

UK Research and Innovation

Rings and strings for enhanced coherent branching algorithms

Jack Holguin in collaboration with Jeff Forshaw and Simon Plätzer

Based on arXiv:2112.13124





Summary

$$\frac{\mathrm{d}(\cos\theta_{in})\mathrm{d}\phi_{n}}{1-\cos\theta_{in}}\Theta(\theta_{in}<\theta)\mapsto \ ^{(n-1)}\mathrm{S}_{i}^{j,k} E_{n}^{2} \Theta(\theta_{in}<\theta) \,\mathrm{d}(\cos\theta_{in})\mathrm{d}\phi_{n}$$
$$^{(n-1)}\mathrm{S}_{i}^{j,k} = \frac{s_{ij}s_{nk} + s_{ik}s_{nj} - s_{jk}s_{ni}}{2s_{ni}s_{nj}s_{nk}}$$

for $s_{ij} = q_i \cdot q_j$. The emitted parton is labelled n, i is its parent, j, k are spectators (defined later), and θ the previous angular scale in the shower. This modification extends the angular-ordered framework to the three-jet limit.

Motivation

In previous work:

- "Parton branching at amplitude level" J. Forshaw, JH, S. Plätzer arXiv:1905.08686
- "Soft gluon evolution and non-global logarithms" R. Ángeles Martínez, M. De Angelis, J. Forshaw, S. Plätzer, M. Seymour arXiv:1802.08531

Collinear poles from soft gluons cause issues in the Monte Carlo implementation (CVolver).

General observation: collinear poles are always colour diagonal. They are "simple", we must be able to exploit this.

Exploiting this is at the core of the coherent branching formalism.

Example: Collinear poles are colour diagonal

$$|M_n(q_1, \dots, q_n)\rangle = \mathbf{J}_n(q_n) |M_{n-1}(q_1, \dots, q_{n-1})\rangle + \mathcal{O}(\lambda^0)$$
$$\mathbf{J}_n^{(0)}(q_n) = \left(\frac{\alpha_s}{\pi}\right)^{\frac{1}{2}} \sum_{i,\lambda_i} \mathbf{T}_i \frac{\varepsilon_{\lambda_i}(q_n) \cdot q_i}{q_n \cdot q_i}$$

$$\mathbf{A}_{n} = \mathbf{J}_{n}^{(0)} |M_{n-1}\rangle \langle M_{n-1} | \mathbf{J}_{n}^{(0)\dagger} = -\frac{\alpha_{s}}{\pi} \sum_{i \neq j} \omega_{ij}(q_{n}) \mathbf{T}_{i} |M_{n-1}\rangle \langle M_{n-1} | \mathbf{T}_{j}^{\dagger}$$
$$\omega_{ij}(q_{n}) = \frac{q_{i} \cdot q_{j}}{q_{n} \cdot q_{i} \ q_{n} \cdot q_{j}}$$

Example: Collinear poles are colour diagonal

$$\mathbf{A}_{n} = \mathbf{J}_{n}^{(0)} |M_{n-1}\rangle \langle M_{n-1}| \mathbf{J}_{n}^{(0)\dagger} = -\frac{\alpha_{s}}{\pi} \sum_{i \neq j} \omega_{ij}(q_{n}) \mathbf{T}_{i} |M_{n-1}\rangle \langle M_{n-1}| \mathbf{T}_{j}^{\dagger}$$
$$[i \cdot j] = \mathbf{T}_{i} |M_{n-1}\rangle \langle M_{n-1}| \mathbf{T}_{j}^{\dagger}$$

$$\begin{aligned} \operatorname{Pole}_{q_n||q_i} \left(\omega_{ij}(q_n) \frac{\mathrm{d}^{3-2\epsilon} \vec{q_n}}{2E_n} \right) &= \frac{\mathrm{d}\theta_{ni}}{(\theta_{ni})^{1+2\epsilon}} \frac{E_i^{\epsilon} \mathrm{d}E_n}{(E_n)^{1+3\epsilon}} \mathrm{d}\phi \\ \sum_j \mathbf{T}_j &= \mathbf{0} \qquad \qquad \operatorname{Pole}_{q_n||q_i} \left(\mathbf{A}_n \frac{\mathrm{d}^{3-2\epsilon} \vec{q_n}}{2E_n} \right) &= \frac{\alpha_{\mathrm{s}}}{\pi} [i \cdot i] \frac{\mathrm{d}\theta_{ni}}{(\theta_{ni})^{1+2\epsilon}} \frac{E_i^{\epsilon} \mathrm{d}E_n}{(E_n)^{1+3\epsilon}} \mathrm{d}\phi \end{aligned}$$

Observation

We have shown the general observation at tree level: collinear poles are always colour diagonal.

