



# R&D perspective on MAPS

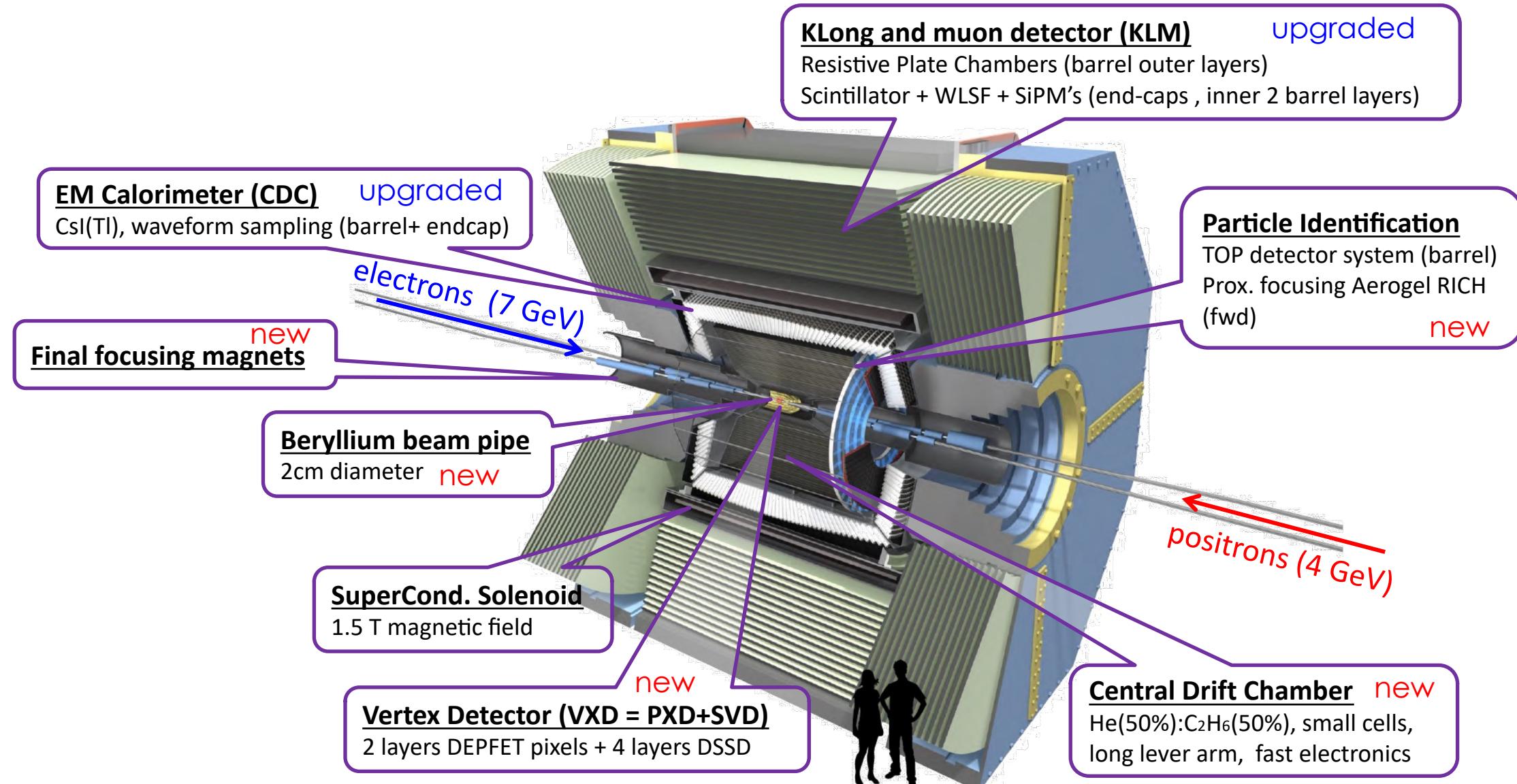
starting with the VXD upgrade

Jerome Baudot

Based on the work of the *Belle II VTX collaboration*

- Belle II context
- VXD upgrade: turning a pixel matrix into a detector
- Possibilities with MAPS beyond 2030

# Belle II detector:



# The Belle II program & upgrades

## ■ Physics program @ SuperKEKB

- Based on accumulation of  $50 \text{ ab}^{-1}$  of  $e^+ + e^-$  at  $\sqrt{s} = M_{Y(4S)}$   
=> requires instantaneous luminosity close to  $6 \times 10^{35} \text{ cm}^{-2} \cdot \text{s}^{-1}$



SuperKEKB collider implementing  
the nano-beam scheme @ high currents

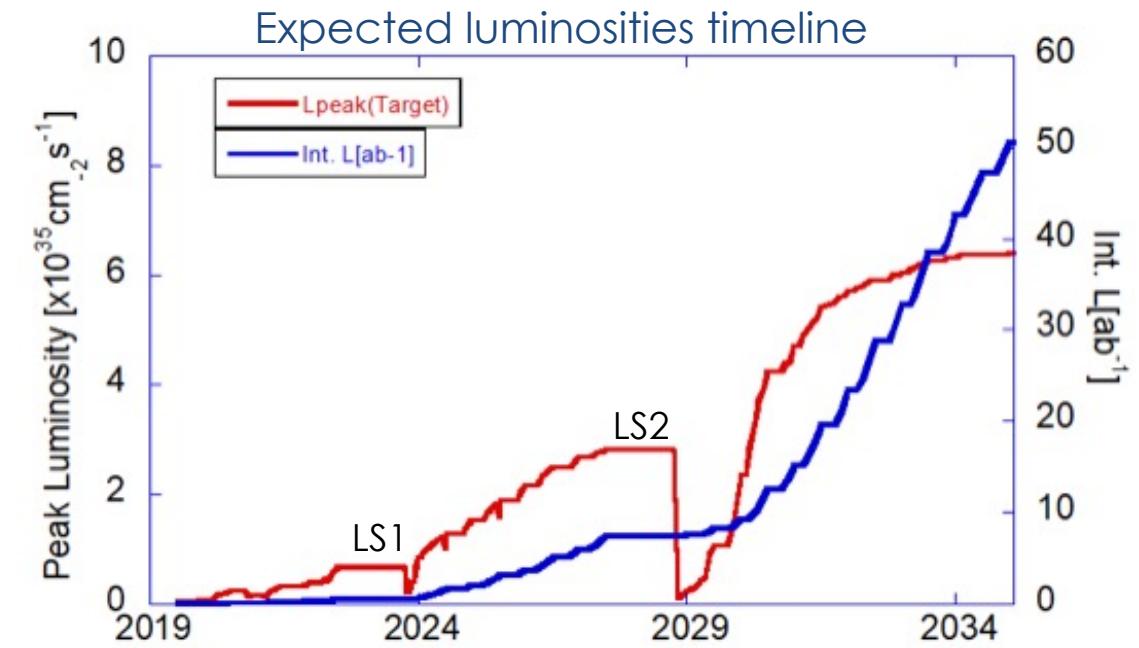


High collision rate

High beam-induced BKG

## ■ Vertexing & tracking upgrades

- Getting more physics with increasing BKG  
=> higher space-time granularity
- **Vertex upgrade ~LS2 (short-term)**
  - DEPFET + DSSD → MAPS (VTX proposal)
  - CDR being prepared for June 2023
- **Tracker upgrade > LS2 (long-term)**
  - CDC → partially/totally replaced by MAPS or TPC
  - Studies on-going



- **5 layers**

- About 2000 OBELIX DMAPS
- Fast enough for including all layers in tracking
- Services mostly on one side (backward region)
- Total event size ~30 kBytes

