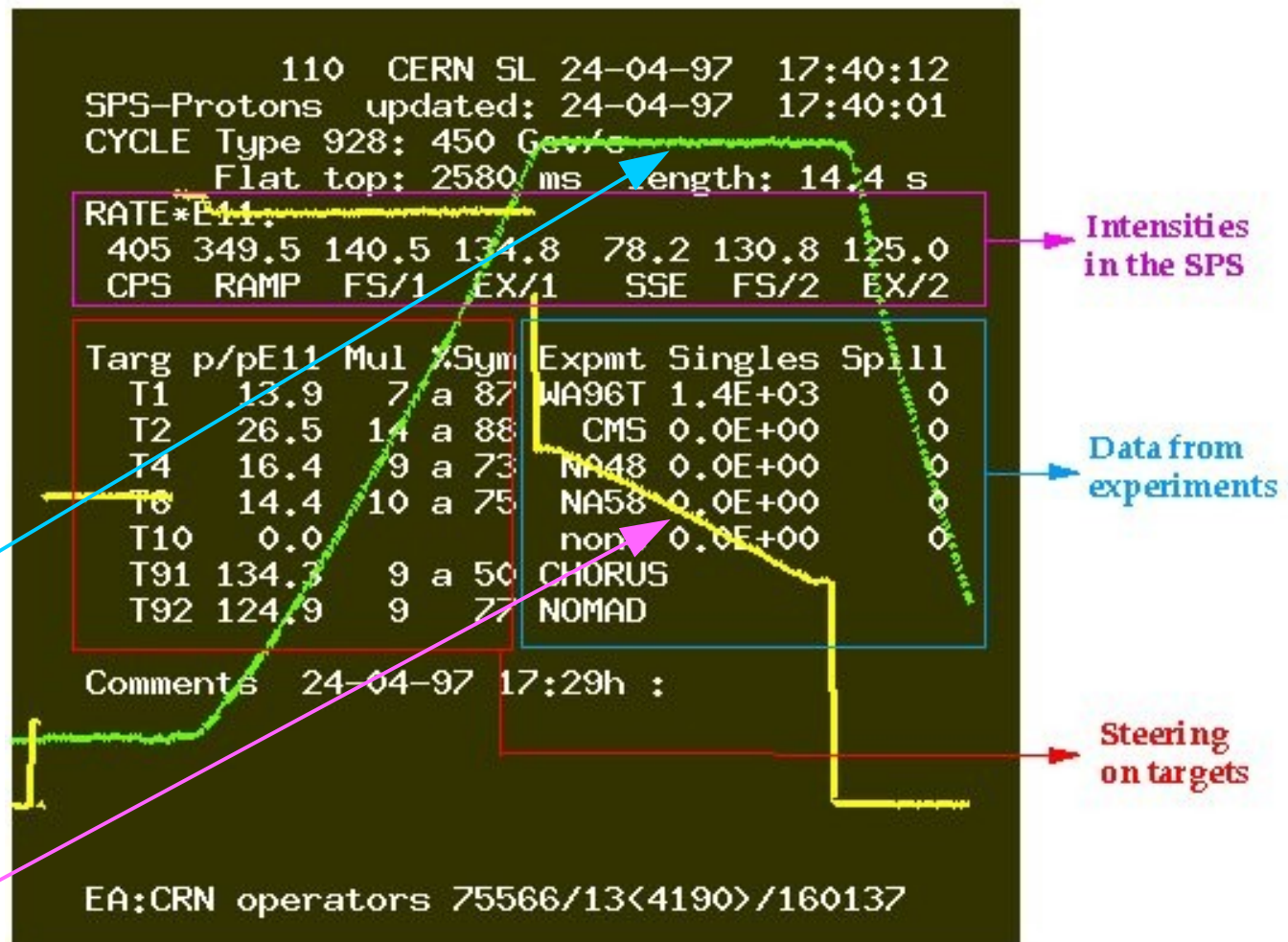
DREAM (2006→): a testbeam case

a possible
SPS cycle

duty cycle:
~ 2 s / 14.4 s
(flat top)

flat top

slow extraction



Trigger = ($\bar{V} \times T_1 \times T_2$ | ped) → easy !

readout system

1 PC → readout of 2 VME crates (via CAEN optical interfaces)

1 PC → storage

6 × 32 ch QDCs + TDCs → CAEN V792, V862, V775

1 × 34 ch (5 Gs/s) digitizer → CAEN V1742
(single event: $\sim 34 \times 1024 \times 12 \text{bit}$)

1 × 4 ch (20 Gs/s) oscilloscope → Tektronix TDS 7254B

... few VME I/O & discriminator boards

... all in the control room

dataflow

1) Pull mode → FE electronics waiting for PC readout
(self-blocking trigger, re-enabled after readout)

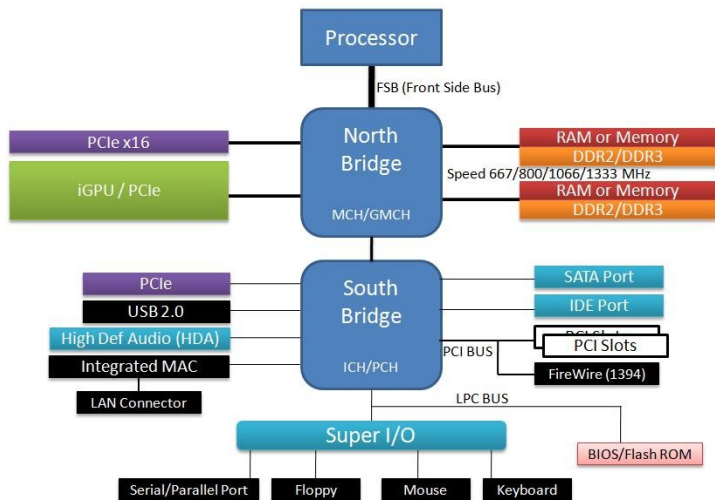
2) Block data transfer → DMA (Direct Memory Access)
data moved by specialised hw (not by CPU)

[Push mode → FE electronics sending data as soon as
available]

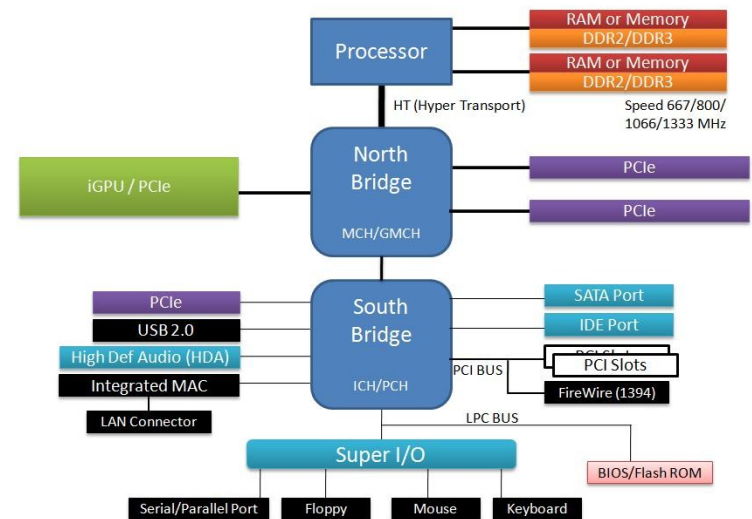
off-topic: computer architecture

main actual implementations

Intel Motherboard Architecture



AMD Motherboard Architecture

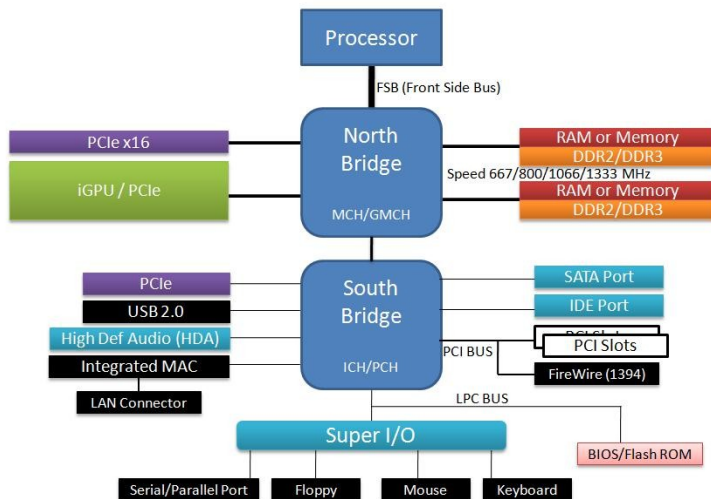


North Bridge: graphics and memory controller hub
South Bridge: I/O controller hub

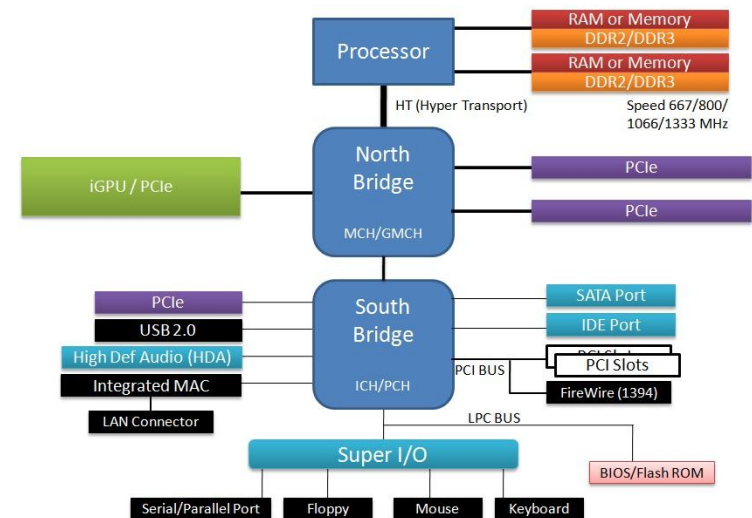
off-topic: computer architecture

main actual implementations

Intel Motherboard Architecture



AMD Motherboard Architecture



→ is really tuned for data acquisition ?

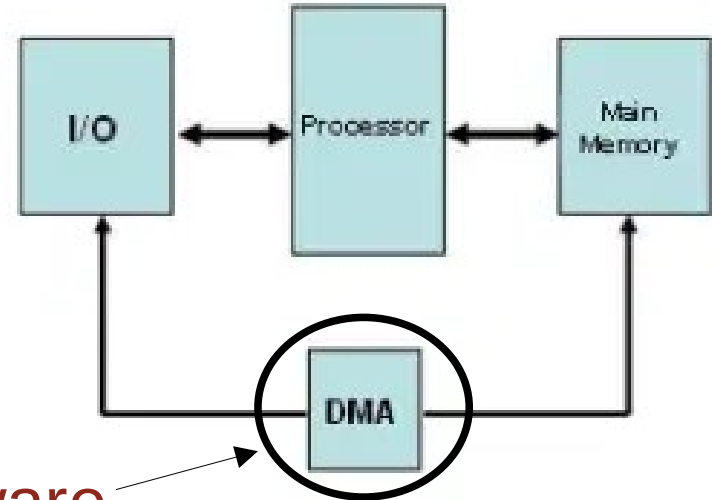


Well, nobody's perfect

off-topic: block transfer

DMA (direct memory access):

- 1) load source address (can be FIFO)
- 2) load destination address (can be FIFO)
- 3) load size (or until “data-available”)
- 4) run



needs specialised hardware

DREAM DAQ

DAQ logic spill-driven (no “real time”, SLC desktops)

in-spill (slow extraction)

poll trigger signal ... if trigger present:

