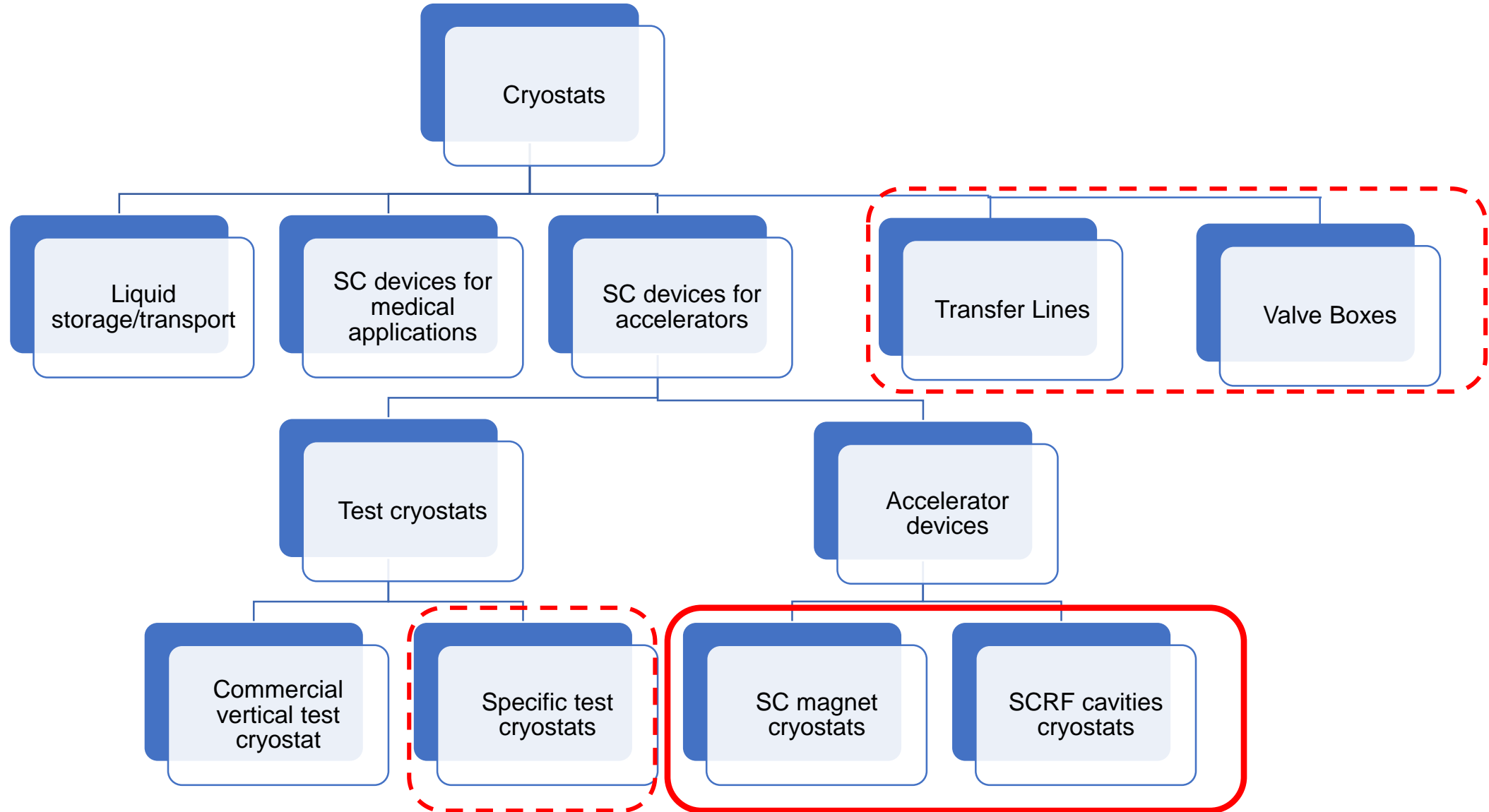


Helium Cryostats for Superconducting Devices

Vittorio Parma
CERN – SY/RF Group

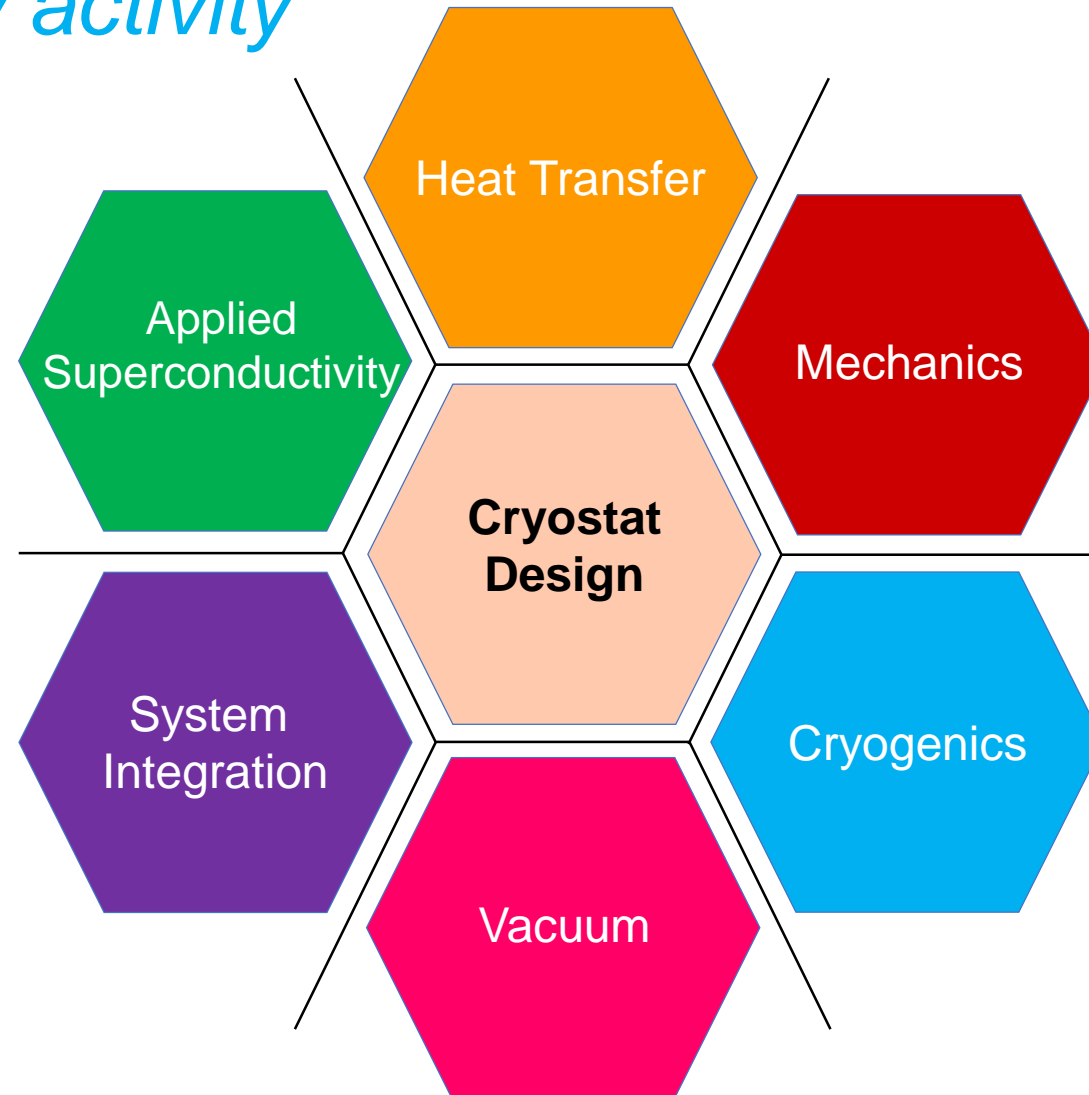
Technical Training: Cryostat Engineering for helium superconducting devices
CERN, 7-9 November 2022

Cryostats by their application

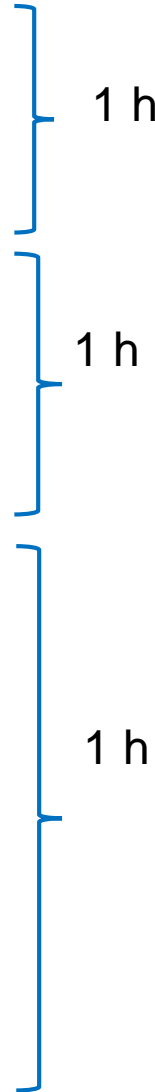


Cryostat Design for SC devices for accelerators:

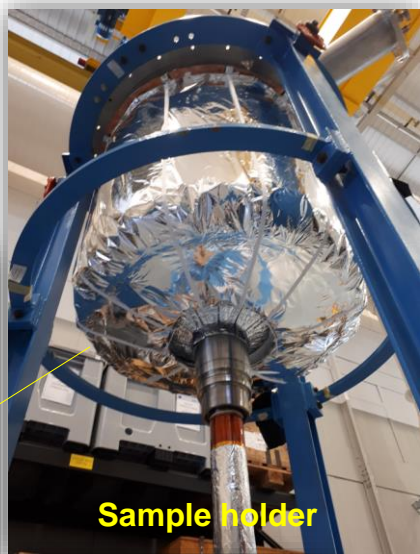
A multidisciplinary activity



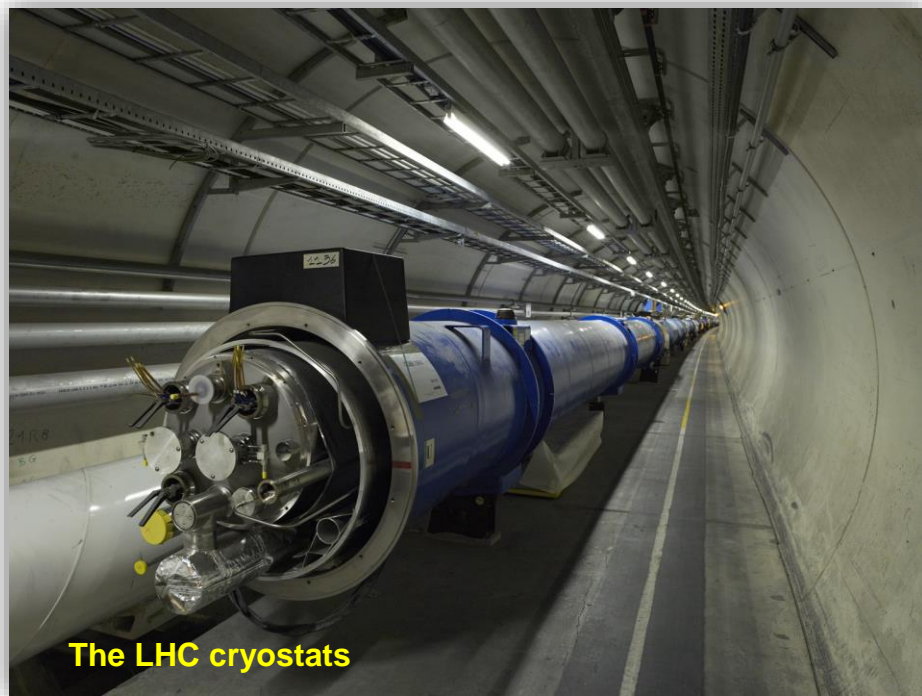
Content

- Helium cryostats for SC devices, functions and requirements
 - Examples of cryostats
 - Mechanical design and construction of cryostats:
 - Materials for cryostats and their properties
 - Pressure/vacuum vessels, codes, and norms
 - Supporting systems
 - Heat transfer mechanisms at cryogenic temperatures:
 - Thermal radiation and thermal design solutions (thermal shielding, MLI)
 - Thermal conduction and thermal design solutions (feedthroughs, heat intercepts)
 - Notions of cryogenic safety
 - Calculation tool: *Cryostat Toolbox v.1.1*
- 
- 1 h
- 1 h
- 1 h

