

Toward a Better Coupling Scheme of Co-simulation for the 1-d Conductor Model

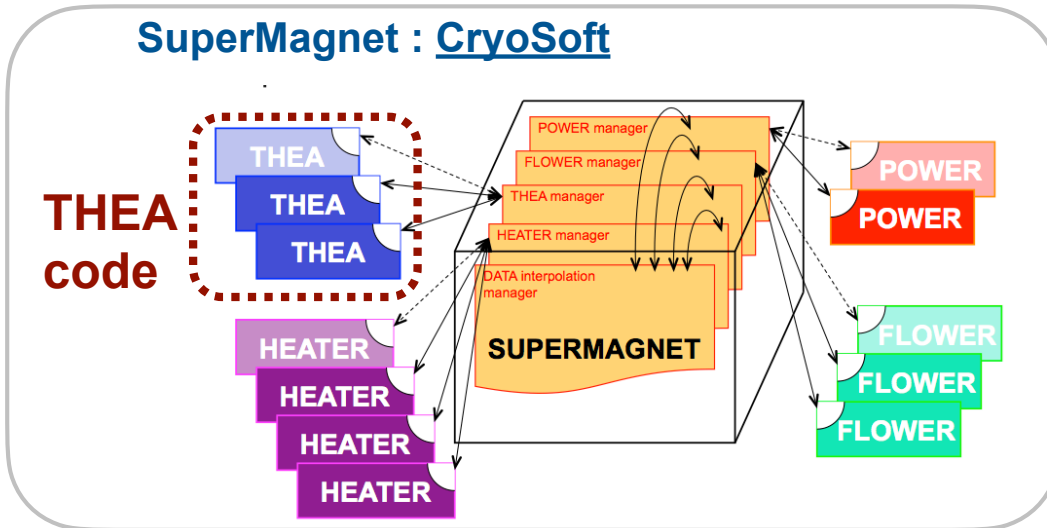
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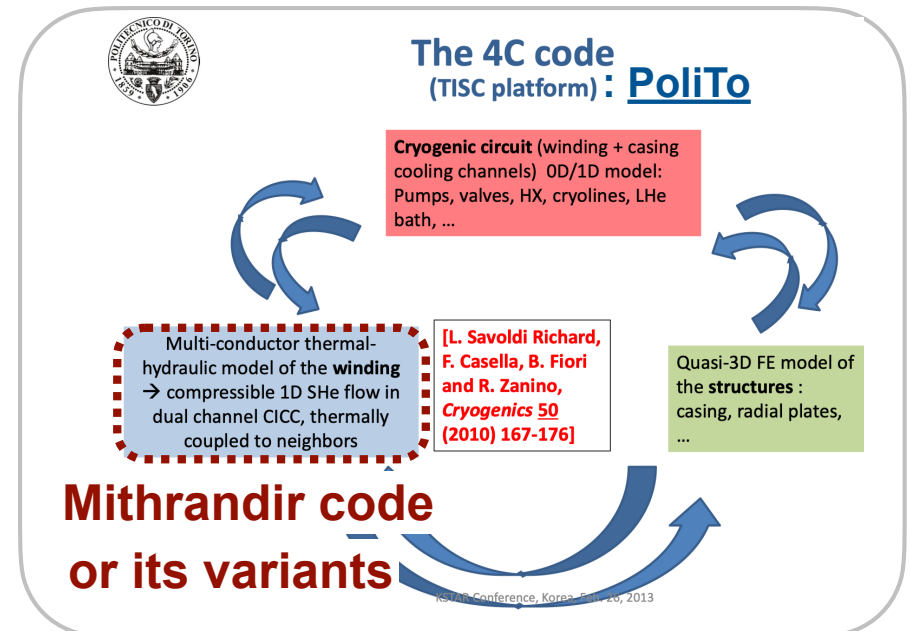
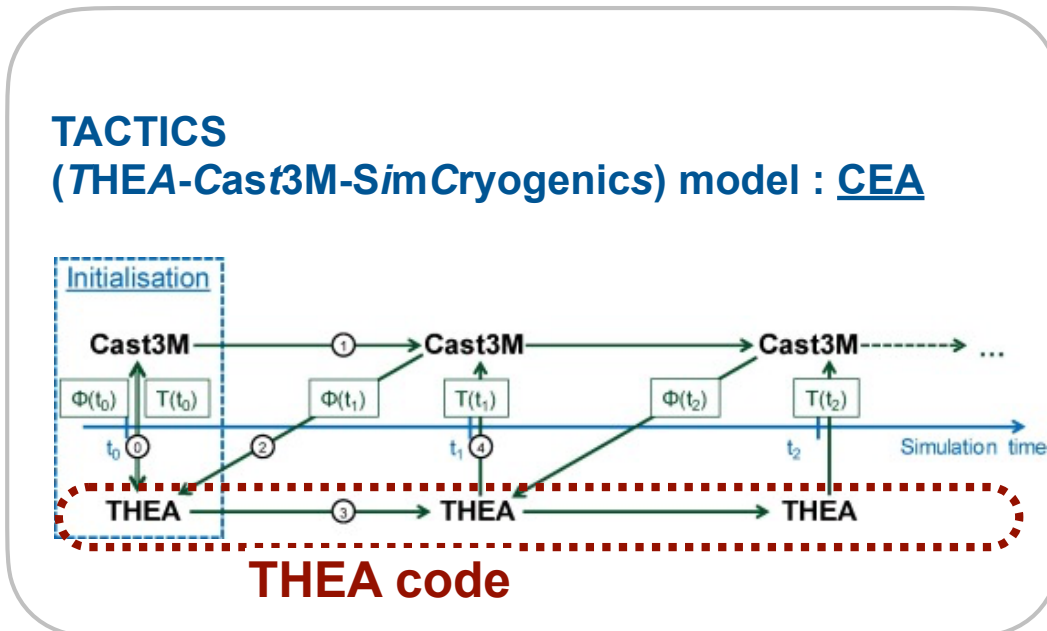
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Motivations (1/3)

✓ The basic idea is “binding” independent executables.



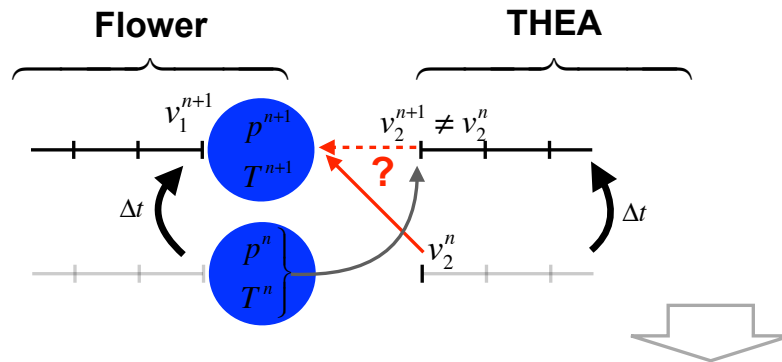
The conductor models are basically critical, in particular, to describe the quench behavior.



Issue #1 : loss of implicit coupling

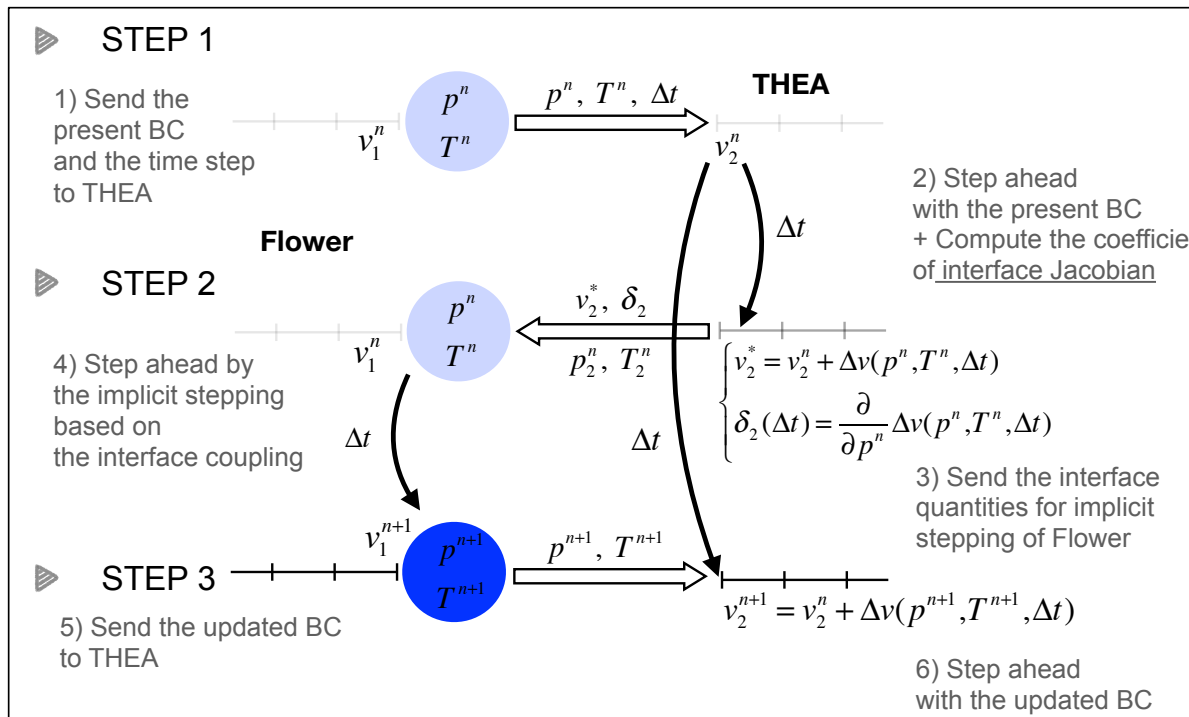
Session VIII-2

Chats 2019 Applied Superconductivity 



✓ **Interfacial problem is rather essential!**

• To recover the implicit coupling, ...



