



# DATAFLOW IN RUN3

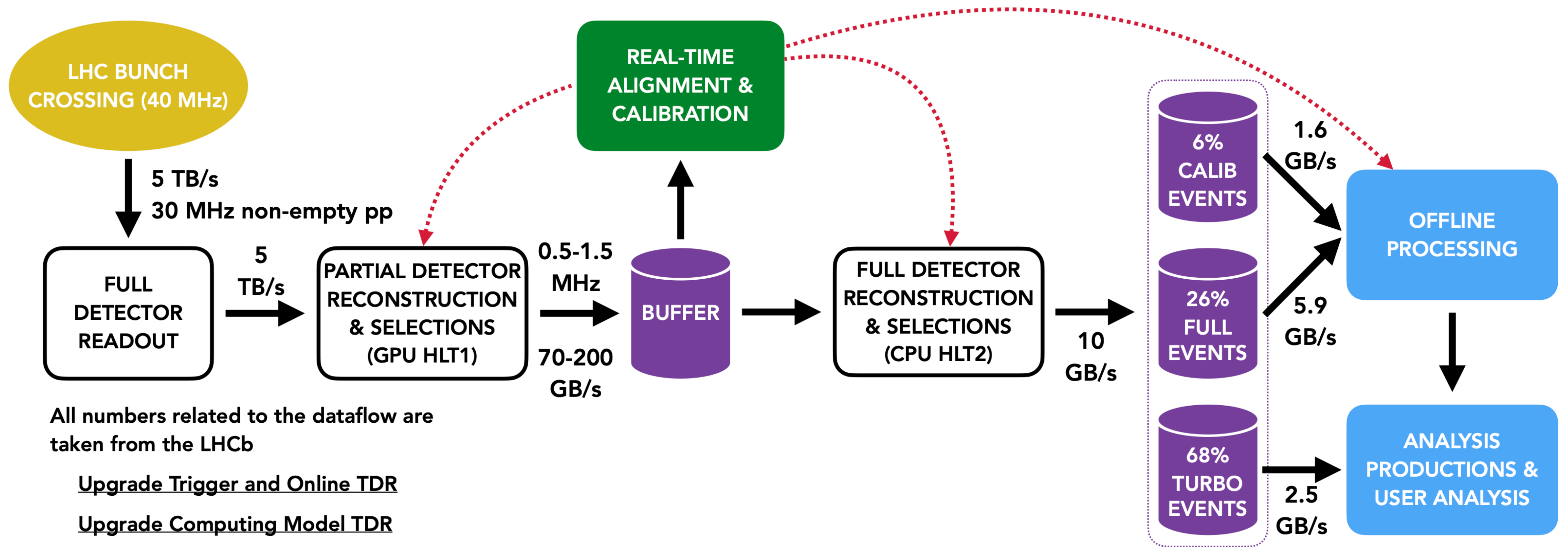
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*Renaud Amalric - LPNHE (Paris)*

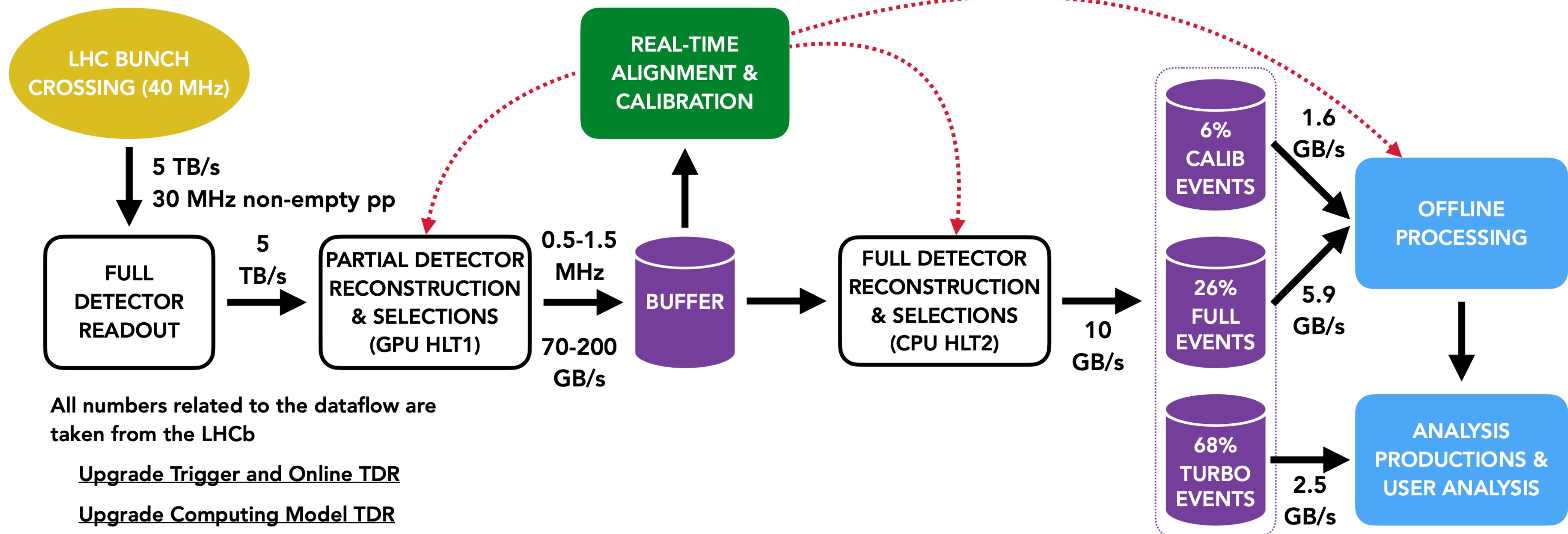
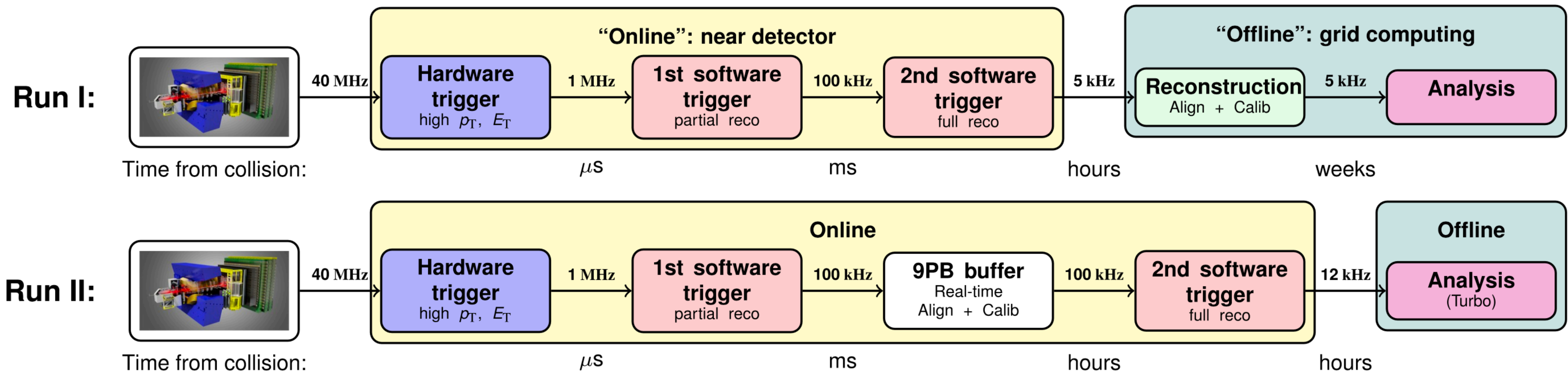
*01/12/2022*



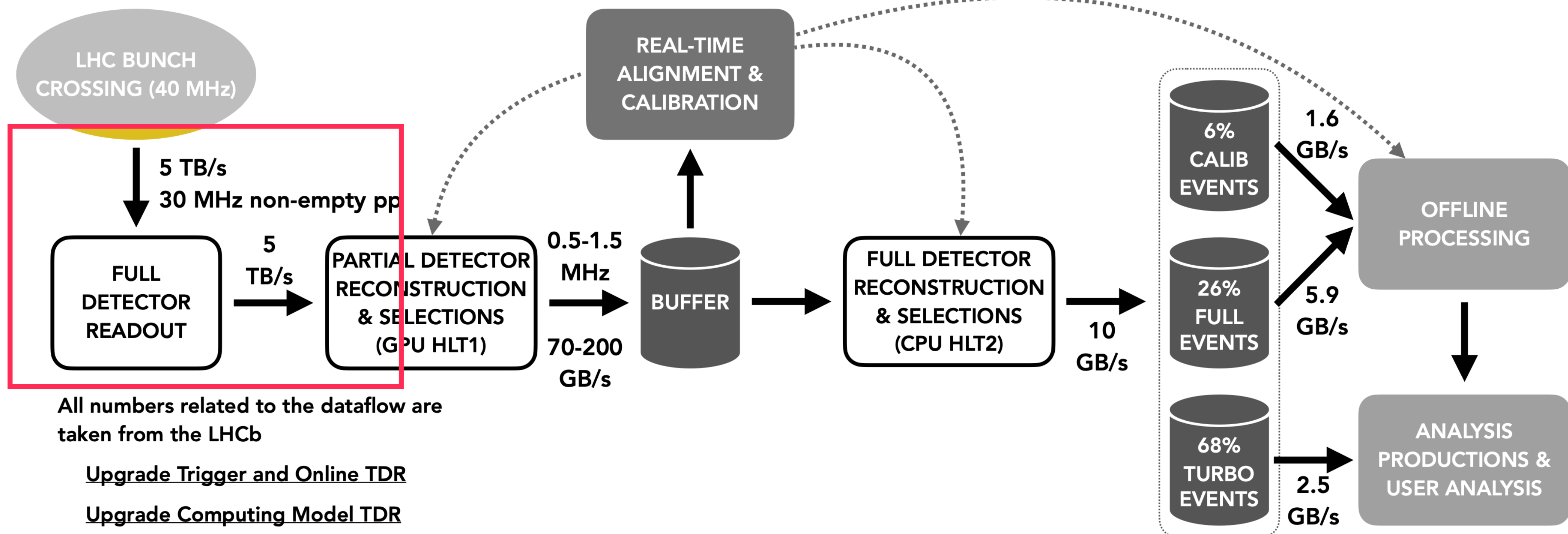
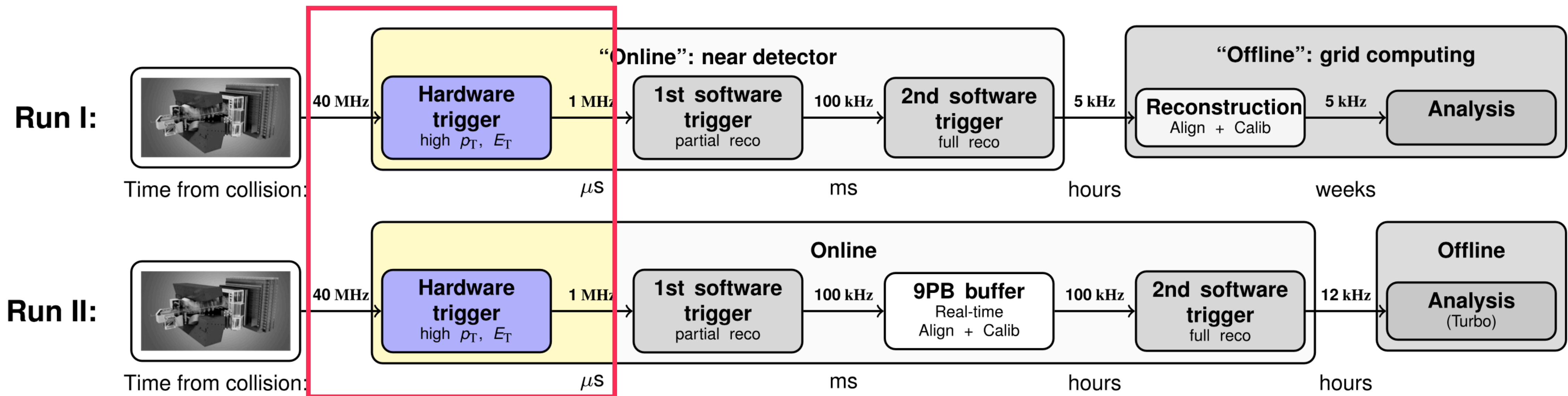
# DATAFLOW IN RUN3



# WHAT CHANGED ?

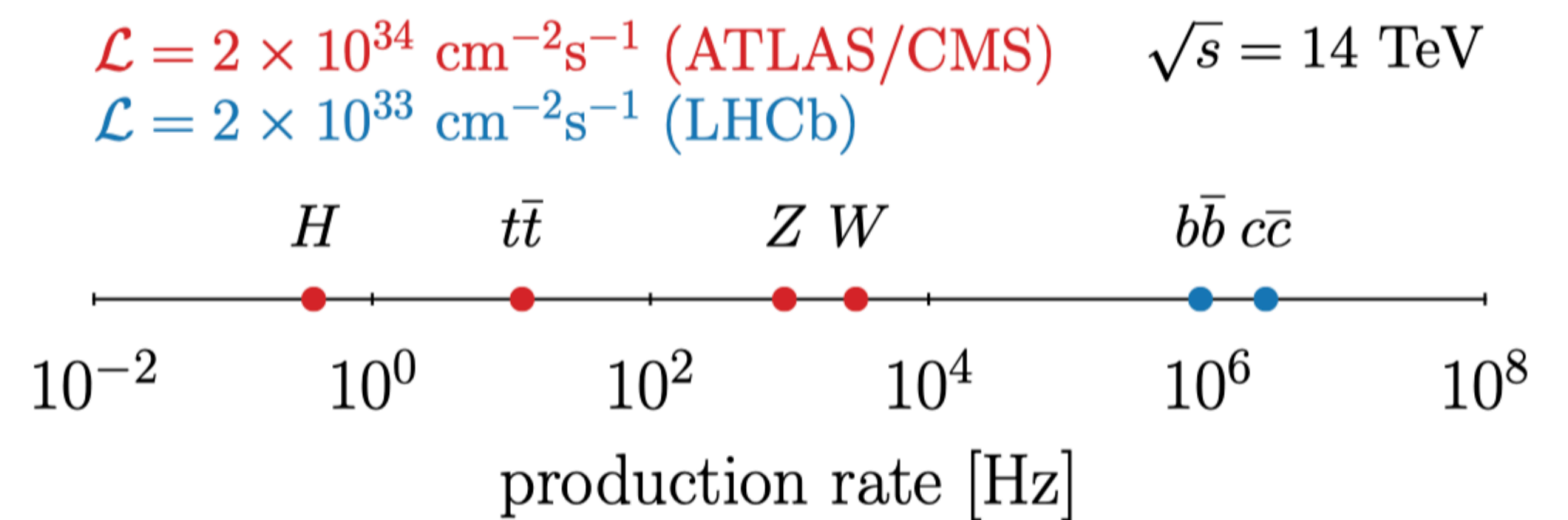


# NO MORE HARDWARE TRIGGER



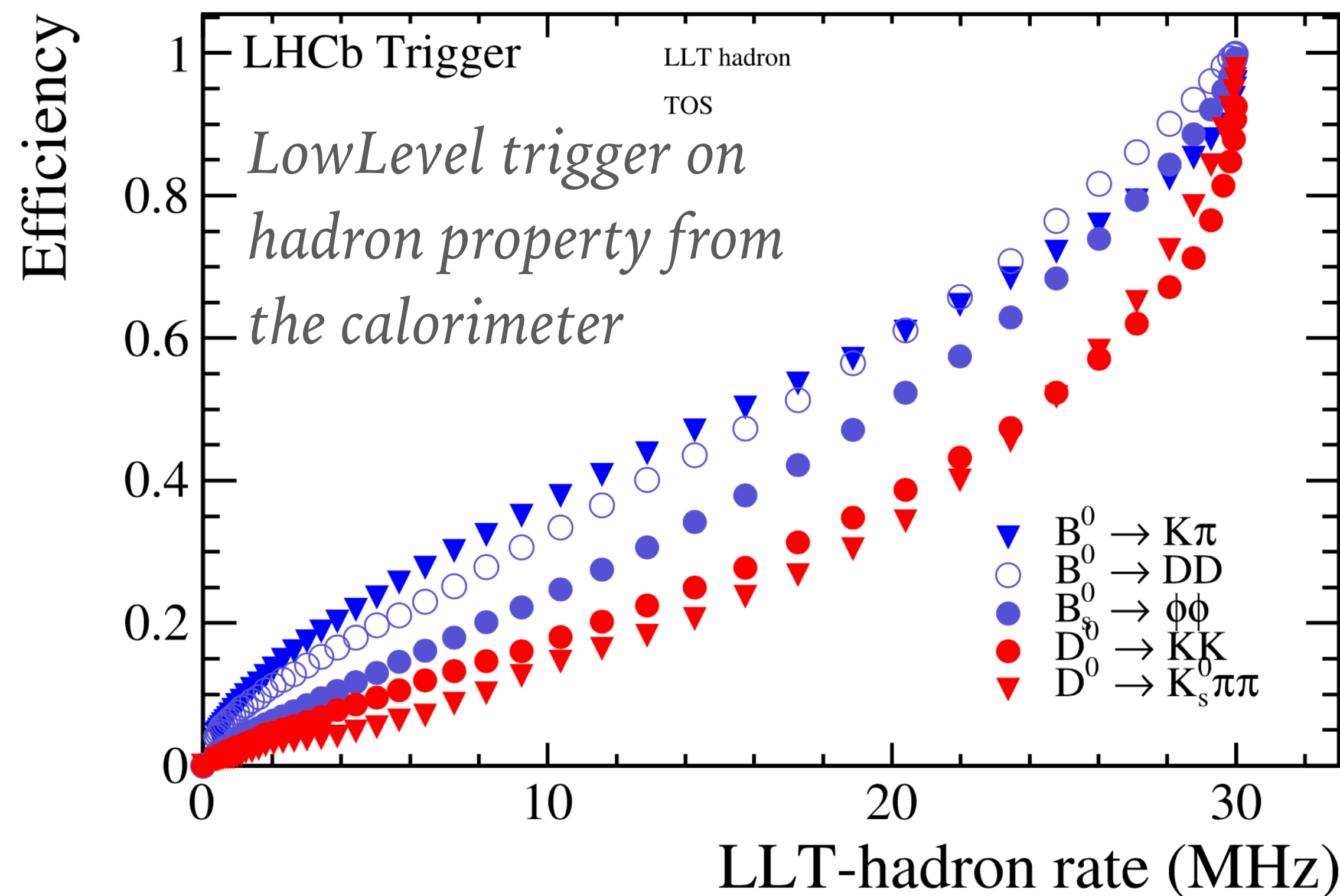
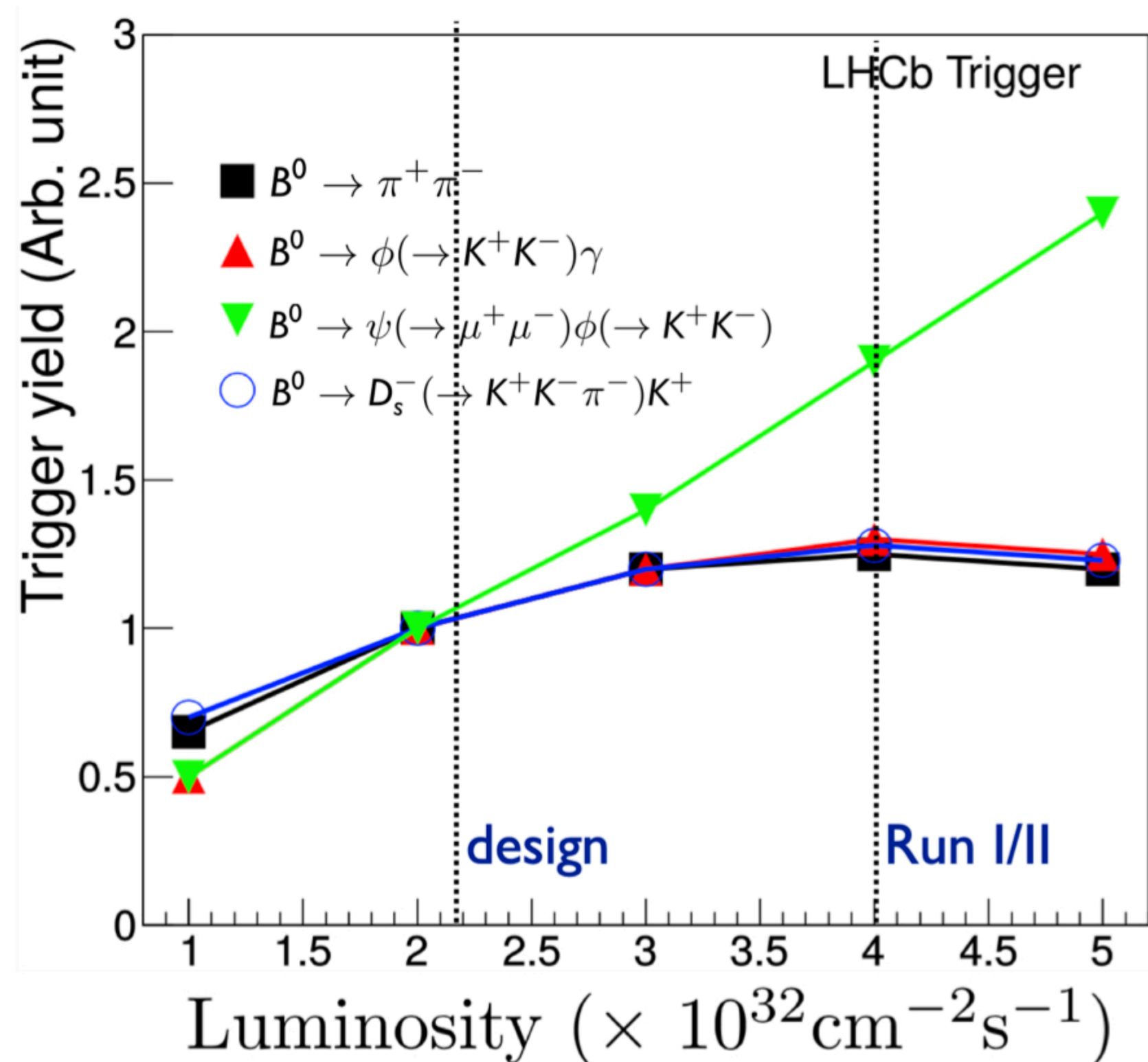
# QUICK WORD ON TRIGGERS