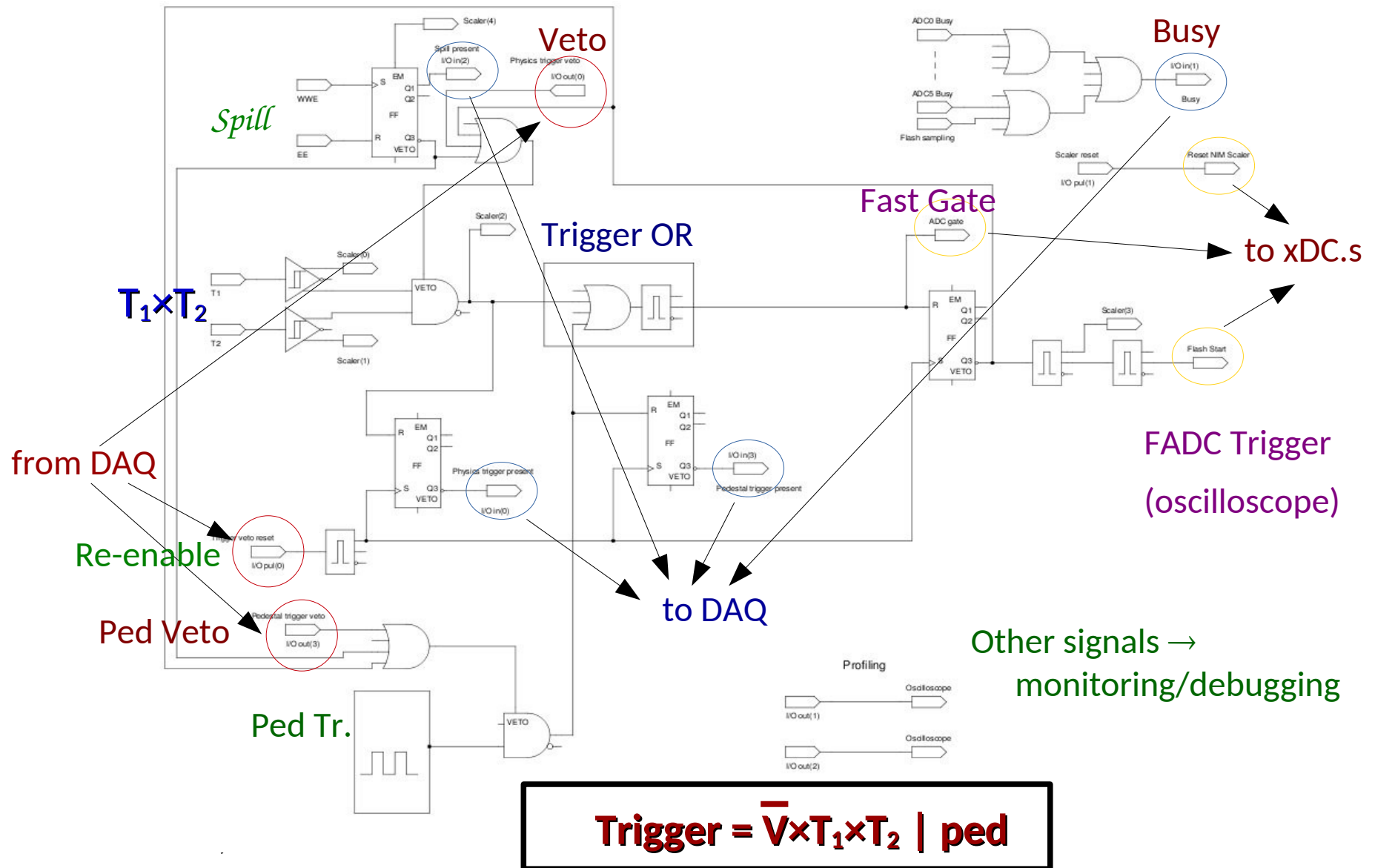
- a) (block) read all VME boards
- b) format & store on large buffers (FIFO over RAM)
- c) re-enable trigger

out-of-spill

- a) read scope (in case) → event size fixed at run start
- b.1) flush buffers to disk (beam and pedestal files) over network
- b.2) monitor data (produce root files)

rate ~ O(1 kHz) limited by DAQ readout

spill-driven (asynchronous) trigger



trigger system

a) crystals w/ fast PMT.s

b) no analog buffering

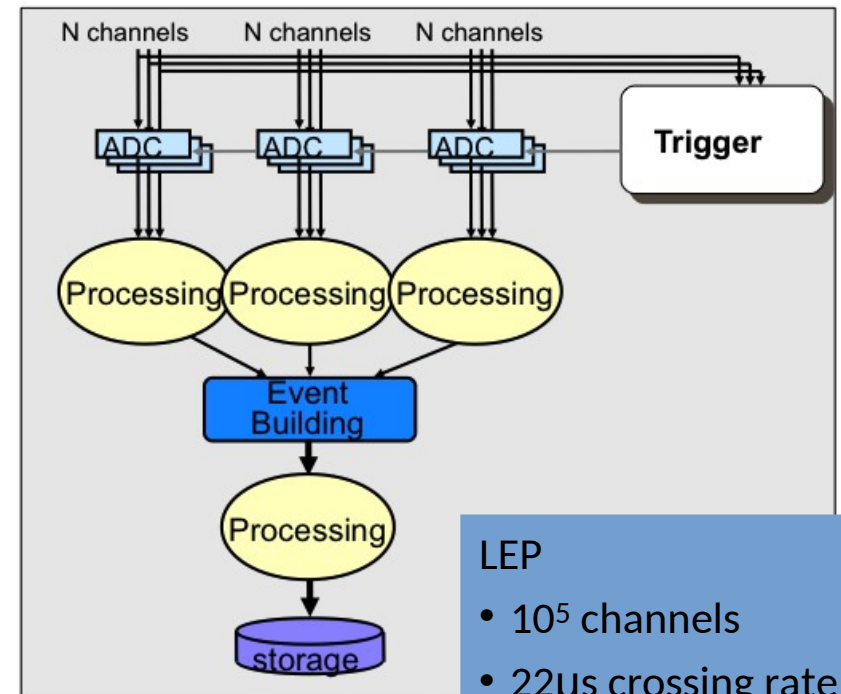
→ low-latency trigger

first discrete, then FPGA

(Xilinx Spartan 3AN evaluation board)

step three: multiple PUs (SBC)

- e.g.: CERN LEP experiments
- complex detectors, moderate trigger rate, very little background
- little pileup, limited channel occupancy
- simpler, slow gas-based main trackers

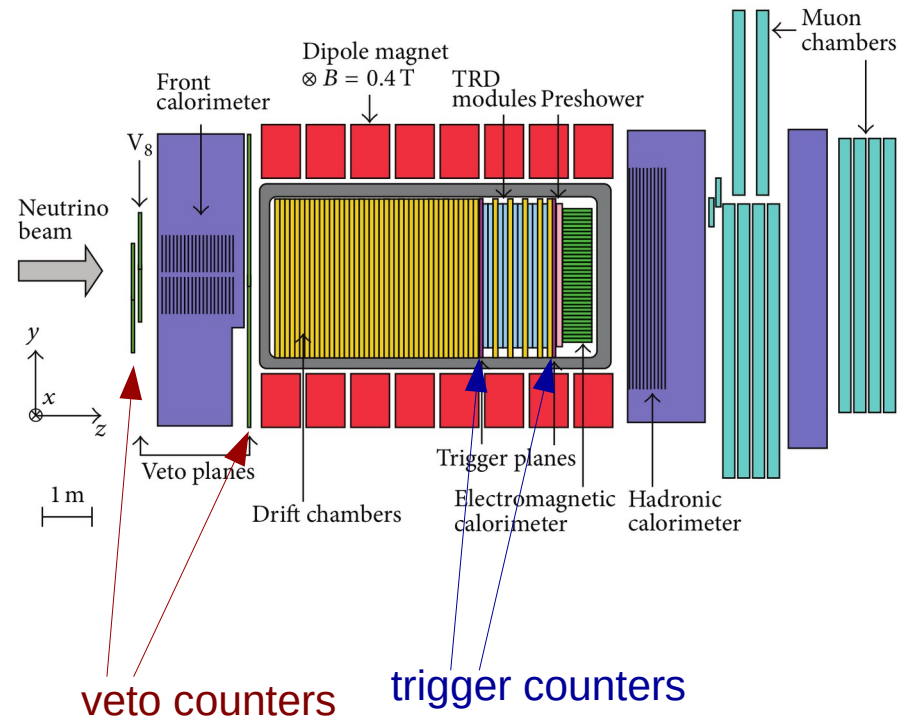


LEP

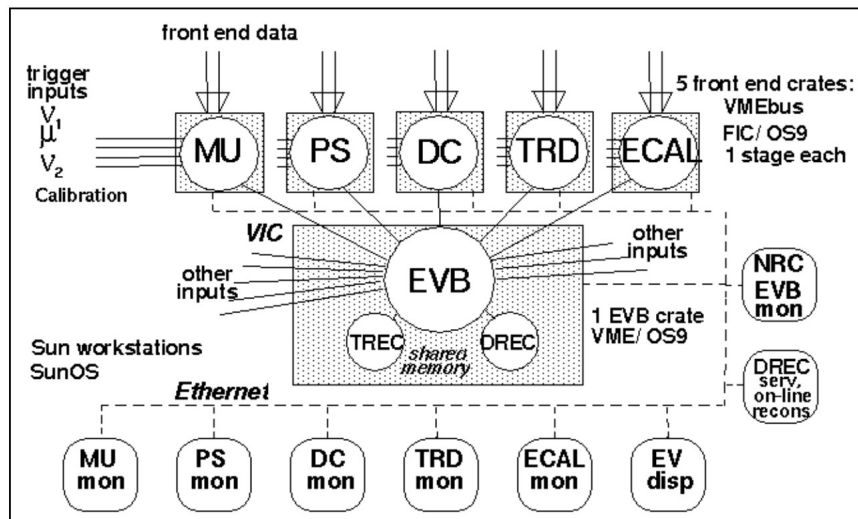
- 10^5 channels
- $22\mu\text{s}$ crossing rate
– no event overlap
- single interaction

NOMAD (1995-1998)

- Search for $\nu_\mu \rightarrow \nu_\tau$ oscillations at the CERN West-Area Neutrino Facility (WANF)
- $2.4 \times 2.4 \text{ m}^2$ fiducial (beam) area
- Two 4 ms spills with 1.8×10^{13} P.o.T. each (ν spills)
- One (2s) slow-extraction spill (μ spill)
- 14.4s cycle duration



→ DAQ layout



WANF - SPS SuperCycle

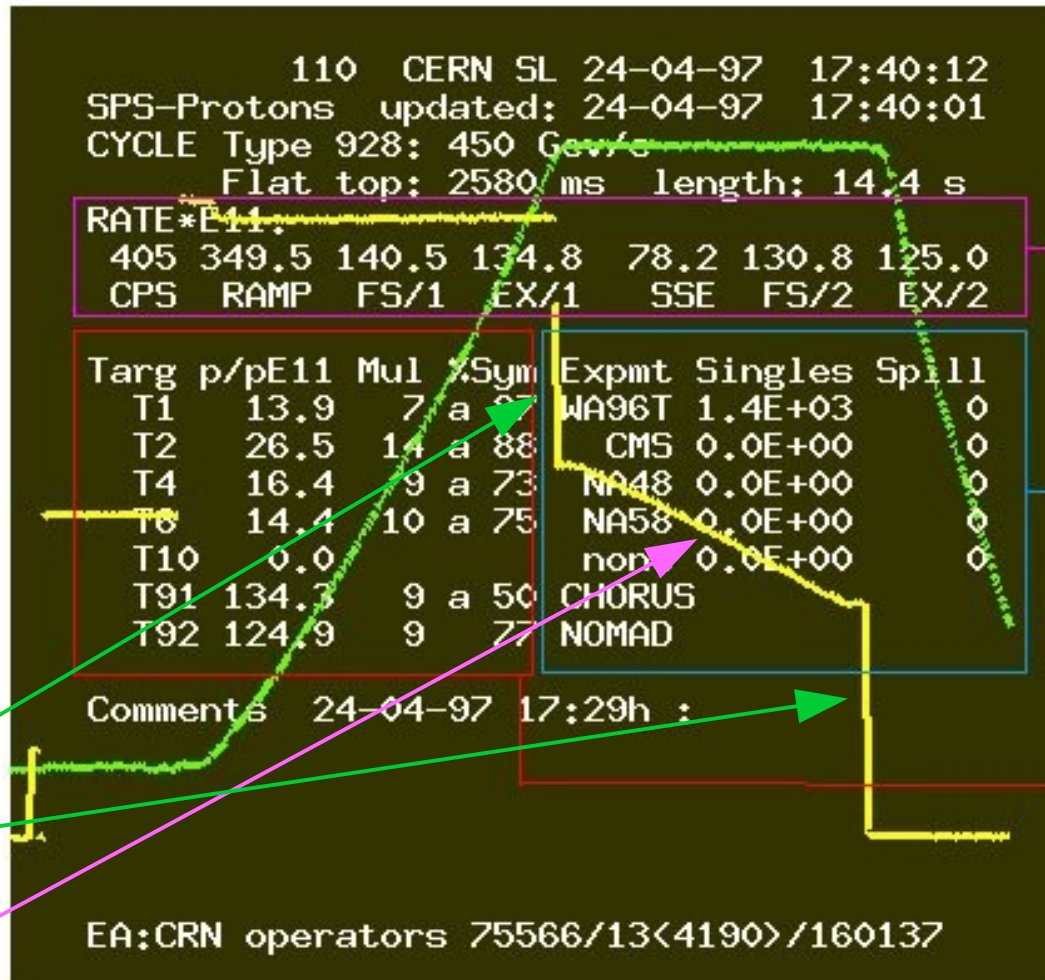
14.4 s cycle
length

2 × 4 ms neutrino
spills (f/s
extractions)

