

# How Uncertain Am I?

Theoretical errors in Bayesian model calibration for EFTs

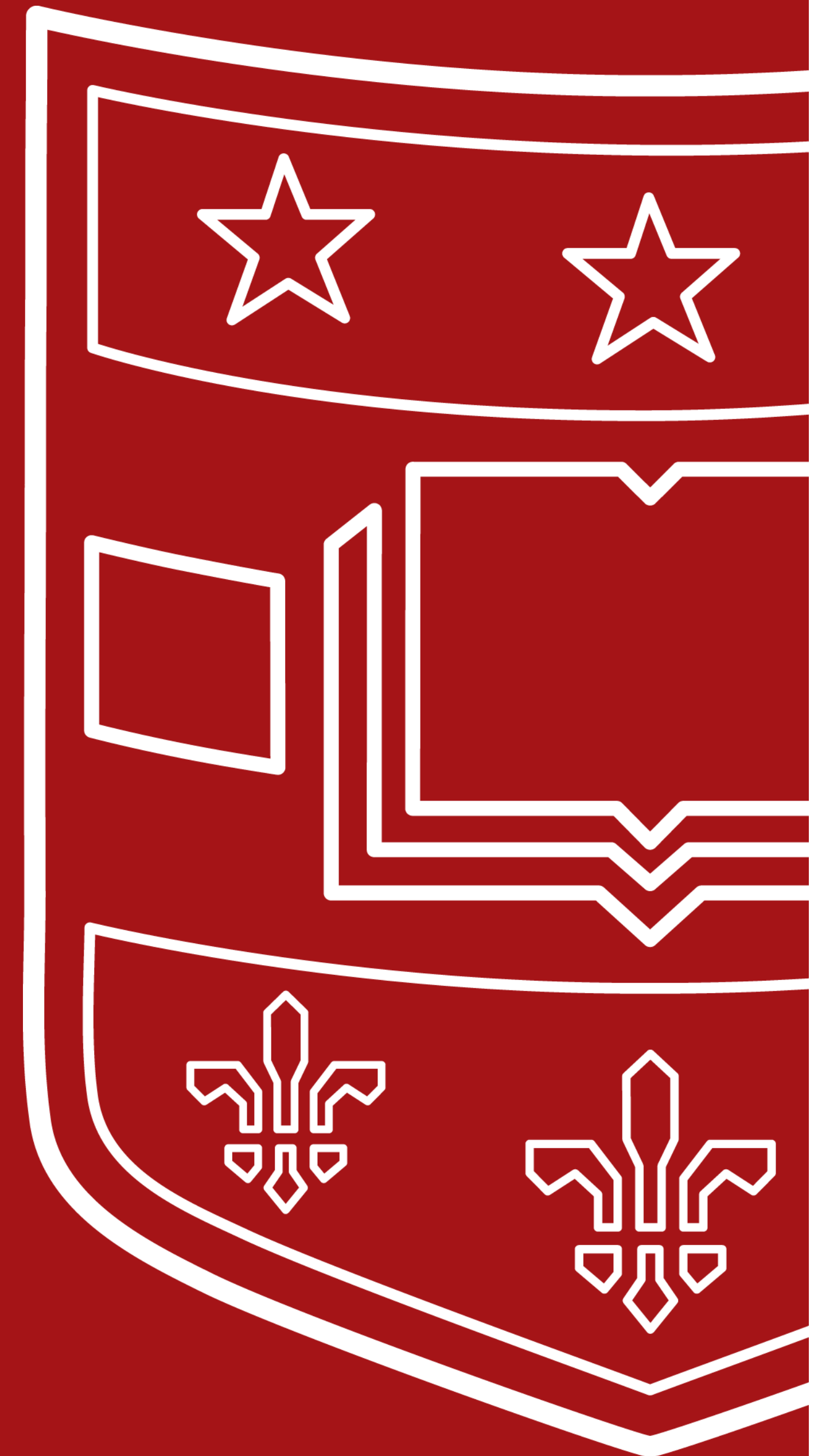
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Dick Furnstahl, and Saori Pastore

ISNET-9 @ WashU

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 Washington University in St. Louis





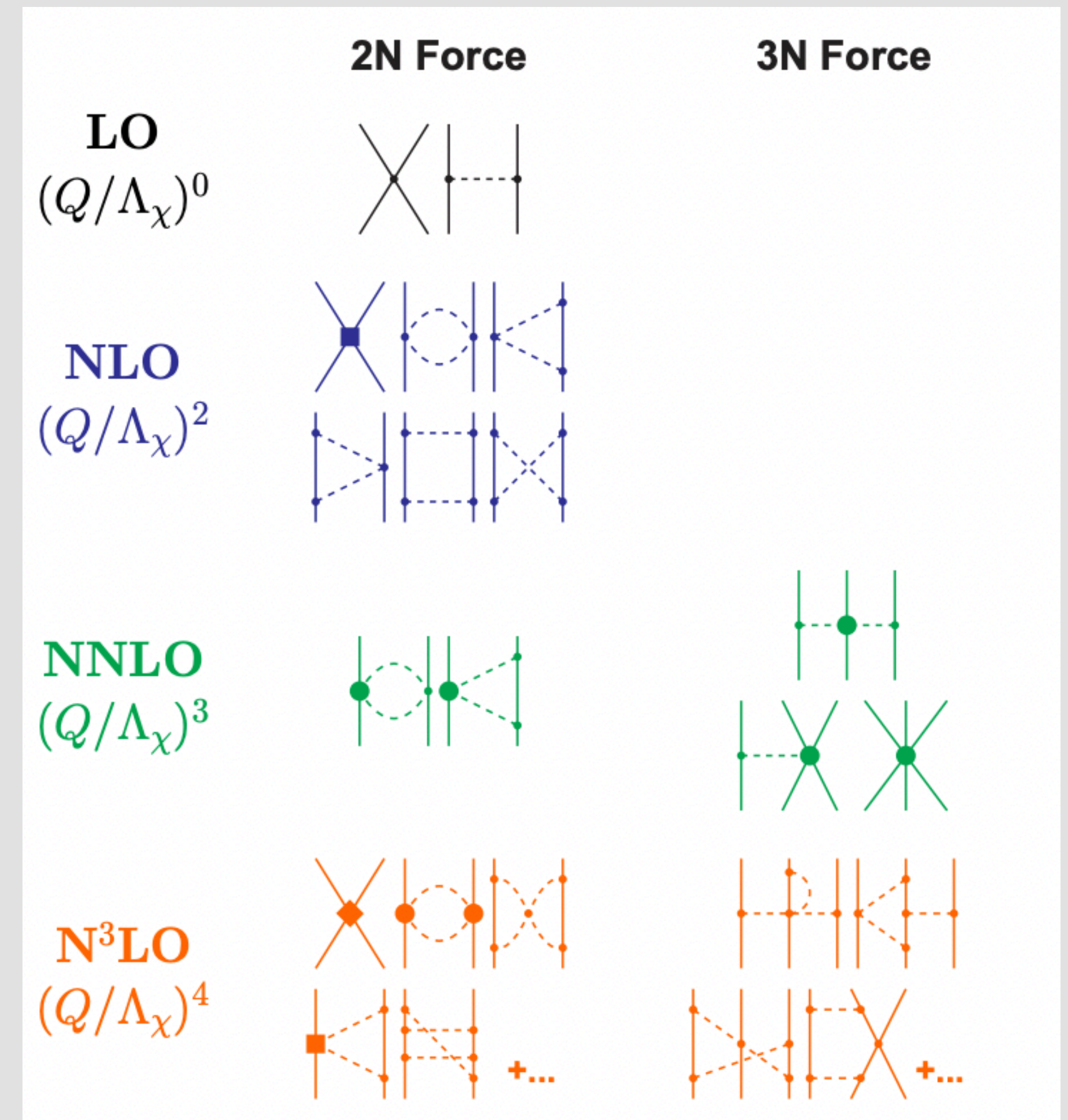
# Effective Field Theory

We take an effective expansion of QCD preserving chiral symmetry.

The interaction can be ordered in terms of powers of  $Q/\Lambda_\chi$

- $Q$  is a momentum or pion mass
- $\Lambda_\chi$  is the symmetry breaking scale

Gives a systematic ordering to improve the interaction.





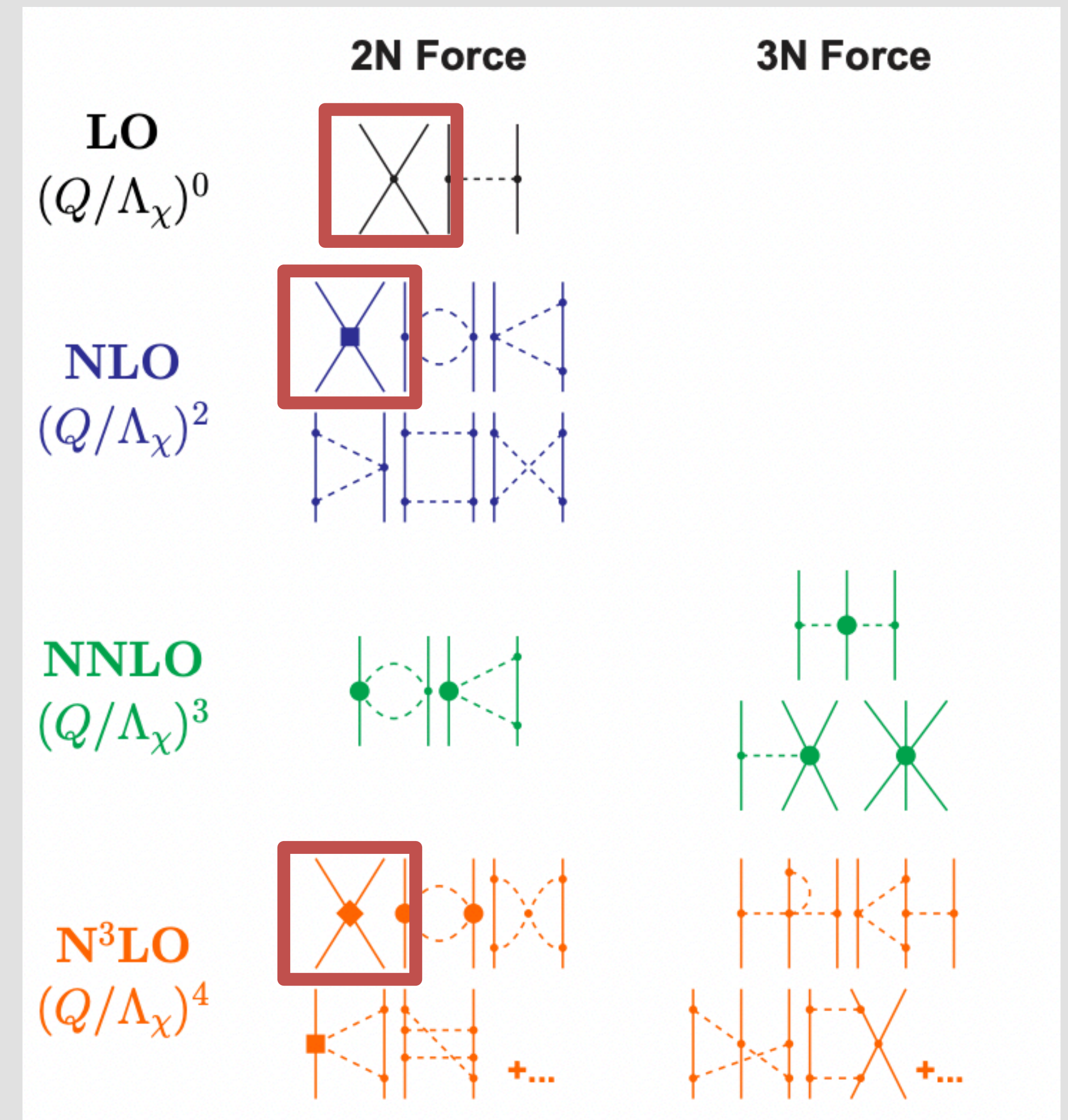
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# Pionless EFT



