

# BIG SAR ANALYSIS READY DATA: REALISING THE ESA-DLR SENTINEL-1 NORMALISED RADAR BACKSCATTER PRODUCT

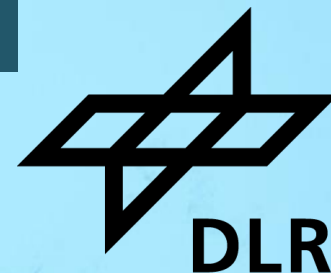
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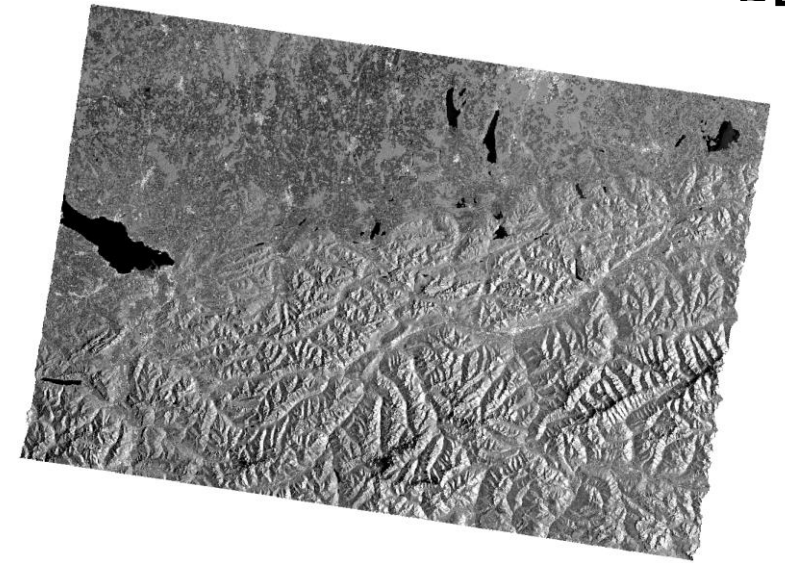
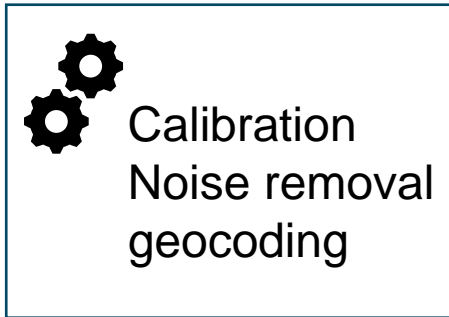
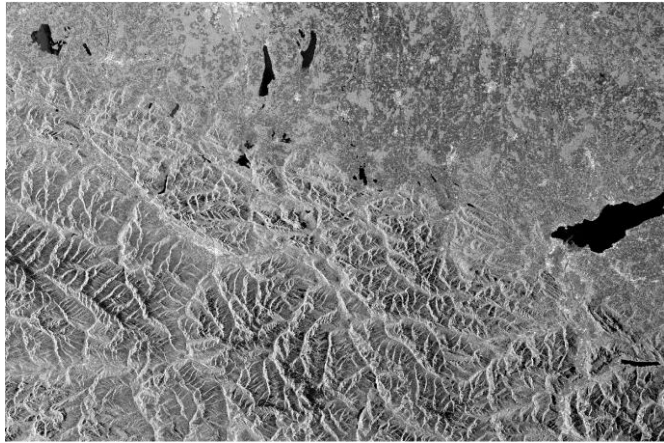
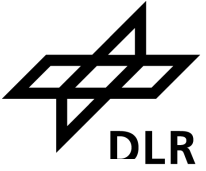
# Sentinel-1



- Synthetic Aperture Radar (SAR) mission of the Copernicus programme
- Operated by ESA
- Free and open data policy
- Application examples:
  - Marine monitoring: ship traffic, ice, sea state
  - Land monitoring: flood mapping, ground deformation
- Revisit time: 12 days (6 with two satellites)
- Satellites:
  - Sentinel-1A: 2014-04-03 –
  - Sentinel-1B: 2016-04-25 – 2022-08-03
  - Sentinel-1C: 2023
- Total data volume as of Sept. 2022:
  - Ground Range Detected (GRD): 2 PB
  - Single Look Complex (SLC): 10 PB



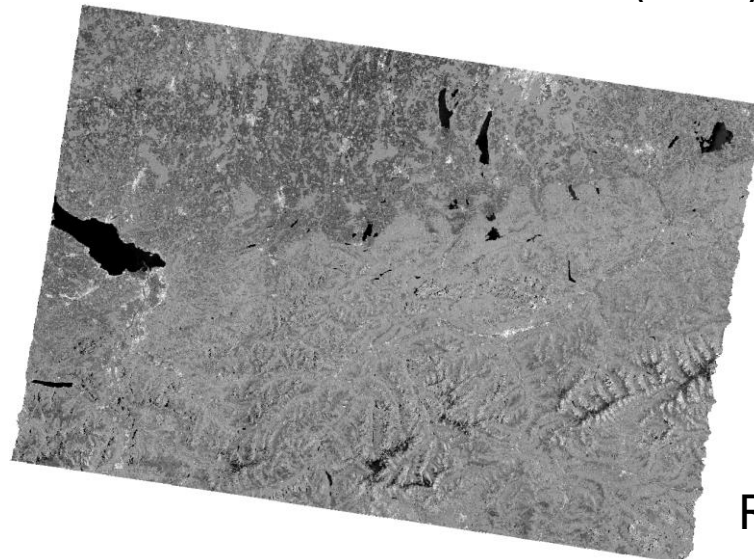
# SAR Image Processing



Ellipsoid-based sigma nought



+ radiometric terrain correction (RTC)



RTC gamma nought

# CEOS Analysis Ready Data



## Current Product Family Specifications

PFS	Type	Version	Download	Metadata Spec	Last Updated
Surface Reflectance	Optical	5.0	PDF   Word	-	8 June 2020
Surface Temperature	Optical	5.0	PDF   Word	-	8 June 2020
Normalised Radar Backscatter	Radar	5.5	PDF   Word	XLSX	13 May 2022
Polarimetric Radar	Radar	3.5	PDF   Word	XLSX	13 May 2022
Aquatic Reflectance	Optical	1.0	PDF   Word	-	23 February 2022
Ocean Radar Backscatter	Radar	1.0	PDF   Word	XLSX	21 September 2022
Nighttime Lights Surface Radiance	Optical	1.0	PDF   Word	-	2 October 2022