- **iVTX = 2 inner ladders**

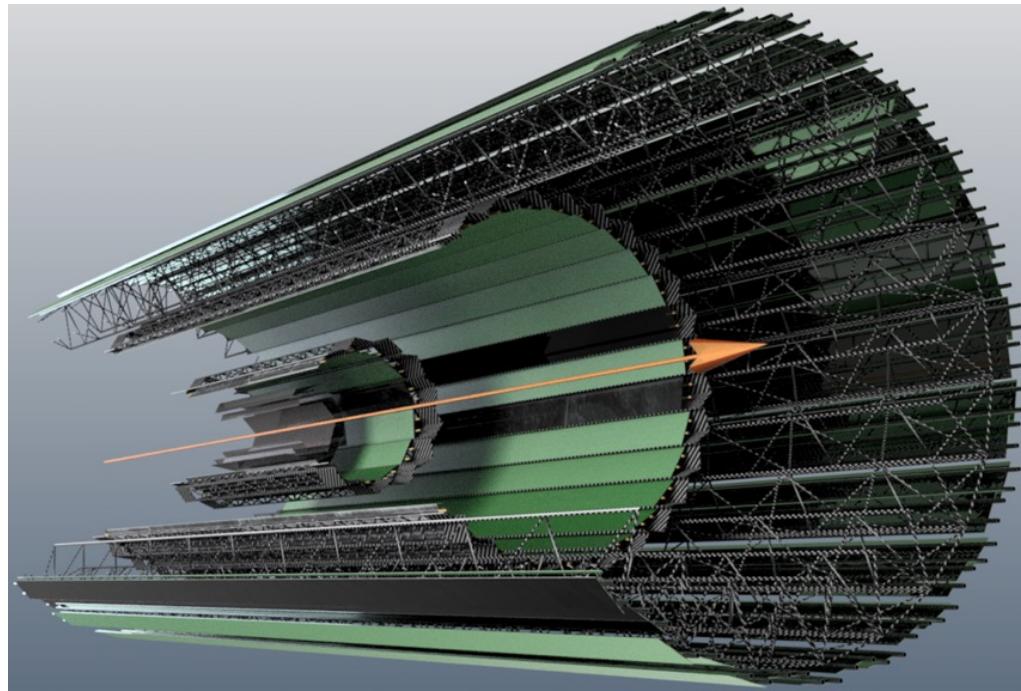
- radius 1.4, 2.2 cm
- short length ~12 cm
- material budget ~0.1 %  $X_0$

- **oVTX = 3 outer ladders**

- radius 4 → 14 cm
- length → 70 cm
- material budget 0.3 → 0.8 %  $X_0$

- VTX collaboration

HEPHY, Vienna	University of Bergamo
CPPM, Marseille	INFN, Pavia
IJCLab, Orsay	INFN & University of Pisa
IPHC, Strasbourg	IFAE, Barcelona
University of Bonn	IMB-CNM-CSIC, Barcelona
University of Dortmund	IFCA (CSIC-UC), Santander
University of Goettingen	IMSE-CNM-CSIC, Seville
KIT, Karlsruhe	IFIC (CSIC-UV), Valencia
KEK, Tsukuba	ITAINNOVA, Zaragoza



# VTX sensor requirements

FROM PHYSICS SIMULATION	Belle-II VTX
Spatial res.	< 10-15 $\mu\text{m}$
Mat. Budget inner-outer layers	0.1-0.8 % $X_0/\text{layer}$
Max hit rate	120 MHz/cm <sup>2</sup>
Time precision	<100 ns
Trigger (freq) (delay)	30 kHz 5-10 $\mu\text{s}$
Rad.hard. (TID) 10years (fluence)	<1 MGy $<5 \times 10^{14} n_{\text{eq}}/\text{cm}^2$

+ covering at least current VXD acceptance  

- radii from 1.4 to 14 cm
- angle from 17 to 160 degrees

CHOOSING A MATRIX	Belle-II DMAPS	TJ-Monopix2	MIMOSIS-1	ATLASPix3
	exp ~2025	2020	2020	2019
Techno		Tower 180 nm	Tower 180 nm	TSI 180 nm
Sens. area	~30x15 mm <sup>2</sup>	17x17 mm <sup>2</sup> !	30x14 mm <sup>2</sup>	20x19 mm <sup>2</sup>
Sens. thick	~30 $\mu\text{m}$	25-100 $\mu\text{m}$	25-30 $\mu\text{m}$	<50 $\mu\text{m}$
Pitch	30 to 40 $\mu\text{m}$	33 $\mu\text{m}$	27x30 $\mu\text{m}^2$	150x50 $\mu\text{m}^2$ !
Signal digits	1 to few bits	7 bits ToT	1 bit	7 bits ToT
Integration	25 to 100 ns	25 ns	5 $\mu\text{s}$	25 ns
Hit rate	120 MHz/cm <sup>2</sup>	>100 MHz/cm <sup>2</sup>	70 MHz/cm <sup>2</sup>	>100 MHz/cm <sup>2</sup>
Bandwidth	320 MHz	320 MHz	2.5 GHz	1.3 GHz
Power	<200 mW/cm <sup>2</sup>	200 mW/cm <sup>2</sup>	50 mW/cm <sup>2</sup>	~140 mW/cm <sup>2</sup>
TID fluence	<1 Mgy $<5 \times 10^{14} n_{\text{eq}}/\text{cm}^2$	100 kGy $10^{15} n_{\text{eq}}/\text{cm}^2$	50 kGy $10^{14} n_{\text{eq}}/\text{cm}^2$	100 kGy $10^{15} n_{\text{eq}}/\text{cm}^2$

