Status of the underground gravitational wave detector KAGRA

Takafumi Ushiba on behalf of the KAGRA Collaboration Institute for Cosmic Ray Research, UTokyo, Japan

The XVIII International Conference on Topics in Astoparticle and Underground Physics (TAUP2023), Aug. 30, 2023





Gravitational waves as a probe of the universe

New eyes to observe the Universe

K. Kokeyama JGW-G1808116

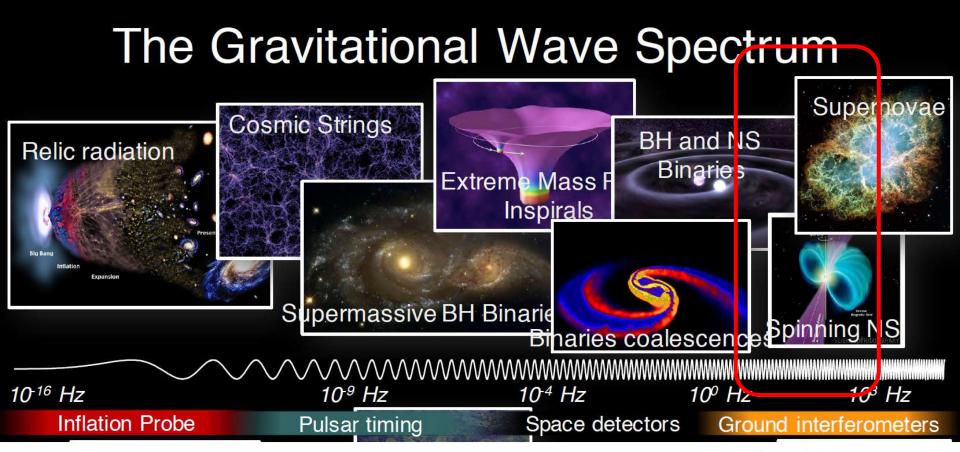
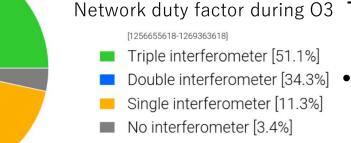


Figure: M Evans

Global network and multi-messenger astronomy



- 90 confident events in O1-O3.
- One successful follow-up observation: GW170817
- GW, short GRB, and afterglow
- Counterpart was identified.
- Standard siren etc.
- Multiple-detector observation is essential for:
- better localization
- better duty cycle



 Increase of the number of detectors are important.

