## A deep neural network based estimator for elliptic flow in heavy-ion collisions Based on: N. Mallick, S. Prasad, A. N. Mishra, R. Sahoo, and G. G. Barnaföldi,

Phys. Rev. D. 105, 114022 (2022)

Workshop on Applications of Artificial Intelligence and Machine Learning



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## Outline

- Heavy-ion collisions and Quark gluon plasma
- Elliptic flow
- Deep Neural Network
- Input to the Model
- DNN Architecture
- Quality Assurance
- Results
- Summary and Outlook

#### **Constituents of matter**



- Energy is related to wavelength by de Broglie's formula:  $p = h/\lambda$
- To probe inside smaller objects we need higher energy



[1] R. Sahoo, "Relativistic Kinematics", [arXiv:1604.02651 [nucl-ex]]

#### **Fundamental interactions**



#### **Standard Model of Elementary Particles**

Perkins, D. (2000). Introduction to High Energy Physics (4th ed.). Cambridge: Cambridge University Press. doi:10.1017/CBO9780511809040

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#### **Strong Interaction**

- Unlike QED, in QCD gluons have color charge which permits gluon-gluon interaction
- Color charges can't freely exist : Color confinement
- At high energies,  $\alpha_s$  becomes smaller : Asymptotic freedom







Obertelli, A., Sagawa, H. (2021). Nuclear Physics and Standard Model of Elementary Particles. In: Modern Nuclear Physics. UNITEXT for Physics. Springer, Singapore

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#### Heavy-ion collisions (HIC) and Quark gluon plasma (QGP)

- Quark gluon plasma (QGP) is a hot and dense state of deconfined quarks and gluons in thermal equilibrium
- The value of the strong coupling constant decreases as the energy density increases: Asymptotic Freedom





 Atomic nuclei
 Neutron stars

 Baryon density
 pre-equilibrium dynamics

 [1] R. Sahoo, AAPPS Bull. 29, 16 (2019).
 collision

 [2] U. Heinz, Int. J. Mod. Phys. A 30, 1530011 (2015).
 collision

 [3] R. Sahoo, and T. K. Nayak, Curr. Sci. 121, 1403 (2021).
 collision



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#### **Kinematic Observable in HIC**



- Transverse Momentum,  $p_T = \sqrt{p_x^2 + p_y^2}$
- Azimuthal Angle,  $\phi = \tan^{-1}\left(\frac{p_y}{p_x}\right)$
- Polar angle,  $\theta = \tan^{-1}\left(\frac{p_T}{p_z}\right)$

- Rapidity,  $y = \frac{1}{2} \ln \left( \frac{E + p_Z}{E p_Z} \right)$
- Pseudo-rapidity,  $\eta = -\ln\left(\tan\frac{\theta}{2}\right)$
- Reaction plane angle,  $\psi_R$ : Angle made by impact parameter (*b*) with *x*-axis

[1] R. Sahoo, "Relativistic Kinematics", [arXiv:1604.02651 [nucl-ex]]

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#### Elliptic Flow ( $v_2$ )



□ Anisotropic flow: hydrodynamic response to spatial deformation of the initial density profile.

$$E\frac{d^{3}N}{dp^{3}} = \frac{d^{2}N}{2\pi p_{T}dp_{T}dy} \left(1 + 2\sum_{n=1}^{\infty} v_{n} \cos[n(\phi - \psi_{n})]\right) = \frac{d^{2}N}{2\pi p_{T}dp_{T}dy} \left(1 + 2v_{1}\cos(\phi - \psi_{1}) + 2v_{2}\cos[2(\phi - \psi_{2})] + 2v_{3}\cos[3(\phi - \psi_{3}) + ...]\right)$$
Directed flow Elliptic flow Triangular flow
$$v_{2} = \left(\cos\left[2(\phi - \psi_{2})\right]\right)$$
N. Mallick, R. Sahoo and S. Tripathy, and A. Ortiz, J. Phys. G 48, 045104 (2021) B. B. Abelev et al. [ALICE Collaboration], JHEP 1506, 190 (2015)
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#### **Deep Neural Network (DNN)**

- It is an ML algorithm inspired by the structure of the neurons in the animal brain
- Three key layers

Input layer: Takes different features as input Hidden layer: Connects to different neurons to weights Output layer: gives the result as a number or class