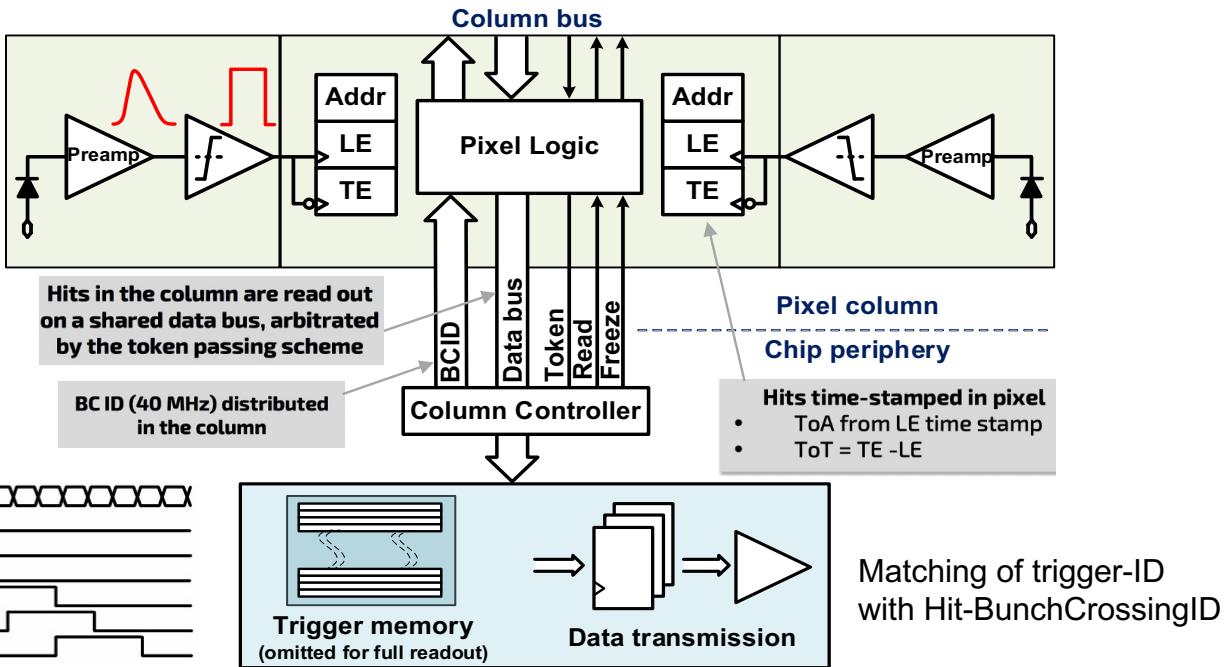
Forerunner for OBELIX sensor

# TJ-Monopix pixel matrix

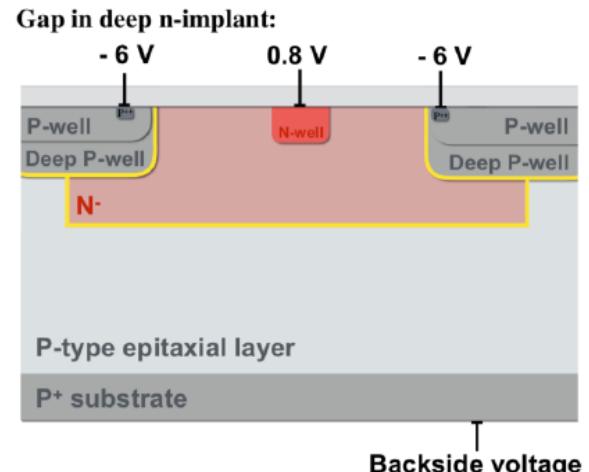
- Collaboration: Bonn, CERN, CPPM, CEA-IRFU  
[DOI: 10.1016/j.nima.2020.164403](https://doi.org/10.1016/j.nima.2020.164403)
- Column-drain read-out Inherited from ATLAS FE-I3
- Detection efficiency assessed up to  $1^{15} n_{eq}/cm^2$

=> Latest characterisation results:  
C.Bespin [Pixel 2022](#), L.Massacesi [TREDI 2023](#)

## The logic:

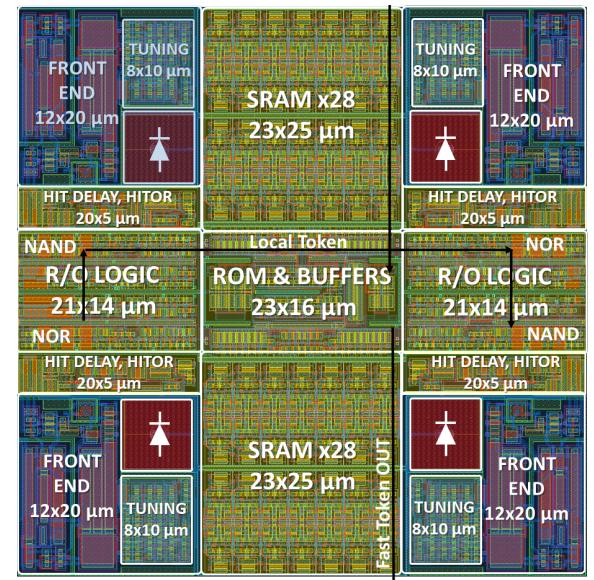


## The Pixel: 3 variants



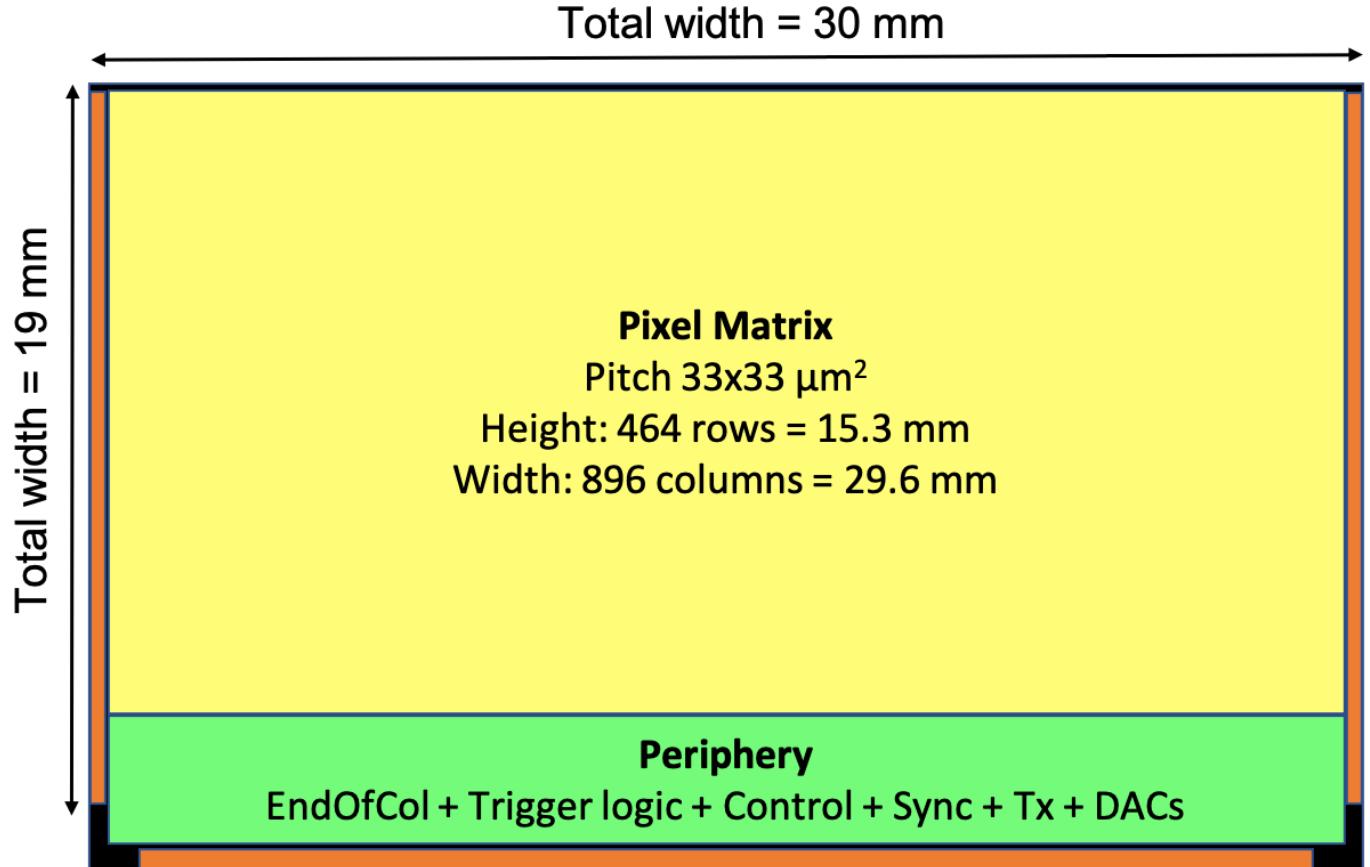
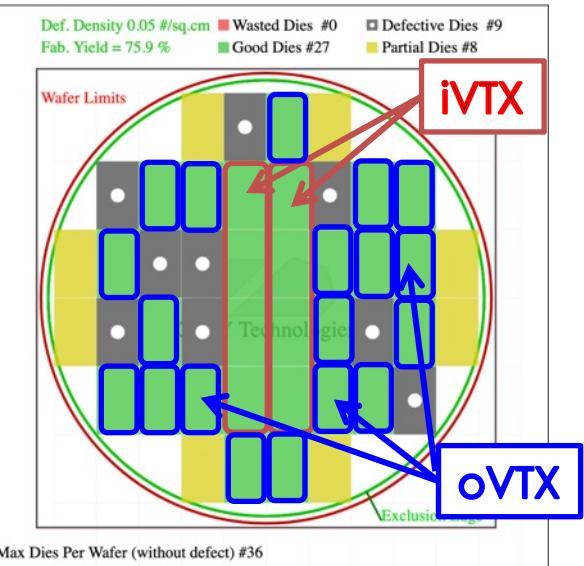
W.Snoeys et al.  
[doi: 10.1016/j.nima.2017.07.046](https://doi.org/10.1016/j.nima.2017.07.046)

