#### Seeding & Pattern - ACTS Seed Finder

Luis Falda Coelho

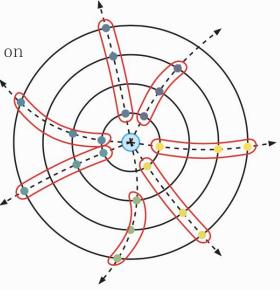
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# The Seeding Algorithm in ACTS

#### Seeding implementation in ACTS:

- Core/include/Acts/Seeding/ based on the ATLAS track seeding with a focus on parallelism, maintainability and as detector agnostic as possible
- Optimised for ITk upgrade
- $\circ$  Can be extended for other experiments
- Track seeds are created by **combining three SPs**
- The seeds define the helical path of a charged particle in a homogeneous magnetic field
- Used by the tracking to search for additional measurements to create a track
- Various constraints and confirmation conditions are applied to reduce the number of seed candidates → decreasing the tracking time
- Cuts are configurable

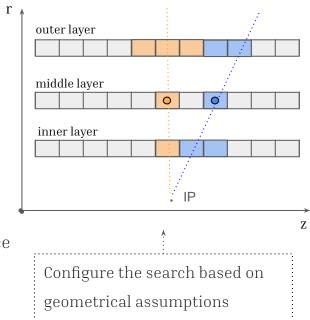


# SP Grid and Group Formation

The SPs in each detector layer are projected on a **rectangular grid** ( $\varphi$ , z) of **configurable granularity** (SpacePointGrid.ipp)

Triplet formation and search for seeds:

- Starts from selecting SP in the middle detector layer. Then matching
   SPs are searched in the inner an outer layers
- Grouping of the SPs in the grid allows to limit the search to neighbouring grid cells improving significantly algorithm performance
- The number of neighboring bins used in the search can be defined for each ( $\varphi$ , z) bin of the grid:



zBinEdges = [-3000.0, -2500.0, -1400.0, -925.0, -450.0, -250.0, 250.0, 450.0, 925.0, 1400.0, 2500.0, 3000.0,] # zBinEdges enables non-equidistant binning in z, in case the binning is not defined the edges are evaluated automatically using equidistant binning zBinNeighborsTop = [[0, 0],[-1, 0],[-1, 0],[-1, 0],[-1, 1],[0, 1],[0, 1],[0, 1],[0, 0],] # allows to specify the number of neighbors desired for each bin, [-1,1] means one neighbor on the left and one on the right, if the vector is empty the algorithm returns the 8 surrounding bins zBinNeighborsBottom = [[0, 1],[0, 1],[0, 1],[0, 1],[0, 0],[-1, 0],[

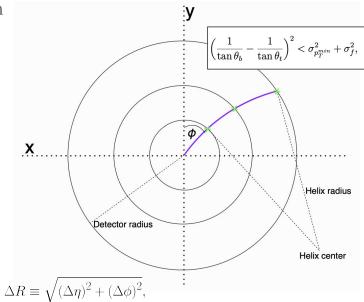
ZBINNeighborsBottom = [[0, 1],[0, 1],[0, 1],[0, 1],[0, 1],[0, 0],[-1,

### Seed Finder

Seed finder (Seedfinder.ipp) receives three iterators constructed from SPs from middle, inner and outer layers:

- createSeedsForGroup function starts by iterating over SPs in the middle layer
- **Configurable cuts are applied** to individual SPs and to combination of SPs:
  - Cuts to middle SPs if outside the region of interest
  - SP duplets are tested for compatibility by applying cuts with two SPs only ( $\eta$ ,  $z_0$ ,  $\Delta R$  between SPs, compatibility with IP)

```
for (auto topSP : topSPs) {
   float rT = topSP->radius();
   float deltaR = rT - rM;
   // if r-distance is too small, try next SP in bin
   if (deltaR < m_config.deltaRMinTopSP) {
      continue;
   }
}</pre>
```