- Gather the information from all the sub-detectors
- Issue : we produce much more information than what we can actually store to disk to be analyse later on
- Need triggers to select in real time what you actually want to store and do this as efficiently as possible
- 2 possibilities
  - Hardware triggers
  - Software triggers



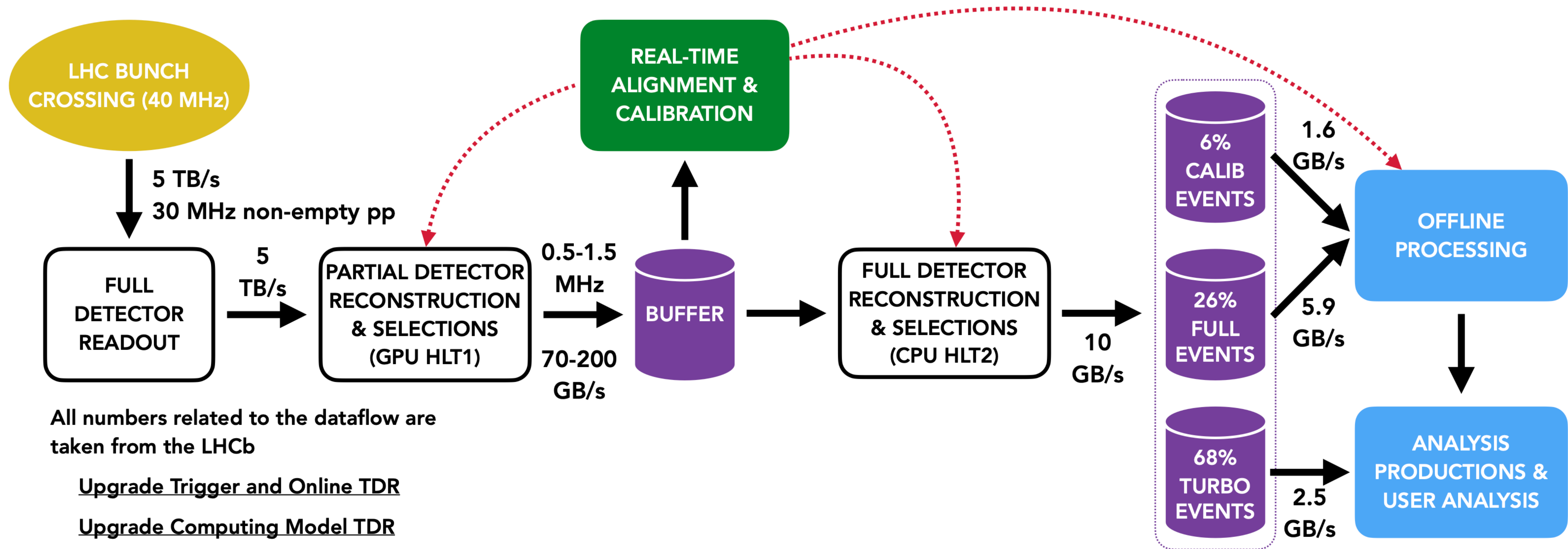
# WHY NO MORE HARDWARE TRIGGERS ?

- Trigger for many hadronic channels saturated already at Run 1–2 luminosity
- Cannot effectively trigger on heavy flavour using hardware signatures

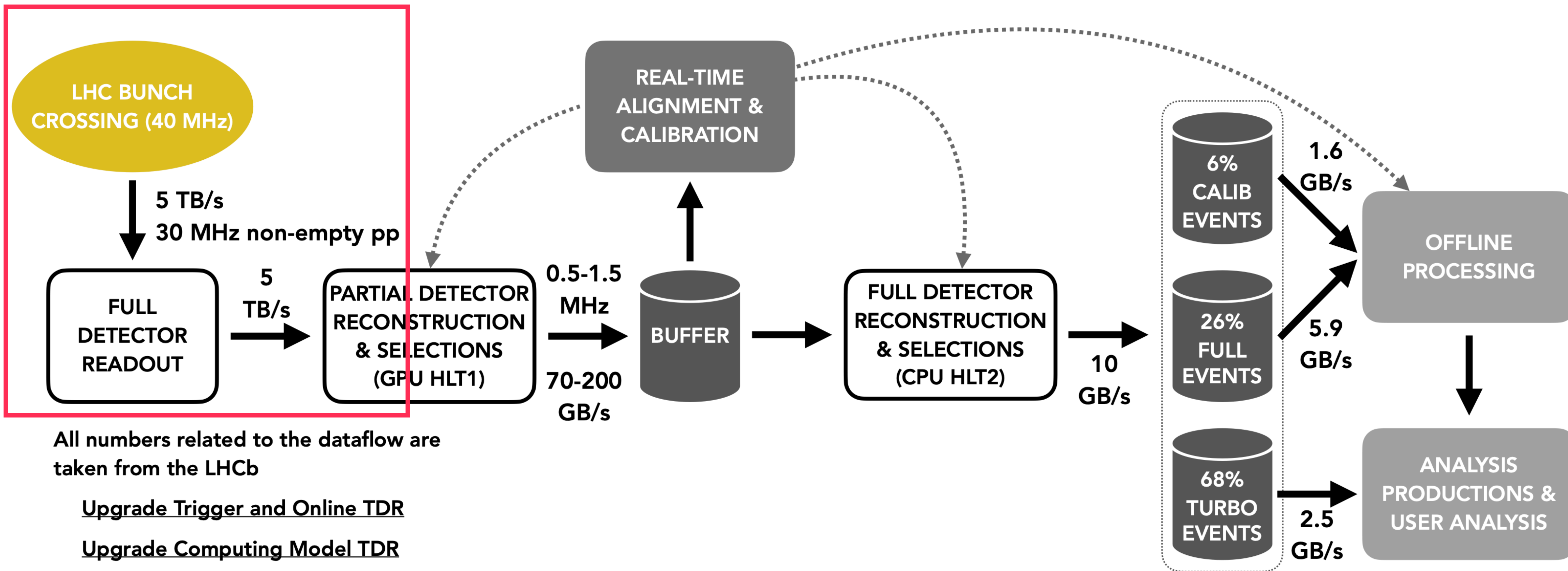


⇒ Fully software triggers

# DATAFLOW IN RUN3



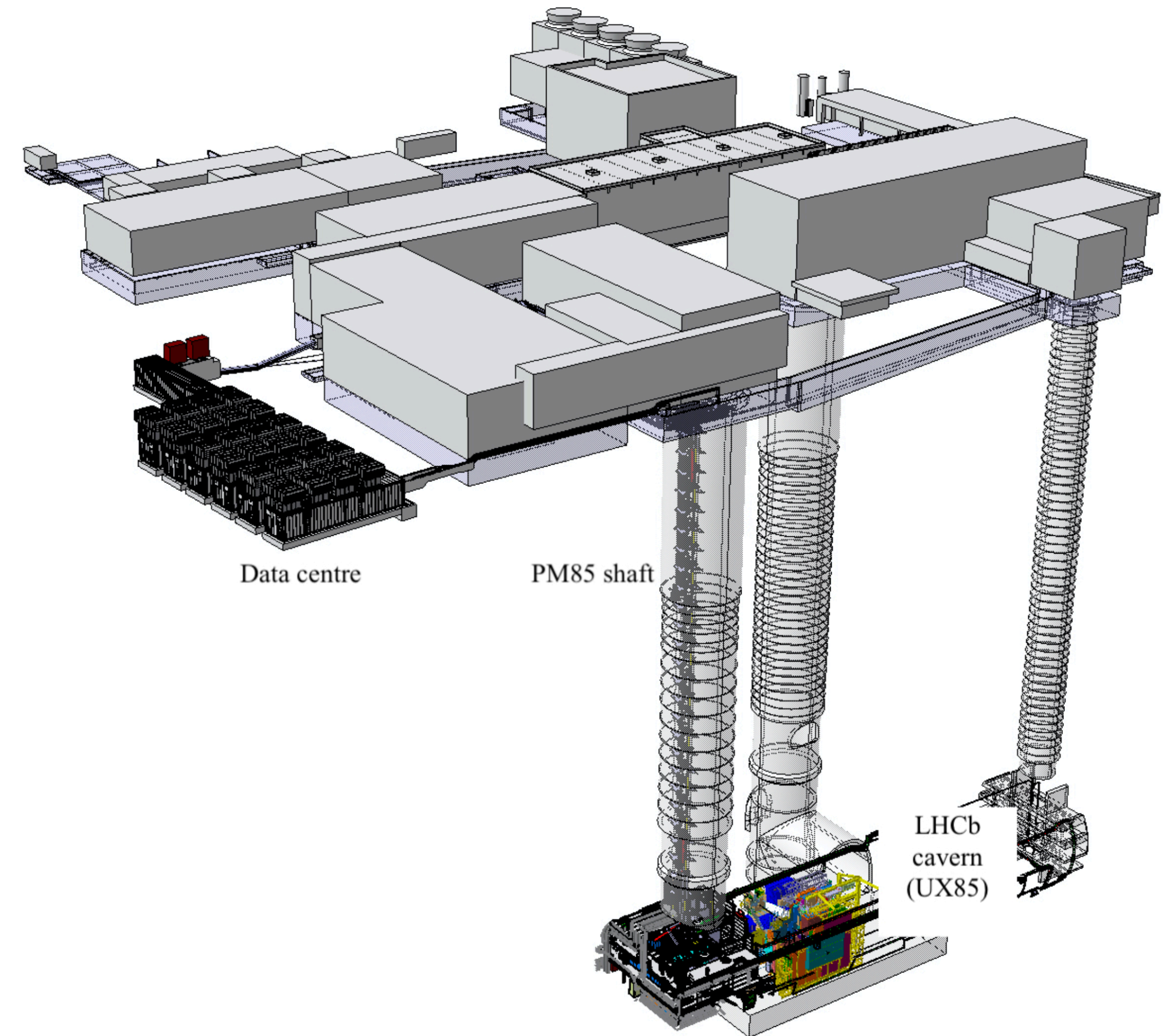
# FROM THE SUB-DETECTORS TO THE COMPUTINGS FARMS





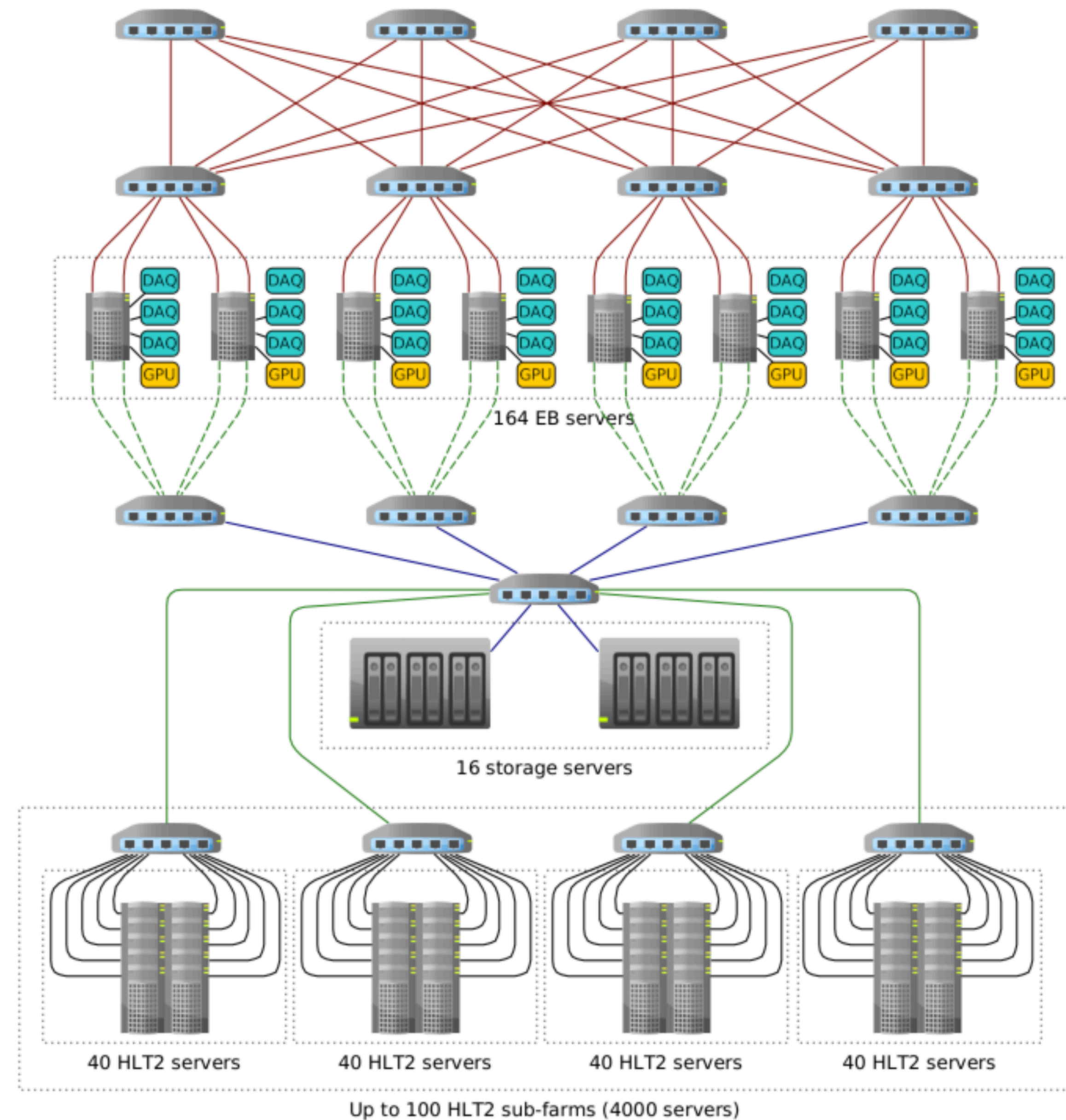
# FROM THE SUB-DETECTORS TO THE COMPUTINGS FARMS

- New architecture to transmit data collected from every bunch crossing all the way to the event-building computing farms.
- The sub-detectors are connected to the data center through long-distance ( $\sim 250\text{m}$ ) optical fibres installed in the PM85 shaft.

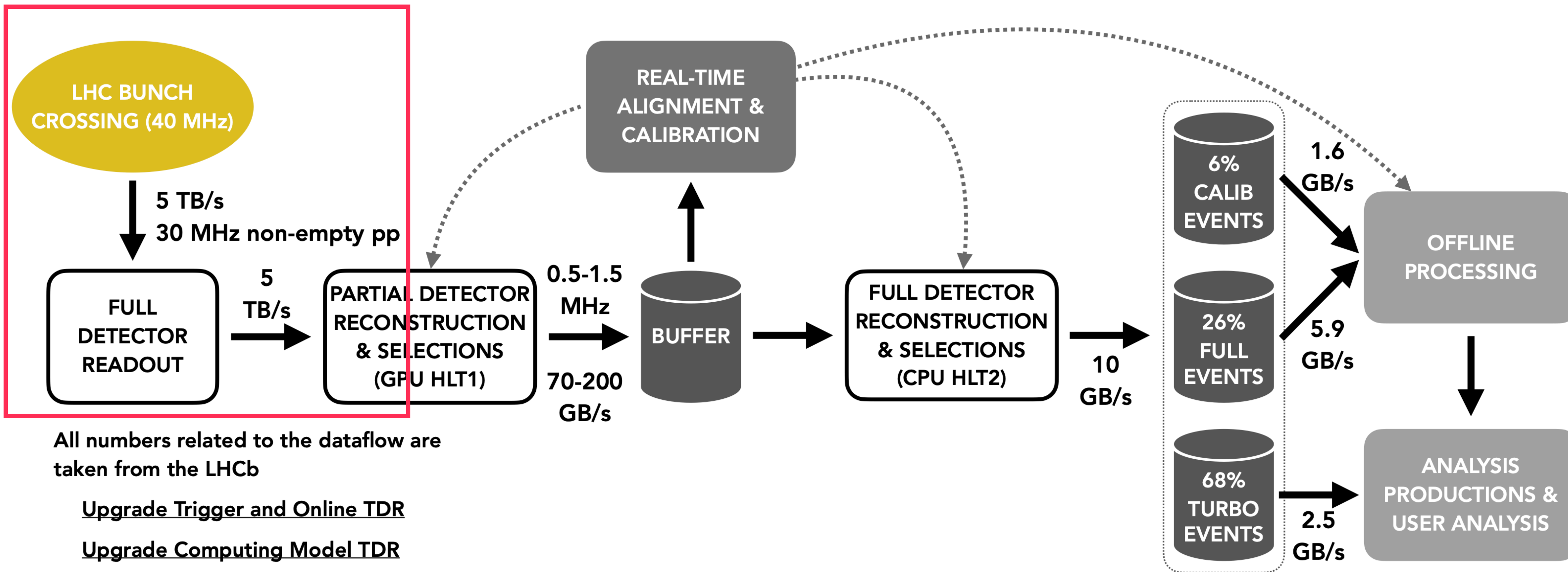


# EVENT BUILDING

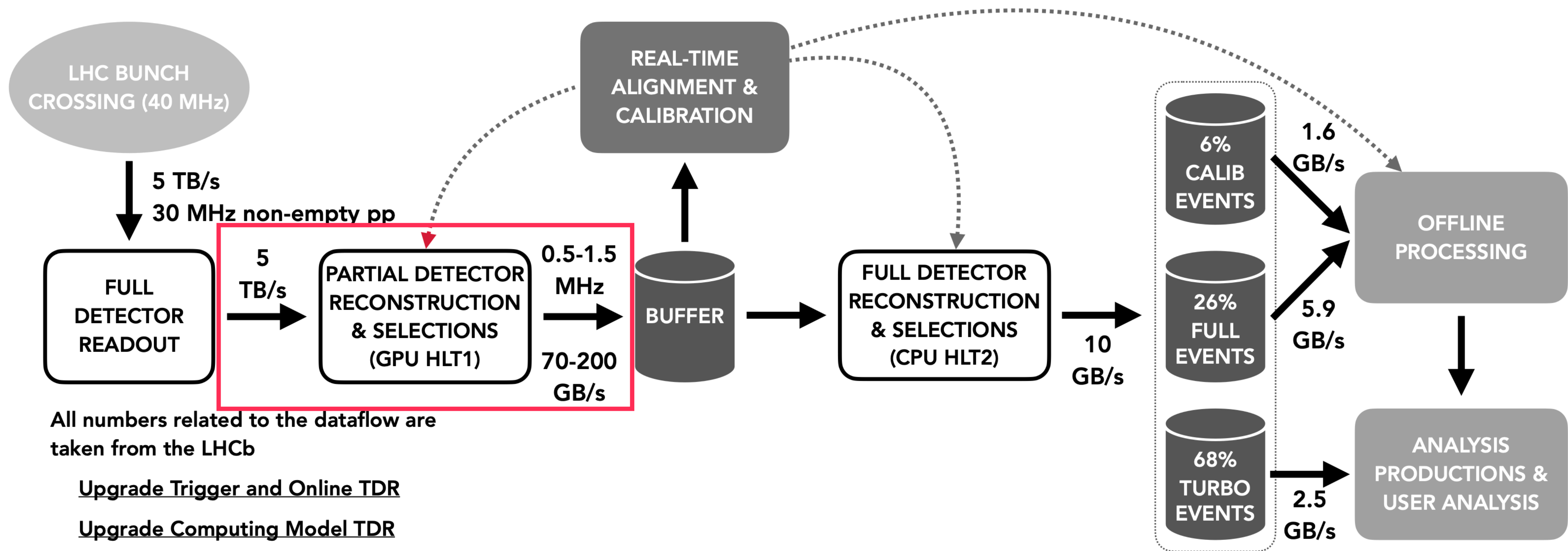
- To perform the selection, the full-software LHCb trigger requires the complete event information from all the sub-detectors.
- Detector's data received by  $\sim 500$  FPGAs
- Regrouped to the same destination - to one server for event-building.
- Event Building : combining the raw data to form single cohesive events
- Event builder farm :  $\sim 170$  servers (with 3 FPGAs each)
- Adding GPUs on those servers to apply the first step of selections  $\rightarrow$  HLT1 and then send the data downstream



