

Simulation-based inference and the places it takes us

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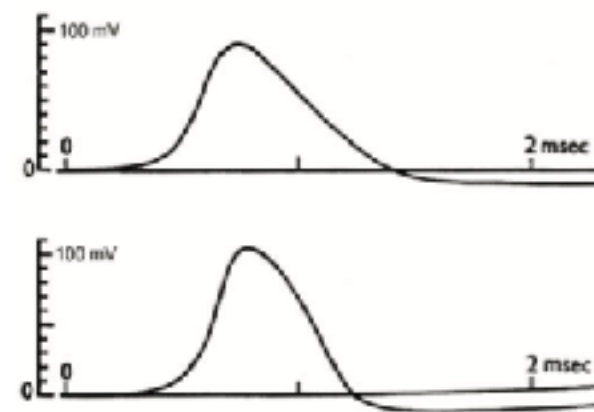
UNIVERSITÄT
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MAX PLANCK INSTITUTE
FOR INTELLIGENT SYSTEMS

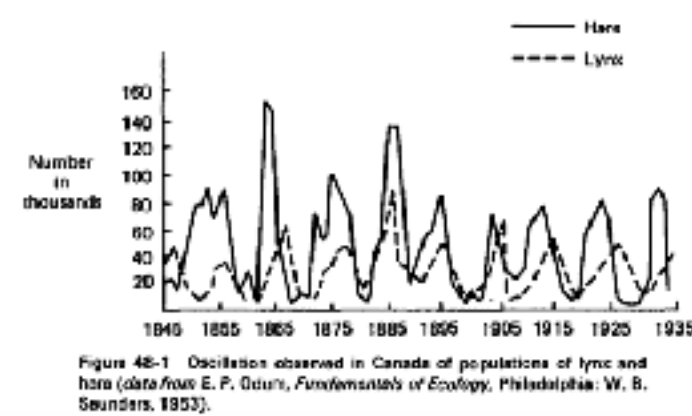


Neurophysiology



fig; Schwiening 2003

Population Dynamics



fig; Saunders 1953

Psychophysics of Decision Making

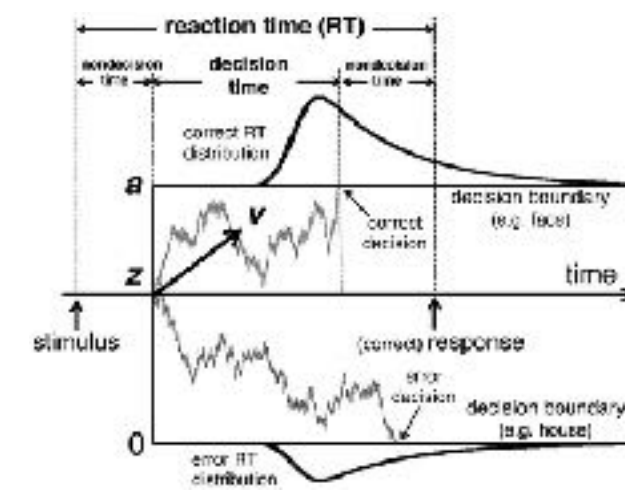


fig: Murata 2014

Particle Physics

$$\mathcal{L}_{SM} = \underbrace{\frac{1}{4}W_{\mu\nu} \cdot W^{\mu\nu} - \frac{1}{4}B_{\mu\nu}B^{\mu\nu} - \frac{1}{4}G_{\mu\nu}^a G^{\mu\nu a}}_{\text{kinetic energies and self-interactions of the gauge bosons}} + \underbrace{L\gamma^\mu(i\partial_\mu - \frac{1}{2}g_T \cdot W_\mu - \frac{1}{2}g'YB_\mu)L + R\gamma^\mu(i\partial_\mu - \frac{1}{2}g'YB_\mu)R}_{\text{kinetic energies and electroweak interactions of fermions}} + \underbrace{\frac{1}{2}[(i\partial_\mu - \frac{1}{2}g_T \cdot W_\mu - \frac{1}{2}g'YB_\mu)\phi]^2 - V(\phi)}_{W^\pm, Z, \gamma \text{ and Higgs masses and couplings}} + \underbrace{g^i(\bar{q}\gamma^\mu T_a q)G_a^\mu}_{\text{interactions between quarks and gluons}} + \underbrace{(G_1 L\phi R + G_2 L\phi_\nu R + h.c.)}_{\text{interactions between neutrinos and couplings to Higgs}}$$

fig: Cranmer 2017

Systems Biology

$$\dot{S} = \alpha - \gamma SI - dS, \quad (3.10a)$$

$$\dot{I} = \gamma SI - \nu I - dI, \quad (3.10b)$$

$$\dot{R} = \nu I - dR, \quad (3.10c)$$

fig; Toni 2018

Cosmology

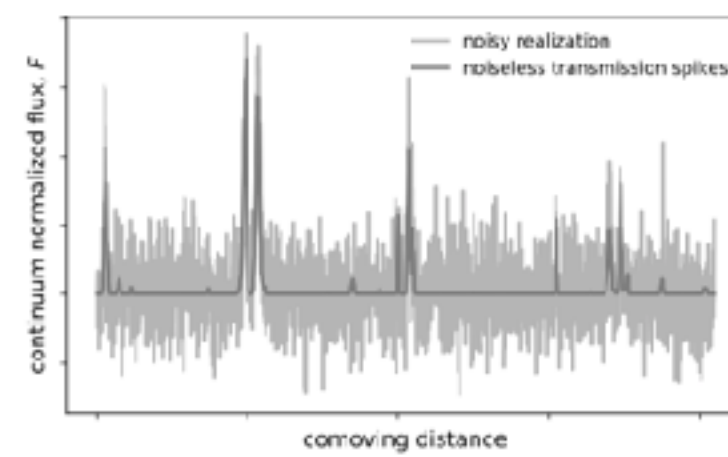


fig: Walting 2018

Molecular Dynamics

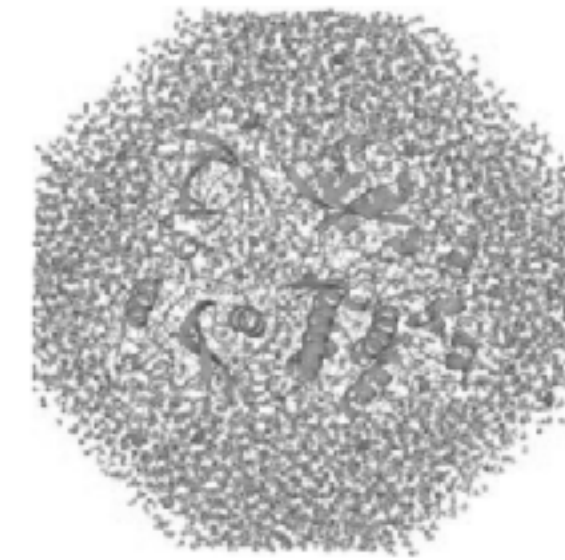
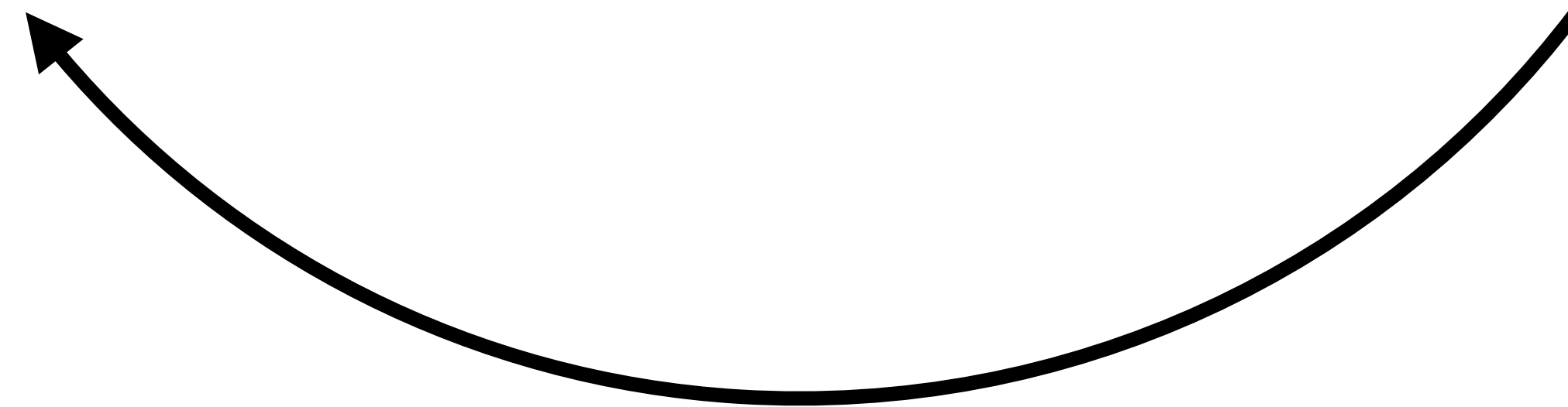
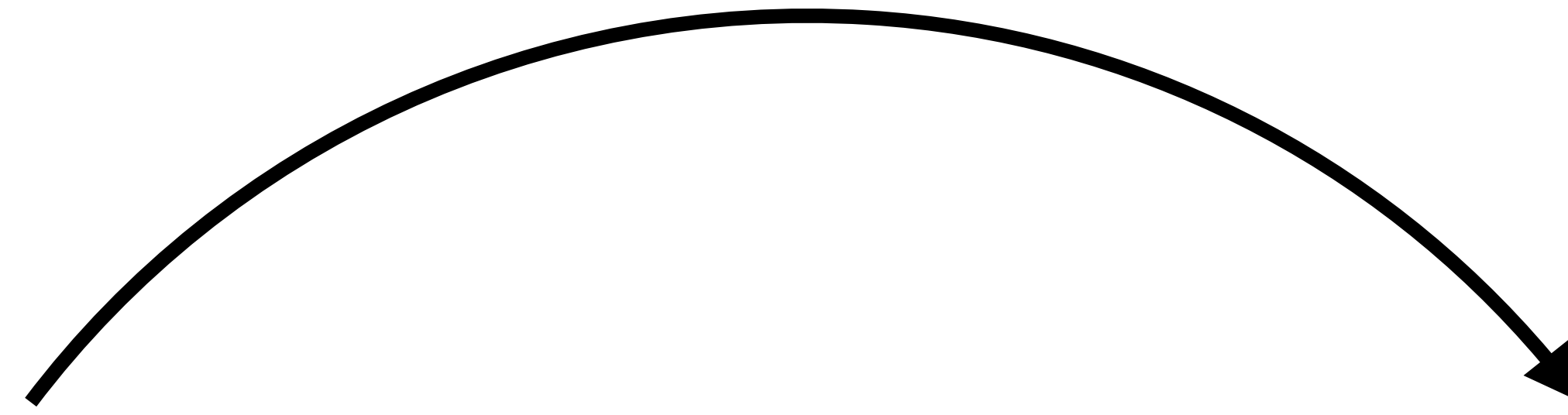


fig: Karplus 2005

...

Mechanistic simulations

Machine Learning

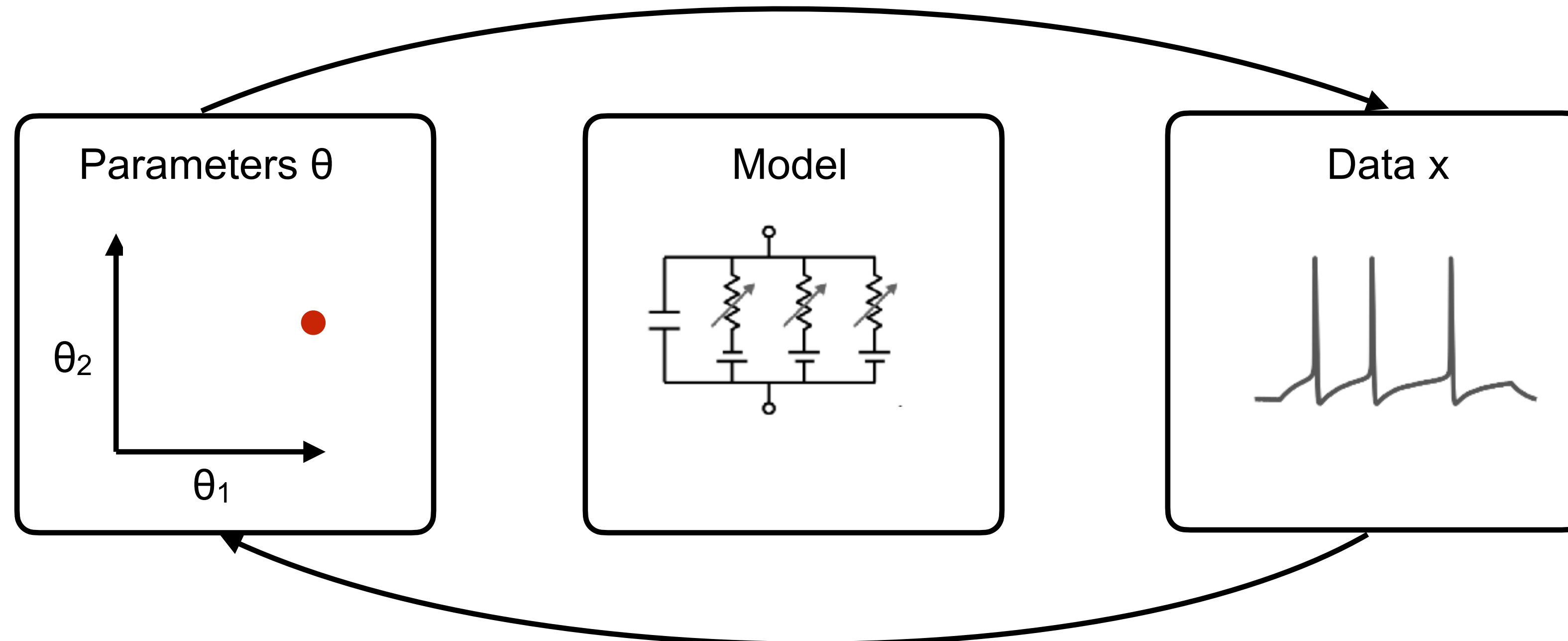


How can we combine these two approaches to build tools for data-driven scientific discovery?

Focus: Neuroscience

How can we find mechanistic/physical models which are compatible with observed data (and prior knowledge)?

Forward simulation

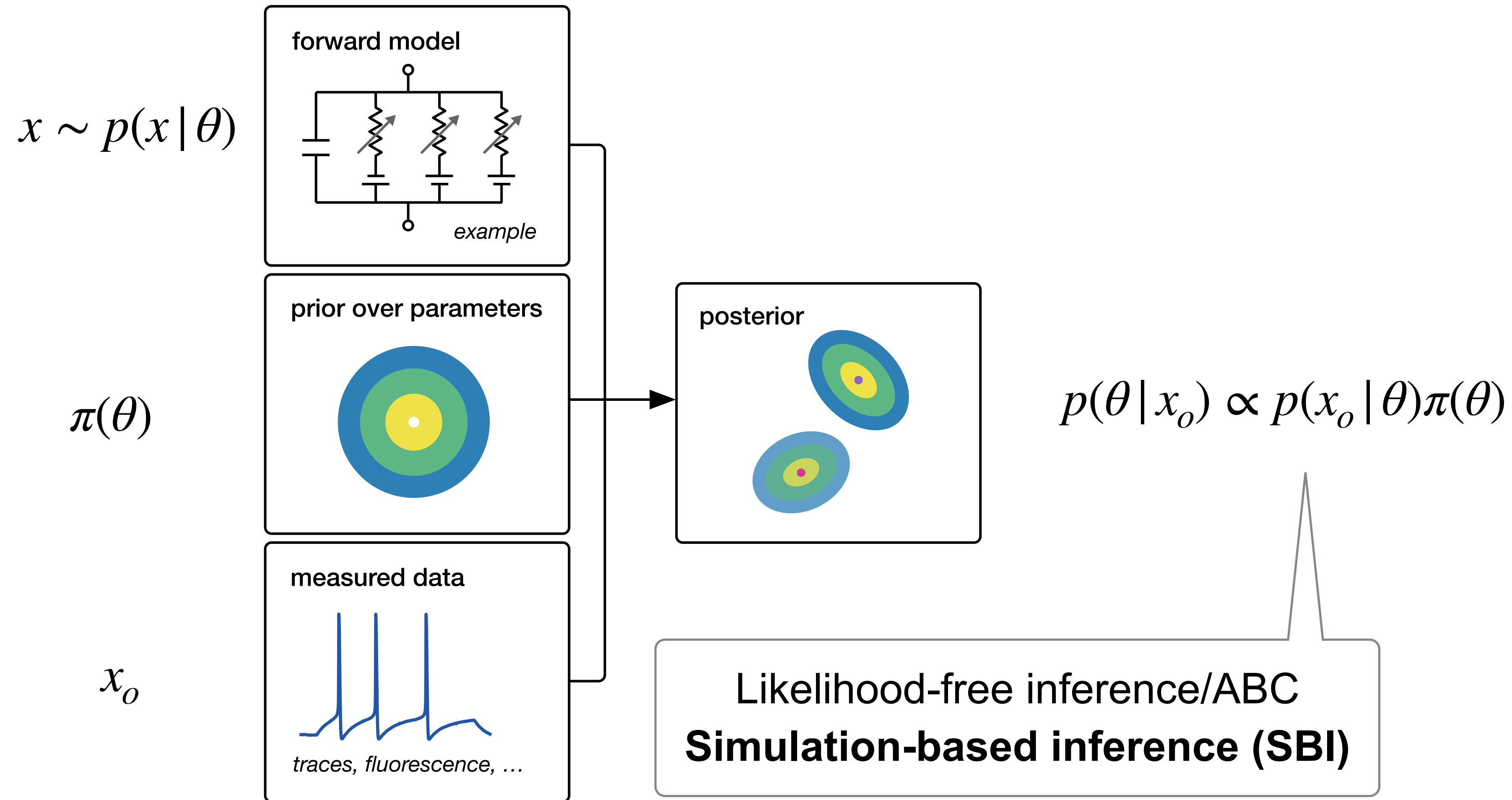


Inference

Challenges:

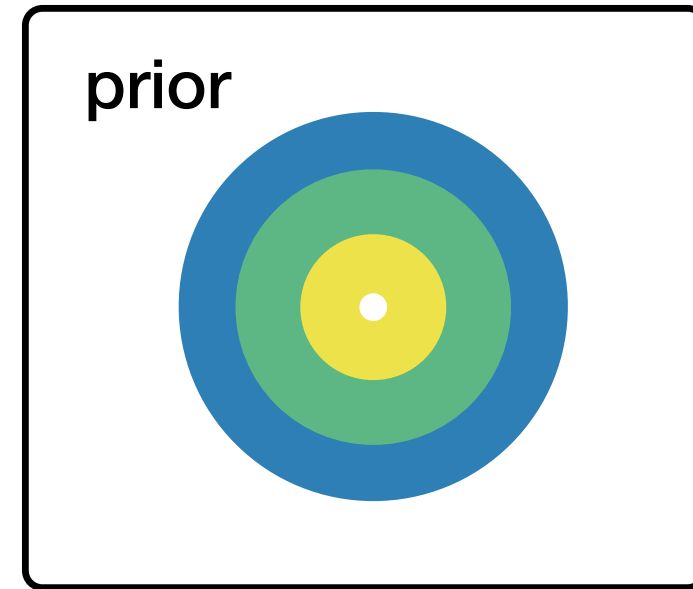
- 1) Forward model often given by simulator
(might be complicated, black-box, non-diffable)
- 2) Inference problems vastly under-constrained

How can we do Bayesian inference for *any* mechanistic model (including ones specified as simulators)?