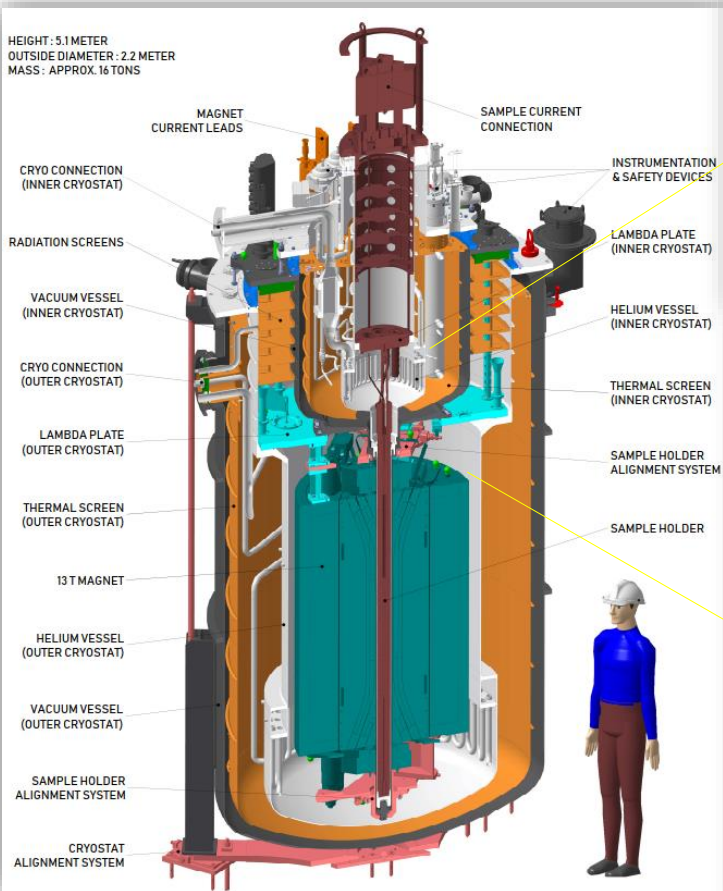
A few examples at CERN



Sample holder



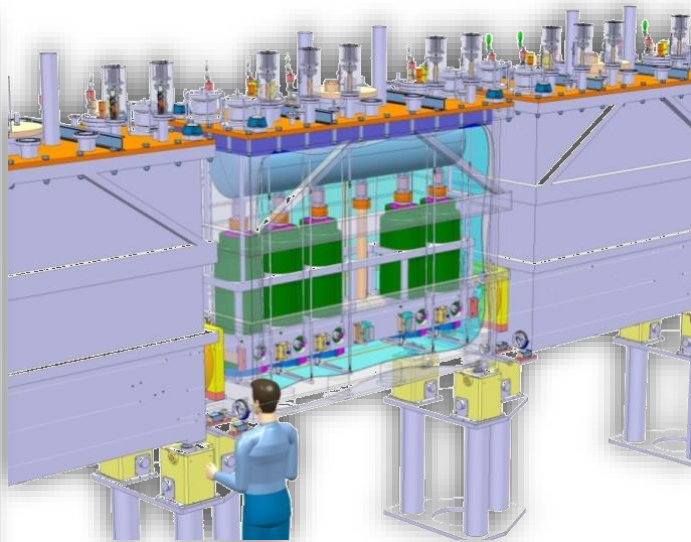
The LHC cryostats



Fresca 2: test station for new SC cables

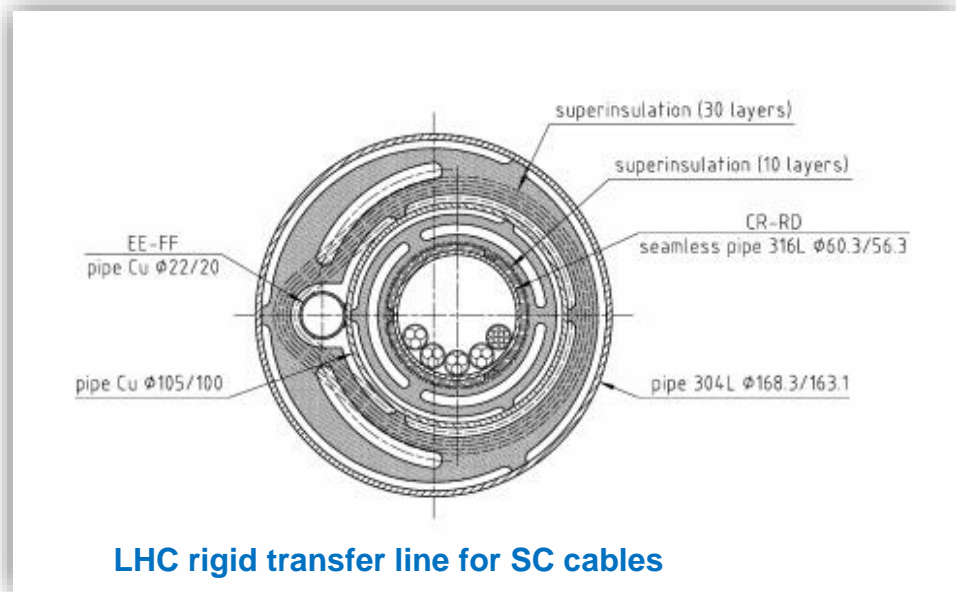
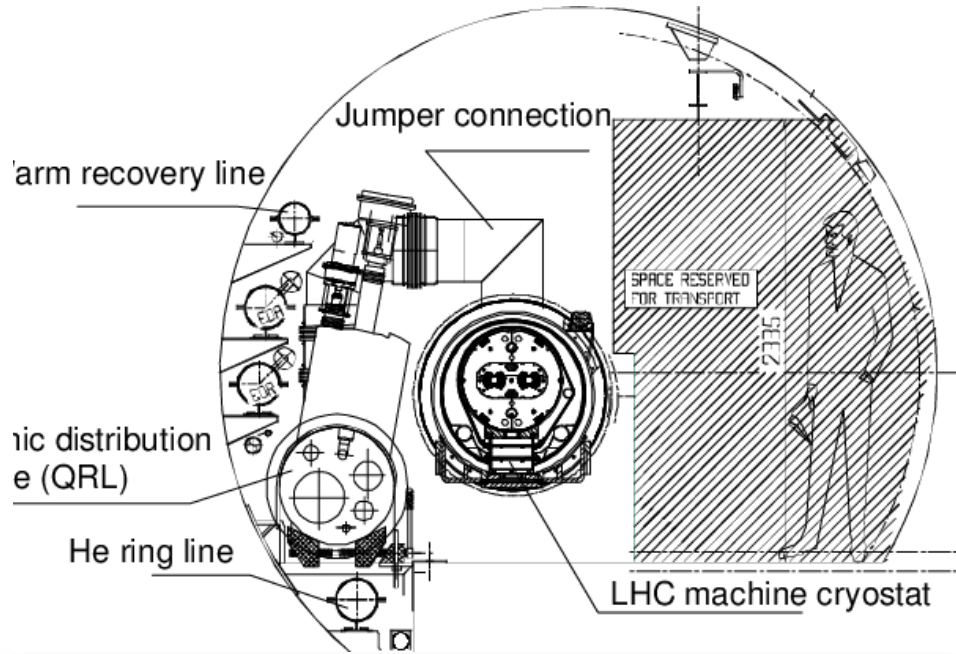


HFM 13 T dipole



The HIE Isolde cryo-modules

A few examples at CERN transfer lines, valve boxes



Functions of a SC device cryostat

Main function: house a SC device to enable it's operation.

Two technical requirements:

1. Mechanical housing of the device:

- Supporting, accurate positioning and alignment of SC devices in accelerators

2. Thermal efficiency:

- Cooling at cryogenic T (steady state, CD, WU)
- Low T preservation → optimal thermal insulation

Often conflicting → calls for trade off design solutions

Many other complementary functions and requirements....:

- Cryogenics operation and control → specific equipment (piping, ph.separators, valves, instrumentation etc.)
- SC device powering: → magnet current leads, cavity RF power couplers/HOMs, etc.
- Integration of instrumentation (beam, vacuum, cryo, control/diagnostics, etc.) → feed-throughs
- magnetic shielding
- Maintainability (accessibility ports)
- Handling and transport features
- ...

Accelerator architecture and cryostat layouts



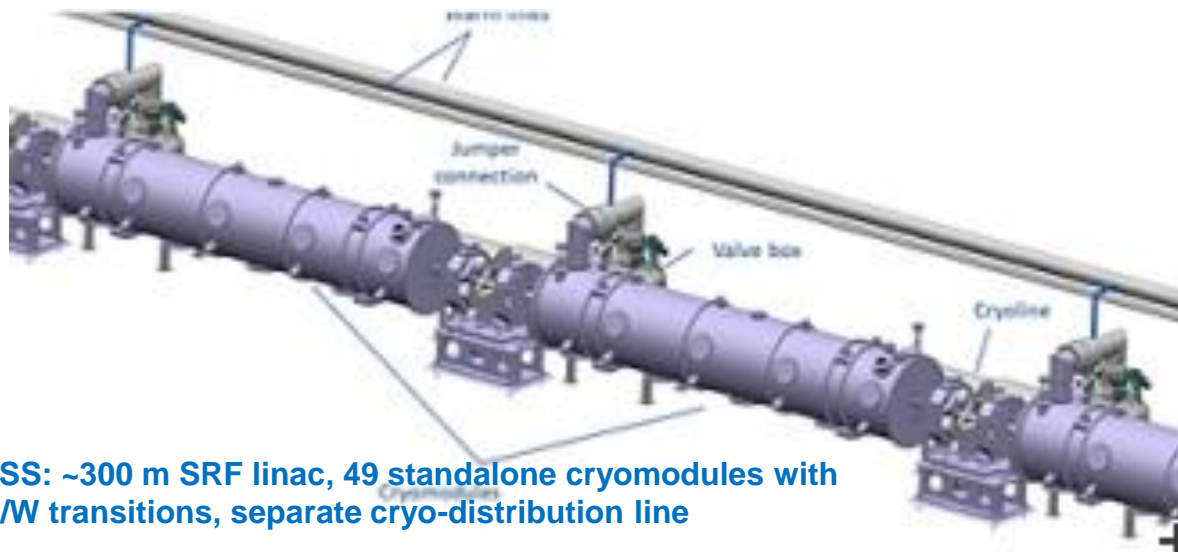
LHC: 2.7 continuous cryostats with separate cryo-distribution line (QRL)

Some key aspects:

- Continuity of SC magnets electrical circuits
- Thermal efficiency of continuous cryostats with integrated cryo-distribution
- C/W transitions: costs and heat loads
- RT equipment needs (e.g. beam instrumentation, beam sect. valves, non-SC magnets, etc.)
- Segmentation for maintainability (e.g. SRF CM can be replaced)
- Staged machine installation (e.g. SRF energy increase)



XFEL main linac: 96 CM, 1.7 km quasi-continuous cryostat with integrated cryo-distribution line.