We are working in an EFT framework without pions

Our interaction takes the form:

$$v^{(LO)}(k) = C_S + C_T \sigma_1 \cdot \sigma_2$$

$$v^{(NLO)}(k) = C_1 k^2 + C_2 k^2 \sigma_1 \cdot \sigma_2 + C_3 S_{12}(k) + C_4 k^2 \tau_1 \cdot \tau_2 \\ + iC_5 S \cdot (K \times k) + C_6 k^2 \tau_1 \cdot \tau_2 \sigma_1 \cdot \sigma_2 + C_7 S_{12}(k) \tau_2 \cdot \tau_2$$

# Pionless EFT



We are working in an EFT framework without pions

Our interaction takes the form: **Undetermined Low Energy Constants (LECs)**

$$v^{(LO)}(k) = \boxed{C_S} + \boxed{C_T} \sigma_1 \cdot \sigma_2$$

$$v^{(NLO)}(k) = \boxed{C_1} k^2 + \boxed{C_2} k^2 \sigma_1 \cdot \sigma_2 + \boxed{C_3} S_{12}(k) + \boxed{C_4} k^2 \tau_1 \cdot \tau_2 \\ + \boxed{C_5} S \cdot (K \times k) + \boxed{C_6} k^2 \tau_1 \cdot \tau_2 \sigma_1 \cdot \sigma_2 + \boxed{C_7} S_{12}(k) \tau_2 \cdot \tau_2$$

# Regularization



To use these interactions, they must be regularized in some fashion and must be local in coordinate space (for QMC).

We employ a Gaussian cutoff in coordinate space, which smears  $\delta$ -functions upon Fourier transformation.

$$f(r) = \frac{1}{\pi^{3/2} R_0^3} e^{-\left(\frac{r}{R_0}\right)^2}$$

For this work, we choose  $R_0 = 2.0$  fm corresponding to a momentum space cutoff of 200 MeV.



# Model Calibration

To calibrate our EFT model, we use a Bayesian framework

$$\underbrace{\rho(\mathbf{a} | \mathbf{y}, I)}_{\text{posterior}} \propto \underbrace{\rho(\mathbf{y} | \mathbf{a}, I)}_{\text{likelihood}} \underbrace{\rho(\mathbf{a} | I)}_{\text{prior}}$$
$$\rho(\mathbf{y} | \mathbf{x}, \sigma, \mathbf{a}) = \prod_i \left( \frac{1}{\sqrt{2\pi\sigma_i}} \right) e^{-\frac{\chi^2}{2}}$$

The **posterior** gives the distribution for a certain set of parameters,  $\mathbf{a}$  (LECs), given data,  $\mathbf{y}$  (scattering data), and any other information,  $I$ , which we maximize.

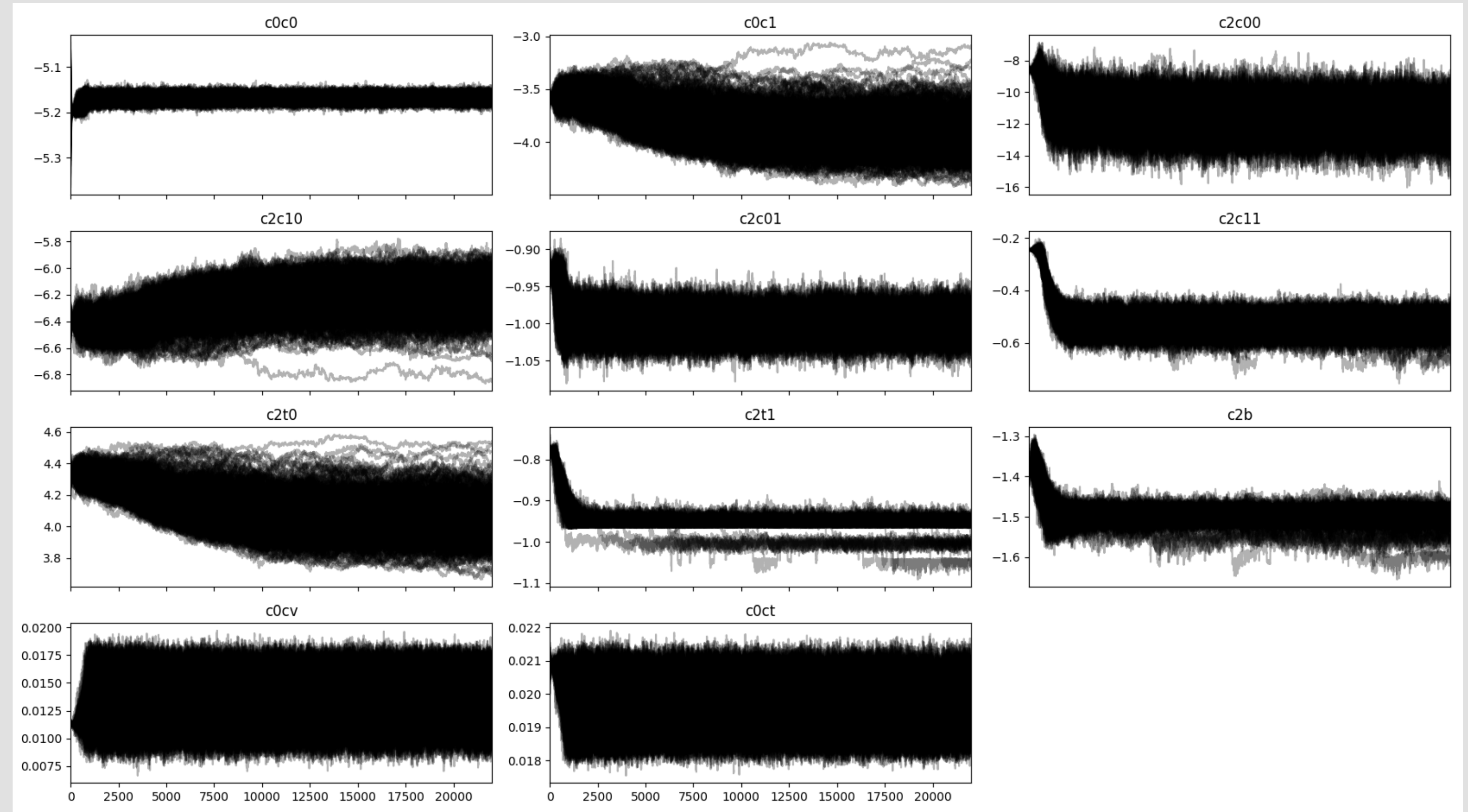
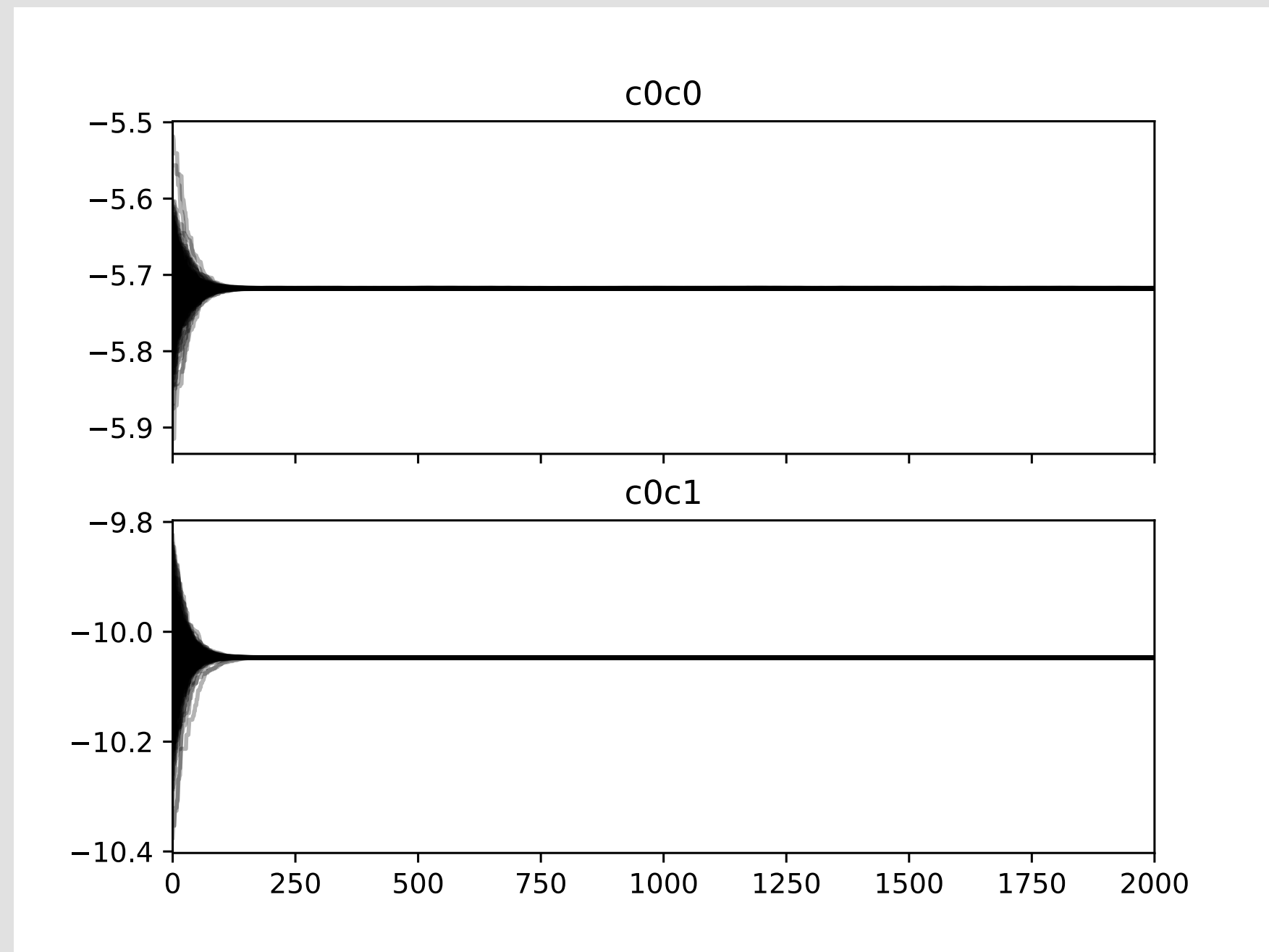
The **likelihood** gives the probability of scattering data for a given parameter set

