

UNIT OF EXCELLENCE MARÍA DE MAEZTU

Quantum reservoir computing in finite dimensions Physical Review E 107 (3), 035306 Rodrigo Martínez-Peña (IFISC) Juan-Pablo Ortega (NTU, Singapore)

PhD supervisors: Roberta Zambrini and Miguel C. Soriano

June 1st 2023











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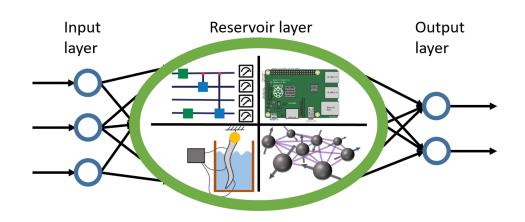


Introduction



- (Quantum) Reservoir Computing
- Motivation of this work

- Result 1
- Result 2 and examples
- Conclusions and outlook







- Ease of use
- Unified theory
- Universal (can emulate Turing machines)





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But it has some problems: • Energy footprint 10% Andrae, A. S.,

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DIEMS: Challenges,

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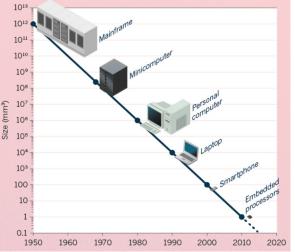
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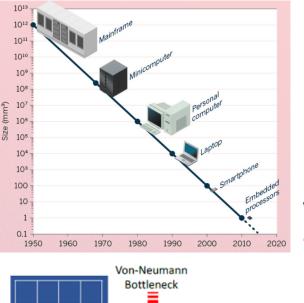
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Processor

'In-memory' Computing

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Tom Dillinger





• Possible alternative in **Neuromorphic Computing:** brain-inspired computing paradigm. **Computation and physical substrate go hand by hand**





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Characteristics:

- Energy efficient
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Machine learning is already taking advantage of this progress. Example: Reservoir Computing







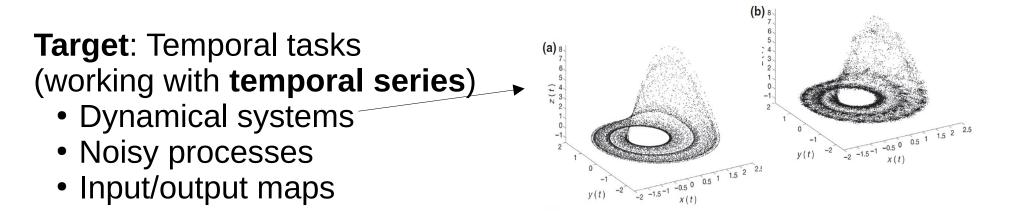


Short answer: machine learning technique that **exploits dynamical systems**





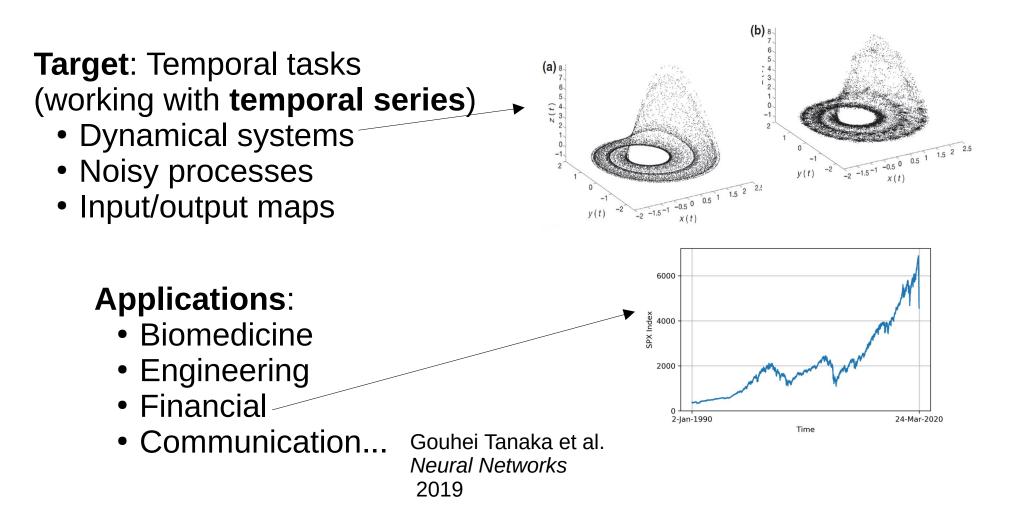
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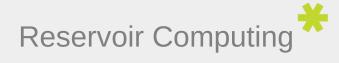




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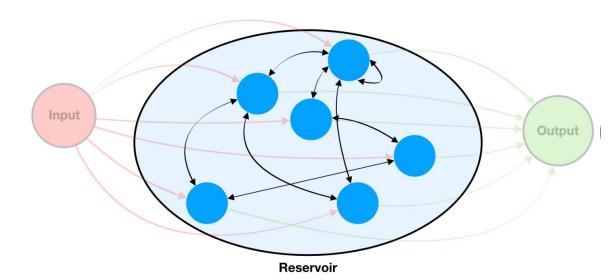








Take a dynamical system (**reservoir**)

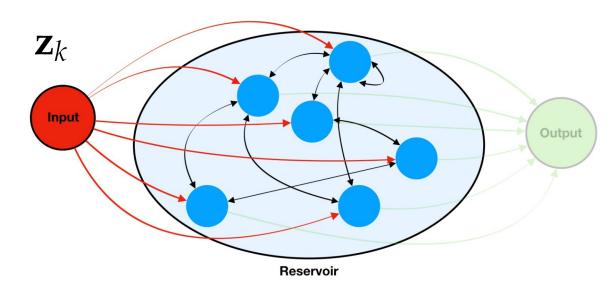






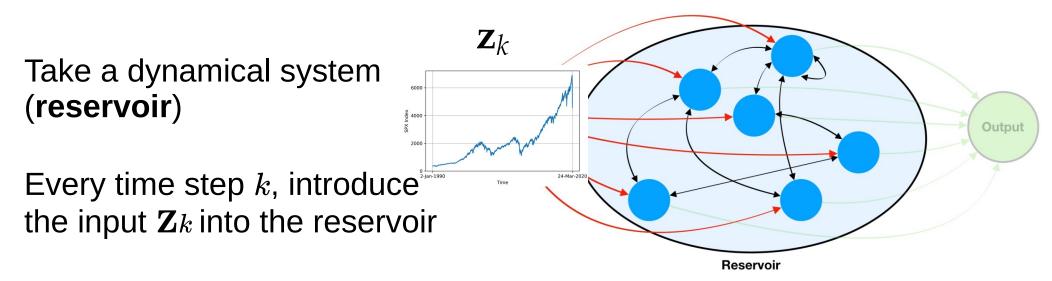
Take a dynamical system (**reservoir**)