However, this observation can be flipped.

Off-diagonal colour structures are always collinear finite.

It doesn't take much work to adapt the previous slides to show that each diagonal colour structure ($[i \cdot i]$) can be associated with a single colour pole.

Useful definitions

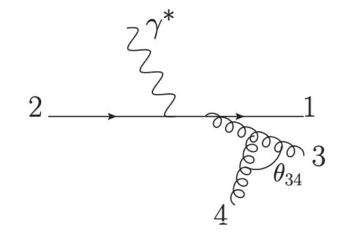
$$(n-1)S_{i}^{j,k} = \frac{1}{2} (\omega_{ij} + \omega_{ik} - \omega_{jk})$$
 A single collinear pole.

$$Pole_{q_{n}||q_{i}} \left({}^{(n-1)}S_{i}^{j,k} \frac{d^{3-2\epsilon}\vec{q_{n}}}{2E_{n}} \right) = Pole_{q_{n}||q_{i}} \left(\omega_{ij}(q_{n}) \frac{d^{3-2\epsilon}\vec{q_{n}}}{2E_{n}} \right) = Pole_{q_{n}||q_{i}} \left(\omega_{ik}(q_{n}) \frac{d^{3-2\epsilon}\vec{q_{n}}}{2E_{n}} \right) = \frac{d\theta_{ni}}{(\theta_{ni})^{1+2\epsilon}} \frac{E_{i}^{\epsilon}dE_{n}}{(E_{n})^{1+3\epsilon}} d\phi$$

$$(n-1)R_{k,l}^{i,j} = \omega_{ij}(q_{n}) - \omega_{ik}(q_{n}) - \omega_{jl}(q_{n}) + \omega_{kl}(q_{n})$$
 No collinear pole.

$$\begin{split} \mathbf{A}_{n} = & \frac{2\alpha_{\mathrm{s}}}{\pi} \left(\begin{array}{c} {}^{(n-1)}\mathbf{S}_{1}^{2,3}[1\cdot1] + {}^{(n-1)}\mathbf{S}_{2}^{1,3}[2\cdot2] + \sum_{i \neq 1,2} {}^{(n-1)}\mathbf{S}_{i}^{1,2}[i\cdoti] \right) \\ & - \frac{\alpha_{\mathrm{s}}}{2\pi} \sum_{i \neq 1,2,3} {}^{(n-1)}\mathbf{R}_{2,3}^{i,1}([i\cdot1-2] + [1-2\cdoti]) - \frac{\alpha_{\mathrm{s}}}{2\pi} \sum_{i \neq 1,2} \sum_{j \neq i,1,2} {}^{(n-1)}\mathbf{R}_{1,2}^{i,j}([i\cdotj] + [j\cdoti]). \end{split}$$

$$\begin{bmatrix} i \cdot j \end{bmatrix} = \mathbf{T}_i \ket{M_{n-1}} \langle M_{n-1} \ket{\mathbf{T}_j^{\dagger}}$$
$$\sum_j \mathbf{T}_j = 0 \quad \omega_{ij}(q_n) = \frac{q_i \cdot q_j}{q_n \cdot q_i \ q_n \cdot q_j}$$



$$\mathbf{A}_{4} = \frac{2\alpha_{s}}{\pi} \left({}^{(3)}\mathbf{S}_{1}^{2,3}[1 \cdot 1] + {}^{(3)}\mathbf{S}_{2}^{1,3}[2 \cdot 2] + {}^{(3)}\mathbf{S}_{3}^{1,2}[3 \cdot 3] \right)$$