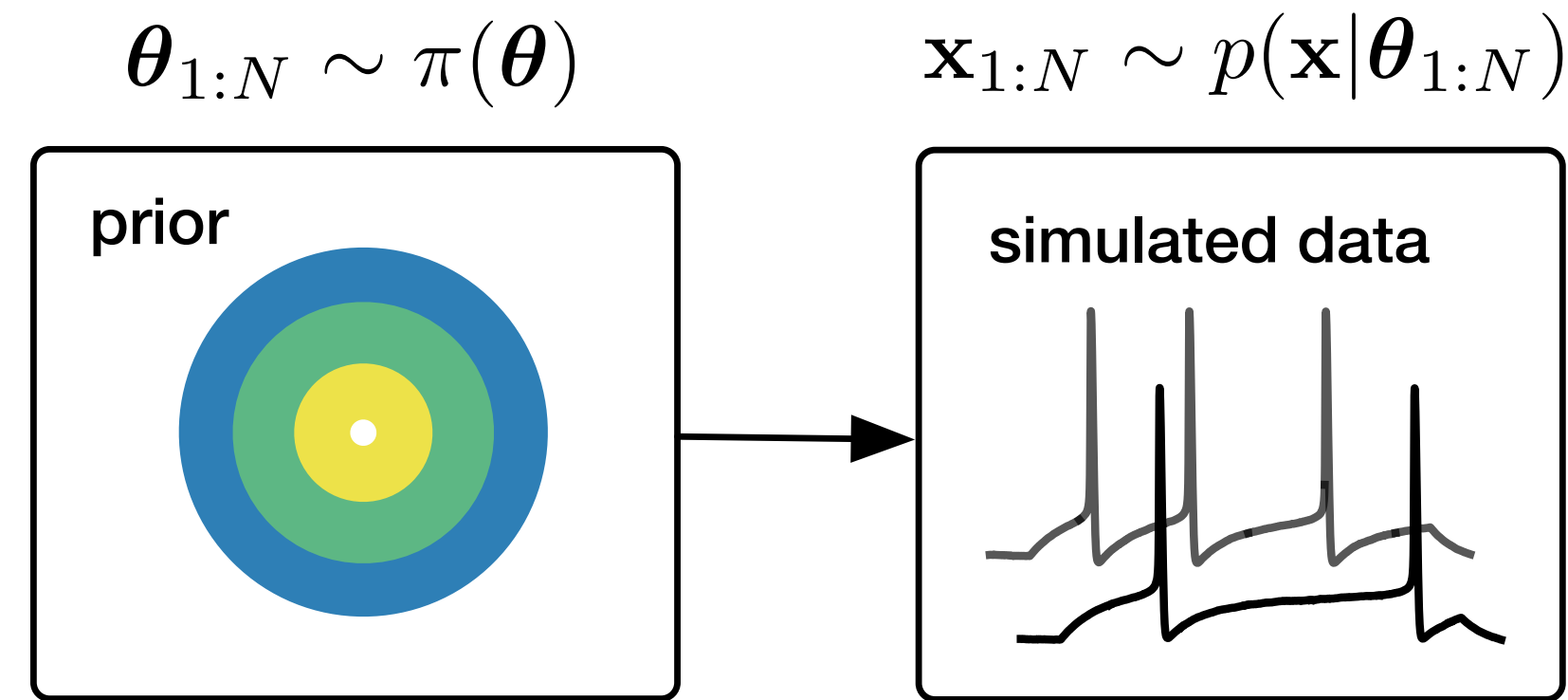


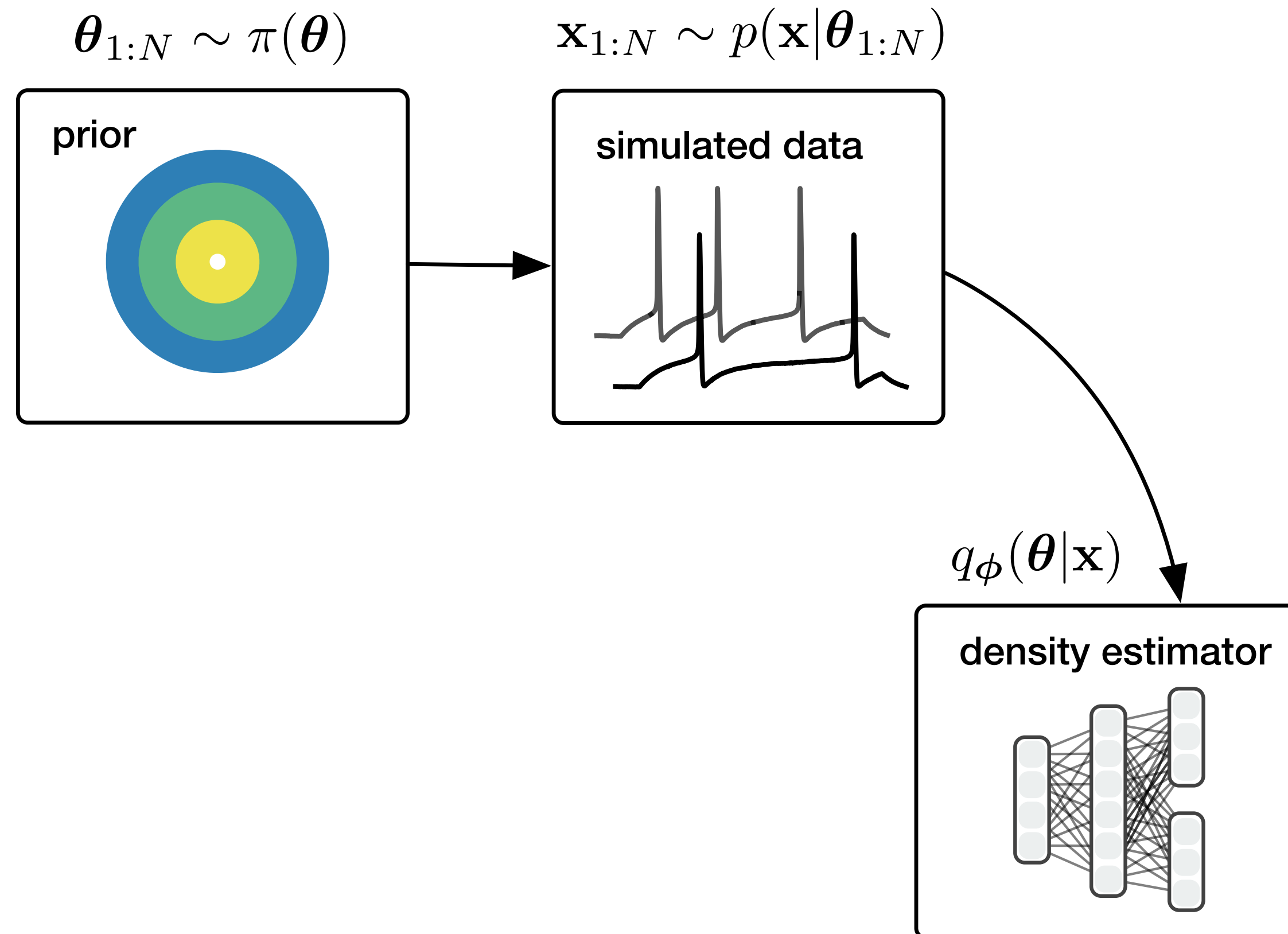
1. Sample parameters from prior

$$\theta_{1:N} \sim \pi(\theta)$$

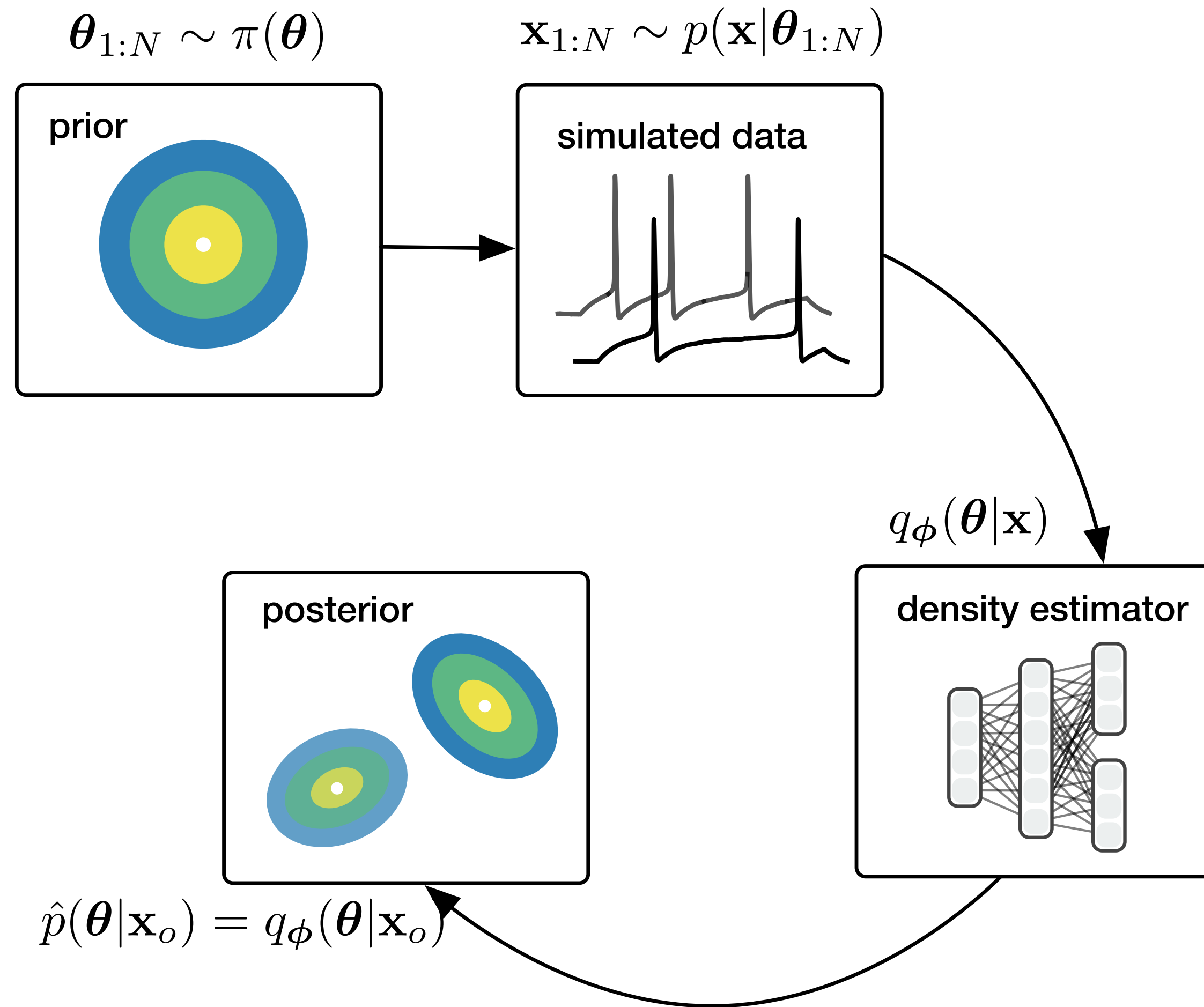


2. Simulate data from parameters

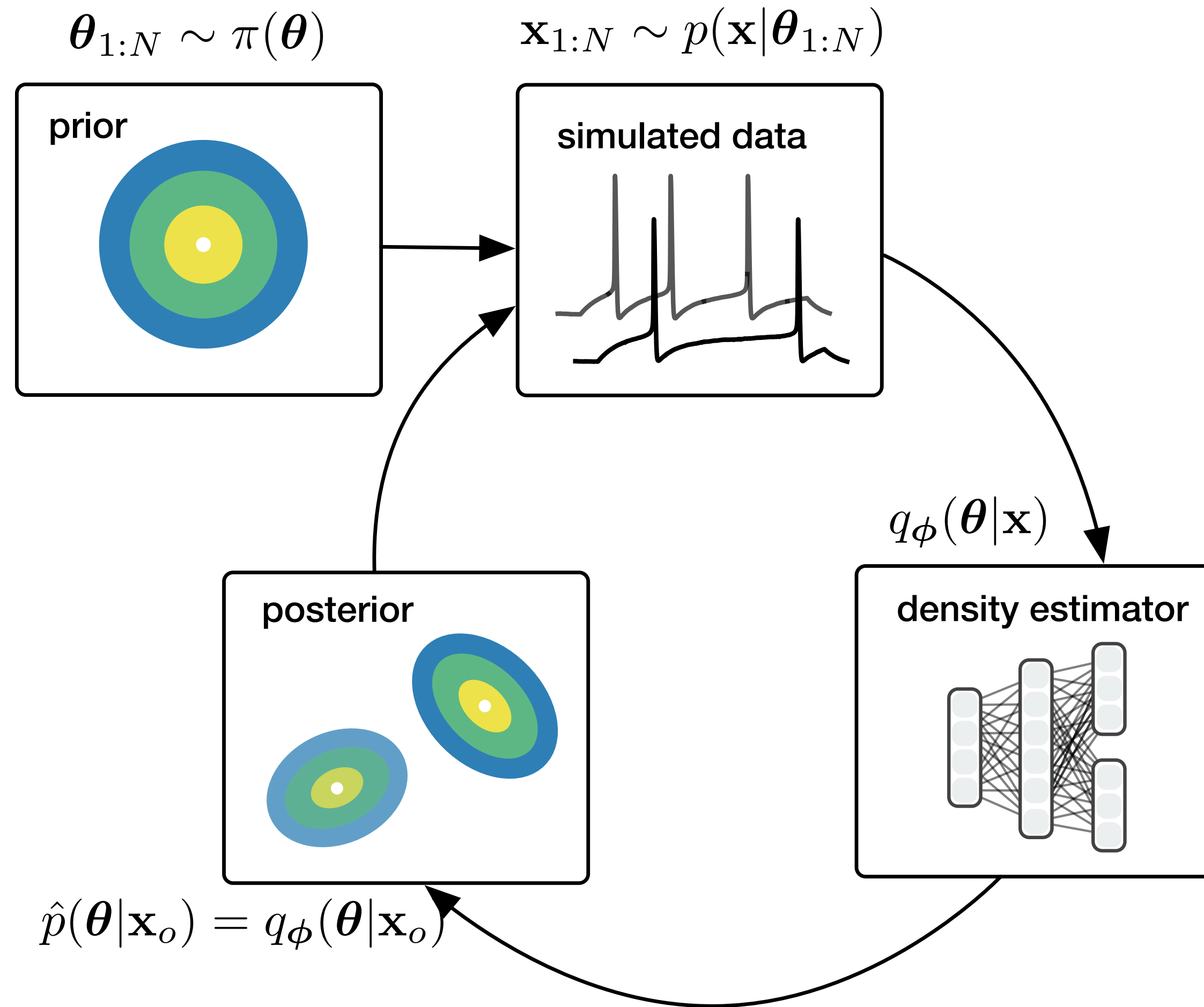




3. Train conditional density estimator to predict parameters from (simulated) data

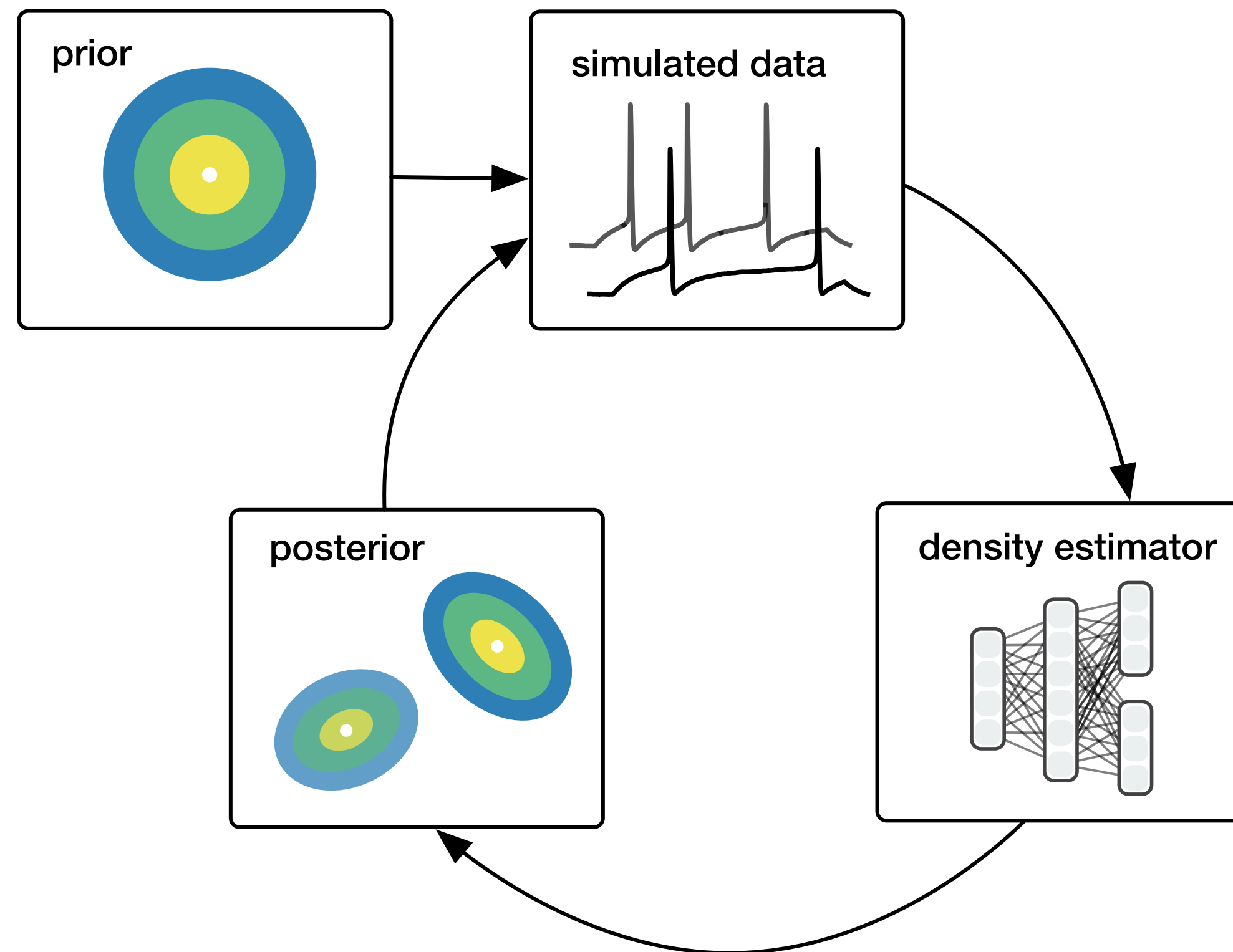


4. Plug empirical data \mathbf{x}_o into density estimator to calculate posterior



5. If needed, adaptively generate more simulations

(Sequential) Neural Posterior Estimation: Train neural networks to perform inference on simulations



Beaumont et al 2002
Blum & Francois 2010
Papamakarios & Murray NeurIPS 2016

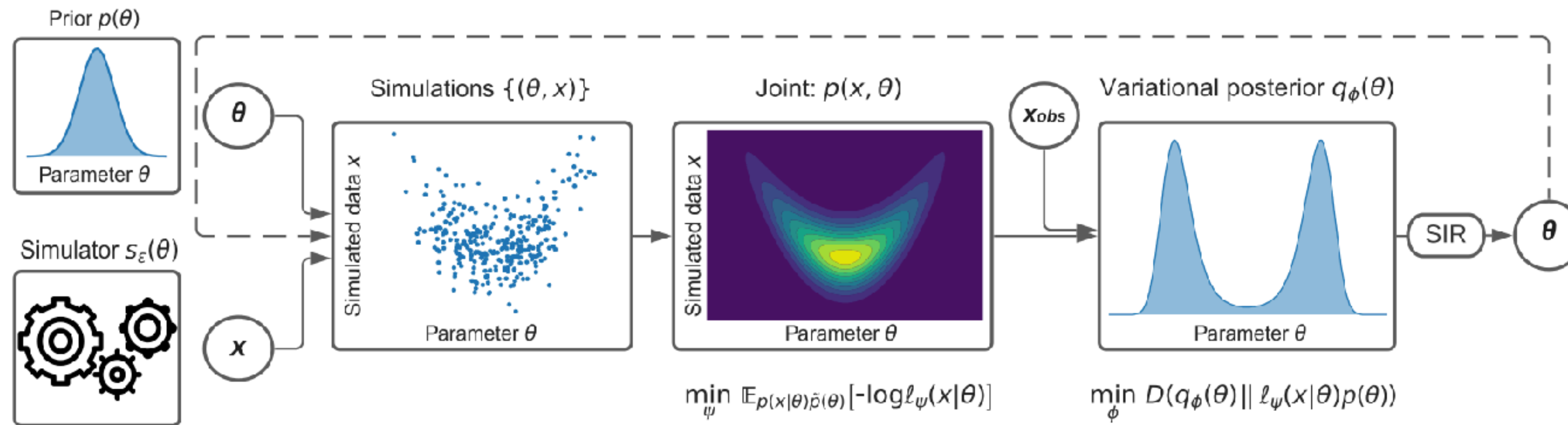
Other SBI approaches, reviewed in Cranmer, Brehmer, Louppe 2020
Website: simulation-based-inference.org/

Lueckmann, Goncalves et al NeurIPS 2017
Greenberg et al ICML 2019
Lueckmann et al PRML 2019
Goncalves, Lueckmann, Deistler et al eLife 2020
Tejero-Cantero et al, JOSS 2020
Lueckmann et al AISTATS 2021
Boelts et al eLife 2022
Ramesh et al ICLR 2022
Dax et al ICLR 2022
Glöckler et al ICLR 2022
Deistler et al NeurIPS 2022
Deistler et al PNAS 2022
Beck et al NeurIPS 2022
Glöckler et al ICML 2023
Gao, Deistler, Macke NeurIPS 2023
Dax, Wildberger, Buchholz et al NeurIPS 2023
Confafreux, Ramesh et al NeurIPS 2023

Code: www.mackelab.org/sbi

Benchmark: sbi-benchmark.github.io/

Alternatives to Neural Posterior Estimation: Sequential Neural Variational Inference (SNVI)