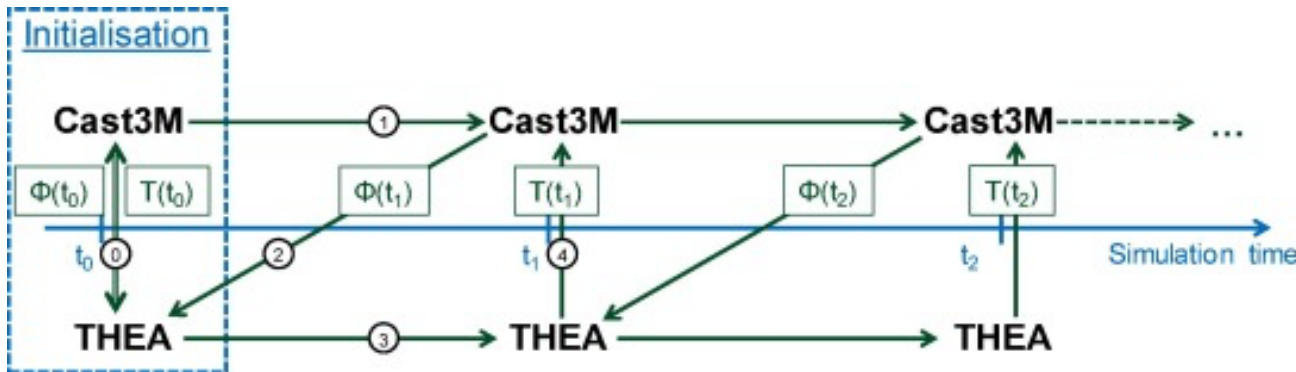
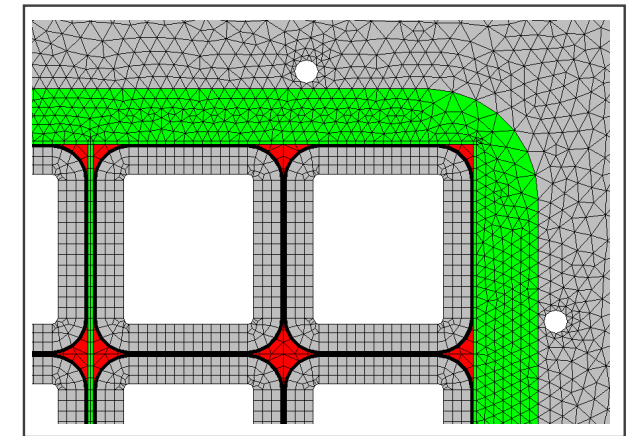
The idea is derived relying on the concept of interface Jacobian!

D. K. Oh, "[5LORa6-08] Coupled Simulation Model of CICC Components Integrated into the Cooling Circuit" presented in ASC2019 Nov. 2 Seattle USA

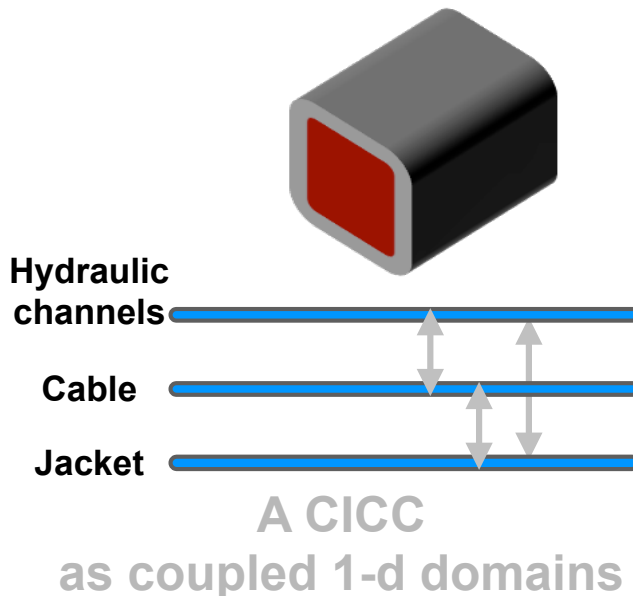


Motivations (3/3)







✓ Now, we are aiming at a new target
i.e. the **thermal interface** of FEM meshes
to a 1-d conductor model !

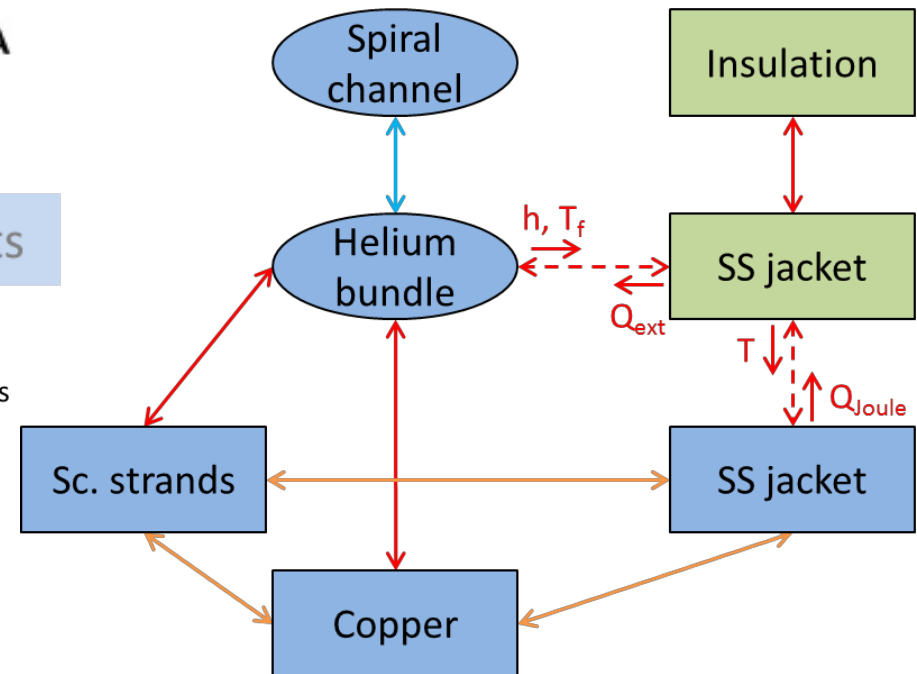


Cast3M components

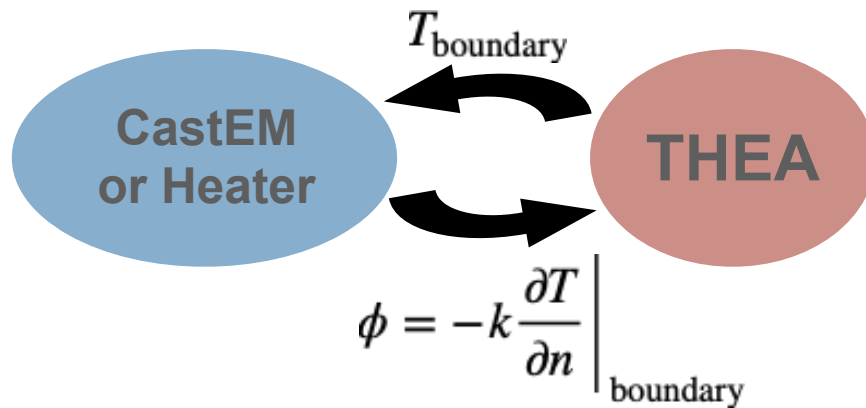


THEA components

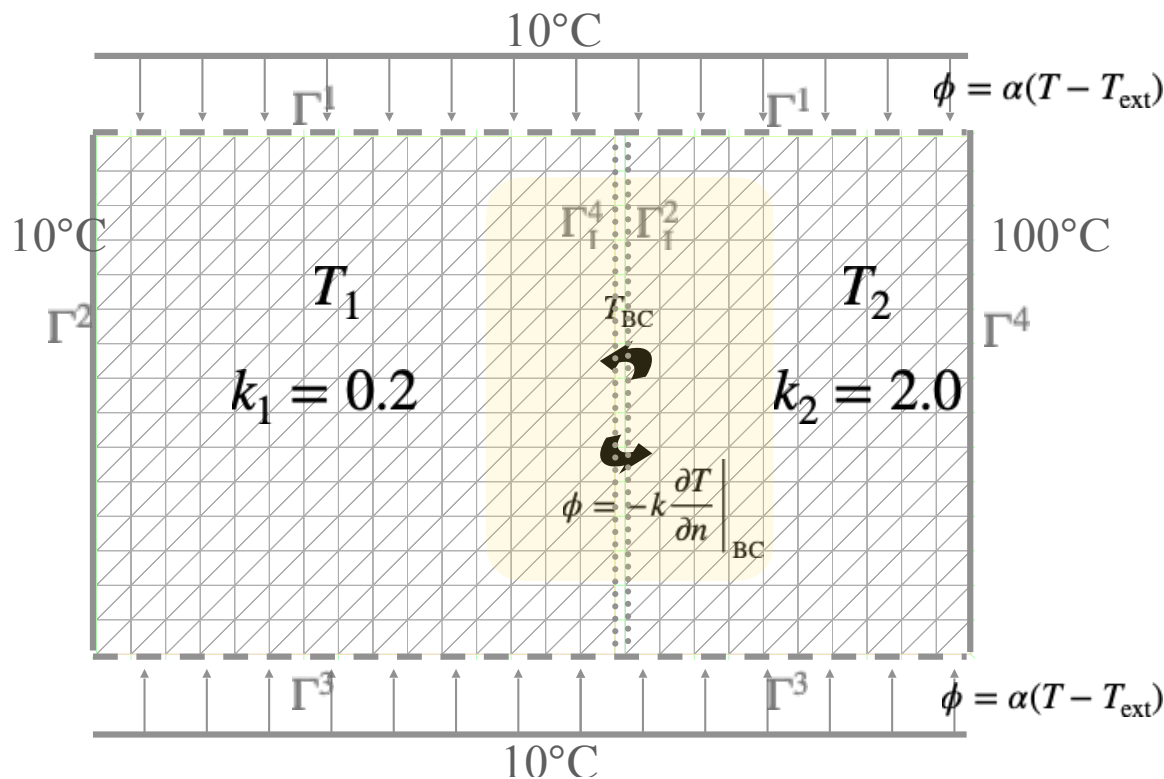
-  Thermal components
-  Hydraulic components
-  Electric transfer
-  Heat & mass transfer
-  Heat transfer
-  Code coupling (Heat transfer)



Let's make it general on the plainest consideration..