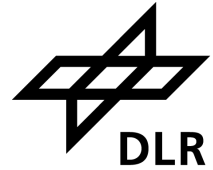
# CEOS Analysis Ready Data



## Under Development / Assessment

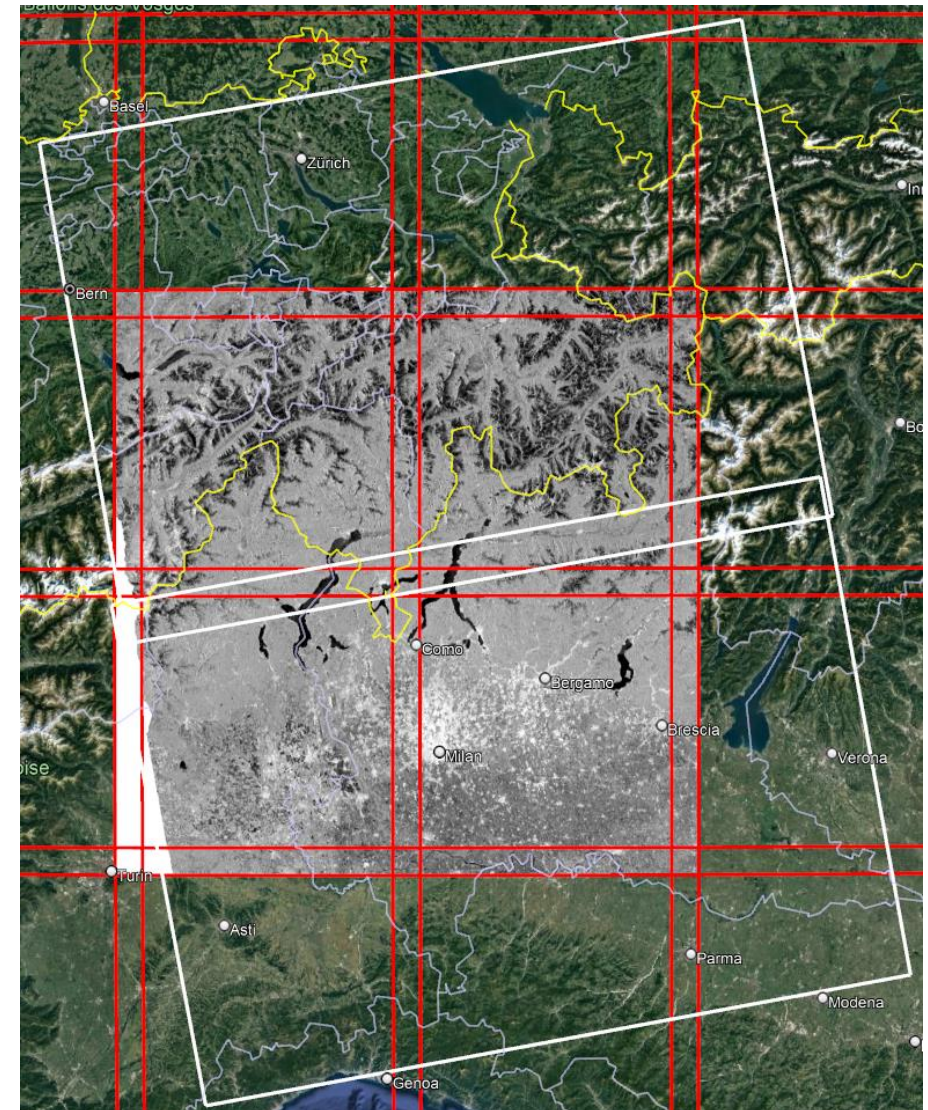
Product	CEOS-ARD Type	PFS Version	Agency	Mission(s)	Access (DOI)	Info	Self Assessment	Peer Review	Sample Products
...									
Landsat L2 Provisional Aquatic Reflectance	Aquatic Reflectance	v1.0	USGS	<a href="#">Landsat 8, 9</a>	TBA	<a href="#">Link</a>	TBA	TBA	<a href="#">Link</a>
NovaSAR-1 RTC	Normalised Radar Backscatter	v5.5	CSIRO	<a href="#">NovaSAR-1</a>	TBA	<a href="#">Link</a>	Ongoing	TBA	TBA
Resourcesat-2/2A	Surface Reflectance	v5.0	ISRO	<a href="#">Resourcesat-2, 2A</a>	TBA	<a href="#">Link</a>	Ongoing	TBA	TBA
RISAT-1A (EOS-04) NRB	Normalised Radar Backscatter	v5.5	ISRO	<a href="#">RISAT-1A (EOS-04)</a>	TBA	TBA	TBA	TBA	TBA
→ Sentinel-1 NRB	Normalised Radar Backscatter	v5.5	ESA	Sentinel-1 (A, B)	TBA	<a href="#">Link</a>	TBA	TBA	TBA
→ Sentinel-1 ORB	Ocean Radar Backscatter	v1.0	ESA	Sentinel-1 (A, B)	TBA	TBA	TBA	TBA	TBA