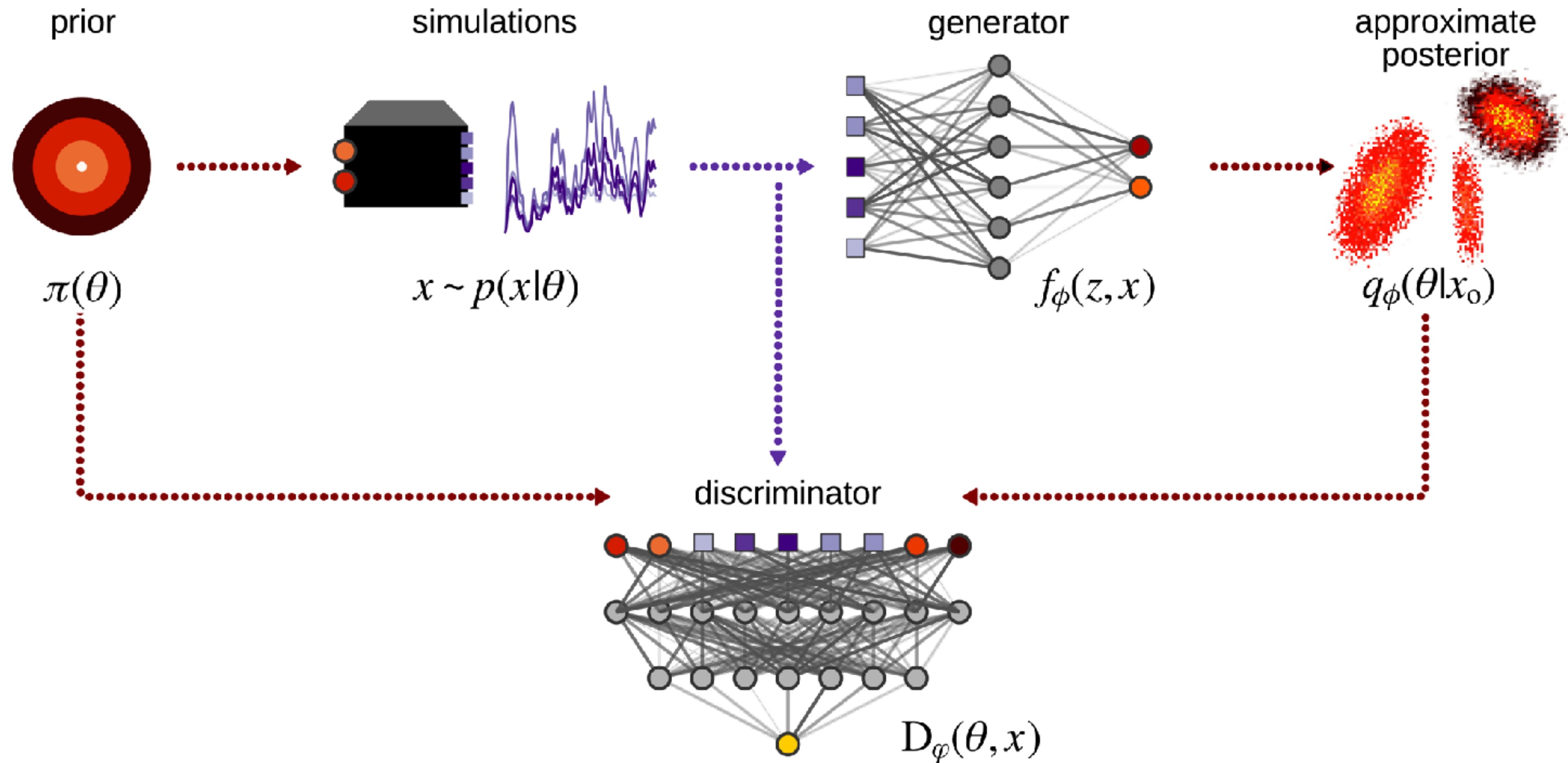
- Sequential Neural Likelihood (SNL, Papamakarios et al 2018): Estimate likelihood from simulations
- Requires additional MCMC
- Solution: Combine SNL with variational inference, learn likelihood and posterior in parallel



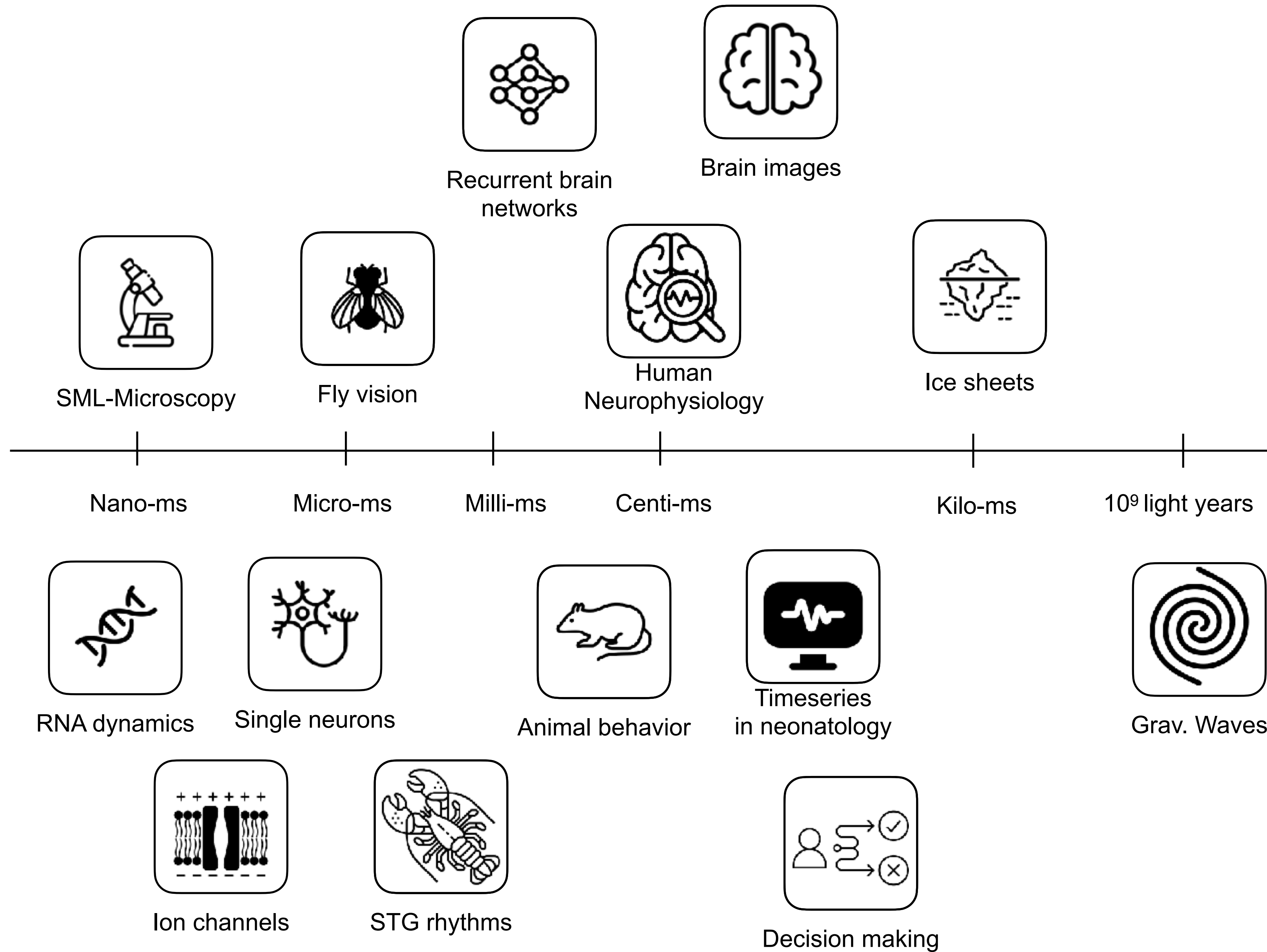
Manuel
Glöckler

Glöckler, Deistler, Macke, ICLR 2022
also see Wiqvist et al 2021

Alternatives to Neural Posterior Estimation: GATSBI: Generative Adversarial Training for SBI



Poornima
Ramesh



Application: Faster inference of gravitational wave models

Bernhard Schölkopf (MPI IS Tübingen)
Alessandra Buonanno (MPI Potsdam)

Image Credit: SXS project



Real-Time Gravitational Wave Science with Neural Posterior Estimation

Maximilian Dax^{1,*}, Stephen R. Green^{2,†}, Jonathan Gair^{2,‡}, Jakob H. Macke^{1,3},
Alessandra Buonanno^{2,4} and Bernhard Schölkopf¹

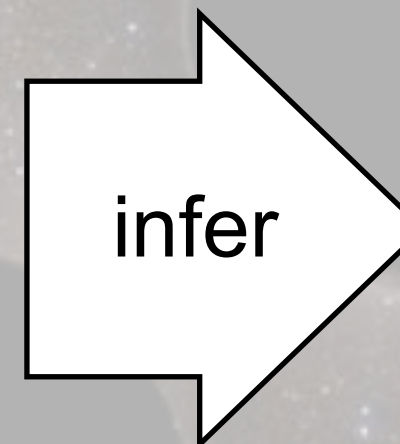
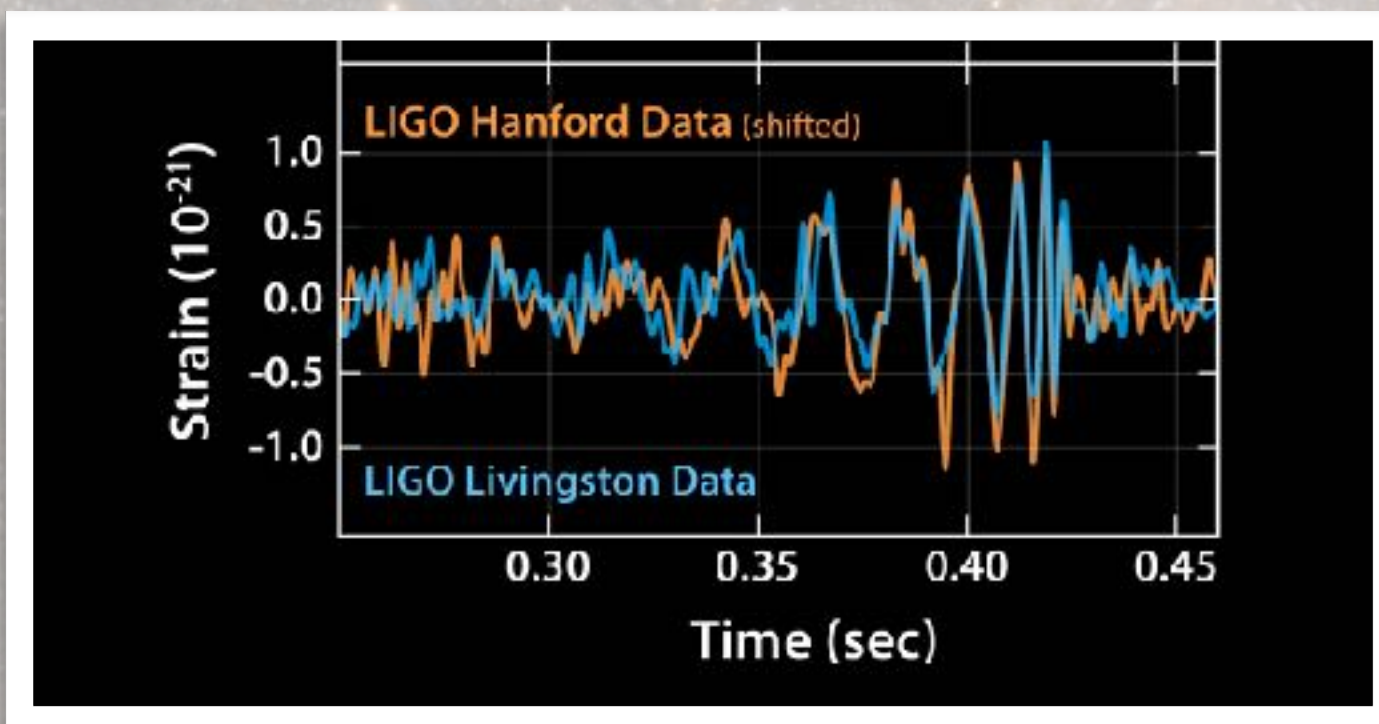
¹Max Planck Institute for Intelligent Systems, Max-Planck-Ring 4, 72076 Tübingen, Germany

²Max Planck Institute for Gravitational Physics (Albert Einstein Institute), Am Mühlenberg 1, 14476 Potsdam, Germany

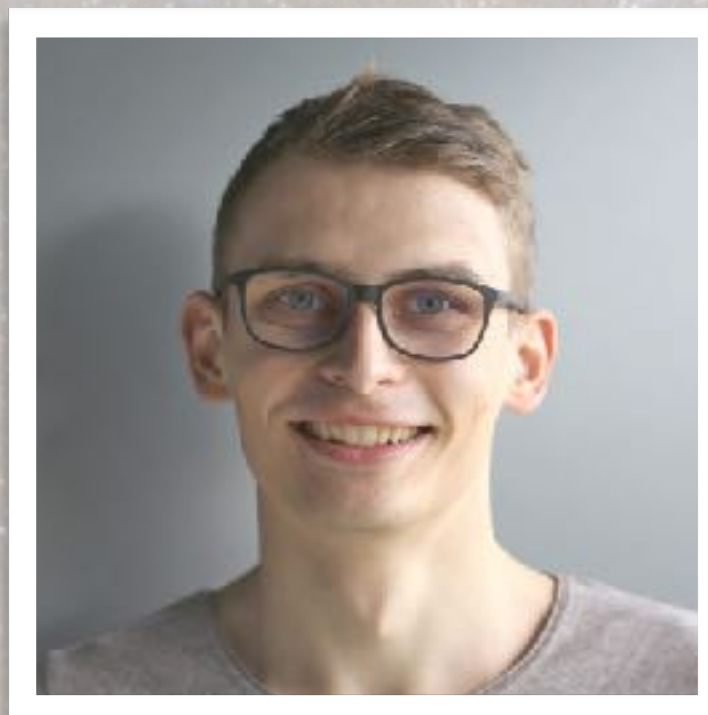
³Machine Learning in Science, University of Tübingen, 72076 Tübingen, Germany

⁴Department of Physics, University of Maryland, College Park, Maryland 20742, USA

 (Received 1 July 2021; accepted 17 November 2021; published 8 December 2021)



Location?
Masses?
Spins?
...



Max Dax



Stephen Green



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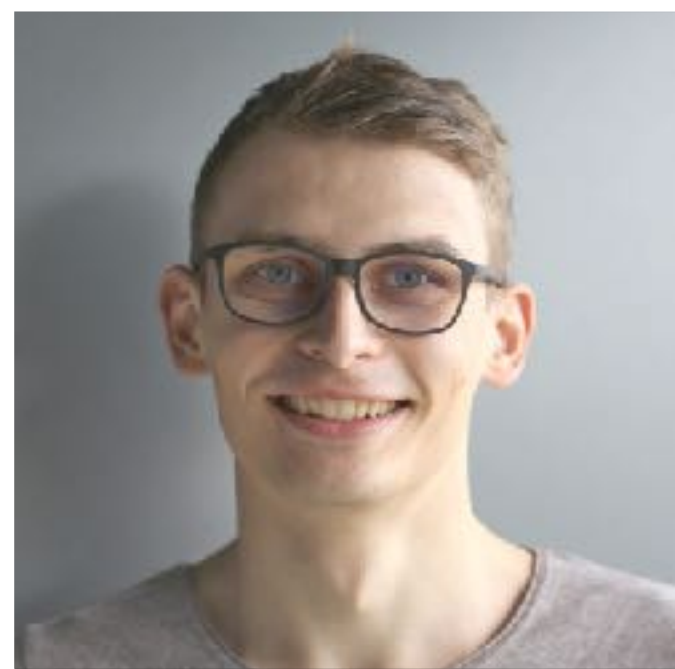
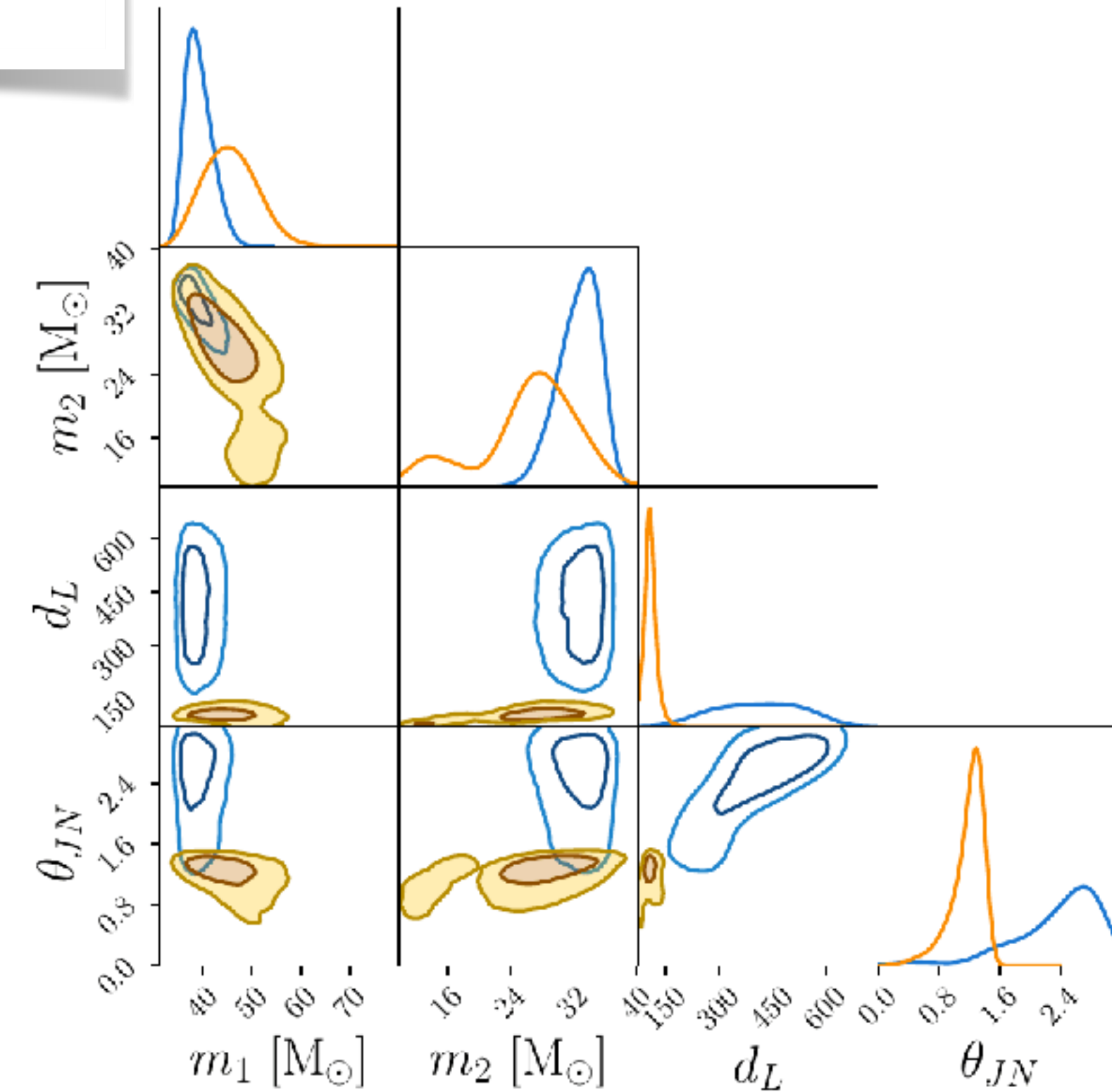
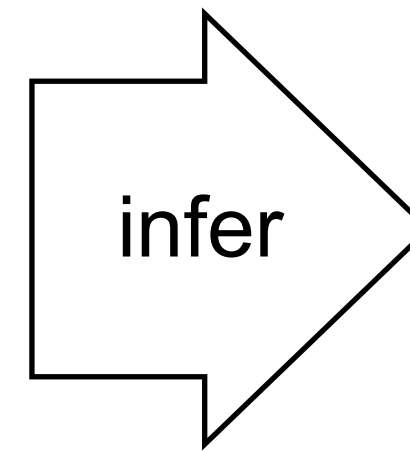
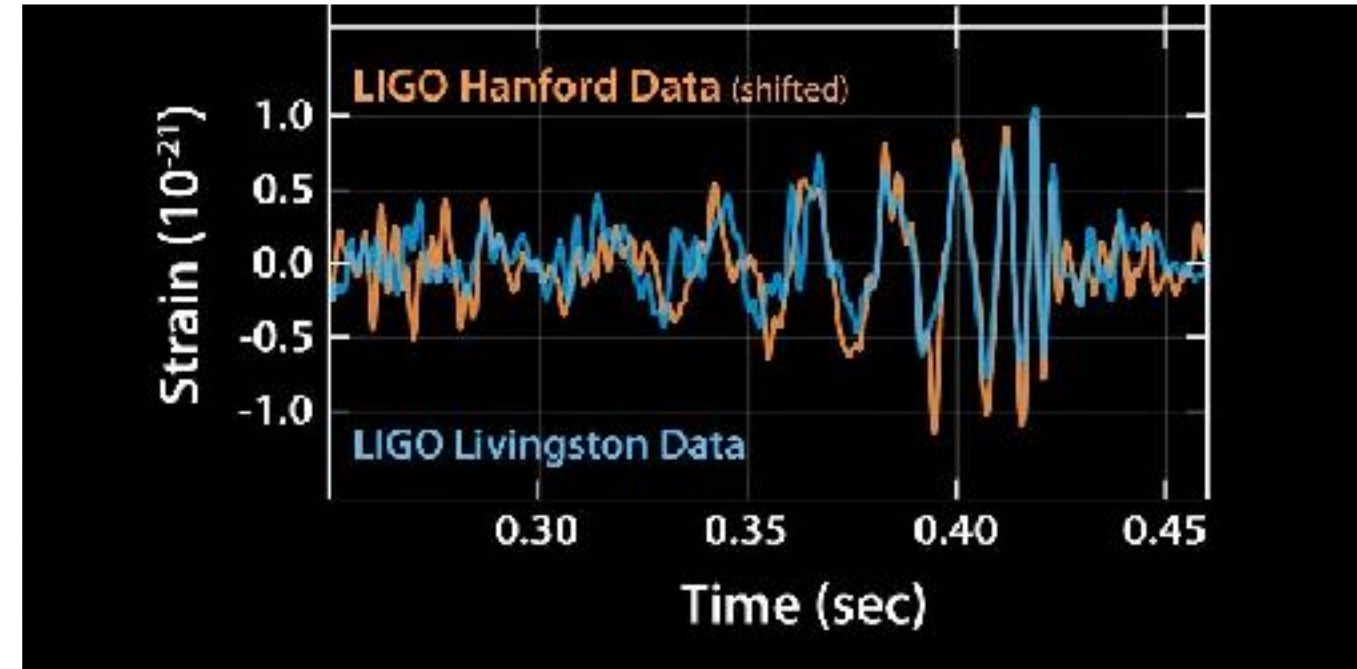
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Max Dax



