

Introduction to Practical Exercises: Magnetic Measurements

Objectives, activities, and safety aspects

Matthias Bonora, Marco Buzio, Lucio Fiscarelli, Melvin Liebsch, Carlo Petrone, TE-MSC

CAS course on "Normal- and Superconducting Magnets", 19.11–02.12.2023 St. Pölten, Austria

Acknowledgement

Many thanks for scientific and technical support to CERN staff:

Ignacio Aviles Santillana, Jose Luis Bardanca Iglesias, Guy Deferne, Dominique Drevard, David Giloteaux, Unai Martinez, Ricardo Beltron Mercadillo, Mariano Pentella, Piotr Rogacki, Stephan Russenschuck, Stefano Sgobba

HTL St. Pölten

Special thanks to Direktor Pfeffel and all technical staff who helped us set up the material.





2/35

Part I Magnetic Measurement Exercises

Objectives and activities





Our goal

To give you all, as magnet designers, makers and users:

 A taste of hands-on experience with some of the most useful magnetic measurement techniques

 A feel for practical capabilities and limits of magnetic field instrumentation





Where?

Facilities kindly made available by HTL St. Pölten, Elektrotechnik School

Courtesy Direktor M. Pfeffel







How to reach us





Room V039-1





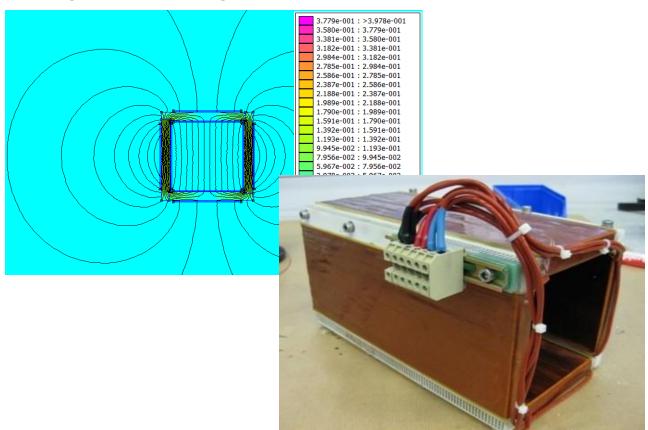


7/35

Test magnets

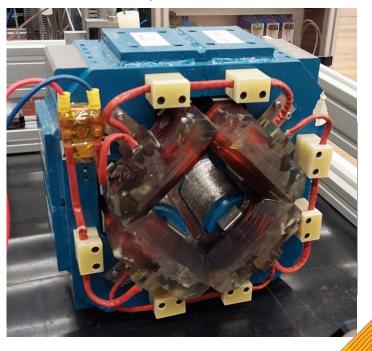
XY dipole corrector PXMCCATWAP

- 2D FEMM Model: 13.9 mT @ 12 A (Courtesy Antony Newborough, CERN)
- "Ugly quad" config possible



Quadrupole PXMCCATWAP

- 2D FEMM Model: 2.5 T/m @ 10 A (Courtesy Attilio Milanese, CERN)
- 3 nominally identical units installed