1 × 2 s muon spill
(slow extraction)

f/s extractions

slow extraction



triggering once more ...

menu for NOMADs:

ν -spill triggers

$$\overline{V} \times T_1 \times T_2$$

$$\overline{V}_8 \times \text{FCAL}$$

$$\overline{V}_8 \times \text{FCAL}' \times T_1 \times T_2$$

$$\overline{T_1 \times T_2} \times \text{ECAL}, \overline{V}_8 \times \text{ECAL}$$

RANDOM

μ -spill triggers

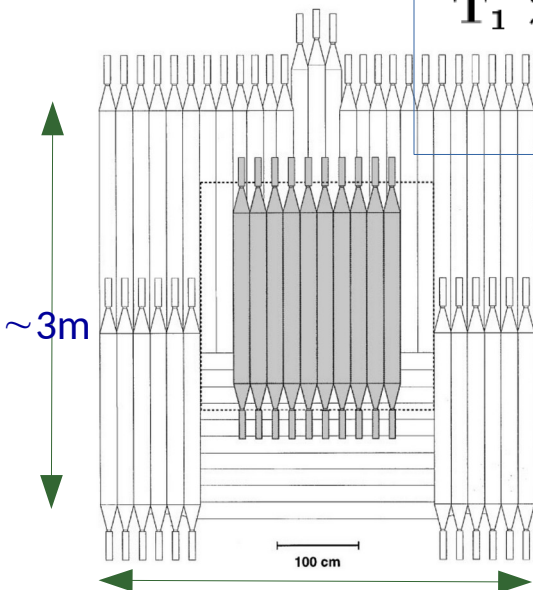
$$V \times T_1 \times T_2$$

$$V_8 \times T_2$$

$$V_8 \times T_1$$

$$V_8 \times T_1 \times T_2 \times \text{FCAL}'$$

$$V \times T_1 \times T_2 \times \text{ECAL}$$



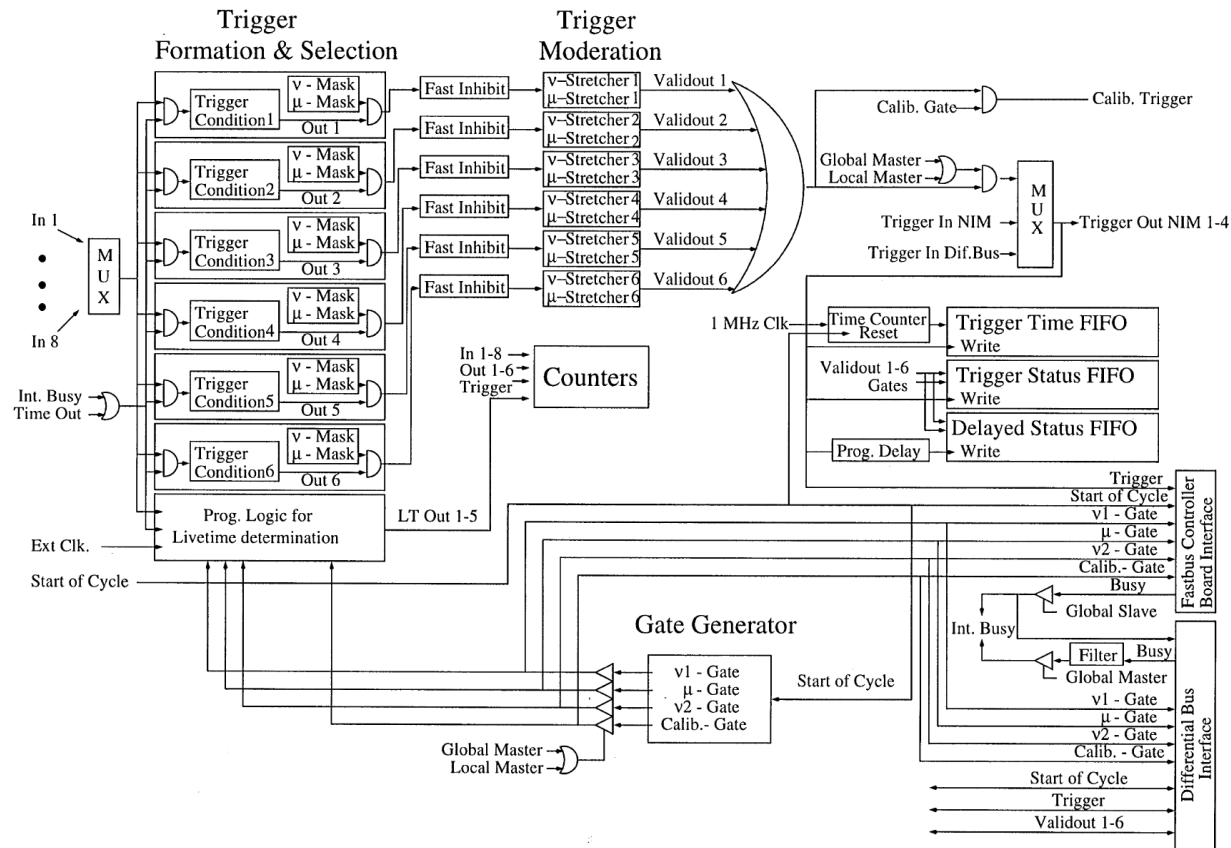
~3m

June 15th, 2023

triggering → FPGAs at work

MOdular TRigger for NOmad (MOTRINO):

6 VME boards providing local and global trigger generation and propagation



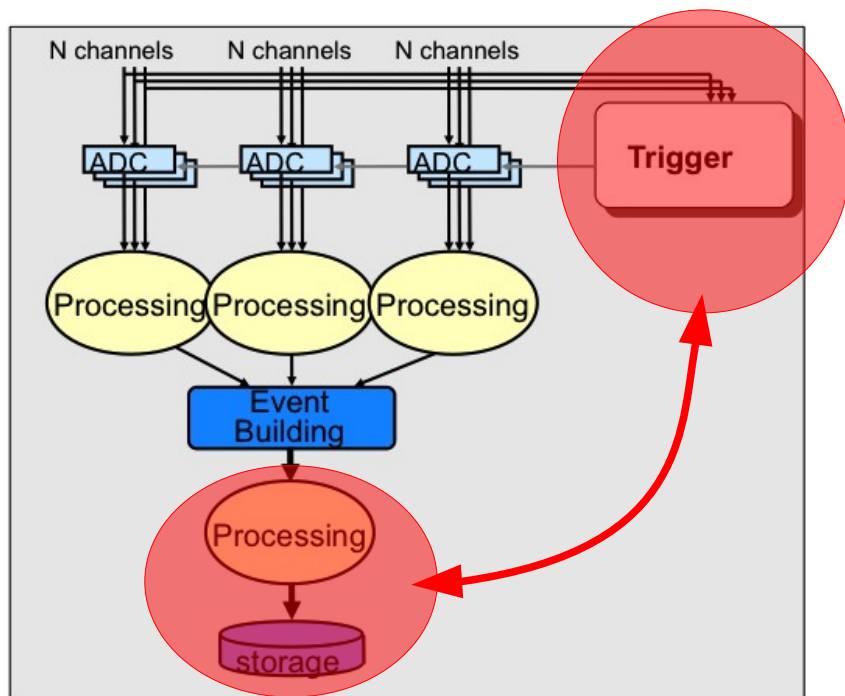
DAQ

- FASTBUS digitisers:
 - ~ 200 (either 64 or 96 channel) xDC boards [x=Q,P,T]
 - $O(\geq 2 \text{ us})$ conversion time, 256 event buffers
- VME readout and processing:
 - Motorola 68040 FIC8234 (OS9 real-time system) VME PUs
 - 5 for readout + 1 for event building
- Typically
 - $\sim 4 \text{ kHz}$ of neutrino triggers (~ 15 evts in each 4ms spill)
 - $\sim 30 \text{ Hz}$ of muon triggers (~ 60 evts in each 2s spill)
 - 256-events in off-spill calibration cycles (calibration triggers)

readout sequence

- On-spill on-board buffering
 - Off-spill (i.e. off-beam) data transfer and processing
 - on spill (or calibration cycle): on-board event buffering (no way to read event by event)
 - end of spill (or calibration cycle): block transfer to VME
 - then event building + storage
 - monitoring and control on SunOs and Solaris workstations
- deadtime in v spills: $\sim 10\%$ due to digitisation

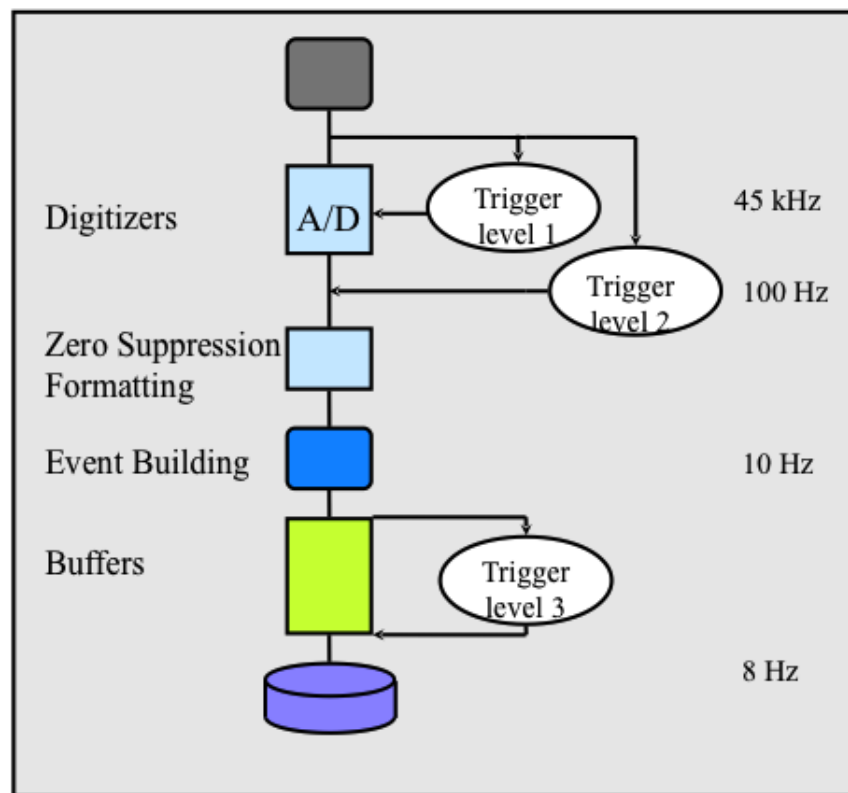
more bottlenecks ?