ESS: ~300 m SRF linac, 49 standalone cryomodules with C/W transitions, separate cryo-distribution line

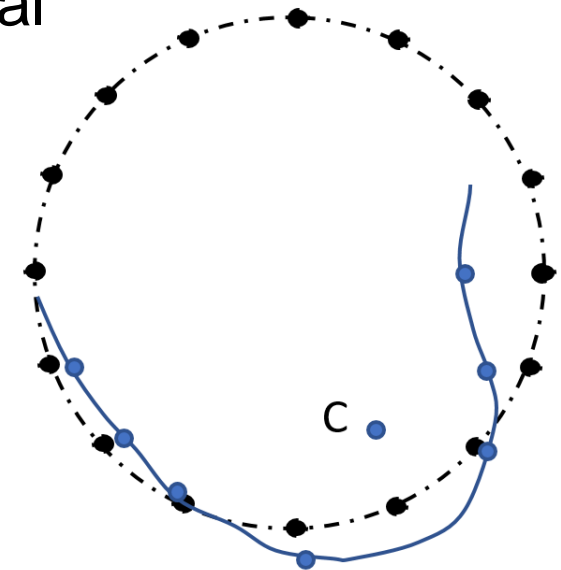
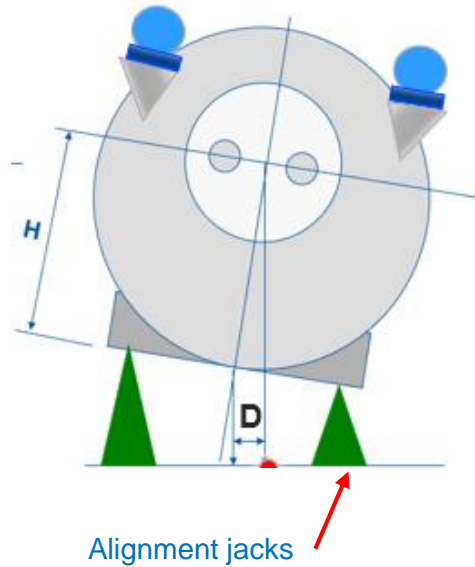
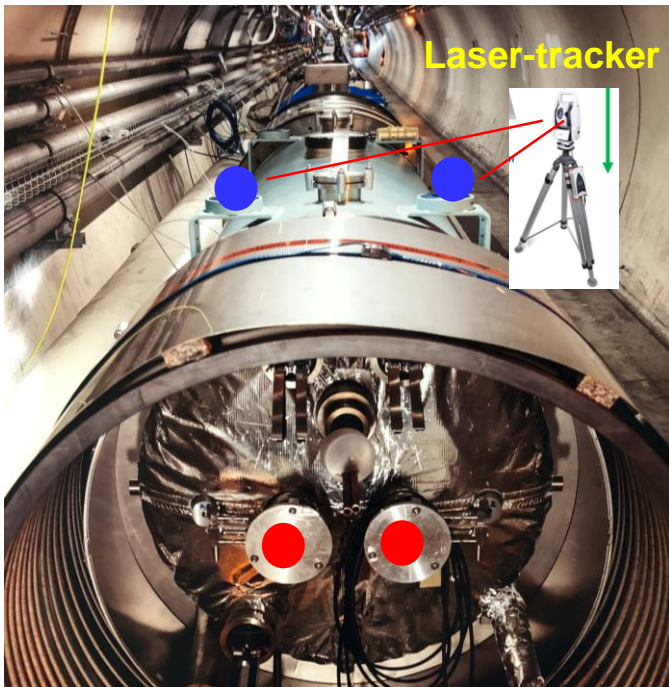
→ No general rule, but “long” machines opt for continuous cryostats to maximize:

- Dipole magnetic length in circular machines (like LHC)
- Real estate accelerating gradient in linacs (XFEL, ILC)

Housing and alignment requirements in accelerators

- *Accurate & reproducible* alignment of the SC device w.r.t. a machine reference network

- Survey measures **fiducials** on the **cryostat vessel** (not the device inside the vessel!)
- Typically alignment within a **few tenths of mm** w.r.t. nominal



Aligning elements in a ring

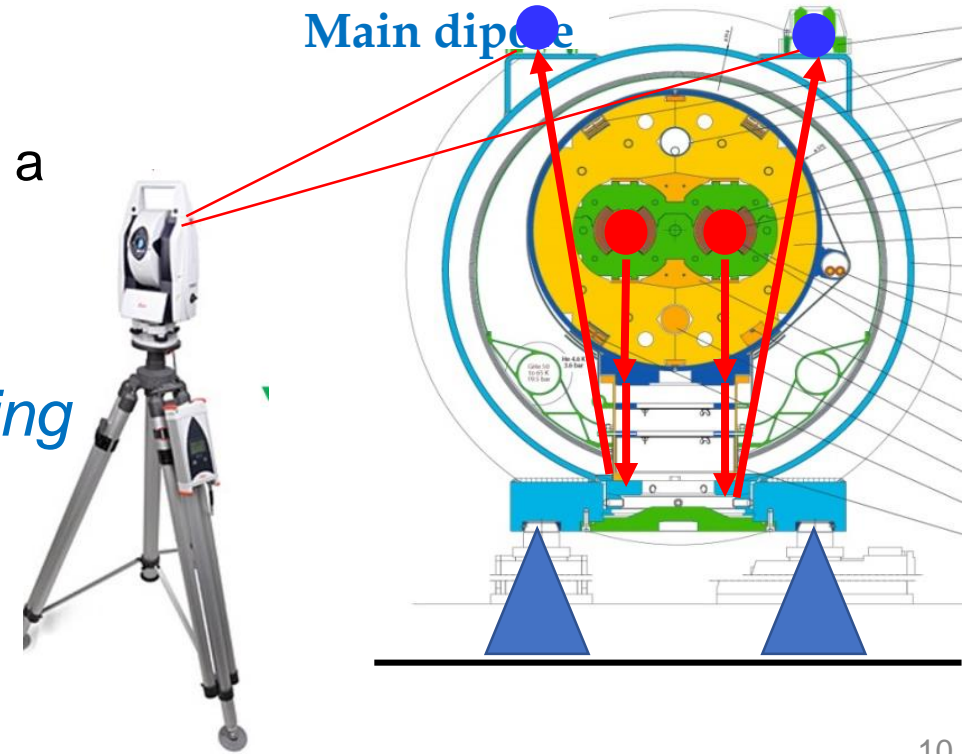
- Survey assumes that the **cryostat** and the inner **SC device** are **rigid bodies** !
- **Alignment** is done by adjusting **external jacks**

Housing and alignment requirements in accelerators

- Cryostats/SC device are not rigid bodies
- SC devices are “weakly” supported inside the cryostat (for thermal efficiency)
- Cryostat vessels are (generally) “relatively” rigid, and not subject to “excessive” permanent deformation
- SC device supporting system has to be designed to guarantee a known thermo-mechanical behaviour to ensure:

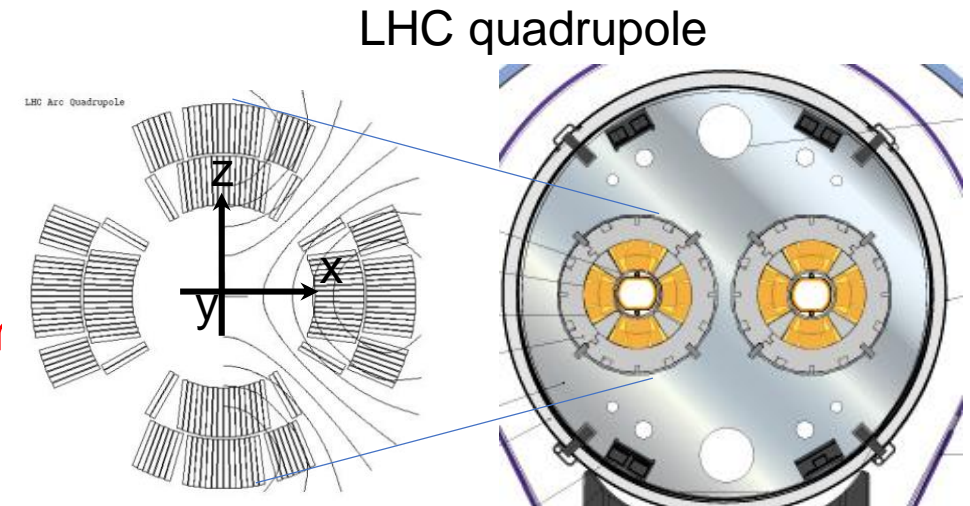
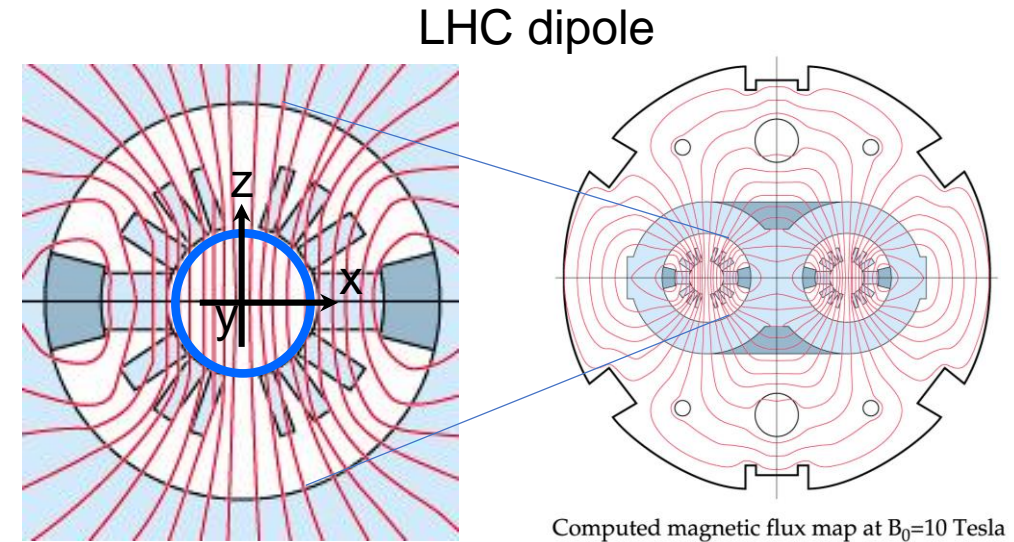
With no internal measurement of the position of the SC device (costly for large machines)

→ Cryostat design: “Accurate & reproducible **positioning** of the SC device w.r.t. to cryostat fiducials”



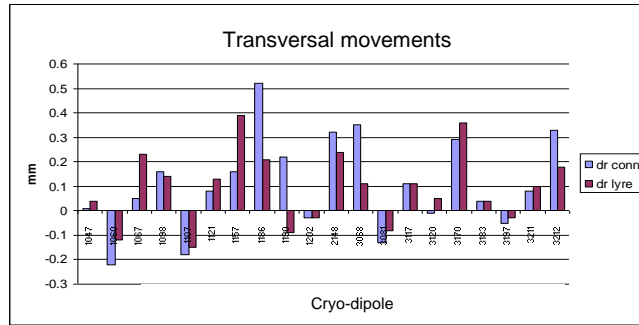
Positioning of SC magnets

- ✓ Position of the beam tube axis
- ✓ Measure magnetic field (main, multipoles) at warm and at cold (cold/warm correlation)
- Dipole magnet positioning accuracy:
 - x-z errors : more tolerant (field has no horizontal axis). (e.g. LHC < 0.48 mm radial (r.m.s.) after 1 year)
 - roll angle (about y) errors: sensitive (gives a kick out of orbit plane) (e.g. LHC < 0.7 mrad (r.m.s.) after 1 year)
- Quadrupole magnet positioning tolerances:
 - x-z errors : sensitive (magnetic axis). (e.g. LHC < 0.37 mm radial (rms) after 1 year)
 - roll angle (about z) errors: more tolerant (e.g. LHC < 1 mrad (rms) after 1 year)

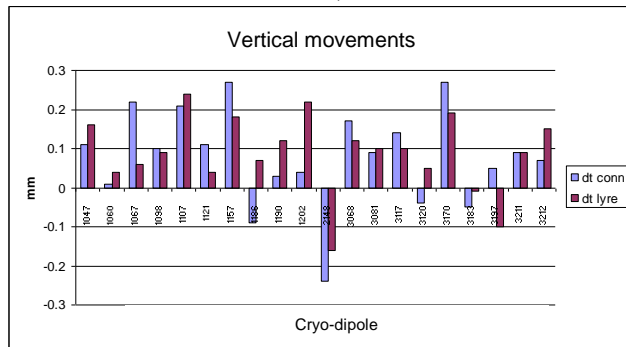


LHC geometrical stability: survey measurements

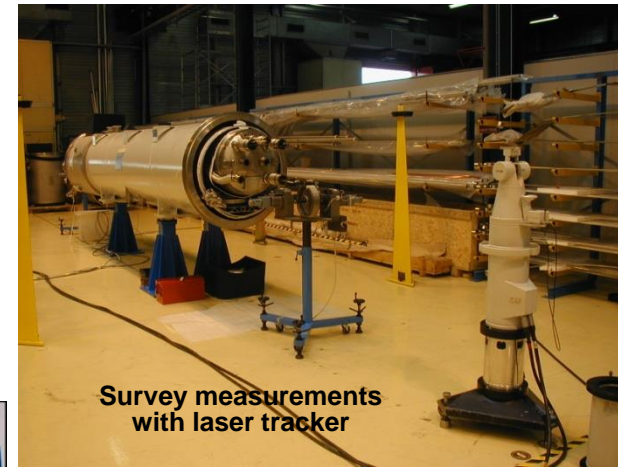
- Cold mass position stability w.r.t. fiducials measurements on 20 cryo-dipoles After transport to the tunnel