: The THEA model gives the boundary temperature of the solid structure (Cast3M or Heater) model, and takes the heat flux of the boundary.



$$\begin{cases} \frac{\partial T}{\partial t} - \nabla \cdot (k \nabla T) = q & \text{at } \Omega \\ T = T_{BC} \text{ or } \phi = -k \frac{\partial T}{\partial n} \Big|_{BC} & \text{at } \partial\Omega \end{cases}$$

weak form

$$\int_{\Omega} \frac{T^{n+1} - T^n}{\Delta t} \tau \, dv + \int_{\Omega} k \nabla T^{n+1} \cdot \nabla \tau \, dv + \oint_{\partial\Omega} k \frac{\partial T^{n+1}}{\partial n} \tau \, dS = \int_{\Omega} q \tau \, dv$$

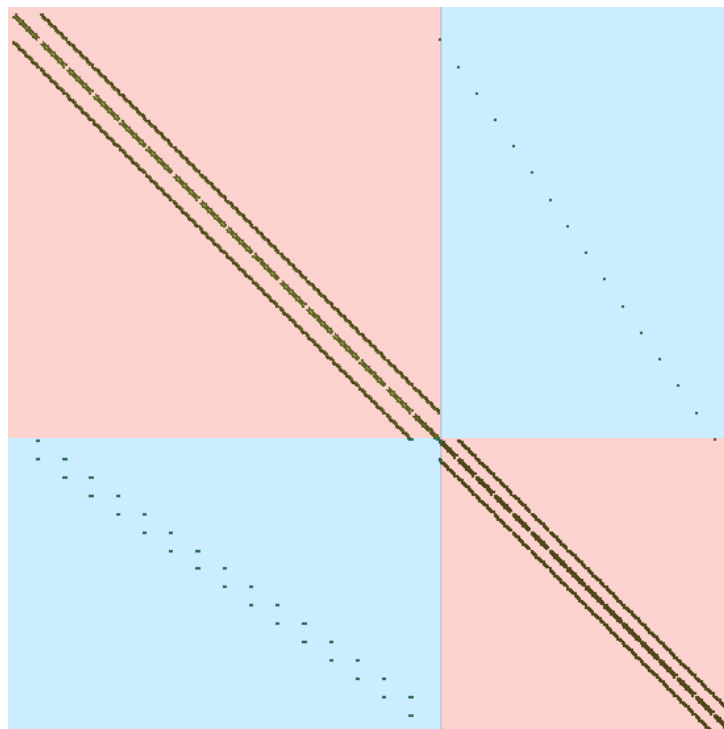
& boundary constraints
($T = T_{BC}$)

In the backward-Euler scheme..

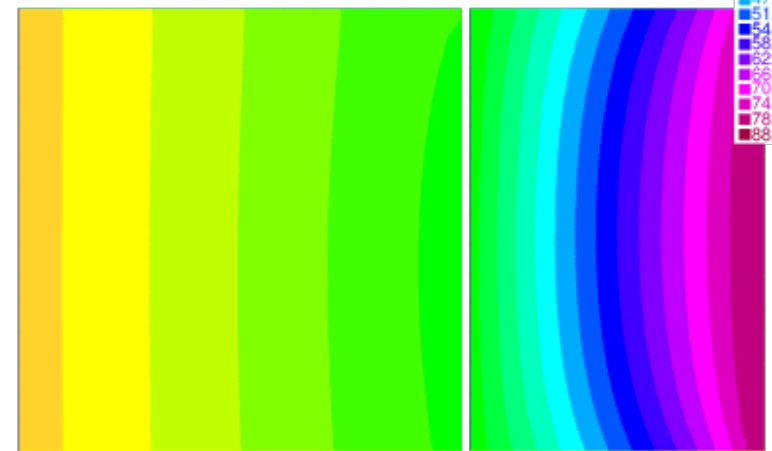
Day 2-1

: It looks trivial, if we take them in total!

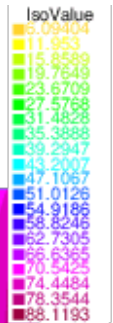
$$\begin{bmatrix} \frac{1}{\Delta t}[\mathbf{M}_1] + [\mathbf{A}_1] & [\mathbf{C}_{12}] \\ [\mathbf{C}_{21}] & \frac{1}{\Delta t}[\mathbf{M}_2] + [\mathbf{A}_2] \end{bmatrix} \cdot \begin{bmatrix} \Delta \mathbf{T}_1 \\ \Delta \mathbf{T}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{q}_1 \\ \mathbf{q}_2 \end{bmatrix} - \begin{bmatrix} [\mathbf{A}_1] & [\mathbf{C}_{12}] \\ [\mathbf{C}_{21}] & [\mathbf{A}_2] \end{bmatrix} \begin{bmatrix} \mathbf{T}_1^n \\ \mathbf{T}_2^n \end{bmatrix}$$



$$T_1/\epsilon = T_2/\epsilon$$



$t = 5 (\Delta t = 0.1)$

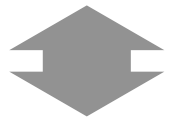


$$-k_1 \frac{\partial T_1}{\partial n} = k_2 \frac{\partial T_2}{\partial n}$$

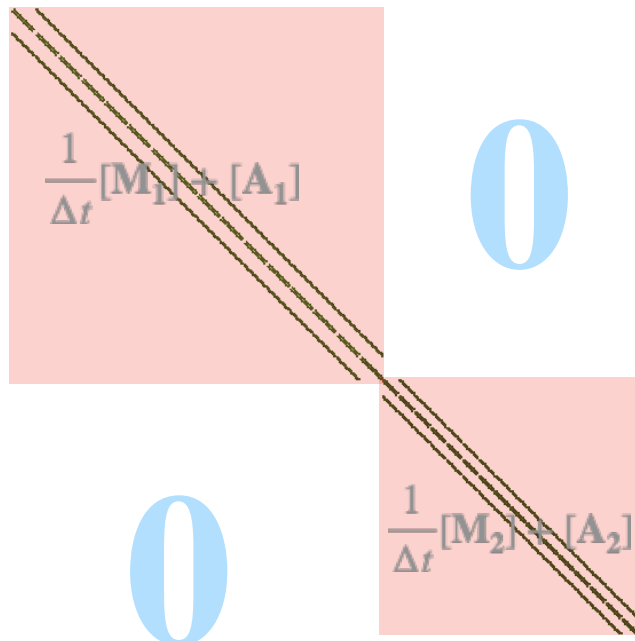
A FreeFEM++ model

Once separated, they bring a trouble..

$$\begin{cases} \left(\frac{1}{\Delta t} [\mathbf{M}_1] + [\mathbf{A}_1] \right) \cdot \Delta \mathbf{T}_1 = \mathbf{q}_1 - [\mathbf{A}_1] \cdot \mathbf{T}_1^n - [\mathbf{C}_{12}] \cdot \mathbf{T}_2^n & \text{Setting } T_{BC} \text{ to \#1} \\ \left(\frac{1}{\Delta t} [\mathbf{M}_2] + [\mathbf{A}_2] \right) \cdot \Delta \mathbf{T}_2 = \mathbf{q}_2 - [\mathbf{A}_2] \cdot \mathbf{T}_2^n - [\mathbf{C}_{21}] \cdot \mathbf{T}_1^n & \text{Transferring } -k \frac{\partial T}{\partial n} \Big|_{BC} \text{ to \#2} \end{cases}$$



$$\begin{bmatrix} \frac{1}{\Delta t} [\mathbf{M}_1] + [\mathbf{A}_1] & \mathbf{0} \\ \mathbf{0} & \frac{1}{\Delta t} [\mathbf{M}_2] + [\mathbf{A}_2] \end{bmatrix} \cdot \begin{bmatrix} \Delta \mathbf{T}_1 \\ \Delta \mathbf{T}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{q}_1 \\ \mathbf{q}_2 \end{bmatrix} - \begin{bmatrix} [\mathbf{A}_1] & [\mathbf{C}_{12}] \\ [\mathbf{C}_{21}] & [\mathbf{A}_2] \end{bmatrix} \begin{bmatrix} \mathbf{T}_1^n \\ \mathbf{T}_2^n \end{bmatrix}$$



