

# Magnetic and electric fields

How to define basic fields and adjust transport settings

Advanced course – ANL, June 2023

### Outline

- Introduction
- Electric and magnetic fields
  - Required cards (+ examples)
  - Plotting fields using Flair
  - User routines
- Particle transport settings in fields
  - Required cards (+ examples)



### Introduction

- Magnetic and/or electric fields are crucial for many simulation problems
  - Accelerator magnets, transfer line magnets, solenoids, spectrometers, magnetic horns, ...



- FLUKA supports the transport of charged particles in *arbitrary* static B and E fields (the latter since FLUKA 4-0.0)
  - This lecture gives a basic introduction how to define fields and presents the relevant transport parameters



## **Electric and magnetic fields**

Required cards: **ELCFIELD**, **MGNFIELD**, **MGNCREAT**e, **MGNDATA** (+ examples)

Plotting fields using Flair

User routines elefld.f and magfld.f



# **Magnetic and electric fields in FLUKA**

- Fields are activated on a per-region basis
  - Magnetic fields can be defined in any region (filled with any material)
  - Electric fields can presently be defined only in vacuum regions
  - A region can contain **only one type of field** (magnetic **or** electric)
- How to define magnetic or electric fields
  - Common (e.g. dipole up to decapole) fields can directly be defined in the input file using the ELCFIELD, MGNFIELD and MGNCREATE cards defining the type of field as well as field strength, region association, symmetry, ...
  - Interpolated fields (2D, cylindrical, 3D) require additional MGNDATA cards
  - Arbitrarily complex fields can be implemented using user routines elefld.f and magfld.f







## **Magnetic and electric fields in FLUKA**





### Magnetic and electric fields in FLUKA

🖨 ASSIGNMA

Mat: IRON ▼ Mat(Decay): ▼ Reg: MAGNET V Step: to Reg: ▼ Field: Magnetic ▼

- Fields are activated on a per-region basis with the **ASSIGNMAt** card
- Strongly recommended to define as such only regions where a magnetic field actually exists, due to the less efficient and less accurate tracking algorithm used in magnetic fields
- Activates an electric or magnetic field if defined using ELCFIELD or MGNFIELD with additionally MGNCREATe/MGNDATA or using a routine (elefld.f/magfld.f)
- Selecting "Electric" or "Magnetic" in Flair activates a field both for prompt and decay radiation, one can however also selectively switch on a field for either of the two (prompt or decay) \*
- Go to "Add > Transport" to add these cards to the input in Flair.

\* The option to activate both types of fields in the same region is shown in Flair but is presently not implemented in FLUKA.)



SDUM = blank

U MGNFIELD	Max Ang (deg):	Bound Acc. (cm):	Min step (cm):
	Bx:	By:	Bz:

- The MGNFIELD card defines a constant magnetic field, where WHAT(4-6) are the Bx, By, Bz components of the magnetic field in the Cartesian coordinate axes.
- Units: Tesla
- In case no values are specified or all components are set to zero (= default setting!) a user-defined subroutine magfld.f is expected to deliver the values (see below).
- The defined magnetic field is applied to **all** regions set as magnetic using the **ASSIGNMAt** card, it is therefore strongly recommended to restrict this to regions where a field effectively exists



SDUM = blank



- The ELCFIELD card defines a constant electric field with WHAT(4-6) the Ex, Ey, Ez components of the electric field in the Cartesian coordinate axes.
- Units: kV/cm
- In case no values are specified or all components are set to zero (= default setting!) a user-defined subroutine elefld.f is expected to deliver the values (see below).
- **f(dp/dx)** is a factor to extend the upper dp/dx tabulation for charged particles (≥1)
- The defined electric field is applied in **all** regions set as electric using the **ASSIGNMAt** card, it is therefore strongly recommended to restrict this to regions where a field effectively exists



SDUM = blank

 Image: Model in the second strength:
 Reg: MAGNET T
 Reg: MAGNET T
 On: Region T

 Reg: MAGNET T
 to Reg: MAGNET T
 Step:

- The MGNFIELD card associates a common field, defined by an MGNCREATE card (here named "FIELD"), to a specific region.
- Still required to explicitly flag the region as magnetic using an **ASSIGNMAt** card, it is not done automatically.
- The magnetic field strength given in WHAT(2) is expressed according to the common field type defined in the associated MGNCREATE card:

**Dipole:** intensity in T

Quadrupole: intensity in T/cm

Sextupole: expansion coefficient in T/cm<sup>2</sup>

Octupole: expansion coefficient in T/cm<sup>3</sup> Decapole: expansion coefficient in T/cm<sup>4</sup> Any other (including constant): a multiplicative factor



- In combination with the **MGNFIELD** card, the **MGNCREATe** card defines
  - Any common field **type**, which can be
    - analytical: constant, dipole, quadrupole, ...
      interpolated: in 2D or 3D field
  - the radius of the core region where an analytical field is defined
  - grid parameters for the interpolated field (in combination with MGNDATA)
  - mirror symmetries if applicable
- Functionality that was formerly only available through user-defined subroutine magfld.f



or a **combination** of both



core radius

type = const

type: CONST V			$B_x = K \cdot u$
 U:	V:	W:	$B_y = K \cdot v$
			$B_z = K \cdot w,$

 The MGNCREATE card for type CONST allows to define the X, Y and Z components of a constant magnetic field (first continuation card), with the strength K defined in the associated MGNFIELD card.



#### type = DIPOLE, ..., DECAPOLE



- The MGNCREATE card for types **DIPOLE**, ... up to **DECAPOLE** define along with the associated MGNFIELD card any common analytical field along with parameters:
  - R: radius (in cm) of the "core" analytical field
  - Sym: mirror symmetries in the magnetic field frame to be applied along each axis, encoded as Sx + Sy\*10 + Sz\*100, with Si one of Sx, Sy, Sz.
  - X0, Y0 : Additional offset along the X and Y axes of the magnet frame for the analytical core region
  - Azm: Azimuthal angle around Z
  - Rbend: the magnet bending radius



type = 2D, RZ, 3D

MGNCREATE	type: 3D 🔻	Sym:
Nx:	Xmin:	Xmax:
Ny:	Ymin:	Ymax:
Nz:	Zmin:	Zmax:

$$egin{aligned} B_x &= K \cdot B_{(i,x)} \ B_y &= K \cdot B_{(i,y)} \ B_z &= K \cdot B_{(i,z)}, \end{aligned}$$



- The MGNCREATE card for types 2D, RZ, 3D, allow to define interpolated fields in combination with MGNDATA cards.
- Toroidal RZ field is a particular kind of 2D field (field coordinates in the XY grid extruded in Z)

• 
$$N_x \rightarrow N_r$$
,  $X_{min} \rightarrow R_{min}$ ,  $X_{max} \rightarrow R_{max}$ 

• 
$$N_y \rightarrow N_z$$
,  $Y_{min} \rightarrow Z_{min}$ ,  $Y_{max} \rightarrow Z_{max}$ 

#### type = 2D/3D + DIPOLE, ..., DECAPOLE



Radius R defines the radius of the analytical core region

X [cm]

### type = 2D/3D + DIPOLE, ..., DECAPOLE

U MGNCREATE FIELD	type: 2D	+DIPOLE ▼ Sym:
R: 5	Xo:	Yo:
Nx: 10	Xmin:	Xmax:
Ny: 10	Ymin:	Ymax:
U MGNFIELD FIELD V S	trength: 2	Rotdefi: 🔻
	Reg: 🔻	to Reg: @LASTREG 🔻
🖉 Mgndata 🕅 Field 🔻	Bx:	By: <b>1</b>
🖉 MGNDATA FIELD 🔻	Bx:	By: <b>1</b>
🖉 Mgndata 🛛 Field 🔻	Bx:	By: <b>1</b>

$$B_x = K \cdot B_{(i,x)}$$
$$B_y = K \cdot B_{(i,y)}$$
$$B_z = K \cdot B_{(i,z)},$$



- Example: combination of MGNCREATE + MGNFIELD + MGNDATA cards to create combination of analytical + interpolated field called "FIELD"
  - Field strength: 2 T
  - Core analytical radius: 5 cm