Stephen Green

Standard method:

Our SBI method(DINGO):

O(days to hours)

O(seconds)

Real-Time Gravitational Wave Science with Neural Posterior Estimation

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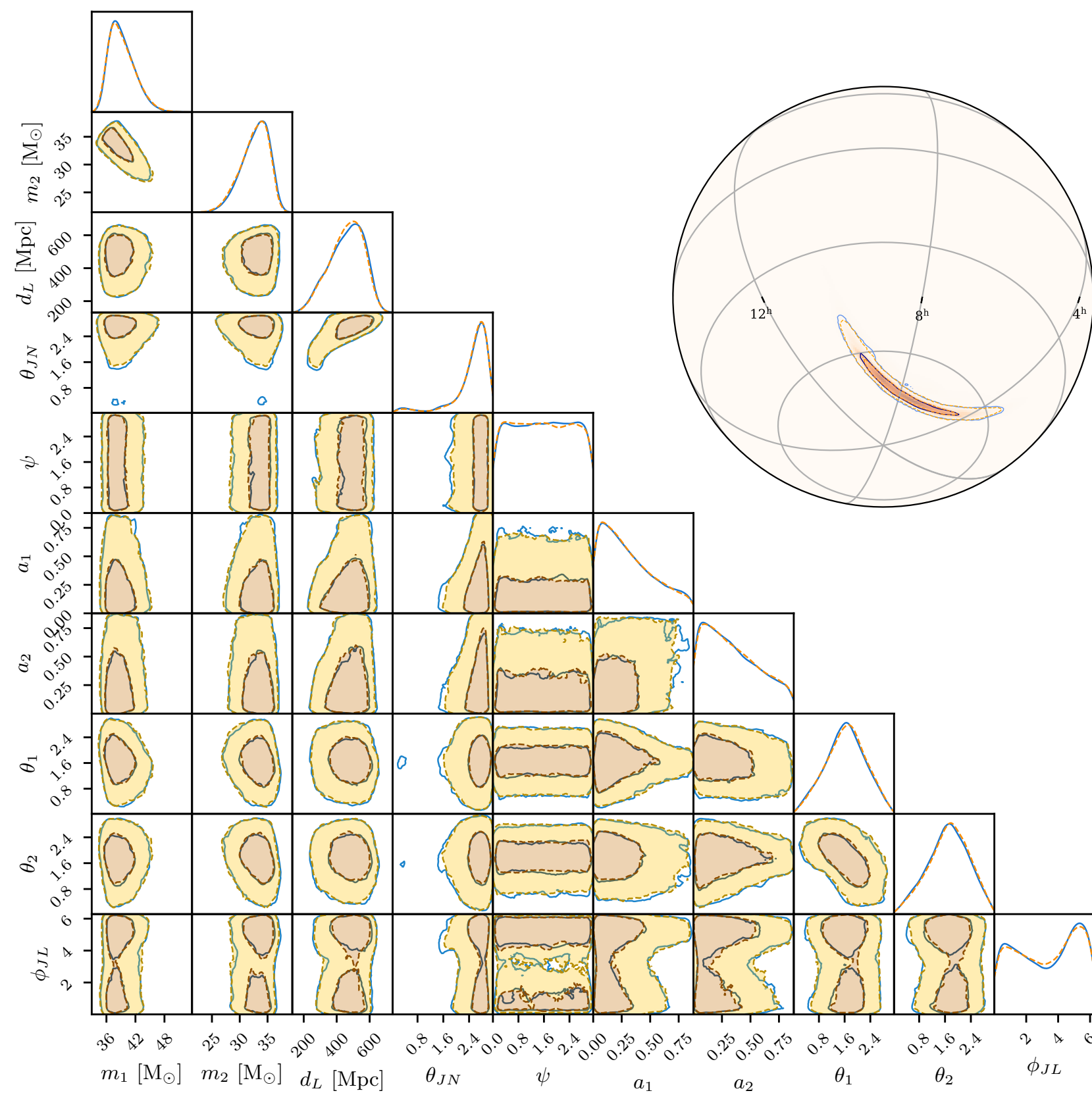
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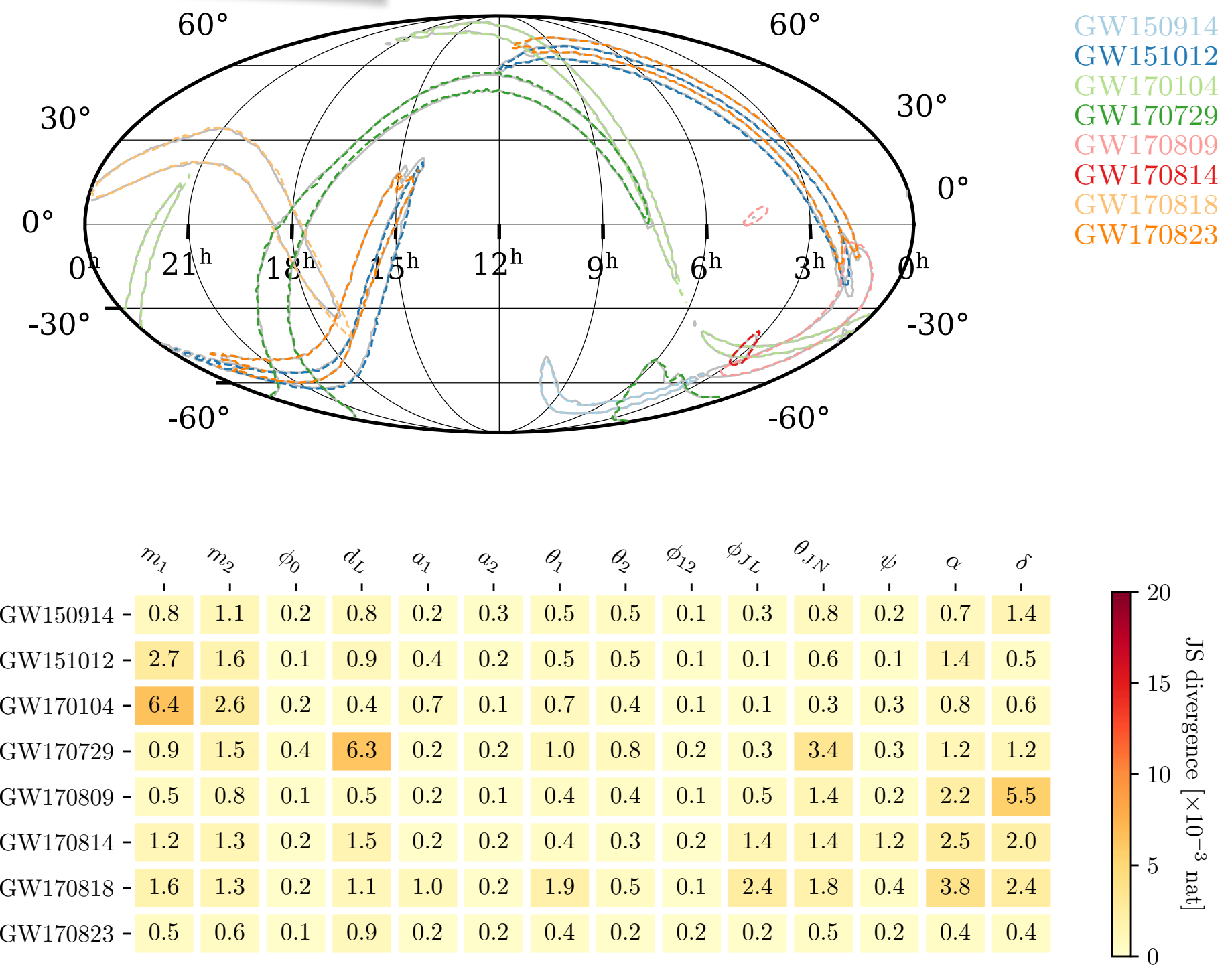
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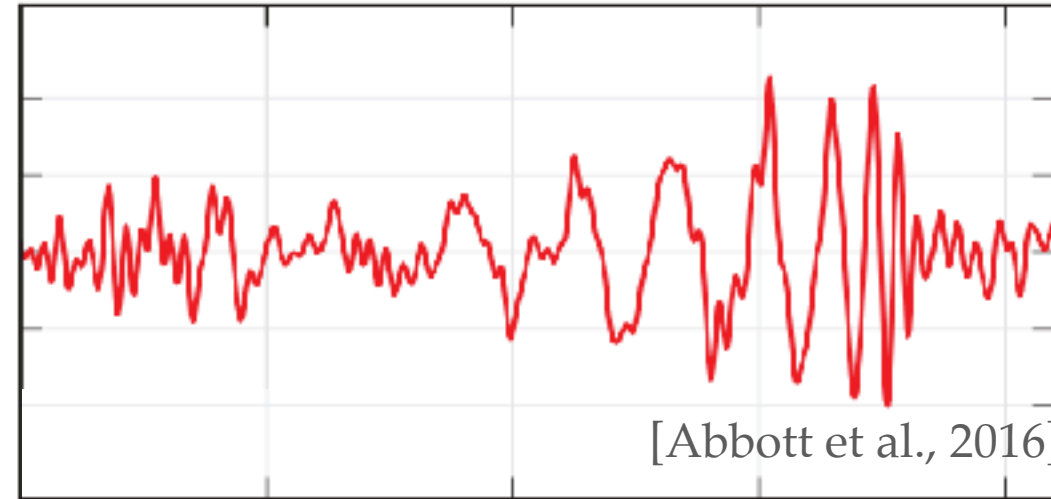
GW150914



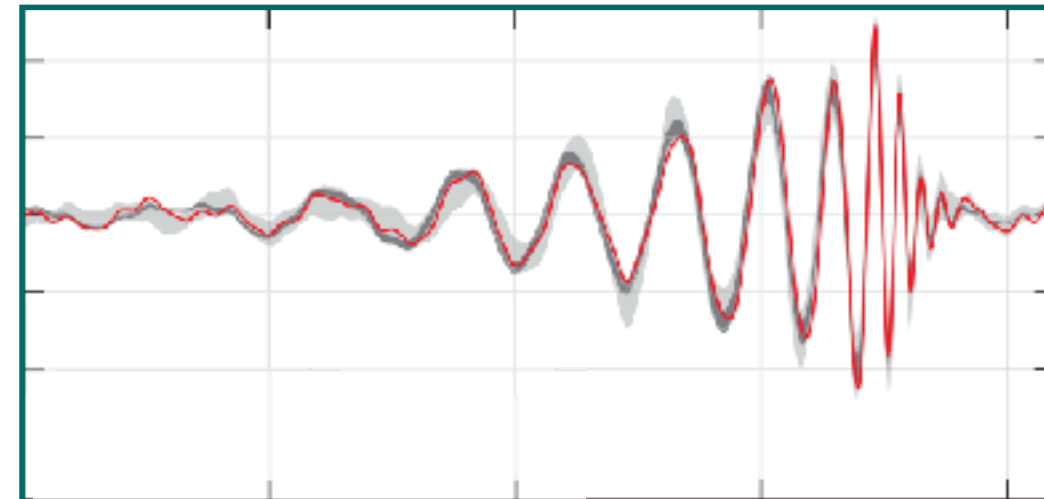
Jensen-Shannon divergence between Dingo and MCMC.
 Average: 0.0009 nat (MCMC-MCMC: 0.0007 nat)

Exploiting problem structure: Symmetries + Noise

$$d \sim p(d|\theta)$$

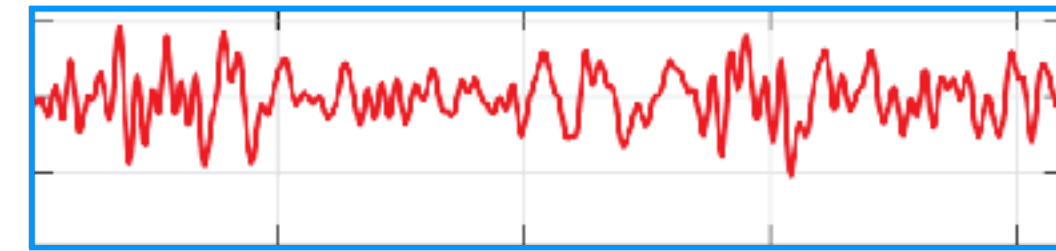


$$h(\theta)$$

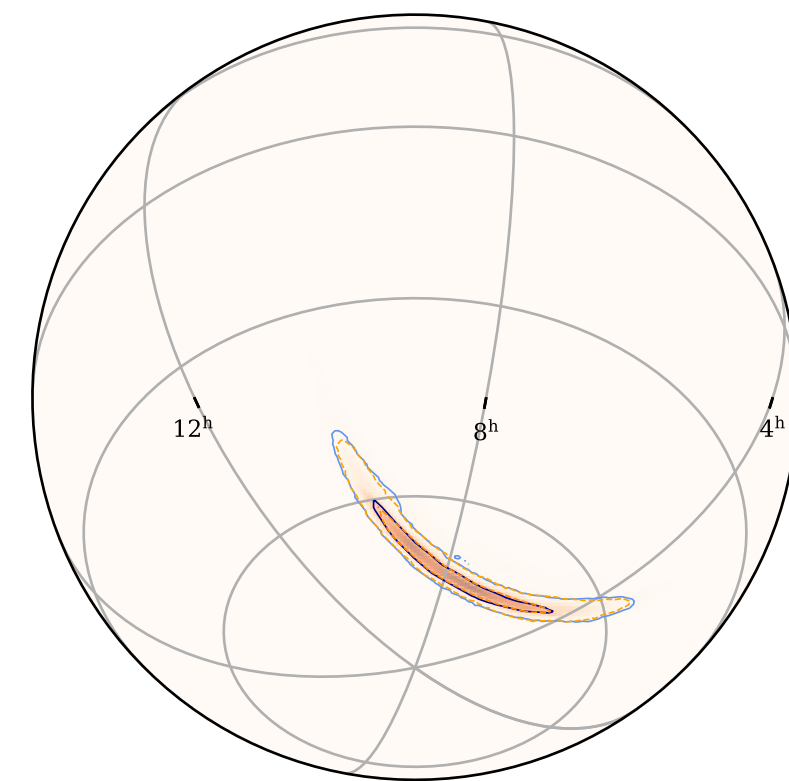
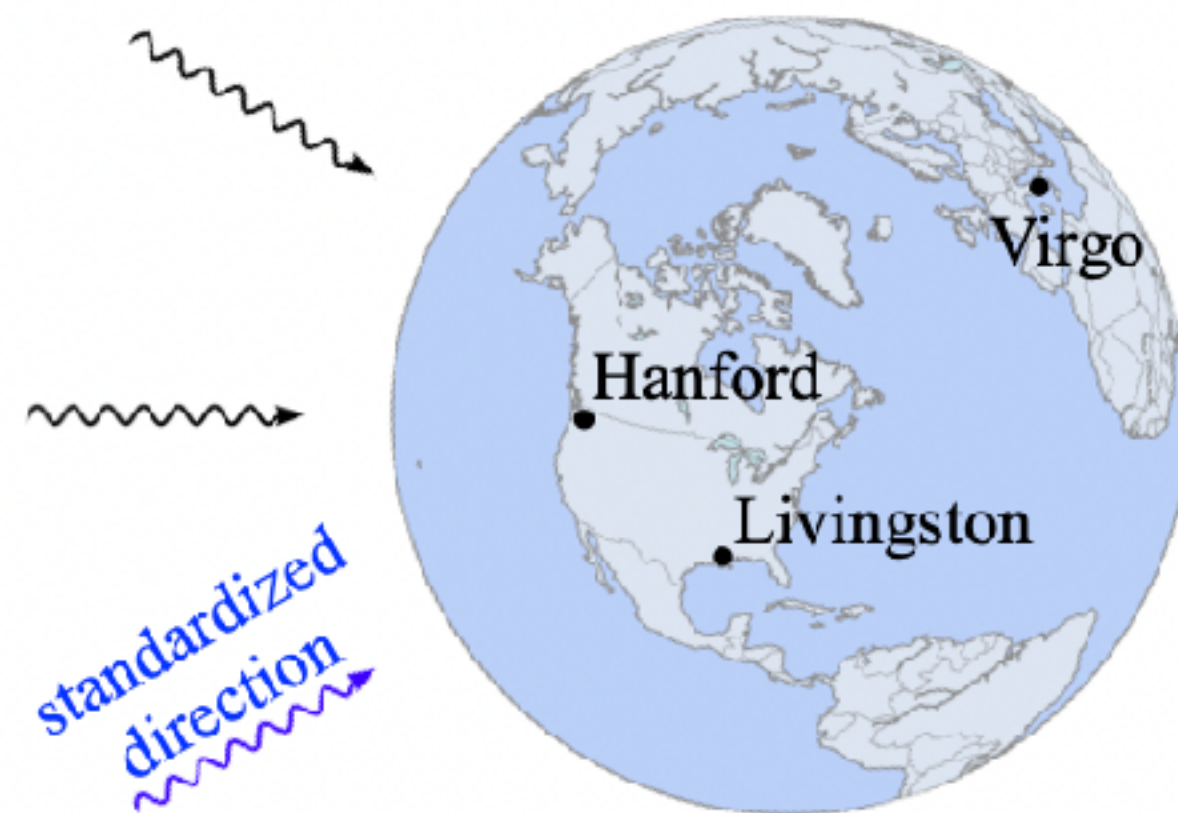


deterministic GW signal from general relativity model

$$n \sim \mathcal{N}(0, S_n)$$

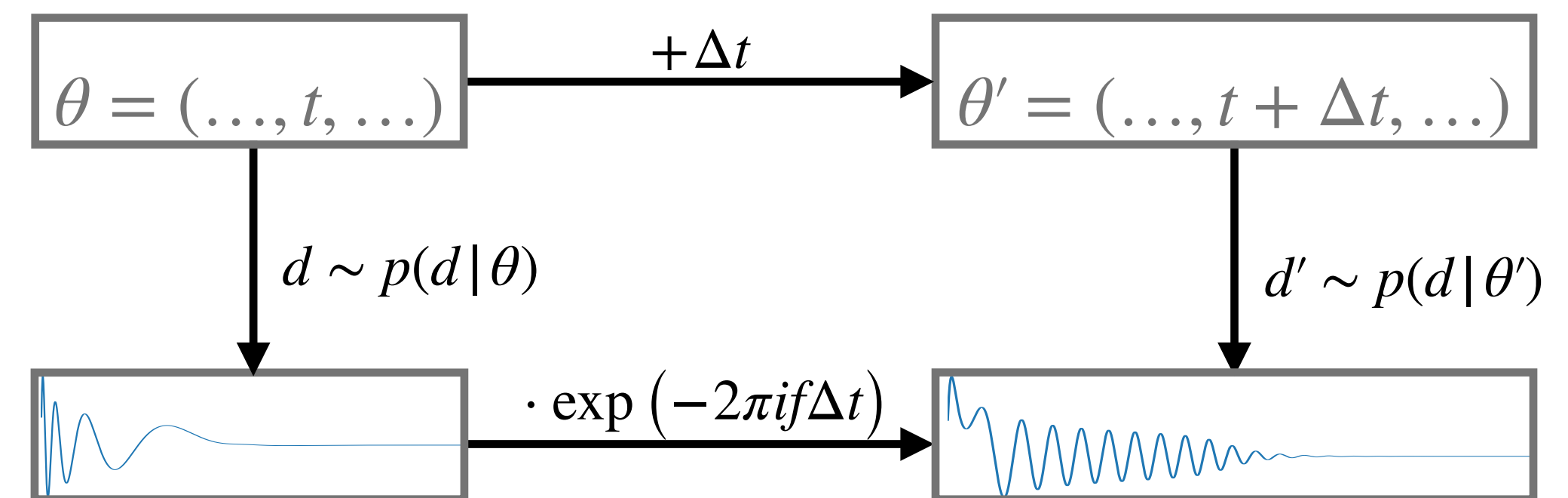


Noise: stationary Gaussian with PSD S_n



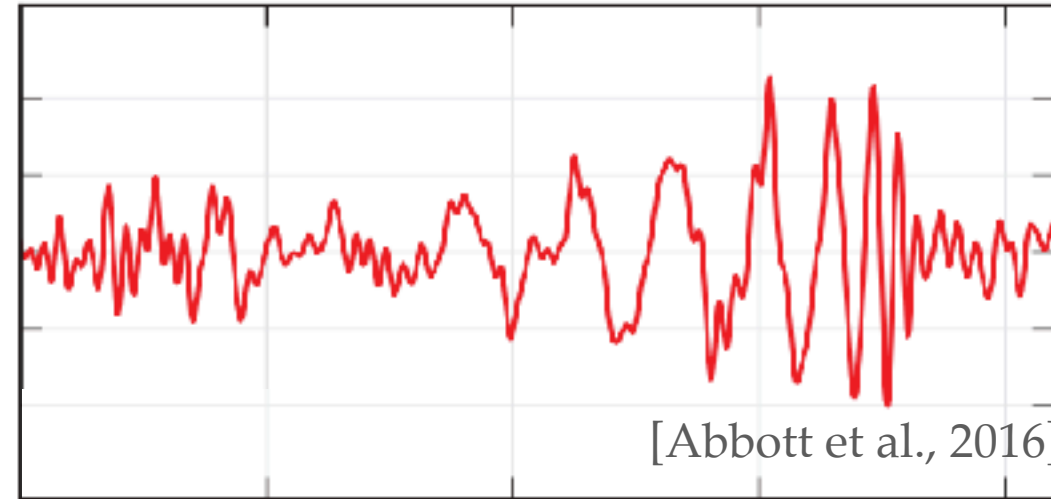
GW simulation:

- **exactly equivariant** under shifts of time $t \in \theta$
- **approx. equivariant** under rotations $(\alpha, \delta) \in \theta$

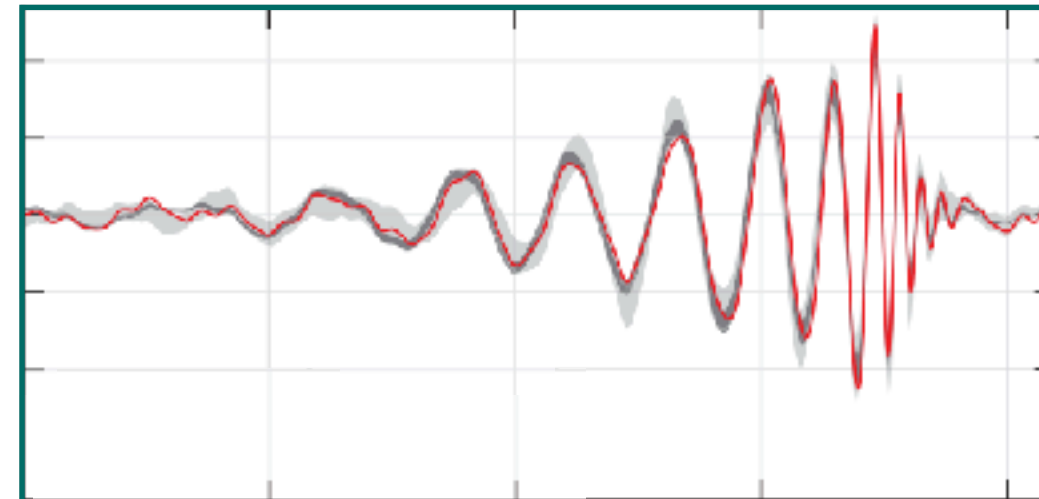


Exploiting problem structure: Symmetries + Noise

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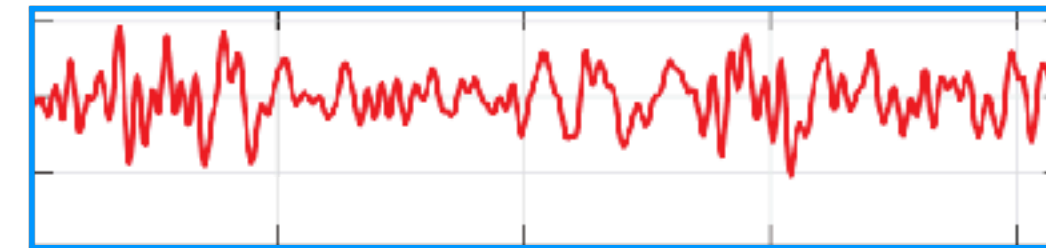


$$h(\theta)$$

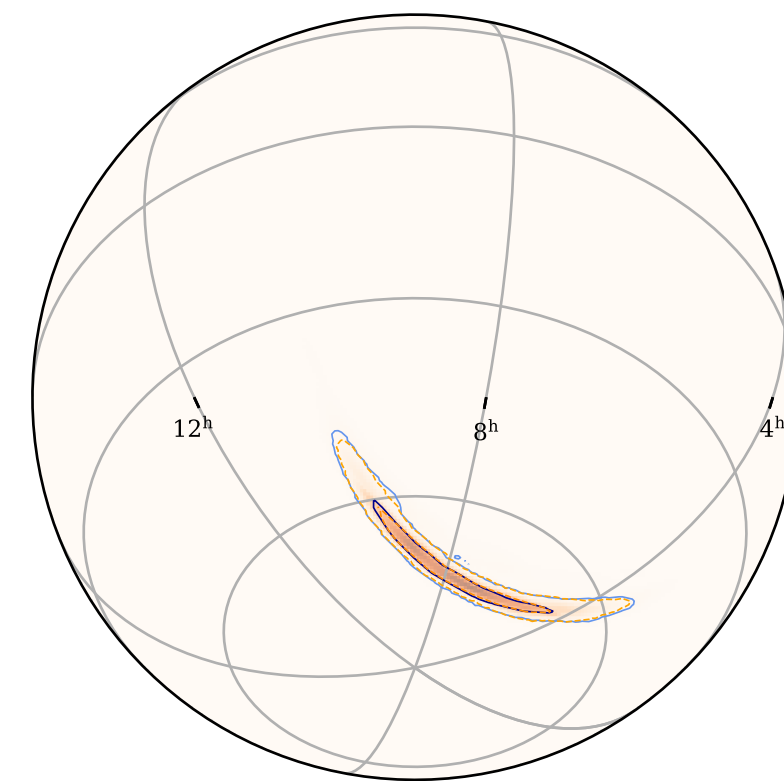
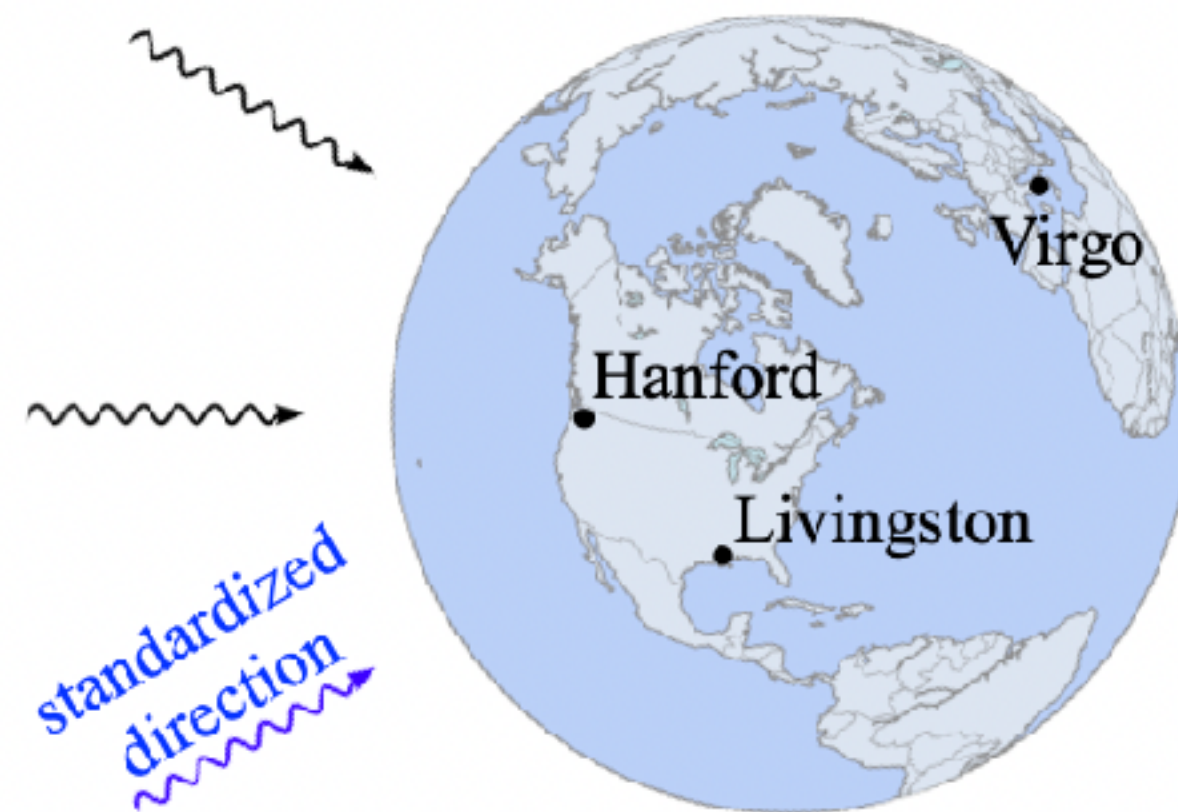


deterministic GW signal from general relativity model

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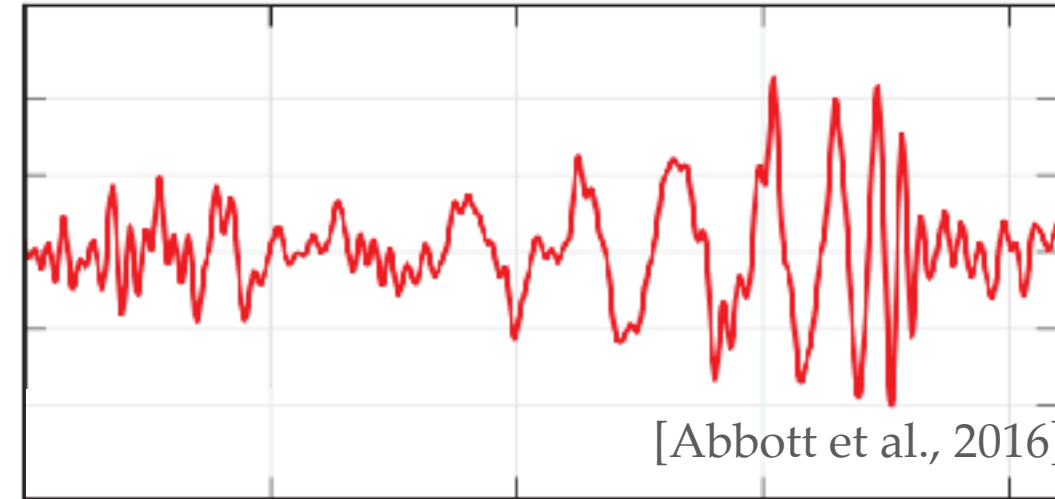
Noise: stationary Gaussian with PSD S_n



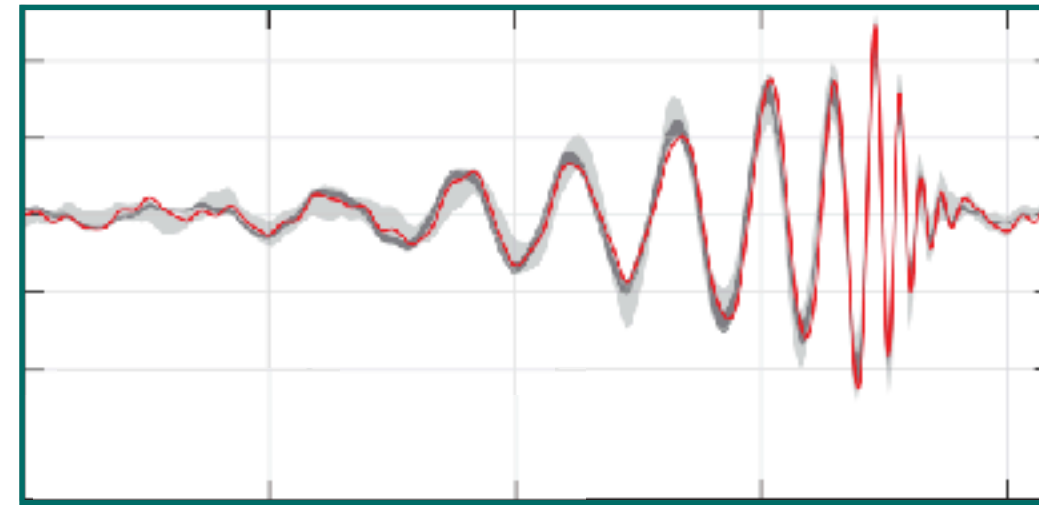
- Chicken-and-egg problem:
 - Once we align on standardized direction, inferring other parameters is easy
 - But don't know direction and time ...
- Solution: Gibbs Sampling
- Group-equivariant neural posterior estimation: Dax, Green, Gair, Schölkopf, Macke, ICLR 2022

Exploiting problem structure: Symmetries + Noise

$$d \sim p(d|\theta)$$

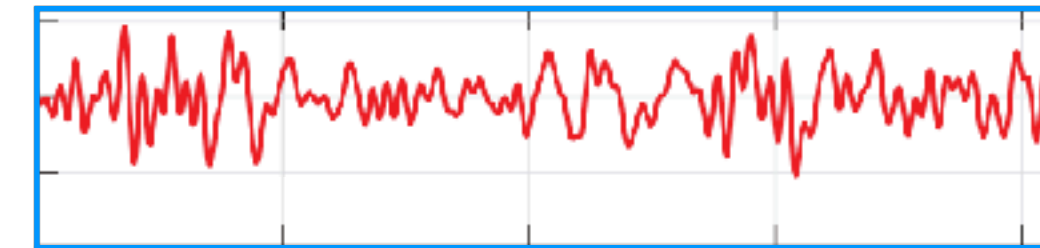


$$h(\theta)$$



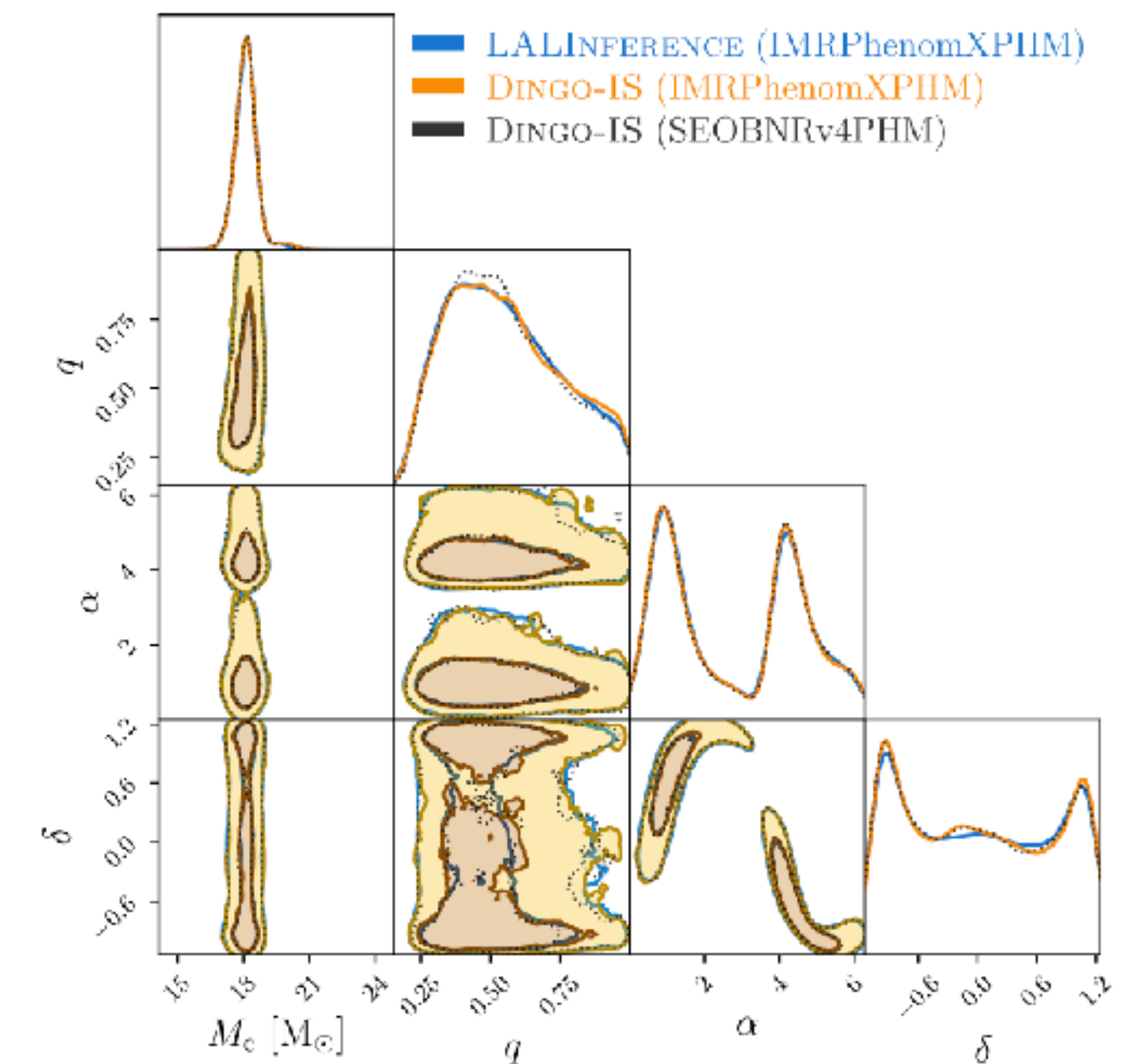
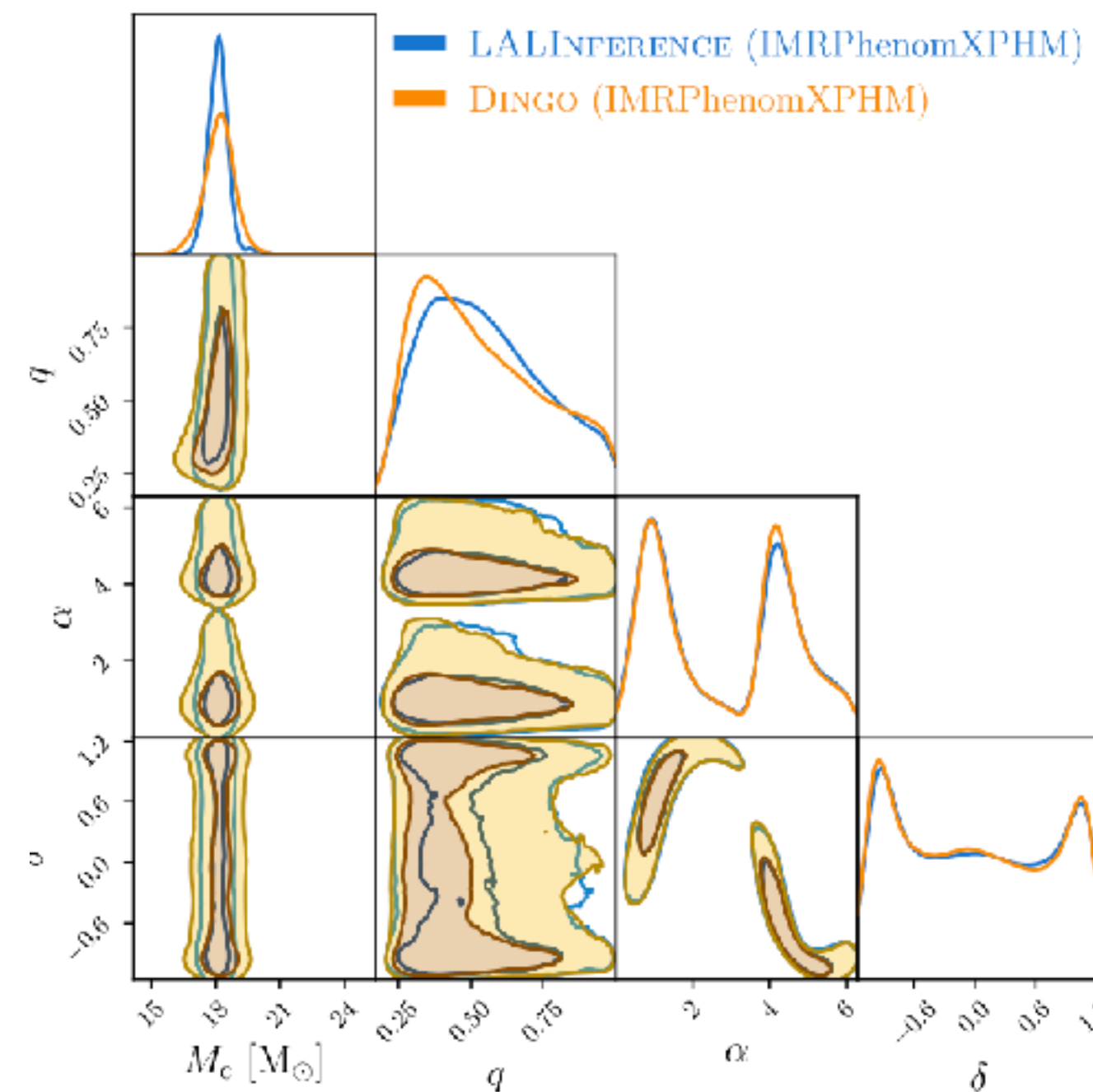
deterministic GW signal from
general relativity model

$$n \sim \mathcal{N}(0, S_n)$$

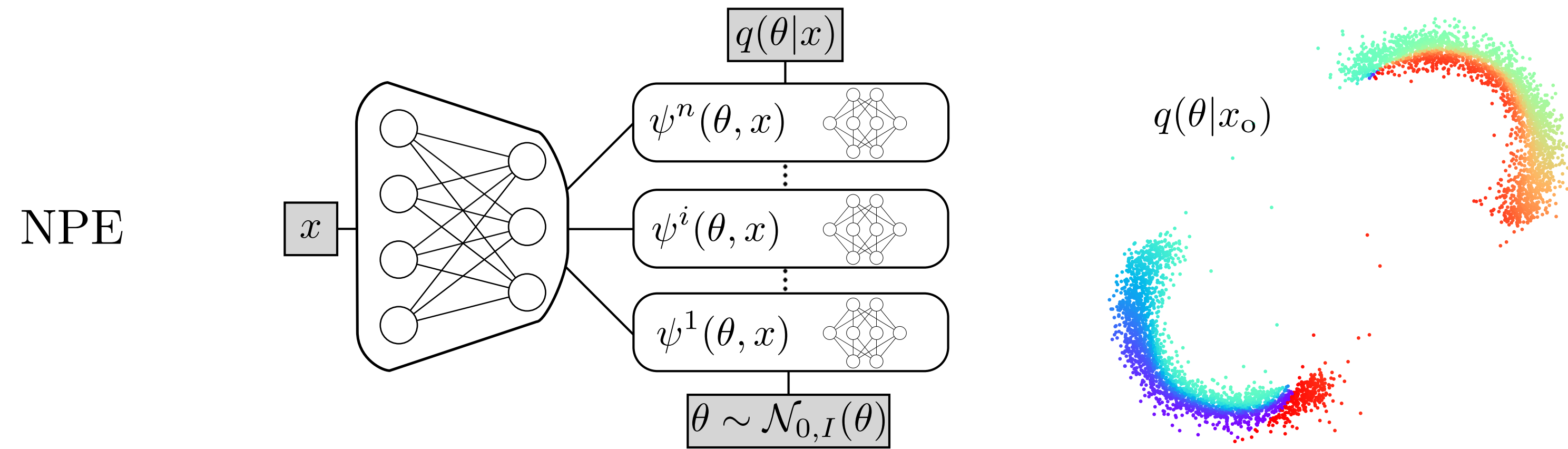


Noise: stationary Gaussian
with PSD S_n

- But noise is non-stationary?
Use probabilistic model of the PSD S_n !
Wildberger et al PRD 2023
- But noise is Gaussian?
Use Importance Sampling to fine-tune!!
Dax et al PRL 2022



