

# Deep Learning Symmetries in Physics and Beyond

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[arxiv:2301.05638](https://arxiv.org/abs/2301.05638)

[arxiv:2302.05383](https://arxiv.org/abs/2302.05383)

[arxiv:2302.00806](https://arxiv.org/abs/2302.00806)

[arxiv:2305.xxxxx](https://arxiv.org/abs/2305.xxxxx)



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FLORIDA

$$\text{Invariance: } f(\mathbf{g}, \mathbf{x}) = f(\mathbf{x}) \quad (1)$$

## Labelled Dataset

$n$  features

$k$  labels

$m$  samples

$x_1^{(1)}$	$x_1^{(2)}$	$\dots$	$x_1^{(n)}$	$y_1^{(1)}$	$\dots$	$y_1^{(k)}$
$x_2^{(1)}$	$x_2^{(2)}$	$\dots$	$x_2^{(n)}$	$y_2^{(1)}$	$\dots$	$y_2^{(k)}$
$\vdots$	$\vdots$	$\ddots$	$\vdots$	$\vdots$	$\ddots$	$\vdots$
$x_m^{(1)}$	$x_m^{(2)}$	$\dots$	$x_m^{(n)}$	$y_m^{(1)}$	$\dots$	$y_m^{(k)}$

$$f_{\mathbf{x};g} = f_{\mathbf{x}_1; \mathbf{x}_2; \dots; \mathbf{x}_m} g \text{ where } \mathbf{x}_i \in \mathbf{V}^n$$

$$f_{\mathbf{y};g} = f_{\mathbf{y}_1; \mathbf{y}_2; \dots; \mathbf{y}_m} g = \begin{cases} \tilde{f}(\mathbf{x}_j)g \\ \underline{\{Z\}} \end{cases}$$

Oracle  
(learned or postulated)



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$$f_{\mathbf{x}_i; g} = f_{\mathbf{x}_1; \mathbf{x}_2; \dots; \mathbf{x}_m; g} \text{ where } \mathbf{x}_i \in \mathbf{V}^n$$

$$f_{\mathbf{y}_i; g} = f_{\mathbf{y}_1; \mathbf{y}_2; \dots; \mathbf{y}_m; g} = \underbrace{f_{\mathbf{x}_i; g}}_{\substack{\text{Oracle} \\ \text{(learned or postulated)}}}$$



## Transformation

Transformation on feature space:

$$g : \mathbf{x}_i \mapsto \mathbf{x}_i^0$$

Transformation is a symmetry if:

$$'(\mathbf{x}_i^0) = '(g(\mathbf{x}_i)) = '(x_i)$$

**Goal:** Find transformations  $g(\mathbf{x}_i)$  which preserve the oracle  $'$ .

# Notation and Set-Up

$$\text{Invariance: } \rho(g(x)) = \rho(x) \quad (1)$$

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$$f(x_i; g) = f(x_1; x_2; \dots; x_m; g) \text{ where } x_i \in V^n$$

$$f(y_i; g) = f(y_1; y_2; \dots; y_m; g) = \begin{cases} \rho(x_i) \\ \rho(z) \end{cases}$$

Oracle  
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**Goal:** Find transformations  $g(x_i)$  which preserve the oracle  $\rho$ .

In physics,  $\rho$  represents a conserved quantity.

g	$\rho$
Time Translation ( $T_0$ )	E
Rotation ( $R_{ij}$ )	$\vec{L}$
Lorentz ( $K$ )	T

# Parameterization of Symmetry Transformations

## Linear

$$x^0 = (I + W) x \quad (2)$$

I identity matrix

W  $n \times n$  matrix to be  
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**Figure: Visualization:** SU(2) generators for a single layer linear model using the L2-norm oracle  $\ell(x) = \|x\|$ .

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Figure: **Visualization:**  $SU(2)$  generators for a single layer linear model using the  $L_2$ -norm oracle  $\ell_2(\mathbf{x}) = \|\mathbf{x}\|_2$ .