## The Layout: 2x2 pixels



# OBELIX (Optimized BELle II pIxel) sensor

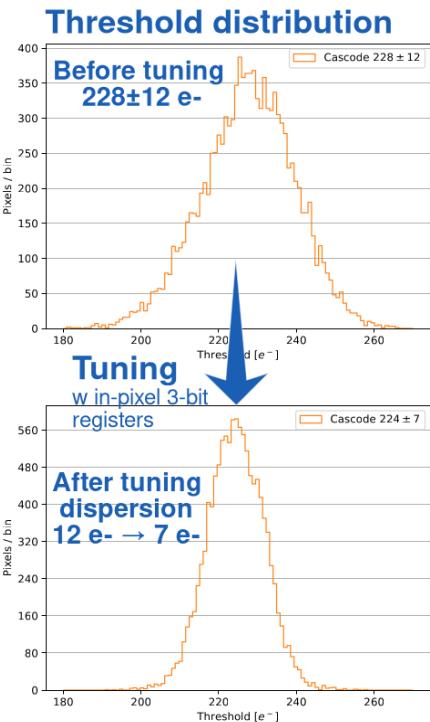
Size optimized  
to maximize (8) sets  
of 4 contiguous sensors



- Digital on-top design  
for continuous verification

## Pixel matrix

- Extension from TJ-Monopix2
  - Layout adapted to digital-tool design
- Frequency ~10-20 MHz  
=> time-stamp precision 100 or 50 ns
- Operation point ( $I_{bias}$ ) tuning on-going

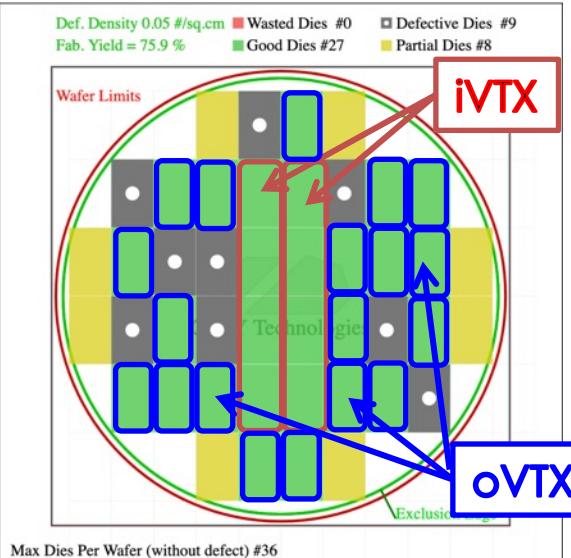


Size optimized to maximize (8) sets of 4 contiguous sensors

Total width = 30.6 mm

Total width = 19 mm

**Periphery**  
EndOfCol + Trigger logic + Control + Sync + Tx + DACs



**Pixel Matrix**  
Pitch  $33 \times 33 \mu\text{m}^2$   
Height: 464 rows = 15.3 mm  
Width: 896 columns = 29.6 mm

## Strong on-going test effort on TJ-Monopix2

- Critical to change any features
- e.g. #trimming bits / pixel for threshold

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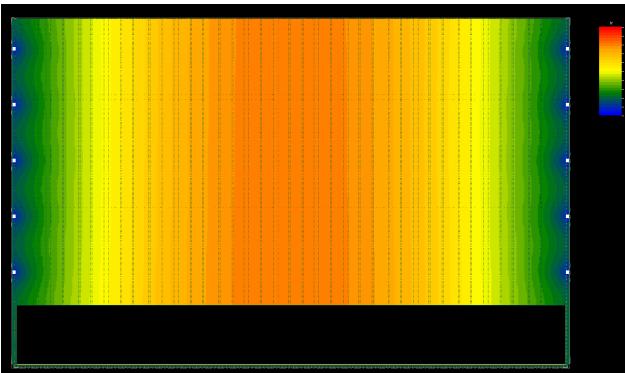
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## ■ Power pads

- Power regulators added  
=> simplified system integration
- But area limited to <150  $\mu\text{m}$

GNDA IR drop (0-30 mV) simulation



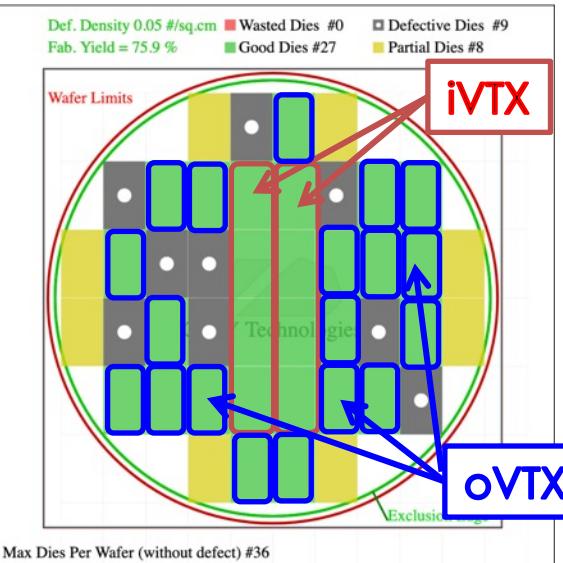
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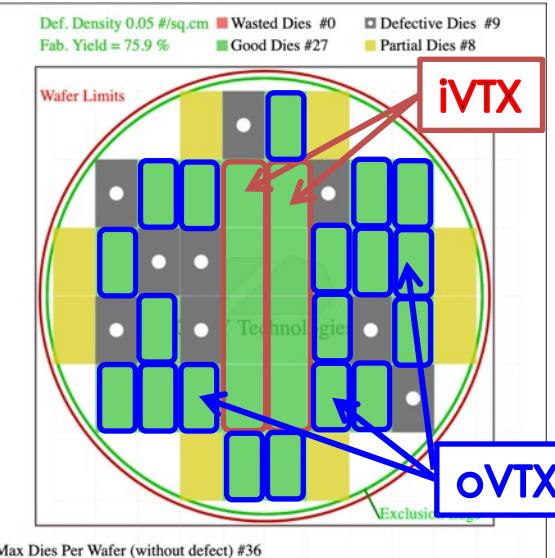