Every time step k, introduce the input \mathbf{Z}_k into the reservoir



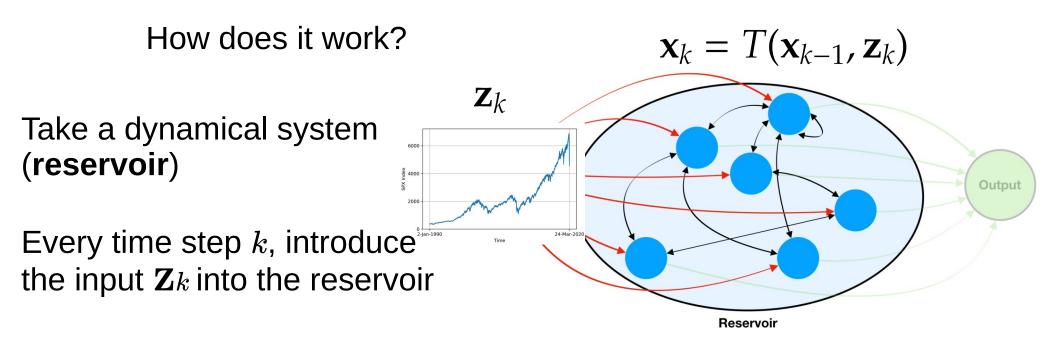






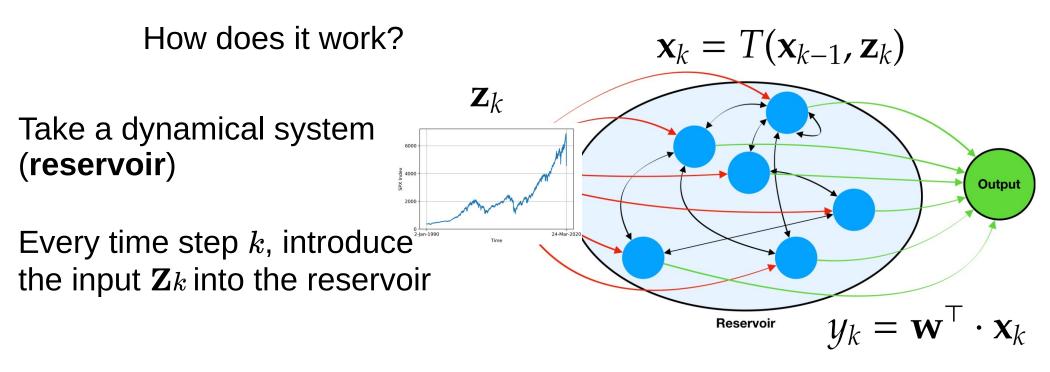








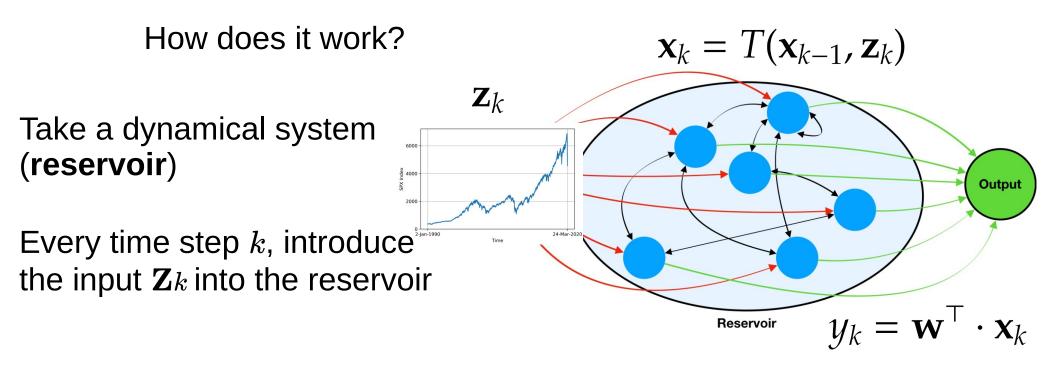




Extract the output information from \mathbf{X}_k : **linear combination** y_k







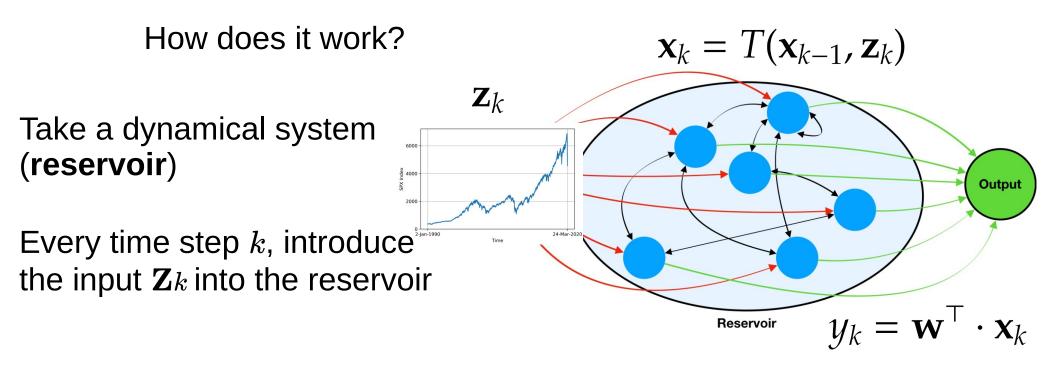
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Supervised ML!