- Find **region** of minimum  $\chi^2$

The **prior** encodes any external information we know about the parameters.

- Initial point/naturalness  $\rightarrow$  ours is relatively uninformative

# Proof of Concept Calibration

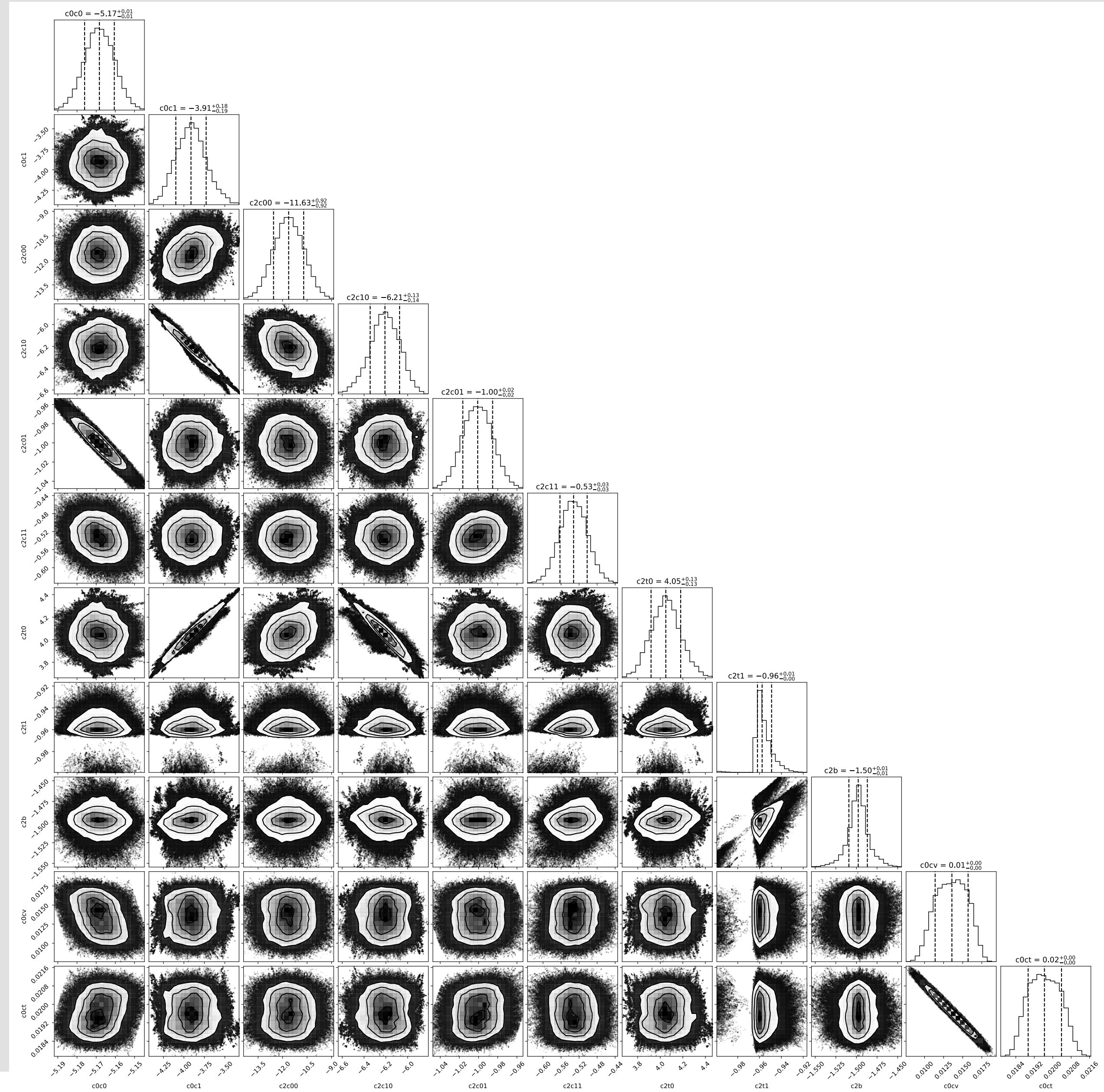
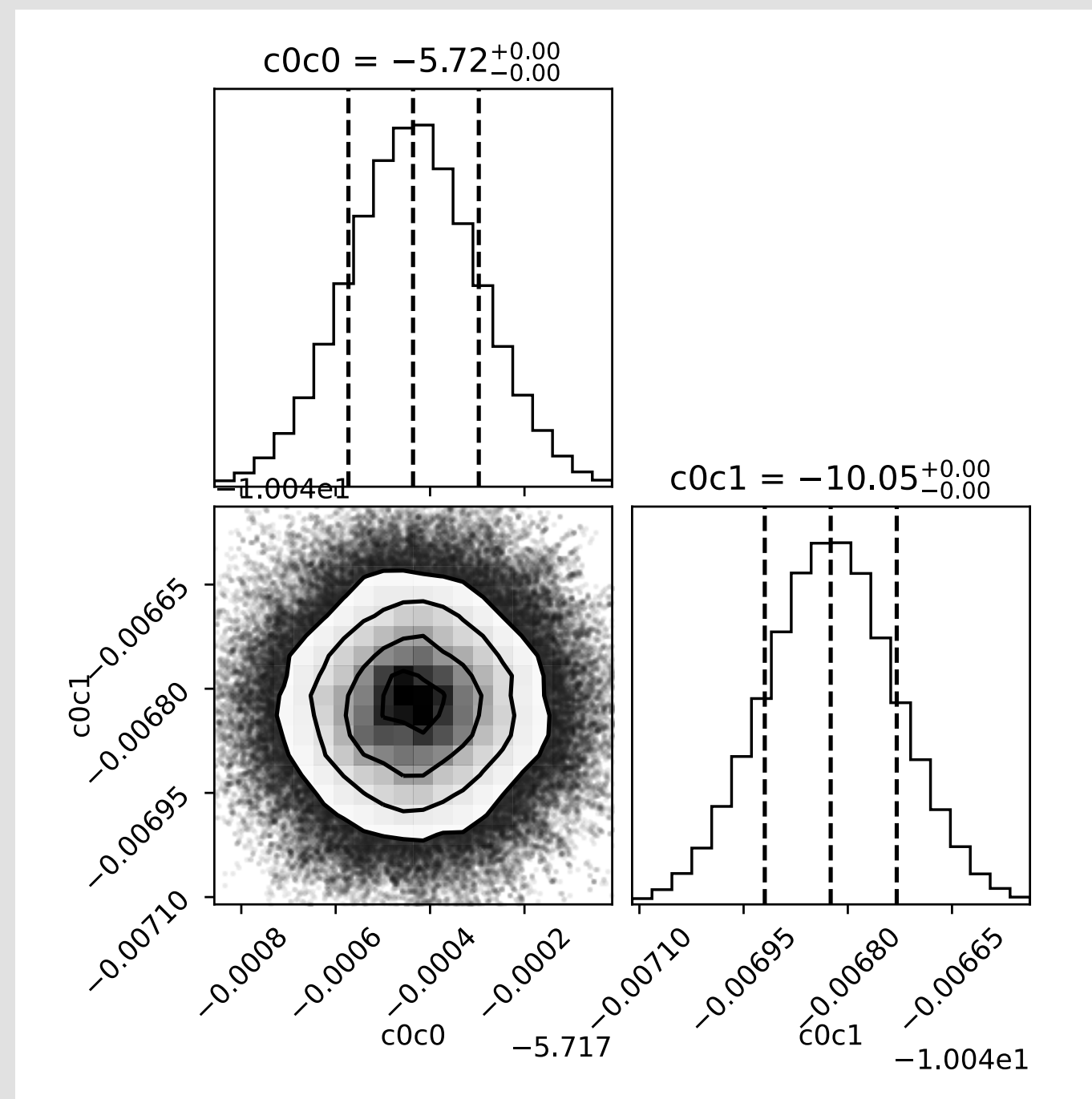


LO: 0.5 MeV,  $n_{data}=57$  (np,  $E_d$ )

NLO: 15 MeV,  $n_{data}=773$  (np, pp,  $E_d$ , np scatt. length)



# 2 fm Cutoff Fits



# Full Bayesian model calibration



In our model calibration, we can include theory errors  
(Wesolowski et. al. Phys. Rev. C **104**, 064001)

$$\chi^2 = \sum_i \frac{(y_i - t_i)^2}{\sigma_{\text{exp},i}^2} \rightarrow \chi^2 = \sum_i \frac{(y_i - t_i)^2}{\sigma_{\text{exp},i}^2 + \sigma_{\text{ther},i}^2}$$

Where

$$\sigma_{\text{ther},i}^2 = \frac{(y_{\text{ref},i} \bar{c} Q_i^{n+1})^2}{1 - Q_i^2}, \quad Q_i = \frac{\max[p_{\text{soft}}, p_i]}{\Lambda_b \sim m_\pi}$$

and  $y_{\text{ref},i}$  sets the scale of the correction for observable  $y_i$ ,  
and  $\bar{c}$  sets the magnitude of the correction.