$t = 5 (\Delta t = 0.1)$

How to recover the lost terms

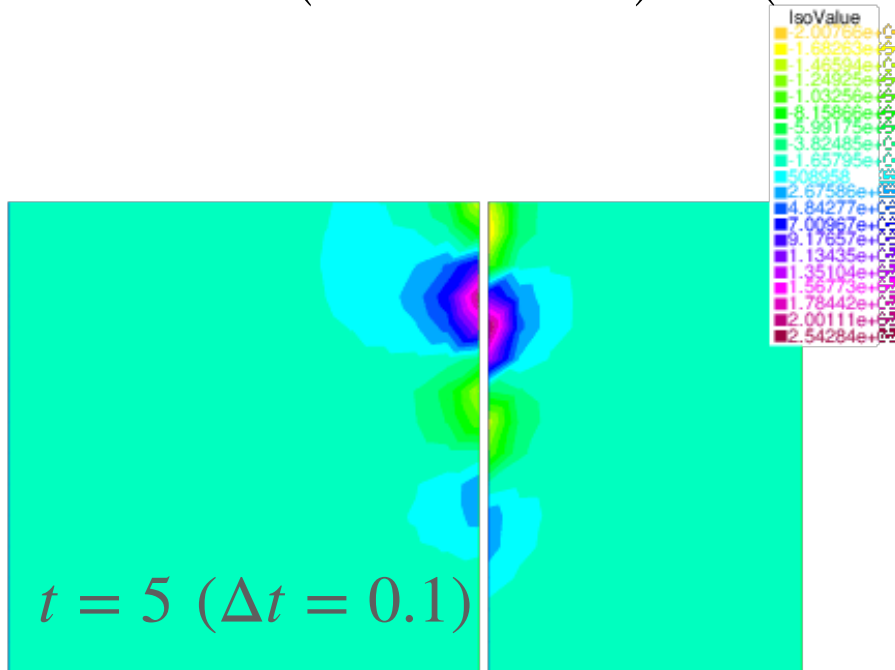
Day 2-1

In sequence

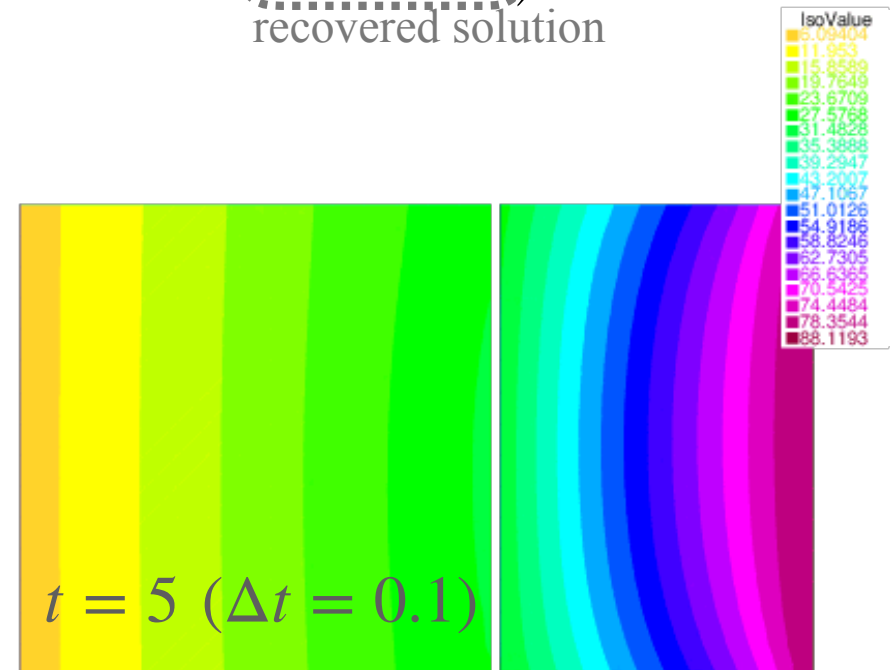
$$\Delta \mathbf{T}_1^* = \left(\frac{1}{\Delta t} [\mathbf{M}_1] + [\mathbf{A}_1] \right)^{-1} \cdot \left(\mathbf{q}_1 - [\mathbf{A}_1] \cdot \mathbf{T}_1^n - [\mathbf{C}_{12}] \cdot \mathbf{T}_2^n \right)$$

$$\Delta \mathbf{T}_2 = \left(\frac{1}{\Delta t} [\mathbf{M}_2] + [\mathbf{A}_2] - \underbrace{[\mathbf{C}_{21}] \cdot [\bar{\mathbf{C}}_{12}]}_{\text{interface Jacobian}} \right)^{-1} \cdot \left(\mathbf{q}_2 - [\mathbf{A}_2] \cdot \mathbf{T}_2^n - [\mathbf{C}_{21}] \cdot \underbrace{\left(\mathbf{T}_1^n + \Delta \mathbf{T}_1^* \right)}_{\text{trial solution}} \right)$$

$$\Delta \mathbf{T}_1 = \left(\frac{1}{\Delta t} [\mathbf{M}_1] + [\mathbf{A}_1] \right)^{-1} \cdot \left(\mathbf{q}_1 - [\mathbf{A}_1] \cdot \mathbf{T}_1^n - [\mathbf{C}_{12}] \cdot \underbrace{\left(\mathbf{T}_2^n + \Delta \mathbf{T}_2 \right)}_{\text{recovered solution}} \right)$$



Without IJ



With IJ

The interface Jacobian makes implicit steps true!

A Lesson Learned

: Conceptually, the interface Jacobian means **changing rate of the boundary value** with respect to the upcoming solution!

➔ However, the changing rate is just one, naturally implicated by the fixed BC for #1

$$[\mathbf{C}_{21}] \cdot [\bar{\mathbf{C}}_{12}] \cdot \Delta \mathbf{T}_2$$

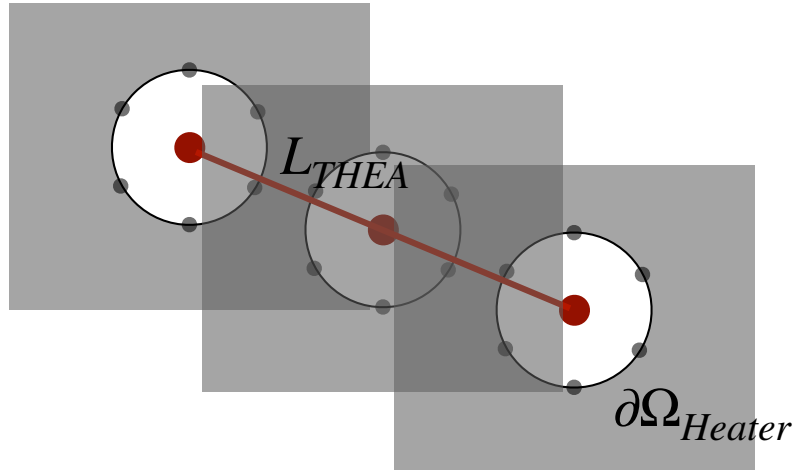
Along the boundary, it just maps the nodal indices of #2 to the indices of #1

The FEM matrix of boundary heat flux as the integration over shape functions along the boundary

$$: \int_{\partial\Omega} -k \frac{\partial T^{n+1}}{\partial n} \tau \, dS \longrightarrow \sum_{ij} \left\{ \int_{\partial\Omega} -k \frac{\partial w_i}{\partial n} v_j \, dS \right\} T_{1i} T_{2j}$$

➔ So, the point is transferring the coefficients of heat flux to the THEA model to build a new component of the system matrix.

For our actual target, i.e., of THEA-Cast3M, or THEA-Heater coupling..



$$q_{THEA} = - \oint_{\partial\Omega_{Heater}} k \frac{\partial T}{\partial n} dS$$

So, the coupling matrix $[C_{21}]$ can be derived from the integral over $\partial\Omega_{Heater}$ and L_{THEA}

$$\text{i.e.} \int_{L_{THEA}} \oint_{\partial\Omega_{Heater}} -k \frac{\partial w_i(S, x)}{\partial n} dS v_j(x) dx .$$

Actually, the interface Jacobian terms are represented simply as the rate $\Delta Q / \Delta T$, i.e., how much the heat load will vary, if the boundary temperature is changed.

So, we revise the THEA code to consider such an idea..

Let's revise the THEA code..

$$\left\{ \frac{[\mathbf{M}]}{\Delta t} + ([\mathbf{A}] + [\mathbf{G}] - [\mathbf{S}]) \right\} \cdot \Delta \mathbf{U} = \mathbf{Q} - ([\mathbf{A}] + [\mathbf{G}] - [\mathbf{S}]) \cdot \mathbf{U}^n$$

$$\mathbf{Q} = \mathbf{Q}^n + [\mathbf{C}] \cdot \Delta \mathbf{T}_{bc} \longleftarrow [\mathbf{C}] = \left[\int_L w_i^T \left(\frac{\Delta q_i}{\Delta T_j} \right) w_j dx \right]_{\text{per BC DoF}}$$



☞ Actually, $\left(\frac{\Delta q_i}{\Delta T_j} \right)$ is diagonal.


$$\left\{ \frac{[\mathbf{M}]}{\Delta t} + ([\mathbf{A}] + [\mathbf{G}] - [\mathbf{S}] - [\mathbf{C}]) \right\} \cdot \Delta \mathbf{U} = \mathbf{Q}^n - ([\mathbf{A}] + [\mathbf{G}] - [\mathbf{S}]) \cdot \mathbf{U}^n$$

That's it!

: The THEA code is now revised in consistent with our idea to include the IJ terms.

What about the counter parts of THEA?

: We are looking for high level commands to evaluate the coupling matrix (or the integral of shape functions).


CHAP. 2.1: STATIONARY LINEAR THERMAL ANALYSIS
CONVECTION AND VOLUME HEAT SOURCE

■ Mathematical formulation

* CONVECTION MODEL
MOC = MODE LHAUT 'THERMIQUE' 'CONVECTION' ;
MAC = MATE MOC 'H' 100. ;

■ Conductivity matrix (but for convection !)

* FIRST MEMBER FOR CONVECTION
CONH = COND MOC MAC ;

$$[K] = \int_V [B]^T [\lambda] [B] dV + \int_{\partial V \varphi} h [N]^T [N] dS$$

■ Equivalent nodal heat flux vector (convection)

* SECOND MEMBER FOR CONVECTION
CHTC = MANU 'CHPO' LHAUT 'T' T0 ;
FLH = CONV MOC MAC CHTC ;

$$\{F\} = \int_V [N]^T q dV + \int_{\partial V \varphi} [N]^T (\varphi_{imp} + hT_f + \varepsilon\sigma(T_\infty^4 - T^4)) dS$$

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$$[C_{21}] \cdot [\bar{C}_{12}] \cdot \Delta T_2 \longrightarrow$$

$$\int_L dx \int_{\partial\Omega} -k \frac{\partial w_i}{\partial n} dS$$

$$\longrightarrow \left. \frac{\Delta Q_1}{\Delta T_2} \right|_{\text{per BC}}$$

Regarding the Heater code,..