## Non-Linear

$$\mathbf{x} \rightarrow \mathcal{Z}(\mathbf{x}) \rightarrow \mathbf{x}^\theta \text{ or } \mathbf{x} \quad (3)$$

$\mathcal{N}$  whose parameters are to be learned by our method



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Figure: **Visualization:**  $SU(2)$  generators for a single layer linear model using the  $L_2$ -norm oracle  $\ell_2(\mathbf{x}) = \|\mathbf{x}\|_2$ .

## Non-Linear

$$\mathbf{x} \rightarrow \left\{ \mathbf{z} \right\} \rightarrow \frac{\mathbf{x}^\theta}{\|\mathbf{x}^\theta\|_2} \quad (3)$$

$NN$  whose parameters are to be learned by our method

Figure: **Visualization:** Grid vector transformation representation for a deep linear layered model using the  $L_1$ -norm oracle  $\ell_1(\mathbf{x}) = \sum_j |\mathbf{x}^{(1)j}| + \sum_j |\mathbf{x}^{(2)j}|$ .





# Loss Function

Ensure Symmetry  $\Rightarrow$  Invariance  $L_{inv}(G_W; f(x_i))$

Enforces invariance among a chosen oracle  $\psi(x)$ , e.g.  $l^2$ -norm  $\psi(x) = \sqrt{\sum_i x_i^2}$ ,

$$L_{inv} = h_{inv} \frac{1}{2m} \sum_{i=1}^n [\psi(F_W x_i) - \psi(x_i)]^2 = h_{inv} \frac{1}{2m} \sum_{i=1}^n [\psi((I + W) x_i) - \psi(x_i)]^2 \quad (4)$$



# Loss Function

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## Ensure non-triviality $(\mathbf{x}^0 \notin \mathbf{x}) \Rightarrow$ Normalization $L_{norm}(G_W; f, \mathbf{x}_i, g)$

Enforces the normalization condition and finding a non-trivial solution

$$L_{norm} = h_{norm} \sum_{j,k} W_{jk} W_{kj} \quad (5)$$



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Figure: Linear: Rotations in 2D,  
 $\psi(\mathbf{x}) = \sqrt{x^2 + y^2}$ .



# Loss Function

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Enforces invariance among a chosen oracle  $\psi(\mathbf{x})$ , e.g.  $l^2$ -norm  $\psi(\mathbf{x}) = \frac{1}{\sqrt{m}} \sum_{i=1}^m x_i^2$ ,

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$$L_{norm} = h_{norm} \sum_{j,k} W_{jk} W_{kj} \frac{1}{2} \quad (5)$$

**Figure: Linear:** Rotations in 2D,  
 $\psi(\mathbf{x}) = \mathbf{x}^T \mathbf{x}$ .

**Figure: Non-linear:** Squeeze mapping  
in 2D,  $\psi(\mathbf{x}) = \mathbf{x}^{(1)} \mathbf{x}^{(2)}$ .



# Finding Multiple Symmetries

## Distinct Transformations $\Rightarrow$ Orthogonality $L_{orth}(G_W; G_W^0)$

This is built on intuition from group theory where the generators of different groups obey orthogonality conditions. Enforces the orthogonality condition and finding distinct generators  $\downarrow$

$$L_{orth} = h_{orth} \sum_{j,k} W_{jk} W_{kj}^0 \quad (6)$$



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$$L_{orth} = \text{tr} \left( W_{jk} W_{kj}^0 \right) \quad (6)$$



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Input Parameter !  $N_g$  (number of generators). We can increase this value to search for more symmetries.



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**Example:** Rotations in  $2D$ ,  $\mathbf{x} \in \mathbb{R}^2; ' = j\mathbf{x}j$

Figure: Success (top). Failure (bottom).



Figure:  $N_g = 1; 2$  Loss



# Rotations in 4 dimensions $\mathfrak{so}(4) \subset \mathfrak{R}^4; \mathbf{J} = \{J_i\}$

Including a closure term  $L_{\text{closure}}$  ensures the generators form a closed algebra.

$$L_{\text{clos}} = h_{\text{clos}} \left( \sum_{i,j} J_i J_j + \sum_{i,j} a_{ij} J_i J_j \right)$$

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Figure:  $N_g = 3$ .