// check if duplet origin on z axis within collision region
float zOrigin = zM - rM \* cotTheta;

if (zOrigin < m\_config.collisionRegionMin ||
 zOrigin > m\_config.collisionRegionMax) {
 continue;

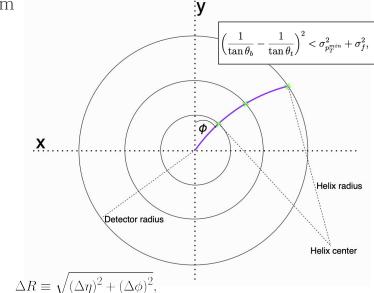
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4

## Seed Finder

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- $\circ$  Compatibility cuts between SP-triplets (ex: curvature compatibility with minimum  $\rm p_{T}$  scattering, transverse impact parameter  $\rm d_{0}$ )
- **Reduce the number of potential seeds** that may not lead to high quality tracks

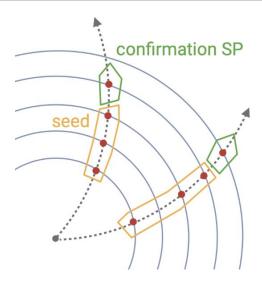
# Seed Filter and Seed Confirmation

After selecting the SP-triplets, a seed filter/confirmation procedure is applied to all the triplet combinations to **rank the seeds based on a weight** and keep only the best seeds:

$$w = -c_1 \cdot d_0 + (c_2 \cdot N_t - |z_0|)$$

Seeds can also be classified as higher quality seeds if they have specific values of d<sub>o</sub>, z<sub>o</sub> and N<sub>t</sub> inside a configurable range of parameters that also depends on the region of the detector (i.e. forward or central region)

```
struct SeedConfirmationRangeConfig {
 // z minimum and maximum of middle component of the seed used to define the
 // region of the detector for seed confirmation
 float zMinSeedConf =
     std::numeric_limits<float>::min(); // Acts::UnitConstants::mm
 float zMaxSeedConf =
      std::numeric limits<float>::max(); // Acts::UnitConstants::mm
 // radius of bottom component of seed that is used to define the number of
 // compatible top required
```



#### float rMaxSeedConf =

std::numeric limits<float>::max(); // Acts::UnitConstants::mm

- // number of compatible top SPs of seed if bottom radius is larger than
- // rMaxSeedConf
- size\_t nTopForLargeR = 0;
- // number of compatible top SPs of seed if bottom radius is smaller than
- // rMaxSeedConf
- size\_t nTopForSmallR = 0;

# Seed Filter and Seed Confirmation

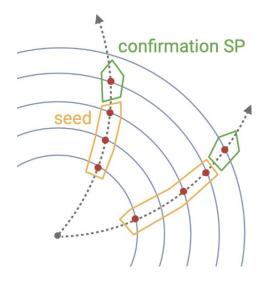
A limit to the number of seeds produced for each middle SP is also applied

int maxQualitySeedsPerSpMConf = std::numeric\_limits<int>::max();

If this limit is extrapolated, the algorithm will check if there is a seed with smaller weight that can be removed

Every SP holds the weight of the best seed containing that  $SP \rightarrow$  one seed is kept only if its weight is greater than the weight of at least one of its SP components:

```
if (weight < bottomSP.quality() and weight < middleSP.quality() and
  weight < topSpVec[i]->quality()) {
    continue;
}
```

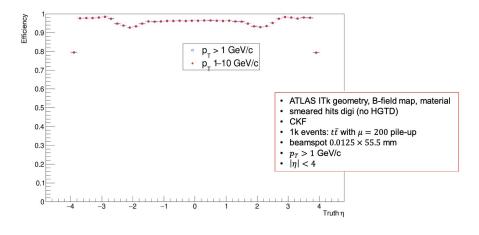


### ACTS-ITk Seeding Performance

ITk seeding configuration incorporated into chained style for Python modules:

 $\circ$  Standalone full chain ITk example  $\rightarrow$  ITk seeding with simple python configuration

Excellent performance when compared to the previous default (generic detector's) seeding configuration





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