: The Heater code, like all the CryoSoft codes, solves the equations with constraints (fixed boundaries), computing their residuals on the r.h.s..

$$\begin{array}{c}
 \text{to be solved} \\
 \text{constraint} \\
 \text{(fixed)} \\
 \mathbf{[F]} \begin{bmatrix} \mathbf{T}_1^{n+1} - \mathbf{T}_1^n \\ \mathbf{T}_2^{n+1} - \mathbf{T}_2^n \end{bmatrix} \\
 \text{fixed} \\
 \text{residual} \\
 \text{(to be solved)}
 \end{array}
 =
 \begin{array}{c}
 \text{fixed} \\
 \begin{bmatrix} \mathbf{Q}_1 \\ \mathbf{Q}_2 \end{bmatrix} \\
 \text{fixed} \\
 \begin{bmatrix} \mathbf{T}_1^n \\ \mathbf{T}_2^n \end{bmatrix}
 \end{array}
 - ([\mathbf{A}] + [\mathbf{G}] - [\mathbf{S}])
 \begin{array}{c}
 \text{fixed} \\
 \begin{bmatrix} \mathbf{T}_1^n \\ \mathbf{T}_2^n \end{bmatrix} \\
 \text{1 : core} \\
 \text{2 : boundary}
 \end{array}$$

Where $\mathbf{[F]} = \frac{[\mathbf{M}]}{\Delta t} + ([\mathbf{A}] + [\mathbf{G}] - [\mathbf{S}])$

☞ We are better to change the solution scheme for correct evaluation of the IJ terms.

$$\begin{array}{c}
 \text{to be solved} \\
 \text{fixed} \\
 \text{residual} \\
 \text{(to be solved)}
 \end{array}
 \mathbf{[F]} \begin{bmatrix} \mathbf{T}_1^{n+1} - \mathbf{T}_1^n \\ \mathbf{0} \end{bmatrix}
 =
 \begin{array}{c}
 \text{fixed} \\
 \begin{bmatrix} \mathbf{Q}_1 \\ \mathbf{Q}_2 \end{bmatrix} \\
 \text{fixed} \\
 \begin{bmatrix} \mathbf{T}_1^n \\ \mathbf{T}_2^{n+1} \end{bmatrix} \\
 \text{constraint} \\
 \text{(fixed)}
 \end{array}
 - ([\mathbf{A}] + [\mathbf{G}] - [\mathbf{S}])$$

Let's revise the Heater code..

: Then, the IJ terms are obtained as the variation along with the boundary temperatures.

$$\begin{array}{l} \text{solution} \\ \text{(dummy)} \end{array} [\mathbf{F}] \begin{bmatrix} \Delta T' \\ \mathbf{0} \end{bmatrix} = \begin{bmatrix} \mathbf{0} \\ \frac{\Delta Q}{\Delta T} \end{bmatrix} - ([\mathbf{A}] + [\mathbf{G}] - [\mathbf{S}]) \begin{bmatrix} \mathbf{0} \\ \mathbf{1} \end{bmatrix} \begin{array}{l} : \text{ core} \\ : \text{ boundary} \end{array}$$

residual
(what we need)

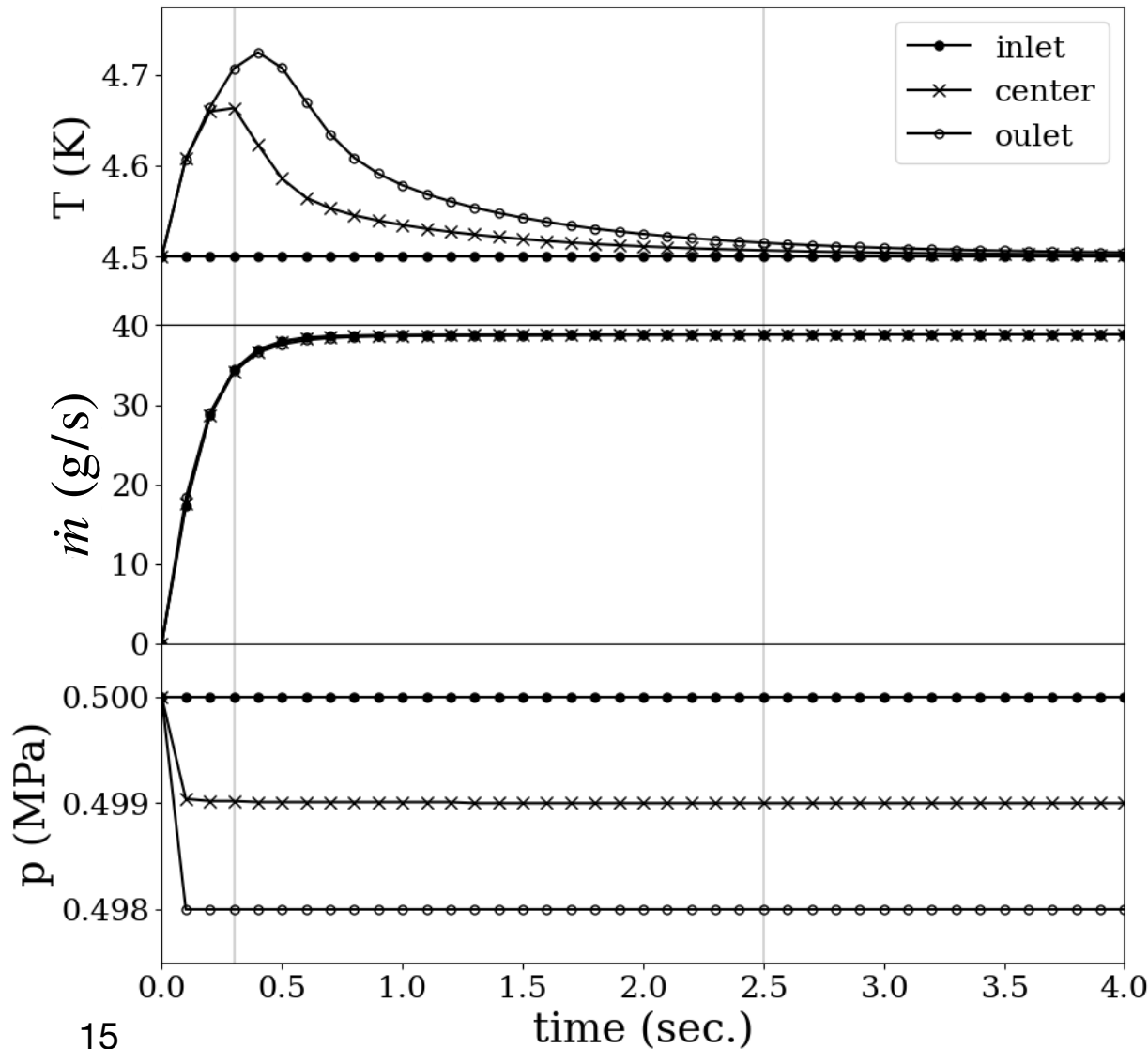
☞ That means we need to solve the matrix again to obtain the IJ terms of $\frac{\Delta Q}{\Delta T}$, which looks costly; any cheaper approximation?

☞ The Heater code is updated to evaluate the additional terms of IJ which will be transferred to the THEA code to compose the [C]-matrix

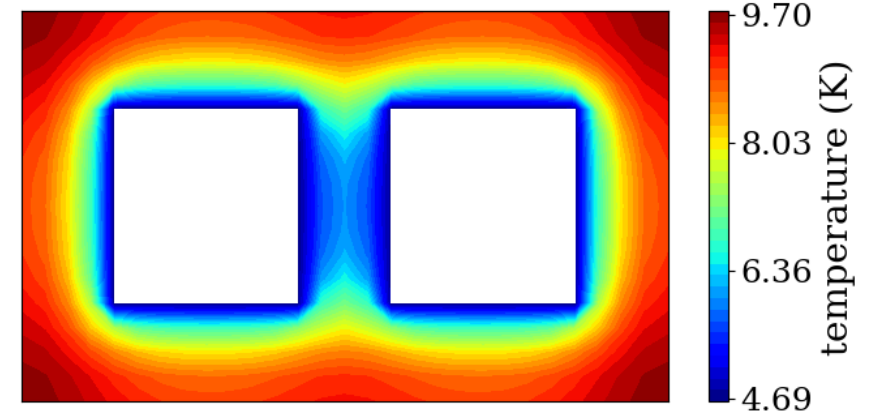
Verification (1/4)

: Let's consider a co-current SUS304 heat exchanger, initially at 10K, with two helium channels (1m) of rectangular flow area (1cm x 1cm)..

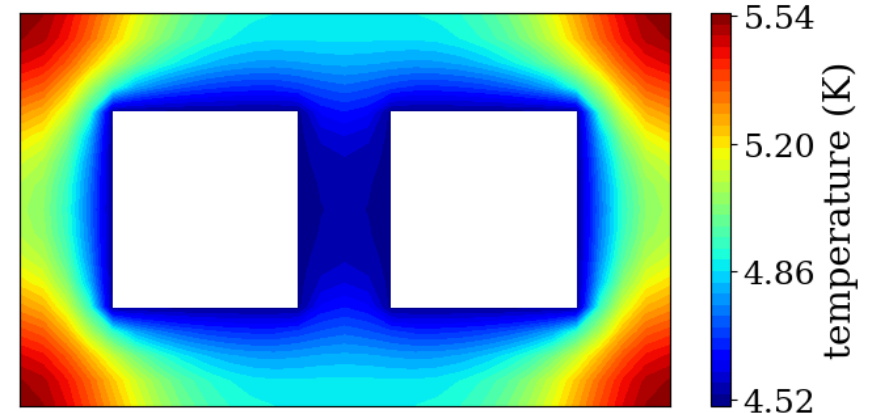
• hydraulic flows



• outlet temperature



time = 0.3 sec.