Mean: +0.1mm; r.m.s.: 0.17mm



Mean: +0.08mm; r.m.s.:0.11mm



Survey measurements with laser tracker



ROCLA vehicle



100 m descent to the tunnel



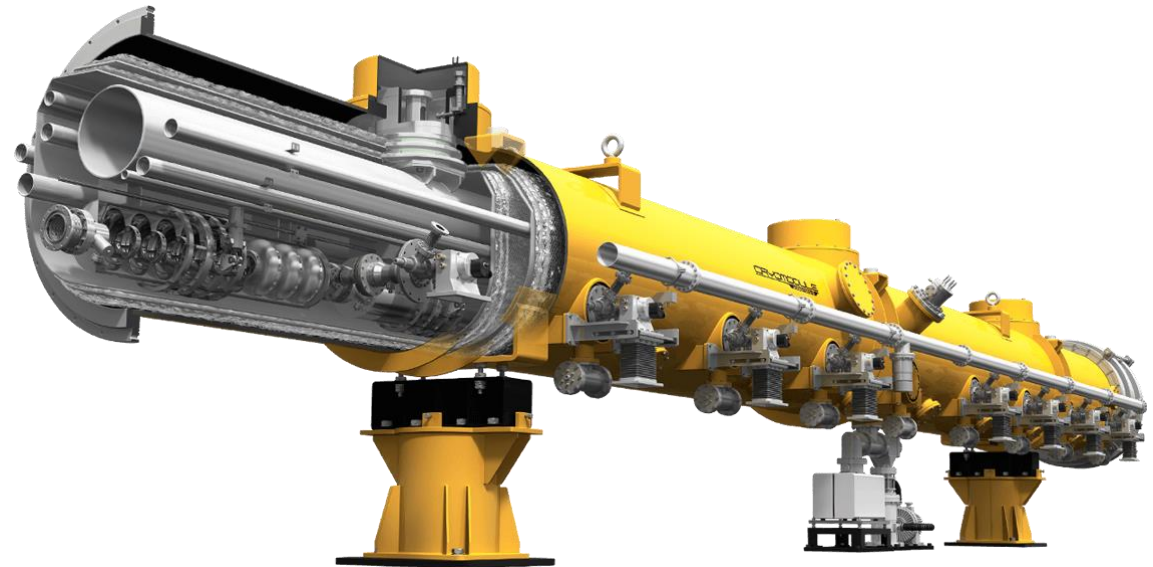
Tunnel transportation

- Quad CM positional stability and reproducibility at cold

Arc SSS (392 units)	Horizontal		Vertical	
	Mean [mm]	St.Dev. [mm]	Mean [mm]	St.Dev. [mm]
Positional reproducibility after 1 cool-down/warm-up cycle	-0.08	0.42	0.04	0.43
Cool-down movements	-0.17	0.22	-1.3	0.36

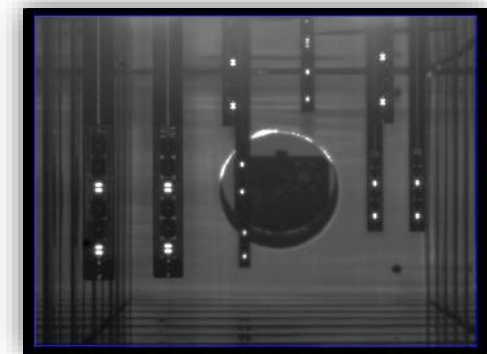
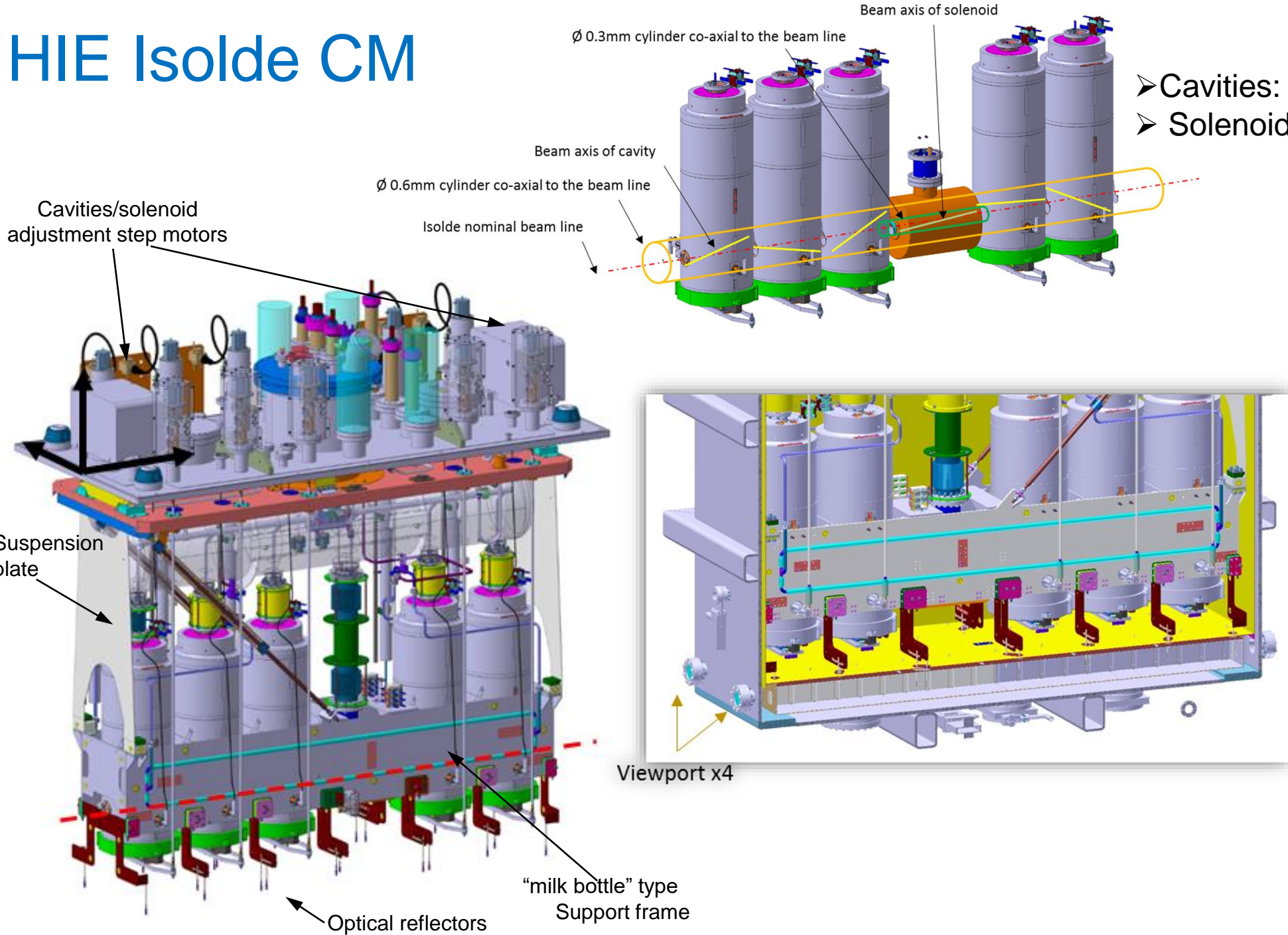
Positioning of SRF cavities

- In general, less stringent **positioning tolerances**. Also, cavities are **smaller** and **lighter** than magnets → less demanding support systems
- Main **effects of misalignment**:
 - ✓ increased **beam losses**
 - ✓ beam **emittance growth**
- Typical figures (r.m.s.):
 - ✓ **ILC**: radial ~ 0.3 mm, tilt ~ 0.3 mrad
 - ✓ **HIE Isolde CM (next slide)**:
 - Cavities: transverse $< \pm 0.45$ mm
 - Solenoid: transverse $< \pm 0.23$ mm

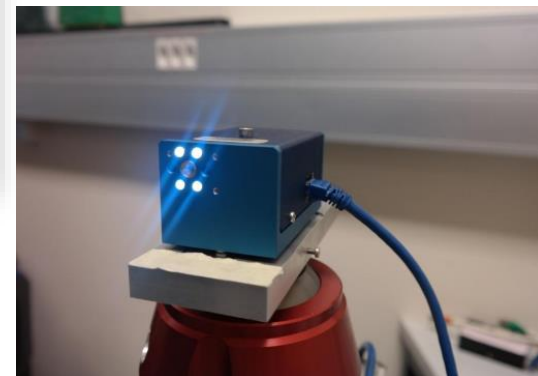


HIE Isolde CM

- Cavities: transverse $< \pm 0.45$ mm
- Solenoid: transverse $< \pm 0.23$ mm



Targets viewed from viewports

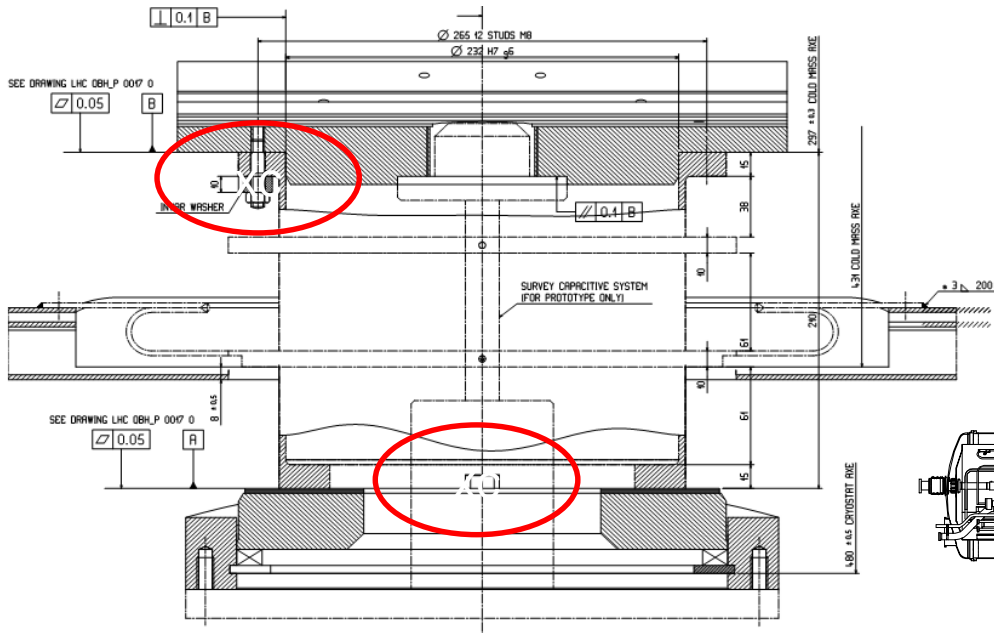
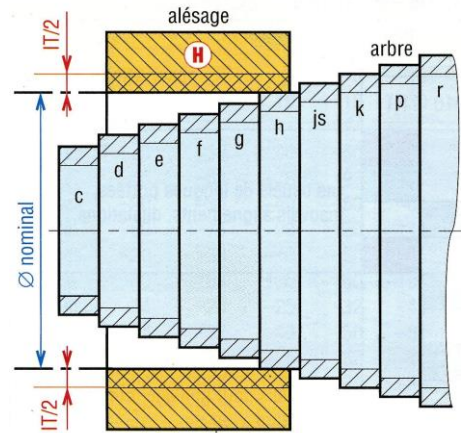