# FROM THE SUB-DETECTORS TO THE COMPUTINGS FARMS



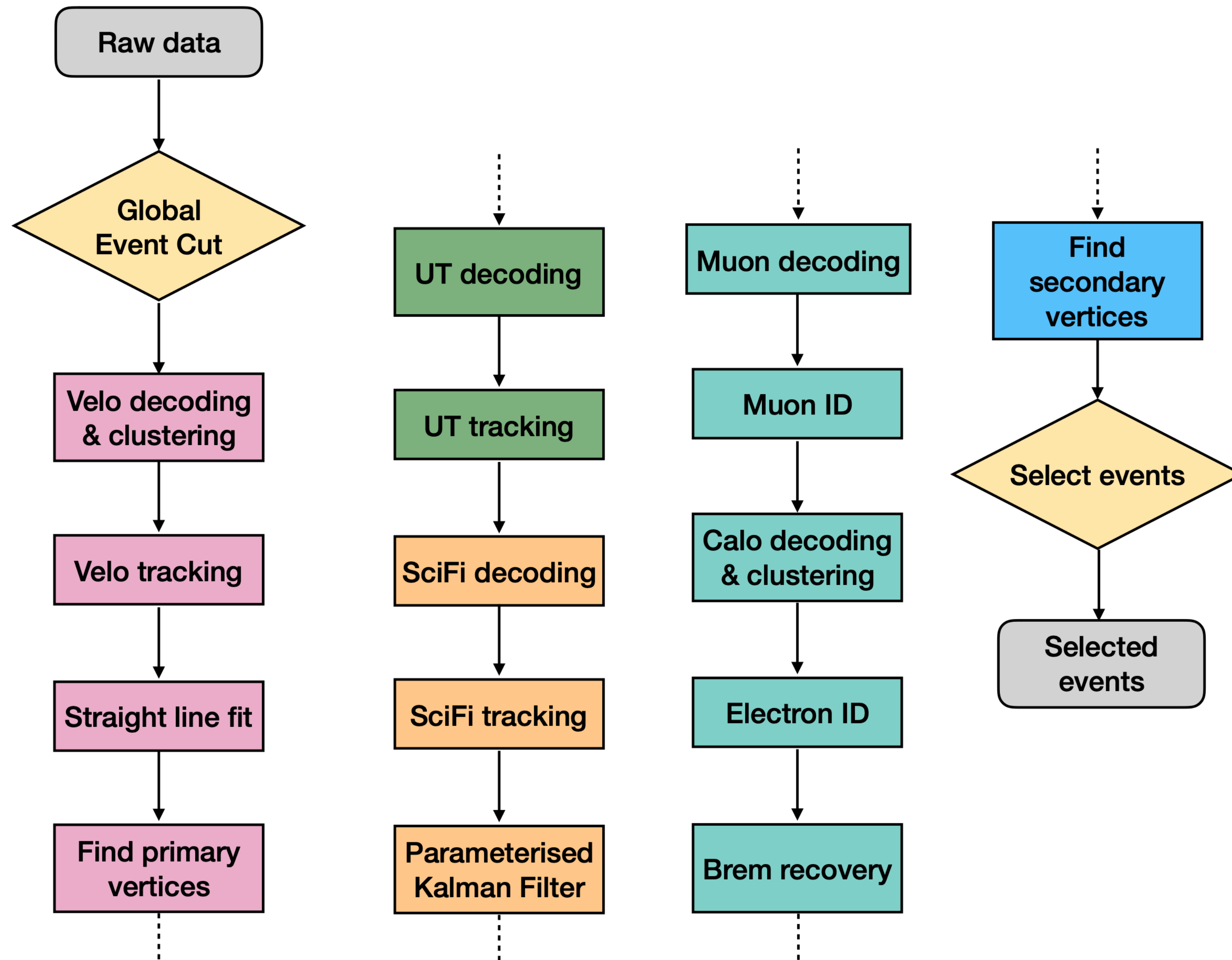
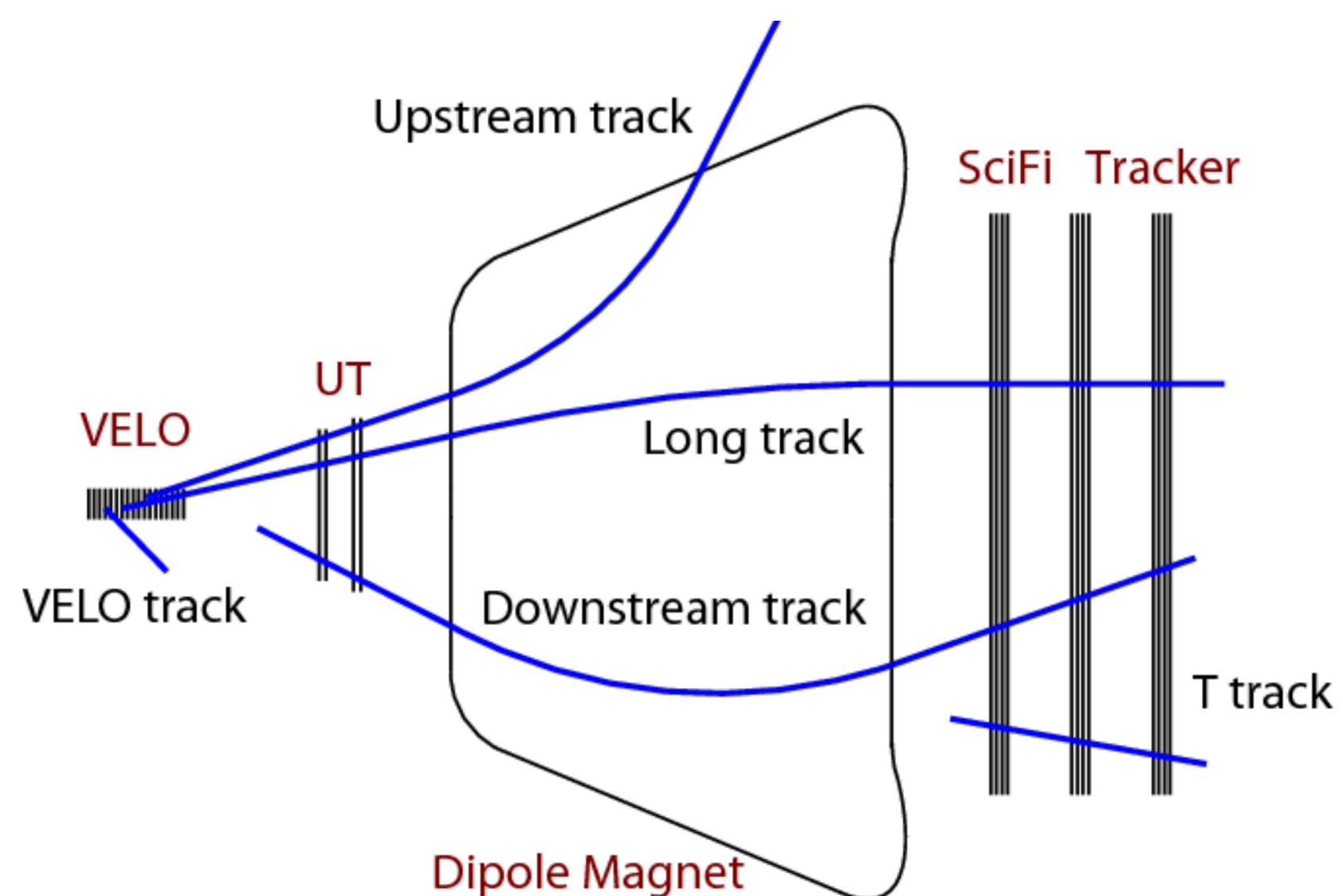
# HIGH LEVEL TRIGGER 1



- Fast and partial reconstruction
  - Charged particle track and vertex reconstruction
  - Electron and muon identification
  
- Up to ~500 GPUs (3 slots available per EB servers)
  - Manageable amount of algorithms
  - Parallel tasks
  - No detailed knowledge of magnetic field & detector required
  
- Software : Allen project

# HLT1 SEQUENCE

→ What do the GPUs have to do ?

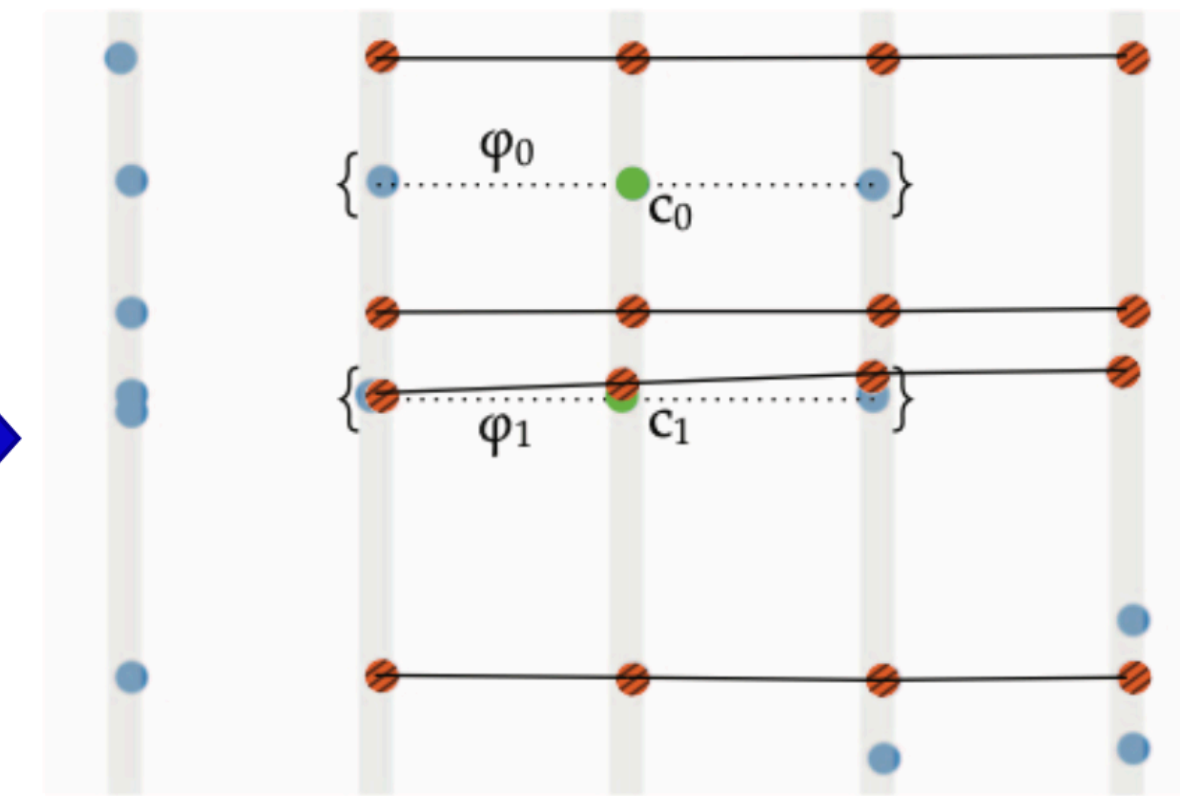
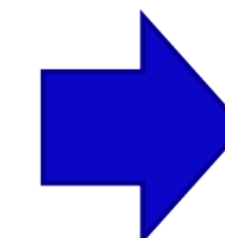
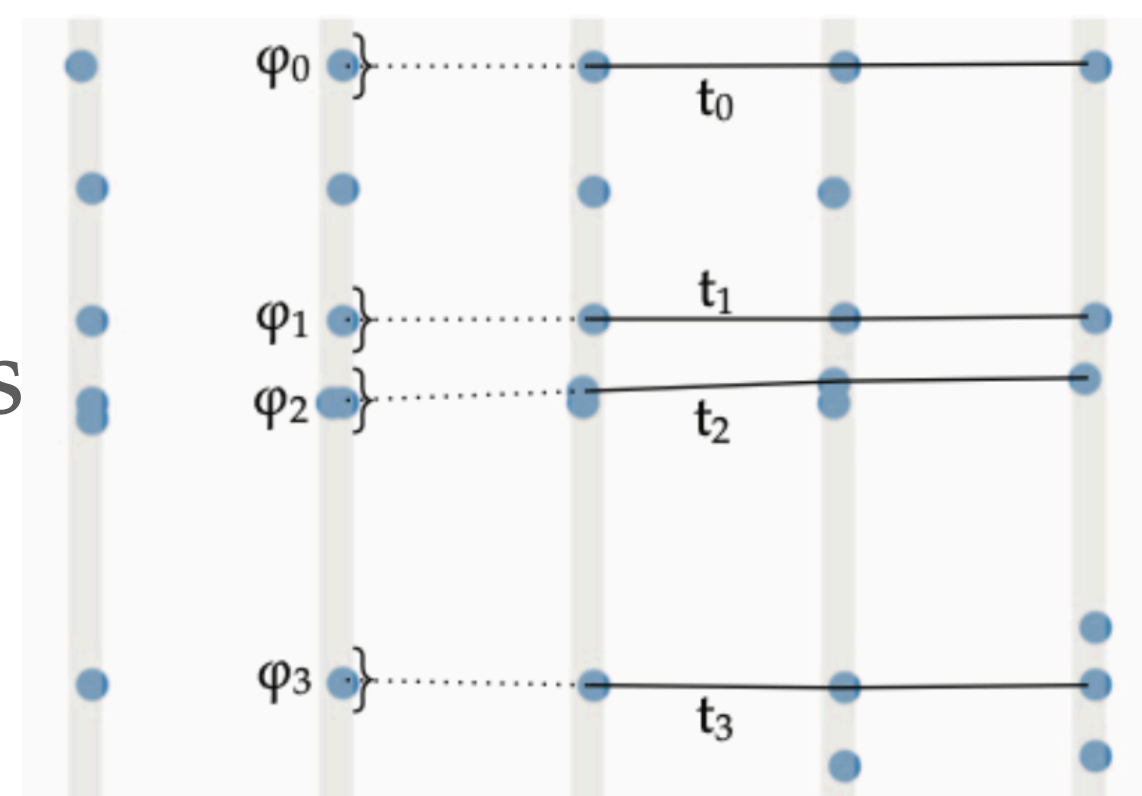