# ESA-DLR NRB Product Characteristics



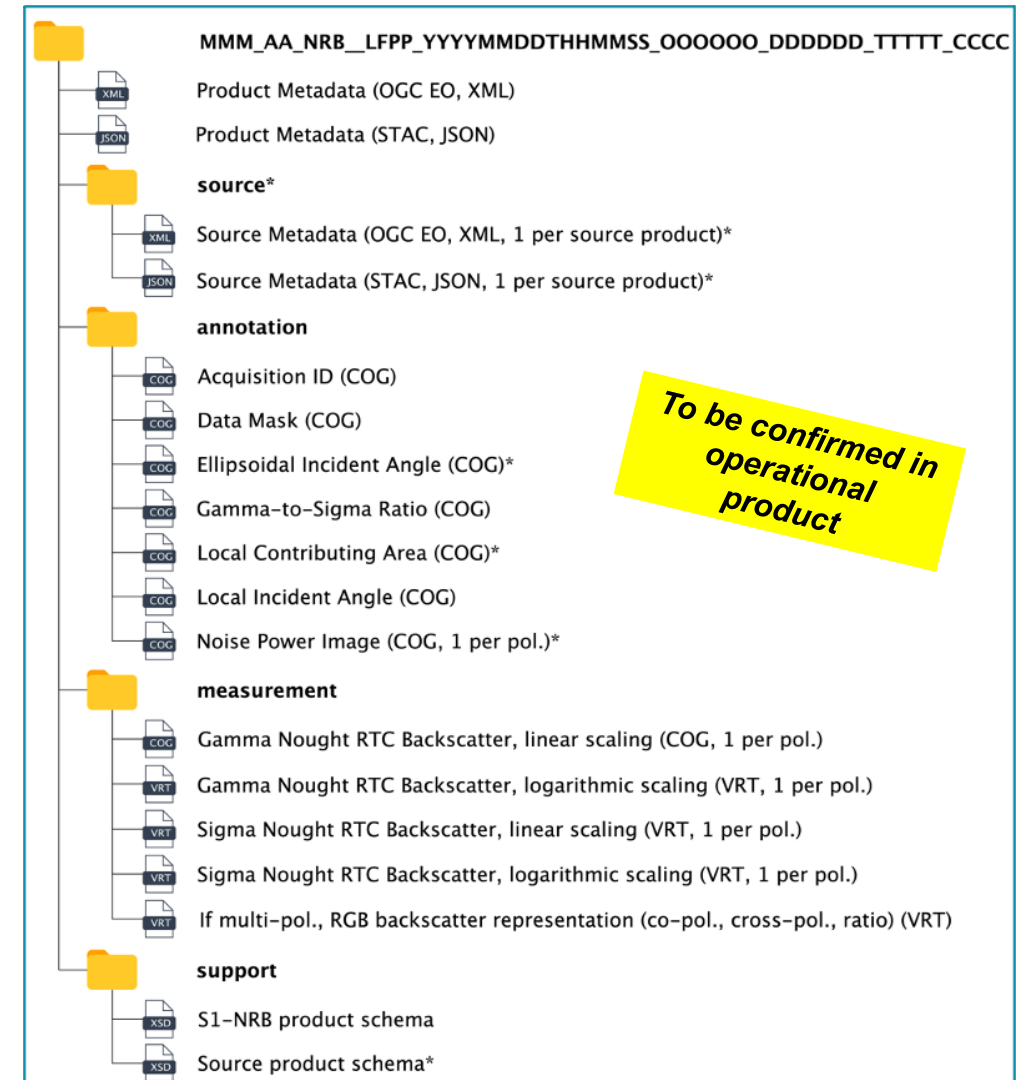
- Seamless mosaics of multiple source scenes
- Exact extent of Sentinel-2 grid cells (based on Military Grid Reference System MGRS)
- UTM projection (UPS over poles)
- 10 m spacing
- 100 km tile plus overlap:
  - 10980 \* 10980 pixels
  - 109.8 \* 109.8 km
- Cloud Optimized GeoTIFF (COG)
  - 512 \* 512 tiling
  - Overview levels: 2, 4, 9, 18, 36
- “LERC\_ZSTD” Raster Compression

<https://sentinel.esa.int/web/sentinel/sentinel-1-ard-normalised-radar-backscatter-nrb-product>



# Product content

- Measurement: radiometrically terrain corrected (RTC) gamma nought ( $\gamma_T^0$ ) backscatter per polarisation
- Ancillary Data:
  - Acquisition ID mask: source scene ID per pixel
  - Data mask: ocean, layover and shadow
  - Ellipsoidal incidence angle
  - Gamma-sigma ratio: convert measurement to RTC sigma nought
  - Local contributing area: area exposed to the sensor
  - Local incidence angle: angle of illumination
  - Noise power: noise subtracted from measurement
- Metadata: OGC EO XML, SpatioTemporal Asset Catalog (STAC) JSON



# Product Size

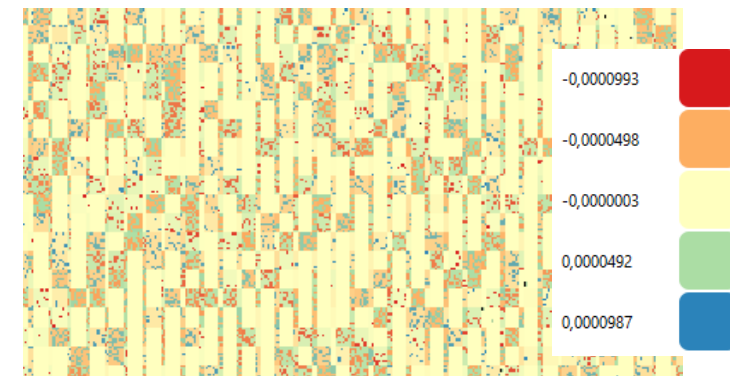


- Example product over the Alps (tile 32TNS)
- “worst case scenario” with full data coverage and strong terrain variation
- Higher ratios in flat terrain (due to higher auto-correlation)
- Near-linear decrease of product size with reduced data coverage
- Overall volume: 3-4 x GRD



Tile location

Image	Max. error	Plain [MB]	Plain, overviews [MB]	Compressed, overviews [MB]	Ratio
Acquisition ID	0	115	153	3.9	39.5
Data Mask	0			0.1	1620.4
Noise power VH	2e-5	460	611	149.3	4.1
Noise power VV	2e-5			150.1	4.1
Gamma/Sigma Ratio	1e-4			209.8	2.9
VH gamma0	2e-5			171.9	3.6
VV gamma0	2e-5			218.3	2.8
Ellipsoidal Incident angle	1e-3			26.2	23.3
Local incident angle	1e-2			211.3	2.9
Local contributing area	0.1			66.2	9.2
<b>TOTAL</b>		<b>3909</b>	<b>5194</b>	<b>1207</b>	<b>4.3</b>



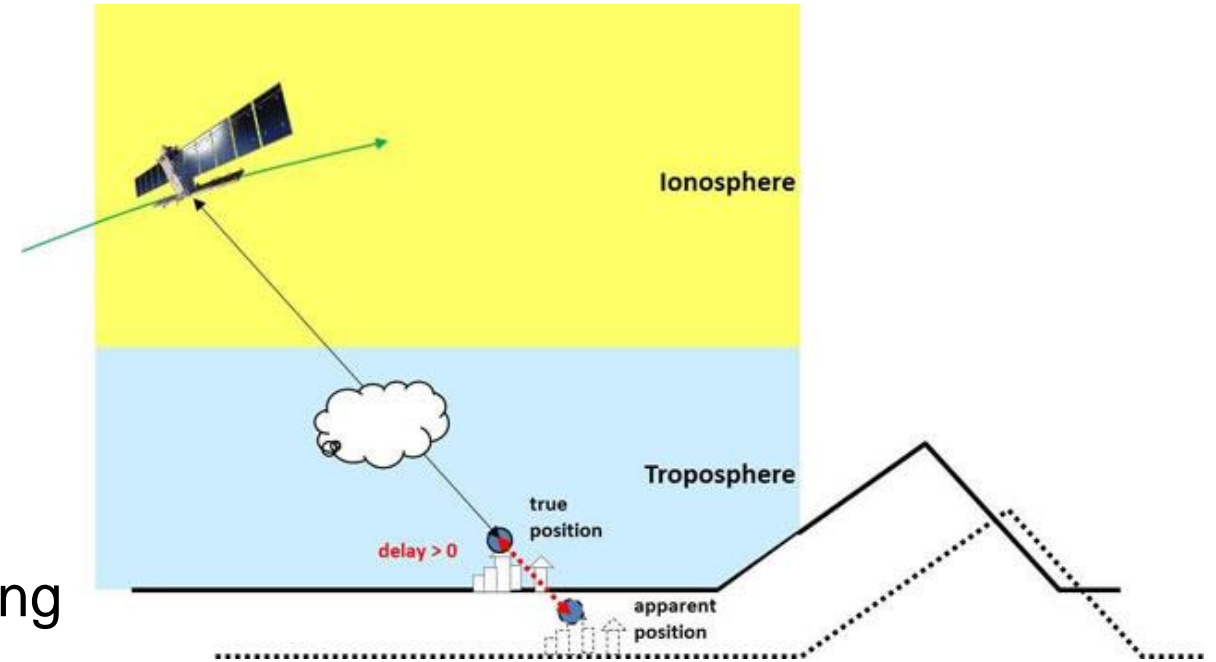
LERC compression artifacts (tile overlap difference) with 1e-4 error