### type = 2D/3D + DIPOLE, ..., DECAPOLE

🔰 MGNCREATI	FIELD type:	2D+DIPOLE V S	ym:	Azm:
R: 5	Xo:		Yo:	Rbend:
Nx: 10	Xmin:	Xm	nax:	
Ny: 10	Ymin:	Ym	nax:	
U MGNFIELD	FIELD   Strength:	2 Roto	lefi: 🔻	On: Region 🔻
	Reg:	▼ to F	leg: @LASTREG 🔻	Step:
🧼 MGNDATA 🛛	FIELD V BX:		By: 1	Bz:
🧼 MGNDATA 🛛	FIELD V BX:		By: 1	Bz:
🖉 MGNDATA 🛛	FIELD ▼ Bx:		By: 1	Bz:



• MGNDATA cards allow the user to input the values of the field in the interpolation grid described via the MGNCREATe card. One such card should be provided per grid point in the order as shown below, to describe more complex fields:



## **Plotting the field in Flair**





Step 4: select Field (or Field Vector,

### **User routines**

- In the case where the standard FLUKA magnetic/electric field implementations are insufficient, dedicated routines can be used to simulate more complex problems
- Such fields can be described in the user subroutines src/user/magfld.f and src/user/elefld.f
- In these routines, the field components and field strength can be defined as a function of the coordinates. They are only called in regions declared as magnetic/electric via the relevant ASSIGNMA card.

```
SUBROUTINE MAGFLD ( X, Y, Z, BTX, BTY, BTZ, B, NREG, IDISC )
Input variables:
    x,y,z = current position
    nreg = current region
Output variables:
    btx,bty,btz = cosines of the magn. field vector
    B = magnetic field intensity (Tesla)
    idisc = set to 1 if the particle has to be discarded
```





### **Particle transport settings in fields**

FLUKA implementation of tracking in fields

Required cards: **ELCFIELD**, **MGNFIELD**, **STEPSIZE** (+ examples)



# **Remarks concerning the tracking in fields**

- When tracking in magnetic fields, FLUKA accounts for:
  - The precession of the MCS (Multiple Coulomb Scattering) final direction around the particle direction: this is critical in order to preserve the various correlations embedded in the FLUKA MCS algorithm
  - The decrease of the particle momentum due to energy losses along a given step and hence the corresponding decrease of its curvature radius.
  - The **precession of a (possible) particle polarization** around its direction of motion: this matters only when polarization of charged particles is an issue (mostly for muons in Fluka)

- When tracking in electric fields inside vacuum, FLUKA accounts for:
  - The change of the projectile energy due to the electric field itself



# **Transport settings**

- The true trajectory of a charged particle inside a field (black) is approximated by linear steps (red)
  - The end point will always be on the true path, but generally not exactly on the region boundary
  - An iteration is performed until a certain boundary crossing accuracy is achieved
- The tracking accuracy can be tuned by the user:
  - The maximum angle (α in deg) subtended by a single step from the centre of the curved path.
  - The maximum permissible error ( $\epsilon$  in cm) in geometry intersections.
- Note:
  - Both conditions ( $\alpha$  and  $\epsilon$ ) are fulfilled during tracking
  - If  $\alpha$  and/or  $\epsilon$  are too large, then geometry boundaries can be missed
  - If they are too small, then the CPU time can increase a lot





# **Global transport settings for B (and E) fields**

• The transport parameters can be globally set on the MGNFIELD (and ELCFIELD) cards









Rule of thumb:  $\epsilon$  shall be *smaller than the region dimensions* (be careful in presence of small structures), but watch out for excessive CPU times



# Global transport settings for B (and E) fields (cont.)

Avoiding too small steps (endless tracking)





# **Region-by-region transport settings for B/E fields**

- The global transport parameters can be overwritten for (selected) regions using the STEPSIZE card
- Region-by-region tuning can save CPU time





# Summary

- EM fields of arbitrary complexity can be included in FLUKA simulations
  - Region-activated using **ASSIGNMAt** card
  - Using a combination of MGNFIELD and/or MGNCREATe and or MGNDATA cards
  - Using dedicated user subroutines magfld.f, elefld.f when standard FLUKA implementation does not suffice
  - In all materials for magnetic fields, in vacuum only for electric fields (!)
  - Only one type of field per region
- Fields can be plotted using Flair for visual inspection
- Tracking settings are a trade-off between accuracy and CPU time
  - Global setting: MGNFIELD, ELCFIELD
  - Locally: **STEPSIZE**