KAGRA



KAGRA entrance



KAGRA entrance in winter season



KAGRA site around BS

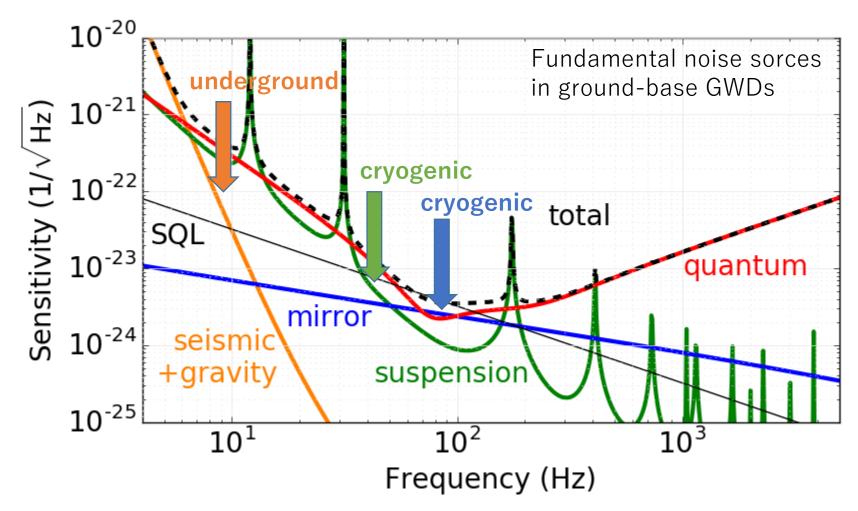
Kamioka

Tokyo

1000km



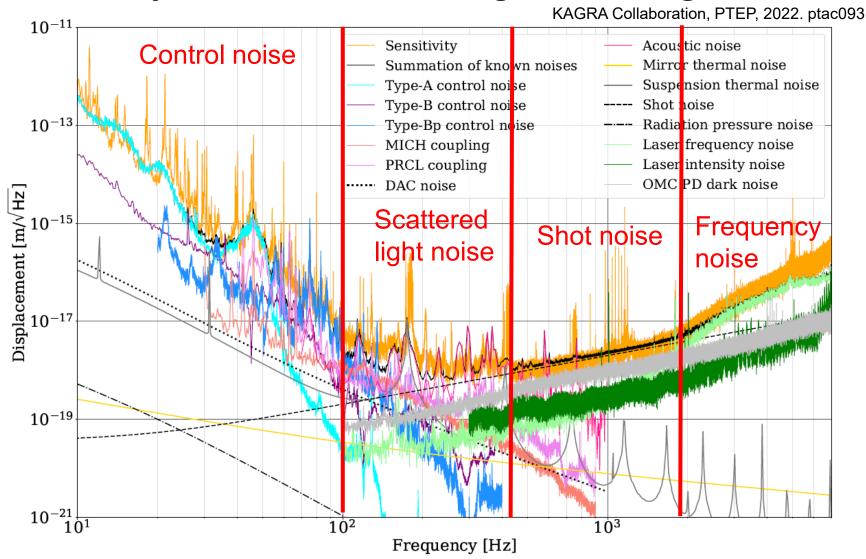
Why underground and cryogenics?



Underground: reduce seismic noise and gravity gradient noise Cryogenic: reduce suspension and mirror thermal noise

→ Design sensitivity is limited by quantum noise at almost all observation band

Sensitivity and noise budget during O3GK



Our 3 years after O3GK (2020 Oct. -)

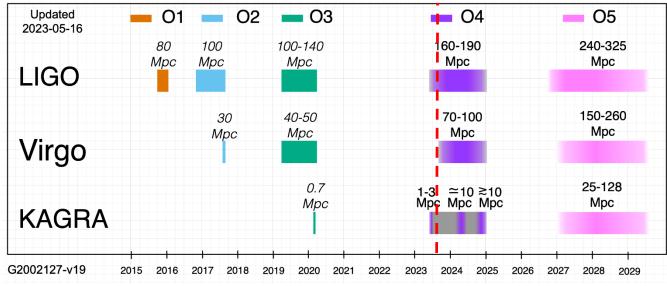
ETMY

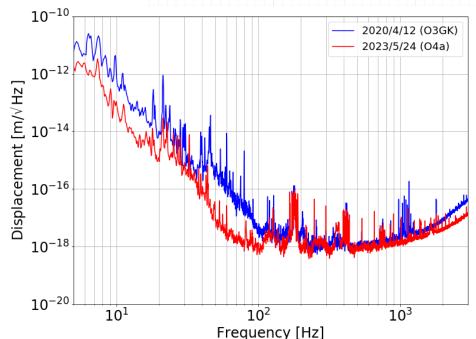
Works in EY

New laser installation forming laser power-2022/10-12 2023/1-3 2020/10-12 2021/1-3 2021/4-6 2023/4-6 2020 (~ 3 months) **New Laser PRFPMI** 2023/1 DC read out 2021/5 2022/7 2022/11 IFO commissioning **ASC** 2022/1 2022/6 2023/4 DC read out 2022/8 IFO commissioning 2021/4 2021/12 IX/EX in air commissioning including lock acquisition Vacuum situations health check Type-B/Br ~9 months area in Vacuum Upgrade of mirror suspensions Type-B/Bp Mirror for control noise reeduction (~20 months) Works in the center Mid-size baffle Baffle installation Payload Works in IX for stray light reduction $(\sim 5 \text{ months})$ Cooling test Repair Payload Works in IY Repair Payload Works in EX Repair Payload