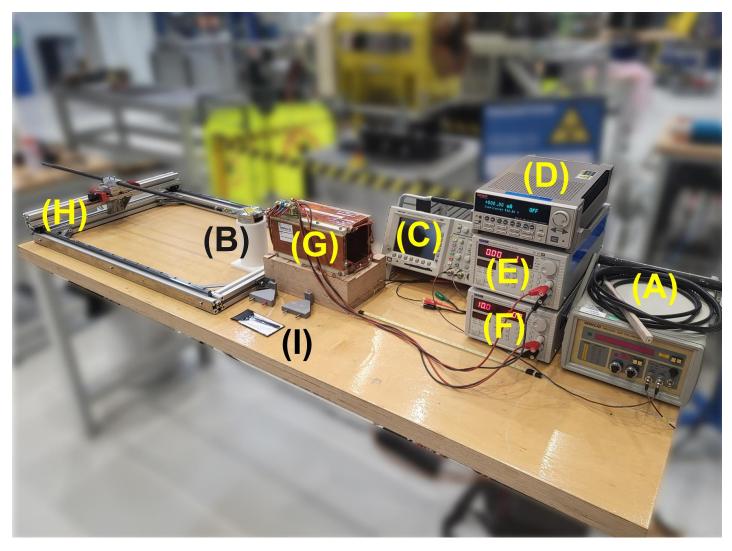




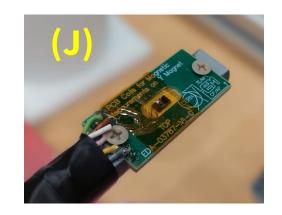


21.11.2023

Table 1 -Hall Probes (Melvin Liebsch)



- (A) NMR teslameter and probe (0.17 0.52 T)
- (B) Calibration permanent magnet (0.290 T)
- (C) Digital oscilloscope
- (D) Keithley 6221 current source
- (E) TSX unipolar power supply (for vertical field)
- (F) TSX unipolar power supply (for horizontal field)
- (G) Dipole corrector magnet (PXMCCATWAP)
- (H) Mapper stage (50 x 700 mm stroke)
- (I) Compass
- (J) Uniaxial Hall sensor HE244 (0.2 V/T @ 2 mA)







21.11.2023

Table 1 - Hall Probes

Goals

- Hall sensor calibration (sensitivity, zero field offset voltage)
- Polarity measurement
- Working principle of XY dipole correctors
- Determine the Sensor orientation with respect to the horizontal and vertical fields
- Mapping of XY dipole corrector (fringe field, ugly quad config)
- Basic usage and working principle of nuclear magnetic resonance (NMR) measurements





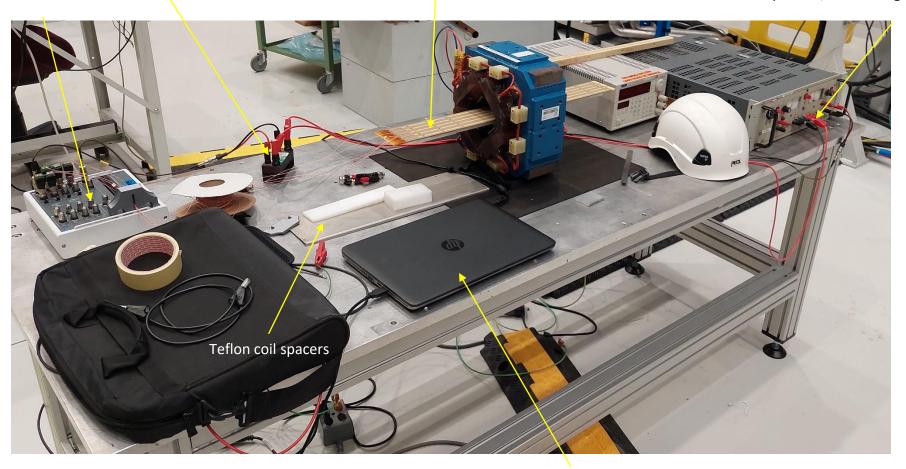
Table 2 - Fixed Induction Coils (Matthias Bonora)

High-precision 5 m Ω shunt for current measurement

NI 6366 USB DAQ, 8 ch., 16-bit 2 Ms/s

5x 16-turn, 24-layer, 2.3 m² XXX mm x XX mm PCB coil array

Kepco 6 A, 70 V voltage-controlled amplifier



Python scripts





Table 2 – Fixed Induction Coils

Goals

- Fixed PCB coil array integral measurement: gradient, centering, magnetic length, harmonics
- Dynamic effects: measurement of transfer function, AC eddy currents at different frequencies
- Degaussing, remanent field measurement
- Comparisons (to other instruments/teams)