Train **only** the linear output y_k , **don't need to tune the dynamical system**!!







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Ready to use!

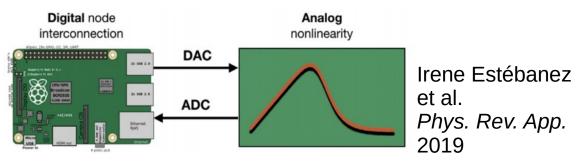


- Fast training (linear regression is enough!) $y_k = \mathbf{w}^\top \cdot \mathbf{x}_k$
- Multitasking (don't need to tune the dynamical system!!)
- Implementable in hardware





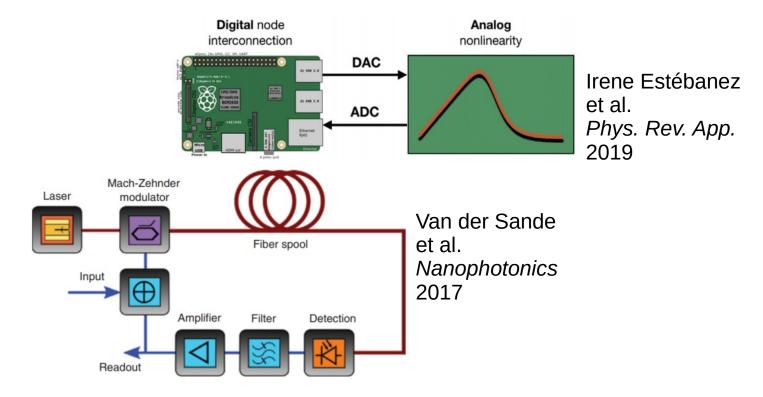
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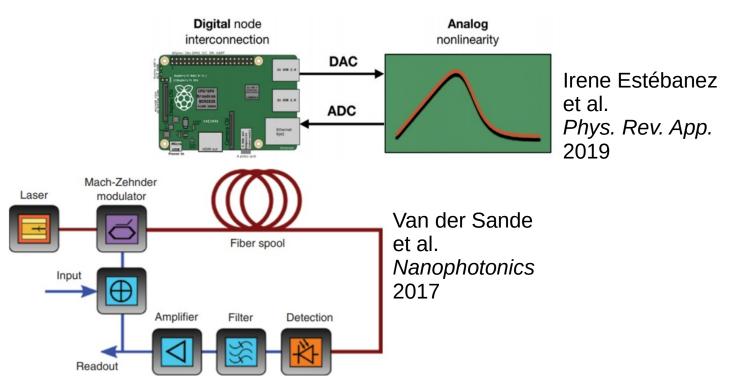




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Nakajima et al. *Scientific Reports* 2015



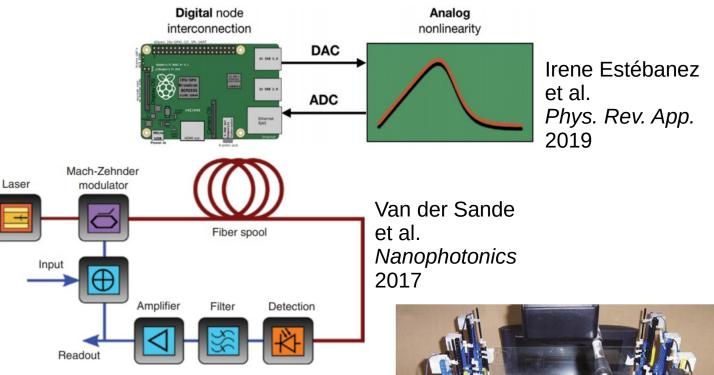




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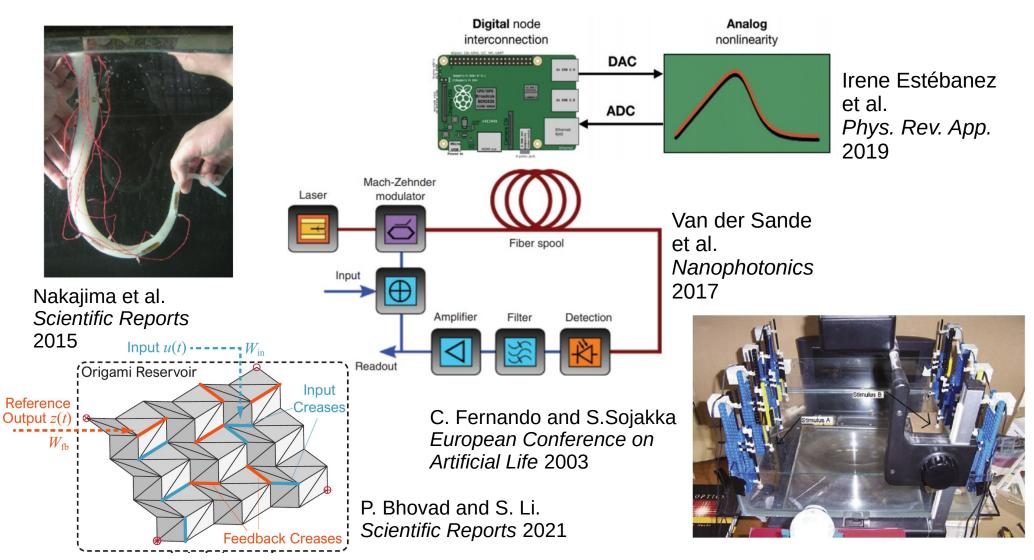
C. Fernando and S.Sojakka European Conference on Artificial Life 2003







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But what about **quantum systems**?