# Extended Timing Annotation Dataset (ETAD)



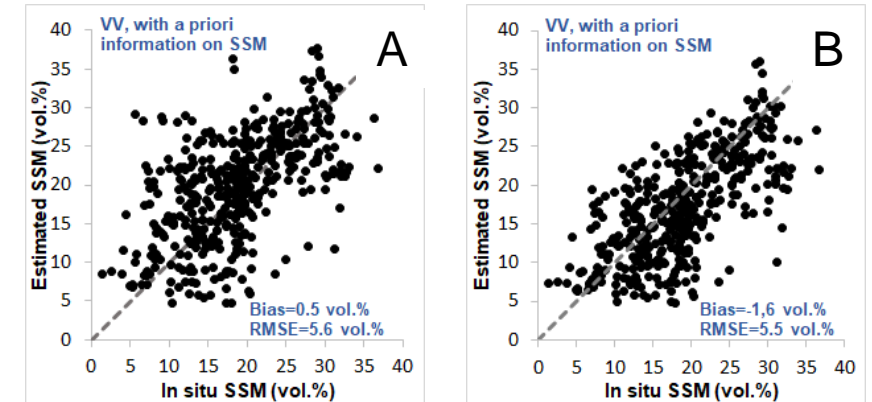
- Geolocation accuracy of Sentinel-1 is approx. 3 m (non-geocoded)
- Main factors for inaccuracies:
  - Atmospheric delay
  - Solid earth tides
  - Instrument movement
- Accuracy can be improved to 0.1 m by utilising the ETAD product
- A new Sentinel-1 product can be created from an existing one and the corresponding ETAD product
- ETAD products will be openly available in the second half of 2023
- Additional inaccuracies in NRB product due to interpolation and DEM



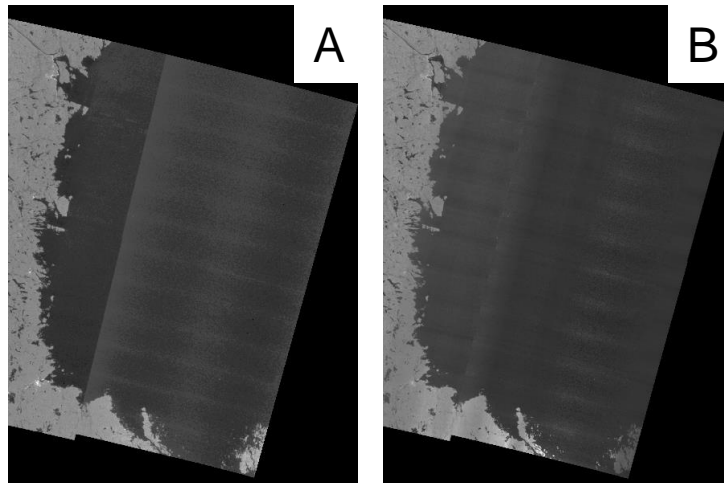
<https://sentinel.esa.int/web/sentinel/missions/sentinel-1/data-products/etad-dataset>

# Use Cases

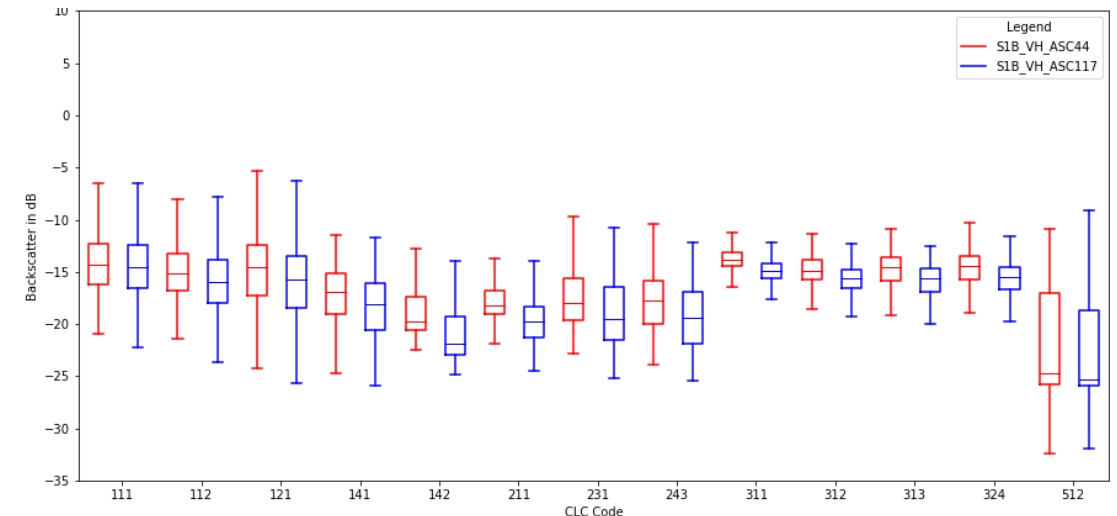
- Soil Moisture (INRAE, France)
  - Investigation of gamma nought RTC suitability for soil moisture retrieval
- Sea Ice (FMI, Finland)
  - Comparison of methods for removal of thermal noise and scalloping effects
- Land Use / Land Cover (Uni Jena, Germany)
  - Testing of S1-NRB data cube capabilities
  - Analysis of backscatter time series variability across different LULC classes and observation scenarios



Surface soil moisture retrieved from  $\sigma_E^0$  (A) and  $\gamma_T^0$  (B).