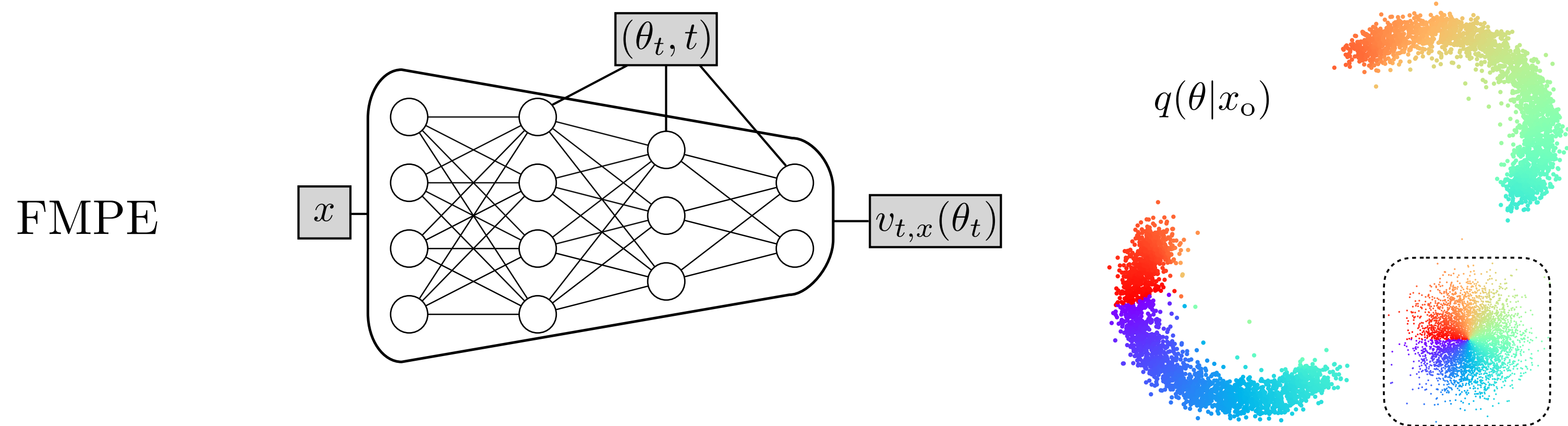
Scaling up: Flow-Matching Neural Posterior Estimation



Jonas Wildberger

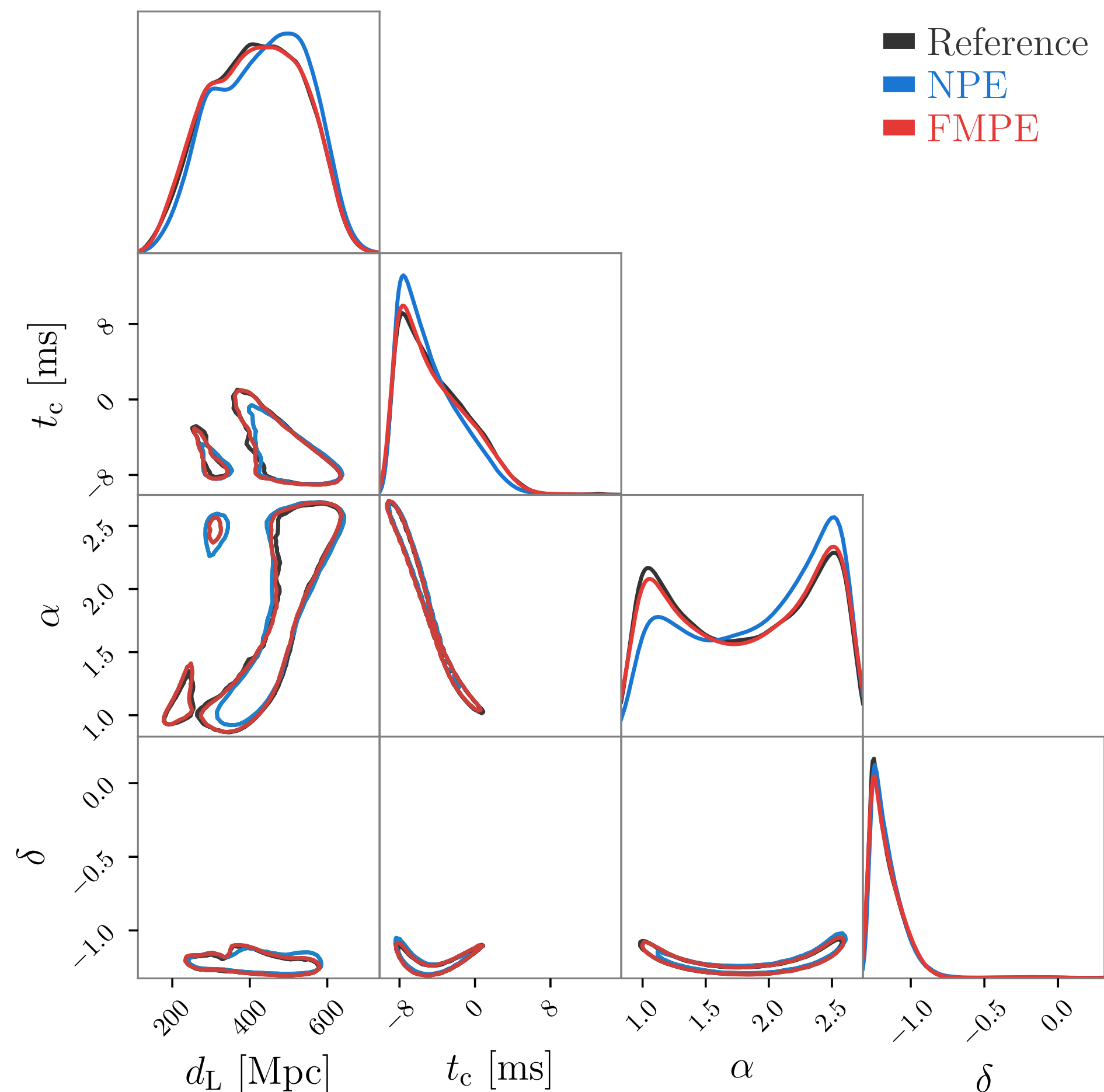


Max Dax



Simon Buchholz
all at MPI-IS

Scaling up: Flow-Matching Neural Posterior Estimation



	NPE	FMPE	GNPE
m_1	1.2	1.3	0.8
m_2	2.5	0.6	1.1
a_1	3.2	0.8	0.2
a_2	1.6	1.0	0.3
t_1	0.8	0.1	0.5
t_2	0.4	0.3	0.5
ϕ_{12}	0.3	0.2	0.1
d_L	4.4	0.1	0.8
t_c	9.1	0.6	—
α	10.1	0.6	0.7
δ	8.6	0.5	1.4
ψ	0.6	0.1	0.2

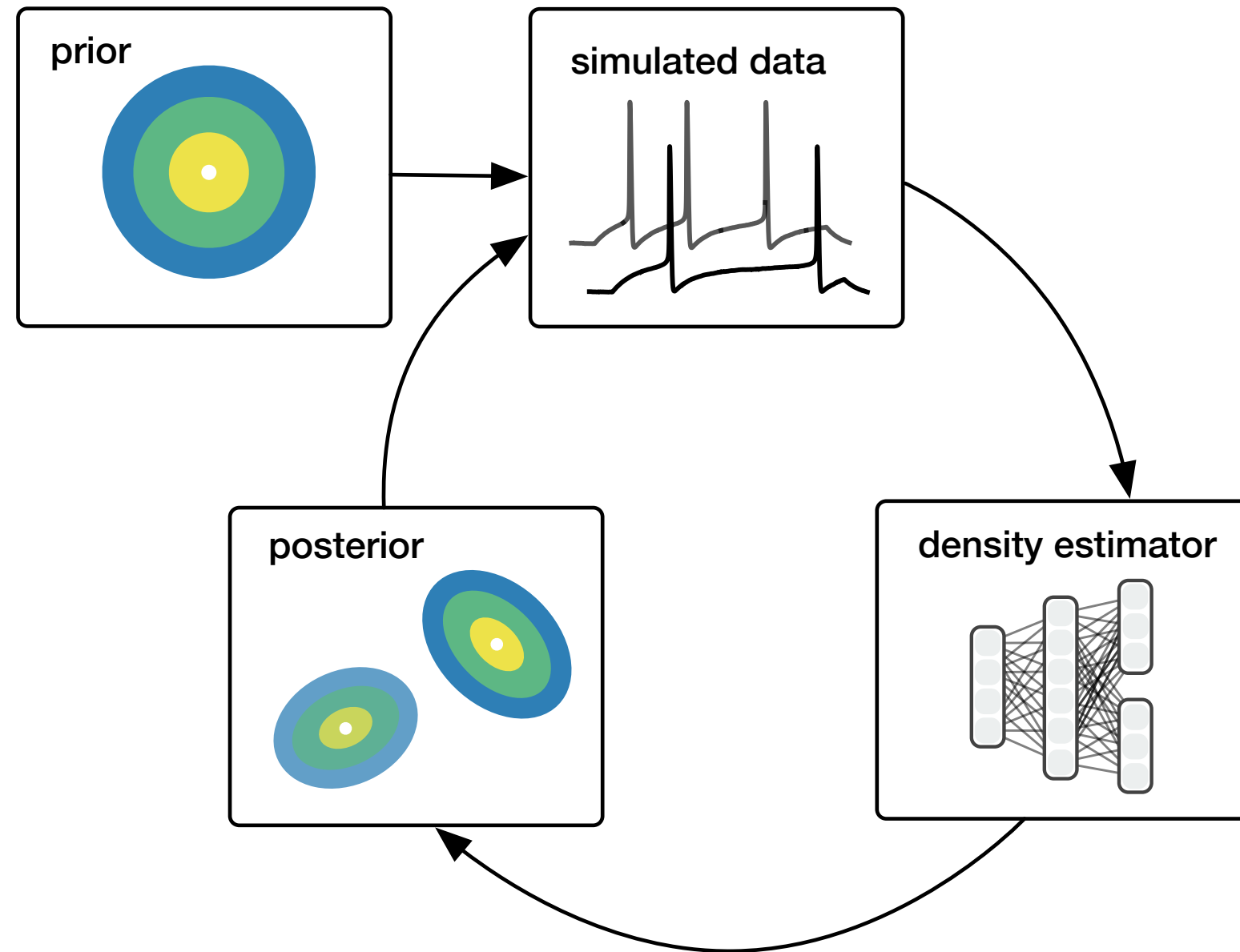
JSD [mnat]

- Gravitational Wave parameters $\theta \in \mathbb{R}^{15}$ (masses, spins etc.)
- Gravitational waves $x \in \mathbb{R}^{15,744}$ (frequency domain data)
- FMPE network $1.9 \cdot 10^8$ learnable parameters, training around **2 days**
- NPE network $1.3 \cdot 10^8$ parameters, training around **3 days**
- FMPE performance **en par with GNPE**

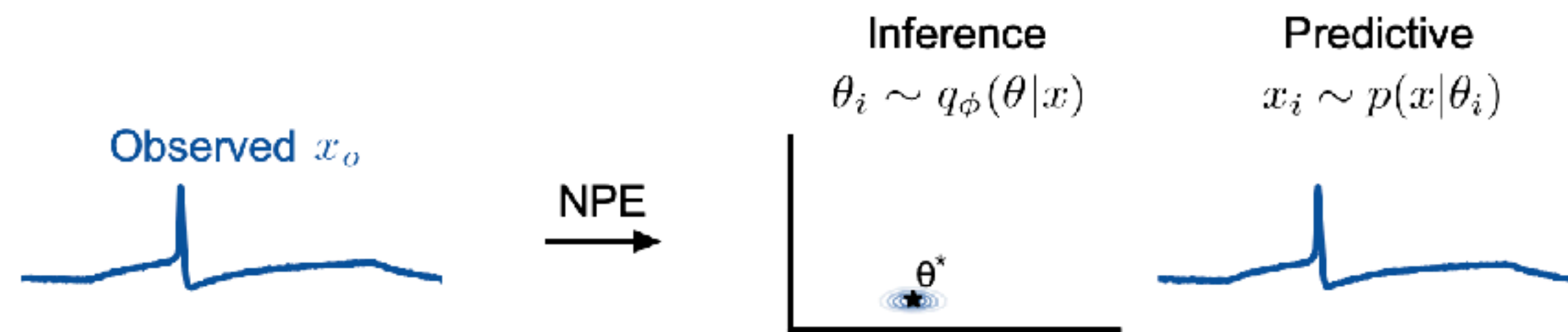
Simulation-based inference:

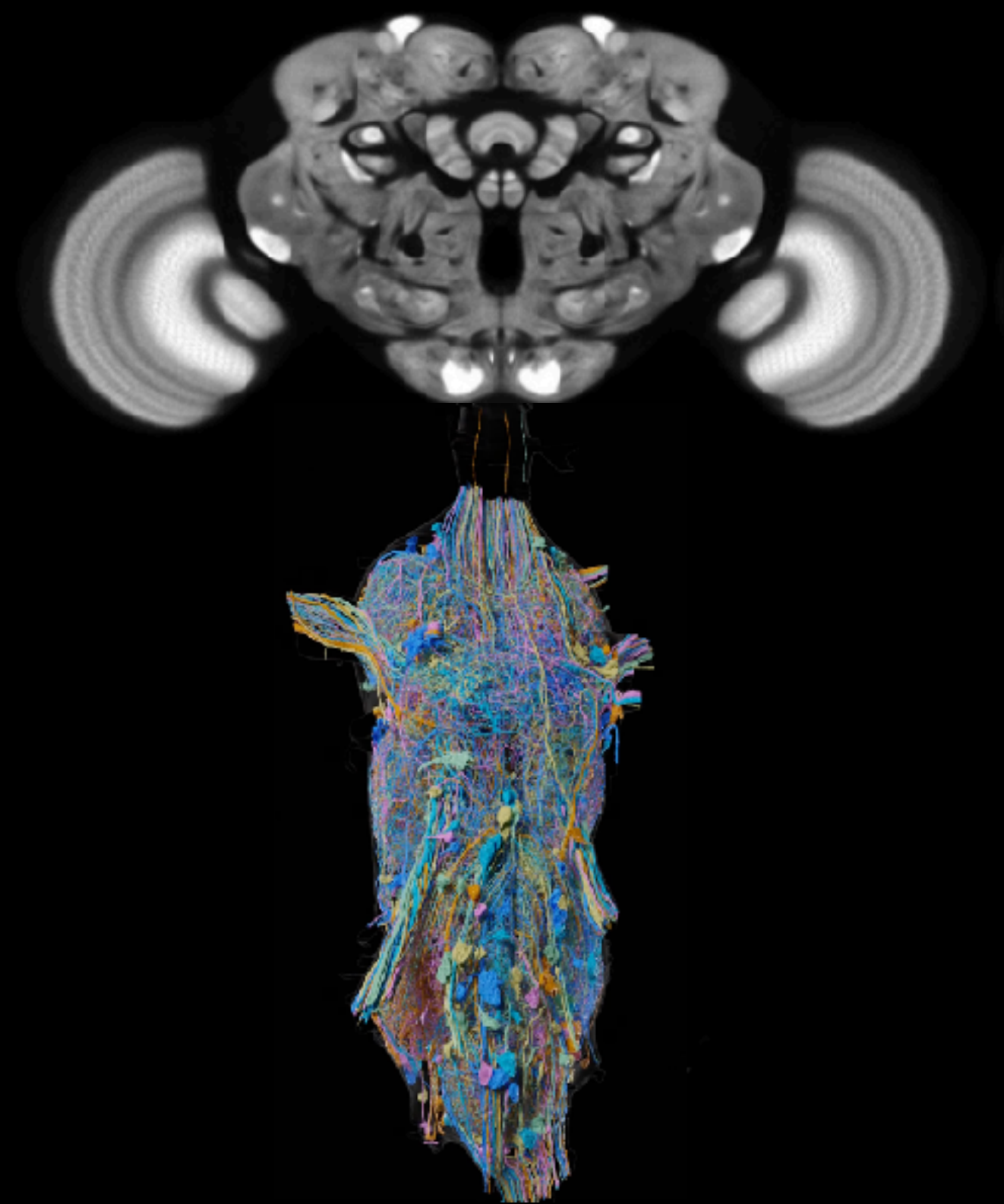
**New perspectives and opportunities across multiple
scientific disciplines ...**

... but ...



- Simulation efficiency
- Mis-specification
Gao, Deistler, Macke, NeurIPS 2023
- Infer models, not just parameters?
Schröder, Macke Arxiv 2023
- Robustness?
Glöckler, Deistler, Macke, ICML 2023