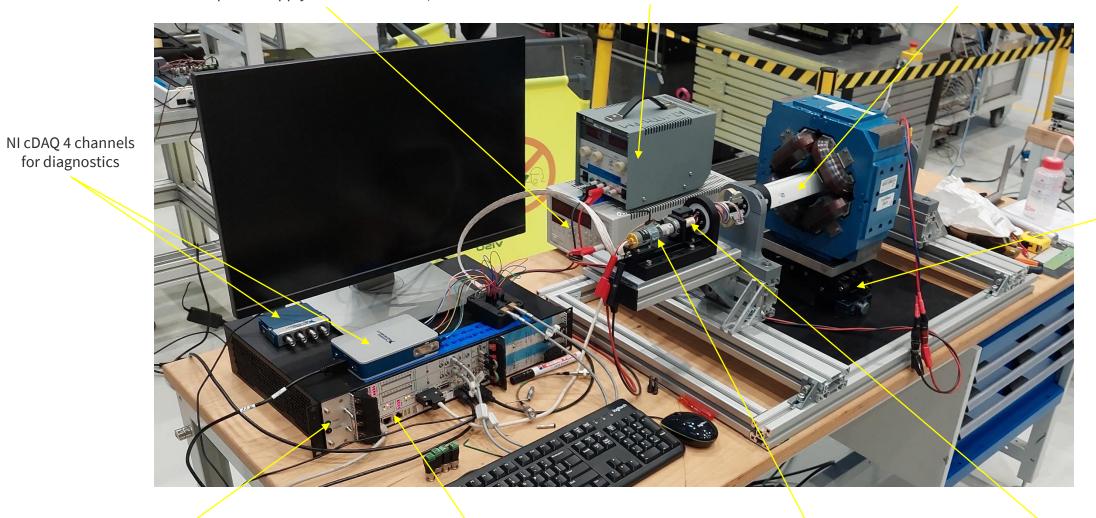
21.11.2023

Table 3 – Rotating Coil (Lucio Fiscarelli)

DC power supply TTi TSX1820P 18V/20A

DC power supply TTi PL330P 32V/3A

60-turn coils 2 x 200 mm x 35 mm



Manual-operated X-Y adjustable support ~100 mm stroke

PXI crate with 2 Fast Digital Integrators 3.0

PC controller running FFMM

DC motor 12 V c.c., 1,31 W, 66 tr/min

Slip rings 10 contacts



for diagnostics

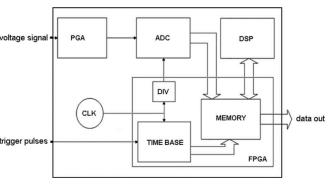


Table 3 – Rotating Coil

Fast Digital Integrator (FDI)

- 18-bit ADC at 500 kS/s
- Time base 50 ns
- Programmable gain from 0.1 to 100
- PXI bus interface





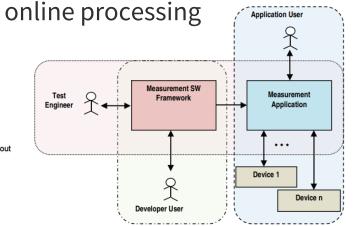
P. Arpaia, L. Bottura, L. Fiscarelli, L. Walckiers; Performance of a fast digital integrator in on-field magnetic measurements for particle accelerators. Rev. Sci. Instrum. 1 February 2012; 83 (2): 024702. https://doi.org/10.1063/1.3673000

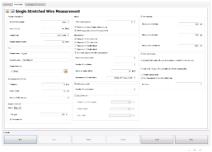
21.11.2023

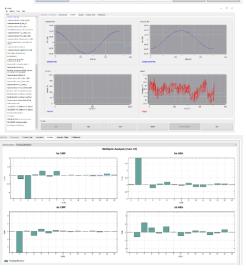
Flexible Framework for Magnetic Measurements (FFMM)

- Open software framework
- Based on free libraries (PoCo, Qt, ...)