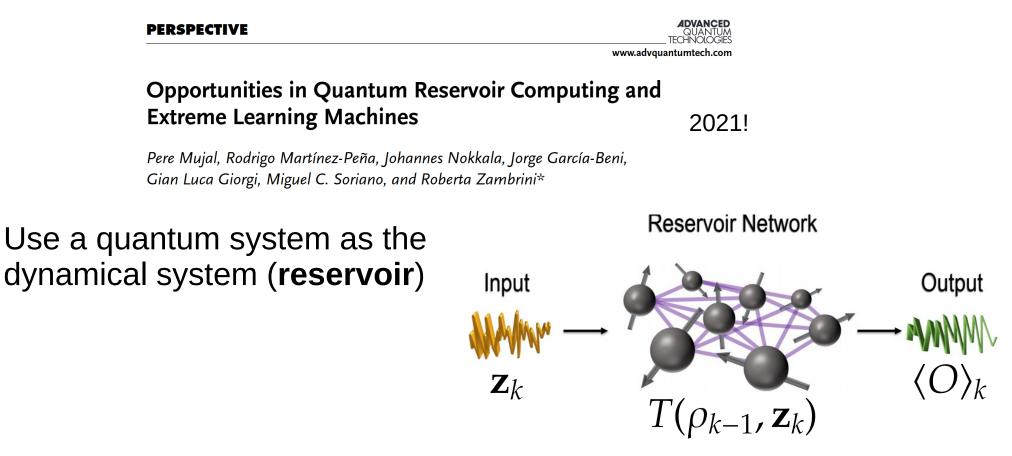
PERSPECTIVE

ADVANCED QUANTUM TECHNOLOGIES www.advquantumtech.com

Opportunities in Quantum Reservoir Computing and Extreme Learning Machines 2021!

Pere Mujal, Rodrigo Martínez-Peña, Johannes Nokkala, Jorge García-Beni, Gian Luca Giorgi, Miguel C. Soriano, and Roberta Zambrini*



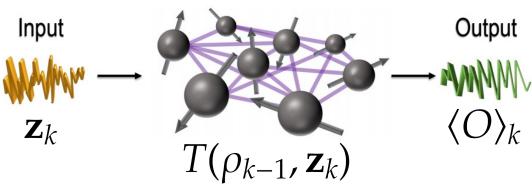






Use a quantum system as the dynamical system (**reservoir**)

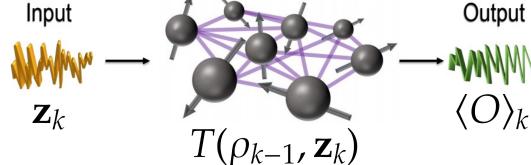
Use the **observables** for the **output**!







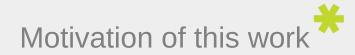
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Why quantum?

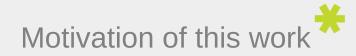
- Number of degrees of freedom increases exponentially in few body systems
- Accessible on noisy quantum devices
- Extension to process quantum data





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Quantum Information Processing (2019) 18:198 https://doi.org/10.1007/s11128-019-2311-9 PHYSICAL REVIEW LETTERS 127, 260401 (2021)

Motivation of this wor

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Jiayin Chen¹ · Hendra I. Nurdin¹

ARTICLE

https://doi.org/10.1038/s42005-021-00556-w OPEN

Communication Physics, 2021

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Johannes Nokkala⊚ ^{1⊠}, Rodrigo Martínez-Peña¹, Gian Luca Giorgi¹, Valentina Parigi⊚ ², Miguel C. Soriano⊚ ¹ & Roberta Zambrini⊚ ^{1⊠}

Learning Temporal Quantum Tomography

Quoc Hoan Trano^{1,*} and Kohei Nakajima^{1,2,†} ¹Graduate School of Information Science and Technology, The University of Tokyo, Tokyo 113-8656, Japan ²Next Generation Artificial Intelligence Research Center, The University of Tokyo, Tokyo 113-8656, Japan

(Received 5 April 2021; revised 11 October 2021; accepted 30 November 2021; published 22 December 2021)

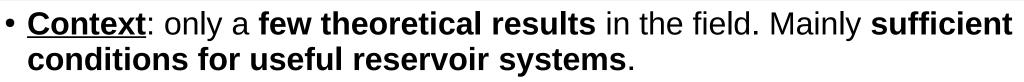
Dissipation as a resource for Quantum Reservoir Computing

Antonio Sannia, Rodrigo Martínez-Peña, Miguel C. Soriano, Gian Luca Giorgi, and Roberta Zambrini

Institute for Cross-Disciplinary Physics and Complex Systems (IFISC) UIB-CSIC, Campus Universitat Illes Balears, 07122, Palma de Mallorca, Spain.

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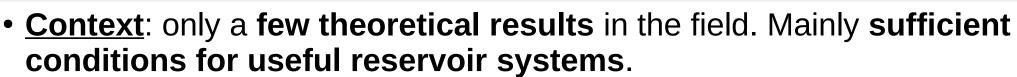
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 What we did: find necessary and sufficient conditions of useful reservoir systems.





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- What we did: find necessary and sufficient conditions of useful reservoir systems.
- <u>Why it is important</u>: universal approximation property and connection with experimental design.









Setup:

- Finite dimensional system
- Classical input information
- Ideal measurements (Some experimental works can be approximated by this limit)



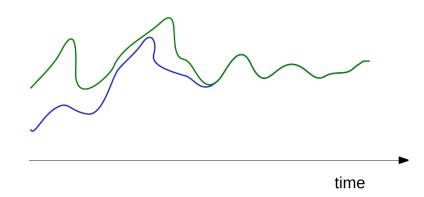


Setup:

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Result:

A quantum reservoir is **useful if and only** if the dynamics of the quantum channel **converges** towards **input-dependent** fixed points



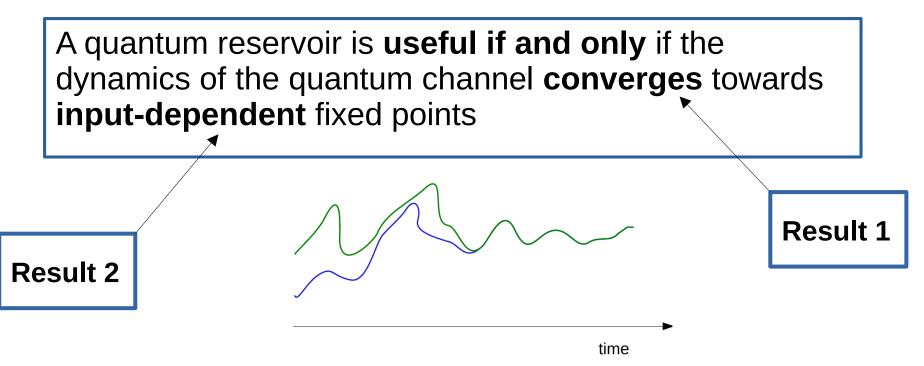




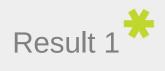
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• At **each time step**: convergence of the quantum channel towards its fixed point