HBCM optical CCD cameras

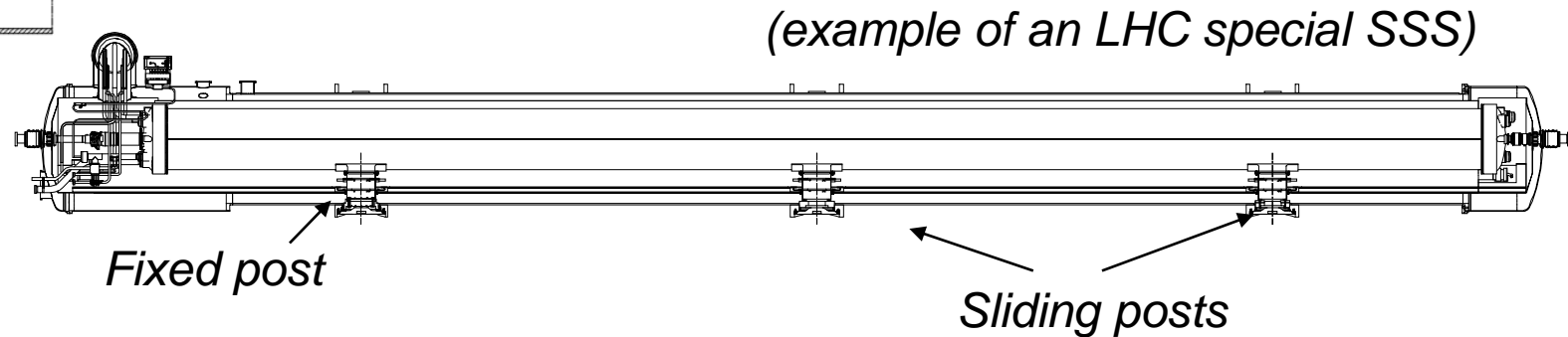
Mechanical accuracy in cryostats assembly

- Positioning accuracy is ensured by precision fitting at assembly
- Machining IT Grade range: 8-10
- Typical close fits: H7/g6

Application, Process	Tolerance (μm)	IT Grade
Slip blocks, reference gages	1-2	1
High quality gages, plus gages	2-3	2
Good quality gages, gap gages	3-5	3
Fits produced by lapping	4-10	4
Ball bearings, Diomand or fine boring, fine grinding	5-12	5
Grinding, fine honing	6-20	6
High quality turning, broaching	12-35	7
Center lathe turning and boring, reaming	14-50	8
Horizontal or vertical boring machine	30-80	9
Milling, slotting, planing, metal rolling or extrusion	50-100	10
Drilling, rough turning and boring, precision tubing	70-140	11
Light press work, tube drawing	120-240	12
Press work, tube rolling	150-500	13
Die casting or molding, rubber moulding	250-1000	14
Stamping	400-1400	15
Sand casting, flame cutting	500-2000	16



Central support post interfaced to vessel/coldmass (232 H7/g6 → play: 15-90 microns)



Positioning reproducibility in cryostats assembly

Positioning reproducibility on:

1. Every cryo-assembly throughout lifetime (transport, thermal-cycles, etc.) → design concepts
2. Across total population of cryo-assemblies → quality & cost

Design concepts:

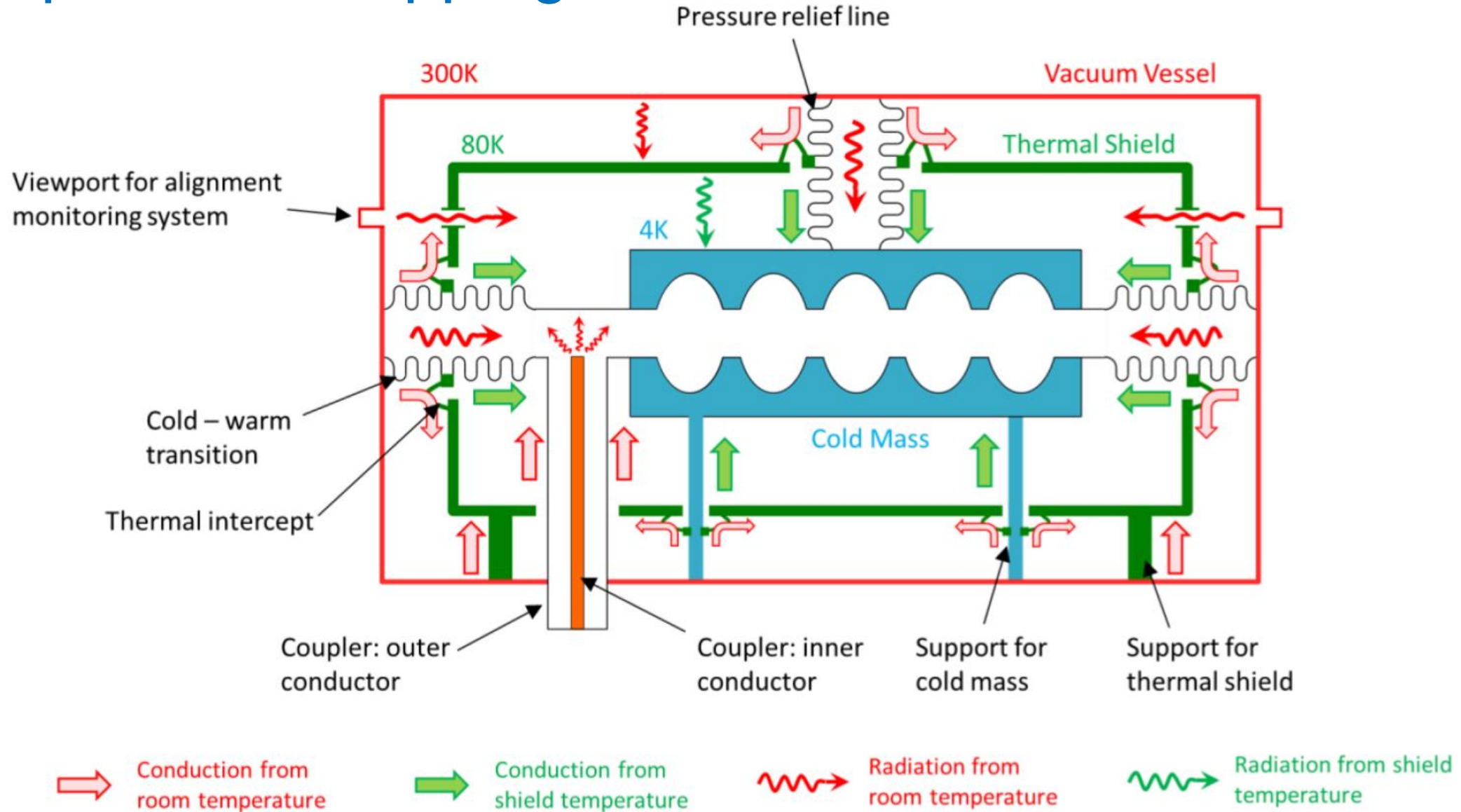
- Cryostat components in **elastic domain** (limited local plasticity)
- **Stress relieving** for dimensional stability (vacuum vessels after welding)
- **Reproducibility to thermal cycles** (limited plays & stick-slips, no micro-cracking etc.)
- **No creep**
- ...

→ Prototyping and testing are mandatory !

Heat Loads and thermal design

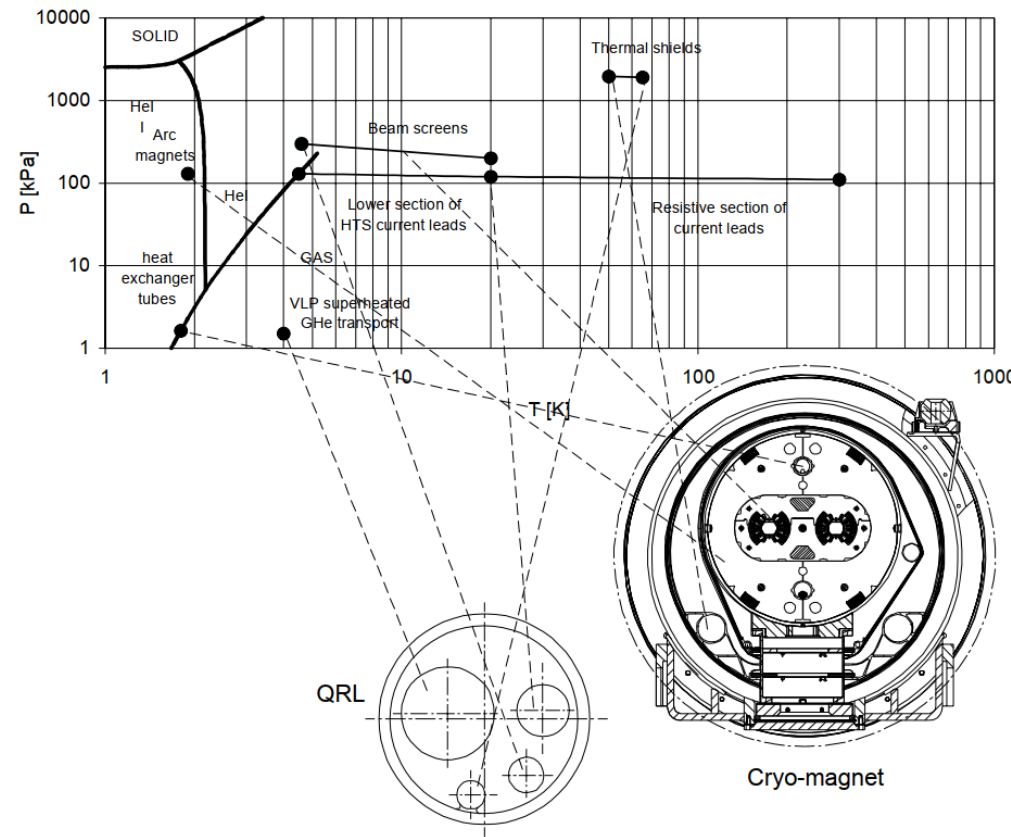
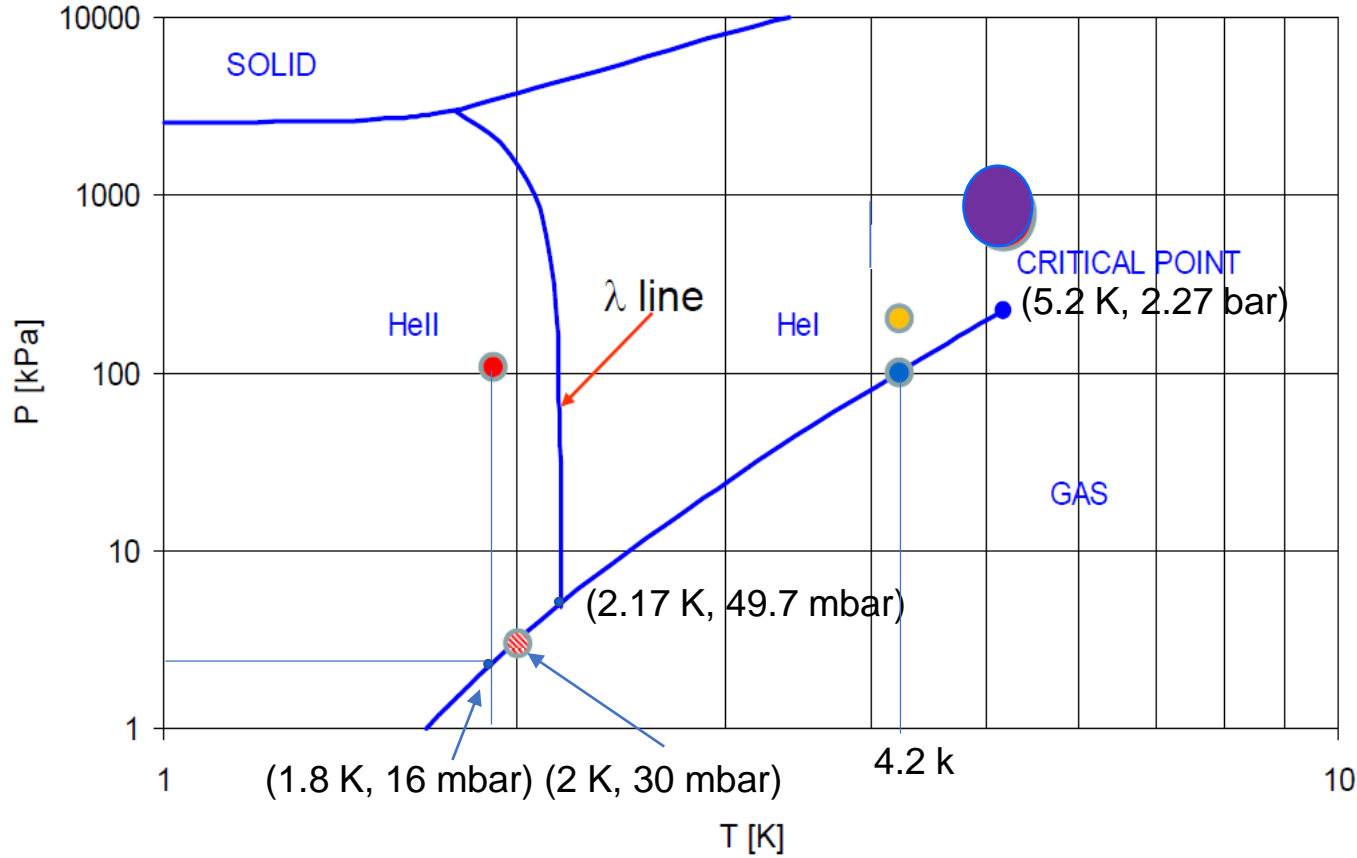
- Static Heat Loads
 - Very much **cryostat related** (supports, shielding, feedthroughs, etc.)
 - **always present** when machine is cold
- Dynamic Heat Loads
 - inherent to **SC device operation** (e.g. resistive heating)
 - and **beam interaction** (e.g. synchrotron radiation, HOM)
 - Dominant but **only present during machine operation** (duty cycles)
- Ensure operation T of the SC device (T_{op})
 - T_{op} depends on SC needs (normally below 25 K) → **helium**
 - helium phase diagram → **choice of useful working points** (p. T)
- Thermal design for thermodynamically efficient operation (i.e. minimal W_{el} of cryoplant):
 - **Steady state** helium heat transfer from the source (SC device, thermal shields, etc.) and transport to the cryoplant → **ΔT budgets, heat and helium mass flows, pressures**
 - **CD/WU phases** → thermo-mechanical transients of SC device, cryogenic cooling power → **ΔT budgets, mass flows, pressures**