Dick Furnstahl



Daniel Phillips



# Correlated theory errors

We can correlate our theory errors as well:

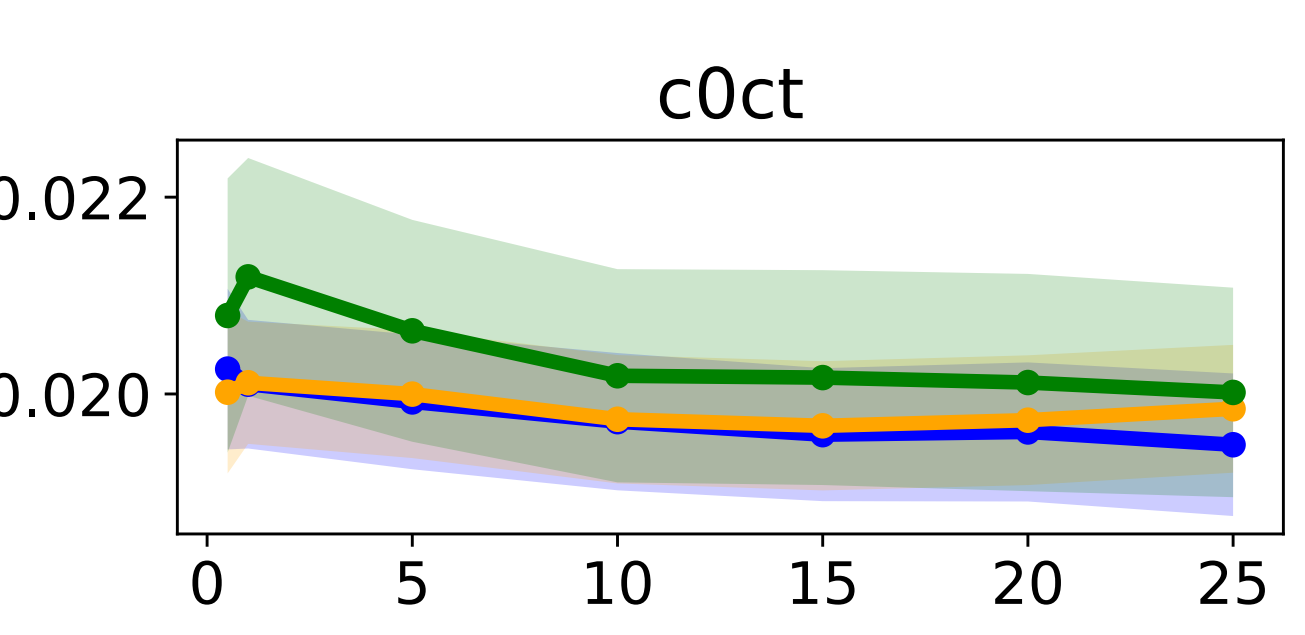
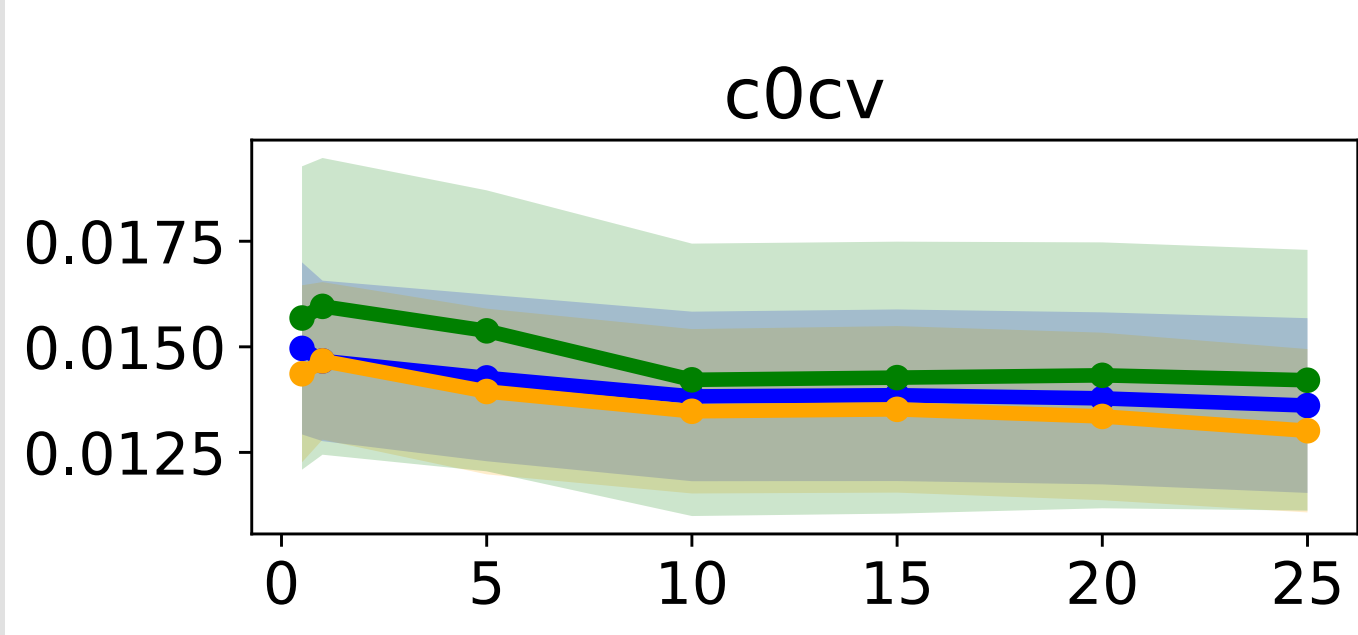
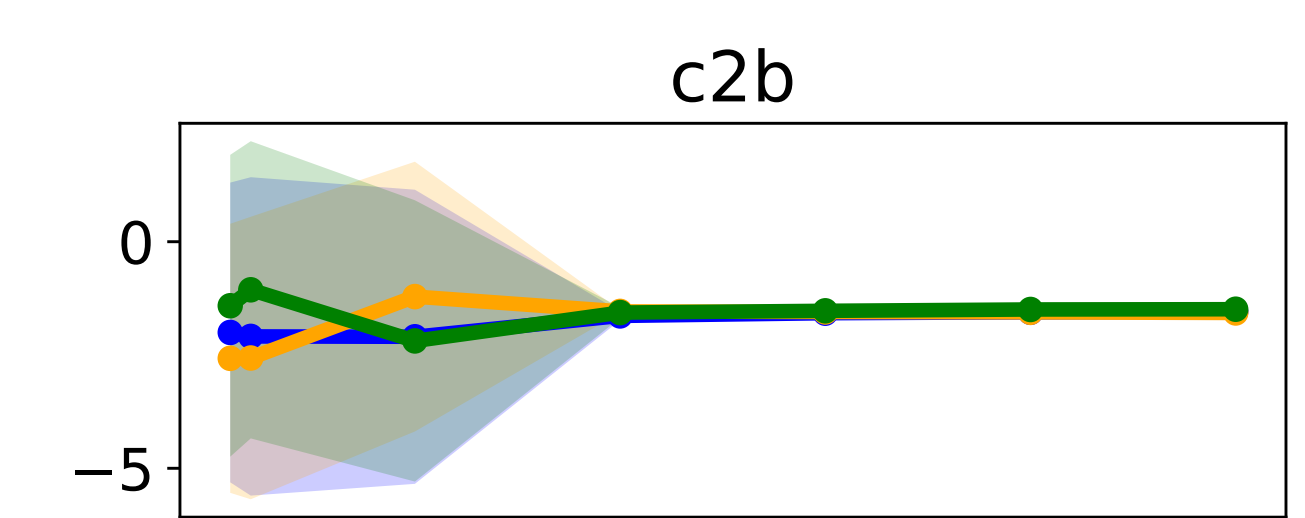
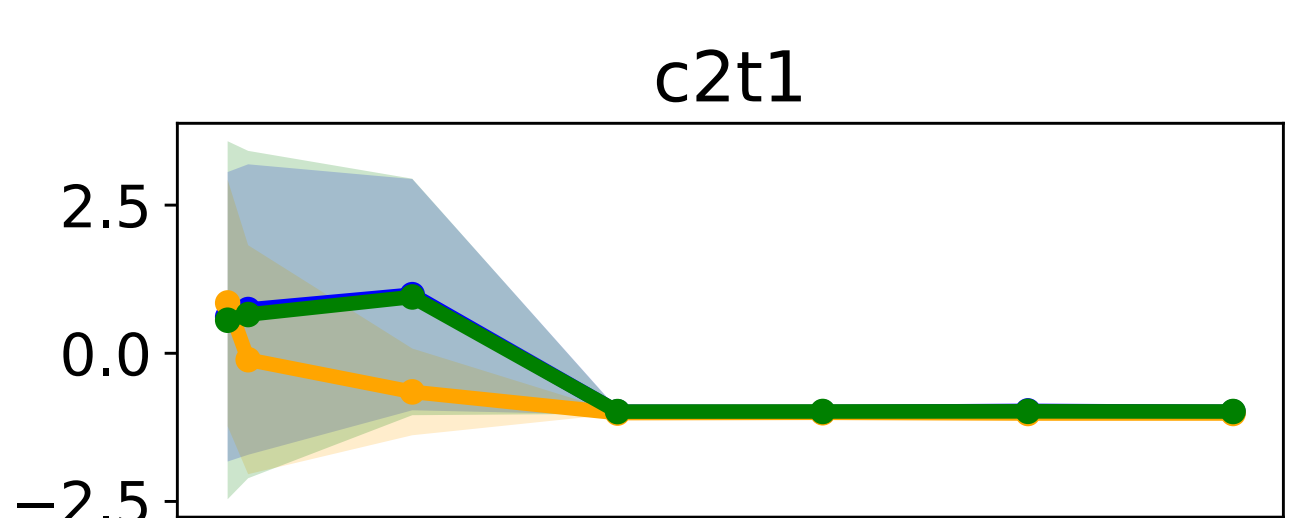
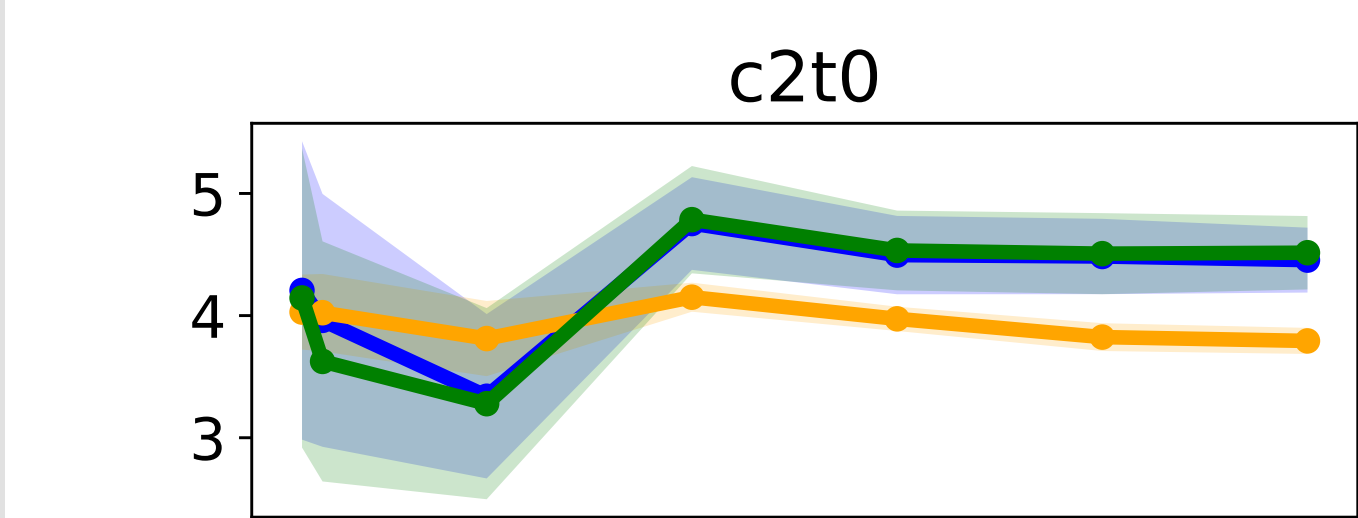
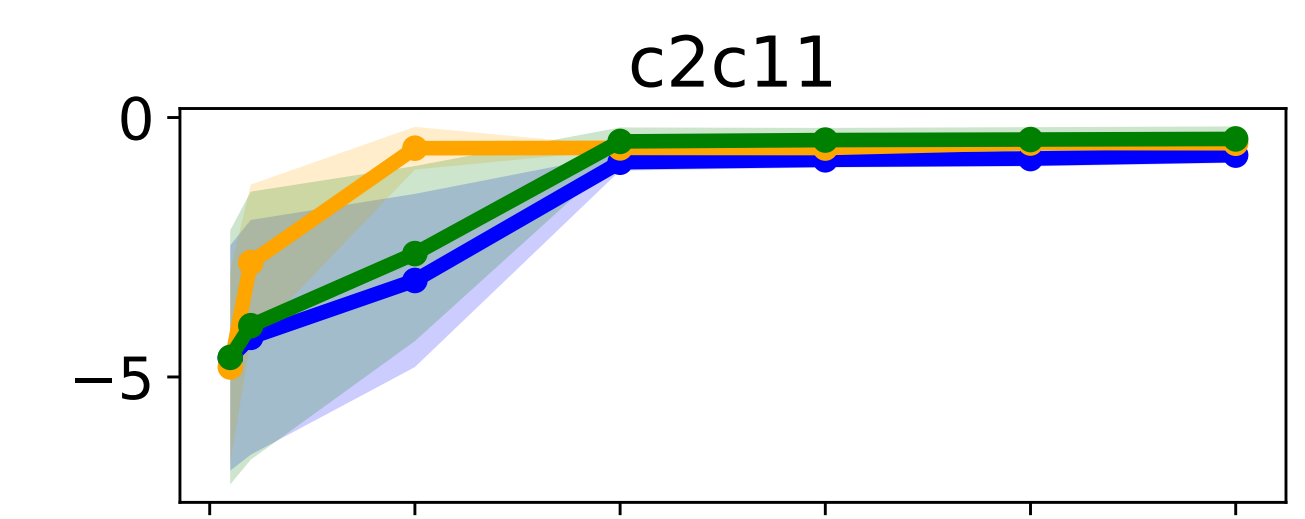
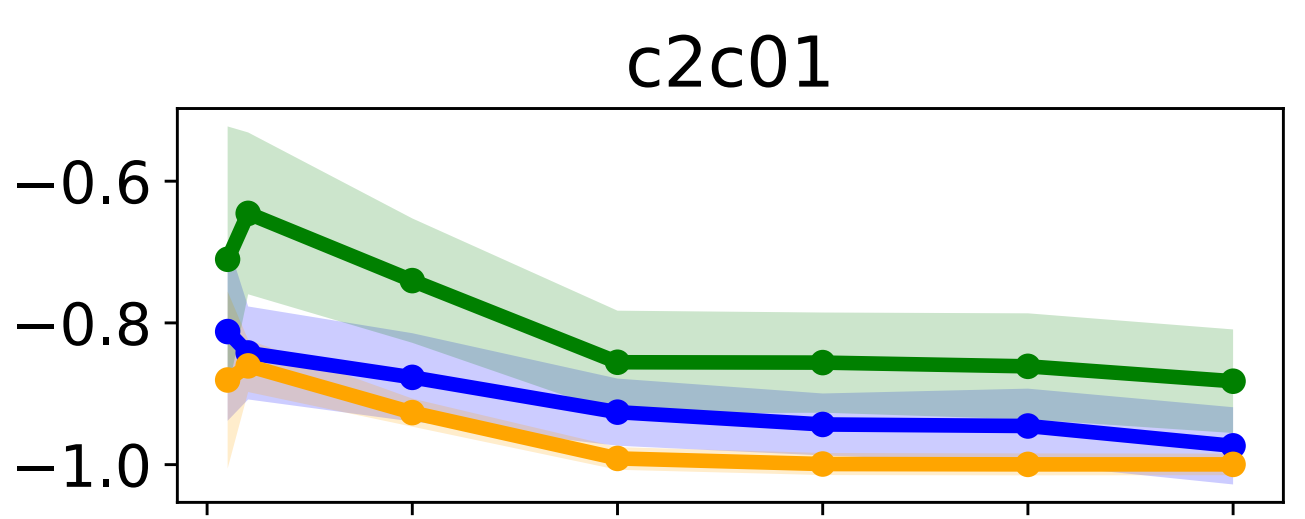
