Recap 2nd Lecture

Each element *i* is represented by transfer matrix \mathbf{M}_i , trajectory from $\vec{x} = \prod_i \mathbf{M}_i \cdot \vec{x}_0$ Matrix Formalism: **Matrices (simple approx.)**: dipole and drift $\mathbf{M}_D = \begin{pmatrix} 1 & L \\ 0 & 1 \end{pmatrix}$ quadrupole $\mathbf{M}_Q = \begin{pmatrix} 1 & 0 \\ \pm 1/f & 1 \end{pmatrix}$ $x''(s) + \left\{ \frac{1}{\rho^2(s)} - k(s) \right\} x(s) = \frac{1}{\rho(s)} \frac{\Delta p}{p_s}$ linearization of all terms **Equations of Motion**: y''(s) + k(s) y(s) = 0build from solution of EQM for individual elements \rightarrow piecewise solution of EQM **Matrices from EQM**: **Transverse "Spaces":** configuration space (x,y), (horz.) trace space (x,x'), (horz.) phase space (x, p_x) based on 2nd statistical moments: $\sigma_x^2 = \overline{x^2}$, $\sigma_{x'}^2 = \overline{x'^2}$ **Beam Size & Divergence**: (Geom.) Emittance: area/ π occupied by the beam in trace space, statistically defined by second moments $\varepsilon_{x} = \sqrt{\overline{x^{2}} \overline{x'^{2}} - \overline{xx'}^{2}}, \qquad \varepsilon_{y} = \sqrt{\overline{y^{2}} \overline{y'^{2}} - \overline{yy'}^{2}}$