- trigger complexity ↔ storage
- single HW trigger not sufficient to reduce rate
- add L2 Trigger
- add HLT

step four: multi-level trigger

Typical Trigger / DAQ structure at LEP



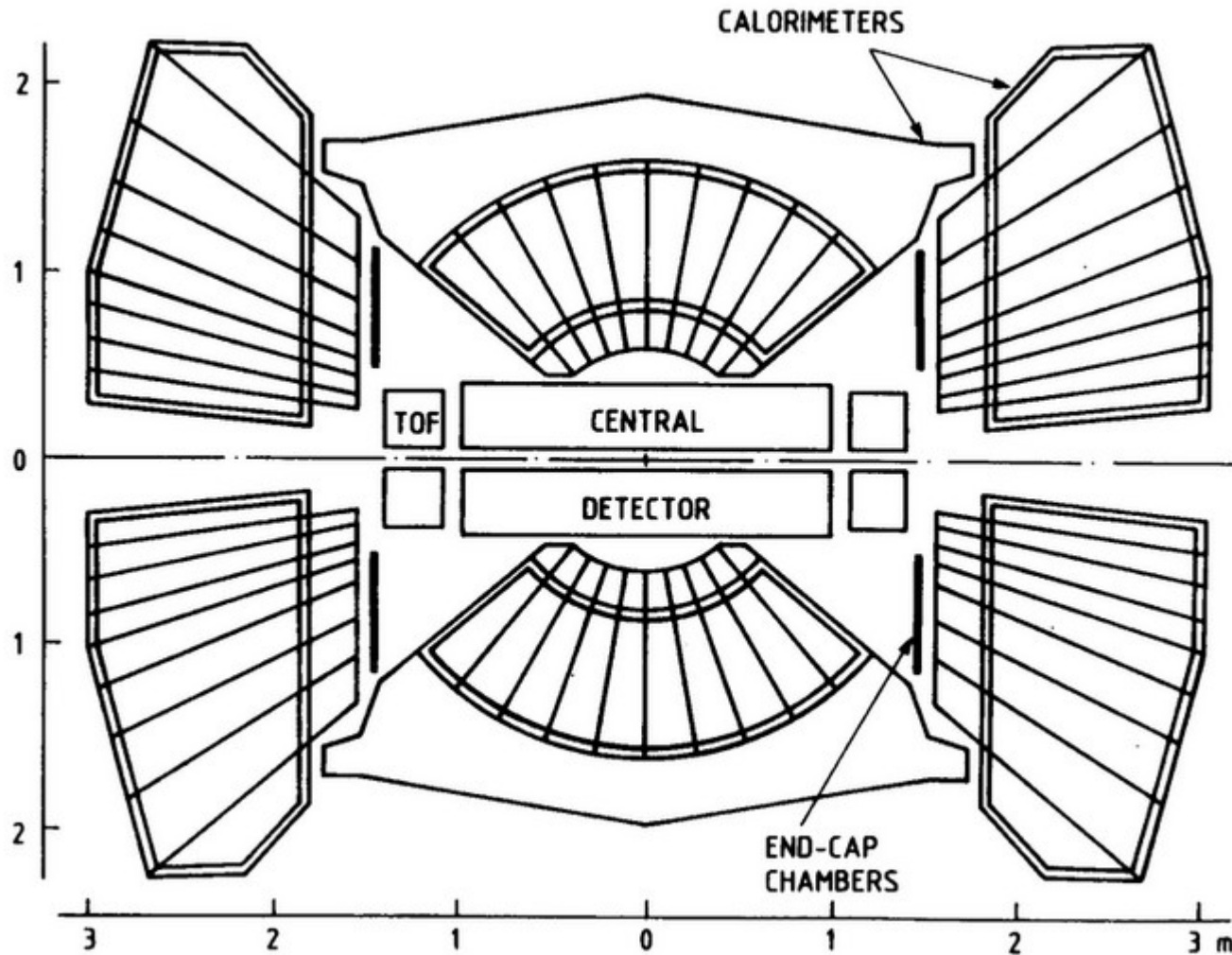
- more complex filters
 - slower
 - applied later in the chain

see Trigger lectures

LEP

- 10^5 channels
- $22\mu\text{s}$ crossing rate
 - no event overlap
- single interaction
- L1 $\sim 10^3$ Hz
- L2 $\sim 10^2$ Hz
- L3 $\sim 10^1$ Hz
- $100\text{kB/ev} \rightarrow 1\text{MB/s}$

Upgraded UA2 experiment (1988-1991)



Upgraded UA2 experiment (1987-1991)

High-lumi $p\bar{p}$ collisions @ CERN $p\bar{p}$ collider:

$$\sqrt{s} = 630 \text{ GeV}$$

$$L = 5 \times 10^{30} \text{ cm}^{-2} \text{ s}^{-1} \text{ (one order of magnitude increase)}$$

Goal:

W/Z physics

QCD

!! top quark and SUSY discovery !!

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Goal:

W/Z physics

QCD

!! top quark and SUSY discovery !!

→ robust theoretical prediction for new physics
unluckily ... nature is wrong!

Upgraded UA2 experiment (1987-1991)

High-lumi $p\bar{p}$ collisions @ CERN $p\bar{p}$ collider:

$$\sqrt{s} = 630 \text{ GeV}$$

$$L = 5 \times 10^{30} \text{ cm}^{-2} \text{ s}^{-1} \text{ (one order of magnitude increase)}$$

Goal:

W/Z physics

QCD

!! top quark and SUSY discovery !!

Complex trigger signatures:

em, jet and missing E_T

Upgraded UA2 experiment (1987-1991)

Three-level trigger selection:

- L1 from on-detector hardware

- L2 over dedicated processors

- L3 over FASTBUS processors (ALEPH event builder)

DAQ readout & monitoring:

- CAMAC & FASTBUS → VAX/VMS platforms

Upgraded UA2 experiment (1987-1991)

Three-level trigger selection:

- L1 from on-detector hardware

- L2 over dedicated processors

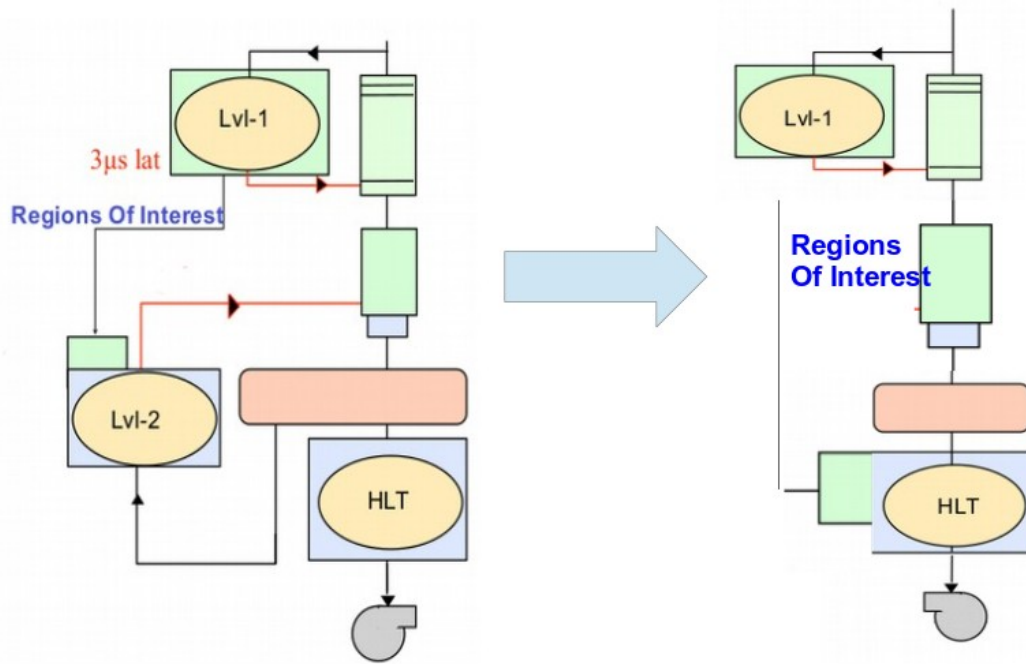
- L3 over FASTBUS processors (ALEPH event builder)

DAQ readout & monitoring:

- CAMAC & FASTBUS → VAX/VMS platforms

No new physics, nevertheless many new/better measurements and observations of SM processes

ATLAS (from Run 1 to Run 2)



- Merge L2 and L3 into single HLT farm
 - preserve Region of Interest but dilute farm separation and fragmentation
 - increase flexibly, computing power efficiency

trigger/event-selection latencies

Possible (e.g. ATLAS Run 1) values:

- L1 : $O(1 \mu\text{s in real-time}) \rightarrow \text{let say} = 1.9 \mu\text{s}$
- L2 : $O(10 \text{ ms}) \rightarrow \text{let say} = 40 \text{ ms}$
- L3(HLT) : $O(\text{s}) \rightarrow \text{let say} = 1 \text{ s}$

Q: do the 3 numbers mean the same thing ?

latency and real-time

real time: system must respond within some fixed delay

→ *Latency = Max Latency*

→ over fluctuations bad, will create deadtime

non-real-time: system responds as soon as it's available

→ *Latency = Mean Latency*

→ over fluctuations fine, shouldn't create deadtime

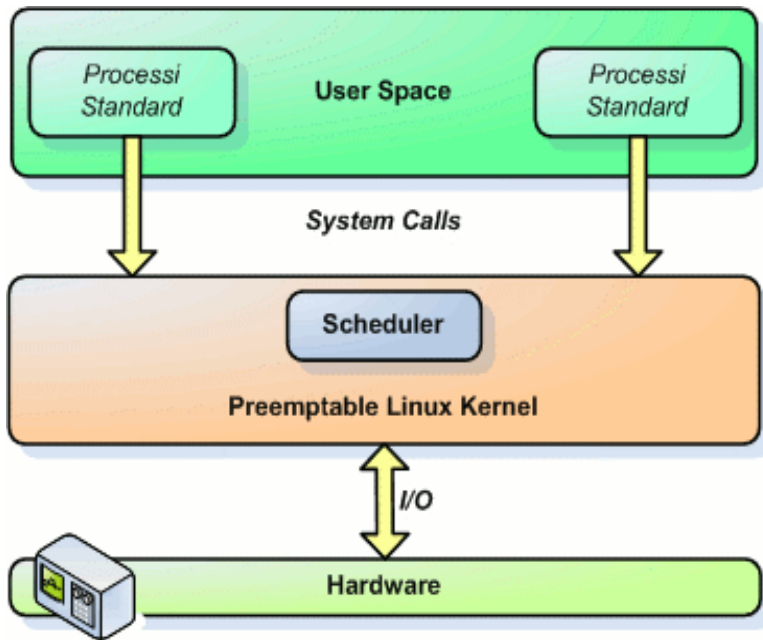
real time o.s. :

very stable time delay in responding to events

standard unix kernels are not real time:

a system call can in principle take any time

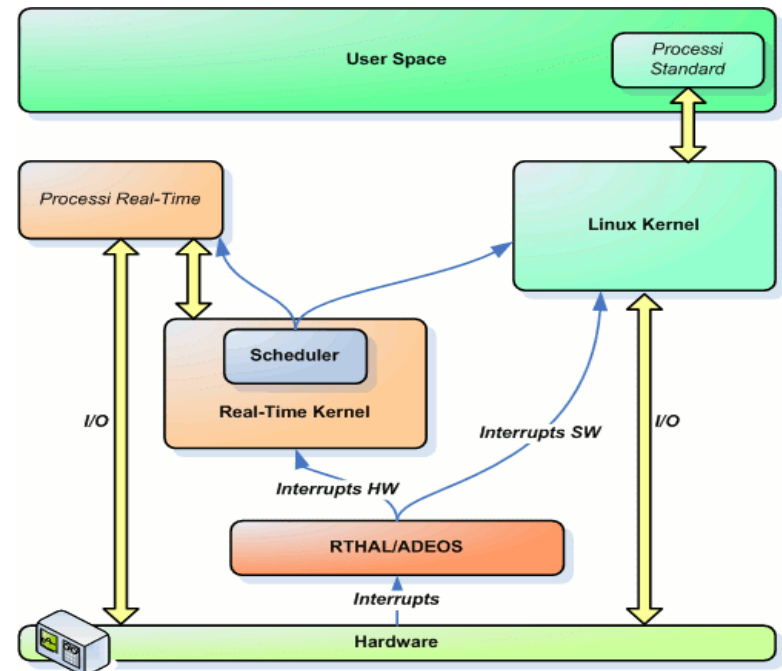
off-topic: real-time linux



Low-latency Ubuntu patch
(soft real time) :

Interruptible linux kernel

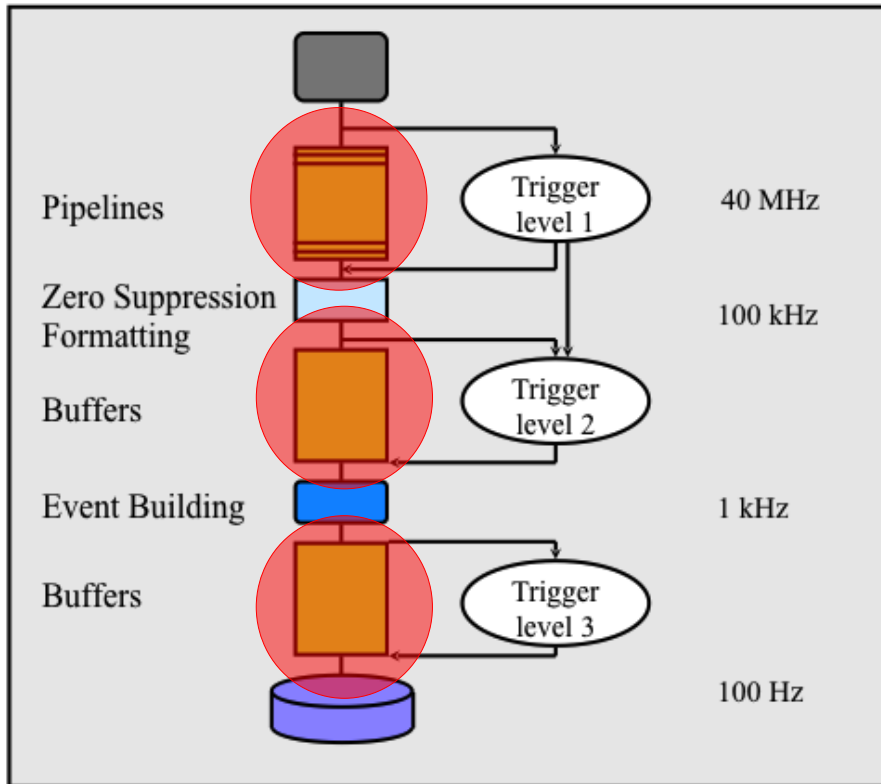
<https://help.ubuntu.com/community/UbuntuStudio/RealTimeKernel>