# HLT1 SEQUENCE - VELO TRACKING AND PV FINDING

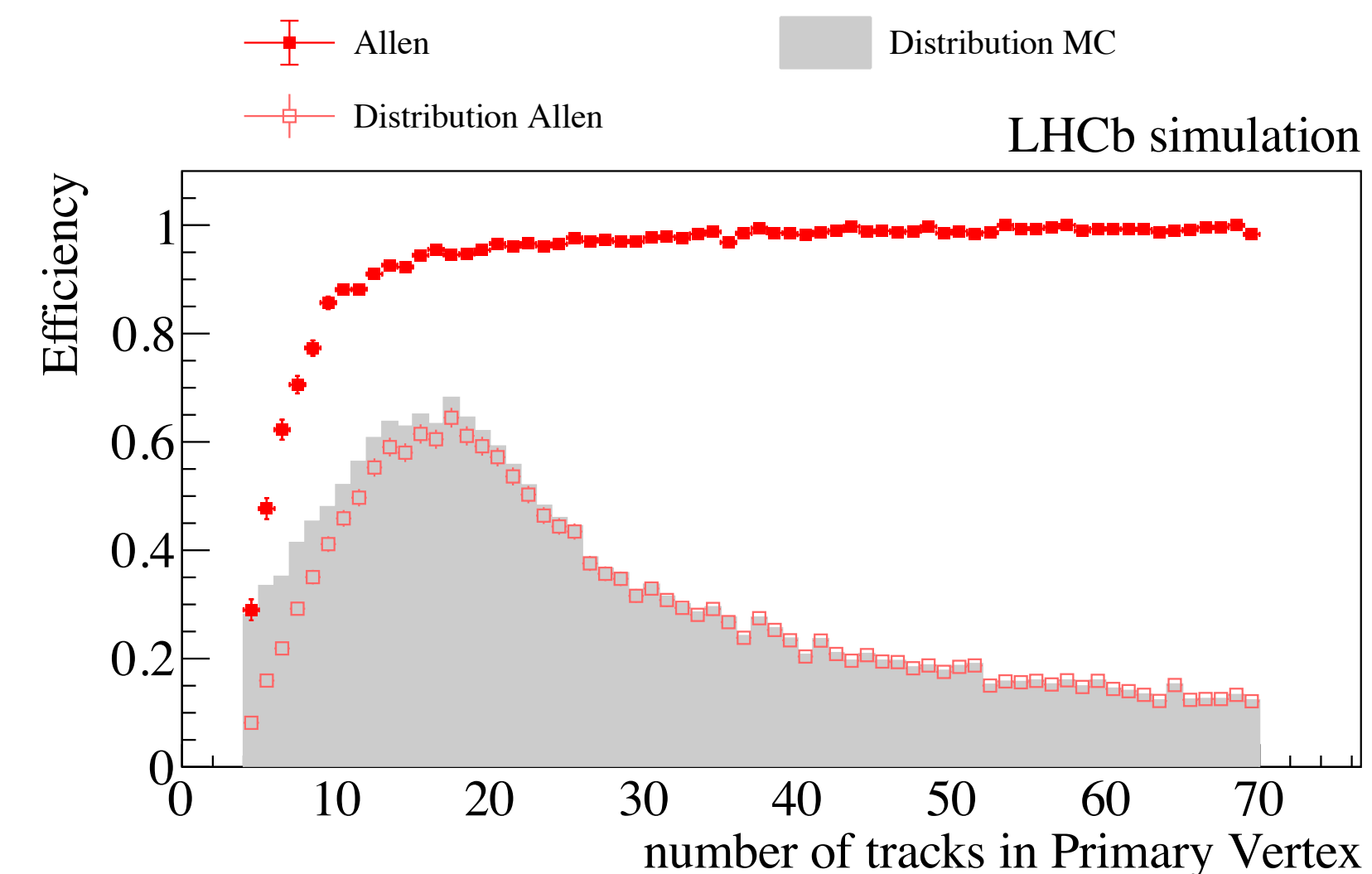
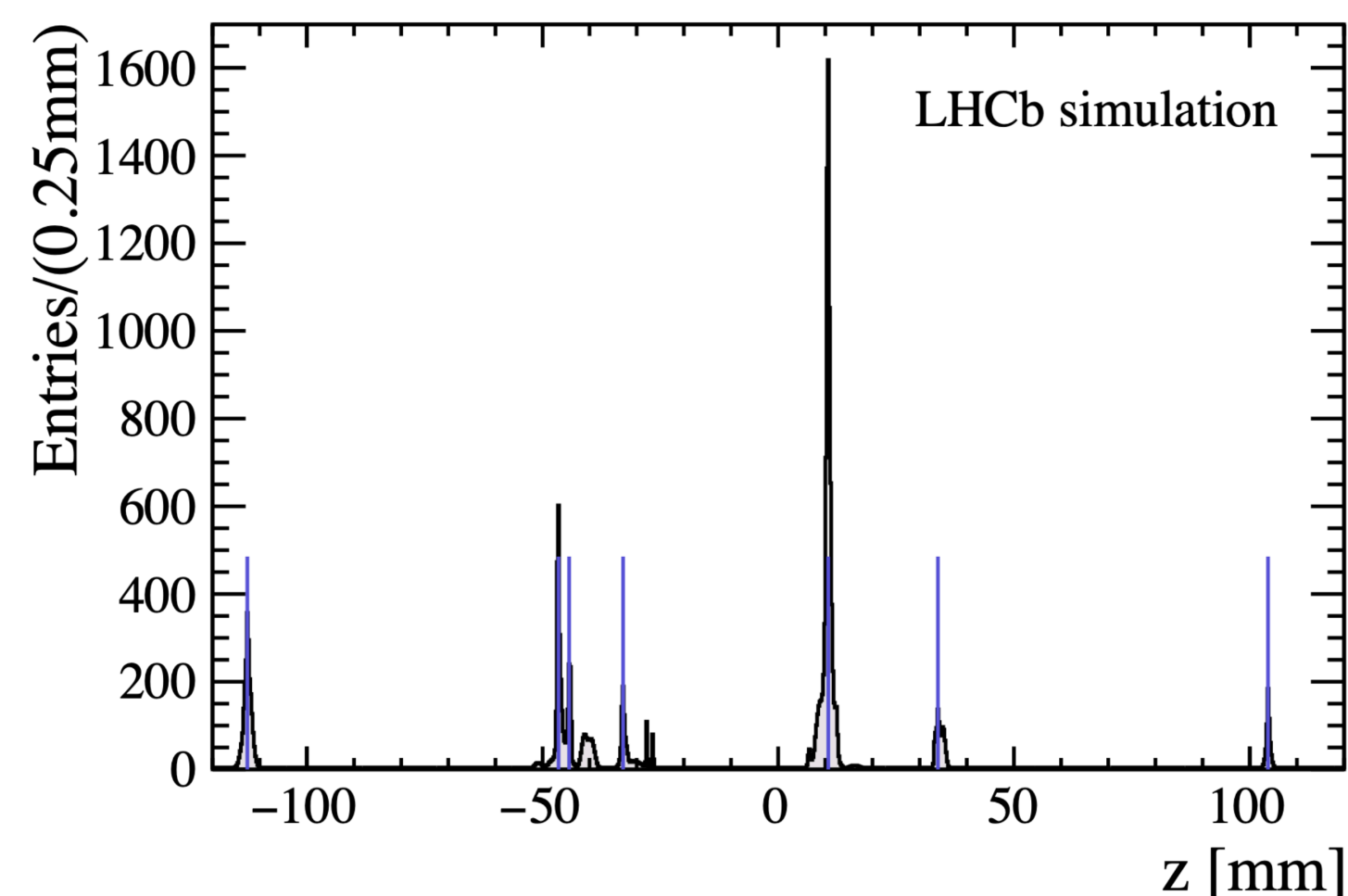
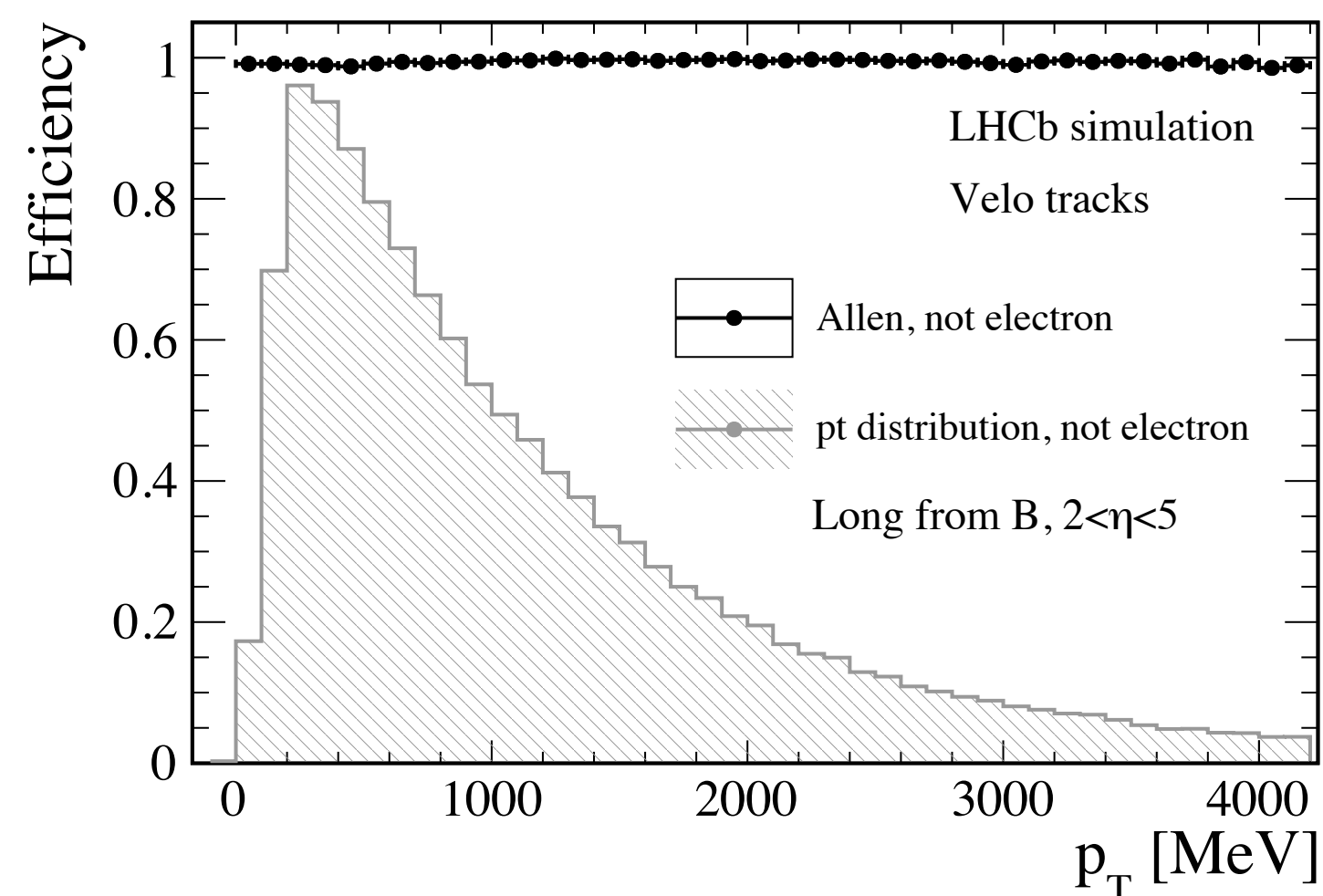
→ Tracks in VELO expected to be straight lines.

→ «Search by Triplet» algorithm:

- Find 3 hits in neighbouring VELO modules
- Format the triplet to other layers
- Do this for all the triplets found

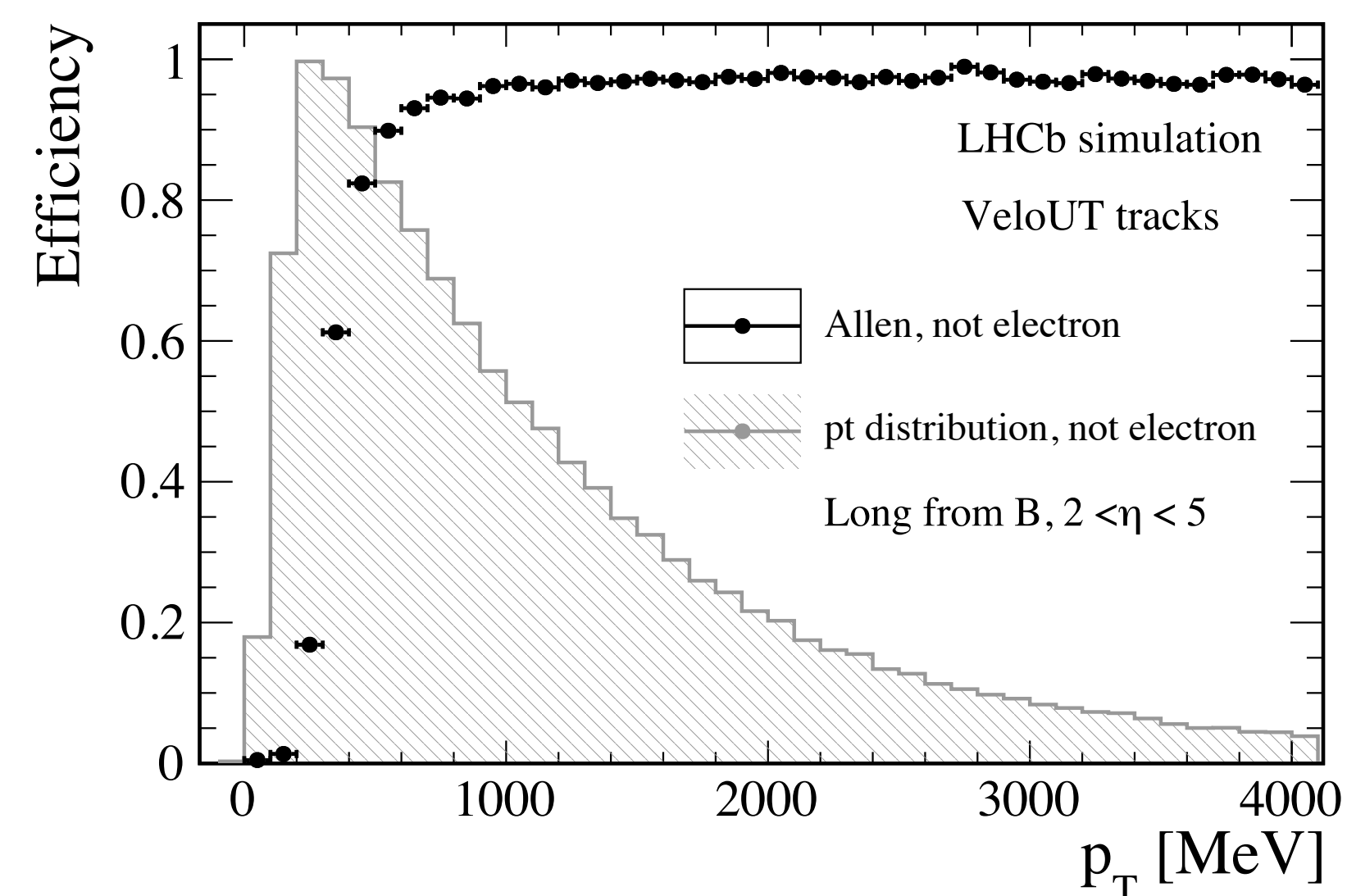
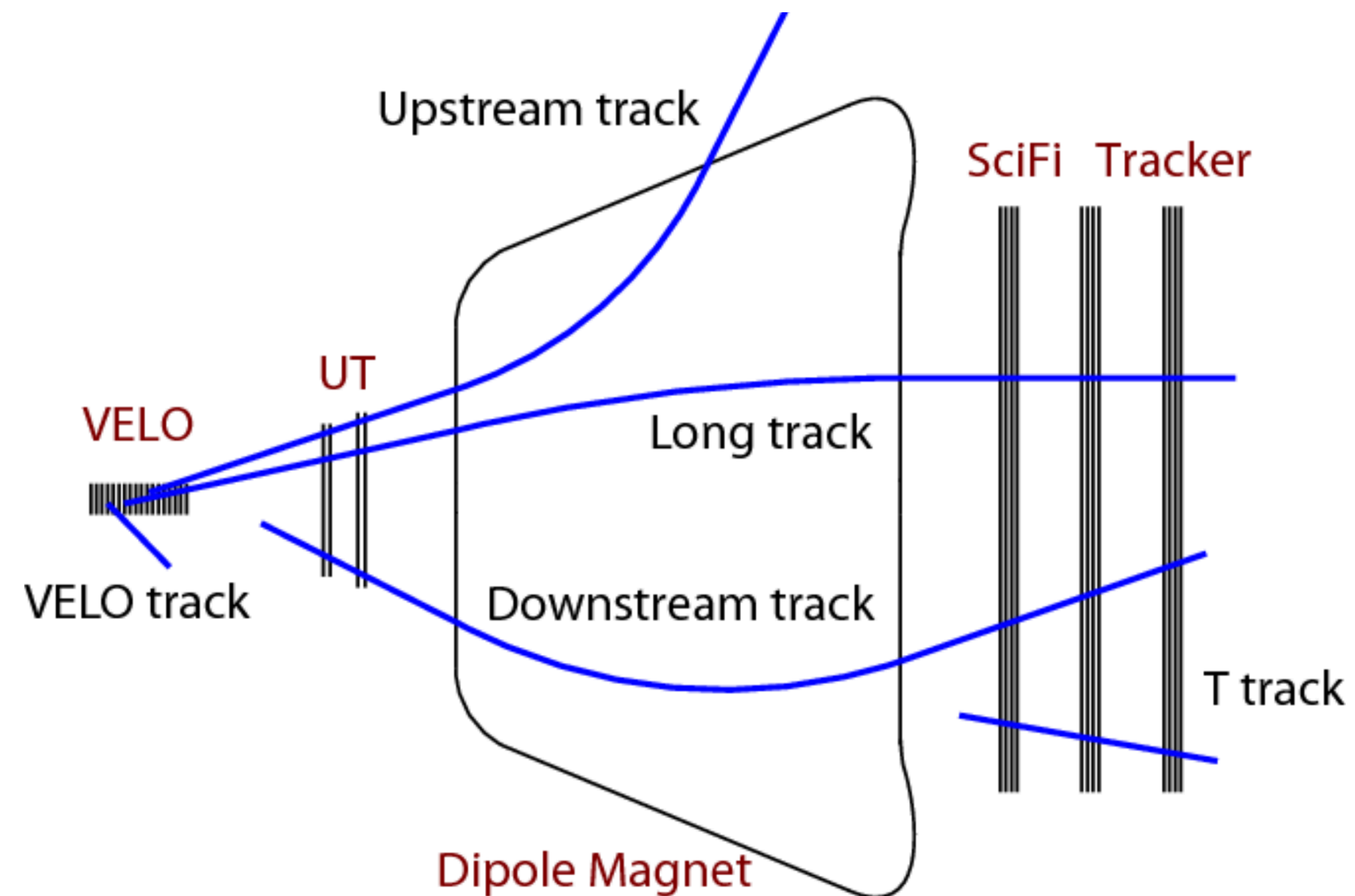


→ Extrapolate the tracks to the beamline : PV's found that the intersection between the track and the beamline.



# HLT1 SEQUENCE - VELO x UT

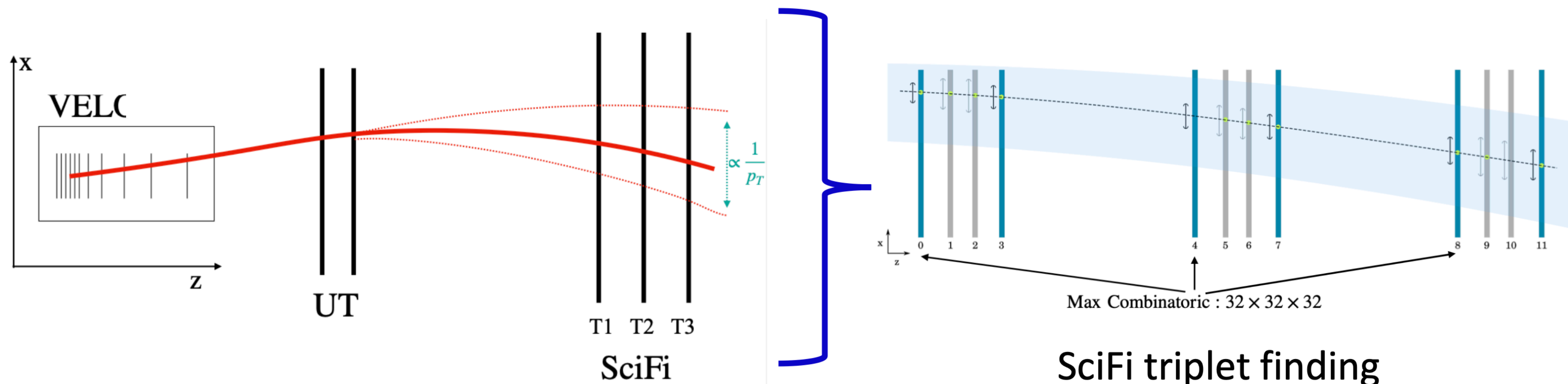
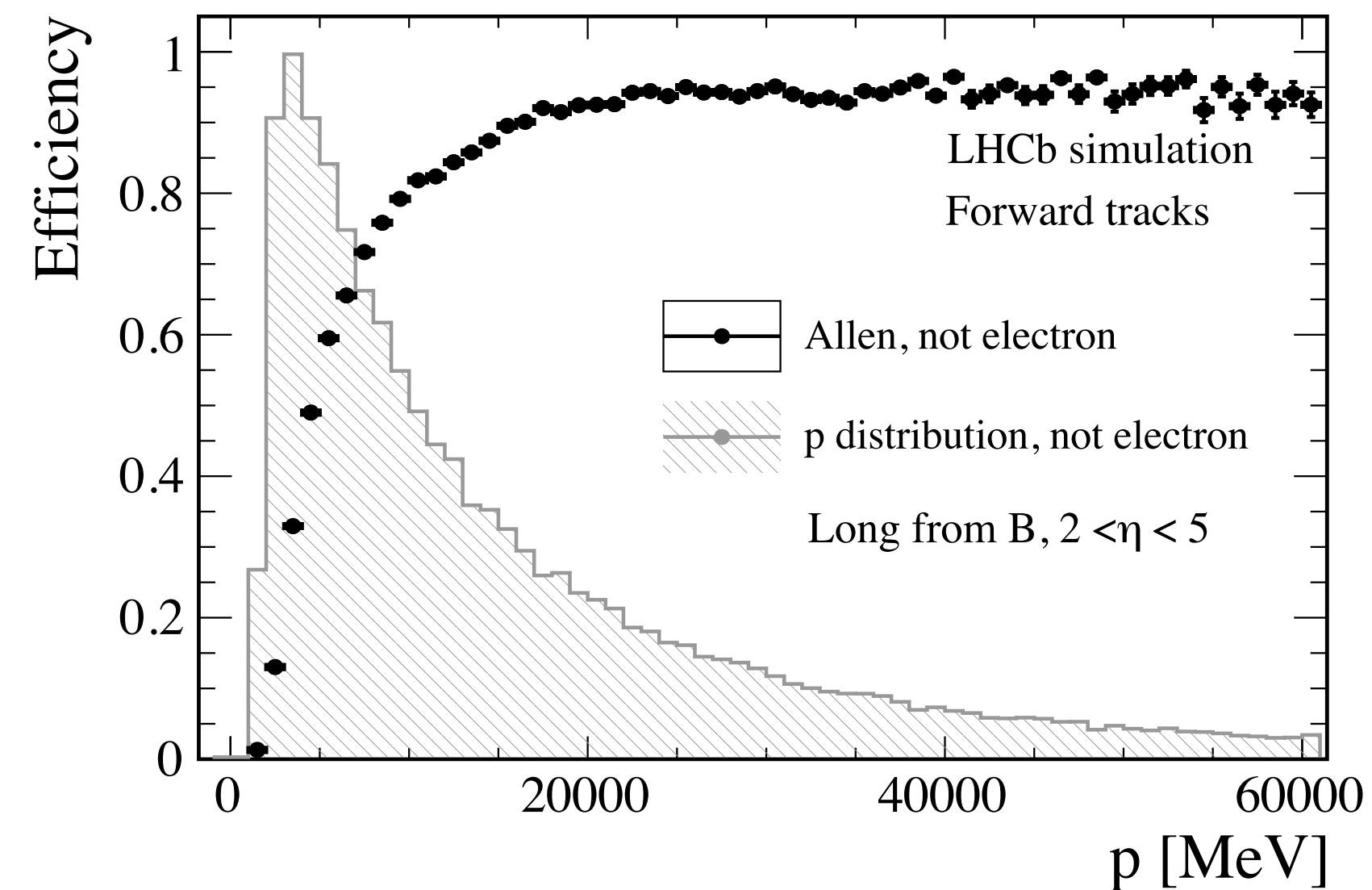
- The UT allows to reconstruct
  - charged particles which decay after the VELO
  - low momentum tracks bending out of the magnetic field region
- Extrapolate the VELO track to the UT silicon strips
- Account for small magnetic field
- Provides a first momentum estimate
- Requires (at least) 3 hits in the UT