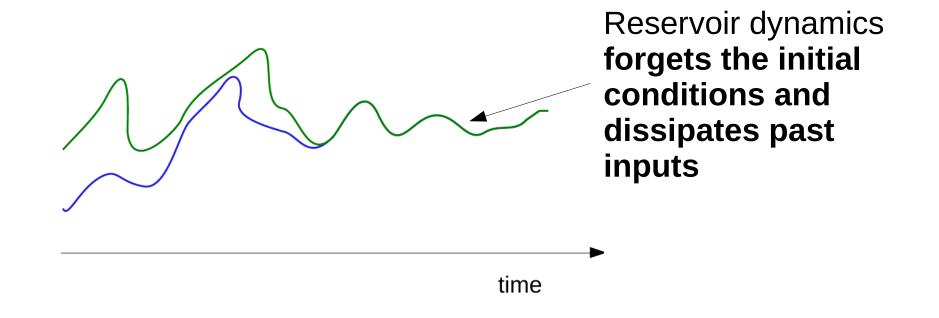
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- Over time steps: fading memory property





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- Over time steps: fading memory property

• Fading Memory Property (FMP): **memory** of past inputs.







<u>Result 1: merging the two scales of convergence.</u> A quantum reservoir has the fading memory property if and only if the dynamics of channel is contracted in some norm at each time step.

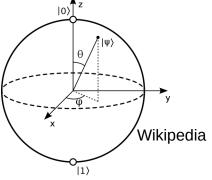




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Example of one qubit:

$$\rho \Rightarrow \mathbf{x} = (1, \langle \sigma^x \rangle, \langle \sigma^y \rangle, \langle \sigma^z \rangle)$$
$$\{B_i\} = \{I, \sigma^x, \sigma^y, \sigma^z\}$$



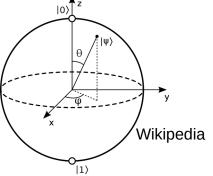




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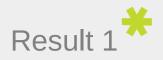
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Quantum channel in observables form: $x_{k,j} = (\widehat{T}(\mathbf{z}_k)|_{\mathcal{H}_0})_{i,j}x_{k-1,j} + \widehat{T}(\mathbf{z}_k)_{0j} \quad \mathcal{H}_0 = \{\sigma^x, \sigma^y, \sigma^z\}$ $\widehat{T}(\mathbf{z}_k)_{ij} = \frac{1}{2} \operatorname{tr}(B_i T(B_j, \mathbf{z}_k))$

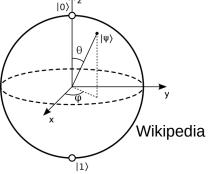




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$$\|\widehat{A}\|\| := \sup_{\|\mathbf{x}\|\neq 0} \frac{\|\widehat{A}\mathbf{x}\|}{\|\mathbf{x}\|} \text{ Induced norm } \|\widehat{T}(\mathbf{z}_k)|_{\mathcal{H}_0}\| < 1$$

D. J. Hartfiel, *Nonhomogeneous matrix products,* 2002

There is an equivalent condition in density matrix form





• <u>Result 2:</u> a quantum reservoir becomes input-dependent (useful in the long-term) if and only if the quantum channel have a unique input-dependent fixed point.

Quantum channel
$$T(\rho^*(\mathbf{z}_k), \mathbf{z}_k) = \rho^*(\mathbf{z}_k)$$
 input fixed point





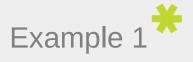
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Quantum channel
in matrix form:
$$T(\rho^*(\mathbf{z}_k), \mathbf{z}_k) = \rho^*(\mathbf{z}_k)$$
 fixed point

• Intuition: convergence makes the system approach an attractor. To drive a system over time steps you need attractors that depends on the input.



 \sim



Is example 1 a useful quantum reservoir?

Example 1:
$$\dot{\rho} = -i[H,\rho] + \gamma L\rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L,\rho\}$$

$$H = \frac{h(\mathbf{z}_k)}{2} \sigma^z \qquad L = \sigma^-$$





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Does this system fading memory property?





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Bloch vector representation:

Does this system fading

memory property?

$$\begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k}\\ \langle \sigma^{y} \rangle_{k}\\ \langle \sigma^{z} \rangle_{k} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0\\ 0 & e^{-\frac{\gamma \Delta t}{2}} \cos(h_{k} \Delta t) & e^{-\frac{\gamma \Delta t}{2}} \sin(h_{k} \Delta t) & 0\\ 0 & -e^{-\frac{\gamma \Delta t}{2}} \sin(h_{k} \Delta t) & e^{-\frac{\gamma \Delta t}{2}} \cos(h_{k} \Delta t) & 0\\ e^{-\gamma \Delta t} - 1 & 0 & 0 & e^{-\gamma \Delta t} \end{pmatrix} \begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k-1}\\ \langle \sigma^{z} \rangle_{k-1} \\ \langle \sigma^{z} \rangle_{k-1} \end{pmatrix}$$

$$x_{k,j} = (\widehat{T}(\mathbf{z}_k)|_{\mathcal{H}_0})_{i,j} x_{k-1,j} + \widehat{T}(\mathbf{z}_k)_{0j}$$