Temperature mapping and Heat Loads



Inspired by P. Duschene and JP. Thermeau

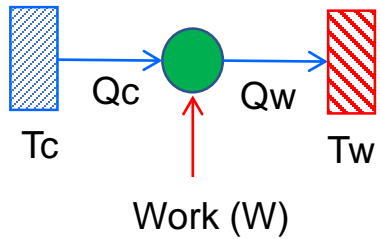
What temperature and pressure ?



- Pressurized He II, Magnets (LHC, Tore Supra)
- Pressurized He I, Magnets (HERA, Tevatron) ← Higher press. to limit voltage breakdown (Paschen curve in He)
- Saturated He II, SRF (CEBAF, TTF, SNS, EXFEL, ESS, ILC)
- Pool boiling, He I, SRF (HERA, LEP, LHC, KEKB)
- Supercritical helium: cooling of thermal shielding

Refrigeration efficiency (Carnot principle)

- Extracts a heat load at $T_c < RT$ and rejects it at T_w (normally RT)
- **Carnot cycle**: minimum mechanical work (i.e. Maximum **Coefficient of Performance, COP_{max}**), depends solely on T_w and T_c
- All **real machines** have a lower efficiency (**non-reversible transformations**), expressed in **fraction of COP_{max}**



1st and 2nd laws of thermodynamics

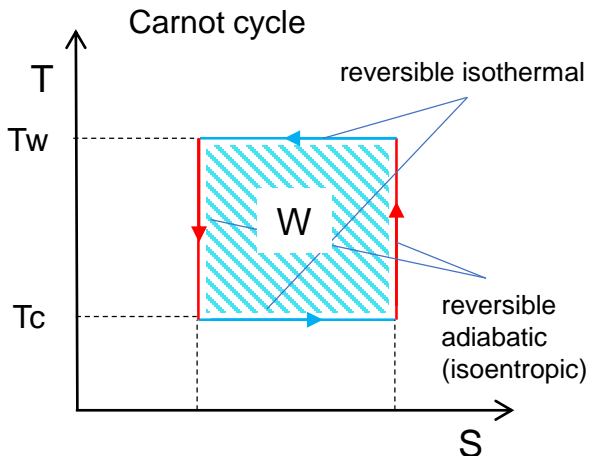
$$Q_c + W = Q_w$$

$$\frac{Q_w}{T_w} \geq \frac{Q_c}{T_c}$$

$$\rightarrow W \geq Q_c \frac{T_w - T_c}{T_c} = \frac{Q_c}{COP_{max}}$$

$$COP_{max} \text{ (Carnot)} = \frac{T_c}{T_w - T_c}$$

Efficiency of a real machine is expressed in *fraction (or %) of Carnot*.



$$W = \frac{1}{COP} Q_c = \frac{1}{x\% COP_{max}} Q_c$$

Fluid	T [K]	Carnot factor (1/COP _{max} or W/Q _c) [W/W] (considering T _w =293K)
LN2	77	2.8
LH2	20.4	13.4
LHe	4.2	68.4
LHe	1.8	161.8

Efficiency for large cryoplants

State-of-the-art figures for large cryo-plants (LHC-like, ~18 kW @ 4.5K):

- COP @ 2 K → ~ 15% of Carnot (990 W_{el}/W_{th})
- COP @ 4.5 K → ~ 30% of Carnot (210 W_{el}/W_{th})
- COP @ 50 K → ~ 30% of Carnot (16 W_{el}/W_{th})

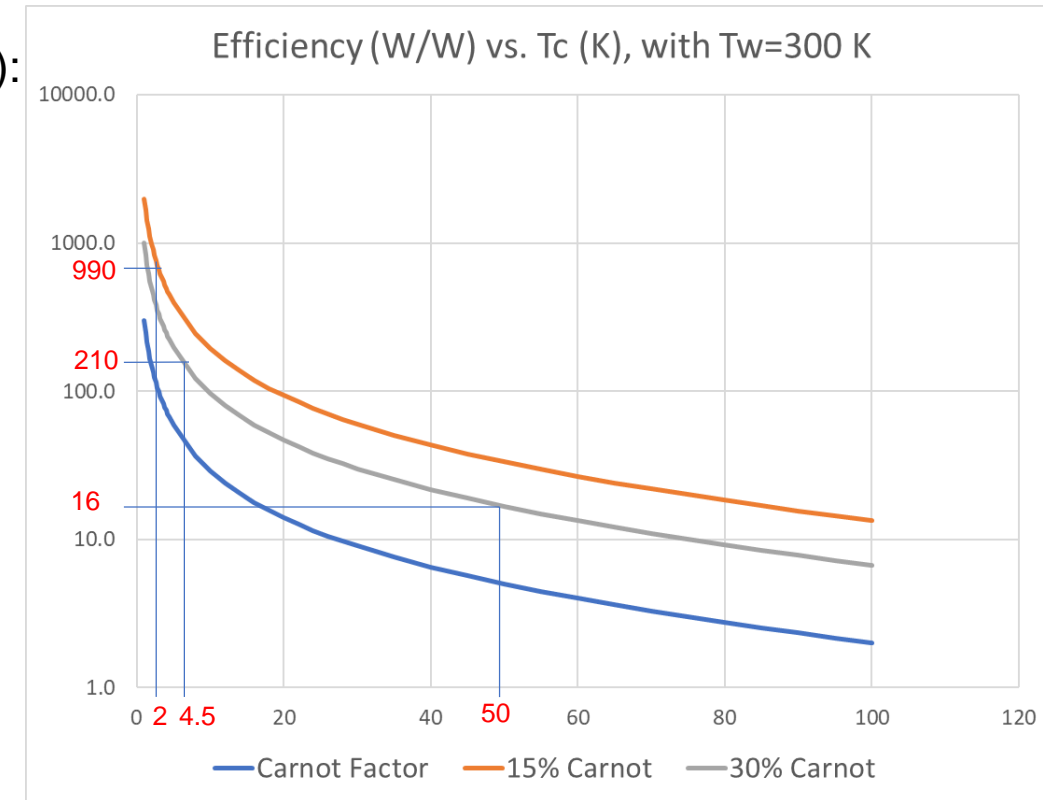
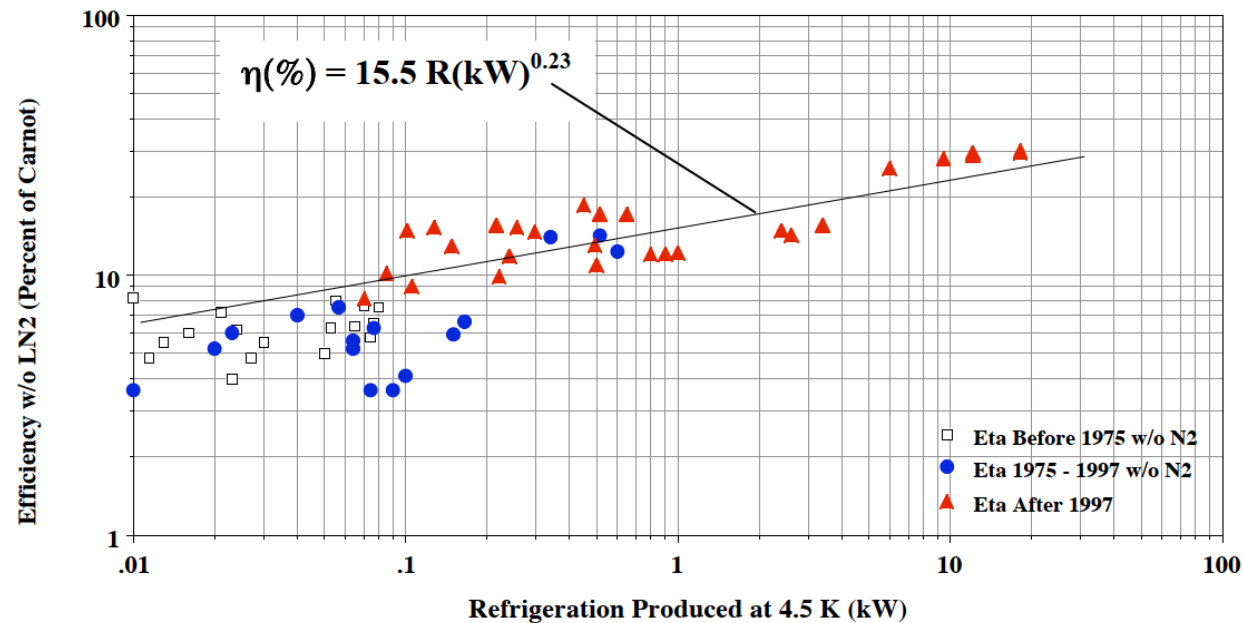