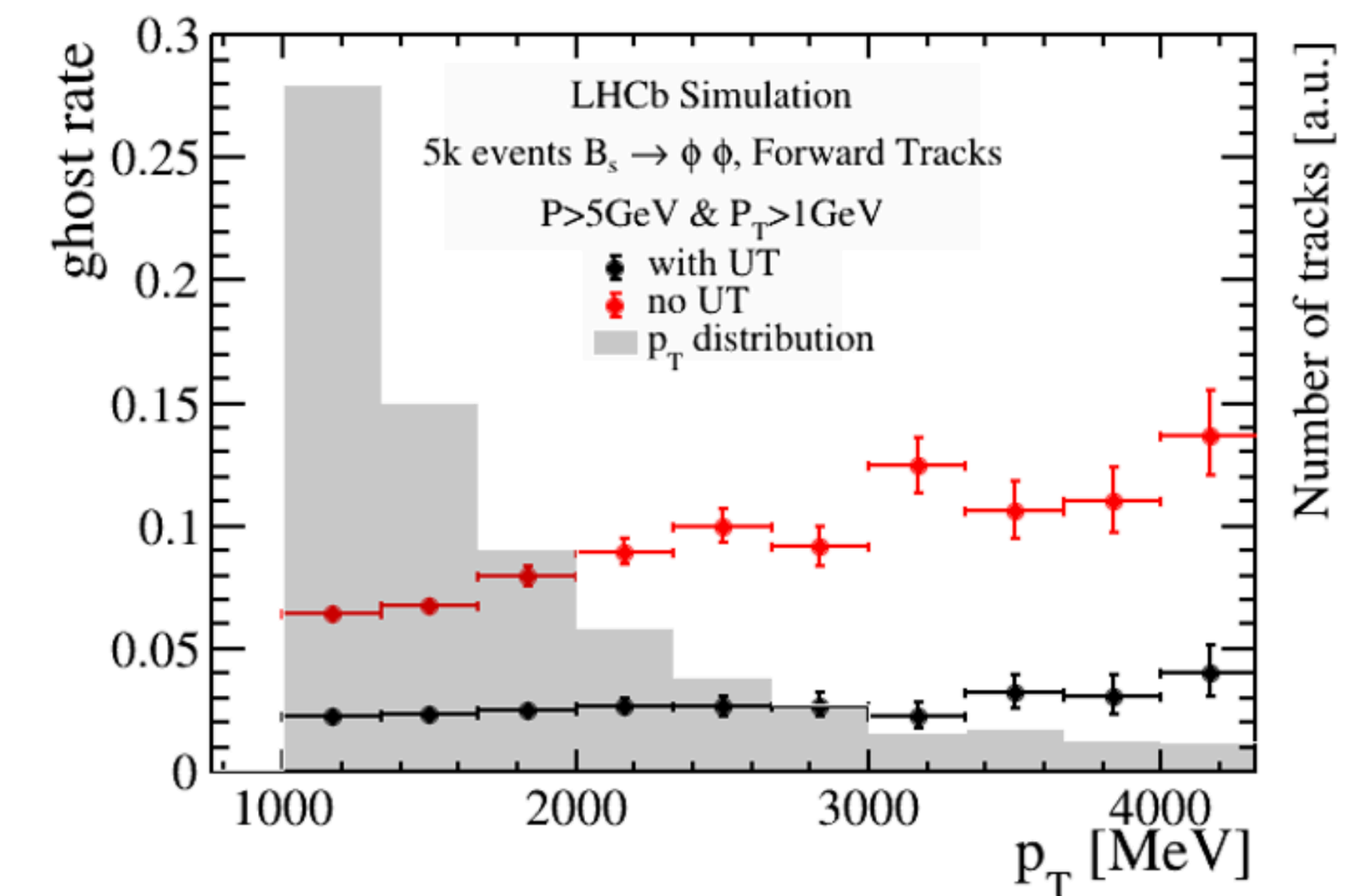
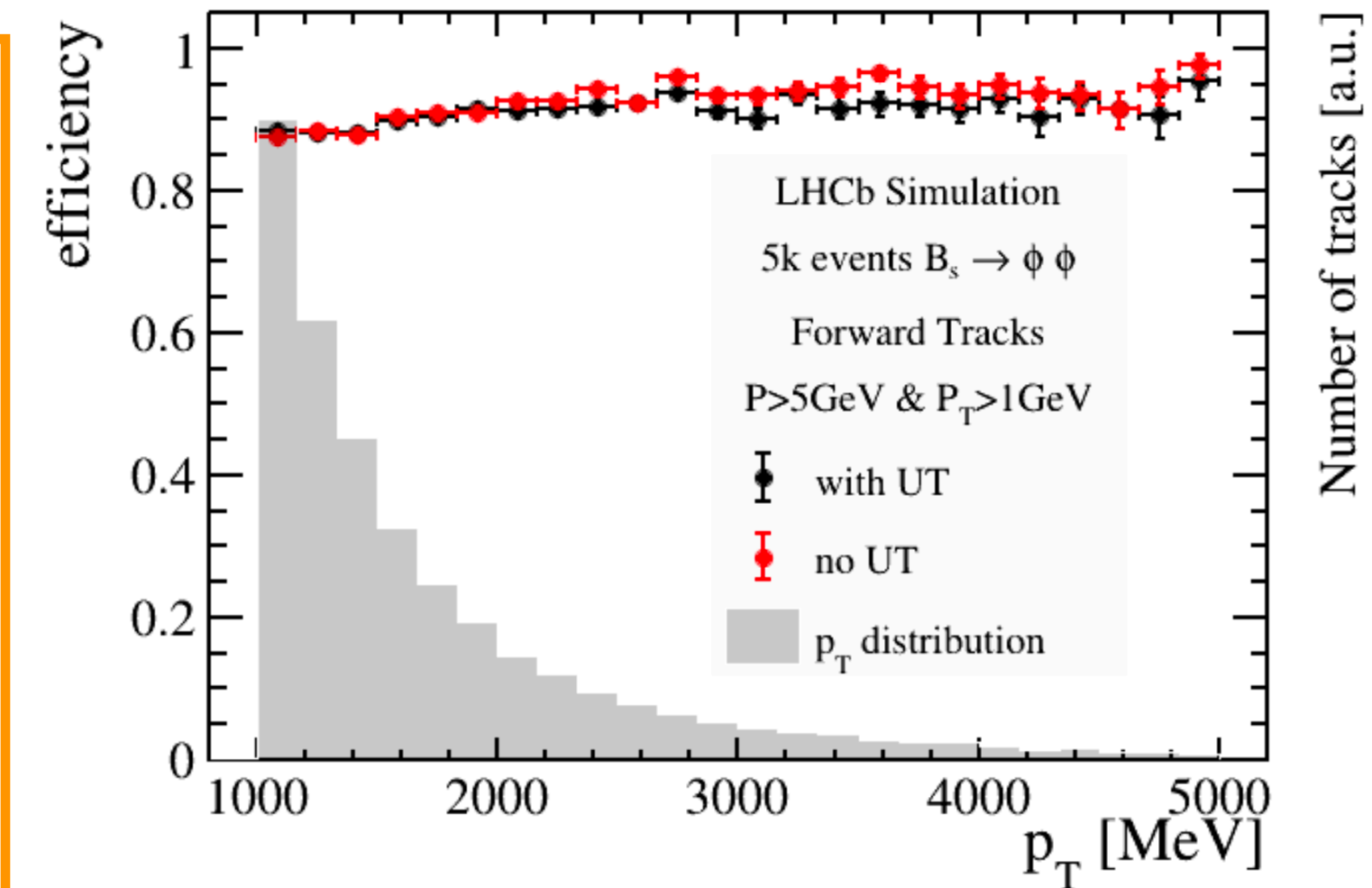
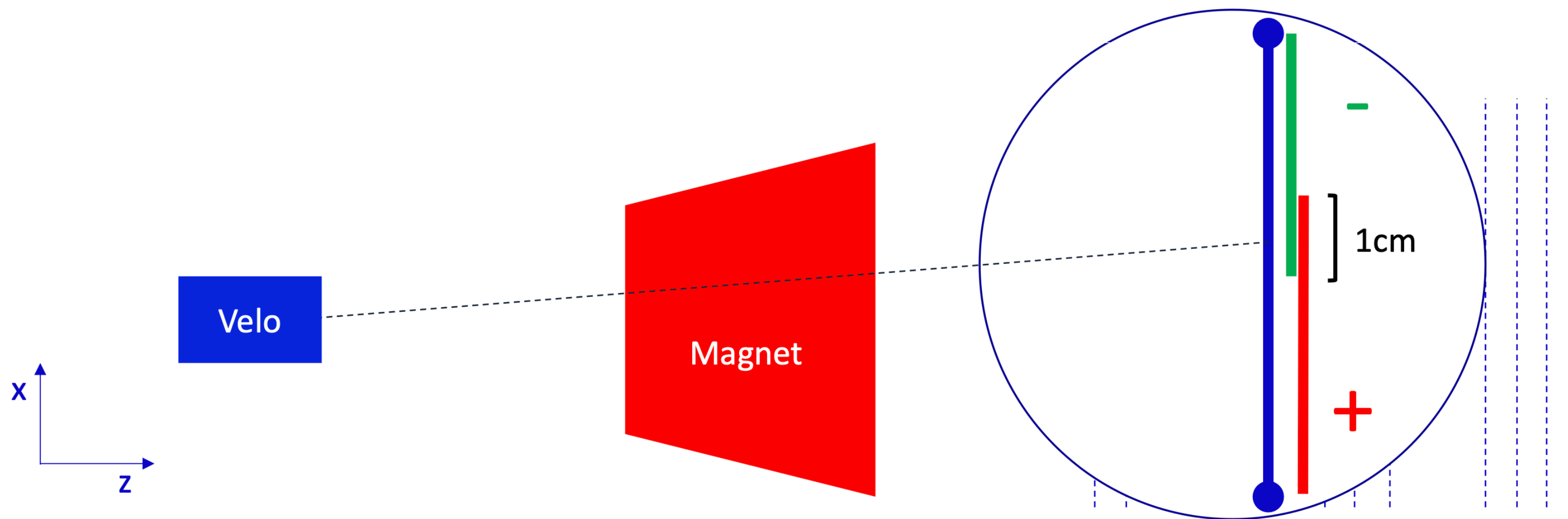
# HLT1 SEQUENCE - VELO x UT x SciFi

- Forward-tracking
- Extrapolate the VELOxUT tracks to the 12 layers of the SciFi
- Extrapolation using B field's parametrised trajectory
- Search of hits from an extrapolated tracks in windows fixed by the momentum estimation in the previous stage
- Reconstruct tracks with  $p > 3$  GeV
- Momentum resolution around 1%



# HLT1 SEQUENCE – VELO x noUT x SciFi

- Without the UT, no initial momentum estimate and no information on the charge of the particle
- Higher  $p$  and  $p_T$  requirements
- Double search windows around the VELO track extrapolation to identify the charge
- Similar reconstruction efficiency for high momentum ( $p > 5$  GeV and  $p_T > 1$  GeV) but with an increase in the ghost rate



*\*Another solution also commissioned:  
Seeding + Matching*

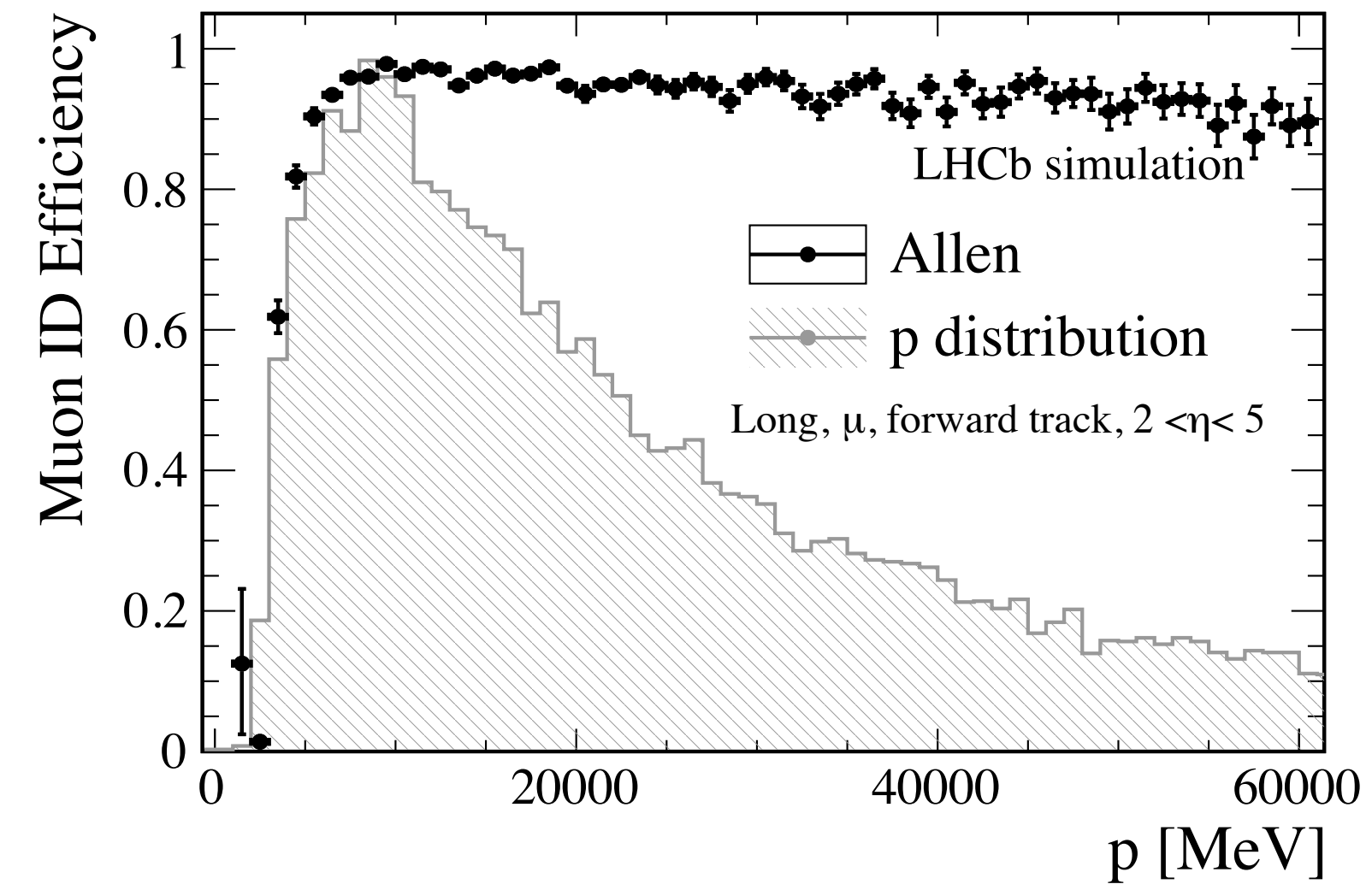
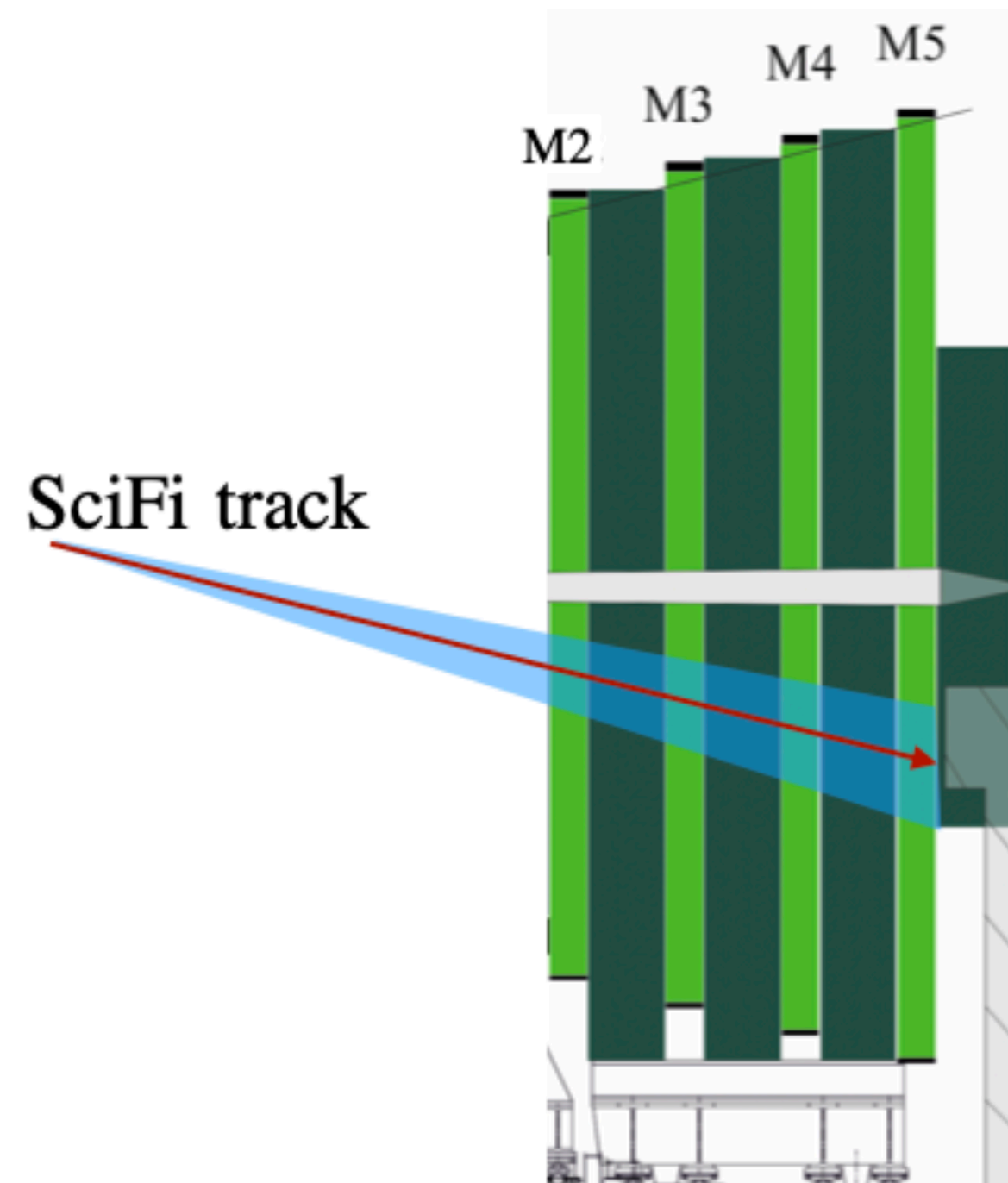
# HLT1 SEQUENCE – KALMAN FILTER

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- Used to improve the estimates of the momentum and the track's impact parameter.
- Method for track fitting, iterates over all hits on a track. For every hit, estimate the state of the track at that location (predictions + measurements).
- Include the previous momentum estimate with the detector description to precisely estimate noise due to multiple scattering and energy loss.
- Gives the best linear estimator for track state.
- At HLT1 level only applied using VELO-parametrisation.