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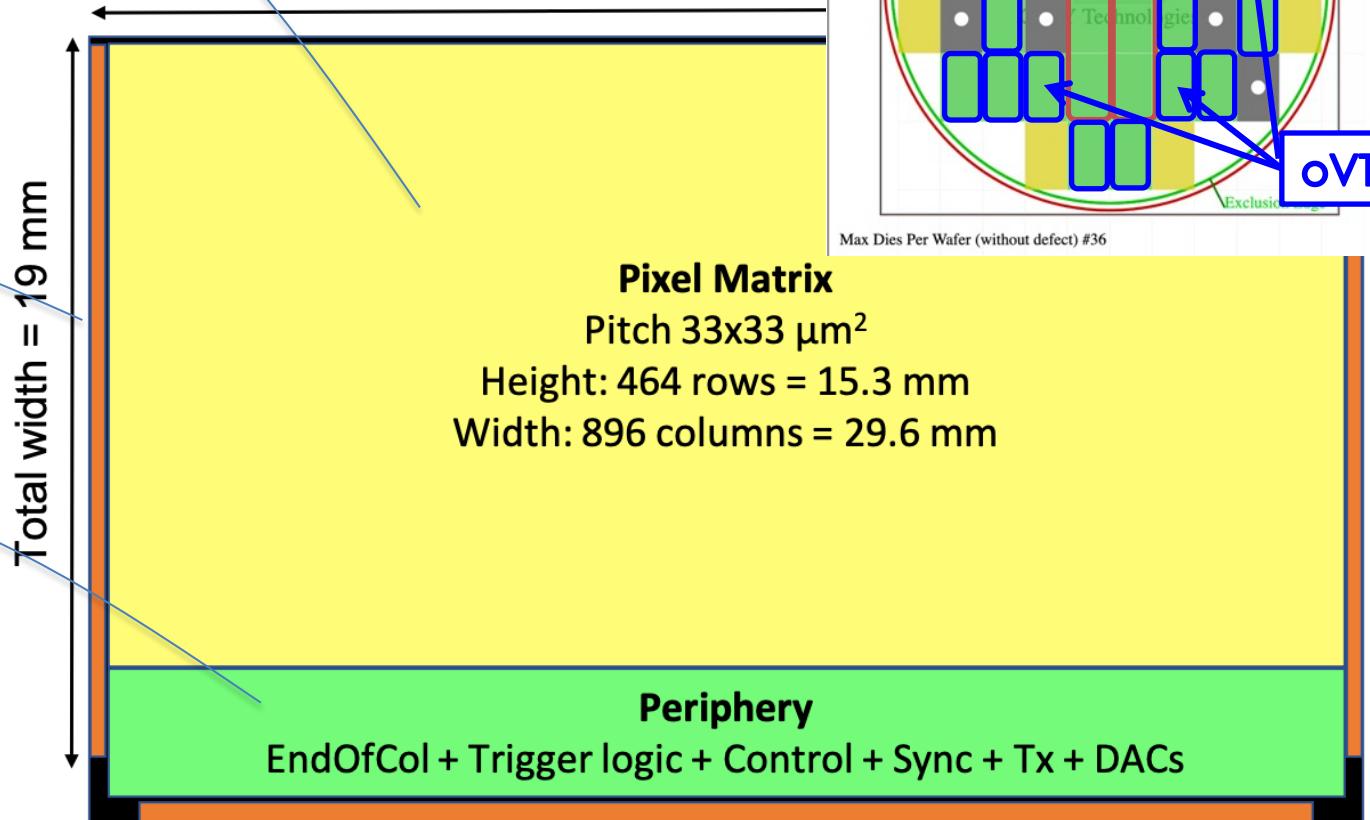


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## ■ Periphery

- New end-of-column + trigger logic  
adapted to Belle II trigger
- HITor fast transmission ~20 ns (4 areas)
- Control using protocol from RD53



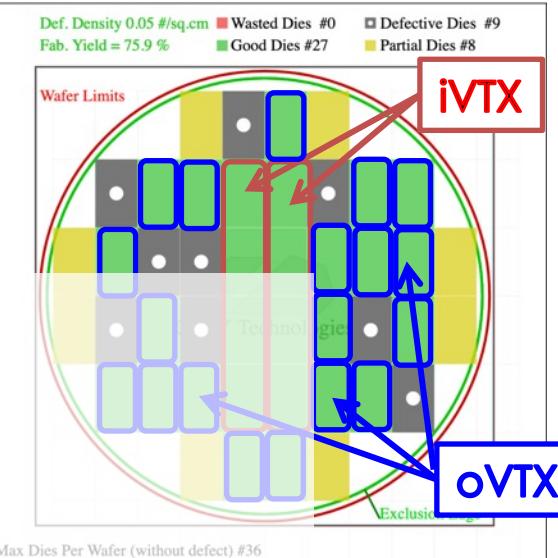
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Size optimized to maximize (8) sets of 4 contiguous sensors

Total width = 30 mm



**OBELIX-1 submission expected Q4-2023 => still R&D phase**

## ■ Power pads

- Power regulators added  
=> simplified system integration
- But area limited to <150  $\mu\text{m}$

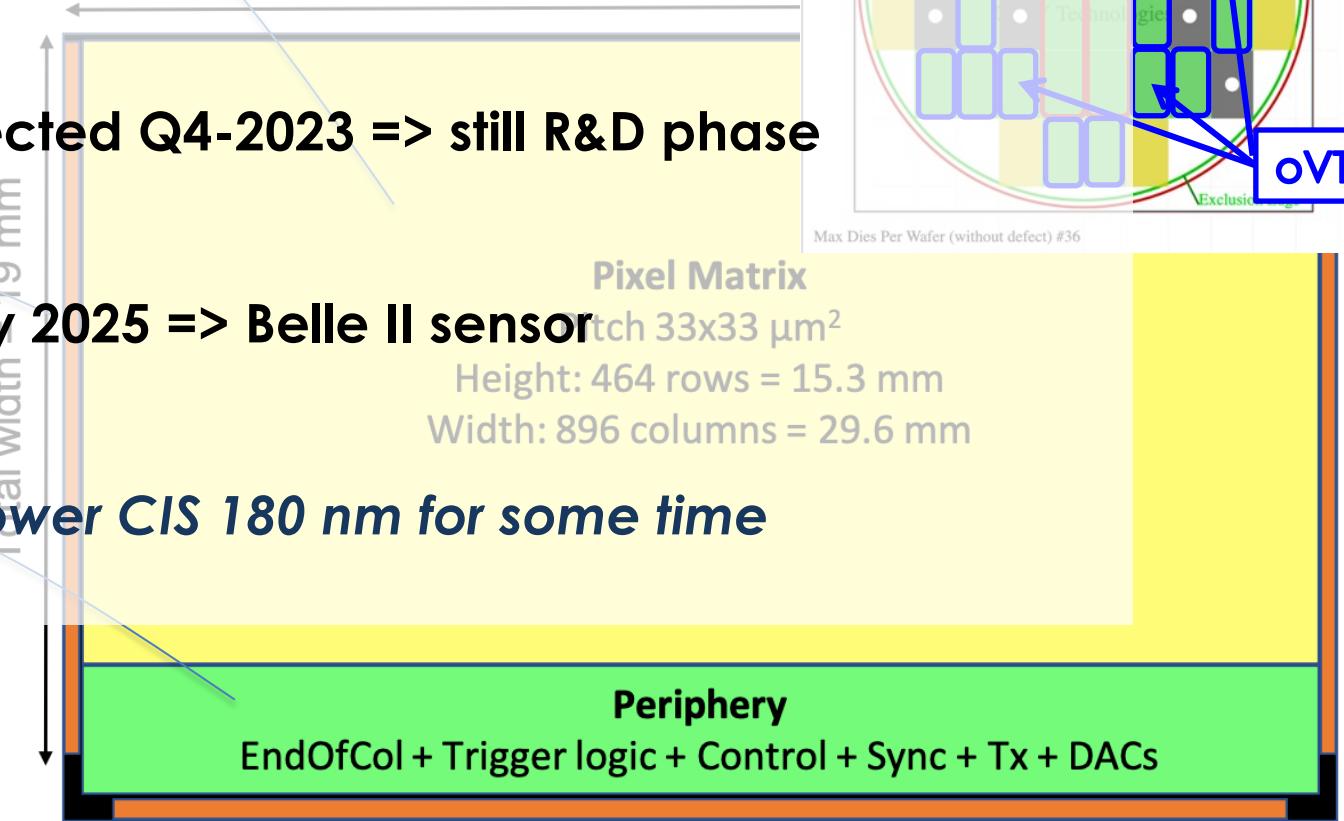
**OBELIX-2 for early 2025 => Belle II sensor**