Bogovic et al 2020
Takemura et al 2023

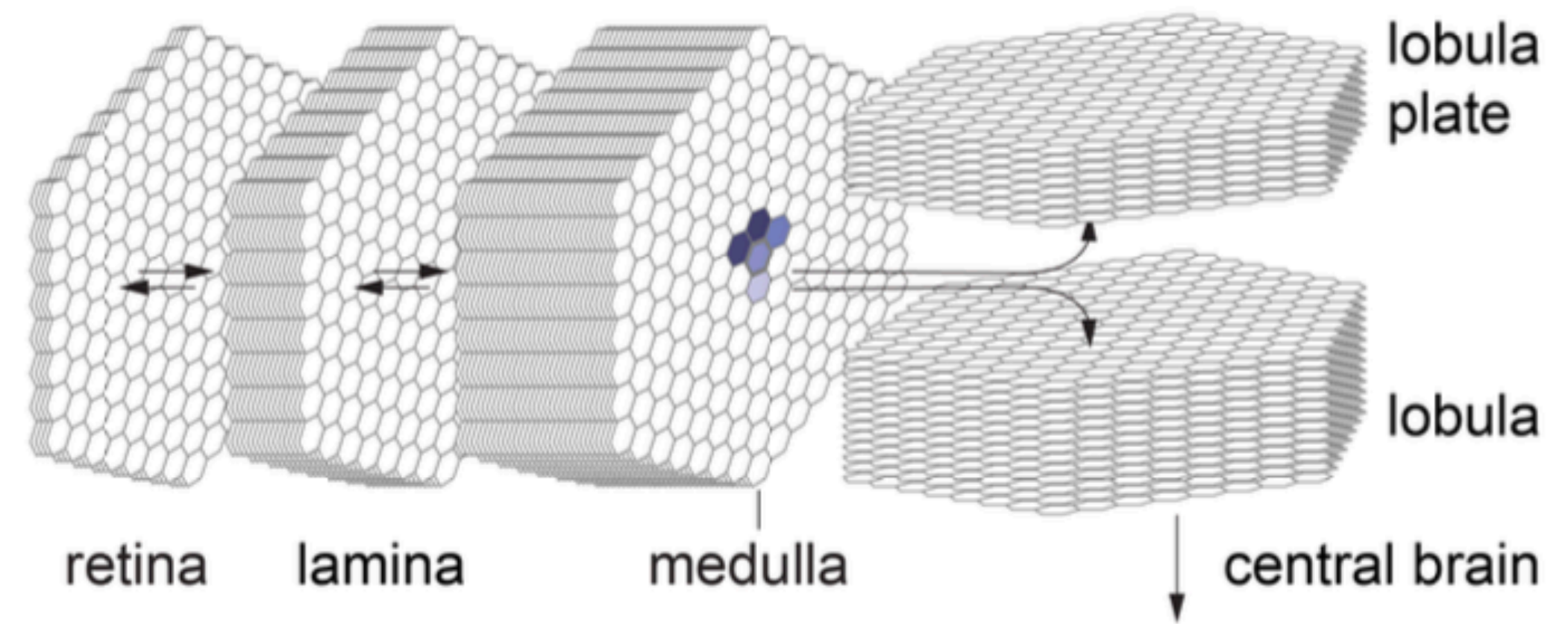
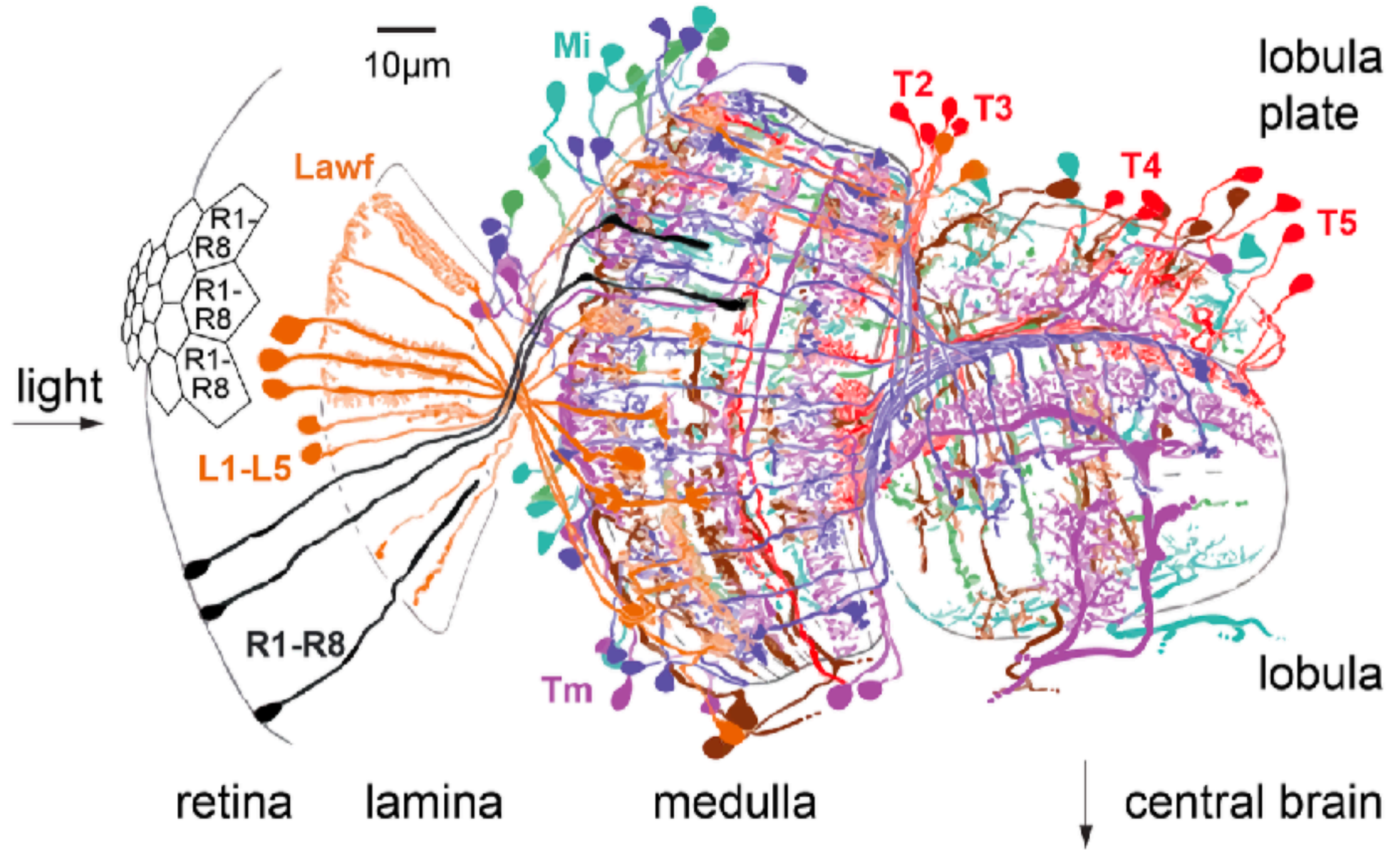


Srinivas Turaga
(HHMI Janelia)

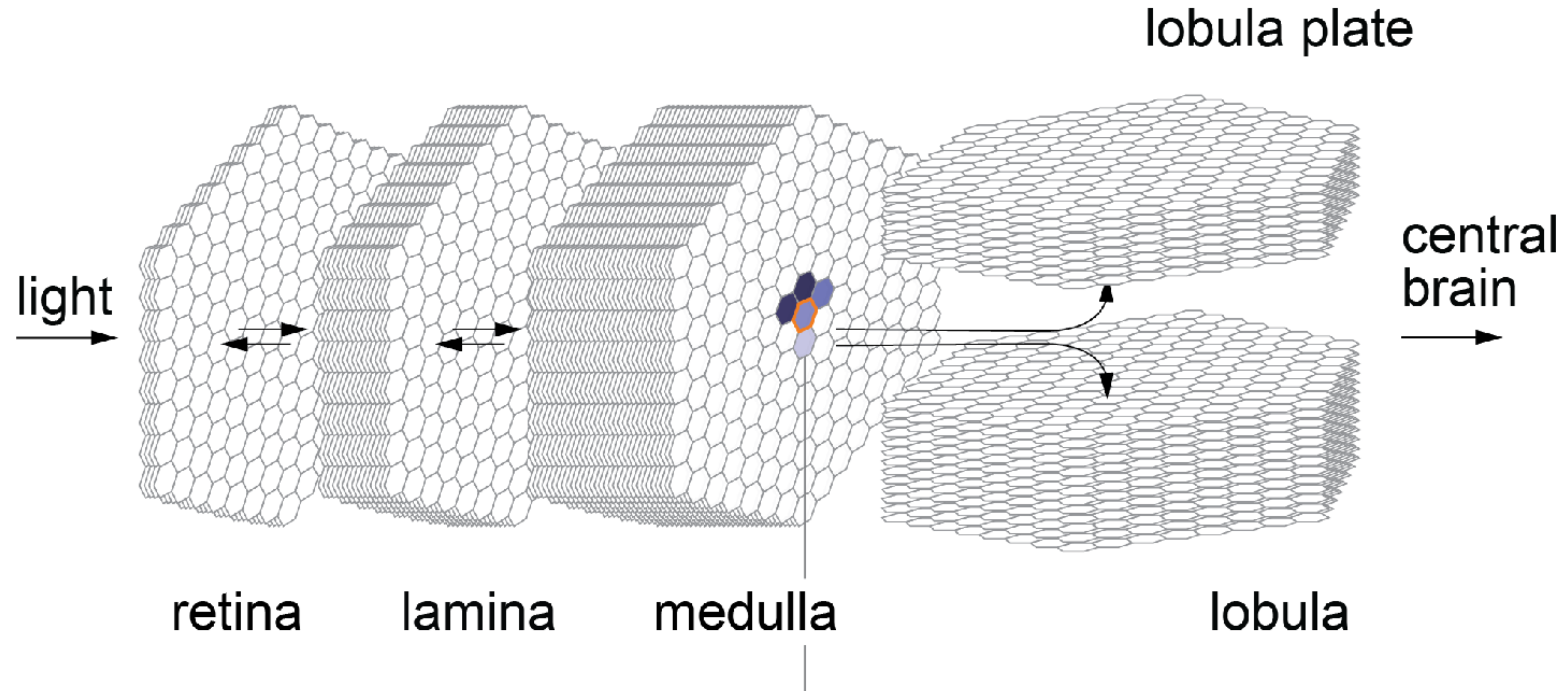


Janne Lappalainen

Optic lobe of the *Drosophila*



We built a recurrent, hexagonally convolutional neural network constrained by the fruit fly optic lobe—a “Deep Mechanistic Network” (DMN)



64 cell types, 44k cells, 1.5Mio connections

We use simple models of single-cell and synaptic dynamics

Non-spiking point neurons:


$$\tau_{t_i} \dot{V}_i = -V_i + \sum_j s_{ij} + V_{t_i}^{\text{rest}}$$

time constants resting potentials

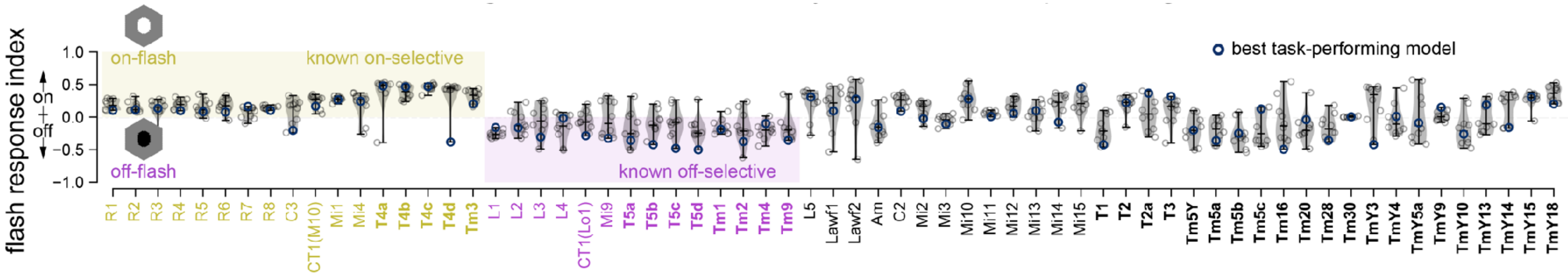
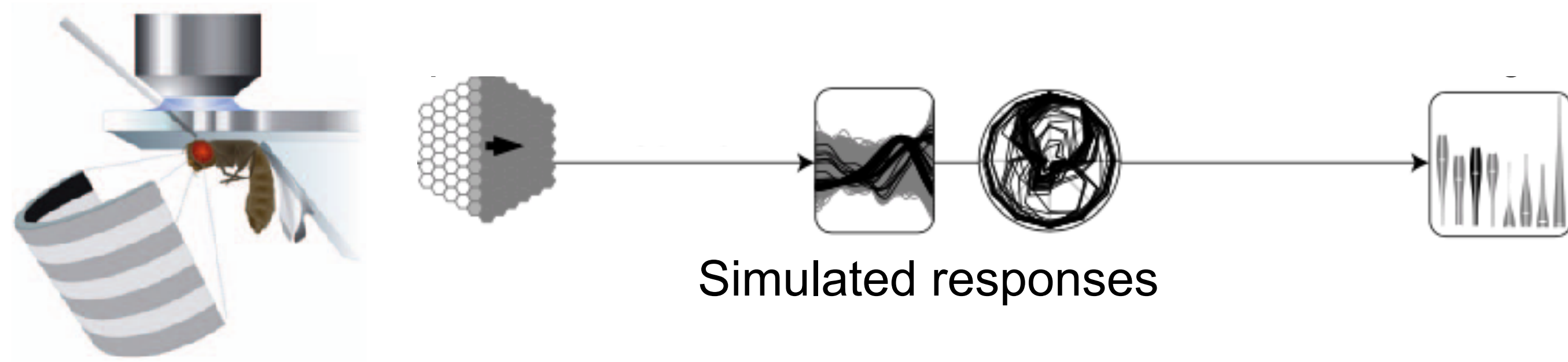
Current-based synapses:

$$s_{ij} = w_{ij} f(V_j) = \alpha_{t_i t_j} \sigma_{t_i t_j} N_{t_i t_j} \Delta u \Delta v f(V_j)$$

scaling coefficient of convolutional filters synapse counts

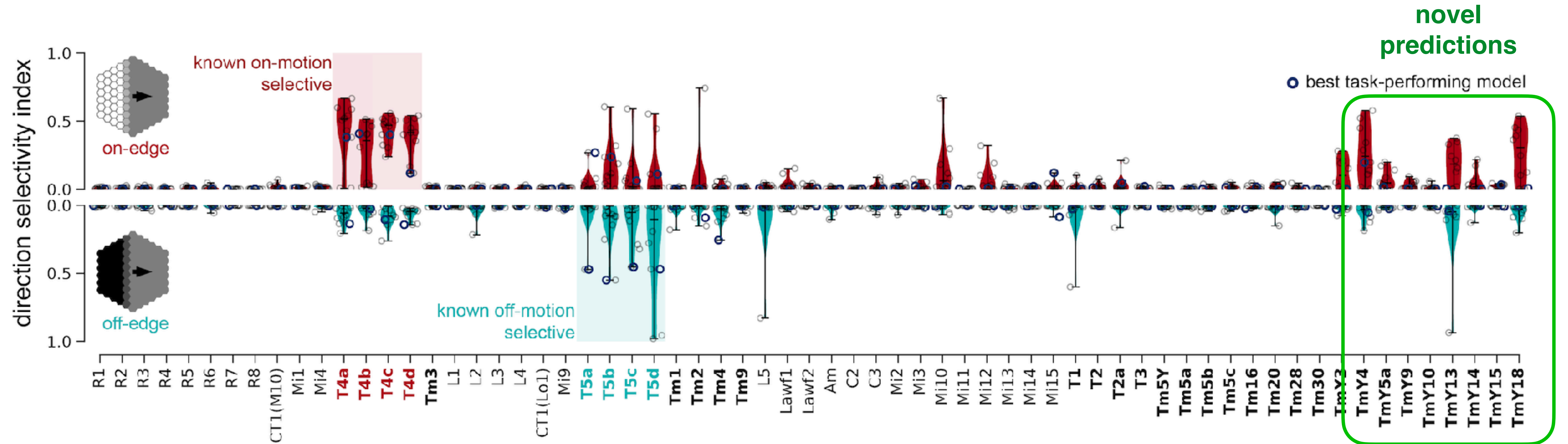
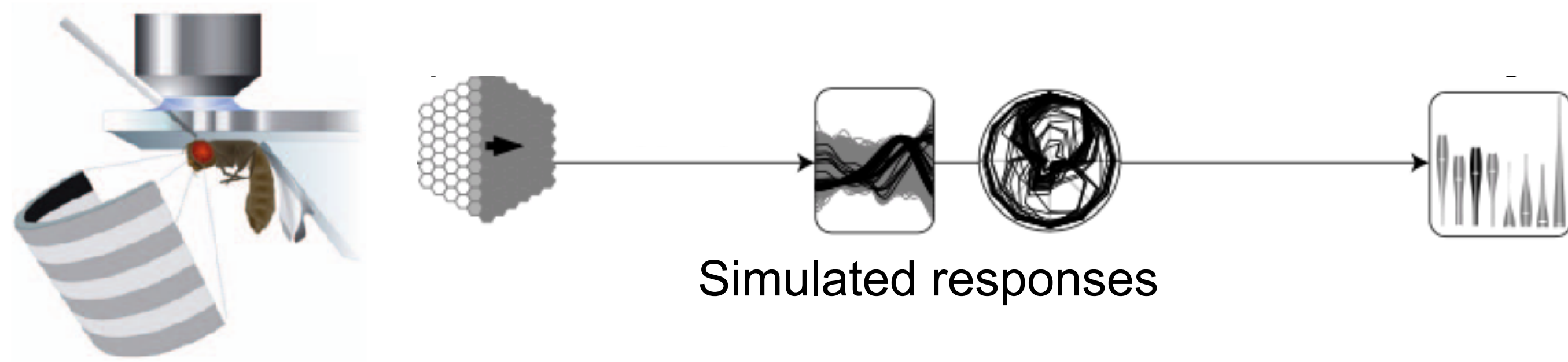
synapse signs 

In-silico neurophysiology on the model: Flash responses

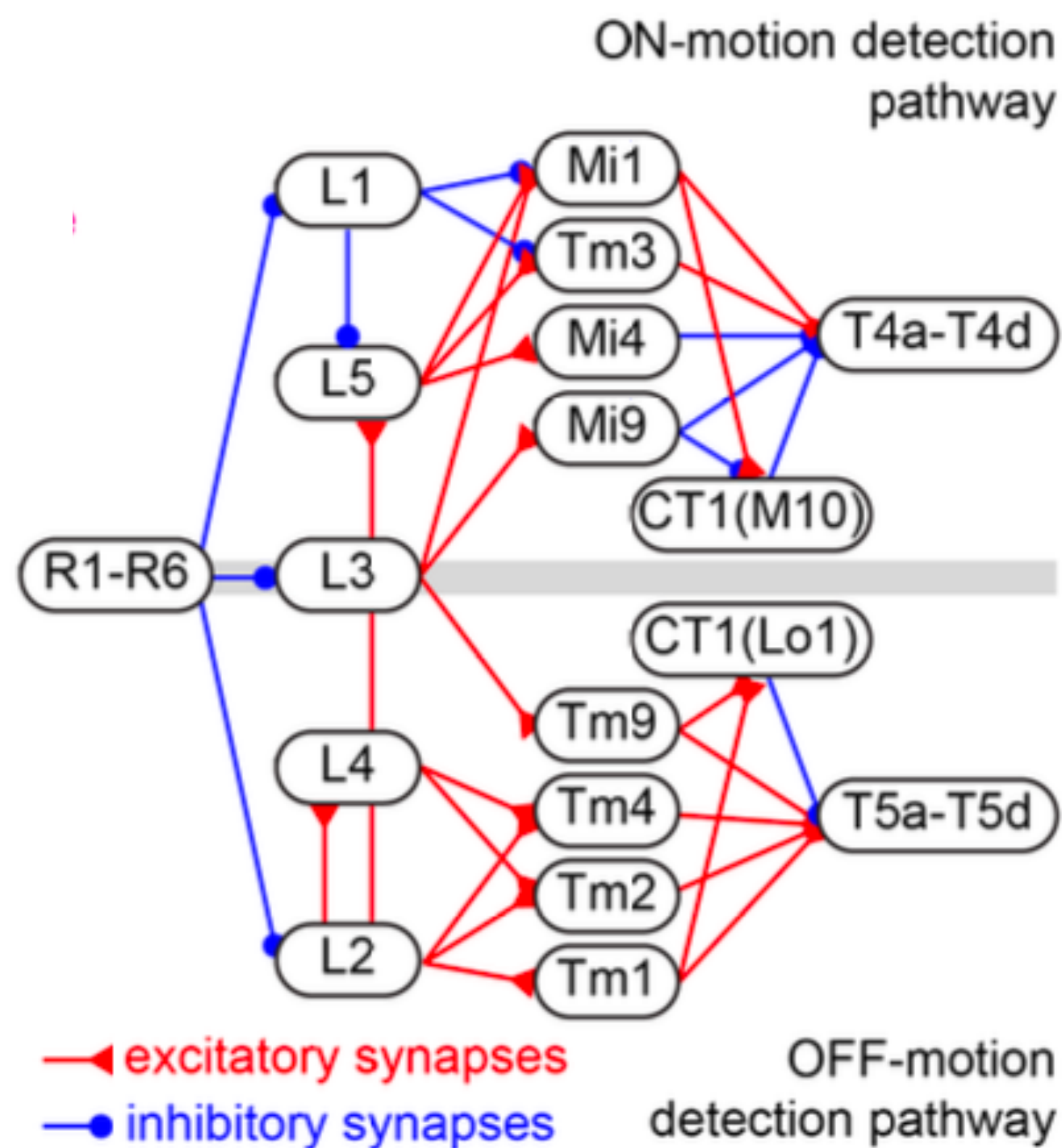


not yet
established

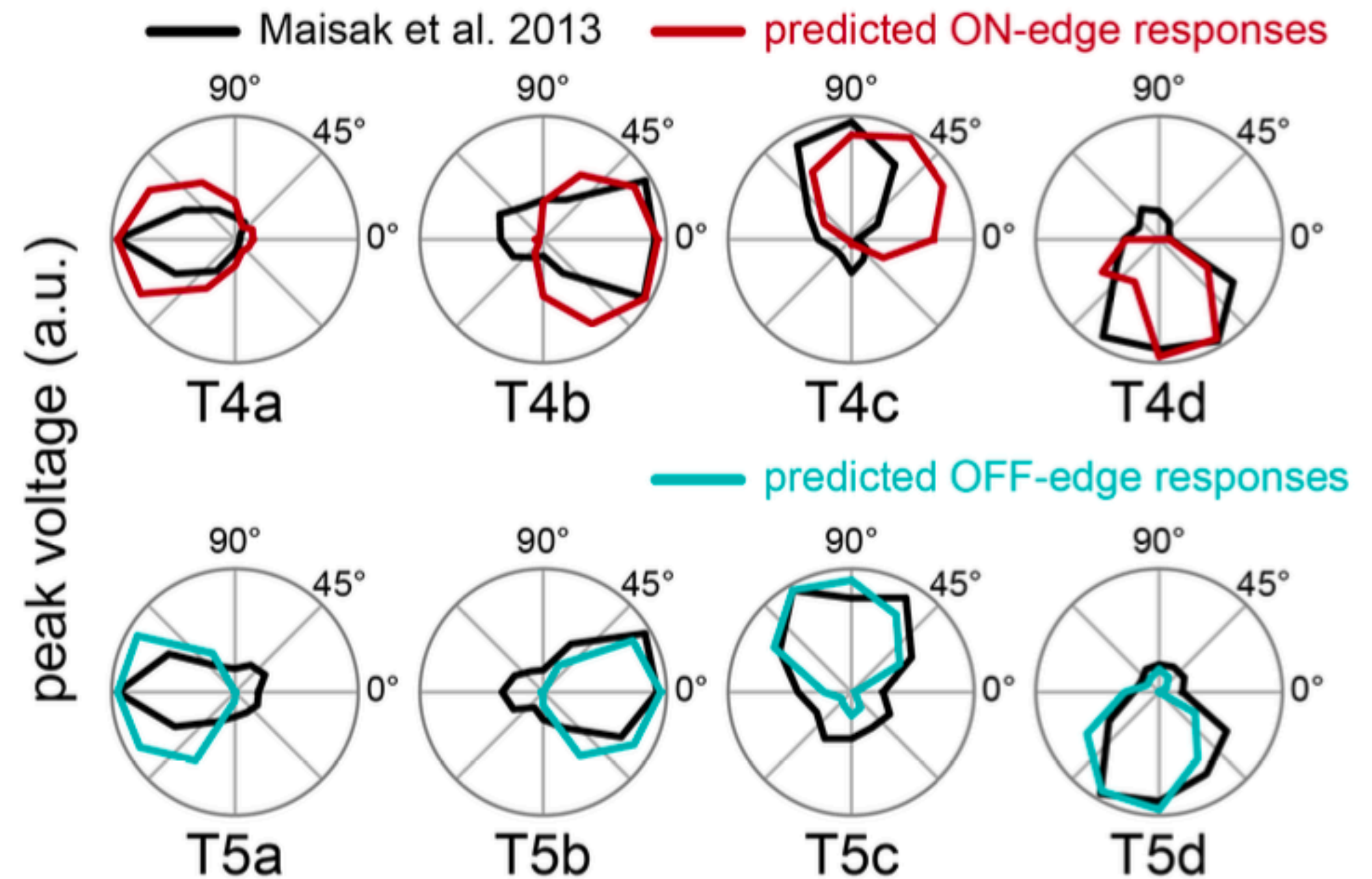
In-silico neurophysiology on the model: Direction selectivity