# HLT1 SEQUENCE – MUON IDENTIFICATION

- Forward tracks matched with hits on Muon stations
- Important for the selection of decays with muons in final state

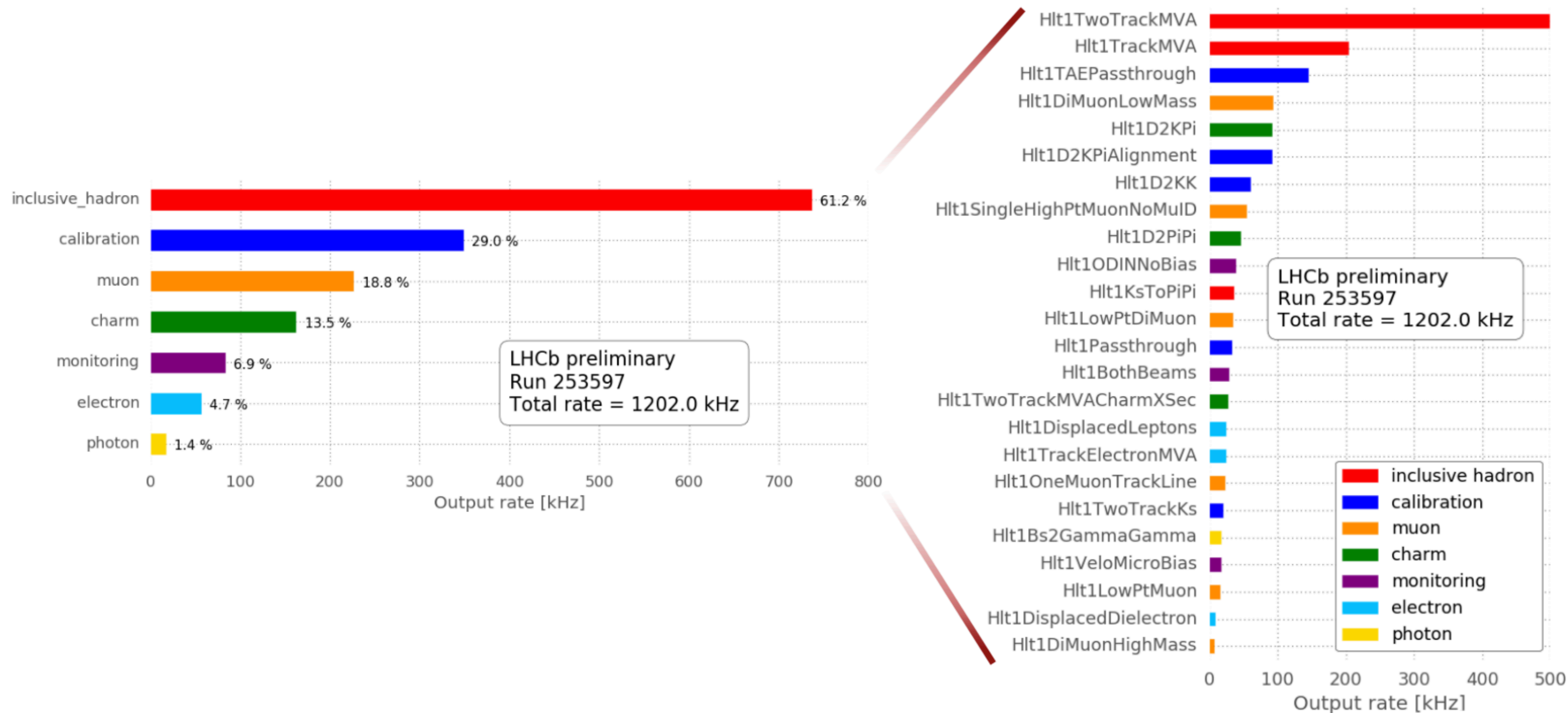


# HLT1 SEQUENCE – CALORIMETER RECONSTRUCTION

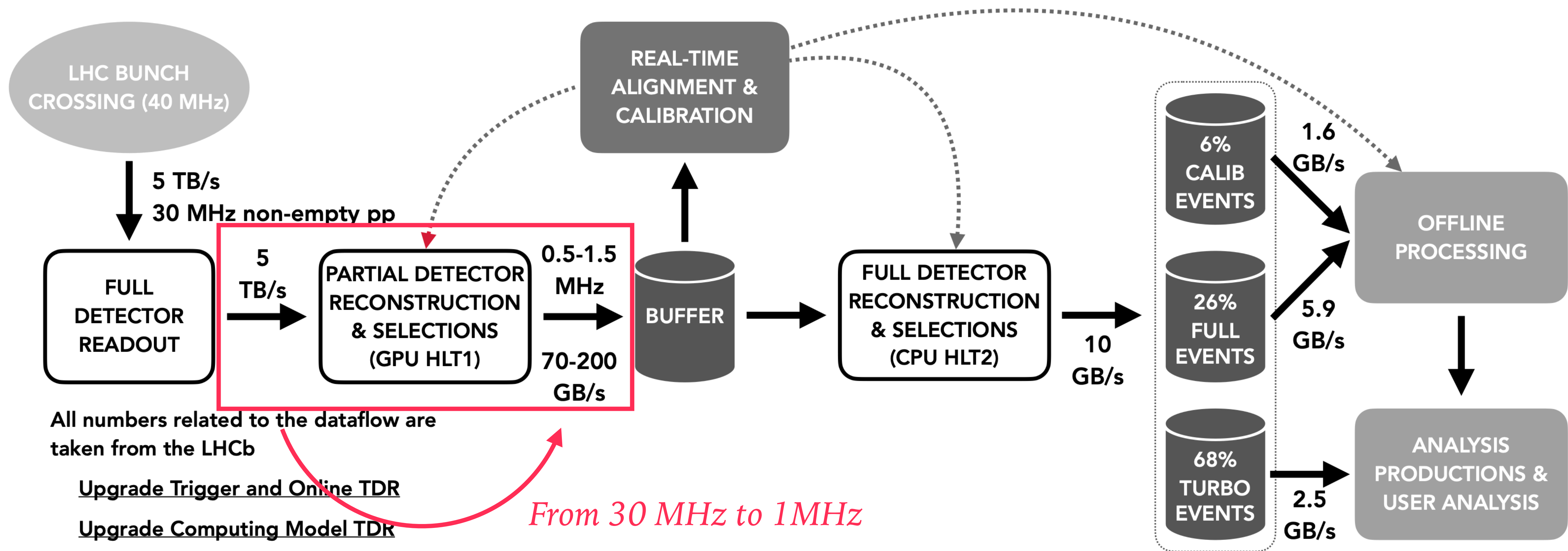
- Look for energetic clusters.
- Enable's photon and electron reconstruction at HLT1 level - for the first time.

# HLT1 SEQUENCE - SELECTIONS

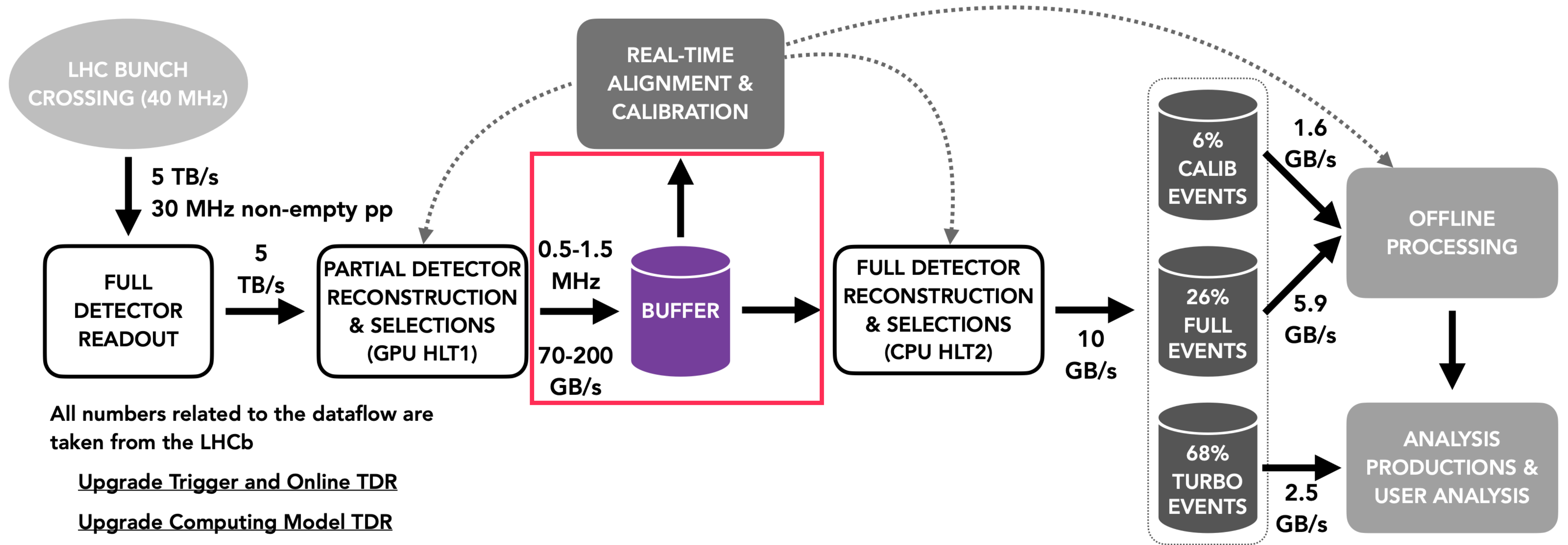
- Selecting events with HLT1 trigger lines for different physics purposes
- Successfully reduced the input rate to reach 1 MHz of output



# HIGH LEVEL TRIGGER 1



# BUFFER



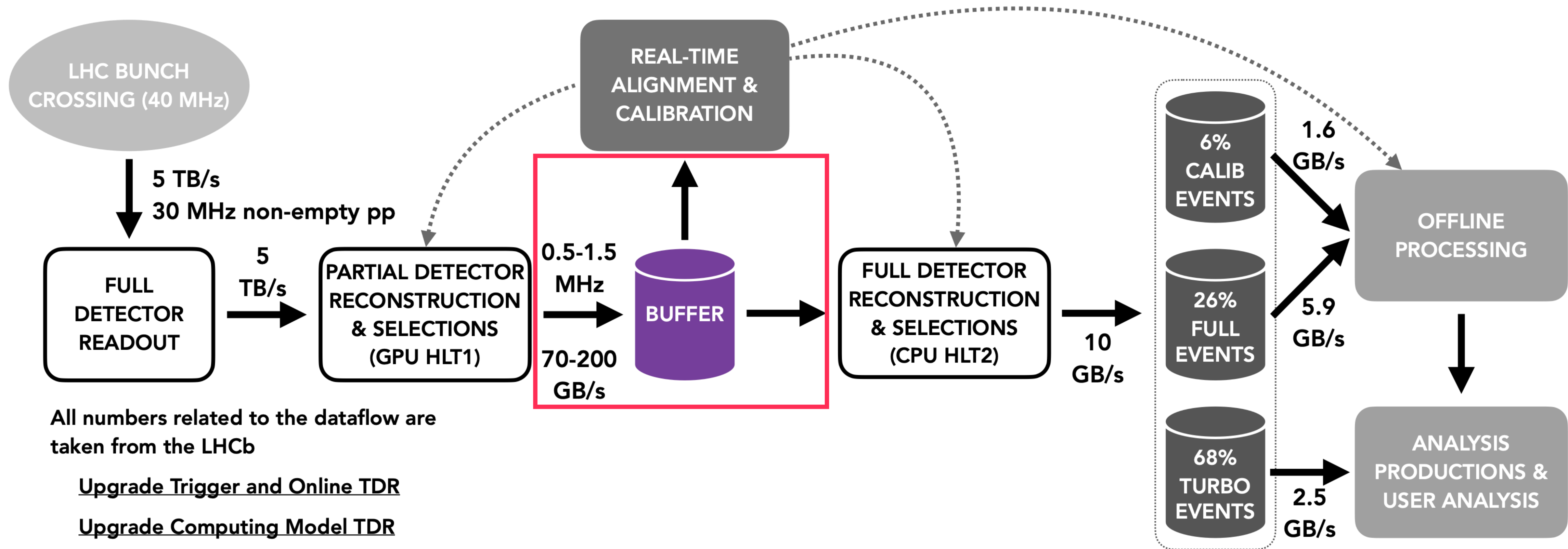
# QUICK WORD ON THE BUFFER

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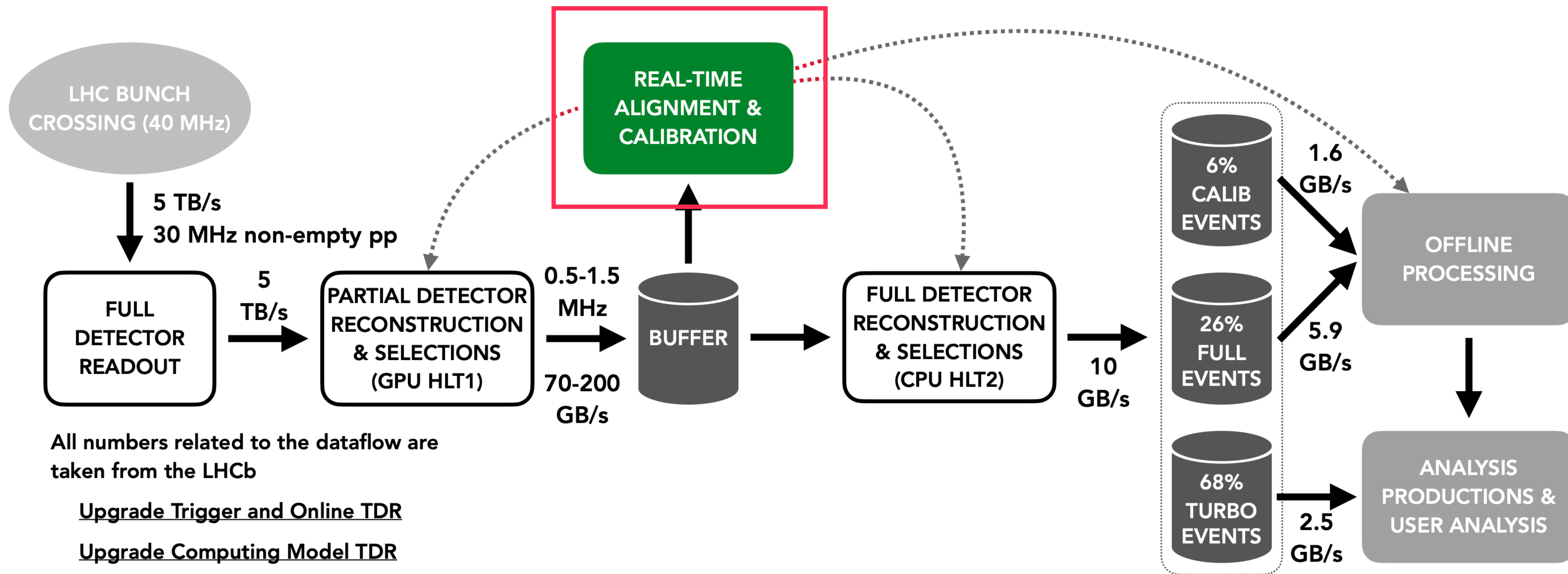
- Serves two purposes:
  - Hold events selected by HLT1 while the Real-Time alignment and calibrations are performed
  - Allows differ processing of the HLT1 selected events in between LHC fills
- Optimal buffer size of around 30PB, which can buffered 80 hours of LHC collisions at an HLT1 1MHz output rate