## Pixel Matrix

Pixel pitch 33x33  $\mu\text{m}^2$   
Height: 464 rows = 15.3 mm  
Width: 896 columns = 29.6 mm

## ■ Periphery

- => **Keep working with Tower CIS 180 nm for some time**
- New end-of-column + trigger logic adapted to Belle II trigger
  - HITor fast transmission ~20 ns (4 areas)
  - Control using protocol from RD53



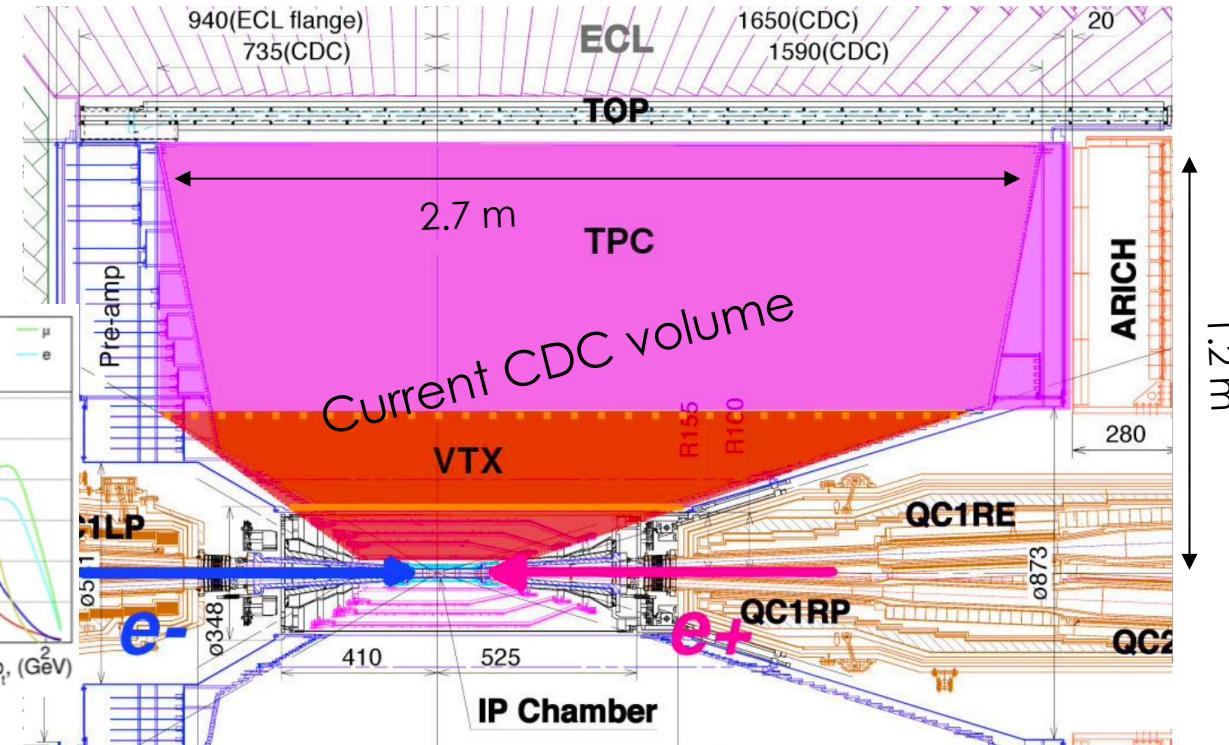
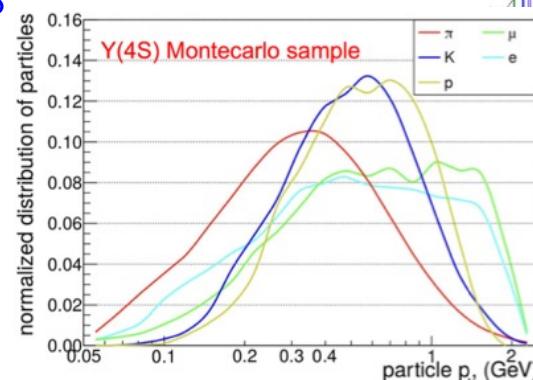
- For now, prospective ideas on simulation BUT strong interest for continuing

## ■ Change to the main tracker

- Replace partially or totally the CDC
- At least inner volume with MAPS
- Typical specs
  - Nanosecond timing
  - Provide trigger info swiftly (10 ns)
  - Large pixels OK

## ■ Introducing fast layer

- Goals: complement PID and provide trigger
  - A priori after main tracker (radius 1.2m)
  - Possibly within VTX volume as well
- Time resolution range 20-100 ps
- Could be MAPS



=> Large synergies with ECFA roadmap requirements

# Take home messages

- A strong community issued from Belle II for R&D on MAPS

- Across Europe & Japan
- Expertise: design + characterisation + integration
  - Currently engaged in R&D with interest in long-term involvement