Motion control, acquisition, and







rasquale Arpaia, Iviarco Buzio, Lucio Fiscarelli, Vitaliano Inglese; A software framework for developing measurement applications under variable requirements. Rev. Sci. Instrum. 1 November 2012; 83 (11): 115103. https://doi.org/10.1063/1.4764664





Table 3 - Rotating Coil

Goals

- Basics of a rotating-coil system (search coil, encoder, integrator)
- Calculation of coil sensitivity, post-processing of the acquired signals
- Standard measurement (gradient, centering, harmonics)
- Measurement at different currents (comparison with dynamic measurement)
- Harmonic feed-down (move coil transversally)
- Impact of rotation speed, effect of integration, effect of signal bucking
- Impact of magnetic perturbations (harmonics and symmetries)
- Comparisons (to other instruments/teams)



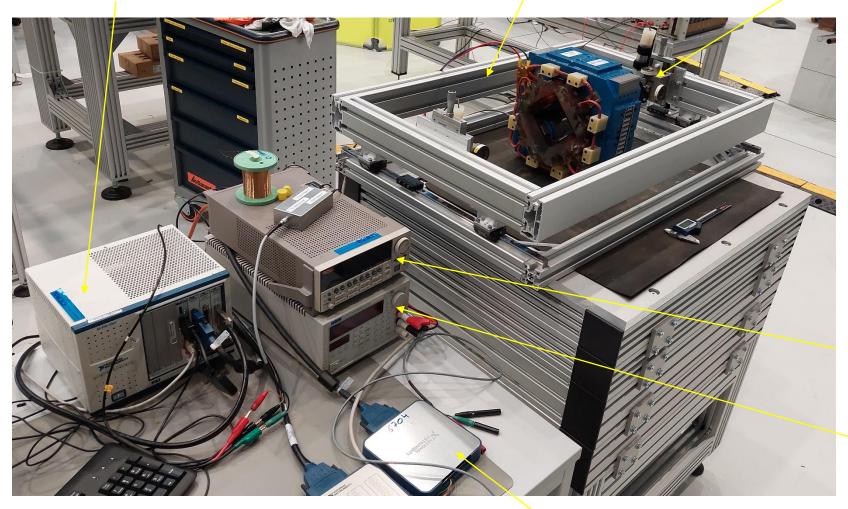


Table 4 - Stretched Wire (Carlo Petrone)

NI PXI express crate with analog control and acquisition modules PXI-6123 8 ch. \times 16-Bit @ 500 kS/s/ch.

Stretched wire support frame

micrometric XY wire end supports





manual wire translation tracked by (XXX μm precision)

Keythley 6221 AC current source for vibrating wire

TT TSX 1820P 18 V, 20 A programmable power supply







Table 4 – Stretched Wire

Goals

- Working principle of the single stretched wire SSW measurement technique
- Integrator drift correction
- Determine the magnetic center and gradient using the SSW technique
- Working principle of the oscillating wire technique
- Validate the central position by the oscillating wire
- Comparisons (to other instruments/teams)

21.11.2023





Table 5 - Magnetic materials (Marco Buzio)

TT 32 V, 2A power supply Matlab post-processing scripts NI USB DAQ 4 ch. \times 24-bit, 50 kS/s/ch. Magnetic and non-magnetic material samples Rad-hard SaCo17 blocks non-magnetic yoke Polarity checker Bartington MAG03 3D fluxgate Picoscope 4 ch. × 12-bit, XXX kS/s/ch. Metrolab THM7025 3D hall probe Foerster Magnetoscop 1.069 CERN Linac4 DTL PM Quad Kepco $\pm 40V$, ± 6 A power amplifier Halbach-array quadrupole ARMCO and mumetal permeameter ring samples





Table 5 - Magnetic materials

Goals

- Identify various kinds of magnetic and non-magnetic materials with the help of permanent magnets, Foerster permeameter
- Measure the impact of welds, cold work ...
- Measure Permanent Magnet samples (Hall probe)
- Measure hysteresis loop of ring steel samples with fluxmetric method (magnetization curves, degaussing ...)
- Measure effectiveness of magnetic shields with a Hall probe/Fluxgate





Part II Safety aspects

- Electrical hazards
- Magnetic hazard
- Mechanical hazards





Electrical hazards





Electrical hazards



- All equipment CE standard, grounded
- Max. ratings of power supplies: 76 V or 32 A or 432 W
- Operational levels: 50 V (ELV range) 10 A or 200 W

NO SPECIFIC RISK



T ≤ 40° C in normal use (but no thermal switches!)



IP20 contacts (finger; no water) additional Kapton protection.