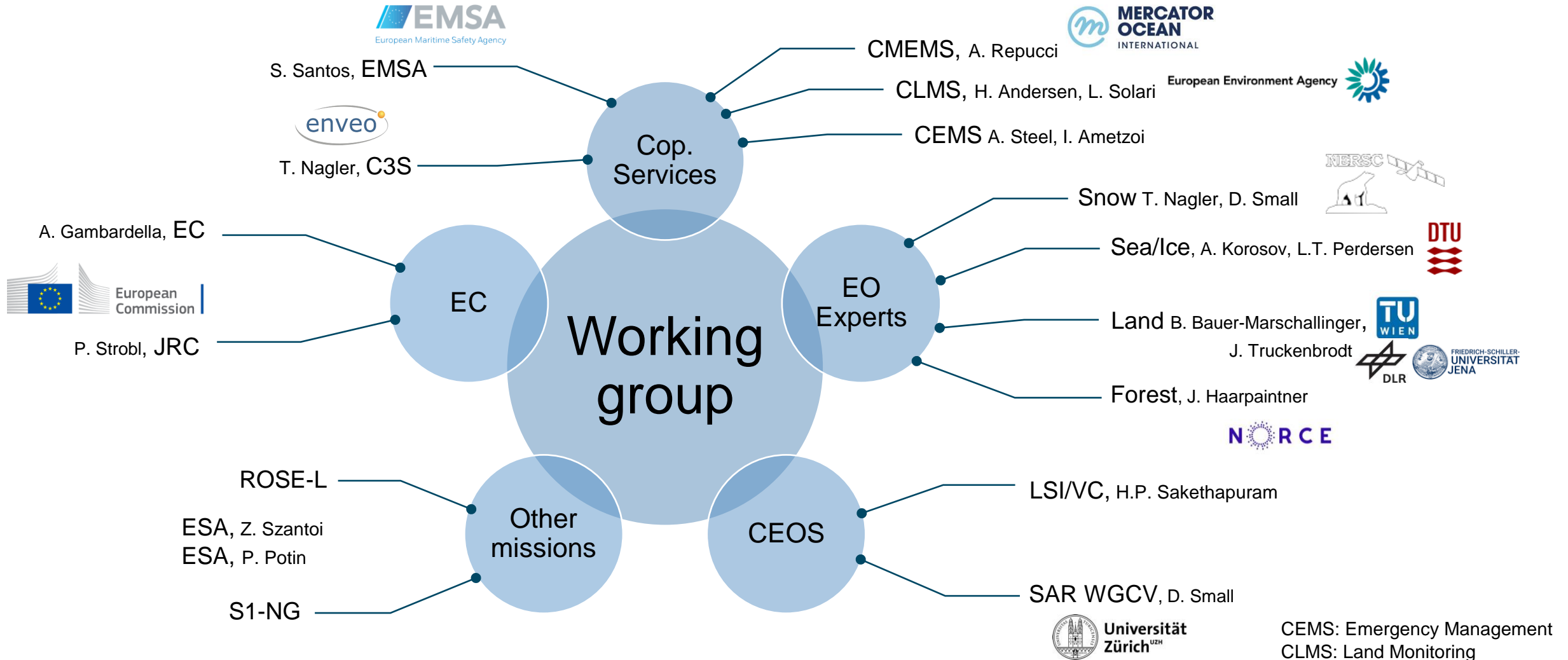


S1 EW VH image after noise removal using the NERSC (A) and FMI (B) methods.



Comparison of backscatter from near range (ASC44) and far range (ASC117) for different CORINE classes.

# NRB Working Group



CEMS: Emergency Management  
 CLMS: Land Monitoring  
 CMEMS: Maritime Env. Monitoring  
 CMS: Maritime Surveillance  
 C3S: Climate Change  
 EGMS: Ground Motion

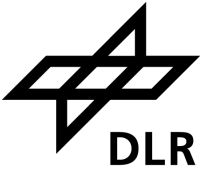
# Instrument Processing Facility



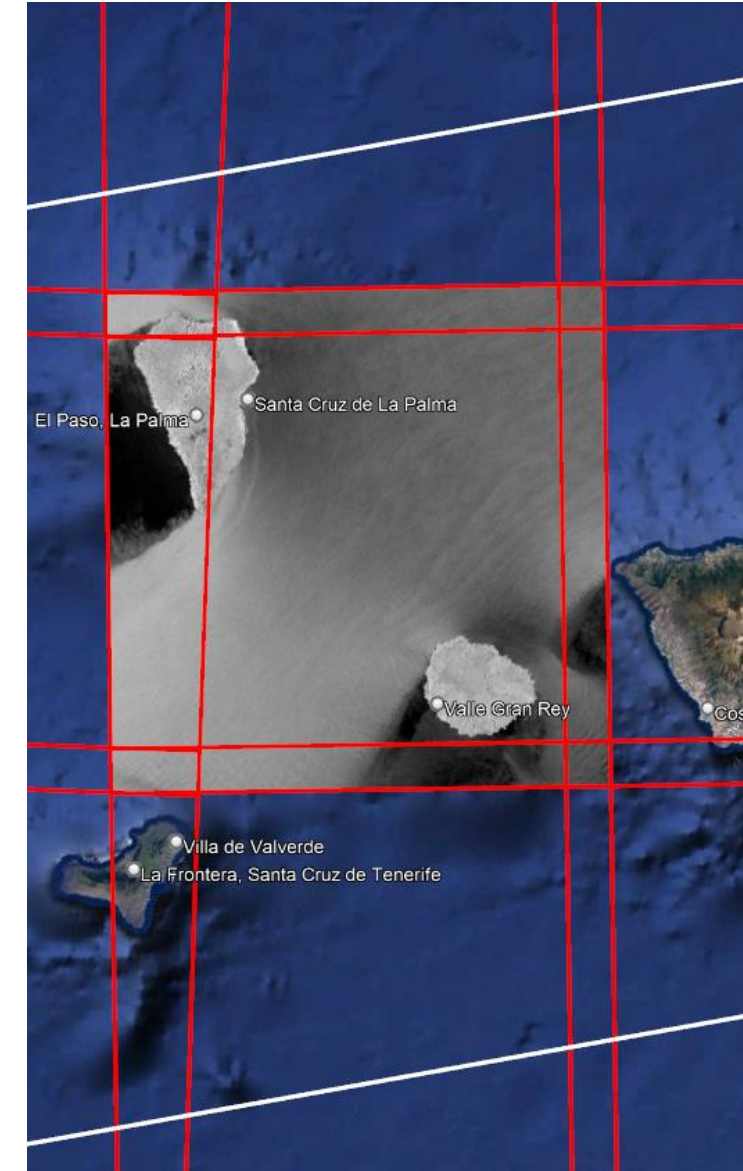
- The IPF processes raw Level-0 data to Level-1 (GRD, SLC) for user uptake
- The Sentinel-1 IPF has undergone several changes since the start of the mission
- Consistent quality of NRB products cannot be assured
- Reprocessing of Sentinel-1 Level-1 products is currently being considered at DLR