# BUFFER

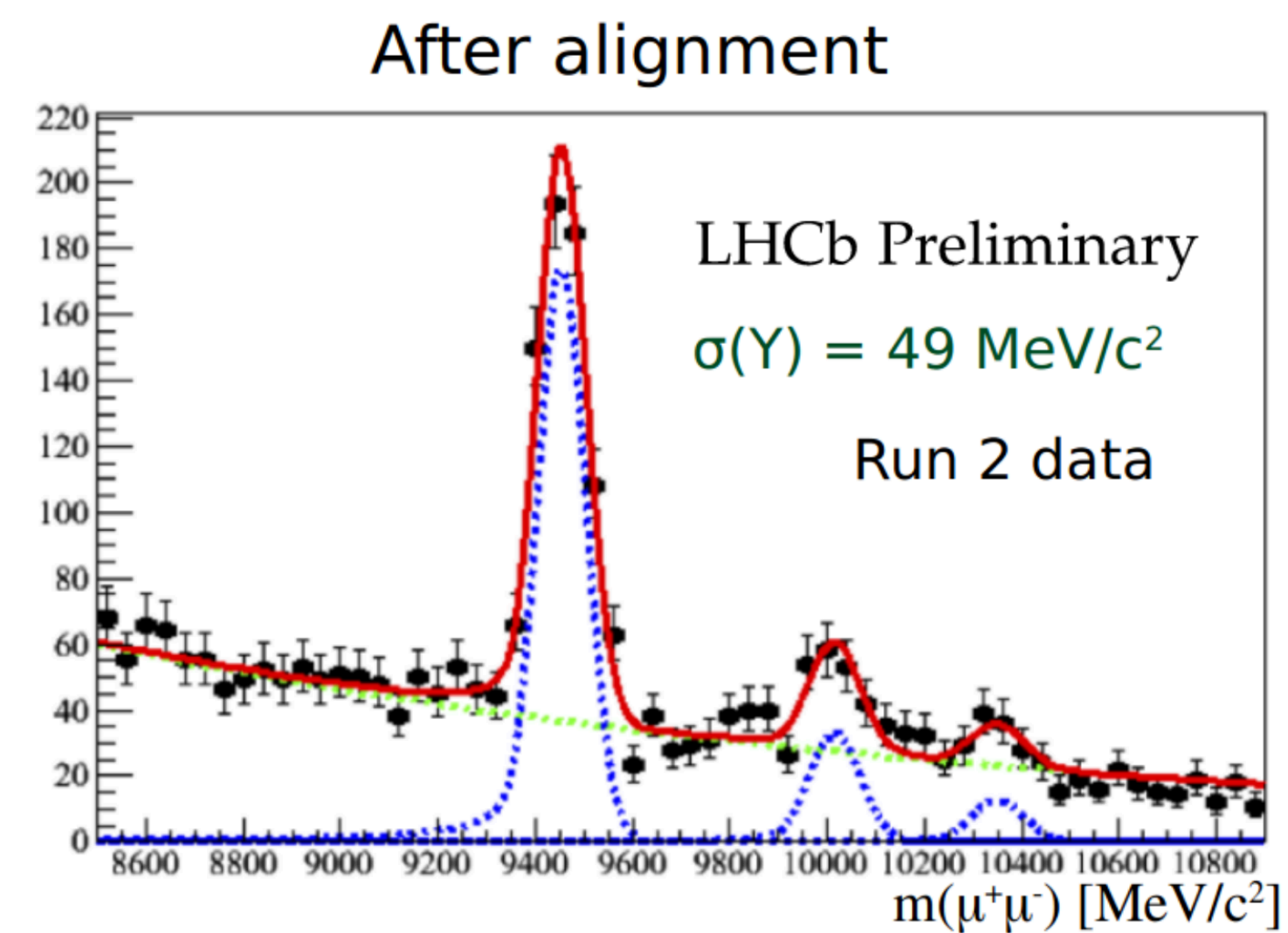
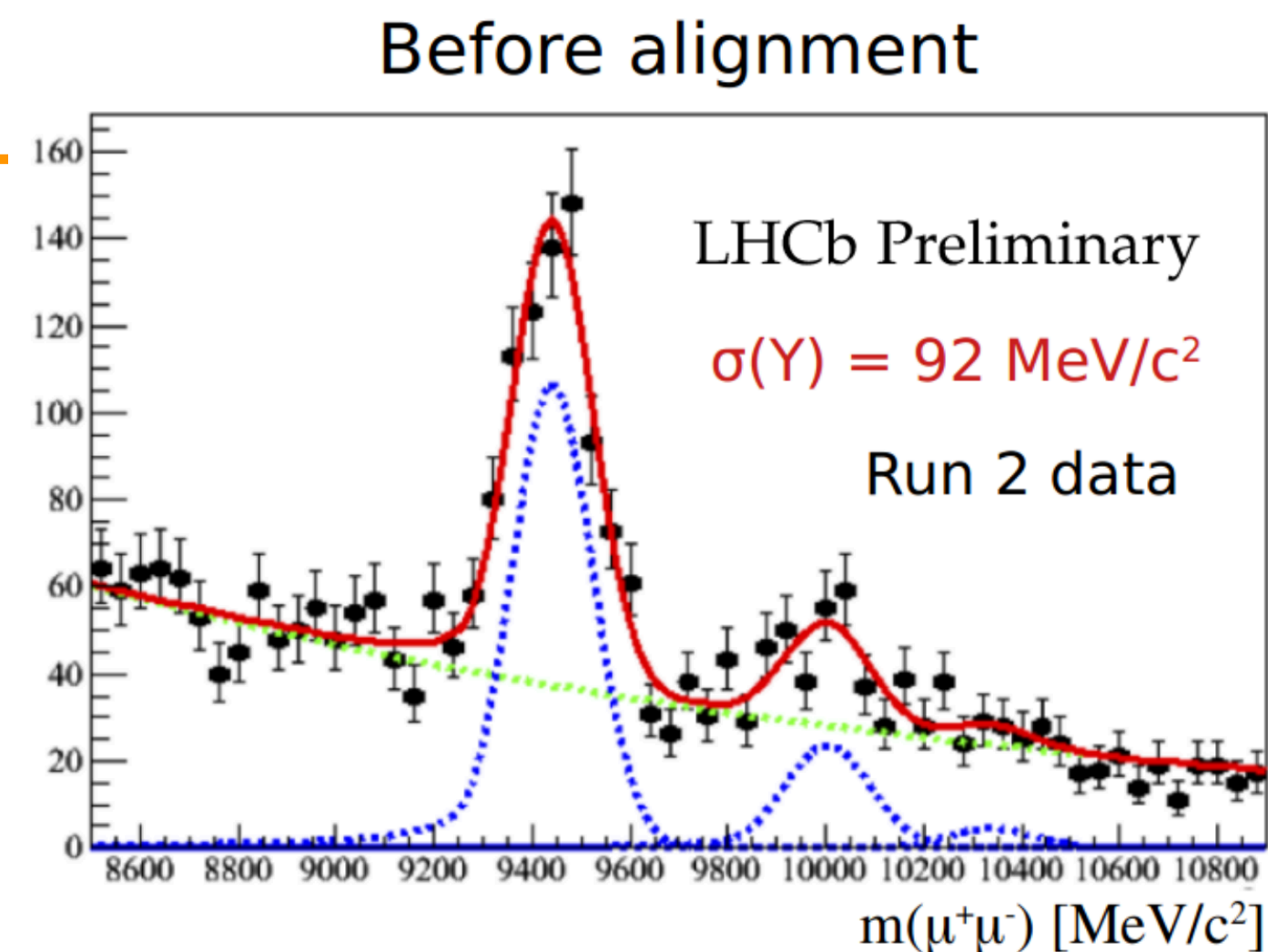


# REAL-TIME ALIGNMENT AND CALIBRATION

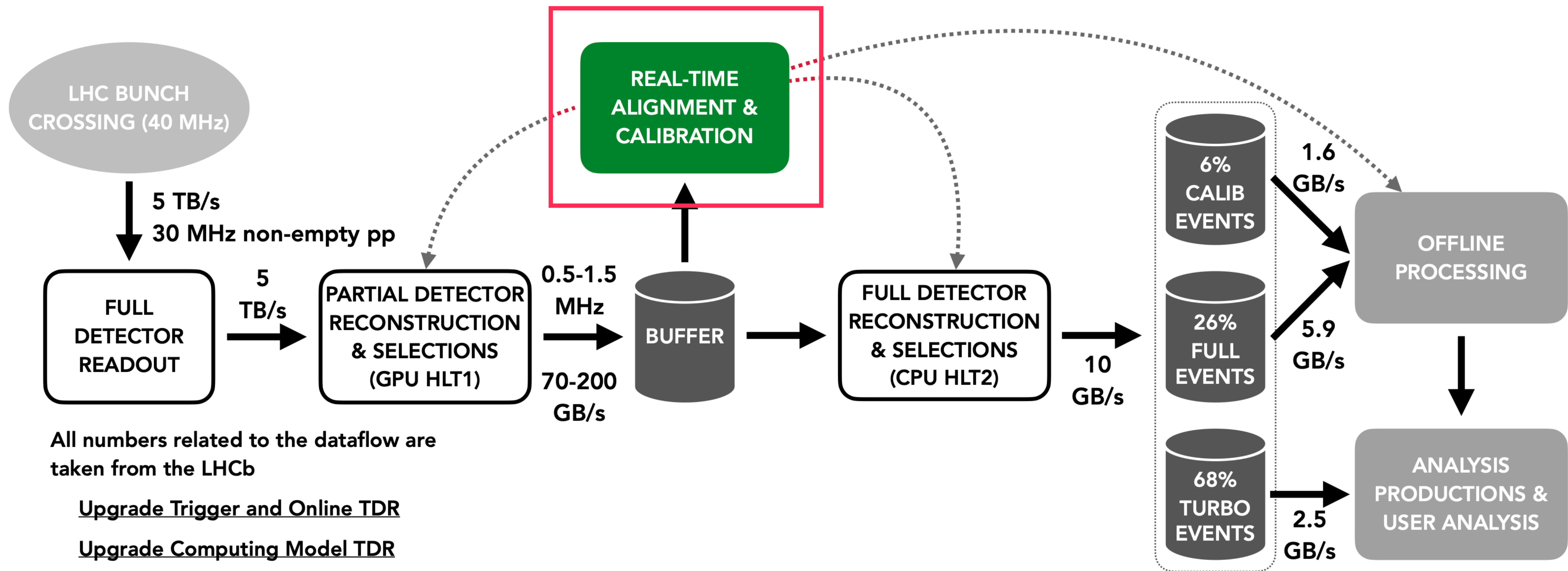


# REAL-TIME ALIGNEMENT & CALIBRATION

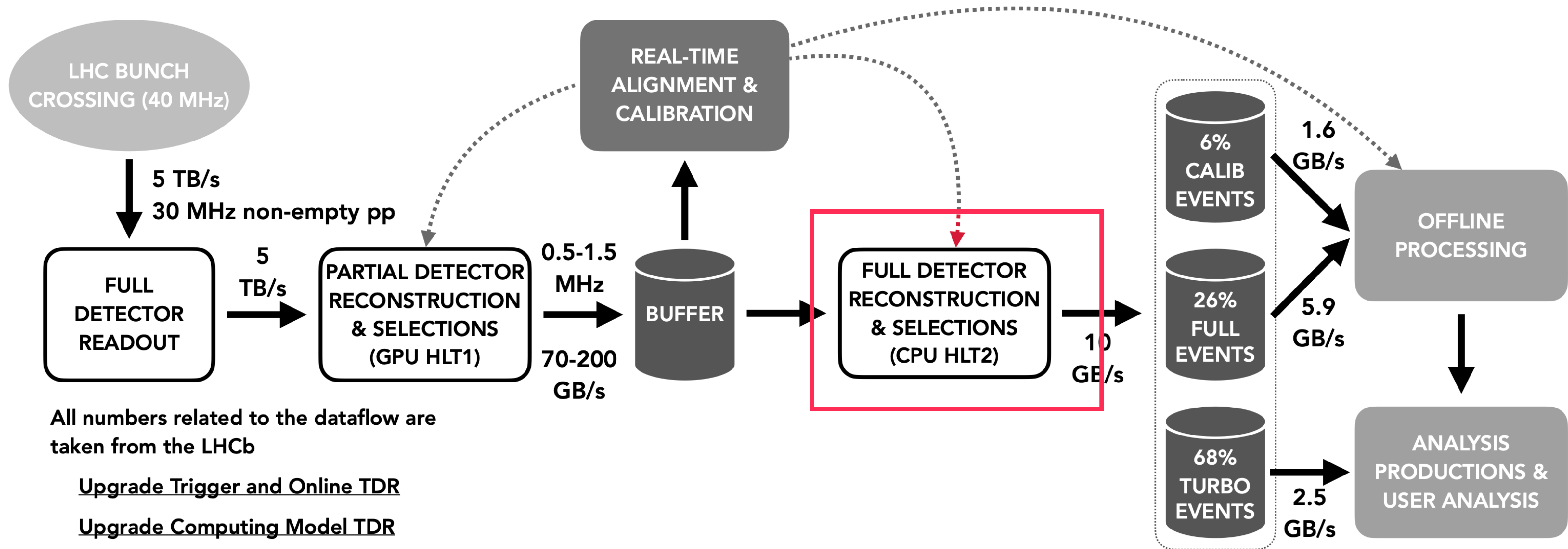
- Use of calibration samples selected by HLT1 stored in buffer
- Real-time calculation of alignment and calibration constants
  - Constants that are used for the reconstruction and selections
  - Ensures measurements of physics parameters to the best resolution possible
- Used to reach offline-quality reconstruct at the HLT2 level
- Alignment for Tracking system and for the RICH mirrors
- Calibration for RICH and CALO



# REAL-TIME ALIGNMENT AND CALIBRATION



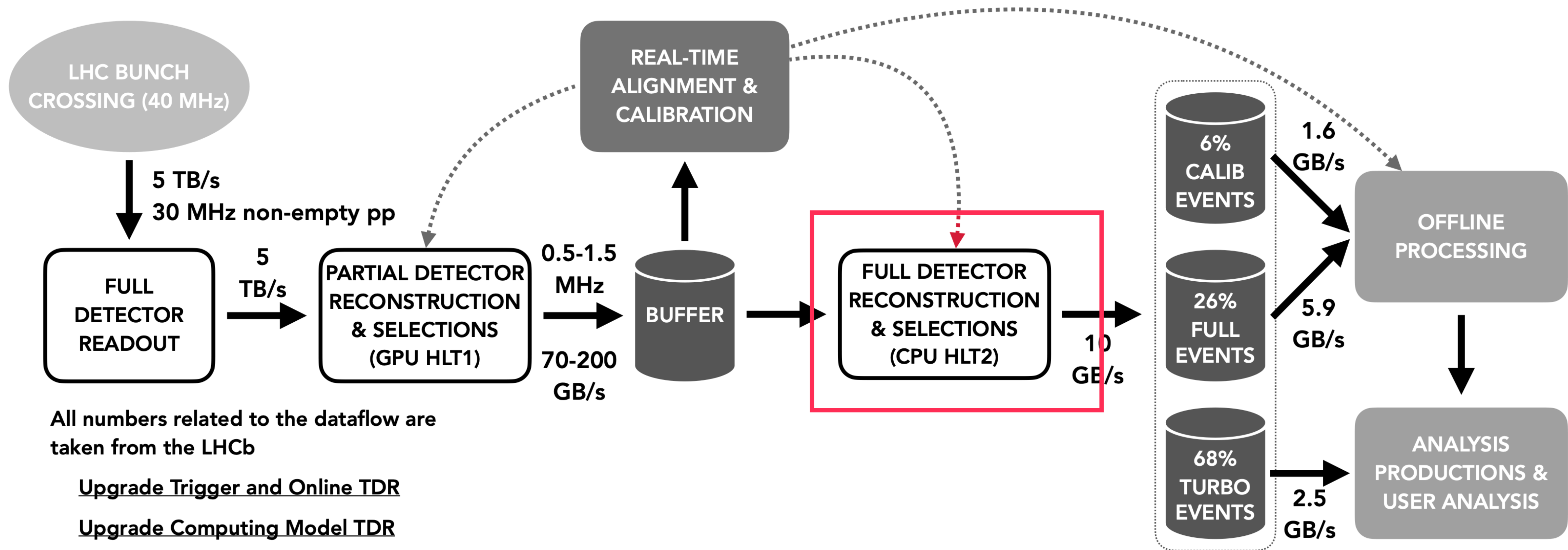
# HIGH LEVEL TRIGGER 2



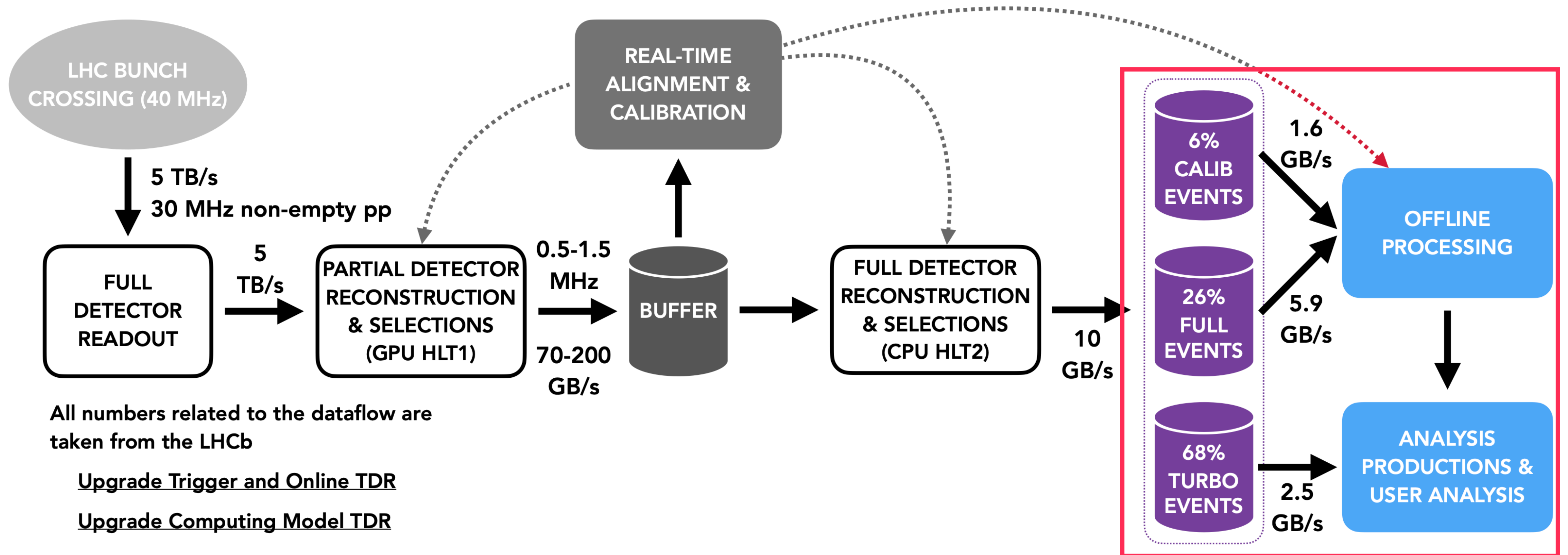
- Full reconstruction → offline-quality reconstruction
  - Aligned and calibrated detector (see previous step)
  - Full particle identification with RICH reconstruction
  - Full track fit, with detailed magnetic field and detector description
  
- Around ~1000 selections algorithms
  - Run2 Stripping (offline) moved to the HLT2 level for Run3 (online)
- The selections are tuned to different signal topology and physics analysis
- Runs on CPUs
- Implemented on Moore