RTAI (hard real time) :
linux kernel as high-priority
application

<https://www.rtai.org/>

step five: dataflow control

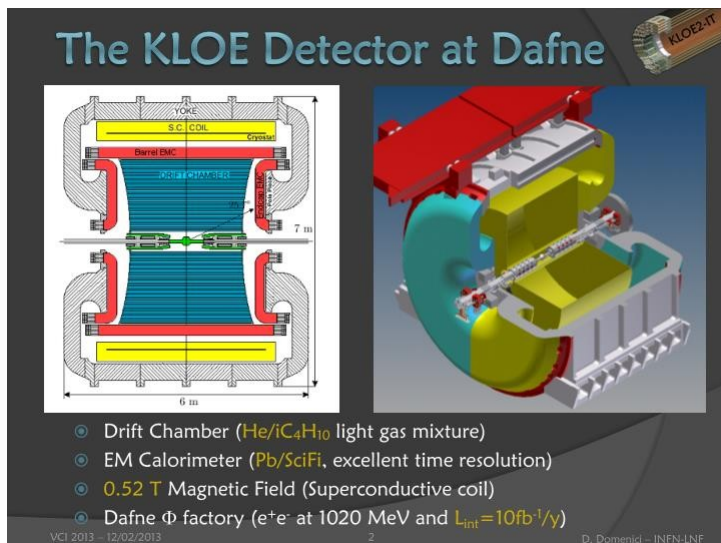


- Buffers:
 - not the “final solution”
 - can overflow due to:
 - bursts
 - unusual event sizes
- Discard
 - either locally
 - or exert “backpressure”
 - ask previous level(s) to block dataflow

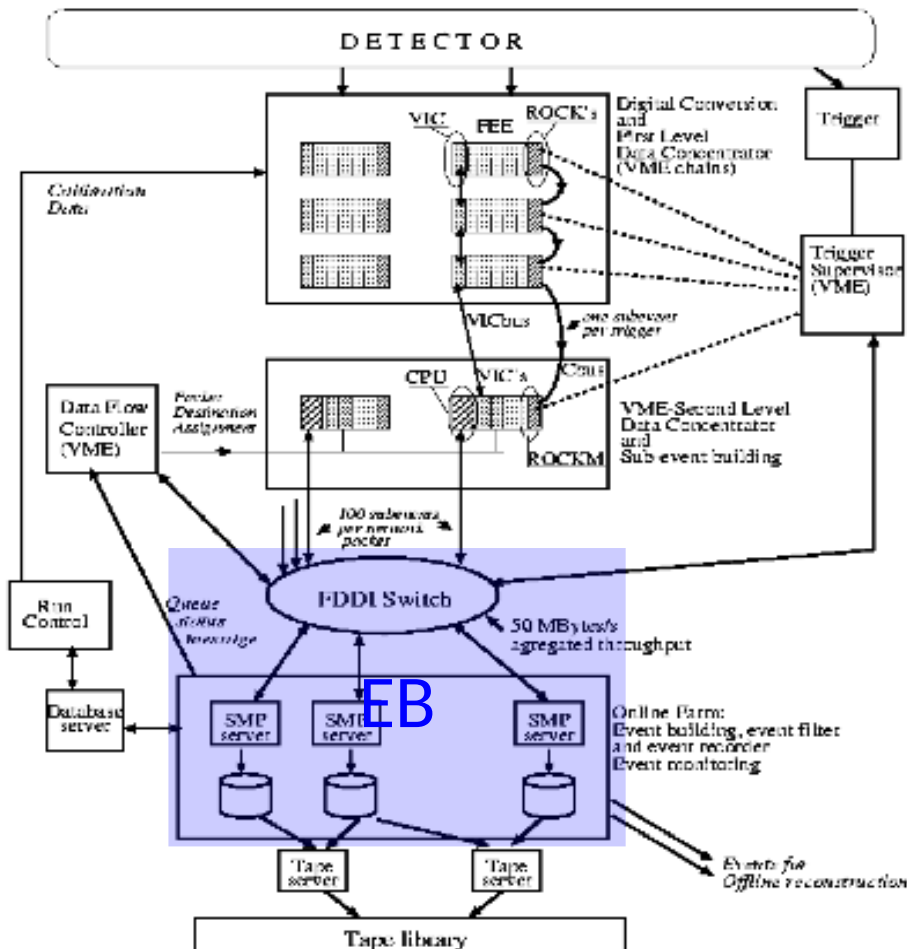
Who controls the flow?
FE (*push*) or EB (*pull*)

a *push* example: KLOE

- DAΦNE e^+e^- collider in Frascati
- CP violation parameters in the Kaon system
- “factory”: rare events in a high-rate beam
- 10^5 channels
- 2.7 ns crossing rate
 - rarely event overlap
 - “double hit” rejection
- high rate of small events
- L1 $\sim 10^4$ Hz
 - 2 μ s fixed deadtime
- HLT $\sim 10^4$ Hz
 - \sim COTS, cosmic rejection only
- 5 kB/ev \rightarrow 50 MB/s [design]



KLOE



- deterministic FDDI network
- buffering at all levels (from FE to EB)
- *push* architecture
vs pull used in ATLAS
see DAQ Software lecture
- try EB load redistribution
before resorting to
backpressure

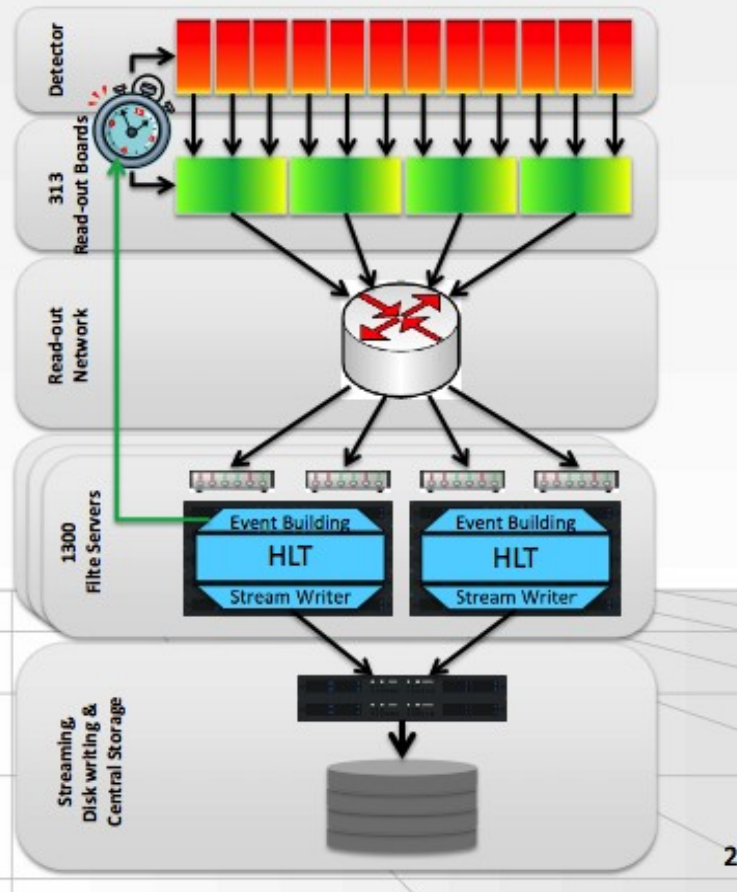
Which LHC experiment has a somewhat similar dataflow architecture ?

LHCb: network is dataflow



From Front-End to Hard Disk

- $O(10^6)$ Front-end channels
- 300 Read-out Boards with 4 x 1 Gbit/s network links
- 1 Gbit/s based Read-out network
- 1500 Farm PCs
- >5000 UTP Cat 6 links
- 1 MHz read-out rate
- Data is pushed to the Event Building layer. There is no re-send in case of loss
- Credit based load balancing and throttling

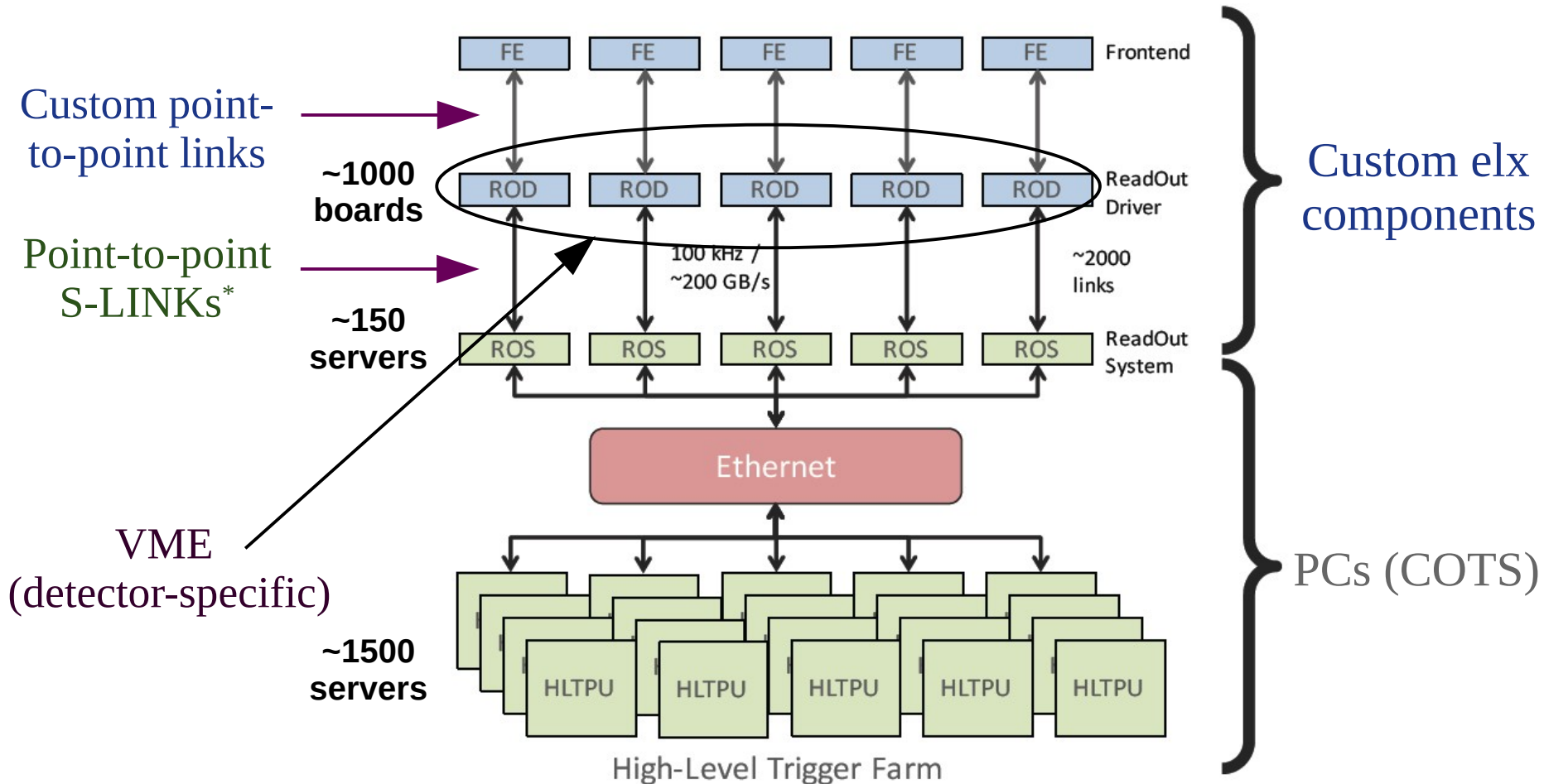


The LHCb Data Acquisition during LHC Run 1
CHEP 2013

more info in "TDAQ for the LHC experiments"