Our own induction coils are voltage generators (<10 V) (transformer secondary)



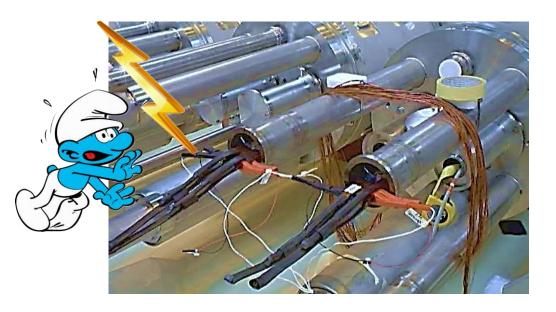


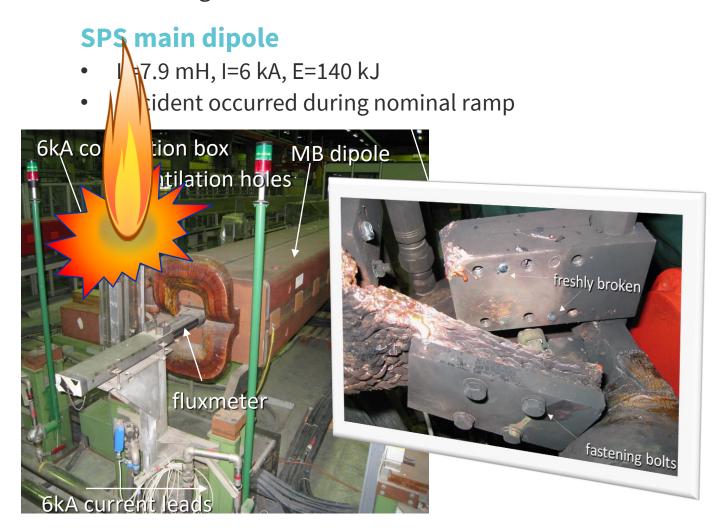
Electrical hazard – circuit break examples

- In case of sudden lead disconnection energy stored in the inductor $E = \frac{1}{2} LI^2$ is released quickly
- Overvoltage → risk of electrical arc, irreversible insulation damage

LHC main NbTi quadrupole

- L=11.2 mH
- Warm test I=2 A, E=0.02 J
- No damage!