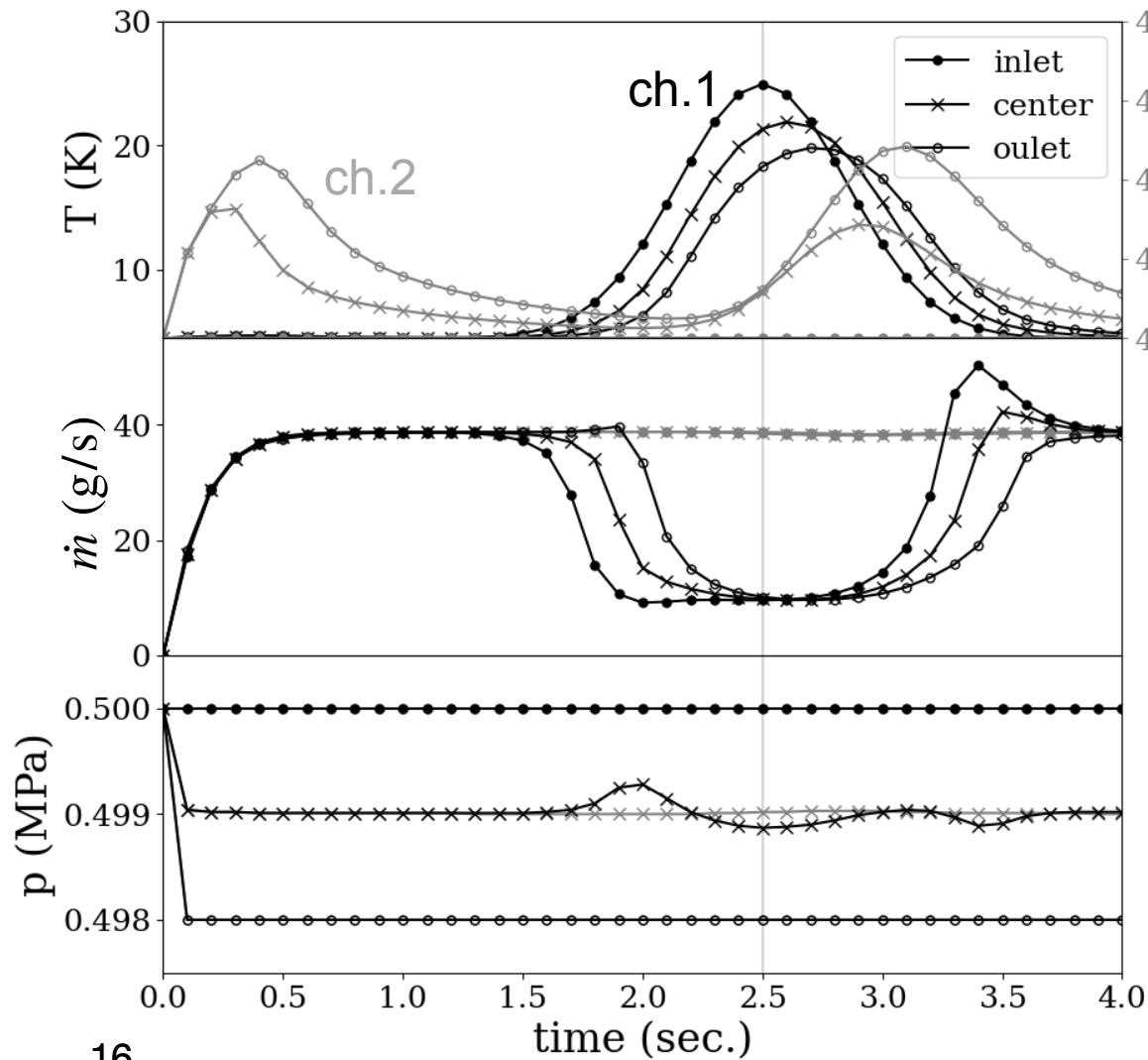


time = 2.5 sec.

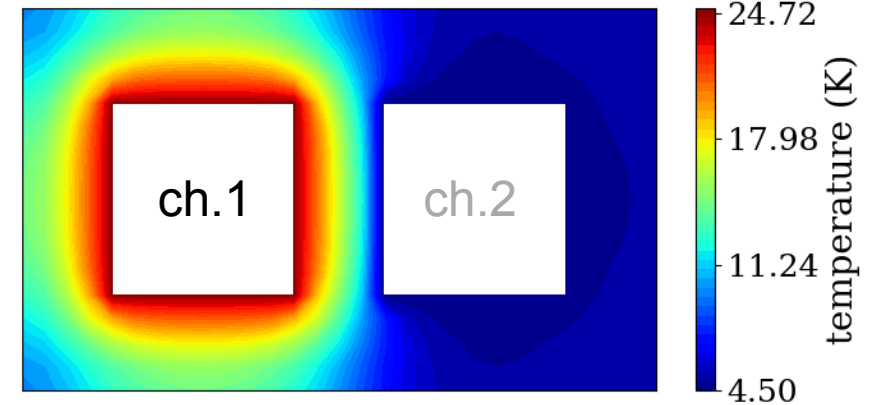
Verification (2/4)

: Then, let's change the inlet temperature of the channel 1 up to 25K and more around 2.5 sec.

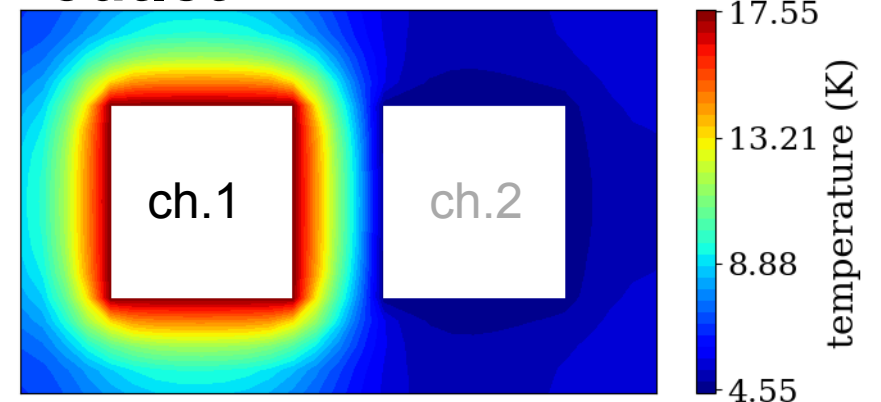
• hydraulic flows



• inlet



• outlet



time = 2.5 sec.

Verification (3/4)

Day 2-1



: What about the stability? ➔ CPU time can be an indicator.

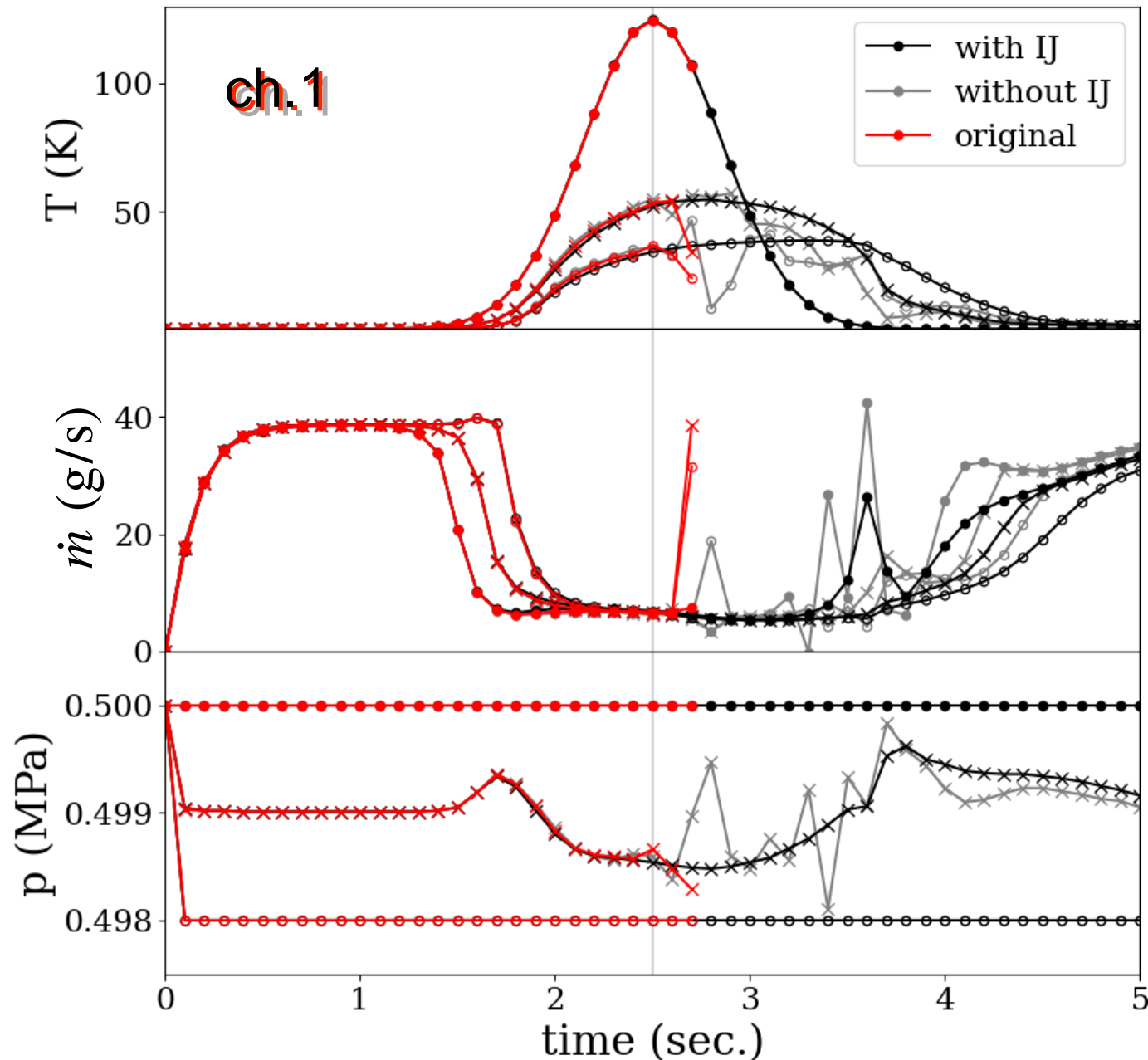
T_{peak} (K)	Original	Modified (CPU time in sec.)	
	(CPU time in sec.)	Without IJ	With IJ
50	13.6 (H1)	10.2 (H1)	10.5 (H1)
	0.59 (T1)	0.57 (T1)	0.57 (T1)
	0.61 (T2)	0.59 (T2)	0.62 (T2)
75	16.7 (H1)	10.5 (H1)	10.5 (H1)
	0.61 (T1)	0.56 (T1)	0.56 (T1)
	0.60 (T2)	0.59 (T2)	0.61 (T2)
100	17.9 (H1)	10.3 (H1)	10.4 (H1)
	1.17 (T1)	0.63 (T1)	0.57 (T1)
	0.60 (T2)	0.57 (T2)	0.60 (T2)
125	broken solution (at ~60% eval.)	11.8 (H1)	10.5 (H1)
		1.40 (T1)	0.65 (T1)
		0.60 (T2)	0.59 (T2)