version	delivery	start usage	end usage	notes
003.61	2023-03-17 12:00:00	2023-03-30 10:19:46		<a href="#">i</a>
003.52	2022-05-12 00:00:00	2022-05-12 10:48:19	2023-03-30 09:29:57	<a href="#">i</a>
003.51	2022-03-04 00:00:00	2022-03-23 16:25:31	2022-05-12 09:31:31	<a href="#">i</a>
003.40	2021-10-08 00:00:00	2021-11-04 07:56:32	2022-03-23 12:25:17	<a href="#">i</a>
003.31	2020-06-19 12:00:00	2020-06-30 12:00:00	2021-11-03 11:08:26	<a href="#">i</a>
003.30	2020-03-09 12:00:00	2020-06-23 08:00:00	2020-06-30 12:00:00	<a href="#">i</a>
003.20	2019-12-16 12:00:00	2020-01-29 10:00:00	2020-06-23 08:00:00	<a href="#">i</a>
003.10	2019-06-04 15:00:00	2019-06-26 10:00:00	2020-01-29 10:00:00	<a href="#">i</a>
002.91	2018-05-29 00:00:00	2018-06-26 08:30:00	2019-06-26 10:00:00	<a href="#">i</a>
002.90	2018-01-16 00:00:00	2018-03-13 12:00:00	2018-06-26 08:30:00	<a href="#">i</a>
002.84	2017-07-12 00:00:00	2017-08-22 10:00:00	2018-03-13 12:00:00	<a href="#">i</a>
002.82	2017-02-27 00:00:00	2017-03-28 06:00:00	2017-08-22 10:00:00	<a href="#">i</a>
002.72	2016-07-29 00:00:00	2016-08-23 12:00:00	2017-03-28 12:00:00	<a href="#">i</a>
002.71	2016-04-21 00:00:00	2016-05-11 12:00:00	2016-08-23 12:00:00	<a href="#">i</a>
002.70	2016-03-31 00:00:00	2016-04-13 12:00:00	2016-05-11 12:00:00	<a href="#">i</a>
002.60	2015-10-09 00:00:00	2015-11-20 12:00:00	2016-04-13 12:00:00	<a href="#">i</a>
002.50	2015-06-30 00:00:00	2015-07-02 12:00:00	2015-11-24 12:00:00	<a href="#">i</a>
002.40	2015-03-09 00:00:00	2015-03-19 00:00:00	2015-07-02 12:00:00	<a href="#">i</a>

# Extension to Ocean Radar Backscatter



- Development so far focused on NRB for land applications
- The CEOS ARD ORB specification was published in 09/22
- A follow-up activity was started in 04/23 to extend the ESA-DLR product specification to ORB
- Formation of a new working group
- Major points being addressed:
  - Pixel spacing(s)
  - Correction of thermal noise
  - Interfacing with NRB in coastal areas
  - Data quality and overall usability
  - Replaceability of GRD product



# Data Cube capabilities



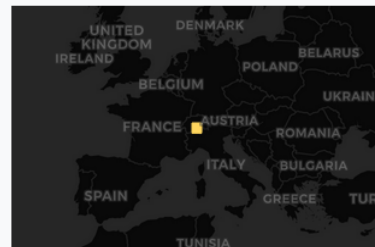
Sentinel-1 NRB STAC Catalog / Sentinel-1 NRB STAC Collection  
/ S1A\_IW\_NRB\_\_1SDV\_20210607T171530\_20210607T171555\_038237\_04832F\_32TMS\_ABCD

## S1A\_IW\_NRB\_\_1SDV\_20210607T171530\_20210607T171

[https://raw.githubusercontent.com/maawoo/copa-nrb-stac/main/32TMS/S1A\\_IW\\_NRB\\_\\_1SDV\\_20210607T171530\\_20210607T171555\\_038237\\_04832F\\_32TMS\\_ABCD](https://raw.githubusercontent.com/maawoo/copa-nrb-stac/main/32TMS/S1A_IW_NRB__1SDV_20210607T171530_20210607T171555_038237_04832F_32TMS_ABCD)

Preview Assets Links

Name	Roles	Content-Type
CARD4L XML Metadata File	metadata, card4l	application/xml
Data Mask Image	data-mask, metadata	image/tiff; application=geotiff; profile=cloud-optimized
Ellipsoid Incidence Angle	ellipsoid-incidence-angle, metadata	image/tiff; application=geotiff; profile=cloud-optimized
Gamma0 RTC to sigma0 RTC ratio	gamma-sigma-ratio, metadata	image/tiff; application=geotiff; profile=cloud-optimized
Local Contributing Area	contributing-area, metadata	image/tiff; application=geotiff; profile=cloud-optimized
Local Incidence Angle	local-incidence-angle, metadata	image/tiff; application=geotiff; profile=cloud-optimized
Noise Power VH	noise-power, metadata	image/tiff; application=geotiff; profile=cloud-optimized
Noise Power VV	noise-power, metadata	image/tiff; application=geotiff; profile=cloud-optimized
VH backscatter data	backscatter, data	image/tiff; application=geotiff; profile=cloud-optimized
VV backscatter data	backscatter, data	image/tiff; application=geotiff; profile=cloud-optimized



### METADATA

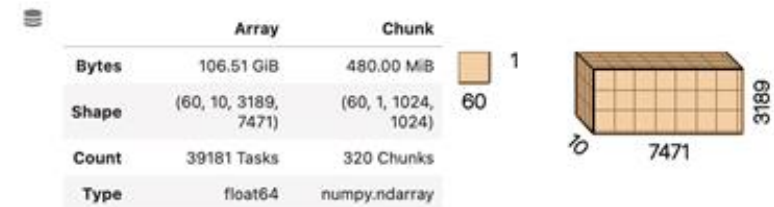
**Keywords** sar, backscatter, esa, copernicus, s1  
**Collection** Sentinel-1 NRB STAC Collection  
**First Acquisition** 7.6.2021, 17:15:30 UTC  
**Last Acquisition** 7.6.2021, 17:15:55 UTC  
**Created** 21.8.2021, 03:11:23 UTC  
**Instruments** c-sar  
**Constellation** sentinel-1  
**Platform** sentinel-1a  
**GSD** 10 m  
**Acquired** 7.6.2021, 17:15:30 UTC