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Figure:  $N_g = 3$ .

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# Rotations in 4 dimensions ( $\mathbf{x} \in \mathbb{R}^4; ' = \mathbf{j}\mathbf{x}\mathbf{j}$ )

Closure  $L_{clos}(a_{[j]})$

Including a closure term  $L_{closure}$  ensures the generators form a closed algebra.

$$L_{clos} = h_{clos} \sum_{j=1}^3 a_{[j]} J_j$$

Figure:  $N_g = 3$ .



Figure:  $N_g = 4$ .

Figure:  $N_g = 6$ .

# Other Examples: Lorentz Group $O(1;3)$ and Unitary Groups $U(n)$

**Figure:** Lorentz group generators,  $O(1;3)$   
preserving the Lorentz vector  
 $'(\mathbf{x}) = x x .$



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preserving the Lorentz vector  
 $'(\mathbf{x}) = x x .$

## Sparsity $L_{sp}(\mathcal{W})$

Enforces the learned generators (axes of rotation) to be in the canonical basis (usual axes),  $\mathcal{X}^n$

$$L_{sp} = \sum_{j \notin I} \sum_{k \notin m} W_{jk} W_{lm}^2 \quad (7)$$



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**Figure:** Lorentz group generators,  $O(1;3)$  preserving the Lorentz vector  
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**Figure:** Canonical representation of  $O(1;3)$  with  $h_{sp} > 0$ .

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# Other Examples: Lorentz Group $O(1;3)$ and Unitary Groups $U(n)$

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**Figure:** Lorentz group generators,  $O(1;3)$  preserving the Lorentz vector  
 $'(\mathbf{x}) = \begin{pmatrix} x \\ x \\ x \end{pmatrix}$ .

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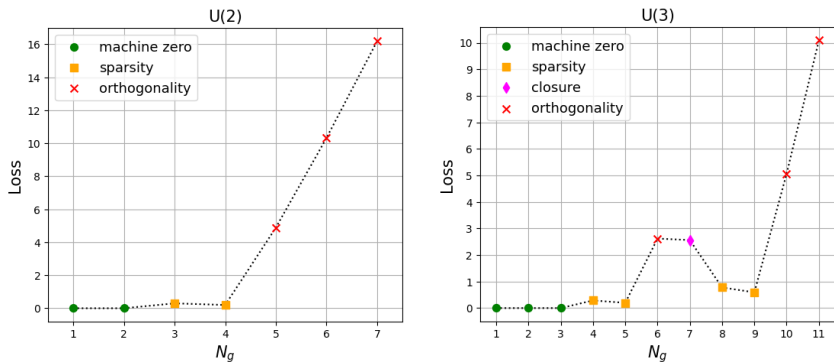
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**Figure:**  $N_g = 8$ ;  $SU(3)$  Gell-Mann matrices preserving  $'(\mathbf{x}) = j\mathbf{x}j$ .



# Understanding the Full Loss Function



**Figure:** The final value of the full loss function as a function of the number of generators  $N_g$  for  $U(n)$  for  $n = 2$  (left panel) and the  $n = 3$  (right panel). The colored symbols identify the dominant contribution to the loss. All hyperparameters  $h_i$  were fixed to 1 except for  $h_{\text{sparsity}} = 0.05$ . The learning rate was  $10^{-3}$ .

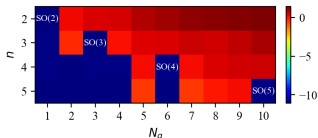


# Summary

## ML Symmetries

- 1 Developed a method for ML symmetries in a labelled dataset.
- 2 General approach.
- 3 Finds the complete symmetry group.
- 4 Can be applied to realistic datasets

Learned  $SO(10)$  generators.



**Figure:** Loss function results for  $n = 2; 3; 4; 5$  dimensions and  $N_g = 1; \dots; 10$  generators. The cells are color coded by the base-10 logarithm of the lowest value of the loss attained during training.



**Figure:** Symmetric morphing of images along contours of the 16-dimensional latent flow. The images in the middle column represent the ideal digits in the dataset. The remaining six images in each row are obtained by moving along the contours.