- Flying (i.e. proper detector perf for physics) is about balance

- The difficult side to monolithic design: everything, everywhere, all at once

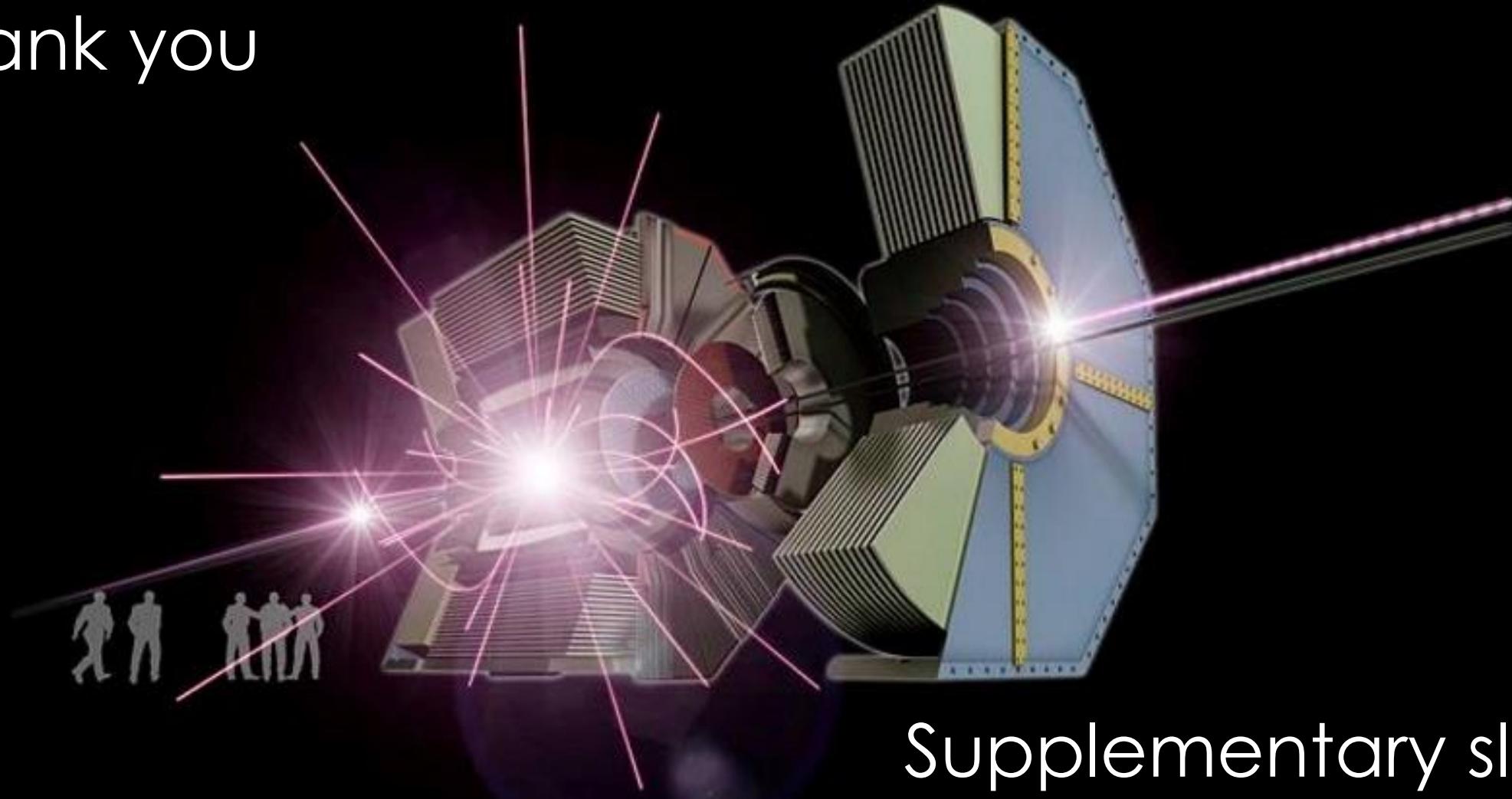


Pixel matrix

CMOS technology

Engineered sensor

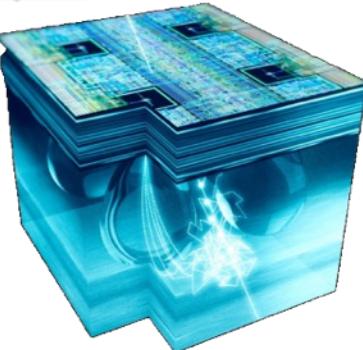
Thank you



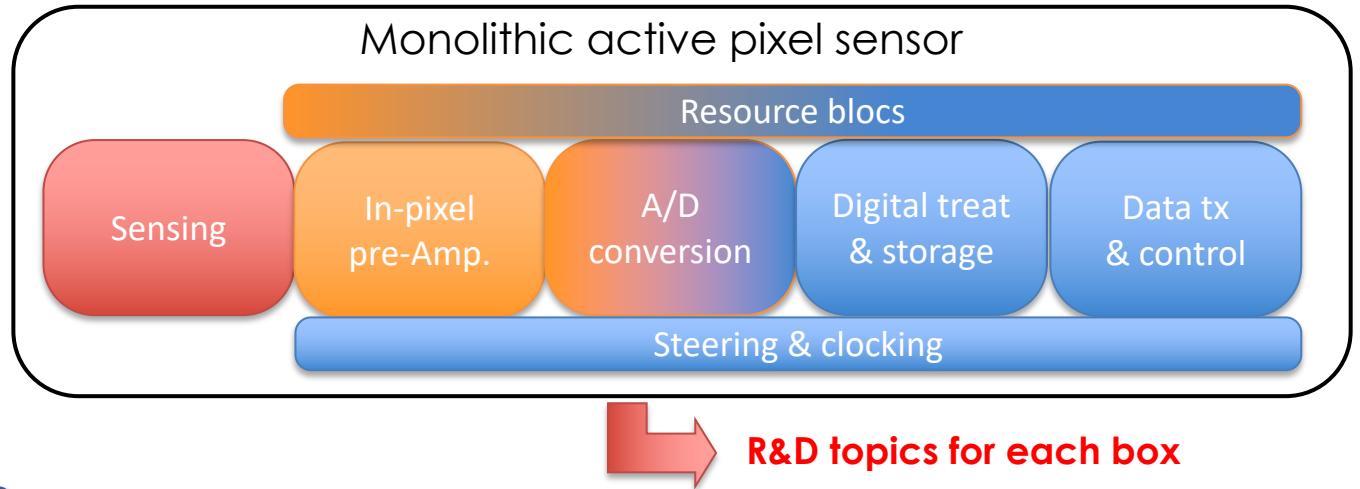
Supplementary slides →

## ■ General concepts

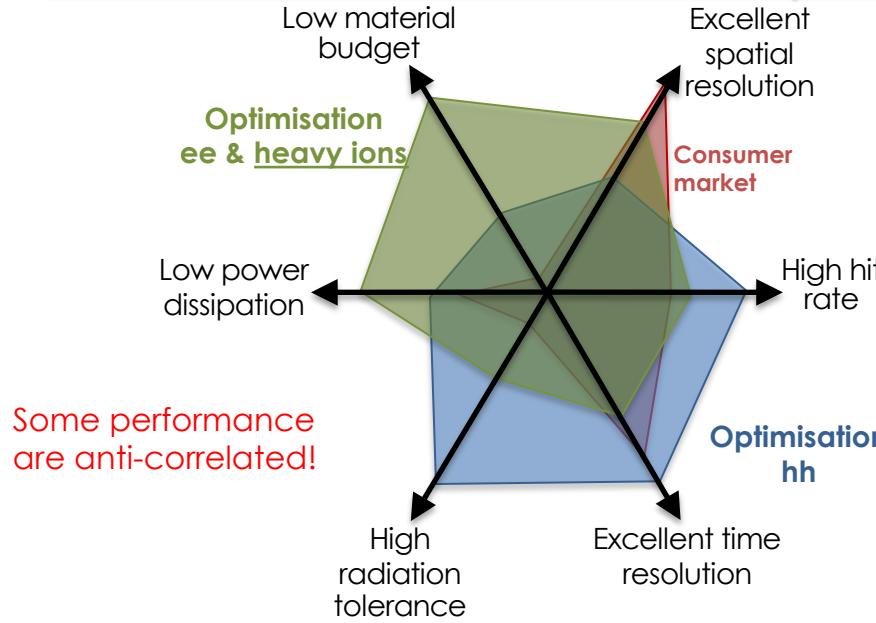
2x2 submatrix view  
thickness ~50 µm  
© M.Mager



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## ■ Performance is a matter of optimisation