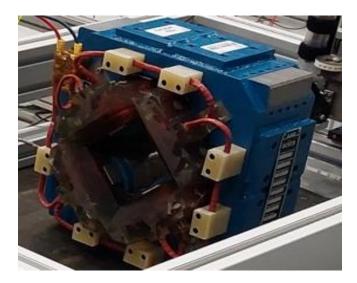




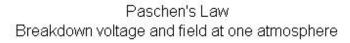
Electrical hazard - CAS exercises

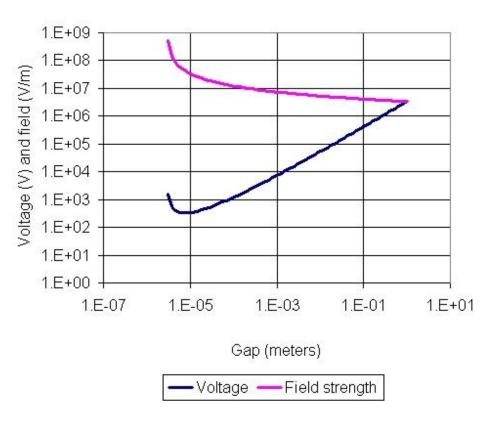


L=4 mH, /=10 A, E=0.2 J



L=32 mH, /=10 A, E=1.6 J





Overvoltage difficult to predict general safe distance in air @ 1 bar = 0.5 m



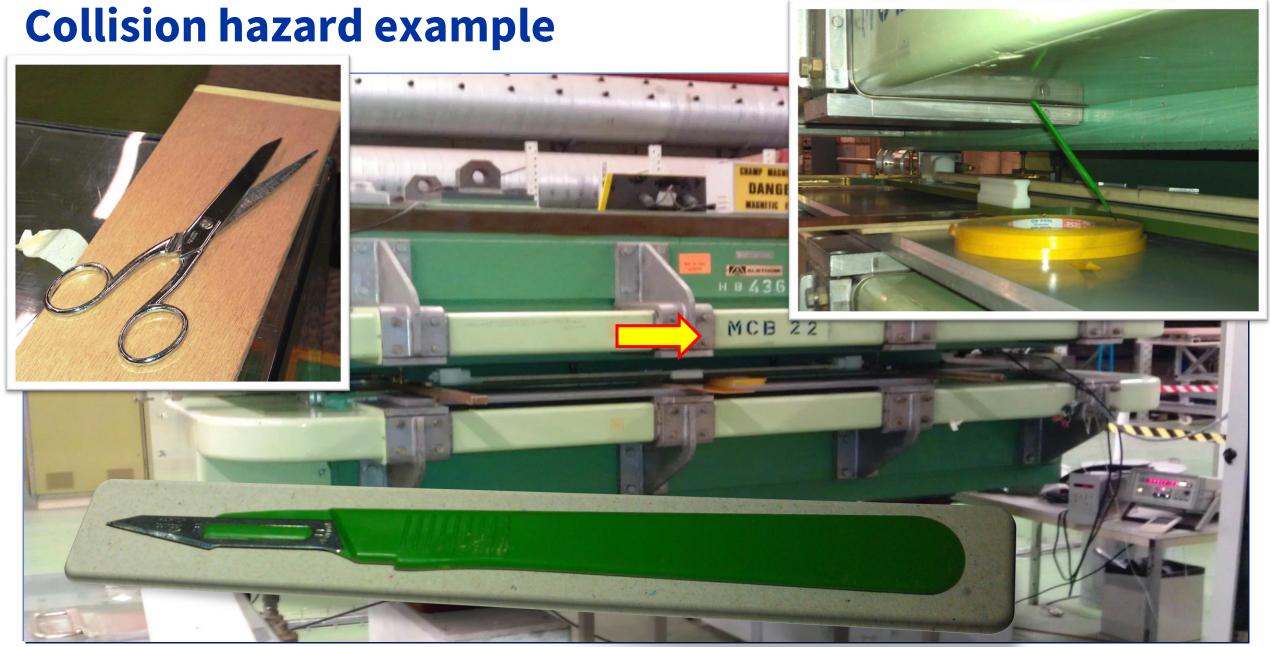


24/35

Magnetic field hazards





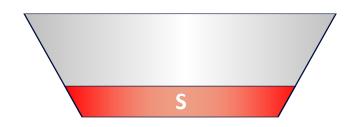






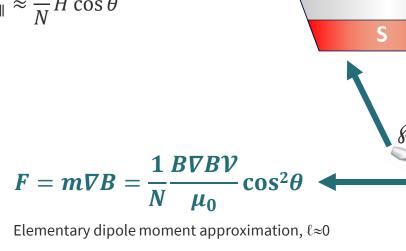
21.11.2023

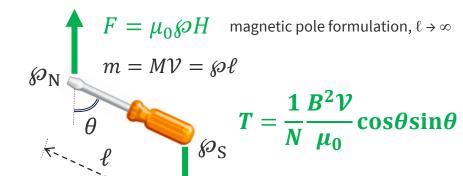
Magnetic forces on ferromagnetic objects



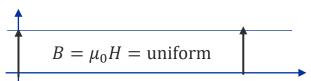
elongated object $N\approx 0$, $\mu_r \rightarrow \infty$ magnetized along easy axis

$$M = \frac{\mu_r - 1}{1 + N(\mu_r - 1)} H_{\parallel} \approx \frac{1}{N} H \cos \theta$$