ATLAS TDAQ in Run 2

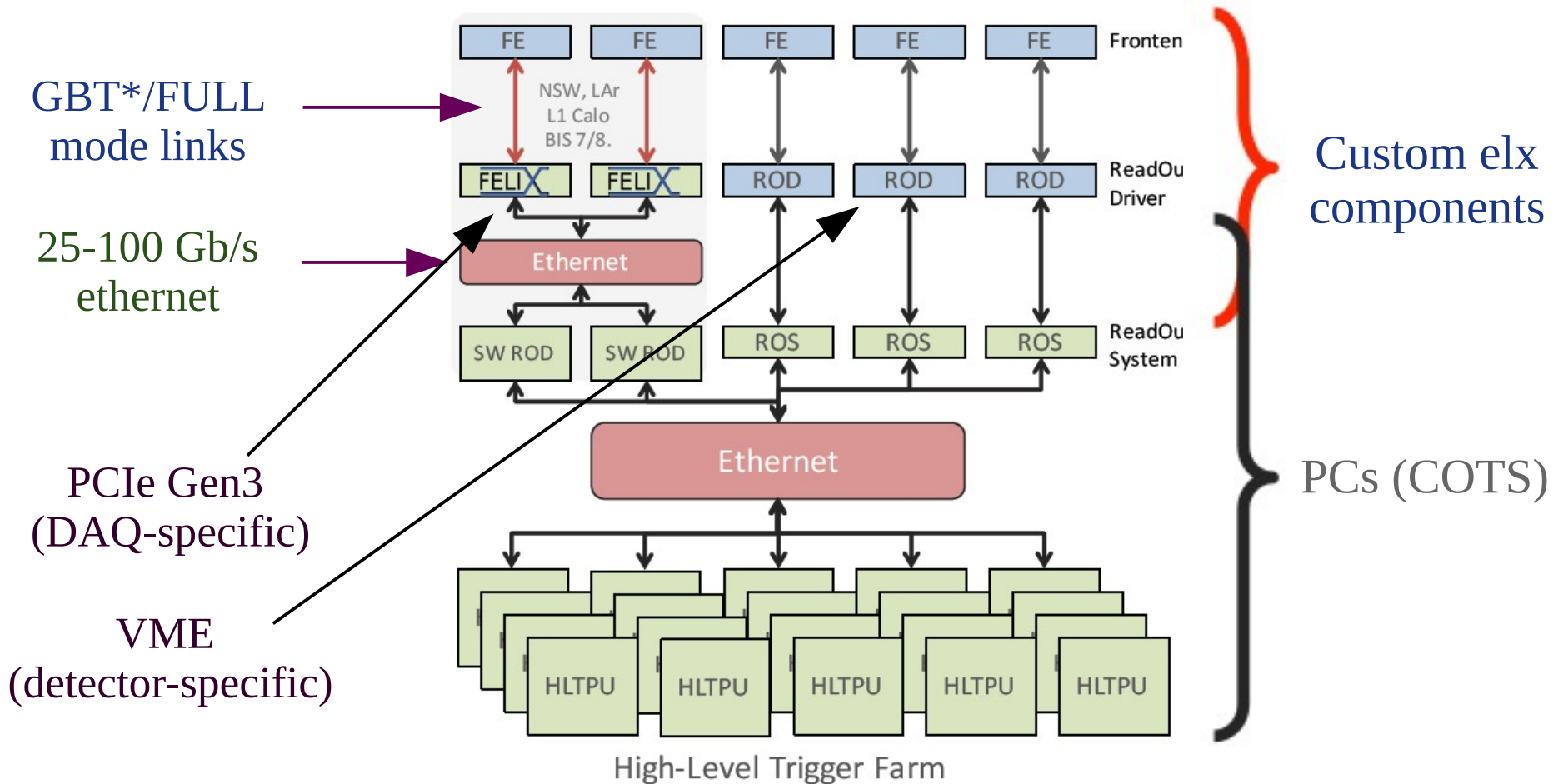
~ 2 MB events, ~ 50 GB/s network bandwidth,
~ 1.5 GB/s recording throughput



*S-LINK: CERN Simple Link

Upgrade for Run 3

Same requirements as Run 2 but reduced custom components



*GBT: GigaBit Transceiver with Versatile Link

ATLAS dataflow

Push mode from front-end elx up to ROS/swROD system

→ data sent as soon as available

Pull mode from ROS to HLT

→ data requested by HLT as soon as HLT is free

⇒ ROS/swROD must handle all critical dataflow issues

looking forward to LS2 and beyond

On some long term, all experiments looking forward to significant increase in L1 trigger rate and bandwidth.

ALICE and LHCb will pioneer this path during LS2

DAQ@LHC Workshop

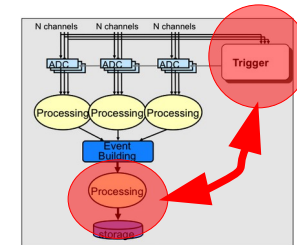
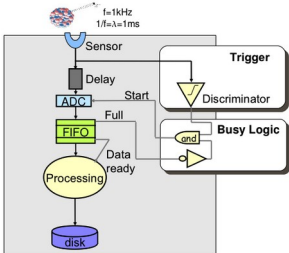


- First level trigger for Pb-Pb interactions **500 Hz** → **50 kHz**
- 22 MB/event
 - **1 TB/s readout** → **500 PB/month**
- Data volume reduction
 - on-line full reconstruction
 - discard raw-data
- Combined DAQ/HLT/offline farm
 - COTS, FPGA and GPGPU



- **1 MHz** → **40 MHz** readout and event building → trigger-less
 - trigger support for staged computing power deployment
- 100 kB/event
 - on-detector zero suppression → rad-hard FPGA
 - 4 TB/s event-building

trends



- Integrate synchronous, low latency in front end
 - limitations do not disappear, but decouple (factorise)
 - all-HW implementation
 - isolated in replaceable(?) components
- Use networks as soon as possible
- Deal with dataflow instead of latency
- Use COTS network and processing
- Use “network” design already at small scale
 - easily get high performance with commercial components

take care, lot of issues not covered:

Hw configuration

Sw configuration

Hw control & recovery

Sw control & recovery

Monitoring

...

Appendices:

A: Students' homework

(with a brief introduction to Italians' body language)

B: Cables and transmission lines

C: Backtrace

D: Profiling

E: Some crude queueing theory

F: NA43/NA63

G: Trigger qualification

Thank you for your patience ...

Lost & Found (off-topics)

Appendix A: students' homework

(with a brief introduction to Italians' body language)

Students' homework

Students' homework

About the number of Italians in Trigger/DAQ, debate one of the following hypotheses:

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*1) baseline: statistical fluctuation or new physics ?
(to be submitted to Nature)*

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*1) baseline: statistical fluctuation or new physics ?
(to be submitted to Nature)*

*2) romantic: what about “Italians do it better” ?
(to be submitted to Vanity Fair)*

Students' homework

About the number of Italians in Trigger/DAQ, debate one of the following hypotheses:

*1) baseline: statistical fluctuation or new physics ?
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(to be submitted to Vanity Fair)*

3) last but not least (the “paranoic/complottist” vision):

Students' homework

About the number of Italians in Trigger/DAQ, debate one of the following hypotheses:

*1) baseline: statistical fluctuation or new physics ?
(to be submitted to Nature)*

*2) romantic: what about “Italians do it better” ?
(to be submitted to Vanity Fair)*

*3) last but not least (the “paranoic/complottist” vision):
what about the famous Mafia-Pizza-Spaghetti-TDAQ connection ?
(will go anonymous on the dark web)*

On the other hand ...

... please, take care !

*you can't afford such a **demanding** environment*

*you can't afford such a **demanding** environment
without specific training ...*

*you can't afford such a **demanding** environment
without specific training ...*

*... about the **Italians'** way*

Luckily

on the web

there are plenty of survival kits

Example 1: basic course (mild concepts)

Example 1: basic course (mild concepts)

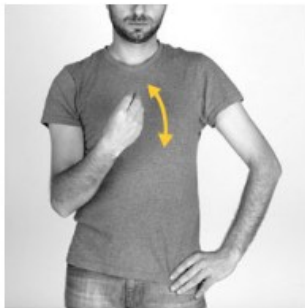
A Short Lexicon of Italian Gestures

For Italians, it comes naturally. But what do they mean when they talk with their hands?

Many things. Roll over the images to learn a few classic gestures. [Related Article »](#)



Perfect!



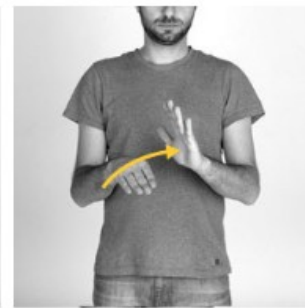
What in God's name
are you saying?



Nothing.



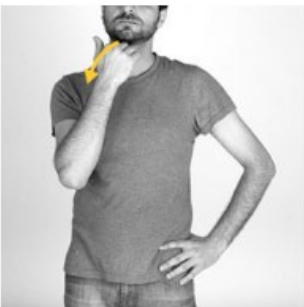
Someone talks too much.



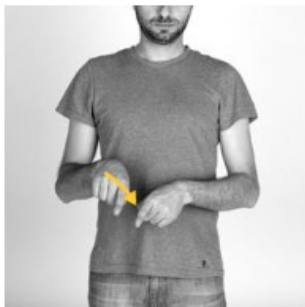
Get out of here.



Slow down or
keep calm.



I don't care.



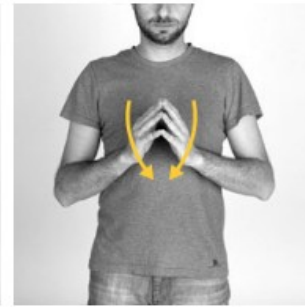
Those two get along.



It wasn't me or
I don't know.



Don't worry,
I'll take care of it.



Why in God's name
did you/I do it?

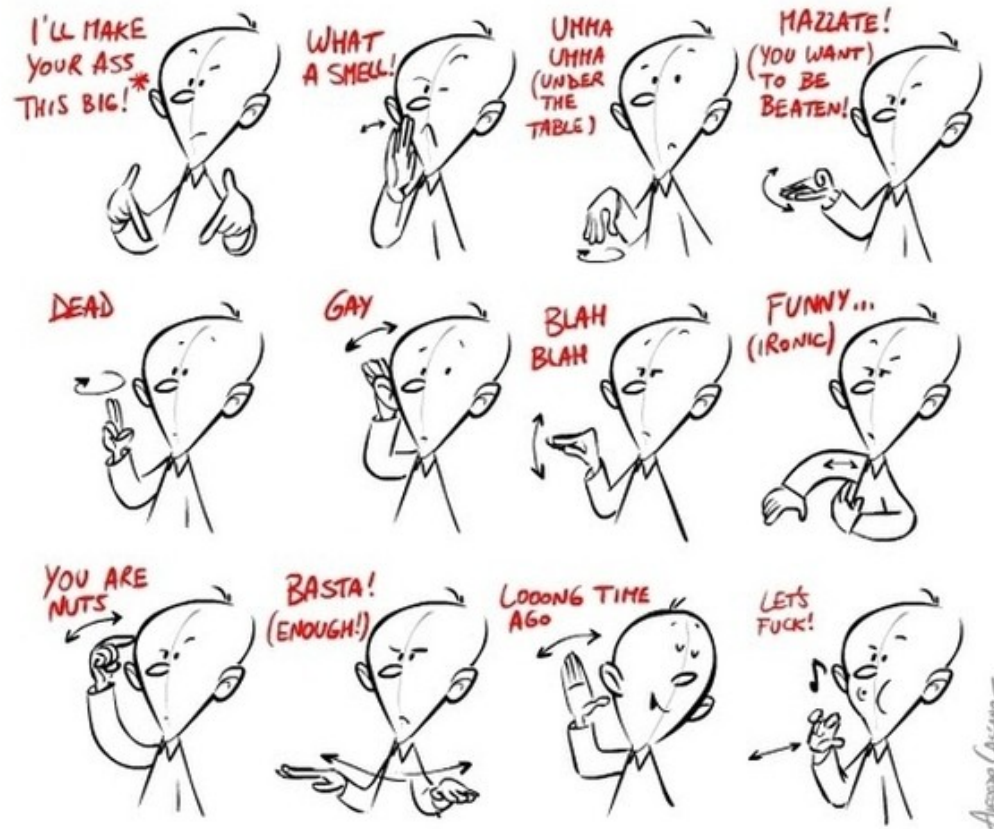


To be afraid.