T. Uchiyama

Joint observing Run

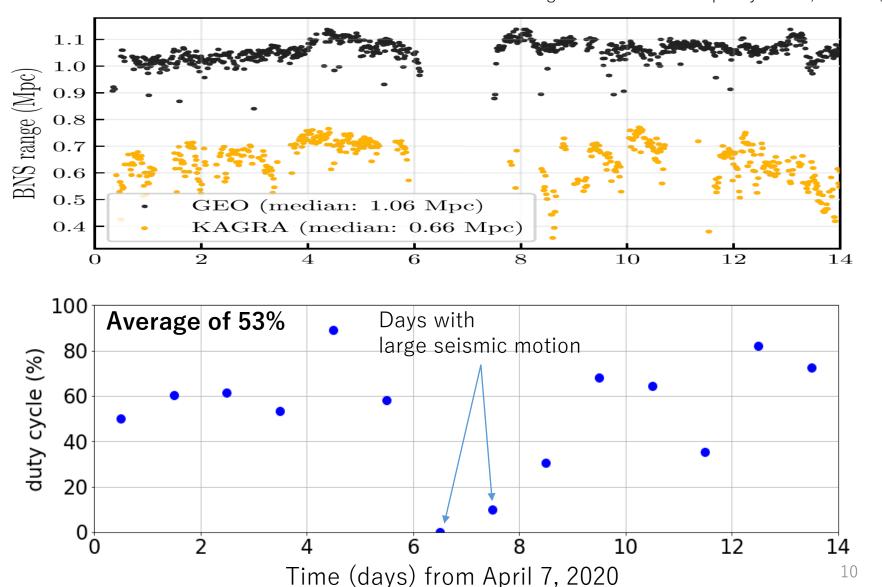




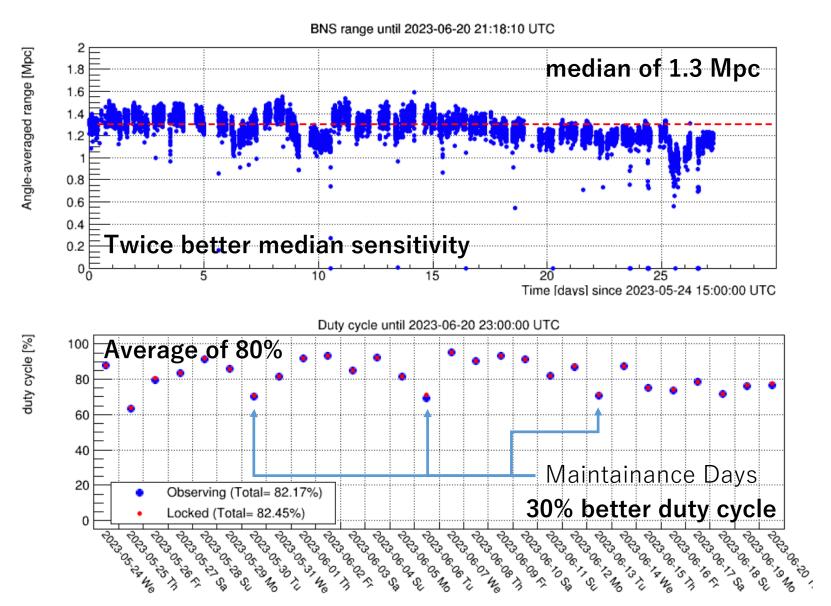
- O4 started from May 24.
- KAGRA joined from May 24 to June 21 with better sensitivity than O3GK.
- KAGRA has commissioning break for improving the sensitivity and will be back to the observing run in next spring.

Go back to previous observing run (O3GK)

Progress of Theor. and Exp. Phys. 2022, 063F01 (2022)



Sensitivity and duty cycle during O4a



Hightlight of commissioning

Better stability

Local damping improvement

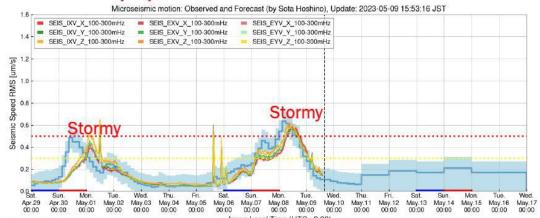
Now PRFPMI can be maintained even in somewhat stormy days.

Alignment-sensing and control (ASC)

- Took time for wave-front sensing (WFS) in a strategic way; now WFS can be implemented for some global DoFs; drastically improved the contrast fluctuation.
- In addition, some noise structures and noise floor got better in the sensitivity curve.