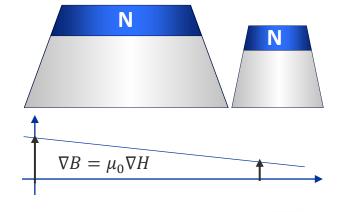








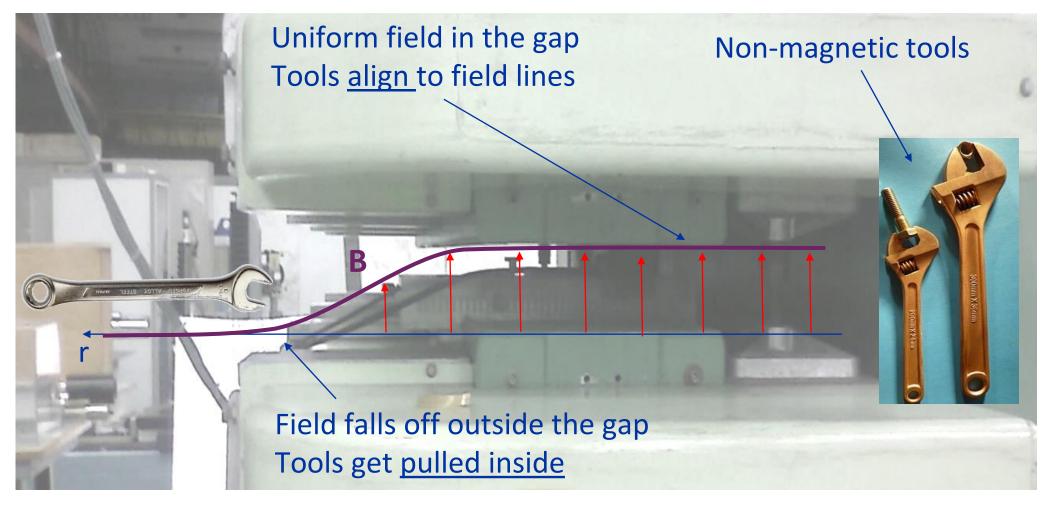
ferromagnetic bodies align to the field, are attracted towards stronger field







Ferromagnetic objects and large magnets



Recommended safety limit for standard tools:

Action level **B** ≥ **3 mT** if generated by a source ≥ **100 mT** (*Directive 2013/35/EU*)





Magnetic field sources - CAS exercises







B≤73 mT



B = 290 mT



B = 400 mT

- Electromagnets not a relevant projectile effect risk
- Permanent magnets: 3 mT threshold exceeded closer < 50 mm.
 Gap is very small, however please do not approach with ferromagnetic objects





Permanent magnets hazards

- Assorted NdFeB magnets will be handed out to test magnetic materials, up to 0.4 T on-contact
- Keep away from credit cards, mechanical watches, mobile phones ... and especially each other!
- Store in the boxes supplied when not in use









Description

We call this magnet with reverence THE DEATH MAGNET. We have no idea what you could reasonably do with this magnet

item number	Q-51-51-25-
Strength 1	approx. 100
Displacement force (1)	approx. 20 kg
Unit of Sale	1 piece

approx. 100 kg
approx. 20 kg
1 piece

CERN staff only





Pacemakers

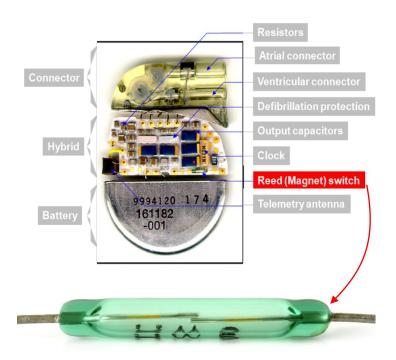
• Most cardiovascular implants switch into programming/diagnostic mode by applying an external field 1~10 mT:

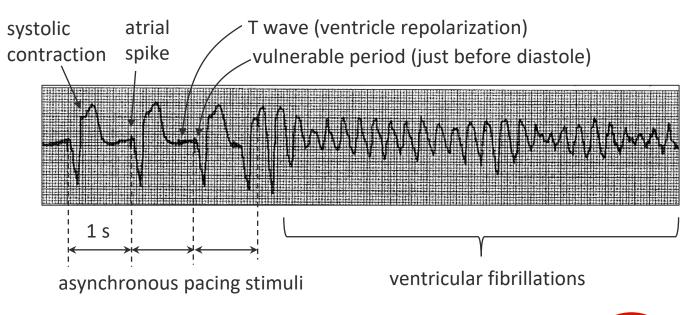
ICV (Implantable Cardioverters/Defibrillators) PM (Pacemakers)