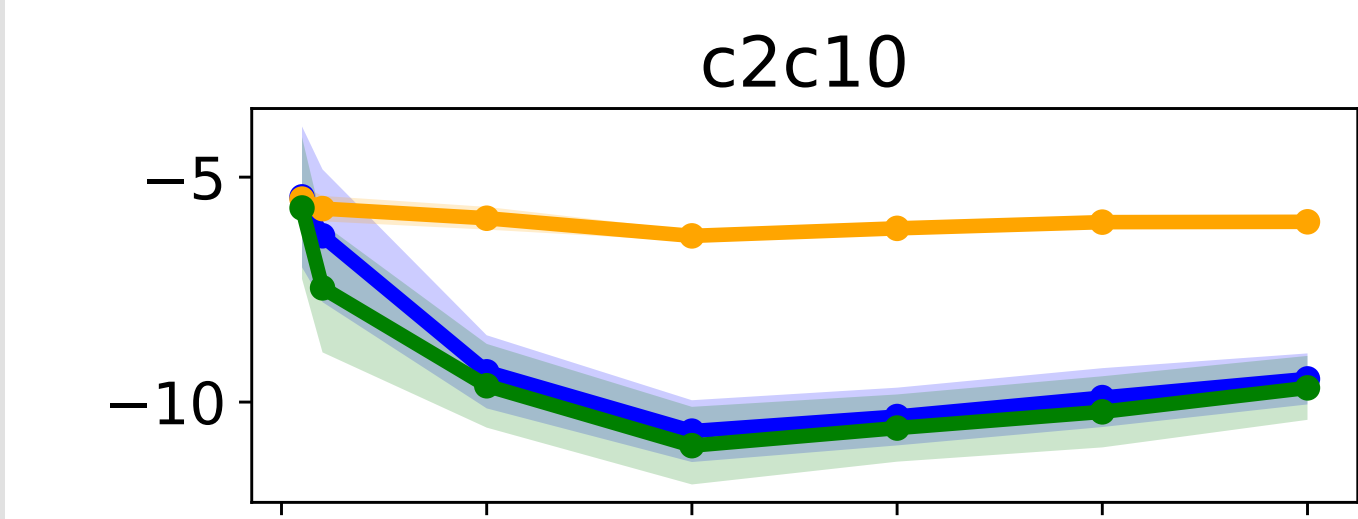
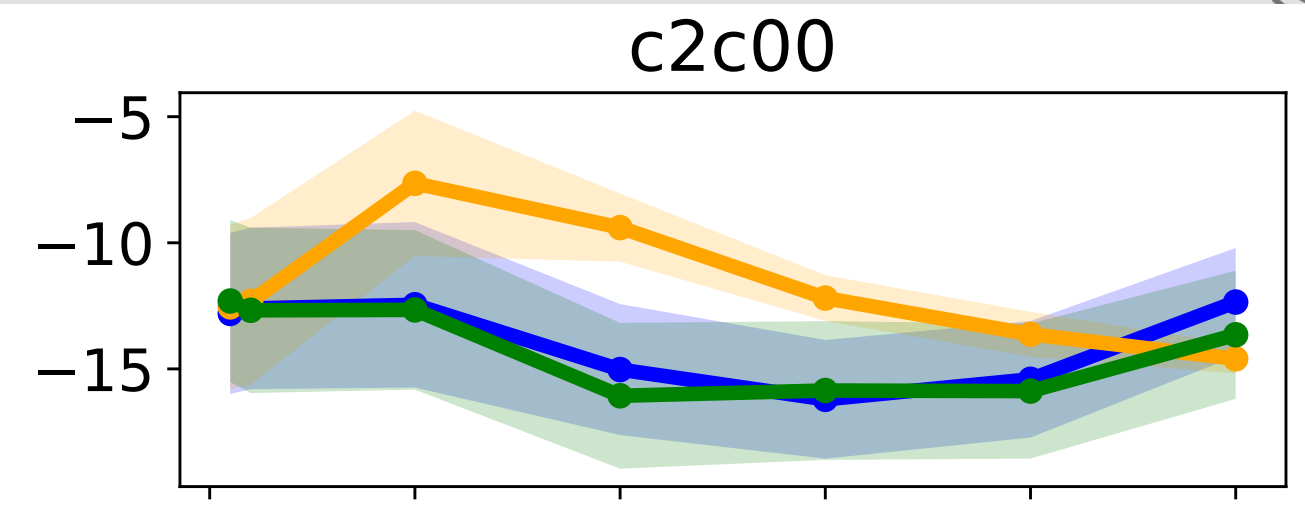
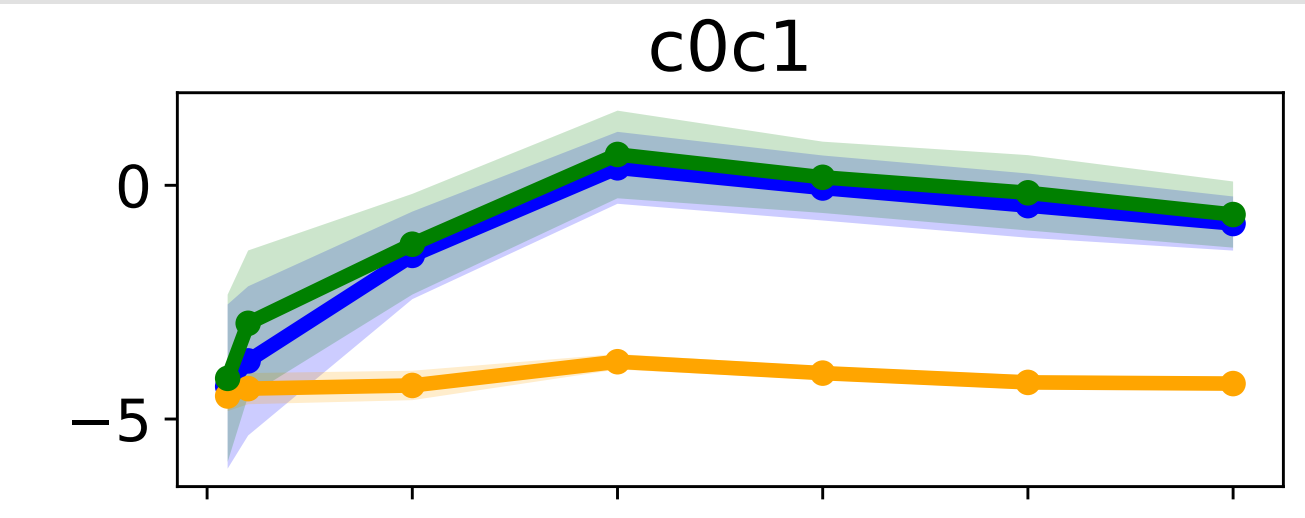
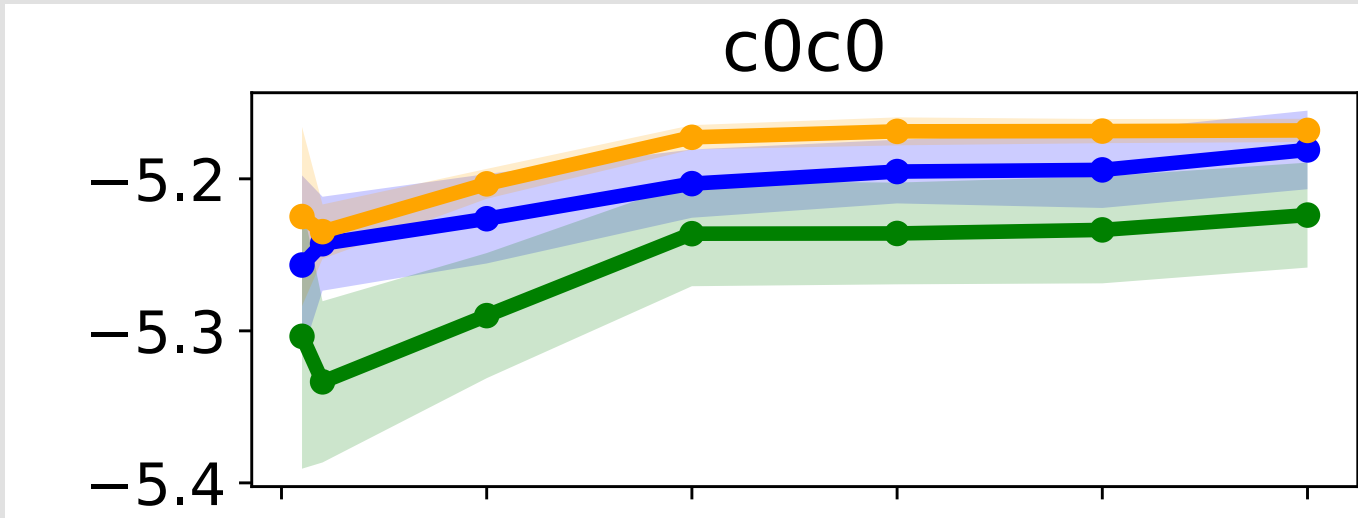
$$\sigma_{\text{ther},i}^2 = \frac{(y_{\text{ref},i} \bar{c} Q_i^{n+1})^2}{1 - Q_i^2} \rightarrow \sigma_{\text{ther},ij}^2 = \frac{y_{\text{ref},i} y_{\text{ref},j} \bar{c}^2 Q_i^{n+1} Q_j^{n+1}}{1 - Q_i Q_j} e^{-|p_i - p_j|/2l_p} e^{-|\theta_i - \theta_j|/2l_\theta}$$