$$^{(n-1)}\mathbf{S}_{i}^{j,k} = \frac{1}{2} \left(\omega_{ij} + \omega_{ik} - \omega_{jk} \right)$$
$$[i \cdot j] = \mathbf{T}_{i} |M_{n-1}\rangle \left\langle M_{n-1} | \mathbf{T}_{j}^{\dagger} \right.$$
$$\sum_{j} \mathbf{T}_{j} = 0 \quad \omega_{ij}(q_{n}) = \frac{q_{i} \cdot q_{j}}{q_{n} \cdot q_{i} \ q_{n} \cdot q_{j}}$$

$$A_{4} = \frac{2\alpha_{s}}{\pi} \left({}^{(3)}S_{1}^{2,3}[1 \cdot 1] + {}^{(3)}S_{2}^{1,3}[2 \cdot 2] + {}^{(3)}S_{3}^{1,2}[3 \cdot 3] \right)$$

$$2P_{ij} = w_{ij}^{(n)} + \frac{E_{i}}{E_{n} q_{i} \cdot q_{n}} - \frac{E_{j}}{E_{n} q_{j} \cdot q_{n}} \qquad E_{n}^{2} \int_{0}^{2\pi} \frac{\mathrm{d}\phi_{q}^{(i)}}{2\pi} P_{ij} = \frac{1}{1 - \cos\theta_{in}} \Theta(\theta_{in} < \theta_{ij})$$

$$P_{ij}^{[i]} = -\frac{(\mathrm{d}\cos\theta_{in}) \mathrm{d}\phi_{q}^{(i)}}{4\pi} \int_{0}^{2\pi} \frac{\mathrm{d}\phi_{q}^{(i)}}{2\pi} P_{ij} \qquad (n-1)S_{i}^{j,k} = \frac{1}{2} \left(\omega_{ij} + \omega_{ik} - \omega_{jk}\right)$$

$$egin{aligned} & [i \cdot j] = \mathbf{T}_i \ket{M_{n-1}} ig M_{n-1} \ket{\mathbf{T}_j^\dagger} \ & \sum_j \mathbf{T}_j = 0 \quad \omega_{ij}(q_n) = rac{q_i \cdot q_j}{q_n \cdot q_i \ q_n \cdot q_j} \end{aligned}$$

$$A_{4} = \frac{2\alpha_{s}}{\pi} \left({}^{(3)}S_{1}^{2,3}[1 \cdot 1] + {}^{(3)}S_{2}^{1,3}[2 \cdot 2] + {}^{(3)}S_{3}^{1,2}[3 \cdot 3] \right)$$

$${}^{(n-1)}\mathbf{S}_{i}^{j,k}\frac{\mathrm{d}\Omega_{n}}{4\pi} \approx \frac{1}{2}\left(P_{ij}^{[i]} + P_{ik}^{[i]}\right) + \frac{1}{2}\left(P_{ji}^{[j]} - P_{jk}^{[j]}\right) + \frac{1}{2}\left(P_{ki}^{[k]} - P_{kj}^{[k]}\right)$$

$$P_{ij}^{[i]} = -\frac{(\mathrm{d}\cos\theta_{in})\,\mathrm{d}\phi_q^{(i)}}{4\pi} \,\int_0^{2\pi} \frac{\mathrm{d}\phi_q^{(i)}}{2\pi} P_{ij}$$

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$$^{(n-1)}\mathbf{S}_{i}^{j,k} = rac{1}{2} \left(\omega_{ij} + \omega_{ik} - \omega_{jk}
ight)$$

 $[i \cdot j] = \mathbf{T}_{i} |M_{n-1}\rangle \langle M_{n-1}| \mathbf{T}_{j}^{\dagger}$
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$${}^{(n-1)}\mathbf{S}_{i}^{j,k}\frac{\mathrm{d}\Omega_{n}}{4\pi} \approx \frac{1}{2}\left(P_{ij}^{[i]} + P_{ik}^{[i]}\right) + \frac{1}{2}\left(P_{ji}^{[j]} - P_{jk}^{[j]}\right) + \frac{1}{2}\left(P_{ki}^{[k]} - P_{kj}^{[k]}\right)$$