- Weights: represents the importance of a neuron
- Activation function: Guides the outcome of each node
- Cost function: Evaluates the accuracy of the prediction
- Optimizer: Methods/Algorithms used to minimize the cost function by updating the weights



• For an input layer *x*, two hidden layers, the output *y* can be represented as:

$$y = F_3\left(CF_2(BF_1(Ax))\right)$$

*A*, *B*, *C* represent the weight matrices  $F_1$ ,  $F_2$ ,  $F_3$  represent the activation functions

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#### **Input to the Model**

- Elliptic flow ( $v_2$ ) is an event property, depends upon:  $\eta$ , mass,  $p_T$ , centrality, etc.
- $v_2$  is calculated using the event plane method and  $\psi_R$  is set to zero in AMPT. ( $\Rightarrow v_2 = (\cos(2\phi))$ )
- $(\eta \phi)$  space is considered as primary input space, divided into (32x32) bin space
- Weighted  $p_T$ , mass and  $\log(\sqrt{(s_{NN}/s_0)})$  are taken as input to the DNN architecture.
- $32 \times 32 \times 3$  (= 3072) features per event
- Trained with 150K minimum bias events of Pb-Pb collisions at  $\sqrt{s_{NN}} = 5.02$  TeV simulated with AMPT.



N. Mallick, S. Prasad, A. N. Mishra, R. Sahoo, and G. G. Barnaföldi, Phys. Rev. D 105, 114022 (2022)

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#### **DNN Architecture**

- Each event has 3072 input features mapped into the first dense layer with 128 nodes and ReLU activation function
- 3 hidden layers with 256 nodes and ReLU activation function
- The final layer has single node as  $v_2$  and linear activation function is used
- ReLU  $(x) = \max(0, x)$
- Cost Function: mean squared error
- Optimiser: adam
- Early stopping mechanism is used to stop the training
- Early stopping patience level of maximum 10 epochs
- Max Epoch=60, batch size = 32

N. Mallick, S. Prasad, A. N. Mishra, R. Sahoo, and G. G. Barnaföldi, Phys. Rev. D 105, 114022 (2022)



#### **Quality Assurance**

0.00200-

0.00175-

0.00150-

0.00125-

0.00075

0.00050-

0.00025

0.00000.

80 0.00100-

- Loss is the mean squared error of • predicted  $v_2$  w.r.t true  $v_2$
- Loss is in the order of  $10^{-4}$ : Good training
- Less to no overfitting/underfitting. •
- Mean absolute error (MAE) of  $v_2$  is defined as:

$$\Delta v_2 = \frac{1}{N_{\text{events}}} \sum_{n=1}^{N_{\text{events}}} |v_{2_n}^{\text{true}} - v_{2_n}^{\text{pred}}|$$

- $v_2^{true} = v_2^{pred}$  straight line is well populated
- 32x32 bin size is faster and has optimum performance compared to other bin size
- Model is quite sturdy and less sensitive to noise of different weights

N. Mallick, S. Prasad, A. N. Mishra, R. Sahoo, and G. G. Barnaföldi, Phys. Rev. D 105, 114022 (2022)



Counts

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15

10

event:

w: weight

number

#### **Results and Discussions**



- AMPT results do not match with experimental data, which can be optimised with different settings available in AMPT
- DNN predictions almost match with the  $v_2$  value from the AMPT, not only at LHC but also at RHIC energies, which is new to DNN

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#### **Results and Discussions**



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#### Summary

- Elliptic flow is one of the important observables to understand the physics of QGP, and it can be successfully predicted with machine learning based DNN algorithm
- The DNN model retains the centrality, energy and  $p_T$  dependence and predicts with accuracy
- The DNN model is quite robust and it's less sensitive to input data with uncorrelated noise

#### Outlook

- The DNN model is yet to be tested for particle dependence (mass dependence)
- If the model retains the particle mass dependence, it could be further tested for different scalings available for elliptic flow
- In AMPT, we have set  $\psi_R = 0$ , we are working on the model to learn random orientation of  $\psi$  and its dependence

# **Thank You**For the attention

# Backup Slides

### A Multi-phase Transport Model (AMPT)

- Initialisation of collisions (HIJING)
- Parton Transport (ZPC)
- Hadronisation (Lund string fragmentation / Quark coalescence)
- Hadron Transport (ART)



**SM** Version

Zi-Wei Lin, Che Ming Ko, Bao-An Li, Bin Zhang, and Subrata Pal, Phys. Rev. C 72, 064901 (2005)