with the goodness of fit determined by the Mahalanobis distance (“modified”  $\chi^2$ )

$$d_M(\vec{a}) = (\vec{y} - \vec{t}(\vec{a}))^T (\sigma_{\text{exp}}^2 + \sigma_{\text{ther},ij}^2)^{-1} (\vec{y} - \vec{t}(\vec{a}))$$

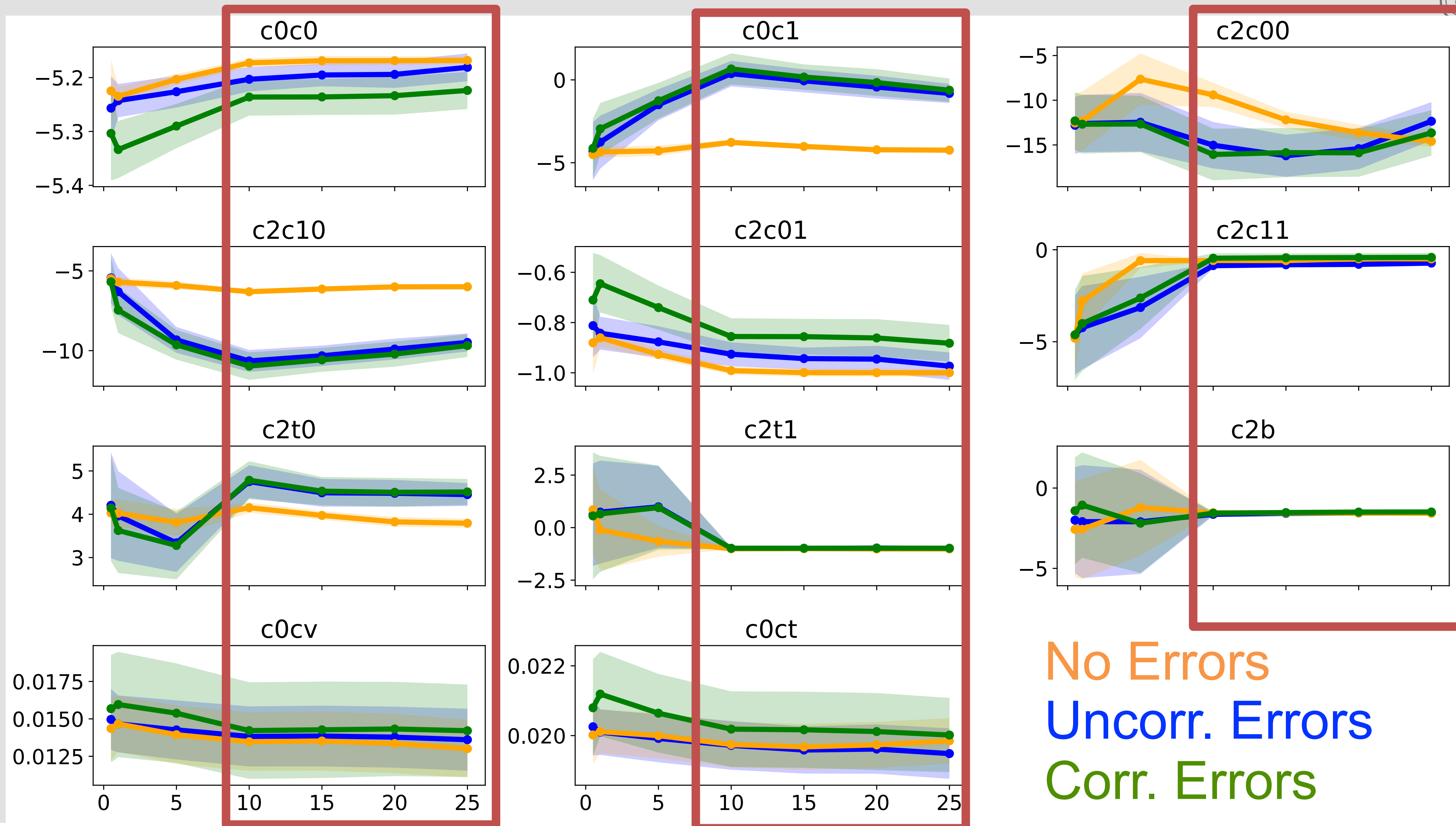
Correlations on data introduces strong degeneracies in the covariance matrix, so we use Gaussian processes to smooth the correlations.

# “Wesolowski Plots” for Pionless EFT at NLO



No Errors  
Uncorr. Errors  
Corr. Errors

# “Wesolowski Plots” for Pionless EFT at NLO





# Full posterior

We have two more parameters to estimate in a full Bayesian model calibration:  $\bar{c}^2$  (scale of truncation error) and  $\Lambda_b$  (EFT breakdown scale).