$$\begin{split} & \stackrel{(n-1)}{\to} \mathbf{S}_{i}^{j,k} \frac{\mathrm{d}\Omega_{n}}{4\pi} \bigg|_{n_{i} \to n_{j}} \approx P_{ij}^{[i]}, \qquad \stackrel{(n-1)}{\to} \mathbf{S}_{i}^{j,k} \frac{\mathrm{d}\Omega_{n}}{4\pi} \bigg|_{n_{i} \to n_{k}} \approx P_{ik}^{[i]}, \\ & \stackrel{(n-1)}{\to} \mathbf{S}_{i}^{j,k} \frac{\mathrm{d}\Omega_{n}}{4\pi} \bigg|_{n_{j} \to n_{k}} \approx P_{ij}^{[i]} + \tilde{P}_{ji}^{[j]}(\theta_{jk}) \approx P_{ik}^{[i]} + \tilde{P}_{ki}^{[k]}(\theta_{jk}), \end{split}$$

Up to terms of the order θ^0 and in a frame where $\theta_{\text{spectators}} = \pi$

$$\tilde{P}_{jk}^{[j]}(\theta_{ij}) = P_{jk}^{[j]}\Theta(\theta_{jn} > \theta_{ij})$$

$$^{(n-1)}\mathbf{S}_{i}^{j,k} = rac{1}{2} \left(\omega_{ij} + \omega_{ik} - \omega_{jk}
ight)$$

 $[i \cdot j] = \mathbf{T}_{i} |M_{n-1}\rangle \langle M_{n-1}| \mathbf{T}_{j}^{\dagger}$
 $\sum_{j} \mathbf{T}_{j} = 0 \quad \omega_{ij}(q_{n}) = rac{q_{i} \cdot q_{j}}{q_{n} \cdot q_{i} \ q_{n} \cdot q_{j}}$

$$A_{4} = \frac{2\alpha_{s}}{\pi} \left({}^{(3)}S_{1}^{2,3}[1 \cdot 1] + {}^{(3)}S_{2}^{1,3}[2 \cdot 2] + {}^{(3)}S_{3}^{1,2}[3 \cdot 3] \right)$$

Up to terms of the order $(\theta_{13}^0 \theta_{i4}^0)$ and in a frame where $\theta_{12} = \pi$

$$\mathbf{A}_{4} \frac{\mathrm{d}\Omega_{n}}{4\pi} \Big|_{n_{1} \to n_{3}} \approx \frac{2\alpha_{s}}{\pi} \left(P_{13}^{[1]}[1 \cdot 1] + (P_{21}^{[2]} + \tilde{P}_{(1+3)2}^{[1+3]}(\theta_{13}))[2 \cdot 2] + P_{31}^{[3]}[3 \cdot 3] \right)$$

$$\overset{\mathbf{A}_{4} \frac{\mathrm{d}\Omega_{n}}{4\pi} \Big|_{n_{1} \to n_{3}} \approx \frac{2\alpha_{s}}{\pi} \left(P_{13}^{[1]}[1 \cdot 1] + (P_{21}^{[2]} + \tilde{P}_{(1+3)2}^{[1+3]}(\theta_{13}))[2 \cdot 2] + P_{31}^{[3]}[3 \cdot 3] \right)$$

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$$\overset{\mathbf{A}_{4} \frac{\mathrm{d}\Omega_{n}}{4\pi} \Big|_{n_{1} \to n_{3}} \approx \frac{1}{\pi} \left(P_{13}^{[1]}[1 \cdot 1] + (P_{21}^{[2]} + \tilde{P}_{13}^{[1+3]}(\theta_{13}))[2 \cdot 2] + P_{31}^{[3]}[3 \cdot 3] \right)$$

$$\overset{\mathbf{A}_{4} \frac{\mathrm{d}\Omega_{n}}{4\pi} \Big|_{n_{1} \to n_{1}} \approx \frac{1}{\pi} \left(P_{13}^{[1]}[1 \cdot 1] + (P_{21}^{[2]} + \tilde{P}_{13}^{[1+3]}(\theta_{13}))[2 \cdot 2] + P_{31}^{[3]}[3 \cdot 3] \right)$$

$$\overset{\mathbf{A}_{4} \frac{\mathrm{d}\Omega_{n}}{4\pi} \Big|_{n_{1} \to n_{1}} \approx \frac{1}{\pi} \left(P_{13}^{[1]}[1 \cdot 1] + (P_{21}^{[2]} + \tilde{P}_{13}^{[1]}[1 \cdot 1] + (P_{13}^{[2]}[1 \cdot 1] + (P_{13}^{[1]}[1 \cdot 1] + (P_{13}^{[1]}[1 \cdot 1] + (P_{13}^{[1]}[1 \cdot 1] + (P_{13}^{[2]}[1 \cdot 1] + (P_{13}^{[2]}[1$$

But why azimuthally average if it constrains us to the $\theta_{12} = \pi$ frame?