Example 2: advanced course (includes sensitive concepts)

Example 2: advanced course (includes sensitive concepts)

- ITALIAN POPULAR GESTURES - CHAPTER II



* THE HANDS DISPLAY THE SIZE OF THE ANUS.

Please take care:

Please take care:

be careful while doing practice!

(especially for the advanced course)

Appendix B: Cables and transmission lines

Spoken about signals, amp.s, digitisers, ... but ...

... almost nothing about how signals are transmitted over long distances. ***Is there any issue ?***

Q(1): what is a cable (for a single signal) ?

a couple of ideal conductors ($R=C=L=0$) ?

Q(2): which speed can it reach ?

Q(3): what's its impedance ?

Q(4): what does it do to your signal ?

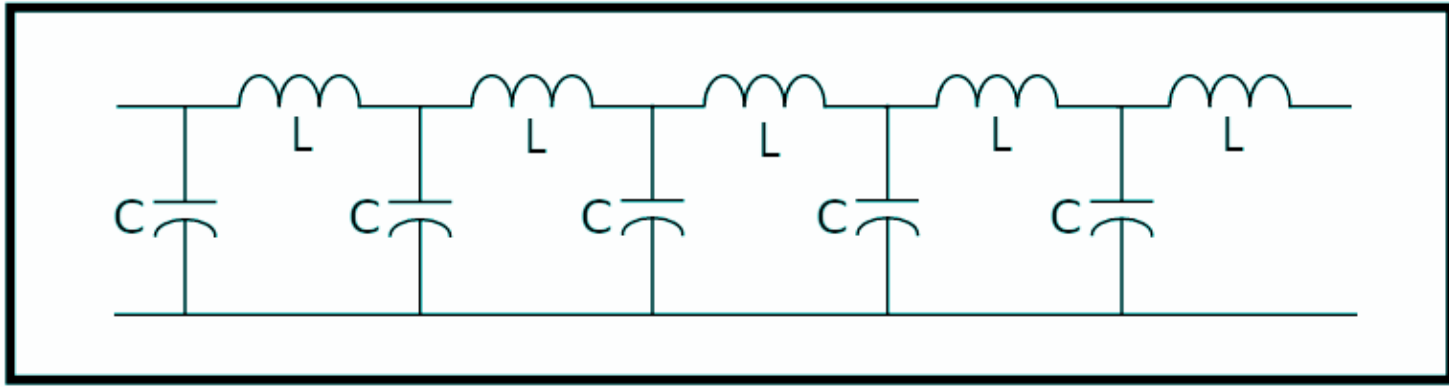
Ok the full line must be properly matched:

$$Z(\text{out}) = Z(\text{cable}) = Z(\text{in})$$

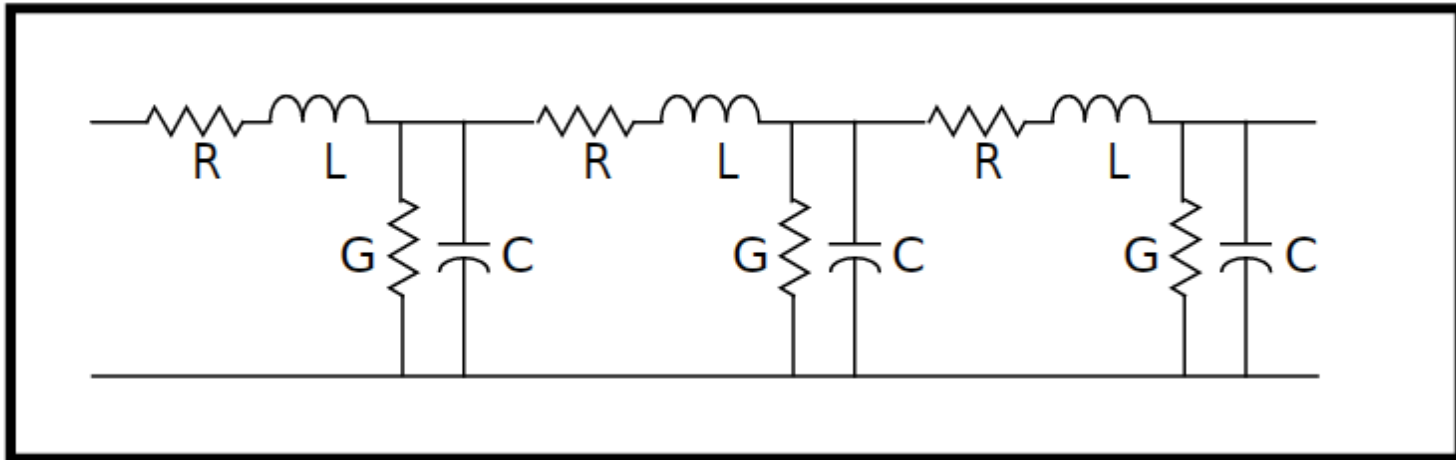
That's all ?

Cables and transmission lines

Lossless transmission line:



Lossy transmission line:

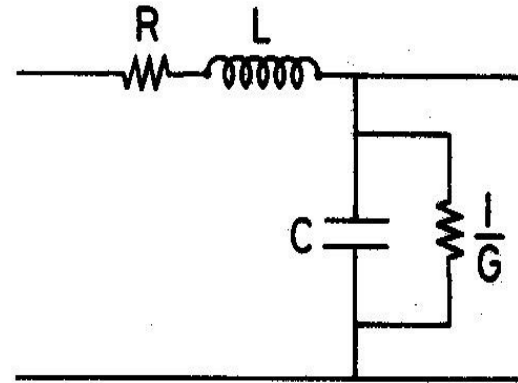


Cables

Cable element (dz):

$$L \approx \frac{\mu}{2\pi} \ln\left(\frac{b}{a}\right) \quad [\text{H/m}]$$

$$C \approx \frac{2\pi\epsilon}{\ln(b/a)} \quad [\text{F/m}]$$



R depends on the frequency (skin effect)

G should be negligible

$$Z = (L/C)^{1/2}$$

$$v_p = (LC)^{-1/2} = (\mu\epsilon)^{-1/2}$$

Cables

Equation for standing waves:

$$\frac{\partial^2 V}{\partial z^2} = LC \frac{\partial^2 V}{\partial t^2} + (LG + RC) \frac{\partial V}{\partial t} + RGV$$

solution:

$$\frac{d^2 V}{dz^2} = (R + i\omega L)(G + i\omega C)V = \gamma^2 V$$

$$\gamma = \alpha + ik = \sqrt{(R + i\omega L)(G + i\omega C)}$$

R usually dominated by the skin effect:

$$R(\omega) = r^* D / (4^* \delta)$$

r = resistance per unit length

D = diameter internal conductor

δ = skin depth $\sim 1/\sqrt{\omega}$

Cable losses

Neglecting the transconductance G :

$$\alpha = R(\omega)/(2Z_0) \sim c\sqrt{\omega}$$

$$k = \omega\sqrt{RC} = \omega/(\beta c)$$

$$V(z,t) = V_1 \exp(-\alpha z) \exp[i(\omega t - kz)]$$

50-Ohm fast ($v = 4$ ns/m) CERN-store cables:

04.61.11.F - COAXIAL CABLE 50 OHM - TYPE C-50-6-1

04.61.11.H - COAXIAL CABLE 50 OHM - LOW LOSS - TYPE C-50-11-1

$f(-3\text{db}, 40 \text{ m, cable C-50-6-1}) \sim 120 \text{ MHz}$

$f(-3\text{dB}, 40 \text{ m, low loss cable}) \sim 640 \text{ MHz}$

Signal distortions

Time parameter:

$$\alpha \sim \mu \sqrt{f}$$
$$\tau_0 = (\mu z)^2 / \pi$$

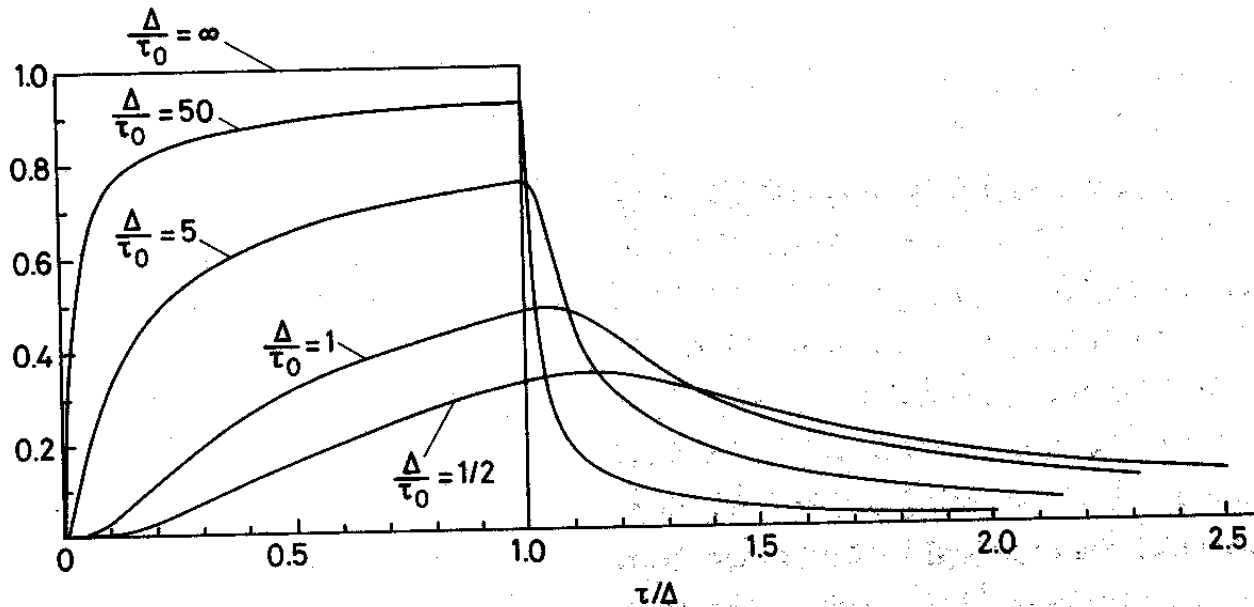
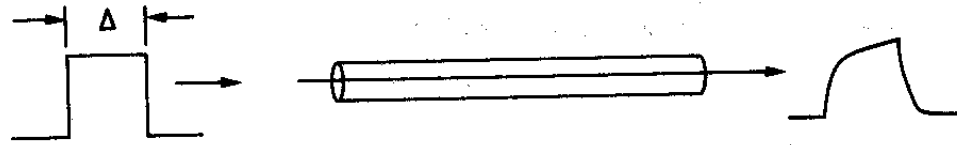
$$\mu z \sim 32^*E-6 \text{ (C-50-6-1), } 14E-6 \text{ (low loss cables)}$$