Full posterior for our EFT:

$$\underbrace{P(\vec{a}, \bar{c}^2, \Lambda_b | \vec{y}_{\text{exp}}, I)}_{\text{Total posterior}} \propto \underbrace{P(\vec{y}_{\text{exp}} | \vec{a}, \Sigma, I)}_{\text{Likelihood for } \vec{a}} \underbrace{P(\vec{a} | I)}_{\text{Prior for } \vec{a}} \underbrace{P(\bar{c}^2 | \Lambda_b, \vec{a}, I)}_{\text{Posterior for } \bar{c}^2} \underbrace{P(\Lambda_b | \vec{a}, I)}_{\text{Posterior for } \Lambda_b}$$

The posterior is found via sampling of  $\{\vec{a}, \bar{c}^2, \Lambda_b\}$ .

# Posterior for $\bar{c}^2$



For  $\bar{c}^2$  we choose (following Melendez et. al. Phys. Rev. C **100**, 044001)

$$P(\bar{c}^2 | \vec{a}, \Lambda_b, I) \sim \chi^{-2}(\nu, \tau^2(\vec{a}, \Lambda_b))$$

With hyper parameters:

$$\nu = \nu_0 + N_{\text{obs}} n_c$$
$$\tau^2(\vec{a}, \Lambda_b) = \frac{1}{\nu} \left( \nu_0 \tau_0 + \sum_{n,i} c_{n,i}^2(\vec{a}, \Lambda_b) \right)$$
$$c_{n,i}(\vec{a}, \Lambda_b) = \frac{y_i^{(n)}(\vec{a}_{(n)}) - y_i^{(n-1)}(\vec{a}_{(n-1)})}{y_{\text{ref}} \left( \frac{\max[p_{\text{soft}}, p_i]}{\Lambda_b} \right)^n}$$



## Posterior for $\Lambda_b$

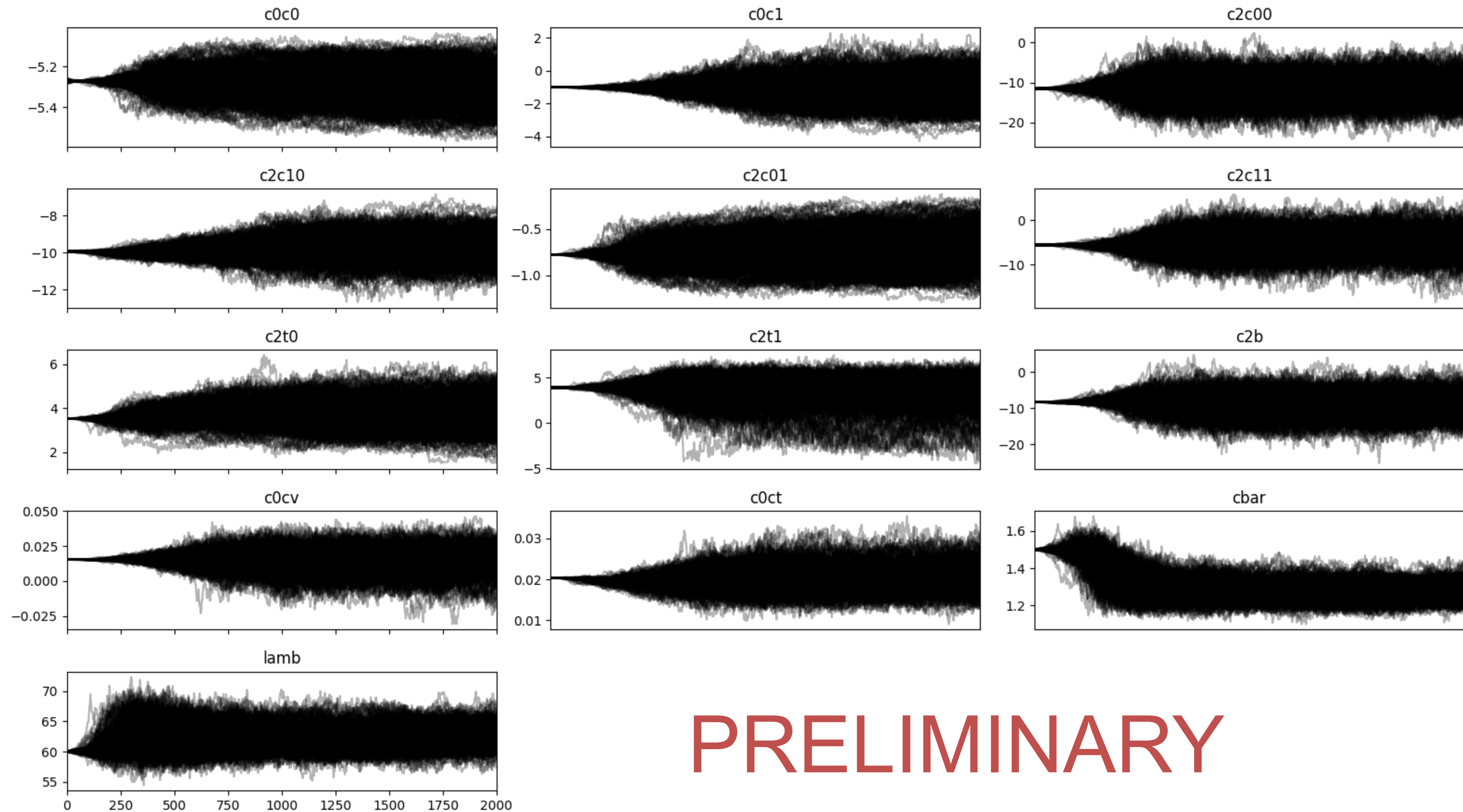
Our posterior for the breakdown scale also uses these hyper parameters:

$$P(\Lambda_b | \vec{a}, I) \propto \frac{P(\Lambda_b | I)}{\tau^\nu \prod_{n,i} \left( \frac{\max[p_{\text{soft}}, p_i]}{\Lambda_b} \right)^n}$$

This posterior needs to be numerically normalized as the normalization constant is dependent on  $\vec{a}$ .