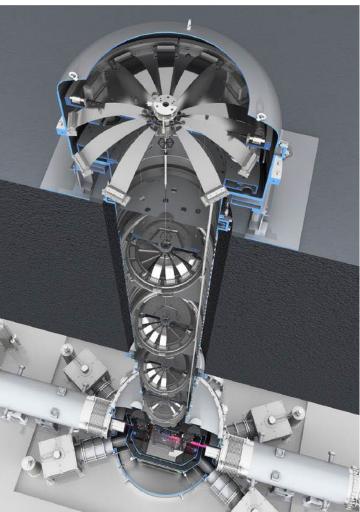
Doppler phase noise cancellation

 For auxiliary green laser paths; now stable lock acquisition is possible even in somewhat stormy days.



GWADW (May 22-26, 2023, Isola d'Elba, Italy)

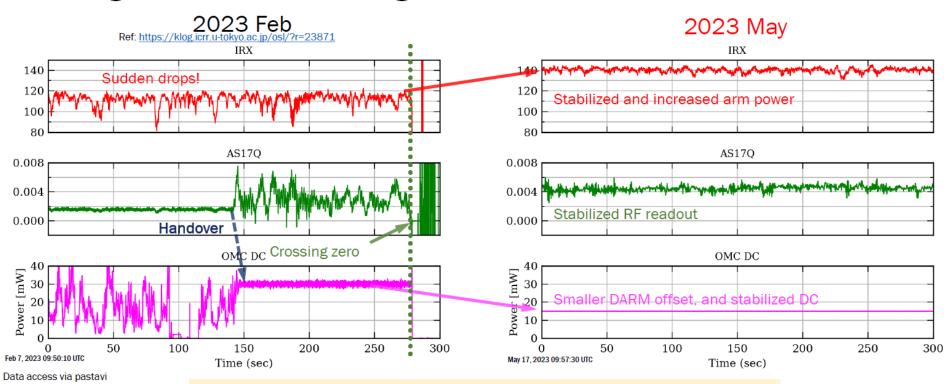




Hightlight of commissioning

T. Akutsu JGW-G2314966

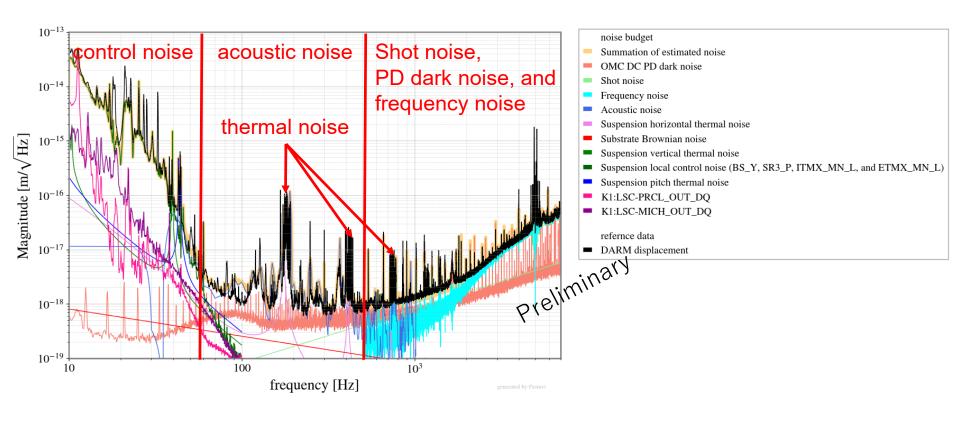
Alignment sensing and control



- · Internal laser power is drastically stabilized; and increased.
- Better AS contrast allows to do handover with smaller DARM offset.
- → Now ready to increase the input power from 1 W for O4b!

GWADW (May 22-26, 2023, Isola d'Elba, Italy)

Noise budget of O4a sensitivity



- We have made noise budget of O4a sensitivity.
- It takes two months to make the noise budget, which is much faster than that during O3GK.
- We are now starting noise hunting to obtain better sensitivity.

Summary

- KAGRA has many hardware upgrade after O3GK.
- O4 observing run has started since 24 of May.
- KAGRA joined O4 observing run from 24 of May to 21 of June with better sensitivity than that in O3GK.
- KAGRA made noise budget of O4a sensitivity and understand the current limitation, which promotes noise hunting.
- KAGRA will come back observing run in the next spring with better sensitivity.