### CARD4L

**Specification** Normalised Radar Backscatter  
**Specification Version** CARD4L-NRB v5.0  
**Measurement Type** gamma-0

```
[4]: nr = ds.where((ds['sat:relative_orbit'] == 44), drop=True).chunk((-1, 1, 1024, 1024))
fr = ds.where((ds['sat:relative_orbit'] == 117), drop=True).chunk((-1, 1, 1024, 1024))
fr
```

```
[4]: xarray.DataArray 'stackstac-31de2c1eacc17eb3540f38b874c70d96'
(time: 60, band: 10, y: 3189, x: 7471)
```



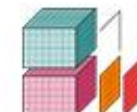
Coordinates: (55)

Attributes:

```
spec: RasterSpec(epsg=32632, bounds=(614990.0, 5618680.0, 689700.0, 5650570.0), resolutions_xy=(10.0, 10.0))
crs: epsg:32632
transform: | 10.00, 0.00, 614990.00|
           | 0.00,-10.00, 5650570.00|
           | 0.00, 0.00, 1.00|
resolution: 10.0
```

```
[6]: eia_min_nr = nr.sel(band='ellipsoid-incidence-angle', time=nr.time[0]).min().values
eia_max_fr = fr.sel(band='ellipsoid-incidence-angle', time=fr.time[0]).max().values
print(f'The Ellipsoid Incidence Angle range is between {eia_min_nr.round(2)}°, f'and {eia_max_fr.round(2)}°')
```

The Ellipsoid Incidence Angle range is between 31.41° and 44.9°



xarray



DASK

# ESA-DLR coordination around 5 axes



## 1. Joint Sentinel-1 ARD NRB product:

- *Objective to have ESA and DLR product definitions aligned.*

## 2. Joint ESA and DLR Sentinel-1 ARD NRB processor:

- *Exchanges of modules and code developed.*
- *Share the new modules developed (e.g. file packaging).*

## 3. Coordination on use cases:

- *Complementary use cases in terms of spatial and temporal coverage, and instruments.*

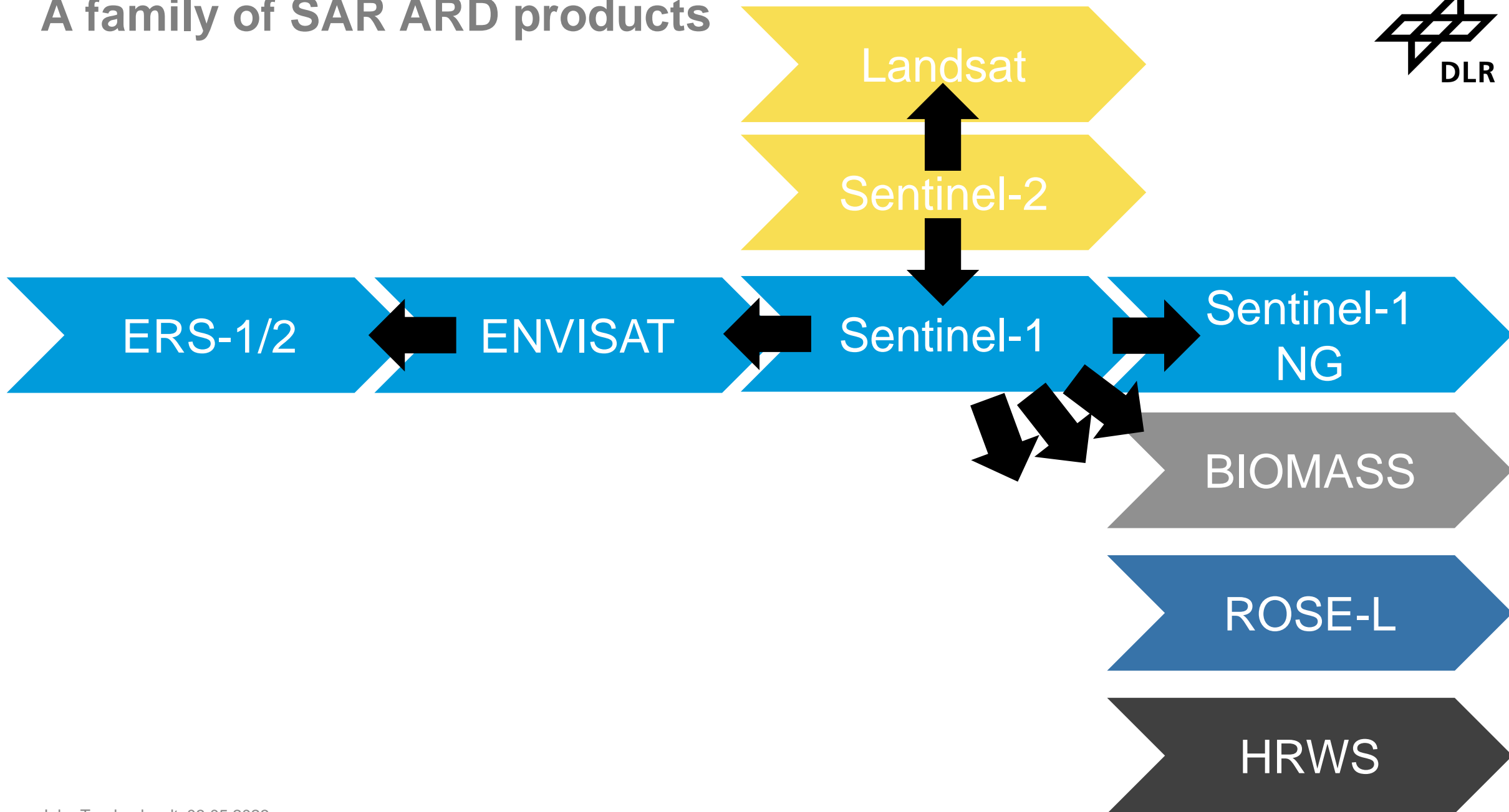
## 4. Coordination on validation:

- *Complementary validations in term of radiometry, geometry, processing modules, etc.*