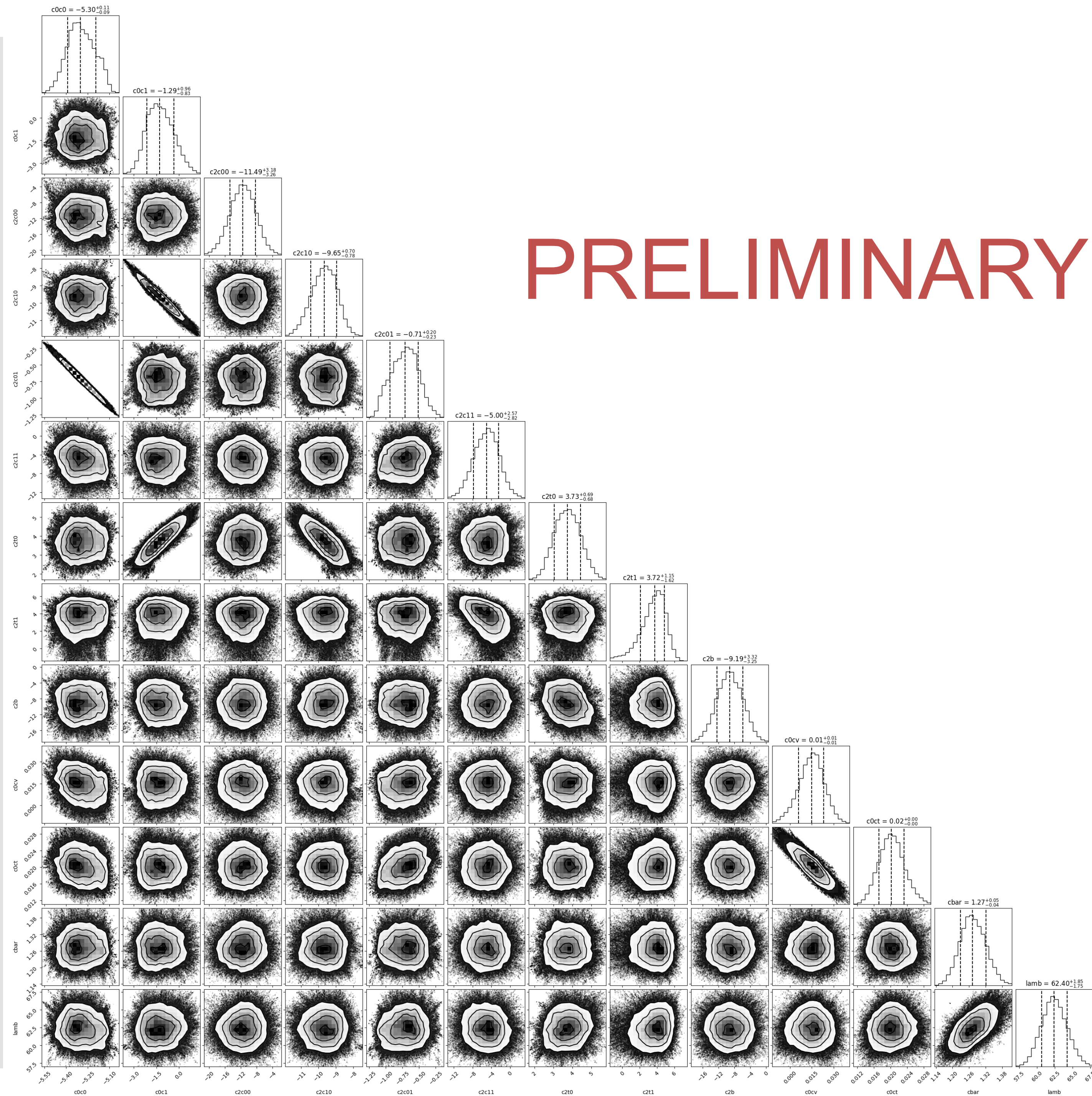


# Full Model Calibration



PRELIMINARY

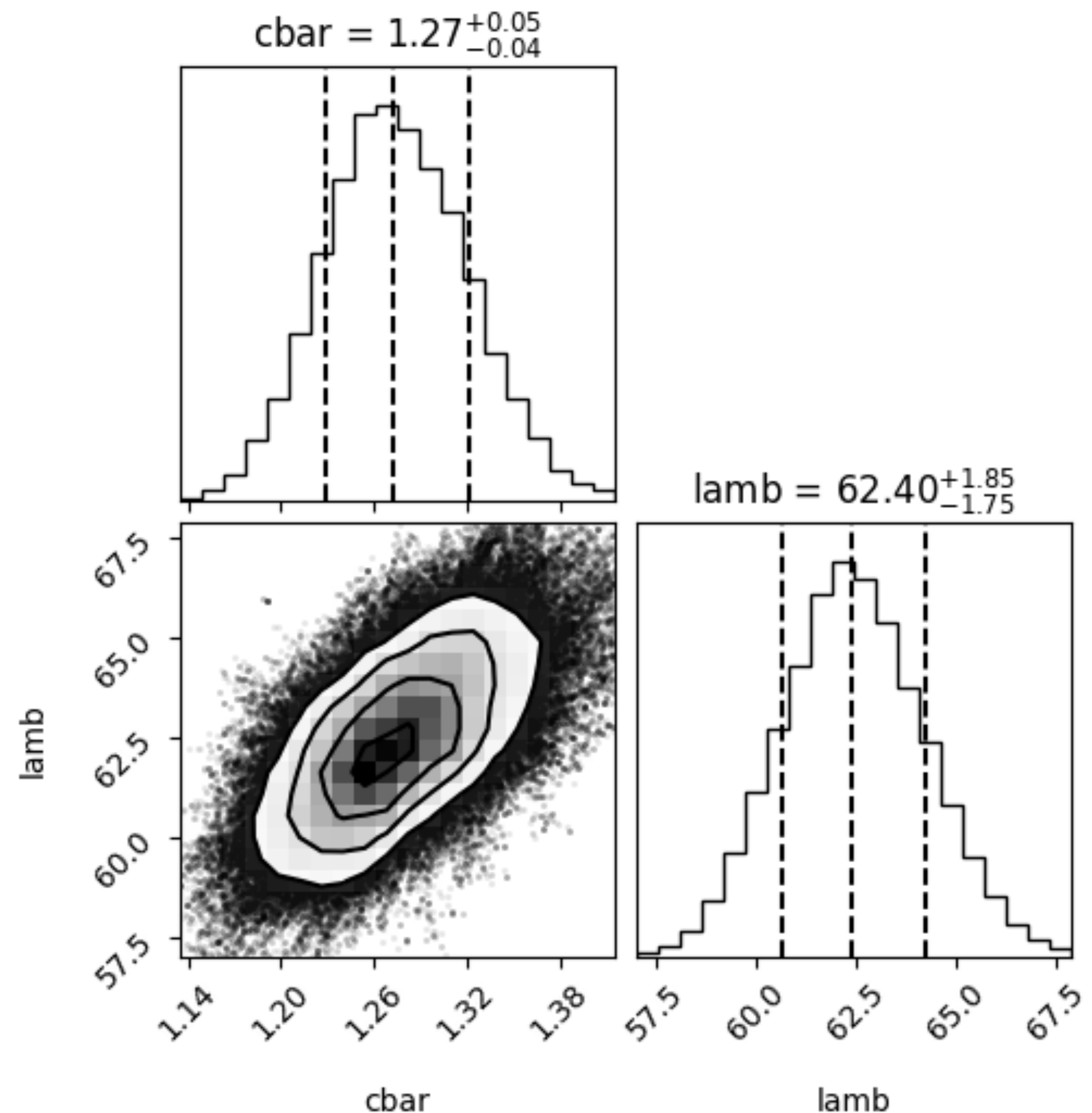
# Marginal Distributions



PRELIMINARY



# Truncation Error Parameters



**PRELIMINARY**

# Future Steps



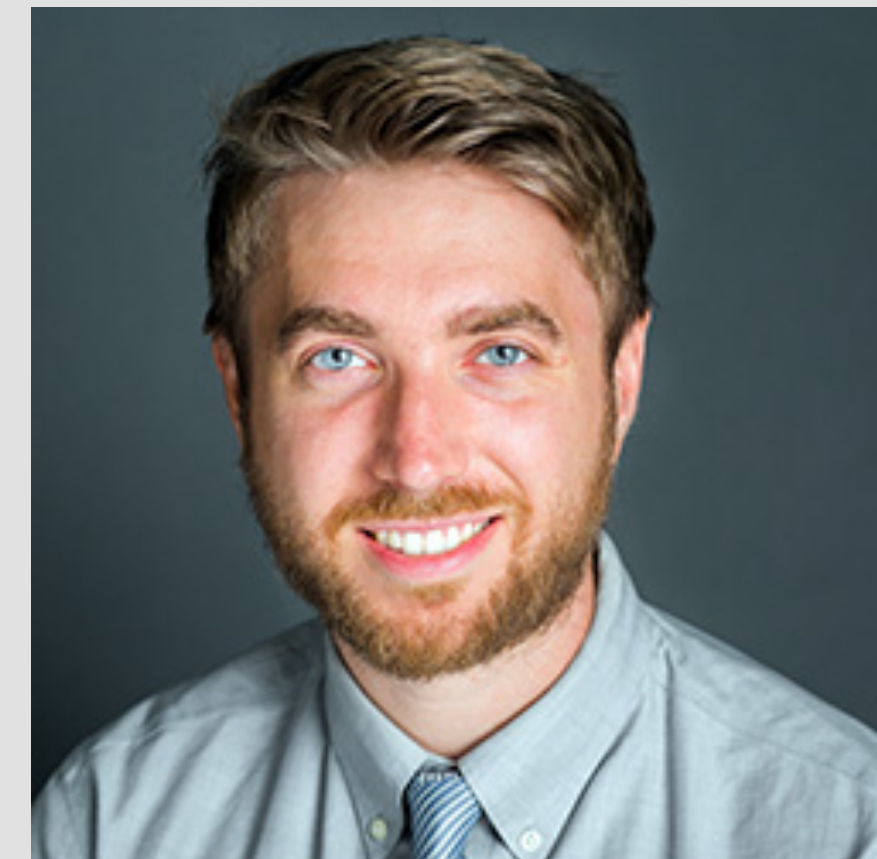
- Investigate fits at N3LO in the pionless regime
- Emulation for calculation of scattering observables



Ozge Surer  
Miami University



Stefan Wild  
LBNL



Matt Plumlee  
Northwestern

- Include other degrees of freedom:  $\pi$ 's and  $\Delta$ 's  $\rightarrow$  A new set of interactions with uncertainty quantification in  $\chi$ EFTs

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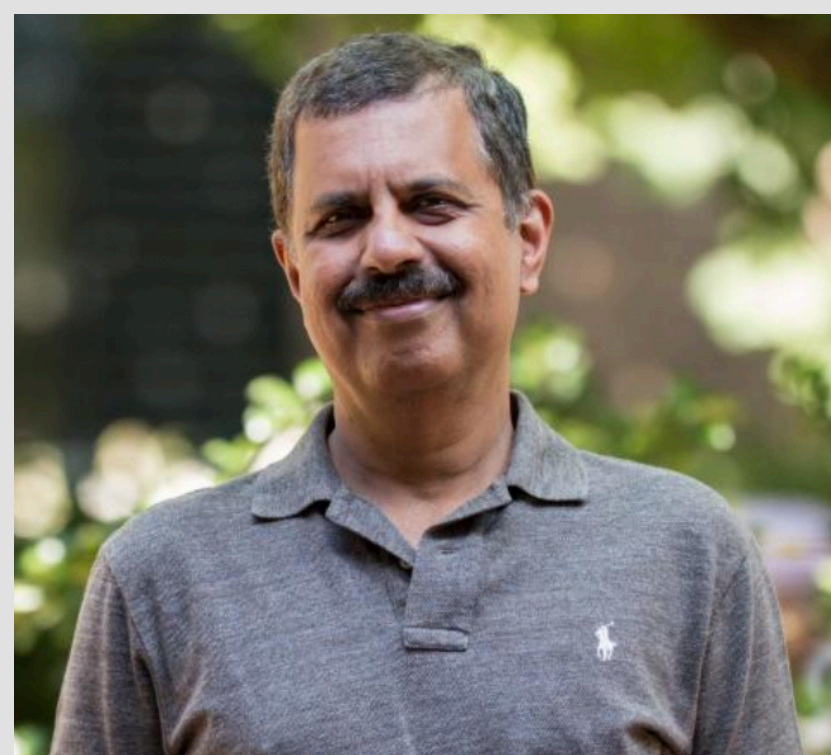
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- Include other degrees of freedom:  $\pi$ 's and  $\Delta$ 's  $\rightarrow$  A new set of interactions with uncertainty quantification in  $\chi$ EFTs, **MODEL MIXED!!!!**

# Acknowledgements

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Piarulli (PI), Pastore (PI),  
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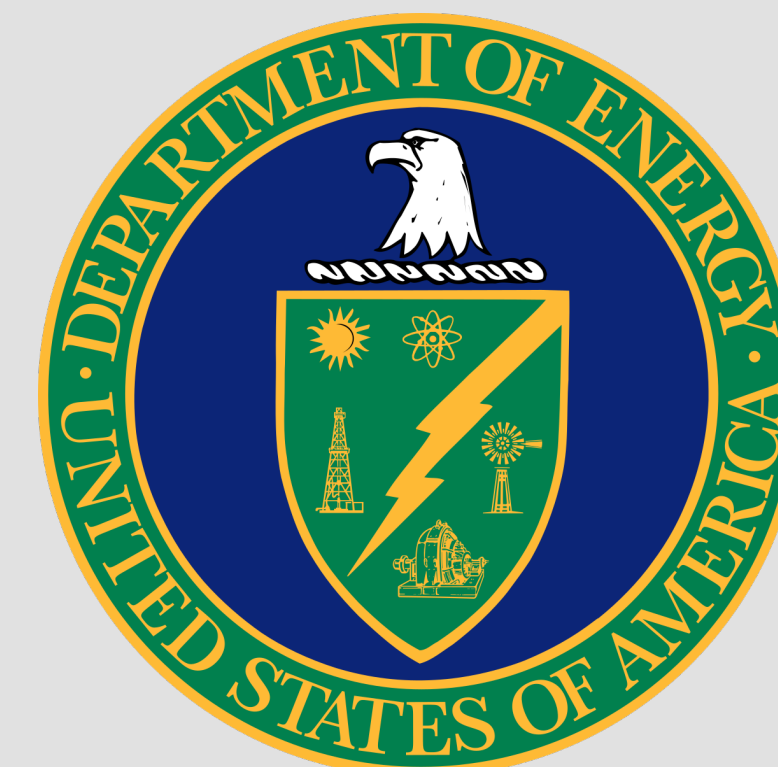


Sai Iyer  
WashU

## Computational Resources



## Funding



## Fellowship/Travel