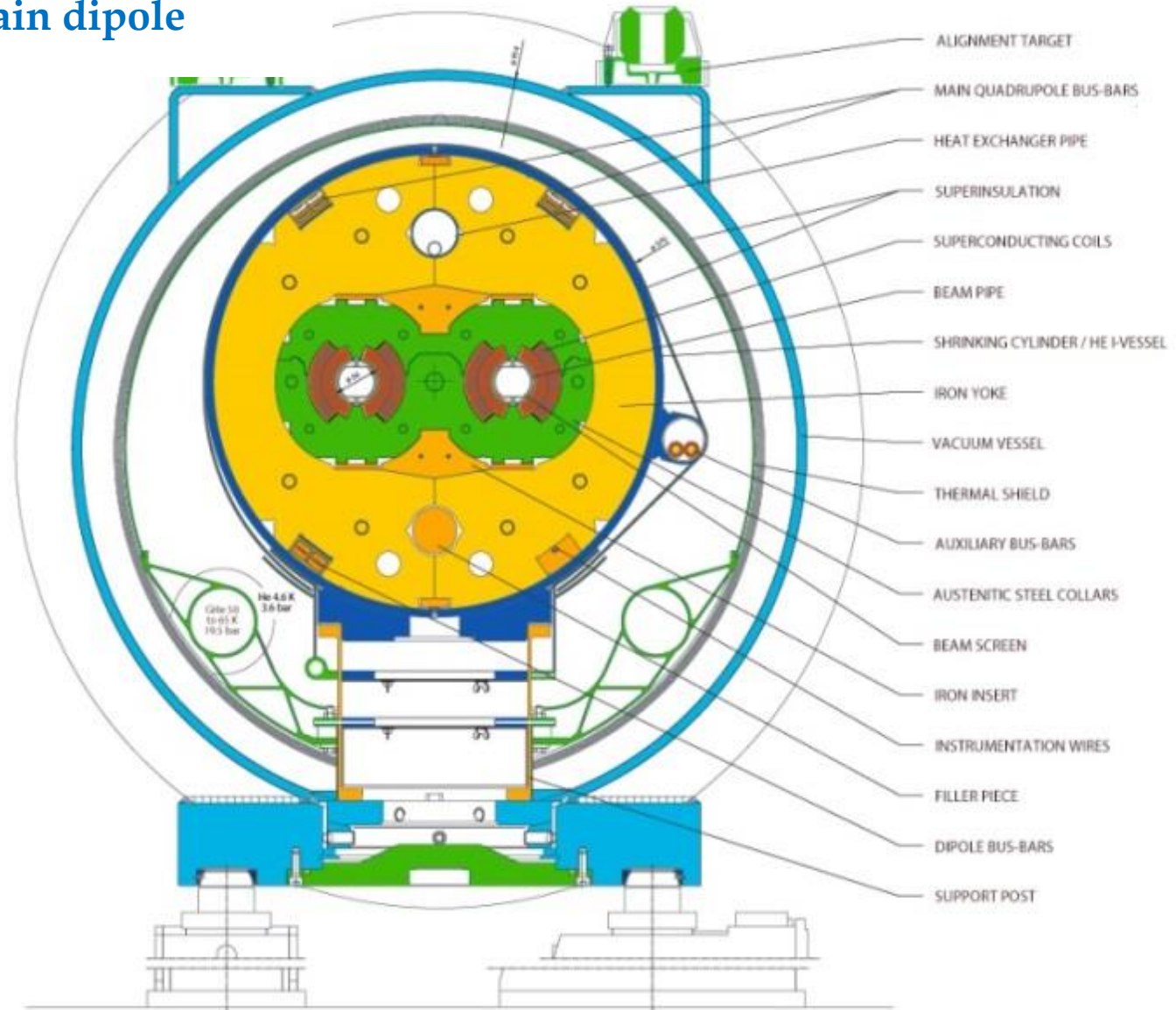
FIGURE 1. Helium Refrigerators Efficiency (percent of Carnot) as a Function of 4.5 K Refrigeration (kW). In all cases, there is no liquid nitrogen pre-cooling in the machines. The open squares are for machines made before 1975; closed circles are machines from 1975 to 1997, and closed triangles are for machines after 1997.

LHC magnet Cryostats

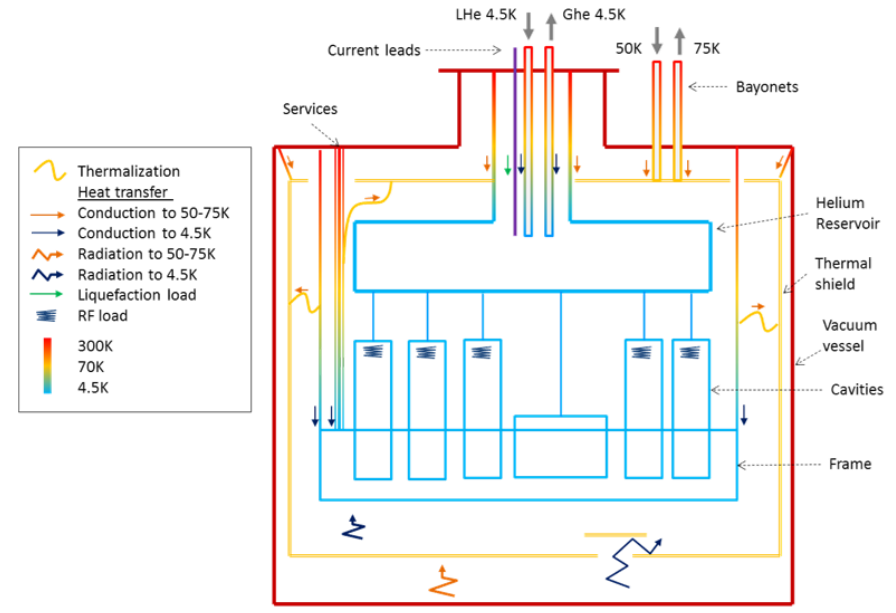
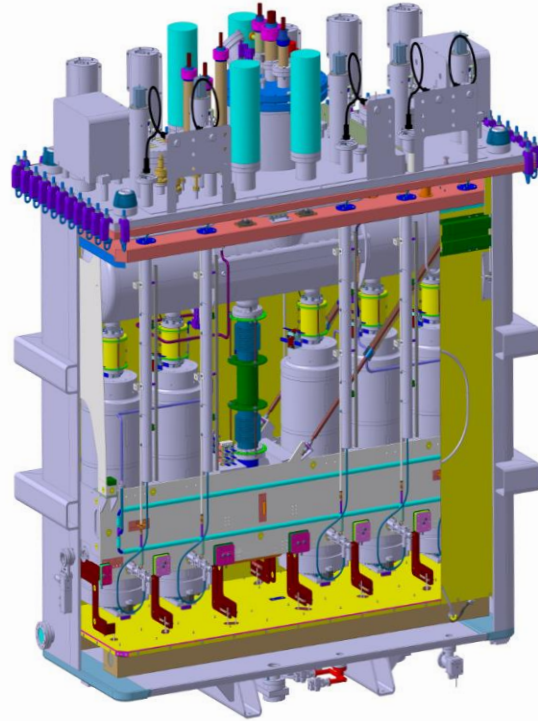
Main dipole

- Static Heat Loads:
 - ✓ 0.25 W/m at 1.9 K
 - ✓ 5 W/m at 50-65 K

- Dynamic Heat Loads (resistive heating + beam induced effects):
 - ✓ ~ 0.2 W/m at 1.9 K



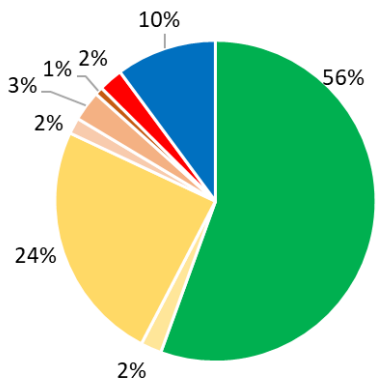
HIE Isolde Cryomodule: No MLI



	Nominal [W]
To GHE circuit 50-75K	362
To LHE circuit 4.5K	70
+ liquefaction load 0.03 g/s	

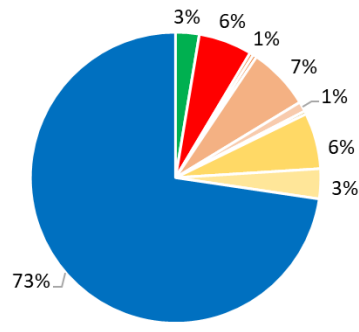


low-ε Ni plated (MLI-free)
Cu thermal shield



- Radiation heat load
- Thermal shield supports
- Reservoir thermalisation
- Suspension sheets thermalisation
- RF cables thermalisation
- GHe Bayonets (CM side)
- Instrumentation
- Dynamic load

Static and dynamic heat load to the GHe circuit.

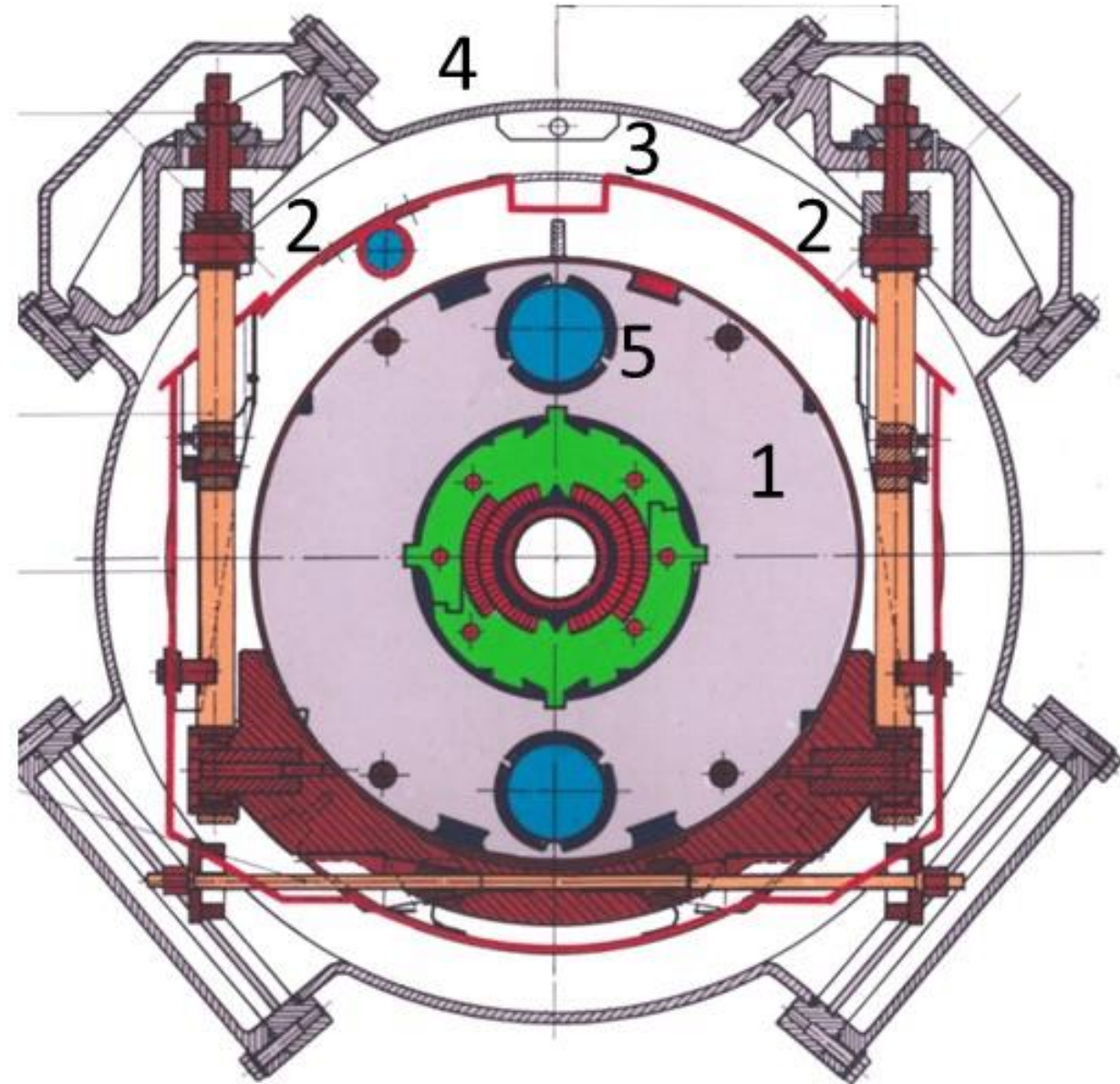


- Radiation heat load
- Reservoir thermalisation
- Diagonal rods
- Suspension sheets thermalisation
- RF supply cables
- RF pick-up cables
- Tuner-coupler rods
- Bayonets (CM side)
- Instrumentation
- Dynamic load

Static and dynamic heat load to the LHe circuit.