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Induced Frobenius norm: maximum singular value

$$|||\widehat{T}|_{\mathcal{H}_0}|||_F = s_{\max}(\widehat{T}|_{\mathcal{H}_0})$$





$$\begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k}\\ \langle \sigma^{y} \rangle_{k}\\ \langle \sigma^{z} \rangle_{k} \end{pmatrix} = \begin{pmatrix} 1\\ 0\\ 0\\ e^{-\gamma \Delta t} - 1 \end{pmatrix} \begin{pmatrix} e^{-\frac{\gamma \Delta t}{2}} \cos(h_{k} \Delta t) & e^{-\frac{\gamma \Delta t}{2}} \sin(h_{k} \Delta t) & 0\\ -e^{-\frac{\gamma \Delta t}{2}} \sin(h_{k} \Delta t) & e^{-\frac{\gamma \Delta t}{2}} \cos(h_{k} \Delta t) & 0\\ 0 & 0 & e^{-\gamma \Delta t} \end{pmatrix} \begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k-1}\\ \langle \sigma^{y} \rangle_{k-1}\\ \langle \sigma^{z} \rangle_{k-1} \end{pmatrix}$$

$$\boxed{T|_{\mathcal{H}_{0}}} \qquad \boxed{T|_{\mathcal{H}_{0}}} \qquad \boxed{T|_{\mathcal{H}_{0}}||| < 1}$$

Induced Frobenius norm: maximum singular value

$$\||\widehat{T}|_{\mathcal{H}_0}\||_F = s_{\max}(\widehat{T}|_{\mathcal{H}_0})$$

$$s_1 = e^{-\gamma \Delta t} < 1$$

 $s_2 = s_3 = e^{-\gamma \Delta t/2} < 1$





$$\begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k}\\ \langle \sigma^{y} \rangle_{k}\\ \langle \sigma^{z} \rangle_{k} \end{pmatrix} = \begin{pmatrix} 1\\ 0\\ 0\\ e^{-\gamma \Delta t} - 1 \end{pmatrix} \begin{pmatrix} e^{-\frac{\gamma \Delta t}{2}} \cos(h_{k} \Delta t) & e^{-\frac{\gamma \Delta t}{2}} \sin(h_{k} \Delta t) & 0\\ -e^{-\frac{\gamma \Delta t}{2}} \sin(h_{k} \Delta t) & e^{-\frac{\gamma \Delta t}{2}} \cos(h_{k} \Delta t) & 0\\ 0 & 0 & e^{-\gamma \Delta t} \end{pmatrix} \begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k-1}\\ \langle \sigma^{y} \rangle_{k-1}\\ \langle \sigma^{z} \rangle_{k-1} \end{pmatrix}$$

$$\boxed{T|_{\mathcal{H}_{0}}} \qquad \boxed{T|_{\mathcal{H}_{0}}|_{\mathcal{H}_{0}}||| < 1$$

Induced Frobenius norm: maximum singular value

$$\||\widehat{T}|_{\mathcal{H}_0}\||_F = s_{\max}(\widehat{T}|_{\mathcal{H}_0})$$

$$s_1 = e^{-\gamma \Delta t} < 1$$

 $s_2 = s_3 = e^{-\gamma \Delta t/2} < 1$

This system has fading memory







$$\||\widehat{T}|_{\mathcal{H}_0}\||_F = s_{\max}(\widehat{T}|_{\mathcal{H}_0})$$

$$s_1 = e^{-\gamma \Delta t} < 1$$

 $s_2 = s_3 = e^{-\gamma \Delta t/2} < 1$

This system has fading memory But...





$$\dot{\rho} = -i[H,\rho] + \gamma L \rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L,\rho\}$$
$$H = \frac{h(\mathbf{z}_k)}{2} \sigma^z \qquad L = \sigma^-$$

Input-independent fixed point: (0, 0)

$$\rho^* = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$





point:

Input-independent fixed

 $\dot{\rho} = -i[H,\rho] + \gamma L\rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L,\rho\}$ $H = \frac{h(\mathbf{z}_k)}{2}\sigma^z \qquad L = \sigma^ \rho^* = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

0.0 --0.2This is supposed to be -0.4 $\langle \sigma^{Z} \rangle$ a driven system! -0.6-0.8 -1.05 10 15 20 0 Jst

Result 2 says that this system is useless for long-input sequences (or not that long...)

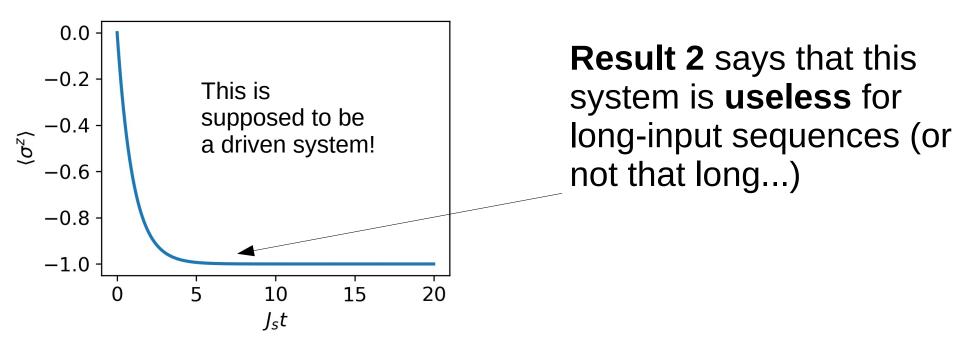




point:

Input-independent fixed

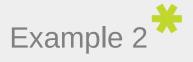
 $\dot{\rho} = -i[H,\rho] + \gamma L\rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L,\rho\}$ $H = \frac{h(\mathbf{z}_k)}{\gamma} \sigma^z \qquad L = \sigma^ \rho^* = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$



<u>Conclusion</u>: fading memory is important, but the design is very important as well!



 \sim



Is example 2 a useful quantum reservoir?

Example 2:
$$\dot{\rho} = -i[H,\rho] + \gamma L\rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L,\rho\}$$

$$H = \frac{h(\mathbf{z}_k)}{2} \sigma^x \qquad L = \sigma^{-1}$$





$$\dot{\rho} = -i[H,\rho] + \gamma$$

Does this system have fading memory property?

$$= -i[H, \rho] + \gamma L \rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L, \rho\}$$
$$H = \frac{h(\mathbf{z}_k)}{2} \sigma^x \qquad L = \sigma^{-1}$$





$$\dot{\rho} = -i[H,\rho] + \gamma L\rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L,\rho\}$$

$$hg \quad H = \frac{h(\mathbf{z}_k)}{2} \sigma^x \qquad L = \sigma^-$$

Does this system have fading memory property?