It prevents us from applying the derivation outside the 2-jet limit where there is no azimuthal symmetry.

Outside the 2-jet limit in the $\theta_{12} = \pi$ frame terms with a θ_{13}^{-1} collinear pole depend on the azimuth.

But why azimuthally average if it constrains us to the $\theta_{12} = \pi$ frame?

What the averaging achieves is it handles the commutation of limits: i.e.

$$\lim_{q_n/E_n \to n_i} \lim_{n_i \to n_j} \omega_{ij}(q_n) \to 0, \qquad \qquad \lim_{n_i \to n_j} \lim_{q_n/E_n \to n_i} \omega_{ij}(q_n) \to \infty.$$

The theta function in $P_{ij}^{[i]}$ always screens us from complications due to conflicting limits. In our case the limits of concern are of the form

$$\lim_{q_n/E_n \to n_i} \lim_{n_i \to n_j} (n-1) \mathbf{R}_{k,l}^{i,j} \to \lim_{q_n/E_n \to n_i} -2^{(n-1)} \mathbf{S}_i^{k,l} \to -\infty$$

 $\lim_{n_i \to n_j} \lim_{q_n/E_n \to n_i} (n-1) \mathbf{R}_{k,l}^{i,j} \to \omega_{kl} + \mathcal{O}(\theta_{in}^0, \theta_{ij}^0)$

The lack of commutativity of these angular limits suggest the presence of poles on the boundaries dividing the limits. It is these poles that average to give theta functions.

However, we do not need to average to handle the poles. What we are doing is computing Laurent series of the density matrix around the emission angles.

When computing Laurent series around a pole you divide the domain with other poles defining boundaries. Then compute the expansion in each region. The union of the expansion across the regions provides the complete expansion (taking care of overlaps).

It turns out that for the simple string only one partition is really necessary:

$$^{(n-1)}\mathbf{S}_{i}^{j,k} = {}^{(n-1)}\mathbf{S}_{i}^{j,k}(\Theta(\theta_{in} < \theta_{ij}) + \Theta(\theta_{in} > \theta_{ij}))$$

which is sufficient for us to show that,

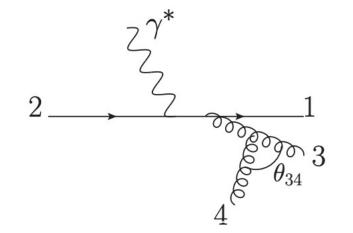
$$^{(n-1)}\mathbf{S}_{i}^{j,k}\big|_{n_{j}\to n_{i}}\approx \ ^{(n-1)}\mathbf{S}_{i}^{j,k}\Theta(\theta_{in}<\theta_{ij})$$

since,

$$(\omega_{ij}(q_n) + \omega_{ik}(q_n) - \omega_{jk}(q_n))\Theta(\theta_{in} > \theta_{ij})|_{n_j \to n_i} \approx 0$$

up to terms of the order θ^0 .

$$(n-1)\mathbf{S}_{i}^{j,k} = \frac{1}{2} (\omega_{ij} + \omega_{ik} - \omega_{jk})$$
$$[i \cdot j] = \mathbf{T}_{i} |M_{n-1}\rangle \langle M_{n-1}| \mathbf{T}_{j}^{\dagger}$$
$$\sum_{j} \mathbf{T}_{j} = 0 \quad \omega_{ij}(q_{n}) = \frac{q_{i} \cdot q_{j}}{q_{n} \cdot q_{i} \ q_{n} \cdot q_{j}}$$