Hera Dipole

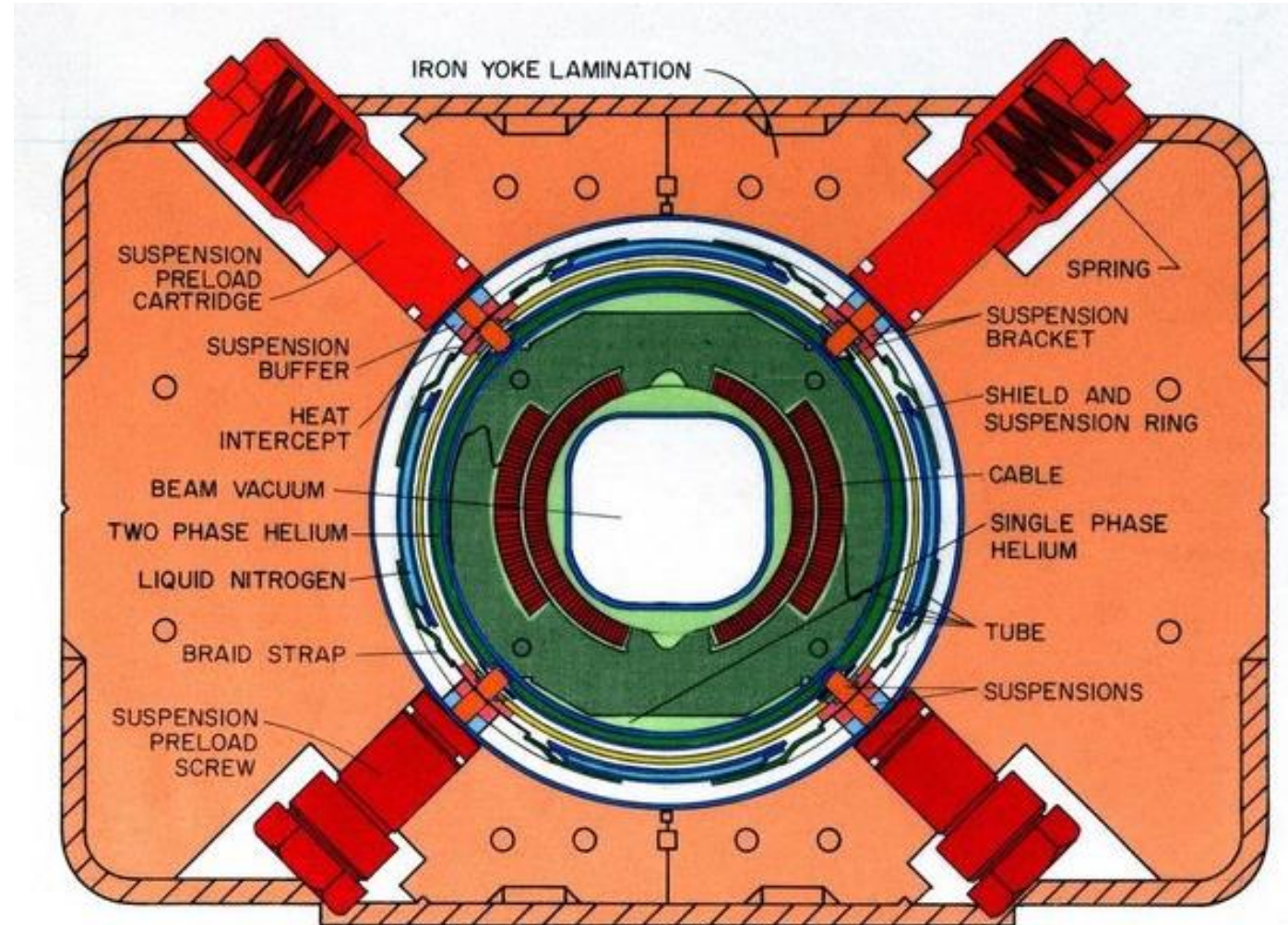
4.7 T, 75mm
9m
(4.5 K)



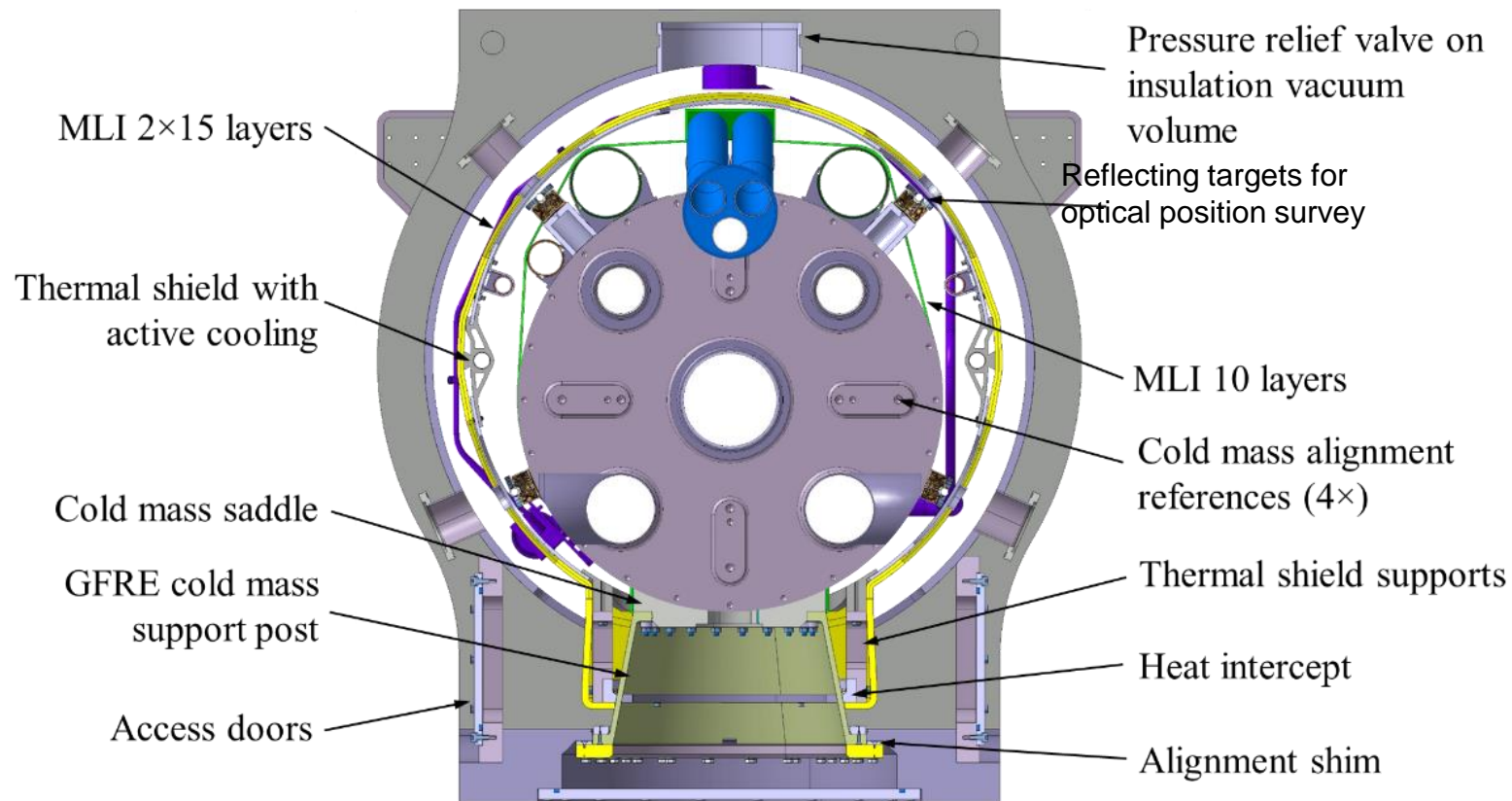
HERA dipole. 1 Helium vessel containing cold mass, 2 Suspension, 3 Radiation shield, 4 Vacuum vessel, 5 Helium pipes.

Tevatron Dipole

4.5 T, 76 mm
6m
(4.6 K)



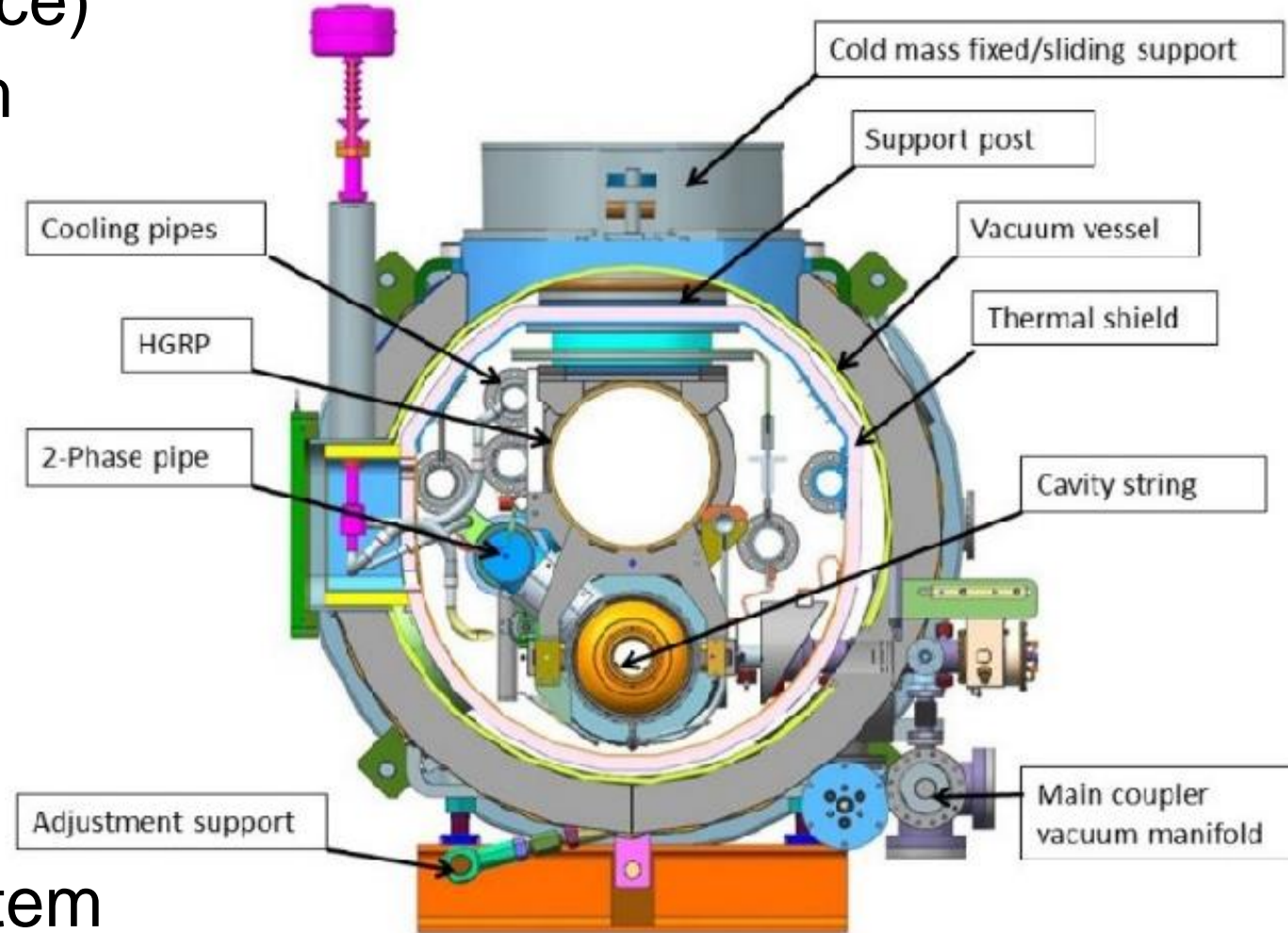
Hi Lumi LHC focusing quadrupole triplets



- NbTi SC magnets operated at 1.9 K (superfluid)
- Larger cold mass to be fitted within LHC dipole outer vacuum vessel diameter (tunnel limitations)
- Conical support posts for better mechanical stability
- Optical position survey and motorized external jacks (alignment in highly irradiated environment)

Typical breakdown of a SC device cryostat

- Helium tank (containing SC device)
- Internal (cold) supporting system
- Thermal shielding with MLI
- Vacuum vessel
- Cryogenic piping
- Instrumentation feedthroughs
- RF Couplers/HOM (for SRF)
- Current leads (for SC magnets)
- Magnetic shielding (for SRF, as needed)
- External supporting/aligning system



LCLS-II 1.3 GHz cryomodule (SLAC)



Thank you for your attention



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- CRYOCOMP® is a database code of the state and thermal properties for technical materials.
- NIST Cryogenic Materials database: <http://www.cryogenics.nist.gov/MPropsMAY/material%20properties.htm>