## 5. Exchange of information related to internal ESA and DLR activities:

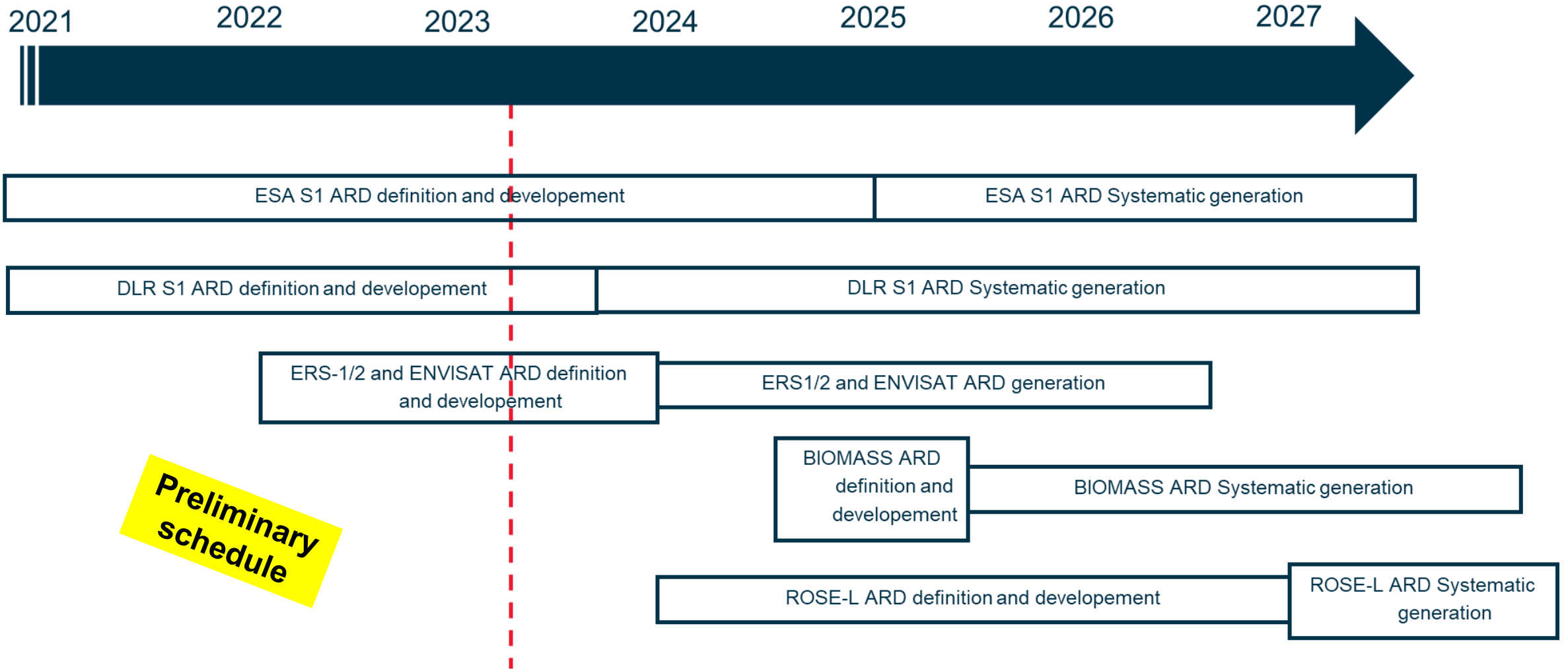
- *Monthly coordination meetings.*

# A family of SAR ARD products





# Time schedule and access for users to ARD NRB

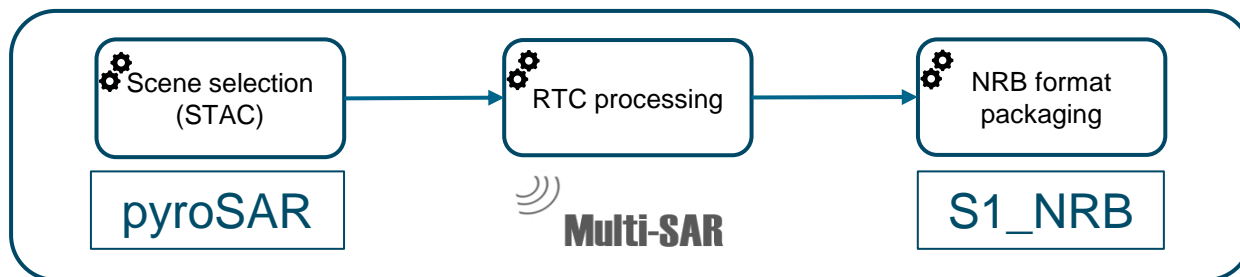


**Preliminary  
schedule**

# NRB Processor



- Open-Source prototype based on Python and ESA SNAP
- Python tools are further developed to increase robustness
- SNAP component is being replaced with DLR in-house Multi-SAR
- Tools have been made compliant with STAC catalogue and HPC Slurm processing environment
- Workflow orchestration is currently being set up



### S1\_NRB

A prototype processor for the Sentinel-1 Normalised Radar Backscatter product

Please refer to the [Documentation](#) for more details about installation and usage instructions, general processor information and the API reference.

Further information about the S1-NRB product can also be found [here](#).

### pyroSAR

A Python Framework for Large-Scale SAR Satellite Data Processing

build passing build passing coverage 50% docs passing pypi package 0.19.0 conda-forge v0.19.0

The pyroSAR package aims at providing a complete solution for the scalable organization and processing of SAR satellite data:

- Reading of data from various past and present satellite missions
- Handling of acquisition metadata
- User-friendly access to processing utilities in [SNAP](#) and [GAMMA Remote Sensing](#) software
- Formatting of the preprocessed data for further analysis
- Export to Data Cube solutions

Head on over to [readthedocs](#) for installation instructions, examples and API reference.

<https://github.com/johntruckenbrodt/pyroSAR>  
[https://github.com/SAR-ARD/S1\\_NRB](https://github.com/SAR-ARD/S1_NRB)

# DLR: terrabyte platform



## External data sources



## terrabyte @ LRZ



Processing  
to ARD

## DLR EO long-term



100 PB archive storage



≈40 PB net storage  
320 Nodes (273 CPU + 47 GPU)  
by end of 2023



Leibniz Supercomputing Centre  
of the Bavarian Academy of Sciences and Humanities

# International activities for EO platforms



- **CEOS:**

- WGISS
- LSI-VCARD



- **ESA**

- WG Data Access & Preservation
- WG Common Architecture



- **OGC**

- EO Exploitation Platform DWG
- GeoDataCube SWG
- Analysis Ready Data SWG



- **Space agency collaborations**

- **USGS-DLR:** Clouds, Data Access
- **CNES-DLR:** FaaS, Zeebe, STAC



- **CCSDS:** Cloud Standardization Group



An aerial grayscale topographic map of a mountainous region, showing intricate terrain features, ridges, and valleys. The text "Thank You!" is centered over the map.

Thank You!