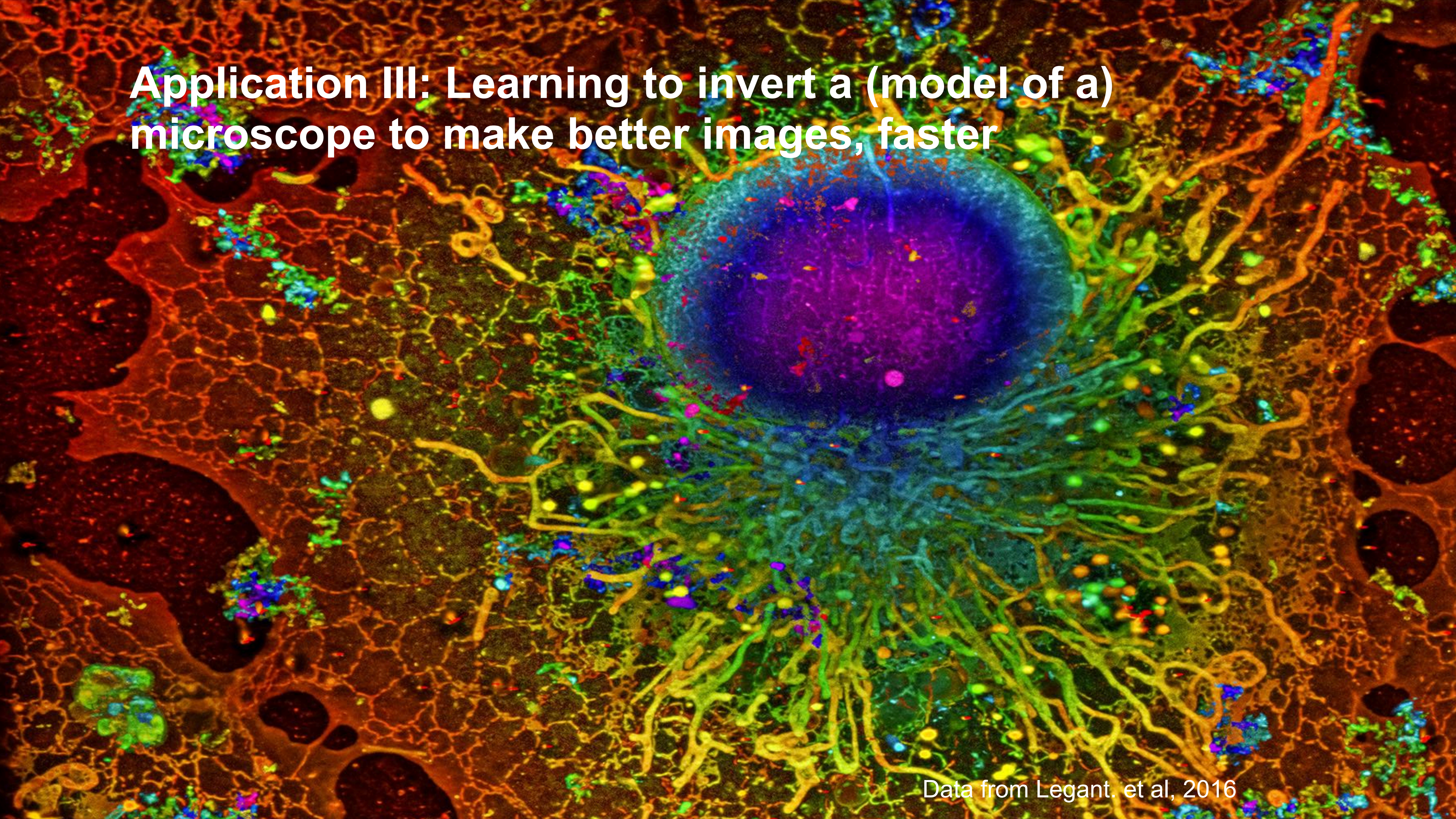
In-silico neurophysiology on the model: T4 and T5 cells



up
front



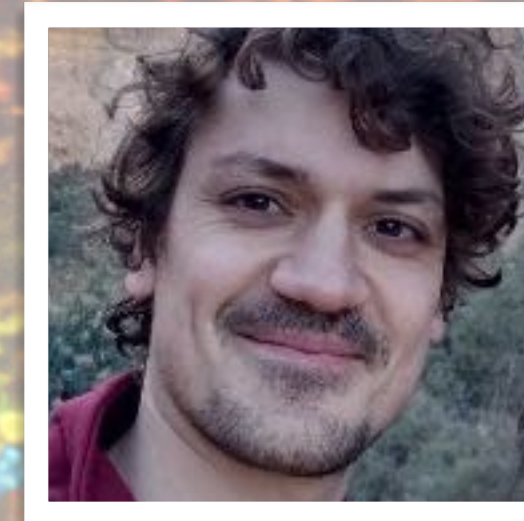
Application III: Learning to invert a (model of a) microscope to make better images, faster





Deep learning enables fast and dense single-molecule localization with high accuracy

Artur Speiser^{1,2,3,4,12}, Lucas-Raphael Müller^{5,6,12}, Philipp Hoess⁵, Ulf Matti⁵, Christopher J. Obara⁷, Wesley R. Legant^{8,9,10}, Anna Kreshuk⁵, Jakob H. Macke^{1,2,3,11,13}, Jonas Ries^{5,13} and Srinivas C. Turaga^{7,13}✉



A Speiser



L Müller

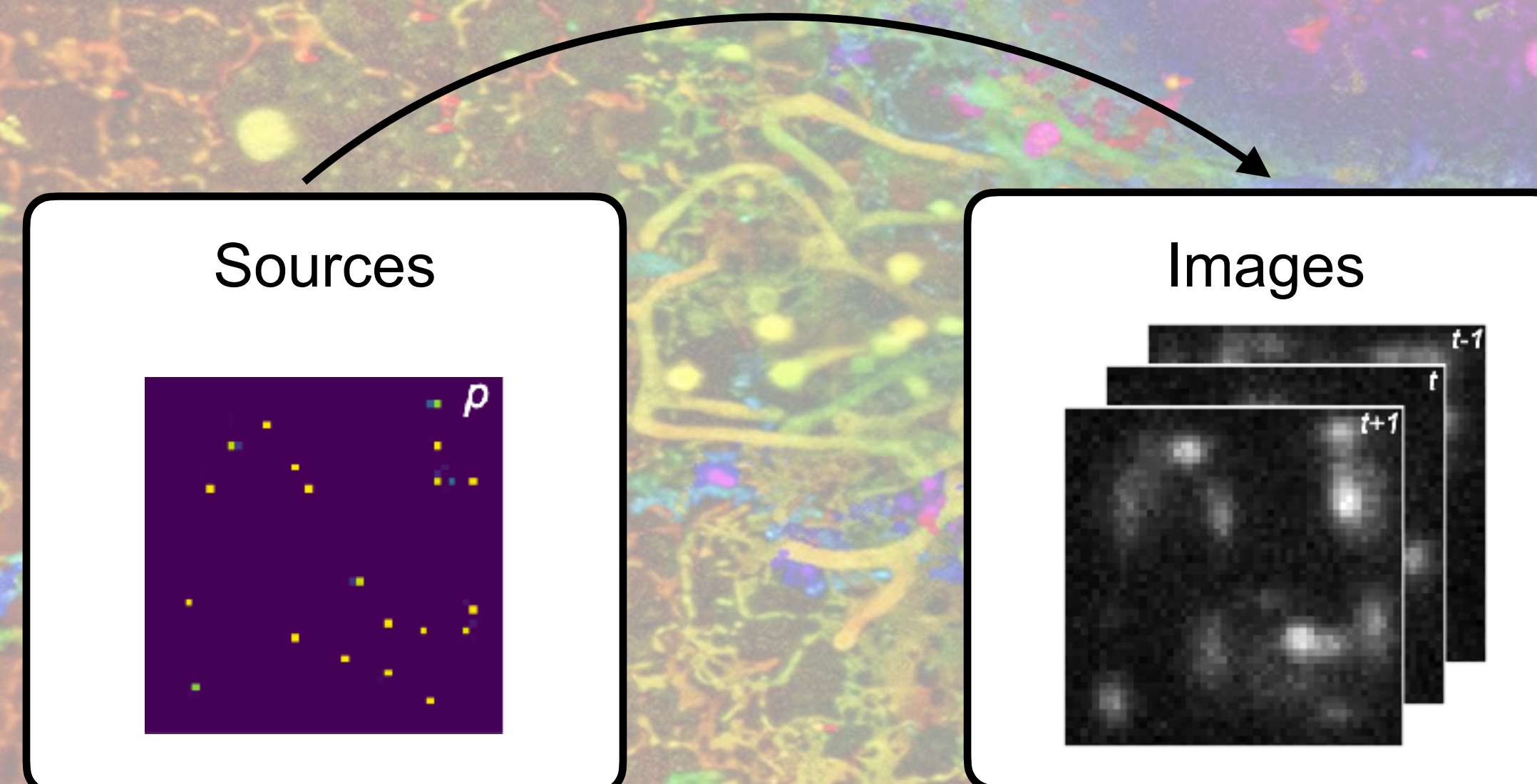


S Turaga



J Ries

Forward model of imaging process

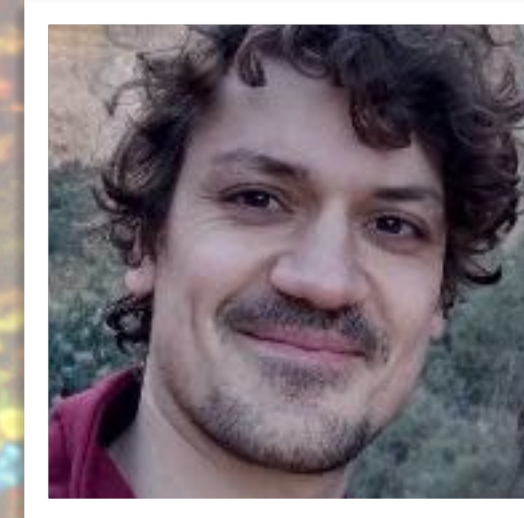


Inference network ('DECODE')



Deep learning enables fast and dense single-molecule localization with high accuracy

Artur Speiser^{1,2,3,4,12}, Lucas-Raphael Müller^{5,6,12}, Philipp Hoess⁵, Ulf Matti⁵, Christopher J. Obara⁷, Wesley R. Legant^{8,9,10}, Anna Kreshuk⁵, Jakob H. Macke^{1,2,3,11,13}, Jonas Ries^{5,13} and Srinivas C. Turaga^{7,13}✉



A Speiser



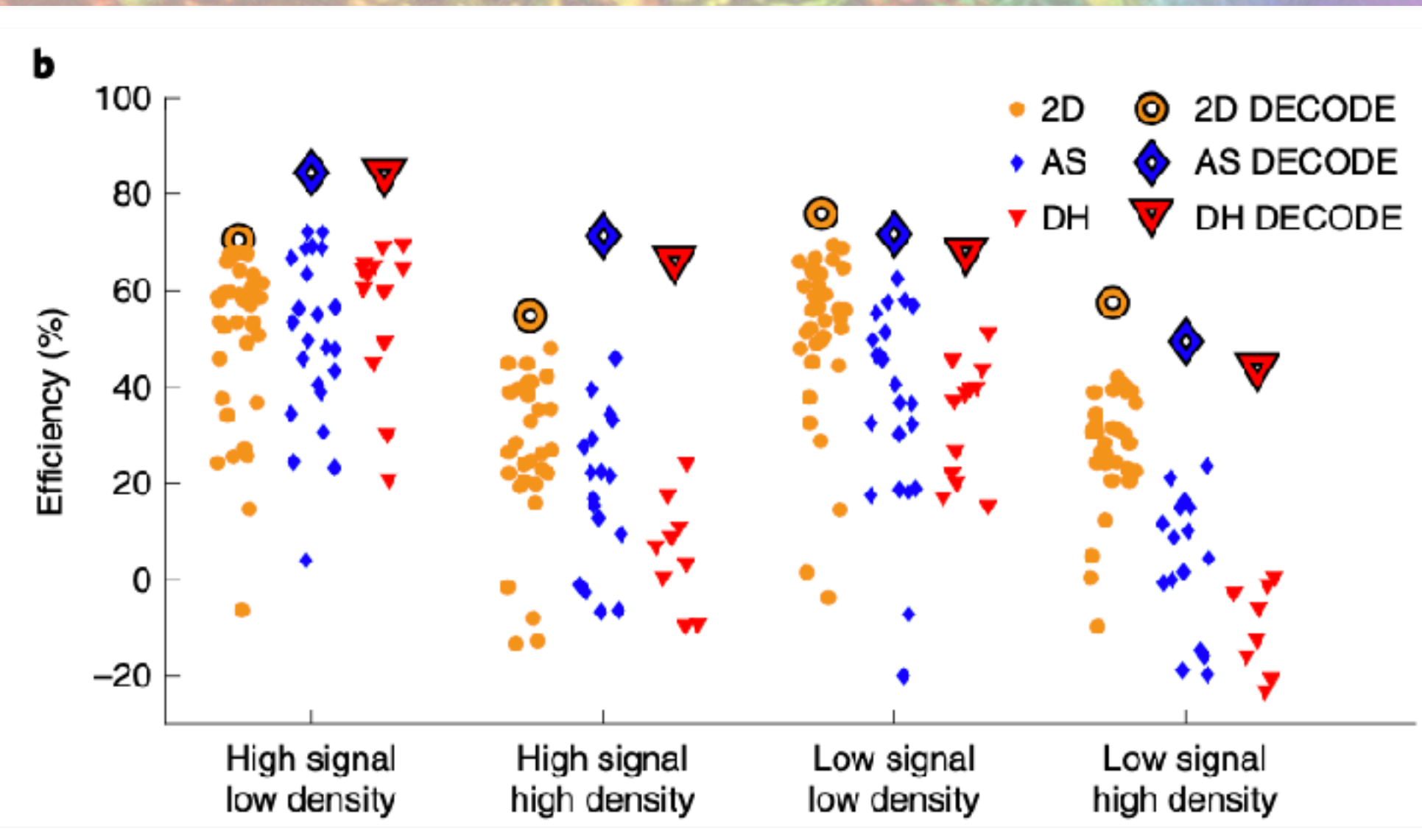
L Müller



S Turaga

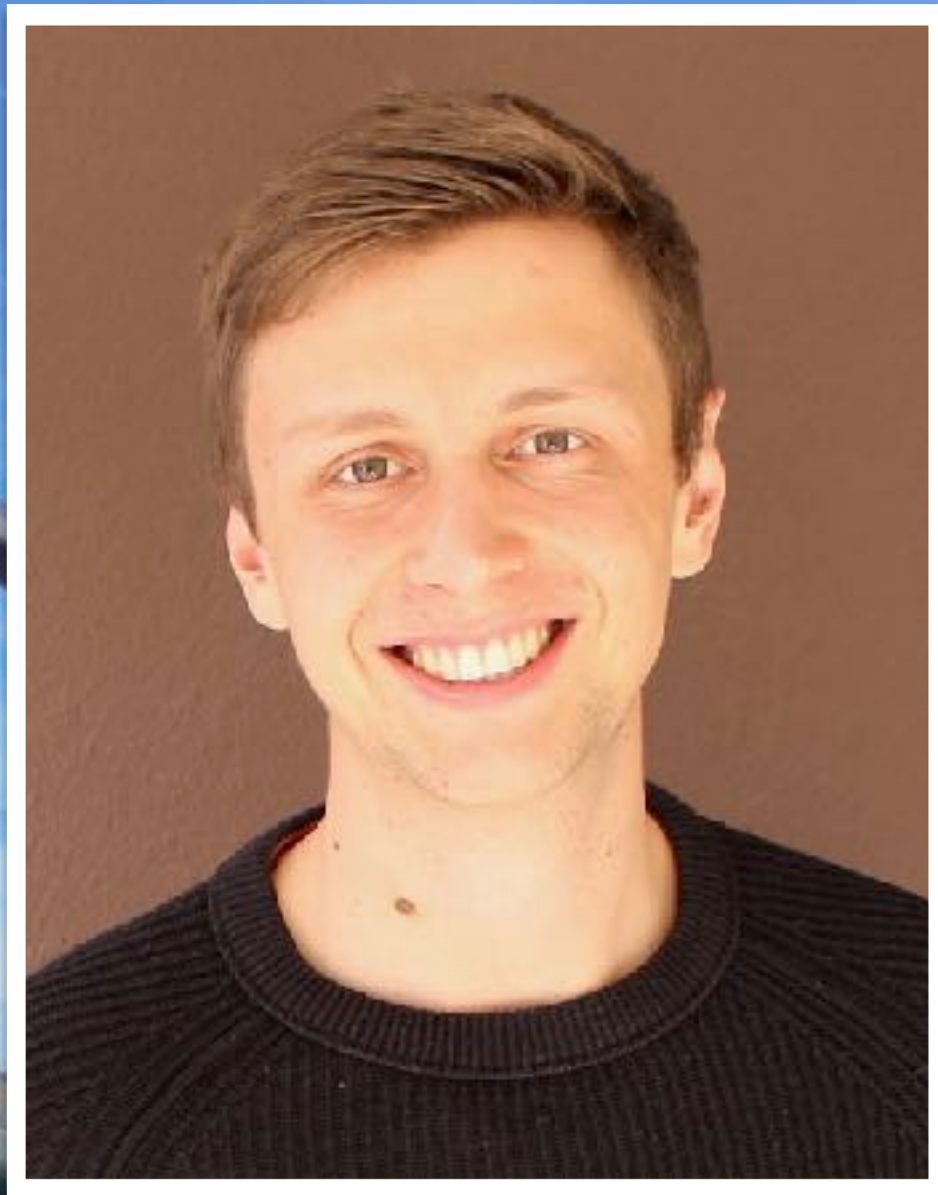


J Ries

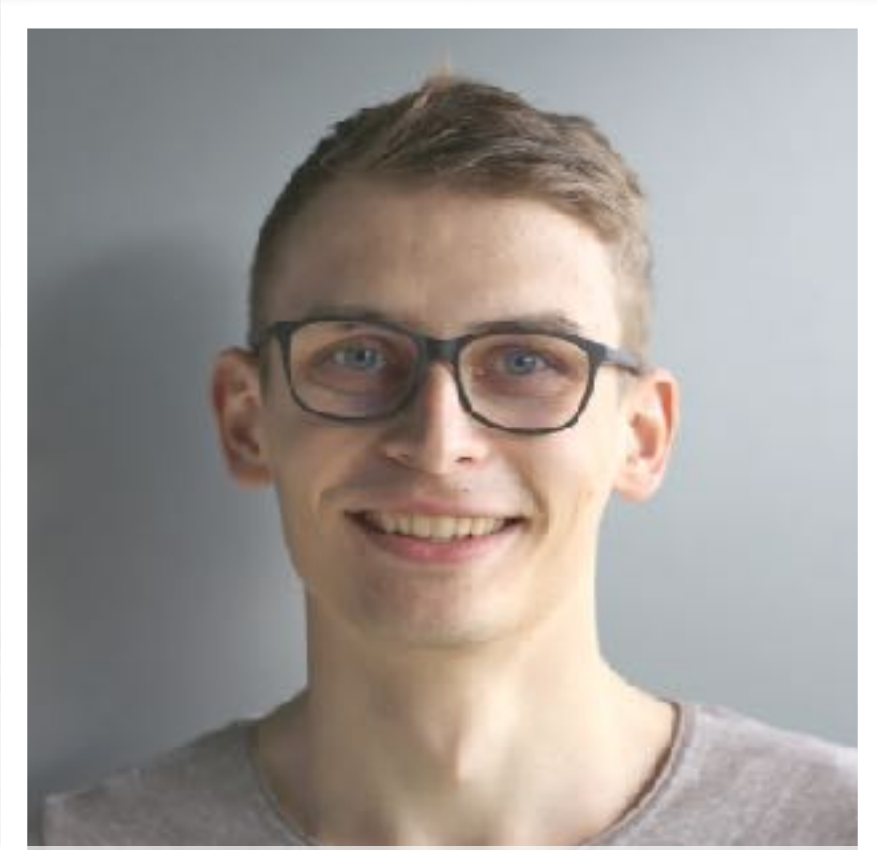


SMLM Challenge, Sage et al 2019

Problem: How to represent posterior distributions over an unknown number of points?



Michael Deistler



**Maximilian Dax
(MPI-IS, supervised by
Bernhard Schölkopf)**



Thanks to ...

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Max Dax
Franziska Gerken
Dr. Stefanie Liebe
Philipp von Bachmann



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16 October 2023 | Tübingen

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