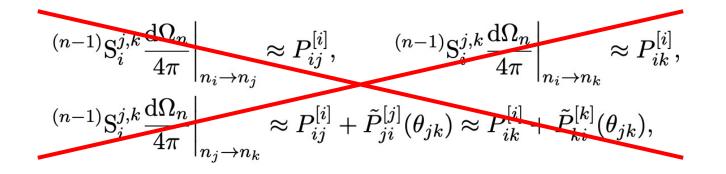


$$\mathbf{A}_{4} = \frac{2\alpha_{s}}{\pi} \left({}^{(3)}\mathbf{S}_{1}^{2,3}[1 \cdot 1] + {}^{(3)}\mathbf{S}_{2}^{1,3}[2 \cdot 2] + {}^{(3)}\mathbf{S}_{3}^{1,2}[3 \cdot 3] \right)$$

$$^{(n-1)}\mathbf{S}_{i}^{j,k} = rac{1}{2} \left(\omega_{ij} + \omega_{ik} - \omega_{jk}
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 $[i \cdot j] = \mathbf{T}_{i} |M_{n-1}\rangle \left\langle M_{n-1} | \mathbf{T}_{j}^{\dagger} \right.$
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$$A_{4} = \frac{2\alpha_{s}}{\pi} \left({}^{(3)}S_{1}^{2,3}[1 \cdot 1] + {}^{(3)}S_{2}^{1,3}[2 \cdot 2] + {}^{(3)}S_{3}^{1,2}[3 \cdot 3] \right)$$



$$(n-1)\mathbf{S}_{i}^{j,k}\big|_{n_{j}\to n_{i}} \approx (n-1)\mathbf{S}_{i}^{j,k}\Theta(\theta_{in} < \theta_{ij})$$

*

$$^{(n-1)}\mathbf{S}_{i}^{j,k} = \frac{1}{2} \left(\omega_{ij} + \omega_{ik} - \omega_{jk} \right)$$
$$[i \cdot j] = \mathbf{T}_{i} |M_{n-1}\rangle \left\langle M_{n-1} | \mathbf{T}_{j}^{\dagger} \right.$$
$$\sum_{j} \mathbf{T}_{j} = 0 \quad \omega_{ij}(q_{n}) = \frac{q_{i} \cdot q_{j}}{q_{n} \cdot q_{i} \ q_{n} \cdot q_{j}}$$

$$A_{4} = \frac{2\alpha_{s}}{\pi} \left({}^{(3)}S_{1}^{2,3}[1 \cdot 1] + {}^{(3)}S_{2}^{1,3}[2 \cdot 2] + {}^{(3)}S_{3}^{1,2}[3 \cdot 3] \right)$$

$$\begin{split} \mathbf{A}_4 \big|_{n_1 \to n_3} &\approx \frac{2\alpha_{\rm s}}{\pi} \bigg[\, {}^{(3)} {\rm S}_1^{2,3} \Theta(\theta_{14} < \theta_{13}) [1 \cdot 1] \\ &+ \, {}^{(3)} {\rm S}_2^{1,3} \Theta(\theta_{(1+3)4} > \theta_{13}) [2 \cdot 2] + \, {}^{(3)} {\rm S}_3^{1,2} \Theta(\theta_{34} < \theta_{13}) [3 \cdot 3] \end{split}$$

Up to terms of the order $(\theta_{13}^0 \theta_{i4}^0)$ and in any frame.

This and the averaged result precisely agree when $\theta_{12} = \pi$.

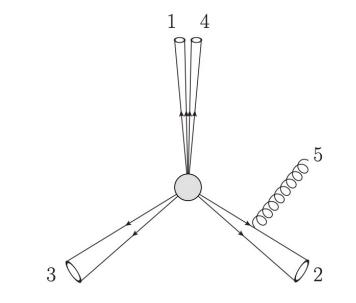
$$^{(n-1)}\mathbf{S}_{i}^{j,k} = \frac{1}{2} \left(\omega_{ij} + \omega_{ik} - \omega_{jk} \right)$$
$$[i \cdot j] = \mathbf{T}_{i} |M_{n-1}\rangle \left\langle M_{n-1} | \mathbf{T}_{j}^{\dagger} \right.$$
$$\sum_{j} \mathbf{T}_{j} = 0 \quad \omega_{ij}(q_{n}) = \frac{q_{i} \cdot q_{j}}{q_{n} \cdot q_{i} \ q_{n} \cdot q_{j}}$$