Solution 2: $\dot{\rho} = -i[H,\rho] + \gamma L\rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L,\rho\}$ Does this system have fading $H = \frac{h(\mathbf{z}_k)}{2} \sigma^x$ $L = \sigma^-$

memory property?

$$\begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k}\\ \langle \sigma^{y} \rangle_{k}\\ \langle \sigma^{z} \rangle_{k} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0\\ 0 & \widehat{T}_{22} & 0 & 0\\ \widehat{T}_{31} & 0 & \widehat{T}_{33} & \widehat{T}_{34}\\ \widehat{T}_{41} & 0 & \widehat{T}_{43} & \widehat{T}_{44} \end{pmatrix} \begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k-1}\\ \langle \sigma^{y} \rangle_{k-1}\\ \langle \sigma^{z} \rangle_{k-1} \end{pmatrix}$$

$$x_{k,j} = (\widehat{T}(\mathbf{z}_k)|_{\mathcal{H}_0})_{i,j} x_{k-1,j} + \widehat{T}(\mathbf{z}_k)_{0j}$$



 $x_{k,j}$



$$\dot{\rho} = -i[H,\rho] + \gamma L\rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L,\rho\}$$

ing
$$H = \frac{h(\mathbf{z}_k)}{2} \sigma^x \qquad L = \sigma^-$$

Does this system have fading memory property?





$$\begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k}\\ \langle \sigma^{y} \rangle_{k}\\ \langle \sigma^{y} \rangle_{k} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0\\ 0 & \widehat{T}_{22} & 0 & 0\\ \widehat{T}_{31} & 0 & \widehat{T}_{33} & \widehat{T}_{34}\\ \widehat{T}_{41} & 0 & \widehat{T}_{43} & \widehat{T}_{44} \end{pmatrix} \begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k-1}\\ \langle \sigma^{y} \rangle_{k-1} \\ \langle \sigma^{y} \rangle_{k-1} \end{pmatrix}$$

$$\widehat{T}_{22} = e^{-\frac{\gamma \wedge t}{2}}$$

$$\widehat{T}_{33} = e^{-\frac{3\gamma \wedge t}{4}} \left(\cosh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right) + \frac{\gamma}{\sqrt{\gamma^{2} - 16h_{k}^{2}}} \sinh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right) \right)$$

$$\widehat{T}_{44} = e^{-\frac{3\gamma \wedge t}{4}} \left(\cosh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right) - \frac{\gamma}{\sqrt{\gamma^{2} - 16h_{k}^{2}}} \sinh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right) \right)$$

$$\widehat{T}_{34} = \frac{4h_{k}e^{-\frac{3\gamma \wedge t}{4}}}{\sqrt{\gamma^{2} - 16h_{k}^{2}}} \sinh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right) + \frac{3\gamma}{\sqrt{\gamma^{2} - 16h_{k}^{2}}} \sinh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right)$$

$$\widehat{T}_{31} = \frac{2\gamma h_{k}}{\gamma^{2} + 2h_{k}^{2}} \left\{ -1 + e^{-\frac{3\gamma \wedge t}{4}} \left(\cosh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right) + \frac{3\gamma}{\sqrt{\gamma^{2} - 16h_{k}^{2}}} \sinh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right) \right) \right\}$$

$$\widehat{T}_{41} = \frac{\gamma}{\gamma^{2} + 2h_{k}^{2}} \left\{ -\gamma + e^{-\frac{3\gamma \wedge t}{4}} \left(\gamma \cosh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right) - \frac{\gamma^{2} + 8h_{k}^{2}}{\sqrt{\gamma^{2} - 16h_{k}^{2}}} \sinh\left(\frac{\Delta t}{4}\sqrt{\gamma^{2} - 16h_{k}^{2}}\right) \right) \right\}$$









$$\begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k}\\ \langle \sigma^{y} \rangle_{k}\\ \langle \sigma^{z} \rangle_{k} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0\\ 0 & \widehat{T}_{22} & 0 & 0\\ \widehat{T}_{31} & \widehat{T}_{33} & \widehat{T}_{34}\\ 0 & \widehat{T}_{43} & \widehat{T}_{44} \end{pmatrix} \begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k-1}\\ \langle \sigma^{y} \rangle_{k-1}\\ \langle \sigma^{z} \rangle_{k-1} \end{pmatrix}$$

obtained
$$\widehat{T}_{41} & 0 & \widehat{T}_{43} & \widehat{T}_{44} \end{pmatrix} \begin{bmatrix} 1\\ \langle \sigma^{y} \rangle_{k-1}\\ \langle \sigma^{z} \rangle_{k-1} \end{pmatrix}$$

subservative
$$\widehat{T}_{\mathcal{H}_{0}} & \|\widehat{T}(\mathbf{z}_{k})\|_{\mathcal{H}_{0}}\|\| < 1$$

Induced Fro maximum s

$$|||\widehat{T}|_{\mathcal{H}_0}|||_F = s_{\max}(\widehat{T}|_{\mathcal{H}_0})$$





$$\begin{pmatrix} 1 \\ \langle \sigma^{x} \rangle_{k} \\ \langle \sigma^{y} \rangle_{k} \\ \langle \sigma^{z} \rangle_{k} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \widehat{T}_{22} & 0 & 0 \\ \widehat{T}_{31} & 0 & \widehat{T}_{33} & \widehat{T}_{34} \\ \widehat{T}_{41} & 0 & \widehat{T}_{43} & \widehat{T}_{44} \end{pmatrix} \begin{pmatrix} 1 \\ \langle \sigma^{x} \rangle_{k-1} \\ \langle \sigma^{y} \rangle_{k-1} \\ \langle \sigma^{z} \rangle_{k-1} \end{pmatrix}$$
benius norm:
$$\widehat{T}|_{\mathcal{H}_{0}} \qquad ||\widehat{T}(\mathbf{z}_{k})|_{\mathcal{H}_{0}}||| < 1$$