$$\tau_0 \sim 320 \text{ ns (C-50-6-1)}$$

$$\tau_0 \sim 60 \text{ ns (low loss cables)}$$

*** Take care: would like $\tau_0 \ll \tau(\text{signal})$

Digital pulse distortions

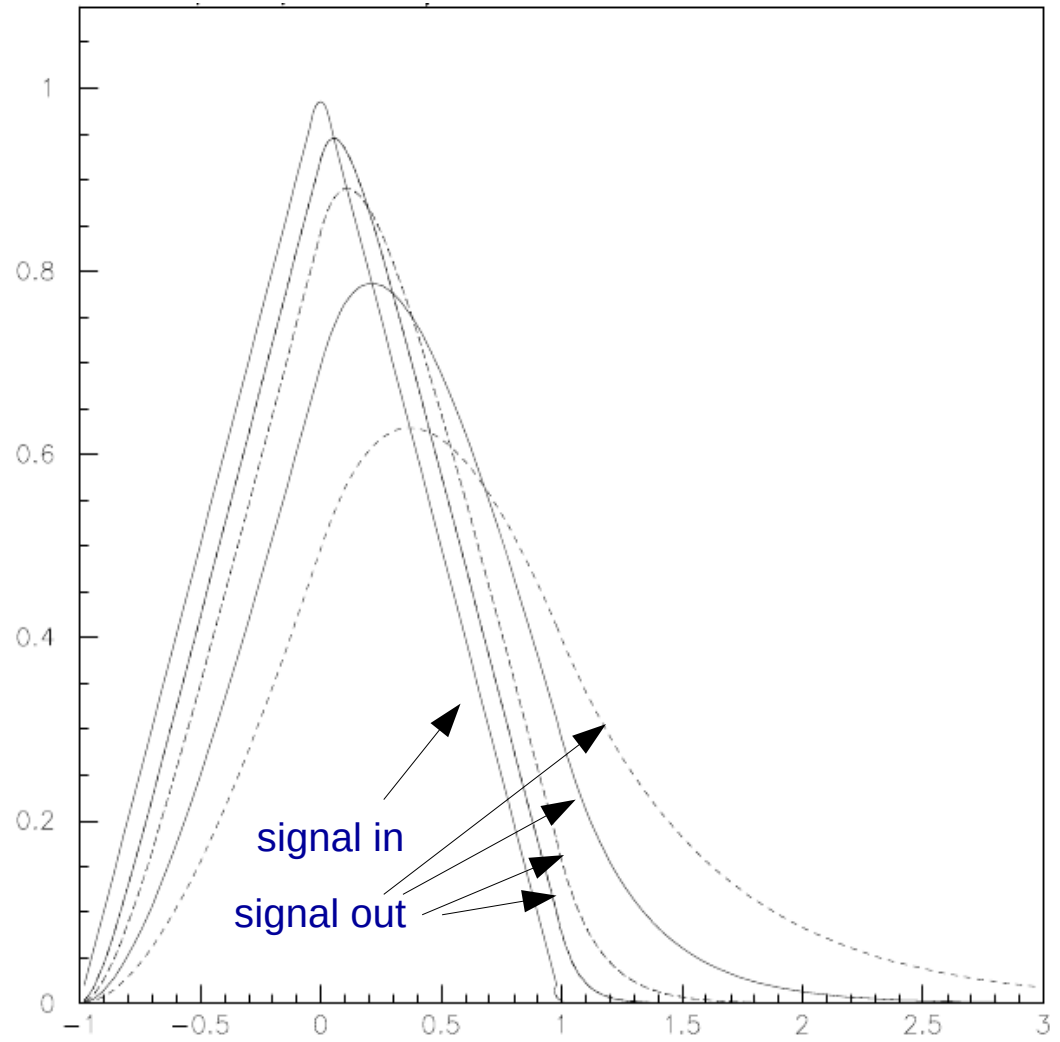


$$\text{for } \alpha \sim a \sqrt{f}$$

$$\tau_0 = (a z)^2 / \pi$$

Bandwidth effects – analog signals

~1ns analog-signal response for
BW ~ 300, 150, 75, ... MHz



Appendix C: Backtrace

Segfaulting ? Have a look at backtrace:

https://www.gnu.org/software/libc/manual/html_node/Backtraces.html

BACKTRACE(3)

Linux Programmer's Manual

BACKTRACE(3)

NAME

backtrace, backtrace_symbols, backtrace_symbols_fd - support for application self-debugging

SYNOPSIS

```
#include <execinfo.h>
```

```
int backtrace(void **buffer, int size);
```

```
char **backtrace_symbols(void *const *buffer, int size);
```

```
void backtrace_symbols_fd(void *const *buffer, int size, int fd);
```

HowTo

1) file “my_segf.cxx” : install a signal handler to print the backtrace

```
#include <stdio.h>
#include <execinfo.h>
#include <signal.h>
#include <stdlib.h>
#include <unistd.h>
```

```
void handler(int sig) {
    void *array[10];
    size_t size;

    // get void*'s for all entries on the stack
    size = backtrace(array, 10);

    // print out all the frames to stderr
    fprintf(stderr, "Error: signal %d:\n", sig);
    backtrace_symbols_fd(array, size, STDERR_FILENO);
    exit(1);
}
```

```
void baz() {
    int *foo = (int*)-1; // make a bad pointer
    printf("%d\n", *foo); // causes segfault
}
```

```
void bar() { baz(); }
void foo() { bar(); }
```

```
int main(int argc, char **argv) {
    signal(SIGSEGV, handler); // install our handler
    foo(); // this will call foo, bar, and baz. Baz segfaults.
}
```

2) compile with -g debug flag on:

```
g++ -g -rdynamic my_segf.cxx -o  
my_segf
```

3) get the crash:

```
[roberto@bob-laptop ~]$ ./my_segf
```

```
Error: signal 11:
```

```
./my_segf(_Z7handleri+0x1c)[0x400a52]
```

```
/lib64/libc.so.6(+0x347e0)[0x7fa55f1c07e0]
```

```
./my_segf(_Z3bazv+0x14)[0x400aab]
```

```
./my_segf(_Z3barv+0x9)[0x400aca]
```

```
./my_segf(_Z3foov+0x9)[0x400ad6]
```

```
./my_segf(main+0x23)[0x400afc]
```

```
/lib64/libc.so.6(__libc_start_main+0xf1)
```

```
[0x7fa55f1ac731]
```

```
./my_segf(_start+0x29)[0x400969]
```

handler

libc

my crash

4) crash is at (`_Z3bazv+0x14`) ... the function name is “`_Z3bazv`” (c++ function name mangling). How to get it ?

5) Demangle it thanks to: <http://demangler.com/>

6) Take the Answer: `baz()` → crash is at (`baz+0x14`)

7) crash is at (baz+0x14) ... open the debugger: `gdb my_segf`

```
(gdb) info address baz
```

Symbol "baz()" is a function at address 0x400a55.

8) so crash is at address (0x499a55+0x14) ... then:

```
(gdb) info line *(0x400a55+0x14)
```

Line 24 of "my_segf.cxx" starts at address 0x400a65 <baz()+16>
and ends at 0x400a7c <baz()+39>.

9) got it ! That's not yet the reason but ...

Appendix D: Profiling

Take care: optimize your code – first of all - where it really needs. To get it, you may use of profiling.

for C/C++ code, look (for example) at this gprof tutorial:

<http://www.thegeekstuff.com/2012/08/gprof-tutorial/>

Very simple, at least for standalone code ...

Appendix E: Some crude queueing theory

N-event buffer ... single queue size N:

P_k : % time with k events in ; P_N = no space available \rightarrow deadtime

$$\sum P_k = 1 \quad [k=0..N]$$

$$\text{rate } [j \rightarrow j+1] = \lambda \cdot P_j \quad (\text{fill at rate } \lambda)$$

$$\text{rate } [j+1 \rightarrow j] = \mu \cdot P_{j+1} \quad (\text{empty at rate } \mu > \lambda)$$

$$\text{steady state: } \mu \cdot P_{j+1} = \lambda \cdot P_j \Rightarrow P_{j+1} = \rho \cdot P_j = \rho^{j+1} \cdot P_0 \quad [\rho = (\lambda/\mu) < \sim 1]$$

$$\text{for } \rho \sim 1 \Rightarrow P_j \sim P_{j+1} \Rightarrow \sum P_k \sim (N+1) \cdot P_0 = 1 \Rightarrow P_0 \sim P_N \sim 1/(N+1)$$

$$\Rightarrow \text{deadtime} \sim 1/(N+1)$$

$$\text{want } \sim 1\% \Rightarrow N \sim 100$$

Appendix F: Some crude queueing theory

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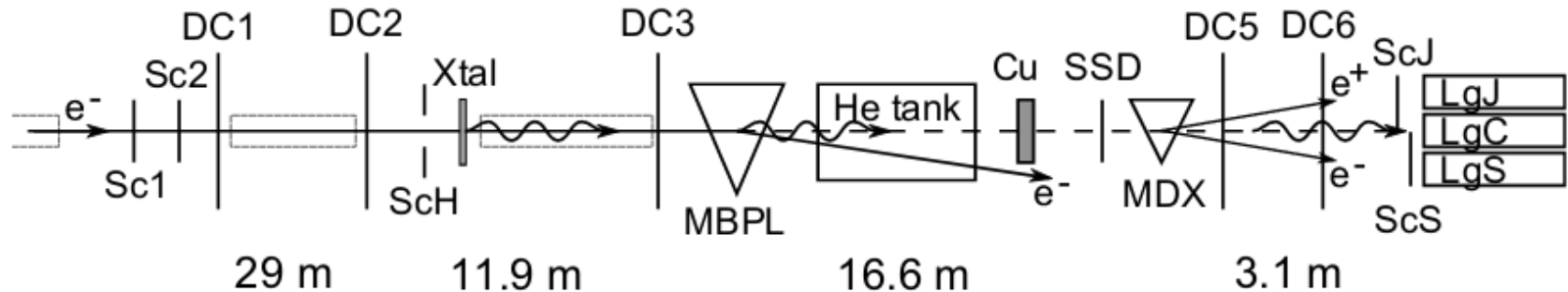
$$\text{for } \rho < 1, P_j \sim P_{j+1} \Rightarrow \sum P_k \sim (N+1) \cdot P_0 = 1 \Rightarrow P_0 \sim P_N \sim 1/(N+1)$$

$$\Rightarrow \text{deadtime} \sim 1/(N+1)$$

$$\text{want } \sim 1\% \Rightarrow N \sim 100$$

Take care: analytic calculation possible for pretty simple systems only

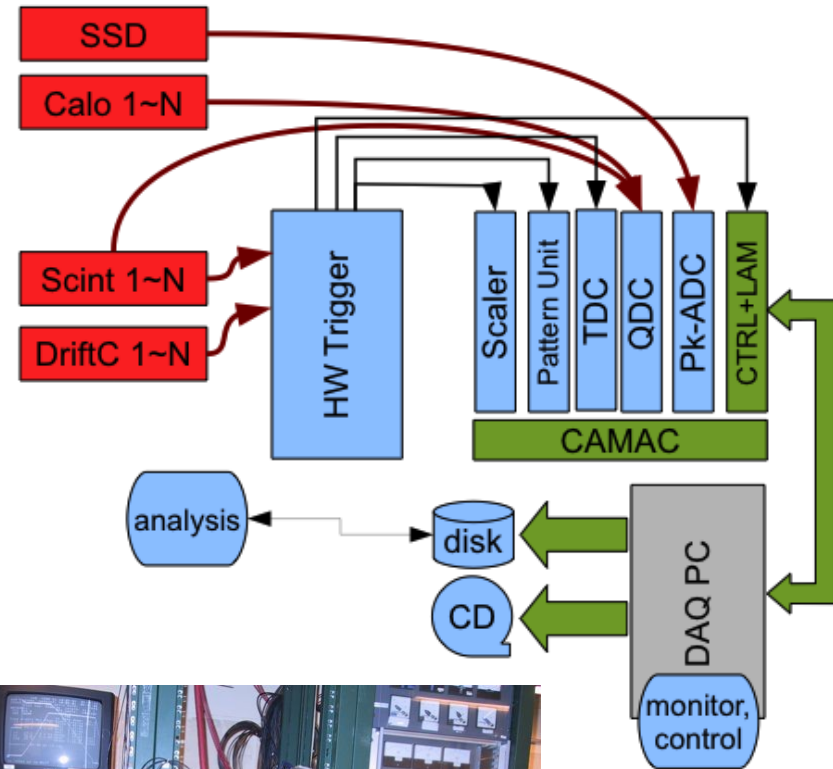
Appendix F: NA43/NA63



- Radiation processes:
coherent emission in crystals
and structured targets, LPM
suppression...
- 80/120 GeV e^- from
CERN SPS slow extraction
- 2s spill every 13.5s
- Needs very high angular resolution
- Long baseline + high-res, low
material detectors
→ drift Chambers
- 10 kHz limit on beam for radiation
damage
→ 2-3 kHz physics trigger

NA43/NA63

- 30-40 TDC, 6-16 QDC, 0-2 PADC
(depending on measurement)
- CAMAC bus
1 MB/s, no buffers, no Z.S.
- single PC readout
- NIM logic trigger (FPGA since 2009)
 - pileup rejection
 - fixed deadtime



Appendix G: Trigger qualification

trigger parameters:

- 1) (high) efficiency → can't be improved at HLT
- 2) (high) purity → can be improved at HLT
- 3) (low) latency → can be compensated for
- 4) (very low) jitter → can't be compensated for
- 5) synch/asynch → synch “easier”

Trigger qualification

Take care:

- 1) higher efficiency \Leftrightarrow lower purity
- 2) can compensate for (some) latency
- 3) can NOT compensate for jitter
- 4) asynch trigger synch'ed will get jitter