$$\begin{split} \mathbf{A}_{4\,\mathrm{jet}+(g)} = & \frac{2\alpha_{\mathrm{s}}}{\pi} \left[{}^{(4)}\mathrm{S}_{1}^{2,3}|1\cdot1|_{4} + {}^{(4)}\mathrm{S}_{2}^{1,3}|2\cdot2|_{4} + {}^{(4)}\mathrm{S}_{3}^{1,2}|3\cdot3|_{4} + {}^{(4)}\mathrm{S}_{4}^{1,2}|4\cdot4|_{4} \right] \\ & - \frac{\alpha_{\mathrm{s}}}{2\pi} \left[{}^{(4)}\mathrm{R}_{1,2}^{3,4}(|1\cdot4|_{4} + |3\cdot4|_{4} - |2\cdot4|_{4} + |4\cdot1|_{4} + |4\cdot3|_{4} - |4\cdot2|_{4}) \right. \\ & + {}^{(4)}\mathrm{R}_{1,2}^{4,3}(|2\cdot4|_{4} + |3\cdot4|_{4} - |1\cdot4|_{4} + |4\cdot2|_{4} + |4\cdot3|_{4} - |4\cdot1|_{4}) \end{split}$$

The same steps can be followed to find the 3jet coherence limit of the matrix element above.

The derivation is a little more subtle, more regions must be identified, but the outcome is elegant (I think).

$$\begin{aligned} \mathbf{A}_{4\,\mathrm{jet}+(g)} \big|_{1||4} &\approx \frac{2\alpha_{\mathrm{s}}}{\pi} \bigg[{}^{(4)}\mathrm{S}_{1}^{2,3} \Theta(\theta_{15} < \theta_{14}) |1 \cdot 1|_{4} + {}^{(4)}\mathrm{S}_{2}^{1,3} |2 \cdot 2|_{4} + {}^{(4)}\mathrm{S}_{3}^{1,2} |3 \cdot 3|_{4} + \\ & {}^{(4)}\mathrm{S}_{4}^{1,2} |4 \cdot 4|_{4} + {}^{(4)}\mathrm{S}_{1}^{2,3} \Theta(\theta_{15} > \theta_{14}) |1 + 4 \cdot 1 + 4|_{4} \bigg]. \end{aligned}$$



$$(n-1)\mathbf{S}_{i}^{j,k} = \frac{1}{2} (\omega_{ij} + \omega_{ik} - \omega_{jk})$$
$$[i \cdot j] = \mathbf{T}_{i} |M_{n-1}\rangle \langle M_{n-1}| \mathbf{T}_{j}^{\dagger}$$
$$\sum_{j} \mathbf{T}_{j} = 0 \quad \omega_{ij}(q_{n}) = \frac{q_{i} \cdot q_{j}}{q_{n} \cdot q_{i} \ q_{n} \cdot q_{j}}$$