Verification (4/4)

Day 2-1

: Let's look into the case of inlet temperature 125 K.



Improved, but..

➔ The hydraulic terminals seem to be the source of instability!

Conclusion

- **A better coupling scheme for integrated modeling is introduced on the lesson learned from the plainest case of thermal contact.**
- ☞ The issue of THEA-Cast3M models in quench is to be understood by pointing out the source of trouble on our attempt of new coupling scheme.

Supplements

Issue #2 : hard boundary constraints

We already developed such a boundary scheme..

* We applied them to the CICC (THEA) models..

Inlet :

$$\left\{ \begin{array}{l} [\text{AU}]_{v, i=1} = \bar{v} \left(\frac{v_2 - v_1}{2} \right) + \frac{1}{\bar{\rho}} \left(\frac{p_2 - p_0^{(in)}}{2} \right) + \frac{\bar{v}}{\bar{\rho} \bar{c}} \left(\frac{p_1 - p_0^{(in)}}{2} \right) \text{ Negligible} \\ [\text{AU}]_{p, i=1} = \bar{\rho} \bar{c}^2 \left(\frac{v_2 - v_1}{2} \right) + \bar{v} \left(\frac{p_2 - p_0^{(in)}}{2} \right) + \bar{c} \left(\frac{p_1 - p_0^{(in)}}{2} \right) \text{ The boundary pressure follows the constraint in the speed of sound.} \\ [\text{AU}]_{T, i=1} = \overline{\rho \phi C_v T} \left(\frac{v_2 - v_1}{2} \right) + \overline{\rho C_v v} \left(\frac{T_2 + T_1}{2} - T_0^{(in)*} \right) + \frac{\phi C_v T (\bar{c} - \bar{v})}{\bar{c}^2} \left(\frac{p_1 - p_0^{(in)}}{2} \right) \text{ The boundary temperature follows the upwind constraint in the flow velocity.} \end{array} \right.$$

Outlet :

$$\left\{ \begin{array}{l} [\text{AU}]_{v, i=n} = \bar{v} \left(\frac{v_n - v_{n-1}}{2} \right) + \frac{1}{\bar{\rho}} \left(\frac{p_0^{(out)} - p_{n-1}}{2} \right) + \frac{\bar{v}}{\bar{\rho} \bar{c}} \left(\frac{p_n - p_0^{(out)}}{2} \right) \\ [\text{AU}]_{p, i=n} = \bar{\rho} \bar{c}^2 \left(\frac{v_n - v_{n-1}}{2} \right) + \bar{v} \left(\frac{p_0^{(out)} - p_{n-1}}{2} \right) + \bar{c} \left(\frac{p_n - p_0^{(out)}}{2} \right) \\ [\text{AU}]_{T, i=n} = \overline{\rho \phi C_v T} \left(\frac{v_n - v_{n-1}}{2} \right) + \overline{\rho C_v v} \left(T_0^{(out)*} - \frac{T_{n-1} + T_n}{2} \right) + \frac{\phi C_v T (\bar{c} - \bar{v})}{\bar{c}^2} \left(\frac{p_n - p_0^{(out)}}{2} \right) \end{array} \right.$$

An application of the decomposed flux boundary (Eq 4 and Eq 5) in the reference, *i.e.*,
D. K. Oh and S. Oh, "Improved 1-d hydraulic network model for cryogenic circuits coupled to CICC models of fusion magnet systems" *Cryogenics* 97 (2019) 133-143

Actually, there is a trick.

$$[\mathbf{IJ}] = [\mathbf{C}_{21}] \cdot \left(\frac{1}{\Delta t} [\mathbf{M}_1] + [\mathbf{A}_1] \right)^{-1} \cdot [\mathbf{C}_{12}] \quad \text{At a glance, matrix inversion seems not avoidable!}$$

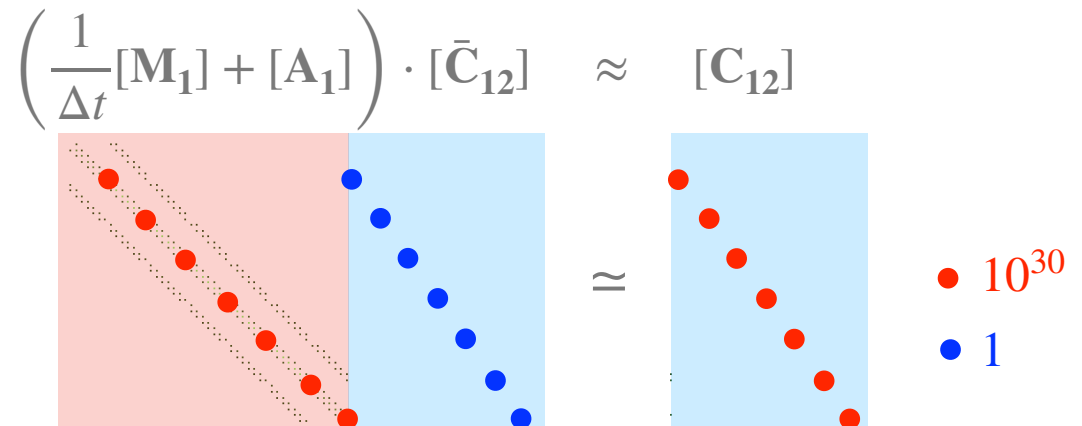
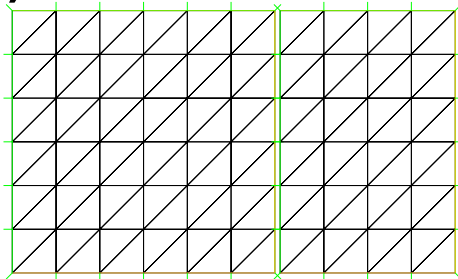
↓ Nonetheless, don't forget the artificial elements (TGV) assigned to be LARGE enough, typically, as 10^{30} to impose the static constraint of temperature boundary condition.

$$\text{Let } [\bar{\mathbf{C}}_{12}] = 10^{-30} \times [\mathbf{C}_{12}] \Rightarrow \left(\frac{1}{\Delta t} [\mathbf{M}_1] + [\mathbf{A}_1] \right) \cdot [\bar{\mathbf{C}}_{12}] \approx [\mathbf{C}_{12}]$$

➡ This means $[\bar{\mathbf{C}}_{12}]$ has the same structure with elements of 1 instead of 10^{30} !

$$\blacksquare [\mathbf{IJ}] \approx [\mathbf{C}_{21}] \cdot [\bar{\mathbf{C}}_{12}]$$