 \rightarrow deactivate

→ asynchronous (fixed) pacing mode

- Recent devices with Hall/GMR sensors can be locked out → "MRI-conditional", safe up to 3 T
- But most PM have still reed switches with thresholds ≥ 0.7 mT
- ~16 fatalities (all MRI-related) reported before 2001





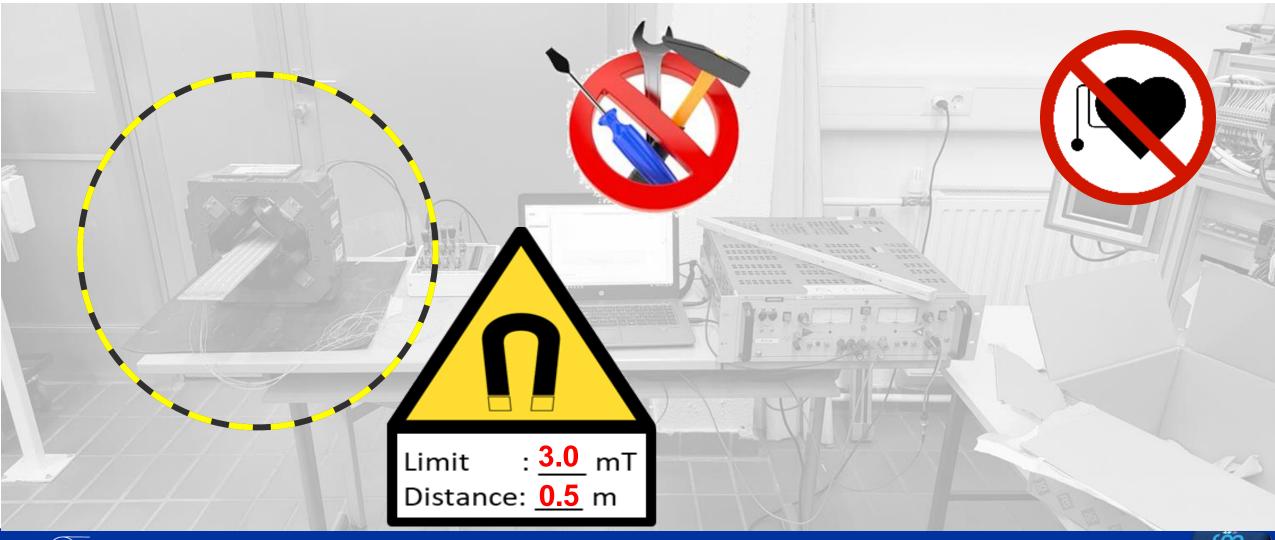
exposure to B > 0.5 mT is absolutely forbidden







Magnetic field hazard - legal obligations





Mechanical hazards

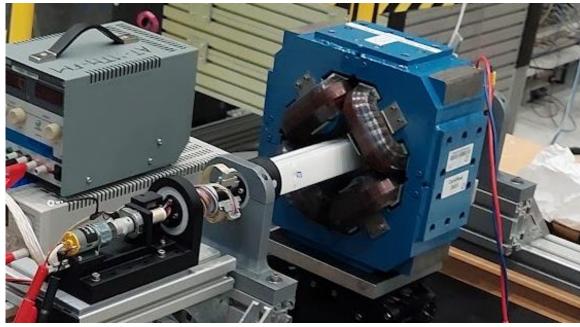




Mechanical hazards







Some exercises feature motorized moving parts. Please do not touch them!



Floor is relatively uncluttered, still ~ 190 000 tripping work accidents/year in EU





34/35

Summary - safety rules

- Please let instructors make/unmake connections
- Bearers of pacemakers, defibrillators, or any other kind of active implant are forbidden to enter the exercise area
- Respect the min. distance of 0.5 m between any magnet and ferromagnetic objects
- Keep the permanent magnets you'll be given 0.5 m away from any other magnet, ferromagnetic object, and potentially sensitive personal items (telephone, watches, credit cards ...)
- Watch your feet!

... and then have safe fun while training with magnets!