Returning to slide 2

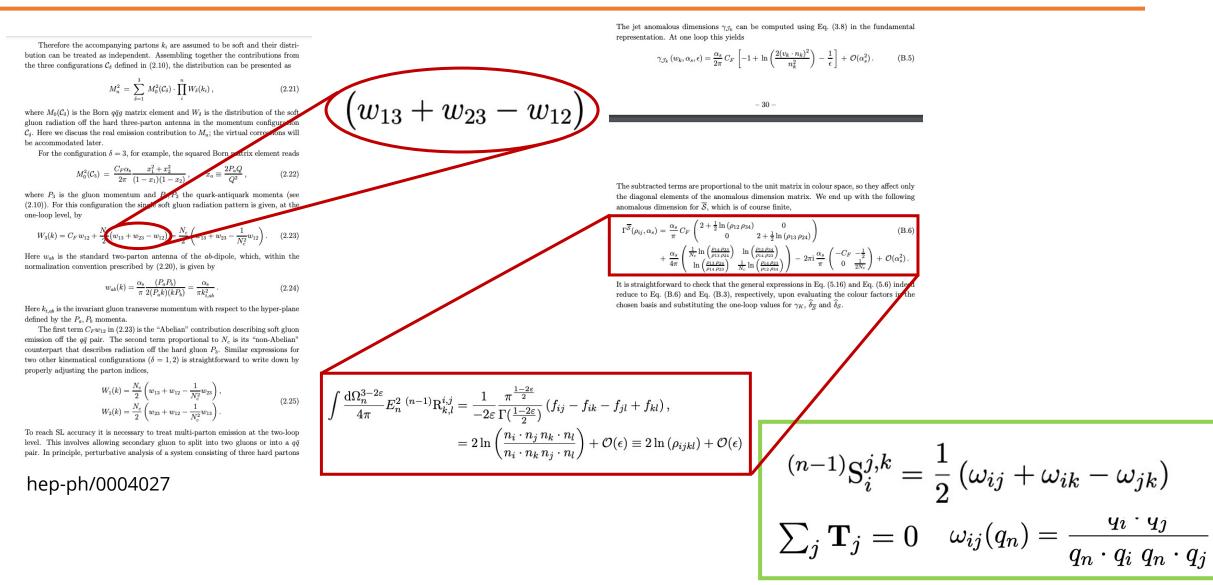
The complete outcome can be summarised

$$\frac{\mathrm{d}(\cos\theta_{in})\mathrm{d}\phi_{n}}{1-\cos\theta_{in}}\Theta(\theta_{in}<\theta)\mapsto \ ^{(n-1)}\mathrm{S}_{i}^{j,k} E_{n}^{2}\Theta(\theta_{in}<\theta) \,\mathrm{d}(\cos\theta_{in})\mathrm{d}\phi_{n}$$
$$^{(n-1)}\mathrm{S}_{i}^{j,k} = \frac{s_{ij}s_{nk}+s_{ik}s_{nj}-s_{jk}s_{ni}}{2s_{ni}s_{nj}s_{nk}}$$

for $s_{ij} = q_i \cdot q_j$. The emitted parton is labelled n, i is its parent, j, k are spectators (defined later), and θ the previous angular scale in the shower. This modification extends the angular-ordered framework to the three-jet limit.

... up to terms of the order θ^0 .

In the literature



Momentum conservation

There is a question of momentum conservation...

$$^{(n-1)}S_i^{j,k} = \frac{1}{2} \left(\omega_{ij} + \omega_{ik} - \omega_{jk} \right)$$
 Two spectators for a given colour structure. Genuine 3->4 transition.

There isn't a known solution to conserving recoils for 3->4 transitions. The problem is consistency between the 2-jet limit and 3-jet limit.

$$q_{5} = \alpha q_{2} + \beta q_{1} + \gamma (q_{3} + q_{4}) + k_{\perp}$$

$$q_{5} = \alpha q_{2} + \beta (q_{1} + q_{3} + q_{4}) + k_{\perp}$$
D.o.f. in k_{\perp} changes

Momentum conservation

There is a question of momentum conservation...

$$^{(n-1)}S_i^{j,k} = \frac{1}{2} (\omega_{ij} + \omega_{ik} - \omega_{jk})$$
 Two spectators for a given colour structure. Genuine 3->4 transition.

There isn't a known solution to conserving recoils for 3->4 transitions.

Solution could be to just pick one of the spectators with a 50% chance each time and use the large body of work on 2->3 recoils.

This is consistent with the 2-jet limit but doesn't "feel right". It would be sufficient for a Parton Shower implementation though.

Concluding

The complete outcome can be summarised

$$\frac{\mathrm{d}(\cos\theta_{in})\mathrm{d}\phi_{n}}{1-\cos\theta_{in}}\Theta(\theta_{in}<\theta)\mapsto \ ^{(n-1)}\mathrm{S}_{i}^{j,k} E_{n}^{2}\Theta(\theta_{in}<\theta)\,\mathrm{d}(\cos\theta_{in})\mathrm{d}\phi_{n}$$
$$^{(n-1)}\mathrm{S}_{i}^{j,k} = \frac{s_{ij}s_{nk}+s_{ik}s_{nj}-s_{jk}s_{ni}}{2s_{ni}s_{nj}s_{nk}}$$

for $s_{ij} = q_i \cdot q_j$. The emitted parton is labelled n, i is its parent, j, k are spectators (defined later), and θ the previous angular scale in the shower. This modification extends the angular-ordered framework to the three-jet limit.

...up to terms of the order θ^0 . Randomly pick j or k as a spectator for recoil in a 2->3 style.