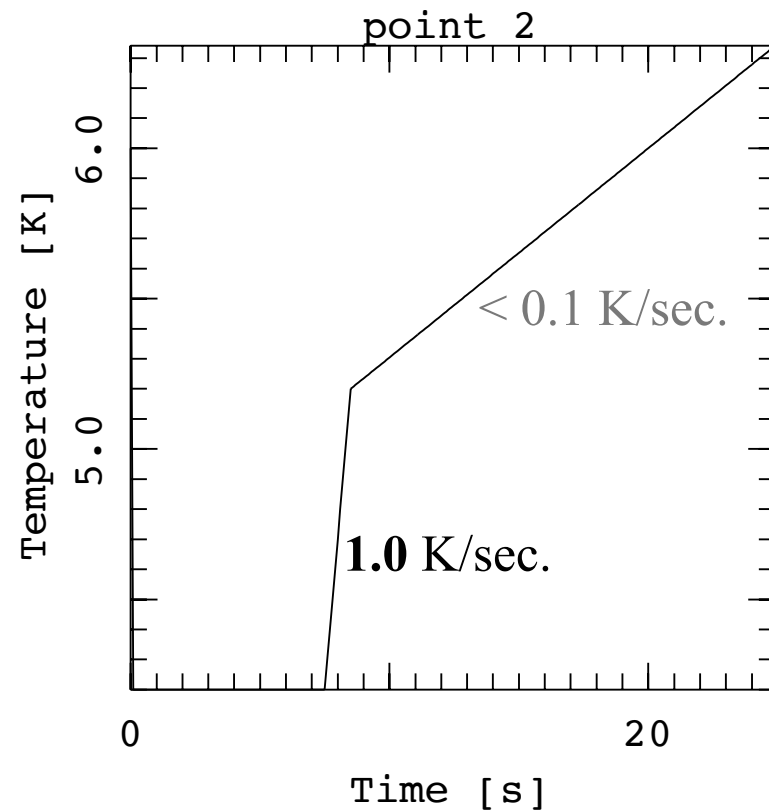
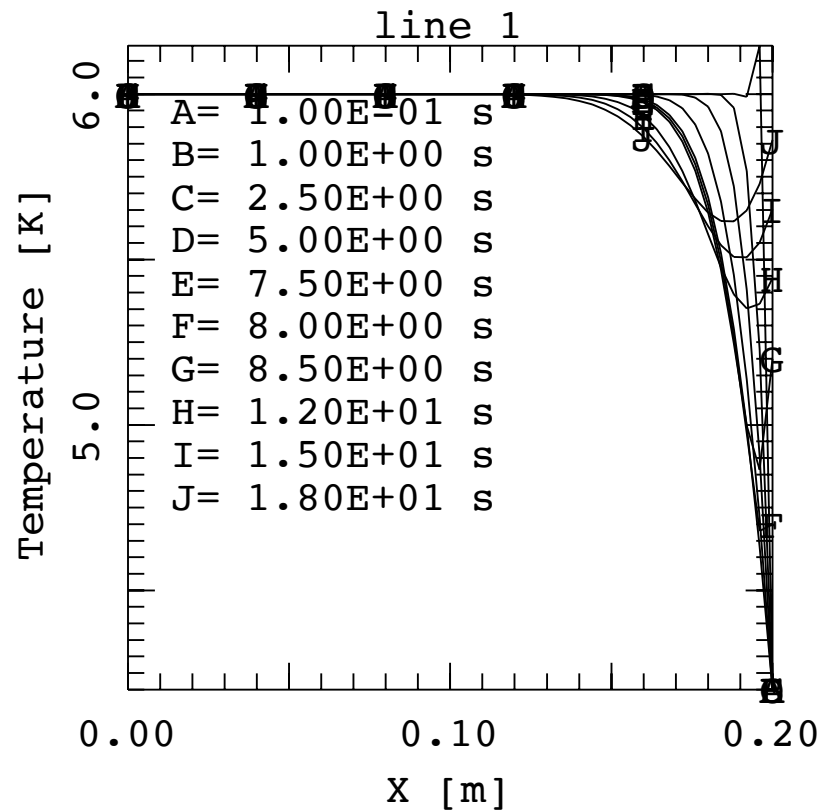
Ex)



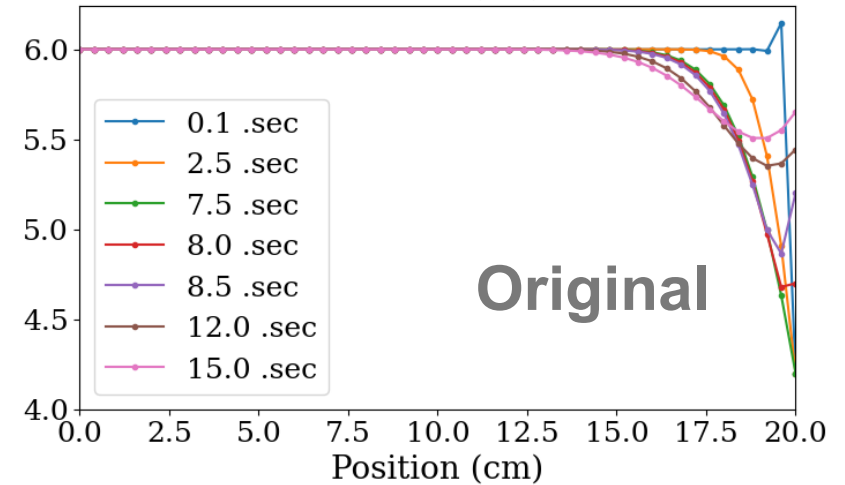
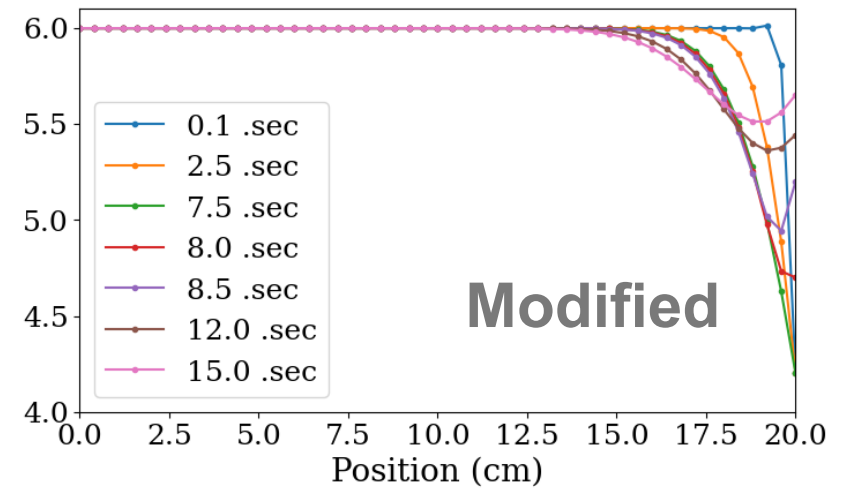
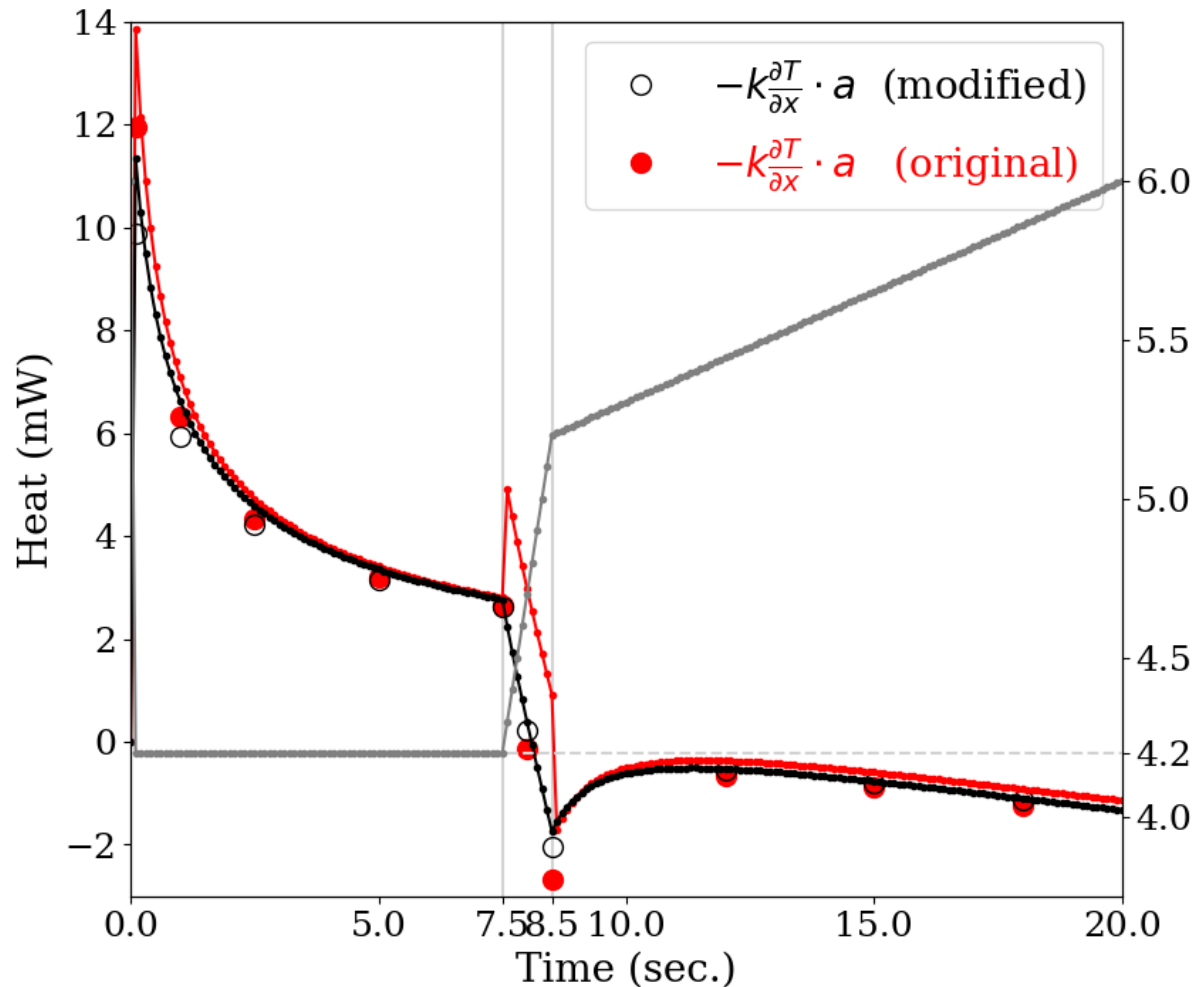
Solution scheme.. What? (1/2)

Let's check the simple 1-d Heater model of a metal wire:

- A SUS304 wire of 0.2m (area = 1.0 cm²)
- 50 elements (51 node)
- Initial temperature : 6 K
- Boundary temperature: Adiabatic (left end), 4.2 to 6 K (right end)



Solution scheme.. What? (2/2)



➡ The original routine looks counting another amount of heat load to change the nodal temperature itself, which may bring an incorrect result deviated from the net heat flow out of the boundary.