Induced From maximum si

$$\||\widehat{T}|_{\mathcal{H}_0}\||_F = s_{\max}(\widehat{T}|_{\mathcal{H}_0})$$

$$s_1 = e^{-\gamma \Delta t/2} < 1$$









$$\begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k}\\ \langle \sigma^{y} \rangle_{k}\\ \langle \sigma^{z} \rangle_{k} \end{pmatrix} = \begin{pmatrix} 1\\ 0\\ \widehat{T}_{22} & 0 & 0\\ 0 & \widehat{T}_{33} & \widehat{T}_{34}\\ 0 & \widehat{T}_{43} & \widehat{T}_{44} \end{pmatrix} \begin{pmatrix} 1\\ \langle \sigma^{x} \rangle_{k-1}\\ \langle \sigma^{z} \rangle_{k-1} \end{pmatrix}$$
Induced Frobenius norm:
maximum singular value
$$\||\widehat{T}|_{\mathcal{H}_{0}}|||_{F} = s_{\max}(\widehat{T}|_{\mathcal{H}_{0}})$$

$$\||\widehat{T}(\mathbf{z}_{k})|_{\mathcal{H}_{0}}||| < 1$$

$$\||\widehat{T}|_{\mathcal{H}_{0}}|||_{F} = s_{\max}(\widehat{T}|_{\mathcal{H}_{0}})$$

$$s_{1} = e^{-\gamma \Delta t/2} < 1$$
This system
has fading
memory!!





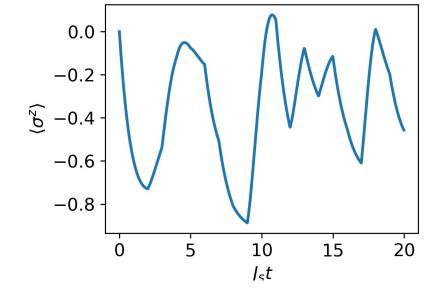
$$\rho^* = \frac{1}{\gamma^2 + 2h_k^2} \begin{pmatrix} h_k^2 & i\gamma h_k \\ -i\gamma h_k & \gamma^2 + h_k^2 \end{pmatrix}$$





Input-dependent fixed point:

$$\rho^* = \frac{1}{\gamma^2 + 2h_k^2} \begin{pmatrix} h_k^2 & i\gamma h_k \\ -i\gamma h_k & \gamma^2 + h_k^2 \end{pmatrix}$$



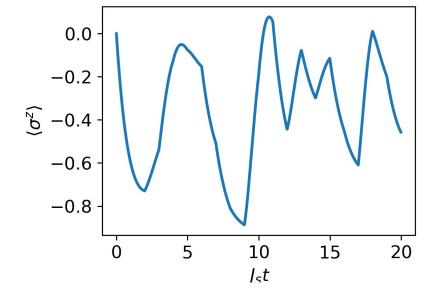
Result 2 states that this system will be always **input-dependent**!





Input-dependent fixed point:

$$\rho^* = \frac{1}{\gamma^2 + 2h_k^2} \begin{pmatrix} h_k^2 & i\gamma h_k \\ -i\gamma h_k & \gamma^2 + h_k^2 \end{pmatrix}$$



$$= -i[H, \rho] + \gamma L \rho L^{\dagger} - \frac{\gamma}{2} \{L^{\dagger}L, \rho\}$$
$$H = \frac{h(\mathbf{z}_k)}{2} \sigma^x \qquad L = \sigma^{-1}$$

Result 2 states that this system will be always **input-dependent**!

<u>Conclusion:</u> we don't know how good the reservoir is for specific tasks, but it works!

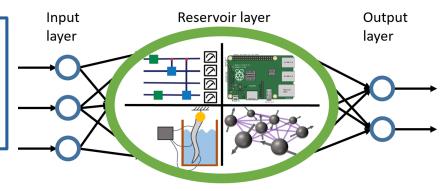








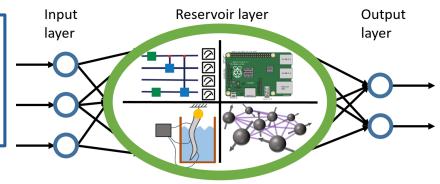
(Quantum) Reservoir Computing might be a good **alternative** to **conventional computers** to process **temporal** data



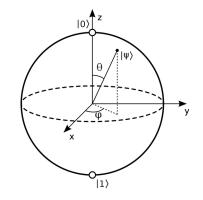




(Quantum) Reservoir Computing might be a good **alternative** to **conventional computers** to process **temporal** data



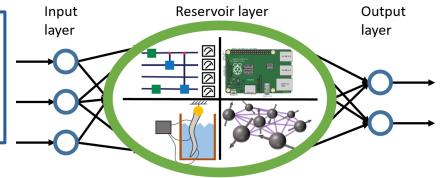
Different representations of quantum systems can provide a **better insight** of **reservoir computing properties**



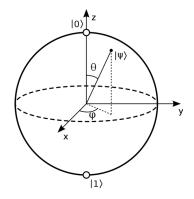




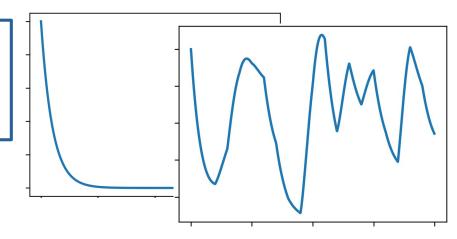
(Quantum) Reservoir Computing might be a good **alternative** to **conventional computers** to process **temporal** data



Different representations of quantum systems can provide a **better insight** of **reservoir computing properties**



A quantum reservoir is **useful if and only if** the dynamics **converges** towards **input-dependent** fixed points







Studying infinite dimensional systems

Extending the theory to nonideal situations: finite number of measurements, POVMs...

Finding the most general conditions for universal approximation property





R. Martínez-Peña, J. P. Ortega, Quantum reservoir computing in finite dimensions. Physical Review E 107 (3), 035306

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THANK YOU

for your attention

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