*More on Moore for Run3 with Jonathan*

# HIGH LEVEL TRIGGER 2

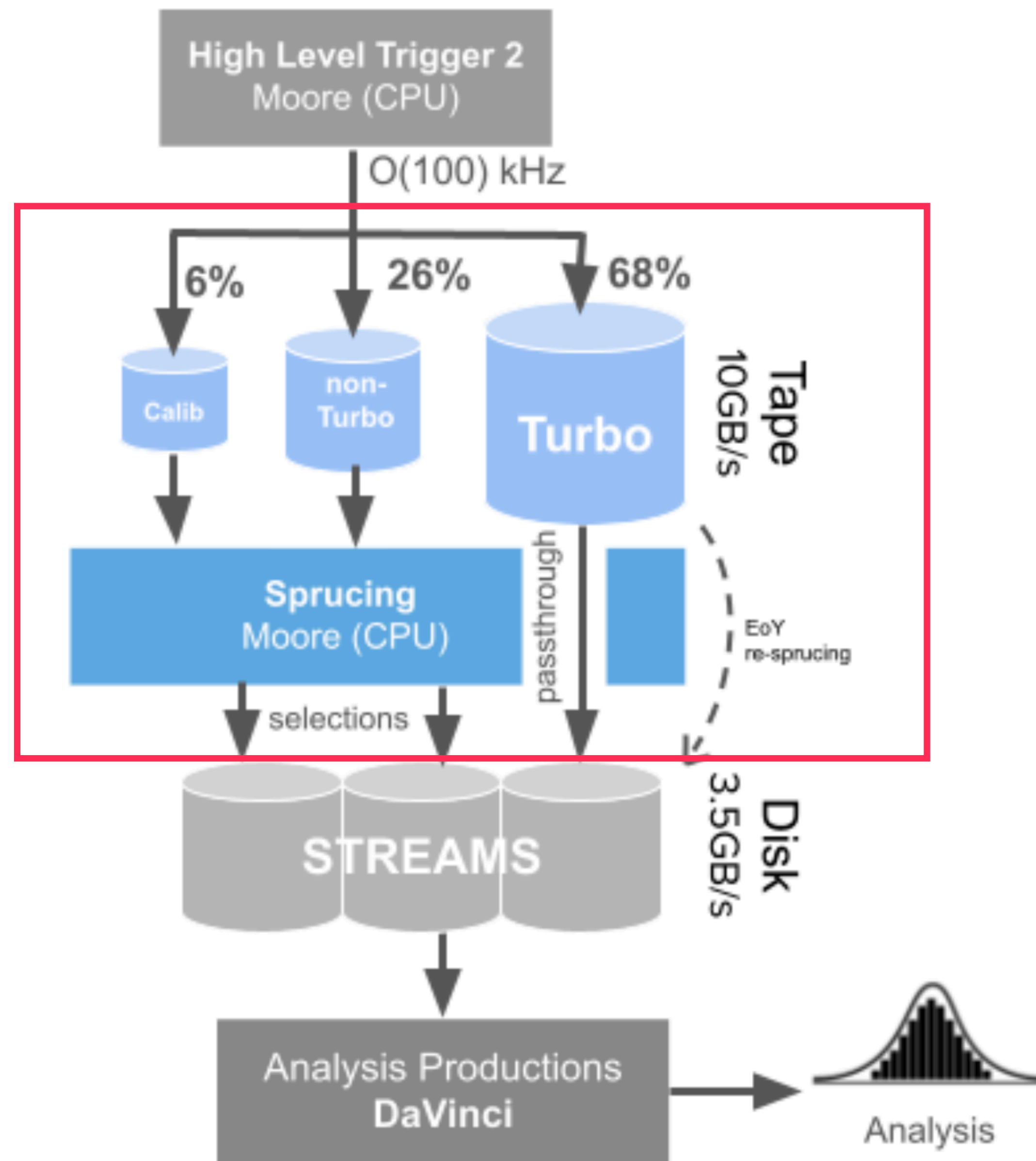


# MOVING TO OFFLINE



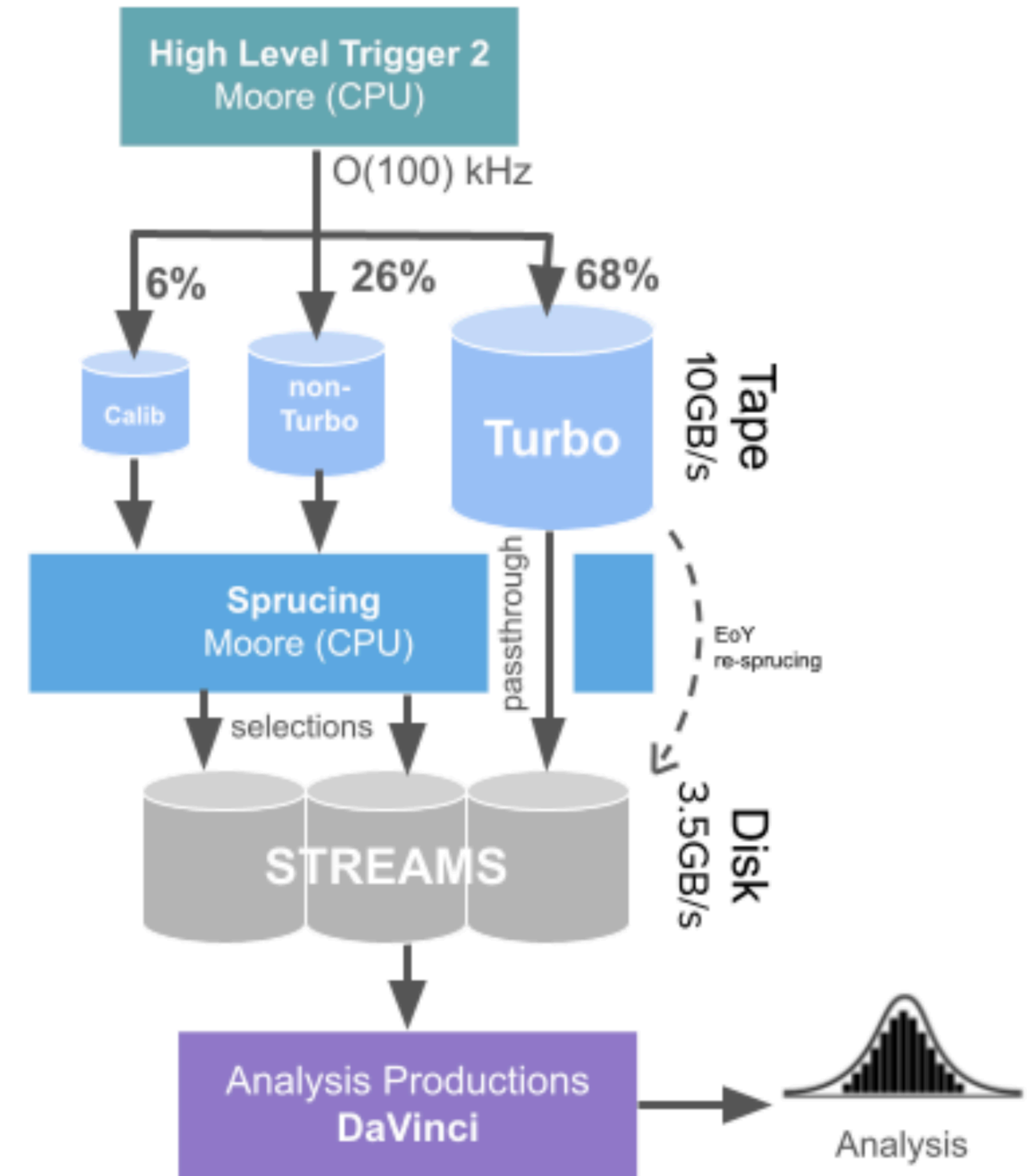


# OFFLINE STREAMS



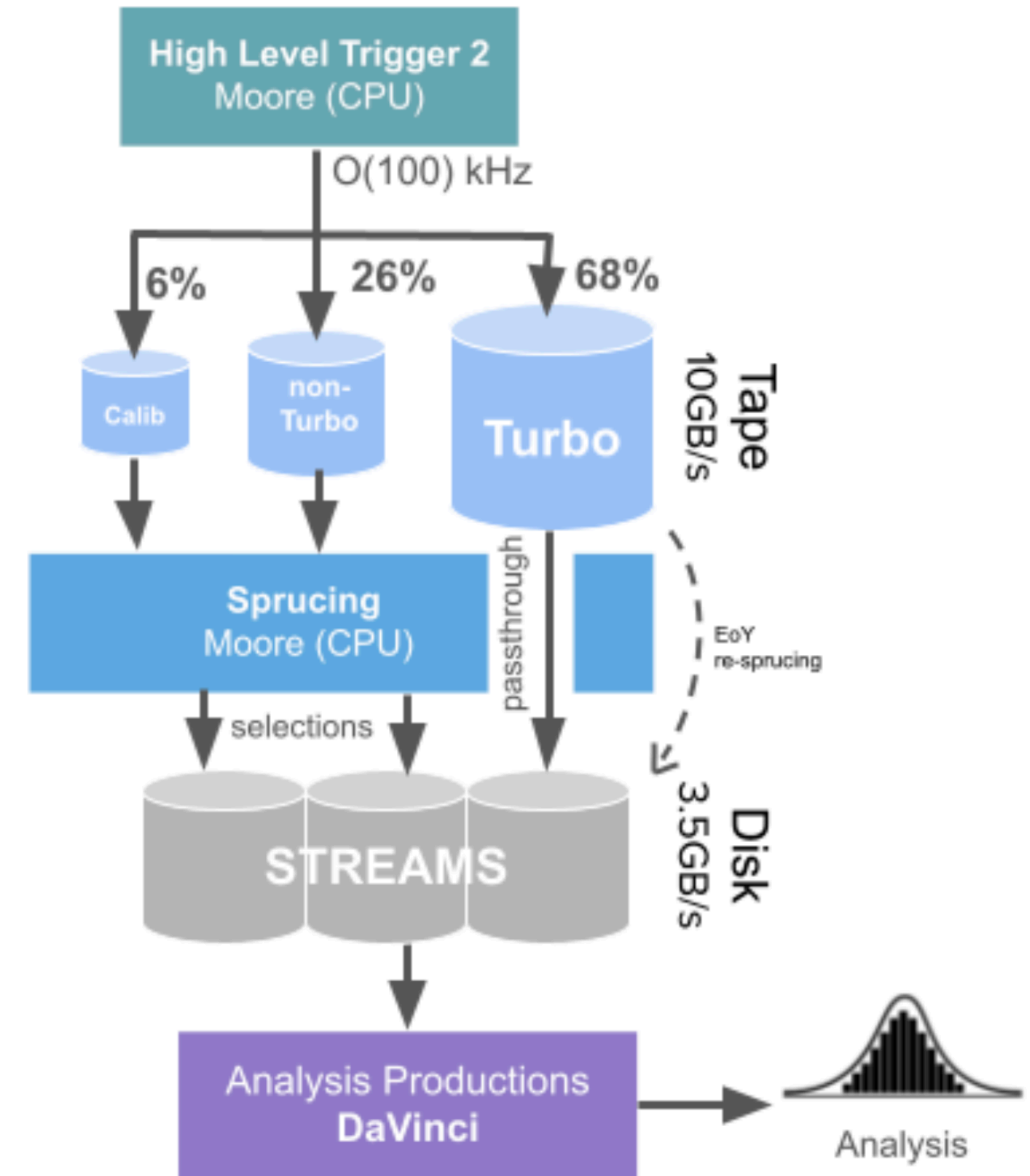
# SPRUCING

- Used for physics selections that can not go straight to disk
- Intermediate step between the tape storage and the disk storage to reduce the data
- Also based on the Moore project
- No offline reconstruction - the reconstruction comes from HLT2
- Typical case that need sprucing are inclusive HLT2 lines or to data selection/processing algorithms that are too intensive to be run online.

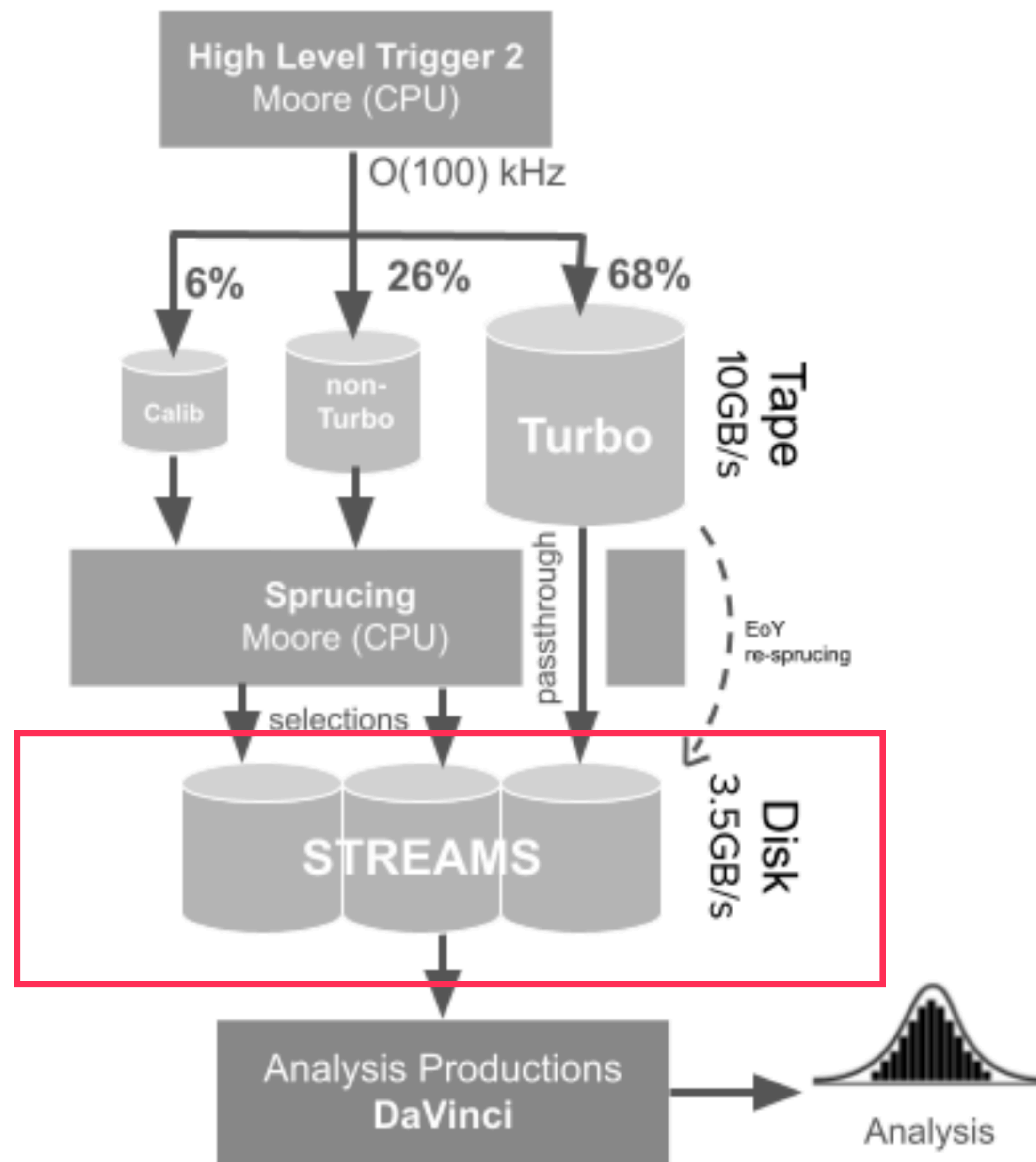


# TURBO

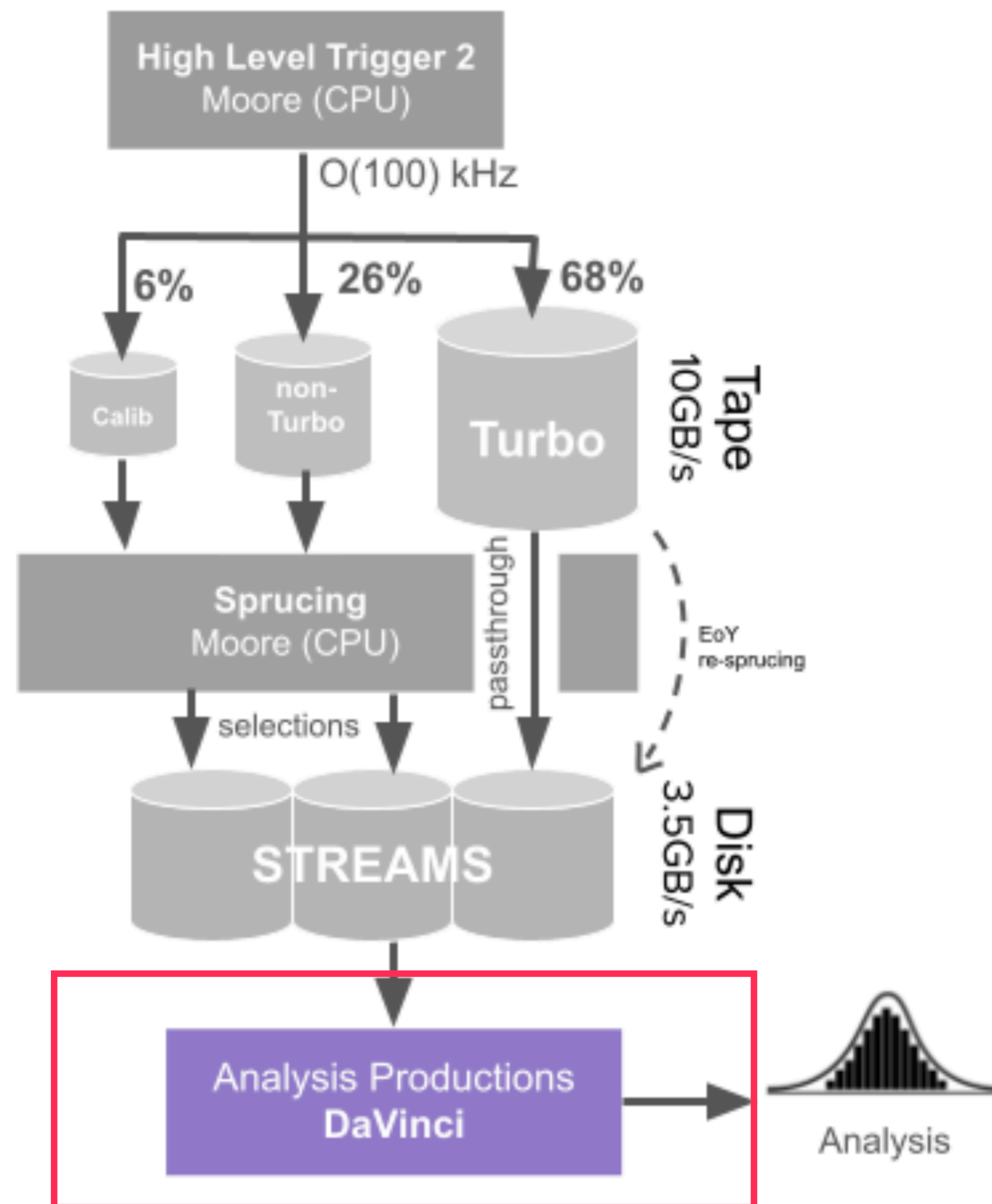
- In Run 2:
  - 70% of the events passed to offline processing
  - 30% to Turbo
- In Run 3:
  - 68% passed to Turbo (Baseline in Run3)
  - 32% to offline processing
- Turbo → bypass the offline processing steps and stripping (save in storage and computing power)
- Saves only the signal candidate



# OFFLINE STREAMS



# OFFLINE STREAMS



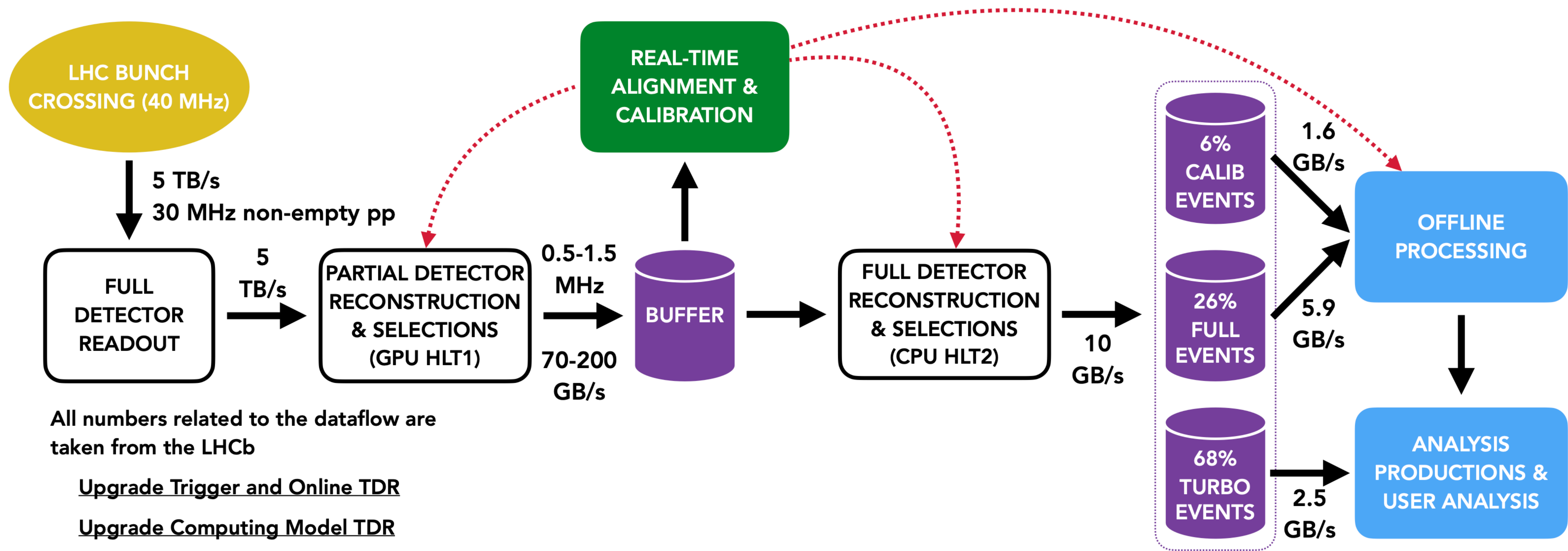
# TUPLE MAKING

- Software : [DaVinci](#)
- Used in the previous runs but majors changes
  - From LoKi to ThOr functors
  - From TupleTools to FunTuples
- FunTuples:
  - More flexibility on the choice of variables
  - Reduces the number of unused variables
  - Reduces storage and computing use

*More on DaVinci for Run3 with Jonathan*

# ANALYSIS PRODUCTION

- Move to central analysis production from the user specific jobs
- To central production managed by DIRAC
- [Analysis Productions](#):
  - Automatic testing
  - Automatic preservation of config details
  - Automatic error interpretation
  - Web interface



**THANK YOU FOR LISTENING !**