or

## Self-supported all silicon module

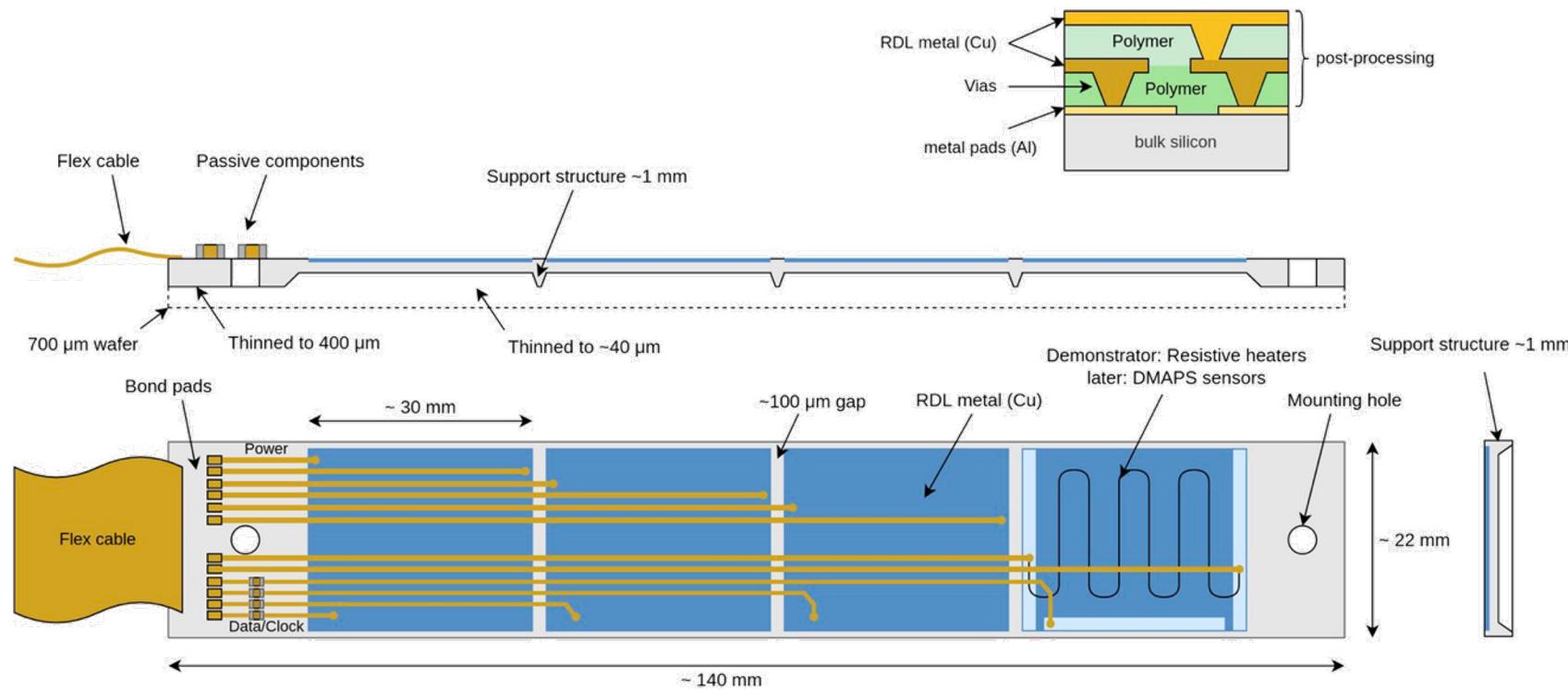
- Inherited from Belle II-PXD, also explored with ATLASpix →
- 4 contiguous sensors diced out of wafer => 12cm long
- Interconnected with redistribution layer
- Heterogeneous thinning
  - "thick" edge walls for stiffness
  - thin (40 µm) sensitive area
- Air-cooled
  - First simulations with 200 mW/cm<sup>2</sup> encouraging



7.1x1.5 cm<sup>2</sup>  
Thickness (edge/center)  
430/90 µm  
Planarity ~17 µm

## Prototyping on-going

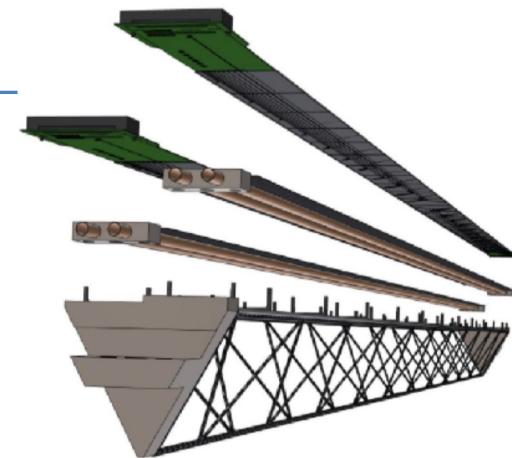
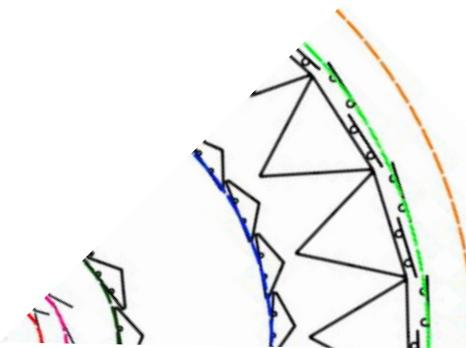
- Process evaluation with dummy wafers
- Thermo-mechanical tests
  - Using resistive heaters
- Electrical tests with RDL
  - Signal integrity, power delivery



# oVTX outer layer concept

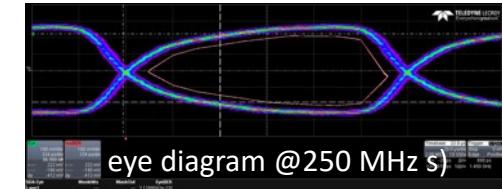
## ■ Long ladders

- Inherited from ALICE-ITS2
  - Carbon-fiber truss support frame
  - Cold-plate with water coolant
  - Long-flex for power & data
- L3-4, radius 4-9 cm, length < cm
  - Single sensor row,  $\sim 0.5\% X_0$
- L5, radius 14 cm, length 70 cm
  - Double sensor rows ,  $\sim 1\% X_0$



## ■ Prototypes for L5 under test

- Truss fabricated
- Flex cable



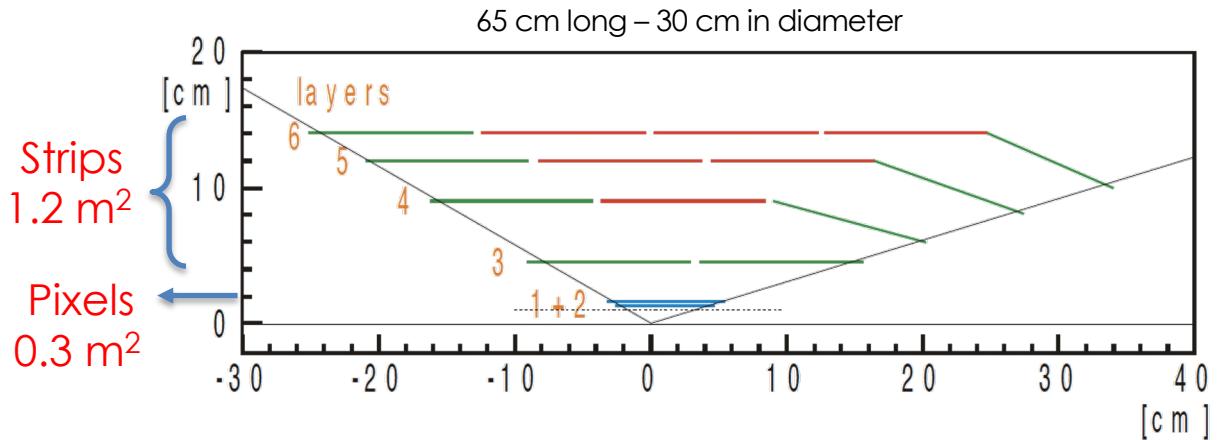
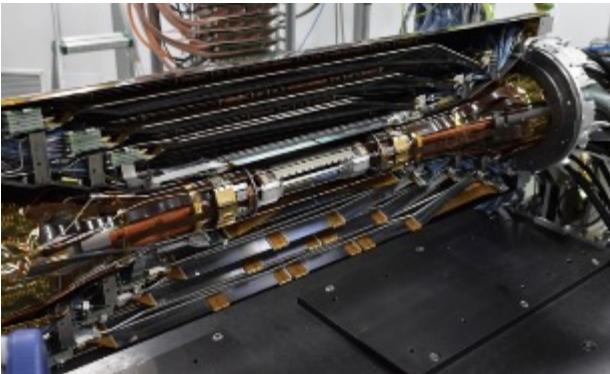
# The current Belle II-VXD

## ■ Two technology system

- **SVD = Double-Sided Strip Detector**

- Read-out sensor connected on sensor = Origami
  - Hit time-stamping  $\sigma_t < 3$  ns
  - Spatial resolution  $\sigma_{s.p.} \sim 8\text{-}30 \mu\text{m}$  depending on pitch

=> SVD technical paper: [arXiv:2201.09824](https://arxiv.org/abs/2201.09824)



- **PXD = DEPFET sensors**

- Very low material budget  $0.2 \% X_0 / \text{layer}$
  - Small first layer radius = 1.4 cm with pixel size  $50 \times (55\text{-}85) \mu\text{m}^2$
  - Long integration time 20  $\mu\text{s}$  / trigger rate & injection bkg